

RX140 Group

Fast Prototyping Board for RX140 Microcontroller Group
FPB-RX140 v1 User's Manual

Renesas RX Family
RX100 Series

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(Rev.5.0-1 October 2020)

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1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a Microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system evaluation test for the given product.

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This Fast Prototyping Board is only intended for use in a laboratory environment under ambient temperature and humidity conditions. A safe separation distance should be used between this and any sensitive equipment. Its use outside the laboratory, classroom, study area, or similar such area invalidates conformity with the protection requirements of the Electromagnetic Compatibility Directive and could lead to prosecution.

The product generates, uses, and can radiate radio frequency energy and may cause harmful interference to radio communications. There is no guarantee that interference will not occur in a particular installation. If this equipment causes harmful interference to radio or television reception, which can be determined by turning the equipment off or on, you are encouraged to try to correct the interference by one or more of the following measures:

- Ensure attached cables do not lie across the equipment.
- Reorient the receiving antenna.
- Increase the distance between the equipment and the receiver.
- Connect the equipment into an outlet on a circuit different from that which the receiver is connected.
- Power down the equipment when not in use.
- Consult the dealer or an experienced radio/TV technician for help.

Note: It is recommended that wherever possible shielded interface cables are used.

The product is potentially susceptible to certain EMC phenomena. To mitigate against them it is recommended that the following measures be undertaken:

- The user is advised that mobile phones should not be used within 10 m of the product when in use.
- The user is advised to take ESD precautions when handling the equipment.

The Evaluation Kit does not represent an ideal reference design for an end product and does not fulfil the regulatory standards for an end product.

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Renesas RX Family

FPB-RX140 v1 User's Manual

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List of Abbreviations and Acronyms

Table 1. List of Abbreviations and Acronyms

| Abbreviation | Full Form |
|---------------------------|---|
| BoM | Bill of Materials |
| CS | Chip Select |
| CTS | Clear to Send |
| EMC | Electro Magnetic Compatibility |
| EMI | Electro Magnetic Interference |
| EU | European Union |
| FPB | Fast Prototyping Board |
| GPIO | General Purpose Input Output |
| I ² C (or IIC) | Inter-Integrated Circuit |
| IDE | Integrated Development Environment |
| I/F | Interface |
| INT | Interrupt |
| I/O | Input/Output |
| IRQ | Interrupt Request |
| LED | Light Emitting Diode |
| LFQFP | Lead Free Quad Flat Package |
| MCU | Micro Controller Unit |
| MISO | Master In Slave Out |
| MOSI | Master Out Slave In |
| NC | Not Connected |
| PWM | Pulse Width Modulation |
| RIIC | Renesas I ² C |
| RSPI | Renesas SPI |
| RTC | Real Time Clock |
| RTS | Request to Send |
| RXD | Receive Data |
| S12ADE | 12-bit Analog to Digital Converter |
| SCI | Serial Communications Interface |
| SCK | Serial Clock |
| SCL | Serial Clock Line |
| SDA | Serial Data Line |
| SMD | Surface Mount Device |
| SPI | Serial Peripheral Interface |
| TXD | Transmit Data |
| UART | Universal Asynchronous Receiver Transmitter |
| USB | Universal Serial Bus |

1. Board Overview

The FPB-RX140 v1, a Fast Prototyping Board for the RX140 MCU, enables users to seamlessly evaluate the features of the RX140 MCU and develop embedded systems applications using the e² studio IDE. Users can use on-board features along with their choice of popular ecosystem add-on modules to bring their big ideas to life.

The key features of the FPB-RX140 v1 are categorized in two groups (consistent with the architecture of the board) as follows:

MCU Native Pin Access

- R5F51406BGFN *1 MCU (referred to as RX MCU)
 - Max 48 MHz, 32-bit RX CPU (RXv2)
 - 256 KB Code Flash, 8 KB Data Flash, 64 KB RAM
 - 80-pin, LQFP package
- Native pin access through 2 x 40-pin male headers (not fitted)
- RX MCU current measurement point for precision current consumption measurement
- RX MCU on-chip oscillators as main clock
- Providing 32.768 kHz crystal oscillator as sub clock

System Control and Ecosystem Access

- Two 5 V input sources
 - USB
 - External power supply (using 2-pin header [not fitted])
- On-board debugger / programmer (E2 emulator On Board (referred as E2OB, FINE Interface))
- User LEDs and switches
 - Two User LEDs (green)
 - Power LED (green) indicating availability of regulated power
 - Debug LED (yellow) indicating the debug connection
 - One User switch
 - One Reset switch
- Two popular ecosystem expansions
 - Two Digilent Pmod™ (Type-2A [expanded SPI], Type-3A [expanded UART] and Type-6A [expanded I²C]) connectors
 - Arduino® (Uno R3) connector

*1: R5F51406BGFN has a built in encryption module.

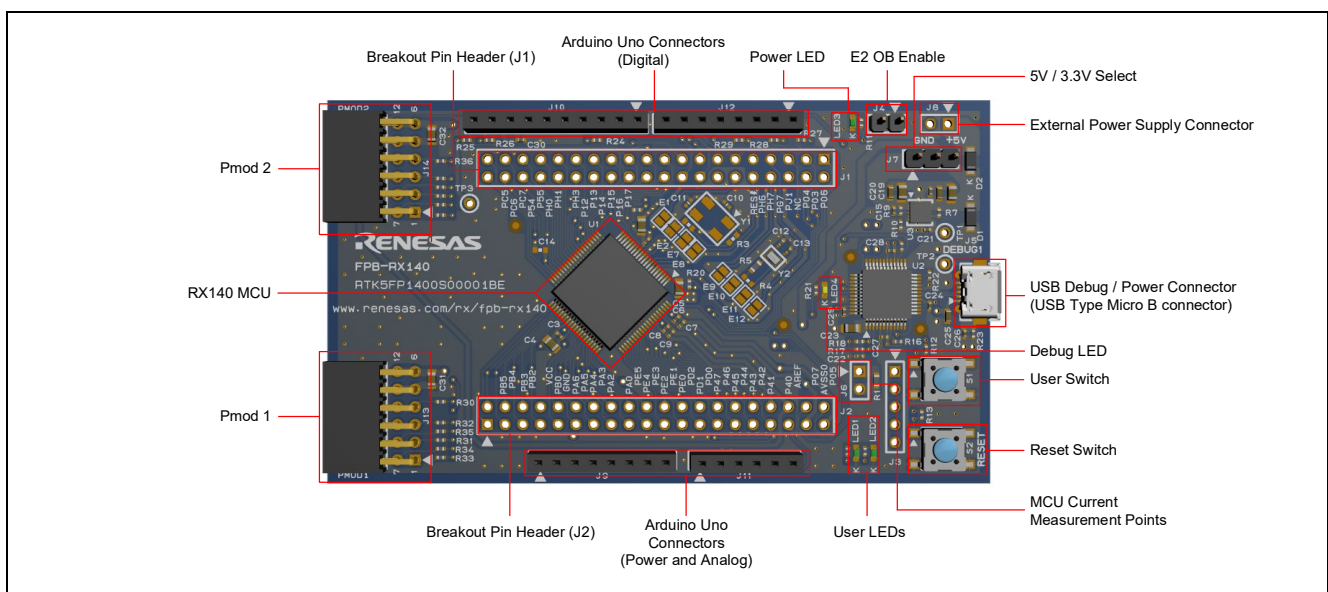


Figure 1. FPB-RX140 v1 Top Side

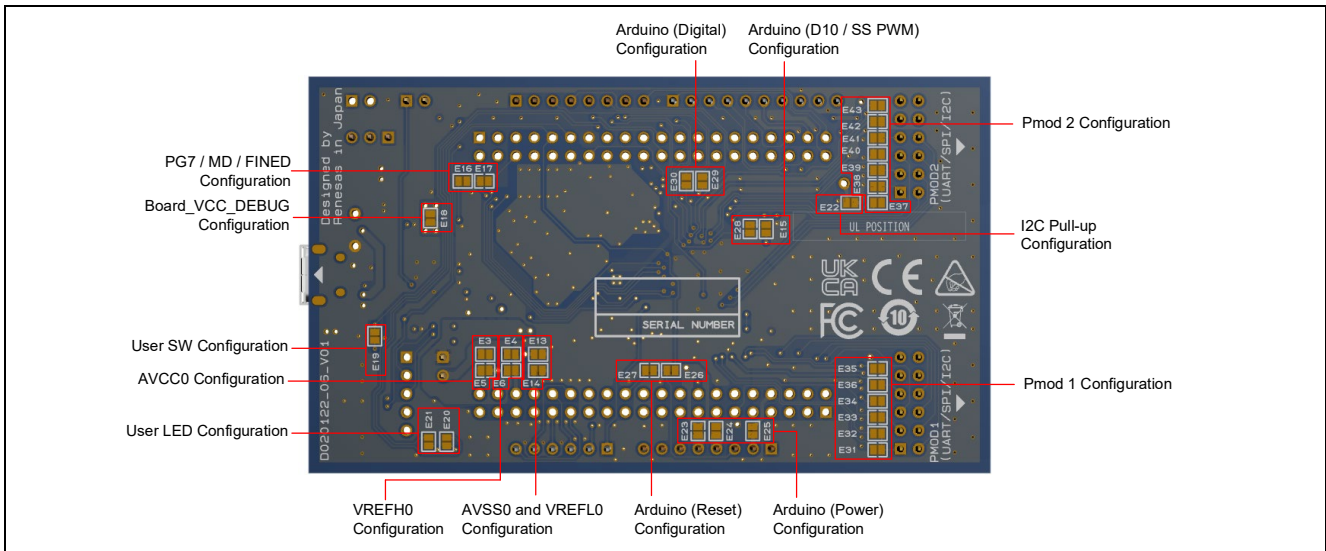


Figure 2. FPB-RX140 v1 Bottom Side

1.1 Assumptions and Advisory Notes

1. It is assumed that the user has a basic understanding of microcontrollers and embedded systems hardware.
2. An Integrated Development Environment (IDE) such as e² studio is required to develop embedded applications on FPB-RX140 v1.

2. Box Contents

The following components are included in the box:

1. FPB-RX140
2. Printed Quick Start Guide

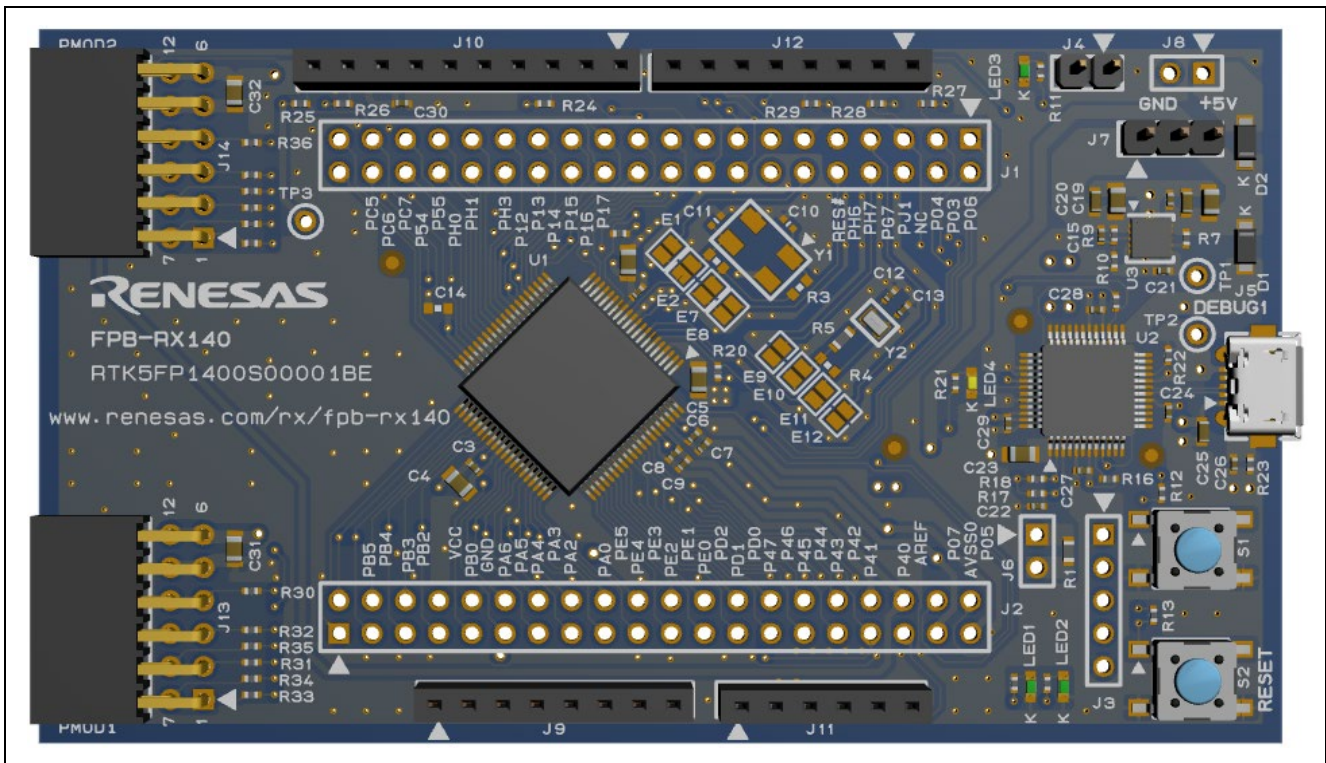


Figure 3. FPB-RX140 v1

3. Ordering Information

- FPB-RX140 v1 orderable part number: RTK5FP1400S00001BE

Note: The underlined character in the orderable part number represents the kit version.

4. Hardware Architecture and Default Configuration

4.1 Board Architecture

The FPB-RX140 v1 is designed with an architecture similar to other boards in the FPB series. Alongside the RX MCU there is an on-board programmer / debugger, pin headers for access to all the pins on the RX MCU, a power supply regulator, some LEDs and switches, and several ecosystem I/O connectors (Pmod and Arduino).

Table 2. Board Architecture

| Category | Features | Function present on all similar boards | Functionality is: |
|-------------------------------------|---|--|---|
| MCU Native Pin Access | RX MCU, breakout pin headers for all RX MCU I/O and power, 2-pin header for RX MCU current measurement (not fitted) | Yes | MCU dependent |
| System Control and Ecosystem Access | Power, debugger, user LEDs and switch, reset switch, ecosystem connectors, boot configuration | Yes | Same or similar across other FPB boards |

4.2 Block Diagram

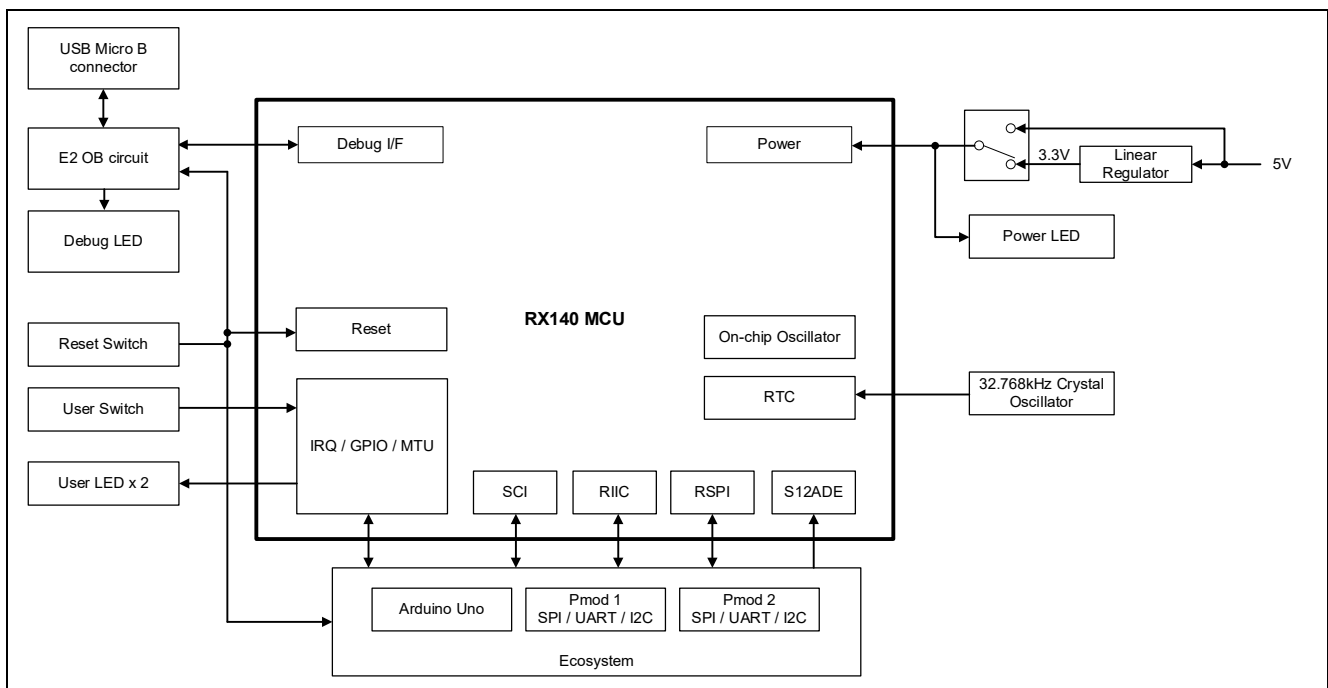


Figure 4. FPB-RX140 v1 Block Diagram

4.3 Component Placement Location and Dimension

Reference number for components on the FPB-RX140 v1 is shown below.

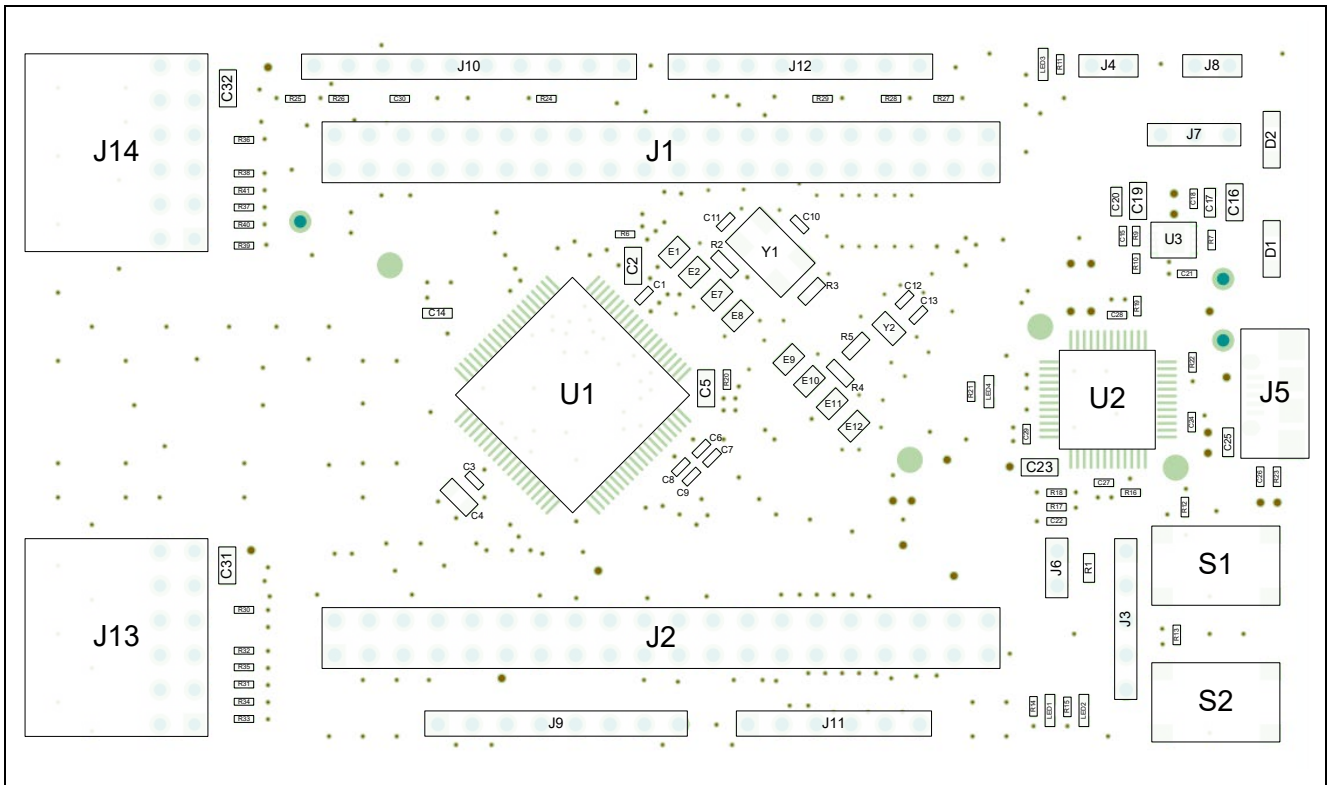


Figure 5. Reference number for components on the FPB-RX140 v1 (top side)

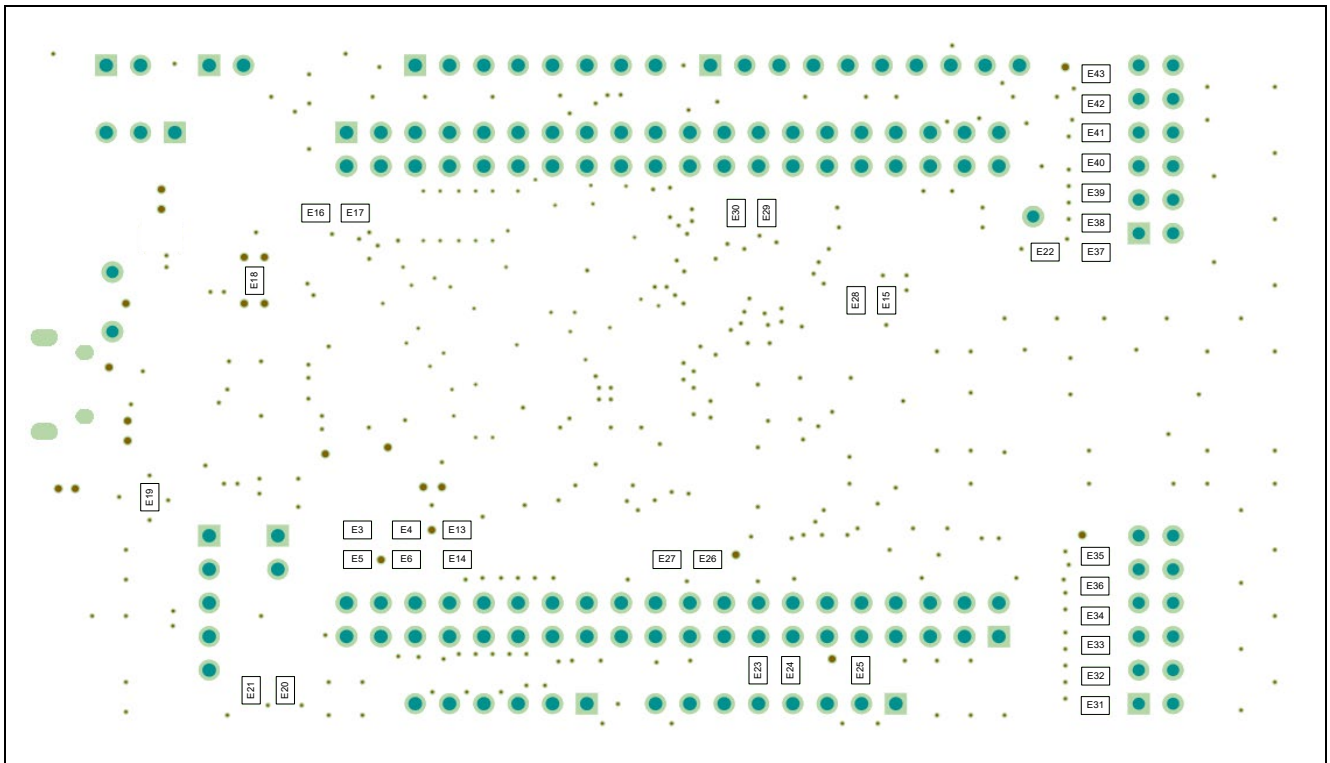


Figure 6. Reference number for components on the FPB-RX140 v1 (bottom side)

Dimension of the FPB-RX140 v1 is shown below.

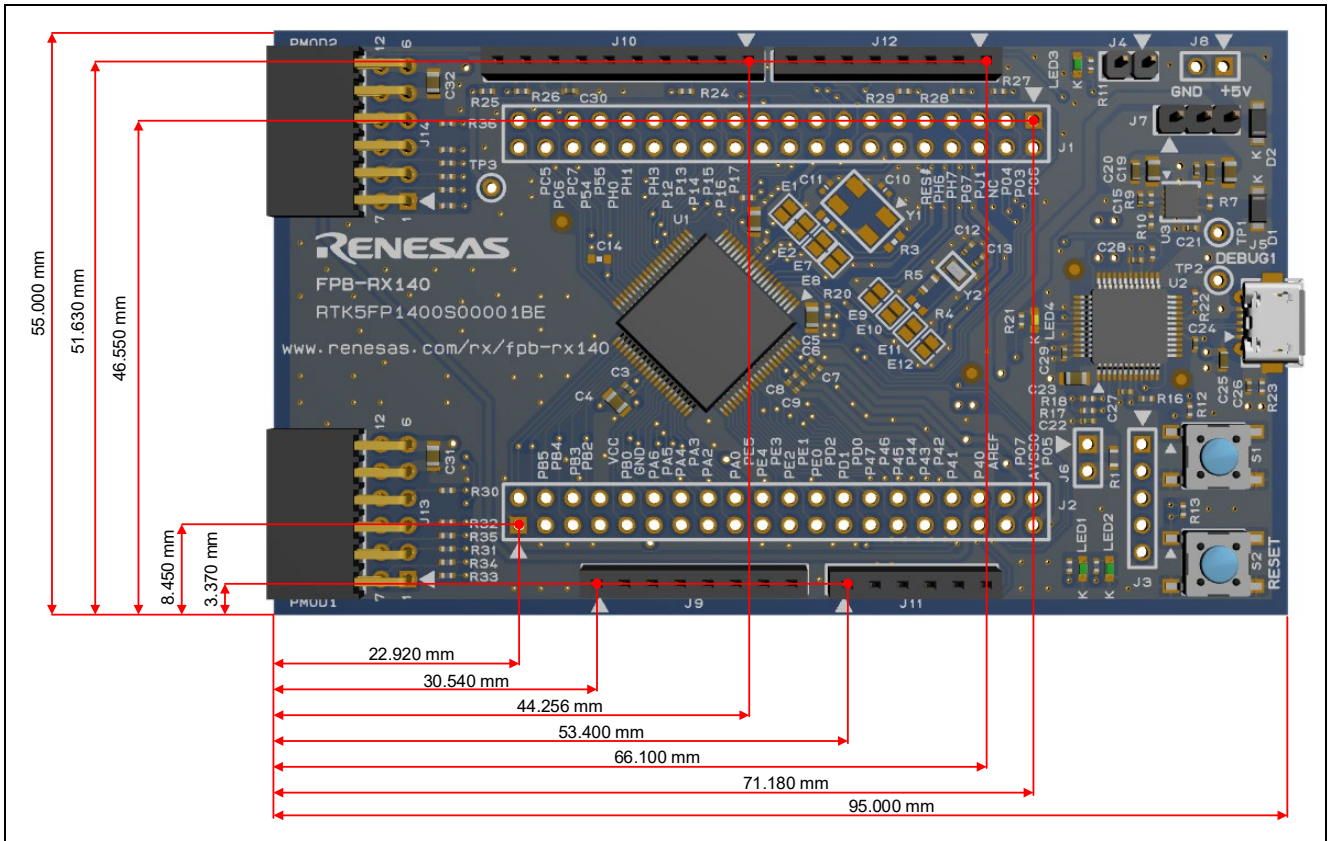


Figure 7. Dimension of the FPB-RX140 v1

4.4 Jumper Settings

Two types of jumpers are provided on the FPB-RX140 v1.

1. Copper jumpers (trace-cut type and solder-bridge type)
2. Traditional pin header jumpers

The following sections describe each type and their default configuration.

4.4.1 Copper Jumpers

Copper jumpers are of two types, designated **trace-cut** and **solder-bridge**.

A **trace-cut jumper** is provided with a narrow copper trace connecting its pads. The silk screen overlay printing around a trace-cut jumper is a solid box. To isolate the pads, cut the trace between pads adjacent to each pad, then remove the connecting copper foil either mechanically or with the assistance of heat. Once the etched copper trace is removed, the trace-cut jumper is turned into a solder-bridge jumper for any later changes.

A **solder-bridge** jumper is provided with two isolated pads that may be joined together by one of three methods:

- Solder may be applied to both pads to develop a bulge on each and the bulges joined by touching a soldering iron across the two pads.
- A small wire may be placed across the two pads and soldered in place.
- A 0Ω SMD resistor may be placed across the two pads to short the pads together by soldering.

For any copper jumper, the connection is considered **closed** if there is an electrical connection between the pads (default for trace-cut jumpers.) The connection is considered **open** if there is no electrical connection between the pads (default for the solder-bridge jumpers).

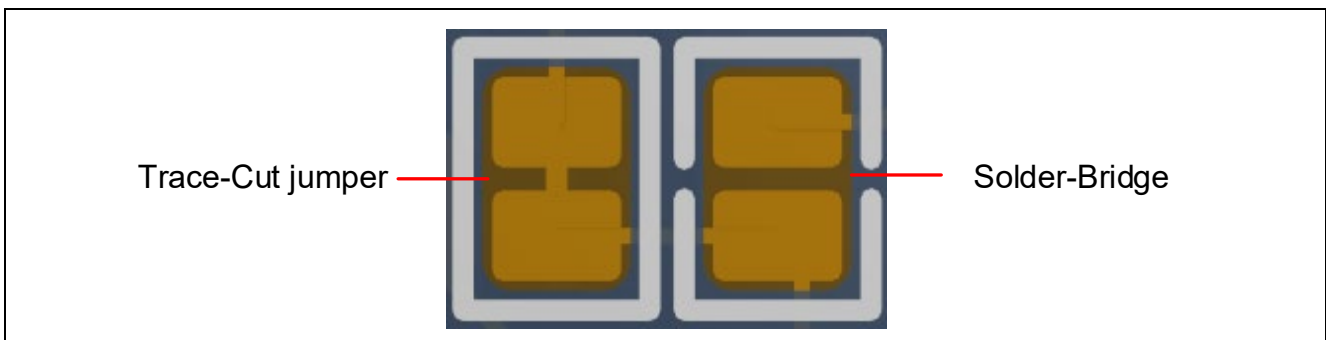


Figure 8. Copper Jumpers

4.4.2 Traditional Pin Header Jumpers

These jumpers are traditional small pitch jumpers that require an external shunt to open/close them. The traditional pin header jumpers on the FPB-RX140 v1 are 0.1" (2.54 mm) pitch headers and use compatible 2.54 mm shunt jumpers.

4.4.3 Default Jumper Configuration

The following table describes the default settings for each jumper on the FPB-RX140 v1. This includes copper jumpers (reference number Ex) and traditional pin header jumpers (reference number Jx). This also includes some 0Ω resistors (reference number Rx) because the resistors are used as jumper function.

Function for copper jumper Ex in the table describe function at Closed. The circuit group for each jumper is the reference number found in the board schematic (available in the Design Package). Functional details for many of the listed jumpers may be found in sections associated with each functional area of the kits.

Table 3. Default Jumper Settings

| Location | Circuit Group | Default (Open / Closed) (Fitted / Not fitted) | Function |
|----------|----------------------|---|---|
| J4 | E2OB | Closed | At open, E2 OB is enabled (Debug on-board mode) |
| | | | At closed, E2 OB is held in reset (Standalone operation mode) |
| | | | Refer to section 5.2 |
| J7 | Power Supply | Jumper on pins 1-2 | Connect Board_VCC to 3.3 V |
| E1 | MCU | Closed | At closed, connect P36 (EXTAL) to breakout pin header J1 |
| E2 | MCU | Open | At closed, connect P36 (EXTAL) to crystal oscillator Y1 |
| E3 | MCU | Closed | At closed, connect AVCC0 to Board_VCC |
| E4 | MCU | Closed | At closed, connect PJ6 (VREFH0) to Board_VCC |
| E5 | MCU | Open | At closed, connect AVCC0 to UC_VCC |
| E6 | MCU | Open | At closed, connect PJ6 (VREFH0) to UC_VCC |
| E7 | MCU | Open | At closed, connect P37 (XTAL) to crystal oscillator Y1 |
| E8 | MCU | Closed | At closed, connect P37 (XTAL) to breakout pin header J1 |
| E9 | MCU | Open | At closed, connect PH6 (XCOUT) to breakout pin header J1 |
| E10 | MCU | Closed | At closed, connect PH6 (XCOUT) to crystal oscillator Y2 |
| E11 | MCU | Closed | At closed, connect PH7 (XCIN) to crystal oscillator Y2 |
| E12 | MCU | Open | At closed, connect PH7 (XCIN) to breakout pin header J1 |
| E13 | MCU | Closed | At closed, connect AVSS0 to GND |
| E14 | MCU | Closed | At closed, connect PJ7 (VREFL0) to GND |
| E15 | MCU | Closed | At closed, connect PC4 (TSCAP / MTIOC0A / SSLA) to breakout pin J1 and Arduino Uno (D10 / SS / PWM) |
| E16 | MCU | Closed | At closed, connect PG7 (MD / FINED) to E2 OB |
| E17 | MCU | Open | At closed, connect PG7 (MD / FINED) to breakout pin J1 |
| E18 | Power Supply | Closed | At closed, connect Board_VCC to Board_VCC_DEBUG (Do not open this copper jumper) |
| E19 | User LEDs & Switches | Closed | At closed, connect P30 (IRQ0) to User switch S1 |
| E20 | User LEDs & Switches | Closed | At closed, connect P20 (MTIOC1A) to LED1 |
| E21 | User LEDs & Switches | Closed | At closed, connect P32 (MTIOC0C) to LED2 |

| Location | Circuit Group | Default (Open / Closed) (Fitted / Not fitted) | Function |
|----------|-----------------------------------|---|--|
| E22 | Arduino Uno | Closed | At closed, connect P16 (SCL0) and P17 (SDA0) to Board_VCC (pull-up) |
| E23 | Arduino Uno | Open | At closed, connect 5.0 V to Arduino Uno (5V) |
| E24 | Arduino Uno | Closed | At closed, connect 3.3 V to Arduino Uno (3.3V) |
| E25 | Arduino Uno | Closed | At closed, connect Board_VCC to Arduino Uno (IOREF) |
| E26 | Arduino Uno | Closed | At closed, connect RES# to Arduino Uno (RESET) |
| E27 | Arduino Uno | Open | At closed, connect PD2 to Arduino Uno (RESET) |
| E28 | Arduino Uno | Open | At closed, connect P34 (MTIOC0A) to Arduino Uno (D10 / SS / PWM) |
| E29 | Arduino Uno | Closed | At closed, connect P20 (MTIOC1A) to Arduino Uno (D5 / PWM) |
| E30 | Arduino Uno | Closed | At closed, connect P30 (IRQ0) to Arduino Uno (D2 / INT) |
| E31 | Pmod 1 | Open | At closed, connect PA6 (CTS5#) to Pmod 1 (CTS / CS / INT) |
| E32 | Pmod 1 | Closed | At closed, connect PE5 (IRQ5) to Pmod 1 (CTS / CS / INT) |
| E33 | Pmod 1 | Open | At closed, connect PA0 to Pmod 1 (TXD / MOSI) |
| E34 | Pmod 1 | Closed | At closed, connect PA4 (TXD5 / SMOSI5 / SSDA5) to Pmod 1 (TXD / MOSI) |
| E35 | Pmod 1 | Open | At closed, connect PA4 (TXD5 / SMOSI5 / SSDA5) to Pmod 1 (RTS / SCK / SDA) |
| E36 | Pmod 1 | Closed | At closed, connect PA1 (SCK5) to Pmod 1 (RTS / SCK / SDA) |
| E37 | Pmod 2 | Closed | At closed, connect P14 (CTS1#) to Pmod 2 (CTS / CS / INT) |
| E38 | Pmod 2 | Open | At closed, connect P12 (IRQ2) to Pmod 2 (CTS / CS / INT) |
| E39 | Pmod 2 | Open | At closed, connect PA2 to Pmod 2 (TXD / MOSI) |
| E40 | Pmod 2 | Closed | At closed, connect P26 (TXD1 / SMOSI1 / SSDA1) to Pmod 2 (TXD / MOSI) |
| E41 | Pmod 2 | Open | At closed, connect P26 (TXD1 / SMOSI1 / SSDA1) to Pmod 2 (RTS / SCK / SDA) |
| E42 | Pmod 2 | Open | At closed, connect P27 (SCK1) to Pmod 2 (RTS / SCK / SDA) |
| E43 | Pmod 2 | Closed | At closed, connect P31 (RTS1#) to Pmod 2 (RTS / SCK / SDA) |
| R1 | MCU CURRENT MEASUREME NT | Fitted (Refer to section 6.2 in detail) | At fitted, connect Board_VCC to UC_VCC |
| | | | At not fitted, the RX MCU current can be measured over this jumper |

5. System Control and Ecosystem Access

The FPB-RX140 v1 provides a power supply regulator, an on-board debugger, simple I/O (switches and LEDs), and popular I/O ecosystem connectors. These are all described in detail below.

5.1 Power

The FPB-RX140 v1 is designed for 5 V operation. An on-board Linear Regulator is used to convert the 5 V supply to a 3.3 V supply. The 3.3 V supply is used to power the RX MCU and other peripheral features by default.

The 3.3 V supply is used to power the RX MCU and other peripheral features by shorting pin 1 and 2 of the pin header jumper J7. The 5 V supply is used to power the RX MCU and other peripheral features by shorting pin 2 and 3 of the pin header jumper J7.

RX MCU specifies power-on VCC rising gradient. When supplying the 5 V to the RX MCU, the power-on VCC rising gradient depends on capability of the power supply that supplies 5 V to the FPB-RX140 v1 because input 5 V to the FPB-RX140 v1 is supplied to the RX MCU through the reverse protection diode.

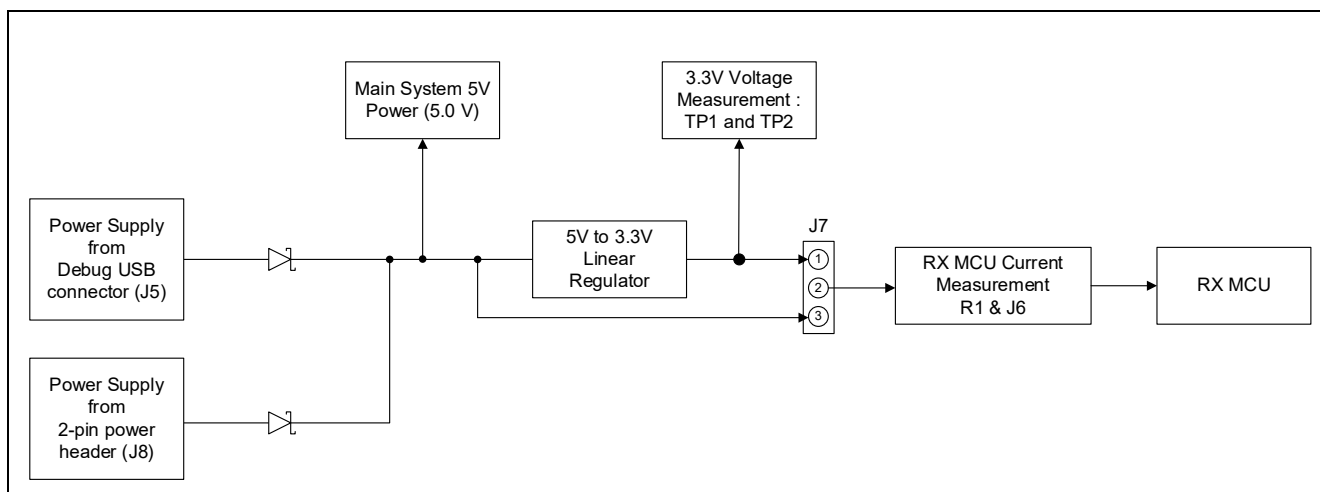


Figure 9. Power Supply

5.1.1 USB

5 V may be supplied from a host PC to the USB connector (J5) labelled DEBUG1 on the board. Power from this source is connected to the main system 5 V power. Reverse current protection is provided between this connector and the main system 5 V power.

5.1.2 Header Connector J8

5 V may be supplied from an external power supply to connector J8. J8 is a standard 2-pin header on a 0.1" (2.54 mm) pitch. Pin 1 is 5 V, and pin 2 is GND. Power from this source is connected to the main system 5 V power. Reverse current protection is provided between J8 and the main system 5 V power.

5.1.3 Power Supply Considerations

Voltage of Main System 5 V Power will be lower than the power supply voltage because of the forward voltage (max 0.55V@1A) of the reverse current protection diode. Main System 5 V Power supplies to external devices connected to Arduino, Pmod 1 and Pmod 2.

The maximum current that could be supplied to the FPB-RX140 v1 is 1 A including current consumption of external boards which are connected to the ecosystem connectors and the breakout pin headers.

5.1.4 Power-up Behavior

When powered, the Power LED (LED3) colored green turns on and blinky example project which is pre-programmed starts and User LED1 and LED2 start blinking.

5.2 Debug and Programming

The FPB-RX140 v1 can be debugged and programmed using the E2 OB.

The FPB-RX140 v1 supports Debug on-board mode in which can debug and program by E2 OB circuit and Standalone operation mode in which RX MCU operates as standalone by disabling E2 OB circuit. The mode can be configured by pin header jumper J4.

Table 4. Operating mode

| J4 | Operating mode |
|--------------------|----------------------|
| Open | Debug on-board mode |
| Jumper on pins 1-2 | Standalone operation |



Figure 10. Pin header jumper J4

5.2.1 E2 OB

USB DEBUG1 (Type Micro B) connector (J5) connects the E2 OB to a host PC, allowing re-programming and debugging of the RX MCU firmware.

The E2 OB connects to the RX MCU using the FINE interface. Please note that connecting the same host PC to multiple FPB-RX140 v1 is not possible.

Table 5. USB Debug Connector

| USB Debug Connector | | FPB-RX140 v1 |
|---------------------|--|--------------|
| Pin | Description | Signal |
| J5-1 | +5VDC | +5V_USB_DBG |
| J5-2 | Data- | USBDBG_DM |
| J5-3 | Data+ | USBDBG_DP |
| J5-4 | USB ID, jack internal switch, cable inserted | NC |
| J5-5 | Ground | GND |

A yellow indicator, LED4, shows the status of the debug interface. When the FPB-RX140 v1 is powered, and LED4 is blinking, it indicates that the E2 OB is not connected to a host PC. When LED4 is on solid, it indicates that it is connected to a host PC.

5.2.2 Settings in e² studio and Renesas Flash Programmer

FPB-RX140 v1 needs to be configured in Debug on-board shown in [Table 4](#) when the MCU is debugged or re-programmed with e² studio. [Figure 11](#) shows the settings for e² studio when creating a new project for the FPB-RX140 v1.

[Debug hardware]: Select [E2 Lite (RX)]

[Target Device]: Select [R5F51406]

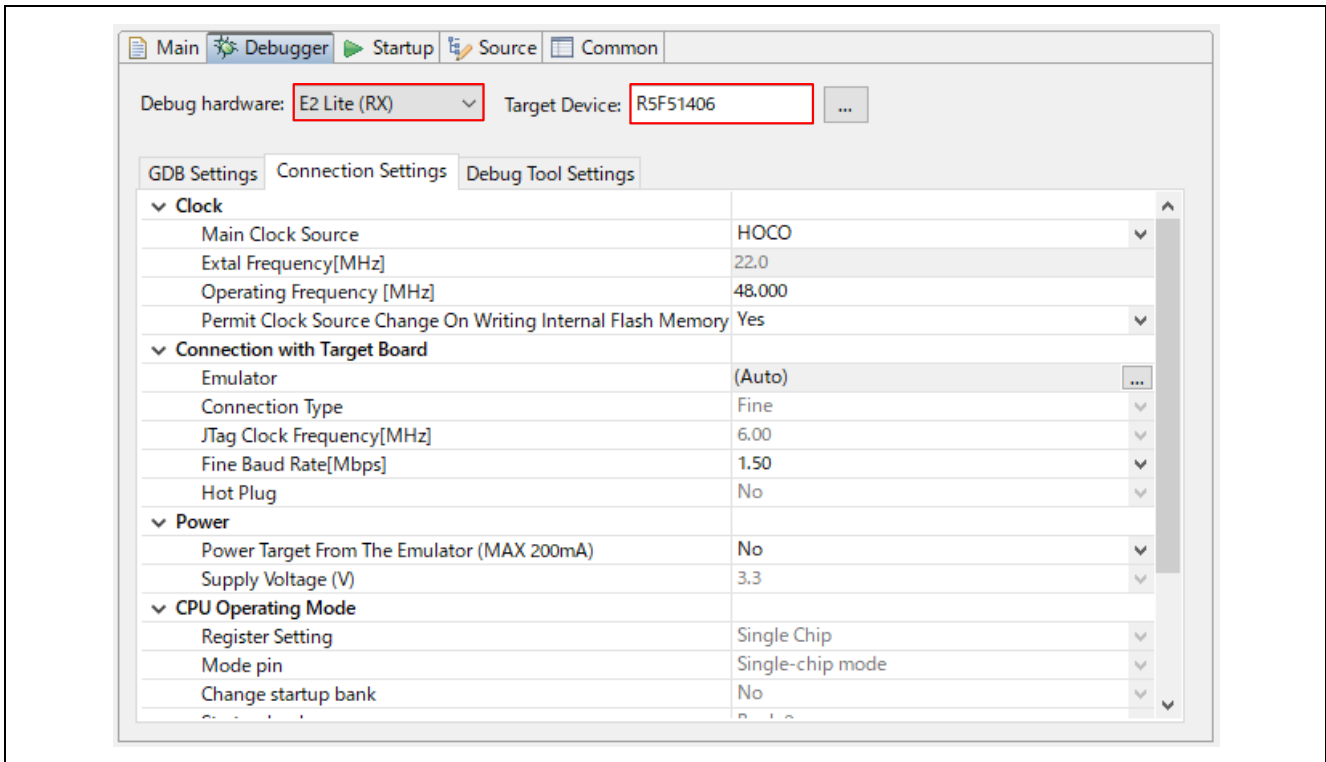


Figure 11. e² Studio Setting

FPB-RX140 v1 needs to be configured in Debug on-board shown in [Table 4](#) when the MCU is re-programmed with Renesas Flash Programmer. [Figure 12](#) shows the settings for Renesas Flash Programmer when creating a new project for the FPB-RX140 v1.

Connect an USB cable between the FPB-RX140 v1 and a host PC and create a new project.

- [Microcontroller]: Select [RX100]
- [Project Name]: Define project name
- [Project Name]: Select project folder location
- [Tool]: Select [E2 emulator Lite]
- [Tool Details]: Select [FINE]

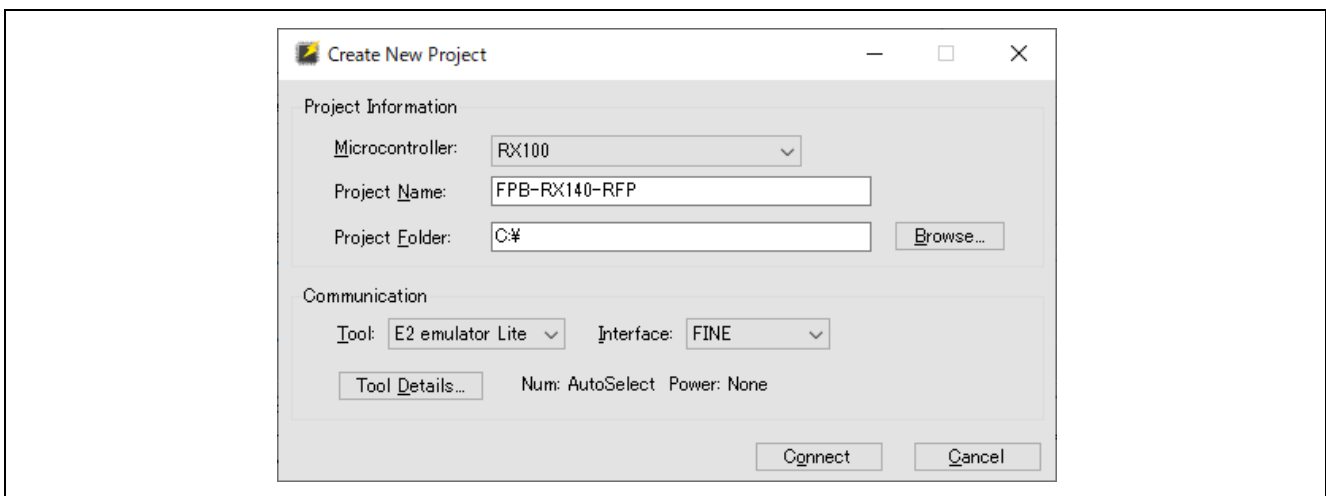


Figure 12. Renesas Flash Programmer Settings

5.3 Ecosystem

The Ecosystem connectors provide users the means to connect several third party add-on modules compatible with two popular ecosystems using the following connectors:

1. Two Digilent Pmod™ (UART / SPI / I²C) connectors
2. Arduino® (Uno R3) connectors

Note: We do not guarantee connection to all types of third party add-on modules. Confirm the specifications of this product and any third party add-on modules you intend to use.

5.3.1 Digilent Pmod™ Connectors

5.3.1.1 Pmod 1

A 12-pin Pmod Type-2A (expanded SPI), Type-3A (expanded UART) and Type-6A (expanded I²C) connector is provided at connector J13 labelled PMOD1. At Type-2A, the RX MCU acts as the SPI master, and the connected module acts as an SPI slave device. At Type-6A, the RX MCU acts as a two-wire serial master, and a connected module acts as a two-wire serial slave.

Table 6. Pmod 1 Connector

| Pmod 1 Connector | | | | FPB-RX140 v1 | Pmod 1 Configuration | |
|------------------|--------------------------------|-----------------|----------------|---------------------------------|----------------------|----------|
| Pin | Default Type-2A | Default Type-3A | Option Type-6A | Signal | Closed | Open |
| J13-1 | CS | | | PE5 (IRQ5) or PA6 (CTS5#) | *1 | |
| | | CTS / GPIO | | PA6 (CTS5#) *2 | E31 | E32 |
| | | | INT | PE5 (IRQ5) | E32 | E31 |
| J13-2 | MOSI | TXD | | PA4 (TXD5 / SMOSI5 / SSSDA5) | E34 | E33, E35 |
| | | | RESET | PA0 | E33, E35 | E34, E36 |
| J13-3 | MISO | RXD | SCL | PA3 (RXD5 / SMISO5 / SSCL5) | | |
| J13-4 | SCK | RTS / GPIO | | PA1 (SCK5) | E36 | E35 |
| | | | SDA | PA4 (TXD5 / SMOSI5 / SSSDA5) *2 | E35 | E34, E36 |
| J13-5 | GND | | | GND | | |
| J13-6 | VCC | | | Board_VCC | | |
| J13-7 | GPIO / INT (slave to master) | | | PB1 (IRQ4) | | |
| J13-8 | GPIO / RESET (master to slave) | | | PB3 | | |
| J13-9 | GPIO / CS2 | | | PB5 | | |
| J13-10 | GPIO / CS3 | | | PB6 / PC0 | | |
| J13-11 | GND | | | GND | | |
| J13-12 | VCC | | | Board_VCC | | |

*1: Connect PE5 (IRQ5) or PA6 (CTS5#) when using Type-2A (CS). Solder copper jumper E32 and cut copper jumper E31 when connecting PE5 (IRQ5). Cut copper jumper E32 and solder copper jumper E31 when connecting PA6 (CTS5#).

*2: Open at shipping.

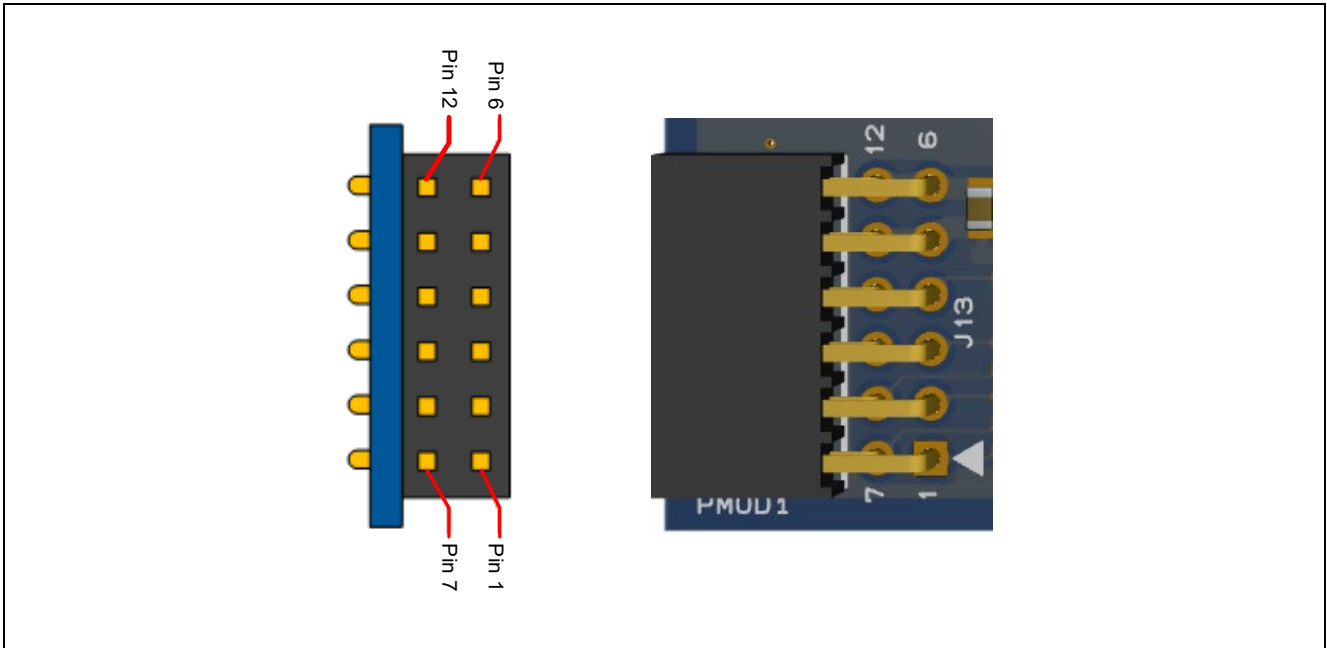


Figure 13. Pmod 1 Connector

Pmod Type-6A Operation

The option for Type-6A (I²C) can be configured at Pmod 1 and supports 3.3 V / 5 V devices. To configure the FPB-RX140 v1 to use the I²C devices with 3.3 V / 5 V operation, configure the copper jumpers using [Table 6](#). Following figure shows the copper jumpers to use the I²C devices.

Note: VCC power that supplies to J13-Pin6 and Pin12 is Board_VCC same as RX MCU power. Board_VCC voltage is selectable either 3.3 V or 5 V by configuring pin header J7.

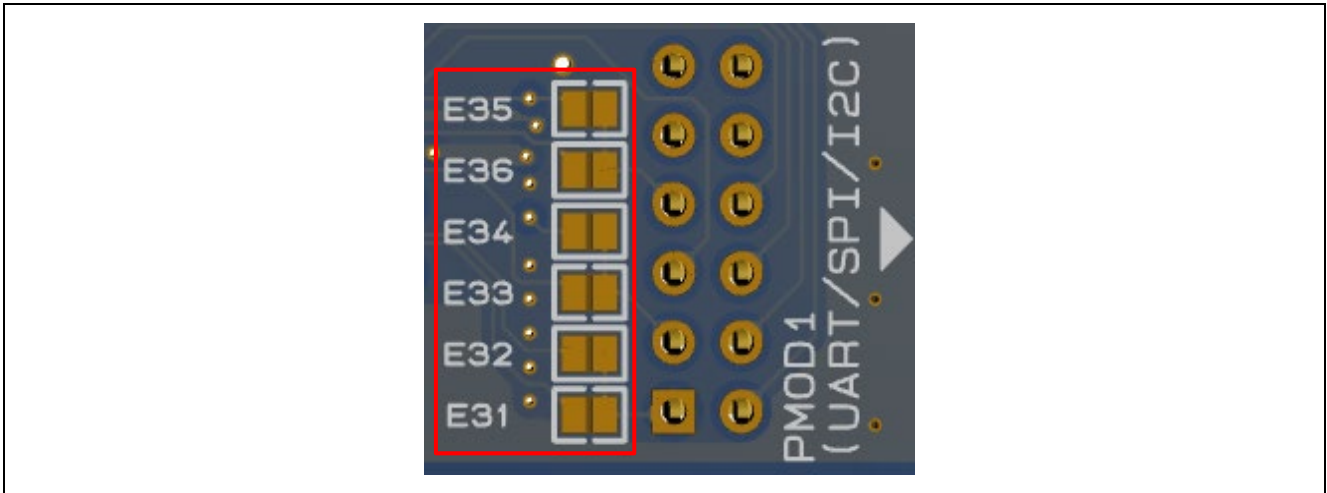


Figure 14. Pmod 1 Copper Jumpers (bottom side)

5.3.1.2 Pmod 2

A 12-pin Pmod Type-2A (expanded SPI), Type-3A (expanded UART) and Type-6A (expanded I²C) connector is provided at connector J14 labelled PMOD2. At Type-2A, the RX MCU acts as the SPI master, and the connected module acts as an SPI slave device. At Type-6A, the RX MCU acts as a two-wire serial master, and a connected module acts as a two-wire serial slave.

Table 7. Pmod 2 Connector

| Pmod 2 Connector | | | | FPB-RX140 v1 | Pmod 2 Configuration | |
|------------------|--------------------------------|-----------------|----------------|---|----------------------|---------------|
| Pin | Option Type-2A | Default Type-3A | Option Type-6A | Signal | Closed | Open |
| J14-1 | CS | CTS / GPIO | | P14 (CTS1#) | E37 | E38 |
| | | | INT | P12 (IRQ2) ^{*1} | E38 | E37 |
| J14-2 | MOSI | TXD | | P26 (TXD1 / SMOSI1 / SSDA1) | E40 | E39, E41 |
| | | | RESET | PA2 | E39, E41 | E40, E42, E43 |
| J14-3 | MISO | RXD | SCL | P15 (RXD1 / SMISO1 / SSCL1) | | |
| J14-4 | SCK | | | P27 (SCK1) ^{*1} | E42 | E41, E43 |
| | | RTS / GPIO | | P31 (RTS1#) | E43 | E41, E42 |
| | | | SDA | P26 (TXD1 / SMOSI1 / SSDA1) ^{*1} | E41 | E40, E42, E43 |
| J14-5 | GND | | | GND | | |
| J14-6 | VCC | | | Board_VCC | | |
| J14-7 | GPIO / INT (slave to master) | | | P13 (IRQ3) | | |
| J14-8 | GPIO / RESET (master to slave) | | | PB2 | | |
| J14-9 | GPIO | | | PB0 | | |
| J14-10 | GPIO | | | PA5 | | |
| J14-11 | GND | | | GND | | |
| J14-12 | VCC | | | Board_VCC | | |

*1: Open at shipping.

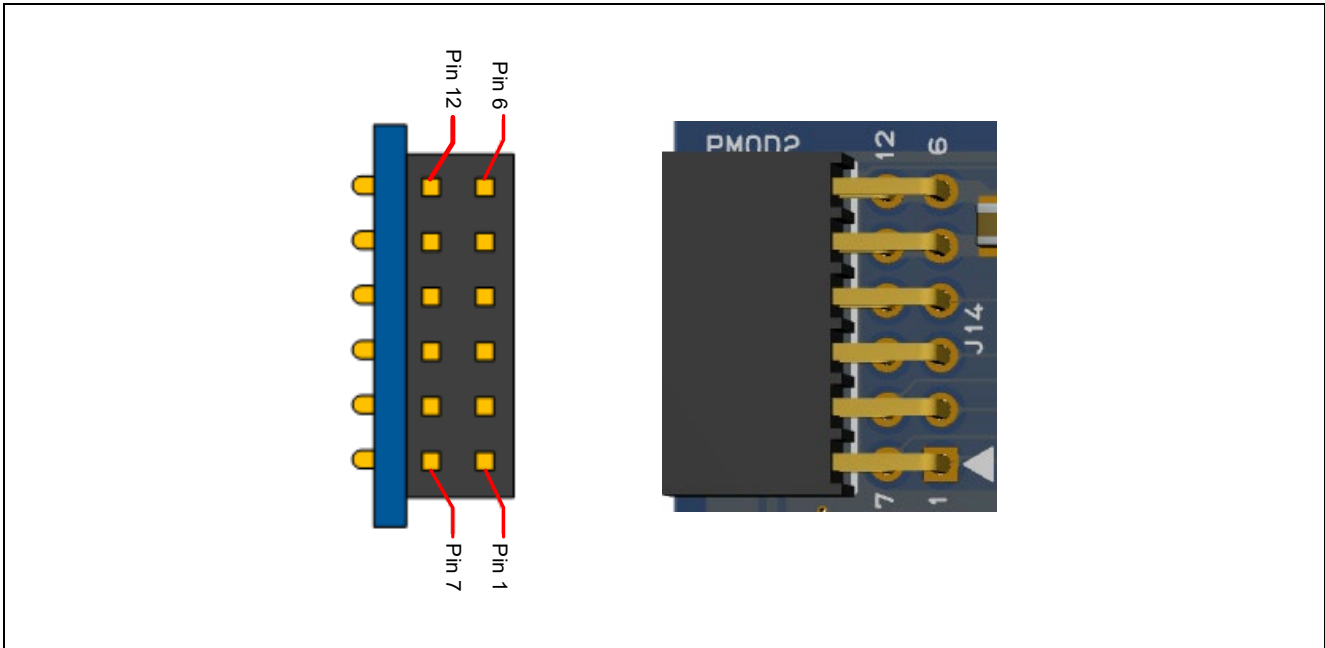


Figure 15. Pmod 2 Connector

Pmod Type-6A Operation

The option for Type-6A (I²C) can be configured at Pmod 2 and supports 3.3 V / 5 V devices. To configure the FPB-RX140 v1 to use the I²C devices with 3.3 V / 5 V operation, configure the copper jumpers using [Table 7](#). Following figure shows the copper jumpers to use the I²C devices.

Note: VCC power that supplies to J14-Pin6 and Pin12 is Board_VCC same as RX MCU power. Board_VCC voltage is selectable either 3.3 V or 5 V by configuring pin header J7.

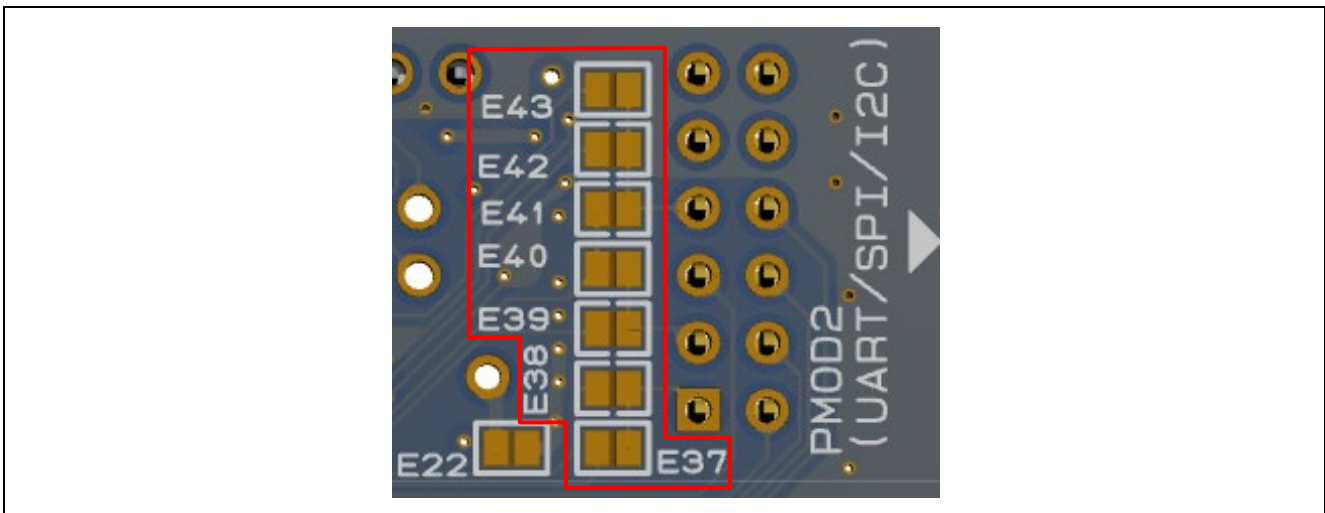


Figure 16. Pmod 2 Copper Jumpers (bottom side)

5.3.2 Arduino® Connector

Arduino Uno R3 compatible connector interface is provided at connector J9, J10, J11 and J12.

Table 8. Arduino Uno Connections

| Arduino Compatible Connector | | FPB-RX140 v1 | Arduino Configuration | |
|------------------------------|------------------|--------------------------|-----------------------|------|
| Pin | Description | Signal | Closed | Open |
| J9-1 | NC | NC | | |
| J9-2 | IOREF | Board_VCC | E25 | |
| J9-3 | RESET | RES# | E26 | E27 |
| | | PD2 *5 | E27 | E26 |
| J9-4 | 3.3V | 3.3 V | E24 | |
| J9-5 | 5 V | 5 V *5 | E23 | |
| J9-6 | GND | GND | | |
| J9-7 | GND | GND | | |
| J9-8 | VIN | NC | | |
| J11-1 | A0 | P40 (AN000) | | |
| J11-2 | A1 | P41 (AN001) | | |
| J11-3 | A2 | P42 (AN002) | | |
| J11-4 | A3 | P43 (AN003) | | |
| J11-5 | A4 | P44 (AN004) | | |
| J11-6 | A5 | P45 (AN005) | | |
| J12-1 | D0 / RX | PD1 (RXD6) | | |
| J12-2 | D1 / TX | PD0 (TXD6) | | |
| J12-3 | D2 / INT | P30 (IRQ0) *1 | E30 | |
| J12-4 | D3 / INT / PWM | PH2 (MTIOC4C / IRQ1) | | |
| J12-5 | D4 | P21 | | |
| J12-6 | D5 / PWM | P20 (MTIOC1A) *2 | E29 | |
| J12-7 | D6 / PWM | PJ1 (MTIOC3A) | | |
| J12-8 | D7 | PC3 | | |
| J10-1 | D8 | PC2 | | |
| J10-2 | D9 / PWM | PE4 (MTIOC4A) | | |
| J10-3 | D10 / SS / PWM | PC4 (MTIOC0A / SSLA0) *4 | E15 | E28 |
| | | P34 (MTIOC0A) *5 | E28 | E15 |
| J10-4 | D11 / MOSI / PWM | PC6 (MTIOC3C / MOSIA) | | |
| J10-5 | D12 / MISO | PC7 (MISOA) | | |
| J10-6 | D13 / SCK | PC5 (RSPCKA) | | |
| J10-7 | GND | GND | | |
| J10-8 | AREF | AREF *6 | | |
| J10-9 | SDA | P17 (SDA0) *3 | | |
| J10-10 | SCL | P16 (SCL0) *3 | | |

*1: The signal is shared with User switch S1.

*2: The signal is shared with user LED1.

*3: I²C pull up can be disconnected by cutting copper jumper E22.

*4: The signal is shared with TSCAP. Cut copper jumper E15 when a capacitor is fitted on C14.

*5: Open at shipping.

*6: The signal is connected to VREFH0 pin of the RX140 MCU.

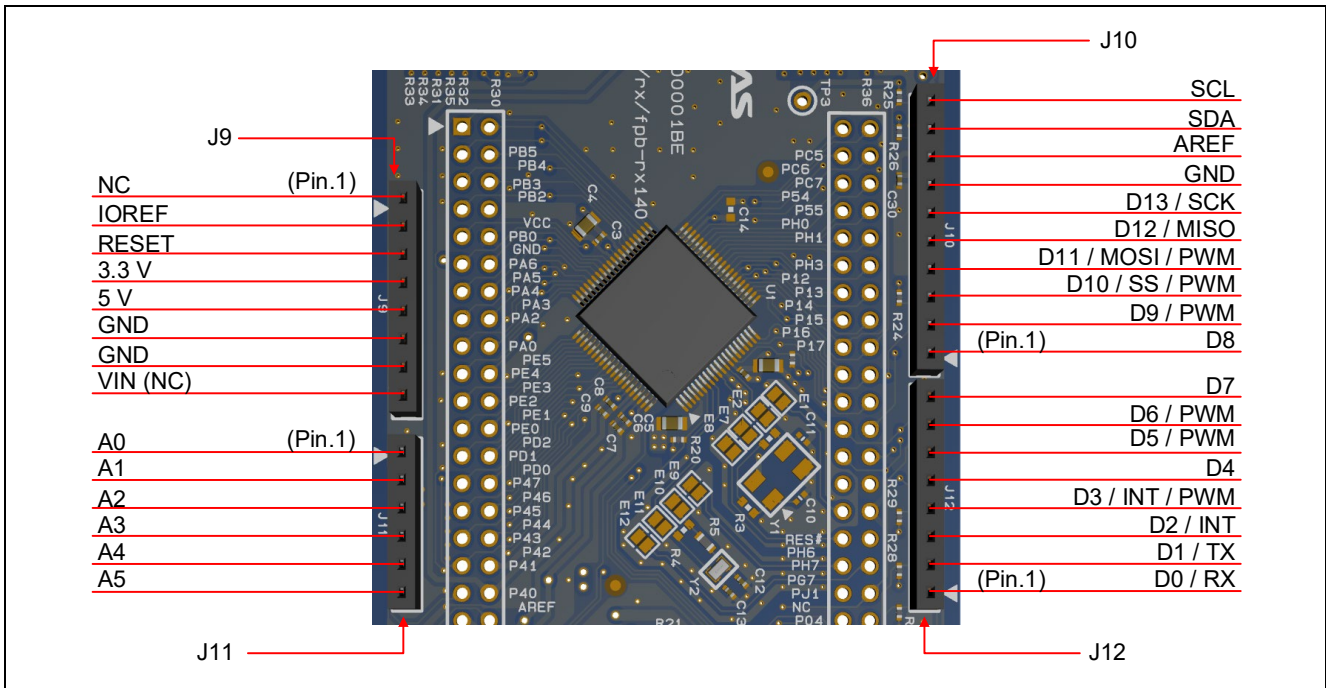


Figure 17. Arduino Uno Connectors

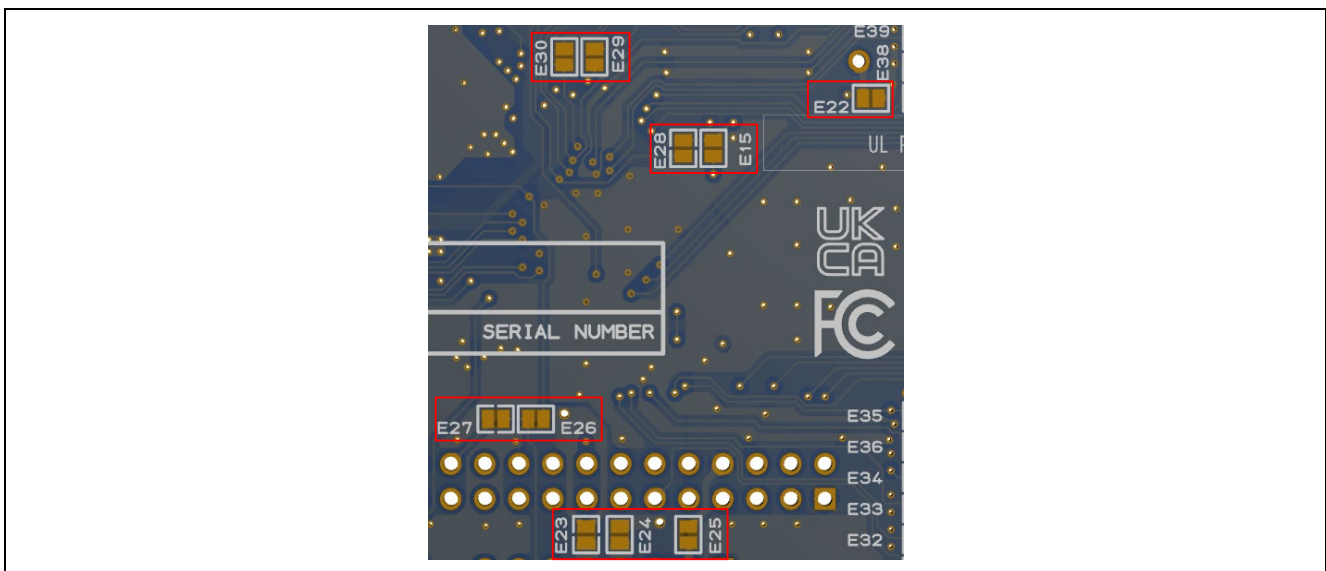


Figure 18. Arduino Uno Copper Jumpers (bottom side)

Arduino Shield Considerations

AREF (J10-Pin8) output from Arduino Shield is connected to VREFH0 (Analog reference voltage supply pin for the 12-bit A/D converter) of RX MCU, however, Board_VCC is connected to VREFH0 at default condition. When Arduino AREF supplies power to VREFH0, the user must disconnect VREFH0 from Board_VCC power. Copper jumper E4 is provided on the FPB-RX140 v1 to disconnect VREFH0 from on-board Board_VCC power.

The FPB-RX140 v1 can supply 5 V power to J9-Pin5 of Arduino Shield by soldering copper jumper E23, however, some of the RX MCU pins which are connected to Arduino Shield are not 5 V tolerant. When the FPB-RX140 v1 supplies 5 V power to Arduino Shield, however Board_VCC = 3.3 V, the user must confirm the RX140 Group User's Manual: Hardware and the specification of Arduino Shield you intend to use.

5.4 Miscellaneous

5.4.1 LED

Four LEDs are provided on the FPB-RX140 v1.

Functions of the LEDs on the FPB-RX140 v1 is described in the following table. User LEDs turn on when RX MCU ports output high level.

Table 9. FPB-RX140 v1 LED Functions

| LED | | | FPB-RX140 v1 | Configuration | |
|------------|--------|-----------|-----------------------------|---------------|------|
| Designator | Color | Function | Signal | Closed | Open |
| LED1 | Green | User LED | P20 (MTIOC1A) ^{*1} | E20 | |
| LED2 | Green | User LED | P32 (MTIOC0C) | E21 | |
| LED3 | Green | Power LED | Board_VCC | | |
| LED4 | Yellow | Debug LED | E2 OB circuit | | |

*1: The signal is shared with Arduino (D5 / PWM).

The User LEDs may be isolated from the RX MCU so that the associated ports can be used for other purposes. To disconnect LED1 from P20 (MTIOC1A), copper jumper E20 must be open. To disconnect LED2 from P32 (MTIOC0C), copper jumper E21 must be open.

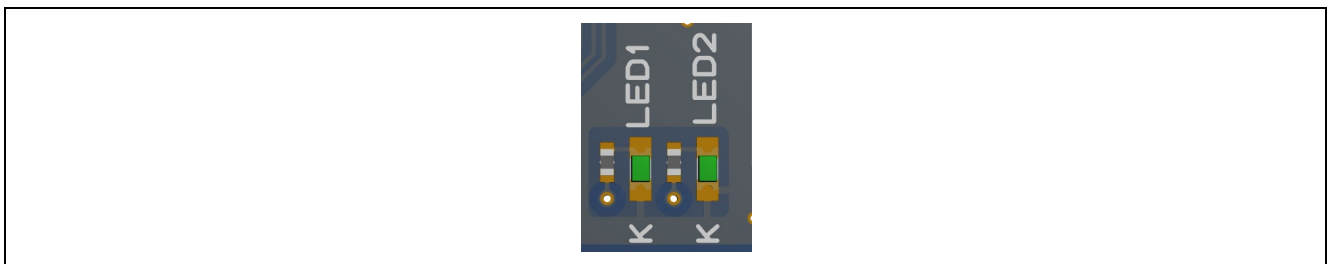


Figure 19. User LEDs (top side) and Copper Jumpers (bottom side)

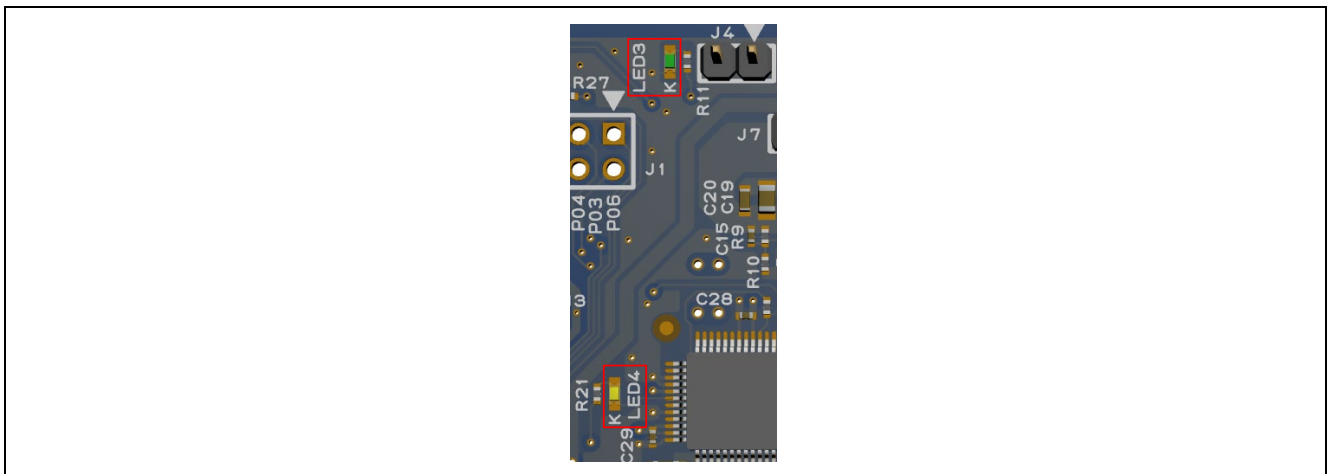


Figure 20. Power LED and Debug LED

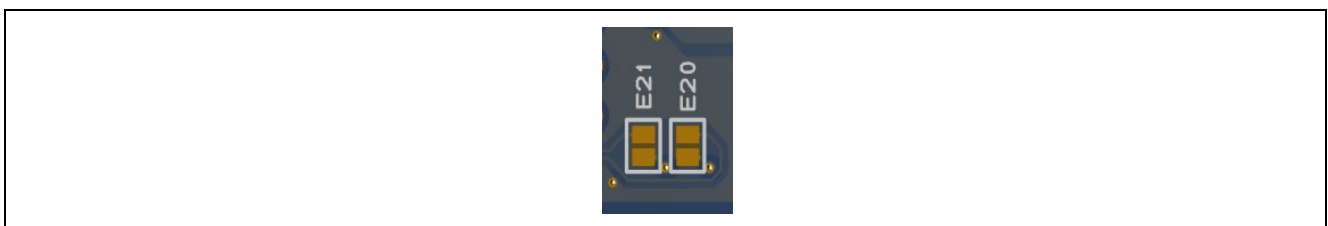


Figure 21. User LEDs Copper Jumpers (bottom side)

5.4.2 User and Reset Switches

Two miniature, momentary, mechanical push-button type SMD switches are mounted on the FPB-RX140 v1. Pressing the reset switch (S2) generates a reset signal to reset the RX MCU.

Table 10. FPB-RX140 v1 Switches

| Switch | | | FPB-RX140 v1 | Configuration | |
|------------|--------------|--------------|---------------|---------------|------|
| Designator | Function | Button Color | Signal | Closed | Open |
| S1 | User switch | Blue | P30 (IRQ0) *1 | E19 | |
| S2 | Reset Switch | Blue | RES# | | |

*1: The signal is shared with Arduino (D2 / INT).

The User switch S1 may be isolated from the RX MCU, so that the associated port can be used for other purposes. To disconnect S1 from P30 (IRQ0), trace cut jumper E19 must be open.

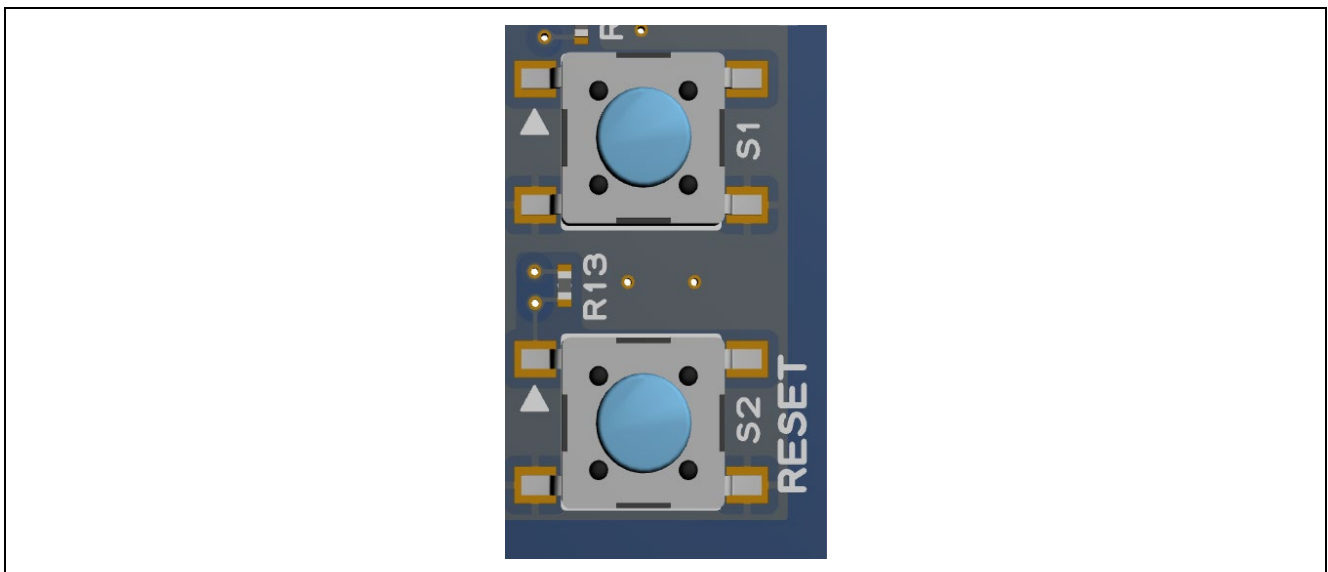


Figure 22. Reset (S2) and User Switch (S1)

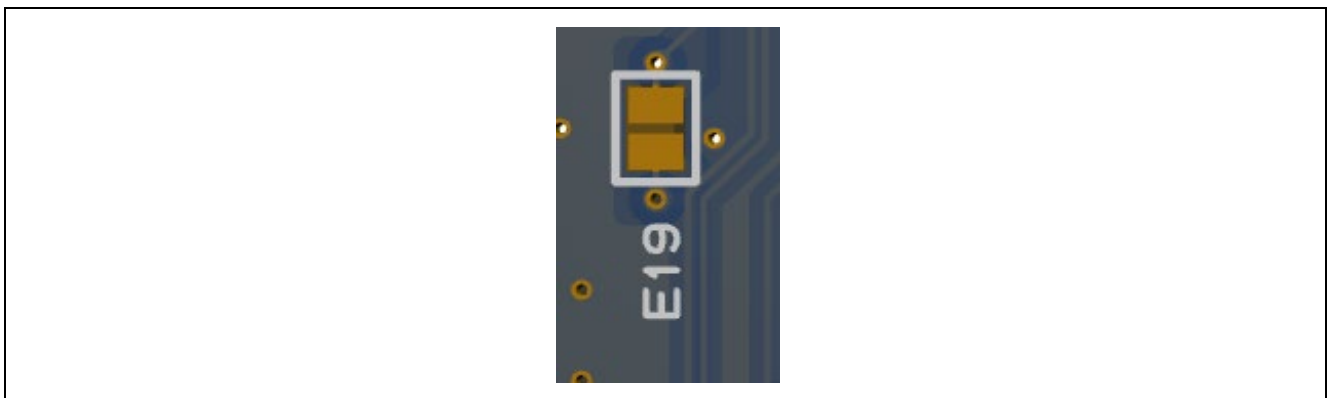


Figure 23. User Switch S1 Copper Jumper (bottom side)

6. MCU Native Pin Access

6.1 Breakout Pin Headers

The FPB-RX140 v1 pin headers (not fitted), J1 and J2, provide access to RX MCU interface signals. Each header pin is labelled with the power or port connected to that pin (Some header pins aren't labelled because of not enough space.). Refer to the RX140 MCU User's Manual: Hardware for details of each port function, and the FPB-RX140 v1 schematic for pin header port assignments.

The placement of the breakout pin headers allows for a standard 2.54 mm (0.100") breadboard to be placed on both pin headers. This can be used for prototyping and testing of custom circuitry for use with the RX MCU.

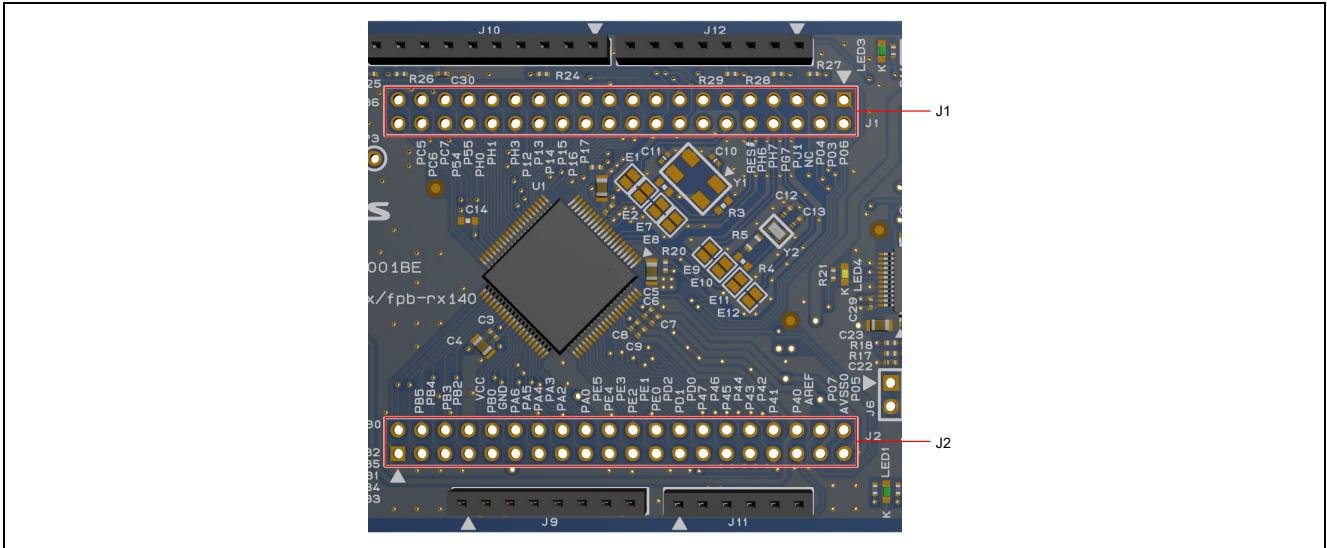


Figure 24. Breakout Pin Headers J1 and J2

6.2 MCU Current Measurement

Two pin header J6 (not fitted) is provided on the FPB-RX140 v1 to measure the RX MCU current.

Resistor R1 is 0Ω (SMD 0603). It should be removed in order to measure the current consumption using an ammeter connected between the pin header pins.

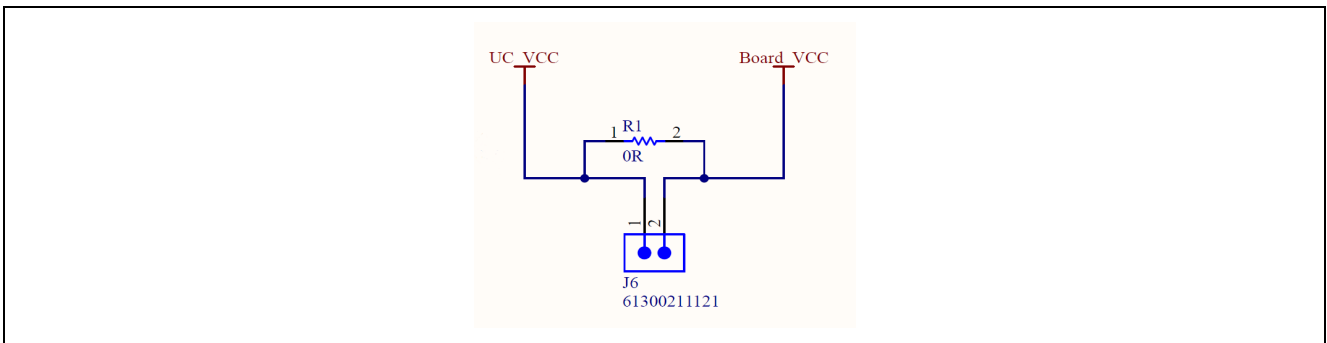


Figure 25. RX MCU Current Measurement Circuit

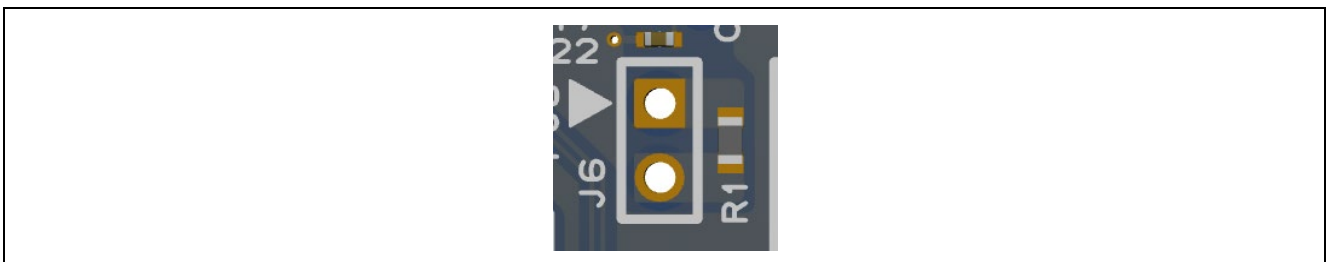


Figure 26. RX MCU Current Measurement Pin Header J6 and R1

7. Recommended Components

[Table 11](#) lists recommended part numbers for the components that can be fitted as required.

Table 11. Recommended Components

| Designator(s) | Description | Manufacturer | Part Number |
|---------------|-----------------------|------------------|-----------------------|
| Y1 | 8 MHz Crystal | Abracon | ABM3B-8.000MHZ-10-1-U |
| J1, J2 | 40-way male header | Wurth Elektronik | 61304021121 |
| J6, J8 | 2-way male header | Wurth Elektronik | 61300211121 |
| R2, R4 | 1 M Ω Resistor | Yageo | RC0603FR-071ML |
| R3 | 0 Ω Resistor | Yageo | RC0603JR-070RL |
| C10, C11 | 10 pF Capacitor | Yageo | CC0402JRNPO9BN100 |
| C14 | 10 nF Capacitor | Yageo | CC0603KRX7R9BB103 |

8. Certifications

The FPB-RX140 v1 meets the following certifications/standards. See page 4 of this user's manual for the disclaimer and precautions.

8.1 EMC/EMI Standards

- FCC Notice (Class A)



This device complies with part 15 of the FCC Rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

NOTE- This equipment has been tested and found to comply with the limits for a Class A digital device, pursuant to Part 15 of the FCC Rules. These limits are designed to provide reasonable protection against harmful interference in a residential installation. This equipment generates, uses and can radiate radio frequency energy and, if not installed and used in accordance with the instructions, may cause harmful interference to radio communications. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause harmful interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Reorient or relocate the receiving antenna.
- Increase the separation between the equipment and receiver.
- Connect the equipment into an outlet on a circuit different from that to which the receiver is connected.
- Consult the dealer or an experienced radio/television technician for help.

- Innovation, Science and Economic Development Canada ICES-003 Compliance:

CAN ICES-3 (A)/NMB-3(A)

- CE Class A (EMC)



This product is herewith confirmed to comply with the requirements set out in the Council Directives on the Approximation of the laws of the Member States relating to Electromagnetic Compatibility Directive 2014/30/EU.

Warning – This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures to correct this interference.

- UKCA Class A (EMC)



This product is in conformity with the following relevant UK Statutory Instrument(s) (and its amendments): 2016 No. 1091 Electromagnetic Compatibility Regulations 2016.

Warning – This is a Class A product. In a domestic environment this product may cause radio interference in which case the user may be required to take adequate measures to correct this interference.

- Taiwan: Chinese National Standard 13438, C6357 compliance, Class A limits
- Australia/New Zealand AS/NZS CISPR 32:2015, Class A

8.2 Material Selection, Waste, Recycling and Disposal Standards

- EU RoHS
- China SJ/T 113642014, 10-year environmental protection use period.
- WEEE Directive (2012/19/EU) & The Waste Electrical and Electronic Equipment Regulations 2013



The WEEE (Waste Electrical and Electronic Equipment) regulations put responsibilities on producers for the collection and recycling or disposal of electrical and electronic waste. Return of WEEE under these regulations is applicable in the UK and European Union.

This equipment (including all accessories) is not intended for household use. After use the equipment cannot be disposed of as household waste, and the WEEE must be treated, recycled and disposed of in an environmentally sound manner.

Renesas Electronics Europe GmbH can take back end of life equipment. Register for this service at; <https://www.renesas.com/eu/en/support/regional-customer-support/weee>

8.3 Safety Standards

- UL 94V-0

9. Design and Manufacturing Information

The design and manufacturing information for the FPB-RX140 v1 is available in the “FPB-RX140 v1 Design Package” available on renesas.com/rx/fpb-rx140.

- Design package file name: fpb-rx140-v1-designpackage.zip
- Design package contents

Table 12. FPB-RX140 v1 Design Package Contents

| File Type | Content | File / Folder Name |
|------------|---------------------|-------------------------|
| File (PDF) | Schematics | fpb-rx140-v1-schematics |
| File (PDF) | Mechanical Drawing | fpb-rx140-v1-mechdwg |
| File (PDF) | 3D Drawing | fpb-rx140-v1-3d |
| File (PDF) | BoM | fpb-rx140-v1-bom |
| Folder | Manufacturing Files | Manufacturing Files |
| Folder | Design Files | Design Files-Altium |

10. Website and Support

Visit the following URLs to learn about the kit and the RX family of microcontrollers, download tools and documentation, and get support.

| | |
|-------------------------------------|---|
| FPB-RX140 Resources | renesas.com/rx/fpb-rx140 |
| RX Kit Information | renesas.com/rx/kits |
| RX Product Information | renesas.com/rx |
| RX Product Support Forum | renesas.com/rx/forum |
| RX Videos | renesas.com/rx/videos |
| RX Kit Feedback and Feature Request | renesas.com/rx/kitfeedback |
| Renesas Support | renesas.com/support |

Revision History

| Rev. | Date | Description | |
|------|----------|-------------|-----------------|
| | | Page | Summary |
| 1.00 | Feb.2.24 | — | Initial release |

● 有害物質の含有表

Table of Hazardous Substance

| 部品名称 Part Name  | 有害物質 Hazardous Substance | | | | | |
|--|-----------------------------|-----------------------|--------------------------|---|---|--|
| | 鉛 Lead (Pb) | 水銀 Mercury (Hg) | カドミウム Cadmium (Cd) | 六価クロム Hexavalent Chromium (Cr(VI)) | ポリ臭化ビフェニル Polybrominated biphenyls (PBB) | ポリ臭化ジフェニルエーテル Polybrominated diphenyl ethers (PBDE) |
| 筐体 Case | O | O | O | O | O | O |
| ボード Board | X | O | O | O | O | O |
| ケーブル Cable | X | O | O | O | O | O |
| ソケット Socket | X | O | O | O | O | O |
| ACアダプタ AC-Adapter | X | O | O | O | O | O |

本表は SJ/T 11364 の規定により作成したものである。
This form is based on the provisions of the SJ/T 11364.

O: 当該部材の全ての均質材料中における該当有害な物質の含有量がいずれも GB/T 26572 基準に規定する限量の要求以下であることを表します。
If certain hazardous substances do not exist in this part, then mark "O" for the corresponding column, which indicates that this hazardous substance contained in all of the homogeneous materials for this part is below the limit requirement in GB/T 26572

X: 少なくとも当該部材のある均質材料中における当該有害な物質の含有量が GB/T 26572 基準に規定する限量の要求を上回ることを表します。
If certain hazardous substance is contained in this part, then "X" for the corresponding column, which indicates that this hazardous substance contained in at least one of the homogeneous materials used for this part is above the limit requirement in GB/T 26572.

このマークは、中華人民共和国で販売される電子情報製品に適用され、マーク中央の数字は環境保護使用期限の年数です。なお、本製品の年数は、通常に使用された場合の年数です。
This mark is applied to EIPs sold in People's Republic of China, and the number in the center indicates the years of the environment-friendly use period. The years for this product is applicable when the product is used normally.

注) この表には電子情報製品全ての添付品を記載しており、製品によっては同梱されていないものがございますのでご了承ください。

Notice) All of the attached items relating to 'Electronic Information Products' are listed in this table.
Please understand that there is not always bundled all of the items because it depends on the product.

● 製造年の確認方法に関して About Confirmation method of produced year

製品或いは梱包箱に表記された銘板ラベル等から製造年をご確認頂けます。
Please confirm the produced year from nameplate label etc on product body or outer box.

Ex) 2016 年の場合

Produced 2016

● 有害物质含有情况表

Table of Hazardous Substance

| 部件名称 Part Name  | 有害物质 Hazardous Substance | | | | | |
|--|-----------------------------|----------------------|----------------------|---|--|--|
| | 铅 Lead (Pb) | 汞 Mercury (Hg) | 镉 Cadmium (Cd) | 六价铬 Hexavalent Chromium (Cr(VI)) | 多溴联苯 Polybrominated biphenyls (PBB) | 多溴二苯醚 Polybrominated diphenyl ethers (PBDE) |
| 外壳 Case | O | O | O | O | O | O |
| 电路板 Board | X | O | O | O | O | O |
| 连接线 Cable | X | O | O | O | O | O |
| 插座 Socket | X | O | O | O | O | O |
| AC 适配器 AC-Adapter | X | O | O | O | O | O |

本表格依据 SJ/T 11364 的规定编制。
This form is based on the provisions of the SJ/T 11364.

O: 表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 标准规定的限量要求以下。
If certain hazardous substances do not exist in this part, then mark "O" for the corresponding column, which indicates that this hazardous substance contained in all of the homogeneous materials for this part is below the limit requirement in GB/T 26572.

X: 表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 标准规定的限量要求。
If certain hazardous substance is contained in this part, then "X" for the corresponding column, which indicates that this hazardous substance contained in at least one of the homogeneous materials used for this part is above the limit requirement in GB/T 26572.

该标识适用于在中华人民共和国境内销售的电子信息产品。本产品的使用年限是组装到整机中, 通常情况下能使用的年限。
This mark is applied to EIPs sold in People's Republic of China, and the number in the center indicates the years of the environment-friendly use period. The years for this product is applicable when the product is used normally.

特别提示) 该表中包括在电子情报产品系列产品所有的附件。产品不同时, 包装内的附件会有所不同。

Notice) All of the attached items relating to 'Electronic Information Products' are listed in this table.

Please understand that there is not always bundled all of the items because it is depends on a product.

● 识别生产日期的方法 About Confirmation method of produced year

请通过产品或产品外包装箱上的序列号识别生产日期。

Please confirm the produced year from nameplate label etc on product body or outer box.

如) 生产日期为2016 年

Produced 2016

FPB-RX140 v1 User's Manual

Publication Date: Feb.2.24 Rev.1.0

Published by: Renesas Electronics Corporation

FPB-RX140 v1 User's Manual