

To our customers,

---

## Old Company Name in Catalogs and Other Documents

---

On April 1<sup>st</sup>, 2010, NEC Electronics Corporation merged with Renesas Technology Corporation, and Renesas Electronics Corporation took over all the business of both companies. Therefore, although the old company name remains in this document, it is a valid Renesas Electronics document. We appreciate your understanding.

Renesas Electronics website: <http://www.renesas.com>

April 1<sup>st</sup>, 2010  
Renesas Electronics Corporation

Issued by: Renesas Electronics Corporation (<http://www.renesas.com>)

Send any inquiries to <http://www.renesas.com/inquiry>.

## Notice

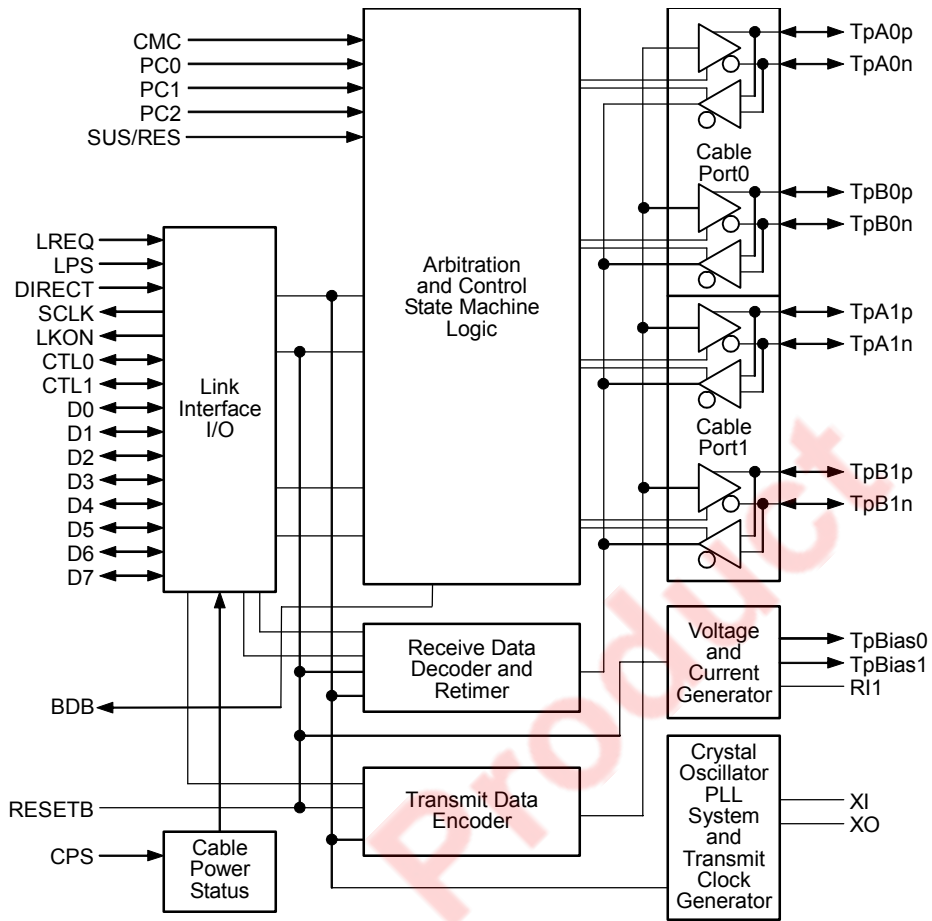
1. All information included in this document is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas Electronics products listed herein, please confirm the latest product information with a Renesas Electronics sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas Electronics such as that disclosed through our website.
2. Renesas Electronics does not assume any liability for infringement of patents, copyrights, or other intellectual property rights of third parties by or arising from the use of Renesas Electronics products or technical information described in this document. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.
3. You should not alter, modify, copy, or otherwise misappropriate any Renesas Electronics product, whether in whole or in part.
4. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
5. When exporting the products or technology described in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations. You should not use Renesas Electronics products or the technology described in this document for any purpose relating to military applications or use by the military, including but not limited to the development of weapons of mass destruction. Renesas Electronics products and technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations.
6. Renesas Electronics has used reasonable care in preparing the information included in this document, but Renesas Electronics does not warrant that such information is error free. Renesas Electronics assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein.
7. Renesas Electronics products are classified according to the following three quality grades: “Standard”, “High Quality”, and “Specific”. The recommended applications for each Renesas Electronics product depends on the product’s quality grade, as indicated below. You must check the quality grade of each Renesas Electronics product before using it in a particular application. You may not use any Renesas Electronics product for any application categorized as “Specific” without the prior written consent of Renesas Electronics. Further, you may not use any Renesas Electronics product for any application for which it is not intended without the prior written consent of Renesas Electronics. Renesas Electronics shall not be in any way liable for any damages or losses incurred by you or third parties arising from the use of any Renesas Electronics product for an application categorized as “Specific” or for which the product is not intended where you have failed to obtain the prior written consent of Renesas Electronics. The quality grade of each Renesas Electronics product is “Standard” unless otherwise expressly specified in a Renesas Electronics data sheets or data books, etc.
  - “Standard”: Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; and industrial robots.
  - “High Quality”: Transportation equipment (automobiles, trains, ships, etc.); traffic control systems; anti-disaster systems; anti-crime systems; safety equipment; and medical equipment not specifically designed for life support.
  - “Specific”: Aircraft; aerospace equipment; submersible repeaters; nuclear reactor control systems; medical equipment or systems for life support (e.g. artificial life support devices or systems), surgical implantations, or healthcare intervention (e.g. excision, etc.), and any other applications or purposes that pose a direct threat to human life.
8. You should use the Renesas Electronics products described in this document within the range specified by Renesas Electronics, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas Electronics shall have no liability for malfunctions or damages arising out of the use of Renesas Electronics products beyond such specified ranges.
9. Although Renesas Electronics endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, Renesas Electronics products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas Electronics product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
10. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. Please use Renesas Electronics products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Renesas Electronics assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
11. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written consent of Renesas Electronics.
12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products, or if you have any other inquiries.

(Note 1) “Renesas Electronics” as used in this document means Renesas Electronics Corporation and also includes its majority-owned subsidiaries.

(Note 2) “Renesas Electronics product(s)” means any product developed or manufactured by or for Renesas Electronics.



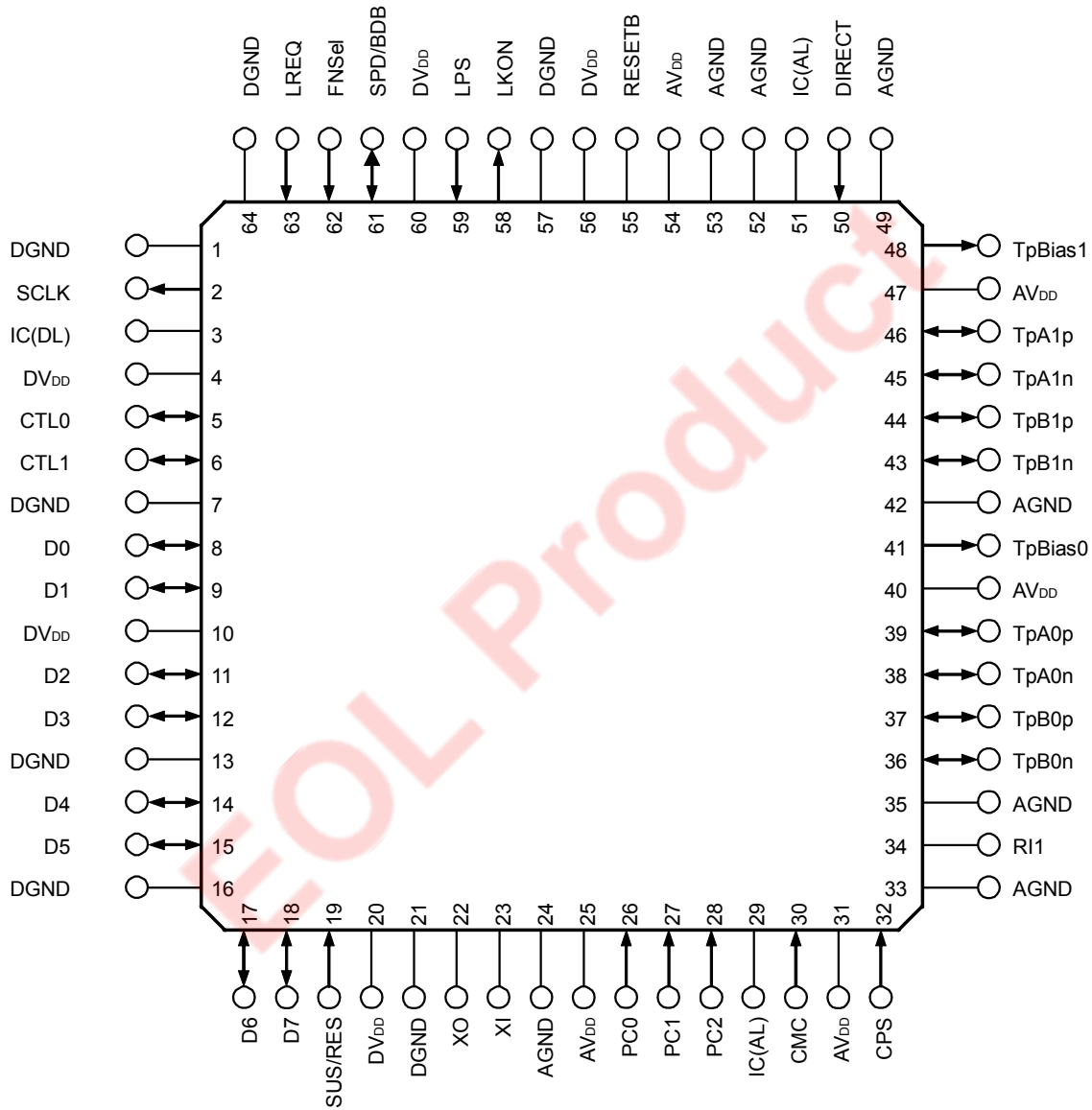
BLOCK DIAGRAM



**PIN CONFIGURATION (Top View)**

- μPD72852AGB-8EU

64-pin plastic LQFP (10 × 10)



**PIN NAME**

AGND	: Analog GND
AV <sub>DD</sub>	: Analog Power
CMC	: Configuration Manager Capable
CPS	: Cable Power Status
CTL0	: Link Interface Control (bit 0)
CTL1	: Link Interface Control (bit 1)
D0-D7	: Data Input/Output
DGND	: Digital GND
DIRECT	: PHY/Link Isolation Barrier Control Input
DV <sub>DD</sub>	: Digital V <sub>DD</sub>
FNSel	: Function Select
IC(AL)	: Internally Connected (Low Clamped)
IC(DL)	: Internally Connected (Low Clamped)
LKON	: Link-on Signal Output
LPS	: Link Power Status Input
LREQ	: Link Request Input
PC0-PC2	: Power Class Set Input
RESETB	: Power-on Reset Input
RI1	: Reference Power Set, Connect Resistor 1
SCLK	: Link Control Output Clock
SPD/BDB	: Speed Select input / BIAS Detected output
SUS/RES	: Suspend/Resume Function Select
TpA0n	: Port 0 Twisted Pair Cable A Negative Phase I/O
TpA0p	: Port 0 Twisted Pair Cable A Positive Phase I/O
TpA1n	: Port 1 Twisted Pair Cable A Negative Phase I/O
TpA1p	: Port 1 Twisted Pair Cable A Positive Phase I/O
TpB0n	: Port 0 Twisted Pair Cable B Negative Phase I/O
TpB0p	: Port 0 Twisted Pair Cable B Positive Phase I/O
TpB1n	: Port 1 Twisted Pair Cable B Negative Phase I/O
TpB1p	: Port 1 Twisted Pair Cable B Positive Phase I/O
TpBias0	: Port 0 Twisted Pair Output
TpBias1	: Port 1 Twisted Pair Output
XI	: Crystal Oscillator Connection XI
XO	: Crystal Oscillator Connection XO

CONTENTS

1. PIN FUNCTIONS..... 7

    1.1 Cable Interface Pins ..... 7

    1.2 Link Interface Pins ..... 7

    1.3 Control Pins ..... 8

    1.4 IC ..... 8

    1.5 Power Supply Pins ..... 8

    1.6 Other Pins ..... 9

2. PHY REGISTERS ..... 10

    2.1 Complete Structure for PHY Registers ..... 10

    2.2 Port Status Page (Page 000) ..... 13

    2.3 Vendor ID Page (Page 001)..... 14

    2.4 Vendor Dependent Page (Page 111 : Port\_select 0000)..... 14

    2.5 Vendor Dependent Page (Page 111 : Port\_select 0001)..... 15

3. INTERNAL FUNCTION..... 16

    3.1 Link Interface ..... 16

        3.1.1 Connection Method ..... 16

        3.1.2 LPS (Link Power Status) ..... 16

        3.1.3 LREQ, CTL0, CTL1 and D0-D7 Pins..... 16

        3.1.4 SCLK..... 16

        3.1.5 LKON ..... 17

        3.1.6 DIRECT..... 17

        3.1.7 Isolation Barrier ..... 17

    3.2 Cable Interface..... 19

        3.2.1 Connections ..... 19

        3.2.2 Cable Interface Circuit..... 20

        3.2.3 Unused Ports ..... 20

        3.2.4 CPS..... 20

    3.3 Suspend/Resume ..... 20

        3.3.1 Suspend/Resume On Mode (SUS/RES = "H")..... 20

        3.3.2 Suspend/Resume Off Mode (SUS/RES = "L") ..... 20

    3.4 PLL and Crystal Oscillation Circuit..... 21

        3.4.1 Crystal Oscillation Circuit ..... 21

        3.4.2 PLL..... 21

    3.5 CMC ..... 21

    3.6 PC0-PC2 ..... 21

    3.7 RESETB ..... 21

    3.8 RI1 ..... 21

4. PHY/LINK INTERFACE ..... 22

    4.1 Initialization of Link Power Status (LPS) and PHY/Link Interface..... 22

    4.2 Link-on Indication ..... 23

    4.3 PHY/Link Interface Operation (CTL0, CTL1, LREQ, D0-D7) ..... 24

        4.3.1 CTL0, CTL1 ..... 24

        4.3.2 LREQ ..... 24

4.3.3 SCLK Timing ..... 28

**4.4 Acceleration Control ..... 29**

**4.5 Transmit Status ..... 30**

**4.6 Transmit ..... 31**

**4.7 Cancel ..... 32**

**4.8 Receive ..... 33**

**5. CABLE PHY PACKET ..... 34**

**5.1 Self\_ID Packet ..... 34**

**5.2 Link-on Packet ..... 35**

**5.3 PHY Configuration Packet ..... 35**

**5.4 Extended PHY Packet ..... 35**

5.4.1 Ping Packet ..... 36

5.4.2 Remote Access Packet ..... 36

5.4.3 Remote Reply Packet ..... 37

5.4.4 Remote Command Packet ..... 37

5.4.5 Remote Confirmation Packet ..... 38

5.4.6 Resume Packet ..... 38

**6. ELECTRICAL SPECIFICATIONS ..... 39**

**7. APPLICATION CIRCUIT EXAMPLE ..... 44**

**8. PACKAGE DRAWING ..... 45**

**9. RECOMMENDED SOLDERING CONDITIONS ..... 46**

EOL Product



## 1. PIN FUNCTIONS

### 1.1 Cable Interface Pins

Name	Pin No.	I/O	Function
TpA0p	39	I/O	Port 0 twisted pair cable A positive phase I/O
TpA0n	38	I/O	Port 0 twisted pair cable A negative phase I/O
TpB0p	37	I/O	Port 0 twisted pair cable B positive phase I/O
TpB0n	36	I/O	Port 0 twisted pair cable B negative phase I/O
TpA1p	46	I/O	Port 1 twisted pair cable A positive phase I/O
TpA1n	45	I/O	Port 1 twisted pair cable A negative phase I/O
TpB1p	44	I/O	Port 1 twisted pair cable B positive phase I/O
TpB1n	43	I/O	Port 1 twisted pair cable B negative phase I/O
SUS/RES	19	I	Suspend/Resume function select 1: Suspend/Resume on (IEEE1394a-2000 compliant) 0: Suspend/Resume off (P1394a draft 1.3 compliant)
CPS	32	I	Cable power status Connect to the cable through a 390 kΩ resistor and to GND through a 100 kΩ resistor. 0: Cable power fail 1: Cable power on

### 1.2 Link Interface Pins

Name	Pin No.	I/O	Function
D0	8	I/O	Data input/output (bit 0)
D1	9	I/O	Data input/output (bit 1)
D2	11	I/O	Data input/output (bit 2)
D3	12	I/O	Data input/output (bit 3)
D4	14	I/O	Data input/output (bit 4)
D5	15	I/O	Data input/output (bit 5)
D6	17	I/O	Data input/output (bit 6)
D7	18	I/O	Data input/output (bit 7)
CTL0	5	I/O	Link interface control (bit 0)
CTL1	6	I/O	Link interface control (bit 1)
LREQ	63	I	Link request input
SCLK	2	O	Link control output clock LPS 1: 49.152 MHz output LPS 0: Clamp to 0 (The clock signal will be output within 25 μsec after change to "0")
LPS	59	I	Link power status input 0: Link power off 1: Link power on (PHY/Link direct connection)
LKON	58	O	Link-on signal output Link-on signal is 6.144 MHz clock output. Please refer to 4.2 Link-on Indication.
DIRECT	50	I	PHY/Link isolation barrier control input 0: Isolation barrier 1: PHY/Link direct connection

**1.3 Control Pins**

Name	Pin No.	I/O	Function
PC0	26	I	Power class set input
PC1	27	I	This pin status will be loaded to Pwr_class bit which allocated to PHY register 4H. IEEE1394a-2000 chapter [4.3.4.1]
PC2	28	I	
CMC	30	I	Configuration manager capable setting This pin status will be loaded to Contender bit which allocated to PHY register 4H. 0: Non contender 1: Contender
RESETB	55	I	Power-on reset input Connect to GND through a 0.1 μF capacitor. 0: Reset 1: Normal
FNSel	62	I	Function Select 0: #61 acts as SPD 1: #61 acts as BDB
SPD	61	I	Speed select ( When FNSel set to 0 ; μPD72852A compliant) 0: MAX. S200 1: MAX. S400
BDB	61	O	BIAS Detected (Logical Inverse) 0: BIAS is detected after suspend debounce timer. 1: BIAS is not detected.

**1.4 IC**

Name	Pin No.	I/O	Function
IC(AL)	29, 51	-	Internally Connected (Low Clamped) Connect to GND.
IC(DL)	3	-	Internally Connected (Low Clamped) Connect to GND.

**1.5 Power Supply Pins**

Name	Pin No.	I/O	Function
AV <sub>DD</sub>	25, 31, 40, 47, 54	-	Analog power
AGND	24, 33, 35, 42, 49, 52, 53	-	Analog GND
DV <sub>DD</sub>	4, 10, 20, 56, 60	-	Digital V <sub>DD</sub>
DGND	1, 7, 13, 16, 21, 57, 64	-	Digital GND

## 1.6 Other Pins

Name	Pin No.	I/O	Function
TpBias0	41	O	Port 0 twisted pair output
TpBias1	48	O	Port 1 twisted pair output
RI1	34	-	Resistor connection pin1 for reference current generator Connect to GND through a 9.1 k $\Omega$ resistor.
XI	23	-	Crystal oscillator connection XI
XO	22	-	Crystal oscillator connection XO

EOL Product

2. PHY REGISTERS

2.1 Complete Structure for PHY Registers

Figure 2-1. Complete Structure of PHY Registers

	0	1	2	3	4	5	6	7
0000	Physical_ID						R	PS
0001	RHB	IBR	Gap_count					
0010	Extended (7)			Reserved	Total_ports			
0011	Max_speed			Reserved	Delay			
0100	Link_active	Contender	Jitter			Pwr_class		
0101	Watchdog	ISBR	Loop	Pwr_fail	Timeout	Port_event	Enab_accel	Enab_multi
0110	Reserved							
0111	Page_select			Reserved	Port_select			
1000	Register0 (page_select)							
1001	Register1 (page_select)							
1010	Register2 (page_select)							
1011	Register3 (page_select)							
1100	Register4 (page_select)							
1101	Register5 (page_select)							
1110	Register6 (page_select)							
1111	Register7 (page_select)							

Table 2-1. Bit Field Description (1/3)

Field	Size	R/W	Reset value	Description
Physical_ID	6	R	000000	Physical_ID value selected from Self_ID period.
R	1	R	0	If this bit is 1, the node is root. 1: Root 0: Not root
PS	1	R		Cable power status. 1: Cable power on 0: Cable power off
RHB	1	R/W	0	Root Hold -off bit. If 1, becomes root at the bus reset.
IBR	1	R/W	0	Initiate bus reset. Setting to 1 begins a long bus reset. Long bus reset signal duration: 166 μsec. Returns to 0 at the beginning of bus reset.
Gap_count	6	R/W	111111	Gap count value. It is updated by the changes of transmitting and receiving the PHY configuration packet Tx/Rx. The value is maintained after first bus reset. After the second bus reset it returns to reset value.
Extended	3	R	111	Shows the extended register map.

Table 2-1. Bit Field Description (2/3)

Field	Size	R/W	Reset value	Description
Total_ports	4	R	0010	Supported port number. 0010: 2 ports
Max_speed	3	R	See Description	Indicate the maximum speed that this node supports. Set variable by SPD pin (61 pin). When SPD = "0" then 001: 98.304 and 196.608 Mbps. When SPD = "1" then 010: 98.304, 196.608 and 393.216 Mbps.
Delay	4	R	0000	Indicate worst case repeating delay time. $144 + (\text{Delay} \times 20) = 144 \text{ nsec}$
Link_active	1	R/W	1	Link active. 1: Enable 0: Disable The logical AND status of this bit and LPS pin. State will be referred to "L bit" of Self-ID Packet#0.
Contender	1	R/W	See Description	Contender. "1" indicate this node support bus manager function. This bit will be referred to "C bit" of Self-ID Packet#0. The reset data is depending on CMC pin setting. CMC pin condition 1: Pull up (Contender) 0: Pull down (Non Contender)
Jitter	3	R	010	The difference of repeating time (Max.-Min.). $(2+1) \times 20 = 60 \text{ nsec}$
Pwr_class	3	R/W	See Description	Power class. Please refer to IEEE1394a-2000 [4.3.4.1]. This bit will be referred to Pwr field of Self-ID Packet#0. The reset data will be determined by PC0-PC2 Pin status.
Watchdog	1	R/W	0	Watchdog Enable. This bit serves two purposes. When set to 1, if any one port does resume, the Port_event bit becomes 1. This function has no effect when SUS/RES (19 pin) = "0". To determine whether or not an interrupt condition shall be indicated to the Link. On condition of LPS = 0 and Watchdog = 0, LKON as interrupt of Loop, Pwr_fail, Timeout is not output. This function has effect both when SUS/RES (19 pin) = "1" or "0".
ISBR	1	R/W	0	Initiate short (arbitrated) bus reset. Setting to 1 acquires the bus and begins short bus reset. Short bus reset signal output : 1.3 μsec Returns to 0 at the beginning of the bus reset.
Loop	1	R/W	0	Loop detection output. 1: Detection Writing 1 to this bit clears it to 0. Writing 0 has no effect.
Pwr_fail	1	R/W	1	Power cable disconnect detect. It becomes 1 when there is a change from 1 to 0 in the CPS bit. Writing 1 to this bit clears it to 0. Writing 0 has no effect.

Table 2-1. Bit Field Description (3/3)

Field	Size	R/W	Reset value	Description
Timeout	1	R/W	0	Arbitration state machine time-out. Writing 1 to this bit clears it to 0. Writing 0 has no effect.
Port_event	1	R/W	0	Set to 1 when the Int_enable bit in the register map of each port is 1 and there is a change in the ports connected, Bias, Disabled and Fault bits. Set to 1 when the Watchdog bit is 1 and any one port does resume. Writing 1 to this bit clears it to 0. Writing 0 has no effect. This bit is not settable when SUS/RES (19 pin) = "0".
Enab_accel	1	R/W	0	Enables arbitration acceleration. Ack-acceleration and Fly-by arbitration are enabled. 1: Enabled 0: Disabled If this bit changes while the bus request is pending, the operation is not guaranteed.
Enab_multi	1	R/W	0	Enable multi-speed packet concatenation. Setting this bit to 1 follows multi-speed transmission. When this bit is set to 0, the packet will be transmitted with the same speed as the first packet.
Page_select	3	R/W	000	Select page address between 1000 to 1111. 000: Port Status Page 001: Vendor ID Page 111: Vendor Dependent Page Others: Unused
Port_select	4	R/W	0000	Port Selection. Selecting 000 (Port Status Page) with the Page_select selects the port. Selecting 111 (Vendor Dependent Page) with the Page_select have to select the Port 1. 0000: Port 0 0001: Port 1 Others: Unused
Reserved	-	R	000...	Reserved. Read as 0.

2.2 Port Status Page (Page 000)

Figure 2-2. Port Status Page

	0	1	2	3	4	5	6	7
1000	AStat		BStat		Child	Connected	Bias	Disabled
1001	Negotiated_speed			Int_enable	Fault	Reserved		
1010	Reserved							
1011	Reserved							
1100	Reserved							
1101	Reserved							
1110	Reserved							
1111	Reserved							

Table 2-2. Bit Field Description

Field	Size	R/W	Reset value	Description
AStat	2	R	XX	A port status value. 00: invalid, 10: "0" 01: "1", 11: "Z"
BStat	2	R	XX	B port status value. 00: invalid, 10: "0" 01: "1", 11: "Z"
Child	1	R		Child node status value. 1: Connected to child node 0: Connected to parent node
Connected	1	R	0	Connection status value. 1: Connected 0: Disconnected
Bias	1	R		Bias voltage status value. 1: Bias voltage 0: No bias voltage
Disabled	1	R/W	See Description	The reset value is set to 0: Enabled.
Negotiated_speed	3	R		Shows the maximum data transfer rate of the node connected to this port. 000: 100 Mbps 001: 200 Mbps 010: 400 Mbps
Int_enable	1	R/W	0	When set to 1, the Port_event is set to 1 if any of this port's Connected, Bias, Disabled or Fault bits change state. This bit has no effect when SUS/RES (19 pin) = "0".
Fault	1	R/W	0	Set to 1 if an error occurs during Suspend/Resume. Writing 1 to this bit clears it to 0. Writing 0 has no effect. This bit has no effect when SUS/RES (19 pin) = "0"
Reserved	-	R	000...	Reserved. Read as 0.

2.3 Vendor ID Page (Page 001)

Figure 2-3. Vendor ID Page

	0	1	2	3	4	5	6	7
1000	Compliance_level							
1001	Reserved							
1010	Vendor_ID							
1011	Vendor_ID							
1100	Vendor_ID							
1101	Product_ID							
1110	Product_ID							
1111	Product_ID							

Table 2-3. Bit Field Description

Field	Size	R/W	Reset value	Description
Compliance_level	8	R	00000001	According to IEEE1394a-2000.
Vendor_ID	24	R	00004CH	Company ID Code value, NEC IEEE OUI.
Product_ID	24	R		Product code.
Reserved	-	R	000...	Reserved. Read as 0.

2.4 Vendor Dependent Page (Page 111 : Port\_select 0000)

Figure 2-4. Vendor Dependent Page

	0	1	2	3	4	5	6	7
1000	Reserved							
1001	Reserved			Long Debounce			Reserved	
1010	Reserved							
1011	Reserved							
1100						W_SPD_ DIS		
1101	Reserved							
1110	Reserved							
1111	Reserved							

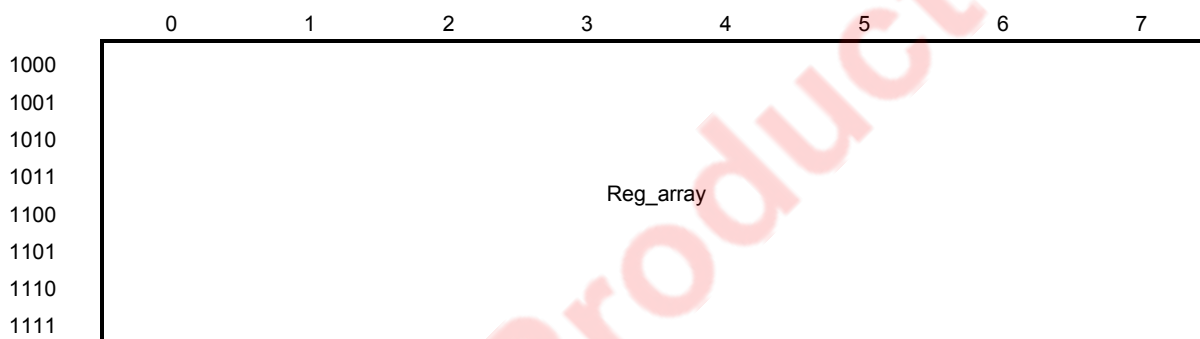


**Table 2-4. Bit Field Description**

Field	Size	R/W	Reset value	Description
Long Debounce	2	R/W	00b	00: suspend debounce timer sets to 420 ns 11: suspend debounce timer sets to 1000 ns.
W_SPD_DIS	1	R/W	0	0: NOT Receive Double speed signal Only First speed signal will be repeated for next port and packet will be decoded by highest speed within received. 1: Receive Double speed signal (IEEE1394a-2000 compliant). Second speed signal will be applied for repeating /decoding.

**2.5 Vendor Dependent Page (Page 111 : Port\_select 0001)**

**Figure 2-5. Vendor Dependent Page contd.**



**Table 2-5. Bit Field Description**

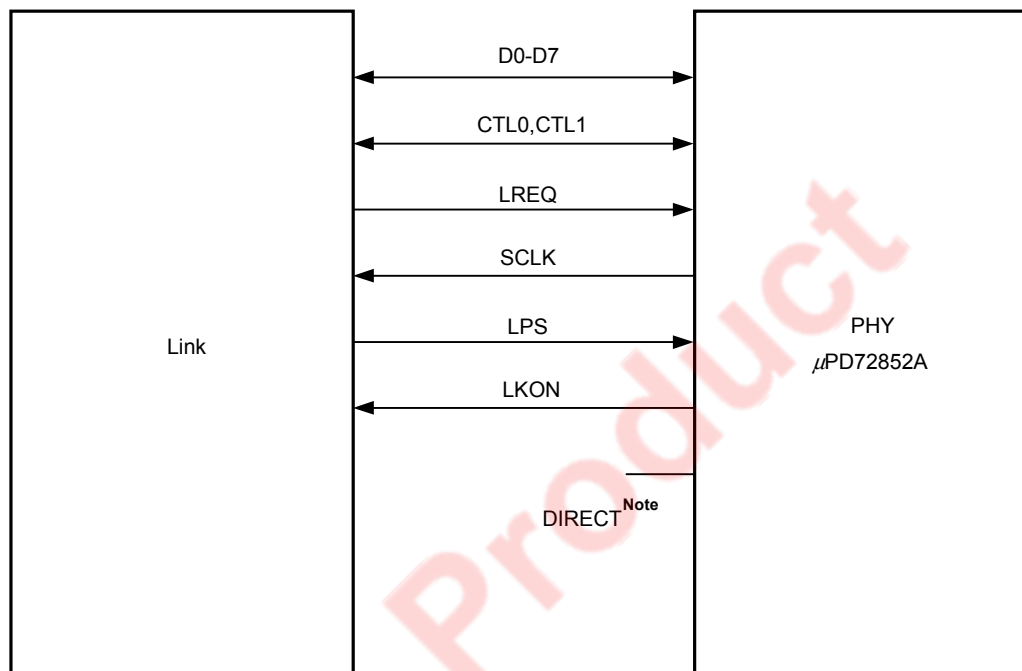
Field	Size	R/W	Reset value	Description
Reg_array	64	R/W	0	This register array is possible R/W.

### 3. INTERNAL FUNCTION

#### 3.1 Link Interface

##### 3.1.1 Connection Method

Figure 3-1. PHY/Link Connection Method



**Note** Clamping to  $V_{DD}$  provides direct connection to Link.  
 Clamping to **GND** connects through isolation barrier to Link.  
 The isolation barrier connection circuit is described in **3.1.7 Isolation Barrier**.

##### 3.1.2 LPS (Link Power Status)

LPS is a function to monitor the On/Off status of the Link power supply. After 1.2 μsec or more, LPS is Low, the PHY/Link is reset and D and CTL are output Low (when the isolation barrier is Hi-Z). After 2.5 μsec or more, LPS is Low, moreover, the PHY stops the supply of SCLK and SCLK outputs Low (when the isolation barrier is Hi-Z).

##### 3.1.3 LREQ, CTL0, CTL1 and D0-D7 Pins

- LREQ : Indicates that a request is received from Link.
- CTL0, CTL1 : Bi-directional pin which controls the functions between the PHY/Link interface.
- D0-D7 : Bi-directional pin which controls the data Transfer/Receive status signal, and the speed code Transfer/Receive status signal.

##### 3.1.4 SCLK

49.152 MHz clock supplied by PHY for the PHY/Link interface synchronization.

### 3.1.5 LKON

When the Link power is off, it outputs a clock of 6.144 MHz. LKON outputs under the following conditions: LPS is Low and the internal PHY register of the Link\_active bit is 0.

- Link-on packet is received.
- Any bit of Loop, Pwr\_fail, Timeout or Port\_event is the PHY internal register becomes 1, and moreover either LPS or Link\_active bit is 0.

When LPS is asserted, LKON returns to Low.

### 3.1.6 DIRECT

Set DIRECT to Low for using the isolation barrier.

### 3.1.7 Isolation Barrier

The IEEE1394 cable holds signals for Data/Strobe in addition to power and ground.

When the ground potential is different between connecting devices, the DC and AC current flows through the ground line in the cable and there is a possibility of malfunction due to ground difference between the two PHY.

The μPD72852A uses the isolation barrier to couple the AC between the PHY/Link interface to overcome the ground difference problem. Connecting the DIRECT pin to Low enables the digital differential circuit of the μPD72852A. The differential circuit propagates only the change in the signal; the interface will be driven only during transitions High → Low or Low → High. The interface will assume the high impedance state when there is no signal change. The μPD72852A uses Schmitt trigger input buffers for D, CTL, LREQ and LPS pins to prevent noise when the bus assumes a high impedance state.

The digital differential circuit and the Schmitt trigger input buffers are needed on the Link layer controller LSI to implement the isolation barrier.

Figure 3-2. Waveforms of the Isolation Barrier

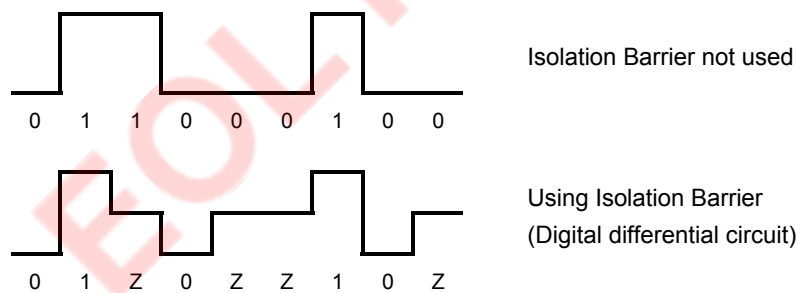
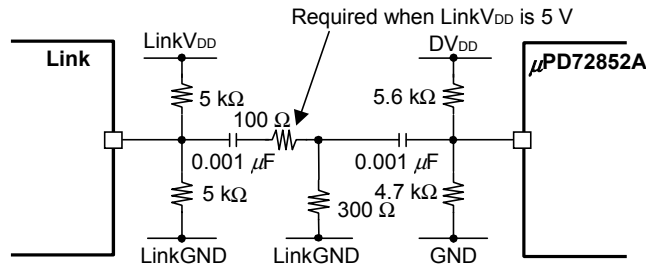
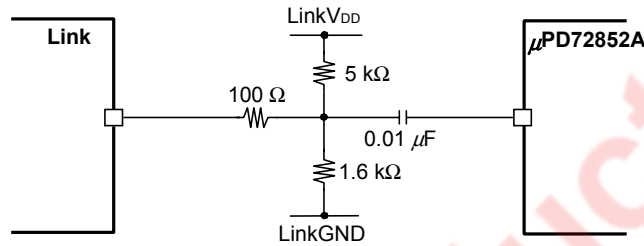


Figure 3-3. Isolation Barrier Circuits

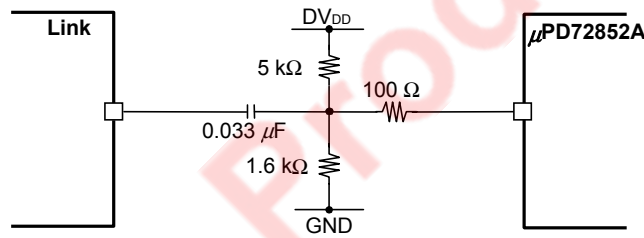
(a) CTL0, CTL1, D0-Dn Isolation Barrier Circuit



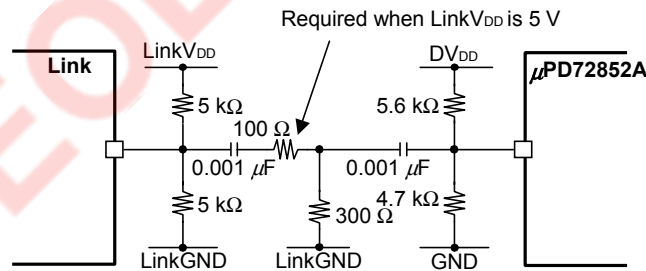
(b) Link-on Isolation Barrier Circuit



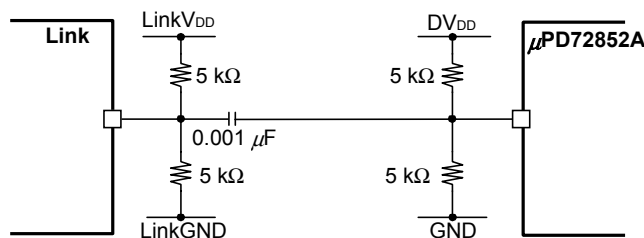
(c) LPS Isolation Barrier Circuit



(d) LREQ Isolation Barrier Circuit



(e) SCLK Isolation Barrier Circuit

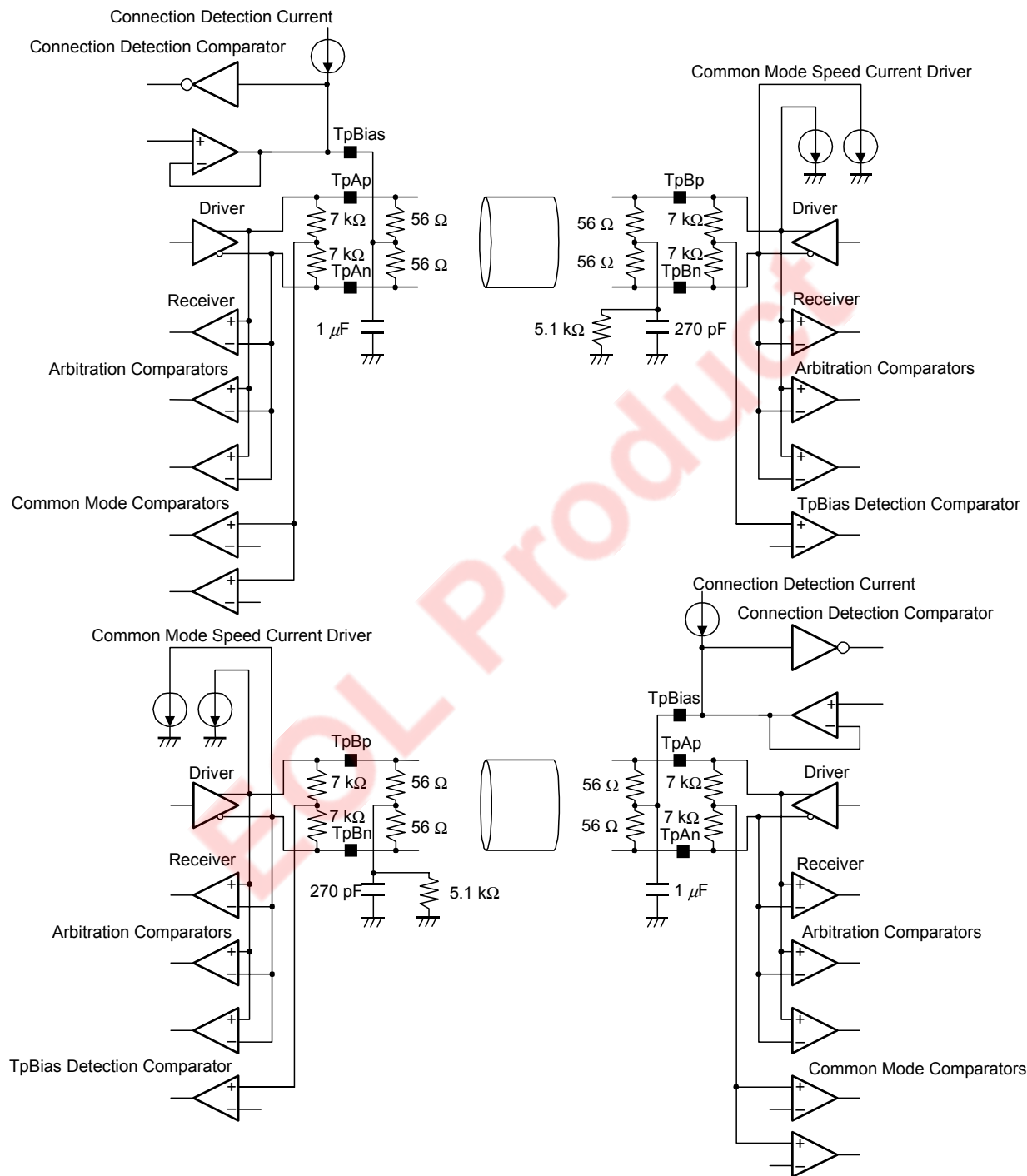


The Operating range of the power supply voltage is between 3.0 V and 3.45 V. Please refer to **IEEE1394a-2000 [5A.8.4]**.

### 3.2 Cable Interface

#### 3.2.1 Connections

Figure 3-4. Cable Interface



### 3.2.2 Cable Interface Circuit

Each port is configured with two twisted-pairs of TpA and TpB.

TpA and TpB are used to monitor the state of the Transmit/Receive line, control signals, data and cables.

During transmission to the IEEE1394 bus, the Data/Strobe signal received from the Link layer controller is encoded, converted from parallel to serial and transmitted.

While receiving from the IEEE1394 bus, the Data/Strobe signal from TpA, TpB is converted from serial to parallel after synchronization by SCLK, then transmitted to the Link layer controller in 2/4/8 bits according to the data rate of 100/200/400 Mbps.

The bus arbitration for TpA and TpB and the state of the line are monitored by the built-in comparator. The state of the IEEE1394 bus is transmitted to the state machine in the LSI.

### 3.2.3 Unused Ports

TpAp, TpAn : Not connected

TpBp, TpBn : GND

TpBias : Not connected

### 3.2.4 CPS

Connect an external resistor of 390 kΩ between the CPS pin and the power cable, and an external resistor of 100 kΩ between the CPS pin and GND to monitor the power of the power cable.

If the cable power falls under 7.5 V there is an indication to the Link layer controller that the power has failed.

## 3.3 Suspend/Resume

### 3.3.1 Suspend/Resume On Mode (SUS/RES = "H")

There are two ways of transition from the active status to the suspended status.

One is when the receipt of a remote command packet that sets the initiate suspend command. After that, the PHY transmits a remote confirmation packet with the ok bit set, subsequently signals TX\_SUSPEND to the connected peer PHY with the port which specified by the port field in the remote command packet, and then the PHY port transitions to the suspended state.

The other is when the receipt of a RX\_SUSPEND or RX\_DISABLE\_NOTIFY signal. When the port observes RX\_SUSPEND, it transmits TX\_SUSPEND to the active ports.

The TX\_SUSPEND transmitted propagates until it reaches a leaf node. The PHY port transitions to the suspended state. The propagation of the suspended domain may be blocked by a PHY compliant with IEEE1394a-2000, a disabled or a suspended port.

Any one of a number of reasons may cause a suspended port to attempt to resume normal operations:

- Bias is detected and there is no fault condition;
- A resume packet is received or transmitted by the PHY;
- A remote command packet that sets the resume port command is received; or
- Either port of a node without active ports detects bias.

### 3.3.2 Suspend/Resume Off Mode (SUS/RES = "L")

- Remote command packet is ignored.
- Resume packet is ignored.
- Disabled, Int\_enable and resume\_int bits in PHY register are ignored.
- Responses to Remote access packet.
- Detects the connection of the port in TpBias.
- Output the 1.85 V voltage of the port in TpBias.

### 3.4 PLL and Crystal Oscillation Circuit

#### 3.4.1 Crystal Oscillation Circuit

To supply the clock of 24.576 MHz  $\pm$  100 ppm, use an external capacitor of 10 pF and a crystal of 50 ppm.

#### 3.4.2 PLL

The crystal oscillator multiplies the 24.576 MHz frequency by 16 (393.216 MHz).

### 3.5 CMC

CMC shows the bus manager function which corresponds to the c bit of the Self\_ID packet and the Contender bit in the PHY register when the input is High.

The value of CMC can be changed with software through the Link layer; this pin sets the initial value during Power-on Reset. Use a pull-up or pull-down resistor of 10 k $\Omega$ , based on the device's specification.

### 3.6 PC0-PC2

The PC0-PC2 pin corresponds to the power field of the Self\_ID packet and Pwr\_class in the PHY register. Refer to Section 4.3.4.1 of the IEEE1394a-2000 specification for information regarding the Pwr\_class. The value of Pwr can be changed with software through the Link layer controller; this pin sets the initial value during Power-on Reset. Use a pull-up or pull-down resistor of 10 k $\Omega$  based on the application.

### 3.7 RESETB

Connect an external capacitor of 0.1  $\mu$ F between the RESETB pin and GND. If the voltage drops below 0 V, a reset pulse is generated. All of the circuits are initialized, including the contents of the PHY register.

### 3.8 RI1

Connect an external resistor of 9.1 k $\Omega$  between the RI1 pin and GND to limit the LSI's current.

## 4. PHY/LINK INTERFACE

### 4.1 Initialization of Link Power Status (LPS) and PHY/Link Interface

The LPS pin monitors the On/Off status of the Link power state. This pin is used during the PHY/Link interface Enable/Disable (initialization).

#### Reset

When the LPS input pin is Low for TLPS\_RESET:

- CTL0, CTL1 and D0-D7 output Low (When the isolation barrier is Hi-Z).
- SCLK continuously supplies the clock signal to the Link.

#### Disable

When the LPS input pin is Low for TLPS\_DISABLE:

- CTL0, CTL1, D0-D7 continue to output Low as TLPS\_RESET has already occurred (When the isolation barrier is Hi-Z).
- SCLK to Link stops and it outputs Low (When the isolation barrier is Hi-Z).

Table 4-1. LPS Timing Parameters

Parameter	Symbol	MIN.	MAX.	Unit
LPS = Low propagation delay (with isolation barrier)	t <sub>LPSL</sub>	0.09	1.00	μs
LPS = High propagation delay (with isolation barrier)	t <sub>LPSH</sub>	0.09	1.00	μs
Reset active	t <sub>LPS_RESET</sub>	1.2	2.75	μs
Disable active	t <sub>LPS_DISABLE</sub>	25	30	μs
Setup time when using isolation barrier	t <sub>RESTORE</sub>	15	20	μs

Figure 4-1. LPS Waveform when Connected to Isolation Barrier

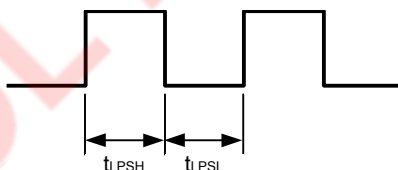
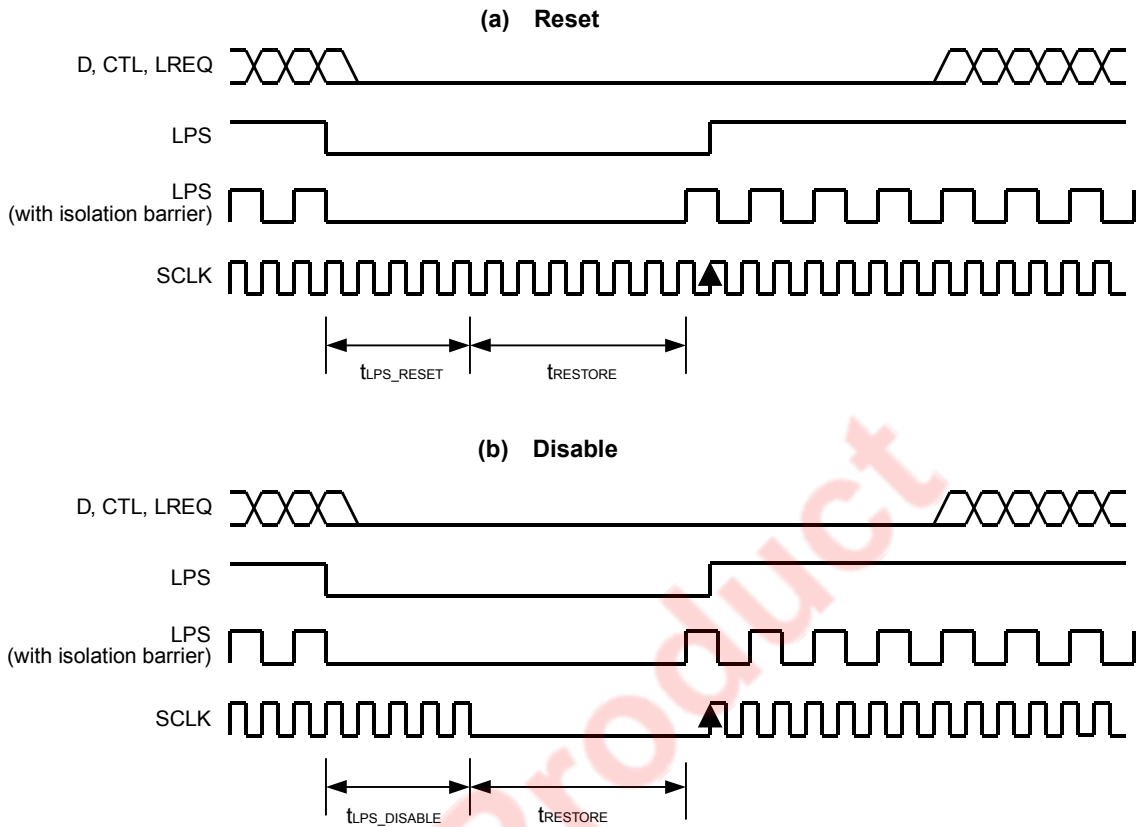




Figure 4-2. PHY/Link Interface Reset and Disable



4.2 Link-on Indication

When the power supply of Link is off (LPS is Low and the internal PHY register Link\_active bit is 0), the pin LKON outputs a clock of 6.144 MHz according to the following conditions:

- Link-on packet is received.
- When any bit of the μPD72852A PHY register's loop, Pwr\_fail, Timeout or Port\_event becomes 1, and either LPS or the Link\_active bit is 0.

Table 4-2. Link-on Timing

Parameter	MIN.	MAX.	Unit
Frequency	4	8	MHz
Duty Cycle	40	60	%
Propagation delay before the Link becomes active (LPS is asserted and the Link_active bit in the PHY register is 1).		500	ns

- If LPS or the Link\_active bit is 0, the Link is considered inactive. When the Link is inactive and any of Loop, Pwr\_fail, Timeout, Port\_event becomes 1, then Link-on is asserted High.
- When the Link is active (both LPS and Link\_active become 1) and Loop, Pwr\_fail, Timeout and Port\_event become 1, Status transfer is sent on the PHY/Link interface.
- The μPD72852A activates the PHY/Link interface when LPS is 1, regardless of the value of the Link active bit.

**4.3 PHY/Link Interface Operation (CTL0, CTL1, LREQ, D0-D7)**

The PHY/Link Interface consists of the following operations:

- Status transfer to the Link layer controller by CTL
- Transmit packet
- Receive packet
- Request from the Link layer controller by LREQ

**4.3.1 CTL0, CTL1**

CTL0, CTL1 controls the PHY/Link interface as shown in the Table 4-3.

**Table 4-3. CTL Controls PHY**

CTL0,CTL1	Type	Content
00	Idle	PHY is in idle function
01	Status	PHY transmitting status information to Link
10	Receive	PHY receiving data from the Link
11	Grant	PHY allows Link to transmit data

This is the operation by which, after Grant, the Link obtains the right to control the interface.

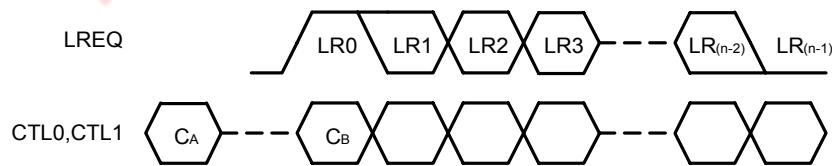
**Table 4-4. CTL Controls Link**

CTL0,CTL1	Type	Content
00	Idle	Link completes the packet transmission and releases the PHY/Link interface.
01	Hold	1) Link transmits Hold until the data is ready for transmission. 2) Link transmits the interface connect packet.
10	Transmit	Link transmits the data to PHY.
11	-	Not used.

**4.3.2 LREQ**

Access to the PHY register and the bus is controlled from the Link layer controller through the LREQ pin of PHY.

**Figure 4-3. LREQ and CTL Timing**



CA : CTL before generation of LREQ  
 CB : CTL during LREQ execution

(1) LREQ format

• Bus Request

**Table 4-5. Bus Request Format**

Bit	Type	Content
0	start	Signal that starts a request : 1
1-3	request	Bus request type: 000: ImmReq acknowledge packet transmit 001: IsoReq isochronous packet transmit 010: PriReq cycle start packet transmit 011: FairReq asynchronous packet transmit
4-6	speed	Transmit speed: 000: 100 Mbps 010: 200 Mbps 100: 400 Mbps other: reserved
7	stop	End request signal : 0 (optional)

• PHY Register Read Request

**Table 4-6. Read Request Register Format**

Bit	Type	Content
0	start	Signal that starts a request : 1
1-3	request	Read Request. 100 : ReadReq
4-7	access address	PHY register address.
8	stop	End request signal : 0

• PHY Register Write Request

**Table 4-7. Write Request Register Format**

Bit	Type	Content
0	start	Signal that starts a request : 1
1-3	request	Write Request. 101 : WriteReq
4-7	access address	PHY register address.
8-15	write data	Write data.
16	stop	End request signal : 0

• Acceleration Controller

**Table 4-8. Acceleration Controller Request Format**

Bit	Type	Content
0	start	Signal that starts a request : 1
1-3	request	110 : Acc Ctrl accelerate controller
4	access address	0: Accelerate disable 1: Accelerate enable
5	stop	End request signal : 0

**Table 4-9. Request Type List**

Bit	Type	Content
000	ImmReq	Used to acknowledge packet transmit. When Idle is detected, PHY immediately controls the bus.
001	IsoReq	Used to transmit isochronous packet. PHY does arbitration after isochronous gap is detected and acquires the bus.
010	PriReq	Used for Cycle master request.
011	FairReq	Fair request.
100	RdReg	PHY register read request.
101	WrReg	PHY register write request.
110	AccCtrl	Disable/enable of arbitration acceleration.
111	-	Unused.

For the Link to execute Priority request and Fair, start the request using LREQ when CTL0, CTL1 becomes idle, after one clock. When request is acknowledged, the μPD72852A outputs Grant to CTL0, CTL1.

The Link of cycle master uses PriReq to transmit the cycle start packet. IsoReq transmits the isochronous packet.

IsoReq becomes effective only as follows:

- The transmission of the cycle start packet is performed on the same isochronous period as Receive. (The period until the subaction gap is detected.)
- During isochronous packet Transmit or Receive.

The μPD72852A cancels IsoReq with the subaction gap detection or bus reset. To meet the timing, do not issue the IsoReq to PHY when CRC operation is performed.

The Link cancel method is described later.

After the packet is received, Link issues ImmReq as the acknowledge packet transmission. The purpose is to prevent another node from detecting subaction gap as ACK\_RESPONSE\_TIME. The μPD72852A acquires the bus after packet receive and returns Grant to CTL0, CTL1. When CRC fails, before Link detects Grant, assert 3 Idle cycles to CTL0, CTL1.

When the bus reset is generated, the unprocessed requests are canceled.

The μPD72852A updates the data of the Write request register and the contents of the Read register are changed. The contents of the register of the specified address are output to the Link as a status transfer in the Read request register, When the status transmission is interrupted by transmitting/receiving packets, the status transmission will re-start from the first bit after completing the transmit/receive of the packets.

The bus request (ImmReq, IsoReq, PriReq, FairReq) is completed (in case of ImmReq, IsoReq, when the subaction gap is detected) when the packet is transmitted or canceled by canceling the bus request.

**(2) LREQ rules**

The Link request and the status of the serial bus are asynchronous; the bus request can be canceled by the status of the serial bus.

The following rules apply to a request by LREQ:

- Link cannot issue a bus request (ImmReq, IsoReq, PriReq, FairReq) if Grant is given to an LREQ request or until the Link's request is canceled. The request can be canceled by the μPD72852A if it detects subaction gap at ImmReq, IsoReq.
- Do not issue a RdReg or WrReg request when the status transmission is not completed by the Read request register.
- All of the bus requests (ImmReq, IsoReq, PriReq, FairReq) are canceled by a bus reset.

In addition, there is a limitation in the request of LREQ according to the state of CTL as shown in Table 4-10.

**Table 4-10. Rules for Other Requests**

Request	State of CTL in Ca to which LREQ is allowed when PHY drives CTL	LREQ issues permission when Link drives CTL	Note
Fair, Priority	Idle, Status	wrong	Fair, Priority request cannot be issued until the unprocessed bus request is completed.
Immediate	Receive, Idle	wrong	Link issues the request after completing the decoding of Destination_ID, when the acknowledge packet is ready. After the packet is received, it is necessary to transmit the first bit of the request within four cycles.
Isochronous	any	correct	If the isochronous packet transmission is prepared for the isochronous period, it is issued. Do not issue the request to transmit the isochronous packet appending to the currently transmitted isochronous packet (Using Hold).
Register Read Register Write	any	correct	Do not issue this request if the unprocessed Read request has not been completed.
AccCtrl	any	correct	To set acceleration bit 0: When the isochronous period starts, if the Enab_accel bit is one, Cycle slave should adjust accelerate bit to 0.  To set acceleration bit 1: Do not set the cycle master. It is issued when the isochronous period ends.

**Table 4-11. PHY Operation Before LREQ Request to the CTL Function Changes**

Request	State of CTL in CB after LREQ was issued	Operation of the PHY
Fair, Priority	Receive	<ul style="list-style-type: none"> <li>Hold the request if the acceleration of arbitration packet transmitted with enable is 8 bits (ACK). Except for 8 bits, the requests are ignored.</li> <li>Ignore the request when the acceleration of arbitration is disabled.</li> </ul>
	Grant	Arbitration Won.
	Idle, Status	Excluding when the bus reset is generated, Hold the requests.
Immediate	Grant	
	Receive	The packet is being transmitted to Link. Request Hold.
	Idle, Status	Excluding when the bus reset is generated, hold the request.
Isochronous	Transmit Idle (driven by Link)	Request Hold.
	Grant	Arbitration Won.
	Receive	Request Hold.
	Status	Request is ignored when sub-action gap is detected.
	Idle	
Register Read	Any (driven by Link)	
	Grant	Request Hold.
	Receive	Request Hold.
	Status	Hold the request until the corresponding register value is returned.
	Idle	
Register Write, Acceleration control	Any	Request is completed.

**4.3.3 SCLK Timing**

**Table 4-12. SCLK Timing**

Timing Constant	Comment	MIN.	MAX.	Unit
BUS_TO_LINK_DELAY	Period from receiving RX_DATA_PREFIX until Receive to CTL is output.	2	9	SCLK cycle
DATA_PREFIX_TO_GRANT	Period when the Grant is output to CTL after TX_DATA_PREFIX is output to a port.		25	SCLK cycle
LINK_TO_BUS_DELAY	Period when TX_DATA_END is output to all ports after transmitting the packet by Link after idle was asserted to CTL.	2	5	SCLK cycle
MAX_HOLD	Maximum period when Hold can be asserted by Link to confirm Grant.		47	SCLK cycle

#### 4.4 Acceleration Control

Enable of ack-acceleration and fly-by on the same isochronous period may create a problem. The isochronous cycle may extend unintentionally when transmitting the asynchronous packet by a node using ack-acceleration and fly-by.

To avoid this problem, Link should control Disable/Enable of these enhancements (ack-Acceleration, fly-by), by Acceleration Control requests. Cycle master cannot issue the Acceleration Control request.

The enhancements should not be used from the generation of the local cycle synchronization event to the confirmation of cycle start. In this period, all Links except for Cycle Master use Acceleration Control as follows:

- Do not issue Fair nor Priority request to Link after generating local cycle synchronization, if the Acceleration Control request's Accelerate bit is not set to 0.
- Link must not use Hold when transmitting continuous primary asynchronous packet after the Acknowledge packet, except after ack\_pending to complete the split transaction.
- Ending the Link during the isochronous period issues the acceleration control request to set the Accelerate bit to 1, enabling these enhancements.

The μPD72852A does not require setting the Acceleration Control during isochronous transmit to enable the isochronous request fly-by acceleration.

It is not necessary to issue Acceleration Control request when the cycle master is absent from the serial bus. These enhancements are enabled if the Enab\_accel bit in the PHY register is set. The μPD72852A supports Variable Acceleration controlled by the Acceleration Control during power-on reset.

### 4.5 Transmit Status

Pin D0, D1 of the μPD72852A transmits status information to the Link. Status is asserted to CTL while transmitting Status. The status transmission is interrupted if the serial bus receives a packet which contains states other than status to CTL. Between two status transmissions, assert Idle to CTL for at least one SCLK cycle.

The μPD72852A transmits status in 16 bits as follows:

- In response to the register request
- After deciding the new Physical\_ID for the Self\_ID period resetting the bus (after a Self\_ID packet is transmitted)

The event indication is the only 4-bit transmission of the μPD72852A.

Figure 4-4. Status Timing

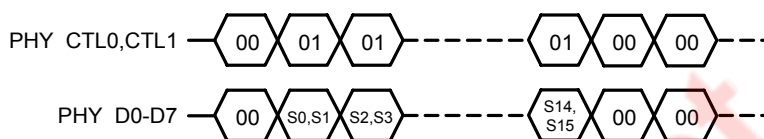


Table 4-13. Status Data Format

Bit(s)	Name	Description
0	ARB_RESET_GAP	Arbitration Reset gap detect
1	SUBACTION_GAP	Subaction gap detect
2	BUS_RESET_START	Bus reset detect
3	Phy_interrupt	Either of the following states is detected: <ul style="list-style-type: none"> <li>• The topology of the bus is a loop</li> <li>• Voltage drop on the power cable</li> <li>• Arbitration state machine timeout</li> <li>• Port Event</li> </ul>
4-7	Address	PHY register address
8-15	Data	Register data

The bits already transmitted are set to 0.

**Example** If the status transmission is interrupted after S0, S1 bit was transmitted, then in the next status transfer, S0, S1 becomes 0.

Therefore one of the following situations will occur when the μPD72852A re-transmits status after an interruption of the status transmission:

- At least one bit of S0-S3 is 1
- The PHY register data contains the interrupt status information

The status transmission always begins with S0, S1.

If the Link executes read request, and Subaction gap and arbitration reset gap are detected, priority is given to the transmission of gap status, postponing the response to the register read request.



### 4.6 Transmit

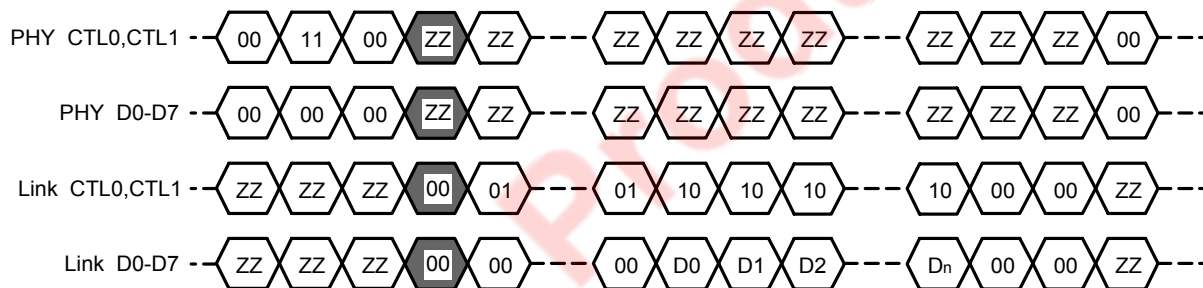
The μPD72852A arbitrates the serial bus using Link's LREQ.

- When the μPD72852A acquires the bus, a Grant period of 1 SCLK is executed to CTL0, CTL1. After that, an Idle period of 1 SCLK cycle is executed.
- Link controls the interface executing Idle, Hold of Transmit to CTL0, CTL1 after 1 SCLK cycle when Grant from PHY is detected.
- Before asserting Hold and Transmit, assert 1 Idle cycle. Do not execute Idle for 2 or more cycles.
- If the packet transmit is not ready, the Hold period can be extended up to MAX\_HOLD.
- The μPD72852A outputs DATA\_PREFIX to the serial bus while Hold is being asserted to CTL.
- When the packet transmit is ready, Link outputs the first bit of the packet and Transmit is asserted to CTL at the same time.
- After transmitting the last bit of the packet, Link outputs for Idle or Hold to CTL for 1 cycle. After that, it outputs Idle for 1 cycle.

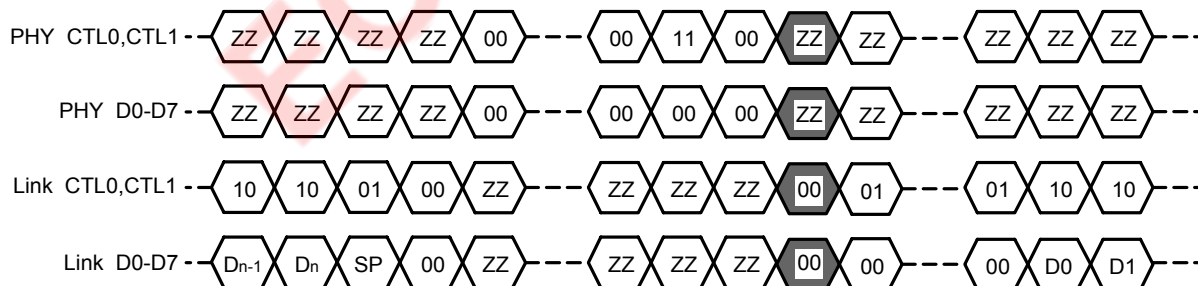
When PHY/Link releases the bus, output Low to CTL and D0-D7 within 1 cycle.

Figure 4-5. Transmit Timing

(a) Single Packet



(b) Concatenated Packet



**Note** In case of packet transmission after Grant, before actual transmission, Hold does not need to be asserted.

Link can transmit continuous packets without releasing the bus.

- Hold is asserted to CTL. This function is used when the Link transmits continuous packets after acknowledge and isochronous packets. Link outputs the transfer rate signal of the following packet to D0-D7 and asserts Hold simultaneously.
- After Hold is detected by MIN\_PACKET\_SEPARATION, the μPD72852A outputs Grant to CTL.

- Link controls the interface by generating Idle, Hold or Transmit to CTL0, CTL1, after 1 SCLK cycle when Grant from PHY is detected.
- Assert 1 Idle cycle before asserting Hold and Transmit (do not output 2 or more Idle cycles). When the packet transmission is not ready, assert Hold. The Hold output period after Grant is detected should not exceed the period provided by MAX\_HOLD.

The following limitations exist though Link can transmit the concatenated packet with a different transfer rate. Link cannot transmit other than S100 connecting packets after S100 (concatenated) packets have been transmitted. A new request to transmit must be issued in order to transmit S100 packets at a transfer rate of S200 or more.

If the Enab\_Multi bit in the PHY register is 0, the μPD72852A assumes the same speed as the first packet, for all of the concatenated packets.

At the end of packet transmission, Link asserts Idle to CTL for a period of 2 cycles.

After sampling Idle from Link, the μPD72852A asserts Idle to CTL for a period of 1 cycle.

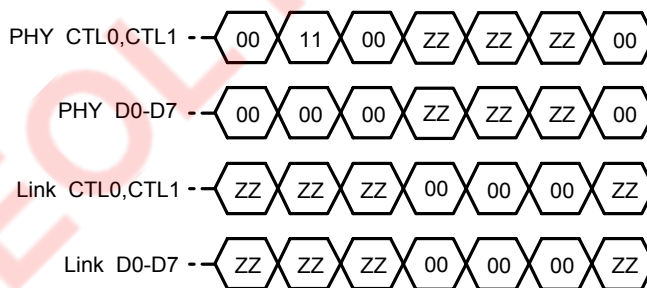
#### 4.7 Cancel

This section describes how Link operates, when after the bus has been acquired by the request of LREQ, there is no data transmission. In this case, a Null packet with no data is transmitted to the serial bus (DATA\_PREFIX → DATA\_END).

Following are two method for canceling the Link:

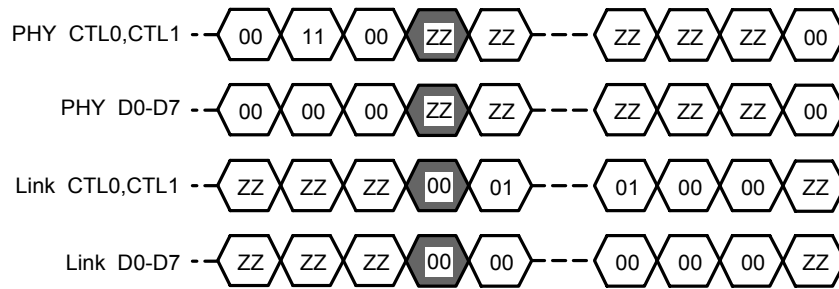
1. As explained in Section 4.6, the Link outputs Idle or Hold, then outputs Transmit to CTL after confirming Grant. Here, the Link asserts Idle for two cycles to CTL, then switches to high impedance. The μPD72852A confirms Cancel at the second Idle cycle. To prevent the bus from switching to high impedance, a third Idle cycle is needed.

**Figure 4-6. Link Cancel Timing (After Grant)**



2. To cancel after asserting Hold, assert Idle between two cycles; it switches to high impedance. This method cancels the packet transmission connection (concatenated) after Grant is received. The μPD72852A cancels with the next Idle cycle of Hold. To prevent CTL from switching to high impedance, assert a second Idle cycle.

Figure 4-7. Link Cancel Timing (After Hold)

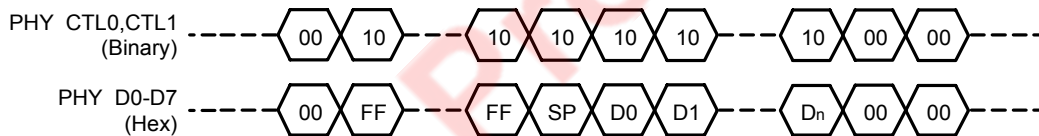


4.8 Receive

This section shows the operation when the packet is received from the serial bus.

- When the μPD72852A detects DATA\_PREFIX on the serial bus, it asserts receive to CTL and all of the D pins assume the logic value of 1.
- The μPD72852A shows the speed code of the transfer rate ahead of the packet using bits D0-D7. Transmitting the speed code with the speed signal is the protocol of the PHY/Link interface. The speed code is not included in the CRC calculation.
- The μPD72852A continues to assert Receive to CTL until the packet is finally transmitted.
- Idle is asserted to CTL, indicating completion of the packet transmission.

Figure 4-8. Receive Timing



The packet transfer rate of the serial bus depends on the topology of the bus. The μPD72852A checks if the node can receive at the faster transfer rate. At this time, DATA\_PREFIX → DATA\_END is transmitted to the μPD72852A. After DATA\_PREFIX is transmitted to the Link, Receive from the serial bus is completed, asserting Idle.

Table 4-14 shows the speed code encoding.

Table 4-14. Speed Encoding

D0-D7		Data rate
Transmitted	Observed	
00000000	00xxxxxx	S100
01000000	0100xxxx	S200
01010000	01010000	S400
11111111	11xxxxxx	Data Prefix

## 5. CABLE PHY PACKET

The node on the serial bus transmits and receives the PHY packet to control the bus.

The PHY packet is composed of 2 quadlets (64-bit); the second quadlet (32-bit) contains the inverse value of the first quadlet.

The PHY packet is transmitted at a transfer rate of S100. All of the PHY packets received from the serial bus are transmitted to the Link.

Though the PHY packet from the μPD72852A is transmitted to the Link, the PHY packet which was transmitted from the Link of the node is not transmitted to the Link.

There are four types of PHY packets, as follows:

- Self\_ID packet
- Link-on packet
- PHY configuration packet
- Extended PHY packet

The Self\_ID packet transmitted automatically by the μPD72852A is also transmitted to the Link of a local node.

The μPD72852A PHY packet Receive from the serial bus operates similar to the PHY packet transmitted by the Link (when the packet transmission to the Link is executed).

### 5.1 Self\_ID Packet

During the Self\_ID phase of the initialization or when the Ping packet responds, the μPD72852A transmits the Self\_ID packet.

Figure 5-1. Self\_ID Packet Format

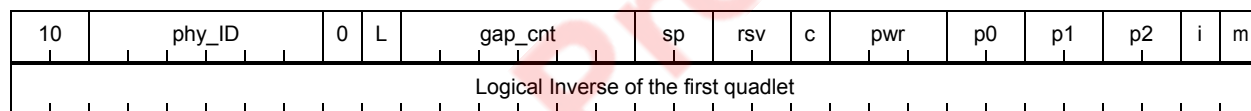


Table 5-1. Self\_ID Packet

Field	Description
phy_ID	Physical ID of the node.
L	Logical product of Link_active and LPS in the PHY register.
gap_cnt	Gap_count value in the PHY register.
sp	Physpeed 10 (corresponds to 98.304, 196.608, 393.216 Mbps).
c	C bit values in the PHY register.
pwr	pwr value in the PHY register. 000: The node does not need the power supply. No power repeat. 001: Obtains power supply for the node. Can supply 15 W or more. 010: Obtains power supply for the node. Can supply 30 W or more. 011: Obtains power supply for the node. Can supply 45 W or more. 100: The node consumes 3 W maximum power. 110: The node consumes 3 W maximum power. At least 3 W are necessary to enable Link. 111: The node consumes 3 W maximum power. At least 7 W are necessary to enable Link.
i	It shows that the node issued Bus Reset and the bus was reset.
m	Read as 0.
rsv	Read as 00.

### 5.2 Link-on Packet

The μPD72852A outputs the Link-on signal of 6.144 MHz from the pin LKON when receiving the Link-on packet.

Figure 5-2. Link-on Packet Format

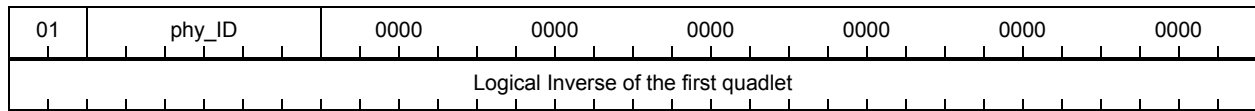


Table 5-2. Link-on Packet

Field	Description
phy_ID	Physical_ID of the destination of the Link-on packet

### 5.3 PHY Configuration Packet

Use the PHY configuration packet to set the gap count for the bus.

Figure 5-3. PHY Configuration Packet Format

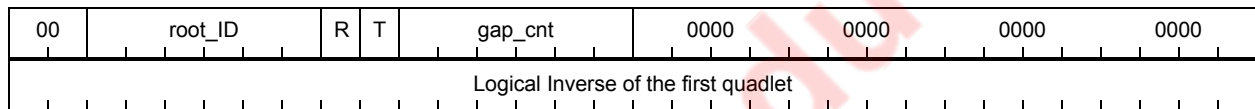


Table 5-3. PHY Configuration Packet

Field	Description
root_ID	Sets the Physical_ID node as root contender (for the next reset).
R	When this bit is set to 1 and the Physical_ID of the node corresponds to the rootID of this packet, the μPD72852A sets the force_root bit. The force_root bit is cleared if there is discrepancy.
T	If this bit is 1, the gap_cnt value of this packet is used as the gap_count value. The gap_count value must not be cleared by the following bus reset, set the gap_count_reset_disable flag in the μPD72852A to TRUE.
gap_cnt	When this packet is received, the gap count is set to this value. While it remains effective for the next bus reset, it will be cleared by the second bus reset to 3FH.

**Remark** Applying 0 to both R,T, regards the following packets as extended PHY packets, the PHY configuration is not recognized.

### 5.4 Extended PHY Packet

An extended PHY packet is defined when both the R (in the PHY configuration packet) and T bits are transmitted as 0. The extended PHY packet does not influence the force\_root\_bit and the gap\_count bit on any node.

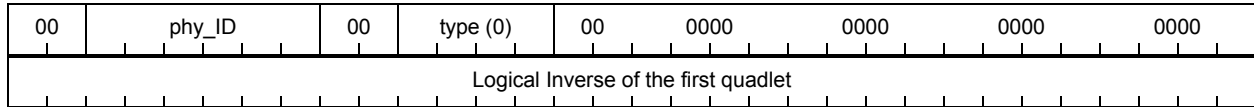
Following are the types of extended PHY packets:

- Ping packet
- Remote access packet
- Remote reply packet
- Remote command packet
- Remote confirmation packet
- Resume packet

**5.4.1 Ping Packet**

When the μPD72852A receives the Ping packet, it will transmit the Self\_ID packet within the RESPONSE\_TIME.

**Figure 5-4. Ping Packet Format**



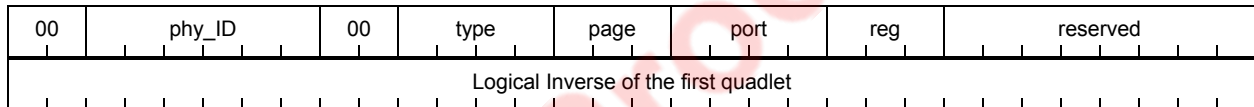
**Table 5-4. Ping Packet**

Field	Description
phy_ID	Physical ID of the destination node of the Ping packet
type	Indicates that there is a Ping packet with a value of 0

**5.4.2 Remote Access Packet**

The Remote access packet reads information in the PHY register of another node. The PHY specified by the Remote access packet transmits the value in the register using the Remote Reply packet.

**Figure 5-5. Remote Access Packet Format**



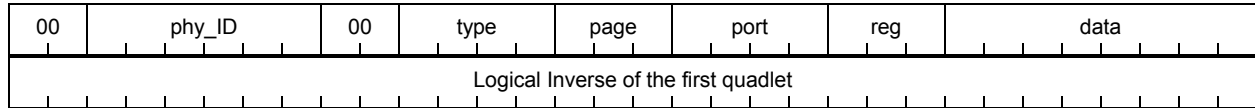
**Table 5-5. Remote Access Packet**

Field	Description
phy_ID	Physical ID of the destination node of the Remote access packet
type	1 = read register (base register), 5 = read register (page register)
page	Specifies the page of the PHY register
port	Specifies the register of each port in the PHY register
reg	Specifies the address when reading the base register. In case of the Page and port registers, specifies the address with 1000+reg.

**5.4.3 Remote Reply Packet**

The μPD72852A transmits the value in the register by using the Remote reply packet as a response to the Remote access packet.

**Figure 5-6. Remote Reply Packet Format**



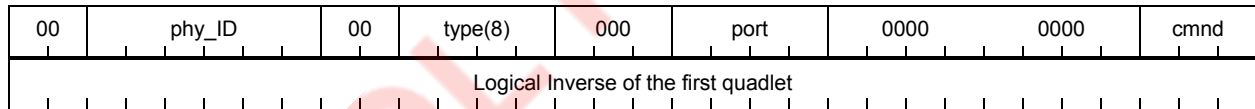
**Table 5-6. Remote Reply Packet**

Field	Description
phy_ID	Physical ID of the node (Node's original packet transmit)
type	3 = register read (base register), 7 = read register (page register)
page	Used when specifying the page of the PHY register
port	Used to specify the register of each port in the PHY register
reg	Specifies the address when reading the base register. In case of the Page and port registers, specify the address with 1000+reg.
data	Contents of the specified register

**5.4.4 Remote Command Packet**

Use the Remote command packet to operate the function of the port of the PHY of another node.

**Figure 5-7. Remote Command Packet Format**



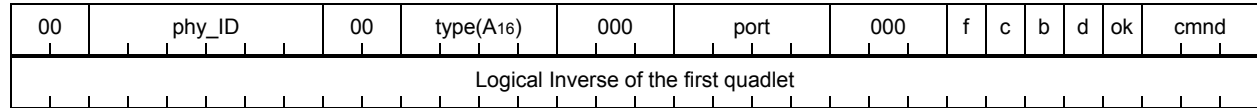
**Table 5-7. Remote Command Packet**

Field	Description
phy_ID	Physical ID of the destination packet
type	Extended PHY packet type; set to 8 for Remote command packet
port	Port of the PHY of the operating node
cmnd	Command 0: NOP 1: Disables the port after transmission of the TX_DISABLE_NOTIFY 2: Suspend initiator 4: Clears to 0 the Fault bit of the port 5: Enables the port 6: Resumes the port

**5.4.5 Remote Confirmation Packet**

The μPD72852A transmits the Remote confirmation when the Remote command packet is received, responding whether cmdnd can be executed.

**Figure 5-8. Remote Confirmation Packet Format**



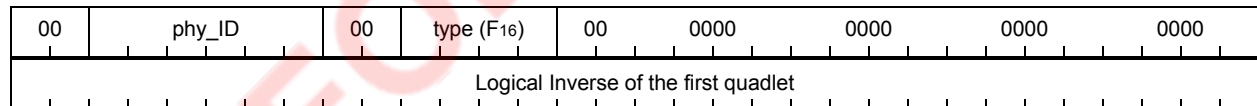
**Table 5-8. Remote Confirmation Packet**

Field	Description
phy_ID	Physical ID of the node (node's original packet transmit)
type	Extended PHY packet type; set to A <sub>16</sub> for Remote confirmation packet
port	Port set from the Remote command packet
f	Fault bit value of the PHY register of this port
c	Connected bit value of the PHY register of this port
b	Bias bit value of the PHY register of this port
d	Disable bit value of the PHY register of this port
ok	1 indicates executing; otherwise it is 0
cmdnd	Specifies the command value with the Remote command packet

**5.4.6 Resume Packet**

When the μPD72852A receives the Resume packet, all of the ports that were suspended resume the connection. The Resume packet does the broadcast.

**Figure 5-9. Resume Packet Format**



**Table 5-9. Resume Packet**

Field	Description
phy_ID	Physical ID of the original packet transmit
type	Extended PHY packet type; set to F <sub>16</sub> for Resume packet



## 6. ELECTRICAL SPECIFICATIONS

### Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating	Unit
Power supply voltage	$V_{DDm}$		-0.5 to +4.6	V
Input voltage	$V_{IN}$		-0.5 to $V_{DD}+0.5$	V
Output voltage	$V_{OUT}$		-0.5 to $V_{DD}+0.5$	V
Storage temperature	$T_{stg}$		-40 to +125	°C

**Caution** Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

★ A CMOS device may cause unusual operation or destruction by Latch-up phenomenon. For your safety, be careful of the factor (serge, noise, static electricity) considered as external stress to Input/Output pins.

In order to avoid outbreak of heat/destruction of the device/board/equipment by an over-current continuing input, please prepare the current restrictions below 1.5 [A] as  $V_{CC}$  input.

### Recommended Operating Ranges

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Power supply voltage	$V_{DD}$	Source power node	3.0	3.3	3.6	V
		Non-source power node	2.7 <sup>Note</sup>	3.0	3.6	V
Operating temperature	$T_A$		0.0		70.0	°C
Power dissipation	$P_b$				440	mW

**Note** For a node does not source power.

DC Characteristics

Common

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Supply current	I <sub>DD</sub>	<b>Note 1</b>		68		mA
		<b>Note 2</b>		60		mA
		<b>Note 3</b>		41		mA
		<b>Note 4</b>		31		mA
		<b>Note 5</b>		115		μA

- Notes**
1. Transmit maximum packet (all ports transmitting maximum size isochronous packet - 4096 bytes, sent on every isochronous interval, S400, data value of CCCCCCCH), V<sub>DD</sub> = 3.3 V, T<sub>A</sub> = 25°C
  2. Repeat typical packet (receiving on one port DV packets on every isochronous interval, S100, and transmitting on the other port), V<sub>DD</sub> = 3.3 V, T<sub>A</sub> = 25°C
  3. Idle (one port receiving and one port transmitting cycle starts), V<sub>DD</sub> = 3.3 V, T<sub>A</sub> = 25°C
  4. 1 port receiving cycle start packet only, V<sub>DD</sub> = 3.3 V, T<sub>A</sub> = 25°C
  5. Suspend mode, V<sub>DD</sub> = 3.3 V, T<sub>A</sub> = 25°C

PHY/Link Interface

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
High-level output voltage	V <sub>OH</sub>	CTL0, CTL1, D0-D7, LKON, SCLK, I <sub>OH</sub> = -9 mA, V <sub>DD</sub> > 3 V	V <sub>DD</sub> -0.45			V
		CTL0, CTL1, D0-D7, LKON, SCLK, I <sub>OH</sub> = -4 mA, V <sub>DD</sub> = 2.7 V	V <sub>DD</sub> -0.4			V
Low-level output voltage	V <sub>OL</sub>	CTL0, CTL1, D0-D7, LKON, SCLK, I <sub>OH</sub> = +9 mA, V <sub>DD</sub> > 3 V			0.4	V
		CTL0, CTL1, D0-D7, LKON, SCLK, I <sub>OH</sub> = +4 mA, V <sub>DD</sub> = 2.7 V			0.4	V
High-level input voltage	V <sub>IH</sub>	LPS, SPD, DIRECT, PC0-PC2, SUS/RES, CMC	0.7V <sub>DD</sub>			V
Low-level input voltage	V <sub>IL</sub>	LPS, SPD, DIRECT, PC0-PC2, SUS/RES, CMC			0.2V <sub>DD</sub>	V
High-level input voltage (schmitt)	V <sub>IHS</sub>	CTL0, CTL1, D0-D7, LREQ, V <sub>DD</sub> > 3 V	0.456V <sub>DD</sub> +0.3		0.456V <sub>DD</sub> +0.9	V
Low-level input voltage (schmitt)	V <sub>ILS</sub>	CTL0, CTL1, D0-D7, LREQ, V <sub>DD</sub> > 3 V	0.456V <sub>DD</sub> -0.9		0.456V <sub>DD</sub> -0.3	V
High-level input current	I <sub>IH</sub>	CTL0, CTL1, D0-D7, V <sub>I</sub> = V <sub>DD</sub> , DIRECT = 0 V	-10			μA
		LPS, SPD, DIRECT, PC0-PC2, SUS/RES, CMC, V <sub>I</sub> = V <sub>DD</sub>	-10			μA
Low-level input current	I <sub>IL</sub>	CTL0, CTL1, D0-D7, LKON, SCLK, V <sub>I</sub> = 0 V, DIRECT = 0 V			10	μA
		LPS, SPD, DIRECT, PC0-PC2, SUS/RES, CMC, V <sub>I</sub> = 0 V			10	μA

Cable Interface

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Differential input voltage	V <sub>ID</sub>	Cable input, 100 Mbps operation	142		260	mV
		Cable input, 200 Mbps operation	132		260	mV
		Cable input, 400 Mbps operation	118		260	mV
TpB common mode input voltage	V <sub>ICM</sub>	100 Mbps speed signaling off	1.165		2.515	V
		200 Mbps speed signaling	0.935		2.515	V
		400 Mbps speed signaling	0.523		2.515	V
Differential output voltage	V <sub>OD</sub>	Cable output (Test load 55 Ω)	172.0		265.0	mV
TpA common mode output voltage	V <sub>OCM</sub>	100 Mbps speed signaling off	1.665		2.015	V
		200 Mbps speed signaling	1.438		2.015	V
		400 Mbps speed signaling	1.030		2.015	V
TpA common mode output current	I <sub>CM</sub>	100 Mbps speed signaling off	-0.81		+0.44	mA
		200 Mbps speed signaling	-4.84		-2.53	mA
		400 Mbps speed signaling	-12.40		-8.10	mA
Power status threshold voltage	V <sub>TH</sub>	CPS			7.5	V
TpBias output voltage	V <sub>TPBIAS</sub>		1.665		2.015	V

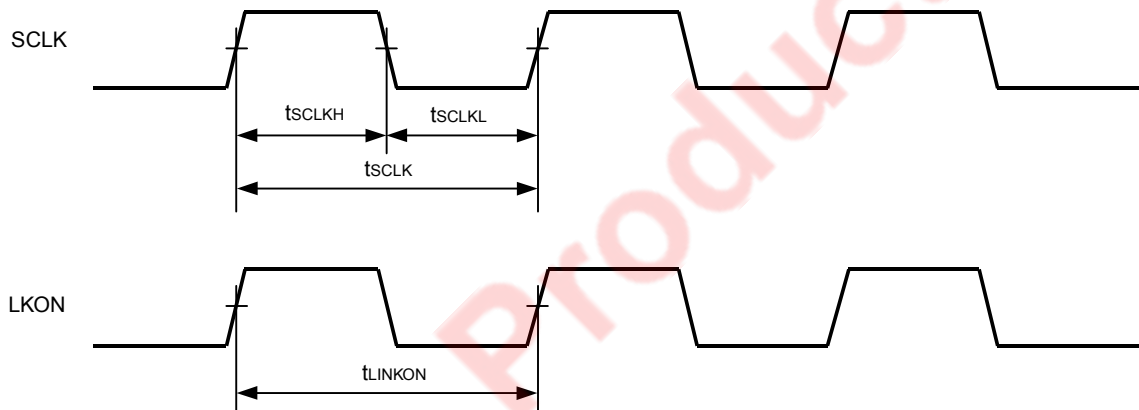
EOL Product

AC Characteristics

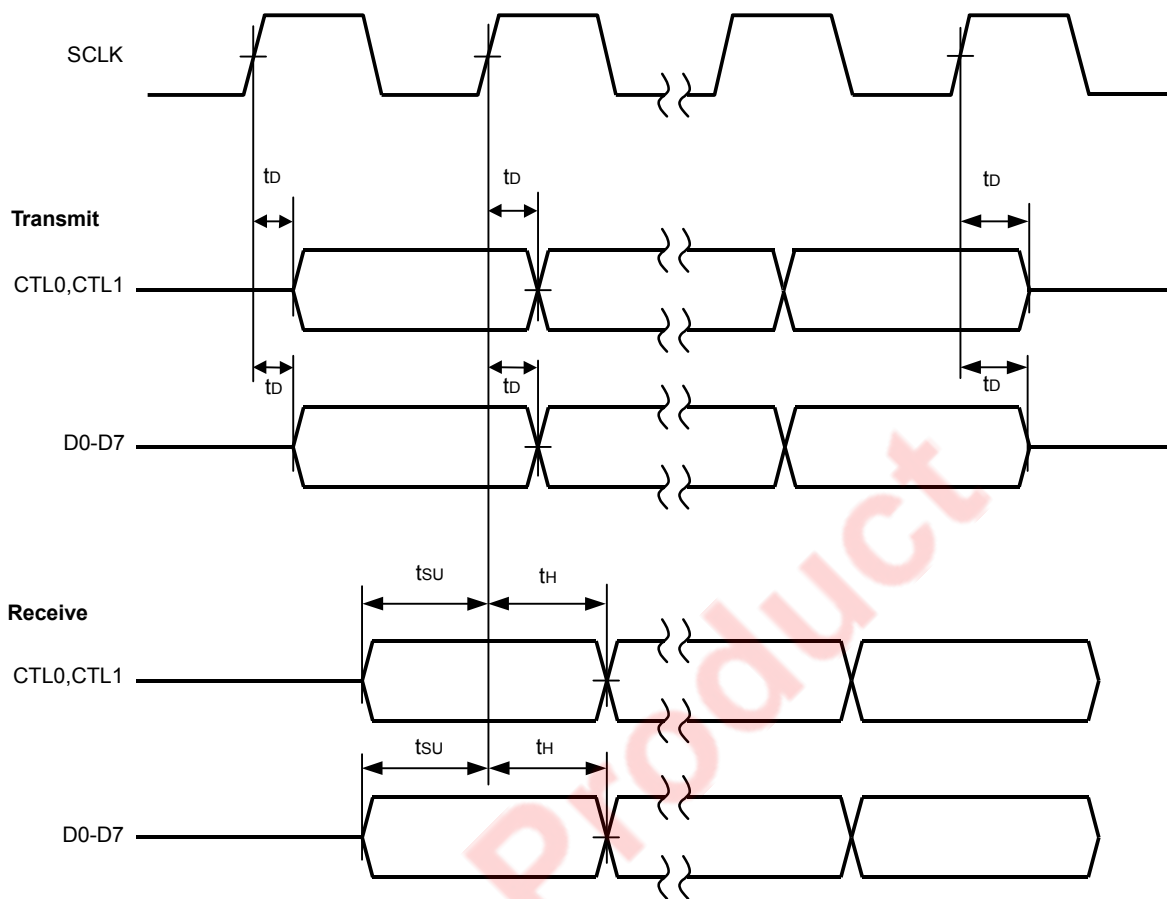
PHY/Link Interface

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
D, CTL, LREQ setup time	$t_{su}$		5			ns
D, CTL, LREQ hold time	$t_{hd}$		0			ns
D, CTL output timing	$t_d$		0.5		9	ns
SCLK cycle time	$t_{SCLK}$		20			ns
SCLK high level time	$t_{SCLKH}$		9		11	ns
SCLK low level time	$t_{SCLKL}$		9		11	ns
LKON cycle time	$t_{LINKON}$		160			ns

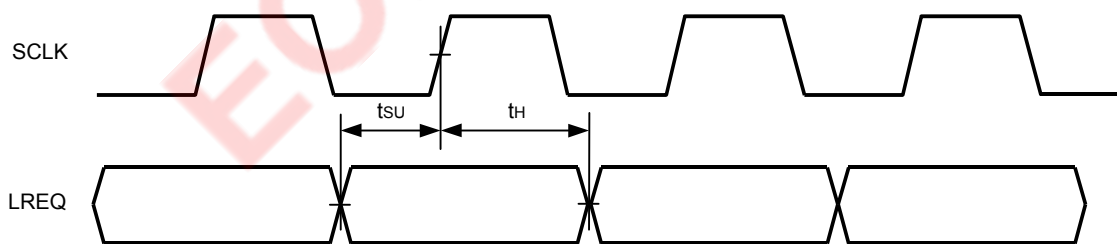
Link Interface Timing (SCLK, LKON)



Link Interface Timing (CTL, D)



Link Interface Timing (LREQ)

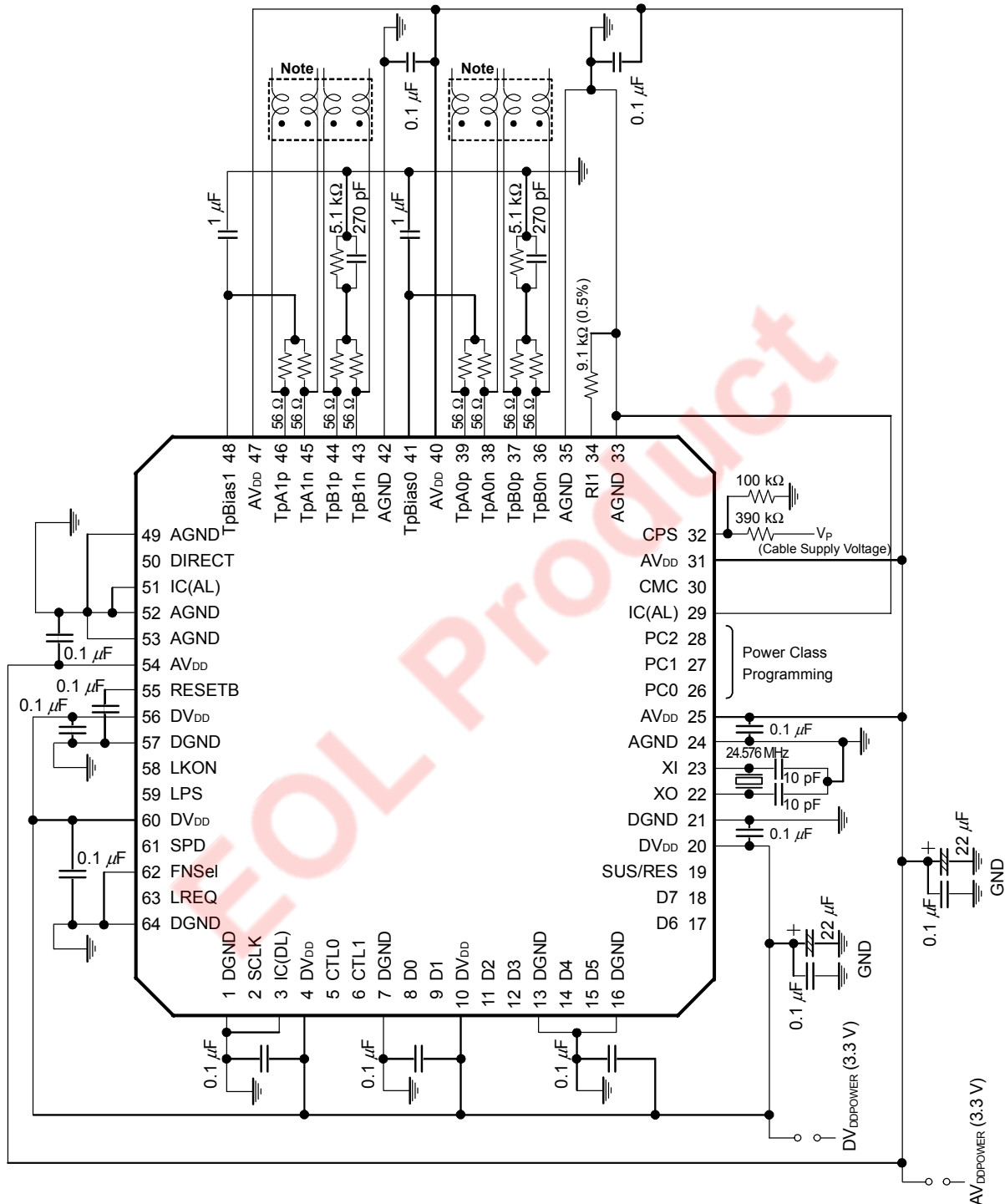


Cable Interface

Parameter	Symbol	Condition	Speed	MIN.	TYP.	MAX.	Unit
TpA, TpB transfer jitter	$t_{JITTER}$	Between TpA and TpB				±0.15	ns
TpA strobe, TpB data transfer	$t_{SKEW}$	Between TpA and TpB				±0.10	ns
TPA, TPB rise time/fall time	$t_r/t_f$	10 % to 90 %, via 55 Ω and 10 pF	S100	0.5		3.2	ns
			S200	0.5		2.2	ns
			S400	0.5		1.2	ns

7. APPLICATION CIRCUIT EXAMPLE

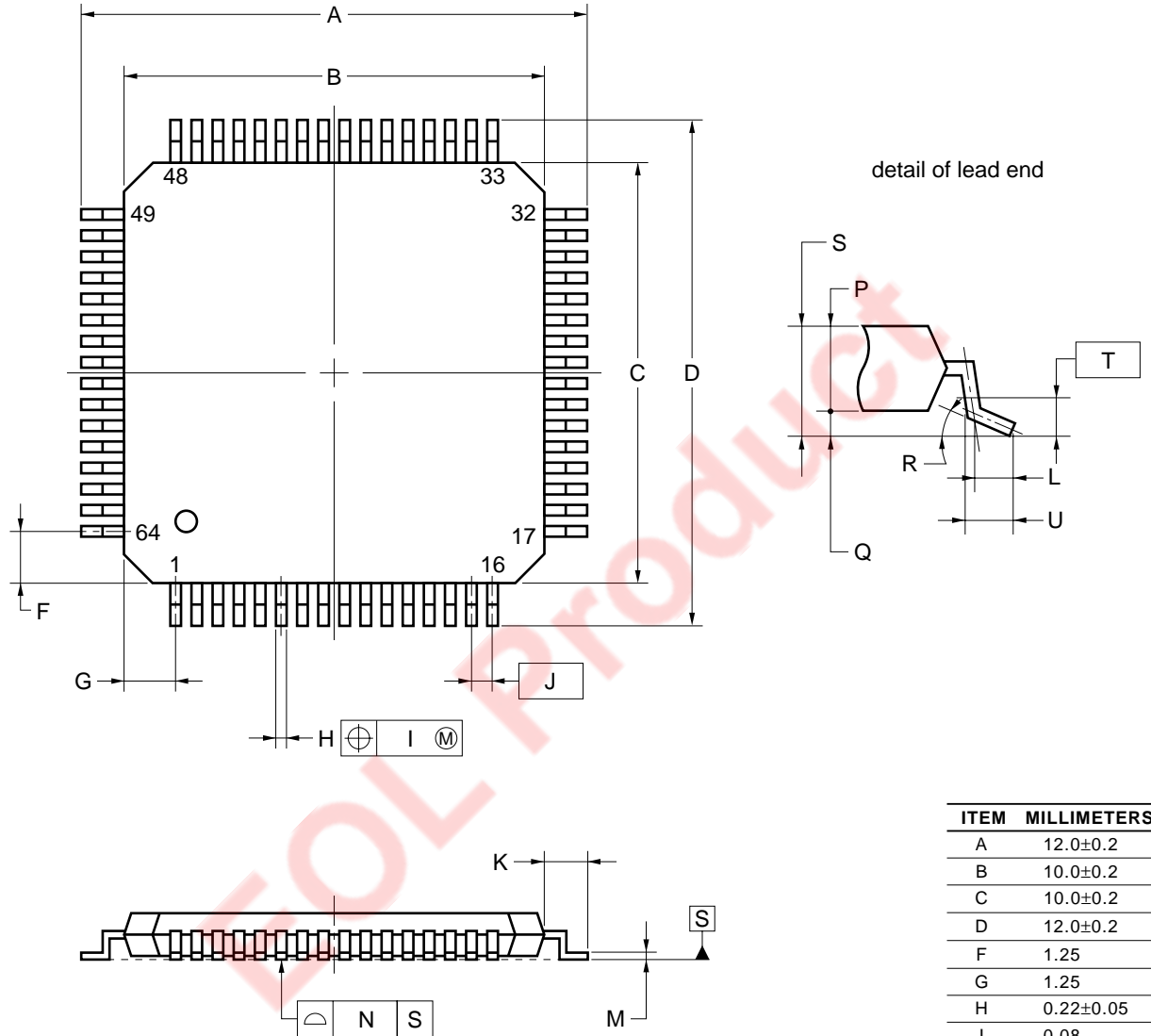
- IEEE1394 Interface



**Note** Common mode choke.  
 Recommendation : TDK Part No. ACM2012-121  
 : MURATA Part No. PLP31DN161SL4

8. PACKAGE DRAWING

64-PIN PLASTIC LQFP (10x10)



NOTE

Each lead centerline is located within 0.08 mm of its true position (T.P.) at maximum material condition.

S64GB-50-8EU-2

**9. RECOMMENDED SOLDERING CONDITIONS**

The μPD72852A should be soldered and mounted under the following recommended conditions.

For soldering methods and conditions other than those recommended below, contact your NEC Electronics sales representative.

For technical information, see the following website.

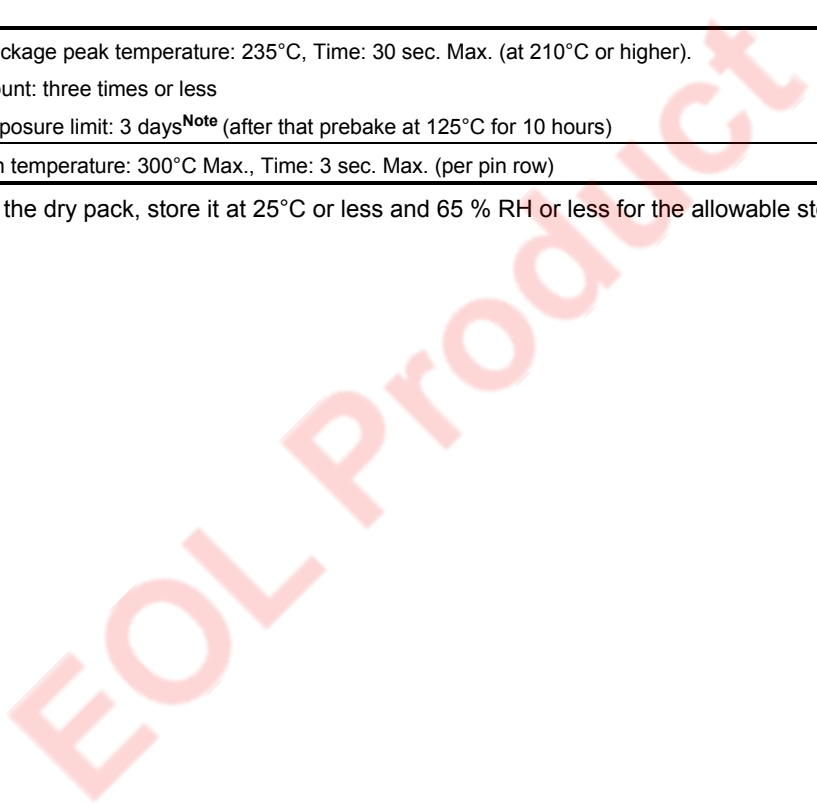
Semiconductor Device Mount Manual (<http://www.necel.com/pkg/en/mount/index.html>)

**Table 9-1. Surface Mounting Type Soldering Conditions**

**μPD72852AGB-8EU: 64-pin plastic LQFP (10 × 10)**

Soldering Method	Soldering Conditions	Recommended Condition Symbol
Infrared reflow	Package peak temperature: 235°C, Time: 30 sec. Max. (at 210°C or higher). Count: three times or less Exposure limit: 3 days <sup>Note</sup> (after that prebake at 125°C for 10 hours)	IR35-103-3
Partial heating	Pin temperature: 300°C Max., Time: 3 sec. Max. (per pin row)	—

**Note** After opening the dry pack, store it at 25°C or less and 65 % RH or less for the allowable storage period.





## NOTES FOR CMOS DEVICES

**① VOLTAGE APPLICATION WAVEFORM AT INPUT PIN**

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN).

**② HANDLING OF UNUSED INPUT PINS**

Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.

**③ PRECAUTION AGAINST ESD**

A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.

**④ STATUS BEFORE INITIALIZATION**

Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.

**⑤ PAY ATTENTION TO CHARGING WITH STATIC ELECTRICITY OF THE DEVICE OR THE SURFACE OF THE DEVICE PACKAGE**

In case the handing of this product and the production manufacturing process, please use the ionizer for this device to eliminate static electricity.

FireWire is a trademark of Apple Computer, Inc.

i.LINK is a trademark of Sony Corporation.

Intel is a trademark of Intel Corporation.

- **The information in this document is current as of March, 2004. The information is subject to change without notice. For actual design-in, refer to the latest publications of NEC Electronics data sheets or data books, etc., for the most up-to-date specifications of NEC Electronics products. Not all products and/or types are available in every country. Please check with an NEC Electronics sales representative for availability and additional information.**
- No part of this document may be copied or reproduced in any form or by any means without the prior written consent of NEC Electronics. NEC Electronics assumes no responsibility for any errors that may appear in this document.
- NEC Electronics does not assume any liability for infringement of patents, copyrights or other intellectual property rights of third parties by or arising from the use of NEC Electronics products listed in this document or any other liability arising from the use of such products. No license, express, implied or otherwise, is granted under any patents, copyrights or other intellectual property rights of NEC Electronics or others.
- Descriptions of circuits, software and other related information in this document are provided for illustrative purposes in semiconductor product operation and application examples. The incorporation of these circuits, software and information in the design of a customer's equipment shall be done under the full responsibility of the customer. NEC Electronics assumes no responsibility for any losses incurred by customers or third parties arising from the use of these circuits, software and information.
- While NEC Electronics endeavors to enhance the quality, reliability and safety of NEC Electronics products, customers agree and acknowledge that the possibility of defects thereof cannot be eliminated entirely. To minimize risks of damage to property or injury (including death) to persons arising from defects in NEC Electronics products, customers must incorporate sufficient safety measures in their design, such as redundancy, fire-containment and anti-failure features.
- NEC Electronics products are classified into the following three quality grades: "Standard", "Special" and "Specific".  
The "Specific" quality grade applies only to NEC Electronics products developed based on a customer-designated "quality assurance program" for a specific application. The recommended applications of an NEC Electronics product depend on its quality grade, as indicated below. Customers must check the quality grade of each NEC Electronics product before using it in a particular application.  
"Standard": Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots.  
"Special": Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support).  
"Specific": Aircraft, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems and medical equipment for life support, etc.

The quality grade of NEC Electronics products is "Standard" unless otherwise expressly specified in NEC Electronics data sheets or data books, etc. If customers wish to use NEC Electronics products in applications not intended by NEC Electronics, they must contact an NEC Electronics sales representative in advance to determine NEC Electronics' willingness to support a given application.

(Note)

- (1) "NEC Electronics" as used in this statement means NEC Electronics Corporation and also includes its majority-owned subsidiaries.
- (2) "NEC Electronics products" means any product developed or manufactured by or for NEC Electronics (as defined above).