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**User's Manual** 

# μ**SAP77016-B06**

**AMR Speech Codec Middleware** 

**Target Devices** 

μPD77018A μPD77019 μPD77110 μPD77111 μPD77112 μPD77113A μPD77114

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# Major Revisions in This Edition

Page	Contents
Throughout	Deletion of $\mu$ PD77018 and 77113 from the target device
p.12	Change of 1.3.1 Features
p.12	Change of 1.3.2 (2) Required memory size
p.13	Change of Table 1-3 Operation Quantity of AMR Speech CODEC
p.14	Change of 1.3.4 Directory configuration
p.15	Change of 1.3.5 Combination of libraries
p.20	2.2.3 amr_EncodeFrame function Change of hardware resource value
p.21	2.2.4 amr_InitDecoder function Change of hardware resource value
p.22	2.2.5 amr_ResetDecoder function Change of hardware resource value
p.23	2.2.6 amr_DecodeFrame function Change of hardware resource value
p.23	Change of Table 2-3 Receive Frame Type
p.25	Change of Table 2-4 Transmit Frame Type
p.26	2.2.10 amr_TX_to_RX function Change of register name and hardware resource value
p.26	Change of Table 2-5 Transmit/Receive Frame Type
p.28	2.2.13 amr_GetVersion function Change of the description of function
p.44	Change of APPENDIX A SAMPLE PROGRAM SOURCE

The mark **\*** shows major revised points.

# PREFACE

Target Readers	This manual is intended systems using the $\mu$ PD770	for users who wish to design and develop application 16 Family.		
	77018A, 77019) and the	cludes the $\mu$ PD7701X Family ( $\mu$ PD77015, 77016, 77017, $\mu$ PD77111 Family ( $\mu$ PD77110, 77111, 77112, 77113A, ual, however, only covers the $\mu$ PD77018A, 77019, 77110, d 77114.		
Purpose		tal is to help users understand the middleware used for developing $\mu$ PD77016 Family application systems.		
Organization	This manual consists of the CHAPTER 1 INTRODUCT CHAPTER 2 LIBRARY S CHAPTER 3 BIT STREAD CHAPTER 4 INSTALLAT APPENDIX A SAMPLE F APPENDIX B RELATED	TION PECIFICATIONS M FORMAT ION PROGRAM SOURCE		
How to Read This Manual	It is assumed that the reader of this manual has general knowledge in the fields of electrical engineering, logic circuits, microcontrollers and the C language.			
	To learn about $\mu$ PD7701X Family hardware functions $\rightarrow$ Refer to $\mu$ PD7701X Family User's Manual Architecture.			
	To learn about $\mu$ PD77111 $\rightarrow$ Refer to $\mu$ PD77111	Family hardware functions Family User's Manual Architecture.		
	•	Family instruction functions Family User's Manual Instruction.		
Conventions	Data significance:Higher digits on the left and lower digits on the rightActive low representation: $\overline{xxx}$ (overscore over pin or signal name)Note:Footnote for item marked with Note in the textCaution:Information requiring particular attentionRemark:Supplementary informationNumber representation:Binary xxxx or ObxxxxDecimal xxxxHexadecimal 0xxxxx			

# **Related Documents**

The related documents indicated in this publication may include preliminary versions. However, preliminary versions are not marked as such.

Document Name	Pamphlet	Data Sheet	User's Manual		Application Note
Part Number			Architecture	Instructions	Basic Software
μPD77016	-	U10891E	U10503E	U13116E	U11958E
μPD77015		U10902E			
μPD77017					
μPD77018A		U11849E			
μPD77019					
μPD77019-013		U13053E			
μPD77110	U12395E	U12801E	U14623E		
μPD77111					
μPD77112					
μPD77113A		U14373E			
μPD77114					
μPD77115		U14867E			

# Documents Related to µPD77016 Family

# **Documents Related to Development Tools**

Document Name	Document No.	
RX77016 User's Manual	Function	U14397E
	Configuration Tool	U14404E
RX77016 Application Note	HOST API	U14371E

Caution The related documents listed above are subject to change without notice. Be sure to use the latest version of each document for designing.

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#### **CHAPTER 1 INTRODUCTION**

# 1.1 Middleware

Middleware is the name given to a group of software that has been tuned so that it draws out the maximum performance of the processor and enables processing that is conventionally performed by hardware to be performed by software.

The concept of middleware was introduced with the development of a new high-speed processor, the DSP, in order to facilitate operation of the environments integrated in the system.

By providing appropriate speech codec and image data compression/decompression-type middleware, NEC is offering users the kind of technology essential in the realization of a multimedia system for the  $\mu$ PD77016 Family, and is continuing its promotion of system development.

#### 1.2 AMR Speech CODEC

The AMR speech CODEC is a 4.75 kbps to 12.2 kbps speech compression/decompression codec standardized by 3GPP (3rd Generation Partnership Project). It includes a multi-rate speech coder, a silence compression function, and an error concealment function. The multi-rate speech coder enables selection of the bit rate from a total of 8 (refer to Table 1-1), except MRDTX<sup>Note1</sup>, and allows bit rate switching on a frame by frame (20 ms) basis.

Codec Mode	Bit Rate
MR122	12.20 kbps (GSM EFR <sup>Note 2</sup> )
MR102	10.20 kbps
MR795	7.95 kbps
MR74	7.40 kbps (IS-641 <sup>Note 3</sup> )
MR67	6.70 kbps (PDC-EFR <sup>Note 4</sup> )
MR59	5.90 kbps
MR515	5.15 kbps
MR475	4.75 kbps
	1.80 kbps

#### Table 1-1. AMR Speech CODEC Bit Rates

- **Notes 1.** The encoder automatically executes compression in the MRDTX mode if the silence compression function is set to ON.
  - 2. GSM EFR: ETSI GSM 06.90 Enhanced Full Rate Speech Codec
  - 3. IS-641: TIA/EIA IS-641 TDMA Enhanced Full Rate Speech Codec
  - 4. PDC-EFR: ARIB 6.7 kbps Enhanced Full Rate Speech Codec

**Remark** For details of each standard, refer to the reports in **APPENDIX B RELATED DOCUMENTS**.

# 1.3 Outline of System

# 1.3.1 Features

- Supports AMR speech CODEC Version 7.6.0 of 3GPP (excluding channel codec).
  - Supports eight bit rates for compression/decompression (refer to Table 1-1 AMR Speech CODEC Bit Rates).
  - Silence compression function (VAD1 and VAD2 options supported)
  - Coding/decoding of 160 samples/frame at sampling frequency of 8 kHz
  - All speech I/O data is 16-bit linear PCM data<sup>Note</sup>.

**Note** In the  $\mu$ SAP77016-B06 library, 13-bit data from the MSB is used.

#### 1.3.2 Operating environment

#### \* (1) Target DSP

• μPD77018A, 77019, 77110, 77111, 77112, 77113A, 77114

## **\*** (2) Required memory size

Memory Space	Туре	Size [Words]		
		Codec Encoder Decoder		
Instruction memory	_	14.1 K	10.2 K	4.4 K
X memory	RAM	2.9 K	2.5 K	2.4 K
	ROM	11.2 K	11.1 K	10.7 K
Y memory	RAM	2.4 K	1.9 K	1.5 K
	ROM	3.6 K	3.2 K	2.8 K

Table 1-2. Required Memory Size

- **Remarks 1.** Locate the X memory and Y memory areas used for the library of the  $\mu$ SAP77016-B06 in the internal ROM/RAM space.
  - 2. The required memory size shown in the table above does not include the buffers for speech data and bit stream data I/O. For details, refer to 2.3 Memory Structure.

## (3) Software tools (Windows<sup>™</sup> version)

DSP tools:	Work bench	WB77016
	High-speed simulator	HSM77016
	Debugger	ID77016

#### 1.3.3 Performance

Table 1-3 shows the MIPS values necessary for executing processing of one frame in real time (20 ms).

#### [Measurement conditions]

- High-speed simulator: HSM77016
- Evaluated speech: Speech file of 3GPP Test Sequences (TS 26.074) is used.
- Evaluation result: Operation quantity is measured when the speech file is compressed and decompressed, to calculate the worst case value.
- The operation quantity for compression is that of the amr\_EncodeFrame function and the operation quantity for decompression is that of the amr\_DecodeFrame function. The operation quantity of other functions and interrupt handlers is not included.

Codec Mode	VAD OFF [MIPS]		VAD1 ON [MIPS]		VAD2 ON [MIPS]	
	Compression	Decompression	Compression	Decompression	Compression	Decompression
MR475	15.116	2.658	15.658	2.658	16.749	2.683
MR515	12.000	2.675	12.542	2.675	13.635	2.675
MR59	14.901	2.674	15.425	2.674	16.552	2.661
MR67	19.331	2.740	19.817	2.740	20.970	2.745
MR74	17.371	2.408	17.864	2.408	18.992	2.407
MR795	18.318	2.783	18.830	2.783	19.934	2.835
MR102	18.548	2.495	19.054	2.495	20.161	2.495
MR122	19.997	2.489	20.510	2.489	21.626	2.489

## Table 1-3. Operation Quantity of AMR Speech CODEC

## \* 1.3.4 Directory configuration

The directory configuration of the  $\mu$ SAP77016-B06 is shown below.



# 1.3.5 Combination of libraries

\*

Table 1-4 shows the combination of the header file and the library to be used.Table 1-5 shows the combination of the library and the DSP when using the Codec library.

## Table 1-4. Combination of Header File and Library

Library	Header File	Code	Constant for RAM	Constant for ROM
Codec library	amr_lib.h	amrcodec.lib	amrcodra.lib	amrcodro.lib
Encoder library	amr_libe.h	amrencod.lib	amrencra.lib	amrencro.lib
Decoder library	amr_libd.h	amrdecod.lib	amrdecra.lib	amrdecro.lib

#### Table 1-5. Combination of Target Device and Library (Codec Library)

Device Name	Code (amrcodec.lib)	RAM Constant (amrcodra.lib)	ROM Constant (amrcodro.lib)
μPD77015	×	×	×
μPD77016	×	×	×
μPD77017	×	×	×
μPD77018A	$\checkmark$	×	$\checkmark$
μPD77019	$\checkmark$	×	$\checkmark$
μPD77110	$\checkmark$	$\checkmark$	×
μPD77111	$\checkmark$	×	$\checkmark$
μPD77112	$\checkmark$	×	$\checkmark$
μPD77113A	$\checkmark$	$\sqrt{Note}$	$\sqrt{Note}$
μPD77114	$\checkmark$	$\sqrt{Note}$	$\sqrt{Note}$
μPD77115	×	×	×

Note Link either of amrcodra.lib or amrcodro.lib.

# **CHAPTER 2 LIBRARY SPECIFICATIONS**

This chapter explains the function specifications and calling conventions of the  $\mu$ SAP77016-B06.

# 2.1 Application Processing Flow

Figures 2-1 and 2-2 show examples of application processing using the  $\mu$ SAP77016-B06.



Figure 2-1. Example of Application Processing Flow (Encoder)



Figure 2-2. Example of Application Processing Flow (Decoder)

# 2.2 Function Specifications

# 2.2.1 amr\_InitEncoder function

The amr\_InitEncoder function initializes the constants, coefficient table, and buffers used for the encoder. Call this function only once when using the encoder.

[Format]	Encoder initialization function amr_InitEncoder Initializes the RAM area necessary for processing the AMR speech CODEC encoder, sets the VAD mode, calls the amr_ResetEncoder function, and initializes parameters. call amr_InitEncoder		
[Argument]	Туре	Argument	Description
	Register	R0L	Turns ON/OFF DTX (silence compression function) (see Table 2-1)
[Return value]	None		
[Registers used]	R0, R1, DP0,	DP1, DP4, D	DP5
[Hardware resources]	Maximum stack level: 4		
	Maximum loop stack level: 1		al: 1
	Maximum number of repetitions: 320		
	Maximum nur	mber of cycle	es: 1256

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

# Table 2-1. DTX Mode

DTX Mode	Value	Description
DTX_OFF	0	Silent compression function OFF
DTX_ON_VAD1	1	Silent compression function ON (VAD1 option)
DTX_ON_VAD2	2	Silent compression function ON (VAD2 option)

# 2.2.2 amr\_ResetEncoder function

The amr\_ResetEncoder function resets the constants, coefficient table, and buffers used for the encoder to the initial status.

[Classification]	Encoder reset function		
[Function name]	amr_ResetEncoder		
[Summary of function]	Resets the parameters necessary for processing the AMR speech CODEC encoder to		
	the initial status.		
[Format]	call amr_ResetEncoder		
[Argument]	None		
[Return value]	None		
[Registers used]	R0, R1, DP0, DP1, DP4, DP5		
[Hardware resources]	Maximum stack level:	3	
	Maximum loop stack level:	1	
	Maximum number of repetitions:	320	
	Maximum number of cycles:	1248	

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

#### 2.2.3 amr\_EncodeFrame function

The amr\_EncodeFrame function compresses speech data of 16 bits  $\times$  160 samples at a specified bit rate. When the silence compression function is set to ON during initialization, the silence compression function is automatically enabled in accordance with speech input.

[Classification] [Function name] [Summary of function] [Format]	Encode processing function amr_EncodeFrame Compresses speech of one frame (160 samples) at a specified bit rate. call amr_EncodeFrame		
[Argument]	Туре	Argument	Description
	Register	R0L	Encode mode (see Table 2-2, excluding MRDTX)
	Register	DP4	First address of speech input buffer
	Register	DP0	First address of bit stream output buffer
[Return value]	Туре	Return Value	Description
[Return value]	Type Register	Return Value R0L	Description Encode mode used for compression (see Table 2-2)
[Return value] [Registers used]	Register R0, R1, R2, F	R0L	·
	Register R0, R1, R2, F	R0L R3, R4, R5, R6 N4, DN5, DN6	Encode mode used for compression (see Table 2-2) 6, R7, DP0, DP1, DP2, DP3, DP4, DP5, DP6, DP7, DN0, DN1,
[Registers used]	Register R0, R1, R2, F DN2, DN3, D	R0L R3, R4, R5, R( N4, DN5, DN6 ck level:	Encode mode used for compression (see Table 2-2) 6, R7, DP0, DP1, DP2, DP3, DP4, DP5, DP6, DP7, DN0, DN1, 6, DN7, DMX, DMY 5
[Registers used]	Register R0, R1, R2, F DN2, DN3, D Maximum sta Maximum loo	R0L R3, R4, R5, R( N4, DN5, DN6 ck level:	Encode mode used for compression (see Table 2-2) 6, R7, DP0, DP1, DP2, DP3, DP4, DP5, DP6, DP7, DN0, DN1, 6, DN7, DMX, DMY 5 3

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

Codec Mode	Value	Description
MR475	0	Compression/decompression mode at 4.75 Kbps
MR515	1	Compression/decompression mode at 5.15 Kbps
MR59	2	Compression/decompression mode at 5.90 Kbps
MR67	3	Compression/decompression mode at 6.70 Kbps
MR74	4	Compression/decompression mode at 7.40 Kbps
MR795	5	Compression/decompression mode at 7.95 Kbps
MR102	6	Compression/decompression mode at 10.20 Kbps
MR122	7	Compression/decompression mode at 12.20 Kbps
MRDTX	8	Compression/decompression mode when silence compression function is enabled

#### Table 2-2. Operation Mode of Encoder/Decoder

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## 2.2.4 amr\_InitDecoder function

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The amr\_InitDecoder function initializes the constants, coefficient table, and buffers used for the decoder. Call this function only once when using the decoder.

[Classification]	Decoder initialization function		
[Function name]	amr_InitDecoder		
[Summary of function]	Initializes the RAM area necessary for processing the AMR speech CODEC decoder,		
	calls the amr_ResetDecoder funct	ion, and initializes parameters.	
[Format]	call amr_InitDecoder		
[Argument]	None		
[Return value]	None		
[Registers used]	R0, R1, R2, DP0, DP1, DP2, DP4	, DP5, DP6, DN5	
[Hardware resources]	Maximum stack level:	3	
	Maximum loop stack level:	1	
	Maximum number of repetitions:	154	
	Maximum number of cycles:	2545	

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

# 2.2.5 amr\_ResetDecoder function

The amr\_ResetDecoder function resets the constants, coefficient table, and buffers used for the decoder to the initial status.

[Classification]	Decoder reset function	
[Function name]	amr_ResetDecoder	
[Summary of function]	Resets the parameters necessary	for processing the AMR speech CODEC decoder to
	the initial status.	
[Format]	call amr_ResetDecoder	
[Argument]	None	
[Return value]	None	
[Registers used]	R0, R1, R2, DP0, DP1, DP2, DP4,	DP5, DP6, DN5
[Hardware resources]	Maximum stack level:	2
	Maximum loop stack level:	1
	Maximum number of repetitions:	154
	Maximum number of cycles:	1009

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

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# 2.2.6 amr\_DecodeFrame function

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The amr\_DecodeFrame function decompresses compressed bit stream data to speech data of 16 bits  $\times$  160 samples.

[Classification]	Decode processing function		
[Function name]	amr_DecodeFrame		
[Summary of function]	Decompresse	es speech of o	one frame (160 samples) from a bit stream.
[Format]	call amr_Dec	odeFrame	
[Argument]	Туре	Argument	Description
	Register	ROL	Decode mode <sup>№ote</sup> (see <b>Table 2-2 Operation Mode of Encoder/</b> <b>Decoder</b> . Except for MRDTX.)
	Register R1L		Receive frame type (see Table 2-3)
	Register         DP4         First address of speech output buffer		First address of speech output buffer
	Register         DP0         First address of bit stream input buffer		
	<b>Note</b> When the receive frame type is RX_NO_DATA, use the decode mode of the preceding frame as the argument.		
[Return value]	None		
[Registers used]	R0, R1, R2, R3, R4, R5, R6, R7, DP0, DP1, DP2, DP3, DP4, DP5, DP6, DP7, DN0, DN1,		
	DN2, DN3, DN4, DN5, DN6, DN7		
[Hardware resources]	Maximum sta	ick level:	5
	Maximum loc	p stack level:	2
	Maximum nu	mber of repet	itions: 170
	Maximum number of MIPS: 2.9		

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

#### Table 2-3. Receive Frame Type

RX_TYPE	Value	Description
RX_SPEECH_GOOD	0	Speech frame (without error)
RX_SPEECH _DEGRADED	1	Speech frame (with error of at least 1 bit)
RX_ONSET	2	ONSET frame
RX_SPEECH_BAD	3	Speech frame (with error)
RX_SID_FIRST	4	Start of SID frame
RX_SID_UPDATE	5	Updates SID frame (without error)
RX_SID_BAD	6	Updates SID frame (with error)
RX_NO_DATA	7	Frame without data

#### 2.2.7 amr\_sid\_sync\_init function

The amr\_sid\_sync\_init function initializes the constants, coefficient table, and buffers used for the SID (Silence Descriptor) synchronization function. Call this function only once when using the encoder.

[Classification]	SID synchronization initialization f	unction
[Function name]	amr_sid_sync_init	
[Summary of function]	Initializes the RAM area neces	sary for the SID synchronization function, calls the
	amr_sid_sync_reset function, and	initializes parameters.
[Format]	call amr_sid_sync_init	
[Argument]	None	
[Return value]	None	
[Registers used]	R0	
[Hardware resources]	Maximum stack level:	1
	Maximum loop stack level:	0
	Maximum number of repetitions:	0
	Maximum number of cycles:	15

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

#### 2.2.8 amr\_sid\_sync\_reset function

The amr\_sid\_sync\_reset function resets the constants, coefficient table, and buffers used for the SID (Silence Descriptor) synchronization function to the initial status.

[Classification]	SID synchronization initialization function			
[Function name]	amr_sid_sync_reset			
[Summary of function]	Resets the parameters necessary for the SID synchronization function to the initial status.			
[Format]	call amr_sid_sync_reset			
[Argument]	None			
[Return value]	None			
[Registers used]	R0			
[Hardware resources]	Maximum stack level:	0		
	Maximum loop stack level:	0		
	Maximum number of repetitions:	0		
	Maximum number of cycles:	8		

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

#### 2.2.9 amr\_sid\_sync function

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The amr\_sid\_sync function determines the transmit frame type in accordance with the encode mode used for compression. Call this function once per encode processing of one frame.

[Classification] [Function name] [Summary of function] [Format]	SID synchronization function amr_sid_sync Determines the frame type from the encode mode used for compression. call amr_sid_sync		
[Argument]	Туре	Argument	Description
	Register	R0L	Encode mode used for compression (see <b>Table 2-2 Operation</b> <b>Mode of Encoder/Decoder</b> .)
[Return value]	Туре	Return Value	Description
	Deviation	Dal	
	Register	R0L	Transmit frame type (see Table 2-4)
[Registers used]	Register R0, R1	ROL	Transmit frame type (see Table 2-4)
[Registers used] [Hardware resources]		-	Transmit frame type (see Table 2-4)
	R0, R1	ck level:	0
	R0, R1 Maximum sta	ck level: p stack level:	0 0

**Remark** When calling this function, be sure to first secure static memory and scratch memory areas. For details, refer to **2.3 Memory Structure**.

#### Table 2-4. Transmit Frame Type

TX_TYPE	Value	Description
TX_SPEECH_GOOD	0	Speech frame
TX_SID_FIRST	1	Start of SID frame
TX_SID_UPDATE	2	SID frame update
TX_NO_DATA	3	Frame without data

# 2.2.10 amr\_TX\_to\_RX function

The amr\_TX\_to\_RX function converts a transmit frame type (TX\_TYPE) to a receive frame type (RX\_TYPE).

[Classification] [Function name] [Summary of function] [Format]	Frame type conversion function amr_TX_to_RX Converts a transmit frame type to a receive frame type. call amr_TX_to_RX		
[Argument]	Туре	Argument	Description
	Register	R1L	Transmit frame type (TX_TYPE)
[Return value]	Туре	Return Value	Description
	Register	R1L	Receive frame type (RX_TYPE)
[Registers used]	R1, R2, R3		
[Hardware resources]	Maximum sta	ick level:	0
	Maximum loo	p stack level:	0
	Maximum nu	mber of repeti	itions: 0
k	Maximum nui	mber of cycle	s: 30

**Remark** Table 2-5 shows the receive frame type corresponding to each transmit frame type. The values in parentheses are the values of each transmit/receive frame type. If any other transmit frame type is specified, 0xFFFF is returned.

Transmit Frame Type	Receive Frame Type
TX_SPEECH_GOOD (= 0)	RX_SPEECH_GOOD (= 0)
TX_SID_FIRST (= 1)	RX_SID_FIRST (= 4)
TX_SID_UPDATE (= 2)	RX_SID_UPDATE (= 5)
TX_NO_DATA (= 3)	RX_SID_NO_DATA (= 7)
TX_SPEECH_DEGRADE (= 4)	RX_SPEECH_DEGRADE (= 1)
TX_SPEECH_BAD (= 5)	RX_SPEECH_BAD (= 3)
TX_SID_BAD (= 6)	RX_SID_BAD (= 6)
TX_ONSET (= 7)	RX_ONSET (= 2)

## Table 2-5. Transmit/Receive Frame Type

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# 2.2.11 amr\_ehf\_test function

The amr\_ehf\_test function checks whether the input speech signal is the homing frame of the encoder.

[Classification] [Function name] [Summary of function] [Format]	Encoder homing frame test function amr_ehf_test Identifies the homing frame of the speech data. call amr_ehf_test		
[Argument]	Туре	Argument	Description
	Register	DP4	First address of speech buffer
[Return value]	Туре	Return Value	Description
	Register	R0L	Test result 0: No homing frame 1: Homing frame
[Registers used]	R0, R1, DP4		
[Hardware resources]	Maximum sta	ack level:	0
	Maximum loc	p stack level:	1
	Maximum nu	mber of repet	itions: 0
	Maximum nu	mber of cycle	s: 967

# 2.2.12 amr\_dhf\_test function

The amr\_dhf\_test function checks whether the input bit stream is the homing frame of the decoder.

[Classification] [Function name] [Summary of function] [Format]	Decoder homing frame test function amr_dhf_test Identifies the homing frame of the bit stream data. call amr_dhf_test			
[Argument]	Туре	Argument	Description	
	Register	DP0	First address of bit stream buffer	
	Register	R6L	Decode mode (see <b>Table 2-2 Operation Mode of Encoder/</b> <b>Decoder</b> , excluding MRDTX)	
[Return value]	Туре	Return Value	ue Description	
	туре		Bessinption	
	Register	ROL	Test result 0: No homing frame 1: Homing frame	

# 2.2.13 amr\_GetVersion function

The amr\_GetVersion function returns the version information of the AMR speech CODEC library.

[Classification] [Function name] [Summary of function] [Format] [Argument]	Version information acquisition function amr_GetVersion Returns the version information. call amr_GetVersion None				
[Return value]	Туре	Value		Description	
	Register	R0H	Major ve	ersion number of library	
	Register	R0L	Minor ve	ersion number of library	
	Register R1H Major version number of AMR speech CODEC		ersion number of AMR speech CODEC		
	Register	R1L	R1L Minor version number of AMR speech CODEC		
[Function]	Example: V	When R0 = 0	x00'0x00	e library and AMR speech CODEC. 02'0x0000, library version: Ver 2.00.00 07'0x0600, version of AMR speech CODEC: Ver 7.6.0	
[Registers used]	R0, R1				
[Hardware resources]	Maximum sta	Maximum stack level:		0	
	Maximum loo	p stack level	:	0	
	Maximum nui	mber of repet	itions:	0	
	Maximum nu	mber of cycle	S:	10	

\*

#### 2.3 Memory Structure

This section explains the structure of the memory required for the  $\mu$ SAP77016-B06 library.

In the  $\mu$ SAP77016-B06, scratch memory and static memory areas must be defined separately. Be sure to use the PUBLIC quasi directive to define a symbol name. For the size of each memory, refer to Table 2-6.

#### (1) Scratch memory area

This area does not have to be saved. The user can use this area freely after encoding/decoding one frame.

```
Example:
```

public	lib_Scra	.tch_x		
public	lib_Scra	tch_y		
SCRATCH_X		XRAMSEG		
lib_Scratc	h_x:	DS	AMR_MAX_SCRATCH_X_SIZE	
SCRATCH_Y		YRAMSEG		
lib_Scratc	h_y:	DS	AMR_MAX_SCRATCH_Y_SIZE	

#### (2) Static memory area

This area always includes saved data. If the user manipulates this area after initialization processing, normal operation of the  $\mu$ SAP77016-B06 library is not guaranteed.

```
Example:
```

```
public
          amr_Static_enc_x
public
         amr Static enc y
public
         amr_Static_dec_x
public
         amr_Static_dec_y
AMR_STATIC_X
                  XRAMSEG
amr_Static_enc_x: DS
                           AMR_MAX_STATIC_ENC_X_SIZE
amr_Static_dec_x: DS
                           AMR MAX STATIC DEC X SIZE
AMR_STATIC_Y
                  YRAMSEG
amr_Static_enc_y:
                  DS
                           AMR_MAX_STATIC_ENC_Y_SIZE
amr_Static_dec_y:
                  DS
                           AMR_MAX_STATIC_DEC_Y_SIZE
```

Table 2-6.	Symbol Name and Size of Memory
------------	--------------------------------

Symbol Name	Size [Words]	X/Y Plane	Description
lib_Scratch_x	2025	Х	Encoder/decoder common scratch area
lib_Scratch_y	909	Y	Encoder/decoder common scratch area
amr_Static_enc_x	509	Х	Static area for encoder
amr_Static_enc_y	955	Y	Static area for encoder
amr_Static_dec_x	402	Х	Static area for decoder
amr_Static_dec_y	525	Y	Static area for decoder

**Remark** The memory area can be allocated by a macro defined by amr\_lib.h (Refer to 2.4 Macro).

## (3) I/O buffer

This is an area that is used to input/output speech data and bit stream data. The user can use the I/O buffer used by the encoder/decoder after encoding/decoding one frame. If the buffer is manipulated during encoding/decoding processing, normal operation of the  $\mu$ SAP77016-B06 is not guaranteed.

#### • I/O buffer necessary for encoder

Output buffer of bit stream data:16 words in X memory spaceInput buffer of speech data:160 words in Y memory space

Example:

ple:	I_O_BUFFER_X	XRAMSEG	
	bitstream_out:	DS	16
	I_O_BUFFER_Y	YRAMSEG	
	speech_in:	DS	160

• I/O buffer necessary for decoder

Input buffer of bit stream data:	16 words in X memory space
Output buffer of speech data:	160 words in Y memory space

Example:	I_O_BUFFER_X	XRAMSEG	
	bitstream_in:	DS	16
	I_O_BUFFER_Y	YRAMSEG	
	speech_out:	DS	160

**Remark** Generally, the I/O buffer of speech data is configured as a double buffer when compression/decompression is executed in real time. In this case, a 320-word data memory is required in the Y memory space as an I/O buffer used by the encoder/decoder, and another 320-word data memory is required in either the X or Y memory space as an I/O buffer used for serial I/O.

# [Notes on simulator]

The library of the  $\mu$ SAP77016-B06 reads a memory space other than an allocated area for faster pointer processing. Therefore, the simulator may issue a warning, depending on the status of memory allocation.

Area Name	Description
amr_Static_enc_x	Memory space other than this area is not accessed.
amr_Static_enc_y	Memory space other than this area is not accessed.
amr_Static_dec_x	Memory space other than this area is not accessed.
amr_Static_dec_y	Memory space other than this area is not accessed.
lib_Scratch_x	Memory in a range from this area to +5 words is accessed.
lib_Scratch_y	Memory in a range from the beginning of this area to -1 word is accessed.

#### Table 2-7. Memory Access Range

# 2.4 Macros

2.4.1 AMR_AllocateScratchMemory macro		
[Classification]	Scratch memory allocation	
[Macro name]	AMR_AllocateScratchMemory	
[Summary of function]	Allocates the scratch memory necessary for AMR speech CODEC processing and	
	declares a symbol name.	
[Format]	%AMR_AllocateScratchMemory	
[Argument]	None	
[Return value]	None	
[Definition symbol]	ib_Scratch_x, lib_Scratch_y	
2.4.2 AMR_AllocateStatic	MemoryForEncoder macro	
[Classification]	Static memory allocation for encoder	
[Macro name]	AMR_AllocateStaticMemoryForEncoder	
[Summary of function]	Allocates the static memory necessary for encoding processing of AMR speech CODEC	
	and declares a symbol name.	
[Format]	%AMR_AllocateStaticMemoryForEncoder	
[Argument]	None	
[Return value]	None	
[Definition symbol]	amr_Static_enc_x, amr_Static_enc_y	
2.4.3 AMR_AllocateStatic	MemoryForDecoder macro	
[Classification]	Static memory allocation for decoder	
[Macro name]	AMR_AllocateStaticMemoryForDecoder	
[Summary of function]	Allocates the static memory necessary for decoding processing of AMR speech CODEC	
	and declares a symbol name.	
[Format]	%AMR_AllocateStaticMemoryForDecoder	
[Argument]	None	
[Return value]	None	
[Definition symbol]	amr_Static_dec_x, amr_Static_dec_y	
Remark The macro	used for the library of the $\mu$ SAP77016-B06 is defined by amr_lib.h. To use the macro,	
include amr_	_lib.h.	

# CHAPTER 3 BIT STREAM FORMAT

Tables 3-1 through 3-9 show the bit allocation of the bit stream in each mode of the  $\mu$ SAP77016-B06.

Bit Position	Description	
b1 to b7	index of 1st LSF submatrix	
b8 to b15	index of 2nd LSF submatrix	
b16 to b23	index of 3rd LSF submatrix	
b24	sign of 3rd LSF submatrix	
b25 to b32	index of 4th LSF submatrix	
b33 to b38	index of 5th LSF submatrix	
	First subframe	
b39 to b47	adaptive codebook index	
b48 to b51	adaptive codebook gain	
b52	sign information for 1st and 6th pulses	
b53 to b55	position of 1st pulse	
b56	sign information for 2nd and 7th pulses	
b57 to b59	position of 2nd pulse	
b60	sign information for 3rd and 8th pulses	
b61 to b63	position of 3rd pulse	
b64	sign information for 4th and 9th pulses	
b65 to b67	position of 4th pulse	
b68	sign information for 5th and 10th pulses	
b69 to b71	position of 5th pulse	
b72 to b74	position of 6th pulse	
b75 to b77	position of 7th pulse	
b78 to b80	position of 8th pulse	
b81 to b83	position of 9th pulse	
b84 to b86	position of 10th pulse	
b87 to b91	fixed codebook gain	
Second subframe		
b92 to b97	adaptive codebook index (relative)	
b98 to b141	same description as b48 to b91	
Third subframe		
b142 to b194	same description as b39 to b91	
	Fourth subframe	
b195 to b244	same description as b92 to b141	

# Table 3-1. Bit Allocation in MR122 Mode

Bit Position	Description
b1 to b8	index of 1st LSF subvector
b9 to b17	index of 2nd LSF subvector
b18 to b26	index of 3rd LSF subvector
First subframe	
b27 to b34	adaptive codebook index
b35	sign information for 1st and 5th pulses
b36	sign information for 2st and 6th pulses
b37	sign information for 3rd and 7th pulses
b38	sign information for 4th and 8th pulses
b39 to b48	position of 1st, 2nd, and 5th pulse
b49 to b58	position of 3rd, 6th, and 7th pulse
b59 to b65	position of 4th and 8th pulse
b66 to b72	codebook gains
Second subframe	
b73 to b77	adaptive codebook index (relative)
b78 to b115	same description as b35 to b72
Third subframe	
b116 to b161	same description as b27 to b72
Fourth subframe	
b162 to b204	same description as b73 to b115

# Table 3-2. Bit Allocation in MR102 Mode

Bit Position	Description	
b1 to b9	index of 1st LSF subvector	
b10 to b18	index of 2nd LSF subvector	
b19 to b27	index of 3rd LSF subvector	
First subframe		
b28 to b35	adaptive codebook index	
b36 to b39	position of 4th pulse	
b40 to b42	position of 3rd pulse	
b43 to b45	position of 2nd pulse	
b46 to b48	position of 1st pulse	
b49	sign information for 4th pulse	
b50	sign information for 3rd pulse	
b51	sign information for 2nd pulse	
b52	sign information for 1st pulse	
b53 to b56	adaptive codebook gain	
b57 to b61	fixed codebook gain	
Second subframe		
b62 to b67	adaptive codebook index (relative)	
b68 to b93	same description as b36 to b61	
Third subframe		
b94 to b127	same description as b28 to b61	
Fourth subframe		
b128 to b159	same description as b62 to b93	

## Table 3-3. Bit Allocation in MR795 Mode
Bit Position	Description				
b1 to b8	index of 1st LSF subvector				
b9 to b17	index of 2nd LSF subvector				
b18 to b26	index of 3rd LSF subvector				
	First subframe				
b27 to b34	adaptive codebook index				
b35 to b38	position of 4th pulse				
b39 to b41	position of 3rd pulse				
b42 to b44	position of 2nd pulse				
b45 to b47	position of 1st pulse				
b48	sign information for 4th pulse				
b49	sign information for 3rd pulse				
b50	sign information for 2nd pulse				
b51	sign information for 1st pulse				
b52 to b58	codebook gains				
	Second subframe				
b59 to b63	adaptive codebook index (relative)				
b64 to b87	37 same description as b35 to b58				
Third subframe					
b88 to b119	same description as b27 to b58				
	Fourth subframe				
b120 to b148	same description as b59 to b87				

#### Table 3-4. Bit Allocation in MR74 Mode

Bit Position	Description				
b1 to b8	index of 1st LSF subvector				
b9 to b17	index of 2nd LSF subvector				
b18 to b26	index of 3rd LSF subvector				
	First subframe				
b27 to b34	adaptive codebook index				
b35 to b38	position of 3rd pulse				
b39 to b42	position of 2nd pulse				
b43 to b45	position of 1st pulse				
b46	sign information for 3rd pulse				
b47	sign information for 2nd pulse				
b48	sign information for 1st pulse				
b49 to b55	codebook gains				
	Second subframe				
b56 to b59	adaptive codebook index (relative)				
b60 to b80	same description as b35 to b55				
Third subframe					
b81 to b109	same description as b27 to b55				
	Fourth subframe				
b110 to b134	same description as b56 to b80				

#### Table 3-5. Bit Allocation in MR67 Mode

Bit Position	Description				
b1 to b8	index of 1st LSF subvector				
b9 to b17	index of 2nd LSF subvector				
b18 to b26	index of 3rd LSF subvector				
	First subframe				
b27 to b34	adaptive codebook index				
b35 to b39	position of 2nd pulse				
b40 to b43	position of 1st pulse				
b44	sign information for 2nd pulse				
b45	sign information for 1st pulse				
b46 to b51	b51 codebook gains				
Second subframe					
b52 to b55	adaptive codebook index(relative)				
b56 to b72	same description as b35 to b51				
Third subframe					
b73 to b97	same description as b27 to b51				
	Fourth subframe				
b98 to b118	same description as b52 to b72				

Bit Position	Description				
b1 to b8	index of 1st LSF subvector				
b9 to b16	index of 2nd LSF subvector				
b17 to b23	index of 3rd LSF subvector				
	First subframe				
b24 to b31	adaptive codebook index				
b32	position subset				
b33 to b35	position of 2nd pulse				
b36 to b38	position of 1st pulse				
b39	sign information for 2nd pulse				
b40	sign information for 1st pulse				
b41 to b46	codebook gains				
	Second subframe				
b47 to b50	adaptive codebook index (relative)				
b51 to b65	same description as b32 to b46				
Third subframe					
b66 to b84	b84 same description as b47 to b65				
	Fourth subframe				
b85 to b103	same description as b47 to b65				

#### Table 3-7. Bit Allocation in MR515 Mode

Bit Position	Description				
b1 to b8	index of 1st LSF subvector				
b9 to b16	index of 2nd LSF subvector				
b17 to b23	index of 3rd LSF subvector				
	First subframe				
b24 to b31	adaptive codebook index				
b32	position subset				
b33 to b35	position of 2nd pulse				
b36 to b38	position of 1st pulse				
b39	sign information for 2nd pulse				
b40	sign information for 1st pulse				
b41 to b48	codebook gains				
Second subframe					
b49 to b52	adaptive codebook index(relative)				
b53 to b61	same description as b32 to b40				
Third subframe					
b62 to b65	same description as b49 to b52				
b66 to b82	same description as b32 to b48				
	Fourth subframe				
b83 to b95	same description as b49 to b61				

#### Table 3-8. Bit Allocation in MR475 Mode

### Table 3-9. Bit Allocation in MRDTX Mode

Bit Position	Description			
b1 to b3	ndex of reference vector			
b4 to b11	index of 1st LSF subvector			
b12 to b20	index of 2nd LSF subvector			
b21 to b29	index of 3rd LSF subvector			
b30 to b35	index of logarithmic frame energy			

The relationship between the bit allocation (b1 through b242) in Tables 3-1 through 3-9 and word data is shown below.

Offset	MSB															LSB
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
+0	b1	b2	b3	b4	b5	b6	b7	b8	b9	b10	b11	b12	b13	b14	b15	b16
+1	b17						•	•	•	•						b32
+2	b33						•	•	•	•						b48
+3	b49						•	•	•	•						b64
+4	b65						•	•	•	•						b80
+5	b81						•	•	•	•						b96
+6	b97						•	•	•	•						b112
+7	b113						•	•	•	•						b128
+8	b129						•	•	•	•						b144
+9	b145						•	•	•	•						b160
+10	b161						•	•	•	•						b176
+11	b177						٠	•	٠	•						b192
+12	b193						•	•	•	•						b208
+13	b209						•	•	•	•						b224
+14	b225						•	•	•	•						b240
+15	b241						•	•	•	•						b256

Figure 3-1. Relationship Between Bit Allocation and Word

#### **CHAPTER 4 INSTALLATION**

#### 4.1 Installation Procedure

The  $\mu$ SAP77016-B06 is supplied in a 3.5" floppy disk (1.44 MB). How to install the  $\mu$ SAP77016-B06 in a host machine is described below. Install the  $\mu$ SAP77016-B06 in a host machine in which an OS such as Windows 95, 98, 2000, or Windows NT<sup>M</sup> 4.0 or later has been installed.

- <1> Set the floppy disk in the floppy disk drive.
- <2> Execute amr\_mw.exe from the floppy disk (the files of the µSAP77016-B06 are compressed in a selfextracting format). The following is an example of when files are copied from the A drive to the C drive.

A:\>amr\_mw.exe<CR>

- <3> A dialog box to specify the directory for installing the µSAP77016-B06 is displayed. Specify a directory. Any directory may be specified. In this example, it is assumed that C:\DSPTools is specified.
- <4> Click the OK button and expansion of the files begins.
- <5> Confirm that the files have been expanded. For each directory, refer to 1.3.4 Directory configuration.

A:\>dir C:\DSPTools<CR>

#### 4.2 Sample Creation Procedure

The sample programs for a single channel and multiple channels (2 channels) are stored in the smp directory (refer to **1.3.4 Directory configuration**). For the source program for a single channel, refer to **APPENDIX A SAMPLE PROGRAM SOURCE**.

An AMR speech CODEC system can be evaluated using a sample program by actually connecting a CD player, DAT, microphone, or speaker to the  $\mu$ SAP77016-B06. Note that additional code such as for a system-dependent block may be required.



Figure 4-1. Example of Sample Program Evaluation System

An example of how to build a sample program (for a single channel) of the  $\mu$ SAP77016-B06 is shown below.

- (1) Start up the WB77016 (workbench).
- (2) Open the sample.prj project file.

**Example:** Specify sample.prj with the Open Project command from the Project menu.

(3) Execute build and confirm that sample. Ink has been created.

**Example:** The sample.Ink file can be created by selecting the Build All command from the Make menu.

(4) Download sample.Ink to the target system using the ID77016 (debugger) and execute it.

#### 4.3 Change of Location

The section names shown in Table 4-1 are given to the library of the  $\mu$ SAP77016-B06. The location can be changed in accordance with the user target system.

#### Table 4-1. Section Name

Section Name	Туре	Description		
AMR_CONST_X	XROMSEG/XRAMSEG	Constant data storage area		
AMR_CONST_Y	YROMSEG/YRAMSEG	Constant data storage area		
AMR_CODEC	IROMSEG/IRAMSEG	AMR speech CODEC program		

#### 4.4 Symbol Naming Regulations

The symbols used for the library of the  $\mu$ SAP77016-B06 are named in accordance with the following regulation. Make sure not to duplicate these symbol names when using the  $\mu$ SAP77016-B06 in combination with another application.

Classification	Naming Regulation			
Function name	amr_XXXX			
Constant symbol name	amr_cnst_XXXX			
Static RAM area symbol name	amr_Static_[encldec]_[xly]			
Scratch RAM area symbol name	lib_Scratch_[xly]			
Code segment name (IMSEG)	AMR_CODEC			
Constant segment name (ROMSEG/RAMSEG)	AMR_CONST_[XIY]			
Macro, constant name (such as #define and equ declarations)	AMR_XXXX			
File name	amrXXXX.*			

#### Table 4-2. Symbol Naming Regulations

**Remark** "XXXX" indicates arbitrary alphanumeric characters.

#### APPENDIX A SAMPLE PROGRAM SOURCE

This appendix shows a sample source of the  $\mu$ SAP77016-B06 (AMR speech CODEC middleware). This sample source was created by referring to the sample source of 3GPP (3rd Generation Partnership Project). For details of each processing, refer to the sample source of 3GPP.

<ul> <li>sample.as</li> </ul>	sm			(1/7)				
/*			*/					
/* F:	ile Informa	*/						
/*			*/					
	ame : sa	-	*/					
			rogram module */					
,	ersion : 2.		*/					
	ate : 20		*/					
	PU : uP		-					
,	ssembler: W		*/					
	/* About : GSM AMR speech codec Version 7.6.0 */							
/* /+			*/					
/* Co			poration 1999, 2000, 2001, 2002 */					
	EC CONFIDEN	_						
,			y NEC Corporation. */					
	-	_	ce does not evidence publication */					
			*/					
,								
/* ======								
* Inclu	de files							
* ======			*/					
#include	"upd7701x.m	ac"						
#include	"amr_lib.h"							
/* ======								
* Memor	y allocate	for AMR CO	DDEC					
* ======			*/					
%AMR_2	AllocateScr	atchMemory	Y					
_	AllocateSta							
%AMR_	AllocateSta	ticMemoryI	ForDecoder					
,								
	variables							
			/* set DTX mode. DTX_OFF, DTX_ON_VAD1, DTX_ON_VAD2 */					
#define M	01.1.1 0		<pre>/* set MULTI mode. 0: normal mode. 1:multi mode */</pre>					
Hacting T		0						
#define L	_FRAME 16	0						
WORK V VI	RAMSEG at 0	<b>v</b> 0000						
_	_		; codec start flag, "1" is start codec.					
_	f_run: ds 1 ; codec start flag, "1" is start codec. f reset: ds 1 ; test sequence reset flag, "-1" is reset.							
f mult		ı MULTI	; multi mode flaq, not "0" is multi rate mode.					
_		1	; RX/TX frame type.					
used_1		1	; used AMR Encoder mode.					
bitst:			; bitstream load/store buffer.					
e mode		MR475	; AMR Encoder mode.					

<ul> <li>samp</li> </ul>	le.asm
--------------------------	--------

(2/7)

sample.asm				(2/7)			
d_mode:	ds	1	; AMR Decoder mode.				
prev_d_mode:	ds	1	; AMR previous codec mode				
dtx_mode:	dw	DTX	; DTX mode.				
f_e_reset:	ds	1	; encoder reset flag.				
f_d_reset:	ds	1	; decoder reset flag.				
f_d_reset_old	l:ds	1	; decoder old reset flag.				
r7save:	ds	3	; r7 register load/sotre buffer for interrupt handler.				
dp7save:	ds	1	; dp7 register load/sotre buffer for interrupt handler.				
mode_cnt:	ds	1	; coder mode count for multi rate mode.				
frame_cnt:	ds	1	; frame count.				
WORK_Y YRAMSEG a	at 02	<0000					
si1_ptr:	ds	1	;				
si1_buff:	ds	L_FRAM	IE ;				
sol_buff:	ds	L_FRAM	1E ;				
speech_in:	ds	L_FRAM	IE ;				
speech_out:	ds	_ L_FRAM	ie ;				
<pre>#define F_RUN #define F RESET</pre>			*f_run:x *f reset:x				
#define F MULTI			*f_reset:x *f multi:x				
#define TX TYPE			*frame type:x				
—							
#define RX_TYPE #define USED_MODE			<pre>*frame_type:x *used mode:x</pre>				
#deline 03ED_MODI	2		"useu_iioue:x				
#define E_MODE			*e_mode:x				
#define D_MODE			*d_mode:x				
#define DTX_MODE			*dtx_mode:x				
#define PREV_D_MODE			*prev_d_mode:x				
#define E_RESET_FLAG			<pre>*f_e_reset:x</pre>				
#define D_RESET_FLAG			*f_d_reset:x				
#define D_RESET_H	FLAG_	OLD	*f_d_reset_old:x				
#define MODE_COUN	ΙT		*mode_cnt:x				
#define FRAME_COU	JNT		*frame_cnt:x				
/* ===============							
* Vector regist	rati	Lon					
			*/				
%BeginVector(Star	-		;Regist start up routine				
%NotUseVector							
%NotUseVector							
%NotUseVector							
%NotUseVector							
-			SI1Handler) ;Regist SI1 handler				
%NotUseVector		,					
%NotUseVector							
%NotUseVector							
%NotUseVector			;				
%NotUseVector	(Vec	ctorHO)	;				
%EndVector							

sample.asm

(3/7)

```
/* _____
* Programe code section
* _____*
MAIN CODE IMSEG at 0x4000
StartUp:
  ;;================================;;;
  ;; Initialize uPD7701x
                                               ;;
  %InitializeSystemRegister ;Initialize system register
%ClearAllRegister ;Clear all uPD7701x register
  ;;============;;;
  ;; Initialize Register & Peripheral Units
                                              ;;
  ;;============;;;
  r01 = 0x0200
                        ;
  *SST1:x = r01
                         ;
  ;;============;;;
  ;; Initialize AMR CODEC module ;;
  ;;================;;;
  /* Initialize AMR encoder */
  clr(r0)
                         ;
  r0l = DTX_MODE
                        ;set DTX mode
  call amr_InitEncoder
                        ;
  call amr_sid_sync_init
                        ;
  /* Initialize AMR decoder */
  call amr InitDecoder
                        ;
  ;;==================;;;
  ;; Initialize buffer
                                               ;;
  /* clear serial input/output buffer */
  r0l = sil buff
                       ;Initialize serial i/o buffer pointer.
  *si1_ptr:y = r0l
                        ;
  dp4 = sil buff
                        ;Initialize serial i/o buffer.
  rep L FRAME*2
                        ;
     *dp4++ = r0h
                         ;
  /* clear speech input/output buffer */
  dp4 = speech in
                       ;
  dp5 = speech out
                        ;
  loop L FRAME {
                        ;
     *dp4++ = r0h
                        ;
     *dp5++ = r0h
                        ;
  }
                         ;
  /* clear flags */
  clr(r0)
                        ;
  F RUN = r01
                        ;clear codec start flag.
  F RESET = r01
                        ;clear codec rest flag.
  TX TYPE = r01
                        ;clear TX type.
                        ;clear RX type.
  RX TYPE = r01
  USED MODE = r01
                        ;clear used AMR encoder mode.
  D MODE = r01
                        ;clear AMR decoder mode.
  PREV D MODE = r01
                        ;clear prev AMR decoder mode.
  E_RESET_FLAG = r01
                       ;clear encoder reset flag.
  D RESET FLAG = r01
                        ;clear decoder reset flag.
```

(4/7)

```
    sample.asm

   MODE_COUNT = r01
                            ;clear mode count.
   FRAME COUNT = r01
                            ;clear frame count.
   r01 = 1
                            ;
   D_RESET_FLAG_OLD = r01 ;set decoder old reset flag.
   ;;========;;;
   ;; Set interrupt mask
                                                     ;;
   ;;===============;;;
   %DisableInterrupt
                            ;
   %SetMask(SR ALL)
                            ;
   %UnSetMask(SR_SI1)
                            ;
   %EnableInterrupt
                            ;
   ;;===============;;;
   ;; Main routine
                                                      ;;
   ;;===============;;
MainLoop:
   /* check reset codec flag */
   r0 = F RESET
                           ;
   if(r0 < 0) jmp StartUp
                            ;
   /* check start codec flag */
   r0 = F RUN
                            ;
   if(r0 == 0) jmp MainLoop
                            ;
   clr(r0)
   F_RUN = r0l ;clear codec start flag.
/* increment frame count */
   r0l = FRAME_COUNT
                            ;
   r0 = r0 + 1
                            ;
   FRAME_COUNT = r01
   /* Copy input/output PCM data */
   dp4 = speech in
                            ;
   dp5 = speech_out
                            ;
   dp6 = sil buff
                            ;
   loop L FRAME {
     rol = *dp6++
                            ;read input PCM data from si1_buff.
      r0 = r0 \& 0xfff8
                            ;
      *dp4++ = r0l
                            ;store PCM data to speech in.
   }
                            ;
   loop L FRAME {
                           ;
     r0l = *dp5++
                           ;read output PCM data from speech out.
      r0l = *dp5++
r0 = r0 & 0xfff8
                           ;
      *dp6++ = r01
                           ;store PCM data to so1_buff.
   }
                            ;
   /* Encode process */
   call Proc AMR Encoder
                            ;
   /* Decode process */
   call Proc_AMR_Decoder
                            ;
   jmp MainLoop
                             ;
/* _____
[Function Name] Proc AMR Encoder
 -----*/
Proc_AMR_Encoder:
   /* check for homing frame */
   dp4 = speech_in
call amr_ehf_test
E_RESET_FLAG = r01
                           ;set speech buffer address.
                           ;test homing frame.
;save reset flag.
```

(5/7)

sample.asm

```
/* multi rate mode */
    r0 = F MULTI
                                  ;
   if(r0 != 0) call MultiRateMode ;
    /* encode speech */
   clr(r0)
r0l = E_MODE
   clr(r0)
                                 ;
   r0l = E_MODE ; set AMR encoder mode.
dp4 = speech_in ; set speech buffer address.
dp0 = bitstream ; set bitstream buffer address.
call amr_EncodeFrame ; encode speech data.
USED_MODE = r0l ; save used AMR encoder mode.
    /*include frame type and mode information in serial bitstream */
    clr(r0)
                                 ;
   r01 = USED MODE
                                 ;set used AMR encoder mode.
   call amr_sid_sync
TX_TYPE = r0l
                                 ;
                                 ;save TX frame type.
   r0 = r0 - TX_NO_DATA
                                 ;
    if ( r0 != 0 ) jmp proc enc noupdate mode;
       clr(r0)
                                 ;
       r0 = r0 - 1
                                  ;
       D MODE = r0l
                                  ;
       jmp proc enc next
                                  ;
proc enc noupdate mode:
       clr(r0)
                                   ;
       r0l = E MODE
                                  ;
       D MODE = r01
                                   ;
proc enc next:
   /* perform homing if homing frame was detected at encoder input */
   r0 = E_{RESET_{FLAG}};
   if(r0 == 0) ret
                                  ;
       call amr ResetEncoder
                                  ;
       call amr_sid_sync_reset
                                  ;
       ret
                                  ;
/* _____
[Function Name] Proc AMR Decoder
-----*/
Proc AMR Decoder:
   /* Convert TX frame type to RX frame type*/
   clr(r1)
r1l = TX_TYPE
call amr_TX_to_RX
                                 ;
                                 ;set TX frame type.
                                 ;
   RX TYPE = r1l
                                 ;save RX frame type.
   clr(r1)
                                  ;
   rll = RX_TYPE
                                  ;
   r0 = r1 - RX NO DATA
                                  ;
    if(r0 != 0) jmp proc_dec_set_prev_mode;
       r0l = PREV_D_MODE ;
       D_MODE = r0l
                                  ;
       jmp proc dec set prev mode end;
proc dec set prev mode:
      r0l = D MODE
                                  ;
       PREV D MODE = r01
                                  ;
proc_dec_set_prev_mode_end:
```

```
    sample.asm

    /* if homed: check if this frame is another homing frame */
    r0 = D RESET FLAG OLD ;
    if(r0 == 0) jmp proc_dec_next_1 ;
        /* only check until end of first subframe */
       clr(r6)
                                 ;
       R6l = D MODE
                                 ;set AMR decoder mode.
        dp0 = bitstream
                                 ;set bitstream buffer address.
                                 ;test homing frame.
        call amr dhf test
        D RESET FLAG = r01
                                 ;save reset flag.
proc dec next 1:
    /* produce encoder homing frame if homed & input=decoder homing frame */
    r0 = D_RESET_FLAG
                                 ;
   if(r0 == 0) jmp proc_dec_start ;
    r0 = D RESET FLAG OLD
                                   ;
    if(r0 == 0) jmp proc dec start ;
       r0l = EHF MASK
                                  ;
        dp4 = speech out
                                  ;
        rep L FRAME
                                  ;
           *dp4++ = r01
                                 ;
       jmp proc dec next 2
                                  ;
proc dec start:
   /* decode frame */
    clr(r0)
                                  ;
    clr(r1)
                                  ;
   r0l = D MODE
                                 ;set AMR decoder mode.
                                 ;set RX TYPE = RX SPEECH.
   rll = RX TYPE
                                 ;set bitstream buffer address.
   dp0 = bitstream
                                 ;set speech buffer address.
   dp4 = speech out
   call amr DecodeFrame
                                 ;decoder bitstream.
    /* if not homed: check whether current frame is a homing frame */
proc dec next 2:
   r0 = D RESET FLAG OLD
    if(r0 != 0) jmp proc_dec_next_3 ;
        /* check whole frame */
       clr(r6)
                                 ;
       R6l = D MODE
                                 ;set AMR decoder mode.
        dp0 = bitstream
                                 ;set bitstream buffer address.
        call amr dhf test
                                 ;test homing frame.
        D RESET FLAG = r01
                                 ;save reset flag.
    /* reset decoder if current frame is a homing frame */
proc dec next 3:
   r0 = D RESET FLAG
                                  ;
    if(r0 != 0) call amr_ResetDecoder;
    r0 = D RESET FLAG
                                  ;
```

;

;

D RESET FLAG OLD = r0h

ret

```
(6/7)
```

(7/7)

```
    sample.asm

/* _____
[Function Name] MultiRateMode
-----*/
MultiRateMode:
  clr(r0)
                           ;
  r0l = MODE COUNT
                           ;
  r1 = r0 \& 0x7
   E MODE = r1l
  r1 = r1 + 1
  MODE COUNT = r11
                           ;
   ret
                           ;
/* _____
[Handler Name] SI1Handler
[RAM]
                     sil buff, sol buff, sil ptr, f run
[Use Register] r7, dp7
     0.200[MIPS] (25*159+27*1[cycle])
[MIPS]
[Use Stacks] loop stack: 0, call stack: 0, repeat: 0
 -----*/
SI1Handler:
   /* Save r7, dp7 register */
   r7save+0:x = r7l
                           ;save r7l
                          ;save r7h
   r7save+1:x = r7h
   r7save+2:x = r7e
                          ;save r7e
   r71 = dp7
                           ;save dp7
   *dp7save:x = r7l
                           ;
   /* input/output PCM data */
   r7l = *si1 ptr:y
                           ;
   dp7 = r71
                           ;
   r7h = *SDT1:x
                           ;
   *dp7##160 = r7h
   r7h = *dp7\#-159
   *SDT1:x = r7h
                           ;
   /* check frame count */
   clr(r7)
                           ;
   r7l = dp7
                           ;
   si1 ptr:y = r71
                           ;
   r7 = r7 - (sil buff + L FRAME);
   if(r7 != 0) jmp sil end
                        ;
   r71 = 1
   F RUN = r71
                           ;
   r7l = si1_buff
                           ;
   si1 ptr:y = r71
                           ;
si1 end:
   /* Restore r7, dp7 register */
   r7l = *dp7save:x
                          ;
  dp7 = r71
                          ;load dp7
                          ;load r7e
   r7e = *r7save+2:x
                          ;load r7h
   r7h = *r7save+1:x
   r7l = *r7save+0:x
                          ;load r7l
   reti
                           ;
/* End of file */
END
```

#### APPENDIX B RELATED DOCUMENTS

The recommendations related to the AMR speech CODEC published by 3GPP are as follows.

- 3GPP TS 26.071 AMR speech Codec; General description
- 3GPP TS 26.073 AMR speech Codec; C-source code
- 3GPP TS 26.074 AMR speech Codec; Test sequences
- 3GPP TS 26.090 AMR speech Codec; Transcoding Functions
- 3GPP TS 26.091
   AMR speech Codec; Error concealment of lost frames
- 3GPP TS 26.092 AMR speech Codec; comfort noise
- 3GPP TS 26.093 AMR speech Codec; Source Controlled Rate operation
- 3GPP TS 26.094 AMR speech Codec; Voice Activity Detector
- 3GPP TS 26.101 AMR speech Codec; Frame Structure
- 3GPP TS 26.102 AMR speech Codec; Interface to lu and Uu

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