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April 1, 2003

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User's Manual

SH7612 E8000 Emulator

HS7612EDD81H

User's Manual

Renesas Electronics
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Rev.1.0 2000.09

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IMPORTANT INFORMATION

READ FIRST

- **READ this user's manual before using this emulator product.**
- **KEEP the user's manual handy for future reference.**

Do not attempt to use the emulator product until you fully understand its mechanism.

Emulator Product:

Throughout this document, the term "emulator product" shall be defined as the following products produced only by Hitachi, Ltd. excluding all subsidiary products.

- Emulator station
- Device control board
- EV-chip board

The user system and a host computer are not included in this definition.

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This emulator product is a software and hardware development tool for systems employing the Hitachi microcomputer HD6417612 (hereafter referred to as SH7612). By exchanging the device control board and EV-chip board, this emulator product can also be used for systems using other E8000-series microcomputers. This emulator product must only be used for the above purpose.

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This emulator product should only be used by those who have carefully read and thoroughly understood the information and restrictions contained in the user's manual. Do not attempt to use the emulator product until you fully understand its mechanism.

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Figures:

Some figures in this user's manual may show items different from your actual system.

Limited Anticipation of Danger:

Hitachi cannot anticipate every possible circumstance that might involve a potential hazard. The warnings in this user's manual and on the emulator product are therefore not all inclusive. Therefore, you must use the emulator product safely at your own risk.

SAFETY PAGE

READ FIRST

- **READ this user's manual before using this emulator product.**

- **<u>KEEP the user's manual handy for future reference.</u>**

Do not attempt to use the emulator product until you fully understand its mechanism.

DEFINITION OF SIGNAL WORDS

DANGER indicates an **imminently** hazardous situation which, **if not avoided**, will result in **DEATH** or **SERIOUS INJURY** to you or other people.

WARNING indicates a **potentially** hazardous situation which, **if not avoided**, could result in **DEATH** or **SERIOUS INJURY** to you or other people.

CAUTION indicates a hazardous situation which, **if not avoided**, may result in **minor** or **moderate injury** to you or other people, or may result in **damage to the machine** or **loss of the user program**. It may also be used to alert against unsafe usage.

NOTE emphasizes essential information.

⚠ WARNING

Observe the precautions listed below. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator product or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

1. **Carefully handle the emulator product to prevent receiving an electric shock because the emulator product has a DC power supply. Do not repair or remodel the emulator product by yourself for electric shock prevention and quality assurance.**
2. **Always switch OFF the emulator and user system before connecting or disconnecting any CABLES or PARTS.**
3. **Always before connecting, make sure that pin 1 on both sides are correctly aligned.**
4. **Supply power according to the power specifications and do not apply an incorrect power voltage. Use only the provided AC power cable. Use only the specified type of fuse.**

Warnings on Emulator Usage

Warnings described below apply as long as you use this emulator. Be sure to read and understand the warnings below before using this emulator. Note that these are the main warnings, not the complete list.

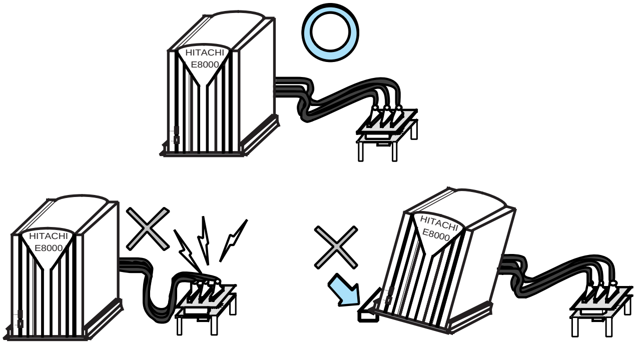
⚠ WARNING

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES or PARTS. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator product or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

⚠ WARNING

Place the emulator station and EV-chip board so that the trace cables are not bent or twisted.

A bent or twisted cable will impose stress on the user interface leading to connection or contact failure. Make sure that the emulator station is placed in a secure position so that it does not move during use nor impose stress on the user interface.



Preface

Thank you for purchasing the emulator for the Hitachi microcomputer SH7612.

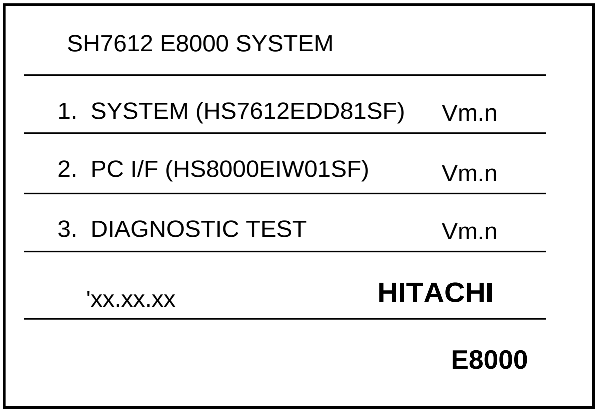
CAUTION

Read section 3, Preparation before Use in Part I, E8000 Guide of this user’s manual before using the emulator product. Incorrect operation will damage the user system, the emulator product, and the user program.

The emulator is an efficient software and hardware development tool for systems based on Hitachi microcomputer SH7612. By exchanging the device control board and the EV-chip board, this emulator can also be used for other microcomputers.

This manual describes the emulator functions and operations. Please read this manual carefully in order to gain a full understanding of the emulator’s performance. In particular, be sure to read section 1.2, Warnings, in Part I, E8000 Guide.

A 3.5-inch system floppy disk in PC 1.44-MB format is packaged together with the EV-chip board.



SH7612 E8000 SYSTEM

1. SYSTEM (HS7612EDD81SF) Vm.n
2. PC I/F (HS8000EIW01SF) Vm.n
3. DIAGNOSTIC TEST Vm.n

'xx.xx.xx **HITACHI**

E8000

Figure E8000 System Disk

Before using the system disk, back up it to a floppy disk according to the instructions in the manuals of the personal computer and the operating system.

Install (copy) the system disk to the personal computer connected to the emulator. For details on the copy procedure, refer to section 3.7, System Program Installation in Part I, E8000 Guide.

Related Manuals:

HS7612EBK81H Manual
HS7612EBH81H Manual
Lan Board Manual
Description Notes on Using the PC Interface Board (HS6000EII01H)
SH Series C Compiler User's Manual
SPARC* SH Series Cross Assembler User's Manual
SPARC H Series Linkage Editor User's Manual
SPARC H Series Librarian User's Manual
Integration Manager User's Manual
Description Notes of Integration Manager SH7612 Definition File
SH7612 E8000 Hitachi Debugging Interface User's Manual

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Part I E8000 Guide

Section 1 Overview

1.1 Overview

This system is an efficient software and hardware development support tool for application systems using the SH7612 microcomputer developed by Hitachi, Ltd. The SH7612 MCU contains the following components on a single chip:

- DSP
- High-speed CPU
- Timer
- Serial communication interface
- SIO
- DMAC
- Hitachi-UDI (Hitachi-User-Debug-Interface) port

The emulator operates in place of the SH7612 MCU and performs realtime emulation of the user system. The emulator also provides functions for efficient hardware and software debugging.

The emulator consists of an emulator (E8000) station, an SH7612 device control board, and an evaluation chip board (hereafter referred to as an EV-chip board), as shown in figure 1.1. The EV-chip board is directly installed onto the user system.

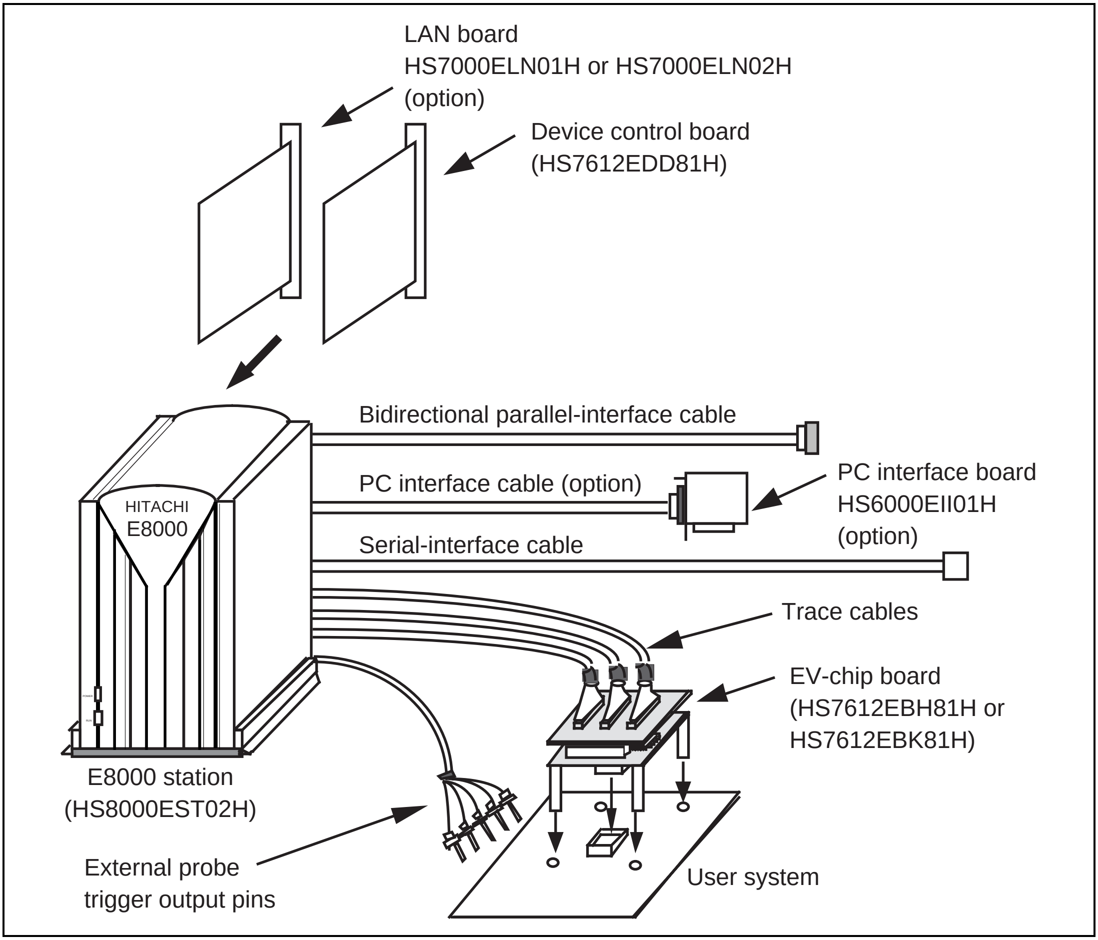


Figure 1.1 Emulator for the SH7612

The emulator provides the following features:

- Realtime emulation of the SH7612 at 66 MHz
- A wide selection of emulation commands, promoting efficient system development
- On-line help functions to facilitate command usage without a manual
- Efficient debugging enabled by variable break functions and a mass-storage trace memory (128 kcycles)
- Command execution during emulation, for example
  - — Trace data display
  - — Emulation memory display and modification
- Measurement of subroutine execution time and count for evaluating the execution efficiency of user programs
- 4-Mbyte standard emulation memory for use as a substitute user-system memory

- An optional LAN board for interfacing with workstations, enabling high-speed downloading (1 Mbyte/min) of user programs

  The LAN board contains Ethernet* (10BASE5) and Cheapernet (10BASE2) interfaces.
- SH7612 Integration Manager (option) can be loaded into the workstation to enable:
  - Graphic display operations in a multi-window environment
  - Source-level debugging
  - Graphic display of trace information
- A PC board for interfacing with a PC, enabling high-speed downloading

  (1 Mbyte/min) of user programs
- SH7612 E8000 Hitachi Debugging Interface (option) can be loaded into the PC to enable:
  - Graphic display operations in a multi-window environment
  - Source-level debugging

1.2 Warnings

CAUTION

READ the following warnings before using the emulator product. Incorrect operation will damage the user system and the emulator product. The USER PROGRAM will be LOST.

1. Check all components with the component list after unpacking the emulator.
2. Never place heavy objects on the casing.
3. Observe the following conditions in the area where the emulator is to be used:
    - Make sure that the internal cooling fans on the sides of the E8000 station must be at least 20 cm (8”) away from walls or other equipment.
    - Keep out of direct sunlight or heat. Refer to section 1.3, Environmental Conditions.
    - Use in an environment with constant temperature and humidity.
    - Protect the emulator from dust.
    - Avoid subjecting the emulator to excessive vibration. For details, refer to section 1.3, Environmental Conditions.
4. Protect the emulator from excessive impacts and stresses.
5. Before using the emulator's power supply, check its specifications such as power output, voltage, and frequency. For details of the power supply, refer to section 1.3, Environmental Conditions.
6. When moving the emulator, take care not to vibrate or otherwise damage it.
7. After connecting the cable, check that it is connected correctly. For details, refer to section 3, Preparation before Use.
8. Supply power to the emulator and connected parts after connecting all cables. Cables must not be connected or removed while the power is on.
9. For details on differences between the SH7612 and the emulator, refer to section 2, Differences between the SH7612 and the Emulator in Part II, Emulator Function Guide.

1.3 Environmental Conditions

CAUTION

The following environmental conditions must be satisfied when using the emulator. Failure to do so will damage the user system and the emulator. The USER PROGRAM will be LOST.

Observe the conditions listed in table 1.1 when using the emulator.

Table 1.1 Environmental Conditions

Item	Specifications	
Temperature	Operating:	+10 to +35°C
	Storage:	–10 to +50°C
Humidity	Operating:	35 to 80% RH, no condensation
	Storage:	35 to 80% RH, no condensation
Vibration	Operating:	2.45 m/s^2 max.
	Storage:	4.9 m/s^2 max.
	Transportation:	14.7 m/s^2 max.
AC input power	Voltage:	AC100-120 V/200-240 V ± 10%
	Frequency:	50/60 Hz
	Power consumption:	200 VA
Ambient gases	There must be no corrosive gases present.	

1.4 Components

The emulator consists of the E8000 station, device control board, and EV-chip board. Check all components after unpacking. If any component is missing, contact the sales office from which the emulator was purchased.

1.4.1 E8000 Emulator Station

Table 1.2 lists the E8000 station components.

Table 1.2 E8000 Station Components (HS8000EST02H)

Classification	Item	Quantity	Remarks
Hardware	E8000 station	1	Power supply, control board, and trace board are installed.
	Trace cable	3	Length: 50 cm
	AC power cable	1	UL cable or B5 cable
	Serial cable	1	RS-232C interface
	Parallel cable	1	Conforms to IEEE-P1284.
	Fuse	1	Spare (3 A or T3.15A corresponding to CE marking)
Manual	HS8000EST02H description notes	1	HS8000EST02HE

1.4.2 SH7612 Device Control Board and EV-Chip Board

Tables 1.3 and 1.4 list the device control board and EV-chip board components. For details, refer to each user’s manual.

Table 1.3 Device Control Board Components

Classification	Item	Quantity	Remarks
Hardware	Device control board	1	One board, installed in the E8000 station
	External probe	1	
Software	3.5-inch floppy disk	1	E8000 system program
Manual	HS7612EDD81H description notes	1	HS7612EDD81HE

Table 1.4 EV-Chip Board Components

Classification	Item	Quantity	Remarks
Hardware	EV-chip board	1	HS7612EBK81H (connector) or two HS7612EBH81H (QFP) boards to be installed in the user system
Manual	HS7612EBK81H or HS7612EBH81H description notes	1	HS7612EBK81HE HS7612EBH81HE

1.4.3 Options

In addition to the E8000 station and EV-chip board components, the options listed in table 1.5 are also available. Refer to each option manual for details on these optional components.

Table 1.5 Optional Component Specifications

Item	Model Name	Specifications
LAN board	HS7000ELN01H HS7000ELN02H	• TCP/IP communications protocol • Ethernet (10BASE5) • Cheapernet (10BASE2)
PC interface board	HS6000EII01H	ISA bus

Section 2 Components

2.1 Emulator Hardware Components

The emulator consists of an E8000 station, an SH7612 device control board, and an SH7612 EV-chip board, as shown in figure 2.1. The emulator station includes a serial-interface cable (RS-232C) and a parallel-interface cable (conforms to IEEE-P1284 and is for the ECP mode) for the host computer interface. By installing a LAN board (option), the emulator can be connected to a workstation via the LAN interface. By installing a PC interface board (option) to a PC to be used, the emulator can be connected to the PC via the ISA bus.

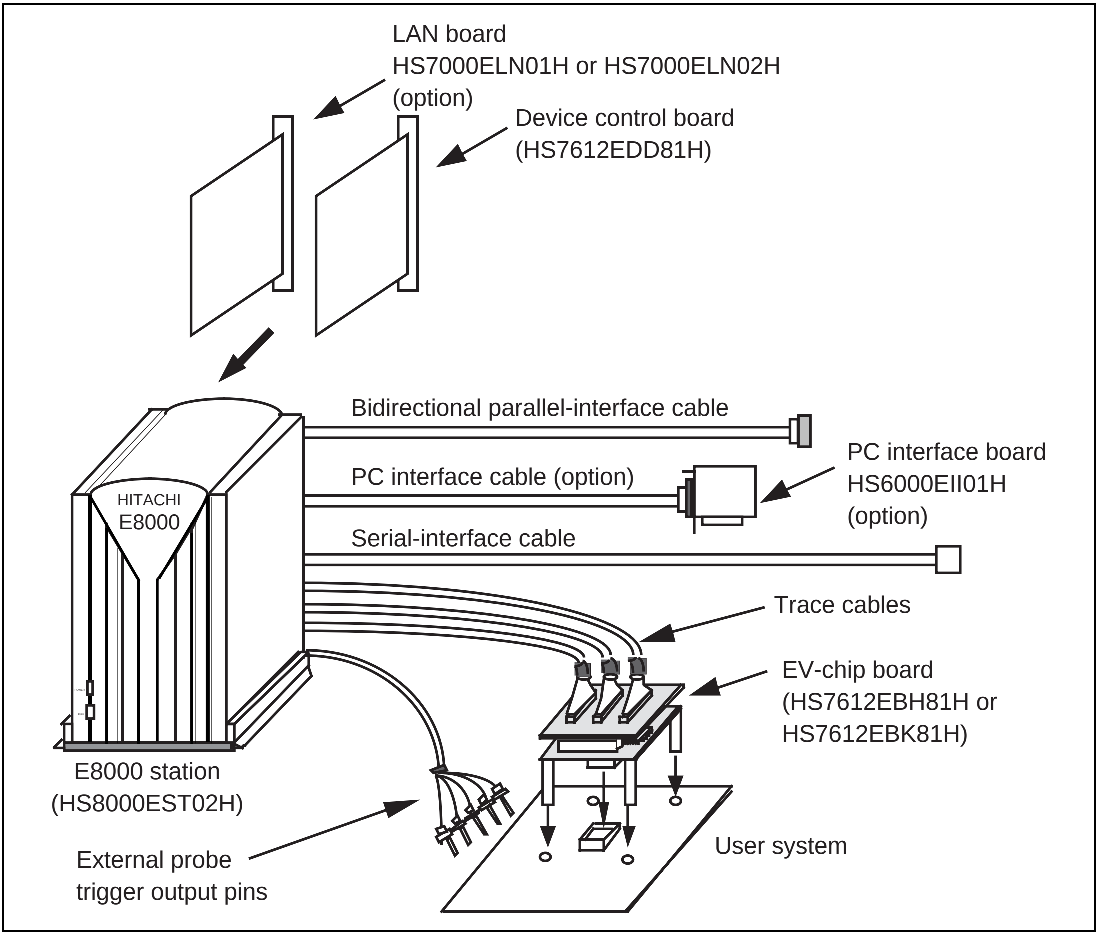


Figure 2.1 Emulator Hardware Components

2.1.1 E8000 Station Components

Front Panel:

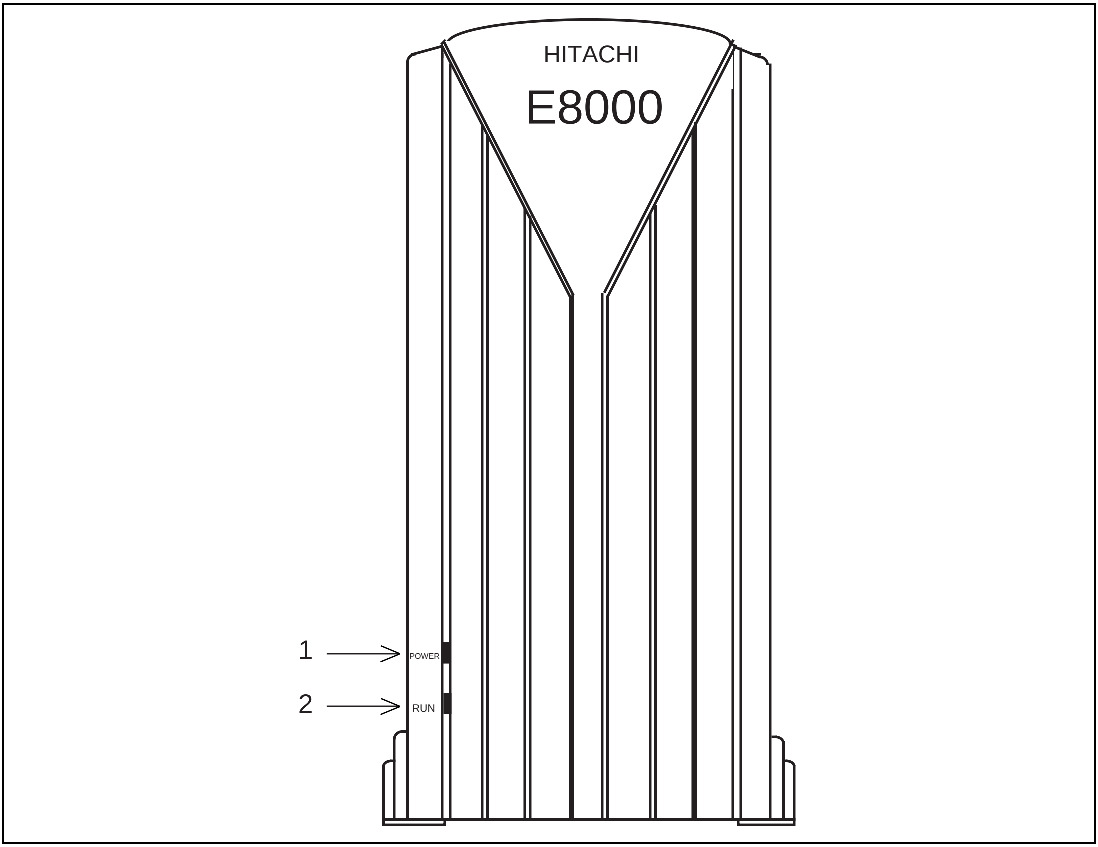


Figure 2.2 E8000 Station Front Panel

1. POWER lamp
   Lit up when the E8000 station power is on.
2. RUN lamp
   Lit up when the user program is running.

Rear Panel:

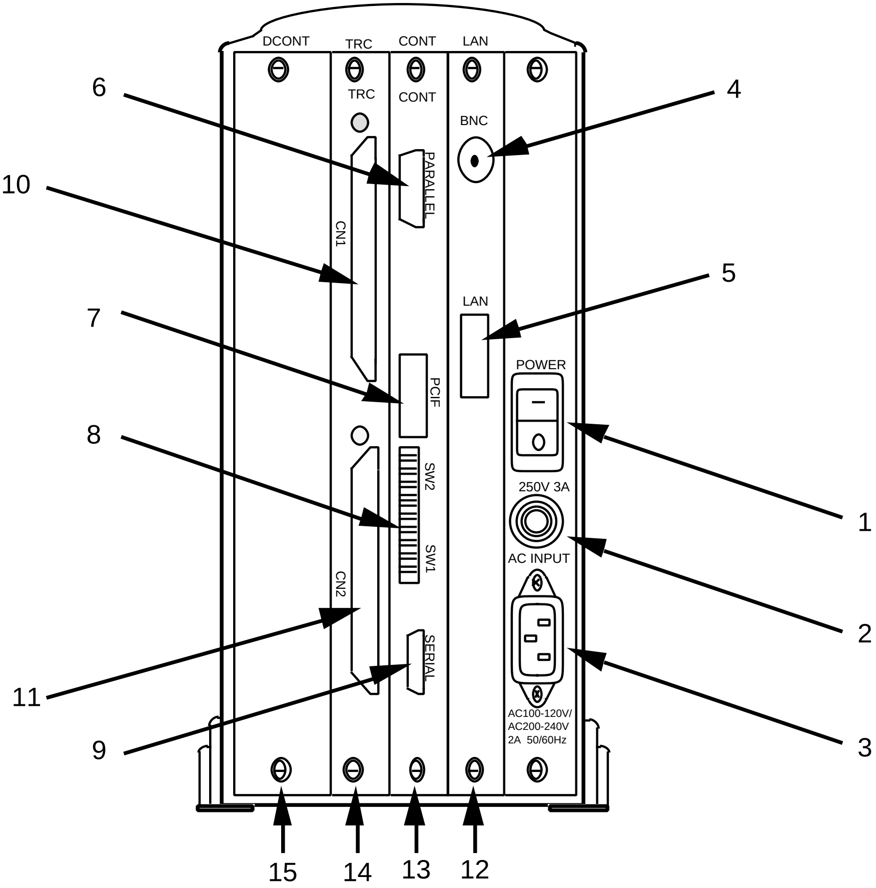


Figure 2.3 E8000 Station Rear Panel

1. Power switch

   Turning this switch to I (input) supplies power to the emulator (E8000 station and EV-chip board).

2. Fuse box

   Contains a 3-A 250-V AC fuse or T3.15A.

3. AC power connector

   For a AC100-120 V/200-240 V power supply.

4. Cheapernet connector

   For a Cheapernet cable. Marked BNC.

5. Ethernet connector

   For an Ethernet cable. Marked LAN.

6. Parallel-interface connector

   For a parallel-interface cable with the host PCIF board. Conforms to IEEE-P1284 (ECP mode). Marked PARALLEL.

7. PC interface cable connector

   For the PC interface cable which connects the PC to the E8000 station. Marked PCIF.

8. Host interface switches

   For selecting the host interface. Specifies the connection of the LAN interface, RS-232C interface, or PC I/F board. When the RS-232C interface is used, the data-bit length, stop-bit length, or parity-setting transfer rate can be switched. Marked SW1 and SW2.

9. Serial-interface connector

   For RS-232C communication with a host PC. Marked SERIAL.

10. Station to EV-chip board interface connector CN1

    For trace cable 1 which connects the E8000 station to the EV-chip board.

11. Station to EV-chip board interface connector CN2

    For trace cable 2 which connects the E8000 station to the EV-chip board.

12. LAN-board slot

    For installing the optional LAN board.

13. Control board slot

    For installing the control board.

14. Trace board slot

    For installing the trace board.

15. Device control board slot

    For installing the device control board (depends on the target device).

2.1.2 Device Control Board Components

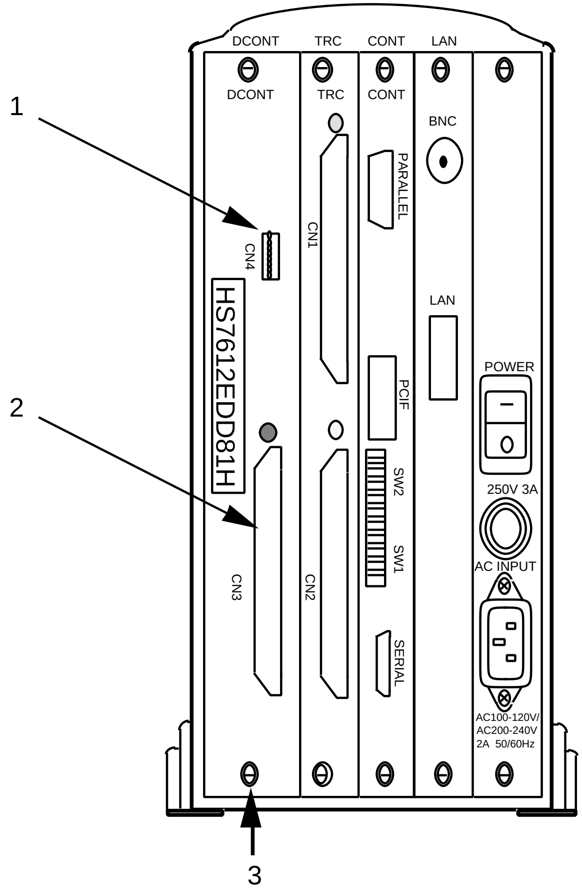


Figure 2.4 Device Control Board

1. External probe connector CN4

   For connecting to the external probe.
2. Station to EV-chip board interface connector CN3

   For trace cable 3 which connects the E8000 station to the EV-chip board.
3. Device control board slot

   For installing the device control board (depends on the target device).

2.1.3 EV-Chip Board Components

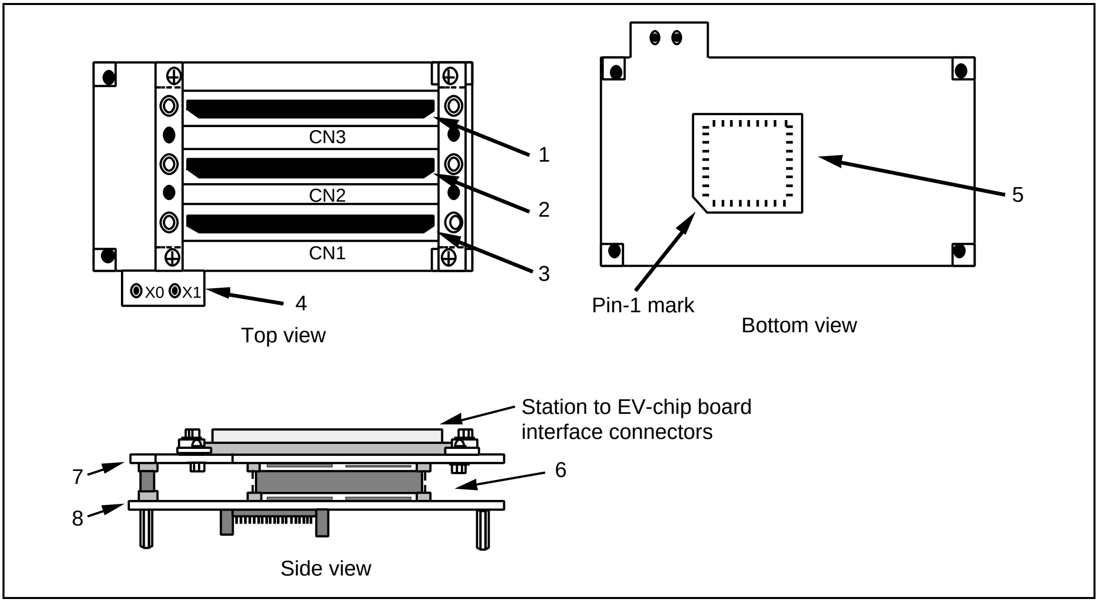


Figure 2.5 EV-Chip Board (HS7612EBH81H) *1

1. Station to EV-chip board interface connector CN3
   For trace cable 3 which connects the emulator to the EV-chip board.
2. Station to EV-chip board interface connector CN2
   For trace cable 2 which connects the emulator to the EV-chip board.
3. Station to EV-chip board interface connector CN1
   For trace cable 1 which connects the emulator to the EV-chip board.
4. Crystal oscillator terminals
   For installing a crystal oscillator to be used as an external clock source for the SH7612.
5. User-system connector
   For connecting the user system.
6. Board connector
   For connecting HS7410PWB20H and HS7410PWB30H.
7. HS7410PWB20H
   Includes connectors for interfacing with the E8000 station.
8. HS7420PWB30H (or HS7420PWB50H*2)
   Includes connectors (QFP-176) for interfacing with the user system.

Notes: 1. For the EV-chip board, there are a QFP176 IC socket type (HS7612EBH81H) and a two 100-pin connector type (HS7612EBK81H), which can be selected in accordance with the user application.

2. The HS7420PWB50H has a connector (2 x 100-pin) to be connected to the user system.

2.2 Emulator Software Components

The emulator's software components are illustrated in figure 2.6. The device control board contains a 3.5-inch floppy disk. The system disk files are described in table 2.1.

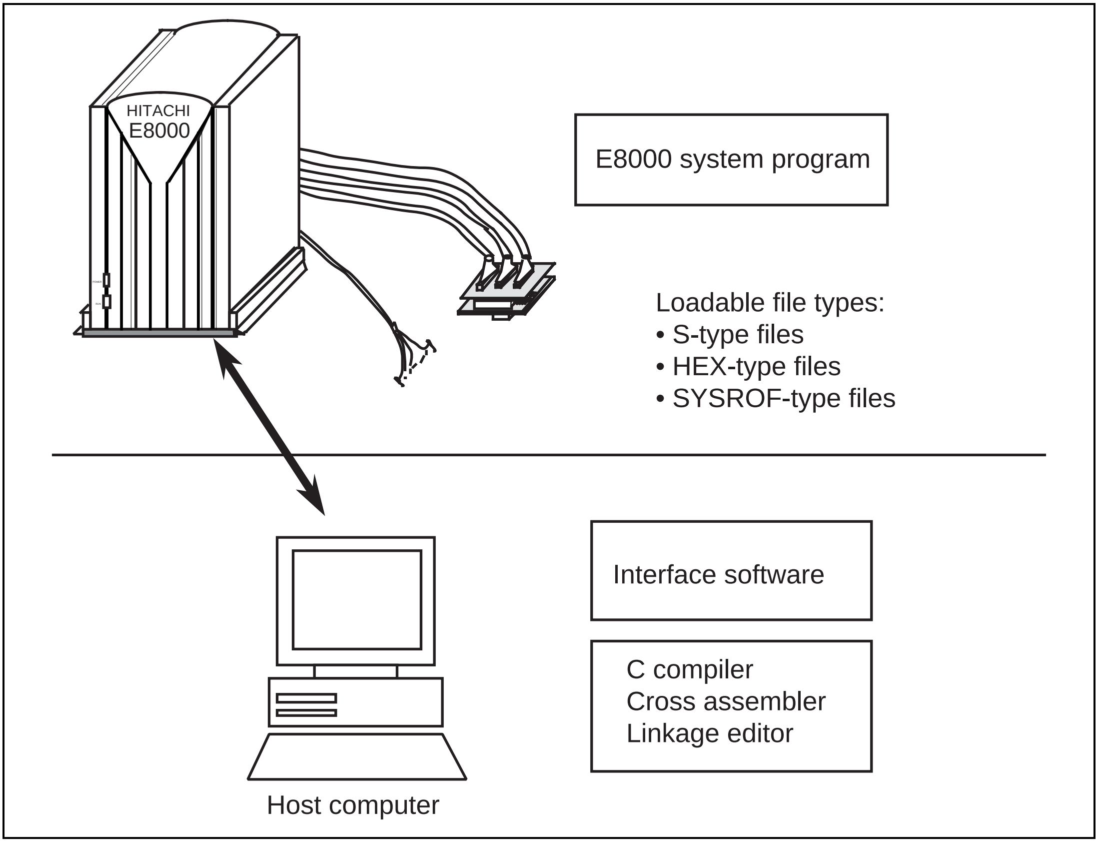


Figure 2.6 Emulator Software Components

Table 2.1 Contents of E8000 System Disk

File Name	Contents	Description
E8000.SYS	E8000 system program	Controls the EV-chip board and processes commands, such as emulation commands. Loaded into the emulator memory.
SHDCT761.SYS	SH7612 control program	Controls the SH7612 in the EV-chip board. Loaded into the emulator memory.
SHCNF761.SYS	Configuration file	Contains SH7612 operating mode and MAP information.
IPW.EXE	Interface program	Operates on the Microsoft Windows95 of the PC and communicates with the emulator.
DIAG.SYS	Diagnostic program	Loaded into the emulator station memory for testing and maintenance.
SETUP.CC*	Load file	Loads files E8000.SYS, SHDCT761.SYS, and SHCNF761.SYS to the emulator memory.

Note: See section 3.7, System Program Installation.

2.3 System Configuration

The E8000 station can be connected to the host computer via a LAN interface (optional LAN board), an RS-232C interface, or a bidirectional parallel interface.

2.3.1 System Configuration Using a LAN Interface

By installing an optional LAN board in the E8000 station, the emulator can communicate with a workstation using a LAN interface. The LAN board contains connectors for both Cheapernet (10BASE2) and Ethernet (10BASE5). The system configuration using a LAN interface is shown in figure 2.7.

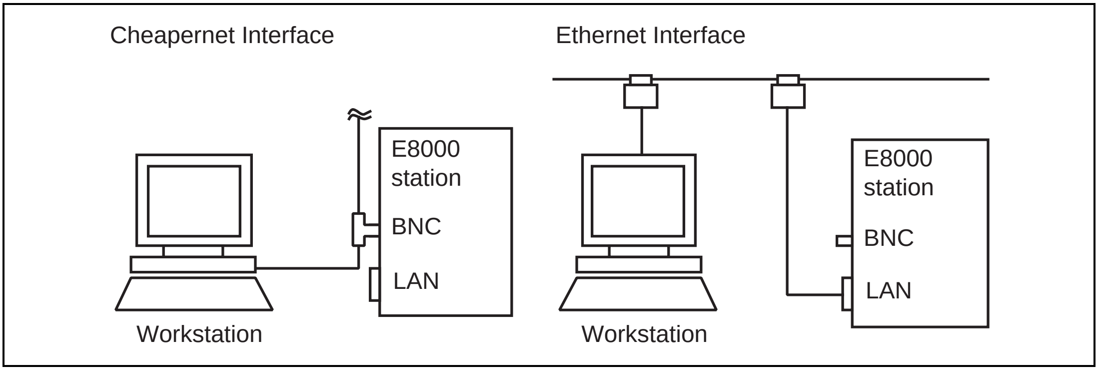


Figure 2.7 System Configuration Using a LAN Interface

Cheapernet Interface: This is achieved by connecting a coaxial cable (referred to as the Cheapernet thin-wire cable) between the BNC connector on the LAN board and the workstation.

Ethernet Interface: This is achieved by connecting transceivers and transceiver cables between the D-SUB connector on the LAN board and the workstation.

2.3.2 System Configuration Using an RS-232C or Bidirectional Parallel Interface

Using an RS-232C interface or a bidirectional parallel interface, the E8000 station can be connected to a personal computer. Figure 2.8 shows the system configuration using the RS-232C or bidirectional parallel interface.

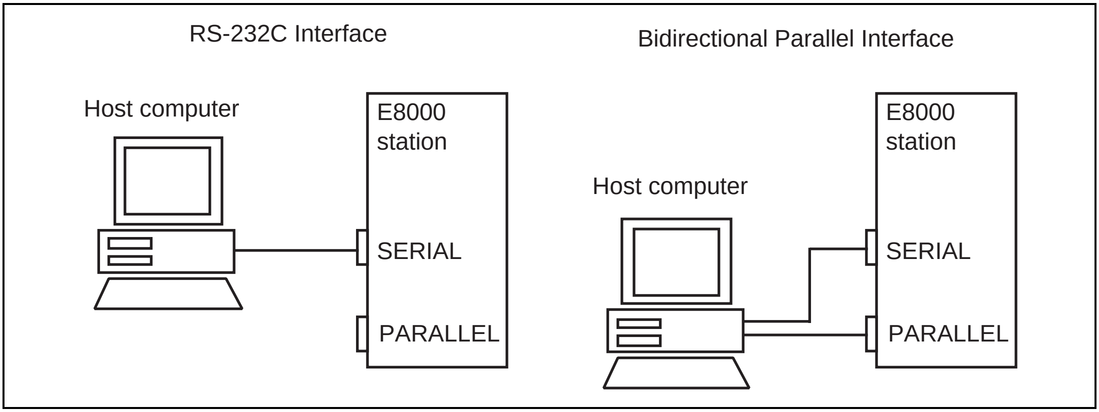


Figure 2.8 System Configuration Using an RS-232C or Bidirectional Parallel Interface

2.3.3 System Configuration Using a PC Interface Board

The E8000 station can be connected to a host computer via a PC interface board. Install the PC interface board to the extension slot of the ISA bus specification in a PC, and connect the interface cable supplied with the PC interface board to the E8000 station. Figure 2.9 shows the system configuration using the PC interface board.

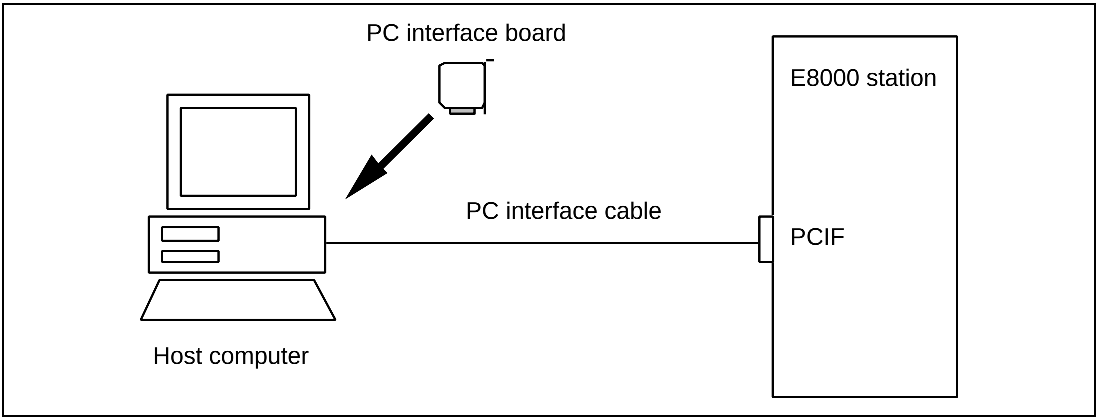


Figure 2.9 System Configuration Using a PC Interface Board

Section 3 Preparation before Use

3.1 Emulator Preparation

CAUTION

Read the reference sections shaded in figure 3.1 and the following warnings before using the emulator. Incorrect operation will damage the user system and the emulator. The USER PROGRAM will be LOST.

Unpack the emulator and prepare it for use as follows:

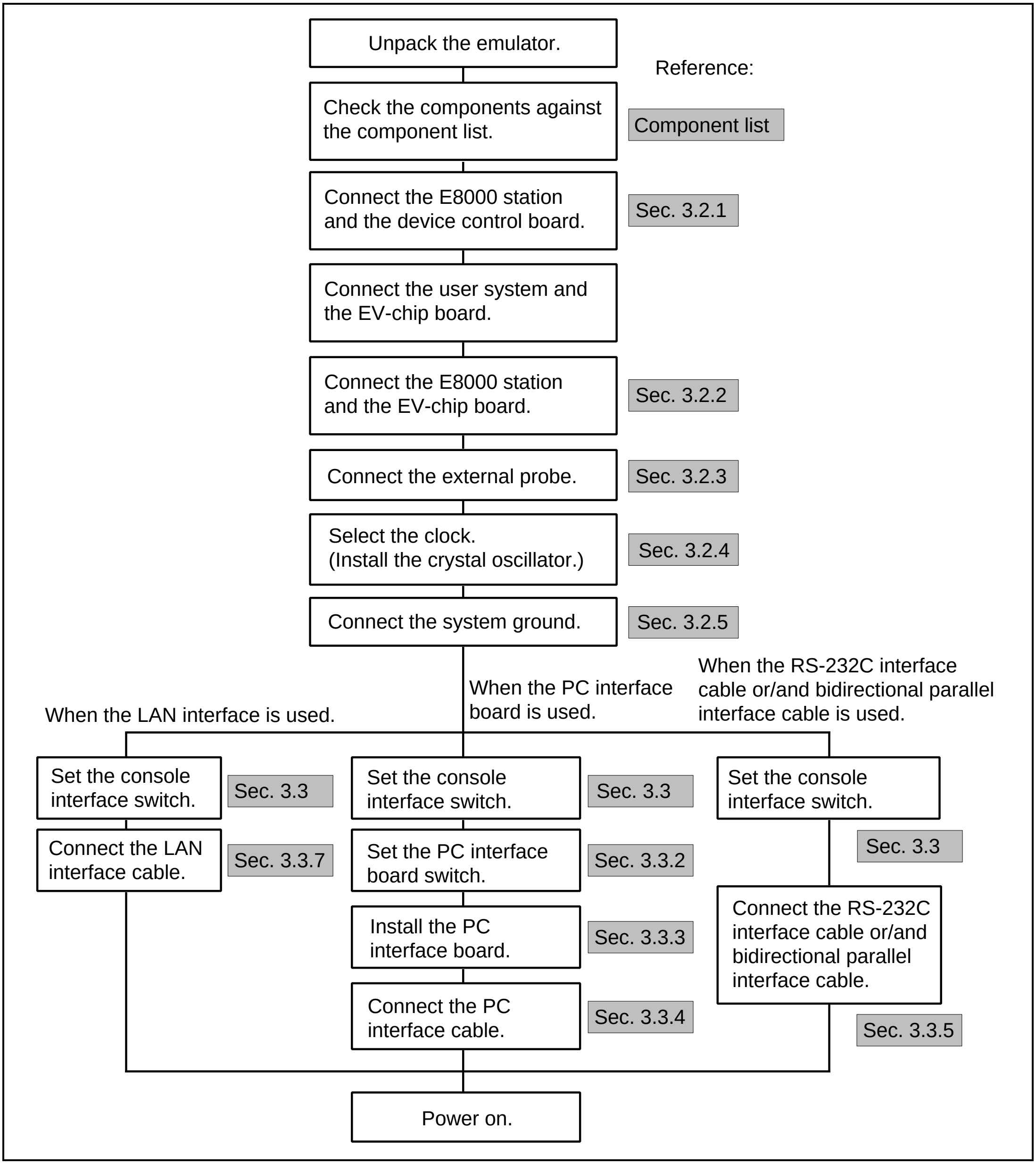


Figure 3.1 Emulator Preparation Flow Chart

3.2 Emulator Connection

3.2.1 Connecting the Device Control Board

At shipment, the device control board is packed separately from the E8000 station. Connect the device control board to the E8000 station according to the following procedure. Also, use the following procedure to connect them after remove the device control board from the E8000 station to change the device control board.

⚠ **WARNING**

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

1. Check that the emulator power switch is turned off. Ensure that the power lamp on the left side of the E8000 station's front panel is not lit.
2. Remove the AC power cable of the E8000 station from the outlet (if the cable is connected to the outlet).
3. Remove the back panel from the E8000 station. For the slot to which the device control board is to be connected, DCONT is marked.
4. Connect the device control board to the E8000 station. When connecting the board, prevent the upper or lower side of the board from lifting off the connector. Alternately tighten the screws on both sides of the board.

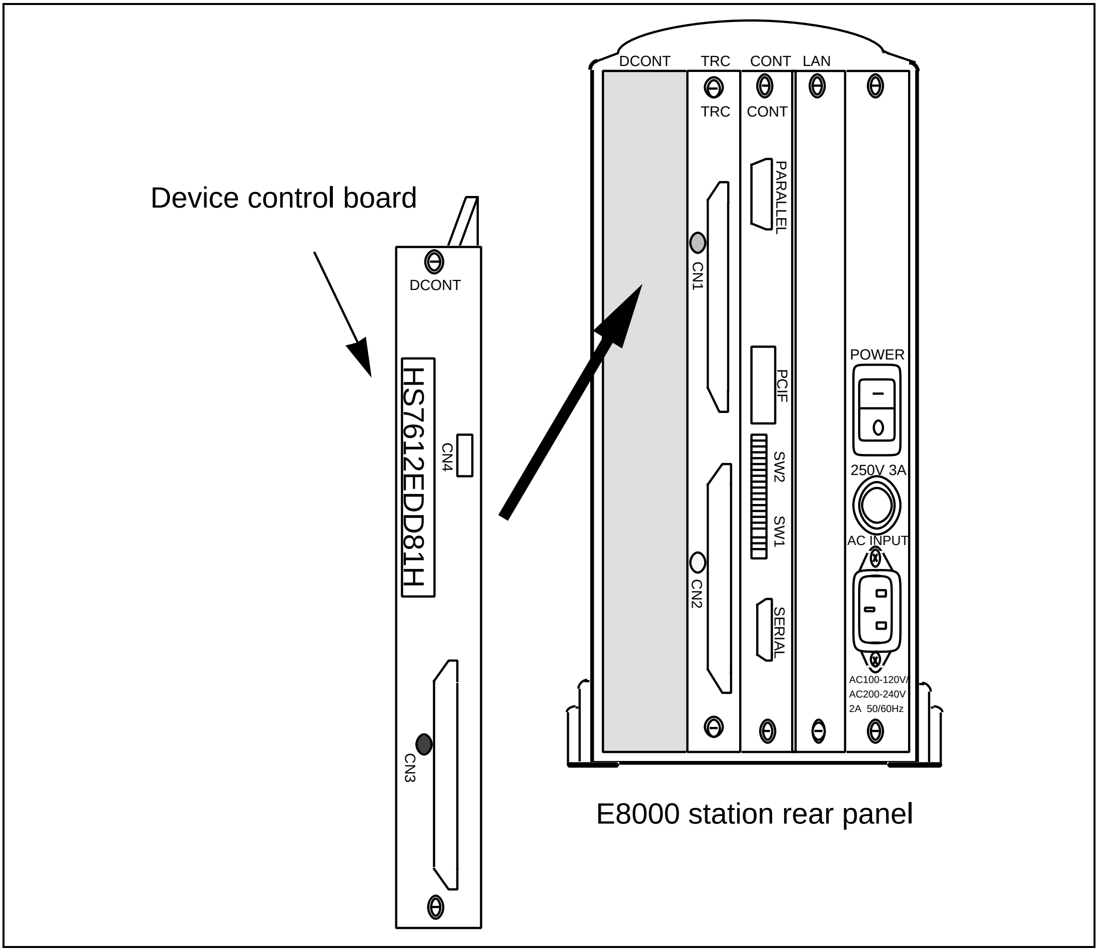


Figure 3.2 Connecting the Device Control Board

3.2.2 Connecting the EV-Chip Board

At shipment, the EV-chip board is packed separately from the E8000 station. Use the following procedure to connect the EV-chip board to the E8000 station, or to disconnect them when moving the emulator:

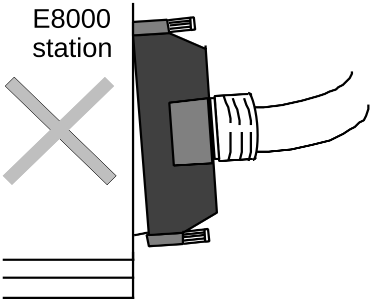
⚠ **WARNING**

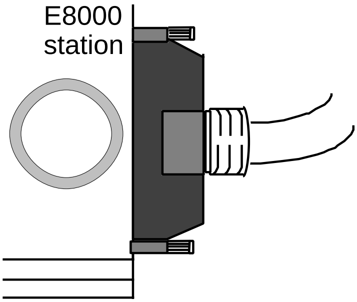
Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

1. Check that the emulator power switch is turned off. Ensure that the power lamp on the left side of the E8000 station's front panel is not lit.
2. Remove the AC power cable of the E8000 station from the outlet (if the cable is connected to the outlet).

⚠ **WARNING**

When connecting the cable, ensure that the upper (A) or lower (B) side of the cable does not lift off the connector. Alternately tighten the screws on both sides of the cable while gradually pushing the cable toward the connector. Failure to do so will result in a FIRE HAZARD, damage the user system and emulator, and will result in PERSONAL INJURY. The USER PROGRAM will be LOST.





3. Connect the trace cables into the station to EV-chip board interface connectors (CN1, CN2, and CN3) on the E8000 station's rear panel. Confirm that the shape of the trace-cable plug matches that of the station to EV-chip board interface connector before connecting. Also note which trace cable is connected to which E8000-station connector so that the other end of the trace cable is connected to the matching connector number on the EV-chip board. After the connection is completed, alternately tighten the screws on both sides of the trace cable to prevent the upper or lower side of the trace cable from lifting off the connector. Figure 3.3 shows how to correctly connect the trace cables to the E8000 station connectors.

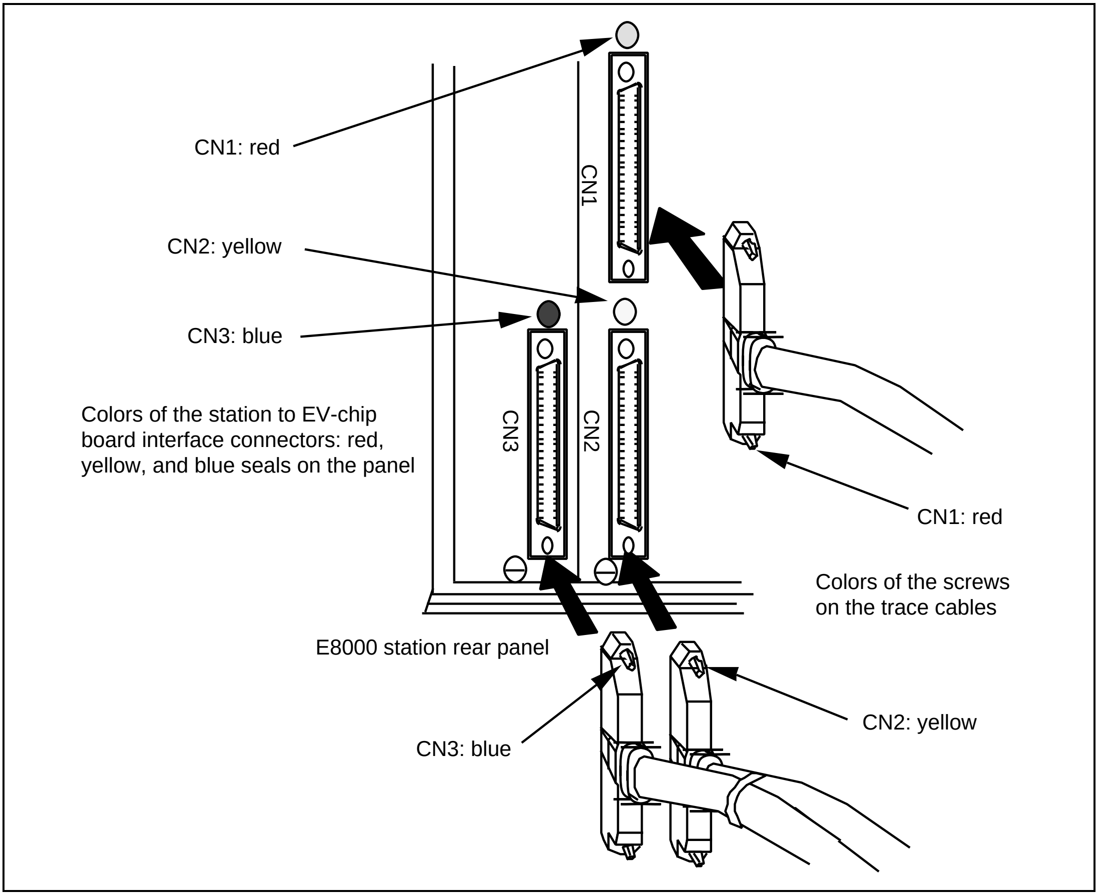


Figure 3.3 Connecting Trace Cables to the E8000 Station

Note: At shipment, the trace cable screws are colored to prevent an insertion error (CN1: red, CN2: yellow, CN3: blue). In addition, trace cables CN2 and CN3 to be connected to the E8000 station are bound into a bundle, and trace cables CN1, CN2, and CN3 to be connected to the EV-chip board are bound into a bundle. Check for the number of cables bound into a bundle and the colors for connectors when connecting the cables.

⚠ WARNING

Make sure the connector shapes and numbers are correctly matched when connecting trace cables to the station to EV-chip interface connectors. Failure to do so will damage the connectors.

4. Connect the trace cables to the station to EV-chip board interface connectors CN1, CN2, and CN3 on the EV-chip board. Confirm that each trace cable connected to a connector on the E8000 station is also connected to its corresponding station to EV-chip board interface connector on the EV-chip board. Connect the cables using the same method as in step 3. Figure 3.4 shows how to connect the trace cables to the EV-chip board interface connectors.

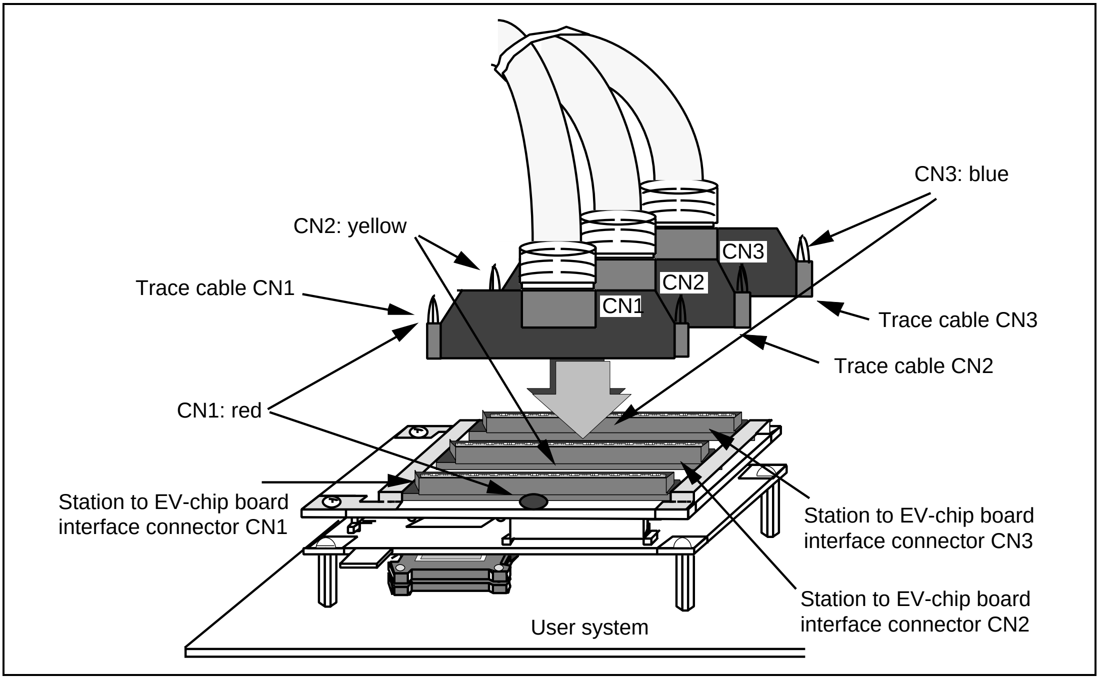


Figure 3.4 Connecting Trace Cables to the EV-Chip Board

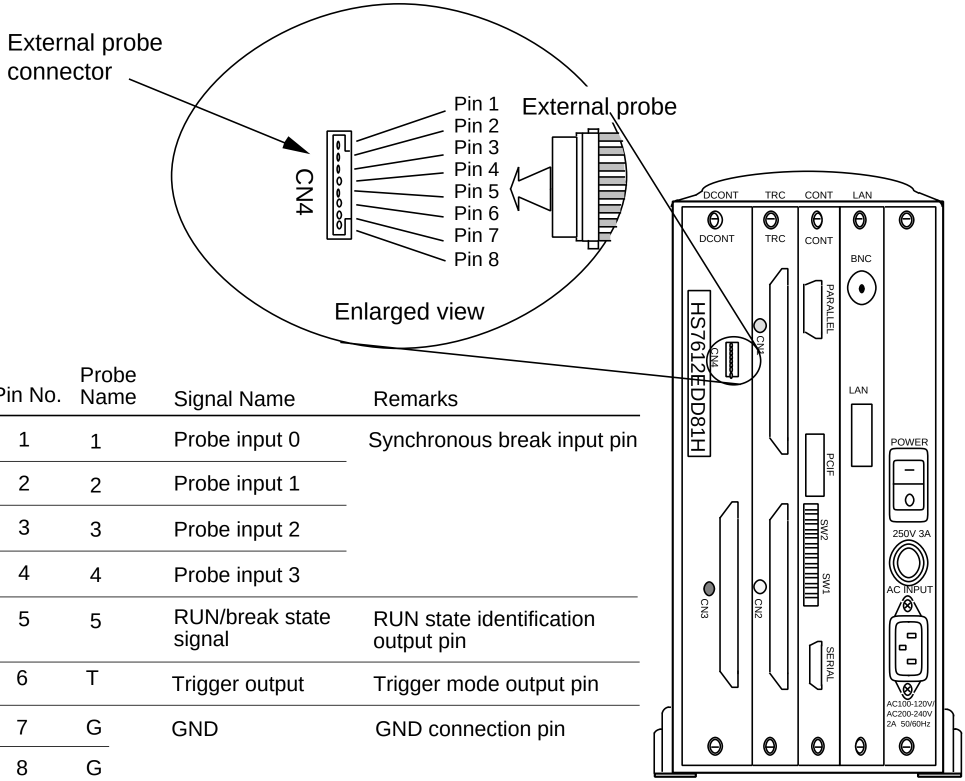
Note: For the connection between the EV-chip board and the user system, refer to section 3, Connecting the EV-Chip Board to the User System, in the Evaluation Chip Board (HS7612EBH81H, HS7612EBK81H) Description Notes.

3.2.3 Connecting the External Probe

CAUTION

Check the external probe direction and connect the external probe to the emulator station correctly. Incorrect connection will damage the probe or connector.

When an external probe is connected to the emulator probe connector on the emulator station's rear panel, it enables external signal tracing and multibreak detection. Figure 3.5 shows the external probe connector.



Pin No.	Probe Name	Signal Name	Remarks
1	1	Probe input 0	Synchronous break input pin
2	2	Probe input 1	
3	3	Probe input 2	
4	4	Probe input 3	
5	5	RUN/break state signal	RUN state identification output pin
6	T	Trigger output	Trigger mode output pin
7	G	GND	GND connection pin
8	G		

Figure 3.5 External Probe Connector

3.2.4 Selecting the Clock

This emulator supports three types of clock for the SH7612: a crystal oscillator attached on the EV-chip board, external clock input from the user system, and the emulator internal clock. The clock is specified with the CLOCK command.

This emulator can use a clock source of up to the SH7612 maximum operating frequency of

66 MHz (quadruple of external clock frequency 16.5 MHz).

CLOCK command
- X (Crystal oscillator: 8 to 16.5 MHz)
- U (External clock: 1 to 33 MHz)
- E (Emulator internal clock: 15 MHz)

Crystal Oscillator: A crystal oscillator is not supplied with the emulator. Use one that has the same frequency as that of the user system. When using a crystal oscillator as the SH7612 clock source, the frequency must be from 8 to 16.5 MHz. When using frequencies outside this range, supply an external clock from the user system.

WARNING

Always switch OFF the emulator and user system before connecting or disconnecting the CRYSTAL OSCILLATOR. Failure to do so will result in a FIRE HAZARD and will damage the user system and emulator or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

Use the following procedure to install the crystal oscillator:

1. Check that the emulator power switch is turned off. Ensure that the power lamp on the left side of the E8000 station’s front panel is not lit.
2. Attach the crystal oscillator into the terminals on the EV-chip board (figure 3.6).

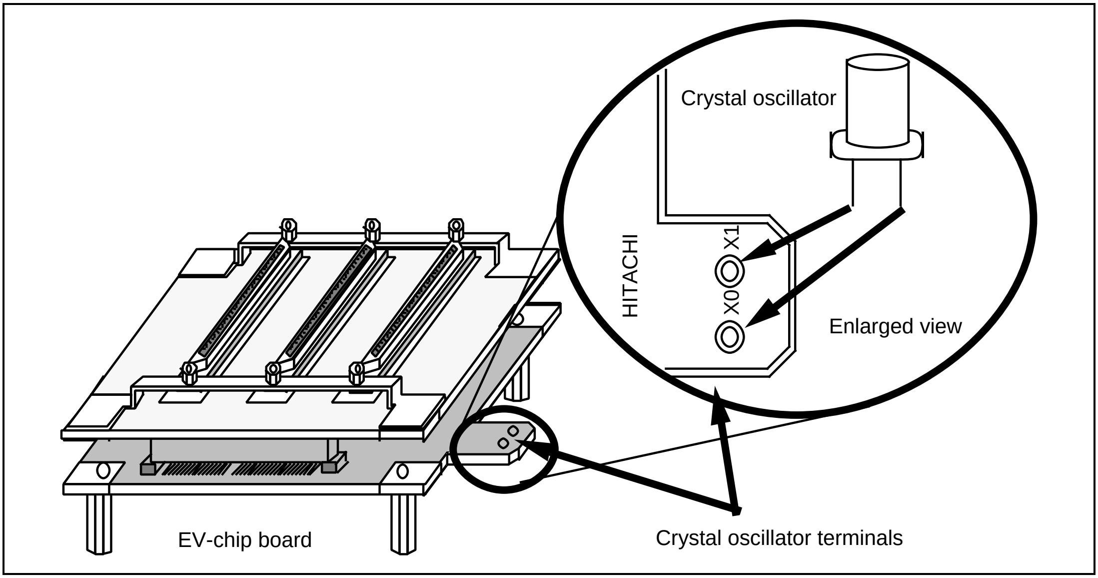


Figure 3.6 Installing the Crystal Oscillator

3. Turn on the user system power and then the emulator power. X (crystal oscillator) will then be automatically specified in the CLOCK command.

Using the crystal oscillator enables execution of the user program at the user system's operating frequency, even when the user system is not connected.

External Clock: Use the following procedure to select the external clock.

⚠ WARNING

Always switch OFF the emulator and user system before connecting or disconnecting the EV-CHIP BOARD and the USER SYSTEM. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

1. Check that the emulator power switch is turned off. Ensure that the power lamp on the left side of the E8000 station's front panel is not lit.
2. Connect the EV-chip board to the user system and supply a clock through the EXTAL pin from the user system.
3. Turn on the user system power and then the emulator power. U (external clock) will then be automatically specified in the CLOCK command.

Emulator Internal Clock: Specify E (15 MHz) with the CLOCK command.

Reference:
When the emulator system program is initiated, the emulator automatically selects the SH7612 clock source according to the following priority:

1. External clock when supplied from the user system
2. Crystal oscillator when attached to the EV-chip board
3. 15-MHz emulator internal clock

3.2.5 Connecting the System Ground

The emulator’s signal ground is connected to the user system’s signal ground via the EV-chip board. In the E8000 station, the signal ground and frame ground are connected (figure 3.7). At the user system, connect the frame ground only; do not connect the signal ground to the frame ground.

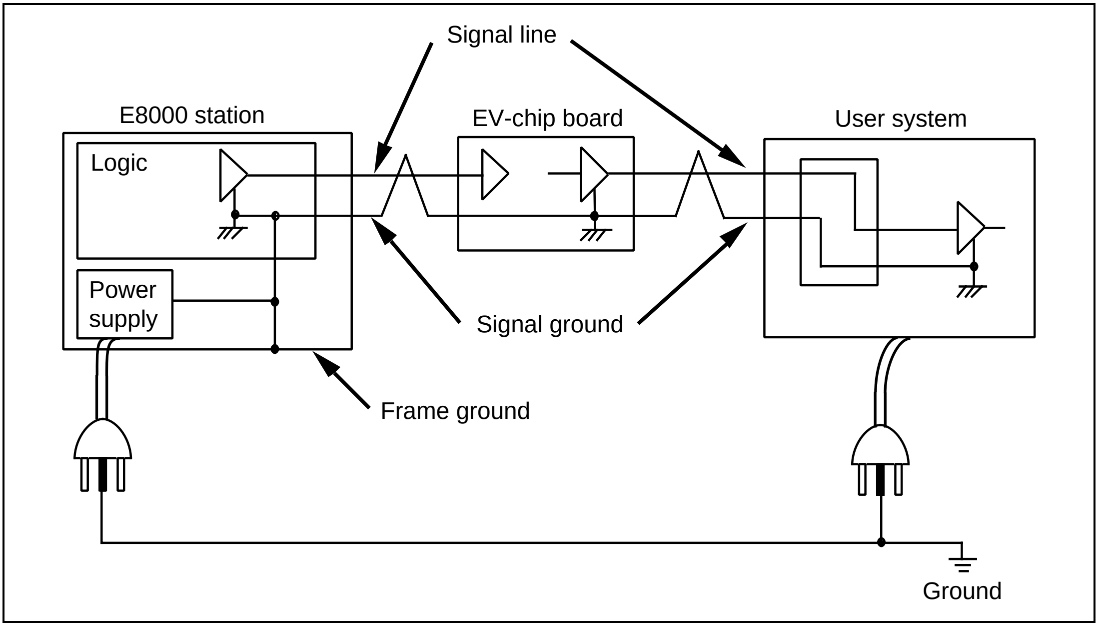


Figure 3.7 Connecting the System Ground

If it is difficult to separate the signal ground from the frame ground, insert the user system power cable and the emulator's power cable into the same outlet (figure 3.8) so that the ground lines of the cables are maintained at the same ground potential.

The user system must be connected to an appropriate ground so as to minimize noise and the adverse effects of ground loops. When connecting the EV-chip board and the user system, confirm that the ground pins of the EV-chip board are firmly connected to the user system's ground.

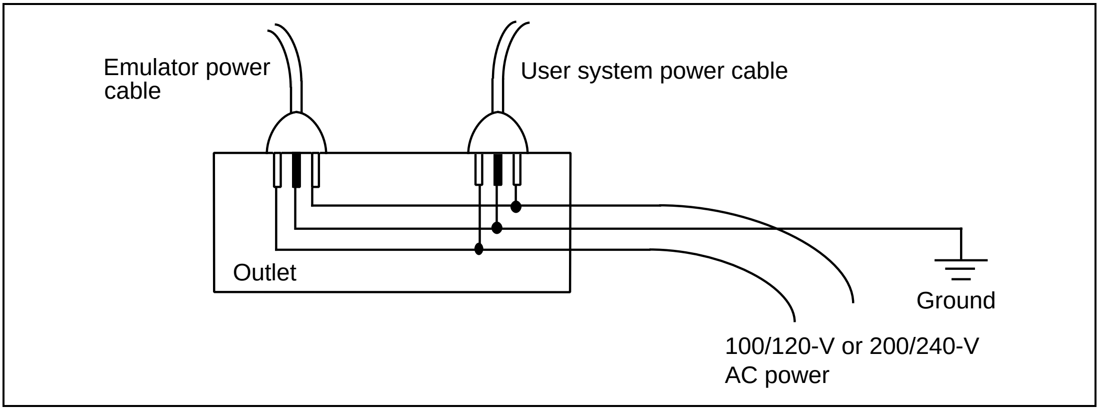


Figure 3.8 Connecting the Frame Ground

3.3 System Connection

The following describes the procedure for connecting the emulator to a work station or a host computer. See figure 2.3 for the connector arrangement in the E8000 station.

Console Interface Setting: The settings of the transfer rate, data-bit length, stop-bit length, and parity can be changed. Use console interface switches SW1 and SW2 on the back of the E8000 station to change the settings. Switches SW1 and SW2 also include switches for the use of the console interface, the LAN interface or the PC interface.

The console interface consists of 16 switches (eight switches in both SW1 and SW2), as shown in figure 3.9. The switch state becomes on when the switches are pushed to the left, and the state becomes off when the switches are pushed to the right.

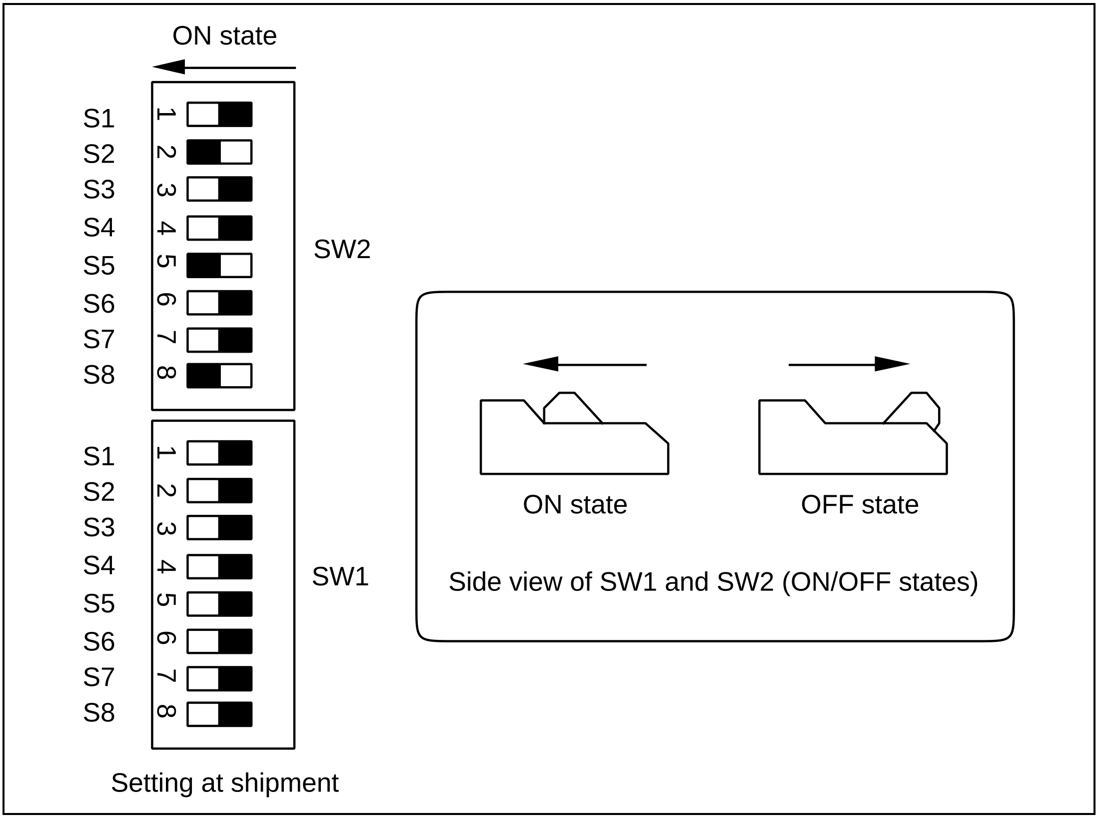


Figure 3.9 Console Interface Switches

To change the console interface settings, turn switches S1 to S8 on or off in the console interface switches SW1 and SW2. Table 3.1 lists the console interface settings and the corresponding setting states.

Note: Be sure to turn off the power supply before changing the settings of console interface switches SW1 and SW2.

Table 3.1 Console Interface Settings *[1]

Transfer Rate (SW2)	**S3**	**S2**	**S1**
2400 BPS	OFF	OFF	OFF
4800 BPS	OFF	OFF	ON
9600 BPS	OFF	ON	OFF (Setting at shipment)
19200 BPS	OFF	ON	ON
38400 BPS	ON	OFF	OFF

Stop-bit Length (SW2)	**S4**
1 bit	OFF (Setting at shipment)
2 bits	ON

Bit Length (SW2)	**S5**
7 bits	OFF
8 bits	ON (Setting at shipment)

Parity (SW2)	**S6**
None	OFF (Setting at shipment)
Parity	ON

Even/odd Parity (SW2)	**S7**
1 bit	OFF (Setting at shipment)
2 bits	ON

Note: Effective only when there is a parity.

Flow Control (Protocol) (SW2)	**S8**
CTS, RTS	OFF
X-ON/OFF	ON (Setting at shipment)

Automatic System Program Initiation (Quit & Warm Start) (SW1)	**S4**
NO	OFF (Setting at shipment)
YES	ON

Console/LAN/PC Interface (SW1) *[2]	**S7**	**S8**
Console *[3]	OFF	OFF (Setting at shipment)
LAN	OFF	ON
PC interface board	ON	ON

Notes: 1. **Switches S1, S2, S3, S5, and S6 of SW1 are not used. Use these switches with the off state. Console interface settings must be performed before the E8000 station power is turned on.**

2. **If the settings of the console interface (S7 and S8 of SW1) are incorrect, the initiation of the E8000 station cannot be confirmed on the screen. After turning off the E8000 station power, correct the interface settings. See section 3.5, Power-On Procedure for Emulator.**

3. **The console interface includes an RS-232C interface and a bidirectional parallel interface.**

3.3.1 PC Interface Board Specifications

Table 3.2 lists the PC interface board specifications.

Table 3.2 PC Interface Board Specifications

Item	**Specifications**
Available host computer	ISA-bus specification PC, or compatible machine
System bus	ISA-bus specification
Memory area	16 kbytes
Memory area setting	Can be set at every 16 kbytes in the range from H'C0000 to H'EFFFF with a switch.

3.3.2 Switch Settings of the PC Interface Board

Memory-area Setting: The PC interface board uses a 16-kbyte memory area on the PC. The memory area to be used must be allocated to the memory area on the PC with a switch on the PC interface board. Any 16 kbytes in the range of H'C0000 to H'EFFFF can be allocated (figure 3.10). Addresses to be allocated must not overlap the memory addresses of other boards. An overlap will cause incorrect operation.

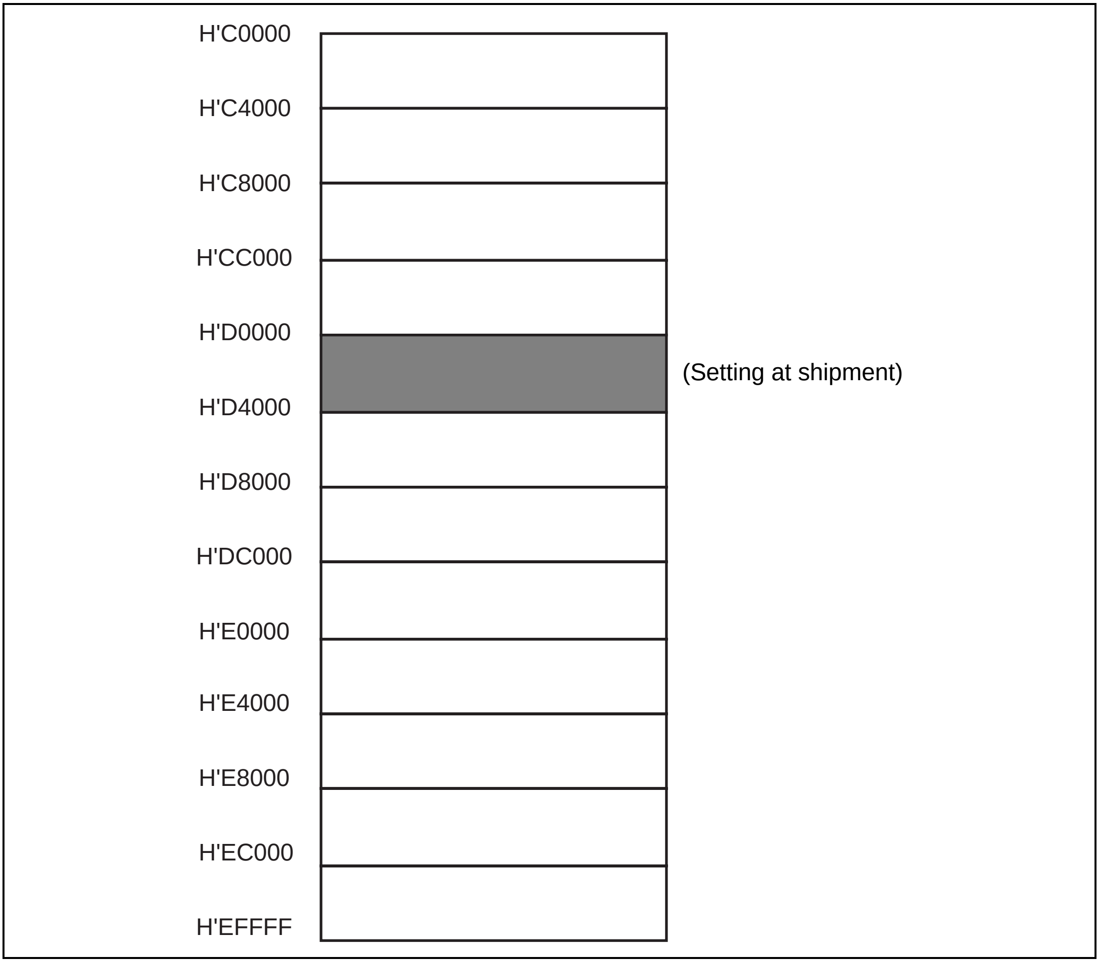


Figure 3.10 Allocatable Memory Area of PC Interface Board

Switch Setting: A rotary switch is installed on the PC interface board (figure 3.11). The switch is used to set the memory-area allocation. Table 3.3 lists the switch setting states. The switch setting at emulator shipment is No. 4 (memory area H'D0000 to H'D3FFF).

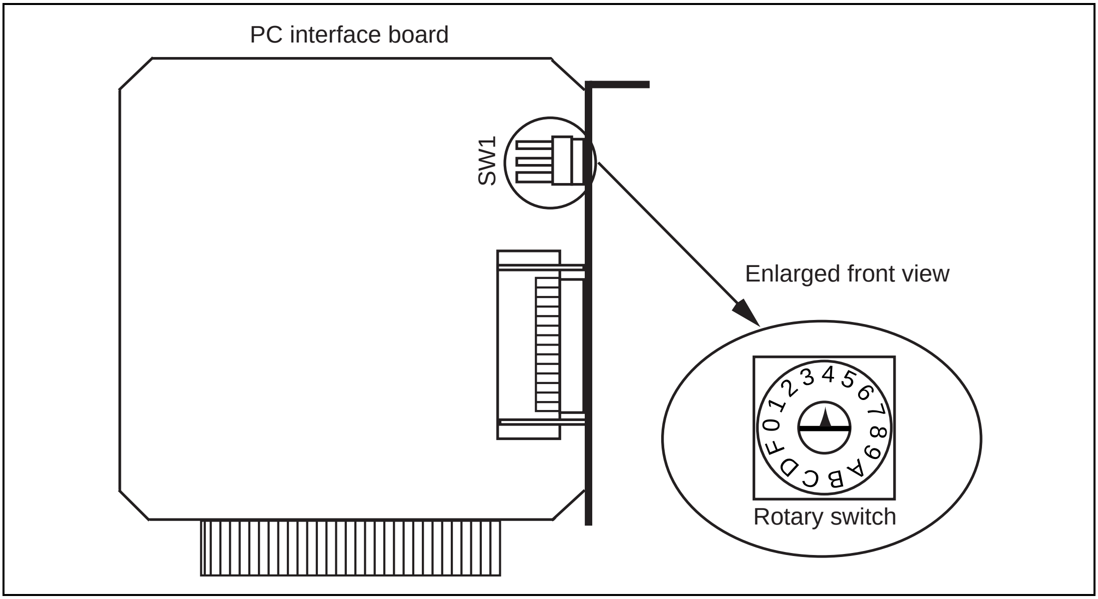


Figure 3.11 PC Interface Board Switch

Table 3.3 Switch Settings for Memory Areas

Switch Setting	Memory Area	Switch Setting	Memory Area
0	H'C0000 to H'C3FFF	8	H'E0000 to H'E3FFF
1	H'C4000 to H'C7FFF	9	H'E4000 to H'E7FFF
2	H'C8000 to H'CBFFF	A	H'E8000 to H'EBFFF
3	H'CC000 to H'CFFFF	B	H'EC000 to H'EFFFF
4 (setting at shipment)	H'D0000 to H'D3FFF	C	Not used
5	H'D4000 to H'D7FFF	D	Not used
6	H'D8000 to H'DBFFF	E	Not used
7	H'DC000 to H'DFFFF	F	Not used

Note: When C to F of the switch are set, memory areas cannot be allocated. Set one of 0 to B.

3.3.3 Installing the PC Interface Board

WARNING

Always switch OFF the PC and peripheral devices connected to the PC before installing the PC interface board. Failure to do so will result in a FIRE HAZARD and will damage the PC, interface board, and peripheral devices, or will result in PERSONAL INJURY.

Remove the cover of the PC and install the PC interface board in the ISA-bus specification extension slot. Tighten the screw after confirming that the PC interface cable can be connected to the board.

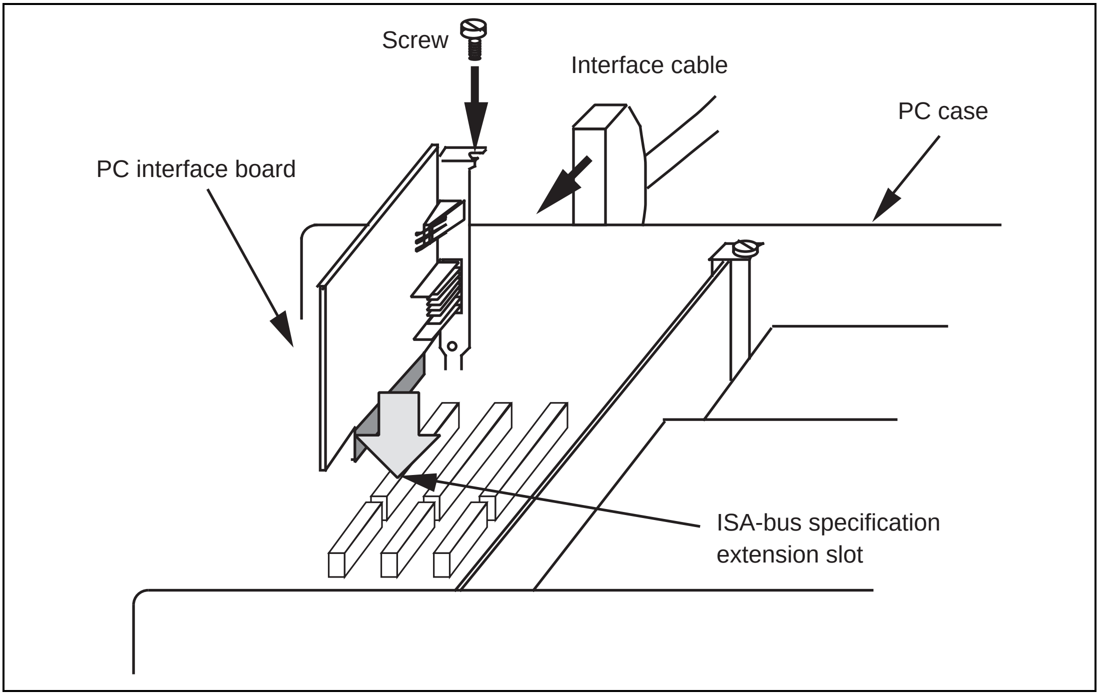


Figure 3.12 Installing the PC Interface Board

3.3.4 Connecting the E8000 Station to the PC Interface Board

WARNING

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator, or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

Before using the emulator, connect the E8000 station to the PC interface board with the PC interface cable supplied, as shown in figure 3.13.

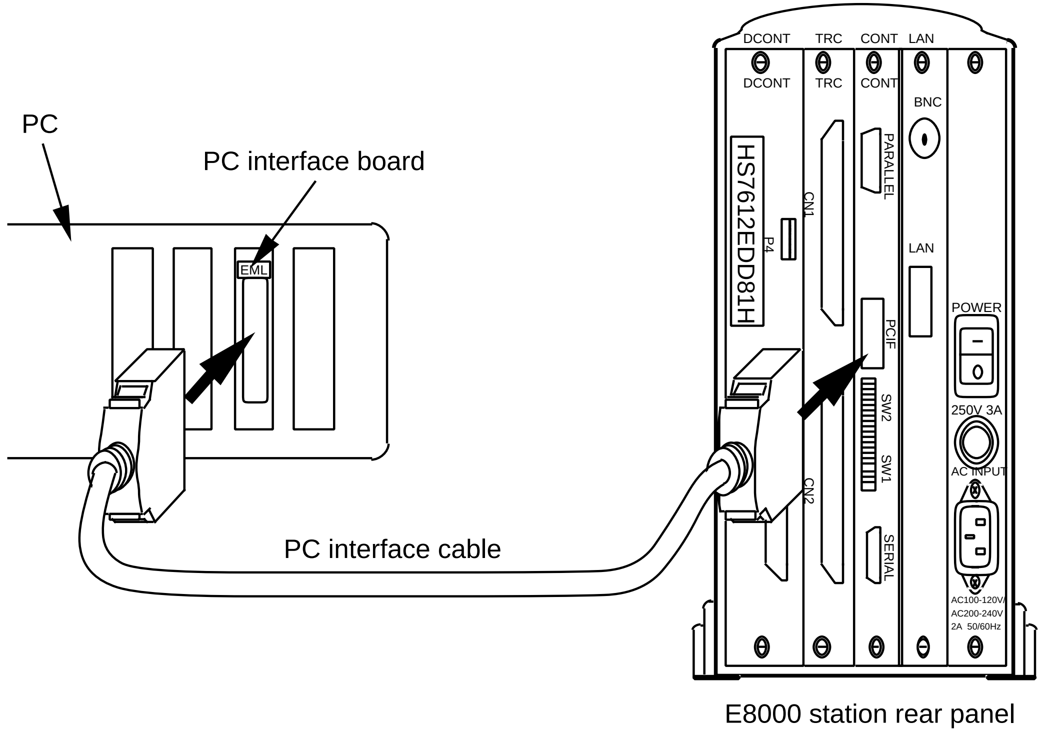


Figure 3.13 Connecting the E8000 Station to the PC Interface Board

3.3.5 Connecting to a Host Computer

⚠ **WARNING**

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

This section describes how to set the host computer interface when the emulator is connected to a host computer. The host computer connector (marked SERIAL) is located on the E8000 station's rear panel. Connecting this connector to a host computer via the RS-232C interface cable enables data transfer between the emulator and the host computer. Table 3.4 lists the host computer interface specifications.

The system program can be loaded to the E8000 station memory with the bidirectional parallel interface. At this time, confirm that the printer driver is specified by the PC settings. Use a host computer to which the bidirectional parallel interface can be applied. See section 3.7, System Program Installation.

Table 3.4 Host Computer Interface Specifications

Item	Specifications
Signal level	RS-232C High: +5 to +15 V Low: –5 to –15 V
Transfer rate	2400/4800/9600/19200/38400 bits per second (BPS)
Synchronization method	Asynchronous method
Start-bit length	1 bit
Data-bit length	7/8 bits
Stop-bit length	1/2 bits
Parity	Even/odd or none
Control method	X-ON/X-OFF control, RTS/CTS control

Host Computer Interface Settings at Emulator Start Up: When the emulator is turned on, or when the emulator system program is initiated, the host computer interface settings are determined by the console interface switches in the same way as in the console interface (the control method will be X-ON/X-OFF control).

Changing the Host Computer Interface Settings: The transfer rate, data-bit length, stop-bit length, parity, and control method can be changed with the console interface switch. For the host computer connector pin assignments and signal names, refer to Appendix A, Connectors.

3.3.6 Connecting to a LAN Interface

⚠ **WARNING**

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

The LAN board for the emulator supports Ethernet (10BASE5) and Cheapernet (10BASE2) interfaces conforming to Ethernet specifications V.2.0. The LAN board communicates with a workstation according to the TCP/IP protocol, and the workstation transfers files and commands according to the FTP/TELNET protocol. The LAN board specifications at each layer of the OSI model are as follows.

Physical and Data Link Layers: The LAN board communicates with Ethernet and Cheapernet. Table 3.5 shows the Ethernet and Cheapernet specifications.

Table 3.5 Ethernet and Cheapernet Specifications

Item	Ethernet	Cheapernet
Transfer rate	10 Mbits/second	10 Mbits/second
Maximum distance between segments	500 m	185 m
Maximum network length	2500 m	925 m
Maximum number of nodes in one segment	100	30
Minimum distance between nodes	2.5 m	0.5 m
Network cable	Diameter: 0.4 inch (1.02 cm) 50-Ω shielded coaxial cable	Diameter: 0.25 inch (0.64 cm) 50-Ω shielded coaxial cable (RG-58A/U)
Network connector	N-type connector	BNC connector
Transceiver cable	Diameter: 0.38 inch (0.97 cm) Ethernet cable to be connected to the 15-pin D-SUB connector	

Network Layer:

- IP (Internet Protocol)
  - Transmits and receives data in datagram format.
  - Does not support IP options.
  - Does not have subnet mask functions when HS7000ELN01H is used. Supports subnet mask functions when HS7000ELN02H is used.
  - Does not support broadcast communications.
- ICMP (Internet Control Message Protocol)

  Supports only echo reply functions.
- ARP (Address Resolution Protocol)

  Calculates Ethernet addresses from IP addresses by using broadcast communications.

Transport Layer:

- TCP (Transmission Control Protocol)

  Logically connects the emulator to the workstation.
- UDP (User Datagram Protocol)

  Not supported.

Session, Presentation, and Application Layers:

- FTP (File Transfer Protocol)

  The emulator operates as a client.
- TELNET (Teletype Network)

  The emulator operates as a server.

Note: The emulator communicates through routers or gateways for the HS7000ELN02H, but not for the HS7000ELN01H.

3.3.7 System Connection Examples

⚠ **WARNING**

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

System configuration examples are shown below.

Ethernet Interface: The LAN board of the emulator has a 15-pin D-SUB connector for the Ethernet transceiver cables. Figure 3.14 shows an example of the Ethernet system configuration. Use commercially available Ethernet transceivers and transceiver cables. Table 3.6 shows a recommended transceiver and transceiver cable.

Note: When using the LAN interface, refer to section 3.5.1, Power-On Procedures for LAN Interface, and set the IP address.

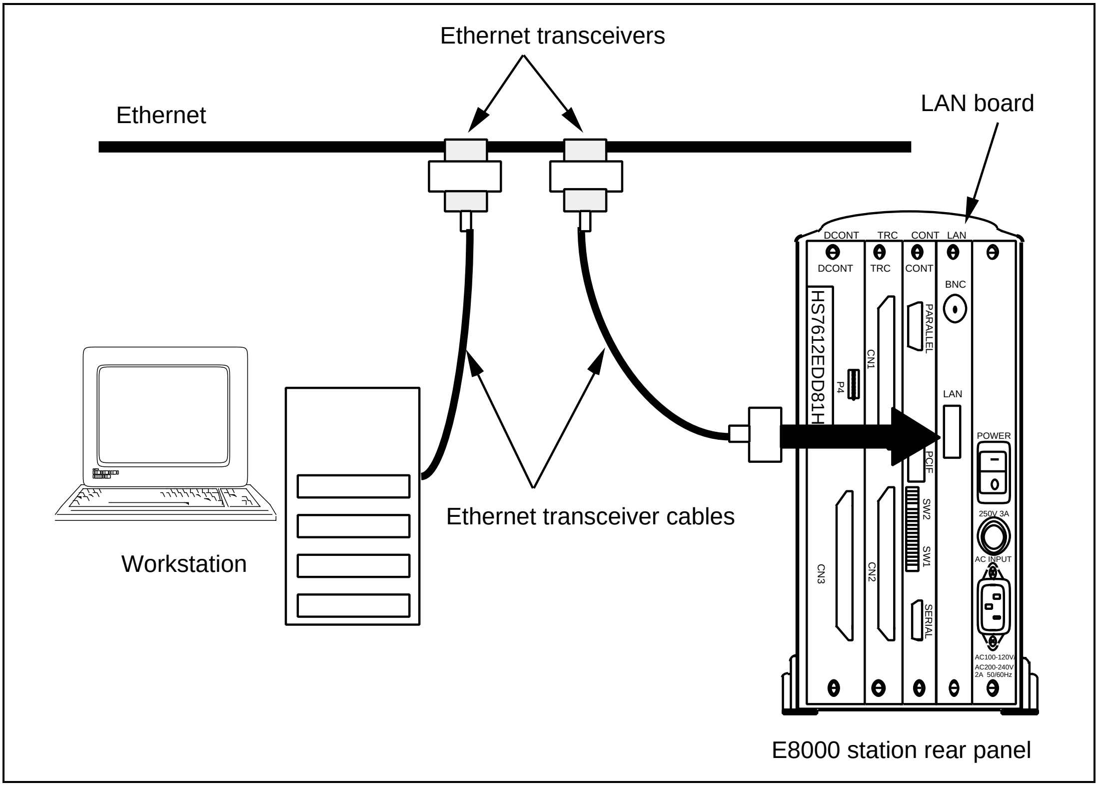


Figure 3.14 Ethernet Interface

Table 3.6 Recommended Transceiver and Transceiver Cable

Item	Product Type	Manufacturer
Transceiver	HBN-200 series	Hitachi Cable, Ltd.
Transceiver cable	HBN-TC-100	Hitachi Cable, Ltd.

For setting up the Ethernet interface, refer to the LAN board user’s manual.

Cheapernet Interface: The LAN board of the emulator incorporates a transceiver and a BNC connector for a Cheapernet interface. Figure 3.15 shows an example of the Cheapernet system configuration. Use a commercially available Cheapernet BNC T-type connector with a characteristic impedance of 50 Ω and a RG-58A/U thin-wire cable or its equivalent. Table 3.7 shows a recommended BNC T-type connector and thin-wire cable.

Note: If a connector or a cable with a characteristic impedance other than 50 Ω is used, the impedance mismatch will cause incorrect data transmission and reception.

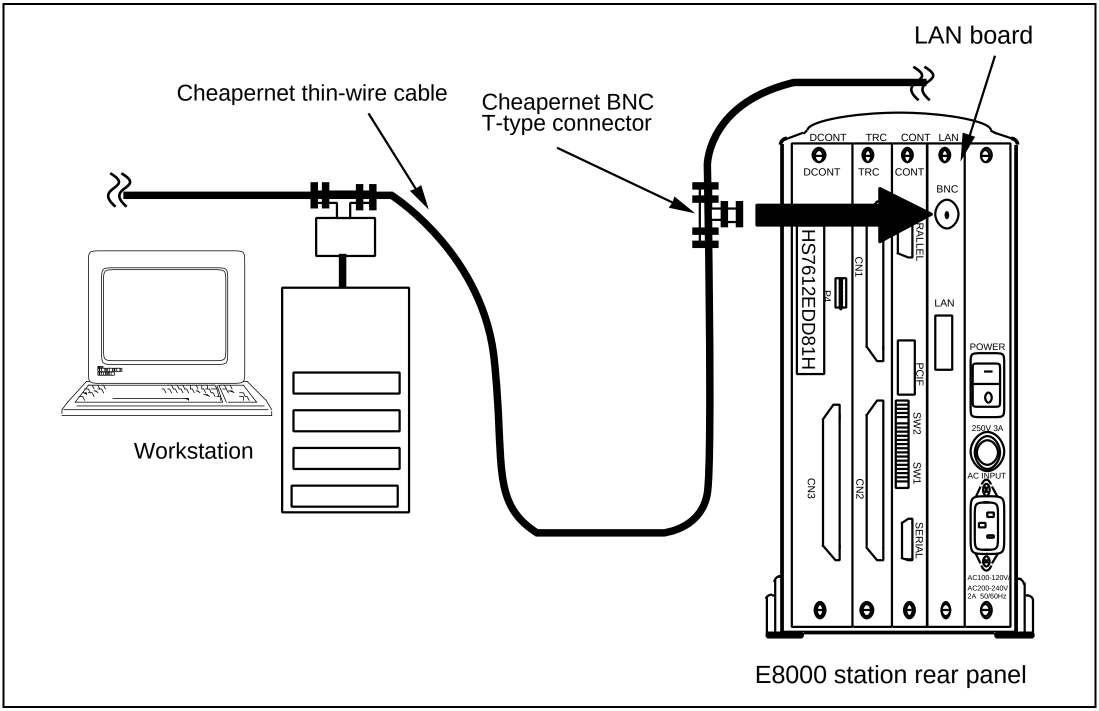


Figure 3.15 Cheapernet Interface

Table 3.7 Recommended BNC T-Type Connector and Thin-Wire Cable

Item	Product Type	Manufacturer
BNC T-type connector	HBN-TA-JPJ	Hitachi Cable, Ltd.
Thin-wire cable	HBN-3D2V-LAN	Hitachi Cable, Ltd.

For setting up Cheapernet, refer to the LAN board user’s manual.

RS-232C Interface: Figure 3.16 shows the E8000 station connected to the host computer via an RS-232C for a serial interface.

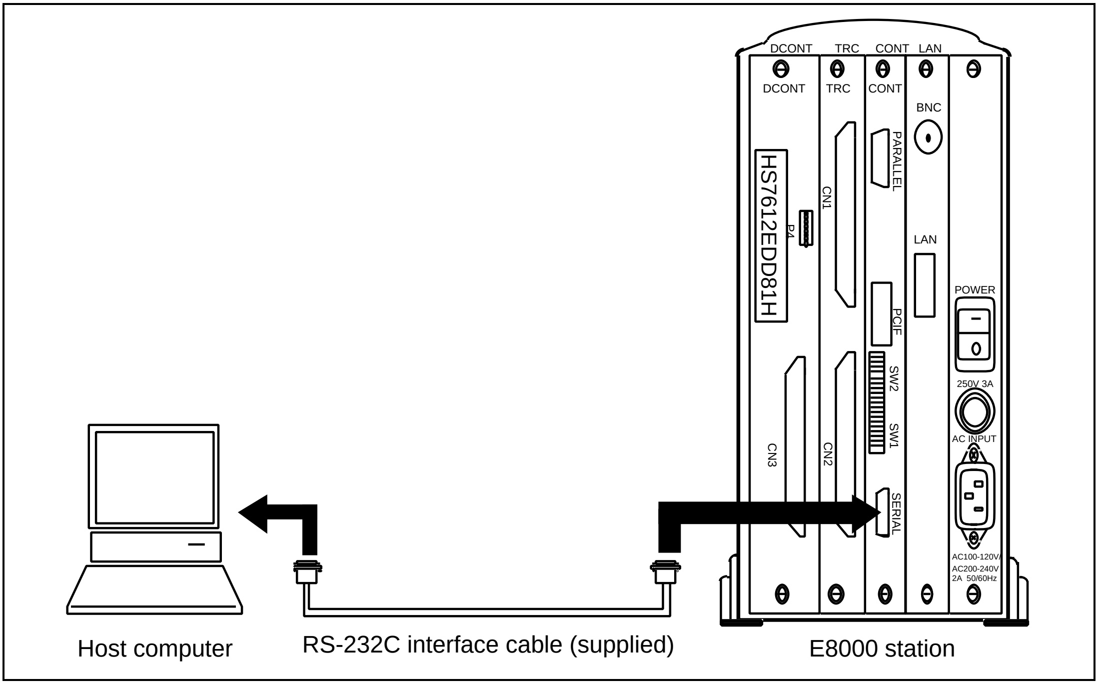


Figure 3.16 RS-232C Interface

Parallel Interface: Figure 3.17 shows the E8000 station connected to a host computer via a parallel cable for a parallel interface. When using the parallel interface, connect not only the parallel interface cable but also the RS-232C cable. It is impossible to use only the bidirectional parallel interface cable. The parallel interface enables higher-speed installation of the system program and higher-speed load, save, or verification of the user program as compared with the RS-232C interface.

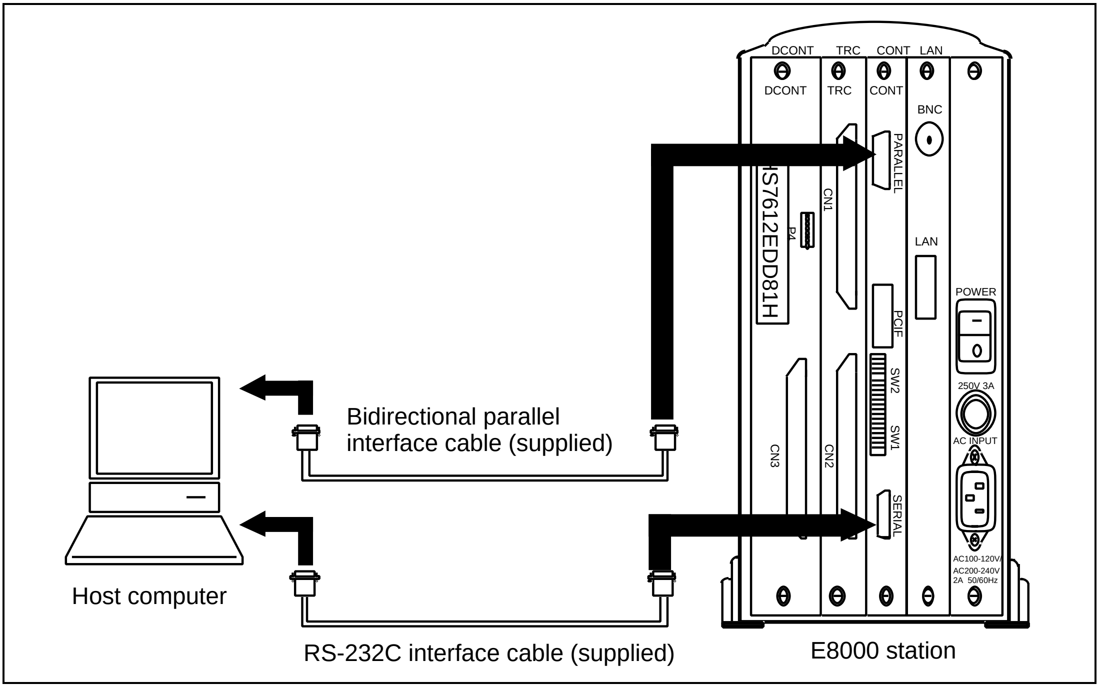


Figure 3.17 Bidirectional Parallel Interface

3.4 Operation Procedures of Interface Software IPW

Interface software IPW is used when the emulator is connected to the host computer via the RS-232C interface. Interface software IPW runs on Microsoft Windows version 3.1 or Windows95.

3.4.1 Installation and Initiation of Interface Software IPW

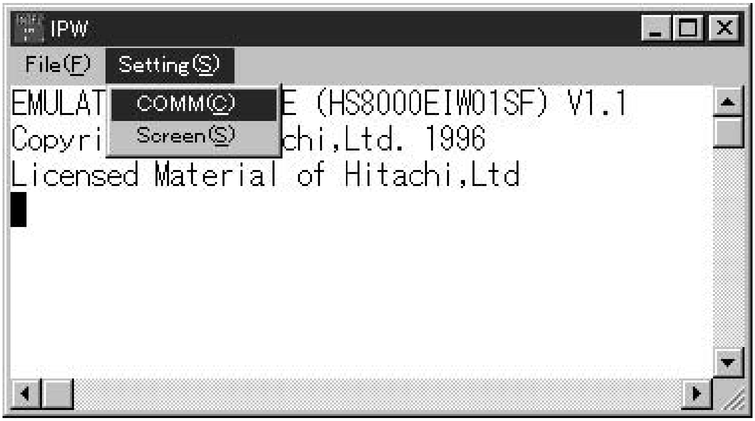
Make a copy of file IPW.EXE in the system disk to a folder. The directory containing the copied folder will become the current directory. Double clicking the IPW icon initiates interface software IPW and displays the IPW window shown in figure 3.18.

```
EMULATOR INTERFACE (HS8000EIW01SF) V1.1
Copyright(C) Hitachi,Ltd. 1996
Licensed Material of Hitachi,Ltd
```

Figure 3.18 IPW Window

3.4.2 Interface Software IPW Settings

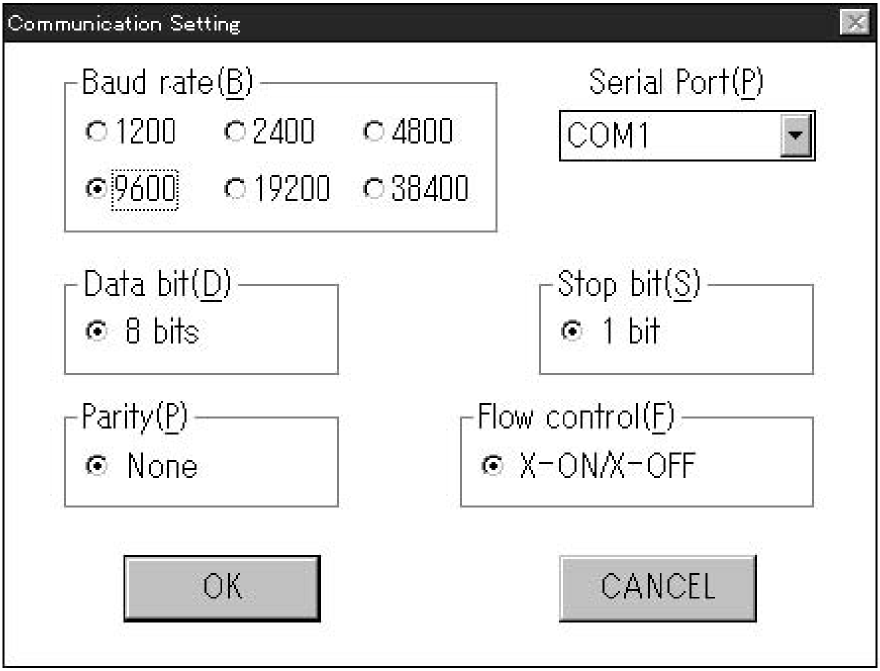
The procedures for operating interface software IPW are shown in the following. Figure 3.19 shows the File menu and Setting menu locations in the interface software IPW display.



EMULAT E (HS8000EIW01SF) V1.1
Copyri chi,Ltd. 1996
Licensed Material of Hitachi,Ltd

Figure 3.19 File Menu and Setting Menu

1. Clicking COMM in the Setting menu displays the Communication Setting box (figure 3.20). The Communication Setting box can also be displayed by pressing (Alt) + S keys and then the C key. Set the communications conditions to be the same as those of the DIP switches on the E8000 station rear panel.



Communication Setting

Baud rate(B)
○ 1200 ○ 2400 ○ 4800
● 9600 ○ 19200 ○ 38400

Serial Port(P): COM1

Data bit(D): ● 8 bits

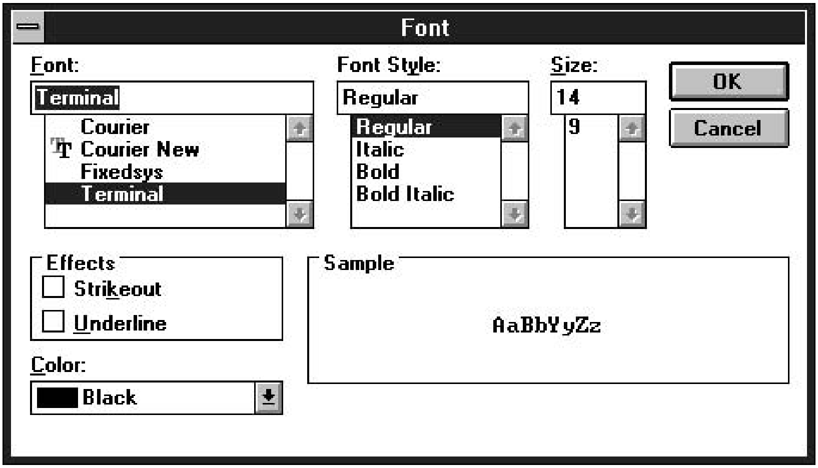
Stop bit(S): ● 1 bit

Parity(P): ● None

Flow control(F): ● X-ON/X-OFF

Figure 3.20 Communication Setting Box

2. Selecting Screen in the Setting menu displays the Screen Setting box (figure 3.21). The Screen Setting box can also be displayed by pressing (Alt) + S keys and then the S key.



Font: Terminal

Font Style: Regular

Size: 14

Effects

☐ Strikeout

☐ Underline

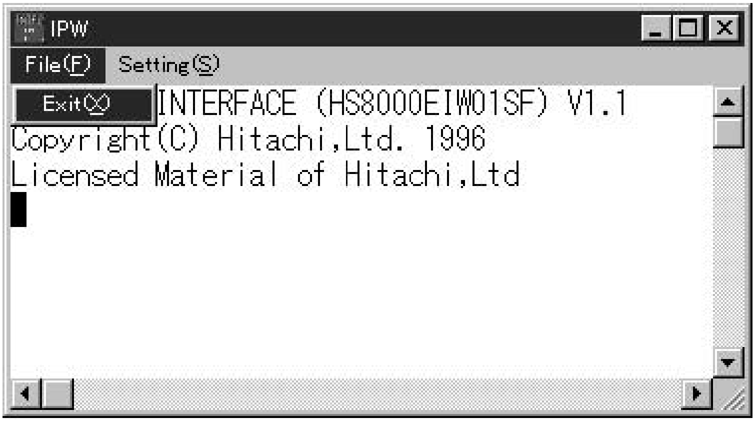
Color: Black

Sample

AaBbYyZz

Figure 3.21 Screen Setting Box

3. Clicking Exit in the File menu terminates interface software IPW. Interface software IPW can also be terminated by pressing (Alt) + F keys and then the X key (figure 3.22). Note that in the following conditions a termination request is ignored and interface software IPW will not be terminated.
   - File transfer between the emulator and host computer
   - Automatic command input from a file



```
INTERFACE (HS8000EIW01SF) V1.1
Copyright(C) Hitachi,Ltd. 1996
Licensed Material of Hitachi,Ltd
```

Figure 3.22 Exit Menu

Note: Set communication setting and screen setting in the Setting menu immediately after IPW initiation because they are not saved at IPW termination.

3.4.3 Debugging Support Functions

Interface software IPW supports the following two debugging functions.

- Automatic command input from a host computer file
- Logging acquisition

The start of automatic command input or start and end of logging acquisition can be specified when the emulator is in command input wait state (the emulator prompt is # or :).

Automatic Command Input: The file from which commands are to be input (command file) is specified with < and <file name> when the emulator is in command input wait state. Do not insert a space between < and <file name>.
Example: :***<FILENAME (RET)***
Commands are sequentially read from the specified command file and transferred to the emulator. As in the following example, when the command file is specified, commands in that file are sequentially executed. Commands requiring further input, such as the MEMORY command, can be read from a file and executed.

Example:
File contents:

```
f 1000000 103ffff 0;w
m 1000000;1
aaaaaaaa
55555555
12345678
.
d 1000000;1
```

Execution results:

```
:f 1000000 103ffff 0;1
:m 1000000;1
 01000000   00000000 ? aaaaaaaa
 01000004   00000000 ? 55555555
 01000008   00000000 ? 12345678
 0100000C   00000000 ? .
:d 1000000;1
<ADDRESS>           <   D   A   T   A   >     <ASCII CODE>
01000000 AAAAAAAA 55555555 12345678 00000000 “....UUUU.4Vx....”
01000010 00000000 00000000 00000000 00000000 “................”
01000020 00000000 00000000 00000000 00000000 “................”
```

The command file reading does not terminate until the end of the file is detected, or the (CTRL) + C keys are pressed. If the (CTRL) + C keys are pressed, the command being executed is terminated and the message below is displayed. According to the input reply, command file reading is continued or terminated.

```
INTFC ERROR - STOP COMMAND CHAIN? (Y/N) : (a) (RET)
          (a)    Y:   Terminate
                 N:   Continue
```

Logging: When logging acquisition is specified, not only are command inputs, execution results, and error messages afterwards the specification displayed on the console, but they are output to the file specified with FILENAME.
Logging is specified with > and characters when the emulator is in command input wait state. Do not insert a space between > and characters.

- To overwrite FILENAME:

  :>***FILENAME (RET)***
- To add to FILENAME:

  :>>***FILENAME (RET)***
- To terminate logging to FILENAME:

  :>***- (RET)***

To overwrite the existing file, enter Y when the following message is displayed.

```
INTFC ERROR - FILE ALREADY EXISTS
          OVERWRITE? (Y/N) : (a) (RET)
               (a)    Y:   Overwrites the existing file with the new file
                      N:   Terminates command execution
```

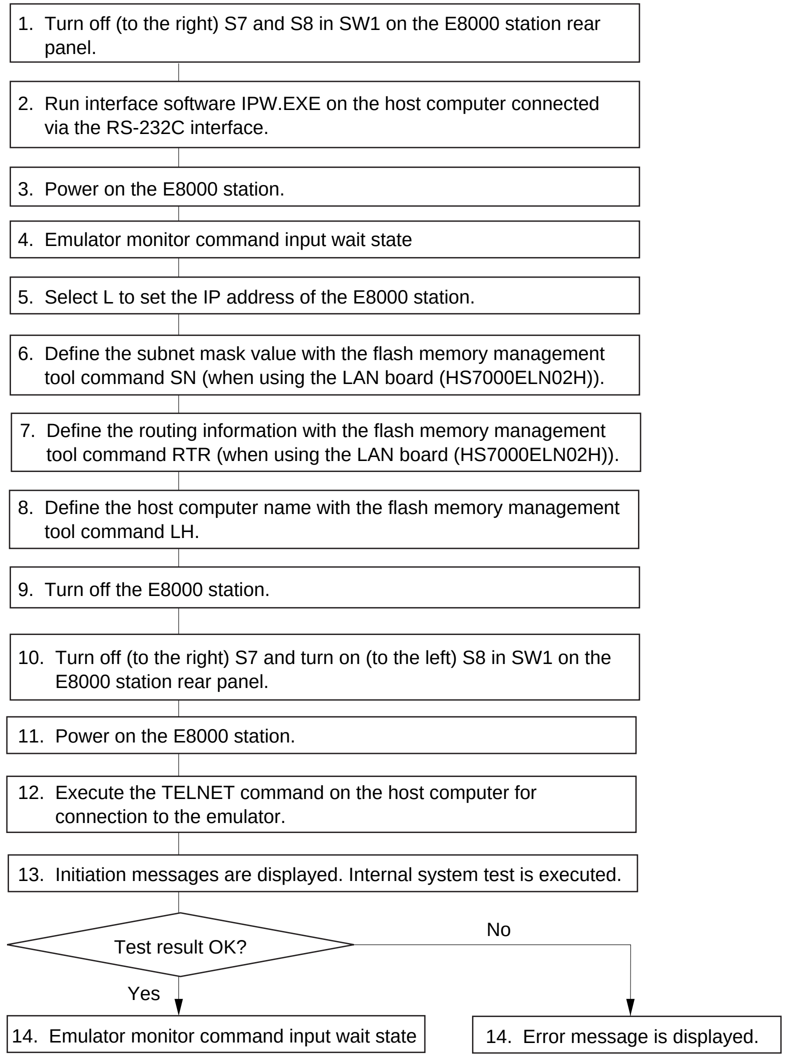
Addresses during load, save, or verification cannot be logged.

3.5 Power-On Procedures for Emulator

The emulator power-on procedures differ in each system configuration. Power on the emulator in the appropriate way for the system configuration, as shown below.

3.5.1 Power-On Procedures for LAN Interface

Figure 3.23 shows the power-on procedures when the LAN interface is used.



1. Turn off (to the right) S7 and S8 in SW1 on the E8000 station rear panel.
2. Run interface software IPW.EXE on the host computer connected via the RS-232C interface.
3. Power on the E8000 station.
4. Emulator monitor command input wait state
5. Select L to set the IP address of the E8000 station.
6. Define the subnet mask value with the flash memory management tool command SN (when using the LAN board (HS7000ELN02H)).
7. Define the routing information with the flash memory management tool command RTR (when using the LAN board (HS7000ELN02H)).
8. Define the host computer name with the flash memory management tool command LH.
9. Turn off the E8000 station.
10. Turn off (to the right) S7 and turn on (to the left) S8 in SW1 on the E8000 station rear panel.
11. Power on the E8000 station.
12. Execute the TELNET command on the host computer for connection to the emulator.
13. Initiation messages are displayed. Internal system test is executed.

14. Emulator monitor command input wait state

14. Error message is displayed.

Figure 3.23 Power-On Procedures for LAN Interface

The following describes the power-on procedures when using the LAN interface.

1. Check that S7 and S8 in console interface switch SW1 on the E8000 station rear panel are turned off (to the right).

2. Run interface software IPW.EXE on the host computer connected to the emulator via the RS-232C interface.

3. Turn on the power switch at the E8000 station rear panel.

4. The emulator waits for an emulator monitor command.

5. Specify the emulator IP address.

   The optional LAN board supports the TCP/IP protocol. When the host computer is connected to the emulator via the LAN interface, the IP address (internet address) of the emulator must be specified with emulator monitor command L.

   Press L and then the (RET) key. The set IP address is displayed. Make sure the IP address is correct. The 32-bit IP address, which is generally expressed in hexadecimal, is displayed in four bytes in decimal. For example, when the IP address has been specified as H'80010101 (H' represents hexadecimal), the emulator will display the IP address as follows and wait for a new IP address input.

   ```
   : IP ADDRESS = 128.1.1.1  :  _
   ```

   Enter a new IP address to change the displayed IP address. When changing the IP address with emulator monitor command L, restart the emulator.

   The host name and IP address of the emulator must be specified in the network database for the host computer. Normally, the network management tool of the host computer is used. For details, refer to the host computer user's manual.

6. Define the subnet mask value when using the LAN board (HS7000ELN02H).

   When the F command (flash memory management tool initiation) is entered while the emulator waits for an emulator monitor command, the emulator displays prompt FM> and waits for a flash memory management tool command (refer to table 3.9).

   ```
   START E8000
     S:START E8000
     F:FLASH MEMORY TOOL
     L:SET LAN PARAMETER
     T:START DIAGNOSTIC TEST
       (S/F/L/T) ?  F (RET)
   FM>
   ```

   Next define the subnet mask value.

```
FM>  SN <subnet mask value>;C (RET)
```

Enter Q (RET) to terminate the flash memory management tool.

```
FM>  Q (RET)
```

7. Set the routing information with the flash memory management tool command RTR when the LAN board HS7000ELN02H is used to connect the host computer in a different network to the emulator. A maximum of ten routing information can be defined. Enter the number to be defined, and then the IP address and the network number of the router.

```
FM> RTR (RET)
*** NO ENTRY DATA
PLEASE SELECT NO. (1–10/L/E/Q/X) ? 1 (RET)
01  IP ADDRESS                    ? <router IP address> (RET)
01  NET ID                        ? <network number> (RET)
```

Enter E (RET) and terminate the RTR command to enable the input contents and save the settings in the emulator.

```
PLEASE SELECT NO. (1–10/L/E/Q/X) ?  E (RET)
LAN CONFIGURATION FILE WRITE OK (Y/N) ?  Y (RET)
FM>_
```

Enter Q (RET) to terminate the flash memory management tool.

```
FM> Q (RET)
```

8. Store the host name and IP address of the host computer in the emulator.

   To transfer data between the host computer and emulator, initiate the FTP server to connect the host computer to the emulator. Before the FTP server is initiated, the host name and IP address of the host computer must be stored in the emulator flash memory. The following describes how to specify the host name and IP address.

   When the F command (flash memory management tool initiation) is entered while the emulator waits for an emulator monitor command, the emulator displays prompt FM> and waits for a flash memory management tool command (refer to table 3.9).

```
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ?  F (RET)
FM>
```

Next enter the LH command, and the following message is displayed.

```
FM>  LH (RET)
 NO    <HOST NAME>    <IP ADDRESS>       NO    <HOST NAME>   <IP ADDRESS>
 01       xxxxxx      xxx.xxx.xxx.xxx    02       xxxxxx     xxx.xxx.xxx.xxx
 03       xxxxxx      xxx.xxx.xxx.xxx    04       xxxxxx     xxx.xxx.xxx.xxx
 05       xxxxxx      xxx.xxx.xxx.xxx    06       xxxxxx     xxx.xxx.xxx.xxx
 07       xxxxxx      xxx.xxx.xxx.xxx    08       xxxxxx     xxx.xxx.xxx.xxx
 09       xxxxxx      xxx.xxx.xxx.xxx
       E8000 IP ADDRESS = xxx.xxx.xxx.xxx
PLEASE SELECT NO.(1-9/L/E/Q/X) ? _
```

Up to nine pairs of host names and IP addresses can be specified. Input a number from 1 to 9. The emulator prompts the host name. Enter a name with up to 15 characters. After that, the emulator prompts the IP address.

```
PLEASE SELECT NO.(1-9/L/E/Q/X) ? 1 (RET)
01 HOST NAME   xxxxxx   <name of host computer> (RET)
01 IP ADDRESS   xxx.xxx.xxx.xxx   <IP address of host computer> (RET)
```

After the IP address has been specified, the emulator will prompt for another selection number. When connecting more than one host computer, continue specifying the host names and IP addresses. To confirm the specifications, enter L (RET) as follows.

```
PLEASE SELECT NO.(1-9/L/E/Q/X) ? L (RET)
 NO    <HOST NAME>    <IP ADDRESS>       NO    <HOST NAME>   <IP ADDRESS>
 01       xxxxxx      xxx.xxx.xxx.xxx    02       xxxxxx     xxx.xxx.xxx.xxx
 03       xxxxxx      xxx.xxx.xxx.xxx    04       xxxxxx     xxx.xxx.xxx.xxx
 05       xxxxxx      xxx.xxx.xxx.xxx    06       xxxxxx     xxx.xxx.xxx.xxx
 07       xxxxxx      xxx.xxx.xxx.xxx    08       xxxxxx     xxx.xxx.xxx.xxx
 09       xxxxxx      xxx.xxx.xxx.xxx
       E8000 IP ADDRESS = xxx.xxx.xxx.xxx
PLEASE SELECT NO.(1-9/L/E/Q/X) ? _
```

To terminate input, enter E, Q, or X followed by (RET).

Entering E (RET) saves the new specifications in the emulator flash memory, initiates the LAN board, and terminates LH command execution.

```
PLEASE SELECT NO.(1-9/L/E/Q/X) ? E (RET)
LAN CONFIGURATION FILE WRITE OK (Y/N) ? Y (RET)
FM>
```

Entering Q (RET) saves the new specifications in the emulator flash memory without initializing the LAN board, and terminates LH command execution.

```
PLEASE SELECT NO.(1-9/L/E/Q/X) ? Q (RET)
LAN CONFIGURATION FILE WRITE OK (Y/N) ? Y (RET)
FM>
```

Entering X (RET) terminates LH command execution without saving the new specifications.

```
PLEASE SELECT NO.(1-9/L/E/Q/X) ? X (RET)
FM>
```

When the emulator waits for a flash memory management tool command (prompt FM>), entering Q (RET) terminates the flash memory management tool.

```
FM>  Q (RET)
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

9. Turn off the E8000 station.

10. Check that S7 and S8 in console interface switch SW1 on the E8000 station rear panel are turned off (to the right) and on (to the left), respectively.

11. Turn on the power switch at the E8000 station rear panel.

12. Execute the TELNET command on the host computer.

13. The following messages are displayed and the internal system tests are executed.

```
E8000 MONITOR (HS8000EST02SR) Vm.n
Copyright (C) Hitachi, Ltd. 1995
Licensed Material of Hitachi, Ltd.

TESTING
  RAM           0123
```

14. If no error occurs, the emulator waits for an emulator monitor command.

```
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
      (S/F/L/T) ? _
```

Refer to section 3.6.1, Emulator Monitor Initiation, for details on operations after emulator power-on and section 3.8, E8000 System Program Initiation, for details on emulator system initiation.

3.5.2 Power-On Procedures for RS-232C Interface

Figure 3.24 shows the power-on procedures when the RS-232C interface is used.

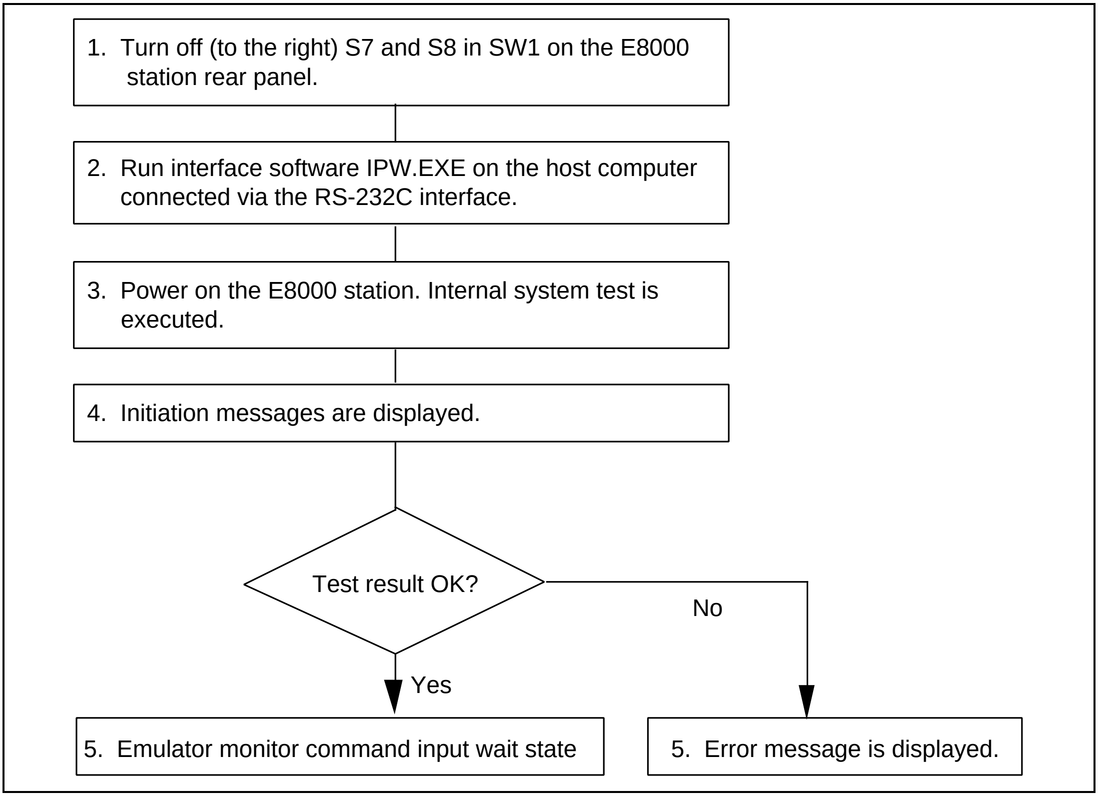


Figure 3.24 Power-On Procedures for RS-232C Interface

Refer to section 3.6.1, Emulator Monitor Initiation, for details on operations after emulator power-on and section 3.8, E8000 System Program Initiation, for details on emulator system initiation.

3.6 Emulator Monitor Commands

3.6.1 Emulator Monitor Initiation

The emulator supports the four monitor commands listed in table 3.8. These commands initiate the E8000 system program, manage flash memory, set an IP address for LAN interface, and execute the diagnostic program. After turned on, the emulator displays the following monitor initiation message and waits for an emulator monitor command input.

Display Message:

```
E8000 MONITOR (HS8000EST02SR) Vm.n
Copyright (C) Hitachi, Ltd. 1995
Licensed Material of Hitachi, Ltd.

TESTING
  RAM          0123

START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
      (S/F/L/T) ? _
```

Table 3.8 Emulator Monitor Commands

Command	Function
S	E8000 system program initiation
F	Flash memory management tool initiation
L	Emulator IP address setting
T	Diagnostic program initiation

3.6.2 S [S] Initiates the E8000 system program

Command Format

- Initiation S (RET)

Description

- Initiation

  Initiates the E8000 system program.

Example

To initiate the E8000 system program:

```
START E8000
 S:START E8000
 F:FLASH MEMORY TOOL
 L:SET LAN PARAMETER
 T:START DIAGNOSTIC TEST
    (S/F/L/T) ? S (RET)

 SH7612 E8000 (HS7612EDD81SF) Vm.n
 Copyright (C) Hitachi, Ltd. 1997
 Licensed Material of Hitachi, Ltd.

 CONFIGURATION FILE LOADING
 HARDWARE REGISTER READ/WRITE CHECK
 FIRMWARE SYSTEM LOADING
 EMULATOR FIRMWARE TEST
 ** RESET BY E8000 !
 CLOCK = EML
 MPU TYPE = SH7612
 MODE = 00 (MD4-0=1F)
 REMAINING EMULATION MEMORY S=4MB
:
```

3.6.3 F [F] Initiates the flash memory management tool

Command Format

- Flash memory management tool F (RET)

Description

- Flash memory management tool

  Initiates the flash memory management tool. The flash memory management tool can use the commands listed in table 3.9.

Table 3.9 Flash Memory Management Tool Commands

Command	Function
DIR	Displays system file loading status
LH	Defines the host name and IP address of the host computer to be connected
Q	Terminates the flash memory management tool
RTR	Defines routing information for remote network
SL	Loads the E8000 system program
SN	Defines the subnet mask value

Note: The RTR and SN commands can be used only when the LAN board HS7000ELN02H is used.

Example

To initiate the flash memory management tool:

```
START E8000
 S:START E8000
 F:FLASH MEMORY TOOL
 L:SET LAN PARAMETER
 T:START DIAGNOSTIC TEST
    (S/F/L/T) ? F (RET)
FM>
```

DIR [DIR] Displays system file loading status

Command Format

- Display DIR (RET)

Description

- Display

  Displays system-file loading status. Displays OK for correctly loaded system file, NG for abnormally loaded on, and NO for not loaded.

Example

To display system file loading status:

```
FM>DIR (RET)
 <FILE ID> <STATUS>
  SYS       OK
  CONF      OK
  LAN       NO
  FIRM      OK
  TRON      NO
  DIAG      OK
  INI       OK
  MON       OK
FM>
```

LH [LH] Defines the host name and IP address of the host computer

Command Format

- Definition LH (RET)

Description

- Definition

  Defines the host name and IP address of the host computer. Enter the host name and IP address as follows after the specified number is entered and the emulator prompts them:

```
PLEASE SELECT NO. (1–9/L/E/Q/X) ? <definition number> (RET)
01  HOSTNAME xxxxxx                 <host name> (RET)
01  IP ADDRESS xxx.xxx.xxx.xxx       <IP address> (RET)
```

- Display

  Entering L (RET) displays the list of the defined host computer.

- Initiation

  Entering E (RET) saves the new specifications in the emulator flash memory, and initiates the LAN board. Entering Q (RET) saves the new specifications in the emulator flash memory without initializing the LAN board, and terminates LH command execution. Entering X (RET) terminates LH command execution without saving the new specifications.

Example

To define the host name of the host computer as host and its IP address as 128.1.1.1:

```
FM>LH (RET)
 PLEASE SELECT NO.(1-9/L/E/Q/X) ? 1 (RET)
 01 HOST NAME xxxxxx           host (RET)
 01 IP ADDRESS xxx.xxx.xxx.xxx 128.1.1.1 (RET)
 PLEASE SELECT NO.(1-9/L/E/Q/X) ? L (RET)
 NO <HOST NAME> <IP ADDRESS>      NO <HOST NAME> <IP ADDRESS>
 01  host        128.1.1.1        02
 03                               04
 05                               06
 07                               08
 09
     E8000 IP ADDRESS = xxx.xxx.xxx.xxx
 PLEASE SELECT NO.(1-9/L/E/Q/X) ? E (RET)
 LAN CONFIGURATION FILE WRITE OK (Y/N) ? Y (RET)
FM>
```

Q [Q] Terminates the flash memory management tool

Command Format

- Termination Q (RET)

Description

- Termination

  Terminates the flash memory management tool.

Example

To terminate the flash memory management tool:

```
FM>Q (RET)
START E8000
 S:START E8000
 F:FLASH MEMORY TOOL
 L:SET LAN PARAMETER
 T:START DIAGNOSTIC TEST
    (S/F/L/T) ?
```

RTR [RTR] Defines the remote network routing information

Command Format

- Definition RTR (RET)

Description

- Definition

  Defines the remote network routing information. Enter the IP address and network number as follows after the specified number is entered and the emulator prompts them:

  FM> ***RTR (RET)***
   PLEASE SELECT NO. (1–10/L/E/Q/X) ? <***definition number***> ***(RET)***
   IP ADDRESS ? ***<router IP address> (RET)***
   NET ID ? <***network number***> ***(RET)***

- Display

  Entering L (RET) displays the list of the defined host computer.

- Initiation

  Entering E (RET) saves the new specifications in the emulator flash memory, and initiates the LAN board. Entering Q (RET) saves the new specifications in the emulator flash memory without initializing the LAN board, and terminates LH command execution. Entering X (RET) terminates LH command execution without saving the new specifications.

Example

To define router IP address 128.1.2.1 for network number 128.1.2.0 as the routing information:

```
FM>RTR (RET)
 PLEASE SELECT NO.(1-10/L/E/Q/X) ? 1 (RET)
 IP ADDRESS                       ? 128.1.2.1 (RET)
 NET ID                           ? 128.1.2.0 (RET)
 PLEASE SELECT NO.(1-10/L/E/Q/X) ? L (RET)
 NO <IP-ADDRESS>     <NET-ID>           NO <IP-ADDRESS>   <NET-ID>
 01  128.1.2.1        128.1.2.0         02
 PLEASE SELECT NO.(1-10/L/E/Q/X) ? E (RET)
 LAN CONFIGURATION FILE WRITE OK (Y/N) ? Y (RET)
FM>
```

SL [SL] Loads the system program

Command Format

- Load SL (RET)

Description

- Load
  Loads the system program.

Example

To load the system program:

```
FM>SL (RET)
 SELECT LOAD No. (1:PC or 2:WS) ? 1 (RET)
 SELECT INTERFACE (1:RS-232C or 2:PARALLEL) ? 2 (RET)
 LOAD E8000 SYSTEM FILE OK (Y/N) ? Y (RET)
 INPUT COMMAND : #B:\E8000.SYS (RET)
 LOAD CONFIGURATION FILE OK (Y/N) ? Y (RET)
 INPUT COMMAND : #B:\SHCNF761.SYS (RET)
 LOAD FIRMWARE FILE OK (Y/N) ? Y (RET)
 INPUT COMMAND : #B:\SHDCT761.SYS (RET)
 LOAD ITRON DEBUGGER FILE OK (Y/N) ? N (RET)
 LOAD DIAGNOSTIC FILE OK (Y/N) ? N (RET)
FM>
```

SN [SN] Defines the subnet mask value

Command Format

- Definition SN <subnet mask value>;[C] (RET)
- Display SN (RET)

Description

- Definition

  Defines the subnet mask value.

  ```
  FM>SN <subnet mask value> (RET)
  FM>
  ```

- Save

  Saves the setting specifications in the E8000 station when the C option is specified.

  ```
  FM>SN <subnet mask value>; C (RET)
   LAN CONFIGURATION FILE WRITE OK (Y/N) ? Y (RET)
  FM>
  ```

- Display

  Displays the subnet mask value.

  ```
  FM>SN (RET)
   SUB-NET-MASK xxx. xxx. xxx. xxx (H’xx. H’xx. H’xx. H’xx)
  ```

Examples

1. To define 255.255.255.0 as the subnet mask value and save the setting specifications in the E8000 station:

   ```
   FM>SN 255.255.255.0;C (RET)
    LAN CONFIGURATION FILE WRITE OK (Y/N) ? Y (RET)
   FM>
   ```

2. To display the subnet mask value:

   ```
   FM>SN (RET)
    SUB-NET-MASK 255.255.255.0  (H’FF.H’FF.H’FF.H’00)
   FM>
   ```

3.6.4 L [L] Sets the emulator IP address

Command Format

- Setting L (RET)

Description

- Setting
  Sets the emulator IP address.

Example

To set the IP address of the E8000 station to 128.1.1.1:

```
START E8000
 S:START E8000
 F:FLASH MEMORY TOOL
 L:SET LAN PARAMETER
 T:START DIAGNOSTIC TEST
    (S/F/L/T) ? L (RET)

E8000 IP ADDRESS = 0.0.0.0 : 128.1.1.1 (RET)
```

3.6.5 T [T] Initiates the diagnostic program

Command Format

- Initiation T (RET)

Description

- Initiation

  Initiates the diagnostic program.

Example

To initiate the emulator diagnostic program:

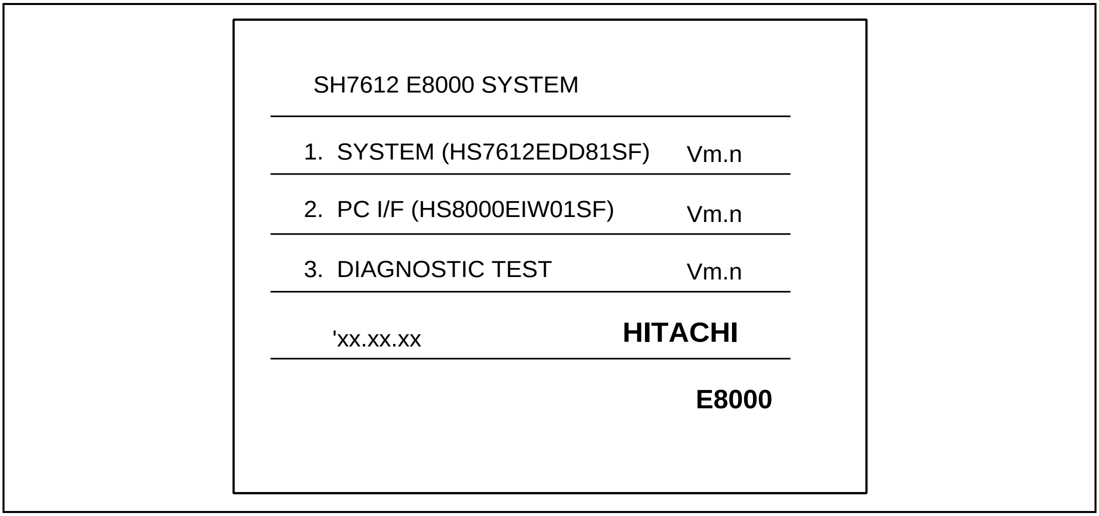
```
START E8000
 S:START E8000
 F:FLASH MEMORY TOOL
 L:SET LAN PARAMETER
 T:START DIAGNOSTIC TEST
    (S/F/L/T) ? T (RET)
```

(The diagnostic program is then initiated.)

3.7 System Program Installation

3.7.1 E8000 System Disk

The emulator contains one floppy disk.



SH7612 E8000 SYSTEM

1. SYSTEM (HS7612EDD81SF) Vm.n
2. PC I/F (HS8000EIW01SF) Vm.n
3. DIAGNOSTIC TEST Vm.n

'xx.xx.xx **HITACHI**

E8000

Figure 3.25 E8000 System Disk

The E8000 system disk with a 1.44-Mbyte format is for PC. This floppy disk contains the following six files:

- E8000.SYS
- SHCNF761.SYS
- SHDCT761.SYS
- SETUP.CC
- IPW.EXE
- DIAG.SYS

E8000.SYS, SHCNF761.SYS, and SHDCT761.SYS are system programs that must be installed to the emulator flash memory with emulator monitor command F (flash memory management tool initiation). SETUP.CC is a file for writing the system programs via the parallel interface. IPW.EXE is a file containing interface software that runs on Microsoft Windows version 3.1 or Windows95 and must be installed to the host computer memory.

3.7.2 Installation

To use the emulator, the E8000 system program must be installed in the emulator flash memory. Load the E8000 system program to flash memory with the system program writing file or with the flash memory management tool using the emulator monitor commands.

Automatic System Program Load by Bidirectional Parallel Interface: If the emulator is connected to the host computer via the bidirectional parallel interface and the E8000 system disk is inserted in drive A of the host computer, the E8000 system program can be automatically loaded with the system program writing file SETUP.CC in the following procedures. It takes approximately one minute.

Operations **Display Message**

1. Initiate IPW in the E8000 system floppy disk.
2. Power on the emulator. For details on the power-on procedures, refer to section 3.5.2, Power-On Procedures for RS-232C Interface.
3. Emulator monitor command prompt

```
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

4. Enter <A:\SETUP.CC (RET) in the monitor command input wait state.

```
(S/F/L/T) ? <A:\SETUP.CC (RET)
```

5. After the system program writing file completes loading the system program, the emulator re-enters the monitor command input wait state.

```
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

6. Installation is completed.

Manual System Program Load by Bidirectional Parallel Interface: To use the emulator, files E8000.SYS, SHCNF761.SYS, and SHDCT761.SYS must be installed in the emulator flash memory.

If the emulator is connected to the host computer via the bidirectional parallel interface, the E8000 system program can be loaded with the following procedures. Note that the E8000 system disk is assumed to be inserted in drive A of the host computer. It takes approximately one minute.

Operations — **Display Message**

1. Initiate IPW in the E8000 system floppy disk.
2. Power on the emulator. For details on the power-on procedures, refer to section 3.5.2, Power-On Procedures for RS-232C Interface.
3. Emulator monitor command prompt

```
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

4. Enter F (RET) to initiate the flash memory management tool. The emulator displays prompt FM> and waits for a flash memory management tool command.

```
(S/F/L/T) ? F (RET)
FM>
```

5. Enter SL (RET) to load the system program.

```
FM> SL (RET)
```

6. Enter 1 (RET) to select PC as the host computer type, and 2 (RET) to select parallel interface as the interface method.

```
 SELECT LOAD No. (1:PC or 2:WS) ? 1 (RET)
 SELECT INTERFACE (1:RS-232C or 2:PARALLEL) ? 2 (RET)
```

7. Enter Y (RET) to allow system program E8000.SYS to be loaded. Then enter the parallel transfer command to load E8000.SYS in the current directory on the PC to the emulator flash memory.

```
 LOAD E8000 SYSTEM FILE OK (Y/N) ? Y (RET)
 INPUT COMMAND : #B:A:\E8000.SYS (RET)

:COMPLETED
```

Operations

Display Message

8. Enter Y (RET) to allow configuration file SHCNF761.SYS to be loaded. Then enter the parallel transfer command to load SHCNF761.SYS in the current directory on the PC to the emulator flash memory.

```
 LOAD CONFIGURATION FILE OK (Y/N) ? Y (RET)
 INPUT COMMAND : #B:A:\SHCNF761.SYS (RET)

:COMPLETED
```

9. Enter Y (RET) to allow firmware file SHDCT761.SYS to be loaded. Then enter the parallel transfer command to load SHDCT761.SYS in the current directory on the PC to the emulator flash memory.

```
 LOAD FIRMWARE FILE OK (Y/N) ? Y (RET)
 INPUT COMMAND : #B:A:\SHDCT761.SYS (RET)

:COMPLETED
```

10. Enter N (RET) not to load the ITRON debugger.

```
 LOAD ITRON DEBUGGER FILE OK (Y/N) ? N (RET)
```

11. Enter N (RET) not to load the diagnostic program.

```
 LOAD DIAGNOSTIC FILE OK (Y/N) ? N (RET)
```

12. Enter DIR (RET) to check whether the necessary files have been loaded.

```
FM>DIR (RET)
  <FILE ID> <STATUS>
   SYS       OK
   CONF      OK
   LAN       NO
   FIRM      OK
   TRON      NO
   DIAG      NO
   INI       OK
   MON       OK
```

13. Enter Q (RET) to terminate the flash memory management tool.

```
FM>Q (RET)
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

14. Installation is completed.

Manual System Program Load by RS-232C Interface: To use the emulator, files E8000.SYS, SHCNF761.SYS, and SHDCT761.SYS must be installed in the emulator flash memory.

If the emulator is connected to the host computer via the RS-232C interface, the E8000 system program can be loaded with the following procedures. Note that the E8000 system disk is assumed to be inserted in drive A of the host computer. It takes approximately 20 minutes.

Operations — **Display Message**

1. Initiate IPW in the E8000 system floppy disk.
2. Power on the emulator. For details on the power-on procedures, refer to section 3.5.2, Power-On Procedures for RS-232C Interface.
3. Emulator monitor command prompt

```
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

4. Enter F (RET) to initiate the flash memory management tool. The emulator displays prompt FM> and waits for a flash memory management tool command.

```
(S/F/L/T) ? F (RET)
FM>
```

5. Enter SL (RET) to load the system program.

```
FM> SL (RET)
```

6. Enter 1 (RET) to select PC as the host computer type, and 1 (RET) to select RS-232C (serial) interface as the interface method.

```
SELECT LOAD No. (1:PC or 2:WS) ? 1 (RET)
SELECT INTERFACE (1:RS-232C or 2:PARALLEL) ? 1 (RET)
```

7. Enter the directory containing the system file. In this example, A:\ (RET) is entered.

```
INPUT SYSTEM DIRECTORY : A:\ (RET)
```

8. Enter Y (RET) to allow system program E8000.SYS to be loaded in the emulator flash memory. Then enter system program file name E8000.SYS.

```
LOAD E8000 SYSTEM FILE OK (Y/N) ? Y (RET)
INPUT FILE NAME : E8000.SYS (RET)
COMPLETED
```

Operations **Display Message**

9. Enter Y (RET) to allow configuration file SHCNF761.SYS to be loaded in the emulator flash memory. Then enter configuration file name SHCNF761.SYS.

```
 LOAD CONFIGURATION FILE OK (Y/N) ? Y (RET)
 INPUT FILE NAME : SHCNF761.SYS (RET)
 COMPLETED
```

10. Enter Y (RET) to allow firmware file SHDCT761.SYS to be loaded in the emulator flash memory. Then enter firmware file name SHDCT761.SYS.

```
 LOAD FIRMWARE FILE OK (Y/N) ? Y (RET)
 INPUT FILE NAME : SHDCT761.SYS (RET)
 COMPLETED
```

11. Enter N (RET) not to load the ITRON debugger.

```
 LOAD ITRON DEBUGGER FILE OK (Y/N) ? N (RET)
```

12. Enter N (RET) not to load the diagnostic program.

```
 LOAD DIAGNOSTIC FILE OK (Y/N) ? N (RET)
```

13. Enter DIR (RET) to check whether the necessary files have been loaded.

```
FM> DIR (RET)
  <FILE ID> <STATUS>
   SYS       OK
   CONF      OK
   LAN       NO
   FIRM      OK
   TRON      NO
   DIAG      NO
   INI       OK
   MON       OK
```

14. Enter Q (RET) to terminate the flash memory management tool.

```
FM> Q (RET)

START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

15. Installation is completed.

Manual System Program Load by LAN Interface: To use the emulator, files E8000.SYS, SHCNF761.SYS, and SHDCT761.SYS must be installed in the emulator flash memory.

If the emulator is connected to the host computer via the LAN interface, the E8000 system program can be loaded with the following procedures. Transfer all files on the system floppy disk to the host computer using the FTP before installation. For details on the transfer method, refer to the host-computer user’s manual. It takes approximately one minute.

Operations — **Display Message**

1. Power on the emulator. For details on the power-on procedures, refer to section 3.5.1, Power-On Procedures for LAN Interface. Confirm the emulator monitor command prompt is displayed.

```
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

2. Enter F (RET) to initiate the flash memory management tool. The emulator displays prompt FM> and waits for a flash memory management tool command.

```
(S/F/L/T) ? F (RET)
FM>
```

3. Enter SL (RET) to load the system program.

```
FM> SL (RET)
```

4. Enter 2 (RET) to select WS as the host computer type since the LAN interface is used.

```
 SELECT LOAD No. (1:PC or 2:WS) ? 2 (RET)
```

5. Enter the host computer name. In this example, hostname is entered.

```
 INPUT SYSTEM LOADING HOST NAME : hostname (RET)
```

6. Enter the user name. In this example, username is entered.

```
 INPUT USER NAME : username (RET)
```

7. Enter the password. In this example, password is entered.

```
 INPUT PASS WORD : password (RET)
```

8. Enter the directory containing the system file. In this example, (RET) is entered to select the current directory of the host computer.

```
 INPUT SYSTEM DIRECTORY : (RET)
```

9. Enter Y (RET) to allow system program E8000.SYS to be loaded in the emulator flash memory. Then enter system program file name E8000.SYS.

```
 LOAD E8000 SYSTEM FILE OK (Y/N) ? Y (RET)
 INPUT FILE NAME : E8000.SYS (RET)
 COMPLETED
```

Operations | **Display Message**

10. Enter Y (RET) to allow configuration file SHCNF761.SYS to be loaded in the emulator flash memory. Then enter configuration file name SHCNF761.SYS.

```
LOAD CONFIGURATION FILE OK (Y/N) ? Y (RET)
INPUT FILE NAME : SHCNF761.SYS (RET)
COMPLETED
```

11. Enter Y (RET) to allow firmware file SHDCT761.SYS to be loaded in the emulator flash memory. Then enter firmware file name SHDCT761.SYS.

```
LOAD FIRMWARE FILE OK (Y/N) ? Y (RET)
INPUT FILE NAME : SHDCT761.SYS (RET)
COMPLETED
```

12. Enter N (RET) not to load the ITRON debugger.

```
LOAD ITRON DEBUGGER FILE OK (Y/N) ? N (RET)
```

13. Enter N (RET) not to load the diagnostic program.

```
LOAD DIAGNOSTIC FILE OK (Y/N) ? N (RET)
```

14. Enter DIR (RET) to check whether the necessary files have been loaded.

```
FM> DIR (RET)
  <FILE ID> <STATUS>
   SYS       OK
   CONF      OK
   LAN       NO
   FIRM      OK
   TRON      NO
   DIAG      NO
   INI       OK
   MON       OK
```

15. Enter Q (RET) to terminate the flash memory management tool.

```
FM> Q (RET)

START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

16. Installation is completed.

3.8 E8000 System Program Initiation

When the emulator is turned on while S4 in DIP SW1 is turned off (to the right) and a manual system program load method is selected, the emulator enters monitor command input wait state, and the E8000 system program must be loaded and initiated by monitor commands. If S4 in DIP SW1 has been turned on (to the left) and the automatic system program load method is selected, the E8000 system program is automatically loaded and initiated.

3.8.1 Initiation on Emulator Monitor

If S is entered, followed by (RET), when the emulator is in monitor command input wait state, the E8000 system program in the emulator flash memory is initiated.

Display at E8000 System Program Initiation:

```
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
      (S/F/L/T) ? S (RET)

  SH7612 E8000 (HS7612EDD81SF) Vm.n
  Copyright (C) Hitachi, Ltd. 1997
  Licensed Material of Hitachi, Ltd.

  CONFIGURATION FILE LOADING
  HARDWARE REGISTER READ/WRITE CHECK
  FIRMWARE SYSTEM LOADING
  EMULATOR FIRMWARE TEST
  ** RESET BY E8000 !
  CLOCK = EML
  MCU TYPE = SH7612
  MODE = 00 (MD4-0=1F)
  REMAINING EMULATION MEMORY S=4MB
:
```

3.8.2 Automatic Initiation of E8000 System Program

If S4 in DIP SW1 has been turned on (to the left) and the automatic system program load method is selected, the E8000 system program is automatically loaded and initiated, and the emulator waits for an emulation command.

Display at Power On:

(Power on)

```
  E8000 MONITOR (HS8000EST02SR) Vm.n
  Copyright (C) Hitachi, Ltd. 1995
  Licensed Material of Hitachi, Ltd.

  TESTING
  RAM           0123

  SH7612 E8000 (HS7612EDD81SF) Vm.n
  Copyright (C) Hitachi, Ltd. 1997
  Licensed Material of Hitachi, Ltd.

  CONFIGURATION FILE LOADING
  HARDWARE REGISTER READ/WRITE CHECK
  FIRMWARE SYSTEM LOADING
  EMULATOR FIRMWARE TEST
  ** RESET BY E8000 !
  CLOCK = EML
  MCU TYPE = SH7612
  MODE = 00 (MD4-0=1F)
  REMAINING EMULATION MEMORY S=4MB
:
```

If the E8000 system program is automatically initiated without being loaded to the emulator flash memory, after displaying an error message, the emulator enters monitor command input wait state. Make sure to load the E8000 system program to the emulator flash memory before initiation.

```
  *** E8000 SYSTEM PROGRAM NOT FOUND
START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

Section 4 Operating Examples

4.1 Emulator Operating Examples

This section covers explanations on how to operate the emulator using examples. Sections 4.2, Basic Examples and 4.3, Application Examples are based on the following user program. These examples assume that the emulator is connected to the host computer by a LAN interface and is used with a TELNET connection.

```
  ADDR      CODE          MNEMONIC    OPERAND
01001000    E00A          MOV         #0A,R0
01001002    E101          MOV         #01,R1
01001004    E201          MOV         #01,R2
01001006    D405          MOV.L       0100101C,R4
01001008    6323          MOV         R2,R3
0100100A    321C          ADD         R1,R2
0100100C    2426          MOV.L       R2,@-R4
0100100E    6133          MOV         R3,R1
01001010    70FF          ADD         #FF,R0
01001012    8800          CMP/EQ      #00,R0
01001014    8BF8          BF          01001008
01001016    0009          NOP
01001018    AFFE          BRA         01001018
0100101A    0009          NOP
0100101C    0F10          .DATA.W     0100
0100101E    0000          .DATA.W     FFFC
```

Store the user program in the host computer before initiating the emulator and download it to the emulator. In these examples, the IP address is set to 128.1.1.1.

CAUTION

In these examples, the IP address is set to 128.1.1.1 to 128.1.1.10. For the actual host computer, an IP address available on the network connected to the emulator must be specified. If an unavailable IP address is specified, the network will have problems.

4.2 Basic Examples

4.2.1 Preparing for Connection of the LAN Host Computer

The following host name and IP address are examples. Specify the actual host computer name and IP address of the host computer.

Operations / **Display Message**

1. Specify the host name and IP address of the host computer to which the emulator is to be connected by the LAN interface. Enter the F command to initiate the flash memory management tool in the monitor command input wait state.

```
START E8000
 S:START E8000
 F:FLASH MEMORY TOOL
 L:SET LAN PARAMETER
 T:START DIAGNOSTIC TEST
   (S/F/L/T) ? F (RET)
FM>_
```

2. Enter LH (RET) to store the host name and IP address of the host computer.

```
FM>LH (RET)
NO <HOST NAME> <IP ADDRESS>       NO <HOST
01                                02
03                                04
05                                06
07                                08
09
    E8000 IP ADDRESS = 128.1.1.1
PLEASE SELECT NO.(1-9/L/E/Q/X) ? _
```

3. Enter 1 as the selection number, HITACHI (RET) as the host name, and 128.1.1.10 (RET) as the IP address. After that, the emulator prompts the user to select another number.

```
PLEASE SELECT NO.(1-9/L/E/Q/X) ? 1 (RET)
01 HOST NAME  HOST_A    ? HITACHI (RET)
01 IP ADDRESS 128.1.1.1 ? 128.1.1.10 (RET)
PLEASE SELECT NO.(1-9/L/E/Q/X) ? _
```

4. Enter E (RET) to enable the settings and to exit interactive mode.

```
PLEASE SELECT NO.(1-9/L/E/Q/X) ? E (RET)
```

5. The emulator confirms whether to save the settings in the configuration file with the above settings.

```
LAN CONFIGURATION FILE WRITE OK (Y/N) ? _
```

6. Enter Y (RET) to save the settings.

```
CONFIGURATION FILE WRITE OK (Y/N) ? Y (RET)
FM>
```

Operations **Display Message**

7. Enter Q (RET) to terminate the flash memory management tool and enter the monitor command input wait state.

```
FM>Q (RET)

 START E8000
  S:START E8000
  F:FLASH MEMORY TOOL
  L:SET LAN PARAMETER
  T:START DIAGNOSTIC TEST
     (S/F/L/T) ? _
```

8. Enter S (RET) to re-initiate the emulator. The emulator is re-initiated, and waits for an emulation command.

```
     (S/F/L/T) ? S (RET)

SH7612 E8000 (HS7612EDD81SF) Vm.n
 Copyright (C) Hitachi, Ltd. 1997
 License Material of Hitachi, Ltd.

 CONFIGURATION FILE LOADING
 HARDWARE REGISTER READ/WRITE CHECK
 FIRMWARE SYSTEM LOADING
 EMULATOR FIRMWARE LOADING
 EMULATOR FIRMWARE TEST
 ** RESET BY E8000 !
 CLOCK = EML
 MCU TYPE = SH7612
 MODE = 00 (MD4-0=1F)
 REMAINING EMULATION MEMORY S=4MB
:
```

4.2.2 Specifying the SH7612 Operating Mode

Specify the emulator operating mode by the following procedures:

Operations — **Display Message**

1. Enter MODE;C (RET) to specify the emulator operating mode.

   ```
   :MODE;C (RET)
   ```

2. The message shown on the right is displayed.

   ```
   E8000 MD(MD4-0) = xx(MD=00) ? _
   ```

3. To select operating mode H’10 of the SH7612, for example, enter 10 (RET).

   ```
   E8000 MD(MD4-0) = xx(MD=00) ? 10 (RET)
   ```

4. After the above entry has been completed, the emulator asks if the mode settings should be stored in the flash memory. To store the mode settings, enter Y (RET). After that, the emulator operates in the mode specified above whenever initiated. If N (RET) is entered, MODE command execution terminates without storing the mode settings, and the emulator enters emulation command input wait state.

   ```
   CONFIGURATION STORE (Y/N) ? Y (RET)
   ```

5. After the above specification has been completed, the E8000 system program automatically terminates and must be re-initiated.

   ```
   START E8000
     S:START E8000
     F:FLASH MEMORY TOOL
     L:SET LAN PARAMETER
     T:START DIAGNOSTIC TEST
       (S/F/L/T) ? _
   ```

6. Enter S (RET) to re-initiate the E8000 system program.

   ```
       (S/F/L/T) ? S (RET)
   ```

4.2.3 Allocating Standard Emulation Memory and Specifying Attributes

To load the user program to memory and run the user program, allocate standard emulation memory by the following procedures:

Operations | **Display Message**

1. Enter MAP 1000000 10FFFFF;S (RET) to allocate standard emulation memory to addresses H'1000000 to H'10FFFFF.

```
:MAP 1000000 10FFFFF;S (RET)
```

2. The message shown on the right, which indicates that memory allocation has been completed, is displayed.

```
REMAINING EMULATION MEMORY S=3MB
```

3. Enter MAP (RET) to display the attributes of all the memory areas.

```
:MAP (RET)
 01000000-010FFFFF;S 21000000-210FFFFF;S
 X-RAM AREA   = 1000E000-1000FFFF
 Y-RAM AREA   = 1001E000-1001FFFF
 INTERNAL I/O = FFFF8000-FFFFBFFF FFFFFC00-
 REMAINING EMULATION MEMORY S=3MB
:
```

4.2.4 Loading the User Program

Connect the emulator to the host computer using the FTP server and load the user program by the following procedures. This example assumes that in host computer HITACHI, the user name is defined as E8000 and its password as PASSWORD.

Operations	**Display Message**
1. Enter FTP HITACHI (RET) to connect the emulator to the host computer using the FTP server.	`:FTP HITACHI (RET)`
2. The emulator asks for the user name. Enter E8000 (RET).	`Username: E8000 (RET)`
3. The emulator asks for the password. Enter PASSWORD (RET).	`Password: PASSWORD (RET)`
4. The message shown on the right, which indicates that the emulator and the host computer have been connected is displayed. The prompt becomes FTP>.	`login command success` `FTP>`
5. To load program PROGRAM.MOT, enter LAN_LOAD ;S:PROGRAM.MOT (RET). This example assumes that the load module is S type.	`FTP> LAN_LOAD ;S:PROGRAM.MOT (RET)`
6. While loading, the address to which the program is being loaded is displayed, as shown on the right.	`LOADING ADDRESS = xxxxxxxx`
7. When the program has been loaded, the start address of the program (TOP ADDRESS) and its end address (END ADDRESS) are displayed.	`TOP ADDRESS = 01001000` `END ADDRESS = 0100101F`

8. Entering BYE (RET) terminates the FTP server connection. The message shown on the right is displayed.	`FTP>BYE (RET)`
	`bye command success`
	`:`

4.2.5 Executing the Program

Execute the loaded program by the following procedures:

Operations **Display Message**

1. Set the initial values of the registers. Enter .SP (RET) to set the stack pointer (SP register) to H'0100FFFC.

```
:.SP (RET)
 R15(SP)=xxxxxxxx ? 0100FFFC (RET)
 PC=xxxxxxxx ? _
```

2. The emulator asks for the program counter value. Enter 1001000 (RET) as the program counter value.

```
 PC=xxxxxxxx ? 1001000 (RET)
```

3. The emulator then asks for the status register value. In this example, other registers need not to be set or changed, therefore, enter . (RET) to exit this interactive mode.

```
 SR=xxxxxxxx ? . (RET)
```

4. Enter GO (RET) to execute the loaded program from the address pointed to by the PC. While the program is executed, the current program counter value is displayed.

```
:GO (RET)

**PC=01001010
```

5. Enter the (BREAK) key to terminate program execution.

```
(BREAK)
PC=01001010 SR=000000F0:****000000000000****----
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=0000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=0000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=0000
 RUN-TIME=D’0000H:00M:00S:000018US:000NS
 +++:BREAK KEY
:
```

Operations	Display Message
6. The contents of the program counter, status register, control registers, general registers R0 to R15, and DSP registers are displayed at GO command termination. RUN-TIME shows the duration of program execution from GO command execution to (BREAK) key entry. BREAK KEY shows that execution has been terminated because the (BREAK) key was entered.	

4.2.6 Setting a Software Breakpoint

Execution of the GO command can be stopped immediately before executing a particular address by setting a software breakpoint by the following procedures:

Operations — **Display Message**

1. Enter BREAK 1001010 (RET) to terminate the GO command immediately before executing the instruction at address H'1001010.

```
:BREAK 1001010 (RET)
```

2. Restart program execution from address H'1001000. This can be done in two ways: one is to first set the program counter to H'1001000, then enter the GO command to execute the program, and the other is to enter the start address directly.

```
:.PC 1001000 (RET)
:GO (RET)

or

:GO 1001000 (RET)
```

3. The GO command execution terminates immediately before the instruction at address H'1001010 is executed. The data shown on the right is displayed. BREAKPOINT shows that the GO command execution was terminated due to a software breakpoint.

```
PC=01001010 SR=000000F0:****000000000000****----
GBR=00000000 VBR=00000000 MACH=00000000 MACL=0000
RS=00000000 RE=00000000 MOD=00000000
R0-7  00000001 000000FF 00000011 00000000 00000000
R8-15 00000000 00000000 00000000 00000000 00000000
DSR=00000000:************************----COB-
A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=0000
A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=0000
RUN-TIME=D’0000H:00M:00S:000018US:000NS
+++:BREAKPOINT
:
```

4.2.7 Executing a Single Step

A single step can be executed using the single-step function by the following procedures:

Operations | **Display Message**

1. The program counter points to the next address to be executed when the GO command terminates. Entering STEP (RET) here executes only a single instruction.

```
:STEP (RET)
```

2. The information shown on the right is displayed. 01001010 ADD #FF,R0 shows the address and mnemonic code executed by the STEP command, and STEP NORMAL END shows that single-step execution has terminated.

```
 PC=01001012 SR=000000F0:****000000000000****
 GBR=00000000 VBR=00000000 MACH=00000000 MACL
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 00000000 00000000 00000000 00
 R8-15 00000000 00000000 00000000 00000000 00
 DSR=00000000:************************----COB
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y
 01001010              ADD       #FF,R0
 +++:STEP NORMAL END
 :
```

3. To repeat single-step execution, enter only (RET). This can be repeated until another command is executed.

```
:(RET)
 PC=01001014 SR=000000F0:****000000000000****
 GBR=00000000 VBR=00000000 MACH=00000000 MACL
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 00000000 00000000 00000000 00
 R8-15 00000000 00000000 00000000 00000000 00
 DSR=00000000:************************----COB
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y
 01001012              CMP/EQ    #00,R0
 +++:STEP NORMAL END
```

4.2.8 Setting Hardware Break Conditions

Various hardware break conditions can be specified by the following procedures:

Operations | **Display Message**

1. Enter BREAK- (RET) to cancel the software breakpoint.

```
:BREAK- (RET)
```

2. To confirm the cancellation, execute the BREAK command (enter BREAK (RET)). *** 45: NOT FOUND shows that no software breakpoint is set.

```
:BREAK (RET)
 ***45:NOT FOUND
:
```

3. To specify that program execution should terminate when data is written to address H'100FFF8, enter BREAK_CONDITION_UBC1 A=100FFF8 W (RET).

```
:BREAK_CONDITION_UBC1 A=100FFF8 W (RET)
```

4. Enter GO 1001000 (RET) to start executing the program from address H'1001000.

```
:GO 1001000 (RET)
```

5. When the break condition is satisfied, the information shown on the right is displayed. BREAK CONDITION UBC1 shows that GO command execution has terminated because the break condition was satisfied.

```
PC=01001012 SR=000000F0:****000000000000****
GBR=00000000 VBR=00000000 MACH=00000000 MACL
RS=00000000 RE=00000000 MOD=00000000
R0-7  00000000 00000000 00000000 00000000 00
R8-15 00000000 00000000 00000000 00000000 00
DSR=00000000:************************----COB
A0G=00 A0=00000000 M0=00000000 X0=00000000 Y
A1G=00 A1=00000000 M1=00000000 X1=00000000 Y
RUN-TIME=D’0000H:00M:00S:000006US:400NS
+++:BREAK CONDITION UBC1
:
```

4.2.9 Displaying Trace Information

Trace information acquired during program execution can be displayed in various ways as follows:

Operations **Display Message**

1. To display the instruction mnemonic information, enter TRACE (RET).

```
:TRACE (RET)
```

```
        IP           ADDR                MNEMONIC      OPERAND
    *-D’000008       01001000            MOV           #0A,R0
    *-D’000007       01001002            MOV           #01,R1
    *-D’000006       01001004            MOV           #01,R2
    *-D’000005       01001006            MOV.L         0100101C,R4
    *-D’000004       01001008            MOV           R2,R3
    *-D’000003       0100100A            ADD           R1,R2
    *-D’000002       0100100C            MOV.L         R2,@-R4
    *-D’000001       0100100E            MOV           R3,R1
    * D’000000       01001010            ADD           #FF,R0
```

2. To display the trace information in bus-cycle units, enter TRACE ;B (RET).

```
:TRACE ;B (RET)
```

```
  BP              AB          DB       MA   RW   STS  IRL   NMI   RES   BRQ   VCC   PRB
  -D’000008   01001000  E00AE101   EXT  R    PRG  1111  1     1     1     1     1111
  -D’000007   01001004  E201D405   EXT  R    PRG  1111  1     1     1     1     1111
 *            01001000                               MOV          #0A,R0
  -D’000006   01001008  6323321C   EXT  R    PRG  1111  1     1     1     1     1111
 *            01001002                               MOV          #01,R1
 *            01001004                               MOV          #01,R2
  -D’000005   0100100C  24266133   EXT  R    PRG  1111  1     1     1     1     1111
 *            01001006                               MOV.L        0100101C,R4
 *            01001008                               MOV          R2,R3
  -D’000004   0100101C  0100FFFC   EXT  R    DAT  1111  1     1     1     1     1111
  -D’000003   01001010  70FF8800   EXT  R    PRG  1111  1     1     1     1     1111
 *            0100100A                               ADD          R1,R2
 *            0100100C                               MOV.L        R2,@-R4
  -D’000002   01001014  8BF80009   EXT  R    PRG  1111  1     1     1     1     1111
 *            0100100E                               MOV          R3,R1
  -D’000001   0100FFF8  00000002   EXT  W    DAT  1111  1     1     1     1     1111
 *            01001010                               ADD          #FF,R0
   D’000000   01001018  AFFE0009   EXT  R    PRG  1111  1     1     1     1     1111
```

Operations	Display Message
3. To temporarily stop the trace information display, enter (CTRL) + S. To continue the trace information display, enter (CTRL) + Q. (CTRL) + S and (CTRL) + Q are also effective with other information displays.	:***TRACE ;B (RET)*** ***(CTRL) + S*** (stops trace information display) ***(CTRL) + Q*** (restarts trace information display)

4.3 Application Examples

4.3.1 Break with Pass Count Condition

The pass count condition can be set to a breakpoint by the following procedures:

Operations **Display Message**

1. Enter BREAK 1001012 5 (RET) to terminate program execution immediately after address H'1001012 is passed five times.

```
:BREAK 1001012 5 (RET)
```

2. To start execution from address H'1001000, enter GO 1001000 (RET).

```
:GO 1001000 (RET)
```

3. When address H'1001012 is passed five times, the data shown on the right is displayed and GO command execution terminates.

```
PC=01001012 SR=000000F0:****000000000000****
GBR=00000000 VBR=00000000 MACH=00000000 MACL=0000
RS=00000000 RE=00000000 MOD=00000000
R0-7  00000001 000000FF 00000011 00000000 00000000
R8-15 00000000 00000000 00000000 00000000 00000000
DSR=00000000:************************----COB--
A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=0000
A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=0000
RUN-TIME=D’0000H:00M:00S:000038US:400NS
+++:BREAKPOINT
:
```

4. Entering BREAK (RET) displays the breakpoint address, the specified count, and the pass count, as shown on the right. The pass count is cleared when the GO command is entered again.

```
:BREAK (RET)
 <ADDR>         <CNT>      <PASS>
 01001012        0005       0005
:
```

4.3.2 Conditional Trace

The acquisition of trace information during program execution can be limited by the following procedures:

Operations — **Display Message**

1. Enter BREAK - (RET) to cancel the breakpoint set in the example of section 4.3.1, Break with Pass Count Condition.

```
:BREAK - (RET)
```

2. Enter TRACE_CONDITION_A1 A=1001010:1001014 ;R (RET) to get trace information only while the program counter is between addresses H'1001010 and H'1001014.

```
:TRACE_CONDITION_A1 A=1001010:1001014;R (RET)
```

3. Enter GO 1001000 (RET) to start executing the program, then the (BREAK) key to terminate the program execution.

```
:GO 1001000(RET)
 ** PC = 01001010

(BREAK)
PC=01001012 SR=000000F0:****000000000000****
GBR=00000000 VBR=00000000 MACH=00000000 MACL
RS=00000000 RE=00000000 MOD=00000000
R0-7  00000000 00000000 00000000 00000000 00
R8-15 00000000 00000000 00000000 00000000 00
DSR=00000000:************************----COB
A0G=00 A0=00000000 M0=00000000 X0=00000000 Y
A1G=00 A1=00000000 M1=00000000 X1=00000000 Y
RUN-TIME=D’0000H:00M:01S:000004US:750NS
+++:BREAK KEY
:
```

4. Enter TRACE ;B (RET) to display the trace information acquired under the specified condition.

```
:TRACE;B (RET)
```

```
     BP         AB         DB       MA    RW    ST    IRL  NMI   RES   BRQ   VCC   PRB
 -D'000039   01001010   70FF8800   EXT   R     PRG   1111  1     1     1     1    1111
 -D'000038   01001014   88F80009   EXT   R     PRG   1111  1     1     1     1    1111
:
```

5. Enter TRACE_CONDITION_A1 - (RET) to cancel the trace acquisition condition.

```
:TRACE_CONDITION_A1 - (RET)
```

4.3.3 Parallel Mode

During program execution in parallel mode, the memory contents can be displayed or modified by the following procedures:

Operations / **Display Message**

1. After executing the GO command, enter (RET) to move to parallel mode.

```
:GO 1001000 (RET)
 ** PC = xxxxxxxx
(RET)
#                         (Moves to parallel mode)
```

2. Enter DUMP 1002000 100200F (RET) to display the memory contents from addresses H'1002000 to H'100200F in parallel mode.

```
#DUMP 1002000 100200F (RET)
              (Dump display)
              . . .
```

3. Enter MEMORY 1001019 FD (RET) to modify the memory contents of address H'1001019 to H’FD in parallel mode.

```
#MEMORY 1001019 FD (RET)
#_
```

4. To exit from parallel mode, enter END (RET).

```
#END (RET)
 ** PC = xxxxxxxx
```

5. To terminate program execution, enter the (BREAK) key.

```
 ** PC = xxxxxxxx
(BREAK)
** PC = xxxxxxxx
PC=01001012 SR=000000F0:****000000000000****
GBR=00000000 VBR=00000000 MACH=00000000 MACL
RS=00000000 RE=00000000 MOD=00000000
R0-7  00000000 00000000 00000000 00000000 00
R8-15 00000000 00000000 00000000 00000000 00
DSR=00000000:************************----COB
A0G=00 A0=00000000 M0=00000000 X0=00000000 Y
A1G=00 A1=00000000 M1=00000000 X1=00000000 Y
RUN-TIME=D’0000H:00M:03S:000034US:750NS
+++:BREAK KEY
: _
```

Operations **Display Message**

6. Enter DISASSEMBLE 1001000 100101F (RET) to confirm that the program has been changed by memory modification in parallel mode.

```
:DISASSEMBLE 1001000 100101F (RET)
```

```
    ADDR         CODE                      MNEMONIC        OPERAND
  01001000      E00A                         MOV           #0A,R0
  01001002      E101                         MOV           #01,R1
  01001004      E201                         MOV           #01,R2
  01001006      D405                         MOV.L         0100101C,R4
  01001008      6323                         MOV           R2,R3
  0100100A      321C                         ADD           R1,R2
  0100100C      2426                         MOV.L         R2,@-R4
  0100100E      6133                         MOV           R3,R1
  01001010      70FF                         ADD           #FF,R0
  01001012      8800                         CMP/EQ        #00,R0
  01001014      8BF8                         BF            01001008
  01001016      0009                         NOP
  01001018      AFFD                         BRA           01001016  (Changed)
  0100101A      0009                         NOP
  0100101C      0F10                         .DATA.W       0101
  0100101E      0000                         .DATA.W       0000
```

4.3.4 Searching Trace Information

A particular part of the acquired trace information can be searched for, using the TRACE_SEARCH command as follows:

Operations	**Display Message**
Enter TRACE_SEARCH A=1001018 (RET) to display the parts of trace information in which the address bus value is H'1001018.	:***`TRACE_SEARCH A=1001018 (RET)`***

```
      BP         AB         DB        MA     RW     ST     IRL   NMI    RES    BRQ    VCC   PRB
 -D'004088   01001018   AFFD0009   EXT    R      PRG    1111   1      1      1      1    1111
 -D'004080   01001018   AFFD0009   EXT    R      PRG    1111   1      1      1      1    1111
 -D'004072   01001018   AFFD0009   EXT    R      PRG    1111   1      1      1      1    1111
              . . .
```

Part II Emulator Function Guide

Section 1 Emulator Functions

1.1 Overview

This emulator is a hardware and software support tool for the development of systems incorporating the SH7612. In addition to a DSP and a high-speed CPU, the SH7612 contains a timer, serial communication interface, an SIO, a DMAC, and Hitachi-UDI (Hitachi-User-Debug-Interface) on the same chip.

Table 1.1 SH7612 Functions

Function		SH7612
Maximum memory size that can be managed		160 Mbytes
Maximum external bus width		32 bits
Cache memory		4 kbytes
Internal RAM		16 kbytes
DMAC		2 channels
Interrupt controller		Five external interrupt sources (NMI and IRL0 to IRL3)
Serial I/O (SIO)		3 channels
Serial communication interface	Asynchronous or clock synchronization	1 channel
Timer	16-bit free running timer	1 channel
I/O port	14 bits	Port A
	16 bits	Port B

The emulator operates in just the same way as the SH7612 on the user system and enables realtime emulation of the user system with functions for debugging hardware and software.

The emulator consists of an emulator station and an evaluation chip board (hereafter called the EV-chip board). The EV-chip board should be connected directly to the user system.

1.2 Specification

The main features of the emulator are its emulation functions and its host computer interface functions, as listed in tables 1.2 and 1.3, respectively.

Table 1.2 Emulation Functions

Command Type	Command	Function	Reference Section
Realtime emulation	GO	Performs realtime emulation in the following cases. The operating frequency is 66 MHz at max. • Executes until a hardware or software break condition is satisfied, or until the (CTRL) + C or (BREAK) key is pressed. • Cycle-reset mode: Executes while the RES signal is sent to the SH7612 at fixed intervals. This mode is effective to observe waveforms after reset. • Parallel mode: Displays trace data and modifies memory contents during emulation.	7.2.21
	EXECUTION_ MODE	Specifies execution mode.	7.2.19
Break condition setting	BREAK_ CONDITION_ UBC	Sets hardware break conditions (1). • Normal break: Execution is forcibly stopped when the specified conditions are satisfied (a maximum of two points). — Address bus value or data bus value (X/Y memory bus) — PC (program counter) value — Read/write condition — Delay/Count — Pass count specification (only for BREAK_CONDITION_UBC1) • Mask specification for address and data conditions — Bit-by-bit specification is enabled for address, PC, or data conditions. • Specification of the satisfaction sequence up to two points	7.2.8

Table 1.2 Emulation Functions (cont)

Command Type	Command	Function	Reference Section
Break condition setting (cont)	BREAK_ CONDITION_ A,B,C	Sets hardware break conditions (2). • Execution is forcibly stopped when the specified conditions are satisfied (a maximum of 24 points). — Address bus value or data bus value — Access type — Read/write condition — Delay count (One channel) — Pass count specification (Eight channels) — External probe value — System control signals — NOT condition • A maximum of seven condition specifications and one reset-point condition specification External probe trigger signal • B channel (eight channels) and UBC (two channels) of SH7612	7.2.7
	BREAK	Sets software break conditions. • Sets up to 255 breakpoints. • Sets pass count.	7.2.6

Table 1.2 Emulation Functions (cont)

Command Type	Command	Function	Reference Section
Trace data acquisition and display	TRACE	Displays execution instruction mnemonic. Displays the following data for each bus cycle: • Address bus value or data bus value • Access area and status • Instruction mnemonic • SH7612 I/O control signals • External probe value • Time stamp (20 ns, 1.6 µs, 52 µs)	7.2.40
	TRACE_ CONDITION_ A,B,C	Sets, displays, and cancels trace condition. • Traces data only when a condition is satisfied. — Address bus value (NOT condition) — Read/write condition — Access type • Stops trace when a trace stop condition is satisfied. — Address bus value or data bus value — Read/write condition — Access type — External probe value — System control signals — NOT condition — Delay count • Subroutine trace	7.2.41

Table 1.2 Emulation Functions (cont)

Command Type	Command	Function	Reference Section
Trace data acquisition and display (cont)	TRACE_CONDITION_A,B,C (cont)	• Low pulse is output from the trigger output terminal when conditions are satisfied. — Address bus value or data bus value — Read/write condition — Access type — External probe value — System control signals — NOT condition — Delay count	7.2.41
	TRACE_SEARCH	Searches for trace data.	7.2.44
	TRACE_MODE	Specifies and displays trace information acquisition mode.	7.2.43
Performance	PERFORMANCE_ANALYSIS1 to 8	A maximum of eight measurement modules Time intervals: 20 ns (6 hours), 406 ns (124 hours), and 1.6 •s (488 hours) A maximum of 65,535 execution count measurements • Subroutine measurement — Subroutine execution count — Access count to specified area in the subroutine — Access count from a subroutine (parent) to another subroutine (child)	7.2.30

Table 1.2 Emulation Functions (cont)

Command Type	Command	Function	Reference Section
Single-step execution	STEP, STEP_OVER, STEP_ INFORMATION	Executes one step at a time, and displays the following. • Instruction mnemonic • Memory contents • Register contents Displays the above data for a specified routine until a specified address is reached. The above operations are performed for a specified number of steps or until a specified address is reached. Specifies information to be displayed during single-step execution. Executes subroutine as a single step.	7.2.37, 7.2.39, 7.2.38
Memory access	MEMORY, DUMP	Displays or modifies memory contents. • Displays or modifies memory contents in 1-, 2-, or 4-byte units. • DUMP displays fixed points of memory contents.	7.2.26, 7.2.17
	MAP	Specifies memory attributes in a 1-Mbyte unit. • User memory • Write protected • Emulation memory Standard: 4 Mbytes	7.2.25
	FILL	Writes data in specified pattern.	7.2.20
	DATA_SEARCH, DATA_CHANGE	Searches for and replaces data in specified pattern.	7.2.15, 7.2.14

Table 1.2 Emulation Functions (cont)

Command Type	Command	Function	Reference Section
Clock selection	CLOCK	• Selects emulator internal clock EML (15 MHz). • Selects user system clock (1 to 33 MHz). • Selects crystal oscillator of EV-chip board (8 to 16.5 MHz).	7.2.11
Register access	REGISTER	Displays and modifies SH7612 register contents.	7.2.33
Line assembly	ASSEMBLE	Assembles instruction mnemonics and specifies memory contents.	7.2.4
Disassembly	DISASSEMBLE	Disassembles memory contents.	7.2.16
Execution time measurement	GO	Measures GO command execution time. • Measures total run time. • Measures execution time from BREAK_CONDITION_UBC2 condition satisfaction to BREAK_CONDITION_UBC1 condition satisfaction.	7.2.21
Test functions	FILL	Reads or writes the specified data to the memory.	7.2.20
	CHECK	Tests SH7612 input signals.	7.2.10
Command input		Enables editing with cursor keys. Copies immediately preceding line. Copies operand of previous command.	
	RADIX	Enables value input in binary, octal, hexadecimal, or ASCII characters. (Default can be specified.)	7.2.32
Results display	RESULT	Displays emulation results.	7.2.35

Table 1.2 Emulation Functions (cont)

Command Type	Command	Function	Reference Section
Others	MOVE, MOVE_TO_RAM	Transfers memory contents. • Memory to memory • ROM (user system memory) to memory	7.2.28, 7.2.29
	CONVERT	Converts number display. • Displays in binary, octal, decimal, hexadecimal, or fixed-point.	7.2.13
	STATUS	Displays emulator operating status.	7.2.36
	GO	Monitors emulation. • Monitors emulation status at constant intervals and displays the emulation status.	7.2.21
	RESET	Inputs RES signal to SH7612.	7.2.34
	MODE	Sets and displays the SH7612 operating mode.	7.2.27
	HELP	Displays all commands.	7.2.22
	HISTORY	Displays the history of the input command.	7.2.23
	ALIAS	Alias function • Defines aliases.	7.2.3
	ID	Displays versions of the system program.	7.2.24
	ABORT	Stops emulation in parallel mode.	7.2.2
	END	Cancels parallel mode.	7.2.18
	QUIT	Quits system program.	7.2.31

Table 1.3 Host Computer Interface Functions

Command Type	Command	Function	Reference Section
Serial interface	INTFC_LOAD	Loads program from host computer.	8.2.1
	INTFC_SAVE	Saves program in host computer.	8.2.2
	INTFC_VERIFY	Verifies memory contents against host computer files.	8.2.3
Bi-directional parallel interface	LOAD	Loads program from host computer.	8.2.4
	SAVE	Saves program in host computer.	8.2.5
	VERIFY	Verifies memory contents against host computer files.	8.2.6

1.3 Realtime Emulation

The emulator enables realtime emulation with a clock frequency of 66 MHz for the SH7612 with no wait states. Realtime emulation consists of the following three modes:

- Normal mode

  Executes only emulation.
- Cycle reset mode

  Forcibly inputs the RES signal to the SH7612 periodically.
- Parallel mode

  Enables the user to display and modify memory and display trace information during user program execution.

The user can select the mode which best suits the user's debugging needs. The following describes each of these modes.

1.3.1 Normal Mode

Normal Mode Function: This mode executes only user program emulation. Until a break condition is satisfied, the emulator executes the user program. When a hardware break condition or software break condition is satisfied, the emulator stops the program execution. When a number of times or sequential break for the software break condition is specified, the emulator stops, only for a moment, the program execution every time the specified address is passed, and then resumes program execution.

Normal Mode Specification: Specifying no option with the GO command sets normal mode.

1.3.2 Cycle Reset Mode

Cycle Reset Mode Function: The emulator inputs the RES signal to the SH7612 after a specified time during realtime emulation and repeats the execution from the reset state. When the RES signal is input to the SH7612, a low-level pulse is output to the trigger output probe concurrently. This function is useful to observe the waveform from the initial state, such as power-on-reset, to a specified time.

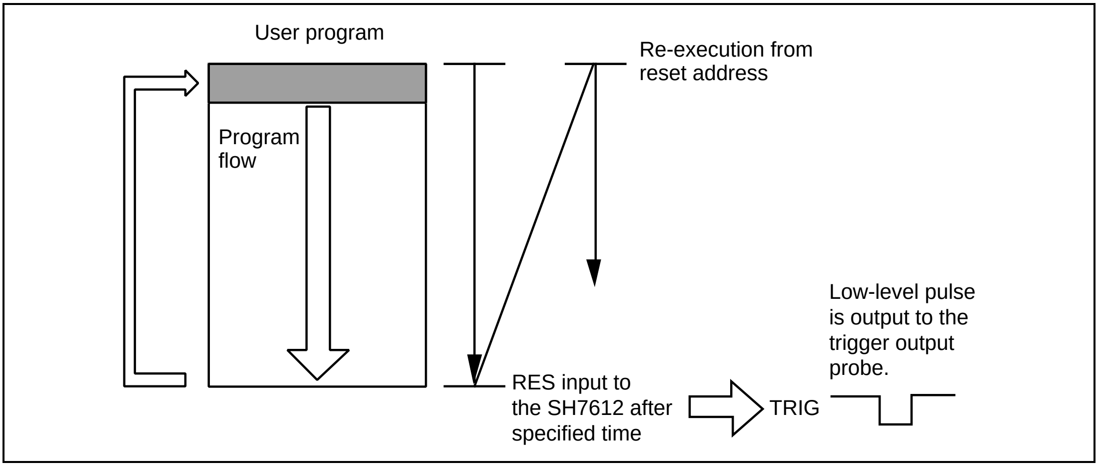


Figure 1.1   Cycle Reset Mode

Cycle Reset Mode Specification: Set “R=n” as a GO command option to specify cycle reset mode. For details, refer to section 7.2.21, GO.

Emulation Stop: In cycle reset mode, hardware break conditions and software break conditions are invalid. To stop emulation, press the (CTRL) + C keys or the (BREAK) key.

Trigger Signal Output Timing in Cycle Reset Mode: In cycle reset mode, the RES signal is output to the SH7612 regardless of the SH7612 operating status when the time specified by the command has elapsed. Figure 1.2 shows the timing in which the TRIG signal is output to the trigger output probe in cycle reset mode.

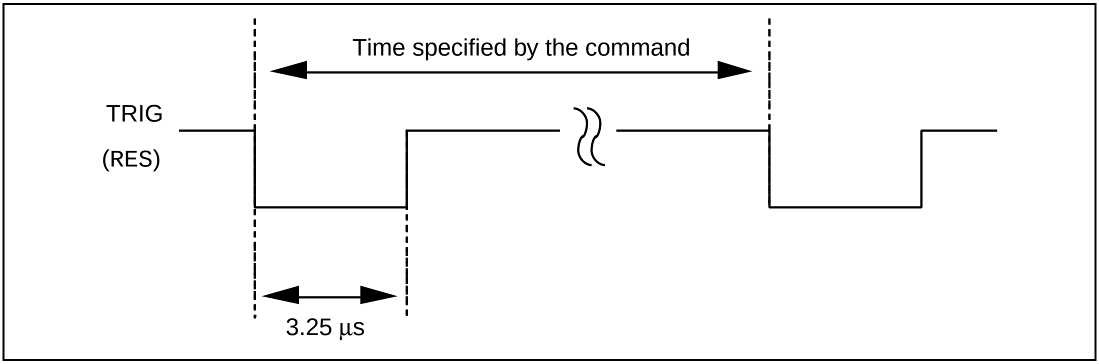


Figure 1.2   Trigger Signal Output Timing

1.3.3 Parallel Mode

Parallel Mode Function: In parallel mode, the emulator can display and modify memory or display trace information during realtime emulation. However, during memory contents display or modification, realtime emulation cannot be performed.

Parallel Mode Specification: Parallel mode can be activated during GO command realtime emulation by any of the following methods as shown in figure 1.3.

- Press the (RET) key
- Press the space key
- Satisfy a trace stop condition specified by the TRACE_CONDITION_A,B,C command

If any of the above occurs, the emulator will display a prompt (#) and enter parallel mode command input wait state. Emulation, however, continues without interruption. Input the END (E) command to return to the normal mode. Input the ABORT (AB) command to stop user program execution in the parallel mode.

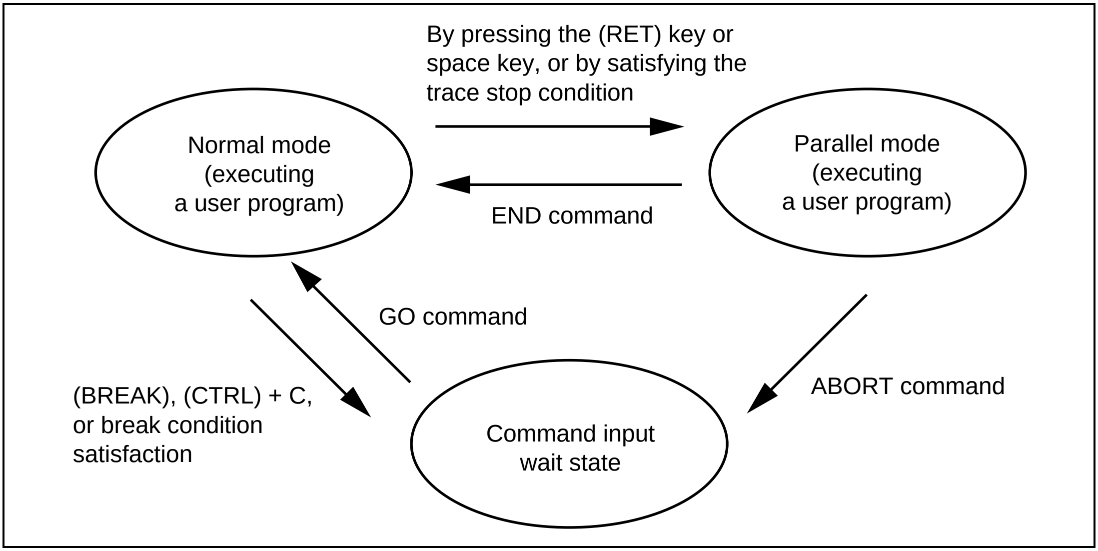


Figure 1.3 Transition to Parallel Mode

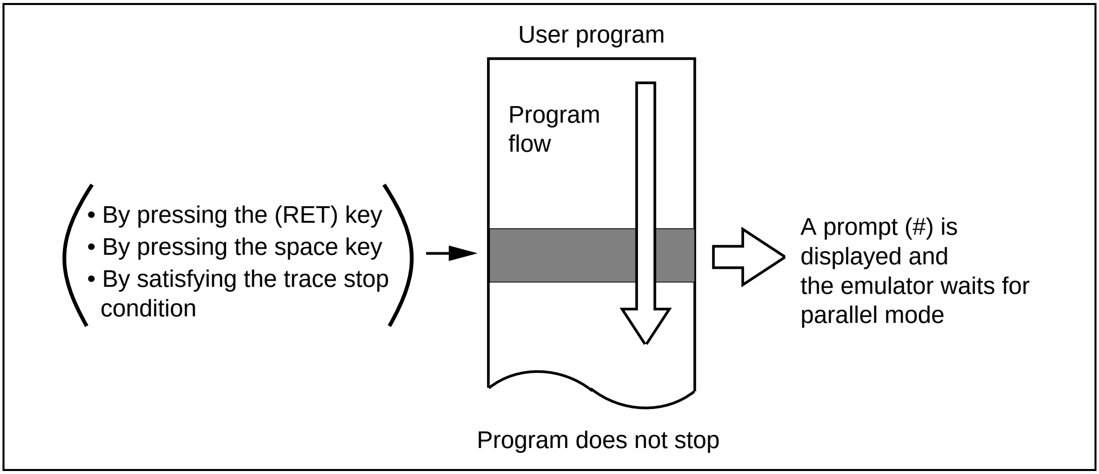


Figure 1.4 Parallel Mode

Note that debugging differs in parallel mode operation depending on the method used to activate it, as follows.

- By pressing the (RET) key or satisfying a trace stop condition
  - — The emulator stops acquiring trace information as soon as parallel mode is entered.
  - — The emulator can execute multiple commands entered by the user in parallel mode. The parallel mode continues even after the command execution is terminated.
  - — The END command terminates the parallel mode and returns the emulator to normal mode (displays the current PC). At this time, the emulator restarts trace information acquisition.
- By pressing the space key
  - — The emulator continues trace information acquisition; however, while the emulator executes the TRACE, TRACE_CONDITION_A,B,C or TRACE_SEARCH command, it acquires no trace information.
  - — In parallel mode, the emulator returns to normal mode after one command execution and displays the current PC. At this time, if trace information acquisition has stopped, the emulator restarts acquisition.

Commands usable in parallel mode are listed in table 7.1.

Notes: 1. When memory (standard emulation memory or internal I/O) is accessed with the MEMORY command, DUMP command, or DISASSEMBLE command in parallel mode, there are some restrictions with respect to user program execution.

- **Standard emulation memory**

  When accessing standard emulation memory in parallel mode, the user program temporarily halts. This pause lasts for about 546 µs during user system clock operation. Therefore, realtime emulation cannot be performed.

- **Internal RAM and I/O**

  When accessing internal I/O, the user program temporarily halts. This pause lasts for about 546 µs during user system clock operation. Therefore, realtime emulation cannot be performed.

- **In the above two cases, the emulator pauses at the following timing.**

  — MEMORY command: At each memory access

  — DUMP command: In 16-byte units

  — DISASSEMBLE command: In 4-byte units

2. During execution of the TRACE, TRACE_SEARCH, TRACE_CONDITION_A,B,C or TRACE_MEMOEY command, the emulator stops trace information acquisition.

3. The emulator cannot enter parallel mode when executing emulation in the following modes:

- **Cycle reset mode (R option of GO command)**
- **Time interval measurement mode (I1 or I2 option of GO command)**

1.4 Break Function

The following four methods are useful to stop emulation. The break function can be used regardless of the SH7612's operating mode.

- Hardware break

  Caused by the SH7612's signal status as specified

- Software break

  Caused by a program counter

- Forced break

  Caused by pressing the (CTRL) + C keys or the (BREAK) key

- Write protect/guarded break

  Caused by writing to a write-protected area or accessing guarded area

1.4.1 Hardware Break

A hardware break can be specified using the BREAK_CONDITION_UBC command or BREAK_CONDITION_A,B,C commands. Specifiable break conditions are listed in table 1.4. The BREAK_CONDITION_UBC command uses the User Break Controller (UBC) in the SH7612, and therefore user programs using the UBC cannot be debugged.

Table 1.4 Specifiable Hardware Break Conditions

Condition	BREAK_ CONDITION_ UBC1	BREAK_ CONDITION_ UBC2	BREAK_ CONDITION_ A (1 to 8)	BREAK_ CONDITION_ B (1 to 8)	BREAK_ CONDITION_ C (1 to 8)
Address condition	O	O	O	O	O
Datacondition	O		O	O	
Read/write condition	O	O	O	O	
Bus cycle specification	O	O	O	O	O
Probe condition			O	O	
External interrupt condition			O	O	
Pass count	O			O	
Delay count specification *[1]				O	
Sequential break	O	O			

Notes: 1. Only the BREAK_CONDITION_B7 can be specified for the delay count specification.

2. O represents specifiable item.

Address Bus Value: A break occurs when the SH7612 address bus value matches the specified condition.

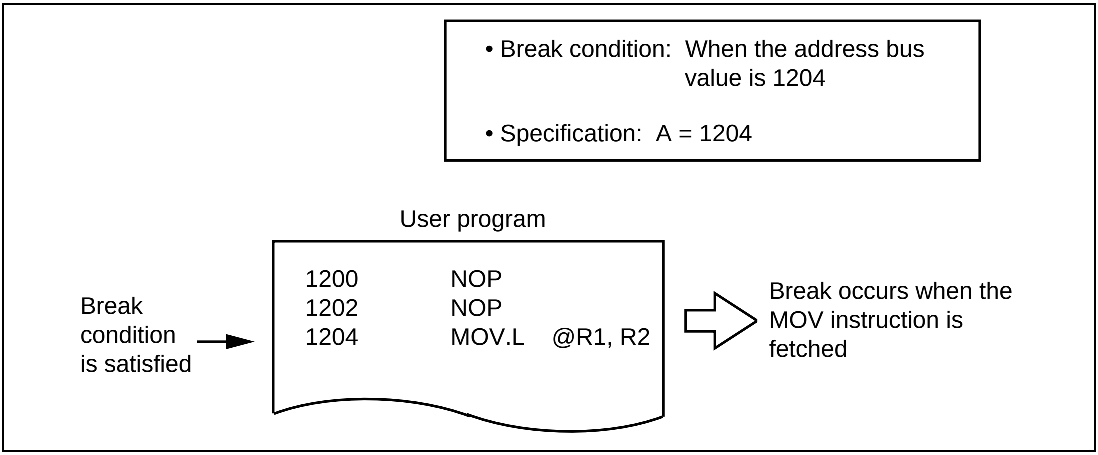


Figure 1.5 Break with Address Bus Value

Data Bus Value: A break occurs when the SH7612 data bus value matches the specified condition. The emulator checks both program fetch and data access for the condition.

The data size must be selected from longword access (LD), word access (WD), or byte access (D).

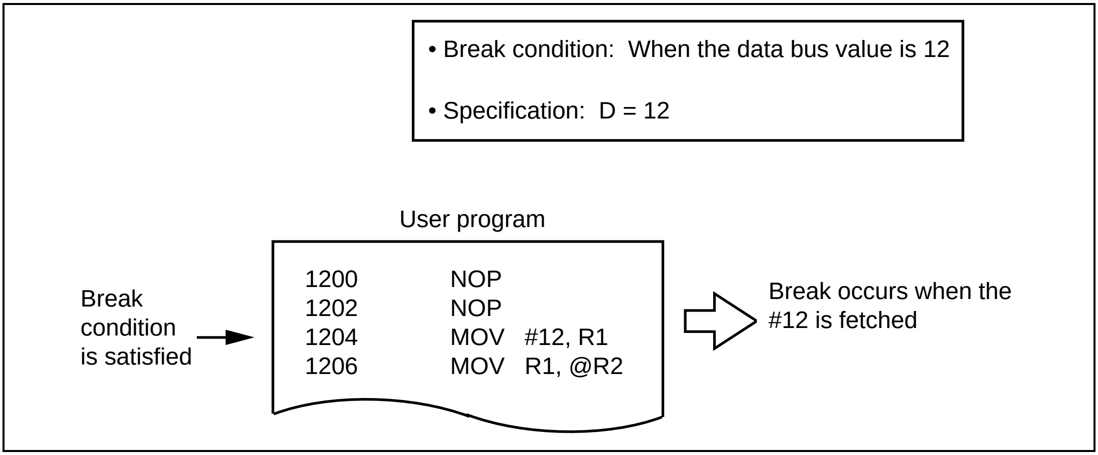


Figure 1.6 Break with Data Bus Value

Read/Write Condition: A break occurs when the SH7612's RD and RDWR signal levels match the specified conditions. Usually, the read/write condition is specified together with the address or data conditions.

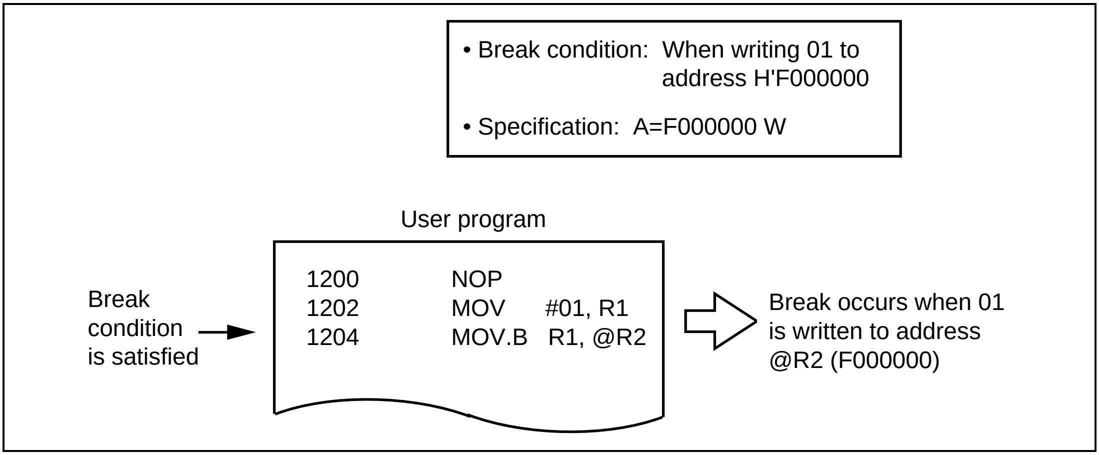


Figure 1.7 Break with Read/Write

Delay Count and Number of Times Break Condition is Satisfied: These functions can only be specified with the BREAK_CONDITION_UBC1* and BREAK_CONDITION_B commands. Note that these functions cannot be specified together; specify one function at a time.

In delay count specification, a break occurs when the above break condition (address bus value, data bus value, or read/write condition) is satisfied and the emulator executes the bus cycle for a specified number of times (65,535 max). When specifying this condition, specify it in combination with any of the above break conditions.

Note: For the BREAK_CONDITION_UBC1 command, only a satisfaction count can be specified.

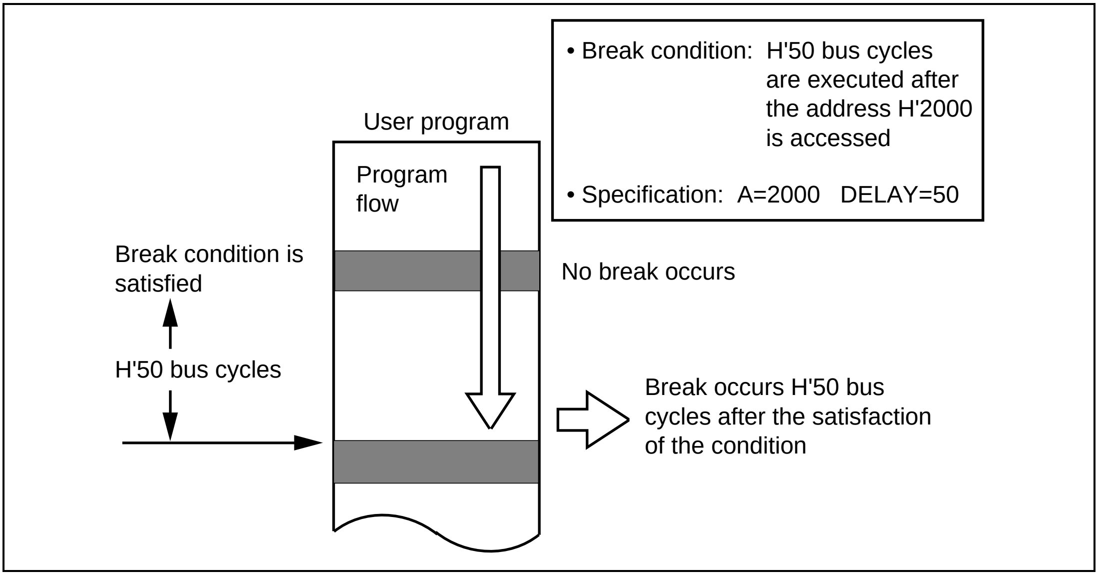


Figure 1.8 Break with Delay Count Specification

In number of times break condition is satisfied specification, a break occurs when the above break condition (address bus value, data bus value, or read/write condition) is satisfied for a specified number of times (65,535 max). When specifying this condition, specify it in combination with any of the above break conditions.

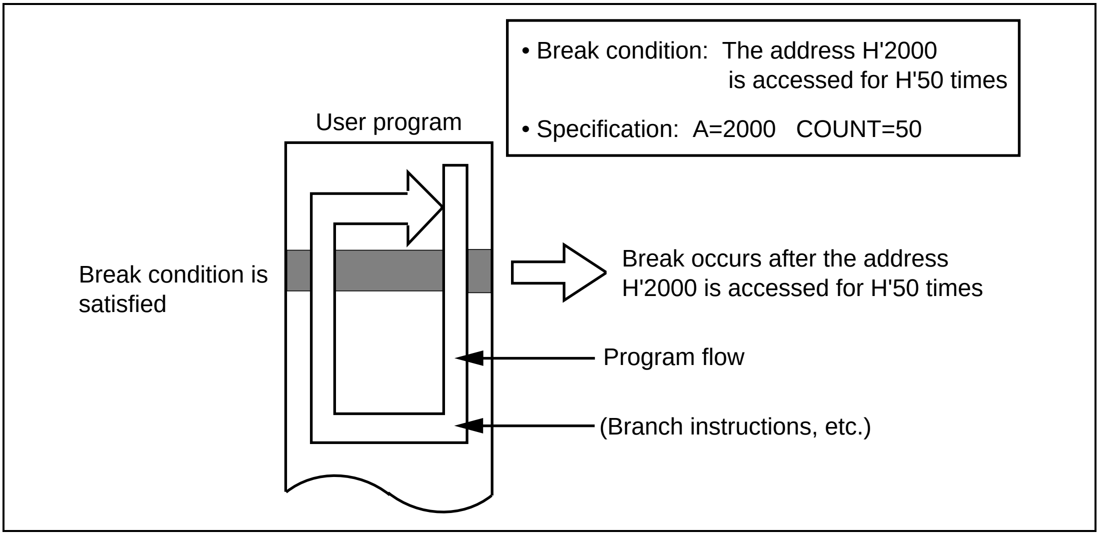


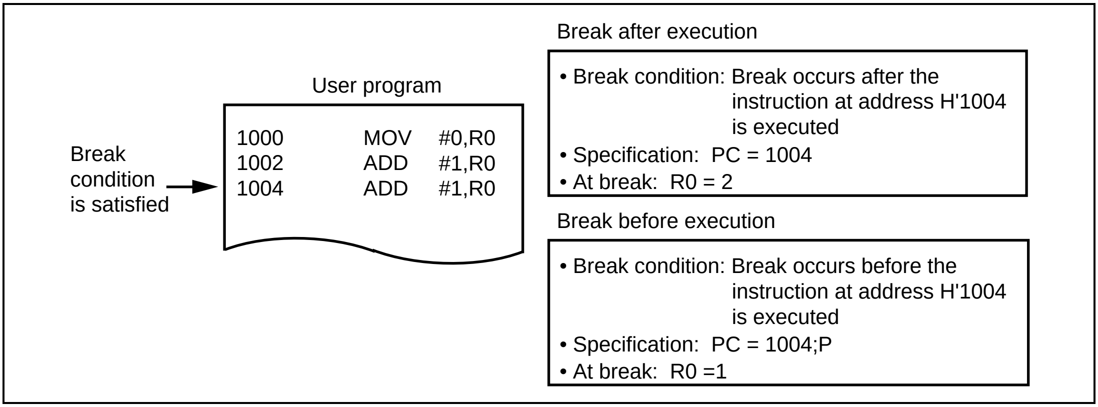
Figure 1.9 Break with Number of Times Break Condition is Satisfied

PC Value (BREAK_CONDITION_UBC1,2): A break occurs when the SH7612 program counter (PC) value satisfies the specified condition. The break timing depends on the ;P option setting as follows:

- PC value without option ;P (PC=1000): Break after execution

  A break occurs after the instruction at the specified address is executed.
- PC value followed by option ;P (PC=1000;P): Break before execution

  A break occurs before the instruction at the specified address is executed.



```
1000          MOV    #0,R0
1002          ADD    #1,R0
1004          ADD    #1,R0
```

Break after execution

- Break condition: Break occurs after the instruction at address H'1004 is executed
- Specification: PC = 1004
- At break: R0 = 2

Break before execution

- Break condition: Break occurs before the instruction at address H'1004 is executed
- Specification: PC = 1004;P
- At break: R0 =1

Figure 1.10   Break with PC Value Specification

Sequential Break Condition: In sequential break mode, a break occurs when hardware break conditions UBC2 and UBC1 have been satisfied in that order.

When executing the user program, specify the mode option of the GO command as a sequential break option (;SB). Unless the option is specified, a sequential break does not occur. In this case, a break occurs whenever each break condition is satisfied.

Specify the break condition with the BREAK_CONDITION_UBC1,2 commands. The user can specify either of the address bus value, the data bus value, or the read/write condition in the above.

- Sequential break mode

  When break condition UBC2 and then break condition UBC1 are satisfied, a break occurs.

Note: When the sequential break option (;SB) of the GO command is specified while the BREAK_CONDITION_UBC1 or 2, or both are not specified, the error message below will be output. At this time, a user program will not be executed.
***** 35:CAN NOT USE THIS MODE**

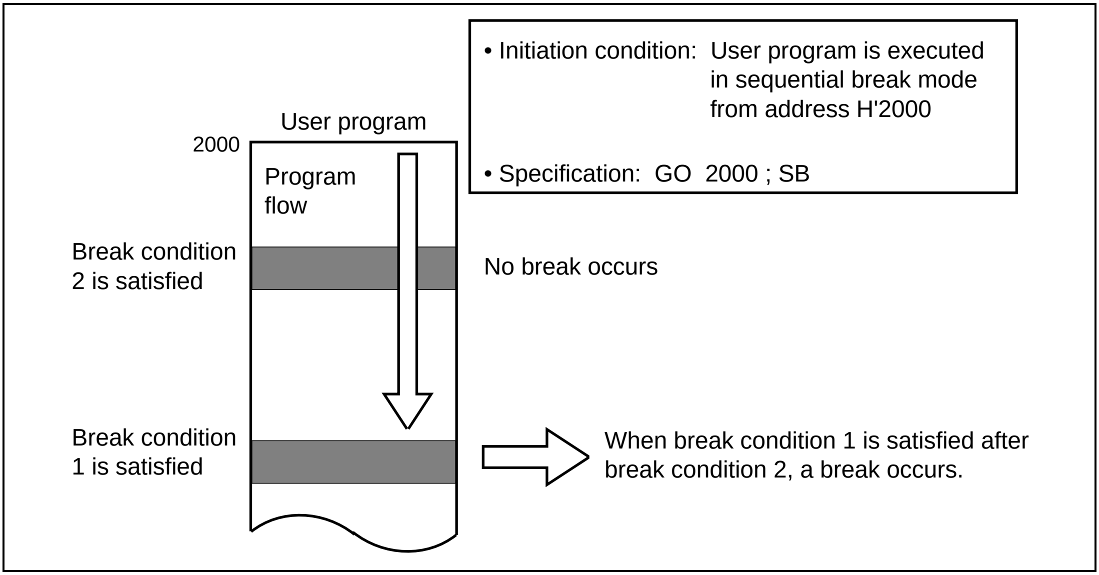


Figure 1.11 Break with Sequential Specification

1.4.2 Software Break

The contents at the specified address are replaced with a break instruction. The program execution stops when the break instruction is executed. The replaced instruction at the address is not executed. After the GO command is executed, the contents at the specified address will be replaced with a break instruction and the user program will be executed. When the user program execution stops, the break instruction will be replaced again with the contents at the specified address. Therefore, the contents at the specified address can be accessed immediately after the user program execution, using the DISASSEMBLE command or the DUMP command. However, note that a break instruction will be read if the memory contents at the break address are accessed in the parallel mode.

No software break must be specified immediately after a delayed branch instruction (at a slot instruction). If specified, a slot invalid instruction interrupt will occur at the branch instruction execution, and a break will not occur.

The software break can be performed in the following two ways:

- Normal break
- Sequential break

Normal Break: A break occurs before executing the breakpoint instruction specified with the BREAK command. At this time, the following can be specified:

- Number of breakpoints: 255 points (max)
- Number of times the break condition is satisfied: A break occurs after executing the breakpoint instruction a specified number of times. The maximum number to specify is 65,535 (H'FFFF).

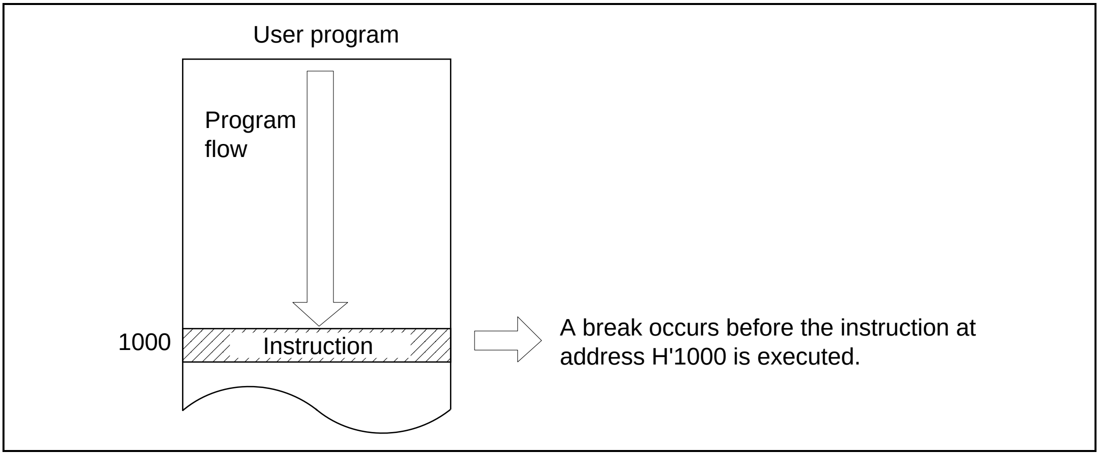


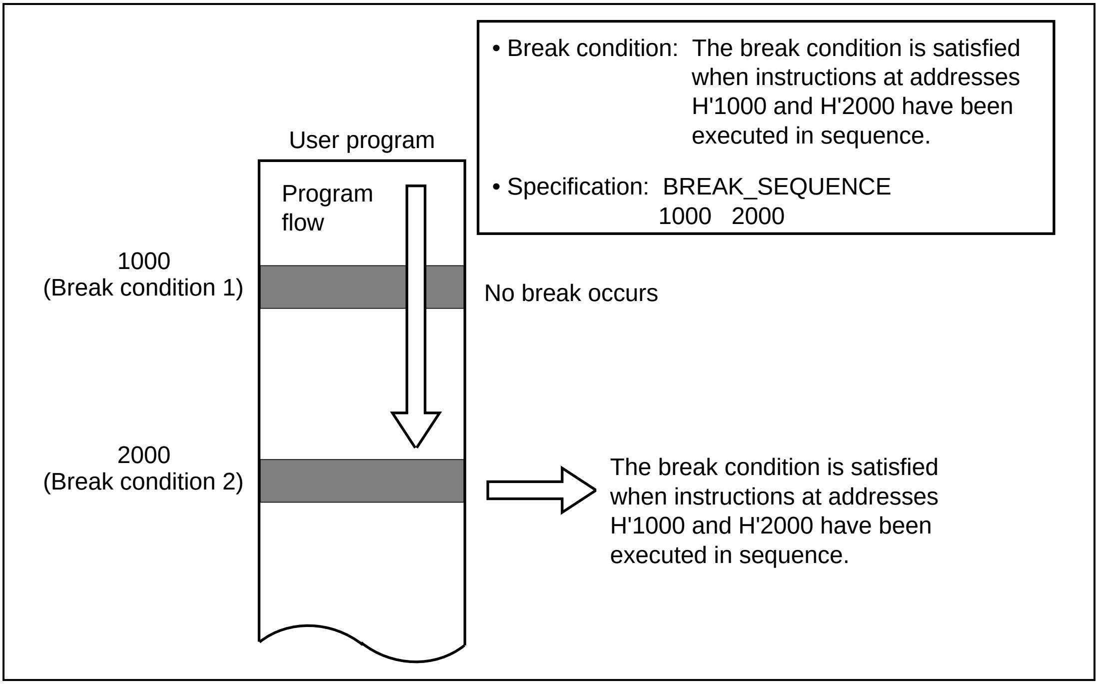
Figure 1.12 Normal Break (Software Break)

Note: When specifying the number of times the break condition is satisfied before generating a normal break, the emulator firmware is activated every time the program passes the break condition address. As a result, the program will not operate in realtime. When the program passes the break condition address, the emulator executes the instruction at the address for one step then returns to program execution. At this time, the BREAK_CONDITION_UBC2 becomes invalid because the BREAK_CONDITION_UBC2 is used to perform the step execution of the break address.

Sequential Break: A sequential break occurs (seven pass points max) when certain conditions are satisfied in a specified order. A reset point can be specified in addition to these pass points.

If the reset point is passed, all sequential break conditions up to that point become invalid and the emulator rechecks from the first break condition.

Figure 1.13 illustrates the usual sequential break and figure 1.14 describes a sequential break when a reset point is specified.



- Break condition: The break condition is satisfied when instructions at addresses H'1000 and H'2000 have been executed in sequence.
- Specification: BREAK_SEQUENCE 1000 2000

No break occurs

The break condition is satisfied when instructions at addresses H'1000 and H'2000 have been executed in sequence.

Figure 1.13 Sequential Break

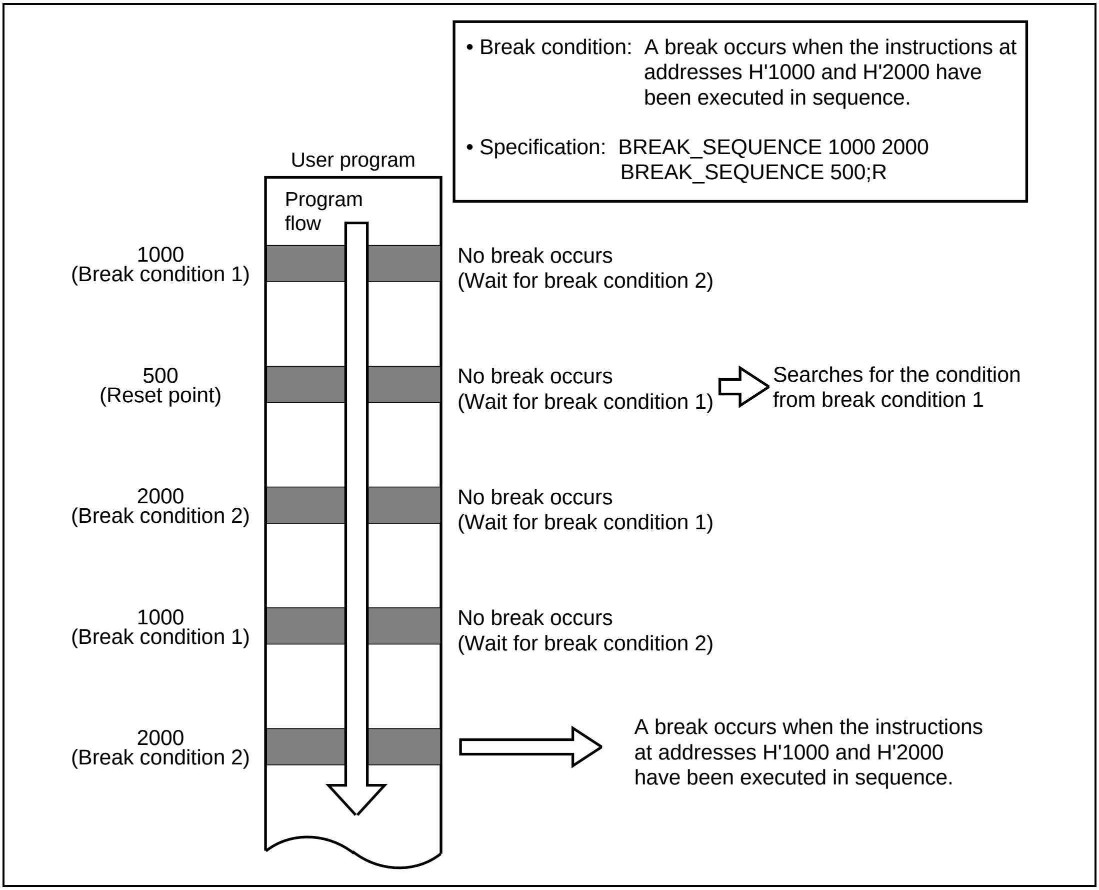


Figure 1.14 Sequential Break (Reset Point Specification)

Note: When specifying the sequential break (BREAK_SEQUENCE), the emulator firmware is activated every time the program passes the pass point or reset point. As a result, the program will not operate in realtime. When the program passes the pass point or reset point, the emulator executes the instruction at the address for one step then returns to program execution. Accordingly, the BREAK_CONDITION_UBC2 settings are invalid at pass point or reset point execution.

1.4.3 Forced Break

Pressing the (CTRL) + C keys or the (BREAK) key stops program execution.

1.5 Realtime Trace Function

The emulator can trace SH7612 external bus information during realtime emulation without affecting the user system. The emulator can fetch external bus information of the SH7612 address or data, and the external probe value up to 131,070 bus cycles. Trace information is referenced with the TRACE command. Display of this information enables a check on executed program.

Trace information:

- Address bus: 28 bits (PC value: 32 bits)
- Data bus (physical address): 32 bits
- External probe: One
- Number of bus cycle clocks (ø): 8 bits (a maximum of 255 kbytes)
- Trace of memory contents: 32 bits (internal 32 bits)

Emulator displays trace information in the following methods:

- Displays the trace information as mnemonic in bus cycle units.
- Searches for the specified information and displays it. Use the TRACE_SEARCH command.

1.5.1 Trace Timing

Trace information is acquired in trace memory synchronized with rising edges in the T3 cycles of the CLK signal.

Note: Because external probe signal input is not synchronized with the CLK signal, it may not be possible to log all the changes in the external probe signal.

In each bus cycle, the clock number is the number of clock (CLK) cycles between the end of the previous bus cycle and the end of the current bus cycle. Figure 1.15 shows an example of the external probe signal trace.

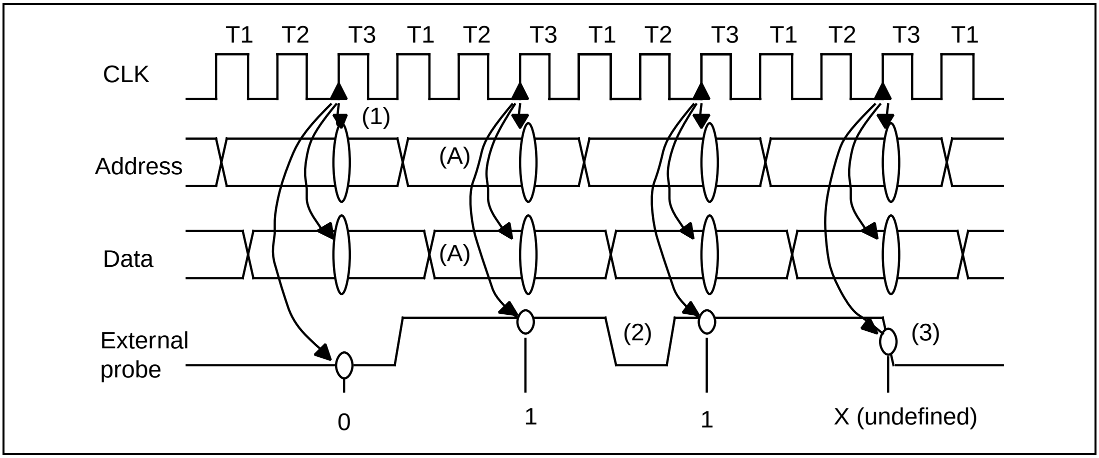


Figure 1.15 External Probe Signal Trace

Example:

- External probe signal
    - — Trace information is sampled at rising edges in the T3 cycles of CLK (figure 1.15 (1)).
    - — When the external probe signal changes between samplings, it cannot be reflected in the trace data (figure 1.15 (2)).
    - — When a sampling edge coincides with a change in the external probe signal, the trace contents are undefined (figure 1.15 (3)).

- Clock number
    - — Three clock cycles are traced in bus cycle (A).

1.5.2 Trace Condition Setting

The user can specify the following five conditions with the TRACE_CONDITION_A,B,C commands. For details, refer to section 7.2.41, TRACE_CONDITION_A,B,C. Table 1.5 shows the maximum specifiable numbers in trace mode.

- Free trace
- Subroutine trace
- Range trace
- Trace stop (parallel mode)
- Subroutine range trace

Table 1.5 Maximum Specifiable Numbers in Trace Mode

	TRACE_ CONDITION_A	TRACE_ CONDITION_B	TRACE_ CONDITION_C	Total
Subroutine trace	—	8	8	16
Range trace	8	8	8	24
Subroutine range trace	—	4	—	4
Trace stop (Parallel mode)	8	8	8	24

Free Trace: In free trace when the user program is executed as a result of the GO, STEP, or STEP_OVER command, tracing is carried out continuously for a maximum of the latest 131,070 bus cycles until a break condition is satisfied. When no parameter is given with the TRACE_CONDITION_A,B,C commands, the default is free trace. Figure 1.16 illustrates the free trace operation.

Note: Only external bus information can be traced at realtime. For details, refer to section 1.5, Realtime Trace Function.

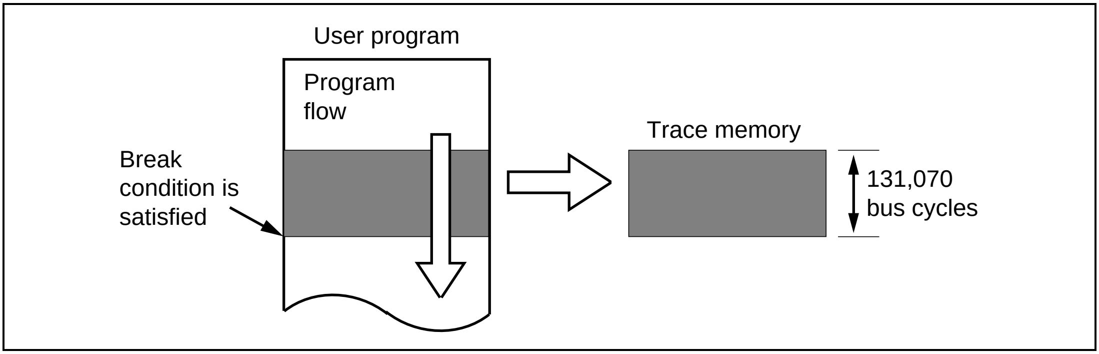


Figure 1.16 Free Trace Execution

Subroutine Trace: When a subroutine trace is specified, the emulator acquires operand accesses and instructions between a specified start address and end address. However, when the specified subroutine calls another subroutine, the called subroutine is not traced. Figure 1.17 illustrates the operation of the subroutine trace.

Note: Only external bus information can be traced at realtime. For details, refer to section 1.5, Realtime Trace Function.

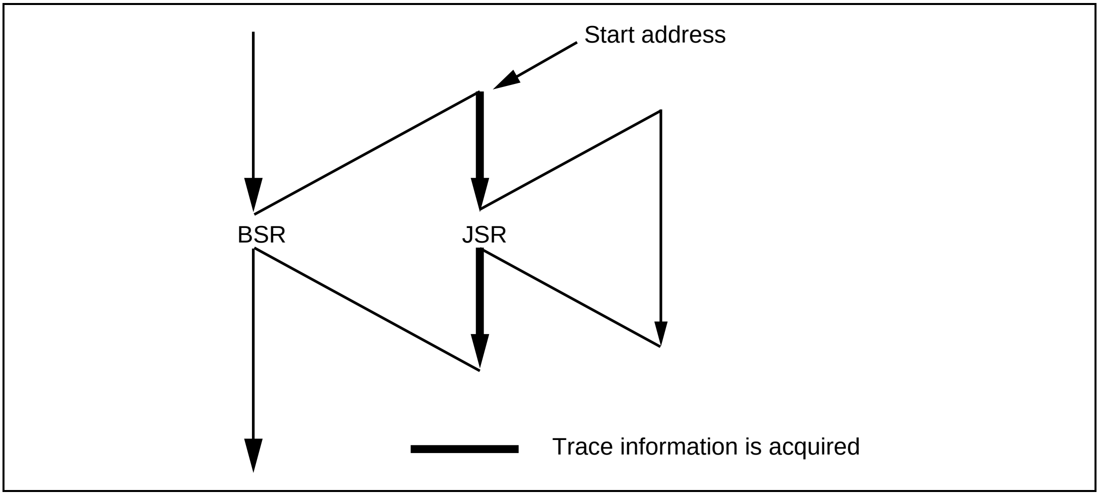


Figure 1.17 Subroutine Trace Specification

Range Trace: When a range trace is specified, the emulator only traces at points where specified conditions are satisfied. The following conditions can be specified.

- Address bus value (within or outside a specified range)
- Read/write condition
- Access type (program-fetch cycle and program-execution cycle)

Note: Only external bus information can be traced at realtime. For details, refer to section 1.5, Realtime Trace Function.

Figure 1.18 illustrates the trace acquisition condition.

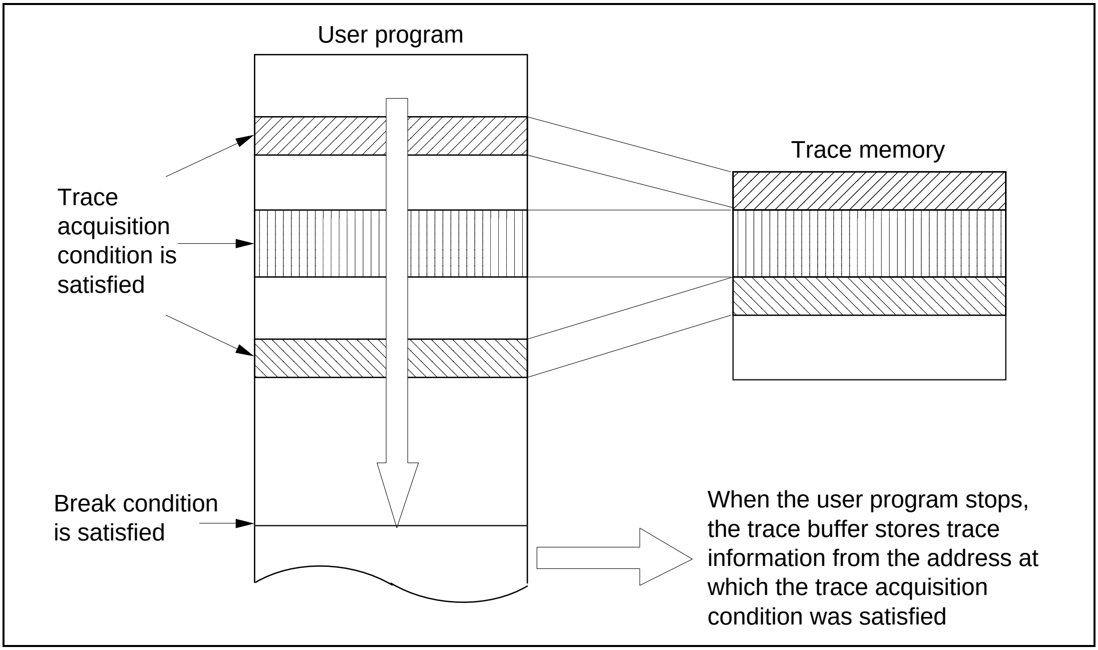


Figure 1.18 Trace Acquisition Condition

Trace Stop (Parallel Mode): When a trace stop condition is specified, the emulator acquires trace information until the specified condition is satisfied. At this point, trace acquisition stops and the emulator prompts for command input in parallel mode, although realtime emulation does not stop. Refer to section 1.3.3, Parallel Mode, for details. Once the trace stop conditions have been satisfied and the trace information has been displayed, the user can specify the trace stop condition again. The user can specify the following conditions.

- Address bus or data bus value
- Read/write condition
- Access type (DAT, DMA, VCF)
- External probe value
- System control signal (BREQ)
- NOT condition
- Delay count (H'1 to H'FFFF)

Figure 1.19 shows the trace stop condition specification.

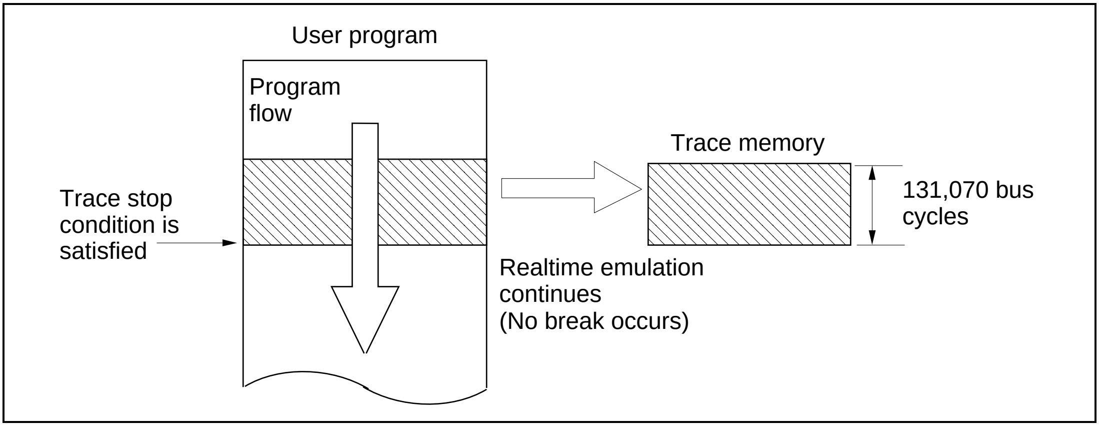


Figure 1.19   Trace Stop Condition Specification

Subroutine Range Trace: Trace information is acquired only when the instructions and operands are accessed in the specified subroutine under the specified condition. The subroutine and condition can be specified with the TRACE_CONDITION_A,B,C commands.

1.5.3 Trace Display

The user can display trace information using the TRACE command. There are three display formats, as follows. When branch instruction trace is specified with the TRACE_MODE command, trace information for branch instruction cycles is displayed.

Instruction Display: Only the executed instruction will be displayed in mnemonics from the trace information.

Bus Cycle Display: Trace information is displayed in bus cycle units.

Search Display: The emulator searches for specified trace information and displays all the corresponding bus cycles. In this case, use the TRACE_SEARCH command.

1.6 Single-Step Function

In addition to realtime emulation, effective debugging is facilitated by the single-step function. This function displays the following information every time a program instruction is executed.

- SH7612 control registers (PC, SR, PR, GBR, VBR, MACH, MACL, RS, RE, MOD)
- SH7612 general registers (R0 to R15)
- DSP registers of SH7612 (DSR, A0G, A0, A1G, A1, M0, M1, X0, X1, Y0, Y1)
- Instruction address
- Instruction mnemonic
- Memory contents
- Cause of termination

1.6.1 Single-Step Execution

Single-step execution has three modes: one in which all the instructions are displayed, one in which only branch instructions are displayed, and another in which instructions of a subroutine executed at first are displayed. To execute this function, use the STEP command, or to execute a subroutine in a single step, use the STEP_OVER command.

Displaying All Instructions: The emulator displays the specified information after every instruction.

Branch Instruction Display: The information is only displayed at branch instructions listed below.

BT, BF, BRA, BSR, JMP, JSR, BTS, BFS, BRAF, BSRF, TRAPA

Subroutine Display: When a subroutine is called, the information for the subroutine executed at first is displayed.

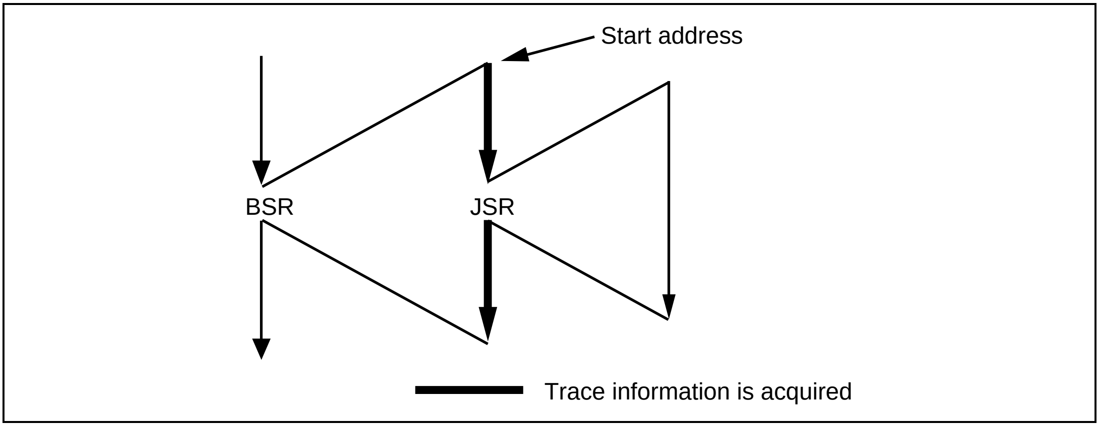


Figure 1.20 Subroutine Display

This function interrupts the execution state display at the JSR, BSR, or BSRF instruction in the designated subroutine and resumes the execution state display when the instruction placed immediately after the JSR, BSR, or BSRF instruction is executed. After that, if another JSR, BSR, or BSRF instruction is executed, the execution state display is interrupted.

Subroutine Step Execution: When executing a JSR, BSR, or BSRF instruction, the emulator treats the called subroutine as a single step. All other instructions are executed one at a time. This function is valid only in the user RAM or the emulation memory area.

1.6.2 Setting Display Information

The user can set the information displayed at each instruction using the STEP_ INFORMATION command. For details, refer to section 7.2.38, STEP_INFORMATION.

1.6.3 Termination of Single-Step Function

The single-step function stops after executing a specified number of steps from the specified start address (or the current PC address). The user can stop execution by specifying a stop address. However, the specified address must be at the start of an instruction. If the second byte of an instruction is specified (not the start of an instruction), the single-step function will not stop and execution continues for the specified number of steps.

1.7 Execution Time Measurement

1.7.1 Execution Time Measurement

GO to BREAK Time: The user can measure the user program execution time by specifying with the GO command. In this mode, the emulator measures the total execution time from when the user program is started with the GO command to when it is stopped by a break.

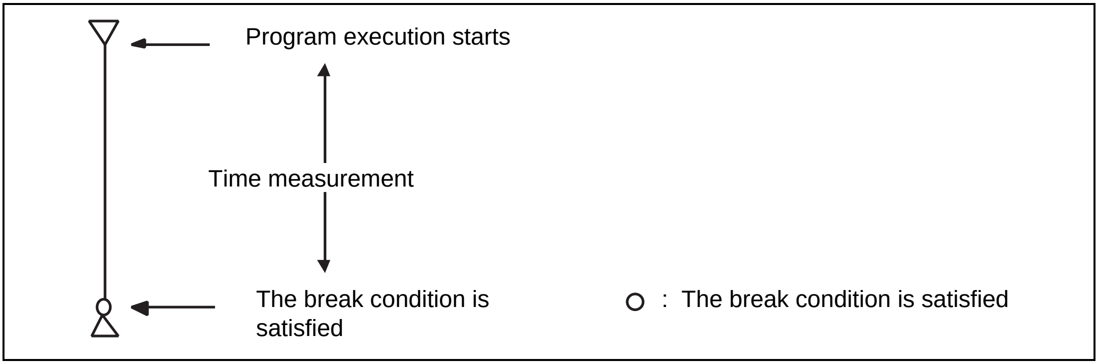


Figure 1.21 Normal Mode Time Measurement Range

Time Interval Measurement Mode 1: The emulator measures the elapsing between the satisfaction of hardware break conditions 2 (BREAK_CONDITION_UBC2) and 1 (BREAK_CONDITION_UBC1).

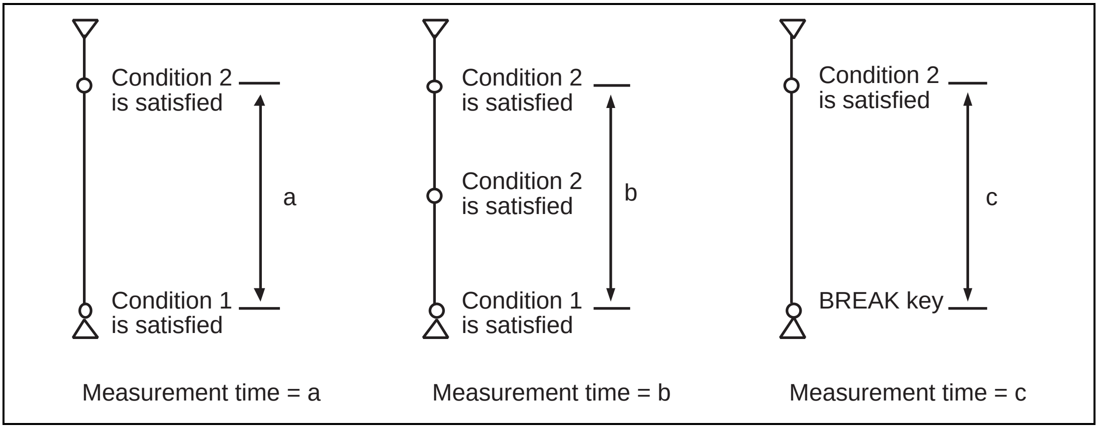


Figure 1.22 Time Interval Measurement Mode 1

In this mode, even if break condition 2 is satisfied, a break does not occur. A break occurs after the hardware break condition 2 and then break condition 1 are satisfied.

Even if break condition 2 is satisfied many times before break condition 1, the emulator measures the time from the first occasion on which break condition 2 is satisfied. When this mode is specified, PC breaks are invalid.

Time Interval Measurement Mode 2: In this mode, the time intervals between the satisfaction of break condition 2 (BREAK_CONDITION_UBC2) and break condition 1 (BREAK_CONDITION_UBC1) are added together. This mode is selected by specifying option I2 with the GO command. In time interval measurement mode 1, a break occurs after the hardware break condition 2 and then break condition 1 are satisfied. However, in this mode, even if break condition 1 is satisfied, a break does not occur. When this mode is specified, PC breaks are invalid.

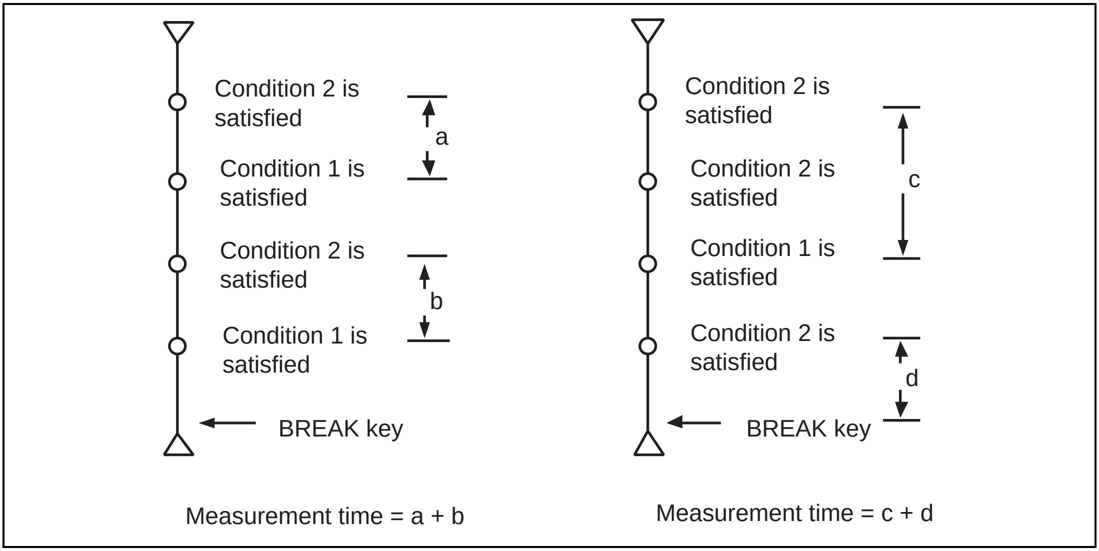


Figure 1.23 Time Interval Measurement Mode 2

1.7.2 Subroutine Time Measurement and Number of Times Measurement

The subroutine time and number of times the subroutines are executed can be measured based on the total program execution time by the PERFORMANCE_ANALYSIS command. Specify the subroutine to be measured with start and end addresses. The maximum number of subroutines which can be measured is shown in table 1.6.

Table 1.6 Maximum Number of Measurable Subroutines

Measurement Mode	Maximum Number of Measurable Subroutines
Time measurement mode 1	8
Time measurement mode 2	8
Time measurement mode 3	4
Access count to specified area	4
Number of nested subroutine calls	4

The measurement results are displayed in the following three ways:

- Numerical ratio of a specified subroutine execution time to a total execution time
- Bar graph indicating the ratio of a specified subroutine execution time to a total execution time
- Numerical value of specified subroutine execution time

For details on the PERFORMANCE_ANALYSIS command, refer to section 7.2.30, PERFORMANCE_ANALYSIS1-8.

Time Measurement Mode 1: The execution time and count of the subroutine specified by the start address and end address.

- Execution count measurement

  This is counted up every time the end address of the specified subroutine is passed.
- Execution time measurement

  The measurement result does not include the execution time of the subroutine called by the specified subroutine (between the start address and end address).

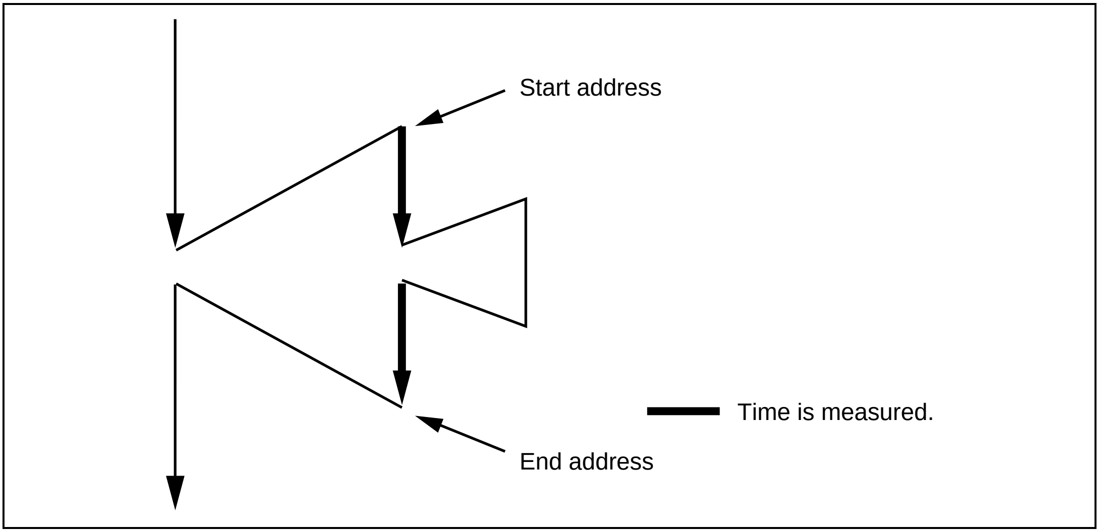


Figure 1.24   Time Measurement Mode 1

Time Measurement Mode 2: The execution time and count of the subroutine specified by the start address and end address.

- Execution count measurement

  This is counted up every time the end address of the specified subroutine is passed.
- Execution time measurement

  The measurement result includes the execution time of the subroutine called by the specified subroutine (between the start address and end address).

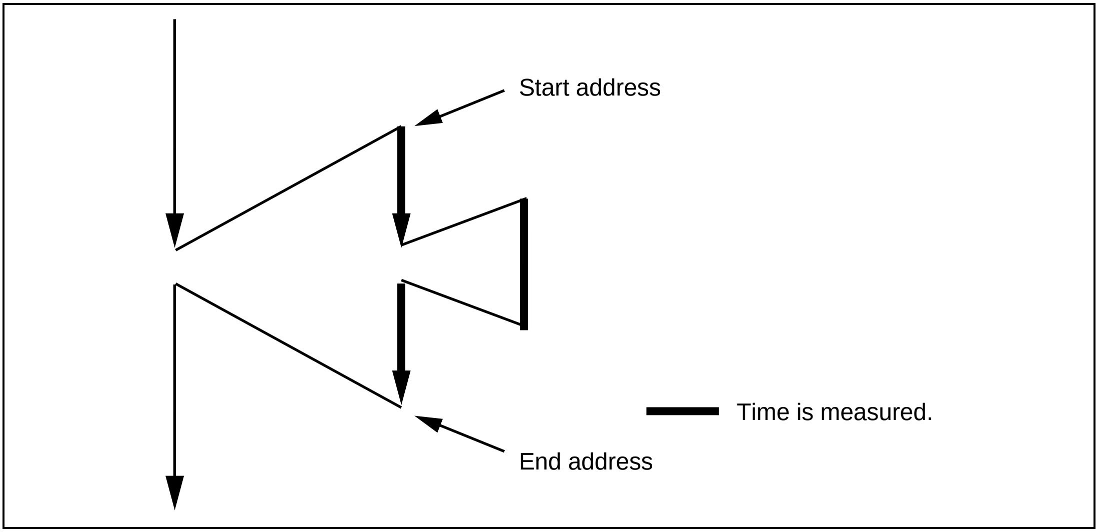


Figure 1.25 Time Measurement Mode 2

Time Measurement Mode 3: The execution time and count of the subroutine specified by the start address range and end address range. In this mode, the combination of the specifiable channels is fixed as follows:

- Channels 1 and 2
- Channels 3 and 4
- Channels 5 and 6
- Channels 7 and 8

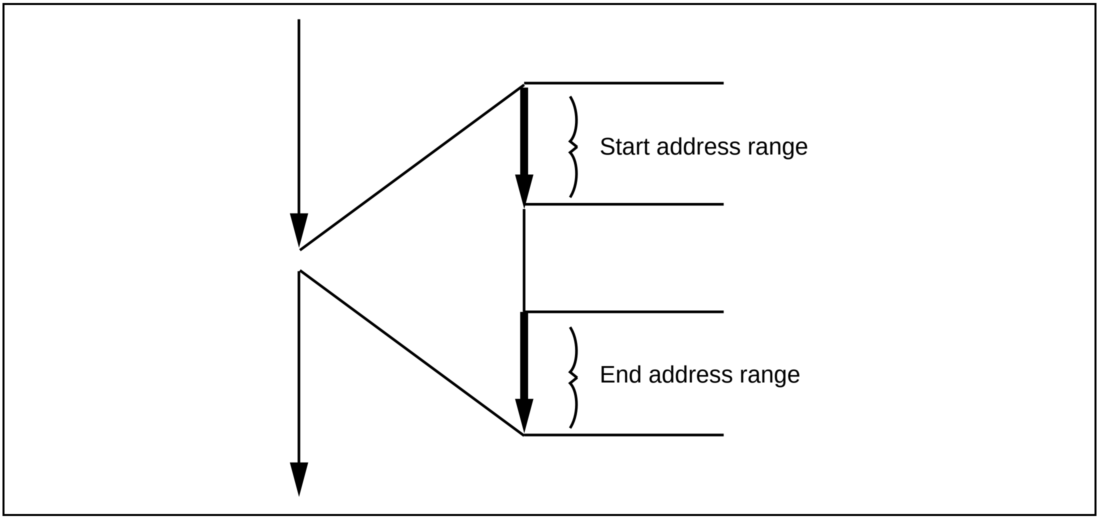


Figure 1.26 Time Measurement Mode 3

- Execution count measurement

  This is counted up every time the end address of the specified subroutine is passed.
- Execution time measurement

  The measurement starts from the program fetch cycles of the start address range and ends with the program fetch cycles of the end address range range. Accordingly, the execution time of a subroutine called during this period is included.

Specified Count Access Range: The access count from the subroutine specified by the start address and end address to the data in the user specification area is measured. The combination of the channels is the same as that for time measurement mode 3. In this case, this is measured in time measurement mode 1.

Subroutine-Call Count Measurement Mode: The access count to a subroutine (child) is measured during subroutine (parent) execution. The combination of the channels is the same as that for time measurement mode 3.

Maximum/Minimum Subroutine Time Detection Function: This is specified in the time measurement mode 2 of PERFORMANCE_ANALYSIS_1,2,3,4. This measures the maximum/minimum execution time for a subroutine specified by the start address and end address.

Timeout Function: This compares a measured value and a user specification time during user specified subroutine execution.

- User specification time < Measured value
  User program execution breaks.
- User specification time > Measured value
  Execution time is measured.

1.8 Trigger Output

During user program execution, the emulator outputs a low-level pulse from the trigger output probe under the following two conditions.

- Trace condition satisfaction
- Hardware break condition satisfaction

When using this pulse as an oscilloscope trigger input signal, it becomes easy to adjust the user system hardware. For example, waveforms can be seen when the user program goes to a specified point.

Trace Condition Satisfaction: When the trigger output is specified using the TRGB and TRGU options of the EXECUTION_MODE command, a low-level pulse is output from the trigger output probe at bus cycles corresponding to the specified condition. The trigger signal is output from the end of the corresponding bus cycle until the end of the next bus cycle. If the conditions are satisfied in consecutive bus cycles, the trigger output remains low.

Hardware Break Condition Satisfaction: During emulation, a low-level pulse is output from the trigger output pin at the end of the bus cycle during which the hardware break condition is satisfied. The trigger signal is output from the end of the corresponding bus cycle until the end of the next bus cycle. If the conditions are satisfied in consecutive bus cycles, the trigger output remains low.

Note: No pulse is output from the trigger output probe when a software break condition is satisfied. In addition, a low-level pulse output timing and pulse width differ depending on each condition.

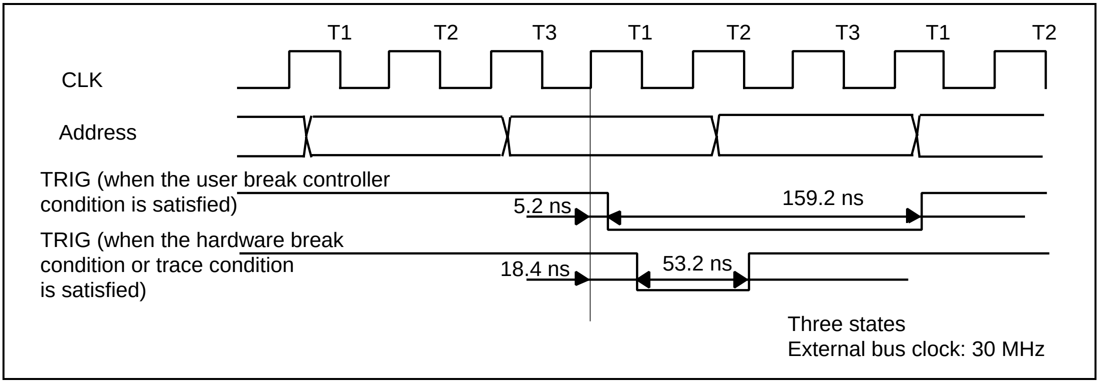


Figure 1.27 Pulse Output Timing

1.9 SH7612 Control and Status Check

The emulator is capable of switching the clock signal supplied to the SH7612, outputting strobe signals when the emulation memory is accessed, checking normal operation, and displaying the execution state. This function is effective for debugging the user system hardware.

Clock Switching: The emulation clock can be supplied from the user system clock (hereafter referred to as the user clock), the crystal oscillator installed on the emulator pod, and the internal clock (15 MHz). To switch the clock, refer to section 7.2.11, CLOCK, and note the following. In addition, refer to section 3.2.4, Selecting the Clock in part I, E8000 Guide.

- When the clock is switched, the emulator inputs a RES signal to the SH7612. This initializes the registers.
- When the user switches to the user clock and the user clock signal is not supplied, an error message is displayed and the internal clock is selected instead.
- When initiating the emulator system program, the emulator selects the SH7612 clock automatically in the following order:
  - When an external clock is supplied from the user system, selects the user clock
  - When a crystal oscillator is installed to the emulator pod, selects the crystal oscillator
  - Selects the emulation clock (15 MHz)

Check of the I/O signals: The emulator checks the connection with the user system at system initiation. By this check, abnormalities such as short circuits of a user system interface signal can be detected. The signals to be checked are as follows:

RES, BREQ, WAIT, IRL0 to IRL3, and NMI

The CHECK command can check the same signals that are checked at system initiation. For details, refer to section 7.2.10, CHECK.

Emulator Execution Status Display: The emulator can display execution status information listed in table 1.7. To display the execution status, use the STATUS command. For details, refer to section 7.2.36, STATUS.

Table 1.7 Execution Status Display

Display Command	Description
MODE=xx	SH7612 operating mode
RADIX=xx	Radix type
BREAK=xx	Number of breakpoints specified with the BREAK command
HOST=xx	Host-computer interface condition
CLOCK=xx	Type of clock (EML, USER, XTAL)
EML_MEM=S:xxxxxxB	Remaining standard emulation memory
STEP_INFO=REG: (a) A: (b) SP: (c)	• Register information displayed by the STEP command • Address range displayed by the STEP command • Display size for stack contents

1.10 Emulation Monitoring Function

The SH7612 emulator monitors the emulation status such as memory accesses or user program execution. Two kinds of status are monitored.

- SH7612 operating status
- User system power and clock status

SH7612 Operating Status: When executing the program with the GO command, the emulator monitors the operating status. When the status changes, the operating status display is updated. The update interval can be selected from no display, 200 ms, and 2 s with the MON option of the EXECUTION_MODE command. With this function, the user can observe the progress of the program. The operating status display and its meaning are shown in table 1.8. For details, refer to the description on operating status display, in section 7.2.21, GO.

Table 1.8 Operating Status Display

Display	Meaning
** RUNNING	The user program execution is initiated. This message is displayed once when GO command execution is started or when parallel mode is canceled. Note that this message will be deleted when **PC=xxxxxxxx is displayed.
** PC=xxxxxxxx	The program fetch address being executed is displayed with intervals of about 200 ms. When specifying the LEV option with the GO command, the satisfied level of the hardware sequential break is displayed. *
** VCC DOWN	User system Vcc (power voltage) is 2.65 V or less. The SH7612 is not operating correctly. (Displayed only when the user clock is selected.)
** RESET	RES signal is low. The SH7612 has been reset.
** WAIT A = xxxxxxxx	WAIT signal is low. The address bus value is displayed. Not displayed during memory access command execution or refresh cycles.
** TOUT A = xxxxxxxx	The SH7612 stops for 80 •s or longer. (The address value is displayed.)
** BREQ	BREQ signal is low.

Note: The time interval for this operating status display can be specified as 2 s, 200 ms, or no display by the MON option of the EXECUTION_MODE command. Default is 200 ms.

User System Power and Clock Status: The emulator monitors the user system power and clock status. If the user system power is off or the clock stops when the SH7612 clock is set to USER with the CLOCK command, the emulator executes the following operation according to the emulator status.

Notes: 1. If the user system power is turned off (Vcc is 2.65 V or lower), this is detected before the clock stop is detected.

2. Clock stop means that only the clock stops and the user system power remains on.

- During user program execution
  - When the user system is turned off (Vcc is 2.65 V or lower), ** VCC DOWN is displayed. When the power is turned on again, the emulation restarts and current position of PC in the user program is displayed.
  - When the clock stops (Vcc is 2.65 V or lower), USER SYSTEM NOT READY (NO CLOCK) is displayed and the emulator system program stops. To operate the emulator again, restart the system program.

- During command input wait state
  - When the user system is turned off (Vcc is 2.65 V or lower), USER SYSTEM NOT READY (NO CLOCK) is displayed and the SH7612 operating clock is switched to the internal 15-MHz clock and the emulator waits for command input. A RES signal is input to the SH7612, and the internal registers are initialized. USER SYSTEM NOT READY (NO CLOCK) is displayed after the user system has been turned off and one command has been executed.
  - When the clock stops (Vcc is 2.65 V or lower), USER SYSTEM NOT READY (NO CLOCK) is displayed and the emulator system terminates. Restart the emulator in order to continue emulation.

1.11 Assembly Function

1.11.1 Overview

The ASSEMBLE command enables line assembly as shown in figure 1.28.

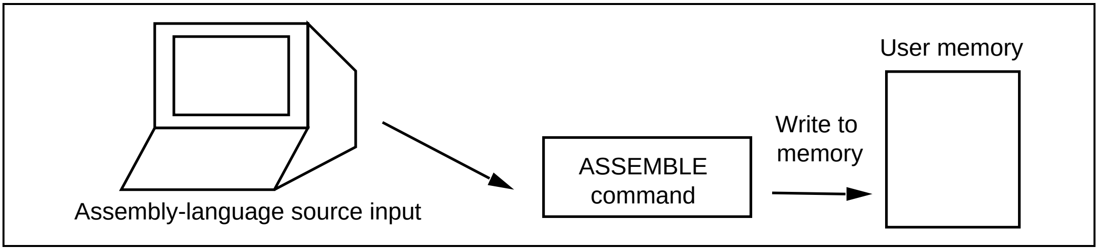


Figure 1.28 Assembly Function

Line assembly: Assembly-language source is input from the console line by line.

Refer to section 7.2.4, ASSEMBLE, for command initiation instructions.

1.11.2 Input Format

The basic instruction format is as follows.

<instruction mnemonic>[Δ<operand>,...Δ][;<comment>] (RET)

<instruction mnemonic>:	Any instruction mnemonic described in the SH7612 Series Programming Manual and any assembler directive listed in table 1.9 can be used.
<operand>:	Any mnemonic described in the SH-Series Programming Manual can be used (table 1.10).
<comment>:	A character string after a semicolon (;) is considered to be a comment.
[ ]:	Items within square brackets ([ ]) can be omitted. However, some <operand> values for specific instructions are required.
Δ:	Indicates a space.

Notes: 1. Continuation lines cannot be input.

2. The default for radix of constants is set by the RADIX command.

Table 1.9 Assembler Directives

Directive	Operand	Description
Δ.DATA[.s]Δ	<value>[,<value>...]	• Reserves an area for initialized fixed-length data. The size of the area is equal to the unit length given by s: B (byte), W (word) or L (longword). Default size is L. • If any <value> exceeds the capacity of the size code (s), an error occurs. • A line can contain up to 40 bytes.
Δ.RES[.s]Δ	<value>	• Reserves data areas. The number of areas is given by <value>. The size of each area is given by s: B (byte), W (word) or L (longword). Default size is L. • Up to 4,294,967,295-byte area can be reserved at one time.

Table 1.10 Operand Descriptions

Format	**Addressing Mode**	**Remarks**	
Rn	Register direct	Rn:	General register name (SP can be specified instead of R15)
SR		SR:	Status register
GBR		GBR:	Global base register
VBR		VBR:	Vector base register
MACH		MACH:	High-order multiply and accumulate register
MACL		MACL:	Low-order multiply and accumulate register
PR		PR:	Procedure register
SSR		SSR:	Saving status register
SPC		SPC:	Saving program counter
@Rn	Register indirect	Rn:	General register name
@Rn+	Register indirect with post-incrementation	Rn:	General register name
@-Rn	Register indirect with pre-decrementation	Rn:	General register name
@(disp, Rn)	Register indirect with displacement	disp:	Displacement value
		Rn:	General register name
@(R0, Rn)	Register indirect with index	R0,Rn:	General register name
@(disp, GBR)	GBR indirect with displacement	disp:	Displacement value
		GBR	Global base register
@(R0, GBR)	GBR indirect with index	R0:	General register name
		GBR	Global base register
@(disp, PC)	PC relative with displacement	disp:	Displacement value
		PC	PC value within vector address table
aaaa	PC relative	aaaa:	Address value (Usable with BF, BT, BRA, and BSR instructions)
#imm	Immediate	imm:	Immediate data value

Notes: 1. For the address value, immediate data value and displacement values, the formula (addition or subtraction) can be used. However, disassemble is displayed only in address value.

2. If the immediate data value is different from the specified operation size, an error occurs.

1.11.3 Disassembly

The emulator has a disassembly function to display user program contents in mnemonics. This function is performed with the DISASSEMBLE command and enables to debug without referencing to a program list. For details, refer to section 7.2.16, DISASSEMBLE.

Section 2 Differences between the SH7612 and the Emulator

When the emulator system is initiated, or when the emulator resets the SH7612 as a result of a command, such as the CLOCK command switching the clock or the RESET command, note that the general registers and part of the control registers are initialized.

Table 2.1 Differences between Initial Values of the SH7612 and Emulator Registers

State	Register	Emulator	SH7612
Emulator initiation (power-on)	PC	Reset vector value	Reset vector value
	R0 to R14	H'00000000	Undefined
	R15 (SP)	Stack pointer value	Stack pointer value
	SR	H'000000F0	H'00000XFX *
	PR	H'00000000	Undefined
	VBR	H'00000000	H'00000000
	GBR	H'00000000	Undefined
	MACH	H'00000000	Undefined
	MACL	H'00000000	Undefined
	DSR	H'00000000	H'00000000
	MOD	H'00000000	Undefined
	RS, RE	H'00000000	Undefined
	A0, A1	H'00000000	Undefined
	M0, M1	H'00000000	Undefined
	X0, X1	H'00000000	Undefined
	Y0, Y1	H'00000000	Undefined
	A0G, A1G	H'00	Undefined

Note: X is an undefined value.

The emulator’s user system interface is provided with pull-up resistors and a buffer, causing the signals to be delayed slightly. Also, the pull-up resistors will change high-impedance signals to high-level signals. Adjust the user system hardware accordingly. Refer to section 4, User System Interface.

The user break controller (UBC) and Hitachi user debugging interface (H-UDI) in the SH7612 cannot be used with this emulator.

The emulator for the SH7612 can use an operating frequency of 66 MHz or lower. Note, however, that the emulator cannot use an operating frequency higher than 66 MHz. If the operating frequency is set to higher than 66 MHz, correct emulation cannot be guaranteed.

Section 3 SH7612 Function Support

The SH7612 has seven clock modes. However, operation using the crystal oscillator (CKPREQ/CKM = 1) is not supported in operating modes 0 to 3. This section describes how the emulator supports the SH7612 functions.

Note: The crystal oscillator bonded to the crystal oscillator terminals X0 and X1 on the evaluation chip board (EV-chip board) is connected to an oscillator within the EV-chip board to perform clock oscillation. This clock source is input to the EXTAL pin of the SH7612. Note that the crystal oscillator cannot be directly connected to the EXTAL and XTAL pins of the SH7612.

3.1 Operating Mode Setting

The user selects the operating mode and CS0 area bus width for the emulator with the MODE command, as shown in table 3.1. For details, refer to section 7.2.27, MODE.

Note: An operating mode specified using the MODE command will be valid only after the emulator is re-initiated. Therefore, the emulator must be reset after specifying an operating mode. At this time, emulator specifications before reset, such as emulation memory attributes and breakpoint settings, will not be saved.

Table 3.1 SH7612 Operating Mode Selection

Operating Mode	Description	Clock Source
Mode 0*[1]	The PLL1 and PLL2 circuits operate. The CKIO pin outputs a clock (Eϕ) with the same phase as the LSI internal clock (Iϕ, Eϕ, Pϕ). The control bit of the frequency modification register (FMR) can switch between operation and stop of the PLL1 and PLL2 circuits. The CKIO pin can become the Hi-Z*[2] state.	Crystal oscillator or external clock input
Mode 1*[1]	The PLL1 and PLL2 circuits operate. The CKIO pin outputs an internal clock (Eϕ) with a phase shift of 1/4ϕ cycles behind the LSI internal system clock ϕ. The control bit of the FMR can switch between operation and stop of the PLL1 and PLL2 circuits. The CKIO pin can become the Hi-Z*[2] state.	
Mode 2*[1]	The PLL2 circuit operates. The CKIO pin outputs a clock from the PLL2 circuit (with the same frequency as an internal Eϕ clock). The phases are not synchronized because the PLL1 circuit always stops. The control bit of the FMR can switch between operation and stop of the PLL2 circuit. The CKIO pin can become the Hi-Z*[2] state.	
Mode 3*[1]	The PLL2 circuit operates. The CKIO pin is always in the Hi-Z*[2] state. The control bit of the FMR can switch between operation and stop of the PLL2 circuit.	
Mode 4	The PLL1 circuit operates. Operate the PLL1 circuit with the same phase between a clock input from the CKIO pin and the LSI internal clock (Iϕ, Eϕ, Pϕ). The PLL2 circuit always stops. The control bit of the FMR can switch between operation and stop of the PLL1 circuit.	External clock input
Mode 5	The PLL1 circuit operates. Operate the PLL1 circuit when the phases of a clock input from the CKIO pin and the LSI internal clock (Iϕ, Eϕ, Pϕ) are shifted by 1/4ϕ cycles behind the system clock ϕ. The PLL2 circuit always stops. The control bit of the FMR can switch between operation and stop of the PLL1 circuit.	
Mode 6	Both the PLL1 and PLL2 circuits always stop. Set mode 6 when operating the SH7612 with the same-frequency clock as a clock input from the CKIO pin.	

Notes: 1. Operating modes 0 to 3

Operating modes 0 to 3 are not supported when a crystal oscillator is connected to the XTAL and EXTAL pins. To use a crystal oscillator in these modes, connect it to the EV-chip board crystal oscillator terminal.

2. High impedance

Table 3.2 shows the relationship between the combination of the MD2 to MD0 pins and the operating mode. Do not switch between pins MD2 to MD0 during operation. If these pins are switched, the operation is not guaranteed.

Table 3.2 Setting and State of Operating Mode

Operating Mode	Pin Name MD2	MD1	MD0	CKPREQ/ CKM	EXTAL	XTAL	CKIO
Mode 0	0	0	0	0	Clock input	Open	Output/Hi-Z*[4]
				1*[1]	Crystal oscillation		
Mode 1	0	0	1	0	Clock input	Open	
				1*[1]	Crystal oscillation		
Mode 2	0	1	0	0	Clock input	Open	
				1*[1]	Crystal oscillation		
Mode 3	0	1	1	0	Clock input	Open	Hi-Z*[4]
				1*[1]	Crystal oscillation		
Mode 4*[2]	1	0	0	*[3]	Open		Clock input
Mode 5*[2]	1	0	1				
Mode 6*[2]	1	1	0				

Notes: Do not use MD2 to MD0 pins in any combination other than those shown above.

1. **Operating modes 0 to 3 are not supported when CKPREQ/CKM = 1.**
2. **In operating modes 4 to 6, a clock is input from the CKIO pin and an emulator internal clock cannot be used.**
3. **In operating modes 4 to 6, the CKPREQ/CKM pin functions as the clock pause request.**
4. **High impedance**

Table 3.3 shows the selection of the CS0-area bus width.

Table 3.3 CS0-area Bus Width Selection

MD4	MD3	CS0-area Bus Width
0	0	8 bits
0	1	16 bits
1	0	32 bits
1	1	Setting prohibited

In the emulator, the operating mode previously set is saved in the configuration file on the flash memory of the E8000 station. At initialization, the emulator initiates the system with the operating mode specified with the MODE command.

3.2 Memory Space

The SH7612 has a maximum of 160-Mbyte memory space in the CS0 to CS4 areas. Standard emulation memory (4 Mbytes) can be set in 1-Mbyte units to the memory area. The CSn area that is not set as emulation memory is set as user system memory. For details, refer to section 7.2.25, MAP.

- U: User system memory
- S: Standard emulation memory

The user can specify write-protected and access-prohibited areas as emulation memory.

Normally, emulation memory and user memory should not be allocated to the same CS area concurrently. If they are, strobe signals (RD, CSn, and WEn) are not output in that CS area.

Access time of the emulation memory is ten clocks per bus cycle (CPU internal clocks), and WAIT count cannot be changed.

Write-protected areas can be allocated to the emulation memory in units of 1 Mbyte or more.

- SW: Write-protected

3.2.1 Internal I/O Area

When the internal I/O area is accessed, the emulator accesses the SH7612 internal I/O, regardless of the memory attribute set with the MAP command. The user can read from and write to the internal I/O area with user program or emulator commands. When writing to the internal I/O area with an emulator command (MEMORY), the following warning message is displayed and the emulator starts writing without verifying.

```
*** 86:  INTERNAL AREA
```

However, the user cannot write to the internal I/O with the FILL command.

3.2.2 External Memory Area

The SH7612 external memory area can be allocated to all memory attributes supported by the emulator. Memory corresponding to the allocated attributes can be accessed with user program or emulator commands.

3.3 Other Functions

3.3.1 Low-Power Mode (Sleep and Standby)

For reduced power consumption, the SH7612 has sleep and standby modes.

The sleep and standby modes are switched using the SLEEP instruction. These modes can be cleared with either the normal clearing cause or with the break condition satisfaction (including (BREAK) or (CTRL) + C key input), and the program breaks. Trace information is not acquired in the sleep and standby modes.

Notes: 1. **When restarting after a break, the user program will restart at the instruction following the SLEEP instruction.**

2. **During sleep mode, if the user accesses or modifies the memory in parallel mode, the sleep mode is cleared and the user program execution continues from the instruction following the SLEEP instruction.**

3.3.2 Interrupts

During emulation, the user can interrupt the SH7612.

- When an interrupt is disabled by the BACKGROUND_INTERRUPT command

  If an interrupt occurs while the emulator is waiting for command input, the interrupt is not processed. However, if an edge sensitive interrupt of internal and external interrupts occurs while the emulator is waiting for command input, the emulator latches the interrupt and executes the interrupt processing routine when the GO command is entered.
- When an interrupt is enabled by the BACKGROUND_INTERRUPT command

  An interrupt is acceptable while the emulator is waiting for command input.

3.3.3 Control Input Signals (RES, WAIT, BREQ)

The SH7612 control input signals are RES, WAIT and BREQ. The RES, WAIT, and BREQ signals are valid during execution with either the GO command or STEP command. Therefore, while the emulator is waiting for command input, the user cannot input RES, WAIT or BREQ signals to the SH7612. The BREQ signals will not be input to the SH7612 during user program execution when the BREQ signal is masked, that is the option BREQ = D is specified, using the EXECUTION_MODE command.

3.3.4 Serial Communication Interface

The serial communication interface signals are connected to the user system directly from the SH7612 on the emulator pod. Therefore, like the 16-bit FRT, the interface is valid during the command input wait state as well as emulation. For example, when writing data to the Transmit Data Register (SCTDR) and clearing the Transmit Data Empty (TDRE) of the Status Register (SCSSR), after the serial communication interface output has been prepared, data is output to the TxD pin.

3.3.5 16-Bit Free-Running Timer (FRT)

The 16-bit FRT operates during the command input wait state as well as during emulation. Even after the user program has stopped when a break condition is satisfied after the user program has been started with a GO command, the 16-bit FRT continues to operate. Therefore, the timer pins are valid even when user program execution has stopped. The user can rewrite the timer registers with the MEMORY command.

3.3.6 DMAC

The DMAC performs data transfer between the memory (internal or external) and a peripheral device (internal or external). The DMAC of the SH7612 operates during the command input wait state as well as during emulation. When transfer is requested, the DMA transfer is performed.

3.3.7 Hitachi User Debugging Interface (Hitachi-UDI)

The Hitachi user debugging interface (Hitachi-UDI) incorporates a data transfer and interrupt request functions. The H-UDI performs serial transfer through the control of an external signal. The E8000 operates using the H-UDI function. Therefore, the H-UDI cannot be used when the E8000 is used.

3.3.8 Bus State Controller

The SH7612 wait state controller has a programmable wait mode and a WAIT pin input mode. While the programmable wait mode is valid when the emulation memory or user external memory is accessed, input to the user WAIT pin is valid only when user external memory is accessed. However, the EXECUTION_MODE command can be used to enable input to the user WAIT pin during emulation memory access cycles. The refresh cycle controller operates continuously when the emulator is carrying out PSRAM/DRAM/SDRAM refresh control, even during the command input wait state.

3.3.9 System Controller (SYSC)

The system controller (for example, a watchdog timer) generates and controls clock signals for all internal modules and external buses. The watchdog timer stops counting during the command input wait state. Therefore, the frequency cannot be changed with emulator commands. To change the frequency, set the frequency modification register by using the user program.

Section 4 User System Interface

The emulator is connected to the user system with the EV-chip board. Probe signal trace and break can be enabled by connecting the external probe to the user system.

The trigger output probe can output a low-level pulse as an oscilloscope trigger signal. For details, refer to section 1.8, Trigger Output.

User System Interface Circuits: The circuits that interface the SH7612 in the emulator to the user system include buffers and resistors, as described below. When connecting the emulator to the user system, adjust the user system hardware compensating for FANIN, FANOUT, and propagation delays.

The AC timing values with the emulator connected are shown in table 4.1.

Note: The values with the emulator connected, in table 4.1, are measurements for reference but are not guaranteed values.

Table 4.1 Bus Timing (Bus Clock: 30 MHz)

Item	Values with Emulator Connected (ns)
tAD	7.2
tBSD	7.2
tCSD	6.2
tNMIS	32.0
tRWD	6.1
tRSD	4.8
tRESS	19.8
tWDD	4.9
tWED	4.8

Adjust the hardware by taking the above into account. The basic bus cycle (two states) and control signal input timing are shown in figures 4.1 and 4.2, respectively. The user system interface circuits connected to the user system are shown in figure 4.3.

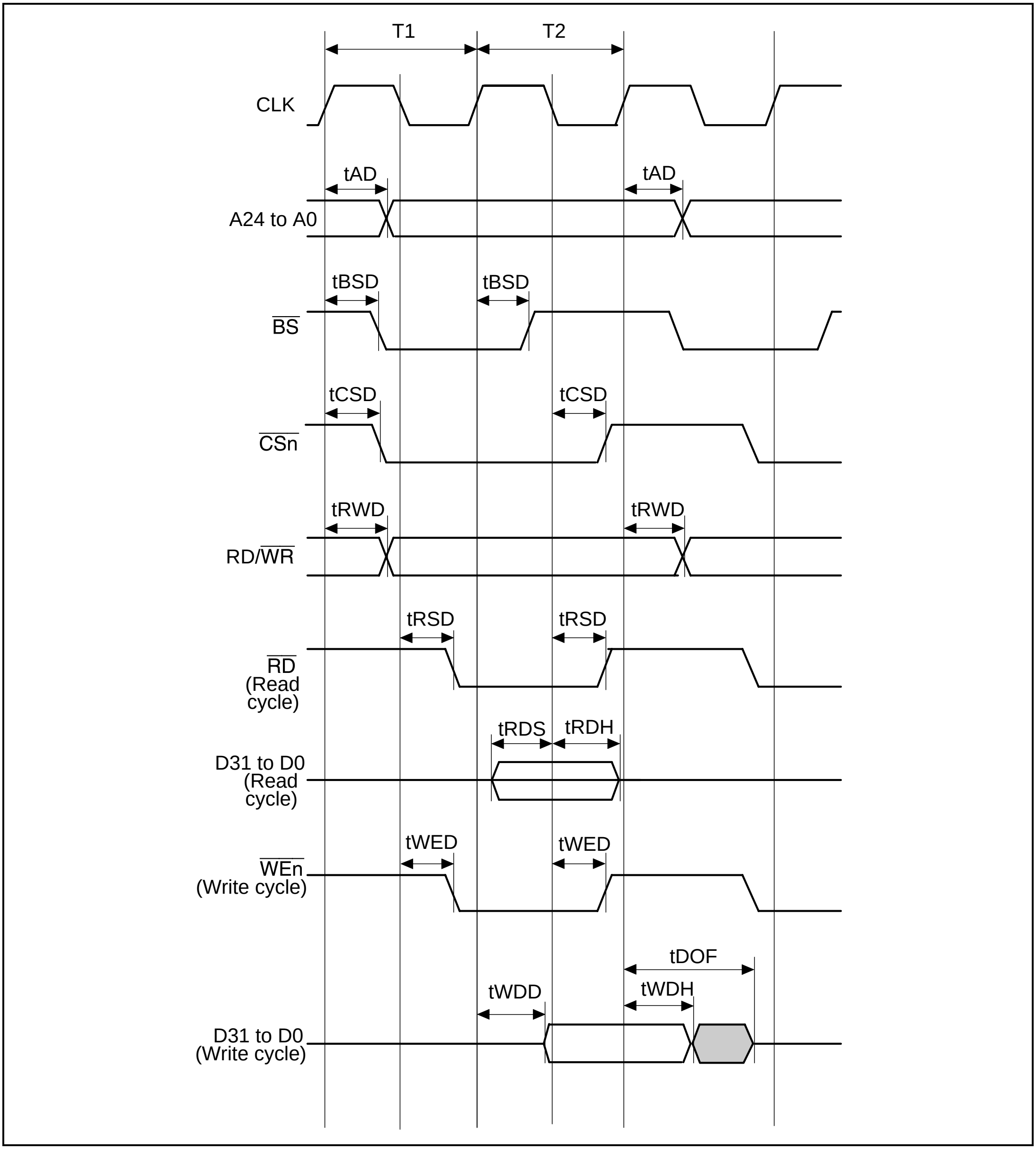


Figure 4.1 Basic Bus Cycle

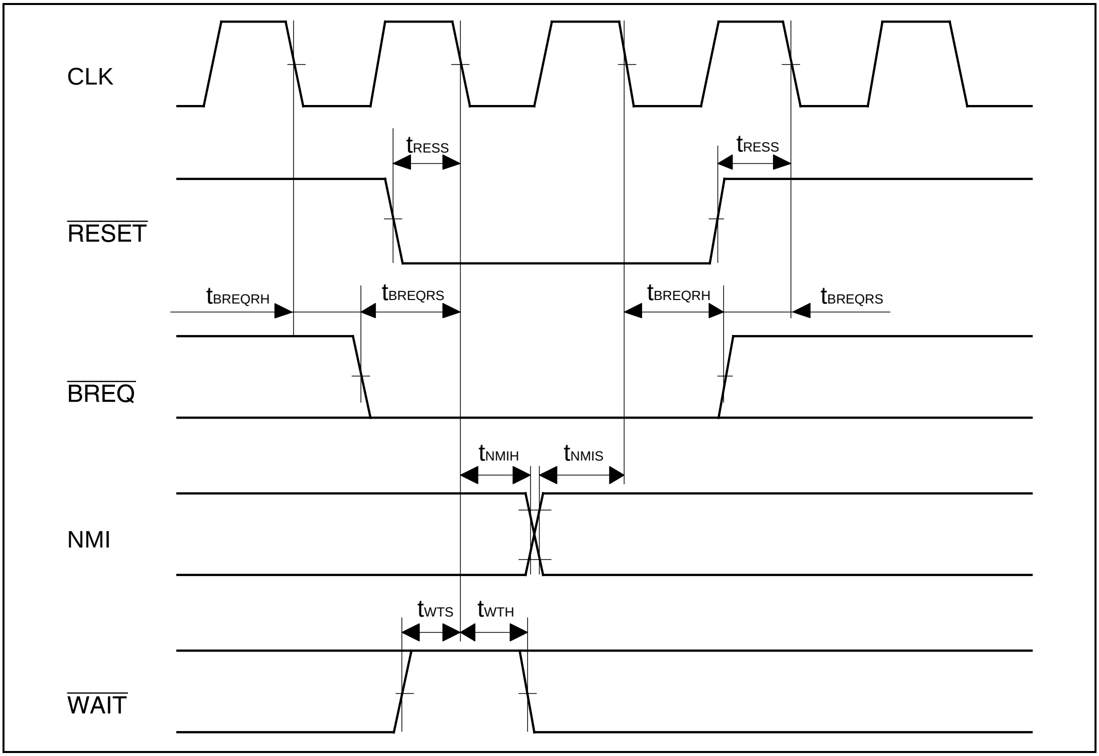


Figure 4.2 Control Signal Timing

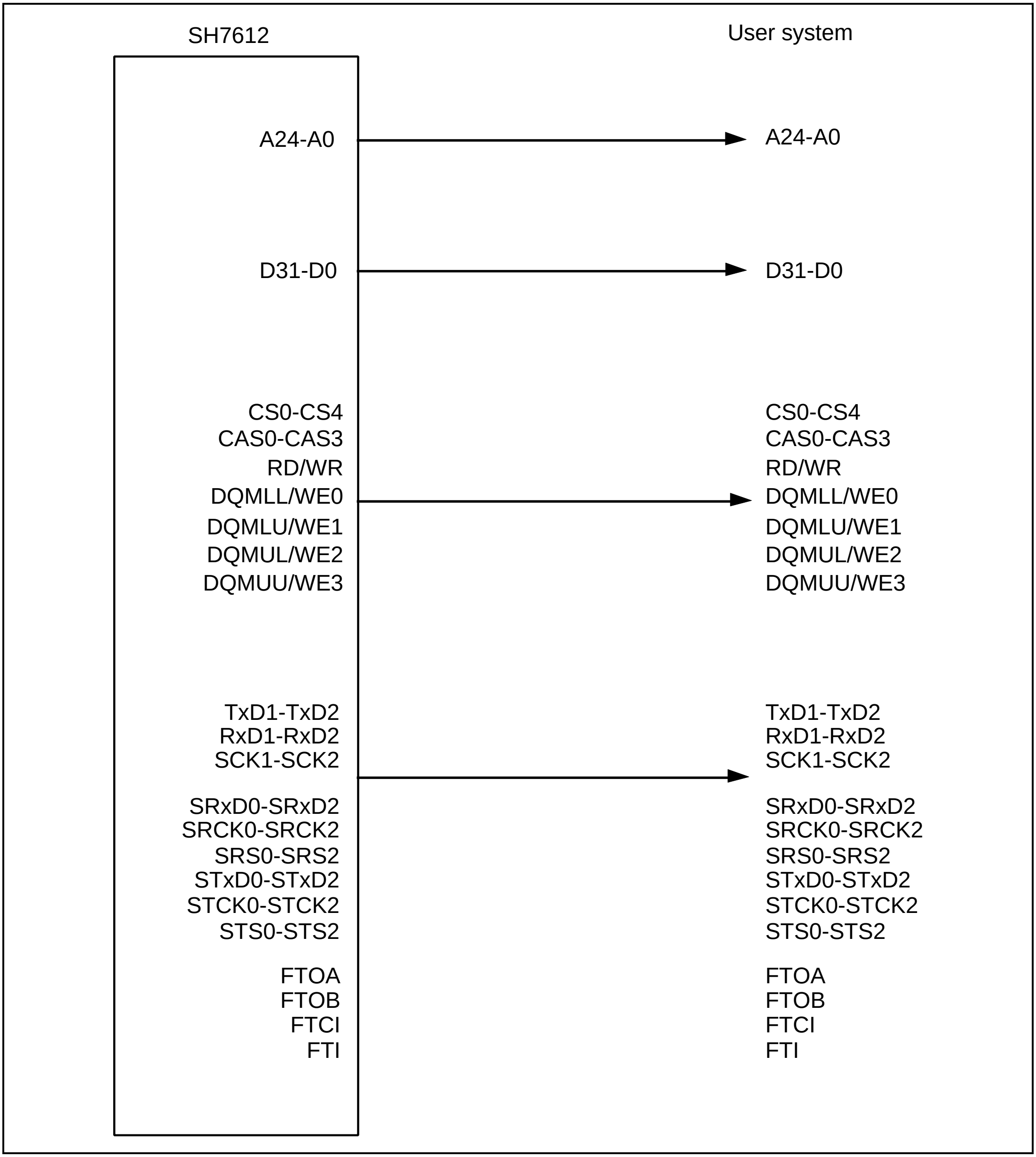


Figure 4.3 User System Interface Circuits

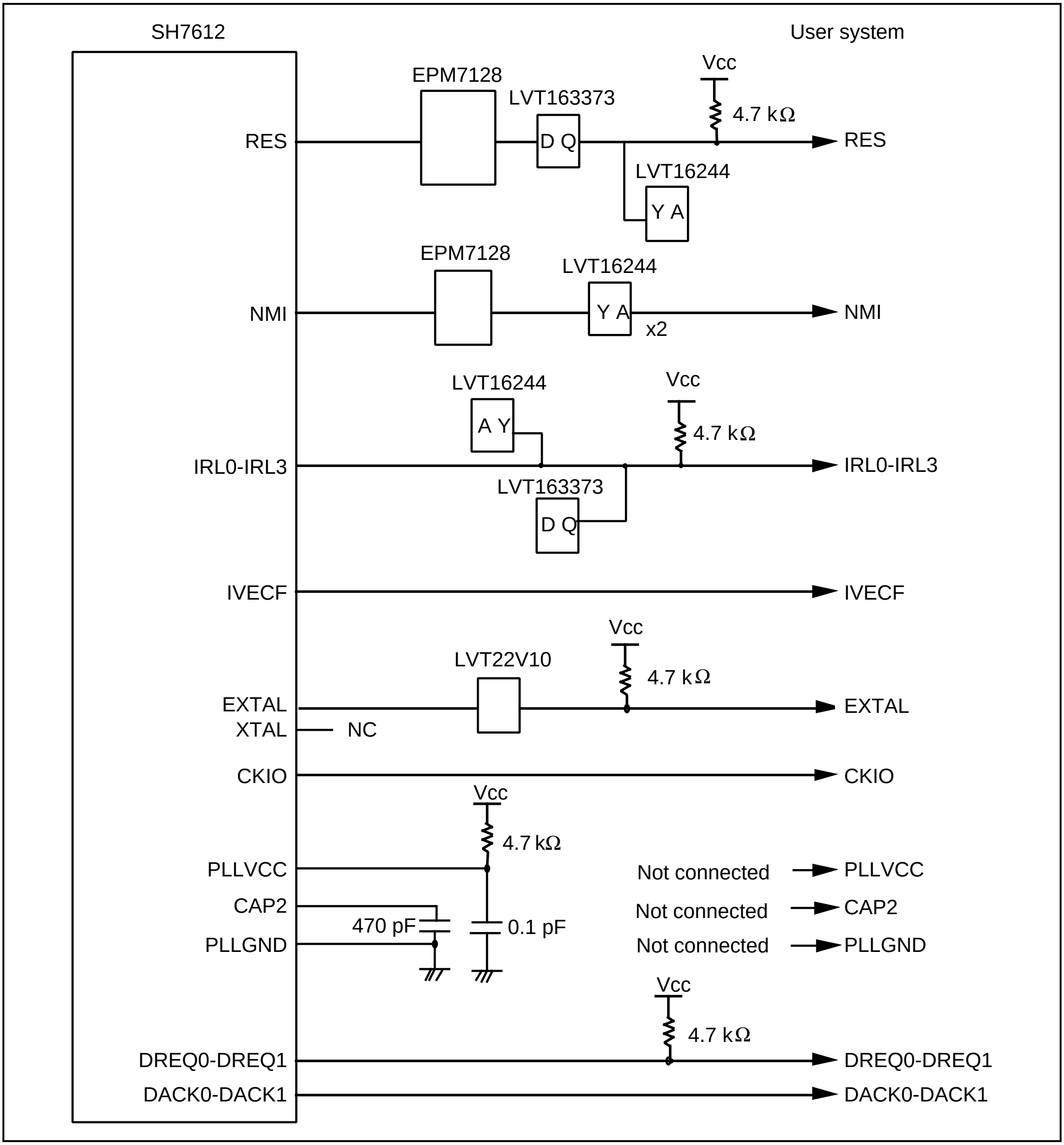


Figure 4.3 User System Interface Circuits (cont)

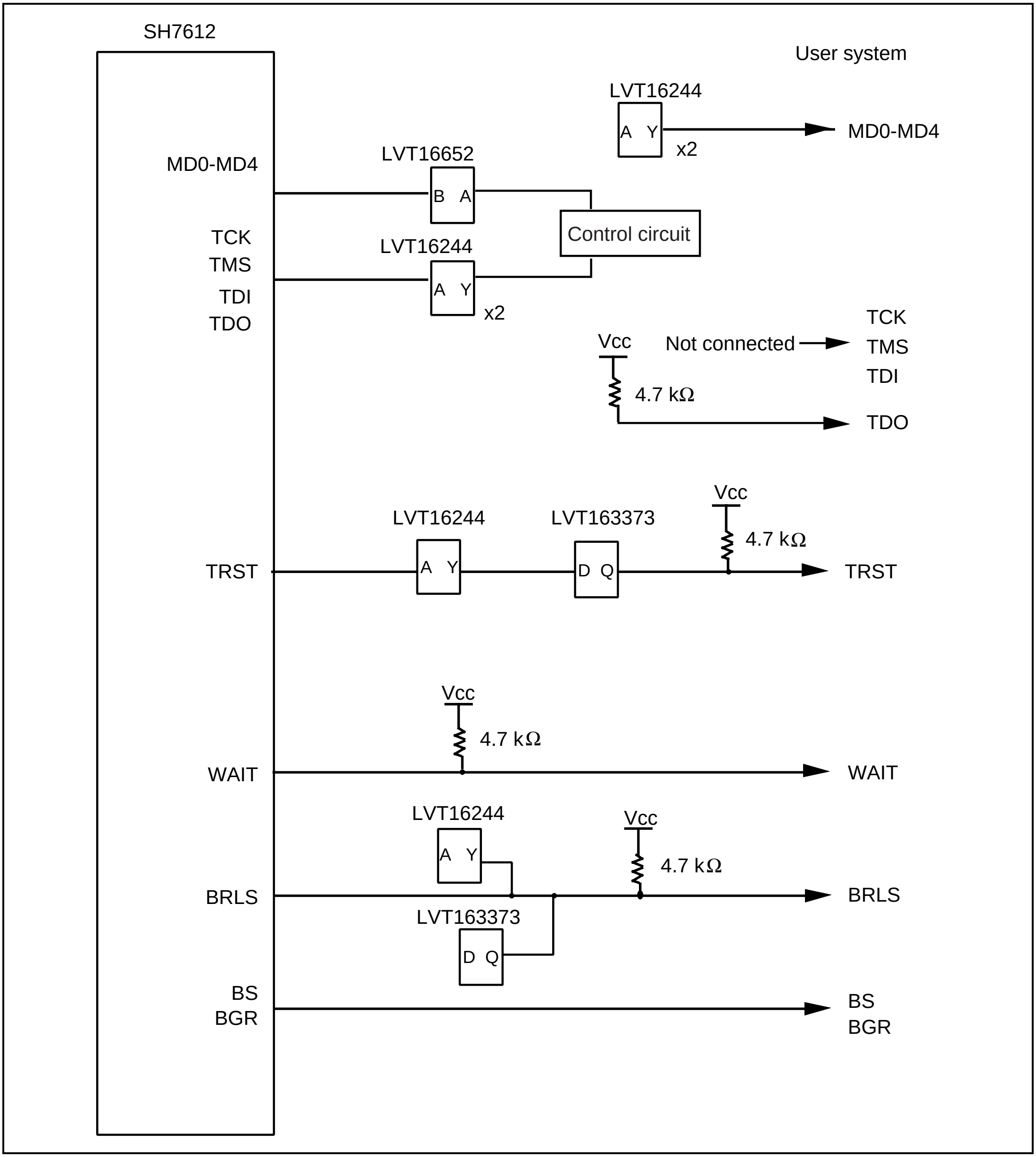


Figure 4.3 User System Interface Circuits (cont)

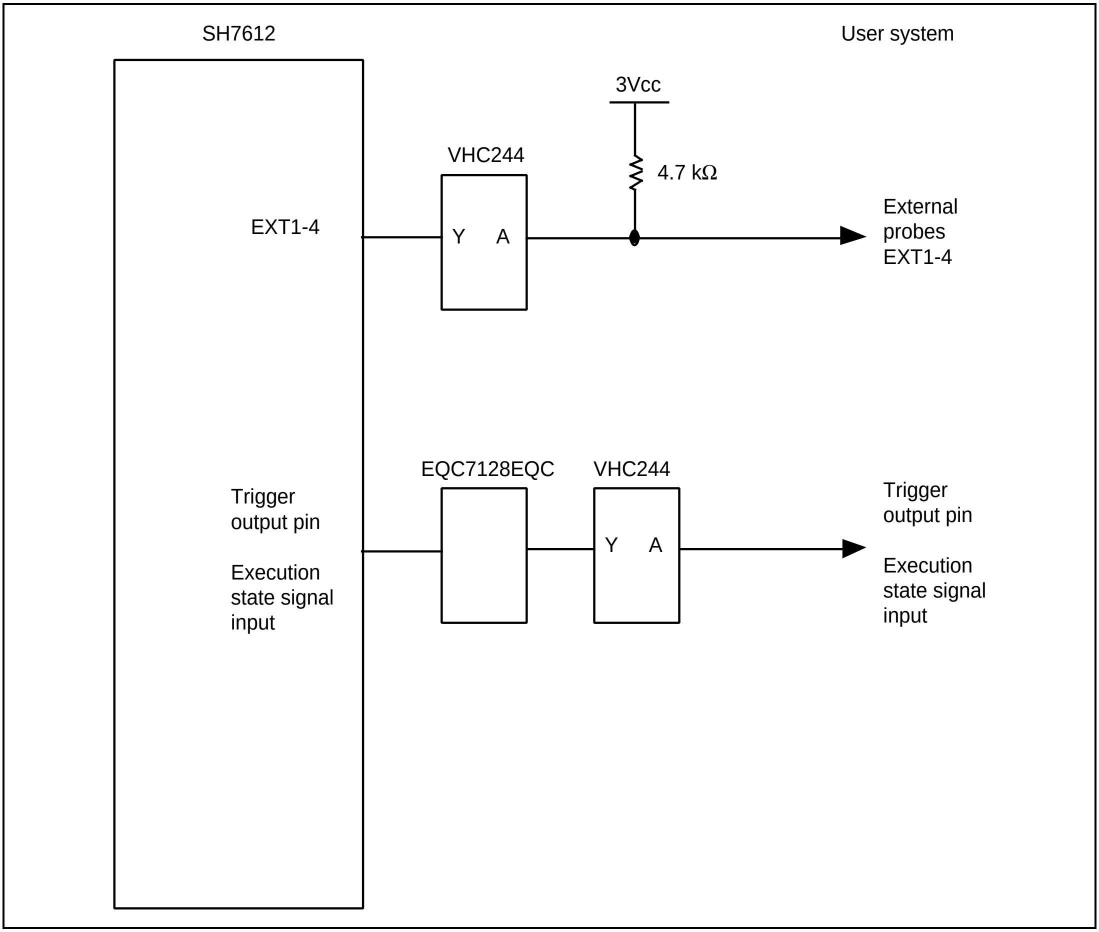


Figure 4.3 User System Interface Circuits (cont)

Section 5 Troubleshooting

The emulator internal system test checks the emulator's internal RAM and registers at power-on and at system program initiation.

5.1 Internal System Test

Internal System Test at Power-On: The emulator checks its internal RAM and registers at power-on. While tests are in progress, the following messages are displayed:

```
E8000 MONITOR (HS8000EST02SR) Vm.n
Copyright (C) Hitachi, Ltd. 1995                   (a)
Licensed Material of Hitachi, Ltd.

TESTING                                            (b)
RAM 0123

START E8000
 S : START E8000
 F : FLASH MEMORY TOOL                             (c)
 L : SET LAN PARAMETER
 T : START DIAGNOSTIC TEST
      (S/F/L/T) ?
```

(a) Emulator monitor start message

(b) Internal RAM and registers are being tested.

- A number from 0 to 3 is displayed as each of the four internal RAM blocks has been tested. If an error occurs, the address, write data, and read data are displayed as follows:

```
** RAM ERROR ADDR=xxxxxxxx  W-DATA=xxxxxxxx  R-DATA=xxxxxxxx
```

- After RAM testing is completed, the registers are tested. No data will be displayed if an error does not occur. If an error occurs, the following message is displayed:

```
*** xxxx REGISTER ERROR W-DATA=xx  R-DATA=xx
```

xxxx: Name of emulator internal register where an error occurs

(c) The emulator monitor is in command input wait state.

Note: Operation continues if an error occurs in step (b), but the error should be investigated according to section 5.2, Troubleshooting Procedure, without loading the emulator system program.

Internal System Test at Emulator System Program Initiation: The emulator system program performs internal system tests, mainly on the emulator registers, at its initiation.

```
SH7612 E8000 (HS7612EDD81SF) Vm.n
Copyright (C) Hitachi, LTD. 1997                (a)
Licensed Material of Hitachi, Ltd.

CONFIGURATION FILE LOADING                      (b)
HARDWARE REGISTER READ/WRITE CHECK              (c)
FIRMWARE SYSTEM LOADING                         (d)
EMULATOR FIRMWARE TEST                          (e)
** RESET BY E8000 !                             (f)
CLOCK = EML                                     (f)
MPU TYPE = SH7612                               (g)
MODE = xx (MD4–0=xx)                            (h)
FAILED AT xxxx                                  (i)
REMAINING EMULATION MEMORY S=4MB                (j)
:_                                              (k)
```

(a) Emulator system program start message. Vm.nn indicates the version number.

(b) Configuration file is being loaded. If an invalid configuration file is assigned, the following message is displayed:

```
*** 54:INVALID CONFIGURATION FILE
```

If no configuration file is contained in the memory, the following message is displayed:

```
*** 55:CONFIGURATION FILE NOT FOUND
```

Re-install the configuration file.

(c) The emulator control registers are being checked. If an error occurs, one of the following messages is displayed:

```
*** xxx  REGISTER ERROR W-DATA = xxxx R-DATA = xxxx                                  (i)
*** SHARED RAM ERROR ADDR = xxxxxx  W-DATA = xxxxxxxx   R-DATA = xxxxxxxx           (ii)
*** BxTBM ERROR  ADDR= xxxxxx  W-DATA= xxxxxxxx   R-DATA = xxxxxxxx                (iii)
*** FIRM RAM ERROR  ADDR= xxxxxx  W-DATA= xxxxxxxx   R-DATA = xxxxxxxx              (iv)
```

(i) An error occurred in the register

xxx: Name of emulator internal register where an error occurs

B0TRAR, ECT, B0CNR, B0MDCNR, B0MASCR, B0CECR, B1CNR, B1MDCNR, B1MASCR, B1CECR, MAPR0, MAPR1, MAPR2, MAPR3

(ii) An error occurred in the shared RAM

(iii) An error occurred in the trace buffer memory

(iv) An error occurred in the firm RAM area (d), (e) The device control board is being tested. If an error occurs, the following message is displayed:

```
*** INVALID FIRMWARE SYSTEM                        (i)
*** EMULATOR FIRMWARE NOT READY                    (ii)
*** FIRMWARE SYSTEM FILE NOT FOUND                 (iii)
```

- (i) The incorrect MCU device control board is connected. Please check the MCU type and use the appropriate emulator system program, or exchange the device control board.
- (ii) The device control board is not connected correctly. Connect the device control board to the emulator correctly.
- (iii) Correct system program for the device control board is not loaded in the memory. Re-install the correct emulator system program and restart the emulator.

(f) The RES signal is input to the MCU, and the specified clock type is displayed.

Note: (f) is not executed if an error has occurred in step (c), (d), or (e)

(g) The MCU type is displayed.

(h) The MCU operating mode on the emulator and the status of user system mode selection pins.

(i) MCU pins are being checked. For details, refer to section 7.2.10, CHECK.

Note: (h) is not executed if an error has occurred in step (c), (d), or (e)

(j) The remaining emulation memory size that can be assigned.

(k) The emulator system program is initiated and the command input wait state is entered.

Emulator System Failure: If an invalid exception occurs during emulator monitor or emulator system program execution, the system shuts down. No key input from the key board will be received but the following message is displayed:

```
<exception>   PC=xxxxxxxx
***  E8000  SYSTEM  DOWN  ***
```

If an error occurs, re-execute using another system disk. If an error still occurs, inform a Hitachi sales agency of the error.

5.2 Troubleshooting Procedure

This section provides a troubleshooting Problem Analysis Diagram (PAD, see figure 5.1) to reduce the time taken by troubleshooting.

As you work through the diagram:

- Follow the instructions that request operator assistance or intervention.
- Note that “system defect” means that the emulator station is malfunctioning. Execute the diagnostic program as described in the Diagnostic Program Manual (HS7612TM81ME), and inform a Hitachi sales agency of the test results in detail because a system defect may be caused by a number of reasons.

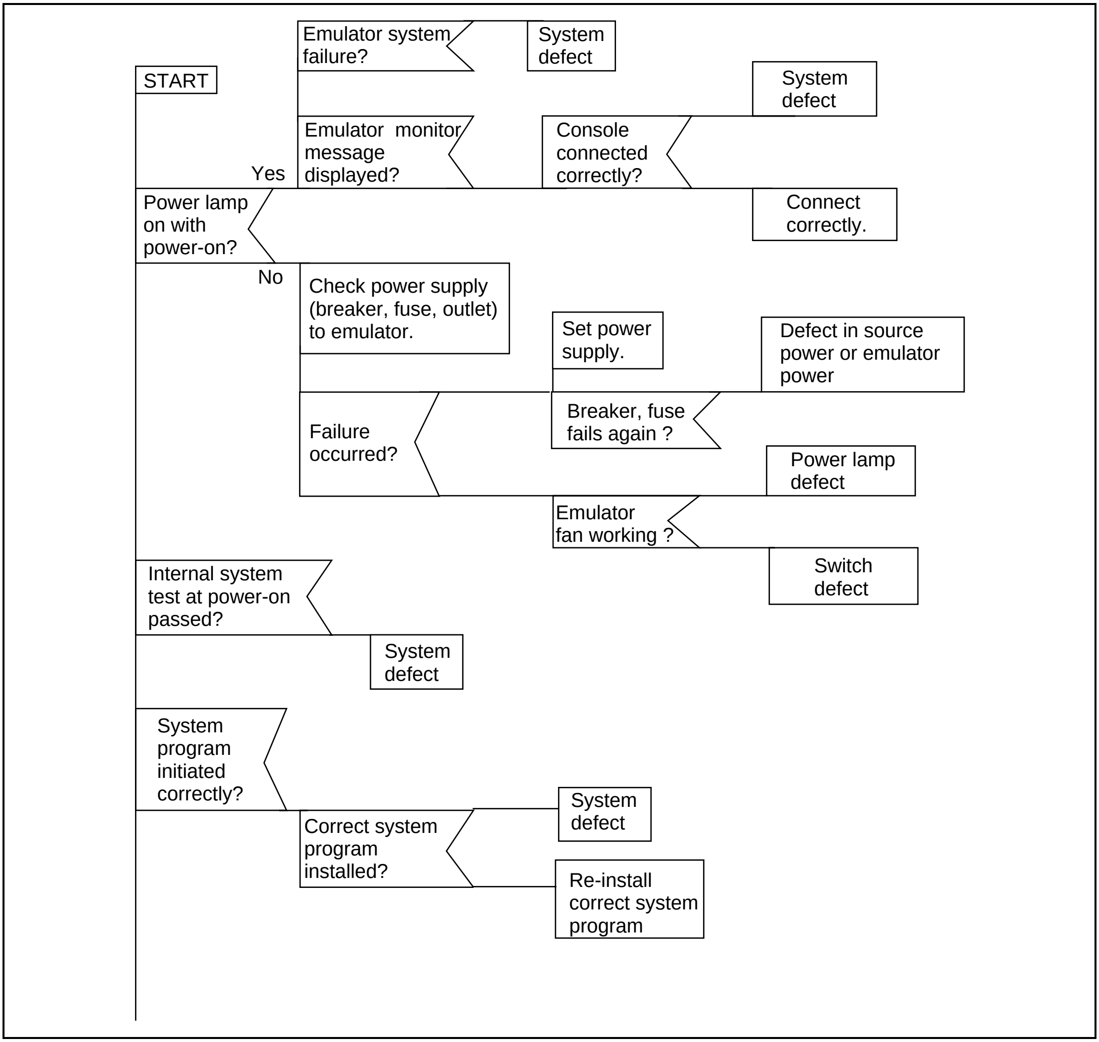


Figure 5.1 Troubleshooting PAD

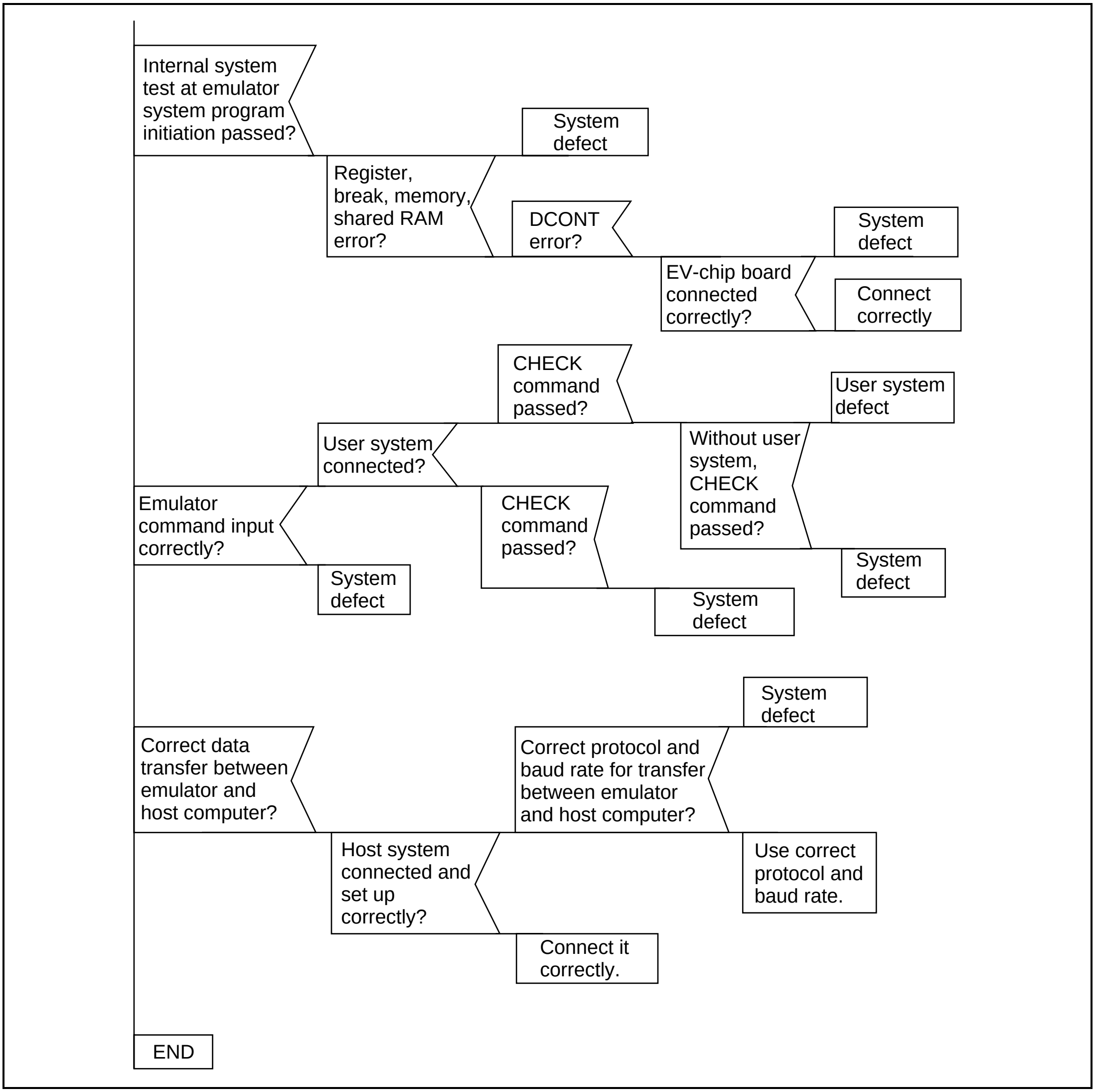


Figure 5.1 Troubleshooting PAD (cont)

Section 6 Command Input and Display

6.1 Command Syntax

6.1.1 Command Input Format

The emulator command format is as follows:

<command>Δ<parameter>;<option> (RET)

Δ: Space
(RET): (RET) key

Note that each command can be specified in abbreviated form to facilitate keyboard operations.

6.1.2 Help Function

All emulator commands can be displayed by entering the HELP command. Any command input format can be displayed by specifying the command name as a parameter of the HELP command.

- To display all emulator commands

  : ***HELP (RET)***
  <All commands are displayed in their full names and abbreviations>

- To display a command input format

  : ***HELPΔ<command name> (RET)***
  <A command input format is displayed>

  In this example, an abbreviation of the command name can be entered as <command name>.

6.1.3 Word Definition

Constants or file names can be entered as command parameters or options. Spaces (Δ) or commas (,) can be inserted between words. Words are described below:

Constants: Numeric constants, character constants, and expression can be used as constants.

- Numeric constants

  The following shows numeric constant formats. A radix is entered at the head of a numeric constant.

  S'nnnnnnnn

  S: Radix of a constant
    B: Binary
    Q: Octal
    D: Decimal
    H: Hexadecimal
    X: Fixed-point
    Default: Value specified with the RADIX command
  nnnnnnnn: Value based on the radix (4-byte value maximum)

  Example: To indicate 100 in decimal:
  D'100

  If the radix is omitted, the radix specified with the RADIX command is automatically used.

  Example: If the radix is omitted while hexadecimal is specified with the RADIX command, entering 10 means H'10.

- Character constants

  Enclosed with single or double quotation marks. If a single or double quotation mark is used as data, add two sequential quotation marks.

  Example 1: ' A' = H'41
  Example 2: ' ' ' = H'27 (single quotation mark ')

  Multiple characters can be included inside the quotation marks within the specified data size as shown below.

  Example: ' AB' = H'4142 (2-byte data)

- Expression

  An expression can be described using numeric constants, character constants, and operators. As an operator, + (addition) or – (subtraction) can be specified.

  Examples: D'10 + H'20
  20 – 4
  –1

File Name: A file name can be specified as a command parameter. The general file name format is as follows:

<drive name>:<file name>.<extension>

6.2 Special Key Input

The emulator supports special key functions to facilitate keyboard operations. In the following description, CTRL + X means pressing the CTRL and X keys simultaneously.

6.2.1 Command Execution and Termination

• Command execution	(RET)	Enters all characters on that line, regardless of the cursor position, and executes the command.
• Command termination	CTRL + C, (BREAK)	Terminates command execution. All characters typed so far are lost and the emulator enters command input wait state.

6.2.2 Display Control

• Display stop	CTRL + S	Temporarily stops display. Resumes display by entering CTRL and Q keys.
• Display restart	CTRL + Q	Resumes display.

6.2.3 Command Re-entry

• Display last entered line	CTRL + L	Redisplays the last line entered. Pressing these keys will repeatedly redisplay up to 16 lines and then return to the last line again.
• Display last entered command	<command name>.	When a period is entered after a command, the previously input parameters of that command are displayed. If two periods are entered after a command, parameters of two commands prior to the entered command are displayed. This key input is useful for executing commands with the same parameters again. (Example) :***D 1000 1010 (RET)*** : Execution of another command :***D. (RET)*** :***D 1000 1010*** : Displays the parameters specified in the previous DUMP command execution and enters command input wait state.

6.2.4 Cursor Control and Character Editing

• Move cursor backwards	CTRL + H	Moves the cursor one position backwards.
• Move cursor to word starting position	CTRL + T	Moves the cursor to the first position of the word (the character following the space).
• Delete one character	CTRL + D	Deletes a character at the cursor position.
• Cancel line	CTRL + X	Deletes the contents of the entire line.
• Advance cursor	CTRL + W	Moves the cursor one position forwards.
• Insert space	CTRL + U	Inserts a space at the cursor.
• Tab over	CTRL + I	Moves the cursor to the (10’s multiple + 1)th column.

Section 7 Emulation Commands

7.1 Overview

The emulator provides a wide range of functions such as break, trace, and performance analysis. Table 7.1 lists the emulation commands that enable these functions.

Table 7.1 Emulation Commands

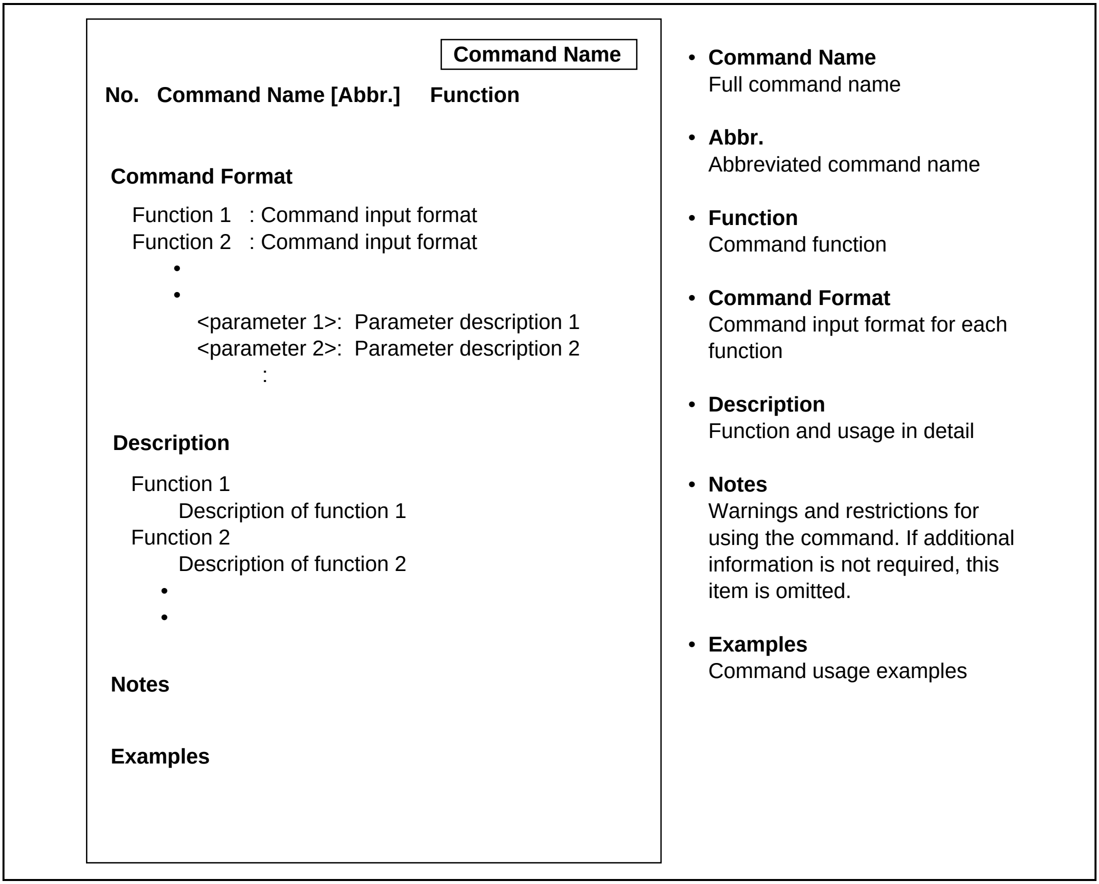
Command	Function	Usable/Unusable in Parallel Mode
.<register>	Modifies and displays register contents	Unusable
ABORT	Terminates emulation in parallel mode	Usable
ALIAS	Sets, displays, and cancels aliases	Usable
ASSEMBLE	Assembles program one line each	Unusable
BACKGROUND_ INTERRUPT	Sets and displays user interrupts in command input wait state	Unusable
BREAK	Sets, displays, and cancels software breakpoints	Only display function is available
BREAK_CONDITION_ A,B,C	Sets, displays, and cancels hardware break conditions	Only display function is available
BREAK_CONDITION_ UBC	Sets, displays, and cancels hardware break conditions	Only display function is available
BREAK_SEQUENCE	Sets, displays, and cancels software sequential breakpoints	Only display function is available
CHECK	Tests SH7612 pin status	Unusable
CLOCK	Sets and displays clock	Only display function is available
CONFIGURATION	Saves and restores configuration information, and displays a list	Unusable
CONVERT	Converts data	Usable
DATA_CHANGE	Replaces memory data	Unusable
DATA_SEARCH	Searches for memory data	Unusable
DISASSEMBLE	Disassembles and displays memory contents	Usable
DUMP	Displays memory contents	Usable
END	Cancels parallel mode	Usable
EXECUTION_MODE	Sets and displays execution mode	Unusable
FILL	Writes data to memory	Unusable

Table 7.1 Emulation Commands (cont)

Command	Function	Usable/Unusable in Parallel Mode
GO	Executes realtime emulation	Unusable
HELP	Displays all commands and command format	Usable
HISTORY	Displays all input commands	Usable
ID	Displays the version number of the E8000 system program	Usable
MAP	Specifies and displays memory attribute	Unusable
MEMORY	Displays and modifies memory contents	Usable
MODE	Specifies and displays the SH7612 operating mode	Unusable
MOVE	Transfers memory contents	Unusable
MOVE_TO_RAM	Moves ROM contents to standard emulation memory	Unusable
PERFORMANCE_ ANALYSIS	Specifies, cancels, initializes, and displays performance analysis data	Usable
QUIT	Terminates E8000 system program	Unusable
RADIX	Specifies and displays radix for numeric input	Usable
REGISTER	Displays register contents	Unusable
RESET	Resets SH7612	Unusable
RESULT	Displays execution results	Unusable
STATUS	Displays emulator execution status	Usable
STEP	Performs single-step execution	Unusable
STEP_INFORMATION	Specifies and displays information during single-step execution	Unusable
STEP_OVER	Performs single-step execution except for subroutines	Unusable
TRACE	Displays trace buffer contents	Usable
TRACE_CONDITION_ A,B,C	Specifies, displays, and cancels trace acquisition conditions	Usable
TRACE_DISPLAY_ MODE	Specifies and displays trace information display mode	Usable
TRACE_MODE	Specifies and displays trace information acquisition mode	Unusable
TRACE_SEARCH	Searches for and displays trace information	Usable

7.2 Emulation Commands

This section provides details of emulation commands in the format shown in figure 7.1.



Command Name

No. Command Name [Abbr.] Function

Command Format

Function 1 : Command input format
Function 2 : Command input format
•
•
<parameter 1>: Parameter description 1
<parameter 2>: Parameter description 2
:

Description

Function 1
Description of function 1
Function 2
Description of function 2
•
•

Notes

Examples

- **Command Name**
  Full command name
- **Abbr.**
  Abbreviated command name
- **Function**
  Command function
- **Command Format**
  Command input format for each function
- **Description**
  Function and usage in detail
- **Notes**
  Warnings and restrictions for using the command. If additional information is not required, this item is omitted.
- **Examples**
  Command usage examples

Figure 7.1 Emulation Command Description Format

Symbols used in the command format have the following meanings:

[ ]:	Parameters enclosed by [ ] can be omitted.
(a/b):	One of the parameters enclosed by ( ) and separated by /, that is, either a or b must be specified.
< >:	Contents shown in < > are to be specified or displayed.
... :	The entry specified just before this symbol can be repeated.
Δ:	Indicates a space. Used only for command format description.
(RET):	Pressing the (RET) key.

Although italic and bold characters are used throughout this manual to indicate input, it is not used in the command format parts of these descriptions.

7.2.1 .<register> [.<register>] Modifies and displays register contents

Command Format

- Modification (direct mode) .<register>[Δ<data>] (RET)
- Modification (interactive mode) .<register> (RET)

<register>: System register, control register, general register, or DSP register to be modified or displayed.

System registers: PC, PR, MACH, MACL

Control registers: SR, GBR, VBR, RS, RE, MOD

General registers: R0, R1, R2, R3, R4, R5, R6, R7, R8,
R9, R10, R11, R12, R13, R14, R15 (SP)

DSP registers: DSR, A0G, A0, A1G, A1, M0, M1, X0, X1, Y0, Y1

<data>: The value to be set in the specified register

Description

- Modification

— Direct mode

Sets the specified value in the specified register. SP can be specified instead of R15. MOD can be specified separately as MS and ME; 16-bit unit each.

: ***.<register> <data> (RET)***

— Interactive mode

If no data is specified on the command line with <register>, register modification is performed in interactive mode. In this case, the emulator displays the current register value and requests its modification. Registers are processed in the following order (and processing can begin at any register):

R0 to R14, R15 (SP), PC, SR, PR, GBR, VBR, MACH, MACL, RS, RE,
MOD, A0G, A0, A1G, A1, M0, M1, X0, X1, Y0, Y1, DSR

Display format for modifying registers in interactive mode is as follows:

```
:.<register> (RET)
   <register>     =xxxxxxxx ?      yyyyyyyy (RET)
   <register>     =xxxxxxxx ?      yyyyyyyy (RET)
       .              .                  .
       .              .                  .
```

yyyyyyyy <data>: Inputs the value to be newly set

.: Terminates the command

^: Displays the previous register

Only (RET): Does not modify the register; displays the following one

To display all register contents, use the REGISTER command.

Note

Registers are set as follows at emulator initiation:

R0 to R14 : H'00000000
R15 (SP) : Power-on reset vector value
MACH : H'00000000
PC : Power-on reset vector value
PR : H'00000000
MOD : H'00000000
A0G, A1G : H'00

VBR : H'00000000
GBR : H'00000000
MACL : H'00000000
SR : H'000000F0
RS, RE : H'00000000
DSR : H'00000000
A0, A1, M0, M1, X0, X1, Y0, Y1 : H'00000000

If the SH7612 is reset by the emulator RESET or CLOCK command, registers are set as follows.

R0 to R14 : The value before reset
R15 (SP) : Power-on reset vector value
MACH : The value before reset
PC : Power-on reset vector value
PR : The value before reset
MOD : The value before reset
A0G, A1G : The value before reset

VBR : H'00000000
GBR : The value before reset
MACL : The value before reset
SR : H'000000F0
RS, RE : The value before reset
DSR : H'00000000
A0, A1, M0, M1, X0, X1, Y0, Y1 : The value before reset

Since the reset values of R0 to R14 in the SH7612 are not fixed, the initial values must be set by a program.

Examples

1. To set H'5C60 in PC, H'FFE00 in SP, H'FF in R1, and H'11 in R2, and then display all registers:

```
:.PC 5C60 (RET)
:.SP FFE00 (RET)
:.R1 FF (RET)
:.R2 11 (RET)
:R (RET)
 PC=00005C60 SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
:
```

2. To modify the contents of control registers in interactive mode:

```
:.PC (RET)
 PC    =00001000 ? 2000 (RET)
 SR    =000003F3 : ****000000000000****--MQIIII00ST ? 303 (RET)
 PR    =00000000 ? . (RET)
:
```

7.2.2 ABORT [AB] Terminates emulation in parallel mode

Command Format

- Termination ABORT (RET)

Description

- Termination
  - Terminates GO command execution in parallel mode (prompt #), and cancels parallel mode.
  - When GO command execution is terminated by the ABORT command in parallel mode, BREAK KEY is displayed as the termination cause.

Example

To terminate GO command emulation in parallel mode:

```
:G RESET (RET)
 ** PC=00001022              (RET)           (To enter parallel mode)
#AB (RET)
 PC=00005C60  SR=000000F0:****000000000000****----IIII00--
 GBR=00000000  VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000  RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 RUN-TIME=D'000H:00M:03S:000409US:120NS
 +++:BREAK KEY
:
```

7.2.3 ALIAS [ALI] Sets, displays, and cancels aliases

Command Format

- Setting ALIASΔ<alias name>Δ<alias definition> (RET)
- Display ALIAS (RET)
- Cancellation ALIAS[Δ]–Δ <alias name> (RET)
  ALIAS[Δ]– (RET)

<alias name>: Alias definition name
<alias definition>: Alias definition contents

Description

- Setting

  Sets aliases for commands. Up to 40 aliases can be set. An alias name is defined with up to 16 characters and an alias definition with up to 230 characters.

  ```
  : ALIASΔ<alias name> Δ <alias definition>  (RET)
  ```

- Display

  Displays defined aliases as follows:

  ```
  : ALIAS (RET)
    <alias name 1>:<alias definition 1>
    <alias name 2>:<alias definition 2>
    <alias name 3>:<alias definition 3>
        :           :
  ```

- Cancellation

  — Cancels the specified alias.

  ```
  : ALIAS – Δ<alias name>  (RET)
  ```

  — When no alias name is specified, cancels all aliases.

  ```
  : ALIAS –  (RET)
  ```

Note

An alias itself cannot be included in the alias definition contents.

Examples

1. To define the alias name for the command to display the contents of register FRC0H as SHOW_FRC0H:

```
:ALI SHOW_FRC0H D 0D000042 @1;B (RET)
:
```

2. To display all defined aliases:

```
:ALI (RET)
 SHOW_FRC0H: D 0D000042 @1;B
 SHOW_FRC0L: D 0D000043 @1;B
 LT: 11 test.abs
:
```

3. To cancel the alias with alias name LT:

```
:ALI– LT (RET)
:
```

7.2.4 ASSEMBLE [A] Assembles program one line each

Command Format

- Line assembly ASSEMBLE Δ<address> (RET)

<address>: The address where the object program is to be written

Description

- Line assembly

— After displaying the memory contents at the specified address, the emulator enters subcommand input wait state. Line input in subcommand input wait state is assembled into machine code which is written to memory. Assembly is continued until a period (finishing subcommand) is entered. The input and output formats are as follows:

```
: ASSEMBLE <address> (RET)
   xxxxxxxx   <disassemble display>
   xxxxxxxx   ?  <subcommand> (RET)
   xxxxxxxx   ?  <subcommand> (RET)
       :          :         :
      (a)                  (b)
```

(a) Address. When an odd address is specified, it is rounded down to an even address.

(b) Subcommand (Input the contents shown in table 7.2).

The subcommands listed in table 7.2 can be used with the ASSEMBLE command:

Table 7.2 Subcommands for Line Assembly

Subcommand	Description
<assembly language statement>	Assembles the input line (statement) into machine code and writes it to the displayed address.
/[<address 1>[Δ<address 2>]]	Disassembles instructions from <address 1> to <address 2> and displays them. If <address 2> is omitted, the first 16 instructions from <address 1> are displayed. If only a slash (/) is input, the contents from the ASSEMBLE command start address to the current address – 1 are disassembled.
(RET) only	Increments the address (odd address + 1, even address + 2), and re-enters subcommand input wait state.
^	Decrements the address (odd address – 1, even address – 2), and re-enters subcommand input wait state.
.	Terminates the ASSEMBLE command.

— Even if an odd address is specified, machine codes are written to memory. In that case, the following warning message is displayed:

*** 82:ODD ADDRESS

— Line assembly with this command can be performed only in areas CS0 to CS4 or the internal memory areas.

Example

To perform line assembly from address H'1000:

```
:A 1000 (RET)
 00001000   .DATA.W  0000
 00001000 ?  LDRS @(4,PC) (RET)
 00001002 ?  LDRE @(2,PC) (RET)
 00001004 ?  SETRC #D’128 (RET)
 00001006 ?  NOP (RET)
 00001008 ?  PADD X0,Y0,A0 PMULS A1,X0,M0 MOVX.W @R4+,X0 MOVY.W @R6+,Y0 (RET)
 0000100C ? .(RET)
:
```

7.2.5 BACKGROUND_INTERRUPT [BI] Sets and displays user interrupts in command input wait state

Command Format

- Setting BACKGROUND_INTERRUPT [Δ(E[:<loop program address>]/D)] [;C] (RET)
- Display BACKGROUND_INTERRUPT (RET)

E/D:	User interrupt accepting mode in command input wait state
E:	Enables user interrupts in command input wait state
D:	Disables user interrupts in command input wait state (default at emulator shipment)
<loop program address>:	Address of the loop program for accepting user interrupts. When omitted, the last address of internal Y-RAM area – 3
C:	Stores the settings as configuration information in emulator flash memory

Description

- Setting
  - Enables user interrupts in command input wait state and sets the address of the loop program for accepting user interrupts. If the above settings are reset when user interrupts have already been enabled, even in the middle of the user interrupt processing, the emulator forcibly terminates the processing and then initiates the loop program for accepting user interrupts again.

    : ***BACKGROUND_INTERRUPT E (RET)***

  - Enables user interrupts in command input wait state and sets the address of the loop program for accepting user interrupts. The loop program must be stored in the RAM area. If no address is specified, the address specified before is used. After setting, the loop program execution starts.

    : ***BACKGROUND_INTERRUPT E:0000FFFC (RET)***

  - Disables user interrupts in command input wait state.

    : ***BACKGROUND_INTERRUPT D (RET)***

- When the C option is specified, the following message is displayed to confirm with the user whether to overwrite the existing configuration information in the emulator flash memory.

```
CONFIGURATION STORE OK (Y/N) ?        (a) (RET)
```

(a) Y: Stores the specifications as configuration information in emulator flash memory. Hereafter, when the emulator is activated, the saved specifications go into effect.

N: Does not overwrite configuration information. The existing specifications are valid.

- When user interrupts are enabled in command input wait state (E is specified), only commands usable in parallel mode and the BACKGROUND_INTERRUPT command can be executed.

- Display

Displays user interrupt accepting mode in command input wait state and the executing address of the loop program for accepting user interrupts. If a break has occurred during user interrupt processing and the loop program has been stopped, the register values at termination and the cause of termination are displayed in the following format.

```
: BACKGROUND_INTERRUPT  (RET)
 USER INTERRUPT=x  LOOP PROGRAM ADDRESS=yyyyyyyy
 [<cause of termination>]
```

x: User interrupt accepting mode

- E: User interrupts are enabled (the loop program is being executed)
- D: User interrupts are disabled (the loop program has been stopped)
- S: A break has occurred during user interrupt processing (the loop program has been stopped)

yyyyyyyy: Address of loop program for accepting user interrupts

<cause of termination>: Register values and the cause of termination (listed in table 7.3) at loop program termination (displayed only when S is selected above)

Display format is as follows:

```
-PC=00005C60  SR=00000000:****000000000000****--------00--
-GBR=00000000  VBR=00000000  MACH=00000000  MACL=00000000  PR=00000000
-RS=00000000  RE=00000000  MOD=00000000
-R0–7   00000000  000000FF  00000011  00000000  00000000  00000000  00000000  00000000
-R8–15  00000000  00000000  00000000  00000000  00000000  00000000  00000000  000FFE00
-DSR=00000000:************************----COB-
-A0G=00  A0=00000000  M0=00000000  X0=00000000  Y0=00000000
-A1G=00  A1=00000000  M1=00000000  X1=00000000  Y1=00000000
+++: <cause of termination>
```

Table 7.3 Causes of BACKGROUND_INTERRUPT Command Termination

Message	Termination Cause
ILLEGAL INSTRUCTION	An illegal instruction was executed.
RESET BY E8000	The emulator terminates program execution with the RESET signal because an error has occurred in the user system.
LOOP PROGRAM ADDRESS IS NOT IN RAM	The executing address of the loop program for accepting user interrupts is not in the RAM area; therefore, the loop program cannot be executed.
STOPPED IN INTERRUPT PROCESS	A break occurred during the user interrupt processing.

Notes

1. In command input wait state, a BRA $ or NOP instruction (instruction code: H'AFFE0009) is set to the address of the loop program for accepting user interrupts and executed. Note the following:
   - Do not specify the address of the loop program for accepting user interrupts in the ROM area. If the specified address is in the ROM area, the loop program cannot be executed. Specify an address within the RAM area and enable user interrupts (select option E) again.
   - Specify the address of the loop program for accepting user interrupts within an area that is not used by the user program. The loop program requires a 4-byte area.
   - When the address of the loop program for accepting user interrupts is specified, the memory contents before this specification are not stored. Therefore, the contents of the loop program address is a BRA $ instruction even after user interrupts are disabled or after the loop program address is changed.

2. When one of the causes of termination listed in table 7.3 occurs during interrupt processing in command input wait state, the interrupt processing stops there. If an emulation command is executed in this state, the following message is displayed after the emulation command execution. In this case, either change the interrupt processing program and enable user interrupts, or disable user interrupts.

   ```
   *** 66: STOPPED THE BACKGROUND INTERRUPT
   ```

3. Do not use this command when using a system, such as an OS, that does not return from the user interrupt processing to the routine where the interrupt has occurred. If used, execution does not return to the loop program for accepting user interrupts even after the user interrupt processing has terminated.
4. Do not generate a reset exception when user interrupts are enabled. If generated, the user program is initiated and execution does not return to the loop program for accepting user interrupts.
5. During user interrupt processing in command input wait state, the software breakpoints (set with the BREAK or BREAK_SEQUENCE command) and hardware break conditions become invalid.
6. During user interrupt processing in command input wait state, no trace information is acquired.

Examples

1. To specify the executing address of the loop program for accepting user interrupts to H'FFFC, and begin to accept user interrupts in command input wait state:

```
:BI E:FFFC (RET)
:
```

2. To display the current user interrupt accepting mode in command input wait state:

```
:BI (RET)
 USER INTERRUPT=S LOOP PROGRAM ADDRESS=0000FFFC
-PC=00005C60 SR=00000000:****000000000000****--------00--
-GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
-RS=00000000 RE=00000000 MOD=00000000
-R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
-R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
-DSR=00000000:************************----COB-
-A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
-A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 +++:ILLEGAL INSTRUCTION
:
```

7.2.6 BREAK [B] Sets, displays, and cancels software breakpoints

Command Format

- Setting BREAKΔ<software breakpoint to be set>[[,<software breakpoint to be set>]...] (RET)
- Display BREAK (RET)
- Cancellation BREAK[Δ]–[<software breakpoint to be cancelled>[,<software breakpoint to be cancelled>]...] (RET)

<software breakpoint to be set>:	<address>[Δ<number of times>]
<address>:	Software breakpoint address
<number of times>:	How many times the specified software breakpoint is to be passed (H'1 to H'FFFF) (Default: H'1)
<software breakpoint to be cancelled>:	Address of the software breakpoint to be cancelled

Note: When an odd address is specified, it is rounded down to an even address.

Description

- Setting

— Sets a software breakpoint at the specified address by replacing its contents with a break instruction (H'0000). GO command emulation terminates when the break instruction is executed. (The instruction at the software breakpoint itself is not executed.) Up to four breakpoints can be set each time this command is issued, and a maximum of 255 breakpoints can be set in total. A software breakpoint can only be set in a RAM area (including standard emulation memory) because the contents of the specified address is replaced with a break instruction to cause a break. Do not set software breakpoints at any of the addresses below:

  - Address that holds an illegal instruction (H'0000)
  - Areas other than CS0 to CS4 (excluding internal RAM area)
  - Address where the BREAK_CONDITION_UBC2 command settings are satisfied (refer to the following descriptions)
  - Address containing a slot delayed branch instruction (refer to the following descriptions)
  - Address of the lower 16 bits of a 32-bit DSP instruction

Note: If a software breakpoint is set at an address in either a cache area or cache-through area, a break will occur in both areas.

— By specifying the number of times a breakpoint must be reached when setting the breakpoint, program execution terminates when reaching the breakpoint for the specified number of times.

Note: When multiple passes are specified for a breakpoint, the program must be temporarily stopped each time a software breakpoint is passed to update the pass count, and user program emulation continues until the number of times the breakpoint must be passed is satisfied. As a result, realtime emulation is not performed.

Example: To generate a break when the instruction at address 300 is executed five times

: ***BREAK 300 5 (RET)***

— Software breakpoints are ignored during STEP and STEP_OVER command execution, so the pass count is not updated at this time.

— When execution starts at the address set with the BREAK command, immediately after execution starts, the BREAK_CONDITION_UBC2 command settings are invalidated. Therefore, even though a BREAK_CONDITION_UBC2 command setting is satisfied immediately after execution start, GO command execution does not terminate.

— If a software breakpoint is set at a slot delayed branch instruction, a slot illegal instruction interrupt occurs instead of terminating program execution. Make sure not to set a software breakpoint at a slot delayed branch instruction.

- Display

Display format is as follows:

: ***BREAK (RET)***

```
<ADDR>    <CNT>    <PASS>
xxxxxxxx   yyyy      zzzz
  (a)       (b)       (c)
```

(a) Setting address
(b) Specified pass count (hexadecimal)
(c) Value of pass counter (shows how many times the specified address has been passed at GO command termination, in hexadecimal)

Note: The pass counter is cleared by the next GO command.

- Cancellation

  Cancels software breakpoints. Breakpoints can be cancelled in the following two ways:

  - Cancellation of specified software breakpoints. A maximum of four breakpoints can be cancelled with one command.

    : ***BREAK–<software breakpoint>[,<software breakpoint>]... (RET)***

  - Cancellation of all software breakpoints.

    : ***BREAK– (RET)***

Examples

1. To set a software breakpoint at address H'100:

```
:B 100 (RET)
:
```

2. To generate a break when address H'6004 has been passed three times:

```
:B 6004 3 (RET)
:
```

3. To display set software breakpoints:

```
:B (RET)
 <ADDR>  <CNT>  <PASS>
 00000100 0001  0000
 00006004 0003  0000
:
```

4. To cancel the software breakpoint at address H'100:

```
:B – 100 (RET)
:
```

5. To cancel all software breakpoints:

```
:B – (RET)
:
```

7.2.7 BREAK_CONDITION_A,B,C [BCA, BCB, BCC] Specifies, displays, and cancels a hardware break condition

Command Format

- Setting BREAK_CONDITION_(A/B/C)(1/2/3/4/5/6/7/8)Δ<condition>
  [[Δ <condition>] [Δ<condition>]...] (RET)
- Display BREAK_CONDITION_(A/B/C)[(1/2/3/4/5/6/7/8)] (RET)
- Cancellation BREAK_CONDITION_(A/B/C)[(1/2/3/4/5/6/7/8)] [Δ] – (RET)

(A/B/C):	Break type
(1/2/3/4/5/6/7/8):	Break number When omitted, all conditions will be displayed or cancelled.
<condition>:	Hardware break condition (refer to tables 7.5 to 7.7, for details)

Description

- Setting

— Specifies hardware break conditions (BREAK_CONDITION_A,B,C). Program execution stops when the specified conditions are satisfied. The specifiable conditions for the three types of hardware breaks (BREAK_CONDITION_A,B,C) are summarized in tables 7.5 to 7.7, respectively.

Table 7.4 Maximum Conditions for Each Break Type

Break Type	Maximum Conditions	Remarks
BREAK_ CONDITION_A	8	The maximum specifiable number of conditions is reduced by the number of conditions set with the TRACE_CONDITION_A command.
BREAK_ CONDITION_B	8	The maximum specifiable number of conditions is reduced by the number of conditions set with the TRACE_CONDITION_B command.
BREAK_ CONDITION_C	8	The maximum specifiable number of conditions is reduced by the number of conditions set with the PERFORMANCE_ANALYSIS and TRACE_CONDITION_C commands.

Table 7.5 Specifiable Conditions (BREAK_CONDITION_A1-A8)

<table>
<tr><th>Item and Input Format</th><th>Description</th></tr>
<tr><td>Address condition
A=<address 1>[:<address 2>]</td><td>When only <address 1> is specified, the condition is satisfied when the address bus value matches the specified value.
When both <address 1> and <address 2> are specified, the condition is satisfied when the address bus value is in the range from <address 1> to <address 2>.
This condition can be masked.</td></tr>
<tr><td>Data condition
D=<1-byte value>
WD=<2-byte value>
LD=<4-byte value></td><td>The condition is satisfied when the data bus value matches the specified value. When D, WD, or LD is specified, the break condition is satisfied when the address is accessed in bytes, words, or longwords, respectively.
This condition can be masked.</td></tr>
<tr><td>Read/Write condition
R: Read
W: Write</td><td>The condition is satisfied in a read cycle (R is specified) or a write cycle (W is specified).</td></tr>
<tr><td>Access type
DAT: Execution cycle
DMA: DMA cycle
VCF: Vector fetch cycle
Default: All bus cycles described above (including program fetch cycle)</td><td>The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.</td></tr>
<tr><td>External probe condition
PRB=<value></td><td>The condition is satisfied when all of the emulator's external probe signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to a probe number, as follows:
3 2 1 0 ← Bit
x x x x ← Specified value
| | | |
4 3 2 1 ← Probe number
x: 0 = Low level
1 = High level
This condition can be masked.</td></tr>
</table>

Table 7.5 Specifiable Conditions (BREAK_CONDITION_A1-A8) (cont)

<table>
<tr><th>Item and Input Format</th><th>Description</th></tr>
<tr><td>External interrupt condition 1
NMI [:L] or NMI: H</td><td>The condition is satisfied when the NMI signal matches the specified level.
NMI or NMI: L: The condition is satisfied when NMI is low
NMI: H: The condition is satisfied when NMI is high</td></tr>
<tr><td>External interrupt condition 2
IRL=<value></td><td>The condition is satisfied when all of the IRL signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to an IRL number, as follows:
3 2 1 0 ← Bit
x x x x ← Specified value
| | | |
3 2 1 0 ← IRL number
x: 0 = Low level
1 = High level
The condition can be masked.</td></tr>
</table>

Table 7.6 Specifiable Conditions (BREAK_CONDITION_B1-B8)

Item and Input Format	Description
Address condition A=<address 1>[:<address 2>] [;NOT]	When only <address 1> is specified, the condition is satisfied when the address bus value matches the specified value. When both <address 1> and <address 2> are specified, the condition is satisfied when the address bus value is in the range from <address 1> to <address 2>. If the NOT option is specified, the condition is satisfied when the address bus value does not match the specified value. This condition can be masked.
Data condition D=<1-byte value>[;NOT] WD=<2-byte value>[;NOT] LD=<4-byte value>[;NOT]	The condition is satisfied when the data bus value matches the specified value. When D, WD, or LD is specified, the break condition is satisfied when the address is accessed in bytes, words, or longwords, respectively. If the NOT option is specified, the condition is satisfied when the data bus value does not match the specified value. This condition can be masked.
Read/Write condition R: Read W: Write	The condition is satisfied in a read cycle (R is specified) or a write cycle (W is specified).
Access type DAT: Execution cycle DMA: DMA cycle VCF: Vector fetch cycle Default: All bus cycles described above (including program fetch cycle)	The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.
External probe condition PRB=<value>	The condition is satisfied when all of the emulator's external probe signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to a probe number, as follows: 3 2 1 0 ← Bit x x x x ← Specified value | | | | 4 3 2 1 ← Probe number x: 0 = Low level 1 = High level This condition can be masked.

Table 7.6 Specifiable Conditions (BREAK_CONDITION_B1-B8) (cont)

Item and Input Format	Description
External interrupt condition 1 NMI [:L] or NMI: H	The condition is satisfied when the NMI signal matches the specified level. NMI or NMI: L: The condition is satisfied when NMI is low NMI: H: The condition is satisfied when NMI is high
External interrupt condition 2 IRL=<value>	The condition is satisfied when all of the IRL signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to an IRL number, as follows: 3 2 1 0 ← Bit x x x x ← Specified value | | | | 3 2 1 0 ← IRL number x: 0 = Low level 1 = High level The condition can be masked.
Satisfaction count specification COUNT=<value> <value>: H'1 to H'FFFF	The condition can be specified in combination with any of the address, data, read/write, access type, external probe, and external interrupt conditions. The complete condition combination is satisfied when the other specified condition has been satisfied for the specified number of times.
Delay count specification DELAY=<value> <value>: H'1 to H'7FFF	This condition can be specified in combination with any of the address, data, read/write, access type, external probe, and external interrupt conditions. The complete condition combination is satisfied when the specified number of bus cycles has been executed after the other specified condition is satisfied. This condition can only be specified with the BREAK_CONDITION_B7 command.

Table 7.7 Specifiable Conditions (BREAK_CONDITION_C1-C8)

Item and Input Format	Description
Address condition A=<address 1>[:<address 2>]	When only <address 1> is specified, the condition is satisfied when the address bus value matches the specified value. When both <address 1> and <address 2> are specified, the condition is satisfied when the address bus value is in the range from <address 1> to <address 2>. This condition can be masked.
Access type DAT: Execution cycle DMA: DMA cycle VCF: Vector fetch cycle Default: All bus cycles described above (including program fetch cycle)	The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.

— Address and data conditions are satisfied when address bus values and data bus values match the specified values. Note the following when specifying break conditions.

a. Access to a 32-bit bus area

- Longword access

  Longword data is accessed in one bus cycle. Only longword data (LD) and a multiple of four can be specified as the data and address conditions, respectively.

- Word access

  Word data is accessed in one bus cycle. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively. 32 bits must be specified as the data bus width. Note that the data condition must be specified in combination with a specific address condition. If no address condition is specified or if the address is masked, the data condition will be satisfied when the address is a multiple of four.

- Byte access

  Byte data is accessed in one bus cycle. Only byte data (D) can be specified as the data condition. Both even and odd address values can be specified as the address condition. 32 bits must be specified as the data bus width. Note that the data condition must be specified in combination with a specific address condition. If no address condition is specified or if the address is masked, the data condition will be satisfied when the address is a multiple of four.

b. Access to a 16-bit bus area

- Longword access

  Longword data is accessed in two word-access cycles. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively. 16 bits must be specified as the data bus width.

- Word access

  Word data is accessed in one bus cycle. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively. 16 bits must be specified as the data bus width.

- Byte access

  Byte data is accessed in one bus cycle. Only byte data (D) can be specified as the data condition. Both even and odd address values can be specified as the address condition. 16 bits must be specified as the data bus width. Note that the data condition must be specified in combination with a specific address condition. If no address condition is specified or if the address is masked, the data condition will be satisfied when the address is a multiple of two.

c. Access to an 8-bit bus area

All addresses can be accessed in byte units. Longword data and word data are accessed in four byte-access cycles and two byte-access cycles, respectively. Both even and odd addresses can be specified as the address condition. Note, however, that only byte data (D) is valid for the data condition. Eight bits must be specified as the data bus width.

- A bit mask in 1-bit or 4-bit units can be specified for the address condition of the BREAK_CONDITION_A,B,C command. When a bit is masked, the condition is satisfied irrespective of its bit value. To implement the mask, specify each digit to be masked at input as an asterisk (*). When <address 2> is not specified for an address condition, <address 1> can be consecutively masked from the lowest bit. It is not possible to mask any desired bit position. Table 7.8 shows address mask specification examples.

  Example: The following condition is satisfied when the lower four bits of the address condition are not specified:

  : ***BREAK_CONDITION_A1   A=H'400000* (RET)***

Table 7.8 Address Mask Specifications (BREAK_CONDITION_A,B,C)

Radix	Mask Unit	Example	Mask Position
Binary	1 bit	B'01110***	Bits 2 to 0 are masked
Hexadecimal	4 bits	H'000F50**	Bits 7 to 0 are masked

Note: When <address 2> is not specified for an address condition, <address 1> can be consecutively masked from the lowest bit. It is not possible to mask any desired bit position, as shown in the following examples.

Examples:

Allowed: BREAK_CONDITION_A1 A = H'10**
Not allowed: BREAK_CONDITION_A1 A = H'1*00
BREAK_CONDITION_A1 A = H'100*:10**

- A bit mask in 1-bit or 4-bit units can be specified for the data, IRL, or PRB condition of the BREAK_CONDITION_A,B,C command. When a bit is masked, the condition is satisfied irrespective of its bit value. To implement the mask, specify each digit to be masked at input as an asterisk (*). Table 7.9 shows these mask specification examples.

  Example: The following condition is satisfied when address 3000000 is the address condition and bit 0 is zero in the byte data condition:

  : ***BREAK_CONDITION_A1   A=H'3000000 D=B'*******0 (RET)***

Table 7.9 Mask Specifications (BREAK_CONDITION_A,B,C)

Radix	Mask Unit	Example	Mask Position	Allowed Condition
Binary	1 bit	B'01*1010*	Bits 0 and 5 are masked	Data (D, WD, LD), IRL, or PRB
Hexa-decimal	4 bits	H'F**50	Bits 15 to 8 are masked	Data (D, WD, LD), IRL, or PRB

— If a hardware break condition is satisfied, emulation may stop after two or more instructions have been executed.

- Display

— Displays specified conditions. The character string that was input for specifying conditions will be displayed as it was input. If the break number is omitted, all specified break conditions for that break type are displayed.

— For BREAK_CONDITION_B1-B8 conditions, satisfaction count since the previous break condition was satisfied is displayed.

— For BREAK_CONDITION_B7 conditions, delay count since the previous break condition was satisfied is displayed.

— If no break condition is specified, a blank is displayed.

```
: BREAK_CONDITION_B (RET)
 BCB1 <B1 break setting>
 BCB2 <B2 break setting>
 BCB3 <B3 break setting>
 BCB4 <B4 break setting>
 BCB5 <B5 break setting>
 BCB6 <B6 break setting>
 BCB7 <B7 break setting>
 BCB8 <B8 break setting>
```

- Cancellation

  Cancels specified conditions. When break numbers 1 to 8 are omitted, all break conditions are cancelled.

  — Cancels all conditions for the BREAK_CONDITION_A command.

  : ***BREAK_CONDITION_A – (RET)***

  — Cancels BREAK_CONDITION_A1 conditions.

  : ***BREAK_CONDITION_A1 – (RET)***

Note

When conditions have already been set with the TRACE_CONDITION_A,B command, conditions cannot be set to the same channel number. For example, when conditions have already been set to TRACE_CONDITION_A1, no conditions can be set to BREAK_CONDITION_A1. To set new conditions, cancel previously set conditions.

When conditions have already been set with the TRACE_CONDITION_C or PERFORMANCE_ANALYSIS command, conditions cannot be set to the same channel number. For example, when conditions have already been set to TRACE_CONDITION_C1 or PERFORMANCE_ANALYSIS1, no conditions can be set to BREAK_CONDITION_C1. To set new conditions, cancel previously set conditions.

Examples

1. To generate a break when byte data H'10 is accessed at address H'F000000:

```
:BCA1 A=F000000 D=10 (RET)
:
```

2. To generate a break when data is written to address H'1000000:

```
:BCA2 A=1000000 W DAT (RET)
:
```

3. To generate a break when reading data in address H'2000000:

```
:BCB1 A=2000000 R  (RET)
:
```

4. To display the specified conditions:

```
:BCA (RET)
 BCA1 A=F000000 D=10
 BCA2 A=1000000 W DAT
 BCA3
 BCA4
 BCA5
 BCA6
 BCA7
 BCA8
:
```

5. To cancel the specified conditions:

```
:BCA1 – (RET)
:BCB1 – (RET)
:
```

7.2.8 BREAK_CONDITION_UBC [BCU] Specifies, displays, and cancels hardware break conditions

Command Format

- Setting BREAK_CONDITION_UBC(1/2)Δ<condition>[[Δ <condition>]
  [Δ<condition>]...] (RET)
- Display BREAK_CONDITION_UBC[(1/2)] (RET)
- Cancellation BREAK_CONDITION_UBC[(1/2)] [Δ] – (RET)

(1/2):	UBC break number When omitted, all conditions will be displayed or cancelled.
<condition>:	Hardware break condition (refer to tables 7.10 and 7.11, for details)

Description

- Setting

— Specifies hardware break conditions (BREAK_CONDITION_UBC). Program execution stops when the specified conditions are satisfied. The specifiable conditions for the two kinds of hardware breaks are summarized in tables 7.10 and 7.11, respectively. The BREAK_CONDITION_UBC conditions can also be satisfied in sequential break mode (program execution stops only when UBC1 and UBC2 settings are satisfied in the sequence of UBC2 break condition followed by UBC1 break condition). The sequential break can be specified with the GO command.

Table 7.10 Specifiable Conditions (BREAK_CONDITION_UBC1)

Item and Input Format	Description
Address condition A=<address> PC=<address>[;P] XA=<X-bus address> YA=<Y-bus address>	The condition is satisfied when the address bus value matches the specified value. When A= is selected, the address bus in data access or program fetch cycles is specified, and when PC= is selected, the address bus in program fetch cycles is specified. When the ;P option is specified with PC=, a break occurs before program execution at the specified address, while if the option is omitted, a break occurs after program execution. When PC= is selected, only the satisfaction count specification is valid. When XA= or YA= is selected, specify the address in words. This condition can be masked.
Data condition D=<1-byte value> WD=<2-byte value> LD=<4-byte value> XD=<X-bus data value> YD=<Y-bus data value>	The condition is satisfied when the data bus value matches the specified value. When D, WD, or LD is specified, the break condition is satisfied when the address is accessed in bytes, words, or longwords, respectively. In program fetch cycles, the data condition is not satisfied irrespective of the data bus value. When XD= or YD= is selected, specify the data value in words. Multiple data conditions cannot be specified. This condition can be masked.
Read/Write condition R: Read W: Write	The condition is satisfied in a read cycle (R is specified) or a write cycle (W is specified).
Access type DAT: Execution cycle DMA: DMA cycle Default: All bus cycles described above (including program fetch cycle)	The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.
Satisfaction count specification COUNT=<value> <value>: H'1 to H'FFF	This condition can be specified in combination with any of the address, data, read/write, and access type conditions. The complete condition combination is satisfied when the other specified condition has been satisfied for the specified number of times.

Table 7.11 Specifiable Conditions (BREAK_CONDITION_UBC2)

Item and Input Format	Description
Address condition A=<address> PC=<address>[;P]	The condition is satisfied when the address bus value matches the specified value. When A= is selected, the address bus in data access or program fetch cycles is specified, and when PC= is selected, the address bus in program fetch cycles is specified. When the ;P option is specified with PC=, a break occurs before program execution at the specified address, while if the option is omitted, a break occurs after program execution. When PC= is selected, no other conditions can be specified. This condition can be masked.
Read/Write condition R: Read W: Write	The condition is satisfied in a read cycle (R is specified) or a write cycle (W is specified).
Access type DAT: Execution cycle DMA: DMA cycle Default: All bus cycles described above (including program fetch cycle)	The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.

— The data conditions of the BREAK_CONDITION_UBC1 break are satisfied when the address bus and data bus values match the specified values. The data bus (the SH7612 internal bus) is always 32 bits long. Note the following when specifying break conditions.

- Longword access

  Longword data is accessed in one bus cycle. Only longword data (LD) and a multiple of four can be specified as the data and address conditions, respectively.

- Word access

  Word data is accessed in one bus cycle. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively.

- Byte access

  Byte data is accessed in one bus cycle. Only byte data (D) can be specified as the data condition. Both even and odd address values can be specified as the address condition.

— A bit mask in 1-bit or 4-bit units can be specified for the address, PC, and data conditions of the BREAK_CONDITION_UBC1,2 command. When a bit is masked, the condition is satisfied irrespective of its bit value. To implement the mask, specify each digit to be masked at input as an asterisk (*). Table 7.12 shows mask specification examples.

Example 1: The following condition is satisfied when the lower four bits of the address condition are not specified:

: ***BREAK_CONDITION_UBC1 A=H'400000* (RET)***

Example 2: The following condition is satisfied when address 3000000 is the address condition and bit 0 is zero in the byte data condition:

: ***BREAK_CONDITION_UBC1 A=H'3000000 D=B'*******0 (RET)***

Table 7.12 Mask Specifications (BREAK_CONDITION_UBC1,2)

Radix	Mask Unit	Example	Mask Position	Allowed Condition
Binary	1 bit	B'01*1010*	Bits 0 and 5 are masked	Address, data (D, WD, LD), or PC
Hexa-decimal	4 bits	H'F**50	Bits 15 to 8 are masked	Address, data (D, WD, LD), or PC

- Display

— Displays specified conditions. The character string that was input for specifying conditions will be displayed as it was input. If break numbers 1 and 2 are omitted, break conditions for both break types are displayed.

— For BREAK_CONDITION_UBC1 break conditions, satisfaction count after the previous break condition was satisfied is displayed.

— If no break condition is specified, a blank is displayed.

```
: BREAK_CONDITION_UBC (RET)
BCU1 <UBC1 break setting>
BCU2 <UBC2 break setting>

          xxx:  Satisfaction count after the condition is satisfied
```

- Cancellation

  Cancels specified conditions. When break numbers 1 and 2 are omitted, all break conditions are cancelled.

  — Cancellation of all break conditions

  : ***BREAK_CONDITION_UBC – (RET)***

  — Cancellation of BREAK_CONDITION_UBC2 break conditions

  : ***BREAK_CONDITION_UBC2 – (RET)***

Notes

1. The BREAK_CONDITION_UBC2 settings are ignored when a stop address is specified with the GO command or during STEP and STEP_OVER command execution.
2. Executing addresses containing software breakpoints (set by the BREAK or BREAK_SEQUENCE command) invalidates the BREAK_CONDITION_UBC2 settings. Make sure not to set software breakpoints at addresses where the BREAK_CONDITION_UBC2 settings are satisfied.
3. A slot delayed branch instruction cannot terminate user program execution before a PC break occurs; setting an execution stop condition for a PC break at a slot delayed branch instruction will stop emulation before executing the branch destination instruction.
4. The BREAK_CONDITION_UBC settings are implemented by the SH7612 user break controller. Accordingly, when the condition that the UBC is used by the user system is specified with the UBC option of the EXECUTION_MODE command, this command cannot be used.

Examples

1. To generate a break when byte data H'10 is accessed at address H'F000000:

```
:BCU1 A=F000000 D=10 (RET)
:
```

2. To generate a break when data is written to address H'1000000:

```
:BCU2 A=1000000 W DAT (RET)
:
```

3. To display the specified conditions:

```
:BCU (RET)
 BCU1 A=F000000 D=10
 BCU2 A=1000000 W DAT
:
```

4. To cancel the specified conditions:

```
:BCU1 – (RET)
:BCU2 – (RET)
:
```

7.2.9 BREAK_SEQUENCE [BS] Sets, displays, and cancels software breakpoints with pass sequence specification

Command Format

- Setting BREAK_SEQUENCEΔ<pass point>Δ<pass point>[Δ<pass point>
  [Δ<pass point>[Δ<pass point>[Δ<pass point>
  [Δ<pass point>]]]]] (RET) (Pass point setting)
  BREAK_SEQUENCEΔ<reset point>;R (RET) (Reset point setting)
- Display BREAK_SEQUENCE (RET)
- Cancellation BREAK_SEQUENCE[Δ]– (RET) (Pass point cancellation)
  BREAK_SEQUENCE[Δ]–;R (RET) (Reset point cancellation)

<pass point>:	Addresses (two to seven points)
R:	Reset point specification
<reset point>:	Address (one point)

Note: When an odd address is specified, it is rounded down to an even address.

Description

- Setting

— Sets pass points to enable the break for which the pass sequence is specified (sequential break). GO command emulation terminates when these pass points have been passed in the specified sequence.

Notes: 1. Do not set a pass point or a reset point at any of the addresses below:
- Address specified with the BREAK command
- Address that holds an illegal instruction (H'0000)
- Areas other than CS0 to CS4 (excluding internal RAM area)
- Address where BREAK_CONDITION_UBC2 settings are satisfied (refer to the following description)
- Address containing a slot delayed branch instruction (refer to the following description)
- Address of the lower 16 bits of a 32-bit DSP instruction

2. Pass points or a reset point are ignored during STEP and STEP_OVER command execution. Therefore, the pass count is not updated during STEP and STEP_OVER command execution.

- If the pass points have not been passed in the specified sequence, break checking begins again from the first pass point.

- When the specified reset point is passed, break checking begins again at the first pass point, even if the remaining pass points are then passed in the assigned sequence.

- When pass points or a reset point are specified, the emulator temporarily stops emulation and analyzes the pass sequence at each point. Therefore, realtime emulation is not performed.

- When execution starts at the address set with the BREAK_SEQUENCE command, immediately after execution starts, the BREAK_CONDITION_UBC2 command settings are invalidated. Therefore, even though a BREAK_CONDITION_UBC2 command setting is satisfied immediately after execution start, GO command execution does not terminate.

- If a pass point is set at a slot delayed branch instruction, instead of terminating program execution, a slot illegal instruction interrupt occurs. Make sure not to set a pass point at a slot delayed branch instruction.

- If a software breakpoint is set at an address in either a cache area or cache-through area, a break will occur in both areas.

- Display

  Displays specified pass points and reset point as follows:

```
: BREAK_SEQUENCE  (RET)
 PASS POINT NO.1    = xxxxxxxx      yyyy
 PASS POINT NO.2    = xxxxxxxx      yyyy
 PASS POINT NO.3    = xxxxxxxx      yyyy
 PASS POINT NO.4    = xxxxxxxx      yyyy
 PASS POINT NO.5    = xxxxxxxx      yyyy
 PASS POINT NO.6    = xxxxxxxx      yyyy
 PASS POINT NO.7    = xxxxxxxx      yyyy
 RESET POINT        = xxxxxxxx      yyyy
                         (a)         (b)
```

(a) Address (If nothing is specified, a blank is displayed.)

(b) Number of times passed (The number of times the pass point was passed is displayed in hexadecimal. If it exceeds H'FFFF, counting restarts from H'0. The number of times passed is cleared by the next GO command.)

- Cancellation

  Cancels specified pass points or a reset point.

  - Cancellation of pass points

    : ***BREAK_SEQUENCE– (RET)***
  - Cancellation of a reset point

    : ***BREAK_SEQUENCE–;R (RET)***

Note

In parallel mode, if a command (for example, memory access) is executed and the emulation stops at a pass point or the reset point at the same time, command execution may not take place. In this case,

```
*** 78: EMULATOR BUSY
```

is displayed. Re-enter the command. If the termination interval is short, the emulator may not enter parallel mode or commands cannot be executed in parallel mode.

Examples

1. To set pass points at addresses H'4000, H'4100, H'4200, and H'4300 in that order and a reset point at address H'2000:

```
:BS 4000 4100 4200 4300  (RET)
:BS 2000 ;R  (RET)
:
```

2. To display the specified pass points and reset point:

```
:BS  (RET)
 PASS POINT NO1 = 00004000   0000
 PASS POINT NO2 = 00004100   0000
 PASS POINT NO3 = 00004200   0000
 PASS POINT NO4 = 00004300   0000
 PASS POINT NO5 = 00004400   0000
 PASS POINT NO6 = 00004500   0000
 PASS POINT NO7 = 00004600   0000
 RESET POINT    = 00002000   0000
:
```

3. To cancel the reset point:

```
:BS – ;R  (RET)
:
```

4. To cancel the pass points and reset point:

```
:BS –  (RET)
:BS – ;R  (RET)
:
```

7.2.10 CHECK [CH] Tests SH7612 pins

Command Format

- Test CHECK (RET)

Description

- Test

  Tests the status of the SH7612 pins shown in table 7.13.

Table 7.13 SH7612 Pin Test

Pin Name	Error Status
RES	RESET signal is fixed low.
NMI	NMI signal is fixed low.
WAIT	WAIT signal is fixed low.
BREQ	BREQ signal is fixed low.
IRL0	IRL0 signal is fixed low.
IRL1	IRL1 signal is fixed low.
IRL2	IRL2 signal is fixed low.
IRL3	IRL3 signal is fixed low.
CKPREQ	CKPREQ signal is fixed low.

If an error occurs,

FAILED AT <pin name>

is displayed.

Example

When the IRL0 signal is low:

```
:CH  (RET)
 FAILED AT IRL0
:
```

7.2.11 CLOCK [CL] Sets or displays clock

Command Format

- Setting CLOCKΔ<clock> (RET)
- Display CLOCK (RET)

<clock>: One of the following clock signals:

E:	Emulator internal CLOCK signal (16.5 MHz)
U:	User system CLOCK signal
X:	Crystal oscillator CLOCK signal (8 to 16.5 MHz)

Description

- Setting
  - When clock mode 0, 1, 2, or 3 is specified as the SH7612 clock mounted on the emulator, selects emulator clock signals from the user system, from crystal oscillator on the EV-chip board, or from the emulator internal clock (installed in the emulator). Resets the SH7612 when a clock is selected, and consequently, internal I/O registers and control registers return to their reset values.
  - Displays the specified clock signal. If the user system clock (U) is specified, but the user system clock signal is not input, an error occurs and the emulator internal clock (E) is set instead (when clock mode is 0, 1, 2, or 3). At emulator initiation, the user system clock (U), crystal oscillator on the EV-chip board (X), and emulator internal clock (E) are selected in that order, and the correct clock signal is set. The emulator internal clock signal cannot be selected when clock mode 4, 5, or 6 is specified with the MODE command. Be sure to input the clock signal from the user system to use the emulator.

- Display

  Displays the current clock signal.

```
: CLOCK  (RET)
  CLOCK = <used clock>
```

<used clock>:

EML:	Emulator internal clock (16.5 MHz)
USER:	User system clock
X'TAL:	Crystal oscillator clock (8 to 16.5 MHz)

Note

If U (user system clock) is specified and the following clock signal problem occurs, the E8000 system program may terminate. In this case,

*** 6: USER SYSTEM NOT READY

is displayed. The E8000 system program must be quit with the QUIT command and restarted.

- User system clock signal is not being received even when U is specified and the user system clock is being used. (Vcc is supplied with no problem)

Examples

1. To use the user system clock signal:

```
:CL U (RET)
 ** RESET BY E8000 !
 CLOCK = USER
:
```

2. To use the emulator internal clock signal:

```
:CL E (RET)
 ** RESET BY E8000 !
 CLOCK = EML
:
```

3. To display the current clock signal:

```
:CL (RET)
 CLOCK = EML
:
```

7.2.12 CONFIGURATION [CNF] Saves and restores configuration information, and displays a list

Command Format

- Saving CONFIGURATIONΔ<configuration number>Δ<comment> ;S (RET)
- Restoration CONFIGURATIONΔ<configuration number> (RET)
- List display CONFIGURATION (RET)

<configuration number>:	1 or 2
<comment>:	Comment on the defined configuration information. A comment can contain of one to 32 characters (not counting the semicolon (;)).

Description

- Saving

  Saves configuration information (various emulation information) that are listed in table 7.14 in the emulator flash memory.

  : ***CONFIGURATION <configuration number> <comment> ;S (RET)***

Table 7.14 Saved Configuration Information

Item	Description
Software breakpoints	Information set by the BREAK and BREAK_SEQUENCE commands
Hardware break conditions	Information set by the BREAK_CONDITION_A,B,C and BREAK_CONDITION_UBC commands
Trace conditions	Information set by the TRACE_CONDITION_A,B,C, TRACE_DISPLAY_MODE, and TRACE_MODE commands
Performance analysis data	Information set by the PERFORMANCE_ANALYSIS command
Memory map	Information set by the MAP command
Emulation operating mode	Information set by the EXECUTION_MODE command
Aliases	Information set by the ALIAS command
Background interrupt data	Information set by the BACKGROUND_INTERRUPT command

- Restoration

  Restores the configuration information saved in the emulator flash memory.

  : ***CONFIGURATION <configuration number> (RET)***

- List display

  Displays the configuration information saved in the emulator flash memory.

  ```
  : CONFIGURATION  (RET)
    1 <comment>
    2 <comment>
  :
  ```

Examples

1. To save configuration information with comment CNF1:

   ```
   :CNF 1 CNF1 ;S (RET)
   :
   ```

2. To restore configuration information saved under configuration number 1:

   ```
   :CNF 1 (RET)
   :
   ```

3. To display the configuration information list:

   ```
   :CNF (RET)
    1 CNF1
    2 ETC
   :
   ```

7.2.13 CONVERT [CV] Converts data

Command Format

- Conversion CONVERTΔ<data> (RET)
  CONVERTΔ<expression> (RET)

<data>: Data to be converted
<expression>: Addition or subtraction
<data>+<data>–<data> ...
–<data>

Description

- Conversion

— Converts data to hexadecimal, decimal, octal, binary, fixed-point, and ASCII formats. Input data is handled as 4-byte values. If there is no corresponding ASCII character (including undisplayable character), a period (.) is displayed instead.

```
: CONVERT <data> (RET)
    H'xxx...  D'xxx...  Q'xxx...  B'xxx...  xxxx
      (a)        (b)       (c)       (d)      (e)
    X'x.xxx...
      (f)
```

(a) Hexadecimal display
(b) Decimal display
(c) Octal display
(d) Binary display
(e) ASCII display
(f) Fixed-point display

— If the H', D', Q', B', or X' radix is not specified for <data> at data input, the radix specified with the RADIX command is assumed.

Note

When an expression includes fixed-point values, the fixed-point values are converted as 4-byte values before the expression is converted. Therefore, the expression cannot be converted correctly.

Examples

1. To convert hexadecimal data (H'7F):

```
:CV H'7F (RET)
 H'7F  D'127  Q'177  B'1111111   ....
 X'0.0000000591
:
```

2. To convert the expression:

```
:CV H'31+D'16 (RET)
 H'41  D'65  Q'101  B'1000001   ...A
 X'0.0000000303
:
```

7.2.14 DATA_CHANGE [DC] Replaces memory data

Command Format

- Replacement DATA_CHANGEΔ<data 1>Δ<data 2>Δ<start address>
  (Δ<end address>/Δ@<number of bytes>)[;[<size>][ΔY]] (RET)

<data 1>:	Old data
<data 2>:	New data
<start address>:	Start address of the memory area to be changed
<end address>:	End address of the memory area to be changed
<number of bytes>:	The number of bytes in the memory area to be changed
<size>:	Length of data B: 1 byte W: 2 bytes L: 4 bytes Default: 1 byte
Y:	Specify Y if a confirmation message is not necessary. If Y is specified, data in all assigned areas is replaced without a confirmation message.

Description

- Replacement

— Replaces <data 1> in the specified memory area (set by the <start address> and <end address> or the <number of bytes>) with <data 2> and verifies the results.

— If option Y is specified, data is replaced without confirmation messages. If option Y is not specified, the following message is displayed whenever the data specified by <data 1> is found.

```
xxxxxxxx  CHANGE  (Y/N) ?   y  (RET)
```

xxxxxxxx: Address where <data 1> was found.

y: Y: <data 1> is replaced with <data 2>.

N: Data is not replaced; continues to search for another occurrence of the specified data. To terminate this command before reaching <end address>, press the (CTRL) + C keys.

— If <data 1> is not found at any point in the replacement range, the following message is displayed:

```
*** 45:NOT FOUND
```

— Memory modification with this command can be performed only in areas CS0 to CS4 or the internal memory areas.

Examples

1. To replace 2-byte data H'6475 in the address range from H'7000 to H'7FFF with H'5308 (with confirmation message):

```
:DC 6475 5308 7000 7FFF ;W  (RET)
 00007508 CHANGE (Y/N) ? Y  (RET)
 00007530 CHANGE (Y/N) ? N  (RET)
:
```

2. To replace 4-byte data 'DATA' in the address range from H'FB80 to H'FE00 with 'DATE' (without confirmation message):

```
:DC 'DATA' 'DATE' FB80 FE00 ;L Y  (RET)
:
```

7.2.15 DATA_SEARCH [DS] Searches for memory data

Command Format

- Search DATA_SEARCHΔ<data>[Δ<start address>[(Δ<end address>/
  Δ@<number of bytes>)]][;[<size>][ΔN]] (RET)

<data>: Data to be searched for

<start address>: Search start address (Default: H'0)

<end address>: Search end address (Default: Maximum address of H'FFFFFFFF)

<number of bytes>: The number of bytes to be searched for (Default: Maximum address of H'FFFFFFFF (same as <end address>))

<size>: Length of data to be searched for

B: 1 byte
W: 2 bytes
L: 4 bytes
Default: 1 byte

N: Data other than the specified data is searched for

Description

- Search
  - Searches for <data> from the start address to the end address (or for the specified <number of bytes>). All addresses where <data> is found are displayed.
  - If data is not found, the following message is displayed:

```
*** 45:NOT FOUND
```

  - If the N option is specified, data other than the specified <data> is searched for.
  - Search with this command can be performed only in areas CS0 to CS4 or the internal memory areas.

Examples

1. To search for 1-byte data H'20 in the address range from H'FB80 to H'FF7F:

```
:DS 20 H'FB80 H'FF7F  (RET)
 0000FBFB 0000FCCD
:
```

2. To search for data other than 2-byte data H'0 in H'100 bytes starting from address H'1000:

```
:DS 0 1000 @100 ; W N (RET)
 *** 45:NOT FOUND
:
```

7.2.16 DISASSEMBLE [DA] Disassembles and displays memory contents

Command Format

- Display DISASSEMBLEΔ<start address>[(Δ<end address>/ Δ@<number of instructions>)] (RET)

<start address>:	Start address of disassembly
<end address>:	End address of disassembly
<number of instructions>:	The number of instructions to be disassembled

Description

- Display

— Disassembles the specified memory contents and displays addresses, machine codes, mnemonics, and operands in the following format. As many lines as necessary are used for the display.

```
ADDR          CODE            MNEMONIC    OPERAND
<address>   <machine code>   <mnemonic>   <operand>
```

— If <end address> or <number of instructions> is omitted, 16 instructions are disassembled and displayed.

— If there is no applicable instruction,

```
DATA.W   xxxx
```

is displayed.

If <start address> is an odd address,

```
DATA.B   xx
```

is displayed.

— Immediately after executing this command (except when it is forcibly terminated by the (CTRL) + C keys or (BREAK) key, or by an error), pressing the (RET) key will disassemble and display the next 16 lines of data.

— Disassemble can be performed only in areas CS0 to CS4 or the internal memory areas.

Examples

1. To disassemble and display six instructions starting from address H'1000:

```
:DA 1000 @6  (RET)
 ADDR     CODE      MNEMONIC    OPERAND
 00001000 E000      MOV         #00,R0
 00001002 2100      MOV.B       R0,@R1
 00001004 2201      MOV.W       R0,@R2
 00001006 430B      JSR         @R3
 00001008 0009      NOP
 0000100A 3400      CMP/EQ      R0,R4
:
```

2. To disassemble and display 16 instructions starting from address H'1000, and to disassemble and display furthermore 16 instructions by only entering (RET):

```
:DA 1000  (RET)
 ADDR     CODE      MNEMONIC    OPERAND
 00001000 1F01      MOV.L       R0,@(4,R15)
 00001002 6673      MOV         R7,R6
 00001004 E001      MOV         #1,R0
 00001006 3708      SUB         R0,R7
 00001008 1F52      MOV.L       R5,@(8,R15)
 0000100A 1F43      MOV.L       R4,@(C,R15)
 0000100C E00A      MOV         #0A,R0
 0000100E 6053      MOV         R5,R0
 00001010 1658      MOV.L       R5,@(20,R6)
 00001012 5568      MOV.L       @(20,R6),R5
 00001014 6053      MOV         R5,R0
 00001016 880A      CMP/EQ      #0A,R0
 00001018 8902      BT          00001020
 0000101A E001      MOV         #01,R0
 0000101C 380C      ADD         R0,R8
 0000101E 0009      NOP
:(RET)
 ADDR     CODE      MNEMONIC    OPERAND
 00001020 2100      MOV.B       R0,@R1
 00001022 2201      MOV.W       R0,@R2
 00001024 2302      MOV.L       R0,@R3
      :                       :
```

3. To disassemble and display five instructions starting from address H'2000:

```
:DA 2000 @5  (RET)
 ADDR     CODE      MNEMONIC    OPERAND
 00002000 F80A70A2  PADD        A0,M0,A0
                    PMULS       X0,Y0,M0
                    MOVX.W      @R4+,X0
                    MOVY.W      @R6+,Y0
 00002004 000B      RTS
 00002006 0009      NOP
 00002008 1F01      MOV.L       R0,@(4,R15)
 0000200A 6673      MOV         R7,R6
:
```

7.2.17 DUMP [D] Displays memory contents

Command Format

- Display DUMPΔ<start address>[(Δ<end address>/Δ[@]<number of bytes>)]
  [;[<display unit>] (RET)

<start address>: Start address for memory dump

<end address>: End address for memory dump

<number of bytes>: Size of data for memory dump

If @ is omitted, this value is determined as <end address> or <number of bytes> according to the inequalities given below.

Default is 256 bytes, as size.

End address: <start address> ≤ specified value

Number of bytes: <start address> > specified value

<display unit>: Size of display unit

B: 1-byte units

W: 2-byte units

L: 4-byte units

XW: 16-bit fixed-point units

XL: 32-bit fixed-point units

Default: 1-byte units

Description

- Display

— When B, W, or L is specified as <display unit>, displays a memory dump of the specified area as follows:

```
<ADDRESS>              <DATA>                      <ASCII CODE>
 xxxxxxxx     xx....................................xx       "xxxx................xx"
   (a)                   (b)                            (c)
```

(a) Address

(b) Memory contents

(c) Memory contents displayed as ASCII codes. If there is no applicable ASCII code, a period (.) is displayed instead.

- If only the (RET) key is pressed after DUMP command execution has been terminated (except for forcible termination), the 256 bytes of data from the next address of the last dump are displayed.

- When XW or XL is specified as <display unit>, displays a fixed-point memory dump of the specified area as follows.

```
<ADDRESS>     <HEX>      <FIXED POINT>
 xxxxxxxx    xxxxxxxx     x.xxxxxxxxxx
   (a)         (b)            (c)
```

(a) Address
(b) Memory contents of address (a) in hexadecimal
(c) Memory contents of address (a) in fixed-point units

Note

If a reserved-area dump is displayed, the contents will be undefined.

Examples

1. To display a memory dump from addresses H'0 to H'2F:

```
:D 0 2F (RET)
 <ADDRESS>             <    D   A    T   A    >                  <ASCII CODE>
 00000000  20 48 20 49 20 54 20 41   20 43 20 48 20 49 20 20  " H I T A C H I  "
 00000010  00 00 00 00 00 00 00 00   00 00 00 00 00 00 00 00  "................"
 00000020  20 20 20 20 20 20 20 20   20 20 20 45 38 30 30 30  "           E8000"
:
```

2. To display H'20 bytes of memory dump from address H'FB80 in 4-byte units:

```
:D FB80  20 ;L (RET)
 <ADDRESS>             <    D   A    T   A    >            <ASCII CODE>
 0000FB80  00000000   00000001    00000002   00000003    "................"
 0000FB90  00000000   00000001    00000002   00000003    "................"
:
```

3. To display a memory dump in 32-bit fixed-point units from addresses H'F000 to H'F3FF:

```
:D F000 F3FF ;XL (RET)
 <ADDRESS>    <HEX>    <FIXED POINT>
 0000F000   70000000   0.8750000000
 0000F004   40000000   0.5000000000
 0000F008   60000000   0.7500000000
   :         :
 0000F3FC   77400000   0.9921875000
:
```

4. To display a memory dump in 16-bit fixed-point units from addresses H'F000 to H'F3FF:

```
:D F000 F3FF ;XW (RET)
 <ADDRESS>  <HEX>  <FIXED POINT>
 0000F000   7000   0.87500
 0000F002   4000   0.50000
 0000F004   6000   0.75000
   :         :
 0000F3FE   7740   0.99218
:
```

7.2.18 END [E] Cancels parallel mode

Command Format

- Cancellation END (RET)

Description

- Cancellation
  - — Cancels parallel mode during GO command execution.
  - — Entering the END command clears old trace information and starts storing new trace information.

Example

To cancel parallel mode during GO command execution:

```
:G (RET)
 ** PC=00003400        (RET)          (Parallel mode entered)
#M FD80 (RET)
 0000FD80  00     ?  FF (RET)         (Command execution in parallel mode)
 0000FD81  00     ?  . (RET)
#E (RET)                              (Parallel mode cancellation)
 ** PC=00003800
:
```

7.2.19 EXECUTION_MODE [EM] Specifies and displays execution mode

Command Format

- Setting EXECUTION_MODE [ΔBREQ=<BREQ option>][ΔTIME=<TIME option>]
  [ΔTRGU=<TRGU option>][ΔTRGB=<TRGB option>]
  [ΔMON=<MON option>][ΔWAIT=<WAIT option>]
  [ΔCT=<CT option>][ΔMB=<MB option>]
  [ΔUBC=<UBC option>] [;C] (RET)
- Setting (interactive mode) EXECUTION_MODE[;C] (RET)

<BREQ option>: Specifies whether the BREQ (bus request) signal inputs are enabled.

E: Enables the BREQ signal inputs (default at emulator shipment)

D: Disables the BREQ signal inputs

<TIME option>: Specifies the minimum time to be measured for the GO command execution.

1: 1.6 µs (default at emulator shipment)

2: 406 ns

3: 20 ns

<TRGU option>: When hardware break conditions (set by the BREAK_CONDITION_UBC(1/2) command) are satisfied, specifies whether a pulse is output from the trigger output pin of the emulator without a break.

E: Outputs a trigger without a break

M: Break occurs and outputs a trigger

D: Break occurs but does not output a trigger (default at emulator shipment)

<TRGB option>: When hardware break conditions (set by the BREAK_CONDITION_B command) are satisfied, specifies whether a pulse is output from the trigger output pin of the emulator without a break.

(1/2/3/4/5/6/7/8): Outputs a trigger when the hardware break condition set by the specified channel of the BREAK_CONDITION_B command is satisfied, without a break

A: Outputs a trigger when any hardware break condition set by the BREAK_CONDITION_B command is satisfied without a break

D: Break occurs but does not output a trigger (default at emulator shipment)

<MON option>: Specifies time interval for execution status display.
- 0: No display
- 1: Approximately 200 ms (default at emulator shipment)
- 2: Approximately 2 s

<WAIT option>: Specifies whether user wait is accepted.
- E: Enables user wait
- D: Disables user wait (default at emulator shipment)

<CT option>: Specifies whether the cache-access trace is enabled.
- E: Enables the cache-access trace
- D: Disables the cache-access trace (default at emulator shipment)

<MB option>: Specifies whether the multi break is enabled.
- E: Enables the multi break
- D: Disables the multi break (default at emulator shipment)

<UBC option>: Specifies whether UBC use by the user program is enabled.
- E: Enables UBC use
- D: Disables UBC use (default at emulator shipment)

C: Stores the settings as configuration information in the emulator flash memory.

Description

- Specification

— Enables or disables the BREQ signal (bus request signal) inputs during user program execution.

- To disable the BREQ signal inputs during emulator operation and user program execution:

  : ***EXECUTION_MODE BREQ=D (RET)***
- To enable the BREQ signal inputs during emulator operation and user program execution:

  : ***EXECUTION_MODE BREQ=E (RET)***

— Specifies the minimum time to be measured for GO command execution.

- To set the minimum time to 1.6 µs:

  : ***EXECUTION_MODE TIME=1 (RET)***
- To set the minimum time to 406 ns:

  : ***EXECUTION_MODE TIME=2 (RET)***
- To set the minimum time to 20 ns:

  : ***EXECUTION_MODE TIME=3 (RET)***

— Specifies whether to continue program execution and whether to output a pulse from the trigger output pin when hardware break conditions set by the BREAK_CONDITION_UBC1,UBC2 commands are satisfied.

- To terminate program execution and not output a pulse when hardware break conditions are satisfied:

  : ***EXECUTION_MODE TRGU=D (RET)***
- To terminate program execution and output a pulse when hardware break conditions are satisfied:

  : ***EXECUTION_MODE TRGU=M (RET)***
- To continue program execution and output a pulse when hardware break conditions are satisfied:

  : ***EXECUTION_MODE TRGU=E (RET)***

— Specifies whether to continue program execution and whether to output a pulse from the trigger output pin when hardware break conditions set by the BREAK_CONDITION_B command are satisfied.

- To continue program execution and output a pulse when the hardware break condition set by the BREAK_CONDITION_B1 command is satisfied:

  : ***EXECUTION_MODE TRGB=1 (RET)***
- To continue program execution and output a pulse when any hardware break condition set by the BREAK_CONDITION_B command is satisfied:

  : ***EXECUTION_MODE TRGB=A (RET)***
- To terminate program execution and not output a pulse when hardware break conditions are satisfied:

  : ***EXECUTION_MODE TRGB=D (RET)***

— Specifies time interval for execution status display during GO command execution.

- To not display PC:

  : ***EXECUTION_MODE MON=0 (RET)***
- To display PC every 200 ms:

  : ***EXECUTION_MODE MON=1 (RET)***
- To display PC every 2 s:

  : ***EXECUTION_MODE MON=2 (RET)***

— Enables or disables user wait.

- To disable user wait:

  : ***EXECUTION_MODE WAIT=D (RET)***
- To enable user wait:

  : ***EXECUTION_MODE WAIT=E (RET)***

— Enables or disables the cache-access trace.

- To disable the cache-access trace:

  : ***EXECUTION_MODE CT=D (RET)***
- To enable the cache-access trace:

  : ***EXECUTION_MODE CT=E (RET)***

— Enables or disables the multi-break function.

- To disable the multi-break function:

  : ***EXECUTION_MODE MB=D (RET)***
- To enable the multi-break function:

  : ***EXECUTION_MODE MB=E (RET)***

— Enables or disables UBC use by the user program.

- To disable UBC use by the user program:

  : ***EXECUTION_MODE UBC=D (RET)***
- To enable UBC use by the user program:

  : ***EXECUTION_MODE UBC=E (RET)***

Notes: 1. When UBC use is enabled, the following functions cannot be used.

- **BACKGROUND_INTERRUPT command**
- **BREAK_CONDITION_UBC command**
- **BREAK_SEQUENCE command**
- **STEP command**
- **STEP_OVER command**
- **SB option of GO command**
- **Continuous GO-command execution after termination by a software break**

2. If conditions have already been set with BREAK_CONDITION_UBC command, the UBC use setting cannot be performed. Cancel the BREAK_CONDITION_UBC command settings before setting UBC use with the EXECUTION_MODE command.

— When the C option is specified, the following message is displayed to confirm with the user whether to overwrite the existing configuration information in the emulator flash memory.

CONFIGURATION STORE OK (Y/N) ? ***(a) (RET)***

(a) Y: Stores the specifications as configuration information in the emulator flash memory. Hereafter, when the emulator is activated, the saved specifications go into effect.

N: Does not overwrite configuration information. The existing specifications are valid.

- Specification (interactive mode)

  When all options are omitted, the current values are displayed and the emulator enters the interactive mode. Enter the required value for each item. Enter (RET) for the item not to be modified. To exit the interactive mode, enter a period (.). In this case, modifications before entering a period are valid.

```
: EXECUTION_MODE (RET)
  BREQ=E   TIME=1.6us   TRGU=D   TRGB=D   MON=1  WAIT=D  CT=D  MB=D  UBC=D
  BREQ (D:DISABLE/E:ENABLE) ?  (RET)                 (Displays current value)
  TIME (1:1.6us/2:406ns/3:20ns) ? (RET)
  TRGU (D:DISABLE/E:ENABLE/M:MULTI) ? (RET)
  TRGB (A:ALL/1:B1/2:B2/3:B3/4:B4/5:B5/6:B6/7:B7/8:B8/D:DISABLE) ? (RET)
  MON (0:DISABLE/1:200ms/2:2s) ? (RET)
  WAIT (D:DISABLE/E:ENABLE) ? D (RET)                (Disables user wait)
  CT (D:DISABLE/E:ENABLE)  ?  (RET)
  MB (D:DISABLE/E:ENABLE) ?  (RET)
  UBC (D:DISABLE/E:ENABLE)  ?  (RET)
:
```

Examples

1. To enable the BREQ (bus request) signal inputs and store configuration information:

```
:EM BREQ=E;C (RET)
 CONFIGURATION STORE OK(Y/N)? Y(RET)
:
```

2. To display the specified values of the current emulation mode and modify them in interactive mode (command execution can be terminated by entering a period (.)):

```
:EM (RET)
 BREQ=E TIME=1.6us TRGU=D TRGB=D MON=1 WAIT=D CT=D MB=D UBC=D
 BREQ (D:DISABLE/E:ENABLE) ? (RET)                (Input (RET) for no modification)
 TIME (1:1.6us/2:406ns/3:20ns) ? 1 (RET)  (Input 1 to set minimum measure time to 1.6 µs)
 TRGU (D:DISABLE/E:ENABLE/M:MULTI) ? . (RET)
                                    (Command is terminated and new settings become valid)
:
```

7.2.20 FILL [F] Writes data to memory

Command Format

- Write FILLΔ<start address>(Δ<end address>/Δ@<number of bytes>)[Δ<data>]
[;[<size>][ΔN]] (RET)

<start address>:	Write start address
<end address>:	Write end address
<number of bytes>:	The number of bytes to be written
<data>:	Data to be written. Default is H'00.
<size>:	Length of data to be written
B:	1 byte
W:	2 bytes
L:	4 bytes
Default:	1 byte
N:	No verification

Description

- Write

— Writes data to the specified memory area. Default value is H'00.

— After data is written, it is also verified. This command can therefore be used as a memory test. If an error occurs, the following message is displayed and processing is terminated.

```
FAILED AT xxxxxxxx   WRITE = yy..'y..'     READ = zz..'z..'
```

xxxxxxxx:	Error address
yy..'y..':	Write data (hexadecimal and ASCII characters)
zz..'z..':	Read data (hexadecimal and ASCII characters)

— Data can be written to only areas CS0 to CS4 or the internal memory areas.

— If W is specified as <size>, but the start address is odd, the lowest bit is rounded down to the preceding even address. If L is specified as <size>, the lower bits are rounded down to become a multiple of four. Writing never exceeds the specified <end address>.

Example

To fill the entire area from addresses H'0 to H'6FFF with 1-byte data H'00:

```
:F 0 6FFF 0  (RET)
:
```

7.2.21 GO [G] Provides realtime emulation

Command Format

- Execution GO[Δ[<start address>][;[<break address>][Δ<mode>]] (RET)

<start address>:	Start address of realtime emulation, or the word RESET
<break address>:	Breakpoint address (Break occurs before the instruction at the break address is executed.)
<mode>:	Emulation mode

R=<n>:	Cycle reset mode; n = 1 to 12
N:	Temporarily invalidates break conditions
I1:	Time interval measurement mode 1
I2:	Time interval measurement mode 2
SB:	BREAK_CONDITION_UBC sequential break mode
TB:	Causes a break to occur at the timeout value specified with the TIME option of the PERFORMANCE_ANALYSIS1 command

Description

- Execution

— Executes realtime emulation (user program execution) starting from the specified <start address>. The following data can be specified as <start address>.

: ***GO <address> (RET)***	: Executes the program from the specified address.
: ***GO (RET)***	: When omitting the address, the program executes from the address where the current PC indicates.
: ***GO RESET (RET)***	: After a RESET signal input to the SH7612, PC and SP are set to the values specified with the reset vector and program execution starts.

— According to the <mode> specification at GO command input, the user program is executed in one of the following modes. If no <mode> is specified, normal emulation mode is assumed.

- Cycle reset mode (R=n; n=1 to 12)

  A RESET signal is input to the SH7612 at the intervals given in table 7.15, and program execution continues. In this mode, all break conditions and trace conditions are invalidated.

- Temporary invalidation of break conditions

  If the N option is specified, software breakpoints (set with the BREAK or BREAK_SEQUENCE command) and hardware break conditions (set with the BREAK_CONDITION_A,B,C or BREAK_CONDITION_UBC command) are invalidated temporarily, and user program emulation continues. The breakpoints and break conditions are invalidated only within one GO command emulation. If the N option is not specified in the next GO command emulation, breakpoints and break conditions are validated again.

- Time interval measurement mode 1

  The execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is measured. After BREAK_CONDITION_UBC2 condition satisfaction, user program execution stops when BREAK_CONDITION_UBC1 conditions are satisfied. In this case, BREAK CONDITION SB will be dispalyed as a cause of termination.

- Time interval measurement mode 2

  The total execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is measured. Even if these break conditions are satisfied, the program does not stop and the execution time between BREAK_CONDITION_UBC2,1 condition satisfaction is added to the previous measured time.

- BREAK_CONDITION_UBC sequential break mode

  Realtime emulation stops only when break conditions set with the BREAK_CONDITION_UBC1,2 command are satisfied in the sequence of the BREAK_CONDITION_UBC2 condition followed by the BREAK_CONDITION_UBC1 condition.

- Timeout break mode

  A break occurs when the timeout or execution count condition specified with the PERFORMANCE_ANALYSIS command is satisfied.

Table 7.15 Cycle Reset Times

Value of n	Reset Interval
1	6.5 µs
2	9.8 µs
3	50 µs
4	100 µs
5	500 µs
6	1 ms
7	5 ms
8	10 ms
9	50 ms
10	100 ms
11	500 ms
12	1 s

The restrictions for each mode at emulation are listed in table 7.16.

Table 7.16 Restrictions for Realtime Emulation Modes

Modes	Restrictions
Cycle reset mode	• Software breakpoints specified with the BREAK or BREAK_SEQUENCE command are ignored. • Hardware break conditions specified with the BREAK_CONDITION_A,B,C or BREAK_CONDITION_UBC command are ignored. • All conditions specified with the TRACE_CONDITION_A,B,C command are ignored. • Parallel mode cannot be entered.
Break prohibition mode	• Software breakpoints specified with the BREAK or BREAK_SEQUENCE command are ignored. • Hardware break conditions specified with the BREAK_CONDITION_A,B,C or BREAK_CONDITION_UBC command are ignored.
Time interval measurement modes 1 and 2	• Software breakpoints specified with the BREAK or BREAK_SEQUENCE command are ignored. • Hardware break conditions specified with the BREAK_CONDITION_A,B,C command are ignored. • Conditions must be specified with the BREAK_CONDITION_UBC1,2 command. • All conditions specified with the TRACE_CONDITION_A,B,C command are ignored. • Parallel mode cannot be entered.
Sequential break mode	• Software breakpoints specified with the BREAK or BREAK_SEQUENCE command are ignored. • Conditions must be specified with the BREAK_CONDITION_UBC1,2 command.
Timeout break mode	Software breakpoints specified with the BREAK or BREAK_SEQUENCE command are ignored.

— If <break address> is specified, realtime emulation stops when the specified address is reached. The instruction at the specified address is not executed. This specification is valid for only the current GO command emulation. BREAK_CONDITION_UBC2 command settings are invalid when a break address is specified.

- During user program execution, program fetch addresses are displayed according to the time interval specified with the MON option in the EXECUTION_MODE command.

- During GO command emulation, pressing the SPACE key or (RET) key enters parallel mode.

- If emulation is terminated, register contents, execution time, and cause of termination are displayed in the following format:

```
PC=00005C60  SR=000000F0:****000000000000****----IIII00--                        (a)
GBR=00000000  VBR=00000000  MACH=00000000  MACL=00000000  PR=00000000
RS=00000000  RE=00000000  MOD=00000000
R0–7   00000000  000000FF  00000011  00000000  00000000  00000000  00000000  00000000
R8–15  00000000  00000000  00000000  00000000  00000000  00000000  00000000  000FFE00
DSR=00000000:************************----COB-
A0G=00  A0=00000000  M0=00000000  X0=00000000  Y0=00000000
A1G=00  A1=00000000  M1=00000000  X1=00000000  Y1=00000000
I-TIME=D'0000H:00M:00S:000000US:000NS (00.0%)      E-COUNT=D'00000              (b)
  MAX=D'0000H:00M:00S:000000US:000NS       MIN=D'0000H:00M:00S:000000US:000NS
                (c)                                      (d)
  AVE=D'0000H:00M:00S:000000US:000NS                                            (e)
RUN-TIME=D'0000H:00M:00S:000000US:000NS                                         (f)
+++: <cause of termination>                                                     (g)
```

(a) The register contents at emulation termination.

(b) In time interval measurement modes 1 and 2, execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is displayed. In only time interval measurement mode 2, the execution count during this period is also displayed.

(c) In time interval measurement modes 1, the maximum execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is displayed.

(d) In time interval measurement modes 1, the minimum execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is displayed.

(e) In time interval measurement modes 1, the average execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is displayed.

Note: The average execution time is obtained by dividing an execution time by the execution count. Accordingly, if emulation stops within the period from BCU2 condition satisfaction to BCU1 condition satisfaction, a correct average execution time will not be displayed.

(f) User program execution time in decimal. According to the TIME option of the EXECUTION_MODE command, the maximum measurable time is 488, 124, or 6 hours, where the minimum measurement time is 1.6 µs, 406 ns, or 20 ns, respectively. If the period exceeds the maximum measurable time, it is displayed as *.

(g) Cause of termination, as listed in table 7.17

Table 7.17 Causes of GO Command Termination

Message	Cause of Termination
BREAK CONDITION UBC1	A break condition specified with the BREAK_CONDITION_UBC1 command was satisfied.
BREAK CONDITION UBC2	A break condition specified with the BREAK_CONDITION_UBC2 command was satisfied.
BREAK CONDITION An	A break condition specified with the BREAK_CONDITION_An command was satisfied (n = 1 to 8).
BREAK CONDITION Bn	A break condition specified with the BREAK_CONDITION_Bn command was satisfied (n = 1 to 8).
BREAK CONDITION Cn	A break condition specified with the BREAK_CONDITION_Cn command was satisfied (n = 1 to 8).
BREAK CONDITION UBC1,2	Multiple break conditions specified with the BREAK_CONDITION_UBC1,2 commands were satisfied.
BREAK CONDITION A1, ... ,8	Multiple break conditions specified with the BREAK_CONDITION_A (A1 to A8) command were satisfied.
BREAK CONDITION B1, ... ,8	Multiple break conditions specified with the BREAK_CONDITION_B (B1 to B8) command were satisfied.
BREAK CONDITION C1, ... ,8	Multiple break conditions specified with the BREAK_CONDITION_C (C1 to C8) command were satisfied.
BREAK CONDITION SB	A sequential break condition specified with the BREAK_CONDITION_UBC1,2 commands was satisfied.
BREAK KEY	The (CTRL) + C keys were pressed or the ABORT command was executed for forcible termination.
BREAKPOINT	Emulation stopped at a software breakpoint specified with the BREAK command.
BREAK SEQUENCE	A condition for passing software breakpoints specified with the BREAK_SEQUENCE command was satisfied.
ILLEGAL INSTRUCTION	A break instruction (H'0000) was executed.
NO EXECUTION	The user program was not executed (this message is displayed only for the RESULT command).
RESET BY E8000	The emulator forcibly terminates program execution with the RESET signal because an error has occurred in the user system.
STOP ADDRESS	Emulation stopped at the break address specified with the GO command.
SUBROUTINE TIMEOUT	The timeout condition specified with the PERFORMANCE_ANALYSIS1 command was satisfied.

Table 7.17 Causes of GO Command Termination (cont)

Message	Cause of Termination
SUBROUTINE COUNT OVERFLOW	The execution count limit specified with the PERFORMANCE_ANALYSIS1 command was exceeded.
TRACE BUFFER OVERFLOW	The trace buffer overflowed.
MULTI BREAK	Emulation stopped by the multi break.

— During user program execution, the SH7612 execution status is displayed. Displayed contents are shown in table 7.18. This status is monitored at time intervals specified with the MON option of the EXECUTION_MODE command, and if there is a difference from the previous status, the status is displayed.

Table 7.18 Execution Status Display

Display	Meaning
** BACK	BACK signal is low.
** PC=xxxxxxxx	During user program execution, the program fetch address is displayed according to the time intervals specified with the MON option in the EXECUTION_MODE command.
** RESET	RESET signal is low. The SH7612 has been reset.
** RUNNING	User program execution has started. This message is displayed once when GO command execution starts or when parallel mode is cancelled. Note that this message will be deleted when **PC=xxxxxxxx (second message in this table) is displayed.
** TOUT A = xxxxxxxx xxxxxxxx: Address bus value	Bus cycle stops for 80 µs or more. The address bus value is displayed. **Note that this message is also displayed when the SH7612 enters sleep or standby mode and bus cycle stops for 80 µs or more.**
** VCC DOWN	User system Vcc (power voltage) is 2.65 V or less. The SH7612 is not operating correctly. (Displayed only when the user clock is selected.)
** WAIT A = xxxxxxxx xxxxxxxx: Address bus value	WAIT signal is low. The address bus value is displayed. The address bus value is not displayed during refresh cycles.
** BREQ	BREQ signal is low.
** PACK	Clock pause signal is low.

- If the TB option is specified, user program execution stops when the timeout value or execution count limit specified with the PERFORMANCE_ANALYSIS1 command is exceeded.

Notes

1. When a hardware break condition (set by the BREAK_CONDITION_A,B,C command) is satisfied during program execution, the program does not terminate until at least one of the instructions that have been already fetched is executed. If another hardware break is satisfied before the user program terminates, several termination causes will be displayed. For further details, study trace information.
2. At each software breakpoint set with the BREAK command or at each pass point set with the BREAK_SEQUENCE command, the program halts at that address, the emulator analyzes the pass count and pass point of the program, and then the program continues. When the memory access command processing in parallel mode occurs during this termination, memory cannot be accessed. At this time,

   ```
   *** 78: EMULATOR BUSY
   ```

   is displayed, and the command should be re-input.

   However, when the interval of termination is too short, the PC is not displayed, the emulator does not enter parallel mode, or commands may not be executed in parallel mode.
3. When the contents of a breakpoint (set by the BREAK command) have been modified by the user program during emulation, that breakpoint will be cancelled at execution stop.
4. When the condition that UBC use is enabled is specified with the UBC option of the EXECUTION_MODE command, the following functions cannot be used.

   (a) Software breakpoints
   - When restarting emulation from the breakpoint set with the BREAK command
   - When specifying the number of times a breakpoint is reached with the BREAK command
   - BREAK_SEQUENCE command

   Under the above conditions, when emulation cannot restart, the following error message is displayed and the emulator enters the command input wait state.

   ```
   *** 8: UBC IS USED BY USER SYSTEM
   ```

   (b) BREAK_CONDITION_UBC sequential break mode

   (c) Emulation execution when <break address> is specified

Examples

1. To reset the SH7612 and start emulation from the reset vector PC address:

```
:G RESET (RET)
 ** PC=00001130
```

2. To start emulation from address H'1000 and stop emulation just before address H'2020 is executed:

```
:G 1000;2020 (RET)
:
```

3. To start emulation from the current PC address in sequential break mode (BREAK_CONDITION_UBC):

```
:G ;SB (RET)
 ** PC=00004250
```

4. To start emulation from the current PC address and modify memory contents in parallel mode:

```
:G (RET)
 ** PC=00010204
#M FEF0 (RET)
 0000FEF0 FE  ?  FF (RET)
 0000FEF1 FF  ?  . (RET)
#END (RET)
 ** PC=00011456
```

7.2.22 HELP [HE] Displays all commands and command format

Command Format

- Display HELP (RET) (All commands are displayed.)
  HELP Δ <command> (RET) (Command format is displayed.)

Description

- Display
  — Displays all emulator command names and abbreviations.

HELP

```
:HE (RET)
  .<REGISTER>                              *AB            : ABORT
 *ALI            : ALIAS                    A             : ASSEMBLE
  BI             : BACKGROUND_INTERRUPT   **B             : BREAK
**BCA,1,2,3,4,5,6,7,8  : BREAK_CONDITION_A,1,2,3,4,5,6,7,8
**BCB,1,2,3,4,5,6,7,8  : BREAK_CONDITION_B,1,2,3,4,5,6,7,8
**BCC,1,2,3,4,5,6,7,8  : BREAK_CONDITION_C,1,2,3,4,5,6,7,8
**BCU,1,2: BREAK_CONDITION_UBC,1,2        **BS            : BREAK_SEQUENCE
  CH             : CHECK                  **CL            : CLOCK
  CNF            : CONFIGURATION           *CV            : CONVERT
  DC             : DATA_CHANGE              DS            : DATA_SEARCH
 *DA             : DISASSEMBLE             *D             : DUMP
 *E              : END                      EM            : EXECUTION_MODE
  F              : FILL  G                : GO
 *HE             : HELP *HT               : HISTORY
 *ID             : ID                       MP            : MAP
 *M              : MEMORY                   MD            : MODE
  MV             : MOVE  MR               : MOVE_TO_RAM
  PA,1,2,3,4,5,6,7,8   : PERFORMANCE_ANALYSIS,1,2,3,4,5,6,7,8
  Q              : QUIT *RX               : RADIX
  R              : REGISTER                 RS            : RESET
  RT             : RESULT                  *ST            : STATUS
  S              : STEP  SI               : STEP_INFORMATION
  SO             : STEP_OVER               *T             : TRACE
 *TCA,1,2,3,4,5,6,7,8  : TRACE_CONDITION_A,1,2,3,4,5,6,7,8
 *TCB,1,2,3,4,5,6,7,8  : TRACE_CONDITION_B,1,2,3,4,5,6,7,8
 *TCC,1,2,3,4,5,6,7,8  : TRACE_CONDITION_C,1,2,3,4,5,6,7,8
 *TDM            : TRACE_DISPLAY_MODE       TMO           : TRACE_MODE
 *TS             : TRACE_SEARCH             L             : LOAD
  SV             : SAVE  V                : VERIFY
  IL             : INTFC_LOAD               IS            : INTFC_SAVE
  IV             : INTFC_VERIFY           *#ASC           : ASC
*#BIN            : BIN                    *#BYE           : BYE
*#CD             : CD                     *#CLOSE         : CLOSE
 *FTP            : FTP                     *LAN           : LAN
  LH             : LAN_HOST                #LL            : LAN_LOAD
 #LSV            : LAN_SAVE                #LV            : LAN_VERIFY
 *LO             : LOGOUT                 *#LS            : LS
*#OPEN           : OPEN *#PWD             : PWD
  RTR            : ROUTER                 *#STA           : STA
  SN             : SUBNET
```

Note: *: Usable in parallel mode

No *: Unusable in parallel mode

****: Available only for display in parallel mode**

#: Available when the FTP server is open.

— Displays command format when command name is specified:

```
:HE <command name>  (RET)        (Displays command format)
:
```

Example

To display GO command format:

```
:HE GO  (RET)
 Executes real-time emulation.
      G [<addr1>][;[<breakaddr>][ <mode>][ LEV]] <RET>
  <addr1>      : {RESET,<address>}
   RESET       : execute after MPU reset
  <address>    : starting address
                 if deleted executes from current PC
  <breakaddr>  : address when stopping the program
  <mode>       : R=<n>   - cycle reset mode ( n = 1 to 12 )
               : N       - temporarily invalidates break conditions
               : I1      - time interval measurement mode 1
               : I2      - time interval measurement mode 2
               : SB      - sequential break mode UBC
               : TB      - time out break mode
                 default - normal mode
:
```

7.2.23 HISTORY [HT] Displays input command history

Command Format

• Display	HISTORY (RET)	(Displays all input commands)
	HISTORY <history number> (RET)	(Displays the input command of the specified history number)

<history number>: History number (1 to 16)

Description

- Display

— Displays the 16 commands most recently input including the HISTORY command in the input order.

— If <history number> is entered, the command corresponding to <history number> is displayed as shown below and the emulator enters command input wait state. When the (RET) key is pressed, the displayed command is executed.

Note

Subcommands cannot be displayed by the HISTORY command.

Example

```
:HISTORY (RET)
 1 MAP
 2 MAP  0 FFFFFF;U
 3 F 0 1000 FF
 4 B 300
 5 BCA1 A=104
 6 HISTORY
:HISTORY 5 (RET)
:BCA1 A=104_ ------------Enters command input wait state
```

7.2.24 ID [ID] Displays version number of E8000 system program

Command Format

- Display ID (RET)

Description

- Display
  Displays the version and revision numbers of the SH7612 E8000 system program.

Example

To display the version and revision numbers of the SH7612 E8000 system program:

```
:ID (RET)
 SH7612 E8000 (HS7612EDD81SF) Vm.n
 Copyright (C) Hitachi, Ltd. 1997
 Licensed Material of Hitachi, Ltd.
:
```

7.2.25 MAP [MP] Specifies and displays memory attribute

Command Format

- Specification MAPΔ<start address>Δ<end address>;<memory attribute> (RET)
- Display MAP[Δ<start address>Δ<end address>] (RET)

<start address>:	Start address of memory area whose attribute is to be specified or displayed
<end address>:	End address of memory area whose attribute is to be specified or displayed
<memory attribute>:	Memory type

U:	Memory in the user system (cancels emulation memory usage)
S:	Standard emulation memory in emulator
SW:	Standard emulation memory in emulator with write protection

Description

- Specification

— Allocates standard emulation memory to areas CS0 to CS4 in 1-Mbyte units. The emulation memory can be write-protected by specifying SW as the memory attribute. The start address is rounded down to 0 or a multiple of H'100000, and the end address is rounded up to a multiple of H'100000, minus one.

```
: MAP 0 H'FFFFF;S (RET)
```

After allocation, the size of the unused standard emulation memory is displayed.

```
REMAINING EMULATION MEMORY   S=xMB
```

xMB: (Standard emulation memory)

When standard emulation memory is allocated to areas CS0 to CS4, user system memory in the same space as the allocated area cannot be accessed correctly.

— To use memory in the user system, specify U for the memory attribute.

— To cancel the write protection of standard emulation memory (SW), respecify S or U as the memory attribute.

- Display

— Displays the memory attribute of the area defined by <start address> and <end address>, in the following format:

```
: MAP <start address>  <end address>  (RET)
 xxxxxxxx–xxxxxxxx;y  xxxxxxxx–xxxxxxxx;y                         (a)
          ...
 xxxxxxxx–xxxxxxxx;y  xxxxxxxx–xxxxxxxx;y
 X-RAM AREA  = xxxxxxxx–xxxxxxxx                                  (b)
 Y-RAM AREA  = xxxxxxxx–xxxxxxxx                                  (c)
 INTERNAL I/O = xxxxxxxx–xxxxxxxx xxxxxxxx–xxxxxxxx xxxxxxxx–xxxxxxxx   (d)
 REMAINING EMULATION MEMORY    S=xMB                              (e)
```

(a) Address range and memory attribute

Displays the addresses in both the cache and cache-through areas to which standard emulation memory is allocated.

y: Standard emulation memory attribute

S: Standard emulation memory in emulator

SW: Standard emulation memory in emulator with write protection

(b) Internal X-RAM address range

(c) Internal Y-RAM address range

(d) Internal I/O address range

(e) Unused standard emulation memory size in hexadecimal

S=xMB (Standard emulation memory)

— When no address is specified, the memory attributes of all memory areas are displayed in the format shown above.

Notes

1. If there is not enough standard emulation memory to satisfy the specification, the memory attribute is specified only for the memory area available.
2. Standard emulation memory cannot be allocated to areas other than areas CS0 to CS4.
3. A memory attribute cannot be allocated to a range that includes a cache area, cache-through area, or reserved area.
4. An area to which emulation memory is allocated cannot be used as user system memory. For example, if area CS0 is assigned to emulation memory, area CS0 cannot be used as user system memory. However, areas CS1 to CS4 can be used as user system memory.
5. A cache area and cache-through area specified in standard emulation memory are handled as the same area. Accordingly, when the map is allocated to either of them, it is allocated to both areas. Memory attributes in both areas are displayed.
6. For specifications of internal memory, refer to the Hardware Manual of the SH7612.

Examples

1. To allocate standard emulation memory to the address range from H'1000000 to H'10FFFFF:

```
:MP 1000000 10FFFFF;S (RET)
 REMAINING EMULATION MEMORY S=3MB
:
```

2. To allocate standard emulation memory to the address range from H'2000000 to H'20FFFFF with write protection:

```
:MP 2000000 20FFFFF;SW (RET)
 REMAINING EMULATION MEMORY S=2MB
:
```

3. To display the memory address ranges and attributes of allocated standard emulation memory, the internal memory address ranges, and the internal I/O address range:

```
:MP (RET)
 01000000-010FFFFF;S     21000000-210FFFFF;S
 02000000-020FFFFF;SW    22000000-220FFFFF;SW
 X-RAM AREA   = 1000F000-0000FFFF
 Y-RAM AREA   = 1001F000-0001FFFF
 INTERNAL I/O = FFFF8000-FFFFBFFF  FFFFFC00-FFFFFDBF    FFFFFE00-FFFFFFFF
 REMAINING EMULATION MEMORY S=2MB
:
```

4. To cancel write protection for the standard emulation memory allocated to the address range from H'2000000 to H'20FFFFF:

```
:MP 2000000 20FFFFF ;S (RET)
 REMAINING EMULATION MEMORY S=2MB
:
```

7.2.26 MEMORY [M] Displays or modifies memory contents

Command Format

- Display, modification MEMORYΔ<address>[Δ<data>][;[<option>][ΔN]] (RET)

<address>: Address of memory area whose contents are to be displayed or modified

<data>: Data to be written to the specified address

<option>: Length of display or modification units

B: 1-byte units
W: 2-byte units
L: 4-byte units
XW: 16-bit fixed-point units
XL: 32-bit fixed-point units
O: Odd address; 1-byte units
E: Even address; 1-byte units
Default: 1-byte units

N: No verification

Description

- Display, modification

  — If <data> is omitted, the emulator displays memory contents at the specified address and enters input wait state of the modification data. The user can then enter data and modify memory contents; this process can then be repeated for the next address. If option N is not specified, the data to be modified is read and verified. Memory contents are displayed, and modified data is input in the following format.

```
: MEMORY <address>  (RET)
 xxxxxxxx     yyyyyyyy      ?  [<data>][;<option>]  (RET)
```

xxxxxxxx:	Address of data to be modified
yyyyyyyy:	Memory contents displayed in modification units.
<data>:	New data. Data length is considered to be the same as that of the data displayed on the screen. If only the (RET) key is pressed, data is not modified, and the next address is displayed.
<option>:	The unit of display or modification can be changed, or the address can be incremented or decremented. When <data> is specified, <option> is processed after the data is modified. When <data> is not specified, a semicolon (;) can be omitted to specify options L, W, O, ^, =, or . (period). Table 7.19 lists option functions.

Notes 1. Data in the internal I/O area is never verified.

2. When the contents of the reserved area are modified without specifying N (no verification), a verify error may occur because the modified data is read as undefined.

Table 7.19 MEMORY Command Options

Option	Description
B	Modification in 1-byte units
W	Modification in 2-byte units
L	Modification in 4-byte units
XW	Modification in 16-bit fixed-point units
XL	Modification in 32-bit fixed-point units
O	Odd address; modification in 1-byte units
E	Even address; modification in 1-byte units
^	Display of previous address contents
=	Display of current address contents
.	Command termination
Default	Display of next address contents

— When specifying <address> and <data>, memory contents are modified immediately and the emulator waits for the next command input.

```
: MEMORY  H'FFF0  H'F8 (RET)
:
```

Examples

1. To modify memory contents from address H'1000:

```
:M 1000 (RET)
 00001000 00        ?   FF (RET)
 00001001 01        ?   10 (RET)
 00001002 22        ?   (RET)
 00001003 00        ?   30;W (RET)
 00001004 0000      ?   1234 (RET)
 00001006 1100      ?   ^ (RET)
 00001004 1234      ?   ;L (RET)
 00001004 12341100  ?   12345678 (RET)
 00001008 00000000  ?   . (RET)
:
```

2. To modify memory contents from address H'8000 in 2-byte units without verification:

```
:M 8000 ;W N (RET)
 00008000  0000  ?  FF (RET)
 00008002  0002  ?  1000 (RET)
 00008004  FFF2  ?  . (RET)
:
```

3. To modify memory contents from address H'F000 in 16-bit fixed-point units:

```
:M F000 ;XW (RET)
 0000F000  0.87544  ?  0.875 (RET)
 0000F002  0.45637  ?  0.5 (RET)
 0000F004  0.39285  ?  . (RET)
:
```

4. To write data H'10 to address H'FE00 without displaying the memory contents:

```
:M FE00 10 (RET)
:
```

7.2.27 MODE [MD] Specifies or displays SH7612 operating mode

Command Format

- Specification MODE;C (RET)
- Display MODE (RET)

Description

- Specification

— Interactively specifies the SH7612 operating mode in the emulator as shown below.

: ***MODE;C (RET)***
E8000 MODE (MD4-0) xx ? ***(a) (RET)***
CONFIGURATION STORE OK (Y/N) ? ***(b) (RET)***

(a) Operating mode. Input hexadecimal values to specify MD4 to MD0 bits.

(b) Confirmation message for configuration information storage

Y: The specified parameters are stored as configuration information in the emulator flash memory.

N: The specified parameters are not stored as configuration information and command execution is terminated.

If Y is input in (b), stores the settings as configuration information in the emulator flash memory. When the emulator is initiated after configuration information storage, it emulates in the stored operating mode. The E8000 system program terminates after the SH7612 operating mode is set, and must then be re-initiated.

- Display

Displays the SH7612 operating mode in the emulator, the operating mode selection pin (MD4 to MD0) status on the user system, and the operating mode setting method in the following format:

: ***MODE (RET)***
MODE = xx (MD4-0=nn) (a)

(a) Operating mode (xx), and operating mode selection pin status on the user system (MD4-0=nn) (refer to table 7.20).

If a value other than those shown in the table is displayed as nn, the SH7612 does not operate correctly. Check the user system. When the user system is not connected, nn is displayed as 1F.

Table 7.20 Operating Mode Selection Pin Status and Display

CS0 Area Bus Width		Clock Mode			
MD4	**MD3**	**MD2**	**MD1**	**MD0**	**Display (nn)**
Low	Low	Low	Low	Low	0
Low	Low	Low	Low	High	1
Low	Low	Low	High	Low	2
:	:	:	:	:	:
High	High	High	High	High	1F

MODE

Notes

1. The emulator operating mode is specified with the MODE command, regardless of the operating mode selection pin (MD4 to MD0) status on the user system.
2. **The emulator does not operate correctly if clock mode 4, 5, or 6 is selected unless the clock signal is input from the user system. Make sure to input the clock signal from the user system. When the user system is not connected, select clock mode 0, 1, 2, or 3 with the MODE command and restart the emulator. If clock mode 4, 5, or 6 is selected and the E8000 does not activate normally, the command-wait state is entered if the break key is input. Select correct mode with the MODE command.**
3. For available emulator operating modes, refer to the Hardware Manual of the SH7612.

Examples

1. To specify the operating mode as mode 2 and store configuration information:

```
:MD;C (RET)
 E8000 MODE (MD4-0) = 1F ? 2 (RET)
 CONFIGURATION STORE OK (Y/N) ? Y (RET)

START E8000
 S:START E8000
 F:FLASH MEMORY TEST
 L:SET LAN PARAMETER
 T:START DIAGNOSTIC TEST
   (S/F/L/T) ? _
```

2. To display the SH7612 operating mode in the emulator:

```
:MD (RET)
 MODE = 00(MD4-0=1F)
:
```

7.2.28 MOVE [MV] Transfers memory contents

Command Format

- Move data MOVEΔ<start address>(Δ<end address>/Δ@<number of bytes>) Δ<destination address> (RET)

<start address>:	Start address of source area
<end address>:	End address of source area
<number of bytes>:	The number of bytes to be transferred
<destination address>:	Start address of destination

Description

- Move data

— Transfers the contents of the memory area specified with <start address> and <end address> or <number of bytes> to an address range starting with <destination address>. Transfer is usually performed from the <start address>. However, if <destination address> is set within the range from <start address> to <end address> or <number of bytes>, transfer is performed from the <end address> or <start address> + <number of bytes>.

— Verifies the transfer. If a verification error occurs,

```
FAILED AT xxxxxxxx     WRITE = yy 'y'   READ = zz 'z'
```

is displayed.

xxxxxxxx:	Address of error
yy 'y':	Write data (hexadecimal and ASCII characters)
zz 'z':	Read data (hexadecimal and ASCII characters)

If areas other than the internal memory areas or areas CS0 to CS4 are included in the destination, transfer is performed to only the internal memory areas and areas CS0 to CS4.

Example

To transfer data in the address range from H'101C to H'10FC to address H'1000:

```
:MV 101C 10FC 1000  (RET)
:
```

7.2.29 MOVE_TO_RAM [MR] Moves contents of ROM to standard emulation memory

Command Format

- Movement MOVE_TO_RAMΔ<start address>Δ<end address>
  [;<memory attribute>] (RET)

<start address>:	Start address of the ROM area to be moved
<end address>:	End address of the ROM area to be moved
<memory attribute>:	Type of standard emulation memory to be allocated

S:	Standard emulation memory
SW:	Standard emulation memory with write protection
Default:	Standard emulation memory (S)

Description

- Movement

— Use this command to temporarily modify ROM contents in the user system and execute the modified program. Transfers user system ROM contents to the specified standard emulation memory area where data can be modified. Data transfer to standard emulation memory is performed in 1-Mbyte units. After data transfer, the unused standard emulation memory area is displayed as follows:

```
REMAINING EMULATION MEMORY   S=xMB
```

S=xMB (Standard emulation memory)

— If there is not enough unused standard emulation memory to satisfy the specification, data transfer is performed only for the memory area available, and command execution terminates.

— Contents of only areas CS0 to CS4 and the internal memory areas can be transferred.

— Refer to the MAP command, for details on write-protected area settings.

Example

To allocate standard emulation memory to the address range from H'0 to H'3FFFF in the user system ROM area and transfer ROM contents:

```
:MR 0 3FFFF;S  (RET)
 REMAINING EMULATION MEMORY S=3MB
:
```

7.2.30 PERFORMANCE_ANALYSIS1-8 [PA,1,2,3,4,5,6,7,8] Specifies, cancels, initializes, and displays performance measurement data

Command Format

- Specification PERFORMANCE_ANALYSIS(1/2/3/4/5/6/7/8)Δ<subroutine name>
  Δ<start address>Δ<end address>[ΔTIME=<timeout value>]
  [ΔCOUNT=<count value>;I1 (RET)
  (Subroutine execution time measurement mode 1)

  PERFORMANCE_ANALYSIS(1/2/3/4/5/6/7/8)Δ<subroutine name>
  Δ<start address>Δ<end address>[ΔTIME=<timeout value>]
  [ΔCOUNT=<count value>;I2 (RET)
  (Subroutine execution time measurement mode 2)

  PERFORMANCE_ANALYSIS(1/3/5/7)Δ<subroutine name>
  Δ<start address range>Δ<end address range>;I3 (RET)
  (Subroutine execution time measurement mode 3)

  PERFORMANCE_ANALYSIS(1/3/5/7)Δ<subroutine name>
  Δ<start address>Δ<end address>;AC=<accessed area address range>Δ<access type> (RET)
  (Area access count measurement mode)

  PERFORMANCE_ANALYSISΔ(1/3/5/7)Δ<subroutine name>
  Δ<start address>Δ<end address>;SC=<called subroutine address range> (RET)
  (Subroutine call count measurement mode)
- Cancellation PERFORMANCE_ANALYSIS[(1/2/3/4/5/6/7/8)][Δ]– (RET)
- Initialization PERFORMANCE_ANALYSISΔ;I (RET)
- Display PERFORMANCE_ANALYSIS[Δ;(A/V)] (RET)

n: Subroutine number

<subroutine name>: Name of the subroutine whose execution performance is to be measured

<start address>: Subroutine entry address

<end address>: Subroutine exit address

<timeout value>: Timeout value of execution time measurement. Can be set for only the PERFORMANCE_ANALYSIS1 command.

Display format: xxx[:yy[:zz[:nnnnnn]]]

xxx: Hour
yy: Minute
zz: Second
nnnnnn: Microsecond

Specifiable range:
xxx: 0 to 999
yy: 0 to 59
zz: 0 to 59
nnnnnn: 0 to 999999

<specified count>: Execution count limit. Can be set for only the PERFORMANCE_ANALYSIS1 command.

Specifiable range: H'1 to H'FFFF

<start address range>: Subroutine entry address range

<start address of subroutine entry range>:<end address of subroutine entry range>

<end address range>: Subroutine exit address range

<start address of subroutine exit range>:<end address of subroutine exit range>

<accessed area address range>: Address range of the area which is accessed by the subroutine

<start address of range>:<end address of range>

<access type>: Bus cycle type for the specified access area

DAT: Execution cycle
DMA: DMA cycle
Default: All access cycles

<called subroutine address range>: Address range of the called subroutine accessed by the calling subroutine

<start address>:<end address>

I: Initializes performance measurement information.

A: Displays specified subroutine addresses.

V: Displays subroutine execution time and execution count in numerical form. If V is omitted, display is in graph form.

Description

- Specification

— Measures the execution time and count of the specified subroutine during user program execution initiated with the GO command. The following modes can be specified.

a. Subroutine execution time measurement mode 1

Measures the execution time and count of the subroutine defined by <start address> and <end address>. Measurement starts when an address within the range from the start address to the end address is prefetched, halts when an address outside the specified range is prefetched, and restarts when an address within the specified range is prefetched again. The subroutine execution count is incremented every time the subroutine end address is fetched. The execution time of subroutines called from the specified subroutine is not included in the measurement results.

b. Subroutine execution time measurement mode 2

Measures the execution time and count of the subroutine defined by <start address> and <end address>. Measurement starts when the start address is prefetched and halts when the end address is prefetched. The subroutine execution count is incremented every time the subroutine end address is fetched. The execution time of subroutines called from the specified subroutine is included in the measurement results.

c. Subroutine execution time measurement mode 3

Measures the execution time and count of the subroutine defined by <start address range> and <end address range>. Measurement starts when an address in the start address range is prefetched and halts when an address in the end address range is prefetched. The subroutine execution count is incremented every time <end address range> is passed.

d. Area access count measurement mode

Counts the number of times the subroutine defined by <start address> and <end address> accesses the range specified by <accessed area address range>. The subroutine execution time is measured using subroutine execution time measurement mode 1.

e. Subroutine call count measurement mode

Counts the number of times the subroutine defined by <subroutine name>, <start address>, and <end address> calls the subroutine specified by <called subroutine address range>. The subroutine execution time is measured using subroutine execution time measurement mode 1.

— Table 7.21 lists the measurement modes that can be specified by each PERFORMANCE_ANALYSIS command. When break conditions or trace conditions have been set, subroutines may not be set to their maximum number.

Table 7.21 Measurement Modes for Each Command

Measurement Mode	PA1	PA2	PA3	PA4	PA5	PA6	PA7	PA8
Subroutine execution time measurement mode 1	O	O	O	O	O	O	O	O
Subroutine execution time measurement mode 2	O	O	O	O	O	O	O	O
Subroutine execution time measurement mode 3	O	X	O	X	O	X	O	X
Area access count measurement mode	O	X	O	X	O	X	O	X
Subroutine call count measurement mode	O	X	O	X	O	X	O	X

Note: O: Mode can be specified.
X: Mode cannot be specified.

— Up to eight subroutines can be specified when using only subroutine execution time measurement mode 1 or 2 for measurement. However, only up to four subroutines can be specified in subroutine execution time measurement mode 3, area access count measurement mode, and subroutine call count measurement mode.

— This command cannot be executed during program execution by the STEP or STEP_OVER command.

— If <timeout value> is specified in the PERFORMANCE_ANALYSIS1 command and the subroutine execution time exceeds the specified timeout value, a break occurs. To enable this, make sure to specify TB as the mode with the GO command.

— If <specified count> is specified in the PERFORMANCE_ANALYSIS1 command and the subroutine execution count reaches the specified count, a break occurs. To enable this, make sure to specify TB as the mode with the GO command.

Note: An execution count that is exceeded is detected when the program passes through the subroutine end address. Consequently, a subroutine execution count that is equivalent to the specified count plus one and the correponding subroutine execution time are displayed.

- Cancellation

— Cancels measuring execution performance for the specified subroutine number.

— If the subroutine number is omitted, all subroutines assigned for execution performance measurement are canceled.

- Initialization

Clears the current execution time and count for all subroutines, as well as the total run time. The total run time begins to be measured only after a subroutine to be measured by this command is assigned. If no subroutines are assigned, the total run time is not measured.

- Display

Displays specified subroutine addresses or performance measurement results, in one of the following three formats. If a subroutine name is specified, the subroutine addresses and measurement results are displayed in numerical form or graph form.

— Execution time ratio displayed in graph form. (No option is specified.)

```
: PERFORMANCE_ANALYSIS  (RET)
  NO      NAME     MODE   RATE      0---10---20---30---40---50---60---70---80---90--100
   1      SUBA      I1    D'10.0%   *****
  (a)      (b)      (c)     (d)       (e)
   2      SUBB      I2    D'20.0%   **********
   3      SUBC      I3    D'20.0%   **********
   4
   5      SUBD      AC    D'15.0%   ********
          <ACCESS>        D'  5.0%  ***                       (g)
   7      SUBE      SC    D'30.0%   ***************
          <CALL-SUB>      D'  5.0%  ***                       (h)
----------------------------------------------------------------------------------------------------
TOTAL RUN-TIME = D'0000H:10M:00S:000020US:000NS               (f)
```

(a) Subroutine number

(b) Subroutine name (up to 8 characters are displayed)

(c) Execution measurement mode

I1:	Subroutine execution time measurement mode 1
I2:	Subroutine execution time measurement mode 2
I3:	Subroutine execution time measurement mode 3
AC:	Area access count measurement mode
SC:	Subroutine call count measurement mode

(d) Execution time ratio as a percentage

(e) Execution time ratio in graph form (in units of 2%/asterisk, rounded up)

(f) Total run time displayed as H (hour), M (minutes), S (second), US (microsecond), and NS (nanosecond).

(g) Execution time ratio as a percentage and in graph form for area access

(h) Execution time ratio as a percentage and in graph form for subroutine call

— Execution time ratio displayed in graph form. (Option A is specified.)

```
: PERFORMANCE_ANALYSIS ;A  (RET)
  NO   NAME  MODE     ADDRESS
   1   SUBA     I1       00000100   00001FF0    TIME=xxxH:xxM:xxS:xxxxxxUS    COUNT=nnnnnnnn
  (a)    (b)      (c)          (d)           (e)              (f)                              (g)
   2   SUBB     I2       00005000   00007FF0
   3   SUBC     I3       00010000  : 0001008F                                            (h)
                         00020000  : 00020098                                            (i)
   4
   5   SUBE     AC       00002030  : 0000207F
       <ACCESS>          FFFFFF00 : FFFFFF7F ; DAT
                                    (j)              (k)
   7   SUBD     SC       00020100  : 0002FFFF
       <CALL-SUB>        00030000  : 00030060                                            (l)
-------------------------------------------------------------------------------------------------------------------
TOTAL RUN-TIME = D'0000H:10M:00S:000020US:000NS                                          (m)
```

(a) Subroutine number

(b) Subroutine name (up to 8 characters are displayed)

(c) Time measurement mode

I1: Subroutine execution time measurement mode 1
I2: Subroutine execution time measurement mode 2
I3: Subroutine execution time measurement mode 3
AC: Area access count measurement mode
SC: Subroutine call count measurement mode

(d) Subroutine start address

(e) Subroutine end address

(f) Timeout value (displayed only when the timeout value is set with the TIME option in mode I1 or I2)

(g) Count value (displayed only when the count value is set with the COUNT option in mode I1 or I2)

(h) Start address range in subroutine execution time measurement mode 3

(i) End address range in subroutine execution time measurement mode 3

(j) Accessed area address range in area access count measurement mode

(k) Access type of accessed area in area access count measurement mode

DAT: Execution cycle

DMA: DMA cycle

(l) Called subroutine address range in subroutine call count measurement mode

(m) Total run time

— Execution time and count displayed as numerical values. (Option V is specified.)

```
: PERFORMANCE_ANALYSIS ;V  (RET)
  NO    NAME    MODE    RATE     RUN-TIME                               E-COUNT
   1    SUBA     I2     D'10.0%  D'0000H:00M:05S:001000US:250NS         D'00005
  (a)    (b)     (c)      (d)                 (e)                          (f)
        MAX  D'0000H:00M:05S:001000US:250NS   MIN  D'0000H:00M:05S:001000US:250NS
                 (g)                                     (h)
        AVE  D'0000H:00M:05S:001000US:250NS
                 (I)
   2    SUBB     I1     D'20.0%  D'0000H:00M:10S:010305US:500NS         D'00010
        AVE  D'0000H:00M:05S:001000US:250NS
   3    SUBC     I3     D'20.0%  D'0000H:00M:10S:010305US:500NS         D'00010
        AVE  D'0000H:00M:05S:001000US:250NS
   4
   5    SUBD     AC     D'10.0%  D'0000H:00M:05S:001000US:250NS         D'00005
   7    SUBE     SC     D'20.0%  D'0000H:00M:10S:010305US:500NS         D'00010
---------------------------------------------------------------------------------
TOTAL RUN-TIME = D'0001H:00M:50S:000020US[:250NS]                       (j)
```

(a) Subroutine number

(b) Subroutine name (up to 8 characters are displayed)

(c) Time measurement mode

I1: Subroutine execution time measurement mode 1

I2: Subroutine execution time measurement mode 2

I3: Subroutine execution time measurement mode 3

AC: Area access count measurement mode

SC: Subroutine call count measurement mode

(d) Execution time ratio as a percentage

(e) Execution time

(f) Area access count in area access count measurement mode or subroutine call count in subroutine call count measurement mode

(g) Subroutine maximum execution time (only for the PERFORMANCE_ANALYSIS 1,2,3,4 command in subroutine execution time measurement mode 2 (I2))

(h) Subroutine minimum execution time (only for the PERFORMANCE_ANALYSIS 1,2,3,4 command in subroutine execution time measurement mode 2 (I2))

(i) Subroutine average execution time (only for the PERFORMANCE_ANALYSIS 1,2,3,4 command)

(j) Total run time displayed as H (hour), M (minutes), S (second), US (microsecond), and NS (nanosecond).

Note

According to the TIME option of the EXECUTION_MODE command, the maximum measurable time is 488, 124, or 6 hours, where the minimum measurement time is 1.6 µs, 406 ns, or 20 ns, respectively.

When conditions have already been set with the BREAK_CONDITION_C or TRACE_CONDITION_C command, conditions cannot be set to the same channel number. For example, when conditions have already been set to BREAK_CONDITION_C1 or TRACE_CONDITION_C1, no conditions can be set to PERFORMANCE_ANALYSIS1. To set new conditions, cancel previously set conditions.

Examples

1. To measure the execution time of subroutines SUBB (H'5000 to H'7FE0) and SUBD (H'20100 to H'2FFFF) and initialize the performance measurement data:

```
:PA2 SUBB 5000 7FE0 ;I2 (RET)
:PA7 SUBD 20100 2FFFF ;SC=30000:30060 (RET)
:PA ;I (RET)
:
```

2. To display addresses of the set subroutines:

```
:PA ;A (RET)
 NO NAME     MODE ADDRESS
  1 SUBA      I1  00000100 00001FF0          COUNT=D'00000
  2 SUBB      I2  00005000 00007FF0
  3 SUBC      I3  00010000:0001008F
                  00020000:00020098
  4
  5 SUBE      AC  00002030 0000207F
    <ACCESS>      FFFFFF00:FFFFFF7F;DAT
  7 SUBD      SC  00020100 0002FFFF
    <CALL-SUB>    00030000:00030060
 -------------------------------------------------------------
 TOTAL RUN-TIME = D'0001H:00M:40S:022917US:000NS
```

3. To display execution time ratio in graph form:

```
:PA (RET)
 NO NAME     MODE RATE   0---10---20---30---40---50---60---70---80---90--100
  1 SUBA      I1  D'10.0% *****
  2 SUBB      I2  D'20.0% **********
  3 SUBC      I3  D'20.0% **********
  4
  5 SUBD      AC  D'15.0% ********
    <ACCESS>      D' 5.0% ***
  7 SUBE      SC  D'20.0% **********
    <CALL-SUB>    D' 5.0% ***
 ---------------------------------------------------------------------------
 TOTAL RUN-TIME = D'0001H:00M:40S:022917US:000NS
```

4. To display execution time and count in numerical form:

```
:PA ;V (RET)
 NO NAME     MODE RATE     RUN-TIME                        E-COUNT
  1 SUBA      I1  D'10.0%  D'0000H:00M:05S:001000US:250NS  D'00005
    AVE D'0000H:00M:05S:001000US:250NS
  2 SUBB      I2  D'20.0%  D'0000H:00M:10S:010305US:500NS  D'00010
    MAX D'0000H:00M:10S:010305US:250NS MIN D'0000H:00M:10S:010305US:250NS
    AVE D'0000H:00M:10S:010305US:250NS
  3 SUBC      I3  D'20.0%  D'0000H:00M:10S:010305US:500NS  D'00010
    AVE D'0000H:00M:10S:010305US:250NS
  4
  5 SUBD      AC  D'10.0%  D'0000H:00M:05S:001000US:250NS  D'00005
  7 SUBE      SC  D'20.0%  D'0000H:00M:10S:010305US:500NS  D'00010
 -----------------------------------------------------------------
 TOTAL RUN-TIME = D'0001H:00M:40S:022917US:000NS
```

5. To cancel all registered subroutines:

```
:PA - (RET)
:
```

7.2.31 QUIT [Q] Terminates E8000 system program

Command Format

- Termination QUIT (RET)

Description

- Termination

  — Terminates the E8000 system program and puts the emulator monitor in command input wait state:

```
: QUIT  (RET)
START  E8000
  S:START  E8000
  F:FLASH  MEMORY  TOOL
  L:SET  LAN  PARAMETER
  T:START  DIAGNOSTIC  TEST
       (S/F/L/T)  ?  _
```

Example

To terminate the E8000 system program:

```
:Q (RET)
START E8000
 S:START E8000
 F:FLASH MEMORY TOOL
 L:SET LAN PARAMETER
 T:START DIAGNOSTIC TEST
    (S/F/L/T) ? _
```

7.2.32 RADIX [RX] Specifies and displays radix for numeric input

Command Format

- Specification RADIXΔ<radix> (RET)
- Display RADIX (RET)

<radix>: Radix to be used for input of numeric values

H: Hexadecimal (default at system program initiation)
D: Decimal
Q: Octal
B: Binary
X: Fixed-point

Description

- Specification

  Specifies the radix used by the emulator to interpret numbers entered on the command line.

  The RADIX command sets the radix to be used for numbers entered simply as numbers. Hexadecimal is used at emulator initiation. Numbers may be entered in any radix at any time, provided that each value is prefixed with the appropriate character.

Table 7.22 Radix and Input Examples

Radix	Input Example
Binary	B'1010
Octal	Q'2370
Decimal	D'6904
Hexadecimal	H'AF10
Fixed-point	X'0.6634049566

- Display

  Displays the currently set radix as follows:

  RADIX = Radix character

  Radix character, displayed as one of the following:

  B:BINARY
  Q:OCTAL
  D:DECIMAL
  H:HEXADECIMAL
  X:FIXED POINT

Examples

1. To set the radix to decimal:

```
:RX D  (RET)
:B 10  (RET)                (10 is input in decimal)
:
```

2. To display the current radix:

```
:RX  (RET)
 RADIX=D:DECIMAL
:
```

7.2.33 REGISTER [R] Displays register contents

Command Format

- Display REGISTER (RET)

Description

- Display
  - — Displays all register contents.
  - — The DSR register setting bits (bits 3 to 1) are displayed, as shown in table 7.23.

Table 7.23 DSR Register Setting Bits

	DSR Register Setting Bits			
Display	**Bit 3**	**Bit 2**	**Bit 1**	**Mode**
COB	0	0	0	Carry or borrow
NEG	0	0	1	Negative
ZER	0	1	0	Zero
OVF	0	1	1	Overflow
SGT	1	0	0	Signed greater than
SGE	1	0	1	Signed greater than or equal

Example

To display all register contents:

```
:R  (RET)
 PC=00005C60 SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
:
```

7.2.34 RESET [RS] Resets SH7612

Command Format

- Reset RESET (RET)

Description

- Reset

  Resets the SH7612. The SH7612 system register, control register, general register, and DSP register contents will be reset to the following values:

  R0 to R14 : The value before reset
  R15 (SP) : Power-on reset vector value
  MACH : The value before reset
  PC : Power-on reset vector value
  PR : The value before reset
  MOD : The value before reset
  A0G, A1G : The value before reset
  VBR : H'00000000
  GBR : The value before reset
  MACL : The value before reset
  SR : H'000000F0
  RS, RE : The value before reset
  DSR : H'00000000
  A0, A1, M0, M1, X0, X1, Y0, Y1 : The value before reset

  The internal I/O register contents will also be reset.

Note

In the SH7612, the initial value of the registers must be set in the program because the register contents are not stable after the SH7612 is reset.

Example

To reset the SH7612:

```
:RS  (RET)
 ** RESET BY E8000 !
:
```

7.2.35 RESULT [RT] Displays execution results

Command Format

- Display RESULT (RET)

Description

- Display

  Displays current register contents, execution time, and the GO, STEP, or STEP_OVER command termination cause. The display format is as follows:

```
:RESULT (RET)
-PC=00005C60  SR=000000F0:****000000000000****----IIII00--
-GBR=00000000  VBR=00000000  MACH=00000000  MACL=00000000  PR=00000000          (a)
-RS=00000000  RE=00000000  MOD=00000000
-R0–7   00000000  000000FF  00000011  00000000  00000000  00000000  00000000  00000000
-R8–15  00000000  00000000  00000000  00000000  00000000  00000000  00000000  000FFE00
-DSR=00000000:************************----COB-
-A0G=00  A0=00000000  M0=00000000  X0=00000000  Y0=00000000
-A1G=00  A1=00000000  M1=00000000  X1=00000000  Y1=00000000
 I-TIME=D'0000H:00M:00S:000000US:000NS (00.0%)         E-COUNT=D'00000          (b)
   MAX=D'0000H:00M:00S:000000US:000NS    MIN=D'0000H:00M:00S:000000US:000NS    (c) and (d)
   AVE=D'0000H:00M:00S:000000US:000NS                                           (e)
 RUN-TIME=D'0000H:00M:00S:000018US:000NS                                        (f)
 +++: <cause of termination>                                                    (g)
```

(a) The register contents at emulation termination.

(b) In time interval measurement modes 1 and 2, execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is displayed. In only time interval measurement mode 2, the execution count during this period is also displayed.

(c) In time interval measurement modes 1 and 2, the maximum execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is displayed.

(d) In time interval measurement modes 1 and 2, the minimum execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_CONDITION_UBC1 condition is satisfied is displayed.

(e) In time interval measurement modes 1 and 2, the average execution time from the point when the BREAK_CONDITION_UBC2 condition is satisfied until the BREAK_ CONDITION_UBC1 condition is satisfied is displayed.

(f) User program execution time in decimal. According to the TIME option of the EXECUTION_MODE command, the maximum measurable time is 488, 124, or 6 hours, where the minimum measurement time is 1.6 µs, 406 ns, or 20 ns, respectively. If the period exceeds the maximum measurable time, it is displayed as *.

(g) Cause of termination.

Note

Displayed register contents show values at program termination, not the current values.

Example

To display execution results:

```
:RT  (RET)
-PC=00005C60 SR=000000F0:****000000000000****----IIII00--
-GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
-RS=00000000 RE=00000000 MOD=00000000
-R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
-R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
-DSR=00000000:************************----COB-
-A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
-A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 RUN-TIME=D'0000H:00M:00S:002241US:000NS
 +++:BREAKPOINT
:
```

7.2.36 STATUS [ST] Displays emulator execution status

Command Format

- Display STATUS (RET)

Description

- Display

  Displays emulator execution status in the following format:

```
MODE=(a)   RADIX=(b)   BREAK=(c)
HOST=(d)   STEP_INFO=REG:(e) /A:(f)   /SP:(g)
CLOCK=(h)   EML_MEM=S:(i)
```

(a) MODE=xx: SH7612 operating mode specified with the MODE command

(b) RADIX=xxx: Default input number type

BIN: Binary
OCT: Octal
DEC: Decimal
HEX: Hexadecimal
FIX: Fixed-point

(c) BREAK=D'xxx: Number of breakpoints (decimal)

(d) HOST=x1x2x3x4x5: Interface conditions with serial port

x1: Baud rate (BPS: Bits per second)

1: 2400 BPS 2: 4800 BPS 3: 9600 BPS 4: 19200 BPS 5: 38400 BPS

x2: Data length for one character

8: 8 bits 7: 7 bits

x3: Parity

N: None E: Even O: Odd

x4: Number of stop bits

1: 1 stop bit 2: 2 stop bits

x5: Busy control method

X: X-ON/X-OFF control R: RTS/CTS control

(e) STEP_INFO=REG:x1 x2 x3: Register information displayed with the STEP command

x1 1: Control register (PC, SR, PR, GBR, VBR, MACH, MACL, RS, RE, and MOD) information is displayed.

Space: No control register (PC, SR, PR, GBR, VBR, MACH, MACL, RS, RE, and MOD) information is displayed.

x2 2: General register (R0 to R15) information is displayed.

Space: No general register (R0 to R15) information is displayed.

x3 3: DSP register (DSR, A0, A0G, A1, A1G, M0, M1, X0, X1, Y0, and Y1) information is displayed.

Space: No DSP register (DSR, A0, A0G, A1, A1G, M0, M1, X0, X1, Y0, and Y1) information is displayed.

(f) /A:xxxxxxxx-xxxxxxxx: Memory address range displayed with the STEP command

(g) /SP:xxxxxxxx: Display size of stack contents

(h) CLOCK=xxxx: Clock signal type

EML: Emulator internal clock

USER: User system clock

XTAL: Crystal oscillator clock

(i) EML_MEM=S:xMB: Remaining size of standard emulation memory

xMB: Remaining size of standard emulation memory

Example

To display the emulator status:

```
:ST (RET)
 MODE=2  RADIX=HEX  BREAK=D'001
 HOST=38N1X   STEP_INFO=REG:12/A:3         /SP:
 CLOCK=EML   EML_MEM=S:4MB
```

7.2.37 STEP [S] Performs single-step execution

Command Format

- Single step STEP [Δ<number of execution steps>[Δ<start address>]]
  [;[<stop PC>][Δ<display option>][ΔI]] (RET)

<number of execution steps>:	Number of steps to be executed (H'1 to H'FFFFFFFF). Default: If <stop PC> and <display option> are specified, H'FFFFFFFF is assumed. If not, H'1 is assumed.
<start address>:	Start address of single-step execution. Default is the current PC address.
<stop PC>:	PC address when single-step execution is terminated. Default is <number of execution steps>.
<display option>:	Specification of instructions to be displayed J: Displays instructions and register contents only when branch instructions are executed R: Displays instructions and register contents only within the opening routine Default: Displays instructions and register contents for all executed instructions
I:	Interrupt permission during STEP command execution

Description

- Single step

  — Performs single-step execution from <start address> to <stop PC> or from <start address> for <number of execution steps>. The type of emulation performed (described below) depends on the specified parameters and option.

  In addition, register and memory contents, address, instruction mnemonic, and termination cause are displayed in the following format:

```
(a)  PC=00001000  SR=000000F0:****000000000000****----IIII00--
     GBR=00000000  VBR=00000000  MACH=00000000  MACL=00000000  PR=00000000
     RS=00000000  RE=00000000  MOD=00000000
     R0-7   00000000  000000FF  00000011  00000000  00000000  00000000  00000000  00000000
     R8-15 00000000  00000000  00000000   00000000  00000000  00000000  00000000  000FFE00
     DSR=00000000:************************----COB-
     A0G=00  A0=00000000  M0=00000000  X0=00000000  Y0=00000000
     A1G=00  A1=00000000  M1=00000000  X1=00000000  Y1=00000000
(b)  <address>:<instruction mnemonic>
(c)  MEMORY
       <memory contents>
(d)  +++: <cause of termination>
```

  (a) Register information
  (b) Address and mnemonic of the executed instruction
  (c) Memory contents display
  (d) Cause of termination (refer to table 7.24)

  Information (a) and (c) is displayed according to specifications made with the STEP_INFORMATION command. The termination cause, (d), is displayed only when the STEP command is completed.

Table 7.24 Causes of STEP Command Termination

Message	Termination Cause
BREAK CONDITION UBC1	A break condition specified with the BREAK_CONDITION_UBC1 command was satisfied.
BREAK CONDITION An	A break condition specified with the BREAK_CONDITION_An command was satisfied (n = 1 to 8).
BREAK CONDITION Bn	A break condition specified with the BREAK_CONDITION_Bn command was satisfied (n = 1 to 8).
BREAK CONDITION Cn	A break condition specified with the BREAK_CONDITION_Cn command was satisfied (n = 1 to 8).
BREAK CONDITION A1, ... ,8	Multiple break conditions specified with the BREAK_CONDITION_A (A1 to A8) commands were satisfied.
BREAK CONDITION B1, ... ,8	Multiple break conditions specified with the BREAK_CONDITION_B (B1 to B8) commands were satisfied.
BREAK CONDITION C1, ... ,8	Multiple break conditions specified with the BREAK_CONDITION_C (C1 to C8) commands were satisfied.
BREAK KEY	The BREAK key or (CTRL) + C keys were pressed for forcible termination.
ILLEGAL INSTRUCTION	A break instruction (H'0000) was executed.
RESET BY E8000	The emulator forcibly terminates program execution with the RESET signal because an error has occurred in the user system.
STEP NORMAL END	The specified number of steps were executed.
STOP ADDRESS	The instruction at <stop PC> was executed.
MULTI BREAK	Emulation stopped by the multi break.

— If <stop PC> and <display option> are omitted, instruction mnemonics and register information are displayed for each step executed.

: ***STEP <number of execution steps> [<start address>] (RET)***

— Instruction mnemonics and register information are also displayed for each step when <stop PC> is specified, and single-step emulation is executed until the instruction at <stop PC> is executed.

: ***STEP [<number of execution steps> [<start address>]]; <stop PC> (RET)***

— If the J option is specified, instruction mnemonics and register information are displayed only for branch instructions, and single-step emulation is executed until the instruction at <stop PC> is executed. If <stop PC> is set at the start address of an interrupt, STEP execution may not terminate.

: ***STEP [<number of execution steps> [<start address>]];[<stop PC>] J (RET)***

The following instructions are valid when the J option is specified:

BT, BF, BRA, JMP, BSR, JSR, BTS, BFS, BRAF, BSRF, TRAPA

— If the R option is specified, instruction mnemonics and register information are displayed only during execution within the opening routine. At that time, single-step execution continues until the instruction at <stop PC> is executed. The jump addresses of branch instructions, such as JSR or BSR, are not displayed. Although this function is similar to the STEP_OVER command function, the latter is recommended because of its faster execution time.

: ***STEP [<number of execution steps> [<start address>]];[<stop PC>] R (RET)***

If a break occurs while executing a subroutine with R option specification, the subroutine start address and its instruction mnemonic are displayed.

— No interrupts are accepted during STEP command execution, unless the I option has been specified.

— After the STEP command has been executed (so long as it was not forcibly terminated), and if no other command has been entered, single-step execution can be continued by simply pressing the (RET) key.

Notes

1. Single-step execution is achieved by using the hardware break function (BREAK_CONDITION_UBC2 command). Accordingly, conditions specified with the BREAK_CONDITION_UBC2 command are invalid when using the STEP command.
2. Software breakpoints specified with the BREAK or BREAK_SEQUENCE command are ignored during single-step execution.

3. If a delayed branch instruction is executed during single-step emulation, single-step execution stops after the instruction immediately following the delayed branch instruction is executed. Therefore, two instruction mnemonics are displayed.
4. If break conditions specified with the BREAK_CONDITION_A,B,C or BREAK_CONDITION_UBC command are satisfied, STEP execution may terminate without executing a single instruction.
5. If the condition that the UBC use is enabled is specified with the UBC option of the EXECUTION_MODE command, the STEP command cannot be used. If this is attempted, the following error message is displayed and STEP command execution is terminated.

*** 8: UBC IS USED BY USER SYSTEM

Examples

1. To execute a program one step at a time, starting from the address given by the current PC:

```
:S (RET)
 PC=00001002 SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 00001000                  MOV      R0,R1
 +++:STEP NORMAL END
:
```

2. To perform single-step execution from addresses H'1060 to H'1070 with information displayed only for branch instructions:

```
:S  FFFF 1060 ;1070 J (RET)
 PC=0000106A SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
 DSR=000000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 00001064                  JMP       @R0
 00001066                  NOP
 PC=0000106E SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 0000106A                  BT        00001070
 PC=00001072 SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 00001070                  NOP
 +++:STOP ADDRESS
:
```

7.2.38 STEP_INFORMATION [SI] Specifies and displays information during single-step execution

Command Format

- Specification STEP_INFORMATION[Δ<register information>][ΔA=<start address>
  [(Δ<end address>/Δ@<number of bytes>)]]
  [ΔSP=<stack display byte count>] (RET)
- Display STEP_INFORMATION (RET)

<register information>:		Register to be displayed
	1:	Displays PC, SR, PR, GBR, VBR, MACH, MACL, RS, RE, and MOD
	2:	Displays R0 to R15
	3:	Displays DSR, A0, A0G, A1, A1G, M0, M1, X0, X1, Y0, and Y1
	ALL:	All register information is output (default at emulator initiation)
	–:	No information displayed
	Default:	ALL
<start address>:		Start address of memory dump
<end address>:		End address of memory dump. (Default is 16 bytes of memory beginning at <start address>.)
<number of bytes>:		Number of bytes of memory dump. (Default is 16 bytes.)
<stack display byte count>:		Number of bytes of stack contents.

Description

- Specification

  Displays register information, executed instruction information, memory contents, and cause of termination during STEP and STEP_OVER command execution. This command also selects the register information and memory contents which are to be displayed.

```
(a) PC=00001000  SR=000000F0:****000000000000****----IIII00--
    GBR=00000000  VBR=00000000  MACH=00000000  MACL=00000000  PR=00000000
    RS=00000000  RE=00000000  MOD=00000000
(b) R0-7   00000000  000000FF  00000011  00000000  00000000  00000000  00000000  00000000
    R8-15 00000000  00000000  00000000  00000000  00000000  00000000  00000000  000FFE00
(c) DSR=00000000:************************----COB-
    A0G=00  A0=00000000  M0=00000000  X0=00000000  Y0=00000000
    A1G=00  A1=00000000  M1=00000000  X1=00000000  Y1=00000000
(d) 00001002                    MOV          #00, R0
(e) MEMORY
    0000FF80  00  04  00  FF  F0  00  02  00    10  00  02  00  0F  00  00  00  "................"
(f) STACK
    000FFFE0  00  00  00  00  00  00  00  00    00  00  00  00  00  00  00  00  "................"
(g) +++:STEP NORMAL END
```

  (a) System and control register information (PC, SR, PR, GBR, VBR, MACH, MACL, RS, RE, and MOD)
  (b) General register information (R0 to R15)
  (c) DSP register information (DSR, A0G, A1G, A0, A1, M0, M1, X0, X1, Y0, and Y1)
  (d) Address and assembler instruction mnemonic of the executed instruction
  (e) Memory contents display
  (f) Stack contents display
  (g) Cause of termination

- Display

  Displays STEP information according to the specified contents. However, the address and assembler instruction mnemonic of each executed instruction are not displayed.

Examples

1. To display only the contents of system and control registers (PC, SR, PR, GBR, VBR, MACH, MACL, RS, RE, and MOD) during STEP or STEP_OVER command execution:

```
:SI 1 (RET)
:
```

2. To display no register information during STEP or STEP_OVER command execution:

```
:SI - (RET)
:
```

3. To display memory contents from addresses H'FB80 to H'FB87 during STEP or STEP_OVER command execution:

```
:SI A=FB80 FB87 (RET)
:
```

4. To display contents according to the specified display information:

```
:SI (RET)
 PC=00001004 SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 000000FF 00000011 00000000 00000000 00000000 00000000 00000000
 R8-15 00000000 00000000 00000000 00000000 00000000 00000000 00000000 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 00001002               MOV           #00,R0
 MEMORY
 0000FF80 00 04 00 FF F0 00 02 00  10 00 02 00 0F 00 00 00  "............."
 STACK
 000FFFE0 00 00 00 00 00 00 00 00  00 00 00 00 00 00 00 00  "............."
 +++:STEP NORMAL END
:
```

7.2.39 STEP_OVER [SO] Performs single-step execution except for subroutines

Command Format

- Execution STEP_OVER [<start address>][;I] (RET)

<start address>: Start address of single-step execution. Default is the current PC address.

I: Interrupt permission during single-step execution

Description

- Execution

— Beginning at <start address>, performs single-step execution of instructions, except for subroutines called by the BSR, JSR, BSRF, or TRAPA instruction. If a BSR, JSR, BSRF, or TRAPA instruction is executed, acts as if the subroutine called by the BSR, JSR, BSRF, or TRAPA instruction is a single instruction. If an instruction other than BSR, JSR, BSRF, or TRAPA is executed, register contents and the executed instruction are shown after each instruction is executed, like in the STEP command.

— If a BSR, JSR, or BSRF instruction is executed, sets a PC break before the instruction following the slot delayed branch instruction for the BSR, JSR, or BSRF instruction, and executes the user program. (The instruction following the slot delayed branch instruction is not executed.)

— During STEP_OVER command execution, register contents can be displayed in the following format. The register information and memory contents are displayed according to the STEP_INFORMATION command specifications.

```
(a)  PC=00001004  SR=000000F0:****000000000000****----IIII00--
     GBR=00000000  VBR=00000000  MACH=00000000  MACL=00000000  PR=00000000
     RS=00000000  RE=00000000  MOD=00000000
     R0-7   00000000  000000FF  00000011  00000000  00000000  00000000  00000000  00000000
     R8-15 00000000  00000000  00000000   00000000  00000000  00000000  00000000  000FFE00
     DSR=00000000:************************----COB-
     A0G=00  A0=00000000  M0=00000000  X0=00000000  Y0=00000000
     A1G=00  A1=00000000  M1=00000000  X1=00000000  Y1=00000000
(b)  <address>:<instruction mnemonic>
(c)  MEMORY
       <memory contents>
(d)  STACK
       <stack contents>
(e)  +++: <cause of termination>
```

(a) Register information
(b) Address and mnemonics of the executed instruction
(c) Memory contents display
(d) Stack contents display
(e) Cause of termination (refer to table 7.25)

— After the STEP_OVER command has been executed (so long as it was not forcibly terminated), and if no other command has been entered, single-step execution can be continued by simply pressing the (RET) key.

— Software breakpoints (specified with the BREAK or BREAK_SEQUENCE command) and hardware break conditions (specified with the BREAK_CONDITION_A,B,C or BREAK_CONDITION_UBC1,2 command) are invalid during STEP_OVER command execution.

— Interrupts are not accepted during STEP_OVER command execution, unless the I option is specified.

— If a break occurs during subroutine execution, the address and instruction mnemonics of the instruction calling the subroutine are displayed.

Table 7.25 Causes of STEP_OVER Command Termination

Message	Termination Cause
BREAK KEY	The (CTRL) + C keys were pressed for forcible termination.
ILLEGAL INSTRUCTION	A break instruction (H'0000) was executed.
ONE STEP END	Single-step execution was completed.
RESET BY E8000	The emulator forcibly terminates program execution with the RESET signal because an error occurs in the user system.
SUBROUTINE END	The called subroutine has finished execution.

Notes

1. When a delayed branch instruction is executed with the STEP_OVER command, execution stops at the instruction immediately following a delayed branch instruction. Therefore, two instruction mnemonics are displayed.
2. Do not use this command when program execution may not return from a subroutine called by a BSR, JSR, BSRF, or TRAPA instruction.
3. If the condition that UBC use is enabled is specified with the UBC option of the EXECUTION_MODE command, the STEP_OVER command cannot be used. If this is attempted, the following error message is displayed and STEP_OVER command execution is terminated.

   *** 8: UBC IS USED BY USER SYSTEM

Example

To execute the program one step at a time, starting from the address given by the current PC, and without displaying instructions within the called subroutine:

```
:SO (RET)
 PC=00001002 SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000001 00000001 00000002 00000003 00000004 00000005 00000006 00000007
 R8-15 00000008 00000009 0000000A 0000000B 00000000 0000000C 0000000D 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 00001000                MOV       R0,R1
 +++:ONE STEP END
:(RET)
```

```
 PC=00001004 SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 00000001 00000002 00000003 00000004 00000005 00000006 00000007
 R8-15 00000008 00000009 0000000A 0000000B 00000000 0000000C 0000000D 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 00001002                MOV       #00,R0
 +++:ONE STEP END
:(RET)
 PC=00001008 SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 00000001 00000002 00000003 00000004 00000005 00000006 00000007
 R8-15 00000008 00000009 0000000A 0000000B 00000000 0000000C 0000000D 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 00001004                BSR       00002020         (Subroutine is not displayed.)
 00001006                NOP
 +++:SUBROUTINE END
:(RET)
 PC=0000100A SR=000000F0:****000000000000****----IIII00--
 GBR=00000000 VBR=00000000 MACH=00000000 MACL=00000000 PR=00000000
 RS=00000000 RE=00000000 MOD=00000000
 R0-7  00000000 00000001 00000002 00000003 00000004 00000005 00000006 00000007
 R8-15 00000008 00000009 0000000A 0000000B 00000000 0000000C 0000000D 000FFE00
 DSR=00000000:************************----COB-
 A0G=00 A0=00000000 M0=00000000 X0=00000000 Y0=00000000
 A1G=00 A1=00000000 M1=00000000 X1=00000000 Y1=00000000
 00001008                NOP
 +++:ONE STEP END
:
```

7.2.40 TRACE [T] Displays trace information

Command Format

- Display TRACE[Δ[–]<start pointer>[:[–]<end pointer>]][;[BP]
  [<display information>]] (RET)

<start pointer>:	Start pointer of trace display. (Default is the PTR option of the TRACE_DISPLAY_MODE command.)
<end pointer>:	End pointer of trace display. (Default is the PTR option of the TRACE_DISPLAY_MODE command.)
–:	Trace up until the break condition is satisfied is displayed. (This option is usually necessary, except for displaying trace information during delays when a delay count condition is specified by the BREAK_CONDITION_B or TRACE_CONDITION_B command.)
BP:	Bus-cycle pointers specified as pointer values. Default is the instruction pointer.
<display information>:	Information to be displayed

B:	Displays bus-cycle information and instruction mnemonic information
N:	Displays bus-cycle information
Default:	Displays instruction mnemonic information

Description

- Display

— Displays trace information acquired during user program execution. Trace information is displayed in instruction mnemonics or in bus-cycle units, according to the specified option.

a. If option specification is omitted, displays instruction mnemonic information in instruction units.

: ***TRACE (RET)***

b. If the B option is specified, displays bus-cycle information and instruction mnemonic information in bus-cycle units.

: ***TRACE ;B (RET)***

c. If the N option is specified, displays bus-cycle information in bus-cycle units.

: ***TRACE ;N (RET)***

— The display range can be specified with pointers in bus-cycle units (bus-cycle pointer) or instruction units (instruction pointer). The pointer value is specified as a relative value from the point where a delay start condition is satisfied (see the following note). Trace information acquired before the delay start condition is satisfied is displayed with a minus (–). To specify a bus-cycle pointer, the BP option must be selected. The default is the instruction pointer.

Note: When a delay count condition is specified with the BREAK_CONDITION_B or TRACE_CONDITION_B command, the combination of conditions also specified is handled as a delay start condition. Delay starts to be counted when the delay start condition is satisfied. When no delay start condition has been specified or termination has been caused by another reason, the pointer value will be relative to the latest trace information.

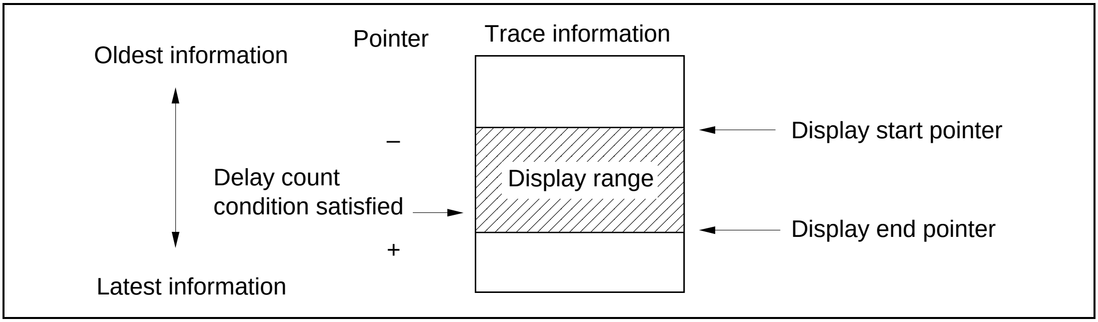


Figure 7.2 Display Range Specified by Pointers

Pointer default is as follows:

a. If <start pointer> is omitted, the start pointer specified by the PTR option of the TRACE_DISPLAY_MODE command is used.

b. If <end pointer> is omitted, the end pointer specified by the PTR option of the TRACE_DISPLAY_MODE command is used.

— To display only instruction mnemonics of the executed instructions, uses the following format:

IP	ADDR	MNEMONIC	OPERAND
* [–]D'xxxxxx	xxxxxxxx	xx – xx	xx – xx
(a)	(b)	(c)	(d)

(a) Instruction pointer

Relative instruction location based on the instruction where a delay count condition is satisfied. An instruction pointer begins with an asterisk (*) to differentiate it from a bus-cycle pointer. Although the pointer usually has a negative value (–D'xxxxxx), if a delay count condition is specified as a break or trace condition, the delay will be indicated as a positive value (D'xxxxxx).

(b) Instruction address

(c) Instruction mnemonic

(d) Instruction operand

— To display trace information in bus-cycle units, uses the following format:

Time Stamp Display:

BP	AB	DB	MA	RW	STS	IRL	NMI	RES	BRQ	VCC	PRB	TIME_STAMP
[-]D'xxxxxx	xxxxxxxx	xxxxxxxx	xxx	x	xxx	xxxx	x	x	x	x	xxxx	x xxxHxxMxxSxxxxxxUxxxN
(a)	(b)	(c)	(d)	(e)	(f)	(g)	(h)	(i)	(j)	(k)	(l)	(m)

Clock Cycle Display:

BP	AB	DB	MA	RW	STS	IRL	NMI	RES	BRQ	VCC	PRB	CLK
[-]D'xxxxxx	xxxxxxxx	xxxxxxxx	xxx	x	xxx	xxxx	x	x	x	x	xxxx	xx
												(n)

(a) Bus-cycle pointer

Number of bus cycles from an instruction where a delay count condition is satisfied. In bus cycles which prefetch instructions, the instruction mnemonics and instruction addresses are displayed as described above. When two instructions are executed in one bus cycle, both mnemonics are displayed along with the address of the first instruction. Although the pointer usually has a negative value (-D'xxxxxx), when a delay count condition is specified as a break or trace condition, the delay will be indicated as a positive value (D'xxxxxx).

(b) Address bus value

(c) Data bus value

According to the SH7612 access size, longword, word, and byte values are displayed at the digits corresponding to the bus lines through which the data is accessed. For bus lines through which no data is accessed, asterisks (**) are displayed.

(d) Memory area type

Table 7.26 MA Display

Display	Description
IO	Internal I/O area access
INT	Internal area access
EXT	CS0 to CS3 area access (including reserved area access)

(e) Read/write type

Table 7.27 R/W Display

Display	Description
R	Data read
W	Data write

(f) MCU status

Table 7.28 STS Display

Display	Description
PRG	Instruction fetch cycle (including PC relative data access cycle)
DAT	Data access cycle (except for PC relative data access cycle)
DMA	Internal DMAC execution cycle
VCF	Vector fetch cycle
REF	Refresh cycle

(g) IRL0 to IRL3 signal level

IRL
x3 x2 x1 x0
x3: IRL3 signal status xn 0: Low level
x2: IRL2 signal status 1: High level
x1: IRL1 signal status
x0: IRL0 signal status

(h) NMI signal level (0 = low level, 1 = high level)

(i) RESET signal level (0 = low level, 1 = high level)

(j) BREQ signal level (0 = low level, 1 = high level)

(k) Vcc voltage

Table 7.29 Vcc Voltage Display

Display	Description
0	Vcc voltage is 2.65 V or less; the MCU is not operating correctly
1	Vcc voltage is more than 2.65 V

(l) External probe signal level (0 = low level, 1 = high level)

(m) Time stamp display

Displayed only when time stamp display is enabled with the TIME option (TIME = E) specification of the TRACE_DISPLAY_MODE command. Time stamp display is disabled in the default setting.

(n) The number of clock cycles required from the end of the previous bus cycle to the end of this bus cycle. Up to 255 (H’FF) clocks are counted. If the number exceeds 255, it is displayed as **. The clock cycle cannot be displayed together with the time stamp display (m).

Note

When the display is in bus-cycle units, the following message is displayed as the emulator cycle following the last bus cycle of user program execution. Note that this emulator cycle does not affect user program execution cycles.

*** E8000 ***

Examples

1. To display all trace information with only instruction mnemonics:

```
:T (RET)
   IP        ADDR      MNEMONIC      OPERAND
*-D'000004  00002010  JSR           @R0
*-D'000003  00002012  NOP
*-D'000002  00002020  MOV.L         R0,@R1
*-D'000001  00002022  NOP
*-D'000000  00002024  MOV.L         R0,R4
:
```

2. To display bus-cycle information and instruction mnemonic information in bus-cycle units, from five instructions before the point where a delay count condition was satisfied:

```
:T -5;B (RET)
    BP        AB        DB      MA  RW STS IRL  NMI RES BRQ VCC PRB
*         00002010           JSR      @R0
*         00002012           NOP
 -D'000005 00002010 400B0009 EXT R  PRG 1111  1   1   1   1  1111
*         00002020           MOV.L    R0,@R1
*         00002022           NOP
 -D'000004 00002020 21020009 EXT R  PRG 1111  1   1   1   1  1111
*         00002024           MOV      R0,R4
 -D'000003 00002024 6403000B EXT R  PRG 1111  1   1   1   1  1111
 -D'000002 0F000000 00002020 EXT W  DAT 1111  1   1   1   1  1111
 -D'000001 00002028 00090009 EXT R  PRG 1111  1   1   1   1  1111
  D'000000 *** E8000 ***
:
```

3. To specify a display range by bus-cycle pointers, and display bus-cycle information and instruction mnemonic information in bus-cycle units:

```
:T -D'20:-D'16;BP B (RET)
     BP        AB        DB     MA  RW STS IRL  NMI RES BRQ VCC PRB
 -D'000020 00002014 AFF40009 EXT R  PRG 1111  1   1   1   1  1111
*          00002014           BRA      00002000
*          00002016           NOP
 -D'000019 00002000 A0060009 EXT R  PRG 1111  1   1   1   1  1111
*          00002000           BRA      00002010
*          00002022           NOP
 -D'000018 00002010 400B0009 EXT R  PRG 1111  1   1   1   1  1111
*          00002010           JSR      @R0
*          00002012           NOP
 -D'000017 00002020 21020009 EXT R  PRG 1111  1   1   1   1  1111
*          00002020           MOV.L    R0,@R1
*          00002022           NOP
 -D'000016 00002024 6403000B EXT R  PRG 1111  1   1   1   1  1111
*          00002024           MOV      R0,R4
*          00002026           RTS
:
```

4. To specify a display range by bus-cycle pointers, and display bus-cycle information in bus-cycle units:

```
:T -D'20:-D'16;BP N (RET)
     BP        AB        DB     MA  RW STS IRL  NMI RES BRQ VCC PRB
 -D'000020 00002014 AFF40009 EXT R  PRG 1111  1   1   1   1  1111
 -D'000019 00002000 A0060009 EXT R  PRG 1111  1   1   1   1  1111
 -D'000018 00002010 400B0009 EXT R  PRG 1111  1   1   1   1  1111
 -D'000017 00002020 21020009 EXT R  PRG 1111  1   1   1   1  1111
 -D'000016 00002024 6403000B EXT R  PRG 1111  1   1   1   1  1111
:
```

7.2.41 TRACE_CONDITION_A,B,C [TCA,TCB,TCC] Specifies, displays, and cancels a trace condition

Command Format

- Setting TRACE_CONDITION_(A/B/C)(1/2/3/4/5/6/7/8)ΔS=<start address>:
  <end address>; ST (RET)
  (Subroutine trace)
  TRACE_CONDITION_(A/B/C)(1/2/3/4/5/6/7/8)Δ<condition>
  [[Δ<condition>][Δ<condition>]...];R (RET)
  (Range trace)
  TRACE_CONDITION_(A/B/C)(1/2/3/4/5/6/7/8)ΔS=<start address>:
  <end address> Δ<condition>[[Δ<condition>]
  [Δ<condition>]...];SR (RET)
  (Subroutine range trace)
  TRACE_CONDITION_(A/B/C)(1/2/3/4/5/6/7/8)Δ<condition>
  [[Δ<condition>][Δ<condition>]...];S (RET)
  (Trace stop)
- Display TRACE_CONDITION_(A/B/C)[(1/2/3/4/5/6/7/8)] (RET)
  TRACE_CONDITION_(A/B/C) (RET)
- Cancellation TRACE_CONDITION_(A/B/C)[(1/2/3/4/5/6/7/8)] – (RET)
  TRACE_CONDITION_(A/B/C) – (RET)

(A/B/C):	Trace condition type
(1/2/3/4/5/6/7/8):	Trace condition number When omitted, all conditions will be displayed or canceled.
<start address>:	Start address of subroutine
<end address>:	End address of subroutine
<condition>:	Trace conditions to be specified
ST:	Subroutine trace mode specification
R:	Range trace mode specification
SR:	Subroutine range trace mode specification
S:	Trace stop specification

Description

- Setting

    — Specifies a trace acquisition condition (trace mode) for user program emulation (GO command execution). Trace condition numbers are automatically set to trace conditions in their specified order. The specified trace acquisition condition (trace mode) will apply for trace acquisition following this command execution.

    Free Trace: Acquires trace information during all bus cycles if no conditions have been set with this command.

    Subroutine Trace: Acquires trace information such as instructions and operands in the range (subroutine) specified by <start address> and <end address>. However, note that if the specified subroutine calls another subroutine, trace information on the called subroutine is not acquired.

    Range Trace: Acquires trace information during bus cycles in which the specified condition is satisfied.

    Subroutine Range Trace: Accesses instructions and operands in the subroutine specified by <start address> and <end address>, and acquires trace information during bus cycles in which the specified condition is satisfied.

    Trace Stop: Stops trace information acquisition when the specified condition is satisfied, and enters command input wait state in parallel mode. Though realtime emulation continues, trace information acquisition is not possible in parallel mode. If a trace stop condition is satisfied,

    ```
    ** TRACE STOP **
    ```

    is displayed.

Table 7.30 Specifiable Conditions in Each Trace Mode

Command No.	Subroutine Trace	Range Trace	Subroutine Range Trace	Trace Stop
TCA1	X	O	X	O
TCA2	X	O	X	O
TCA3	X	O	X	O
TCA4	X	O	X	O
TCA5	X	O	X	O
TCA6	X	O	X	O
TCA7	X	O	X	O
TCA8	X	O	X	O
TCB1	O	O	O	O
TCB2	O	O	X	O
TCB3	O	O	O	O
TCB4	O	O	X	O
TCB5	O	O	O	O
TCB6	O	O	X	O
TCB7	O	O	O	O
TCB8	O	O	X	O
TCC1	O	O	X	O
TCC2	O	O	X	O
TCC3	O	O	X	O
TCC4	O	O	X	O
TCC5	O	O	X	O
TCC6	O	O	X	O
TCC7	O	O	X	O
TCC8	O	O	X	O
All	16	24	4	24

Note: O: Condition can be specified.
X: Condition cannot be specified.

- When conditions for subroutine trace, range trace, or subroutine range trace are specified together, the trace acquisition conditions for each mode are ORed. If no conditions are specified for these modes, free trace is assumed.

- When the specified trace stop condition is satisfied, trace information acquisition stops and the emulator enters parallel mode and waits for command input. To resume trace information acquisition, exit parallel mode with the END command.

- In range trace or trace stop mode, the items shown in tables 7.31 to 7.33 can be specified as <condition> and they can be combined by ANDing them. Several conditions can be specified in any order.

Table 7.31 Specifiable Conditions (TRACE_CONDITION_A)

Item and Input Format	Description
Address condition A=<address 1>[:<address 2>]	When only <address 1> is specified, the condition is satisfied when the address bus value matches the specified value. When both <address 1> and <address 2> are specified, the condition is satisfied when the address bus value is in the range from <address 1> to <address 2>. This condition can be masked.
Data condition D=<1-byte value> WD=<2-byte value> LD=<4-byte value>	The condition is satisfied when the data bus value matches the specified value. When D, WD, or LD is specified, the condition is satisfied when the address is accessed in bytes, words, or longwords, respectively. In program fetch cycles, the data condition is not satisfied irrespective of the data bus value. This condition can be masked.
Read/Write condition R: Read W: Write	The condition is satisfied in a read cycle (R is specified) or a write cycle (W is specified).
Access type DAT: Execution cycle DMA: DMA cycle VCF: Vector fetch cycle Default: All bus cycles described above (including program fetch cycle)	The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.

Table 7.31 Specifiable Conditions (TRACE_CONDITION_A) (cont)

Item and Input Format	Description
External probe condition PRB=<value>	The condition is satisfied when all of the emulator's external probe signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to a probe number, as follows: 3 2 1 0 ← Bit x x x x ← Specified value | | | | 4 3 2 1 ← Probe number x: 0 = Low level 1 = High level This condition can be masked.
External interrupt condition 1 NMI [:L] or NMI: H	The condition is satisfied when the NMI signal matches the specified level. NMI or NMI: L: The condition is satisfied when NMI is low NMI: H: The condition is satisfied when NMI is high
External interrupt condition 2 IRL=<value>	The condition is satisfied when all of the IRL signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to an IRL number, as follows: 3 2 1 0 ← Bit x x x x ← Specified value | | | | 3 2 1 0 ← IRL number x: 0 = Low level 1 = High level The condition can be masked.

Table 7.32 Specifiable Conditions (TRACE_CONDITION_B)

Item and Input Format	Description
Address condition A=<address 1>[:<address 2>][;NOT]	When only <address 1> is specified, the condition is satisfied when the address bus value matches the specified value. When both <address 1> and <address 2> are specified, the condition is satisfied when the address bus value is in the range from <address 1> to <address 2>. If the NOT option is specified, the condition is satisfied when the address bus value does not match the specified value. This condition can be masked.
Data condition D=<1-byte value>[;NOT] WD=<2-byte value>[;NOT] LD=<4-byte value>[;NOT]	The condition is satisfied when the data bus value matches the specified value. When D, WD, or LD is specified, the break condition is satisfied when the address is accessed in bytes, words, or longwords, respectively. If the NOT option is specified, the condition is satisfied when the data bus value does not match the specified value. This condition can be masked.
Read/Write condition R: Read W: Write	The condition is satisfied in a read cycle (R is specified) or a write cycle (W is specified).
Access type DAT: Execution cycle DMA: DMA cycle VCF: Vector fetch cycle Default: All bus cycles described above (including program fetch cycle)	The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.
External probe condition PRB=<value>	The condition is satisfied when all of the emulator's external probe signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to a probe number, as follows: 3 2 1 0 ← Bit x x x x ← Specified value | | | | 4 3 2 1 ← Probe number x: 0 = Low level 1 = High level This condition can be masked.

Table 7.32 Specifiable Conditions (TRACE_CONDITION_B) (cont)

Item and Input Format	Description
External interrupt condition 1 NMI [:L] or NMI: H	The condition is satisfied when the NMI signal matches the specified level. NMI or NMI: L: The condition is satisfied when NMI is low NMI: H: The condition is satisfied when NMI is high
External interrupt condition 2 IRL=<value>	The condition is satisfied when all of the IRL signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to an IRL number, as follows: 3 2 1 0 ← Bit x x x x ← Specified value | | | | 3 2 1 0 ← IRL number x: 0 = Low level 1 = High level The condition can be masked.
Satisfaction count specification COUNT=<value> <value>: H'1 to H'FFFF	The condition can be specified in combination with any of the address, data, read/write, access type, external probe, and external interrupt conditions. The complete condition combination is satisfied when the other specified condition has been satisfied for the specified number of times. This condition can only be specified for trace stop.
Delay count specification DELAY=<value> <value>: H'1 to H'7FFF	This condition can be specified in combination with any of the address, data, read/write, access type, external probe, and external interrupt conditions. The complete condition combination is satisfied when the specified number of bus cycles has been executed after the other specified condition is satisfied. This condition can only be specified for trace stop. This condition can only be specified with the TRACE_CONDITION_B7 command.

Table 7.33 Specifiable Conditions (TRACE_CONDITION_C)

Item and Input Format	Description
Address condition A=<address 1>[:<address 2>]	When only <address 1> is specified, the condition is satisfied when the address bus value matches the specified value. When both <address 1> and <address 2> are specified, the condition is satisfied when the address bus value is in the range from <address 1> to <address 2>. This condition can be masked.
Access type DAT: Execution cycle DMA: DMA cycle VCF: Vector fetch cycle Default: All bus cycles described above (including program fetch cycle)	The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.

— Address and data conditions are satisfied when address bus values and data bus values match the specified values. Note the following when specifying trace conditions.

a. Access to a 32-bit bus area

- Longword access

  Longword data is accessed in one bus cycle. Only longword data (LD) and a multiple of four can be specified as the data and address conditions, respectively.

- Word access

  Word data is accessed in one bus cycle. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively. 32 bits must be specified as the data bus width. Note that the data condition must be specified in combination with a specific address condition. If no address condition is specified or if the address is masked, the data condition will be satisfied when the address is a multiple of four.

- Byte access

  Byte data is accessed in one bus cycle. Only byte data (D) can be specified as the data condition. Both even and odd address values can be specified as the address condition. 32 bits must be specified as the data bus width. Note that the data condition must be specified in combination with a specific address condition. If no address condition is specified or if the address is masked, the data condition will be satisfied when the address is a multiple of four.

b. Access to a 16-bit bus area

- Longword access

  Longword data is accessed in two word-access cycles. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively. 16 bits must be specified as the data bus width.

- Word access

  Word data is accessed in one bus cycle. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively. 16 bits must be specified as the data bus width.

- Byte access

  Byte data is accessed in one bus cycle. Only byte data (D) can be specified as the data condition. Both even and odd address values can be specified as the address condition. 16 bits must be specified as the data bus width. Note that the data condition must be specified in combination with a specific address condition. If no address condition is specified or if the address is masked, the data condition will be satisfied when the address is a multiple of two.

c. Access to an 8-bit bus area

All addresses can be accessed in byte units. Longword data and word data are accessed in four byte-access cycles and two byte-access cycles, respectively. Both even and odd addresses can be specified as the address condition. Note, however, that only byte data (D) is valid for the data condition. Eight bits must be specified as the data bus width.

— A bit mask in 1-bit or 4-bit units can be specified for the address condition of the TRACE_CONDITION_A,B,C command. When a bit is masked, the condition is satisfied irrespective of its bit value. To implement the mask, specify each digit to be masked at input as an asterisk (*). Table 7.34 shows address mask specification examples.

Example: The following condition is satisfied when the lower four bits of the address condition are not specified:

: ***TRACE_CONDITION_A1   A=H'400000* ;S (RET)***

Table 7.34 Address Mask Specifications (TRACE_CONDITION_A,B,C)

Radix	Mask Unit	Example	Mask Position
Binary	1 bit	B'01101***	Bits 2 to 0 are masked
Hexadecimal	4 bits	H'F50***	Bits 11 to 0 are masked

Note: When <address 2> is not specified for an address condition, <address 1> can be consecutively masked from the lowest bit. It is not possible to mask any desired bit position, as shown in the following examples.

Examples:

Allowed: TRACE_CONDITION_A1 A = H'10 ;R**

Not allowed: TRACE_CONDITION_A1 A = H'1*00 ;R

TRACE_CONDITION_A1 A = H'100*:10 ;R**

— A bit mask in 1-bit or 4-bit units can be specified for the data, IRL, or PRB condition of the TRACE_CONDITION_A,B,C command. When a bit is masked, the condition is satisfied irrespective of its bit value. To implement the mask, specify each digit to be masked at input as an asterisk (*). Table 7.35 shows these mask specification examples.

Example: The following condition is satisfied when address 4000000 is the address condition and bit 0 is zero in the byte data condition:

: ***TRACE_CONDITION_A1 A=H'4000000 D=B'*******0 ;S (RET)***

Table 7.35 Mask Specifications (TRACE_CONDITION_A,B,C)

Radix	Mask Unit	Example	Mask Position	Allowed Condition
Binary	1 bit	B'01*1010*	Bits 0 and 5 are masked	Data (D, WD, LD), IRL, or PRB
Hexadecimal	4 bits	H'F**50	Bits 15 to 8 are masked	Data (D, WD, LD), IRL, or PRB

— In parallel mode, this command is executed as follows:

Parallel mode is entered by the (RET) key, or the trace stop condition is satisfied:

- This command setting is invalid during parallel mode.
- No trace information is acquired.
- As soon as parallel mode is terminated, this command setting is validated, and trace information acquisition starts. In this case, conditions that have been satisfied are all cleared, and the conditions are rechecked from the beginning. Old trace information is also cleared. At this time,

  *** 81:TRACE CONDITION RESET

  is displayed.

Parallel mode is entered by the (SPACE) key:

- This command setting is valid.
- Trace information is acquired.
- During the following command execution, this command setting is invalid and no trace information is acquired:
  - (i) A condition is newly set with the TRACE_CONDITION_A,B,C command
  - (ii) TRACE command
  - (iii) TRACE_SEARCH command

  As soon as the above command is terminated, this command setting is validated, and trace information acquisition starts. In this case, conditions that have been satisfied are all cleared. Old trace information is also cleared. At this time,

  *** 81:TRACE CONDITION RESET

  is displayed.

- Display

  Displays specified conditions as follows. In addition to condition numbers, character strings that were input for specifying conditions will be displayed as they were input. If no trace condition is specified, a blank is displayed.

```
: TRACE_CONDITION_A (RET)
  TCA1  A=1000 : 2000 ;R
  TCA2  S=5000 : 53FF ;ST
  TCA3  A=3000 : 4000 ;R
  TCA4  A=6000 : 7000 ;R
  TCA5
  TCA6
  TCA7
  TCA8
```

- Cancellation

  Cancels conditions specified with the TRACE_CONDITION_A command.

```
: TRACE_CONDITION_A –  (RET)
```

Note

When conditions have already been set with the BREAK_CONDITION_A,B command, conditions cannot be set to the same channel number. For example, when conditions have already been set to BREAK_CONDITION_A1, no conditions can be set to TRACE_CONDITION_A1. To set new conditions, cancel previously set conditions.

When conditions have already been set with the BREAK_CONDITION_C or PERFORMANCE_ ANALYSIS command, conditions cannot be set to the same channel number. For example, when conditions have already been set to BREAK_CONDITION_C1 or PERFORMANCE_ ANALYSIS1, no conditions can be set to TRACE_CONDITION_C1. To set new conditions, cancel previously set conditions.

Examples

1. To specify a trace stop condition:

```
:TCA1  A=4320 ;S (RET)
:
```

2. To specify a range trace condition:

```
:TCA2  A=2000:27FF ;R (RET)
:
```

3. To specify a subroutine range trace condition:

```
:TCB1  S=1000:13FF A=2000:27FF ;SR (RET)
:
```

4. To display specified trace conditions:

```
:TCA (RET)
 TCA1 A=4320 ;S
 TCA2 A=2000:27FF ;R
 TCA3
 TCA4
 TCA5
 TCA6
 TCA7
 TCA8
:
```

5. To cancel the trace condition specified with the TRACE_CONDITION_A3 command:

```
:TCA3- (RET)
:
```

6. To cancel all trace conditions specified with the TRACE_CONDITION_A command:

```
:TCA- (RET)
:
```

7.2.42 TRACE_DISPLAY_MODE [TDM] Specifies and displays trace information display mode

Command Format

- Setting TRACE_DISPLAY_MODEΔPTR=[–]<start pointer>
  [:[–]<end pointer>]Δ<display item>=(D/E)
  [[Δ<display item>=(D/E)]...][;C] (RET)
- Display TRACE_DISPLAY_MODE (RET)

<start pointer>:	Default start pointer for trace information display and search (emulator shipment: –D'4095)
<end pointer>:	Default end pointer for trace information display and search (emulator shipment: D'4095)
<display item>:	Information to be displayed at trace information display A (address bus), D (data bus), MA (memory area type), RW (read/write), ST (status), IRL (IRL signals), NMI (NMI signal), RES (RESET signal), BREQ (BREQ signal), VCC (VCC voltage state), PRB (external probe), TIME (time stamp), and CLK (clock cycle)
C:	Stores the settings as configuration information in the emulator flash memory

Description

- Setting

— Specifies the default values of start and end pointers for trace information display and search which are used when the pointer values are not specified in the TRACE or TRACE_SEARCH command. Trace information in the emulator is available for approximately 128,000 bus cycles. Use this command to specify the range of the default values when all trace information is not required. The specified pointers will function as bus-cycle pointers in the TRACE_SEARCH command, and according to the option as instruction or bus-cycle pointers in the TRACE command. The pointer value ranges from –131070 to 131070. When exceeding this range, start and end pointers are automatically specified as –131070 and 131070, respectively.

: ***TRACE_DISPLAY_MODE PTR = –D'2048:D'2048 (RET)***

— Sets trace items to be displayed as bus-cycle information at trace information display with the TRACE or TRACE_SEARCH command.

: ***TRACE_DISPLAY_MODE∆zzzz = (E/D) (RET)***

zzzz: Information to be displayed at trace information display
A, D, MA, RW, ST, IRL, NMI, RES, BREQ, VCC,
PRB, TIME, and CLK
E: Display is enabled
D: Display is disabled

Note: TIME and CLK cannot be set as E (display enabled) at the same time.

Table 7.36 shows the default of each trace item display at emulator shipment.

Table 7.36 Shipment Defaults of TRACE_DISPLAY_MODE Command

Trace Items	Default at Shipment
A, D, MA, RW, ST, IRL, NMI, RES, BREQ, VCC, and PRB	E
TIME and CLK	D

— • When the C option is specified, the following message is displayed to confirm with the user whether to overwrite the existing configuration information in the emulator flash memory.

: ***TRACE_DISPLAY_MODE ;C (RET)***
: CONFIGURATION STORE OK (Y/N) ? ***(a) (RET)***

(a) Y: Stores the specifications as configuration information in the emulator flash memory. Hereafter, when the emulator is activated, the saved specifications go into effect.

N: Does not overwrite configuration information. The existing specifications are valid.

- Display

  Displays the specified trace mode as shown below.

```
: TRACE_DISPLAY_MODE (RET)
  PTR = –D'yyyyyy : D'yyyyyy
  DISPLAY ITEM = zzzz zzzz ...
```

yyyyyy: Default values of start and end bus-cycle pointers for trace information display and search

zzzz: Information to be displayed at trace information display

A, D, MA, RW, ST, IRL, NMI, RES, BREQ, VCC, PRB, TIME, and CLK

Examples

1. To set the default values of the pointers to addresses –D'10 and D'10 at trace information display:

```
:TDM PTR=-D'10:D'10 (RET)
:
```

2. To display the specified contents:

```
:TDM (RET)
 PTR=–D'000010:D'000010
 DISPLAY ITEM=A D MA RW ST IRL NMI RES BREQ VCC PRB
:
```

3. To specify not to display external probe information (PRB) as bus-cycle information at trace information display with the TRACE or TRACE_SEARCH command:

```
:TDM PRB=D (RET)
:
```

7.2.43 TRACE_MODE [TMO] — Specifies and displays trace information acquisition mode

Command Format

- Setting TRACE_MODE [ΔDMA=(D/E)][ΔREF=(D/E)][ΔOVFB=(D/E)]
  [ΔTIME=(0/1/2/3)][;C] (RET)
- Display TRACE_MODE (RET)

DMA: Specifies whether trace information acquisition for DMA cycles are enabled.
- D: Disables trace information acquisition for DMA cycles
- E: Enables trace information acquisition for DMA cycles (default at emulator shipment)

REF: Specifies whether trace information acquisition for refresh cycles are enabled.
- D: Disables trace information acquisition for refresh cycles
- E: Enables trace information acquisition for refresh cycles (default at emulator shipment)

OVFB: Specifies whether a break occurs when the trace buffer overflows.
- D: A break does not occur when the trace buffer overflows (default at emulator shipment)
- E: A break occurs when the trace buffer overflows

TIME: Specifies the minimum time stamp unit.
- 0: Acquires trace information on the number of clock cycles (CLK) instead of time stamp
- 1: 20 ns (default at emulator shipment)
- 2: 1.6 µs
- 3: 52 µs

C: Stores the settings as configuration information in the emulator flash memory.

Description

- Specification

— Enables or disables trace information acquisition for DMA cycles.

- To enable trace information acquisition during DMA cycles:
  : ***TRACE_MODE DMA=E (RET)***
- To disable trace information acquisition during DMA cycles:
  : ***TRACE_MODE DMA=D (RET)***

— Enables or disables trace information acquisition for refresh cycles.

- To enable trace information acquisition during refresh cycles:
  : ***TRACE_MODE REF=E (RET)***
- To disable trace information acquisition during refresh cycles:
  : ***TRACE_MODE REF=D (RET)***

— Specifies whether or not to generate a break when the trace buffer overflows.

- To generate a break when the trace buffer overflows:
  : ***TRACE_MODE OVFB=E (RET)***
- To not generate a break when the trace buffer overflows:
  : ***TRACE_MODE OVFB=D (RET)***

— Specifies minimum time stamp unit.

- To acquire trace information on the number of clock cycles. The time stamp is not acquired.
  : ***TRACE_MODE TIME=0 (RET)***
- To set the minimum time stamp unit to 20 ns:
  : ***TRACE_MODE TIME=1 (RET)***
- To set the minimum time stamp unit to 1.6 µs:
  : ***TRACE_MODE TIME=2 (RET)***
- To set the minimum time stamp unit to 52 µs:
  : ***TRACE_MODE TIME=3 (RET)***

— When the C option is specified, the following message is displayed to confirm with the user whether to overwrite the existing configuration information in the emulator flash memory.

CONFIGURATION STORE OK (Y/N) ? ***(a) (RET)***

(a) Y: Stores the specifications as configuration information in the emulator flash memory. Hereafter, when the emulator is activated, the saved specifications go into effect.

N: Does not overwrite configuration information. The existing specifications are valid.

- Display

  Displays the specified trace mode in the following format:

```
: TRACE_MODE (RET)
 DMA=x   REF=x   OVFB=y   TIME=zzzzz
```

x: Enables or disables trace information acquisition for DMA cycles and refresh cycles

E: Trace information is acquired

D: No trace information is acquired

y: A break occurs when the trace buffer overflows

zzzzz: Minimum time stamp unit

Table 7.37 Display of Minimum Time Stamp Unit

Display	Description
CLK	Acquires trace information on the number of clock cycles. Does not acquire trace information on time stamp.
20ns	20 nanoseconds
1.6us	1.6 microseconds
52us	52 microseconds

Examples

1. To set the minimum time stamp unit to 20 ns:

```
:TMO TIME=1 (RET)
:
```

2. To display the specified contents:

```
:TMO (RET)
 DMA=E  REF=E  OVFB=D  TIME=20ns
:
```

7.2.44 TRACE_SEARCH [TS] Searches for and displays trace information

Command Format

- Search and display TRACE_SEARCH[Δ<condition>[Δ<condition>...]
  [;[–] <start bus-cycle pointer>[:[–]<end bus-cycle pointer>] [L]]] (RET)

<condition>:	Condition governing trace information to be searched for or displayed. If this is omitted, the number of bus cycles and the number of instructions in the trace buffer are displayed.
–:	Specified when searching for trace information acquired before the trace or break condition has been satisfied. (This option is usually necessary, except for displaying trace information during delays when a delay count condition is specified by the BREAK_ CONDITION_B or TRACE_CONDITION_B command.)
<start bus-cycle pointer>:	Start pointer of bus cycle to be searched for or displayed.
<end bus-cycle pointer>:	End pointer of bus cycle to be searched for or displayed. If both <start bus-cycle pointer> and <end bus-cycle pointer> are omitted, bus cycles are searched for or displayed according to the pointers specified with the TRACE_DISPLAY_MODE command.
L:	Displays the last bus-cycle information to be searched for.

Description

- Search and display

— Searches for information in the trace buffer under the specified conditions, and displays all applicable bus-cycle information. If <start bus-cycle pointer> and <end bus-cycle pointer> are specified, searches for and displays the bus-cycle information between <start bus-cycle pointer> and <end bus-cycle pointer>. Trace information is displayed in the same format as the bus-cycle information display by the TRACE command.

— If no conditions are specified, the number of bus cycles and instructions saved in the trace buffer are displayed.

```
: TRACE_SEARCH (RET)
  INSTRUCTION NUMBER = D'xxxxxx      BUS-CYCLE NUMBER = D'yyyyyy
```

xxxxxx: Number of instructions (decimal)
yyyyyy: Number of bus cycles (decimal)

- If the L option is specified, displays only the last bus-cycle information to be searched for.
- Items listed in table 7.38 can be specified for <condition>, and they can be combined by ANDing them.

Table 7.38 Specifiable Conditions (TRACE_SEARCH)

Item and Input Format	Description
Address condition A=<address 1>[:<address 2>]	When only <address 1> is specified, the condition is satisfied when the address bus value matches the specified value. When both <address 1> and <address 2> are specified, the condition is satisfied when the address bus value is in the range from <address 1> to <address 2>. This condition can be masked.
Data condition D=<1-byte value> WD=<2-byte value> LD=<4-byte value>	The condition is satisfied when the data bus value matches the specified value. When D, WD, or LD is specified, the condition is satisfied when the address is accessed in bytes, words, or longwords, respectively. This condition can be masked.
Read/Write condition R: Read W: Write	The condition is satisfied in a read cycle (R is specified) or a write cycle (W is specified).
Access type DAT: Execution cycle DMA: DMA cycle VCF: Vector fetch cycle REF: Refresh cycle Default: All bus cycles described above (including program fetch cycle)	The condition is satisfied when the bus-cycle type matches the specified type. Multiple access types cannot be specified; either select one of the access types on the left, or specify none.
External probe condition PRB=<value>	The condition is satisfied when all of the emulator's external probe signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to a probe number, as follows: 3 2 1 0 ← Bit x x x x ← Specified value | | | | 4 3 2 1 ← Probe number x: 0 = Low level 1 = High level This condition can be masked.

Table 7.38 Specifiable Conditions (TRACE_SEARCH) (cont)

<table>
<tr><th>Item and Input Format</th><th>Description</th></tr>
<tr><td>Memory type condition
INT: Internal area
IO: Internal I/O area
EXT: External area
CAC: Cache</td><td>Searches for a bus cycle in which the specified memory area type is accessed.</td></tr>
<tr><td>External interrupt condition 1
NMI [:L] or NMI: H</td><td>The condition is satisfied when the NMI signal matches the specified level.
NMI or NMI: L: The condition is satisfied when NMI is low
NMI: H: The condition is satisfied when NMI is high</td></tr>
<tr><td>External interrupt condition 2
IRL=<value></td><td>The condition is satisfied when all of the IRL signals match the specified values. Specify <value> as 1-byte data. Each bit corresponds to an IRL number, as follows:
3 2 1 0 ← Bit
x x x x ← Specified value
| | | |
3 2 1 0 ← IRL number
x: 0 = Low level
1 = High level
The condition can be masked.</td></tr>
<tr><td>RES</td><td>Searches for a bus cycle in which the RESET signal is low.</td></tr>
<tr><td>Time stamp
TS=<elapsed time 1>
[Δ<elapsed time 2>]</td><td>Searches for the specified elapsed time.
When only <elapsed time 1> is specified, searches for the time specified with <elapsed time 1>. When both <elapsed time 1> and <elapsed time 2> are specified, searches for the time range specified with <elapsed time 1> and <elapsed time 2>.
<elapsed time 1> = hhh[:mm[:ss[:uuuuuu]]]
<elapsed time 2> = hhh[:mm[:ss[:uuuuuu]]]
hhh: Hour
mm: Minute
ss: Second
uuuuuu: Microsecond</td></tr>
</table>

— When an address or data condition is specified, the emulator searches for a bus cycle where address bus and data bus values match the specified values, respectively. Note the following when specifying search conditions.

a. Access to a 32-bit bus area

- Longword access

  Longword data is accessed in one bus cycle. Only longword data (LD) and a multiple of four can be specified as data and address conditions, respectively.

- Word access

  Word data is accessed in one bus cycle. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively.

- Byte access

  Byte data is accessed in one bus cycle. Only byte data (D) can be specified as the data condition. Both even and odd addresses can be specified as the address condition.

b. Access to a 16-bit bus area

- Longword access

  Longword data is accessed in two word-access cycles. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively.

- Word access

  Word data is accessed in one bus cycle. Only word data (WD) and a multiple of two can be specified as the data and address conditions, respectively.

- Byte access

  Byte data is accessed in one bus cycle. Only byte data (D) can be specified as the data condition. Both even and odd address values can be specified as the address condition.

c. Access to an 8-bit bus area

All addresses can be accessed in byte units. Longword data and word data are accessed in four byte-access cycles and two byte-access cycles, respectively. Both even and odd addresses can be specified as the address condition. Note, however, that only byte data (D) is valid for the data condition.

- A bit mask in 1-bit or 4-bit units can be specified for address, data, IRL, or PRB condition. When a bit is masked, the condition is satisfied irrespective of its bit value. To implement the mask, specify each digit to be masked at input as an asterisk (*). Table 7.39 shows mask specification examples.

  Example 1: To search for a bus cycle where bit 0 is zero in the byte data condition:

  ```
  : TRACE_SEARCH  A=4000000   D=B'*******0 (RET)
  ```

  Example 2: To search for a bus cycle where IRL2 is zero in the IRL condition (IRL pins other than IRL2 are ignored):

  ```
  : TRACE_SEARCH  IRL=B'*0** (RET)
  ```

Table 7.39 Mask Specifications (TRACE_SEARCH)

Radix	Mask Unit	Example	Mask Position	Allowed Condition
Binary	1 bit	B'01*1010*	Bits 0 and 5 are masked	Address, data (D, WD, LD), IRL, or PRB
Hexa-decimal	4 bits	H'F**50	Bits 15 to 8 are masked	Address, data (D, WD, LD), IRL, or PRB

- The display contents are the same as the bus-cycle display of the TRACE command. However, instruction mnemonics are not displayed.

- If no trace information satisfies the specified condition,

  ```
  *** 45: NOT FOUND
  ```

  is displayed.

- If there is no trace information in the trace buffer,

  ```
  *** 39: BUFFER EMPTY
  ```

  is displayed.

Examples

1. To search for bus cycles where data is written to addresses from H'1000000 to H'1000050:

```
:TS A=1000000:1000050 W (RET)
     BP       AB       DB    MA  RW ST  IRL  NMI RES BRQ VCC PRB
 -D'000063 01000003 ******44 EXT W  DAT 1110  1   1   1   1  1111
 -D'000062 01000022 ****3344 EXT W  DAT 1111  1   1   1   1  1111
 -D'000060 01000040 11223344 EXT W  DAT 1111  1   1   1   1  1111
:
```

2. To search for the last bus cycle where IRL0 is low:

```
:TS IRL=B'***0 ;L (RET)
     BP       AB       DB    MA  RW ST  IRL  NMI RES BRQ VCC PRB
 -D'000063 01000003 ******44 EXT W  DAT 1110  1   1   1   1  1111
:
```

Section 8 Data Transfer from Host Computer Connected by RS-232C Interface

8.1 Overview

When the emulator is connected to a host computer by the RS-232C interface, data can be transferred between the host computer and the emulator or between the host computer and memory in the user system connected to the emulator. This enables the following transmission of host computer load module files:

- Loads a load module file in the host computer to user system memory
- Saves data in the user system memory as a load module file in the host computer

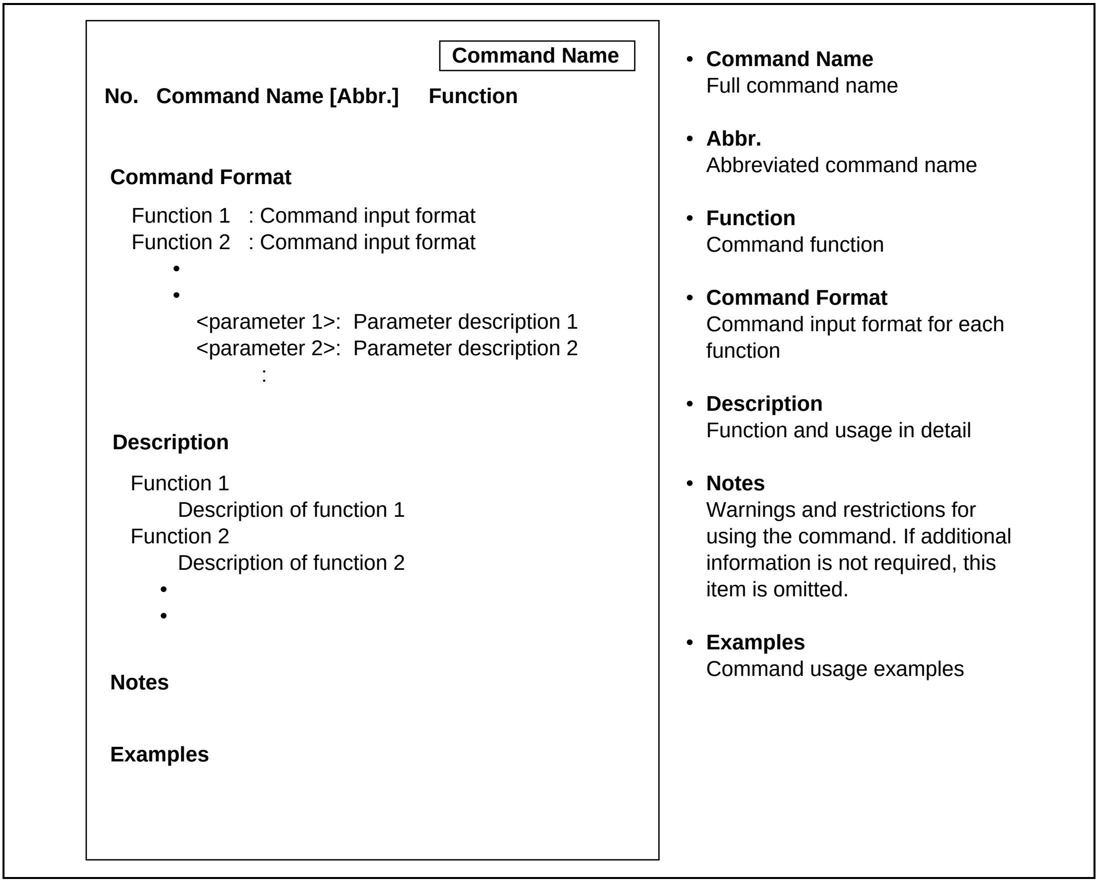
Commands listed in table 8.1 can be used to transfer data between the emulator and host computer.

Table 8.1 Host-Computer Related Commands

Command	Function	Usable/Unusable in Parallel Mode
INTFC_LOAD	Loads program from host computer. — Serial interface	Unusable
INTFC_SAVE	Saves program in host computer. — Serial interface	Unusable
INTFC_VERIFY	Verifies memory contents against host computer file. — Serial interface	Unusable
LOAD	Loads program from host computer. — Bidirectional parallel interface	Unusable
SAVE	Saves program in host computer. — Bidirectional parallel interface	Unusable
VERIFY	Verifies memory contents against host computer file. — Bidirectional parallel interface	Unusable

8.2 Host-Computer Related Commands

This section provides details of host-computer related commands in the format shown in figure 8.1.



Command Name

No. **Command Name [Abbr.]** **Function**

Command Format

Function 1 : Command input format
Function 2 : Command input format
•
•
<parameter 1>: Parameter description 1
<parameter 2>: Parameter description 2
:

Description

Function 1
Description of function 1
Function 2
Description of function 2
•
•

Notes

Examples

- **Command Name**
  Full command name
- **Abbr.**
  Abbreviated command name
- **Function**
  Command function
- **Command Format**
  Command input format for each function
- **Description**
  Function and usage in detail
- **Notes**
  Warnings and restrictions for using the command. If additional information is not required, this item is omitted.
- **Examples**
  Command usage examples

Figure 8.1 Description Format of Host-Computer Related Command

Symbols used in the command format have the following meanings:

[ ]:	Parameters enclosed by [ ] can be omitted.
(a/b):	One of the parameters enclosed by ( ) and separated by /, that is, either a or b must be specified.
< >:	Contents shown in < > are to be specified or displayed.
... :	The entry specified just before this symbol can be repeated.
Δ:	Indicates a space. Used only for command format description.
(RET):	Pressing the (RET) key.

Although italic and bold characters are used throughout this manual to indicate input, it is not used in the command format parts of these descriptions.

8.2.1 INTFC_LOAD [IL] Loads program from host computer — Serial interface

Command Format

- Load INTFC_LOAD[Δ<offset>][;<load module type>]:<file name> (RET)

<offset>: Value to be added to the load module address
<load module type>: Load module type
  R: SYSROF-type load module
  S: S-type load module
  H: HEX-type load module
  M: Memory image file
  E: ELF-type load module
  Default: SYSROF-type load module
<file name>: File name in the host computer

Description

- Load

— Loads a user program from the host computer into user system memory via the serial interface. Use interface software IPW for the host computer.

:***INTFC_LOAD[;<load module type>]:<file name> (RET)***

When loading is completed, the start and end addresses are displayed as follows:

TOP ADDRESS = <start address>
END ADDRESS = <end address>

— An offset (value to be added) can be specified for the address of an SYSROF-type, ELF-type, S-type, or HEX-type load module.

:***INTFC_LOAD <offset>;S :<file name> (RET)***

If an offset is specified, a load address is calculated as follows:

Load address = <load module address> + <offset>

Notes

1. The load module can be loaded only to the internal memory areas or areas CS0 to CS4.
2. Verification is not performed during load. If the program must be verified, use the INTFC_VERIFY command. For details, refer to section 8.2.3, INTFC_VERIFY.

Examples

1. To load SYSROF-type load module F11.ABS:

```
:IL :F11.ABS (RET)
 TOP ADDRESS = 00007000
 END ADDRESS = 00007FFF
:
```

2. To load S-type load module ST.MOT:

```
:IL ;S :ST.MOT(RET)
 TOP ADDRESS = 00000000
 END ADDRESS = 00003042
:
```

8.2.2 INTFC_SAVE [IS] Saves program in host computer — Serial interface

Command Format

- Save INTFC_SAVEΔ<start address>(Δ<end address>/Δ@<number of bytes>) [;[<load module type>][ΔLF]]:<file name> (RET)

<start address>:	Start memory address
<end address>:	End memory address
<number of bytes>:	Number of bytes to be saved
<load module type>:	Load module type
S:	S-type load module
H:	HEX-type load module
Default:	S-type load module
LF:	Adds an LF code (H'0A) to the end of each record
<file name>:	File name in the host computer

Description

- Save

— Saves the specified memory contents in the specified load module type in a host computer file via the serial interface. Use interface software IPW for the host computer. An S-type or HEX-type load module can be saved. An SYSROF-type or ELF-type load module cannot be saved.

:***INTFC_SAVE <start address> <end address>[;<load module type>] :<file name> (RET)***

When save is completed, the start and end memory addresses are displayed as follows:

TOP ADDRESS = <start address>
END ADDRESS = <end address>

— When the LF option is specified, the emulator adds an LF code (H'0A) to the end of each record in addition to a CR code (H'0D) in the S-type or HEX-type load module.

Notes

1. Do not save data in the area other than the internal memory areas and areas CS0 to CS4.
2. Verification is not performed after save. If the program must be verified, use the INTFC_VERIFY command. For details, refer to section 8.2.3, INTFC_VERIFY.
3. If the specified file name already exists, an overwrite confirmation message is displayed. If N is entered to halt save, some unnecessary characters may be output to the following line.

Example

To save memory contents in the address range from H'7000 to H'7FFF in host computer file F11.MOT in the S-type load module format:

```
:IS 7000 7FFF :F11.MOT (RET)
 TOP ADDRESS = 00007000
 END ADDRESS = 00007FFF
:
```

8.2.3 INTFC_VERIFY [IV] Verifies memory contents against host computer file — Serial interface

Command Format

- Verification INTFC_VERIFY [Δ<offset>][;<load module type>]:<file name> (RET)

<offset>: Value to be added to the address
<load module type>: Load module type
R: SYSROF-type load module
S: S-type load module
H: HEX-type load module
M: Memory image file
E: ELF-type load module
Default: SYSROF-type load module
<file name>: File name in the host computer

Description

- Verification

— Verifies data transferred from the host computer against data in memory via the serial interface. Use interface software IPW for the host computer.

:***INTFC_VERIFY[;<load module type>]:<file name> (RET)***

— If a verification error occurs, all errors will be displayed in the following format:

```
<ADDR>          <FILE>          <MEM>
xxxxxxxx          yy 'y'           zz 'z'
```

xxxxxxxx: Verification error address
yy 'y': Load module data (in hexadecimal and ASCII characters)
zz 'z': Memory data (in hexadecimal and ASCII characters)

— An offset (value to be added or subtracted) can be specified for the address of an SYSROF-type, ELF-type, S-type, or HEX-type load module.

:***INTFC_VERIFY <offset> ;S :<file name> (RET)***

If an offset is specified, a verification address is calculated as follows:

Verification address = <load module address> + <offset>

Note

Do not verify data in the area other than the internal memory areas and areas CS0 to CS4.

Example

To verify SYSROF-type load module F1.ABS against the memory contents:

```
:IV :F1.ABS (RET)
 <ADDR>     <FILE>    <MEM>
 00001012    31'1'     00'.'
:
```

8.2.4 LOAD [L] Loads program from host computer — Bidirectional parallel interface

Command Format

- Load LOAD[Δ<offset>][;<load module type>]:<file name> (RET)

<offset>: Value to be added to the load module address

<load module type>: Load module type

R:	SYSROF-type load module
S:	S-type load module
H:	HEX-type load module
M:	Memory image file
E:	ELF-type load module
Default:	SYSROF-type load module

<file name>: File name in the host computer

Description

- Load

— Loads a user program from the host computer into user system memory via the bidirectional parallel interface. Use interface software IPW for the host computer to transfer the specified file to the emulator via the bidirectional parallel interface. Enter #B• before the command to request data output to the host computer.

:***#B LOAD[;<load module type>]:<file name> (RET)***

When loading is completed, the start and end addresses are displayed as follows:

```
TOP ADDRESS = <start address>
END ADDRESS = <end address>
```

— An offset (value to be added) can be specified for the address of an SYSROF-type, ELF-type, S-type, or HEX-type load module.

:***#B LOAD <offset>;S :<file name> (RET)***

If an offset is specified, a load address is calculated as follows:

Load address = <load module address> + <offset>

Notes

1. Do not load data to the area other than the internal memory areas and areas CS0 to CS4.
2. Verification is not performed during load. If the program must be verified, use the VERIFY command. For details, refer to section 8.2.6, VERIFY.

Examples

1. To load SYSROF-type load module F11.ABS:

```
:#B L:F11.ABS (RET)
 TOP ADDRESS = 00007000
 END ADDRESS = 00007FFF
:
```

2. To load S-type load module ST.MOT:

```
:#B L;S:ST.MOT (RET)
 TOP ADDRESS = 00000000
 END ADDRESS = 00003042
:
```

8.2.5 SAVE [SV] Saves program in host computer — Bidirectional parallel interface

Command Format

- Save SAVEΔ<start address>(Δ<end address>/Δ@<number of bytes>) [;[<load module type>][ΔLF]]:<file name> (RET)

<start address>: Start memory address
<end address>: End memory address
<number of bytes>: Number of bytes to be saved
<load module type>: Load module type
S: S-type load module
H: HEX-type load module
Default: S-type load module
LF: Adds an LF code (H'0A) to the end of each record
<file name>: File name in the host computer

Description

- Save

— Saves the specified memory contents in the specified load module type in a host computer file via the bidirectional parallel interface. Use interface software IPW for the host computer. An S-type or HEX-type load module can be saved. An SYSROF-type or ELF-type load module cannot be saved. Enter #N• before the command to request data receipt to the host computer.

:***#N SAVE <start address> <end address>[;<load module type>]:<file name> (RET)***

When save is completed, the start and end memory addresses are displayed as follows:

```
TOP ADDRESS = <start address>
END ADDRESS = <end address>
```

— When the LF option is specified, the emulator adds an LF code (H'0A) to the end of each record in addition to a CR code (H'0D) in the S-type or HEX-type load module.

Notes

1. Do not save data in the area other than the internal memory areas and areas CS0 to CS4.
2. Verification is not performed after save. If the program must be verified, use the VERIFY command. For details, refer to section 8.2.6, VERIFY.

Example

To save memory contents in the address range from H'7000 to H'7FFF in host computer file F11.MOT in the S-type load module format:

```
:#N SV 7000 7FFF :F11.MOT (RET)
 TOP ADDRESS = 00007000
 END ADDRESS = 00007FFF
:
```

8.2.6 VERIFY [V] Verifies memory contents against host computer file — Bidirectional parallel interface

Command Format

- Verification VERIFY [Δ<offset>][;<load module type>]:<file name> (RET)

<offset>: Value to be added to the address

<load module type>: Load module type

R:	SYSROF-type load module
S:	S-type load module
H:	HEX-type load module
M:	Memory image file
E:	ELF-type load module
Default:	SYSROF-type load module

<file name>: File name in the host computer

Description

- Verification

— Verifies data transferred from the host computer against data in memory via the bidirectional parallel interface. Use interface software IPW for the host computer. Enter #BΔ before the command to request data output to the host computer.

```
:#B VERIFY[;<load module type>]:<file name> (RET)
```

— If a verification error occurs, all errors will be displayed in the following format:

```
<ADDR>          <FILE>          <MEM>
xxxxxxxx          yy 'y'            zz 'z'
```

xxxxxxxx:	Verification error address
yy 'y':	Load module data (in hexadecimal and ASCII characters)
zz 'z':	Memory data (in hexadecimal and ASCII characters)

— An offset (value to be added or subtracted) can be specified for the address of an SYSROF-type, ELF-type, S-type, or HEX-type load module.

:***#B VERIFY <offset> ;S :<file name> (RET)***

If an offset is specified, a verification address is calculated as follows:

Verification address = <load module address> + <offset>

Note

Do not verify data in the area other than the internal memory areas and areas CS0 to CS4.

Example

To verify SYSROF-type load module F1.ABS against the memory contents:

```
:#B V:F1.ABS (RET)
 <ADDR>     <FILE>    <MEM>
 00001012    31'1'     00'.'
:
```

Section 9 Data Transfer from Host Computer Connected by LAN Interface

9.1 Overview

The optional LAN board supports the FTP client function. This function enables the following data transfer between the emulator and the host computer connected via the LAN interface.

- Loads a load module file in the host computer to user system memory
- Saves data in the user system memory as a load module file in the host computer
- Transfers files between the emulator and host computer

The emulator supports the LAN commands listed in table 9.1 to transfer data between the emulator and the host computer. These commands are explained in section 9.3, LAN Commands.

Table 9.1 LAN Commands

Command	Function	Usable/Unusable in Parallel Mode
ASC	Specifies the file type to be transferred as ASCII	Usable
BIN	Specifies the file type to be transferred as binary	Usable
BYE	Terminates the FTP interface (Re-connects the FTP interface with the FTP command)	Usable
CD	Changes the directory of the FTP server	Usable
CLOSE	Disconnects the host computer from the FTP interface (Re-connects the host computer to the FTP interface with the OPEN command)	Usable
FTP	Connects the host computer and emulator via the FTP interface	Usable
LAN	Displays emulator IP address	Usable
LAN_HOST	Displays all defined host computers	Usable
LAN_LOAD	Loads a load module file from the host computer to memory via the FTP interface	Unusable
LAN_SAVE	Saves the specified memory contents in the host computer connected via the FTP interface	Unusable
LAN_VERIFY	Verifies memory contents against the host computer file connected via the FTP interface	Unusable
LS	Displays the host computer directory connected via the FTP interface	Usable
OPEN	Connects the host computer to the FTP interface	Usable
PWD	Displays the current directory name of the host computer connected via the FTP interface	Usable
ROUTER	Displays routing information	Usable
STA	Displays the type of file to be transferred	Usable
SUBNET	Displays the subnet mask value	Usable
LOGOUT	Disconnects from the TELNET*	Usable

Note: The optional LAN board supports the TELNET server function in addition to the FTP client function. When the emulator is connected to the host computer through TELNET, the emulator can be disconnected from the TELNET with the LOGOUT command. For details on the TELNET interface, refer to section 3.5.1, Power-On Procedure for LAN Interface, in Part I, E8000 Guide. Note that the FTP can be connected via TELNET or the RS-232C interface.

9.2 LAN Data Transfer

9.2.1 Setting the Data Transfer Environment

The optional LAN board enables data transfer between the emulator and host computer via the FTP interface. The transfer environment must be specified before starting data transfer as follows. Note that the optional LAN board supports the FTP client function only.

Procedure:

1. Specify the host computer environment, including the host computer name and IP address, to the network database of the host computer. For details, refer to the appropriate host computer's User’s Manual.

2. Specify the following emulator environment:

    a. Emulator IP address

    Specify the emulator IP address with the emulator monitor command L. Since the emulator IP address is written to the emulator flash memory, it needs not to be written each time the LAN interface is used. The emulator IP address can be modified as required.

    b. Host computer IP address (host computer connected via FTP interface)

    With the emulator monitor flash memory management tool command LH, specify the name and IP address of the host computer to be connected to the emulator via the FTP interface when initiating the E8000 system program. Since the specified host name and IP address are written to the emulator flash memory, they need not to be written each time the LAN interface is used. The host computer name and IP address can be modified as required.

9.2.2 Data Transfer

Data transfer is performed by connecting the emulator to the host computer via the FTP interface after the environmental settings have been completed. In the FTP interface, the optional LAN board supports only the client function. Therefore, the FTP command must be entered to the emulator and not the host computer to establish the FTP interface. Transfer data using the following procedure.

Procedure:

1. E8000 system program initiation

   Initiate the E8000 system program with the emulator monitor command S after confirming that the host computer to be connected has been defined with the emulator monitor flash memory management tool command LH.

2. FTP connection

   Connect the emulator to the designated host computer with the FTP command using the format shown below. Enter the host computer name defined with the emulator monitor flash memory management tool command LH. In addition, enter the user name and password.

   ```
   :FTP <host computer name> (RET)
    Username <user name> (RET)
    Password <password> (RET)
    login command success
   FTP>
   ```

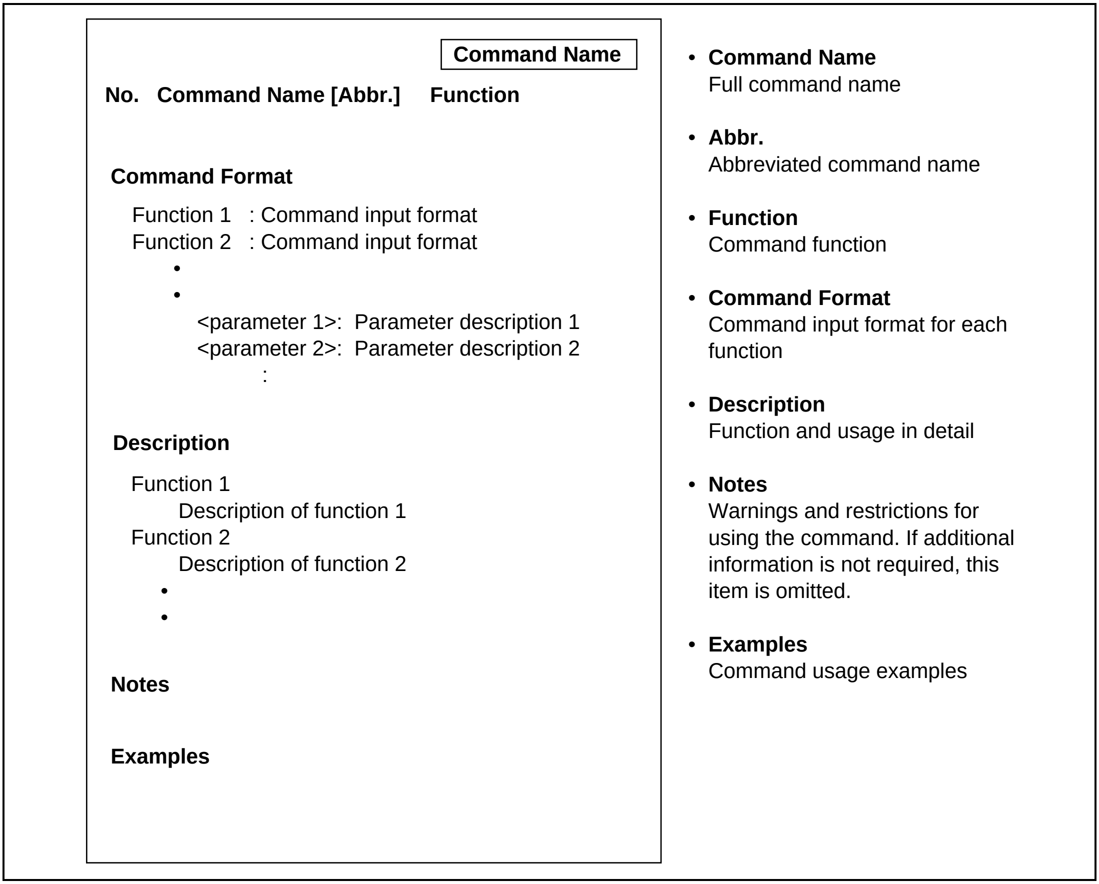
3. Transfer data using the LAN_LOAD, LAN_SAVE, or LAN_VERIFY command after the FTP interface is established. For details, refer to the corresponding command descriptions.

9.2.3 Notes on FTP Interface

Before turning off the emulator power, the FTP interface must be terminated using the BYE command. Otherwise, the host computer interface processing may remain uncompleted. In this case, the FTP interface cannot be re-established correctly even if the emulator is re-initiated.

9.3 LAN Commands

This section provides details of LAN commands in the format shown in figure 9.1.



Command Name

No. Command Name [Abbr.] Function

Command Format

Function 1 : Command input format
Function 2 : Command input format
•
•
<parameter 1>: Parameter description 1
<parameter 2>: Parameter description 2
:

Description

Function 1
Description of function 1
Function 2
Description of function 2
•
•

Notes

Examples

- **Command Name**
  Full command name
- **Abbr.**
  Abbreviated command name
- **Function**
  Command function
- **Command Format**
  Command input format for each function
- **Description**
  Function and usage in detail
- **Notes**
  Warnings and restrictions for using the command. If additional information is not required, this item is omitted.
- **Examples**
  Command usage examples

Figure 9.1 LAN Command Description Format

Symbols used in the command format have the following meanings:

[ ]: Parameters enclosed by [ ] can be omitted.
(a/b): One of the parameters enclosed by ( ) and separated by /, that is, either a or b must be specified.
< >: Contents shown in < > are to be specified or displayed.
... : The entry specified just before this symbol can be repeated.
Δ: Indicates a space. Used only for command format description.
(RET): Pressing the (RET) key.

Although italic and bold characters are used throughout this manual to indicate input, it is not used in the command format sections of these descriptions.

9.3.1 ASC [ASC] Specifies the file type as ASCII

Command Format

- Setting ASC (RET)

Description

- Setting

  Specifies the file type as ASCII in the FTP interface. To load an SYSROF-type load module file, binary must be specified with the BIN command.

Example

To set the file type as ASCII in the FTP interface:

```
FTP> ASC (RET)
 asc command success
FTP>
```

9.3.2 BIN [BIN] Specifies the file type as binary

Command Format

- Setting BIN (RET)

Description

- Setting

  Specifies the file type as binary in the FTP interface. This specification is required to transfer files with the LAN_LOAD, LAN_SAVE, or LAN_VERIFY command. To load or verify an SYSROF-type load module file, binary must be specified with this command. Otherwise, a transfer error will occur. At emulator initiation, binary is the default setting.

Example

To set the file type as binary in the FTP interface:

```
FTP> BIN (RET)
 bin command success
FTP>
```

9.3.3 BYE [BYE] Terminates the FTP interface

Command Format

- FTP interface termination BYE (RET)

Description

- FTP interface termination

  Terminates the FTP interface and changes the prompt to a colon (:). To re-establish the FTP interface, enter the FTP command. For details, refer to section 9.3.6, FTP.

Example

To terminate the FTP interface:

```
FTP> BYE (RET)
 bye command success
:
```

9.3.4 CD [CD] Changes the directory name of the FTP server

Command Format

- Directory change CD Δ<directory name> (RET)

  <directory name>: Name of new directory

Description

- Directory change

  Changes the current directory of the FTP server (connected host computer) to the specified directory. The modified directory must be formatted depending on which host computer is connected via the FTP interface.

Example

To change the current directory of the FTP server to subdir:

```
FTP> CD subdir (RET)
 cd command success
FTP>
```

9.3.5 CLOSE [CLOSE] Disconnects the host computer from the FTP interface

Command Format

- FTP interface disconnection CLOSE (RET)

Description

- FTP interface disconnection

  Disconnects the FTP interface from the host computer to which it is currently connected. Before changing host computers, disconnect the FTP interface with this command and re-connect with the OPEN command. For details, refer to section 9.3.13, OPEN.

Example

To disconnect the FTP interface and change the host computer to be connected:

```
FTP> CLOSE (RET)
 bye command success
FTP> OPEN HOST1 (RET)
 Username ABC (RET)
 Password ****** (RET)
 login command success
FTP>
```

9.3.6 FTP [FTP] Connects host computer and emulator via the FTP interface

Command Format

- FTP interface connection FTP <host name> (RET)

<host name>: Name of the host computer to be connected with the FTP server (The host computer name must be already defined with the flash memory management tool.)

Description

- FTP interface connection

— Connects the host computer and emulator via the FTP interface to enable data transfer with the LAN_LOAD, LAN_SAVE, or LAN_VERIFY command. The host name specified in this command must be defined with the flash memory management tool.

— If <host name> has been defined, enter the user name and password in the following format. After FTP command execution, the prompt changes from a colon (:) to FTP>. Emulation commands can be executed even after FTP connection.

```
: FTP <host name>  (RET)
  Username    (a)  (RET)
  Password    (b)  (RET)
  login command success
FTP>          (c)
```

(a) Enter user name.
(b) Enter password.
(c) An FTP> prompt is displayed after FTP connection.

Note

A password must be specified before a host computer can be connected via the FTP interface. If no password is specified, specify one before connection.

Example

To connect the emulator to host computer HOST1 via the FTP interface:

```
:FTP HOST1 (RET)
 Username USER1 (RET)
 Password ******** (RET)
 login command success
FTP>
```

9.3.7 LAN [LAN] Displays emulator IP address

Command Format

- Display LAN (RET)

Description

- Display

  — Displays the emulator's internet (IP) address stored in the emulator, in the following format:

```
: LAN  (RET)
  E8000 INTERNET ADDRESS  xxx.xxx.xxx.xxx
                                (a)
```

(a) Emulator IP address

— Specify the emulator IP address with the emulator monitor command L.

Example

To display the emulator IP address:

```
:LAN (RET)
 E8000 INTERNET ADDRESS 128.1.1.10
:
```

9.3.8 LAN_HOST [LH] Displays the names and IP addresses of all defined host computers

Command Format

- Display LAN_HOST (RET)

Description

- Display

  Displays the LAN host computer names and internet addresses defined in the emulator flash memory in the following format:

```
: LAN_HOST  (RET)
NO   <HOST NAME>   <IP ADDRESS>      NO   <HOST NAME>   <IP ADDRESS>
01    xxxxxx        xxx.xxx.xxx.xxx  02    xxxxxx        xxx.xxx.xxx.xxx
03    xxxxxx        xxx.xxx.xxx.xxx  04    xxxxxx        xxx.xxx.xxx.xxx
05    xxxxxx        xxx.xxx.xxx.xxx  06    xxxxxx        xxx.xxx.xxx.xxx
07    xxxxxx        xxx.xxx.xxx.xxx  08    xxxxxx        xxx.xxx.xxx.xxx
09    xxxxxx        xxx.xxx.xxx.xxx
```

Example

To display all of the defined host computer names and IP addresses:

```
:LH (RET)
 NO <HOST NAME>  <IP ADDRESS>   NO <HOST NAME>  <IP ADDRESS>
 01  HOST1        128.1.1.1     02  HOST2        128.1.1.4
 03  HOSTX        128.1.1.8     04
 05                             06
 07                             08
 09
:
```

9.3.9 LAN_LOAD [LL] **Loads a load module file from the host computer to memory via the FTP interface**

Command Format

- Load LAN_LOAD [Δ<offset>][;<load module type>]:<file name> (RET)

<offset>: Value to be added to the load module address

<load module type>: Load module type

R: SYSROF-type load module
S: S-type load module
H: HEX-type load module
M: Memory image file
E: ELF-type load module
Default: SYSROF-type load module

<file name>: File name in the host computer

Description

- Load

— Loads a load module file from the host computer to memory via the FTP interface. Before executing this command, the emulator must be connected to the host computer with the FTP command. For details, refer to section 9.3.6, FTP.

— The current load address is displayed as follows:

```
LOADING ADDRESS = xxxxxxxx
```

xxxxxxxx: Current load address (continuously updated)

When loading is completed, the start and end addresses are displayed as follows:

```
TOP ADDRESS = <start address>
END ADDRESS = <end address>
```

— An offset (value to be added) can be specified for the address of an SYSROF-type, ELF-type, S-type, or HEX-type load module.

: ***LAN_LOAD <offset> ;S:<file name> (RET)***

If an offset is specified, a load address is calculated as follows:

Load address = <load module address> + <offset>

Notes

1. Do not load data to the area other than the internal memory areas and areas CS0 to CS4.
2. Verification is not performed during load. If the program must be verified, use the LAN_ VERIFY command. For details, refer to section 9.3.11, LAN_VERIFY.
3. Before loading an SYSROF-type load module, the file type must be changed to binary code with the BIN command. At emulator initiation, binary code is selected as the default. However, if ASCII is selected with the ASC command, change the file type to binary code with the BIN command before loading. For details, refer to section 9.3.2, BIN.

Example

To load an SYSROF-type load module, enter the following command line. F11.ABS indicates the host computer file name. Before entering the LAN_LOAD command, connect the emulator to the host computer with the FTP command:

```
:FTP HOST1 (RET)
 Username USER1 (RET)
 Password ******** (RET)
 login command success
FTP> LL :F11.ABS (RET)
 LOADING ADDRESS   00007000
 TOP ADDRESS = 00007000
 END ADDRESS = 00007FFF
FTP>
```

9.3.10 LAN_SAVE [LSV] Saves the specified memory contents in the host computer connected via the FTP interface

Command Format

- Save LAN_SAVEΔ<start address>(Δ<end address>/Δ@<number of bytes>) [;[<load module type>][ΔLF]]:<file name> (RET)

<start address>:	Start memory address
<end address>:	End memory address
<number of bytes>:	The number of bytes to be saved
<load module type>:	Load module type
S:	S-type load module
H:	HEX-type load module
M:	Memory image file
Default:	S-type load module
LF:	Adds an LF code (H'0A) to the end of each record
<file name>:	File name in the host computer

Description

- Save

— Saves the specified memory contents in the host computer connected via the FTP interface. An S-type, HEX-type, or M-type load module can be saved. An SYSROF-type or ELF-type load module cannot be saved. Before executing this command, connect the emulator to the host computer with the FTP command.

— The current save address is displayed as follows:

```
SAVING ADDRESS = xxxxxxxx
```

xxxxxxxx: Current save address (continuously updated)

When save is completed, the start and end memory addresses are displayed as follows:

```
TOP ADDRESS = <start address>
END ADDRESS = <end address>
```

— When the LF option is specified, the emulator adds an LF code (H'0A) to the end of each record in addition to a CR code (H'0D).

Notes

1. Do not save data in the area other than the internal memory areas and areas CS0 to CS4.
2. Verification is not performed after save. If the program must be verified, use the LAN_VERIFY command, if necessary. For details, refer to section 9.3.11, LAN_VERIFY.

Example

To save the memory contents in the address range from H'7000 to H'7FFF in the host computer as an S-type load module file (file name: F11.S), enter the following command line. Before entering the LAN_SAVE command, connect the emulator to the host computer with the FTP command:

```
:FTP HOST1 (RET)
 Username USER1 (RET)
 Password ******** (RET)
 login command success
FTP>LSV 7000 7FFF :F11.S (RET)
 SAVING ADDRESS   00007000
 TOP ADDRESS = 00007000
 END ADDRESS = 00007FFF
FTP>
```

9.3.11 LAN_VERIFY [LV] Verifies memory contents against the host computer file connected via the FTP interface

Command Format

- Verification LAN_VERIFY [Δ<offset>][;<load module type>]:<file name> (RET)

<offset>: Value to be added to the load module address

<load module type>: Load module type

R:	SYSROF-type load module
S:	S-type load module
H:	HEX-type load module
M:	Memory image file
E:	ELF-type load module
Default:	SYSROF-type load module

<file name>: File name in the host computer

Description

- Verification

— Verifies the file in the host computer connected via the FTP interface against data in memory in the following format. Before executing this command, connect the emulator to the host computer with the FTP command.

FTP> ***LAN_VERIFY <load module type>:<file name> (RET)***

— If a verification error occurs, the address and its contents are displayed as follows:

```
<ADDR>          <FILE>          <MEM>
xxxxxxxx          yy 'y'          zz 'z'
```

xxxxxxxx: Verification error address

yy 'y': Load module data (in hexadecimal and ASCII characters)

zz 'z': Memory data (in hexadecimal and ASCII characters)

— An offset (value to be added or subtracted) can be specified for the address of an SYSROF-type, ELF-type, S-type, or HEX-type load module.

FTP> ***LAN_VERIFY <offset> ;S :<file name> (RET)***

If an offset is specified, a verification address is calculated as follows:

Verification address = <load module address> + <offset>

Notes

1. Do not verify data in the area other than the internal memory areas and areas CS0 to CS4.
2. Before verifying an SYSROF-type load module, the file type must be changed to binary code with the BIN command. At emulator initiation, binary code is selected as the default. However, if ASCII is selected with the ASC command, change the file type to binary code with the BIN command before verifying. For details, refer to section 9.3.2, BIN.

Example

To verify SYSROF-type load module file F11.ABS in the host computer against the memory contents:

```
:FTP HOST1 (RET)
 Username USER1 (RET)
 Password ******** (RET)
 login command success
FTP>LV :F11.ABS (RET)
 VERIFYING ADDRESS   00000C00
 TOP ADDRESS = 00000000
 END ADDRESS = 00000FFF
FTP>
```

9.3.12 LS [LS] Displays the host computer directory connected via the FTP interface

Command Format

- Display LS [Δ <directory name>] (RET)

  <directory name>: Name of host computer directory (Default: Current directory of the host computer)

Description

- Display

  Displays the specified directory contents in the host computer connected via the FTP interface. If <directory name> is omitted, the current directory contents are displayed. Note that the directory name must be specified according to the connected host computer format.

Example

To display the contents of the host computer current directory:

```
FTP>LS (RET)
abc.s
xyz
FTP>
```

9.3.13 OPEN [OPEN] Connects the host computer to the FTP interface

Command Format

- FTP interface connection OPEN <host name> (RET)

<host name>: Name of the host computer to be connected via the FTP interface (The host computer name must be already defined with the flash memory management tool.)

Description

- FTP interface connection

  Connects the emulator to the specified host computer via the FTP interface. This command can also be used to change the host computer connected to the emulator. To change the host computer, first disconnect the current host computer using the CLOSE command and then connect the new host computer using this command.

```
FTP>OPEN <host name> (RET)
  Username    (a) (RET)
  Password    (b) (RET)
  login command success
FTP>
```

(a) Enter user name.
(b) Enter password.

Note

A password must be specified before a host computer can be connected via the FTP interface. If no password is specified, specify one before connection.

Example

To disconnect the emulator from the current host computer and connect it to the new host computer HOST1:

```
FTP>CLOSE (RET)
 bye command success
FTP>OPEN HOST1 (RET)
 Username USER1 (RET)
 Password ******** (RET)
 login command success
FTP>
```

9.3.14 PWD [PWD] Displays the current directory name of the host computer connected via the FTP interface

Command Format

- Display PWD (RET)

Description

- Display
  Displays the current directory name of the host computer connected via the FTP interface.

Example

To display the current directory name of the host computer connected via the FTP interface:

```
FTP>PWD (RET)
/usr/e8000
FTP>
```

9.3.15 ROUTER [RTR] Displays the remote network routing information

Command Format

- Display ROUTER (RET)

Description

- Display

  Displays the routing information defined with the emulator monitor flash memory management tool command RTR.

Note

Routing information can be defined with the emulator monitor flash memory management tool command RTR.

Example

To display the defined routing information:

```
:RTR (RET)
 No. IP-ADDRESS    NET-ID      No. IP-ADDRESS    NET-ID
 01  128.1.1.80    168.1.1.0   02  128.1.1.50    160.1.1.0
:
```

9.3.16 STA [STA] Displays the file type to be transferred

Command Format

- Display STA (RET)

Description

- Display

  Displays in the following format, the file type (binary or ASCII) to be transferred by the LAN_LOAD, LAN_SAVE, or LAN_VERIFY command.

  FTP>***STA (RET)***
  type mode is BINARY (Binary)

  FTP>***STA (RET)***
  type mode is ASCII (ASCII)

Example

To display the file type to be transferred:

```
FTP>STA (RET)
 type mode is BINARY
FTP>
```

9.3.17 SUBNET [SN] Displays the subnet mask value

Command Format

- Display SUBNET (RET)

Description

- Display

  Displays the subnet mask value defined with the emulator monitor flash memory management tool command SN.

```
: SUBNET (RET)
  SUBNET MASK  xxx.xxx.xxx.xxx (H'yy.H'yy.H'yy.H'yy)
                     (a)                (b)
```

(a) Subnet mask value (in decimal)

(b) Subnet mask value (in hexadecimal)

Note

The subnet mask value can be defined with the emulator monitor flash memory management tool command SN.

Example

To display the defined subnet mask value:

```
:SN (RET)
 SUBNET MASK 255.255.255.128 (H'FF.H'FF.H'FF.H'80)
:
```

9.3.18 LOGOUT [LO] Disconnects from the TELNET

Command Format

- TELNET disconnection LOGOUT (RET)

Description

- TELNET disconnection

  Disconnects the emulator from the TELNET. This command is valid only when the emulator is connected to the host computer via the TELNET interface.

Example

To disconnect the emulator from the TELNET interface:

```
:LO (RET)
```

Section 10 Error Messages

10.1 Emulator Error Messages

The E8000 system program outputs error messages in the format below. Table 10.1 lists error messages, descriptions of the errors, and error solutions.

```
*** nn:   <error message>
    nn:   Error No.
```

Table 10.1 Emulator Error Messages

Error No.	Error Message	Description and Solution
1	INTERNAL ERROR (nn)	An error occurred in the E8000 system program or station. Error code nn gives specific details. Contact a Hitachi sales agency and inform them of the code and state.
2	HOST I/O ERROR (nn)	An I/O error occurred in data transfer between the emulator and host computer. Error code nn gives specific details. Refer to table 10.2.
5	INVALID DEVICE CONTROL BOARD	The connected device control board is not supported by this E8000 system program. Check the E8000 system program and device control board numbers.
6	USER SYSTEM NOT READY	The user clock or crystal oscillator clock was not input and therefore could not be selected. The emulator internal clock was used instead. Check if the clock signal is output correctly.
8	UBC IS USED BY USER SYSTEM	The command cannot be used because the UBC (user break controller) is open to the user system.
9	INVALID OPTION	The specified option is incorrect. Check the specified option.
10	FLASH MEMORY IS WRITE PROTECTED	Flash memory is write-protected. Remove write protection.
11	FLASH MEMORY WRITE ERROR	An error occurred during write to flash memory.
13	FILE NOT FOUND	The configuration information specified to be restored with the CONFIGURATION command was not found in the emulator flash memory.

Table 10.1 Emulator Error Messages (cont)

Error No.	Error Message	Description and Solution
15	INVALID FILE	The specified file has invalid contents and cannot be read from or written to. Check the contents of the specified file.
20	SYNTAX ERROR	The command syntax is incorrect. Correct the syntax.
21	INVALID COMMAND	The specified command is invalid, or this command cannot be executed in parallel mode. Correctly enter the command.
22	INVALID DATA	The specified data is invalid. Correctly enter the data.
23	INVALID ADDRESS	The specified address or address range is invalid. Correctly enter the address.
24	DATA OVERFLOW	The specified data is more than 4 bytes. Correctly specify the data.
27	INVALID CONDITION	Invalid conditions are specified. Correctly enter the conditions.
28	DOUBLE DEFINITION	The item has already been defined. Check the item to be defined.
29	TOO MANY ALIASES	Too many aliases are specified. Delete any unnecessary alias and re-specify.
31	INSUFFICIENT MEMORY	The size of emulation memory to be allocated with the MAP command was not available. Emulation memory was allocated within the available memory size.
32	INVALID ASM MNEMONIC	An instruction mnemonic in an assembly-language statement is invalid. Correct the instruction mnemonic.
33	INVALID ASM OPERAND	An operand in an assembly-language statement is invalid. Correct the operand.
34	ALREADY ASSIGNED	A condition cannot be specified by the BREAK_CONDITION_A,B,C, TRACE_CONDITION_A,B,C, or PERFORMANCE_ANALYSIS command. Too many conditions are specified. Cancel a condition for another command and re-specify.

Table 10.1 Emulator Error Messages (cont)

Error No.	Error Message	Description and Solution
35	CANNOT USE THIS MODE	GO The GO command cannot be executed because settings for the execution mode are invalid. Correctly specify the settings necessary for the specified execution mode.
37	TOO MANY POINTS	Too many points are specified. Remove any unnecessary settings and re-enter.
38	SET POINT IS NOT IN RAM	A write-protected address is specified by the BREAK or BREAK_SEQUENCE command. Specify a correct address.
39	BUFFER EMPTY	TRACE or TRACE_SEARCH The trace buffer is empty. Check trace conditions and execution state, and re-execute. Then display trace information.
42	CANNOT CHANGE ATTRIBUTE OF X/Y MEMORY AREA	An attempt was made to change the memory attribute of the internal memory area. Allocate emulation memory to areas other than the internal memory area.
43	CANNOT RECOVER A = xxxxxxxx	The break instruction at the address (xxxxxxxx) where a breakpoint is specified with the BREAK or BREAK_SEQUENCE command could not be recovered after GO command execution terminates. Accordingly, a break instruction remains at the breakpoint address. A hardware error might have occurred. Correct the error, and reload and re-execute the program.
44	VERIFY ERROR	A verification error occurred when modifying memory contents. Writing to ROM was attempted or there was a hardware error. Check the memory area.
45	NOT FOUND	The specified data or information was not found. Correctly specify data.
46	BREAKPOINT ADDRESS	The memory contents of the specified address cannot be modified in parallel mode because the address is used by the BREAK or BREAK_SEQUENCE command.
47	FTP NOT CONNECTED	The command cannot be executed because the FTP interface is not connected. Connect the FTP interface with the FTP command.

Table 10.1 Emulator Error Messages (cont)

Error No.	Error Message	Description and Solution
48	FTP ALREADY CONNECTION	The FTP interface has already been connected. Disconnect the FTP interface and re-enter the command.
49	CONDITION ALREADY USED	The condition cannot be specified because another command has already specified it.
50	RESERVED AREA	A reserved area was accessed.
51	INTERNAL I/O AREA	The internal I/O area was accessed.
52	INTERNAL AREA	An attempt was made to access an area other than CS0 to CS4. This area cannot be accessed with this command. Check the specified address.
54	INVALID CONFIGURATION FILE	The configuration file in emulator flash memory is invalid. Re-install the configuration file from the system disk.
55	CONFIGURATION FILE NOT FOUND	The configuration file was not found in the emulator flash memory. Re-install the configuration file from the system disk.
56	INVALID CONFIGURATION CHECK ERROR	The configuration file in emulator flash memory contains invalid data. Re-install the configuration file from the system disk.
57	ILLEGAL INSTRUCTION ADDRESS	The memory contents of the address specified with the BREAK or BREAK_SEQUENCE command is a break instruction (H'0000). A breakpoint cannot be specified at this address.
58	CANNOT SELECT EMULATOR CLOCK	An operating mode not supported with this emulator was specified. Check the operating mode.
59	TOO MANY CHARACTERS	Too many characters were specified. Check the number of characters.
60	ALL BREAKPOINT DELETED	All software breakpoints specified with the BREAK or BREAK_SEQUENCE command were cancelled.
61	CANNOT GET INTO PARALLEL MODE	The execution mode specified with the GO command prevents the emulator from entering parallel mode. Change the execution mode.
62	LAN BOARD DISCONNECTION	This command cannot be executed because the LAN board is not installed. Install the optional LAN board and re-enter the command.

Table 10.1 Emulator Error Messages (cont)

Error No.	Error Message	Description and Solution
66	BACKGROUND INTERRUPT COMMAND STOPPED	The BACKGROUND_INTERRUPT command execution was terminated.
67	LAN I/O ERROR	A LAN I/O error occurred. Refer to table 10.3.
68	INVALID HOST NAME	The specified host name is not defined in flash memory. Define the host name with the emulator monitor command F (flash memory management tool initiation).
69	OUT OF CS AREA ADDRESS	An attempt was made to allocate emulation memory to an area other than CS0 to CS4. Check the specified address.
71	MAPPING BOUND MUST BE IN 1MB UNITS	Memory was allocated in 1-Mbyte units with the MAP or MOVE_TO_RAM command. For details, refer to the MAP command.
73	BREAK POINT IS DELETED A = xxxxxxxx	A software breakpoint specified at the displayed address was cancelled because the contents of the address were modified with the user program.
74	CANNOT SET A = xxxxxxxx	A breakpoint cannot be specified at the displayed address by the BREAK or BREAK_SEQUENCE command before GO command execution. A hardware error might have occurred or the contents of the memory address might be a break instruction (H'0000). Correct the error, and reload and re-execute the program.
77	ALL BREAKPOINT DELETED	All software breakpoints specified by the BREAK or BREAK_SEQUENCE command were cancelled.
78	EMULATOR BUSY	The emulator was processing a break processing in parallel mode, so another command could not be executed. Re-enter the command. This error occurs when software breakpoints are set with the BREAK or BREAK_SEQUENCE command.
81	TRACE CONDITION RESET	Satisfied trace conditions are all reset when parallel mode is entered. When parallel mode is terminated, the trace conditions are rechecked from the beginning.

Table 10.1 Emulator Error Messages (cont)

Error No.	Error Message	Description and Solution
82	ODD ADDRESS	An instruction was written to an odd address with the ASSEMBLE command. Processing was initiated from the odd address.
83	INVALID OPERAND SIZE	An invalid operand size was specified with the ASSEMBLE command. Processing was performed with the correct size.
84	INVALID ABSOLUTE ADDRESS	An invalid operand address was specified with the ASSEMBLE command. Processing was performed with the maximum address allowed.
86	INTERNAL AREA	An area other than CS0 to CS4 was also to be processed. Processing specified with the MEMORY command is performed normally, but other command processings are performed for only the CS0 to CS4 areas.
87	INTERNAL I/O AREA	The internal I/O area was accessed.
88	RESERVED AREA	A reserved area was accessed.
92	PERFORMANCE ANALYSIS TABLE BUSY	The minimum unit for execution performance measurement cannot be changed during execution time measurement by the PERFORMANCE_ANALYSIS command. Delete the PERFORMANCE_ANALYSIS command setting and change the minimum unit.

Table 10.2 Host I/O Error Codes

Error Code	Description and Solution
D1	Parity error: The parity bit specified with the DIP switch must match the host computer specifications.
D2	Overrun error: The emulator control method is not recognized by the host computer.
D3	Framing error: The baud rate and stop bit specified with the DIP switch must match the host computer specifications.
D4	Load module format error: The load module format of the transferred file is incorrect. Check the file contents.
DC	Timeout error: Check the connection between the emulator and host computer. Also check the operation status of the host computer.

The E8000 system program outputs LAN I/O error messages in the format below. Table 10.3 lists the error messages with brief descriptions.

LAN I/O ERROR (E0xx)
socket library error nn: <error message>

xx: Process in which error occurred (see table 10.4)
nn: Error code
<error message>: Refer to table 10.3

If an error message other than that listed in table 10.3 is displayed, refer to the description for the host computer error messages.

Table 10.3 LAN I/O Error Messages

Error No.	Error Message	Description
01	not listen	The socket cannot be created.
02	Insufficient Buffer	The internal buffer is insufficient.
03	Socket not Support	The requested function is not supported.
04	Socket is Already	The socket has already been connected.
05	time out error	A timeout error has occurred.
06	Ip Address Nothing	The IP address destination is undefined.
07	Not Socket Connection	The socket has not been connected.
08	connection failire	A connection failure has occurred.
09	Illegal IP Address	An illegal IP address has been specified.
10	be Shutdowning	The connection is being terminated.
11	Not Socket Entry	The socket information has not been defined.
12	Socket is already	The socket information has already been defined.
13	HOSTS Name Nothing	The host computer name does not exist.
14	Socket not Assign Connected	The socket cannot be assigned.
15	illegal port No.	The port number is invalid.
16	initialized error	An error has occurred during LAN board initialization.

Table 10.3 LAN I/O Error Messages (cont)

Error No.	Error Message	Description
17	Not Terminate	The LAN board has not been terminated.
18	terminate error	A LAN board termination error has occurred.
19	Not inialized	The LAN board has not been initialized.
20	Illeagal Borad	An error has occurred in the LAN board.
21	System Error	A LAN board system error has occurred.
22	Illegal Request	An invalid request has been issued.
23	Parameter Error	The parameter data is invalid.
24	Response Timeout Happend	A response timeout error has occurred.
25	Check Sum Error	A checksum error has occurred.
26	ICMP Error	An ICMP error has occurred.
27	ethernet address error	An Ethernet address error has occurred.
28	not HOST File	The HOSTS information does not exist.
30	illegal initialized	The HOSTS initialization information is invalid.
31	illegal My data	Main station information is invalid.
32	illega Other Party data	Remote station information is invalid.
33	remote Nothing	Remote station has not been defined.
34	transmission error	A data transfer error has occurred.
35	closing error	A termination error has occurred.
FF	unknown error	An undefined error has occurred.

Table 10.4 Process Code for LAN I/O Error Messages

Error No.	Process
01	Initialization
02	TELNET data transfer
03	TELNET close
04	TELNET open
10	FTP connection
20	File transmission
30	File reception
40	FTP disconnection
50	Directory modification
60	Directory display
70	Current directory display
80	File transfer binary specification
90	File transfer ASCII specification
A0	Forcible termination

10.2 IBM PC Interface Software Error Messages

The IBM PC interface software outputs error messages on the IBM PC. Table 10.5 lists error messages, descriptions of the errors, and error solutions.

Table 10.5 Interface Software Error Messages

Error Message	Description and Solution
INTFC ERROR - ABORT BY BREAK	File transfer has been forcibly terminated by pressing the (BREAK), (STOP), or (CTRL) + C keys.
INTFC ERROR - ALREADY ASSIGNED	The specified command is already being executed. Re-execute the command after command execution has been completed.
INTFC ERROR - EMULATOR NOT READY	The debugger power has been turned off or a cable connected to the debugger has been disconnected. Check that the debugger power is turned on and that cables are connected correctly, and restart. If the same error occurs again, inform a Hitachi sales agency.
INTFC ERROR - ENVIRONMENT NOT SPECIFIED	The specified environment variable name could not be found. Specify the environment variable name with the SET command.
INTFC ERROR - FILE ALREADY EXISTS OVERWRITE ? (Y/N):	The specified IBM PC file already exists. Enter Y to transfer any way after deleting the file; enter N to cancel transfer.
INTFC ERROR - FILE CLOSE ERROR	An error has occurred while closing an IBM PC file.
INTFC ERROR - FILE DELETE ERROR	An error has occurred while deleting an IBM file. Check the specified file name.
INTFC ERROR - FILE NOT FOUND	The IBM PC file specified at load cannot be found or the file name contains an error. Check the specified file name.
INTFC ERROR - FILE OPEN ERROR	The directory to which the specified IBM PC file is to be saved is full or the file name contains an error.
INTFC ERROR - FILE READ ERROR	An error has occurred while reading an IBM PC file.
INTFC ERROR - FILE RENAME ERROR	An error has occurred while changing an IBM PC file name. Check the specified file name.

Table 10.5 Interface Software Error Messages (cont)

Error Message	Description and Solution
INTFC ERROR - FILE WRITE ERROR	An error has occurred while writing to an IBM PC file. The available memory on the disk is insufficient.
INTFC ERROR - INVALID COMMAND	An invalid command has been sent from the debugger.
INTFC ERROR - I/O ERROR	An I/O error has occurred during file transfer. Check the cable connection and the operating environment, and re-transfer the file.
INTFC ERROR - NO INTERFACE BOARD	The interface board is not inserted in the IBM PC expansion slot. Check the DIP switch setting on the interface board and that the interface board is inserted in the expansion slot correctly, and re-transfer. If the same error occurs again, inform a Hitachi sales agency.
INTFC ERROR - STOP COMMAND CHAIN ? (Y/N):	Automatic command input from the IBM PC file has been completed. Enter Y to terminate command input; enter N to continue command input.
INTFC ERROR - SYNTAX ERROR	An error exists in the IBM PC file name. Refer to the debugger and IBM PC manuals and specify a correct file name.
INTFC ERROR - TIMEOUT ERROR	A timeout error has occurred during data transfer from the debugger. Check the cable connection and re-transfer.

Part III Appendices

Appendix A Connectors

A.1 Serial Connector

Figure A.1 shows the serial connector pin alignment in the emulator station. Table A.1 lists signal names and their usage.

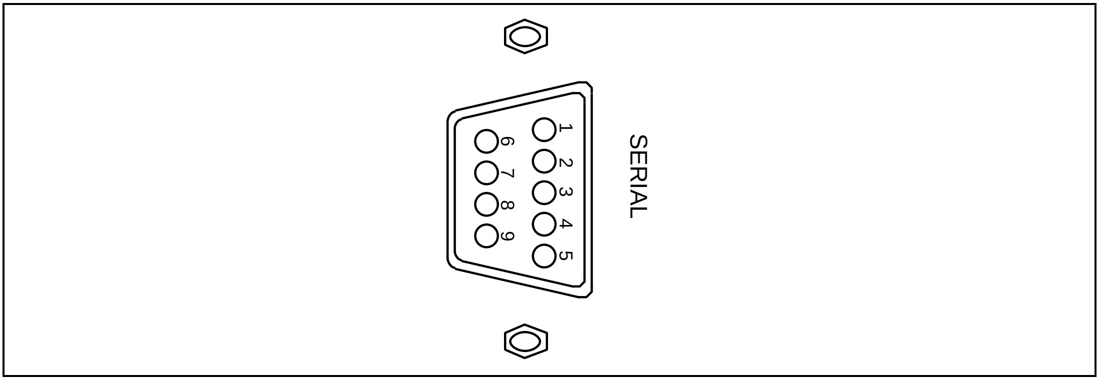


Figure A.1 Serial Connector Pin Alignment at the Emulator Station

Table A.1 Signal Names and Usage of Serial Connector

Pin No.	Signal name	Usage
1	—	Not connected
2	Receive Data (RD)	Data receive line
3	Transmit Data (TD)	Data transmit line
4	Data Terminal Ready (DTR)	High when emulator's power is on.
5	Ground (GND)	Connected to the emulator's frame ground.
6	Data Set Ready (DSR)	Not connected
7	Request To Send (RTS)	High when emulator's power is on.
8	Clear To Send (CTS)	Not connected
9	—	Not connected

A.2 Parallel Connector

Figure A.2 shows the parallel connector pin alignment at the emulator station. Table A.2 lists signal names.

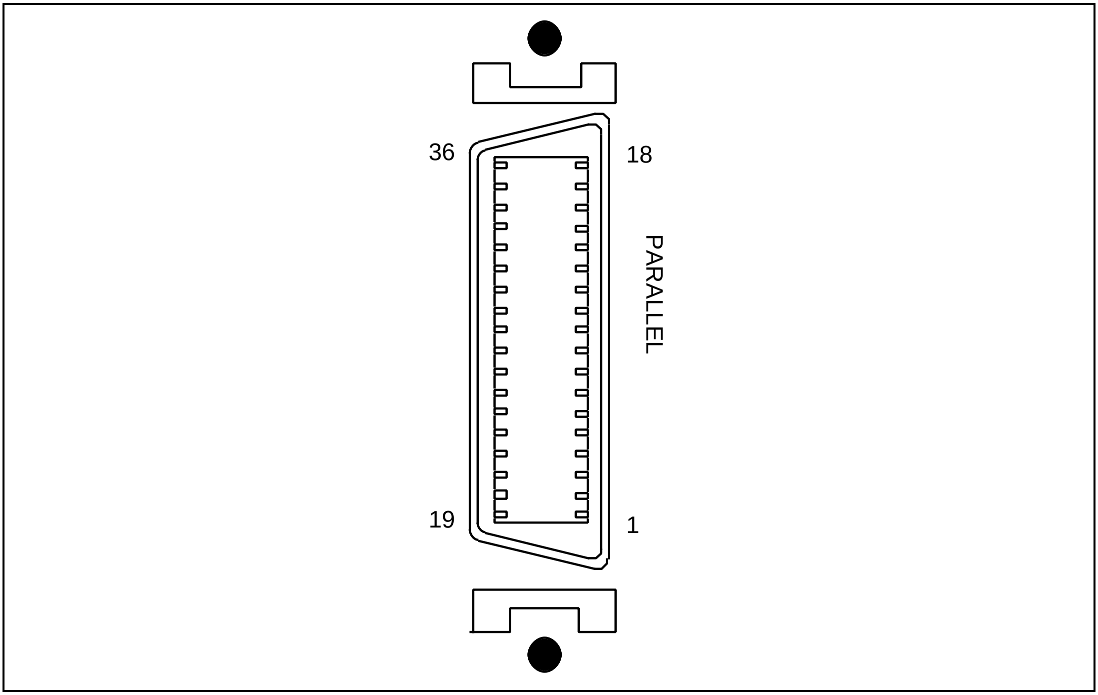


Figure A.2 Parallel Connector Pin Alignment at the Emulator Station

Table A.2 Signal Names of Parallel Connector

Pin No.	Signal Name	Pin No.	Signal Name
1	PeriphAck	19	SignalGround
2	Xflag	20	SignalGround
3	PeriphClk	21	SignalGround
4	nPeriphRequest	22	SignalGround
5	nAckReverse	23	SignalGround
6	Data1 (LSB)	24	SignalGround
7	Data2	25	SignalGround
8	Data3	26	SignalGround
9	Data4	27	SignalGround
10	Data5	28	SignalGround
11	Data6	29	SignalGround
12	Data7	30	SignalGround
13	Data8 (MSB)	31	SignalGround
14	nReverseRequest	32	SignalGround
15	HostClk	33	SignalGround
16	IEEE1284 active	34	SignalGround
17	HostAck	35	SignalGround
18	HostLogicHigh	36	PeripheralLogicHigh

A.3 LAN Connector

Figure A.3 shows the LAN connector pin alignment at the emulator station. Table A.3 lists signal names.

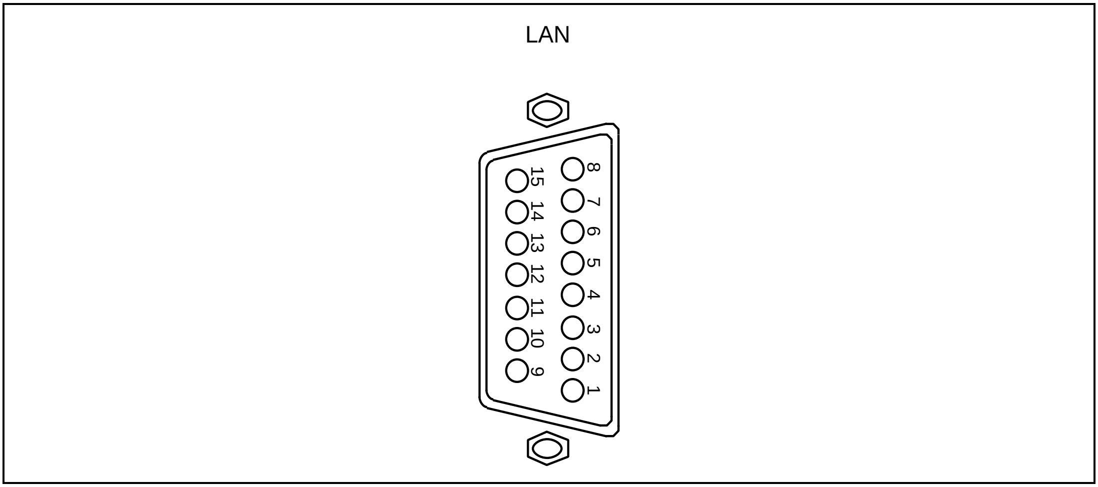


Figure A.3 LAN Connector Pin Alignment at the Emulator Station

Table A.3 Signal Names

Pin No.	Signal Name
1	Not connected
2	COL+
3	TX+
4	—
5	RX+
6	GND
7	—
8	—
9	COL–
10	TX–
11	—
12	RX–
13	+12 V
14	—
15	—

A.4 Serial Interface Cable

Figure A.4 shows the wiring for the serial interface cable.

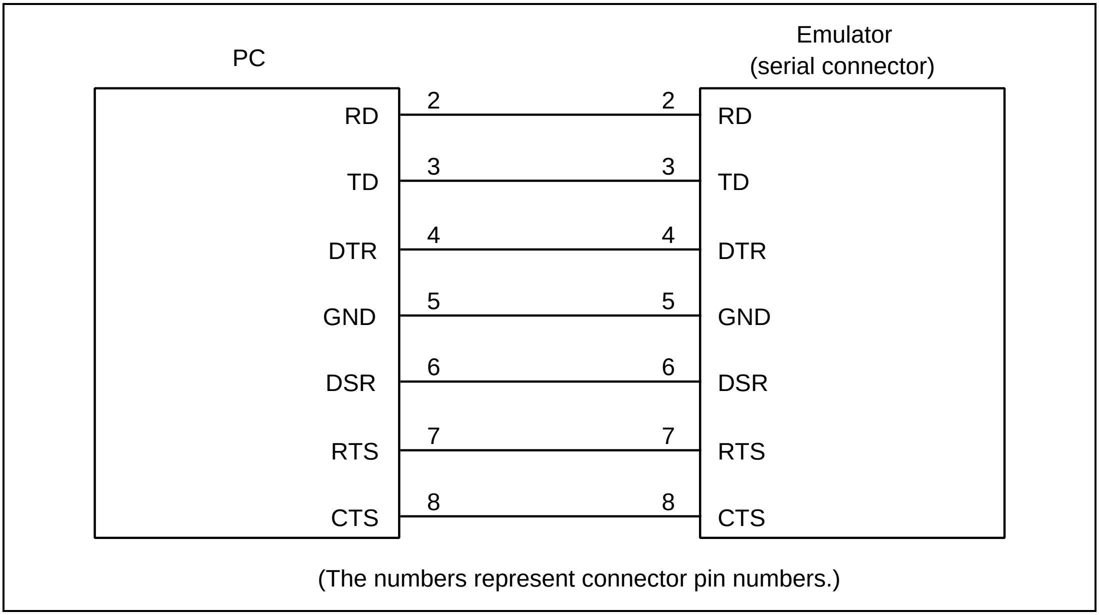
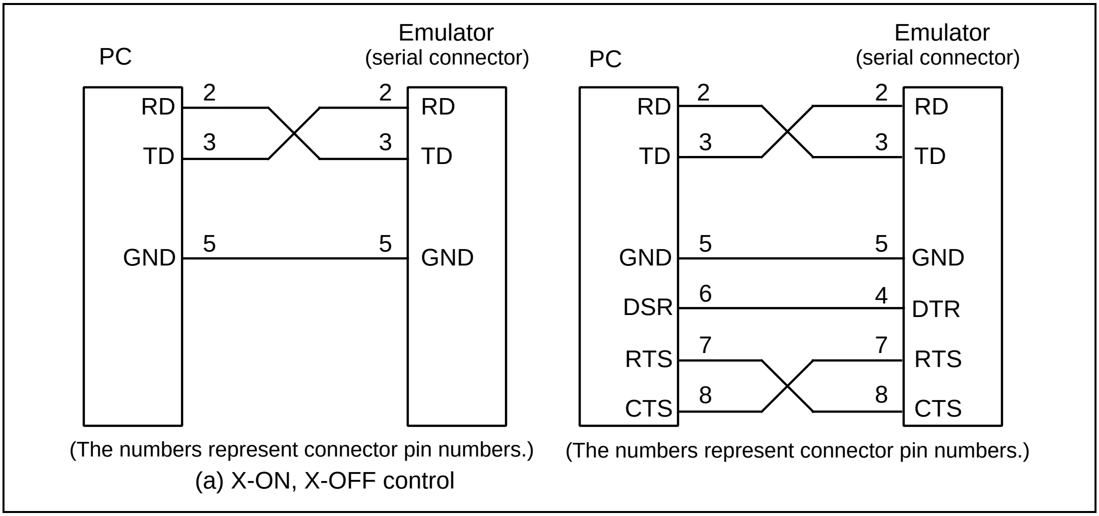


Figure A.4 Serial Interface Cable

Note that the serial interface cable provided may not be suitable for some host computers. In that case, use the wiring shown in figure A.5.

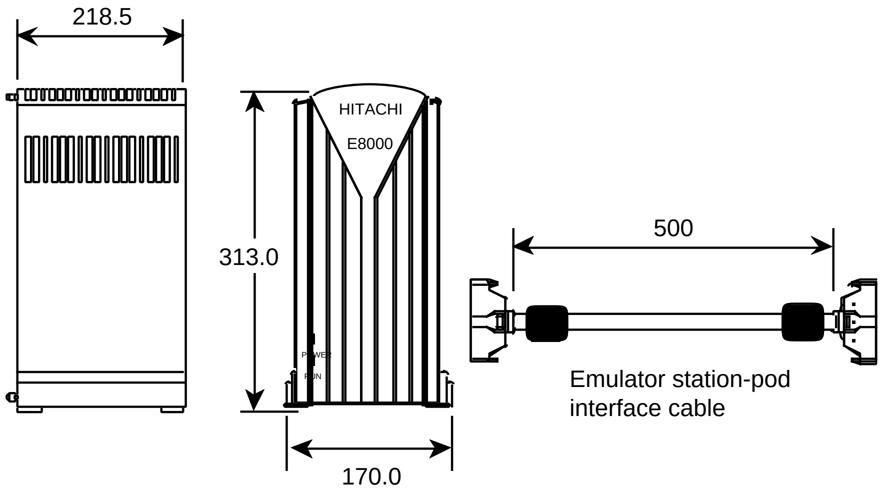


(a) X-ON, X-OFF control

Figure A.5 Serial Interface Cable (Using Other Cables)

Appendix B Emulator External Dimensions and Weight

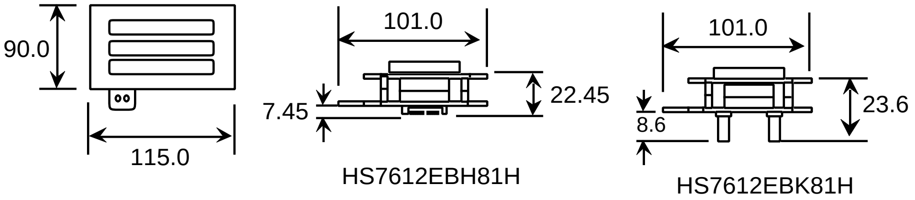
Figures B.1 and B.2 show the external dimensions and weight of the emulator station and EV-chip board, respectively.



Unit: mm

Weight of the emulator station: 5.05 kg

Figure B.1 External Dimensions and Weight of the Emulator Station



Weight of the EV-chip board: HS7612EBH81H: 0.180 kg
HS7612EBK81H: 0.170 kg

Unit: mm

Figure B.2 External Dimensions and Weight of the EV-Chip Board

Appendix C Connecting the Emulator to the User System

C.1 Connecting to the User System

⚠ WARNING

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD, and will damage the user system or emulator or result in PERSONAL INJURY. Also, the USER PROGRAM will be LOST.

The emulator is connected to the user system by using the QFP-type EV-chip board (HS7612EBH81H) or the connector-type EV-chip board (HS7612EBK81H).

Table C.1 EV-Chip Boards and User Interfaces

EV Chip Board	User Interface
HS7612EBH81H	176-pin QFP (NQPACK176SD)
HS7612EBK81H	Specific connector (FX2-100P-1.27SVL) x 2

Note: The NQPACK176SD is manufactured by TOKYO ELETECH CORPORATION.
The FX2-100P-1.27SVL is manufactured by Hirose Electric Co., Ltd.

C.1.1 Connection Using the HS7612EBH81H

⚠ **WARNING**

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD, and will damage the user system or emulator or result in PERSONAL INJURY. Also, the USER PROGRAM will be LOST.

Notes: 1. For more details on the HS7612EBH81H, refer to the user's manual supplied with the EV-chip board.

2. This EV-chip board can only be used in combination with the specific QFP socket (NQPACK176SD).

Mount the 176-pin QFP socket (NQPACK176SD manufactured by TOKYO ELETECH CORPORATION) on the user system to connect the emulator. Pin assignment is the same as for the actual SH7612 chip. Refer to the Pin Assignment in the SH7612 Hardware Manual.

Figure C.1 shows the connection of the HS7612EBH81H, figure C.2 shows the size restriction for the installed components of the HS7612EBH81H, and figure C.3 shows the connector installation location on the user system.

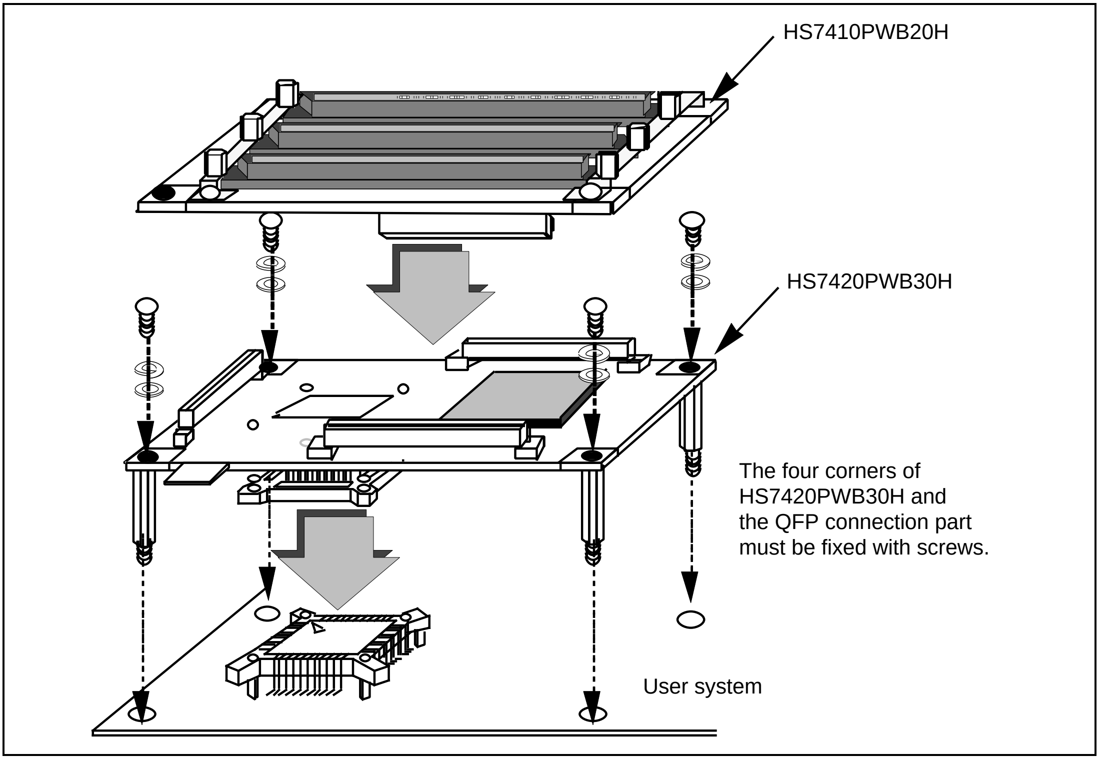


Figure C.1 Connection of the HS7612EBH81H

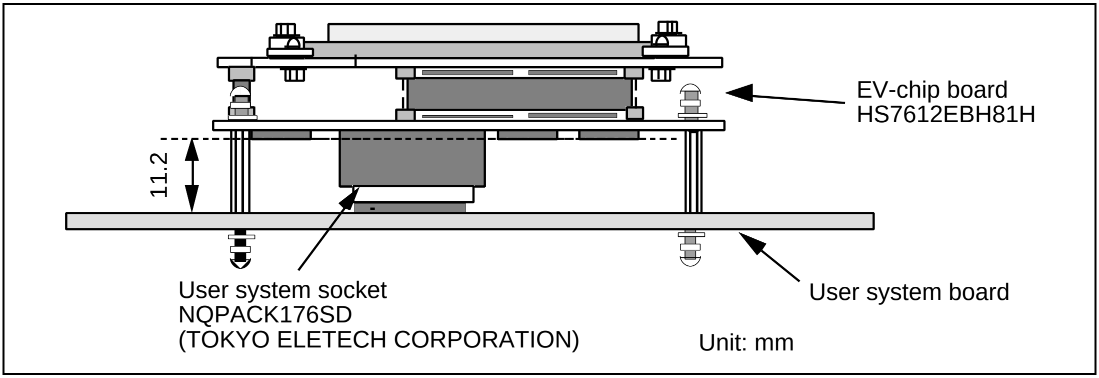


Figure C.2 Component Installation Size Restriction

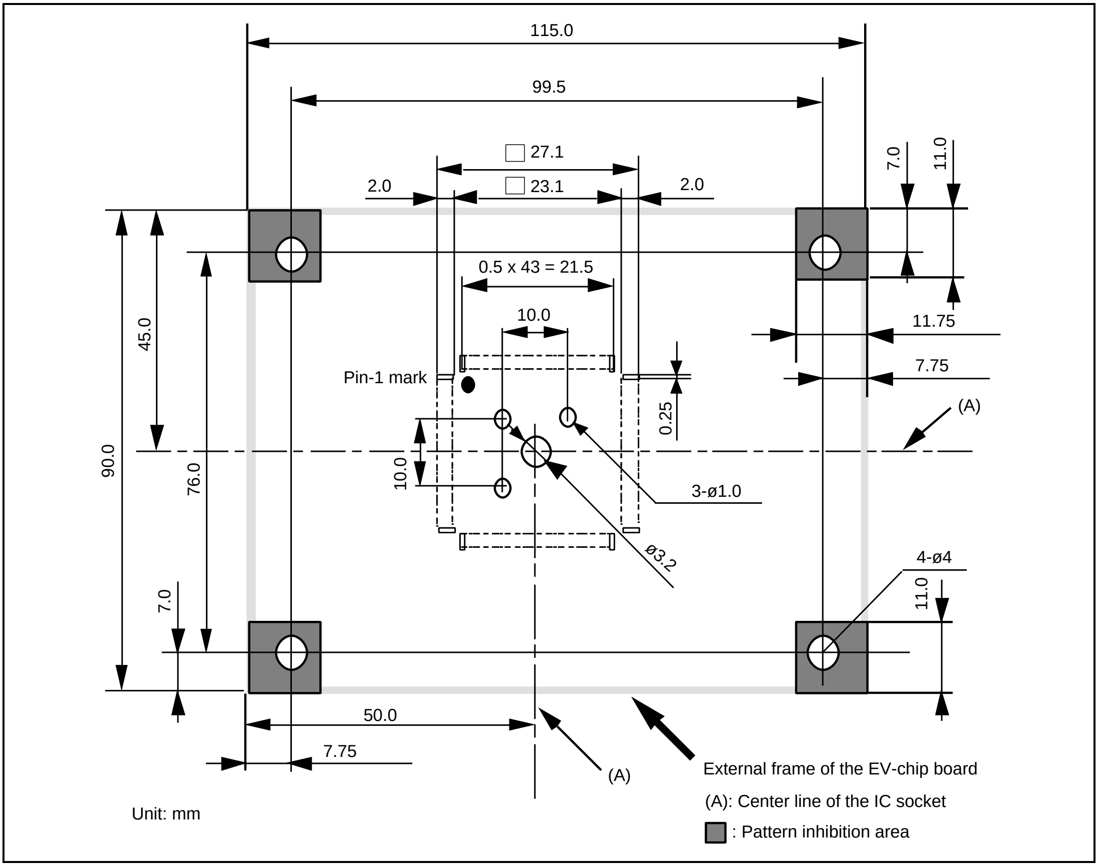


Figure C.3 Connector Installation Location on the User System

C.1.2 Connection Using the HS7612EBK81H

⚠ **WARNING**

Always switch OFF the emulator and user system before connecting or disconnecting any CABLES. Failure to do so will result in a FIRE HAZARD, and will damage the user system or emulator or result in PERSONAL INJURY. Also, the USER PROGRAM will be LOST.

Notes: 1. For more details on the HS7612EBK81H, refer to the user's manual supplied with the EV-chip board.

2. This EV-chip board can only be used in combination with the specified connector (FX2-100P-1.27SVL manufactured by Hirose Electric Co., Ltd.).

Mount the specific connector (FX2-100P-1.27SVL manufactured by Hirose Electric Co., Ltd.) on the user system to connect the emulator.

Figure C.4 shows the connection of the HS7612EBK81H, figure C.5 shows the size restriction for the installed components of the HS7612EBK81H, and figure C.6 shows the connector installation location on the user system.

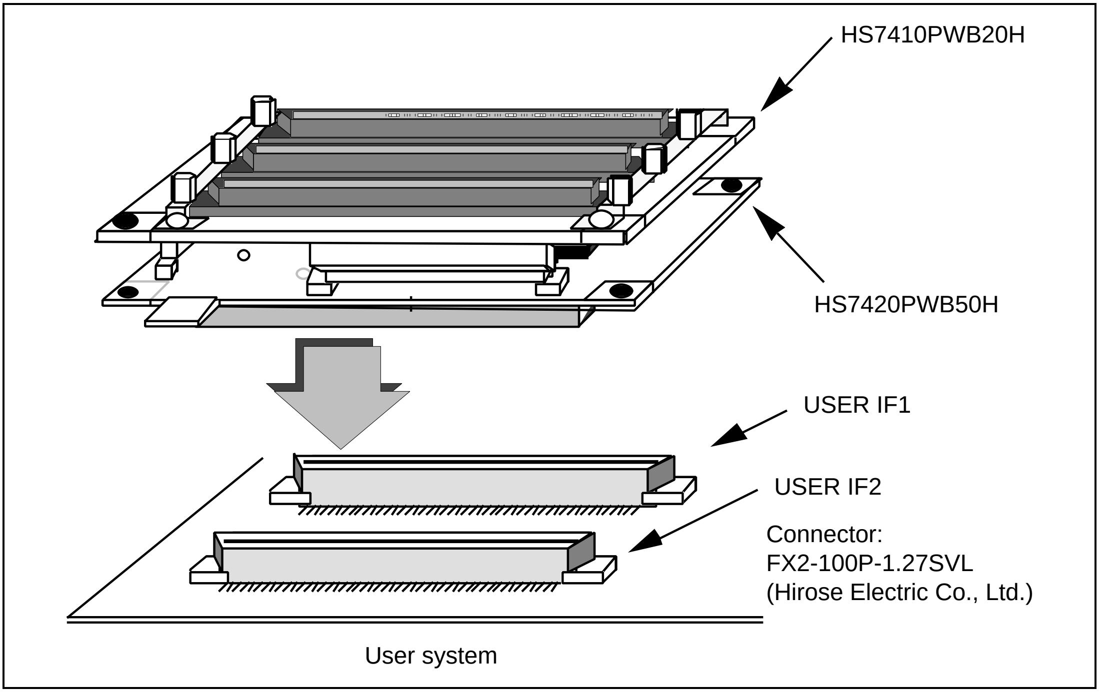


Figure C.4 Connection of the HS7612EBK81H

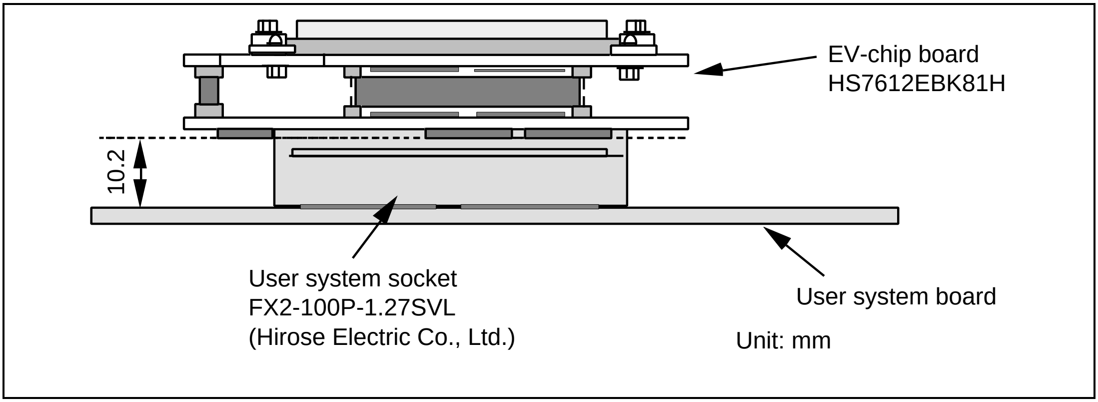


Figure C.5 Component Installation Size Restriction

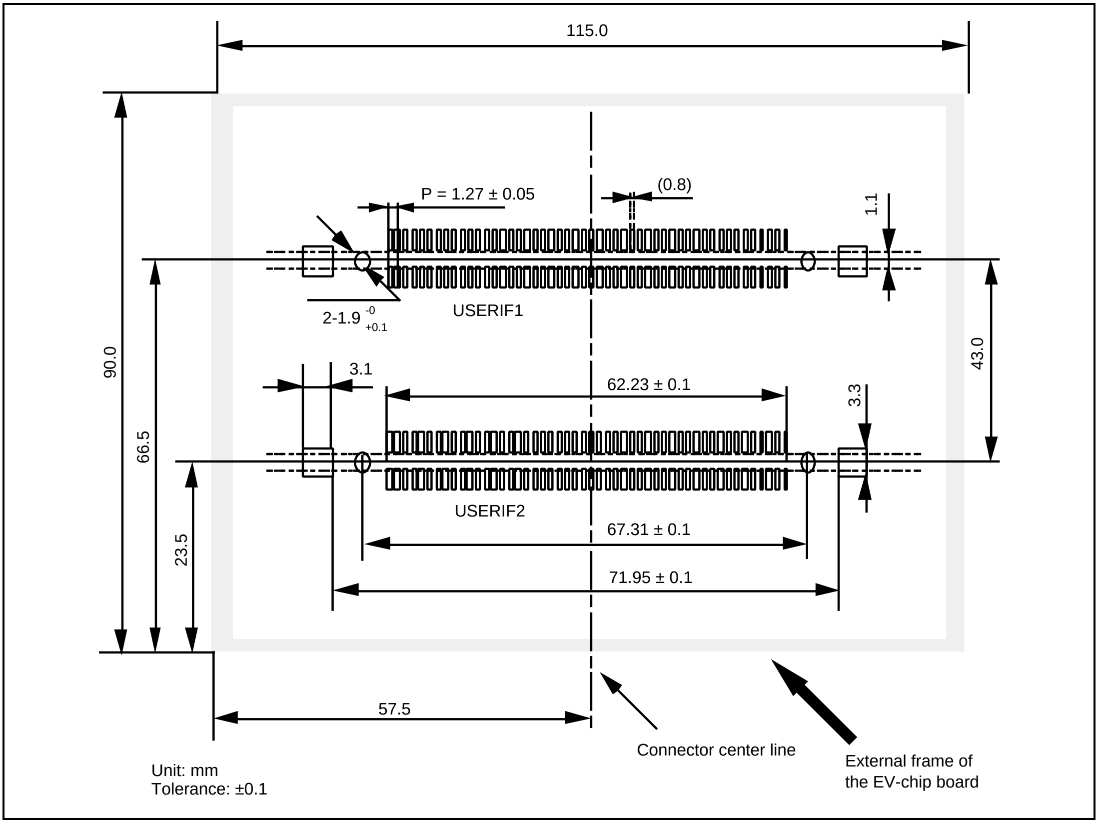


Figure C.6 Connector Installation Location on the User System

C.2 User Interface Pin Assignment

Table C.2 lists the pin assignment of the 176-pin QFP IC socket for the HS7612EBH81H.

Table C.2 Pin Assignment of the HS7612EBH81H

Pin No.	Pin Name	Pin No.	Pin Name	Pin No.	Pin Name
1	NMI	32	D7	63	D30
2	$\overline{\text{RES}}$	33	D8	64	D31
3	VCC *1	34	VCC4	65	$\overline{\text{BGR}}$
4	GND *2	35	D9	66	$\overline{\text{BRLS}}$
5	GND *2	36	GND4	67	DACK0
6	NC	37	D10	68	DACK1
7	NC	38	D11	69	DREQ0
8	GND	39	D12	70	DREQ1
9	MD4	40	D13	71	$\overline{\text{WAIT}}$
10	NC	41	D14	72	$\overline{\text{RAS}}$
11	VCC1	42	VCC5	73	VCC8
12	MD3	43	D15	74	$\overline{\text{CAS}}$/$\overline{\text{OE}}$
13	GND1	44	GND5	75	GND8
14	EXTAL	45	D16	76	DQMUU/$\overline{\text{WE3}}$
15	MD2	46	D17	77	DQMUL/$\overline{\text{WE2}}$
16	NC	47	D18	78	DQMLU/$\overline{\text{WE1}}$
17	GND	48	D19	79	DQMLL/$\overline{\text{WE0}}$
18	CKIO	49	D20	80	$\overline{\text{CAS3}}$
19	VCC2	50	VCC6	81	$\overline{\text{CAS2}}$
20	MD1	51	D21	82	$\overline{\text{CAS1}}$
21	GND2	52	GND6	83	$\overline{\text{CAS0}}$
22	MD0	53	D22	84	CKE
23	D0	54	D23	85	$\overline{\text{RD}}$
24	D1	55	D24	86	VCC9
25	D2	56	D25	87	REFOUT
26	VCC3	57	D26	88	GND9
27	D3	58	VCC7	89	$\overline{\text{BS}}$
28	GND3	59	D27	90	$\overline{\text{CS0}}$
29	D4	60	GND7	91	$\overline{\text{CS1}}$
30	D5	61	D28	92	$\overline{\text{CS2}}$
31	D6	62	D29	93	$\overline{\text{CS3}}$

Table C.2 Pin Assignment of the HS7612EBH81H (cont)

Pin No.	Pin Name	Pin No.	Pin Name	Pin No.	Pin Name
94	$\overline{\text{CS4}}$	122	A18	150	TCK/PA13
95	RD/$\overline{\text{WR}}$	123	A19	151	VCC16
96	A0	124	A20	152	TMS/PA12
97	A1	125	VCC14	153	GND16
98	A2	126	A21	154	TDI/PA11
99	VCC10	127	GND14	155	VCC17
100	A3	128	A22	156	TDO/PA10
101	GND10	129	A23	157	GND17
102	A4	130	A24	158	PA9/STS2
103	A5	131	PB15/SRCK0/SCK2	159	PA8/STXD2
104	A6	132	PB14/SRS0/RXD2	160	$\overline{\text{WDTOVF}}$/PA7
105	A7	133	PB13/SRXD0/TXD2	161	FTCI/PA6
106	A8	134	PB12/STCK0/SCK1	162	FTI/PA5
107	VCC11	135	PB11/STS0/RXD1	163	FTOA/PA4
108	A9	136	PB10/STXD0/TXD1	164	FTOB/CKPO
109	GND11	137	PB9/SRCK1/$\overline{\text{RTS}}$	165	SCK/PA2
110	A10	138	VCC15	166	VCC18
111	VCC12	139	PB8/SRS1/$\overline{\text{CTS}}$	167	RXD/PA1
112	A11	140	GND15	168	GND18
113	GND12	141	PB7/SRXD1/TIOCA2	169	TXD/PA0
114	A12	142	PB6/STCK1/TIOCB2/TCLKD	170	$\overline{\text{IVECF}}$
115	A13	143	PB5/STS1/TIOCA1	171	$\overline{\text{CTPACK}}$
116	A14	144	PB4/STXD1/TIOCB1/TCLKC	172	$\overline{\text{CKPREQ}}$/CKM
117	VCC13	145	PB3/SRCK2/TIOCA0	173	$\overline{\text{IRL3}}$
118	A15	146	PB2/SRS2/TIOCB0	174	$\overline{\text{IRL2}}$
119	GND13	147	PB1/SRXD2/TIOCC0/TCLKA	175	$\overline{\text{IRL1}}$
120	A16	148	PB0/STCK2/TIOCD0/TCLKB	176	$\overline{\text{IRL0}}$
121	A17	149	$\overline{\text{TRST}}$		

Notes: 1. Pay attention to board design so that mode change is enabled with this pin during debugging with the E10 emulator (E10 series).

2. Connect to the ground of the user system. When this pin is connected to the ground, the emulator regards that the emulator is connected to the user system.

Tables C.3 and C.4 list the pin assignment of the 100-pin connector for the HS7612EBK81H.

Table C.3 Pin Assignment of the HS7612EBK81H User Interface (USER I/F1)

Pin No.	Pin Name	Pin No.	Pin Name	Pin No.	Pin Name
1	NC	35	A19	69	GND
2	MD0	36	A18	70	PB0/STCK2/TIOCD0/TCLKB
3	MD1	37	GND	71	PB1/SRXD2/TIOCC0/TCLKA
4	MD2	38	A15	72	PB2/SRS2/TIOCB0
5	$\overline{\text{RES}}$	39	A14	73	PB3/SRCK2/TIOCA0
6	GND	40	GND	74	GND
7	NMI	41	A11	75	PB8/SRS1/$\overline{\text{CTS}}$
8	$\overline{\text{CKPREQ}}$/CKM	42	A10	76	PB9/SRCK1/$\overline{\text{RTS}}$
9	$\overline{\text{CKPACK}}$	43	GND	77	PB10/STXD0/TXD1
10	$\overline{\text{IVECF}}$	44	A7	78	PB11/STS0/RXD1
11	GND	45	A6	79	GND
12	FTOA/PA4	46	GND	80	NC
13	FTI/PA5	47	A3	81	A24
14	FTCI/PA6	48	A2	82	GND
15	$\overline{\text{WDTOVF}}$/PA7	49	GND	83	A21
16	GND	50	(CAP2)NC	84	A20
17	TMS/PA12	51	$\overline{\text{MD3}}$	85	GND
18	TCK/PA13	52	$\overline{\text{MD4}}$	86	A17
19	NC	53	GND *	87	A16
20	$\overline{\text{TRST}}$	54	GND *	88	GND
21	GND	55	$\overline{\text{IRL0}}$	89	A13
22	PB4/STXD1/TIOCB1/TCLKC	56	$\overline{\text{IRL1}}$	90	A12
23	PB5/STS1/TIOCA1	57	$\overline{\text{IRL2}}$	91	GND
24	PB6/STCK1/TIOCB2/TCLKD	58	$\overline{\text{IRL3}}$	92	A9
25	PB7/SRXD/TIOCA2	59	GND	93	A8
26	GND	60	TXD/PA0	94	GND
27	PB12/STCK0/SCK1	61	RXD/PA1	95	A5

Table C.3 Pin Assignment of the HS7612EBK81H User Interface (USER I/F1) (cont)

Pin No.	Pin Name	Pin No.	Pin Name	Pin No.	Pin Name
28	PB13/SRXD0/TXD2	62	SCK/PA2	96	A4
29	PB14/SRS0/RXD2	63	FTOB/CKP0	97	GND
30	PB15/SRCK0/SCK2	64	GND	98	A1
31	GND	65	PA8/STXD2	99	A0
32	A23	66	PA9/STS2	100	GND
33	A22	67	TDO/PA10		
34	GND	68	TDI/PA11		

Note: Connect to the ground of the user system. When this pin is connected to the ground, the emulator regards that the emulator is connected to the user system.

Table C.4 Pin Assignment of the HS7612EBK81H User Interface (USER I/F2)

Pin No.	Pin Name	Pin No.	Pin Name	Pin No.	Pin Name
1	GND	35	$\overline{\text{CAS}}$/$\overline{\text{OE}}$	69	D19
2	EXTAL	36	N.C	70	GND
3	(XTAL)NC	37	GND	71	D22
4	GND	38	CASLH/DQMLU/ WE1N	72	D23
5	D0	39	CASLL/DQMLL/ WE0N	73	GND
6	D1	40	GND	74	D26
7	GND	41	$\overline{\text{CAS1}}$	75	D27
8	D4	42	$\overline{\text{CAS0}}$	76	GND
9	D5	43	GND	77	D30
10	GND	44	REFOUT	78	D31
11	D8	45	$\overline{\text{BS}}$	79	GND
12	D9	46	GND	80	DACK0
13	GND	47	$\overline{\text{CS2}}$	81	DACK1
14	D12	48	$\overline{\text{CS3}}$	82	GND
15	D13	49	GND	83	$\overline{\text{WAIT}}$
16	GND	50	(CAP1)/NC	84	$\overline{\text{RAS}}$
17	D16	51	UVCC	85	GND
18	D17	52	GND	86	CASHH/DQMUU/ WE3N
19	GND	53	N.C	87	CASHL/DQMUL/ WE2N
20	D20	54	CKI0	88	GND
21	D21	55	GND	89	$\overline{\text{CAS3}}$
22	GND	56	D2	90	$\overline{\text{CAS2}}$
23	D24	57	D3	91	GND
24	D25	58	GND	92	CKE
25	GND	59	D6	93	$\overline{\text{RD}}$
26	D28	60	D7	94	GND
27	D29	61	GND	95	$\overline{\text{CS0}}$
28	GND	62	D10	96	$\overline{\text{CS1}}$
29	BGR	63	D11	97	GND

Table C.4 Pin Assignment of the HS7612EBK81H User Interface (USER I/F2) (cont)

Pin No.	Pin Name	Pin No.	Pin Name	Pin No.	Pin Name
30	$\overline{\text{BRLS}}$	64	GND	98	$\overline{\text{CS4}}$
31	GND	65	D14	99	RD/$\overline{\text{WR}}$
32	DREQ0	66	D15	100	GND
33	DREQ1	67	GND		
34	GND	68	D18		

C.3 Precautions for User System Connection

When connecting the EV-chip board to the user system, note the following:

1. Secure the E8000 station location.

   Place the E8000 station and EV-chip board so that the station to EV-chip board interface cable is not bent or twisted, as shown in figure C.7. A bent or twisted cable will impose stress on the user interface, leading to connection or contact failure. Make sure that the emulator station is placed in a secure position so that it does not move and impose stress on the user interface during use.

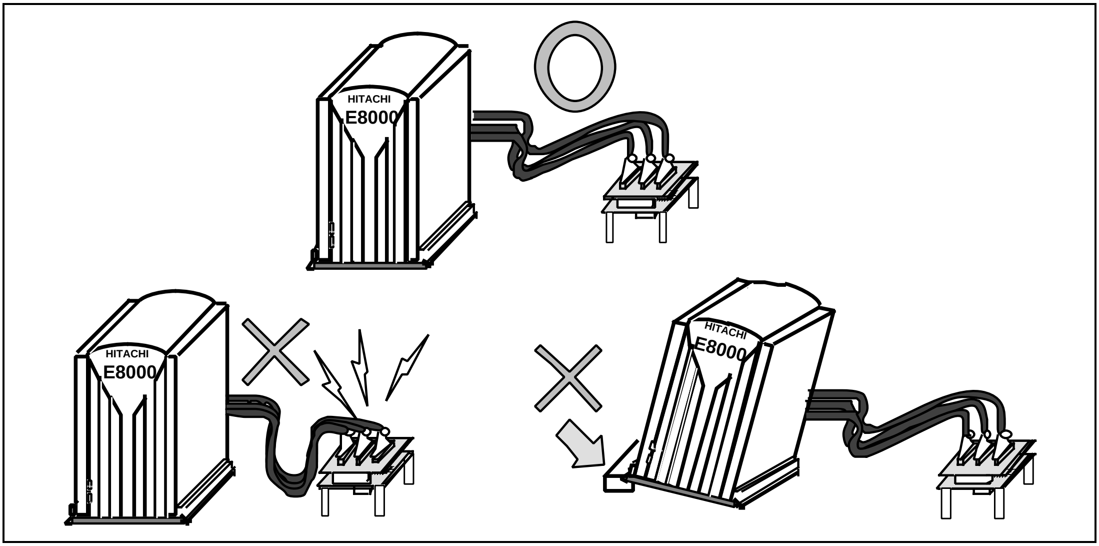


Figure C.7 Examples of Securing the Emulator Station

2. Make sure the power supply is off.

   Before connecting the EV-chip board to the user system, check that the emulator and the user system are off.

3. Connect the Uvcc to the user system power.

   The emulator monitors the Uvcc pin (pins 6, 11, 19, 26, 34, 42, 50, 58, 73, 86, 99, 107, 111, 117, 125, 138, 151, 155, and 166 for HS7612EBH81H, and pin 51 on USER IF2 for HS7612EBK81H) to determine whether the user system is on or off. Accordingly, after connecting the user system to the emulator, be sure to supply power to the Uvcc pin. Otherwise, the emulator assumes that the user system is not connected.

Appendix D Memory Map

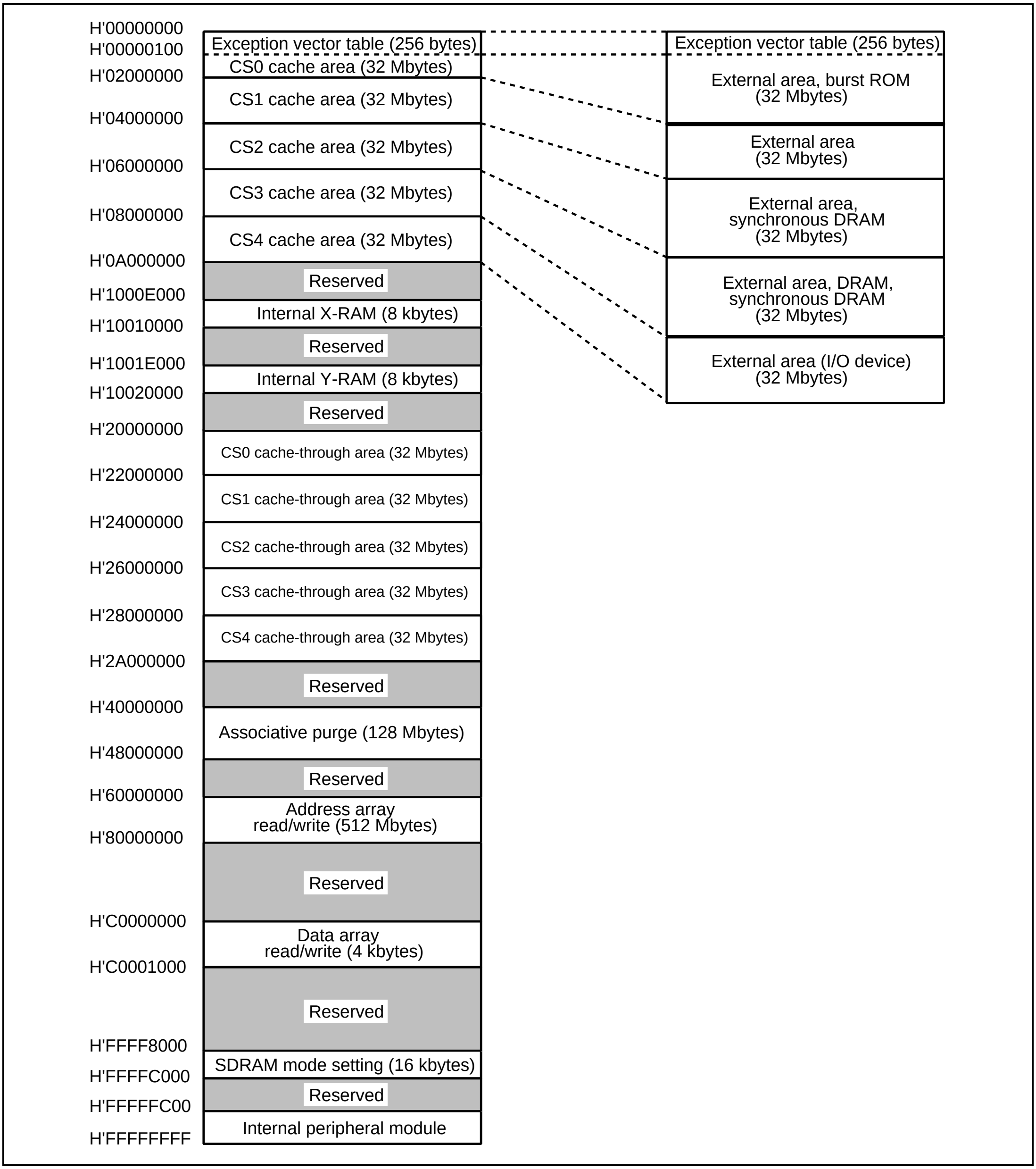


Figure D.1 Memory Map

Appendix E ASCII Codes

Upper four bits Lower four bits	0	1	2	3	4	5	6	7
0	NUL	DLE	SP	0	@	P	`	p
1	SOH	DC1	!	1	A	Q	a	q
2	STX	DC2	"	2	B	R	b	r
3	ETX	DC3	#	3	C	S	c	s
4	EOT	DC4	$	4	D	T	d	t
5	ENQ	NAK	%	5	E	U	e	u
6	ACK	SYN	&	6	F	V	f	v
7	BEL	ETB	'	7	G	W	g	w
8	BS	CAN	(	8	H	X	h	x
9	HT	EM	)	9	I	Y	i	y
A	LF	SUB	*	:	J	Z	j	z
B	VT	ESC	+	;	K	[	k	{
C	FF	FS	,	<	L	\	l	|
D	CR	GS	-	=	M	]	m	}
E	SO	RS	.	>	N	^	n	~
F	SI	US	/	?	O	_	o	DEL

Figure E.1 ASCII Codes

SH7612 E8000 Emulator User’s Manual

Publication Date: 1st Edition, September 2000
Published by: Electronic Devices Sales & Marketing Group
Semiconductor & Integrated Circuits
Hitachi, Ltd.
Edited by: Technical Documentation Group
Hitachi Kodaira Semiconductor Co., Ltd.
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