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April 1st, 2010
Renesas Electronics Corporation

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SH-4A, SH4AL-DSP E200F Emulator

Additional Document for User's Manual
Supplementary Information on Using
the SH7780

Renesas Microcomputer Development
Environment System
SuperH™ Family

E200F for SH7780 R0E877800EMU00E

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Section 1 Connecting the Emulator with the User System

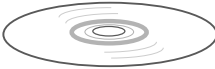
1.1 Components of the Emulator

The E200F emulator supports the SH7780. Table 1.1 lists the components of the emulator.

Table 1.1 Components of the Emulator

Classification	Component	Appearance	Quantity	Remarks
Hardware	Emulator main unit		1	R0E0200F2EMU00: Depth: 185.0 mm, Width: 130.0 mm, Height: 45.0 mm, Mass: 321.0 g
	AC adapter		1	Input: 100 to 240 V Output: 12 V 4.0 A Depth: 120.0 mm, Width: 72.0 mm, Height: 27.0 mm, Mass: 400.0 g 
	AC cable		1	Length: 2000 mm
	USB cable		1	Length: 1500 mm, Mass: 50.6 g
	External probe		1	Length: 500 mm, Pins 1 to 4: probe input pins, T: trigger output pin, G: GND pin

Table 1.1 Components of the Emulator (cont)

Classification	Component	Appearance	Quantity	Remarks
Software	E200F emulator setup program, SH-4A, SH4AL-DSP E200F Emulator User's Manual, Supplementary Information on Using the SH7780*		1	R0E0200F0EMU00S, R0E0200F0EMU00J, R0E0200F0EMU00E, R0E877800EMU00J, R0E877800EMU00E (provided on a CD-R)

Note: Additional document for the MPUs supported by the emulator is included. Check the target MPU and refer to its additional document.

1.2 Connecting the Emulator with the User System

To connect the E200F emulator (hereinafter referred to as the emulator), the H-UDI port connector must be installed on the user system to connect the user system interface cable. When designing the user system, refer to the recommended circuit between the H-UDI port connector and the MPU.

It is impossible to connect this emulator to the 14-pin and 36-pin connectors that are recommended for the E10A-USB emulator. The 38-pin connector has the same specification as the optional 38-pin connector for the E10A-USB emulator. When designing the user system, read the E200F emulator user's manual and the hardware manual for the relevant device.

H-UDI port connectors are of the 38-pin, 36-pin, and 14-pin types described below. Use the 38-pin type with the SH7780 E200F emulator.

1. 38-pin type (with AUD function, and supporting high-density mounting and high-speed operation)

This connector supports high-density mounting and high-speed operation. A large amount of trace information can be acquired in realtime by the AUD trace function. This connector also supports window tracing for the acquisition of memory data in a specified range (accessed addresses and data in memory access).

2. 36-pin type (with AUD function)

The AUD trace function is supported. A large amount of trace information can be acquired in realtime. This connector also supports window tracing for the acquisition of memory data in a specified range (accessed addresses and data in memory access). The 36-pin connector cannot be used for connection of the SH7780 E200F emulator. Instead, this connector is for use with the E10A-USB emulator (with AUD function).

3. 14-pin type (without AUD function)

The AUD trace function cannot be used because only the H-UDI function is supported. This connector cannot be used for connection of the SH7780 E200F emulator. Instead, this connector is for use with the E10A-USB emulator.

1.3 Installing the H-UDI Port Connector on the User System

Table 1.2 shows the recommended H-UDI port connectors for the SH7780 E200F emulator.

Table 1.2 Recommended H-UDI Port Connector

Connector	Type Number	Manufacturer	Specifications
38-pin connector	2-5767004-2	Tyco Electronics AMP K.K.	Mictor type

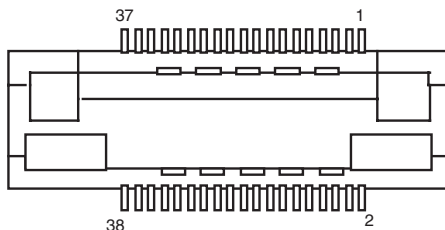
Note: When designing the 38-pin connector layout on the user board, do not place any other signals under the H-UDI connector to reduce cross-talk noises, etc.

1.4 Pin Assignments of the H-UDI Port Connector

Figure 1.1 shows the pin assignments of the 38-pin H-UDI port connector.

Pin No.	Signal	Input/ Output ^{*1}	SH7780 Port 1	Pin No. Port 2	Note	Pin No.	Signal	Input/ Output ^{*1}	SH7780 Port 1	Pin No. Port 2	Note
1	N.C.	—				20	N.C.	—			
2	N.C.	—				21	_TRST ^{*2}	—	D17		←
3	MPMD (GND) ^{*4}	—				22	N.C.	—			
4	N.C.	—				23	N.C.	—			
5	_UCON (GND) ^{*3}	—				24	AUDATA3	—	C18		B16
6	AUDCK	Output	B18		B13	25	N.C.	—			
7	N.C.	—				26	AUDATA2	—	D18		A16
8	_ASEBRK/ BRKACK ^{*2}	Input/ output	C17		←	27	N.C.	—			
9	_RESET ^{*2}	Output	A12		← User reset	28	AUDATA1	—	A19		A15
10	N.C.	—				29	N.C.	—			
11	TDO	Output	B17		←	30	AUDATA0	—	B19		C14
12	UVCC_AUD	Output				31	N.C.	—			
13	N.C.	—				32	AUDSYNC	—	A18		C13
14	UVCC	Output				33	N.C.	—			
15	TCK	Input	C16		←	34	N.C.	—			
16	N.C.	—				35	N.C.	—			
17	TMS	Input	D16		←	36	N.C.	—			
18	N.C.	—				37	N.C.	—			
19	TDI	Input	A17		←	38	N.C.	—			

- Notes: 1. The input or output is based on the target system.
2. The symbol (⌋) means that the signal is active-low.
3. The emulator monitors the GND signal of the user system and detects whether or not the user system is connected.
4. When the user system interface cable is connected to this pin and the MPMD pin is set to 0, do not connect to GND but to the MPMD pin directly.
5. The GND bus leads, which are allocated on the center of the H-UDI port connector, must be connected to GND.



38-pin Mictor connector 2-5767004-2
manufactured by Tyco Electronics AMP K.K.

Figure 1.1 Pin Assignments of the H-UDI Port Connector (38 Pins)

1.5 Recommended Circuit between the H-UDI Port Connector and the MPU

1.5.1 Recommended Circuit (38-Pin Type)

Figure 1.2 shows a recommended circuit for connection between the H-UDI port connector (38 pins) and the MPU when the emulator is in use.

- Notes:
1. Do not connect anything to the N.C. pins of the H-UDI port connector.
 2. The MPMD pin must be 0 when the emulator is connected and 1 when the emulator is not connected, respectively.
 - (1) When the emulator is used: $MPMD = 0$
 - (2) When the emulator is not used: $MPMD = 1$Figure 1.2 shows an example of circuits that allow the MPMD pin to be GND (0) whenever the emulator is connected by using the user system interface cable.
 3. When a network resistance is used for pull-up, it may be affected by a noise. Separate TCK from other resistances.
 4. The /TRST pin must be at the low level for a certain period when the power is supplied regardless of whether the H-UDI is used or not.
 5. The pattern between the H-UDI port connector and the MPU must be as short as possible. Do not connect the signal lines to any other components on the board.
 6. Since the H-UDI and AUD of the MPU operates with the VDDQ (3.3 V) voltage, supply only the VDDQ (3.3 V) voltage to the UVCC pin.
 7. The resistance value shown in figure 1.2 is for reference.
 8. For the pin processing in cases where the emulator is not used, refer to the hardware manual of the related MPU.
 9. For the AUDCK pin, guard the pattern between the H-UDI port connector and the MPU at GND level.

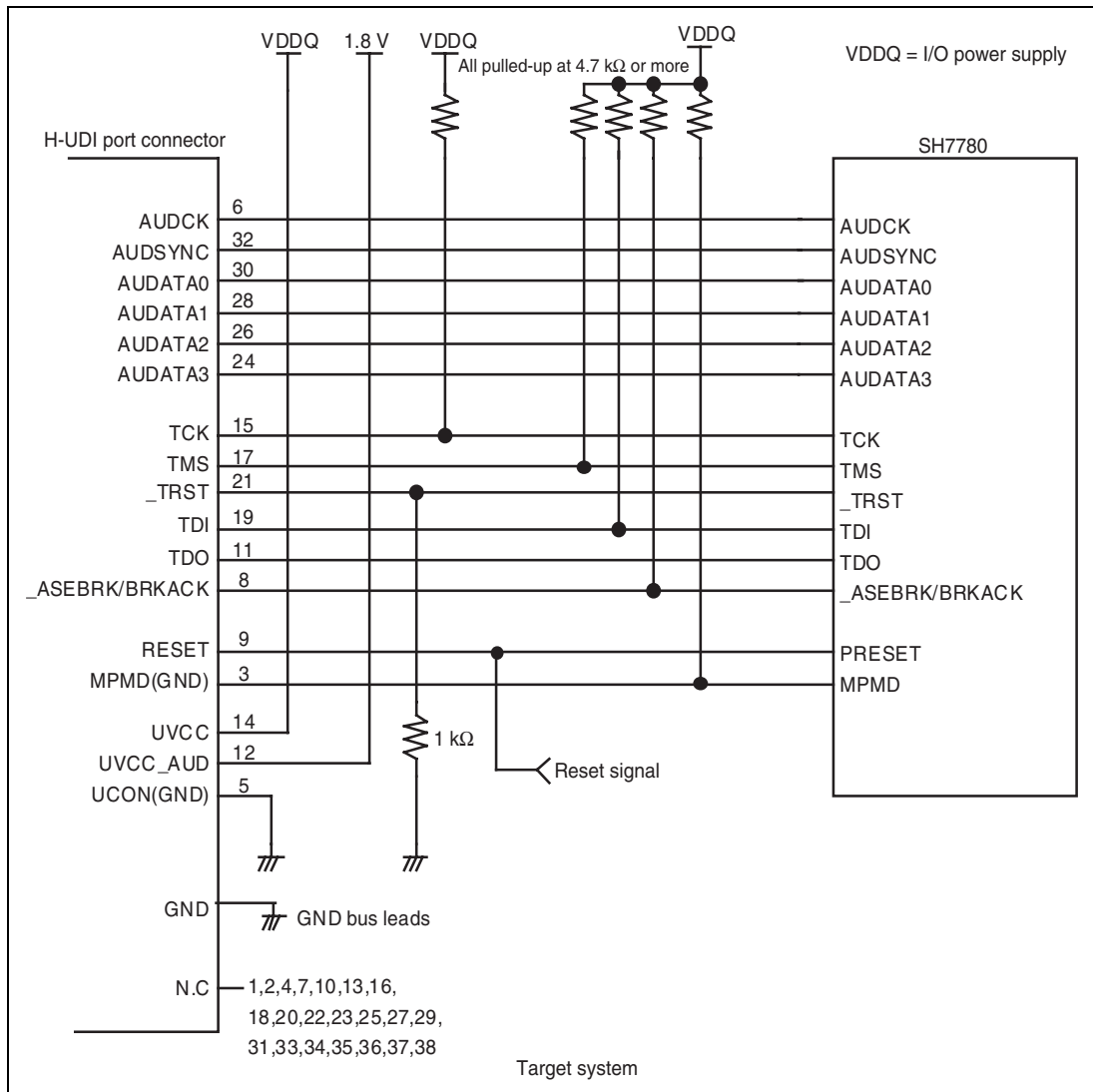


Figure 1.2 Recommended Circuit for Connection between the H-UDI Port Connector and MPU when the SH7780 E200F Emulator is in Use (38-Pin Type)

1.5.2 Restriction on Component Mounting

Components mounted around the user system connector must be no higher than a limit (5 mm). The H-UDI probe connector on the emulator is of the straight (plug) type.

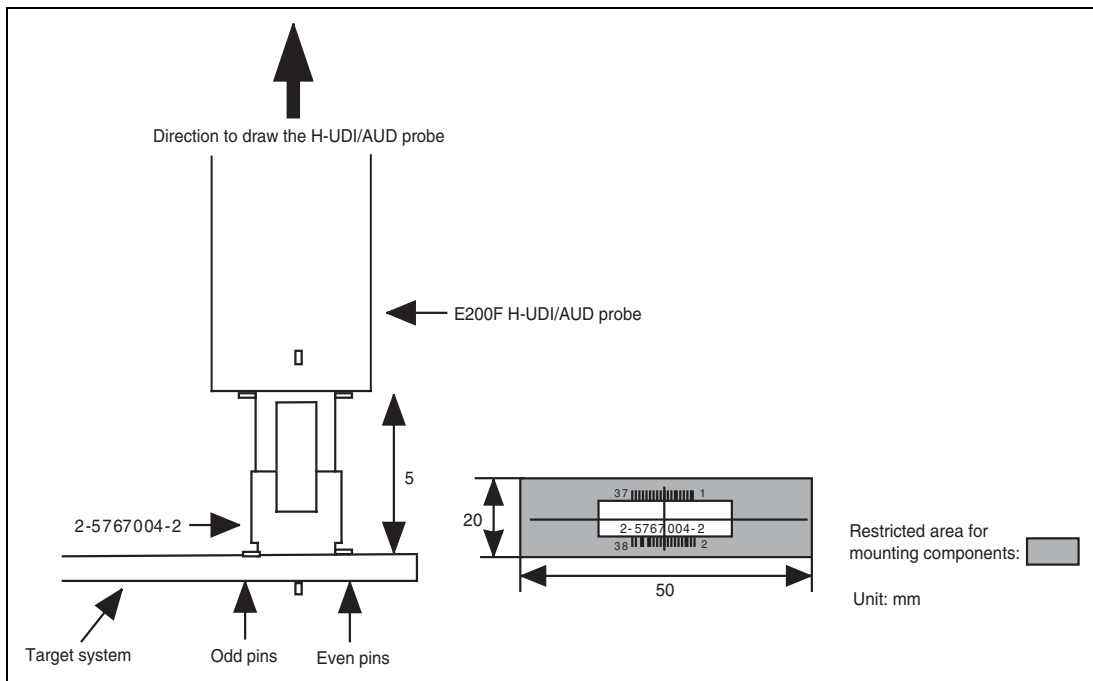


Figure 1.3 Restriction on Component Mounting

Section 2 Software Specifications when Using the SH7780

2.1 Differences between the SH7780 and the Emulator

1. When the emulator system is initiated, it initializes the general registers and part of the control registers as shown in table 2.1. The initial values of the actual SH7780 registers are undefined. When the emulator is initiated from the workspace, a value to be entered is saved in a session.

Table 2.1 Register Initial Values at Emulator Link Up

Register	Emulator at Link Up
R0 to R14	H'00000000
R15 (SP)	H'A0000000
R0_BANK to R7_BANK	H'00000000
PC	H'A0000000
SR	H'700000F0
GBR	H'00000000
VBR	H'00000000
MACH	H'00000000
MACL	H'00000000
PR	H'00000000
DBR	H'00000000
SGR	H'00000000
SPC	H'00000000
SSR	H'000000F0
FPUL	H'00000000
FPSCR	H'00040001
FR0 to FR15	H'00000000
XF0 to XF15	H'00000000

2. The emulator uses the H-UDI; do not access the H-UDI.

3. Low-Power States (Sleep and Module Standby)

For low-power consumption, the SH7780 has sleep and module standby states.

The sleep and module standby states are switched using the SLEEP instruction. When the emulator is used, the sleep state can be cleared with either the normal clearing function or with the [STOP] button, and a break will occur.

Note: The memory must not be accessed or modified in sleep state.

4. Reset Signals

The SH7780 reset signals are only valid during emulation started with clicking the GO or STEP-type button. If these signals are enabled on the user system in command input wait state, they are not sent to the SH7780.

Note: Do not break the user program when the `_PRESET` or `_BREQ` signal is being low and the `WAIT` control signal is being active. A `TIMEOUT` error will occur. If the `WAIT` control signal and the `_BREQ` signal are fixed to active and low during break, respectively, a `TIMEOUT` error will occur at memory access.

5. Direct Memory Access Controller (DMAC)

The DMAC operates even when the emulator is used. When a data transfer request is generated, the DMAC executes DMA transfer.

6. Memory Access during User Program Execution

When a memory is accessed from the memory window, etc. during user program execution, the user program is resumed after it has stopped in the emulator to access the memory.

Therefore, realtime emulation cannot be performed.

The stopping time of the user program is as follows:

Environment:

Host computer: 800 MHz (Pentium® III)

JTAG clock: 30 MHz (TCK clock)

When a one-byte memory is read from the command-line window, the stopping time will be about 45 ms.

7. Memory Access during User Program Break

The emulator can download the program for the flash memory area (for details, refer to section 6.22, Download Function to the Flash Memory Area, in the SH-4A, SH4AL-DSP E200F Emulator User's Manual). Other memory write operations are enabled for the RAM area. Therefore, an operation such as memory write or `BREAKPOINT` should be set only for the RAM area.

8. Cache Operation during User Program Break

When cache is enabled, the emulator accesses the memory by the following methods:

- At memory write: Writes through the cache, then issues a single write to outside. The LRU is not updated.
- At memory read: Reads memory from the cache. The LRU is not updated.

Therefore, when memory read or write is performed during user program break, the cache state does not change.

- At breakpoint set: Disables the instruction cache.

9. Port

The AUD pin is multiplexed as shown in table 2.2.

Table 2.2 Multiplexed Functions

	Function 1	Function 2
Port 1	FALE	AUDCK
	_FCE	AUDSYNC
	FD0	AUDATA0
	FD1	AUDATA1
	FD2	AUDATA2
	FD3	AUDATA3
Port 2	_DRAK2/_CE2A	AUDCK
	_DRAK3/_CE2B	AUDSYNC
	_DREQ2/_INTB	AUDATA0
	_DREQ3/_INTC	AUDATA1
	_DACK2/_MRESETOUT	AUDATA2
	_DACK3/_IRQOUT	AUDATA3

Note: Function 1 can be used when the AUD pins of the device are not connected to the emulator. When the AUD trace is enabled, the emulator changes settings so that function 2 is forcibly used.

10. UBC

When [User] is specified in the [UBC mode] list box in the [Configuration] dialog box, the UBC can be used in the user program.

Do not use the UBC in the user program as it is used by the emulator when [EML] is specified in the [UBC mode] list box in the [Configuration] dialog box.

11. Memory Access during Break

In the enabled MMU, when a memory is accessed and a TLB error occurs during break, it can be selected whether the TLB exception is controlled or the program jumps to the user exception handler in [TLB Mode] in the [Configuration] dialog box. When [TLB miss exception is enable] is selected, a “Communication Timeout error” will occur if the TLB exception handler does not operate correctly. When [TLB miss exception is disable] is selected, the program does not jump to the TLB exception handler even if a TLB exception occurs. Therefore, if the TLB exception handler does not operate correctly, a “Communication Timeout error” will not occur but the memory contents may not be correctly displayed.

12. Loading Sessions

Information in [JTAG clock] of the [Configuration] dialog box cannot be recovered by loading sessions. Thus the TCK value will be 5 MHz.

13. [IO] Window

— Display and modification

Do not change values of the User Break Controller because it is used by the emulator.

For each watchdog timer register, there are two registers to be separately used for write and read operations.

Table 2.3 Watchdog Timer Register

Register Name	Usage	Register
WTCSR(W)	Write	Watchdog timer control/status register
WTCNT(W)	Write	Watchdog timer counter
WTCSR(R)	Read	Watchdog timer control/status register
WTCNT(R)	Read	Watchdog timer counter

- The watchdog timer operates only when the user program is executed. Do not change the value of the frequency change register in the [IO] window or [Memory] window.
- The internal I/O registers can be accessed from the [IO] window. However, note the following when accessing the SDMR register of the bus-state controller. Before accessing the SDMR register, specify addresses to be accessed in the I/O-register definition file (SH7780.IO) and then activate the HEW. After the I/O-register definition file is created, the MPU’s specifications may be changed. If each I/O register in the I/O-register definition file differs from addresses described in the hardware manual, change the I/O-register definition file according to the description in the hardware manual. The I/O-register definition file can be customized depending on its format. Note that, however, the E200F emulator does not support the bit-field function.

— Verify

In the [IO] window, the verify function of the input value is disabled.

14. Illegal Instructions

If illegal instructions are executed by STEP-type commands, the emulator cannot go to the next program counter.

15. [Reset CPU] and [Reset Go] in the [Debug] Menu

When a reset is issued from [Reset CPU] or [Reset Go] in the [Debug] menu, the clock pulse generator or system controller is not initialized.

2.2 Specific Functions for the Emulator when Using the SH7780

In the SH7780, a reset must be input when the emulator is activated.

2.2.1 Notes on Using the Trace Functions

The emulator supports the trace functions listed in table 2.4.

Table 2.4 Trace Functions

Function	Internal Trace	AUD Trace	Memory Output Trace
Branch trace	Supported (eight branches)	Supported	Supported
Range memory access trace	Supported (eight events)	Supported	Supported
Software trace	Supported (eight events)	Supported	Supported

Internal Trace Function: This function is activated by selecting the [Internal trace] radio button in the [Trace type] group box of the [Trace mode] page. Set the trace condition to be used.

Notes: 1. If an interrupt is generated at the program execution start or end, including a step operation, the emulator address may be acquired. In such a case, the following message will be displayed. Ignore this address because it is not a user program address.

*** EML ***

2. If a completion-type exception occurs during exception branch acquisition, the next address to the address in which an exception occurs is acquired.
3. Trace information cannot be acquired for the following branch instructions:
 - The BF and BT instructions whose displacement value is 0
 - Branch to H'A0000000 by reset

AUD Trace Function: This function is operational when the AUD pin of the device is connected to the emulator. It is activated by selecting the [AUD trace] radio button in the [Trace type] group box of the [Trace mode] page.

- Notes: 1. When the trace display is performed during user program execution, the mnemonics, operands, or source is not displayed.
2. The AUD branch trace function outputs the differences between newly output branch source addresses and previously output branch source addresses. The window trace function outputs the differences between newly output addresses and previously output

addresses. If the previously output address is the same as the upper 16 bits, the lower 16 bits are output. If it matches the upper 24 bits, the lower 8 bits are output. If it matches the upper 28 bits, the lower 4 bits are output.

The emulator regenerates the 32-bit address from these differences and displays it in the [Trace] window. If the emulator cannot display the 32-bit address, it displays the difference from the previously displayed 32-bit address.

3. If the 32-bit address cannot be displayed, the source line is not displayed.
4. In the emulator, when multiple loops are performed to reduce the number of AUD trace displays, only the IP counts up.
5. In the emulator, the maximum number of trace displays is 524288 lines. However, the maximum number of trace displays differs according to the AUD trace information to be output. Therefore, the above pointers cannot be always acquired.
6. The AUD trace acquisition is not available when [User] is selected in the [UBC mode] list box of the [Configuration] dialog box. In this case, close the [Trace] window.
7. If a completion-type exception occurs during exception branch acquisition, the next address to the address in which an exception occurs is acquired.

Memory Output Trace Functions: This function is activated by selecting the [Use Memory trace] radio button in the [Trace type] group box of the [Trace mode] page.

In this function, write the trace data in the specified user memory range.

Specify the start address to output a trace for the [Start] edit box in the [User memory area] group box, and the end address for the [End Address] edit box.

- Notes:
1. The memory range for which trace is output is the address on the system bus and not supported for the MMU or cache.
 2. In the memory range for output, do not specify the ranges that the user program has been downloaded or the user program accesses.
 3. The range for trace output must be 1 MB or less.

2.2.2 Notes on Using the JTAG (H-UDI) Clock (TCK) and AUD Clock (AUDCK)

1. Set the JTAG clock (TCK) frequency to lower than the frequency of the SH7780 peripheral module clock (CKP).
2. Set the AUD clock (AUDCK) frequency to 100 MHz or lower. If the frequency is higher than 100 MHz, the emulator will not operate normally.
3. The set value of the JTAG clock (TCK) is initialized by executing [Reset CPU] or [Reset Go].

2.2.3 Notes on Setting the [Breakpoint] Dialog Box

1. When an odd address is set, the next lowest even address is used.
2. A BREAKPOINT is accomplished by replacing instructions of the specified address. Accordingly, it can be set only to the internal RAM area. However, a BREAKPOINT cannot be set to the following addresses:
 - ROM areas in CS0 to CS6
 - Areas other than CS0 to CS6
 - Areas other than the internal RAM
 - A slot instruction of a delayed branch instruction
 - An area that can be only read by MMU
3. During step operation, BREAKPOINTS are disabled.
4. When execution resumes from the address where a BREAKPOINT is specified, single-step operation is performed at the address and execution is continued from the next PC value. Therefore, realtime operation cannot be performed.
5. When a BREAKPOINT is set to the slot instruction of a delayed branch instruction, the PC value becomes an illegal value. Accordingly, do not set a BREAKPOINT to the slot instruction of a delayed branch instruction.
6. Note on DSP repeat loop:

A BREAKPOINT is equal to a branch instruction. In some DSP repeat loops, branch instructions cannot be set. For these cases, do not set BREAKPOINTS. Refer to the hardware manual for details.
7. When the [Normal] option is selected in the [Memory area] group box in the [General] page of the [Configuration] dialog box, a BREAKPOINT is set to a physical address or a virtual address according to the SH7780 MMU status during command input when the VPMAP_SET command setting is disabled. The ASID value of the SH7780 PTEH register during command input is used. When VPMAP_SET command setting is enabled, a BREAKPOINT is set to a physical address into which address translation is made according to the VP_MAP table. However, for addresses out of the range of the VP_MAP table, the address to which a BREAKPOINT is set depends on the SH7780 MMU status during command input. Even when the VP_MAP table is modified after BREAKPOINT setting, the address translated when the BREAKPOINT is set valid.
8. When the [Physical] option is selected in the [Memory area] group box in the [General] page of the [Configuration] dialog box, a BREAKPOINT is set to a physical address. A BREAKPOINT is set after disabling the SH7780 MMU upon program execution. After setting, the MMU is returned to the original state. When a break occurs at the corresponding virtual address, the cause of termination displayed in the status bar and the [Output] window is ILLEGAL INSTRUCTION, not BREAKPOINT.

9. When the [Virtual] option is selected in the [Memory area] group box in the [General] page of the [Configuration] dialog box, a BREAKPOINT is set to a virtual address. A BREAKPOINT is set after enabling the SH7780 MMU upon program execution. After setting, the MMU is returned to the original state. When an ASID value is specified, the BREAKPOINT is set to the virtual address corresponding to the ASID value. The emulator sets the BREAKPOINT after rewriting the ASID value to the specified value, and returns the ASID value to its original value after setting. When no ASID value is specified, the BREAKPOINT is set to a virtual address corresponding to the ASID value at command input.
10. An address (physical address) to which a BREAKPOINT is set is determined when the BREAKPOINT is set. Accordingly, even if the VP_MAP table is modified after BREAKPOINT setting, the BREAKPOINT address remains unchanged. When a BREAKPOINT is satisfied with the modified address in the VP_MAP table, the cause of termination displayed in the status bar and the [Output] window is ILLEGAL INSTRUCTION, not BREAKPOINT.
11. If an address of a BREAKPOINT cannot be correctly set in the ROM or flash memory area, a mark ● will be displayed in the [BP] area of the address on the [Source] or [Disassembly] window by refreshing the [Memory] window, etc. after Go execution. However, no break will occur at this address. When the program halts with the event condition, the mark ● disappears.

2.2.4 Notes on Setting the [Event Condition] Dialog Box and the BREAKCONDITION_SET Command

1. When [Go to cursor], [Step In], [Step Over], or [Step Out] is selected, the settings of Event Condition 3 are disabled.
2. When an Event Condition is satisfied, emulation may stop after two or more instructions have been executed.
3. If a PC break address condition is set to the slot instruction after a delayed branch instruction, user program execution cannot be terminated before the slot instruction execution; execution stops before the branch destination instruction.

2.2.5 Note on Setting the UBC_MODE Command

In the [Configuration] dialog box, if [User] is set while the [UBC mode] list box has been set, Ch10 (IA_OA_R) and Ch11 (OA_OA_CT_R) of Event Condition cannot be used.

2.2.6 Note on Setting the PPC_MODE Command

In the [Configuration] dialog box, if [User] is set while the [PPC mode] list box has been set, Ch1 and Ch2 of the performance analysis function and options 1 and 2 of the profile function cannot be used.

Section 3 Preparing to Connect the Trace Unit

3.1 Connecting the E200F Trace Unit with the User System

To use the external bus trace function in the emulator, the emulator and the user system must be connected via the external bus trace unit (R0E0200F0ETU00). Install the trace unit connector on the user system for connection of the trace unit, referring to section 3.2, Installing the Trace Unit Connector, in this manual. When designing the user system, read the SH-4A, SH4AL-DSP E200F Emulator User's Manual and hardware manual for the related MPU.

3.2 Installing the Trace Unit Connector

3.2.1 Trace Unit Connector Installed on the User System

Table 3.1 shows the recommended trace unit connector.

Table 3.1 Recommended Connector

Type Number	Manufacturer	Specification
QTH-090-04-L-D-A	Samtec, Inc.	QTH series, 0.5-mm pitch, 180 pins

Note: To connect the connector on the trace unit, do not place any components within 6 mm of the trace unit connector.

3.2.2 Pin Assignments of the User System Connector

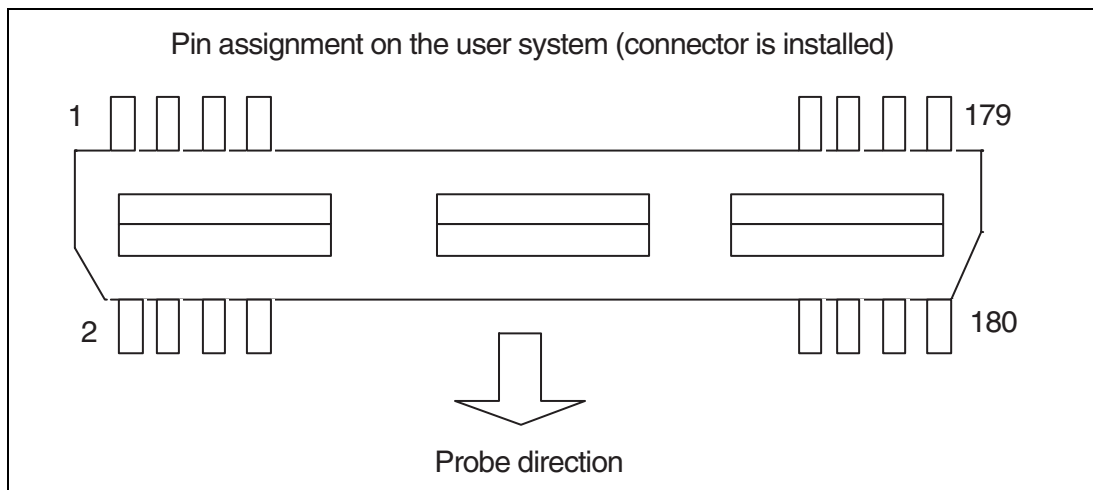


Figure 3.1 Pin Assignments of the User System Connector

3.2.3 Recommended Foot Pattern

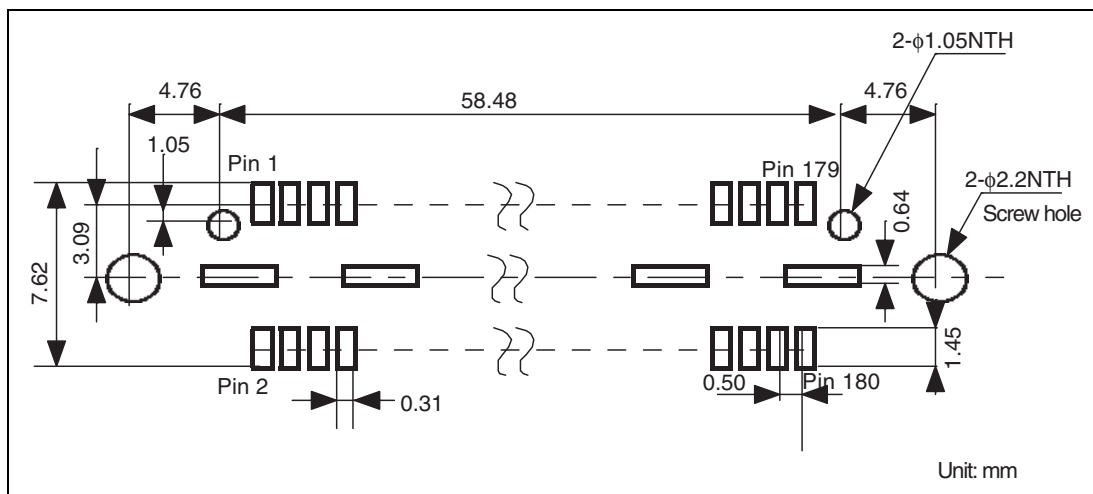


Figure 3.2 Recommended Foot Pattern (on which the Connector is Installed)

3.2.4 Restrictions on Component Installation

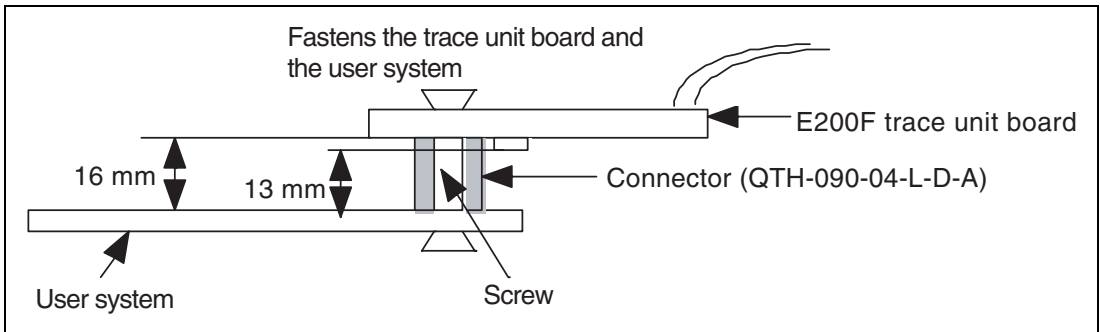


Figure 3.3 Restrictions on Component Installation

3.2.5 Pin Assignments of the Trace Unit Connector

Table 3.2 shows the pin assignments of the trace unit connector.

Table 3.2 Pin Assignments of the Trace Unit Connector

Connector in the user system: QTH-090-04-L-D-A; Samtec (180 pins)

Pin No.	I/O	Connector Pin Name	SH7780 Signal Name	Meaning of Signal	Note
1	I	UA-P0	A0	Address bus A0	
2	I	UA-P1	A1	Address bus A1	
3	I	UA-P2	A2	Address bus A2	
4	I	UA-P3	A3	Address bus A3	
5	I	UA-P4	A4	Address bus A4	
6	I	UA-P5	A5	Address bus A5	
7	I	UA-P6	A6	Address bus A6	
8	I	UA-P7	A7	Address bus A7	
9	I	GND	GND	GND	
10	I	GND	GND	GND	
11	I	UA-P8	A8	Address bus A8	
12	I	UA-P9	A9	Address bus A9	
13	I	UA-P10	A10	Address bus A10	
14	I	UA-P11	A11	Address bus A11	
15	I	UA-P12	A12	Address bus A12	
16	I	UA-P13	A13	Address bus A13	
17	I	UA-P14	A14	Address bus A14	
18	I	UA-P15	A15	Address bus A15	
19	I	GND	GND	GND	
20	I	GND	GND	GND	
21	I	UA-P16	A16	Address bus A16	
22	I	UA-P17	A17	Address bus A17	
23	I	UA-P18	A18	Address bus A18	
24	I	UA-P19	A19	Address bus A19	
25	I	UA-P20	A20	Address bus A20	
26	I	UA-P21	A21	Address bus A21	
27	I	UA-P22	A22	Address bus A22	

Table 3.2 Pin Assignments of the Trace Unit Connector (cont)

Connector in the user system: QTH-090-04-L-D-A; Samtec (180 pins)

Pin No.	I/O	Connector Pin Name	SH7780 Signal Name	Meaning of Signal	Note
28	I	UA-P23	A23	Address bus A23	
29	I	GND	GND	GND	
30	I	GND	GND	GND	
31	I	UA-P24	A24	Address bus A24	
32	I	UA-P25	A25	Address bus A25	
33	I	UA-P26	GND	GND	
34	I	UA-P27	GND	GND	
35	I	UA-P28	GND	GND	
36	I	UA-P29	GND	GND	
37	I	UA-P30	GND	GND	
38	I	UA-P31	GND	GND	
39	I	GND	GND	GND	
40	I	GND	GND	GND	
41	IO	UD-P0	D0	Data bus D0	
42	IO	UD-P1	D1	Data bus D1	
43	IO	UD-P2	D2	Data bus D2	
44	IO	UD-P3	D3	Data bus D3	
45	IO	UD-P4	D4	Data bus D4	
46	IO	UD-P5	D5	Data bus D5	
47	IO	UD-P6	D6	Data bus D6	
48	IO	UD-P7	D7	Data bus D7	
49	I	GND	GND	GND	
50	I	GND	GND	GND	
51	IO	UD-P8	D8	Data bus D8	
52	IO	UD-P9	D9	Data bus D9	
53	IO	UD-P10	D10	Data bus D10	
54	IO	UD-P11	D11	Data bus D11	

Table 3.2 Pin Assignments of the Trace Unit Connector (cont)

Connector in the user system: QTH-090-04-L-D-A; Samtec (180 pins)

Pin No.	I/O	Connector Pin Name	SH7780 Signal Name	Meaning of Signal	Note
55	IO	UD-P12	D12	Data bus D12	
56	IO	UD-P13	D13	Data bus D13	
57	IO	UD-P14	D14	Data bus D14	
58	IO	UD-P15	D15	Data bus D15	
59	I	GND	GND	GND	
60	I	GND	GND	GND	
61	IO	UD-P16	D16	Data bus D16	
62	IO	UD-P17	D17	Data bus D17	
63	IO	UD-P18	D18	Data bus D18	
64	IO	UD-P19	D19	Data bus D19	
65	IO	UD-P20	D20	Data bus D20	
66	IO	UD-P21	D21	Data bus D21	
67	IO	UD-P22	D22	Data bus D22	
68	IO	UD-P23	D23	Data bus D23	
69	I	GND	GND	GND	
70	I	GND	GND	GND	
71	IO	UD-P24	D24	Data bus D24	
72	IO	UD-P25	D25	Data bus D25	
73	IO	UD-P26	D26	Data bus D26	
74	IO	UD-P27	D27	Data bus D27	
75	IO	UD-P28	D28	Data bus D28	
76	IO	UD-P29	D29	Data bus D29	
77	IO	UD-P30	D30	Data bus D30	
78	IO	UD-P31	D31	Data bus D31	
79	I	GND	GND	GND	
80	I	GND	GND	GND	
81	IO	UD-P32	N.C. ¹⁾	Not connected	

Table 3.2 Pin Assignments of the Trace Unit Connector (cont)

Connector in the user system: QTH-090-04-L-D-A; Samtec (180 pins)

Pin No.	I/O	Connector Pin Name	SH7780 Signal Name	Meaning of Signal	Note
82	IO	UD-P33	N.C. ^{†1}	Not connected	
83	IO	UD-P34	N.C. ^{†1}	Not connected	
84	IO	UD-P35	N.C. ^{†1}	Not connected	
85	IO	UD-P36	N.C. ^{†1}	Not connected	
86	IO	UD-P37	N.C. ^{†1}	Not connected	
87	IO	UD-P38	N.C. ^{†1}	Not connected	
88	IO	UD-P39	N.C. ^{†1}	Not connected	
89	I	GND	GND	GND	
90	I	GND	GND	GND	
91	IO	UD-P40	N.C. ^{†1}	Not connected	
92	IO	UD-P41	N.C. ^{†1}	Not connected	
93	IO	UD-P42	N.C. ^{†1}	Not connected	
94	IO	UD-P43	N.C. ^{†1}	Not connected	
95	IO	UD-P44	N.C. ^{†1}	Not connected	
96	IO	UD-P45	N.C. ^{†1}	Not connected	
97	IO	UD-P46	N.C. ^{†1}	Not connected	
98	IO	UD-P47	N.C. ^{†1}	Not connected	
99	I	GND	GND	GND	
100	I	GND	GND	GND	
101	IO	UD-P48	N.C. ^{†1}	Not connected	
102	IO	UD-P49	N.C. ^{†1}	Not connected	
103	IO	UD-P50	N.C. ^{†1}	Not connected	
104	IO	UD-P51	N.C. ^{†1}	Not connected	
105	IO	UD-P52	N.C. ^{†1}	Not connected	
106	IO	UD-P53	N.C. ^{†1}	Not connected	
107	IO	UD-P54	N.C. ^{†1}	Not connected	
108	IO	UD-P55	N.C. ^{†1}	Not connected	

Table 3.2 Pin Assignments of the Trace Unit Connector (cont)

Connector in the user system: QTH-090-04-L-D-A; Samtec (180 pins)

Pin No.	I/O	Connector Pin Name	SH7780 Signal Name	Meaning of Signal	Note
109	I	GND	GND	GND	
110	I	GND	GND	GND	
111	IO	UD-P56	N.C. ¹⁾	Not connected	
112	IO	UD-P57	N.C. ¹⁾	Not connected	
113	IO	UD-P58	N.C. ¹⁾	Not connected	
114	IO	UD-P59	N.C. ¹⁾	Not connected	
115	IO	UD-P60	N.C. ¹⁾	Not connected	
116	IO	UD-P61	N.C. ¹⁾	Not connected	
117	IO	UD-P62	N.C. ¹⁾	Not connected	
118	IO	UD-P63	N.C. ¹⁾	Not connected	
119	I	GND	GND	GND	
120	I	GND	GND	GND	
121	I	UCONT-P0	_WE0/_REG	Write enable 0/ PCMCIA REG	
122	I	UCONT-P1	_WE1	Write enable 1	
123	I	UCONT-P2	_WE2/_IORD	Write enable 2/ PCMCIA IORD	
124	I	UCONT-P3	_WE3/_IOWR	Write enable 3/ PCMCIA IOWR	
125	I	UCONT-P4	R/_W	Read/write	
126	I	UCONT-P5	_RD/_FRAME	Read	
127	I	UCONT-P6	_BS	Bus start	
128	I	UCONT-P7	_PRESET	Power-on reset	
129	I	UCONT-P8	STATUS0/ CMT_CTR0	Status/CMT_CTR0	
130	I	UCONT-P9	STATUS1/ CMT_CTR1	Status/CMT_CTR1	
131	I	UCONT-P10	_BREQ	Bus mastership request	

Table 3.2 Pin Assignments of the Trace Unit Connector (cont)

Pin No.	I/O	Connector Pin Name	SH7780 Signal Name	Meaning of Signal	Connector in the user system: QTH-090-04-L-D-A; Samtec (180 pins)
					Note
132	I	UCONT-P11	_BACK	Bus mastership recognition	
133	I	UCONT-P12	_RDY	Bus ready	
134	I	UCONT-P13	TCLK/_IOIS16	TMU/PCMCIA IOIS	
135	I	UCONT-P14	_DRAK2/ _CE2A/ AUDCK	DMAC/PCMCIA	
136	I	UCONT-P15	_DRAK3/ _CE2B/ AUDSYNC	DMAC/PCMCIA	
137	I	UCONT-P16	SCIF1_TXD/ MCCLK/ MODE5	SCIF1_TXD/ MCCLK/MODE5	
138	I	UCONT-P17	GND	GND	
139	I	UCONT-P18	GND	GND	
140	I	UCONT-P19	NMI	NMI	
141	I	UCONT-P20	IRQ/_IRL0	IRQ/_IRL0	
142	I	UCONT-P21	IRQ/_IRL1	IRQ/_IRL1	
143	I	UCONT-P22	IRQ/_IRL2	IRQ/_IRL2	
144	I	UCONT-P23	IRQ/_IRL3	IRQ/_IRL3	
145	I	UCONT-P24	IRQ/_IRL4/ FD4/MODE3	IRQ/_IRL4/FD4/ MODE3	

Table 3.2 Pin Assignments of the Trace Unit Connector (cont)

Connector in the user system: QTH-090-04-L-D-A; Samtec (180 pins)

Pin No.	I/O	Connector Pin Name	SH7780 Signal Name	Meaning of Signal	Note
146	I	UCONT-P25	IRQ/_IRL5/ FD5/MODE4	IRQ/_IRL5/FD5/ MODE4	
147	I	UCONT-P26	IRQ/_IRL6/ FD6/MODE6	IRQ/_IRL6/FD6/ MODE6	
148	I	UCONT-P27	IRQ/_IRL7/ FD7	IRQ/_IRL7/FD7	
149	I	UCONT-P28	N.C. ¹⁾	Not connected	
150	I	UCONT-P29	N.C. ¹⁾	Not connected	
151	I	UCONT-P30	N.C. ¹⁾	Not connected	
152	I	UCONT-P31	N.C. ¹⁾	Not connected	
153	I	GND	GND	GND	
154	I	GND	GND	GND	
155	I	MPUCLK	CLKOUT	Clock output	Connect CLKOUT of SH7780.
156	I	GND	GND	GND	
157	I	GND	GND	GND	
158	I	DDRCLK-P/ ASECK-P	GND	GND	
159	I	GND	GND	GND	
160	I	DDRCLK-N/ ASETS-N	GND	GND	
161	I	GND	GND	GND	
162	I	GND	GND	GND	
163	I	CS0IN-N	_CS0	Area selection 0	Connect _CS of SH7780. Fix unused _CS to high level.
164	I	CS1IN-N	_CS1	Area selection 1	Connect _CS of SH7780. Fix unused _CS to high level.

Table 3.2 Pin Assignments of the Trace Unit Connector (cont)

Pin No.	I/O	Connector Pin Name	SH7780 Signal Name	Meaning of Signal	Connector in the user system: QTH-090-04-L-D-A; Samtec (180 pins)
					Note
165	I	CS2IN-N	_CS2	Area selection 2	Connect _CS of SH7780. Fix unused _CS to high level.
166	I	CS3IN-N	_CS3	Area selection 3	Connect _CS of SH7780. Fix unused _CS to high level.
167	I	CS4IN-N	_CS4	Area selection 4	Connect _CS of SH7780. Fix unused _CS to high level.
168	I	CS5IN-N	_CS5	Area selection 5	Connect _CS of SH7780. Fix unused _CS to high level.
169	I	CS6IN-N	_CS6	Area selection 6	Connect _CS of SH7780. Fix unused _CS to high level.
170	I	CS7IN-N	N.C. ¹	Not connected	
171	I	CS8IN-N	N.C. ¹	Not connected	
172	I	CS9IN-N	N.C. ¹	Not connected	
173	O	EM0OUT-N	EM0OUT-N	Emulation-memory select output	Connect this signal instead of CS of the MPU when an emulation memory is used. ²
174	O	EM1OUT-N	N.C. ¹	Not connected	
175	O	EM2OUT-N	N.C. ¹	Not connected	
176	O	EMEN-P	N.C. ¹	Not connected	
177	I	UVCC1	I/O power supply	3.3-V power supply	Connect the 3.3-V power supply.
178	I	UVCC2	I/O power supply	3.3-V power supply	Connect the 3.3-V power supply.
179	I	UVCC3	I/O power supply	3.3-V power supply	Connect the 3.3-V power supply.
180	I	UCNN-N	Connected to user connector	GND (for detecting connection of the user system)	Connect this signal to GND on the user system.

Notes: 1. Do not connect anything to this pin.

2. Refer to section 3.2.8, Description of Emulation Memory Control Signal.

3.2.6 Layout of the Trace Unit Connector

When designing the user system, there are restrictions on the position to install the trace unit connector. Figure 3.4 shows the external dimensions of the trace unit.

The size of the printed-circuit board of the E200F trace unit is 90 mm × 125 mm. The size of components around the user system connector must not exceed the limit on component installation (the height must be 10 mm or less).

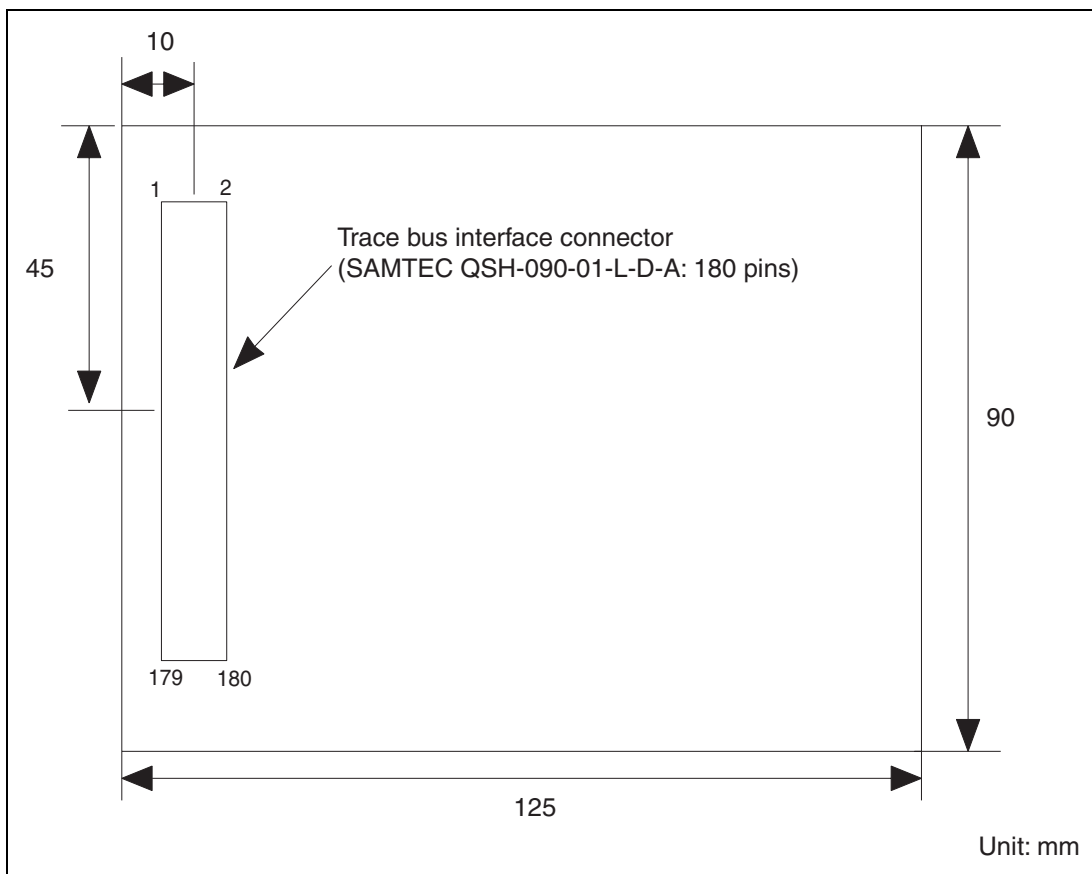


Figure 3.4 External Dimensions of the Trace Unit (on which the Connector is Installed)

- Notes:
1. The external bus trace interface connector installed on the user system must be as close to the MPU as possible.
 2. Wiring pattern of clock lines (CLKOUT)
The followings are notes on wiring of clock lines for the E200F trace interface signals. Take them into consideration when designing the user system to embed suitable clock lines.
 - (a) Clock lines must be as short as possible.
 - (b) Clock lines must be surrounded by the GND pattern for protection so that the signals will be of low-impedance.
 - (c) Other layers next to the layer with clock line wiring should have solid patterns of GND/VCC so that the signals will be of low-impedance.
 - (d) To prevent affect by the crosstalk noise, other signal patterns must not be embedded along with the clock lines.

3.2.7 Restrictions on Using the Trace Unit

- (1) This trace unit supports the external bus memory interfaces of SH7780; SRAM interface and byte-selection SRAM interface (except for SRAM page mode). For other memory interfaces (burst ROM, MPX, DDR-SDRAM, PCI, and PCMCIA), bus trace acquisition and bus event detection are not supported.
- (2) When the sequential trace stop condition or delay-count trace stop condition is specified, trace acquisition will stop after several cycles have been passed from the stop condition match cycle.
- (3) During break mode, a timestamp value of the external bus trace information that has been acquired by a trace is not counted up.
- (4) When an emulation memory is used, it is not possible to access the memory on the user system which is in the same area as an area where the emulation memory has been set.
- (5) When an emulation memory is accessed, at least six wait cycles are required. Set the number of wait cycles by using bits WR3 to WR0 in the CS0 area wait control register (CS0WCR).
- (6) When an emulation memory is used, set the same bus width (8 bits, 16 bits, or 32 bits) as that of the CS0 area on the user system. If the different bus width is set, the emulation memory will be illegally accessed.
- (7) The emulator occupies the CS0 area where the emulation memory has been set. Accordingly, it is not possible to access the memory in the user system side of that area.
- (8) This trace unit is available for the external 8-, 16-, or 32-bit data bus width. When the data bus width is 8 or 16 bits, unused data bus pins D31 to D8 (for 8-bit bus width) or D31 to D16 (for 16-bit bus width) of the trace unit connector must be fixed to high or low level. In addition, when area 0 is used with the emulation memory, the bus width of the emulation memory needs

to be set. For details, refer to section 5.1.8, Changing the Memory Map Setting, in the SH-4A, SH4AL-DSP E200F Emulator User's Manual.

3.2.8 Description of Emulation Memory Control Signal

When the CS signal of the MPU is connected directly to the memory or used to generate the CS signal of the memory, connect the EM0OUT-N signal (pin 173) of the external bus connector instead of the CS signal of the MPU.

Even if the emulator is not used, prepare the jumper pins as shown in figure 3.5 so that connection of the CS signal can be easily changed.

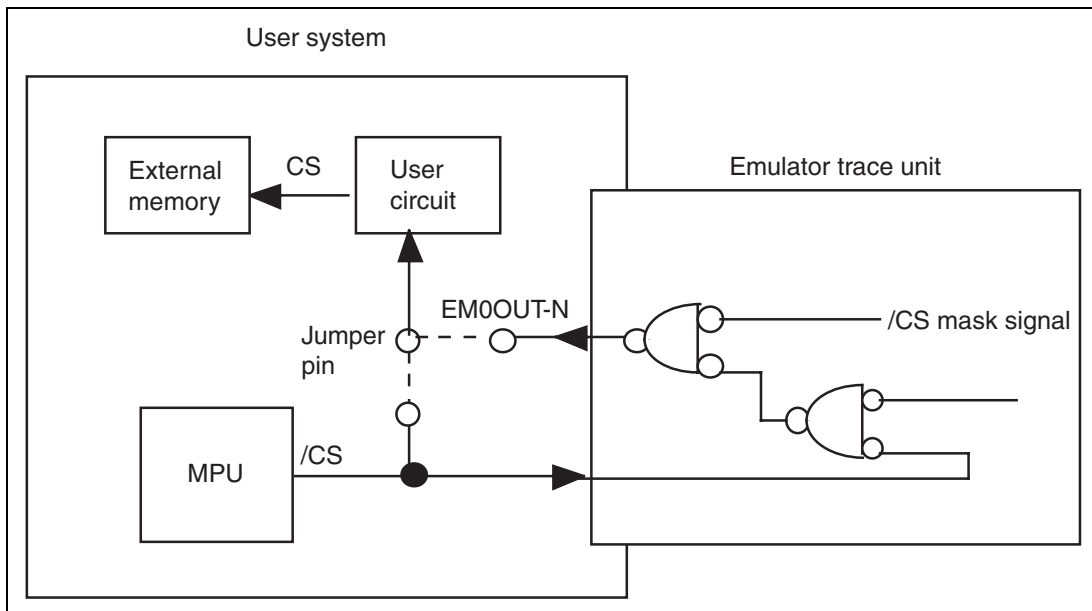


Figure 3.5 EM0OUT-N Signal (Pin 173)

**SH-4A, SH4AL-DSP E200F Emulator
Additional Document for User's Manual
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Publication Date: Rev.1.00, April 4, 2005
Rev.4.00, January 28, 2008
Published by: Sales Strategic Planning Div.
Renesas Technology Corp.
Edited by: Customer Support Department
Global Strategic Communication Div.
Renesas Solutions Corp.

Renesas Technology Corp. Sales Strategic Planning Div. Nippon Bldg., 2-6-2, Ohte-machi, Chiyoda-ku, Tokyo 100-0004, Japan



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REJ10J1168-0400