

E1/E20 Emulator

Additional Document for User's Manual
(Notes on Connection)

Supported Devices:
V850ES, V850E1

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1. Outline

1.1 Features

E1/E20 Emulator is an on-chip debug emulator with flash programming function, which is used for debugging and programming a program to be embedded in on-chip flash memory microcontrollers. This product can debug with the target microcontroller connected to the target system, and can write programs to the on-chip flash memory of microcontrollers.

1.2 Cautions on Using E20

The functions used for debugging of the V850E2M, V850E2S device by using the E20 are the same as in the E1. Large trace function, characteristic functions of the E20, cannot be used. The power supply function from the E20 is not supported.

1.3 Configuration of Manuals

Documentation for the E1/E20 emulator manual is in two parts: the E1/E20 Emulator User's Manual and the E1/E20 Emulator Supplementary Document for the User's Manual (this manual). Different versions of the latter correspond to different sets of MCUs. Be sure to read both of the manuals before using the E1/E20 emulator (hereinafter referred to as "the emulator").

(1) The E1/E20 emulator user's manual has the following contents:

- Components of the emulators
- Emulator hardware specification
- Connection to the emulator and the host computer and user system

(2) The E1/E20 Emulator Supplementary Document for the User's Manual has the following contents:

- For use in hardware design, an example of connection and the interface circuit required to connect the emulator.
- Notes on using the emulator

2. Designing the User System

To connect the E1/E20 emulator (hereinafter referred to as the emulator), a connector for the user system interface cable must be mounted on the user system. When designing the user system, read this section of this manual and the hardware manual for the MCUs.

2.1 Connecting the Emulator with the User System

Table 2-1 shows the type numbers of the E1/E20 emulators

Table 2-1 Type Numbers

	Type Number	Manufacturer	仕様
14-pin Connector	7614-6002	Sumitomo 3M Limited	14-pin straight type (Japan)
	2514-6002	3M Limited	14-pin straight type (other countries)

Figures 2.1 and 2.2 show examples of the connection between a user system interface cable of the 14-pin type. Do not mount other components with a height exceeding 10 mm within 5 mm of the connector on the user system. 38-pin of the E20 is not supported. To use the E20, use the 38-pin/14-pin conversion adapter [R0E000200CKA00] that comes with the E20 for connection.

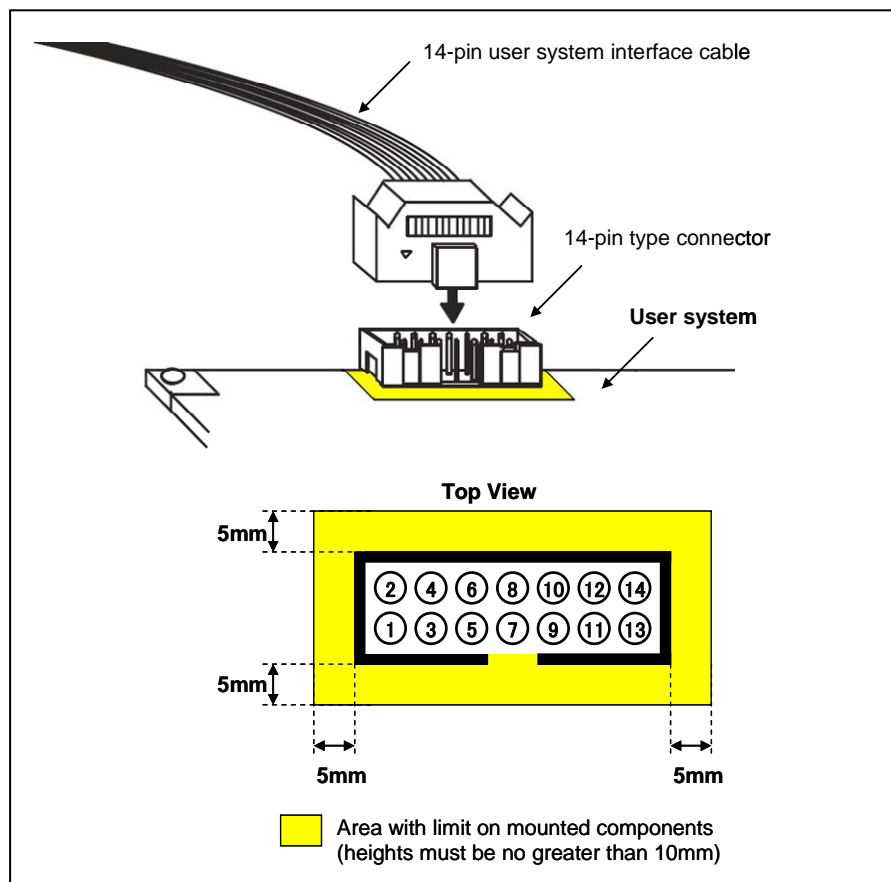


Figure 2-1 Connecting the User System Interface Cable to the 14-pin Connector of the E1/E20 Emulator

2.2 Pin Assignments of the Connector on the User System

Table 2-2 shows the pin assignments of the 14-pin connectors.

Table 2-2 Pin assignments of the connector (14-pin)

Pin No.	Signal (# : Low Active)			Input/ Output ^{note3}
	JTAG Connection	UART Connection	CSI Connection	
1	TCK	–	SCK	入力
2 【注1】	GND	GND	GND	–
3	TRST#	CLK	CLK	入力
4	FLMDO	FLMDO	FLMDO	入力
5	TDO	RxD	SI	出力
6	–	RESET_IN#	RESET_IN#	出力
7	TDI	TxD	SO	入力
8	VDD	VDD	VDD	–
9	TMS	FLMD1	FLMD1	入力
10	–	RESET_OUT# 【注2】	RESET_OUT# 【注2】	入力
11	–	–	HS	出力
12 【注1】	GND	GND	GND	–
13	RESET_OUT#	RESET_OUT# 【注2】	RESET_OUT# 【注2】	入力
14 【注1】	GND	GND	GND	–

Notes 1. Securely connect pins 2, 12, and 14 of the connector to GND of the user system. These pins are used for electrical grounding as well as for monitoring of connection with the user system by the E1/E20.

2. Securely connect both pin 10 and pin 13. These pins are also used to monitor the user system.

3. Input to or output from the user system

2.3 Recommended Circuit between the Connector and the MCU

This section describes recommended circuits for connection between the 14-pin connector and the MCU. There are 3 types of connection JTAG, UART and CSI as following table. Select the relevant circuit for the purpose.

Table 2-3

Interface Type	Debugging		Programming
	Support	User space for debugging	Support
JTAG	○	None	×
UART	○	ROM:2K bytes, RAM:16 bytes	○
CSI	○	ROM:2K bytes, RAM:16 bytes	○

2.3.1 JTAG Recommended Circuit

Figure 2-2 shows a recommended circuit for JTAG connection. Be sure to take into consideration the specifications of the target device as well as measures to prevent noise when designing your circuit.

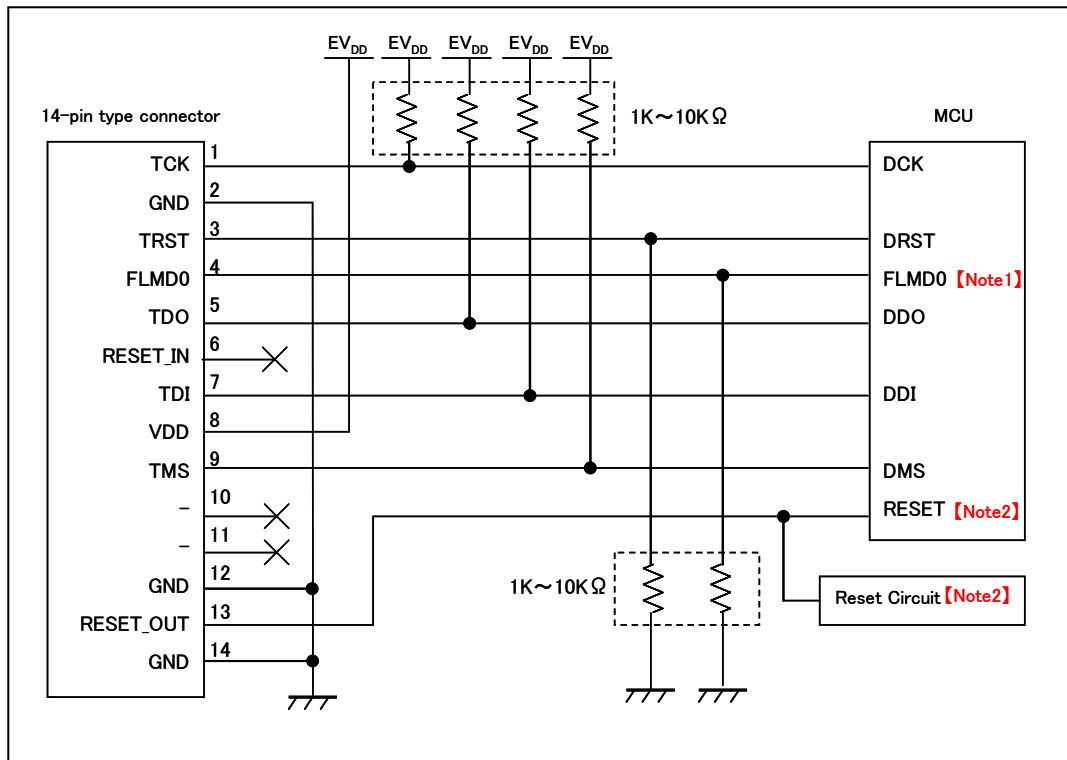


Figure 2-2 JTAG recommended circuit

[Caution] Wiring patterns between the connector and the MCU must be as short as possible

[Note] 1. This circuit is for not using flash self programming. To use flash self programming, refer to 2.3.4.

2. This circuit is for reset MCU between turning on the user system to startup the debugger, and this circuit is designed assuming that RESET signal is output from the N-ch open-drain buffer. For details, refer to 0.

2.3.2 UART Recommended Circuit

Figure 2-3 shows a recommended circuit for UART connection. Be sure to take into consideration the specifications of the target device as well as measures to prevent noise when designing your circuit.

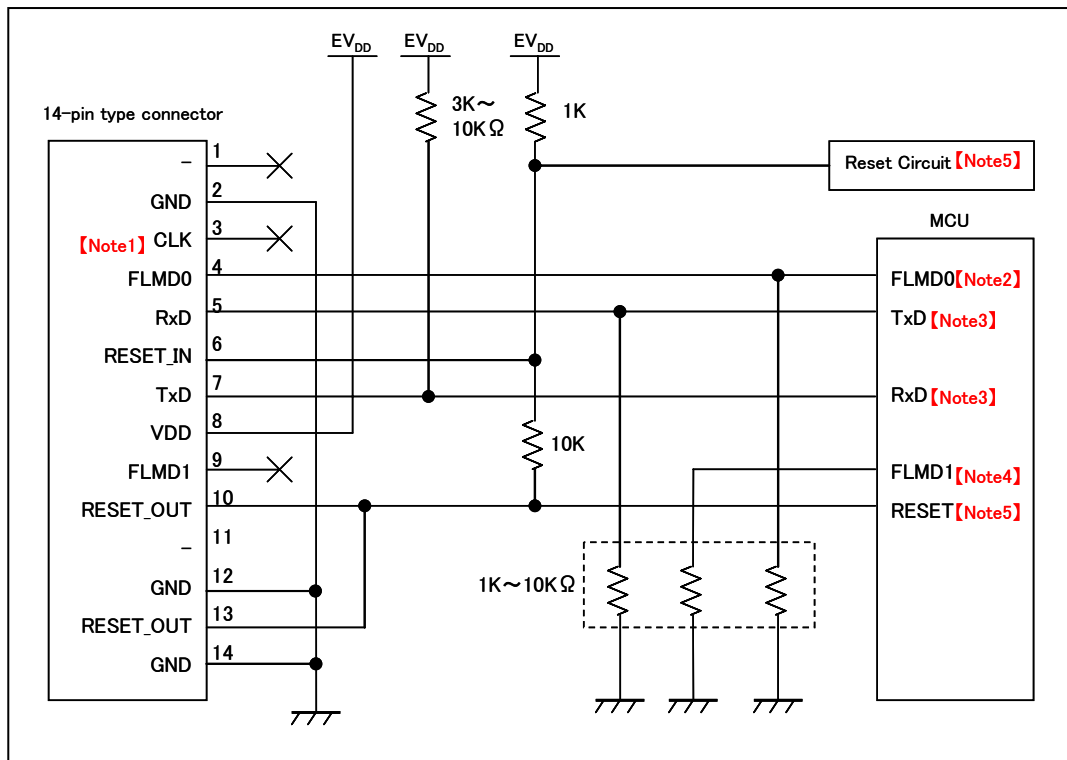


Figure 2-3 UART recommended circuit

- 【Note】 1. This pin may be used to supply an external clock during flash programming (4, 8 or 16 MHz). For the connection, refer to the user's manual for the target device.
- 2. This circuit is for not using flash self programming. To use flash self programming, refer to 2.3.4.
- 3. Read the serial interface pin names on the target device side as those for flash programming supported by the target device (For example, Tx D0/Rx D0).
- 4. In case the alternate function of this pin is used, connect to FLMD1 pin. The emulator output low level when flash programming.
- 5. This circuit is designed assuming that RESET signal is output from the N-ch open-drain buffer (out put resistance: 100Ω or less). For details, refer to 0.

2.3.3 CSI Recommended Circuit

Figure 2-4 shows a recommended circuit for CSI connection. Be sure to take into consideration the specifications of the target device as well as measures to prevent noise when designing your circuit.

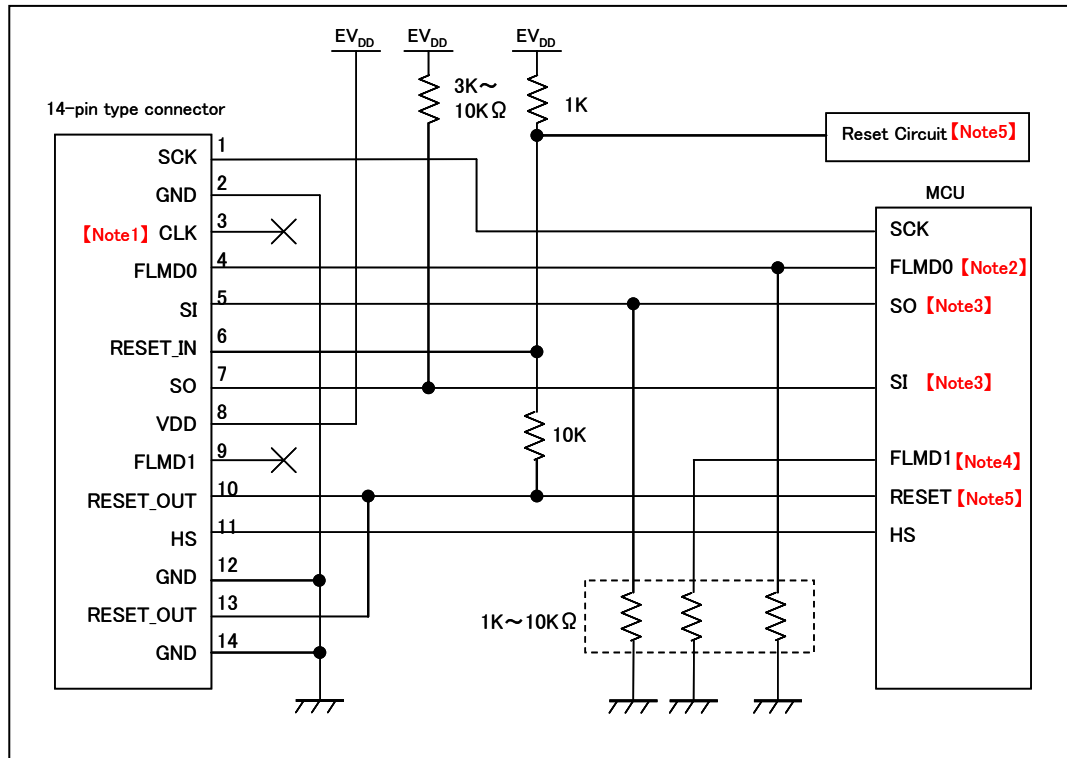


Figure 2-4 CSI recommended circuit

- [Note] 1. This pin may be used to supply an external clock during flash programming (4, 8 or 16 MHz). For the connection, refer to the user's manual for the target device.
- 2. This circuit is for not using flash self programming. To use flash self programming, refer to 2.3.4.
- 3. Read the serial interface pin names on the target device side as those for flash programming supported by the target device (For example, SOB0/SIB0).
- 4. In case the alternate function of this pin is used, connect to FLMD1 pin. The emulator output low level when flash programming.
- 5. This circuit is designed assuming that RESET signal is output from the N-ch open-drain buffer (out put resistance: 100Ω or less). For details, refer to 0.

2.3.4 Regarding Connection of FLMD0

FLMD0 is used to write the flash memory. In case the user program use flash self programming, connect as Figure 2-5. PortX indicates arbitrary Port.

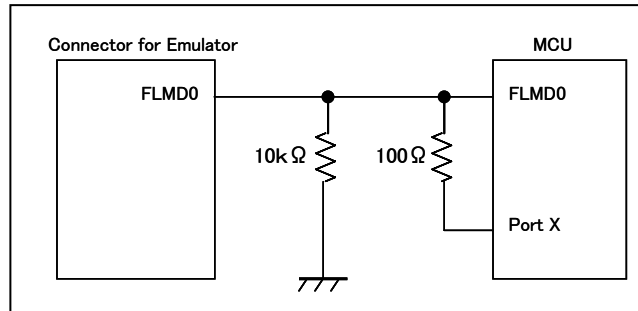


Figure 2-5 Recommended circuit when using flash self programming

2.3.5 Regarding Connection of RESET

RESET connection depends on each interface type, JTAG, UART or CSI. Refer to following due to the interface type.

(1) JTAG interface

Connect the RESET signal as shown in Figure 2-6 if any of the conditions listed below is satisfied. When none of the following conditions are satisfied, leave open the pin for the RESET signal that is output from the E1/E20 emulator.

- The target device should be kept in the reset state before debugger startup or after debugger termination.
- The JTAG signal pins are alternate-function pins in the specifications of the target device, and OCDM register is set to use port/peripheral function pin at the user program.

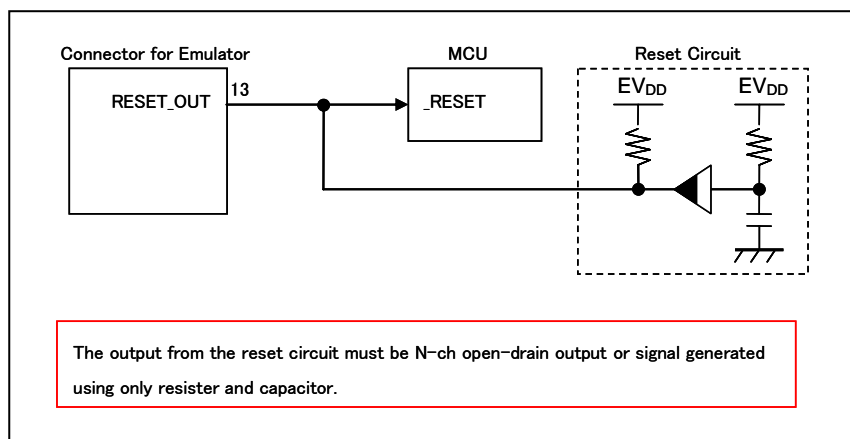


Figure 2-6 Reset circuit in case of JTAG connection

(2) UART/CSI Interface

Select one of the following 3 methods and connect the reset signal in the circuit. During on-chip debugging, a reset signal from the target system is input to E1/E20 Emulator, masked, and then output to the target device. Therefore, the reset signal connection varies depending on whether E1/E20 emulator is connected.

•Automatically switching the reset signal via series resistor

This connection in Figure 2-7 is designed assuming that the reset circuit on the target system contains an N-ch open-drain buffer (output resistance: 100Ω or less). The VDD or GND level may be unstable when the logic of RESET_IN/OUT of E1/E20 Emulator is inverted, so observe the conditions described below in Remark.

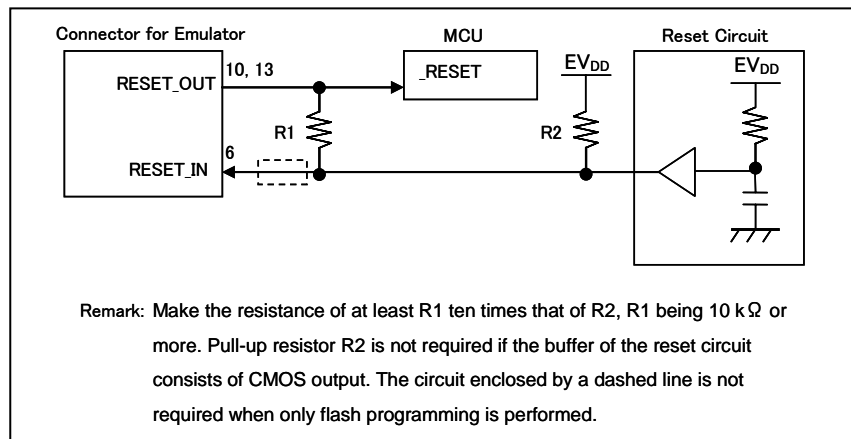


Figure 2-7 Reset circuit in case of UART/CSI connection 1

•Manually switching the reset signal with jumper

Figure 2-8 illustrates the circuit connection for the case where the reset signal is switched using the jumper, with or without E1/E20 emulator connected. This connection is simple, but the jumper must be set manually.

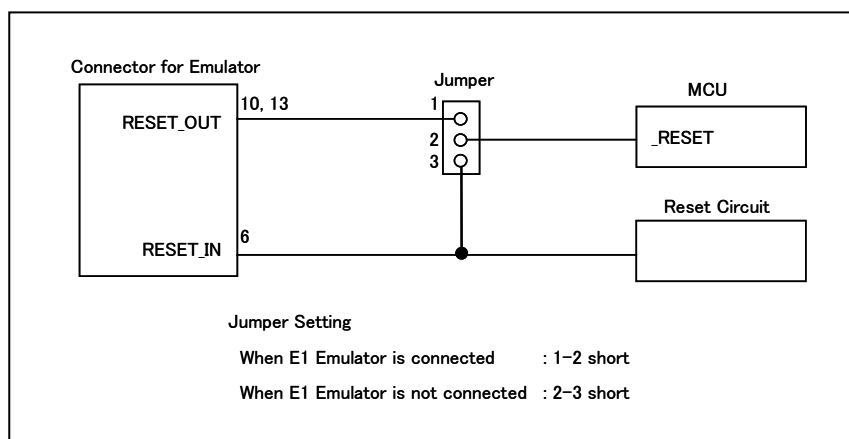


Figure 2-8 Reset circuit in case of UART/CSI connection 2

- Resetting the target device by power-on clear (POC) only

Figure 2-9 illustrates the circuit connection for the case where the target device is only reset via POC without using the reset pin. RESET_OUT is valid only when the debugger is running or during flash programming.

The operation is not guaranteed if the power to the target system is shut down during debugging. Note that the POC function cannot be emulated.

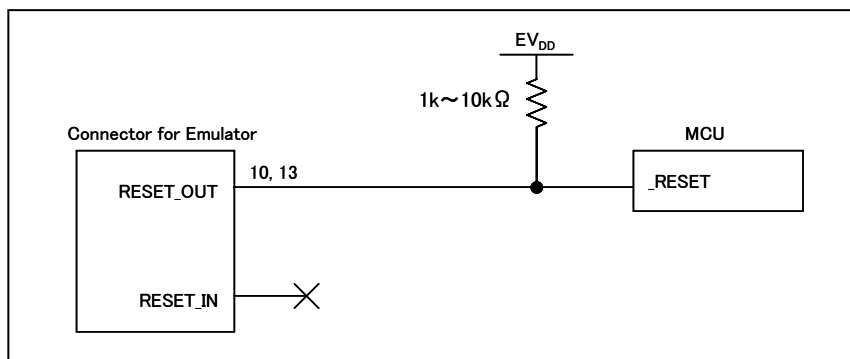


Figure 2-9 Reset circuit in case of UART/CSI connection 3

3. Setting of Security ID and Securing of debugging resources

The user must prepare the following to perform communication between E1/E20 emulator and the target device and implement each debug function. Refer to the descriptions on the following sections and set these items in the user program or using the compiler options. When using JTAG interface, the setting of this section is needless.

3.1 Setting of Security ID

This setting is required to prevent the memory from being read by an unauthorized person. Embed a security ID at addresses 0x70 to 0x79 in the internal flash memory. The debugger starts only when the security ID that is set during debugger startup and the security ID set at addresses 0x70 to 0x79 match. If bit 7 of address 0x79 is "0", however, debugging is disabled. In such a case, there are no methods to start the debugger. Debugging is mainly disabled for mass-produced devices.

If the user has forgotten the security ID or to enable debugging, erase the flash memory and set the security ID again.

[How to set security ID]

Embed a security ID at addresses 0x70 to 0x79 in the user program.

If the security ID is embedded as follows, for example, the security ID set by the debugger is "123456789ABCDEF123D4" (not case-sensitive).

Address	Value
0x70	0x12
0x71	0x34
0x72	0x56
0x73	0x78
0x74	0x9A
0x75	0xBC
0x76	0xDE
0x77	0xF1
0x78	0x23
0x79	0xD4

3.2 Reset handler

A reset handler includes the jump instruction for the debug monitor program. When using JTAG interface, the setting of this section is needless.

[How to secure areas]

It is not necessary to secure this area intentionally. When downloading a program, however, the debugger rewrites the reset vector in accordance with the following cases. If the rewritten pattern does not match the following cases, the debugger generates an error.

- When two nop instructions are placed in succession from address 0

Before writing		After writing
0x0 nop	→	Jumps to debug monitor program at 0x0
0x2 nop		0x4 xxxx
0x4 xxxx		

- When two 0xFFFF are successively placed from address 0 (already erased device)

Before writing		After writing
0x0 0xFFFF	→	Jumps to debug monitor program at 0x0
0x2 0xFFFF		0x4 xxxx
0x4 xxxx		

- The jr instruction is placed at address 0 (when using Renesas Electronics compiler CA850)

Before writing		After writing
0x0 jr disp22	→	Jumps to debug monitor program at 0x0
		0x4 jr disp22 - 4

- mov32 and jmp are placed in succession from address 0 (when using IAR compiler ICCV850)

Before writing		After writing
0x0 mov imm32,reg1	→	Jumps to debug monitor program at 0x0
0x6 jmp [reg1]		0x4 mov imm32,reg1
		0xa jmp [reg1]

- The jump instruction for the debug monitor program is placed at address 0

Before writing		After writing
Jumps to debug monitor program at 0x0	→	No change

3.3 Securing of area for debugging

The area for debugging is for performing initialization processing for debug communication interface and RUN or break processing for the CPU. The internal ROM area must be filled with 0xFF. This area must not be rewritten by the user program.

[How to secure areas]

It is not necessarily required to secure this area if the user program does not use this area.

To avoid problems that may occur during the debugger startup, however, it is recommended to secure this area in advance, using the compiler. The following shows examples for securing the area, using the Renesas Electronics compiler CA850. Add the assemble source file and link directive code, as shown below.

- Assemble source (Add the following code as an assemble source file.)

```
-- Secures 2 KB space for monitor ROM section
.section "MonitorROM", const
.space 0x800, 0xffNote

-- Secures interrupt vector for debugging
.section "DBG0"
.space 4, 0xff

-- Secures interrupt vector for serial communication for receive
-- Secures vector for receive error interrupt and receive status interrupt, if any
-- Change the section name according to serial communication mode used
.section "INTCSI00"
.space 4, 0xff

-- Secures 16 byte space for monitor ROM section
.section "MonitorRAM", bss
.lcomm monitorramsym, 16, 4 /* defines monitorramsym symbol */
```

Note The downloading speed can be increased by replacing this line with the statement "monitorramsym:" to perform a symbol definition only. This effect is not applicable if values are filled into a hole (area without a code). When performing filling, the filling value must be 0xFF for securing the area.

- Link directive (Add the following code to the link directive file.)

The following shows an example when the internal ROM end address is 0x3fff and internal RAM end address is 0x3fefff.

```
MROMSEG : !LOAD ?R V0x03f800{
MonitorROM = $PROGBITS ?A MonitorROM;
};
MRAMSEG : !LOAD ?RW V0x03feff0{
MonitorRAM = $NOBITS ?AW MonitorRAM;
};
```

3.4 Securing of communication serial interface

UART or CSI-H/S is used for communication between E1/E20 emulator and the target system. The settings related to the serial interface modes are performed by the debug monitor program, but if the setting is changed by the user program, a communication error may occur.

To prevent such a problem from occurring, communication serial interface must be secured in the user program.

[How to secure communication serial interface]

Create the user program observing the following points.

- Serial interface registers

Do not set the registers related to UART and CSI-H/S in the user program.

- Interrupt mask register

When UART is used, do not mask receive end interrupts^{Note}. When CSI-H/S is used, do not mask transmit end interrupts. The following shows an example.

Example Setting other than below is prohibited when the target device is the V850ES/KJ2 and CSI00 is used.

	7	6	5	4	3	2	1	0
CSI0IC0	x	0	x	x	x	x	x	x

x:Any

Note: Do not mask receive these interrupts when there is a receive error interrupt or a receive status interrupt.

- Port registers

When UART is used, do not set port registers to make the TxD and RxD pins invalid. When CSI-H/S is used, do not set port registers to make the SI, SO, SCK and H/S pins invalid. The H/S pin is used as the port output for debugging. The following shows two examples.

Example 1: Setting other than below is prohibited when the target device is the V850ES/KJ2 and UART0 is used.

	7	6	5	4	3	2	1	0
PFC3	x	x	x	x	x	x	0	0

	7	6	5	4	3	2	1	0
PMC3L	x	x	x	x	x	x	1	1

x: Any

Example 2: Setting other than below is prohibited when the target device is the V850ES/HG2 and CSIB0 is used.

	7	6	5	4	3	2	1	0
PMC4	x	x	x	x	x	1	1	1
PMCCM	x	x	x	x	x	x	x	0
PMCM	x	x	x	x	x	x	x	0
PCM	x	x	x	x	x	x	x	Read-only ^{Note}

x: Any

Note: The port values corresponding to the H/S pin are changed by the monitor program according to the debugger status. To perform port register settings in 8-bit units, usually the user program can use read-modify-write. If an interrupt for debugging occurs before writing, however, an unexpected operation may be performed.

4. Specifications

Specifications are below table.

Large Item	Middle Item	Small Item	Specification
Hardware Common	Target host machine		Computer equipped with a USB port OS is due to the software tool.
	User system interface		14-pin connector
	Host machine interface		USB2.0 (Full speed/ High speed)
	Connection to the user system		Connection by the provided user-system interface cable
	Power supply function (E1 Emulator used)		3.3V or 5.0V, set in software tool, can be supplied to the user system (with current up to 200 mA)
	Power supply for the emulator		No need (the host computer supplies power through the USB)
Related debugging	Break	Software break	ROM area :4 points RAM area :2000 points
		Hardware break	2points (commonly used by execution and access)
		Forced break	Available
	Event	Number of events	2points (commonly used by execution and access)
		Available function	Only hardware break
		Combination of events	OR, sequential
	Trace		Unavailable
	Performance measurement	Measurement item	From run to break
		Performance	JTAG interface Resolution 100ns, Max. measurement time 3.5 minutes (During DCK is 20MHz) UART/CSI interface Resolution 100us, Max. measurement time 100 hour
	Realtime RAM monitor		Available (CPU is used when monitoring)
	Direct memory modification		Available (CPU is used when monitoring)
	Debugging console		Unavailable
	Downloading to external flash memory		Available (Depends on Software)
	Hot plug-in		Unavailable
Security		10-byte ID code authentication	
Related programming	Clock supply		16, 8, or 4 MHz clock can be supplied Clock mounted on the target system can be used
	Security flag setting		Available
	Standalone operation		Unavailable (must be connected to host machine)

5. Notes on Usage

Make sure to notes on usage in this section.

5.1 Lists

Table 5-1 Lists of notes on usage

No	Item	Target
1	Handling of device that was used for debugging	JTAG, UART, CSI
2	Alternate functions	JTAG, UART, CSI
3	Notes on downloading	JTAG, UART, CSI
4	Regarding ROM correction function	JTAG, UART, CSI
5	Regarding current consumption	JTAG, UART, CSI
6	Regarding standby release with debugging functions	JTAG, UART, CSI
7	Notes on flash self programming	JTAG, UART, CSI
8	Regarding POC function and emulation of turning OFF	JTAG, UART, CSI
9	Regarding I/O buffer when using reset mask	JTAG
10	When forced break, RRM function and DMM function do not operate	UART, CSI
11	Writing to peripheral I/O registers that requires a specific sequence, using DMM function	UART, CSI
12	Writing quality of flash programming	UART, CSI
13	Debugging with real machine running	UART, CSI
14	Regarding watchdog timer	UART, CSI
15	Regarding external reset	UART, CSI
16	Regarding reset vector handling	UART, CSI

5.2 Details

No.1 Handling of device that was used for debugging

Target: JTAG, UART, CSI

Description: Do not mount a device that was used for debugging on a mass-produced product, because the flash memory was rewritten during debugging and the number of rewrites of the flash memory cannot be guaranteed. When the flash memory can not be rewritten, the software tool generates the error. In case of that, change the mounted device.

No.2 Alternate functions

Target: JTAG, UART, CSI

Description: The alternate functions of these pins cannot be used during on-chip debugging. And be careful not to conflict the signals from emulator while the flash programming is operating.

No.3 Notes on downloading

Target: JTAG, UART, CSI

Description: When debugging, reset CPU before downloading. If DMA transfer to the internal RAM is performed while a program is being downloaded to the flash memory, downloading of the program may not be performed normally.

No.4 Regarding ROM correction function

Target: JTAG, UART, CSI

Description: Do not use the ROM correction function or else unexpected breaks will occur.

No.5 Regarding current consumption

Target: JTAG, UART, CSI

Description: The current consumption in the target device increases during debugging compared with that in normal operation mode, because the OCD unit of the target device operates during debugging.

No.6 Regarding standby release with debugging functions

Target: JTAG, UART, CSI

Description: In case using the RRM function and DMM function, the standby mode is released when the memory is read or written.

No.7 Notes on flash self programming

Target: JTAG, UART, CSI

Description: Do not break in ROM area during flash environment. In case of monitoring memory with RRM function, a temporary break is executed. So do not use RRM function when using flash self programming.

Do not modify the debug monitor area when using UART/CSI interface.

No.8 Regarding POC function and emulation of turning OFF

Target: JTAG, UART, CSI

Description: Make sure that the power to the target system is not shut down during debugging. Regarding to check the operation of POC function and tuning OFF, perform without the emulator. In case the user system is turning OFF instantaneously, the debugger may hang up.

No.9 Regarding I/O buffer when using reset mask

Target: JTAG

Description: The I/O buffer (port pin) may enter the reset status depending on the target device when a reset is input from the pin, even if reset is masked by the mask function.

No.10 When forced break, RRM function and DMM function do not operate

Target: UART, CSI

Description: Forced breaks, RRM function and DMM function cannot be executed if one of the following conditions is satisfied.

- Interrupts are disabled (DI)
- Interrupts issued for UART/CSI interface are masked
- Standby mode is entered while standby release by a maskable interrupt is prohibited
- When using UART interface, the main clock has been stopped
- When using UART interface, a clock different from the one specified in the debugger is used for communication

No.11 Writing to peripheral I/O registers that requires a specific sequence, using DMM function

Target: UART, CSI

Description: Peripheral I/O registers that requires a specific sequence cannot be written with the DMM function.

No.12 Writing quality of flash programming

Target: UART, CSI

Description: To improve the writing quality, fully understand, verify, and evaluate the following items before using E1/E20 emulator.

- Circuits are designed as described in the user's manuals for the device and E1/E20 emulator.
- The device, E1/E20 emulator and the software are used as described in each user's manual.
- The power supplied to the target system is stable.

No.13 Debugging with real machine running

Target: UART, CSI

Description: If debugging is performed with a real machine running, without using emulator, write the user program using the programming software. Programs downloaded by the debugger include the monitor program, and such a program malfunctions if it is not controlled via E1/E20 emulator.

No.14 Regarding watchdog timer

Target: UART, CSI

Description: The watchdog timer is forcibly stopped by the debug monitor program. Therefore, do not use the option byte to specify that the watchdog timer cannot be stopped. For details about the option byte settings, see the user's manual of the target device.

No.15 Regarding external reset

Target: UART, CSI

Description: A break occurs when an external reset occurs (except when resets are masked) or an internal reset occurs.

No.16 Regarding reset vector handling

Target: UART, CSI

Description: Reset vector handling is not supported.

E1/E20 Emulator
Additional Document for User's Manual (Notes on Connection)

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