Old Company Name in Catalogs and Other Documents

On April 1st, 2010, NEC Electronics Corporation merged with Renesas Technology Corporation, and Renesas Electronics Corporation took over all the business of both companies. Therefore, although the old company name remains in this document, it is a valid Renesas Electronics document. We appreciate your understanding.

Renesas Electronics website: http://www.renesas.com

April 1st, 2010 Renesas Electronics Corporation

Issued by: Renesas Electronics Corporation (http://www.renesas.com)

Send any inquiries to http://www.renesas.com/inquiry.

Notice

- 1. All information included in this document is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas Electronics products listed herein, please confirm the latest product information with a Renesas Electronics sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas Electronics such as that disclosed through our website.
- Renesas Electronics does not assume any liability for infringement of patents, copyrights, or other intellectual property rights of third parties by or arising from the use of Renesas Electronics products or technical information described in this document. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.
- 3. You should not alter, modify, copy, or otherwise misappropriate any Renesas Electronics product, whether in whole or in part.
- 4. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
- 5. When exporting the products or technology described in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations. You should not use Renesas Electronics products or the technology described in this document for any purpose relating to military applications or use by the military, including but not limited to the development of weapons of mass destruction. Renesas Electronics products and technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations.
- 6. Renesas Electronics has used reasonable care in preparing the information included in this document, but Renesas Electronics does not warrant that such information is error free. Renesas Electronics assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein.
- 7. Renesas Electronics products are classified according to the following three quality grades: "Standard", "High Quality", and "Specific". The recommended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below. You must check the quality grade of each Renesas Electronics product before using it in a particular application. You may not use any Renesas Electronics product for any application categorized as "Specific" without the prior written consent of Renesas Electronics. Further, you may not use any Renesas Electronics. Renesas Electronics shall not be in any way liable for any damages or losses incurred by you or third parties arising from the use of any Renesas Electronics product for an application categorized as "Specific" or for which the product is not intended where you have failed to obtain the prior written consent of Renesas Electronics. The quality grade of each Renesas Electronics product is "Standard" unless otherwise expressly specified in a Renesas Electronics data sheets or data books, etc.
 - "Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; and industrial robots.
 - "High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control systems; anti-disaster systems; anticrime systems; safety equipment; and medical equipment not specifically designed for life support.
 - "Specific": Aircraft; aerospace equipment; submersible repeaters; nuclear reactor control systems; medical equipment or systems for life support (e.g. artificial life support devices or systems), surgical implantations, or healthcare intervention (e.g. excision, etc.), and any other applications or purposes that pose a direct threat to human life.
- 8. You should use the Renesas Electronics products described in this document within the range specified by Renesas Electronics, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas Electronics shall have no liability for malfunctions or damages arising out of the use of Renesas Electronics products beyond such specified ranges.
- 9. Although Renesas Electronics endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, Renesas Electronics products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas Electronics product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
- 10. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. Please use Renesas Electronics products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Renesas Electronics assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
- 11. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written consent of Renesas Electronics.
- 12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products, or if you have any other inquiries.
- (Note 1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its majorityowned subsidiaries.
- (Note 2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.

M30850T2-CPE

User's Manual

Compact Emulator for M32C/80, 84, 85 and 86 Groups

Keep safety first in your circuit designs!

 Renesas Technology Corp. puts the maximum effort into making semiconductor products better and more reliable, but there is always the possibility that trouble may occur with them. Trouble with semiconductors may lead to personal injury, fire or property damage. Remember to give due consideration to safety when making your circuit designs, with appropriate measures such as (i) placement of substitutive, auxiliary circuits, (ii) use of nonflammable material or (iii) prevention against any malfunction or mishap.

Notes regarding these materials

- 1. These materials are intended as a reference to assist our customers in the selection of the Renesas Technology Corp. product best suited to the customer's application; they do not convey any license under any intellectual property rights, or any other rights, belonging to Renesas Technology Corp. or a third party.
- 2. Renesas Technology Corp. assumes no responsibility for any damage, or infringement of any third-party's rights, originating in the use of any product data, diagrams, charts, programs, algorithms, or circuit application examples contained in these materials.

3. All information contained in these materials, including product data, diagrams, charts, programs and algorithms represents information on products at the time of publication of these materials, and are subject to change by Renesas Technology Corp. without notice due to product improvements or other reasons. It is therefore recommended that customers contact Renesas Technology Corp. or an authorized Renesas Technology Corp. product distributor for the latest product information before purchasing a product listed herein.

The information described here may contain technical inaccuracies or typographical errors. Renesas Technology Corp. assumes no responsibility for any damage, liability, or other loss rising from these inaccuracies or errors.

Please also pay attention to information published by Renesas Technology Corp. by various means, including the Renesas Technology Corp. Semiconductor home page (http://www.renesas.com).

- 4. When using any or all of the information contained in these materials, including product data, diagrams, charts, programs, and algorithms, please be sure to evaluate all information as a total system before making a final decision on the applicability of the information and products. Renesas Technology Corp. assumes no responsibility for any damage, liability or other loss resulting from the information contained herein.
- 5. Renesas Technology Corp. semiconductors are not designed or manufactured for use in a device or system that is used under circumstances in which human life is potentially at stake. Please contact Renesas Technology Corp. or an authorized Renesas Technology Corp. product distributor when considering the use of a product contained herein for any specific purposes, such as apparatus or systems for transportation, vehicular, medical, aerospace, nuclear, or undersea repeater use.
- 6. The prior written approval of Renesas Technology Corp. is necessary to reprint or reproduce in whole or in part these materials.
- 7. If these products or technologies are subject to the Japanese export control restrictions, they must be exported under a license from the Japanese government and cannot be imported into a country other than the approved destination. Any diversion or reexport contrary to the export control laws and regulations of Japan and/ or the country of destination is prohibited.
- 8. Please contact Renesas Technology Corp. for further details on these materials or the products contained therein.

Preface

The M30850T2-CPE is a compact emulator for the M32C/80, 84, 85 and 86 Groups MCUs with the real-time trace function. This user's manual mainly describes specifications of the M30850T2-CPE compact emulator and how to setup it. For details on the following products included with the M30850T2-CPE, refer to each product's online manual.

- Emulator debugger: M32C Compact Emulator Debugger
 Commilian
 M2T NC208WA (available tion comming)
- C compiler: M3T-NC308WA (evaluation version)
 Integrated development environment: High-performance Embedded Workshop

All the components of this product are shown in "1.1 Package Components" (page 13). If there is any question or doubt about this product, contact your local distributor.

The related manuals for using this product are listed below. You can download the latest manuals from the Renesas Tools homepage (http://www.renesas.com/en/tools).

Related manuals

Item	Manual	
Accessory tools	M3T-100LCC-DMS User's Manual	
	M3T-DUMMY100S User's Manual	
	M3T-DIRECT100S User's Manual	
	M3T-FLX-100NRB User's Manual	
	M3T-100LCC-QSD User's Manual	
	M3T-FLX-100NSD User's Manual	
	M3T-F160-100NSD User's Manual	
	M3T-FLX-144NSD User's Manual	
Emulator debugger	M32C Compact Emulator Debugger User's Manual	
C compiler	NC308 User's Manual	
Assembler	AS308 User's Manual	
Integrated development environment	High-performance Embedded Workshop User's Manual	

Important

Before using this product, be sure to read this user's manual carefully. Keep this user's manual, and refer to this when you have questions about this product.

Emulator:

The emulator in this document refers to the following products that are manufactured by Renesas Technology Corp.:

- (1) Compact emulator main unit
- (2) Package converter board for connecting the user system

The emulator herein does not include the customer's user system and host machine.

Purpose of use of the emulator:

This emulator is a device to support the development of a system that uses the M16C Family M32C/80 Series and M32C/80, 84, 85 and 86 Groups of Renesas 16/32-bit single-chip MCUs. It provides support for system development in both software and hardware.

Be sure to use this emulator correctly according to said purpose of use. Please avoid using this emulator for other than its intended purpose of use.

For those who use this emulator:

This emulator can only be used by those who have carefully read the user's manual and know how to use it.

Use of this emulator requires the basic knowledge of electric circuits, logical circuits, and MCUs.

When using the emulator:

- (1) This product is a development supporting unit for use in your program development and evaluation stages. In massproducing your program you have finished developing, be sure to make a judgment on your own risk that it can be put to practical use by performing integration test, evaluation, or some experiment else.
- (2) In no event shall Renesas Solutions Corp. be liable for any consequence arising from the use of this product.
- (3) Renesas Solutions Corp. strives to renovate or provide a workaround for product malfunction at some charge or without charge. However, this does not necessarily mean that Renesas Solutions Corp. guarantees the renovation or the provision under any circumstances.
- (4) This product has been developed by assuming its use for program development and evaluation in laboratories. Therefore, it does not fall under the application of Electrical Appliance and Material Safety Law and protection against electromagnetic interference when used in Japan.
- (5) Renesas Solutions Corp. cannot predict all possible situations or possible cases of misuse where a potential danger exists. Therefore, the warnings written in this user's manual and the warning labels attached to this emulator do not necessarily cover all of such possible situations or cases. Please be sure to use this emulator correctly and safely on your own responsibility.
- (6) This product is not qualified under UL or other safety standards and IEC or other industry standards. This fact must be taken into account when taking this product from Japan to some other country.

Usage restrictions:

This emulator has been developed as a means of supporting system development by users. Therefore, do not use it as a device used for equipment-embedded applications. Also, do not use it for developing the systems or equipment used for the following purposes either:

- (1) Transportation and vehicular
- (2) Medical (equipment where human life is concerned)
- (3) Aerospace
- (4) Nuclear power control
- (5) Undersea repeater

If you are considering the use of this emulator for one of the above purposes, please be sure to consult your local distributor.

About product changes:

We are constantly making efforts to improve the design and performance of this emulator. Therefore, the specification or design of this emulator or its user's manual may be changed without prior notice.

About the rights:

- (1) We assume no responsibility for any damage or infringement on patent rights or any other rights arising from the use of any information, products or circuits presented in this user's manual.
- (2) The information or data in this user's manual does not implicitly or otherwise grant a license for patent rights or any other rights belonging to us or third parties.
- (3) This user's manual and this emulator are copyrighted, with all rights reserved by us. This user's manual may not be copied, duplicated or reproduced, in whole or part, without prior written consent of us.

About diagrams:

The diagrams in this user's manual may not all represent exactly the actual object.

Precautions for Safety

Definitions of Signal Words

In both the user's manual and on the product itself, several icons are used to insure proper handling of this product and also to prevent injuries to you or other persons, or damage to your properties.

This chapter describes the precautions which should be taken in order to use this product safely and properly. Be sure to read this chapter before using this product.





Notes on Con	necting the Power Supply of the Emulator:
	o not use any power cable other than the one that is included with the product.
	he power cable included with the product has its positive and negative poles color-coded by red and black, spectively.
	y attention to the polarities of the power supply. If its positive and negative poles are connected in reverse, e internal circuit may be broken.
	b not apply any voltages exceeding the product's rated power supply voltage (5.0 V \pm 5%). Extreme voltages ay cause a burn due to abnormal heat or cause the internal circuit to break down.
Cautions to B	e Taken for Turning On the Power:
• Tu	rn ON/OFF the power of the emulator and user system as simultaneously as possible.
	o not leave either the emulator or user system powered on, because of leakage current the internal circuits may damaged.
• W	hen turning on the power again after shutting off the power, wait about 10 seconds.
Cautions to B	e Taken for Handling This Product:
•Us	se caution when handling the main unit. Be careful not to apply a mechanical shock.
	o not touch the connector pins of the emulator main unit and the target MCU connector pins directly. Static ectricity may damage the internal circuits.
	o not pull this emulator by the communications interface cable or the cable for connecting the user system. nd, excessive flexing or force may break conductors.
Caution to Be	Taken for System Malfunctions:
If • If	the emulator malfunctions because of interference like external noise, do the following to remedy the trouble.
) Press the RESET button on the emulator upper panel.
(2)) If normal operation is not restored after step (1), shut OFF the emulator once and then reactivate it.

Contents

Preface 3 Important 4 Precautions for Safety 6 User Registration 11 Terminology 12 1. Outline 13 1.1 Package Components 13 1.2 System Configuration 14 1.2.1 System Configuration 14 1.2.1 System Configuration 14 1.2.2 Names and Functions of each part of the Emulator 15 1.3 Specifications 18 1.4 Operating Environment. 20 2.2 Installing the Emulator Debugger 21 2.3 Attaching the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.1 Curring ON the Over 25 2.6.3 Turning ON the User System 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check 28 2.7.1 Self-check 29 2.8 Connecting to 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.1 Connecting to 100-		Page
Precautions for Safety 6 User Registration 11 Terminology 12 1. Outline 13 1. Package Components 13 1.1 Package Components 13 1.2 System Configuration 14 1.2. Tystem Configuration 14 1.2. System Configuration 14 1.2. System Configuration 14 1.3. Specifications 18 1.4 Operating Environment 19 2. Stup 20 2.1 Ristling the Enulator Debugger 20 2.1 Ristling the Enulator Debugger 21 2.3. Connecting the Host Machine 23 2.4 Connecting the Host Machine 23 2.5 Connecting the Host Machine 23 2.6 Checking Connections of the Emulator System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7. Self-check 29 2.8 Connecting the User System 26 2.8 Connecting the User System 26 2.8 Connecting to a 100-pin LCC s	Preface	3
User Registration 11 Terminology 12 1 Outline 13 1.1 Package Components 13 1.2 System Configuration 14 1.2.1 System Configuration 14 1.2.1 System Configuration 14 1.2.2 Names and Functions of each part of the Emulator 15 1.3 Specifications 18 1.4 Operating Environment 19 2. Setup 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Emulator Debugger 21 2.3 Attaching the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Hower 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.2 Checking Connections of the Emulator Starts Up Normally 26 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.7 Self-check 28 2.7 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check. 29 <t< td=""><td>Important</td><td>4</td></t<>	Important	4
Terminology 12 1. Outline 13 1.1 Package Components 13 1.2 System Configuration 14 1.2.1 System Configuration 14 1.2.1 System Configuration 14 1.2.2 Names and Functions of each part of the Emulator 15 1.3 Specifications 18 1.4 Operating Environment 19 2. Installing the Emulator Debugger 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check 28 2.7 1 Self-check Procedure 28 2.8.1 Connecting to a 100-pin LCC socket 31 2.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.4 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 34 2.8.2 Connecting to a 100-pin 0.5-mm-pit	Precautions for Safety	6
1. Outline 13 1.1 Package Components 13 1.1 Package Components 13 1.2 System Configuration 14 1.2.1 System Configuration 14 1.2.2 Names and Functions of each part of the Emulator 15 1.3 Specifications 18 1.4 Operating Environment 19 2. Setup 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Emulator Debugger 21 2.3 Attaching the Forite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check 28 2.7.1 Self-check Procedure 28 2.7.2 fan Error is Detected in the Self-check. 29	•	
1.1 Package Components 13 1.2 System Configuration 14 1.2.1 System Configuration 14 1.2.2 Names and Functions of each part of the Emulator 15 1.3 Specifications 18 1.4 Operating Environment 19 2. Setup 20 2.1 Flowchart of Starting Up the Emulator 20 2.1 Flowchart of Starting Up the Emulator 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.2 Checking Connections of the Emulator System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 26 2.7.5 Eff-Check 28 2.7.1 Self-Check Procedure 28 2.7.1 Self-Check Procedure 28 2.8.2 Connecting the Juse System 30 2.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32	Terminology	12
1.2 System Configuration 14 1.2.1 System Configuration 14 1.2.2 Names and Functions of each part of the Emulator 15 1.3 Specifications 18 1.4 Operating Environment 19 2. Setup 20 2.1 Flowchart of Starting Up the Emulator 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Emulator Debugger 21 2.3 Attaching the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6 Turning ON VOFF the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check 28 2.7.1 fan Error is Detected in the Self-check. 28 2.7.2 If an Error is Detected in the Self-check. 29 2.8 Connecting to a 100-pin LCC socket 31 2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (P	1. Outline	13
1.2.1 System Configuration 14 1.2.2 Names and Functions of each part of the Emulator 15 1.3 Specifications 18 1.4 Operating Environment. 19 2. Setup. 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Emulator Debugger 21 2.3 Attaching the Ferrite Core 21 2.4 Connecting the Host Machine 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.2 Checking Connecting the Host Machine 25 2.6.3 Turning ON/OFF the Power 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 26 2.7 Self-check 28 2.7.1 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check. 29 2.8 Connecting to a 100-pin LCC socket 23 2.8.1 Connecting to a 100-pin LCC socket 33 2.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.3 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)<	1.1 Package Components	13
1.2.2 Names and Functions of each part of the Emulator. 15 1.3 Specifications 18 1.4 Operating Environment. 19 2. Setup. 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Emulator Debugger 21 2.3 Attaching the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6 1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.1 MCU Power Supply Source System 25 2.6.3 LED Display Uhen the Emulator System 25 2.6.4 Power Supply to the User System 26 2.7 Self-check 28 2.7.1 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check. 29 2.8 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2) 33 2.8.4 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 34 2.8.5 Connecting to a 100-pin 0.5-mm	1.2 System Configuration	14
1.3 Specifications 18 1.4 Operating Environment 19 2. Setup. 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Environment 20 2.3 Attaching the Fortife Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.1 MCU Power Supply to the Emulator System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check 28 2.7.1 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check. 29 2.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3) 34 2.8.4 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 34 2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 34 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foo	1.2.1 System Configuration	14
1.4 Operating Environment. 19 2. Setup. 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Ferrite Core 21 2.3 Attaching the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper. 24 2.6.1 MCU Power Supply to the User System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check 28 2.7.1 f an Error is Detected in the Self-check. 28 2.7.2 If an Error is Detected in the Self-check. 29 2.8 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1). 32 2.8.1 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2). 33 2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3). 34 2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3). 34 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3). 36 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Patte	1.2.2 Names and Functions of each part of the Emulator	15
2. Setup 20 2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Emulator Debugger 21 2.3 Attaching the Ferrite Core 22 2.4 Connecting the Host Machine 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6 Turning ON the Power 24 2.6 Turning ON/OFF the Power 24 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply Connections of the Emulator System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check 28 2.7.1 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check. 29 2.8 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 33 2.8.5 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 33 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 33 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 34 2.8.6 Connecting to a 100-pin 0.5-mm-p	1.3 Specifications	18
2.1 Flowchart of Starting Up the Emulator 20 2.2 Installing the Emulator Debugger 21 2.3 Attaching the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.2 Checking Connections of the Emulator System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 26 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7. Self-check 28 2.7.1 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check. 29 2.8 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.1 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2) 33 2.8.4 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 32 2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 35 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 36 2.8.8 Connecti	1.4 Operating Environment	19
2.2 Installing the Emulator Debugger 21 2.3 Attaching the Ferrite Core 22 2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper. 24 2.6.2 Checking Connections of the Emulator System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check. 28 2.7.1 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check. 29 2.8.1 Connecting the User System 30 2.8.1 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.4 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 35 2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 33 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.6 Connecting to	2. Setup	20
2.3 Attaching the Ferrite Core 22 2.4 Connecting the Host Machine 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper. 24 2.6.2 Checking Connections of the Emulator System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 25 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7. Self-check 28 2.7.1 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check 28 2.7.2 If an Error is Detected in the Self-check 29 2.8 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.1 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3) 34 2.8.5 Connecting to a 100-pin 0.55-mm-pitch Foot Pattern (Part 3) 34 2.8.5 Connecting to a 100-pin 0.55-mm-pitch Foot Pattern (Part 3) 34 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 36 2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern (Part 3) 36	2.1 Flowchart of Starting Up the Emulator	20
2.4 Connecting the Power Supply for the Emulator 22 2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper 24 2.6.2 Checking Connections of the Emulator System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 26 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7 Self-check 28 2.7.1 f an Error is Detected in the Self-check. 29 2.8 Connecting to a 100-pin LCC socket 30 2.8.1 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2) 33 2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3) 34 2.8.5 Connecting to a 100-pin 0.55-mm-pitch Foot Pattern (Part 3) 34 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 144-pin 0.	2.2 Installing the Emulator Debugger	21
2.5 Connecting the Host Machine 23 2.6 Turning ON the Power 24 2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper. 24 2.6.2 Checking Connections of the Emulator System 25 2.6.3 Turning ON/OFF the Power 25 2.6.4 Power Supply to the User System 26 2.6.5 LED Display When the Emulator Starts Up Normally 26 2.7.5 Self-check 28 2.7.1 Self-check Procedure 28 2.7.1 Self-check Procedure 28 2.7.1 Self-check Procedure 28 2.7.2 If an Error is Detected in the Self-check 29 2.8 Connecting the User System 30 2.8.1 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2) 33 2.8.4 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 35 2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.9.1 Setting Switch	2.3 Attaching the Ferrite Core	22
2.6 Turning ON the Power.242.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper.242.6.2 Checking Connections of the Emulator System.252.6.3 Turning ON/OFF the Power252.6.4 Power Supply to the User System252.6.5 LED Display When the Emulator Starts Up Normally262.7 Self-check282.7.1 Self-check Procedure282.7.2 If an Error is Detected in the Self-check.292.8 Connecting to a 100-pin LCC socket312.8.1 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.9.1 Setting Switches of Emulator392.9.1 Setting Switches of Emulator392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483.1 Starting Up the Emulator Debugger (Init Dialog Box)49Notes on selecting a Processor Mode55Notes on selecting a Processor Mode55Notes on Selecting a Proces	2.4 Connecting the Power Supply for the Emulator	22
2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper	2.5 Connecting the Host Machine	23
2.6.2 Checking Connections of the Emulator System252.6.3 Turning ON/OFF the Power252.6.4 Power Supply to the User System252.6.5 LED Display When the Emulator Starts Up Normally262.7 Self-check282.7.1 Self-check Procedure282.7.2 If an Error is Detected in the Self-check292.8 Connecting the User System302.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)342.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)342.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 104-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern (Part 2)363.8.9 Changing Settings392.9.1 Setting Switches of Emulator392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger (Init Dialog Box)443.9 Notes on selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window593.4 Hardware Break	2.6 Turning ON the Power	24
2.6.3 Turning ON/OFF the Power252.6.4 Power Supply to the User System252.6.5 LED Display When the Emulator Starts Up Normally262.7 Self-check282.7.1 Self-check Procedure282.7.2 If an Error is Detected in the Self-check.292.8 Connecting the User System302.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)342.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)342.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 104-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern382.9 Changing Settings392.9.1 Setting Switches of Emulator392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger (Init Dialog Box)49Notes on selecting a Processor Mode55Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window593.4 Hardware Breakpoint Setting Window <t< td=""><td>2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper</td><td>24</td></t<>	2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper	24
2.6.4 Power Supply to the User System252.6.5 LED Display When the Emulator Starts Up Normally262.7 Self-check282.7.1 Self-check282.7.2 If an Error is Detected in the Self-check292.8 Connecting the User System302.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)352.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.9 Changing Settings392.9 1 Setting Switches of Emulator392.9 2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger)493.1 Starting Up the Emulator Debugger (Init Dialog Box)493.2 Starting Up the Emulator Debugger (EMEM Dialog Box)55Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window593.4 Hardware Breakpoint Setting Window633.5 Trace Window68	2.6.2 Checking Connections of the Emulator System	25
2.6.5 LED Display When the Emulator Starts Up Normally262.7 Self-check282.7.1 Self-check Procedure282.7.2 If an Error is Detected in the Self-check.292.8 Connecting the User System302.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)342.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)342.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.9 Changing Settings392.9.1 Setting Switches of Emulator392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger)493.1 Starting Up the Emulator Debugger (Init Dialog Box)49Notes on selection of whether or not to use the watchdog timer503.2 Starting Up the Emulator Debugger (EMEM Dialog Box)55Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window633.5 Trace Window68	2.6.3 Turning ON/OFF the Power	25
2.7 Self-check282.7.1 Self-check Procedure282.7.2 If an Error is Detected in the Self-check292.8 Connecting the User System302.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)342.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.9 Changing Settings392.9.1 Setting Switches of Emulator392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger)493.1 Starting Up the Emulator Debugger (Init Dialog Box)49Notes on selection of whether or not to use the watchdog timer503.2 Starting Up the Emulator Debugger (EMEM Dialog Box)55Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window683.5 Trace Window68	2.6.4 Power Supply to the User System	25
2.7.1 Self-check Procedure282.7.2 If an Error is Detected in the Self-check292.8 Connecting the User System302.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)342.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.9 Changing Settings392.9 Changing Settings392.9.1 Setting Switches of Emulator392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger)49Notes on selection of whether or not to use the watchdog timer503.2 Starting Up the Emulator Debugger (EMEM Dialog Box)55Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window633.5 Trace Window68	2.6.5 LED Display When the Emulator Starts Up Normally	
2.7.2 If an Error is Detected in the Self-check.292.8 Connecting the User System.302.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)342.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.9 Changing Settings392.9.1 Setting Switches of Emulator382.9 Changing Settings392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger)493.1 Starting Up the Emulator Debugger (Init Dialog Box)49Notes on selection of whether or not to use the watchdog timer503.2 Starting Up the Emulator Debugger (EMEM Dialog Box)55Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window633.5 Trace Window68	2.7 Self-check	
2.8 Connecting the User System.302.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)342.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)342.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern382.9 Changing Settings392.9.1 Setting Switches of Emulator392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger)493.1 Starting Up the Emulator Debugger (Init Dialog Box)49Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window593.4 Hardware Breakpoint Setting Window633.5 Trace Window68	2.7.1 Self-check Procedure	
2.8.1 Connecting to a 100-pin LCC socket312.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)322.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)332.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)342.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)352.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)362.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)372.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern382.9 Changing Settings392.9.1 Setting Switches of Emulator392.9.2 Selecting Clock Supply442.9.3 A/D Conversion Bypass Capacitors483. Usage (Emulator Debugger)493.1 Starting Up the Emulator Debugger (Init Dialog Box)49Notes on selection of whether or not to use the watchdog timer503.2 Starting Up the Emulator Debugger (EMEM Dialog Box)55Notes on Selecting a Processor Mode55Notes on Selecting a Processor Mode563.3 Program Window593.4 Hardware Breakpoint Setting Window633.5 Trace Window68	2.7.2 If an Error is Detected in the Self-check	29
2.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1) 32 2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2) 33 2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3) 34 2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 35 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern 38 2.9 Changing Settings 39 2.9.1 Setting Switches of Emulator 39 2.9.2 Selecting Clock Supply 44 2.9.3 A/D Conversion Bypass Capacitors 48 3. Usage (Emulator Debugger) 49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window <td>2.8 Connecting the User System</td> <td>30</td>	2.8 Connecting the User System	30
2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2) 33 2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3) 34 2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 35 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern 38 2.9 Changing Settings 39 2.9.1 Setting Switches of Emulator 39 2.9.2 Selecting Clock Supply 44 2.9.3 A/D Conversion Bypass Capacitors 48 3. Usage (Emulator Debugger) 49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	2.8.1 Connecting to a 100-pin LCC socket	31
2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3) 34 2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 35 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.7 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.9 Changing Settings 39 2.9.1 Setting Switches of Emulator 39 2.9.2 Selecting Clock Supply 44 2.9.3 A/D Conversion Bypass Capacitors 48 3. Usage (Emulator Debugger) 49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	2.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)	32
2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1) 35 2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern 38 2.9 Changing Settings 39 2.9.1 Setting Switches of Emulator 39 2.9.2 Selecting Clock Supply 44 2.9.3 A/D Conversion Bypass Capacitors 48 3. Usage (Emulator Debugger) 49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)	33
2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2) 36 2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern 38 2.9 Changing Settings 39 2.9.1 Setting Switches of Emulator 39 2.9.2 Selecting Clock Supply 44 2.9.3 A/D Conversion Bypass Capacitors 48 3. Usage (Emulator Debugger) 49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)	34
2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3) 37 2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern 38 2.9 Changing Settings 39 2.9.1 Setting Switches of Emulator 39 2.9.2 Selecting Clock Supply 44 2.9.3 A/D Conversion Bypass Capacitors 48 3. Usage (Emulator Debugger) 49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)	35
2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern 38 2.9 Changing Settings 39 2.9.1 Setting Switches of Emulator 39 2.9.2 Selecting Clock Supply 44 2.9.3 A/D Conversion Bypass Capacitors 48 3. Usage (Emulator Debugger) 49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)	
2.9 Changing Settings	2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)	37
2.9.1 Setting Switches of Emulator	2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern	
2.9.2 Selecting Clock Supply .44 2.9.3 A/D Conversion Bypass Capacitors .48 3. Usage (Emulator Debugger) .49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) .49 Notes on selection of whether or not to use the watchdog timer .50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) .55 Notes on Selecting a Processor Mode .55 Notes on Selecting a Processor Mode .56 3.3 Program Window .59 3.4 Hardware Breakpoint Setting Window .63 3.5 Trace Window .68	2.9 Changing Settings	
2.9.3 A/D Conversion Bypass Capacitors 48 3. Usage (Emulator Debugger) 49 3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	2.9.1 Setting Switches of Emulator	
3. Usage (Emulator Debugger)	2.9.2 Selecting Clock Supply	44
3.1 Starting Up the Emulator Debugger (Init Dialog Box) 49 Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	2.9.3 A/D Conversion Bypass Capacitors	48
Notes on selection of whether or not to use the watchdog timer 50 3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	3. Usage (Emulator Debugger)	49
3.2 Starting Up the Emulator Debugger (EMEM Dialog Box) 55 Notes on Selecting a Processor Mode 55 Notes on Selecting a Processor Mode 56 3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68	3.1 Starting Up the Emulator Debugger (Init Dialog Box)	49
Notes on Selecting a Processor Mode .55 Notes on Selecting a Processor Mode .56 3.3 Program Window .59 3.4 Hardware Breakpoint Setting Window .63 3.5 Trace Window .68	Notes on selection of whether or not to use the watchdog timer	50
Notes on Selecting a Processor Mode .55 Notes on Selecting a Processor Mode .56 3.3 Program Window .59 3.4 Hardware Breakpoint Setting Window .63 3.5 Trace Window .68	3.2 Starting Up the Emulator Debugger (EMEM Dialog Box)	55
3.3 Program Window 59 3.4 Hardware Breakpoint Setting Window 63 3.5 Trace Window 68		
3.4 Hardware Breakpoint Setting Window		
3.5 Trace Window	3.3 Program Window	59
	3.4 Hardware Breakpoint Setting Window	63
3.6 RAM Monitor Window73	3.5 Trace Window	68
	3.6 RAM Monitor Window	73

	Page
4. Hardware Specifications	
4.1 Target MCU Specifications.	
4.2 Differences between the Actual MCU and Emulator	
Notes on the User System (Power Supply, Order of Powering On)	
Notes on Using This Product When the Voltage of VCC1 is Higher than That of VCC2	
Note on Differences between the Actual MCU and Emulator	
Note on RESET# Input Note on RDY# Input	
Note on HOLD# Input	
Note on NMI# Input	
Notes on Reset Vector Area	
Notes on Stack Area	
Note on Maskable Interrupts	
Notes on Access Prohibited Area	
Note on DMA Transfer	
Note on DMAC II Transfer Completion Interrupts	
Note on Final Evaluation	
4.3 Connection Diagram	
4.4 External Dimensions	
4.4.1 External Dimensions of the Compact Emulator	
4.4.2 External Dimensions of the M30800T-PTC	
4.4.3 External Dimensions of the M3T-F160-100NSD	
4.4.4 External Dimensions of the M3T-FLX-144NSD	
4.5 Notes on Using This Product	
Notes on the Self-check	
Note on Quitting the Emulator Debugger	
Notes on Clock Supply to the MCU	
Notes on Using the CPU Clock at Less than 16 MHz	
Notes on EMEM Dialog Box	86
Notes on Address-Match Interrupts	86
Notes on the Watchdog Function	86
Notes on Debugging in CPU Rewrite Mode	87
Note on Software Breaks	
Note on Downloading Programs	87
Notes on Service-Life of the MCU's Internal Flash ROM	87
Note on Voltage Detect Circuit	87
Note on Protect Register	88
Note on Memory Access	
Notes on A/D Conversion	88
Notes on CE Declaration of Conformity	89
5. Troubleshooting	
5.1 Flowchart to Remedy the Troubles	
5.2 When the Emulator Debugger Does Not Start Up Properly	
5.3 How to Request for Support	
6. Maintenance and Guarantee	
6.1 User Registration	
6.2 Maintenance	
6.3 Guarantee	
6.4 Repair Provisions	
6.5 How to Make Request for Repair	96

User Registration

When you have purchased the emulator presented in this user's manual, please be sure to register it. As the H/W Tool Customer Registration Sheet is included with this manual, fill it in and email to the following address. Your registered information is used for only after-sale services, and not for any other purposes. Without user registration, you will not be able to receive maintenance services such as a notification of field changes or trouble information. So be sure to carry out the user registration.

For more information about user registration, please email to the following address.

regist_tool@renesas.com

Terminology

Some specific words used in this user's manual are defined as follows:

Emulator M30850T2-CPE

This means the compact emulator (this product) for M32C/80, 84, 85 and 86 Group MCUs.

MCU board M30850T2-EPBM

The MCU board M30850T2-EPBM with an evaluation MCU.

Emulator system

This means an emulator system built around the M30850T2-CPE emulator. The M30850T2-CPE emulator system is configured with an emulator main unit M30850T2-CPE, M32C compact emulator debugger and host machine.

M32C compact emulator debugger

This means a software tool which you can control the emulator from a host machine through the USB interface.

Firmware

This means a program stored in the flash ROM of the emulator. It analyzes contents of communication with the emulator debugger and controls the emulator M30850T2-CPE. This program is downloadable from the emulator debugger to upgrade firmware or to support other MCUs.

Host machine

This means a personal computer used to control the M30850T2-CPE emulator system.

Software break

A software break is a function to break the program before the system executes an instruction at the specified address. The instruction at the preset address will not be executed.

Hardware break

A hardware break is a function to break the program when the system detects a write/read of data to/from memory or a leading/trailing edge of the signal entered from the external trace cable. The former break function is called address break; and the latter break function is called trigger break. While the instruction at the address where the software break is set is not executed, a hardware break is performed after the specified instruction is executed.

Target MCU

This means the microcomputer you are going to debug.

User system

This means a user's application system using the microcomputer to be debugged.

User program

This means a user's application program to be debugged.

Evaluation MCU

This means a microcomputer mounted on the emulator which is operated in the special mode for the emulator.

#

In this user's manual, this symbol is used to show active LOW. (e.g. RESET#)

1. Outline

This chapter describes the package components, the system configuration and the preparation for using this product for the first time.

1.1 Package Components

The M30850T2-CPE package consists of the following items. When unpacking it, check to see if your M30850T2-CPE contains all of these items.

Table 1.1 Package components

Item	Quantity	
M30850T2-CPE compact emulator		
M30800T-PTC (pre-mounted) converter board for 100-pin LCC socket	1	
IC61-1004-051 100-pin LCC socket made by Yamaichi Electronics Co, Ltd.	1	
OSC-3 (32MHz) oscillator circuit board	1	
OSC-2 oscillator circuit bare board	1	
USB interface cable for connecting host machine and emulator	1	
Power supply cable for compact emulator	1	
Ferrite core for connecting power supply cable		
H/W Tool Customer Registration Sheet (English)		
H/W Tool Customer Registration Sheet (Japanese)		
M30850T2-CPE User's Manual (this manual)		
M30850T2-CPE User's Manual (Japanese)		
M30850T2-CPE Release Notes (English)		
M30850T2-CPE Release Notes (Japanese)		
CD-ROM - M32C compact emulator debugger	1	
- C compiler M3T-NC308WA		
(evaluation version)		

* Please keep the M30850T2-CPE's packing box and cushion material in your place for reuse at a later time when sending your product for repair or other purposes. Always use these packing box and cushion material when transporting this product.

* If there is any question or doubt about the packaged product, contact your local distributor.

1.2.1 System Configuration

Figure 1.1 shows a configuration of the M30850T2-CPE system.



Figure 1.1 System configuration

 Compact emulator M30850T2-CPE (this product) This is a compact emulator for the M32C/80, 84, 85 and 86 Groups with the real-time trace functions (hereafter, emulator).

(2) USB interface cable (included)

This is an interface cable for the host machine and the emulator.

(3) Power supply for emulator

This is a power supply for the emulator. Supply 5.0 V \pm 5% (DC).

Prepare a power supply complies with CE marking requirements separately. The power cable is included with this product. Note: Be aware that there are some AC adapters whose power supply voltage varies rather widely with its load. You are recommended to use an AC adapter with a switching power supply or a stabilized power supply.

(4) User system

This is your application system. This emulator can be used without the user system.

(5) Power supply for the user system

This is a power supply for the user system. As this emulator cannot supply the power to the user system, supply the power to the user system separately from the emulator.

(6) Host machine

This is a personal computer for controlling the emulator.

(7) Pitch converter board such as M30800T-PTC (included)

This is a pitch converter board for connecting to an MCU foot pattern on the user system (for 100-pin 0.65-mm-pitch LCC socket). For details, refer to "2.8 Connecting the User System" (page 30).

1.2.2 Names and Functions of each part of the Emulator

Figure 1.2 shows the names of the LEDs on the upper panel of the emulator.



Figure 1.2 Names of the LEDs on the upper panel of the M30850T2-CPE

(1) System Status LEDs

The system status LEDs indicate the emulator main unit's operating status etc. Table 1.2 lists the definition of the system status LEDs.

Table 1.2 Definitions	of the system	status LEDs
Tuble 1.2 Definitions	or the system	Status LLDS

Name	Number	Color	Status	Meaning
POWER	LED1	Orange	ON	Power is supplied to the emulator.
			OFF	Power is not supplied to the emulator.
SAFE	LED2	Green	ON	Emulator system has started normally.
			OFF	Emulator system has not started normally.

(2) Target Status LEDs

The target status LEDs indicate the target MCU's power supply and operating status. Table 1.3 lists the definition of each target status LED.

Name	Number	Color	Status	Meaning	
POWER	LED3	Orange	ON	Power is supplied to the target MCU.	
			OFF	Power is not supplied to the target MCU.	
CLOCK	LED4	Green	ON	The target MCU internal clock is oscillating.	
			OFF	The target MCU internal clock is not oscillating.	
RESET	LED5	Red	ON Target MCU is being reset.		
			OFF	OFF Target MCU is not being reset.	
RUN	LED6	Green	ON User program is being executed.		
			OFF	User program is not being executed.	

Table 1.3 Definitions of the	e target status LEDs
------------------------------	----------------------

(3) System Reset Switch

By pressing the system reset switch, you can initialize the emulator system. Table 1.4 shows the functions of the system reset switch depending on the state of the emulator.

Table 1.4 Functions of the system reset switch

State of Emulator	Function
When the user's program is helted	Initializes the emulator and waits for a command from the
When the user's program is halted	emulator debugger
When the user's program is executed	Stops the user's program, initializes the emulator, and
	waits for a command from the emulator debugger.

IMPORTANT

Notes on a System Reset:

- After pressing the system reset switch, restart the emulator debugger. Otherwise the display of emulator debugger and the actual value (in the emulator) may not match.
- When the emulator debugger does not start up normally even after rebooting, turn off the emulator and then turn on again.

(4) Power Connector (J1)

This is a connector for connecting the power supply to this product. For details, refer to "2.4 Connecting the Power Supply for the Emulator" (page 22).

(5) USB Cable Connector (J2)

This is a USB cable connector for connecting the host machine to this product. For details, "2.5 Connecting the Host Machine" (page 23).

(6) MCU Power Supply Source Selection Jumper (JP1)

This is a jumper switch to set the power supply source to the MCU. For details on this switch, see "2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper" (page 24).

(7) MCU Power Supply Voltage Selection Jumper (JP2)

This is a jumper switch to set the power supply voltage of the MCU. This setting is valid when the MCU power supply source selection jumper is set to INT only. For details on this switch, see "2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper" (page 24).

(8) Switches and Selection Jumpers on the M30850T2-EPBM

These are switches to change the connections in the emulator according to the user system. For details on the settings, see "2.9 Changing Settings" (page 39).

1.3 Specifications

Table 1.5 and 1.6 list specifications of the M30850T2-CPE.

Applicable MCUs	M32C/80, 84, 85 and 86 Group	M32C/80, 84, 85 and 86 Groups		
Evaluation MCU	M30855FHGP			
	ROM size: 512 KB + 4 KB, RAM size: 24 KB			
Usable mode	Single-chip mode			
	Memory expansion mode			
Maximum operating frequency	VCC1=VCC2=4.25.5V: 32N	ſHz		
	VCC1=VCC2=3.05.5V: 24N	ſHz		
	Dual-power supply specification	on*		
	$(4.8 \text{ V} \le \text{VCC1} \le 5.2 \text{ V} \text{ and } 3.2 \text{ V}$	$3 V \le VCC2 \le VCC1$): 32MHz		
Applicable power supply	User system connected	3.05.5 V		
	(JP1=EXT)			
	User system not connected	3.3 V or 5.0 V		
	(JP1=INT)	(supplied from the emulator, set by JP2)		
Basic debugging functions	- Download			
	- Software break (max. 64 por	ints)		
	- Program execution/stop (allows free-run execution supporting software breaks)			
	- Memory reference/setting (r	eference/setting C-variables, run-time execution)		
	- Register reference/setting			
	- Disassemble display			
	- C-level debugging, etc.			
Real-time trace function	- 64K-cycle bus information recordable			
	(Address: 24-bit, Data: 16-b			
	- 5 trace modes supported (Break/Before/About/After/Full)			
	- Can be recorded ON/OFF by events			
Real-time RAM monitor function	- 1,024 bytes (256 bytes x4)			
	- Data/last access result			
Hardware break function	2 points (Address match, bus r	2 points (Address match, bus match, max. 255 pass counts) Time between program start and stop		
Execution time measurement function				

Table 1.5 M30850T2-CPE specifications (1/2)

* Notes on Using This Product in Dual-power Supply Specification

- If using this product when the voltage of VCC1 is higher than that of VCC2, the VCC2 must be 3.3 V or more.

- If using a CPU clock of more than 30MHz, set the SFR area of the intelligent I/O function to 2-wait (set the PM13 bit to "1") when reading this area.

These precautions only need to be observed when using an emulator, and does not apply for the actual MCU.

Table 1.6 M30850T2-CPE specifications (2/2)				
Connection to user system (see "2.8 Connecting the User	For 144-pin 0.5-mm-pitch LQFP (144P6O-A)	M3T-FLX-144NSD (not included)		
System" on page 30)	For 100-pin 0.5-mm-pitch LQFP (100P6Q-A)	 M30800T-PTC (included) + M3T-100LCC-QSD (not included) M30800T-PTC (included) + M3T-100LCC-DMS (not included) + M3T-FLX-100NSD (not included) M3T-F160-100NSD (not included) 		
	For 100-pin 0.65-mm-pitch QFP (100P6S-A):	 M30800T-PTC (included) + M3T-100LCC-DMS (not included) + M3T-FLX-100NRB (not included) M30800T-PTC (included) + M3T-100LCC-DMS (not included) + M3T-DUMMY100S (not included) M30800T-PTC (included) + M3T-100LCC-DMS (not included) + M3T-100LCC-DMS (not included) + M3T-DIRECT100S (not included) 		
	100-pin LCC socket	M30800T-PTC (included) + IC61-1004-051 (included)		
Power supply for emulator	DC 5.0 V \pm 5 % / (2 A) externally supplied (Prepare a power supply which complies with CE marking requirements separately.)			
Host machine interface	USB (USB 1.1 full-speed*, mini-B standard connector)			
Overseas standards	EN55022: 1998 Class A, EN55024: 1998			

* Available to connect the host machine that supports USB 2.0. With the USB interface, not all hardware (such as host machine, USB devices, USB hub) combination will work and guaranteed.

1.4 Operating Environment

Be sure to use thins emulator with the operating environmental of the emulator and host machine listed in Tables 1.7 and 1.8.

Item	Description				
Operating temperature	5 to 35°C (no dew)				
Storage temperature	-10 to 60°C (no dew)				

Table 1.7 Operating environmental conditions

Table 1.8 Operating environment of the host machine

Item	Description
Host machine	IBM PC/AT compatibles with USB1.1
OS	Windows Me ^{*1}
	Windows 98
	Windows XP
	Windows 2000
CPU	Pentium III 600 MHz or more recommended
Host machine interface	USB 1.1 full-speed ^{*2}
Memory	128 MB or more recommended
Pointing device such as mouse	Mouse or any other pointing device usable with the above OS that can be
	connected to the main body of the host machine.
CD drive	Needed to install the emulator debugger or refer to the user's manual

*1 Windows and Windows NT are either registered trademarks or trademarks of Microsoft Corporation in the United States and other countries.

*2 Available to connect the host machine that supports USB 2.0. With the USB interface, not all hardware (such as host machine, USB devices, USB hub) combination will work and guaranteed.

2. Setup

This chapter describes the preparation for using this product, the procedure for starting up the emulator and how to change settings.

2.1 Flowchart of Starting Up the Emulator

The procedure for starting up the emulator is shown in Figure 2.1. For details, refer to each section hereafter. And, when the emulator does not start up normally, refer to "5. Troubleshooting" (page 90).





2.2 Installing the Emulator Debugger

If the OS used in your host machine is Windows XP or 2000, this installation must be executed by a user with administrator rights. Be aware that users without administrator rights cannot complete the installation.

The "auto_run.exe" starts up by inserting the included CD into the CD-ROM drive, and the HTML page for installation will open. Install the C compiler, emulator debugger and USB driver as occasion demands.

In process of installation, "user information" dialog box to enter the user information (contractor, section, contact address, and host machine) will open. The supplied information will be turned into a format by which technical support will be provided by e-mail.

Attach the ferrite core included with this product close to the DC plug of the power cable. Without the ferrite core it may cause interference.

The power cable should be wound around the ferrite core as shown in the figure, and close the ferrite core until it clicks.



Figure 2.2 Attaching the ferrite core

2.4 Connecting the Power Supply for the Emulator

Connect the power supply for the emulator to the power connector (J1). The specification of the power supply for the emulator is listed in Table 2.1.

Table 2.1 Specification of power supply of the emulator

Power supply voltage	DC 5.0 V±5%/2 A
----------------------	-----------------

Figures 2.3 and 2.4 show the specifications of the power connector (J1) and an applicable plug, respectively.



Figure 2.3 Power connector specifications



Notes on Connecting a Power Supply of the Emulator:

- The power cable included in this product package is colored red (+) and black (-).
- Be careful about the polarity of the power supply. Connecting to the wrong electrode could destroy internal circuits.
- Do not apply a voltage exceeding the specified voltage of the product (5.0 V ±5%), because it may cause burn injuries and the failure of internal circuits.
- Use the power supply which complies with CE marking requirements.

2.5 Connecting the Host Machine

Connect the emulator and the host machine with the USB interface cable.

Connect the USB interface cable (included) to the USB interface connector (J2) and the USB port of the host machine (see Figure 2.5).



Figure 2.5 Connecting the emulator system

2.6 Turning ON the Power

2.6.1 MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper

Set the MCU power supply source selection jumper and the MCU power supply voltage selection jumper of the emulator according to conditions of use.



Figure 2.6 Jumper switch locations

These are the jumper switches to select power supply to the MCU and its power voltage. As shown in Table 2.2 below, set the switch according to the connection to the user system.

Connection to the user system	MCU power supply source selection jumper (JP1)	MCU power supply voltage selection jumper (JP2)	Description
Not connected	INT	3.3 V	Supplied from the emulator. The MCU operating voltage is 3.3 V.
		5.0 V	Supplied from the emulator. The MCU operating voltage is 5.0 V.
Connected	EXT	Invalid	Supplied from the user system. This emulator consumes max. 500 mA of electrical current from the user system.

Table 2.2 Setting jumper switches

Note on Jumper Switch Settings:

- Always shut OFF the emulator before changing the setting of the jumper switches, and connecting the cable. Otherwise the internal circuit may cause a break.
- When the MCU power supply source selection jumper and MCU power supply voltage selection jumper are set to INT and 5.0 V respectively, the selection jumper JP1 on the M30850T2-EPBM must be set as VCC1=VCC2 side.

2.6.2 Checking Connections of the Emulator System

Before turning the power ON, check the connection of the interface cable to the host machine, emulator, and user system.

2.6.3 Turning ON/OFF the Power

Turn ON/OFF the power of the emulator and user system as simultaneously as possible.

Do not leave either the emulator or user system powered on, because of leakage current the internal circuits may be damaged. When turning ON the power again after shutting OFF the power, wait for about 10 seconds.

2.6.4 Power Supply to the User System

This emulator cannot supply the power to the user system. Therefore design your system so that the user system is powered separately. This product consumes max. 500mA of electrical current from the user system. Please consider the capacity of the power supply of the user system.

The voltage of the user system should be within the following. And do not change the voltage of the user system after turning on the power.

(1) When JP1 of the M30850T2-EPBM is set as VCC1=2: $3.0 \text{ V} \le \text{VCC1} = \text{VCC2} \le 5.5 \text{ V}$

(2) When JP1 of the M30850T2-EPBM is set as VCC1 > 2:

 $\begin{array}{l} 4.8 \ V \leq VCC1 \leq 5.2 \ V \\ 3.3 \ V \leq VCC2 < VCC1 \end{array}$

2.6.5 LED Display When the Emulator Starts Up Normally

After the emulator starts up, check the status of the LEDs to see whether the emulator operation is enabled or not. Figure 2.7 shows the positions of the emulator status LEDs.



Figure 2.7 Positions of the system status LEDs and target status LEDs

(1) System status LEDs

Check that the LED1 and LED2 of the system status LEDs are lit immediately after the power is activated. If it is not lit, shut off the emulator and check the power supply for the emulator is properly connected.

(2) Target status LEDs

Target status LEDs light as shown in Figure 2.8 when the user system is not connected and as shown in Figure 2.9 when a user system is connected. After turning on the power, only the LED5 (RESET) lights on. Check the target status LEDs display normally after starting up the emulator debugger.

When the target status LEDs do not display as shown in Figures 2.8 and 2.9, refer to "5. Troubleshooting" (page 90).







Figure 2.9 Target status LEDs display when the emulator starts up normally (when user system connected)

IMPORTANT

Note on the Target Status CLOCK LED:

- If the LED is not turned on, check the following.
 - (1) After powering on the emulator (before starting up the emulator debugger):
 - Make sure that the oscillator circuit board is properly installed in the emulator and it is oscillating normally.
 - (2) After the emulator debugger is started up (after the Init dialog box settings are completed): Make sure that the oscillator selected in the Init dialog box is oscillating normally.

2.7 Self-check

2.7.1 Self-check Procedure

To run the self-check of the emulator, do so as explained here below. While the self-check is in progress, the LEDs will change as shown in Figure 2.10.

- (1) If the user system is connected, disconnect it.
- (2) Set the switches as the factory-settings to execute the self-check (see Table 2.3).
- (3) Within 2 seconds of activating power to the emulator, press the system reset switch on the emulator upper panel.
- (4) Check the SAFE LED starts flashing and then press the system reset switch again.
- (5) The self-check will start. If the normal result is displayed in about 10 seconds, the self-check terminated normally.

Table 2.3 Switch settings for the self-check

Switch	Setting
MCU power supply source selection jumper (JP1)	INT
MCU power supply voltage selection jumper (JP2)	5V



Figure 2.10 LED display during the self-check

2.7.2 If an Error is Detected in the Self-check

Table 2.4 lists how to remedy the troubles if the target status LED display is abnormal in the self-check. When an error is detected, shut off the emulator and the user system and follow the steps in the Table 2.4.

Table 2.4 Error display in the self-check and how to remedy it

LED display				
				Problem & Remedy
	Blinking	OFF		
POWER	CLOCK	RESET	RUN	
				The emulator system is not working properly. - Check that power is supplied to the emulator.
				- The emulator may be damaged. Contact your local distributor.
				A clock is not supplied to the emulator.
			-	- Check that the oscillator circuit board (OSC-3) is attached.
				The power is not supplied to the emulator.Check that the power supply cable is connected properly.Check of jumper switch settings (see Table 2.3).
				The block 0 area (address FFF000hFFFFFh) may be rewritten when debugging in the CPU rewrite mode.Within 2 seconds of activating power to the emulator, press the system reset switch to restart the emulator debugger. The firmware will be redownloaded.
				The emulator system is not working properly. - The emulator may be damaged. Contact your local distributor.
	- [- [- [

IMPORTANT

Notes on the Self-check:

- Be sure to disconnect the user system before executing the self-check.
- Use the preinstalled oscillator circuit board OSC-3 (32 MHz) to execute the self-check.
- If the self-check does not result normally (excluding target status errors), the emulator may be damaged. Then, contact your local distributor.

2.8 Connecting the User System

Figure 2.11 shows the connection of the M30850T2-CPE and the user system.



Note on Connecting the User System:

• Take care not to attach the converter board in a wrong direction. It may cause a fatal damage to the emulator and user system.

2.8.1 Connecting to a 100-pin LCC socket

Here following is a procedure of connecting to a 100-pin LCC socket (Yamaichi Electronics Co., Ltd.: IC61-1004-051, etc.) on the user system.

- (1) Attach the CN2 side of the M30850T2-CPE to the CN2 side of the M30800T-PTC.
- (2) Attach the M30800T-PTC to the 100-pin LCC socket.



Figure 2.12 Connecting to a 100-pin LCC socket

Notes on Connecting the User System:

- Take care not to attach a converter board in a wrong direction. It may cause a fatal damage to the emulator and user system.
- The connectors of the M30850T2-CPE and M30800T-PTC are guaranteed for only 50 insertion/removal iterations.
- For purchasing the IC61-1004-051 or for technical information, contact Yamaichi Electronics Co., Ltd.

2.8.2 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 1)

Figure 2.13 shows how to connect the compact emulator to a 100-pin 0.65-mm-pitch foot pattern on the user system with the M3T-DUMMY100S (not included), and here following is its procedure.

For details on the M3T-100LCC-DMS and M3T-DUMMY100S, refer to each user's manual.

- (1) Mount the M3T-DUMMY100S to the user system.
- (2) Attach the M3T-100LCC-DMS to the M3T-DUMMY100S.
- (3) Attach the M30800T-PTC to the M30850T2-CPE.
- (4) Attach the M30800T-PTC to the M3T-100LCC-DMS.



Figure 2.13 Connecting to a 100-pin 0.65-mm-pitch foot pattern (part 1)

Notes on Connecting the User System:

- Take care not to attach a converter board in a wrong direction. It may cause a fatal damage to the emulator and user system.
- The small connectors of the M3T-100LCC-DMS and the M3T-DUMMY100S are guaranteed for only 20 insertion/removal iterations.
- The small connectors of the M30850T2-CPE and M30800T-PTC are guaranteed for only 50 insertion/removal iterations.

2.8.3 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 2)

Figure 2.14 shows how to connect the compact emulator to a 100-pin 0.65-mm-pitch foot pattern on the user system with the M3T-DIRECT100S (not included), and here following is its procedure. For details on the M3T-100LCC-DMS and M3T-DIRECT100S, refer to each user's manual.

- (1) Attach the M3T-DIRECT100S to the user system.
- (2) Attach the M3T-100LCC-DMS to the M3T-DIRECT100S.
- (3) Attach the M30800T-PTC to the M30850T2-CPE.
- (4) Attach the M30800T-PTC to the M3T-100LCC-DMS.



Figure 2.14 Connecting to a 100-pin 0.5-mm-pitch foot pattern (part 2)

Notes on Connecting the User System:

- Take care not to attach a converter board in a wrong direction. It may cause a fatal damage to the emulator and user system.
- The small connectors of the M3T-100LCC-DMS and M3T-DIRECT100S are guaranteed for only 20 insertion/removal iterations.
- The small connectors of the M30850T2-CPE and M30800T-PTC are guaranteed for only 50 insertion/removal iterations.

2.8.4 Connecting to a 100-pin 0.65-mm-pitch Foot Pattern (Part 3)

Figure 2.15 shows how to connect the compact emulator to a 100-pin 0.65-mm-pitch foot pattern on the user system with the M3T-FLX-100NRB (not included), and here following is its procedure. For details on the M3T-100LCC-DMS and M3T-FLX-100NRB, refer to each user's manual.

- (1) Attach the M3T-FLX-100NRB to the user system.
- (2) Attach the M3T-100LCC-DMS to the M3T-FLX-100NRB.
- (3) Attach the M30800T-PTC to the M30850T2-CPE.
- (4) Attach the M30800T-PTC to the M3T-100LCC-DMS.



Figure 2.15 Connecting to an 100-pin 0.65-mm-pitch foot pattern (part 3)

Notes on Connecting the User System:

- Take care not to attach a converter board in a wrong direction. It may cause a fatal damage to the emulator and user system.
- The small connectors of the M3T-100LCC-DMS and M3T-FLX-100NRB are guaranteed for only 20 insertion/removal iterations.
- The small connectors of the M30850T2-CPE and M30800T-PTC are guaranteed for only 50 insertion/removal iterations.

*NQPACK, YQPACK, YQSOCKET, YQ-GUIDE, HQPACK, TQPACK and TQSOCKET are trademarks of Tokyo Eletech Corporation.
2.8.5 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 1)

Figure 2.16 shows how to connect the compact emulator to a 100-pin 0.5-mm-pitch foot pattern on the user system with the M3T-100LCC-QSD (not included), and here following is its procedure. For details on the M3T-100LCC-QSD, refer to its user's manual.

- (1) Attach the M3T-100LCC-QSD to the user system.
- (2) Attach the M30800T-PTC to the M30850T2-CPE.
- (3) Attach the M30800T-PTC to the M3T-100LCC-QSD.



Figure 2.16 Connecting to a 100-pin 0.5-mm-pitch foot pattern (part 1)

- Take care not to attach the converter board in a wrong direction. It may cause a fatal damage to the emulator and the user system.
- The small connectors of the M30850T-CPE and M30800T-PTC are guaranteed for only 50 insertion/removal iterations.

2.8.6 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 2)

Figure 2.17 shows how to connect the compact emulator to a 100-pin 0.5-mm-pitch foot pattern on the user system with the M3T-FLX-100NSD (not included), and here following is its procedure. For details on the M3T-100LCC-DMS and M3T-FLX-100NSD, refer to each user's manual.

- (1) Attach the M3T-FLX-100NSD to the user system.
- (2) Attach the M3T-100LCC-DMS to the M3T-FLX-100NSD.
- (3) Attach the M30800T-PTC to the M30850T2-CPE.
- (4) Attach the M30800T-PTC to the M3T-100LCC-DMS.



Figure 2.17 Connecting to a 100-pin 0.5-mm-pitch foot pattern (part 2)

- Take care not to attach the converter board in a wrong direction. It may cause a fatal damage to the emulator and user system.
- The small connectors of the M3T-100LCC-DMS and M3T-FLX-100NSD are guaranteed for only 20 insertion/removal iterations.
- The small connectors of the M30850T2-CPE and M30800T-PTC are guaranteed for only 50 insertion/removal iterations.

2.8.7 Connecting to a 100-pin 0.5-mm-pitch Foot Pattern (Part 3)

Figure 2.18 shows how to connect the compact emulator to a 100-pin 0.5-mm-pitch foot pattern on the user system with the M3T-F160-100NSD (not included), and here following is its procedure. For details on the M3T-F160-100NSD, refer to its user's manual.

(1) Mount the NQPACK100SD included with the M3T-F160-100NSD to the user system.

- (2) Attach the YQPACK100SD included with the M3T-F160-100NSD to the NQPACK100SD.
- (3) Insert the YQ-GUIDE's included with the YQPACK100SD to the YQPACK100SD.
- (4) Attach the M3T-F160-100NSD to the YQPACK100SD.
- (5) Attach the M30850T2-CPE to the M3T-F160-100NSD.



Figure 2.18 Connecting to a 100-pin 0.5-mm-pitch foot pattern (part 3)

- Take care not to attach the converter board in a wrong direction. It may cause a fatal damage to the emulator and user system.
 - The small connectors of the M30850T2-CPE and M3T-F160-100NSD are guaranteed for only 50 insertion/removal iterations.

2.8.8 Connecting to a 144-pin 0.5-mm-pitch Foot Pattern

Figure 2.19 shows how to connect the compact emulator to a 144-pin 0.5-mm-pitch foot pattern on the user system with the M3T-FLX-144NSD (not included), and here following is its procedure. For details on the M3T-FLX-144NSD, refer to its user's manual.

- (1) Attach the NQPACK144SD included with the M3T-FLX-144NSD to the user system.
- (2) Attach the YQPACK144SD included with the M3T-FLX-144NSD to the NQPACK144SD.
- (3) Insert the YQ-GUIDE's included with the YQPACK144SD to the YQPACK144SD.
- (4) Attach the M3T-FLX-144NSD to the YQPACK144SD.
- (5) Attach the M30850T2-CPE to the M3T-FLX-144SD.



Figure 2.19 Connecting to a 144-pin 0.5-mm-pitch foot pattern

- Take care not to attach the converter board in a wrong direction. It may cause a fatal damage to the emulator and user system.
 - The small connectors of the M30850T2-CPE and M3T-FLX-144NSD are guaranteed for only 50 insertion/removal iterations.

2.9 Changing Settings

2.9.1 Setting Switches of Emulator

Set the switches of the emulator according to the condition.



Figure 2.20 Positions of the switches

(1) MCU Power Supply Source Selection Jumper/MCU Power Supply Voltage Selection Jumper

These are the jumper switches to select power supply to the MCU and its power voltage. As shown in Table 2.5 below, set the switch according to the connection to the user system.

Table 2.5 Setting jumper switches

Connection to the user system	MCU power supply source selection jumper (JP1)	MCU power supply voltage selection jumper (JP2)	Description
Not connected	INT	3.3 V	Supplied from the emulator. The MCU operating voltage is 3.3 V.
Not connected		5.0 V	Supplied from the emulator. The MCU operating voltage is 5.0 V.
Connected	EXT	Invalid	Supplied from the user system. This emulator consumes max. 500 mA of electrical current from the user system.

Note on Setting Jumper Switches:

- Always shut OFF the emulator before changing the setting of the jumper switches, and connecting the cable. Otherwise the internal circuit may cause a break.
- When the MCU power supply source selection jumper and MCU power supply voltage selection jumper are set to INT and 5.0 V respectively, the selection jumper JP1 on the M30850T2-EPBM must be set as VCC1=VCC2 side.

JP1, SW1 to SW4 of the M30850T2-EPBM are on the emulator side panel. Table 2.6 shows the settings of JP1, SW1 to SW4 on the M30850T2-EPBM.

Switch	Switch name	Setting	Description
JP1*	VDDIO	(Factory-setting)	$3.0 \text{ V} \le \text{VCC1} = \text{VCC2} \le 5.5 \text{ V}$
		VCC1=2	4.8 V \leq VCC1 \leq 5.2 V and 3.3 V \leq VCC2 $<$ VCC1
SW1	AVCC	AVCC INT AVSS EXT INT (Factory-setting)	Connects pins AVCC and AVSS of the MCU to the user system.
	AVSS	AVCC AVSS EXT INT	Connects pin AVCC of the MCU to the internal power supply of the emulator, and connects pin AVSS to the GND in the emulator.
		P87 XCIN VCONT (Factory-setting)	Connects pin P87 of the MCU to the user system.
SW2	P87	P87 XCIN VCONT	Connects pin P87 of the MCU to the sub-clock oscillator circuit (32.768 kHz).
		P87 XCIN VCONT	Do not set to VCONT. Pin P87 is disconnected.
		P86 NC VSS (Factory-setting)	Connects pin P86 of the MCU to the user system.
SW3	P86	P86 NC VSS	Does not connect pin P86 of the MCU.
		P86 NC VSS	Do not set to VSS. Connects pin P86 to the VSS in the emulation probe.
SW4	XOUT	(Factory-setting)	Does not connect pin XOUT of the MCU.
		NC XOUT	Connects pin XOUT of the MCU to the user system.

Table 2.6 Switch settings of the M30850T2-EPBM (JP1, SW1 to SW4)

* This JP1 is not the MCU Power Supply Source Selection Jumper (JP1) on the upper side of the emulator. Be careful about the direction when connecting.

(3) Setting SW5 on the M30850T2-EPBM

Table 2.7 lists the examples of setting the switch SW5. It is necessary to change the setting if using the analog input port selection function of the A/D converter.

Setting the SW5 enables to set each analog input pin for selecting an analog input port. When selecting AN00 to AN07 or AN20 to AN27 for the analog input port select bits (bit 2 and bit 1 of 0394h), set the pins used for A/D conversion to ON, the pins not used to OFF.

Analog input port	Setting	Description
When not using the analog input port selection function	AD ON 0 7	 This is the setting when not using the analog input port selection function. When using this product with the conditions below, use this setting. When using the memory expansion mode When using the multi-port sweep mode When selecting AN0 to AN7 for analog input port select bits When selecting AN150 to AN157 for analog input port select bits
When using AN23 to AN27	AD23 to AD27 used: ON AD ON 0 7 OFF 0 0 0 0 0 7 AD20 to AD22 unused: OFF	This is a setting when using the analog input port selection function and using AN23 to AN27 for analog input pins. Set the analog input pins to ON. With this setting, set the direction registers of ports P153 to P157 to input. Pins P150 to P152 can be used for I/O port, ISTxD0, ISCLK0 and ISRxD0.
When using AN20 to AN27	AD20 to AD27 used: ON AD ON 0 7 OFF 0 0 0 0 7 OFF 0 0 0 0 7	This is a setting when using the analog input port selection function and using AN20 to AN27 for analog input pins. Set the analog input pins to ON. With this setting, set the direction registers of ports P150 to P157 to input. Pins P150 to P157 cannot be used for I/O port, ISTxD0, ISCLK0 and ISRxD0.
When using AN04 to AN07	AD04 to AD07 used: ON AD ON 0 7 OFF 0 0 0 0 7 OFF 0 0 0 0 7 AD 00 0 0 7 OFF 0 0 0 0 0 7 AD 00 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	This is a setting when using the analog input port selection function and using AN04 to AN07 for analog input pins. Set the analog input pins to ON. With this setting, set the direction registers of ports P154 to P157 to input. Pins P150 to P153 can be used for I/O port, ISTxD0, ISCLK0 and ISRxD0.
When using AN03 to AN05 and AN25 to AN27	AD03 to AD05 used: ON AD25 to AD27 used: ON AD ON 0 7 OFF 0 0 0 0 7 AD00 to AD02 unused: OFF AD20 to AD22 unused: OFF	This is a setting when using the analog input port selection function and using AN03 to AN05 and AN25 to AN27 for analog input pins. Set the analog input pins to ON. With this setting, set the direction registers of ports P153 to P157 to input. Pins P150 to P152 can be used for I/O port, ISTxD0, ISCLK0 and ISRxD0.

Table 2.7 Switch settings of t	he M30850T2-EPBM (SW5)
--------------------------------	------------------------

IMPORTANT

Notes on Switch JP1 of the M30850T2-EPBM:

- If using this product when the voltage of VCC1 is higher than that of VCC2, set the JP1 to VCC1>2.
- If using a CPU clock of more than 30MHz when using the voltage of VCC1 is higher than that of VCC2, set the SFR area of the intelligent I/O function to 2-wait (set the PM13 bit to "1") when reading this area.

These precautions only need to be observed when using an emulator, and does not apply for the actual MCU.

IMPORTANT

Notes on Switch SW5:

- When using this product in memory expansion mode, be sure to set the all SW5 to ON.
- When setting the register below to use the analog input port selection function, you need to set the direction register of port P15 for a pin that performs A/D conversion to "input".

And you need to set the function selection register of port P15 for a pin that performs A/D conversion to "I/O port".

A/D0 control register 2 (address 394h)

b2, b1

1, 0 : AN00 to AN07

1, 1 : AN20 to AN27

Also, when the P0 group and P2 group are selected for A/D input, port P15 cannot be used as an I/O port. When setting the register above, port P15 cannot be used as an I/O port even if A/D conversion is halting.

• When using the A/D converter in multi-port sweep mode, be sure to set the all SW5 to ON. When setting the register below to use multi-port sweep mode, you need to set the direction register of port P15 for a pin that performs A/D conversion to "input".

And you need to set the function selection register of port P15 for a pin that performs A/D conversion to "I/O port".

A/D0 control register 4 (address 392h)

b3, b2

1, 0 : AN0 to AN7, AN00 to AN07

1, 1 : AN0 to AN7, AN20 to AN27

Also, when the P0 group and P2 group are used for multi-port sweep mode, port P15 cannot be used as an I/O port. When setting the register above, port P15 cannot be used as an I/O port even if A/D conversion is halting. Because a converter board and other devices are used between the evaluation MCU and the user system, the A/D converter operates differently from an actual MCU. Make the final evaluation of the A/D converter using an actual MCU.

2.9.2 Selecting Clock Supply

You can choose a clock supplied to the evaluation MCU by the Emulator tab in the Init dialog box of the emulator debugger. Table 2.8 shows the clocks and their initial settings.

Table 2.8 Clock supply to the MCU

Clock	Emulator debugger display	Description	Initial setting
Main (V. V.)	Internal	Internal oscillator circuit board (OSC-3 or OSC-2)	Yes
Main (X _{IN} -X _{OUT})	External	Oscillator circuit on the user system	-
Cub (V V)	Internal	Internal oscillator circuit (32.768 kHz)	-
Sub (X_{CIN} - X_{COUT})	External	Oscillator circuit on the user system	Yes

(1) Using an Internal Oscillator Circuit Board

1. Kinds of Oscillator Boards

The M30850T2-CPE comes with an oscillator circuit board OSC-3 (32 MHz). And an oscillator circuit bare board OSC-2 is included with this product. If you use an internal oscillator circuit board of the emulator as a main clock, choose "Internal" in the emulator debugger after replacing oscillator circuit boards to change a clock supplied to an MCU.

2. Replacing Oscillator Circuit Boards

Figure 2.21 shows how to replace the oscillator circuit boards.



Figure 2.21 Replacing oscillator circuit boards



3. Using the Internal Oscillator Circuit Bare Board

To use this product at a frequency you like, build a desired oscillator circuit on the included OSC-2 oscillator circuit bare board. Figure 2.22 shows an external view of the OSC-2 oscillator circuit bare board and the connector pin locations. Figure 2.23 shows the circuitry of the oscillator circuit bare board OSC-2. Use the number of oscillator circuits recommended by the oscillator manufacturer.



Figure 2.22 External view of the oscillator circuit board OSC-2 and its connector pin locations



Figure 2.23 Circuits of the oscillator circuit bare board OSC-2

(2) Using an Oscillator Circuit on the User System

To operate this product with an external clock, construct an oscillator circuit as shown in Figure 2.24 in the user system and input the oscillator output at 50% duty (within the operating range of the evaluation MCU) into pin X_{IN} . And pin X_{OUT} should be open. Choose "External" in the emulator debugger to use this clock.





Make note that in the oscillator circuit shown in Figure 2.25 where a resonator is connected between pins X_{IN} and X_{OUT} , oscillation does not occur because a converter board and other devices are used between the evaluation MCU and the user system. It is same for sub-clock oscillator circuits (X_{CIN} and X_{COUT}).



Figure 2.25 Circuit in which oscillation does not occur

2.9.3 A/D Conversion Bypass Capacitors

There is a foot pattern on the M30850T2-EPBM board for mounting bypass capacitors for an A/D conversion circuit near the MCU. Mount suitable bypass capacitors as occasion demands. Figure 2.26 shows where they are installed and the configuration of this product.



Figure 2.26 Foot pattern for A/D conversion bypass capacitors and the configuration of this product

IMPORTANT

Note on the A/D Converter Function:

• Because a converter board and other devices are used between the evaluation MCU and the user system, the A/D converter operates differently from that of an actual MCU. Make the final evaluation of the A/D converter with an actual MCU.

3. Usage (Emulator Debugger)

This chapter describes how to start up the emulator debugger and how to use the major windows.

3.1 Starting Up the Emulator Debugger (Init Dialog Box)

(1) MCU tab

1. Specifying the MCU file

Init X MCU Debugging Information Emulator Resume MCU: Refer Serial No: 2-M30850-4CM030 Self Check	 Specifying the MCU file Click the "Refer" button. A file selection dialog box will be displayed, so select the desired MCU file. The MCU file contains the information specific to the target MCU. The MCU file you have selected is displayed in the MCU section of the MCU tab.
Resource Image: Enable the Address Match Interrupt Break Function. Debug the program using the Watchdog Timer. Debug the program using the CPU Rewrite Mode. Enable the Trace Point Function. OK Cansel Help Next Hide	Shows the currently connected emulators in list form. Select the serial No. of the emulator you want to be connected.

2. Using or not using the address match break function

MCU: m30850.mcu Refer Serial No: 2-M30850-4CM030 Self Check Resource Resource Resource Debug the Address Match Interrupt Break Function. Debug the program using the Watchdog Timer. Debug the program using the CPU Rewrite Mode. Enable the Trace Point Function.	мси	Debugging	Information E	mulator Re	sume		
Resource Thable the Address Match Interrupt Break Function. Debug the program using the Watchdog Timer. Debug the program using the CPU Rewrite Mode.	MCU:	m30850.mc	u			Refer	
Resource Thable the Address Match Interrupt Break Function. Debug the program using the Watchdog Timer. Debug the program using the CPU Rewrite Mode.	Serial N	lo.:	2-M30850-4	СМ030			_
		nable the Debug the p Debug the p	program using t program using t	he Watchdo he CPU Rei	reak Funct g Timer.	ion.	

Using or not using the address match break function

Specify whether or not to use the address match break function.

- To use the address match break function (default), select the check box (marked by a check mark when selected). In this case, the address match interrupt is used by the emulator, and cannot be used in the user program.
- When not using the address match break function, deselect the check box (check mark cleared). In this case, the address match interrupt can be used in the user program.

This option can be selected or deselected only when you are starting up the emulator debugger.

3. Using or not using the watchdog function



IMPORTANT

Notes on selection of whether or not to use the watchdog timer:

• If the check box "Debug the program using the Watchdog Timer" is selected, while the user program remains idle the emulator is performing refresh processing (by writing to the watchdog timer start register) within the emulator control program.

Therefore, the watchdog timer starts after the user program has stopped.

- To use the watchdog timer to debug the user program, select this check box. If this check box is unselected, the emulator may run out of control after the user program has stopped.
- To debug a user system that does not use the watchdog timer, do not select this check box. If this check box is selected, the watchdog timer starts after the user program has stopped, so that if the user program is reexecuted, the watchdog timer underflows generating a watchdog timer interrupt or a reset.

4. Using or not using the CPU rewrite mode



5. Using or not using the trace point function



6. Executing the self-check

Init		×
MCU	Debugging Information Emulator Resume	
MCU:	m30850.mcu Refer	
Serial	No.: 2-M30850-4CM030 -	
⊢ Re:	source	
	Enable the Address Match Interrupt Break Function. Debug the program using the Watchdog Timer.	
	Debug the program using the CPU Rewrite Mode. Enable the Trace Point Function.	
_		
	OK Cansel Help Next Hid	le

Using or not using CPU rewrite mode

Specify whether or not to debug in CPU rewrite mode. To debug the user system that uses CPU rewrite mode, select the check box. This option can be selected or deselected only when you are starting up the emulator debugger. [Supplementary explanation]

When debugging in CPU rewrite mode is enabled, the following functions cannot be used:

- Setting the address match breakpoint
- Software breakpoint setting in the internal ROM area
- Execution of COME in the internal ROM area

Using or not using the trace point function The emulator has two-point events, which are shared by the trace function and the hardware break function. Specify whether or not to use the trace point function. When not using the trace point function (default), deselect the check box. In this case, the events are used for the hardware break function. To use the trace point function, select the check box. In this case, the events are used for the trace point function. To use the trace point function, select the check box. In this case, the events are used for the trace point function.

Executing the self-check				
Enable this function when you want the emulator to be self-				
checked at startup. Be sure to select the check box only				
when you want the emulator to be self-checked at startup.				
This function may be enabled in the following cases:				
- When you are using the emulator you have just purchased				
- When you fail to download the firmware				
- When you successfully download the firmware, but fail				
to start up the emulator				
- When you want to confirm whether the emulator is				
operating normally because, for example, the MCU runs				
out of control or something is wrong with the trace				
results				

This function can be enabled only when you are starting up the emulator debugger.

(2) Debugging Information tab

1. Specifying the compiler used and the object format



Specifying the compiler used and the object format

Specify the compiler you are using and the format of the object file output by the compiler.

- Compiler

Select the compiler you are using.

(By default, the C compiler from Renesas is selected.)

- Object Format

Select the format of the object file that is output by the compiler you are using.

Specifying the method for storing debug information

There are two methods for storing debug information: onmemory method where data is held in memory and an ondemand method where data is held in a temporary file.

- On Memory

This method helps to speed up processing if your computer has sufficient memory.

- On Demand

This method helps to reduce the amount of memory needed. To use this method, select the "On Demand" check box.

(3) Emulator tab

1. Specifying the target clock



Spe	ecifying the target clock
Spec	ify the clock sources supplied to the MCU (main cloch
and	sub clock). Select the appropriate clock source
acco	rding to the clock used by your target MCU.
- Ir	nternal
Е	mulator's internal clock
- E	xternal
U	ser system clock
The	option you have specified here remains effective the
next	time you start up.

(4) Resume tab

1. Automatically executing a script command

Init	×
MCU Debugging Information Emulator Resume	
Init File: Refer	
⊽ Resume	
T AutoDownLoad	
OK Cansel Help Next Hid	e

Automatically executing a script command

To automatically execute a script command when starting up the debugger, click the "Refer..." button and specify the script file to be executed.

Clicking the "Refer..." button brings up a file selection dialog box. The script file you have selected is displayed in the Init File: section of the dialog box shown here. If you do not want to automatically execute a script command, delete the character string displayed in the Init File: section of the dialog box.

What you specify here is reflected at only startup. If you specify back again in the Init dialog box after startup, whatever you specified has no effect. (Be sure to restart the emulator debugger.)

2. Restoring the last window state



Restoring the last window state

To restore the window state (window position and window size) in which you last closed the debugger, select the "Resume" check box. (This check box is by default selected.)

Downloading the load module again

To download the load module (user program) again, select the "AutoDownLoad" check box. (This check box is by default deselected.)

3.2 Starting Up the Emulator Debugger (EMEM Dialog Box)

(1) STATUS tab

1. Specifying the processor mode

Emem X	Specifying the processor mode Select the appropriate processor mode that suits your system.
Processor Mode: MCU Status MCU Status MCU Status MCU Status MCU Status Memory Expansion 8 Bit Memory Expansion 16	
OK Cansel Help Next Hide	

IMPORTANT

Notes on Selecting a Processor Mode:

- When setting single-chip mode or memory expansion mode, the level of pin CNVSS of the MCU status should be "L". The MCU status shows the pin level of the user system.
- When setting memory expansion mode, pins RDY# and HOLD# of the user system should be "H".
- When the user system is not connected, all modes are available.

1. Referring to the MCU Status

Emem Status Emulation Memory Flash Clear	×	
Processor Mode: MCU Status MCU Status MCU Status MCU Status Memory Expansion 16 Bit Memory		Referring to the MCU Status It shows the status of each MCU pin. Check it to see if the MCU status matches the selected processor mode. If a slider is at the center, it means that the pin status is indeterminate.

IMPORTANT

Notes on Selecting a Processor Mode:

- The MCU status is shown in "MCU Status" of the EMEM dialog box. Check that it is matching the specified processor mode.
- Check that the RDY# and HOLD# are "H" level. If they are "L" level, as the MCU enters a wait status and the emulator debugger cannot receive the signal from the MCU, an error is displayed.

(2) Emulation Memory tab

1. Setting the Bank Address of the Debug Monitor



(3) Flash Clear tab

1. Setting to clear the MCU's internal flash ROM



Setting to clear the MCU's internal flash ROM

Specify whether or not you want the MCU's internal flash ROM to be cleared when downloading the user program or data. (When cleared, the content of the flash ROM is initialized to 0xFF.) The MCU's internal flash ROM is listed in block units.

- Any block which has had its check box selected is not cleared when downloading. The memory content of this block remains intact unless overwritten by downloading.
- Any block which has had its check box deselected is cleared when downloading.
- Click the Select All button, and all blocks will be selected (marked by a check mark, so that none of the blocks is cleared when downloading).
- Click the Clear All button, and all blocks will be deselected (check marks removed, so that all of them are cleared when downloading).

The option you have specified here remains effective the next time you start up.

3.3 Program Window

- (1) Downloading the program
- 1. Downloading from the work space window





Download the object program you want to debug.

Select Download from "xxx.x30" of "Download module".

Or you can select "Download" from the "Debug" menu for the same effect.

2. Showing the source program



Editor (source) window

The editor (source) window is a window that always shows the content of the source file corresponding to the current position of the program counter.

The program counter position is marked by a yellow arrow. Here, you can execute the program up to the cursor position, and set or clear software breakpoints.

Because the present emulator uses the MCU's internal flash ROM, the initial value for the ROM area data at the time of purchase is "FFh."

(2) Program execution

1 Resetting the user program

<u></u>	

<u>CPU reset</u>
Resets the target MCU.
Or you can select "CPU Reset" from "Debug" menu for the
same effect.

2 Executing the user program (Go)



<u>Go</u>
Runs the program beginning with the current PC position.
Or you can select "Go" from "Debug" menu for the same
effect.

3 Executing the user program (Go Free)



Go Free

Runs the program beginning with the current PC position. The software and hardware breaks set in it are ignored.

4 Executing the user program (Reset Go)



Reset Go
Runs the program after reset.
Or you can select "Reset Go" from "Debug" menu for the

same effect.

5 Step execution of the user program



<u>Step In</u>

Single-steps the program executing each statement (including those in functions).

Step Over

Single-steps the program executing each function call as one step.

Step Out

Exists a function and stops at a statement in the program next to the one that called the function.

Or you can select "Step In" or other corresponding

commands from "Debug" menu for the same effect.

6 Stopping the user program

Or you can select "Stop" from "Debug" menu for the same effect.

7 Editor (Source) window after you have stopped the user program

F0118 6A09		JEQ	F0122H	
F011A 75A1		LDE.W	[A1A0],R1	
⇒ <mark>₹€11C B2</mark>		INC.₩	AO	
F011D B2		INC.W	AO	
F011E C923		ADD.W	#2H,R3	
F0120 FEF3		JMP.B	F0114H	
F0122 F3		RTS		
F0123 D902	sw_wait	MOV.W	#0H,R2	
F0125 77820F00		CMP.W	#000FH,R2	

Editor (Source) window

The position at which the user program has stopped is marked by a yellow arrow.

(3) Setting breakpoints

1. Screen after breakpoint setup



Screen after breakpoint setup There are three types of breakpoints as described below. Address match breakpoint This breakpoint can be set only when you chose to use the address match break function on the MCU tab of the Init dialog box. A breakpoint can be set or cleared by double-clicking in the address match breakpoint display area in the editor (source) window. (A blue circle is displayed at the setting line) Up to eight breakpoints can be set. The address match break causes the program to stop before executing the address at which a breakpoint is set. Software breakpoint A software breakpoint can be set or cleared by doubleclicking the software breakpoint display area in the editor (source) window (A red circle is displayed at the setting line). This is rewritten to a break instruction, therefore, because of rewriting flash ROM, program execution starts with a delay of several seconds after setting ROM area. If the breakpoint you set is a software breakpoint, the program stops before executing the instruction at the set breakpoint. Hardware breakpoint A hardware breakpoint can be set or cleared by rightclicking the breakpoint display area.

If the breakpoint you set is a hardware breakpoint, the program stops after executing the instruction at the set breakpoint (after several cycles).

(4) Executing up to the cursor position

1. Setup procedure for running the program up to the cursor position



2. After the execution has finished

ample h8	1					
Accembly source 1 50 iii keelvlarc 51		#pr	agma section ResetPRG			Ā
Geource file 52						
- <u>A</u> dbactc 53 - <u>A</u> kwarc.c 54	0400	-e	ntry(vect=0) void PowerON	Reset(voi	d)	
A resetprec 55	0408	÷.	set imask cor(1):			
rkc 56	040a		<pre>set_imask_cor(1); _INITSCT();</pre>			
load modules 57						
ample h8abs 58		11	_CALL_INIT();	11	Remove	th
strch 59	040e		_INIT_IOLIB():	11	Use SIM	
ckseth 61	0406		_INTI_TOUTD():	11	026.01%	1 1
62		11	errno=0;	11	Remove	th
63		11	srand(1);	11	Remove	th
64		11	_slptr=NULL;	11	Remove	th
65		11		22		
66 67	0412	11.	HardwareSetup(); set_imask_cor(0);	11	Remove	th
68	0412		Set_Imask_cor(0);			
69	0414	4	main():			
70						
71	0418		_CLOSEALL();	11	Use SIM	11
72		11	CALL END().		D	1.7
73		11.	_CALL_END():	11	Remove	th
1.1.76	0410		alasa().			٠Č
	-	-				2
Te_ No_ Sample N	8.c 🗢 reu	elprec				

Setup procedure for running the program up to the cursor position

- Click the line in the editor (source) window that you want to be executed.
- (2) Click the execution button to the cursor position.

Or you can select "Go to Cursor" from "Debug" menu for the same effect.

3.4 Hardware Breakpoint Setting Window

- (1) Breakpoint setup dialog box
- 1. Opening the hardware breakpoint setup dialog box



2. Hardware Break Point Setting Window in initial state

Image: Pass ADDRE ACCE CONDITION I A1 000000 FETCH (addr) == 000000 I A2 000000 FETCH (addr) == 000000	H/W breakpoint Setting Window in initial state Select the "Enable H/W Break" check box, and this break function will be enabled, allowing you to set hardware breakpoints.
Combination AND Detail PID Enable Detail Reset Save Load Set Close	

3. Opening the break event setting dialog box

Image: Window Provided and Provide	1	Setting Break Event Click the event line at which you want set a break event.
Combination AND Detail. Reset Save Load Set Close		

4. Opening the break event setting dialog box

	Fetch				
	-Setting				
	Range:	(addr) == Addres	ss1		
	Address 1:	000000 💌	Address 2: 🛛	00000	3 E
	Function:				
	Source File :				3
	Function :				3
A	CCESS: FETCH				

Specifying the event type

Click to select the event type you want to set.

- FETCH
 - Detects an instruction prefetch.
- DATA ACCESS
 - Detects a memory access.
- BIT SYMBOL
 - Detects a bit access.

(2) When FETCH is selected

1. Window for setting addresses

A1 - Set Event Status Event Type: FETCH Fetch Setting Range: (addr) == Address1 Address 1: 000000 Address 2: 000000 Address 2: 000000 Address 2: 000000 Address 3: 0000000 Address 3: 000000 Address 3: 0000000 Address 3: 0000000 Address 3: 000000 Address 3: 0000000	Setting the address You can set eight conditions, e.g., a specified address, a specified address range, etc. When you have finished setting the address, click OK.
Address 1: 0000000 • Address 2: 0000000 • For the source of the sou	

(3) When DATA ACCESS is selected

1. Window for setting the address

	Setting the address
A1 - Set Event Status	You can set eight conditions, e.g., a specified address, a
Event Type: DATA ACCESS -	specified address range, etc.
Address: Data Setting Range: Address 1: O00000 • Address 2: Function: • Source File: • Function: • ACCESS: READ ADDRESS: 000000 CONDITION: Gadred) == 000000	

2. Window for setting data

vent Type: DATA ACCESS
Address Data
Setting
Range: (data) == Data1
Data 1: 0000 Data 2: 0000
Access: READ Mask. 0000
ACCESS: READ
ADDRESS: 000000 CONDITION: (addr) == 000000, (data) == 0000

Setting data

You can set two conditions, e.g., specified data or not to compare data.

Setting the access condition

You can set three conditions, e.g., read, write, and read/write. When you have finished setting the data and access condition, click OK.

3. Example Data Settings

Event setting for even-address word access	Setting a break event
MOV.W R0,512h(R0=0203h)	A1
Cycle Label Address Data BUS BHE BIU R/W RWT CPU -00059 000512 0203 ◀ਿb 0 DW W 0 RW	Address 1 :000512 Data 1 :0203
High-order and low-order data effective	MASK :FFFF
	Access :WRITE
Event setting for odd-address word access MOV.W R0,519h(R0=0203h) Cycle Label Address Data BUS BHE BIU R/W RWT CPU	Setting a break event (using 2 events) A1 A2
-00026 000519 0302 16b 0 0W W 0 CW -00025 00051A 0302 16b 1 DW W 0	Address 1 :000519 Address 1 :00051A Data 1 :0300 Data 1 :0002
Odd-address high-order data effective	MASK :FF00 MASK :00FF
Even-address low-order data effective	Access :WRITE Access :WRITE
	Set the combinatorial events to AND.
Event setting for even-address byte access	Setting a break event
MOV.B R0L,516h(R0L=03h)	A1
Cycle Label Address Data BUS BHE BIU R/W RWT CPU	Address 1 :000516
	Data 1 :0003
Low-order data effective	MASK :00FF
	Access :WRITE
Event setting for odd-address byte access MOV.B R0L,515h(R0L=03h)	Setting a break event
Cycle Label Address Data BUS BHE BIU R/W RWT CPU -00046 000515 0315 ≪6b 0 DB W 0 RW	A1 Address 1 :000515
<u>-00046</u> 000515 0315 ≪b 0 BB ₩ 0 R₩ High-order data effective	Data 1 :0300
ווקויטועבו עמנמ בוובטוויב	MASK :FF00
	Access :WRITE

(4) Setting the combinatorial event condition

1. Window for setting the combinatorial event condition



Setting the combinatorial event condition
There are following three conditions that you can choose for
the combinatorial events.
- OR
The program breaks when one of the specified events
occurs.
- AND
The program breaks when all of the specified events
occur.
- AND (Same Time)
The program breaks when the specified events occur at
the same time.
When you have finished setting the combinatorial event
condition, click the "Set" button.

3.5 Trace Window

(1) Trace window

1. Opening the trace window



Range: -065535	i, 000000 Area: Be	efore Break Fil	e: Cycle	-00069	Add	ress: FEC	18E Time	e:				
Cycle	Label	Address	Data	BUS	BHE	BIU	R/W	RWT	CPU	OPC	OPR	
-000691		FE018E	FEFA	16b	0	F	R	0	CPU	1	0	
-000690]	0006CE	0006	16b	0	TATA	W	0	CPU	2	1	
-000689		0006CA	0000	16b	0	RW	R	0	CPU	0	1	
-000688		0006CE	0006	16b	0	RW	R	0	CPU	0	1	
-000687	ļ	FE0190	64FA	16b	0	F	R	0	-	-	-	
-000686		FE0192	FE39	16b	0	F	R	0	-	-	-	
-000685		FE0194	B899	16b	0	F	R	0	CPU	1	0	
-000684		FE0196	C9F8	16b	0	F	R	0	CPU	1	1	
-000683	ļ	0006CE	0006	16b	0	RW	R	0	CPU	0	1	
-000682		FE0198	889E	16b	0	F	R	0	CPU	2	0	
-000681		0006C8	0001	16b	0	RW	R	0	CPU	0	1	
-000680		FE019A	02A1	16b	0	F	R	0 '		-	-	
-000679		FE019C	B299	16b	0	F	R	0	CPU	2	0	
-000678		FE019E	7F08	16b	0	F	R	0	-	-	-	
-000677		FE019E	7F08	16b	1	-	-	1	CPU	2	0	
-000676		FE01A0	C9FE	16b	0	F	R	0	CPU	0	1	
-000675		FE01A2	CIDE	16b	0	F	R	0	-	-	-	
-000674		FE01A2	C1DE	16b	1	-	-	1	-	-	-	_
-000673		FE01A2	C1DE	16b	1	-	-	1	CPU	2	0	-

Trace window

The trace window is used to show the results of real-time trace measurements. It has the following four display modes:

- Bus mode

Bus information per cycle can be inspected. The contents are displayed in order of execution paths.

- Disassemble + data access mixed mode

The executed instruction and the content of the accessed data can be inspected together. Contents are displayed in

order of the execution paths. - Disassemble mode

The execution paths of the executed instructions can be inspected. The contents are displayed in order of execution paths.

- Source mode The execution paths of the source program can be inspected.

These modes can be switched over using the respective toolbar buttons.

The trace window shows the measurement result when a real-time trace measurement has finished. The trace window remains blank until the real-time trace measurement in progress finishes.

Bus display	Explanation of the trace window (bus display)
Image: Construction	 The following explains the displayed contents, from left to right. Address Shows the status of the address bus. Data Shows the status of the data bus. BUS Shows the width of the external data bus. In the present emulator, only "16b" for 16 bits wide bus is displayed. BHE Shows the status (0 or 1) of the BHE (Byte High Enable) signal. If this signal = 0, the odd-address data is valid. BIU Shows the status between the BIU (Bus Interface Unit)
Disassemble display Note of the set of	and memory or I/O.SymbolStatus-: No changeWAIT: Executing the wait instructionRBML: Read (bytes) ML onF: FetchQC: Discontinuous fetchRWML: Read (words) ML onINT: Interrupt acknowledge cycleRB: Read (bytes)WB: Write (bytes)DRB: Read (bytes) by DMADWB: Write (bytes) by DMARW: Read (words)
CMP.W #0000AK,-4H(FB) F0017F 77FC0A00 CMP.W #0000AK,-4H(FB) F017D CMP.W #0000AK,-4H(FB) F017D CMP.W #0000AK,-4H(FB) F017D CMP.W #0000AK,-4H(FB) F017D CMP.W F017D F017D CMP.W F017D	 WW : Write (words) DRW : Read (words) by DMA DWW : Write (words) by DMA - R/W Shows the status of the data bus. Displayed as "R" for Read, "W" for Write, and "-" for no access. - RWT This is the signal to indicate a valid bus cycle. When valid, RWT = 0. The Address, Data, and the BIU signals are effective when this signal is 0. - CPU

Shows the status between the CPU and BIU (Bus

Shows the op-code size in the read data.

Shows the code size except op-code.

Interface Unit).

- OPC

- OPR

REJ10J0865-0300 Rev.3.00 December 16, 2005 REVESAS

(2) Suspending and resuming trace measurement

1. Suspending trace measurement



Click this toolbar button to suspend the trace measurement in progress.

2. Resuming trace measurement

💵 🗸 🖻 🖌	0000	▾◣╤ӟ	2	- <						
lange: -065535	, 000000 Area: Bef	ore Break Fil	e: Cycle	: -00001	5 Addr	ess: F800	064 Time:	_		
Cycle	Label	Address	Data	BUS	BHE	BIU	R/W	RWT	CPU	OF 🔺
-000015		F80064	E8F1	16b	0	F	R	0	-	-
-000014		F80066	9ADO	16b	0	F	R	0	CPU	2
-000013	1	F80068	BBF6	16b	0	F	R	0	CPU	1
-000012		F80068	BBF6	16b	1	-	-	1	-	-
-000011		F80068	BBF6	16b	1	-	-	1	CPU	2
-000010		F8006A	BBCE	16b	0	F	R	0	CPU	2
-000009		F8006C	BBFF	16b	0	F	R	0	CPU	1
-000008		F8005E	8888	16b	0	QC	R	0	CPU	0
-000007		F80060	8 E A 8	16b	0	F	R	0	-	-
-000006		F80062	E88C	16b	0	F	R	0	CPU	2
-000005		7c9B05	E88C	16b	0	RB	R	0	-	-
-000004		F80064	E8F1	16b	0	F	R	0	-	-
-000003		F80066	9ADO	16b	0	F	R	0	CPU	2
-000002		F80068	BBF6	16b	0	F	R	0	CPU	1
-000001		F80068	BBF6	16b	1	-	-	1	-	

Re-Start
Click this toolbar button to resume the trace measurement in
progress.
(3) Trace point setup window

ſ

1. Opening the trace point setup dialog box



2. Trace Point Setting Window in initial state

	nt Status				
	SS E ADDR 1 B1 000000 1 B2 000000) FETCH (add	NDITION r) == 000000 r) == 000000	\checkmark	
			.,		
	bination				
	Diriation	▼ Detail	Enable	Detail	
OR					

Trace Point Setting Window in initial state

Be sure to enable the trace point function in the Init dialog box before you set up in this window. Here, you can set events in the same way as for the hardware breakpoints.

3. Specifying a trace range

Reset Save Load Set Close Close 64K cycles of instruction execution after a trace began is recorded.	Image: Setting Window Event Status PASS E ADDRE ACCE CONDITION 1 B1 000000 1 B1 000000 1 B2 000000 FETCH (addr) == 000000 Combination PID OR Detail Trace Area Write Condition Break Total Detail Reset Save Load Set	 Break 64K cycles of instruction execution before the user program stopped is recorded. Before 64K cycles of instruction execution before a trace point condition was met is recorded. About 64K cycles of instruction execution before and after a trace point condition was met is recorded. After 64K cycles of instruction execution after a trace point condition was met is recorded. Full 64K cycles of instruction execution after a trace began is
--	---	--

4. Setting the trace write condition



3.6 RAM Monitor Window

(1) RAM monitor window

1 Opening the RAM monitor window



_	RAM monitor
	Clicking this button opens the RAM monitor window.
	Or you can select "RAM monitor" from "CPU" of "Display" menu for the same effect.

(2) RAM monitor area setting window

1. Opening RAM monitor area setting window

	Base Clicking this toolbar button opens the RAM monitor area
Image: state	setting window.
Image: Control of the second	

2. RAM monitor area setting window in initial state



3. RAM monitor area setting dialog box

		<u>Sp</u>
Set RRAM Area	F	You
		mon
Start: 000400		
Size: 4 📑 🗲 blocks		<u>Sp</u>
Area: 000400 - 0007FF		You
		num
OK Cancel		byte
	1	

Specifying the start address

ou can set the start address of the RAM area to be nonitored.

Specifying the size

You can set the size to be monitored by specifying the number of blocks from the start address. One block is 256 bytes in size.

4. RAM monitor area setting dialog box when RAM monitor area is changed from 400h to 1 block



5. RAM monitor area setting dialog box



<u>Changing the RAM monitor display area</u> You can change the manner in which the RAM monitor area		
Fou can change the manner in which the KAM monitor area		
you have set in the above dialog box is displayed.		
- †	Shows the blocks at the preceding addresses.	
- ↓	Shows the blocks at the following addresses.	
1	y sections change with the access attribute as	
descri	bed below.	
descri - Gr	bed below. een Addresses accessed for read	
descri - Gr	bed below.	
descri - Gr - Re	bed below. een Addresses accessed for read	

4. Hardware Specifications

This chapter describes specifications of this product.

4.1 Target MCU Specifications

Table 4.1 lists the specifications of target MCUs which can be debugged with this product.

T-11. 4 1 C	· · · : C · · · · · · · ·	- 6 + +	MOLL (C 41	MOOSOTO CDE
1 able 4.1 S	pecifications	of target	MCUS I	for the	M30850T2-CPE

Item	Description		
Applicable MCU	M32C/80, 84, 85 and 86 Groups		
Applicable MCU mode	Single-chip mode, memory expansion mode		
Maxi. ROM/RAM capacity	1. Internal flash ROM: 512KB+4KB		
	0F000h0FFFFh, F80000hFFFFFFh		
	2. Internal RAM: 24KB		
	00400h063FFh		
Operating voltage/frequency	VCC1=VCC2=4.25.5 V: 32 MHz		
	VCC1=VCC2=3.05.5 V: 24 MHz		
	Dual-power supply specification		
	(4.8 V \leq VCC1 \leq 5.2 V and 3.3 V \leq VCC2 $<$ VCC1): 32MHz *		

* If using a CPU clock of more than 30MHz, set the SFR area of the intelligent I/O function to 2-wait (set the PM13 bit to "1") when reading this area.

This precaution only needs to be observed when using an emulator, and does not apply for the actual MCU.

4.2 Differences between the Actual MCU and Emulator

Differences between the actual MCU and emulator are shown below. When debugging the MCU using this product, be careful about the following precautions.

IMPORTANT

```
Notes on the User System (Power Supply, Order of Powering On):
```

- When the user system is connected, be sure to set the JP1 of the emulator to "EXT".
- This emulator cannot supply the power to the user system. Therefore design your system so that the user system is powered separately.
- This emulator consumes max. 500 mA of electric current from the user system.
- The voltage of the user system should be as follows.
 - (1) When JP1 of the M30850T2-EPBM is set as VCC1 = 2:
 - $3.0 \text{ V} \le \text{VCC1} = \text{VCC2} \le 5.5 \text{ V}$
 - (2) When JP1 of the M30850T2-EPBM is set as VCC1 > 2: 4.8 V \leq VCC1 \leq 5.2 V
 - $3.3 V \le VCC1 \le 5.2 V$
- Do not change the voltage of the user system after turning on the power.

Notes on Using This Product When the Voltage of VCC1 is Higher than That of VCC2:

- If using this product when the voltage of VCC1 is higher than that of VCC2, set the JP1 to VCC1>2. For the switch JP1, refer to "2.9 Changing Settings" (page 39).
- When the JP1 is set to VCC1>VCC2, the voltage of VCC2 on the user system should be 3.3 V or more.
- If using a CPU clock of more than 30MHz when the voltage of VCC1 is higher then that of VCC2, set the SFR area of the intelligent I/O function to 2-wait (set the PM13 bit to "1") when reading this area.

These precautions only need to be observed when using an emulator, and does not apply for the actual MCU.

	IMPORTANT
	ences between the Actual MCU and Emulator:
-	erations of the emulator system differ from those of actual MCUs as listed below.
	Reset condition
	Initial values of internal resource data of an MCU at power-on
	Interrupt stack pointer (ISP) after a reset is released
(4)	Capacities of the internal memories (ROM and RAM)
	The MCU whose RAM size is 24 KB (400h63FFh) is mounted on this product. The internal flash memory is automatically allocated to F000hFFFFh and F80000hFFFFFh in the single-chip mode and memory expansion mode.
(5)	Oscillator circuit
	 Make note of the fact that in the oscillator circuit where a resonator is connected between pins X_{IN} and X_{OUT}, oscillation does not occur because a converter board and other devices are used between the evaluation MCU and the user system. It is same for a sub-clock oscillator (X_{CIN} and X_{COUT}). For notes on when using the oscillator circuit on the user system, refer to "2.9.2 Selecting Clock Supply" (page 44).
(6)	A/D conversion
	The characteristics of the A/D converter differ from those of actual MCU because there are a converter board and other devices between the evaluation MCU and the user system.
(7)	Port P15
	As one of I/O ports (P15) is connected to the user system through the analog switch circuit, electric
	characteristics slightly differ from those of an actual MCU.
(8)	When the SW4 is set to XOUT in stop mode, a clock is output from the XOUT pin.
Note on RESE	T# Input:
	ow input to pin RESET# from the user system is accepted only when a user program is being executed en the RUN status LED on the emulator's upper panel is lit).
Note on RDY#	Input:
	sure to input "L" to pin RDY# of the user system during the user program executing (when the RUN status
	D on the emulator's upper panel is lit). Inputting "L" to pin RDY# during the user program stopping may se a malfunction of the emulator.
Note on HOLD	# Input:
● Be s LEI	sure to input "L" to pin HOLD# of the user system during the user program executing (when the RUN status O on the emulator's upper panel is lit). Inputting "L" to pin HOLD# during the user program stopping may se a malfunction of the emulator.

Note on NMI# Input:

• A low input to pin NMI# from the user system is accepted only when a user program is being executed (when the RUN status LED on the emulator's upper panel is lit).

IMPORTANT

Notes on Reset Vector Area:

- For a reset vector area, memory of the emulator is always selected regardless of the setting of the EMEM dialog box.
- A reset vector area can be changed only when a program is stopped.

Notes on Stack Area:

- With this product, a maximum 8 bytes of the user stack is consumed as a work area. Therefore, ensure the +8 byte maximum capacity used by the user program as the use stack area.
 - Even if the user stack does not have an enough area, do not use areas which cannot be used as a stack (SFR area, RAM area which stores data, or ROM area) as a work area. Using areas like this is a cause of user program crashes and destabilized emulator control.
- With this product, the interrupt stack pointer (ISP) is set at 00500h and used as a stack area after a reset is released.

Note on Maskable Interrupts:

• Even if a user program is not being executed (including when run-time debugging is being performed), the evaluation MCU keeps running so as to control the emulator, so the function such as timer is operated. Take note that when the user program is not being executed (including when run-time debugging is being performed), a peripheral I/O interruption is not accepted.

Notes on Access Prohibited Area:

- The emulator control register (000020h--00003Fh) in the SFR is read- and write-protected. When this register is accessed, emulator control cannot be utilized.
- With this product, address FFFFFh cannot be read or written in correctly.

Note on DMA Transfer:

- With this product, the user program is stopped with a loop program to a specific address. Therefore, if a DMA request is generated by a timer or other source while the user program is stopped, DMA transfer is executed. However, make note of the fact that DMA transfer while the program is stopped may not be performed correctly. Also note that the below registers have been changed to generate DMA transfer as explained here even when the user program is stopped.
 - (1) DMA0 transfer count register DCT0
 - (2) DMA1 transfer count register DCT1
 - (3) DMA0 memory address register DMA0
 - (4) DMA1 memory address register DMA1
 - (5) DMA2 transfer count register DCT2 (R0)
 - (6) DMA3 transfer count register DCT3 (R1)
 - (7) DMA2 memory address register DMA2 (A0)
 - (8) DMA3 memory address register DMA3 (A1)

Note on DMAC II Transfer Completion Interrupts:

• You can use DMAC II transfer completion interrupts during program execution only. Do not generate DMAC II transfer completion interrupts when you use any function but program execution.

Note on Final Evaluation:

• Be sure to evaluate your system with an evaluation MCU. Before starting mask production, evaluate your system and make final confirmation with a CS (Commercial Sample) version MCU.

4.3 Connection Diagram

Figures 4.1 and 4.2 show a part of the connection diagram of the M30850T2-CPE. This connection diagram mainly shows the interface section. The signals not shown in Figures 4.1 and 4.2 connect the evaluation MCU and the user system directly. The circuits not connected to the user system such as the emulator's control system are omitted. Table 4.2 shows IC electric characteristics of this product for reference purposes.



Figure 4.1 Connection diagram (1/2)



Figure 4.2 Connection diagram (2/2)

Table 4.2 Electrical characteristics of the 74HC4066

Symbol	Item	Condition	S	Standard values			
Symbol	псш	Vcc	Min.	Standard	Max.	Unit	
Davi	ON register	2.0	-	160	-		
Ron	ON resistor	4.5	-	70	100	Ω	
ΔR on	ON resistor difference	4.5	-	10	-		
Iin	Switch input leak current	12.0	-	-	±100	nA	

4.4 External Dimensions

4.4.1 External Dimensions of the Compact Emulator

Figure 4.3 shows external dimensions of the M30850T2-CPE connected with the M30800T-PTC and LCC socket.



Figure 4.3 External dimensions of the compact emulator

4.4.2 External Dimensions of the M30800T-PTC

Figure 4.4 shows external dimensions of the converter board M30800T-PTC for a 100-pin QFP (100P6S).



Figure 4.4 External dimensions of the M30800T-PTC

4.4.3 External Dimensions of the M3T-F160-100NSD

Figure 4.5 shows external dimensions of the converter board M3T-F160-100NSD for a 100-pin LQFP (100P6Q).



Figure 4.5 External dimensions of the M3T-F160-100NSD

4.4.4 External Dimensions of the M3T-FLX-144NSD

Figure 4.6 shows external dimensions of the converter board M3T-FLX-144NSD for a 144-pin LQFP (144P6Q).



Figure 4.6 External dimensions of the M3T-FLX-144NSD

4.5 Notes on Using This Product

Notes on using this product are listed below. When debugging the MCU using this product, be careful about the following precautions.

IMPORTANT

Notes on the Self-check:

- If the self-check does not result normally (excluding target status errors), the emulator may be damaged. Then contact your local distributor.
- Run the self-check with the user system not connected.

Note on Quitting the Emulator Debugger:

• To restart the emulator debugger after it ends, always shut power to the emulator off once and then on again.

Notes on Clock Supply to the MCU:

- A clock supplied to the evaluation MCU is selected by the Emulator tab in the Init dialog box of the emulator debugger.
 - (1) When "Internal" is selected:

A clock generated by the oscillator circuit board in the M30850T2-CPE is supplied. It is continually supplied regardless of the status of the user system clock and that of the user program execution.

- (2) When "External" is selected: A clock generated by the oscillator in the user system is supplied. It depends on the status of the oscillation (on/off) of the user system.
- When operating this product with a sub clock, be sure to set the SW2 and SW3 to XCIN and NC, respectively.

Notes on Using the CPU Clock at Less than 16 MHz:

• To use the CPU clock at less than 16 MHz, execute the command shown below in the Script Window after starting the emulator debugger.

[Command]

_settimeout 300, 300

Once this command is executed, it remains effective the next time you start the emulator debugger. Therefore, you do not need to execute this command again.

• When you use the CPU clock at less than 1 MHz, contact your local distributor.

IMPORTANT

Notes on EMEM Dialog Box:

Observe the following when setting up EMEM dialog box of the emulator debugger.

- (1) Debug Monitor Bank Address
 - When "E0" is specified, 64 KB of area starting from E00000h are allocated for use by the debug monitor.
 - The 64 KB allocated for the debug monitor cannot be used.
 - The below areas cannot be set for the debug monitor.
 - 1) MCU internal resources (ROM/RAM/SFR area)
 - 2) Multiplex area
 - 3) Interrupt vector area
 - It is not possible to view or set the content of the specified area. Even on the memory window or in the reverse assemble area of the program/source windows, the content of this area is not displayed correctly though it can be displayed.
- (2) Processor Mode
 - Set a processor mode for the target MCU.
 - To set single-chip mode or memory expansion mode, pin CNVSS used with MCU status must be "L". MCU status indicates pin level of the user system.
 - To set memory expansion mode, pins RDY# and HOLD# used with MCU status must be "H".
 - When the user system is not connected, all modes are available.

Notes on Address-Match Interrupts:

- Do not single-step an address where an address-match interrupt occurs.
- When using an address-match interrupt, do not select the check box of "Enable the Address Match Interrupt Break Function" in the MCU tab of the Init dialog box. When not using an address-match interrupt, select the check box.
- When you use address-match breaks, if a low reset is input during a user program execution, a debug monitor program (about 100 cycles) is executed after a reset is released. Take note that it has effects on the user program execution time and the result of a trace.

Notes on the Watchdog Function:

- When using the watchdog function of the MCU, check the box of "Debug the program using the watchdog timer" in the MCU tab of the Init dialog box. If this check box is selected, while the user program remains idle the emulator is performing refresh processing (by writing to the watchdog timer start register) within the emulator control program. If this check box is unselected, the emulator may run out of control after the user program has stopped.
- When not using the watchdog function of the MCU, do not select the box of "Debug the program using the watchdog timer". If this check box is selected, while the user program remains idle the emulator is performing refresh processing (by writing to the watchdog timer start register) within the emulator control program, and the watchdog timer starts. If the user program is reexecuted, the watchdog timer underflows generating a watchdog timer interrupt or a reset.
- If the reset circuit of the user system has a watchdog timer, disable it when using the emulator.

IMPORTANT Notes on Debugging in CPU Rewrite Mode: • To debug a program in CPU rewrite mode, check the box "Debug the program using the CPU Rewrite Mode" in the MCU tab of the Init dialog box. When you do not debug a program in CPU rewrite mode, uncheck the box. • When you debug a program in CPU rewrite mode, the block 0 area (FFF000h--FFFFFh) must not be rewritten. Otherwise, the emulator will be out of control. • When debugging in CPU rewrite mode is enabled, you cannot use the following functions. (1) Setting an address match breakpoint (2) Setting a software breakpoint to the internal ROM area (3) Executing COME to the internal ROM area • Do not use the following functions to the rewrite control program area (from setting CPU rewrite mode select bit to releasing it). If any of these are used, malfunctions may occur (e.g. The emulator cannot shift to CPU rewrite mode or contents of ROM cannot be read our properly.). (1) Single stepping (2) Setting a software breakpoint (3) Setting a hardware breakpoint (4) Executing COME Note on Software Breaks: • A software break generates a break interruption by forcibly inserting a BRK instruction "08h" instead of an instruction code. Therefore, when referencing the result of a trace in bus mode, "08h" is displayed for the instruction fetch address where a software break is set. Note on Downloading Programs: • When you download a program to an internal ROM area and set software breaks, the main clock operates in divide-by-8 mode. Keep it in mind when you specify a watchdog timer refresh interval. Notes on Service-Life of the MCU's Internal Flash ROM: • With the M30850T2-CPE, programs are downloaded to the MCU's flash ROM when debugging in single-chip mode or memory expansion mode. Because the number of write/erase cycles of this ROM is limited, the ROM must be replace when at the end of its service-life. • If the following errors occur frequently during program download, replace the MCU board. Flash ROM erase error occurred ERROR (16258) Flash ROM verify error occurred ERROR (16259) To purchase the product for replacement or request for repair, contact your local distributor. Note on Voltage Detect Circuit: • With the M30850T2-CPE, as the power voltage cannot be change after powering on the user system, the voltage detect circuit (voltage down detect interrupt and hardware reset 2) cannot be used with this product.

IMPORTANT
Note on Protect Register:
 The protect is not canceled when bit 2 of protect register PRCR (PRC2), which enables writing into the port P9 direction register and the SI/Oi control register, is changed with the below procedure. (1) Step execution of an instruction setting PRC2 to "1"
 (2) Setting a break point from an instruction setting PRC2 to "1" to where the port P9 direction register or the function select register A3 is set (3) Setting ("1") PRC2 from the dump window or script window during use program execution
Note on Memory Access:
• When setting memory expansion mode as a processor mode, it may be changed to memory expansion mode temporarily before the user program itself changes from single-chip mode to memory expansion mode. Take due consideration on this phenomenon in the following cases:
(1) Immediately before executing the program after setting a software break(2) Immediately after stopping the program when a software break is set
Notes on A/D Conversion:
 When setting the register below to use the analog input port selection function, you need to set the direction register of port P15 for a pin that performs A/D conversion to "input". And you need to set the function selection register of port P15 for a pin that performs A/D conversion to "I/O port)"
A/D0 control register 2 (address 394h) b2, b1
1, 0 : AN00 to AN07 1, 1 : AN20 to AN27
Also, when the P0 group and P2 group are selected for A/D input, port P15 cannot be used as an I/O port, When setting the register above, port P15 cannot be used as an I/O port even if A/D conversion is halting For the switch SW5, refer to "2.9.1 Setting Switches of Emulator" (page 39).
• When setting the register below to use multi-port sweep mode, you need to set the direction register of port P15 for an pin that performs A/D conversion to "input". And you need to set the function selection register of port P15 for a pin that performs A/D conversion to "I/O port".
A/D0 control register 4 (address 392h)
b3, b2 1, 0 : AN0 to AN7, AN00 to AN07 1, 1 : AN0 to AN7, AN20 to AN27
Also, when the P0 group and P2 group are used for multi-port sweep mode, port P15 cannot be use as an I/O port. When setting the register above, port P15 cannot be used as an I/O port even if a/D conversion is halting.
• Because a converter board and other devices are used between the evaluation MCU and the user system, the A/D converter operates differently from an actual MCU. Make the final evaluation of the A/D converter using an actual MCU.

IMPORTANT

Notes on CE Declaration of Conformity:

- This product complies with CE marking (EN55022: 1998 Class A, EN55024: 1998). Please use it with care described below.
 - * Electrostatic Discharge Precautions must be taken when handling the product.
 - * Must not be used within 30 meters of a domestic radio or television receiver.
 - * For correct operation of this product, it is recommended that Mobile phones are not used within 10 meters of this product system.
 - * This product should be powered down when not in use.
- This product generates, uses, and can radiate radio frequency energy and may cause harmful interference to radio communications.
- If this product causes harmful interference to radio or television reception, which can be determined by turning this product off or on, you are encouraged to try to correct the interference by one or more of the following methods;
 - * Ensure attached cables do not lie across the probe board and converter board.
 - * Reorient the receiving antenna.
 - * Increase the distance between the product and the receiver.
 - * Connect the product into an outlet on a circuit different from that to which the receiver is connected.
 - * Consult the dealer or experienced radio/TV technician for help.
- Attach the ferrite core included with this product close to the DC plug of the power cable. Without the ferrite core it may cause interference.

The power cable should be wound around the ferrite core as shown in the figure, and close the ferrite core until it clicks.



5. Troubleshooting

This chapter describes how to troubleshoot when this product does not work properly.

5.1 Flowchart to Remedy the Troubles

Figure 5.1 shows the flowchart to remedy the troubles from when power to the emulator is activated until the emulator debugger starts up. Check this while the user system is disconnected. For the latest FAQs visit the Renesas Tools Homepage.

http://www.renesas.com/en/tools



Figure 5.1 Flowchart to remedy the troubles

5.2 When the Emulator Debugger Does Not Start Up Properly (1) When the LEDs of the M30850T2-CPE Do Not Display Normally

Error	Connection to the user system	Checkpoint	
LEDs do not light up.	-	Check that the power cable is connected. See "2.4 Connecting a Power Supply" (page 22).	
Target Status POWER LED does not light up.	Connected	Check that power is properly supplied to the user system and the user system is properly grounded.	
Target Status CLOCK LED does not light up.	Not connected	 Check that both the main and sub clocks of the emulator debugger are not set to "EXT". See the CLK command of the emulator debugger. Check that the oscillator circuit board is properly installed in the emulator and is oscillating. See "2.9.2 Selecting Clock Supply" (page 44). 	
	Connected	When the clock is supplied from an external oscillator, check that the oscillator circuit in the user system is oscillating properly.	
Target Status RESET LED does not go out.	Connected	Check that the reset pin of the user system is pulled up.	

(2) MCU Setting Dialog Box Does Not Appear at Debugger Startup

Table 5 2	Charlensinte	of among of	dalar a an atomtron
Table 3.2	Checkpoints	of errors at	debugger startup

Error	Checkpoint	
Communication error occurred.	Check that the USB cable is connected properly.	
Data was not sent to the target.	See "2.5 Connecting the Host Machine" (page 23).	
Not compact emulator.	Check that an emulator other than the compact emulator (such as PC4701, PC7501) is not connected.	
Target MCU is in the reset state.	 (1) Check that the reset pin of the user system is pulled up. (2) Check that the reset pin of the user system has changed from Low to High level. 	
Target MCU cannot be reset.	 (1) Check that pin NMI# is held High. (2) If the reset circuit of the user system has a watchdog timer, disable the timer. (3) Check that power is properly supplied to the user system and that the user system is properly grounded. 	
Target is in "HOLD" state.	The MCU is either in stop mode or wait mode. Either reset the MCU or cancel the mode with an interrupt. <i>See MCU specifications.</i>	
Target clock is stopped.	When the clock is supplied from an external oscillator, check that the oscillator circuit in the user system is oscillating properly.	
Target MCU is not receiving power.	Check that power is properly supplied to the user system and that the user system is properly grounded.	

(3) Errors Occur at Debugger Startup

Error	Checkpoint
Target MCU is uncontrollable.	 Check that the NQPACK etc. mounted on the user system is soldered properly. Check that the connector is installed properly to the user system. Check that pin CNVSS is held Low.

5.3 How to Request for Support

After checking the items in "5 Troubleshooting", fill in the text file which is downloaded from the following URL, then send the information to your local distributor.

)

http://tool-support.renesas.com/eng/toolnews/registration/support.txt

For prompt response, please specify the following information:

- (1) Operating environment
 - Operating voltage: [V]
 - Operating frequency: [MHz]
 - Clock supply to the MCU: Internal oscillator/External oscillator
- (2) Condition
 - The emulator debugger starts up/does not start up
 - The error is detected/not detected in the self-check
 - Frequency of errors: always/frequency (
- (3) Problem

6. Maintenance and Guarantee

This chapter describes how to maintenance, repair provisions and how to request for repair.

6.1 User Registration

When you purchase our product, be sure register as a user. For user registration, refer to "User registration" (page 11) of this user's manual.

6.2 Maintenance

- (1) If dust or dirt collects on any equipment of your emulation system, wipe it off with a dry soft cloth. Do not use thinner or other solvents because these chemicals can cause the equipment's surface coating to separate.
- (2) When you do not use this product for a long period, for safety purposes, disconnect the power cable from the power supply.

6.3 Guarantee

If your product becomes faulty within one year after its purchase while being used under good conditions by observing "IMPORTANT" and "Precautions for Safety" described in this user's manual, we will repair or replace your faulty product free of charge. Note, however, that if your product's fault is raised by any one of the following causes, we will repair it or replace it with new one with extra-charge:

- Misuse, abuse, or use under extraordinary conditions
- Unauthorized repair, remodeling, maintenance, and so on
- Inadequate user's system or misuse of it
- Fires, earthquakes, and other unexpected disasters

In the above cases, contact your local distributor. If your product is being leased, consult the leasing company or the owner.

6.4 Repair Provisions

(1) Repair with extra-charge

The products elapsed more than one year after purchase can be repaired with extra-charge.

(2) Replacement with extra-charge

If your product's fault falls in any of the following categories, the fault will be corrected by replacing the entire product instead of repair, or you will be advised to purchase new one, depending on the severity of the fault.

- Faulty or broken mechanical portions
- Flaw, separation, or rust in coated or plated portions
- Flaw or cracks in plastic portions
- Faults or breakage caused by improper use or unauthorized repair or modification
- Heavily damaged electric circuits due to overvoltage, overcurrent or shorting of power supply
- Cracks in the printed circuit board or burnt-down patterns
- Wide range of faults that makes replacement less expensive than repair
- Unlocatable or unidentified faults

(3) Expiration of the repair period

When a period of one year elapses after the model was dropped from production, repairing products of the model may become impossible.

(4) Transportation fees at sending your product for repair Please send your product to us for repair at your expense.

6.5 How to Make Request for Repair

If your product is found faulty, follow the procedure below to send your product for repair.



Note on Transporting the Product:

• When sending your product for repair, use the packing box and cushion material supplied with this product when delivered to you and specify handling caution for it to be handled as precision equipment. If packing of your product is not complete, it may be damaged during transportation. When you pack your product in a bag, make sure to use conductive polyvinyl supplied with this product (usually a blue bag). When you use other bags, they may cause a trouble on your product because of static electricity.

Compact Emulator for M32C/80, 84, 85 and 86 Groups M30850T2-CPE User's Manual

Publication Date:	Dec. 16, 2005	Rev.3.00	
Published by:	Sales Strategic Planning Div. Renesas Technology Corp.		
Edited by:	Microcomputer Tool Development Department Renesas Solutions Corp.		

© 2005. Renesas Technology Corp. and Renesas Solutions Corp., All rights reserved. Printed in Japan.

M30850T2-CPE User's Manual



Renesas Electronics Corporation 1753, Shimonumabe, Nakahara-ku, Kawasaki-shi, Kanagawa 211-8668 Japan