

To our customers,

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April 1<sup>st</sup>, 2010  
Renesas Electronics Corporation

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**240-OUTPUT TFT-LCD SOURCE DRIVER  
 (COMPATIBLE WITH 64 GRAY SCALES)**

The  $\mu$ PD16635 is a source driver for TFT-LCDs capable of dealing with displays with 64 gray scales. Data input is based on digital input configured as 6 bits by 6 dots (2 pixels), which can realize a full-color display of 260,000 colors by output of 64 values  $\gamma$ -corrected by an internal D/A converter and 5-by-2 external power modules. Because the output dynamic range is as large as 11.5 V<sub>P-P</sub>, level inversion operation of the LCD's common electrode is rendered unnecessary. Also, to be able to deal with full-dot inversion when mounted on a single side, this source driver is equipped with a built-in 6-bit D/A converter circuit whose odd output pins and even output pins respectively output gray scale voltages of differing polarity. Assuring a maximum clock frequency of 33 MHz when driving at 3.0 V, this driver is applicable to SVGA-standard TFT-LCD panels.

**FEATURES**

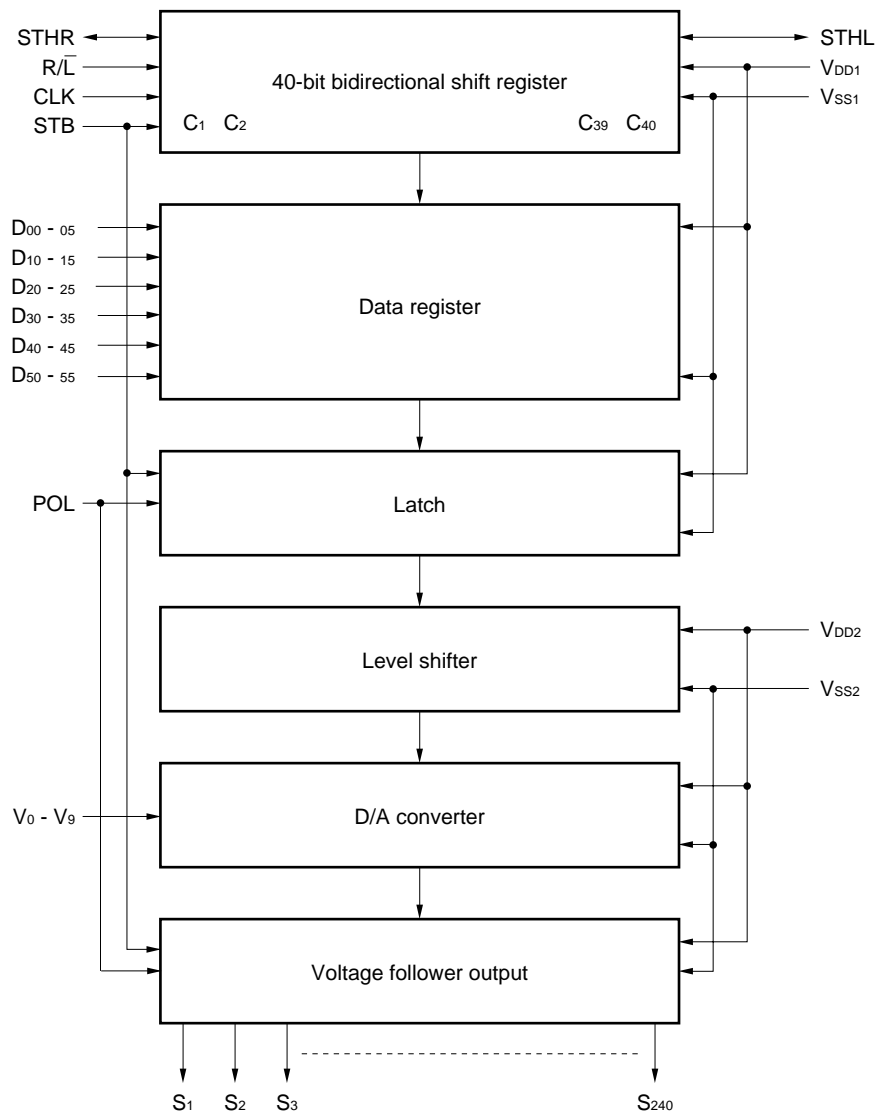
- Capable of outputting 64 values by means of 5-by-2 external power modules (10 units) and a D/A converter
- Output dynamic range 11.5 V<sub>P-P</sub> min. (@ V<sub>DD2</sub> = 13.5 V)
- CMOS level input
- Input of 6 bits (gradation data) by 6 dots
- High-speed data transfer: f<sub>max</sub> = 33 MHz (internal data transfer speed when operating at 3.0 V)
- 240 outputs
- Dedicated full-dot inversion driver
- Single-sided mounting possible (loaded with slim TCP)

**ORDERING INFORMATION**

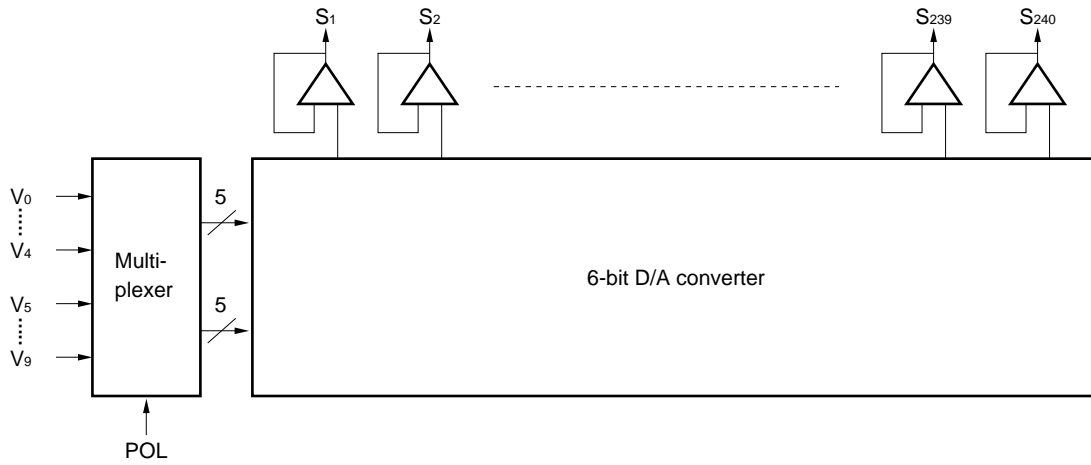
Part Number	Package
$\mu$ PD16635N-xxx	TCP (TAB package)

The TCP's external shape is customized. To order your TCP's external shape, please contact a NEC salesperson.

1. BLOCK DIAGRAM



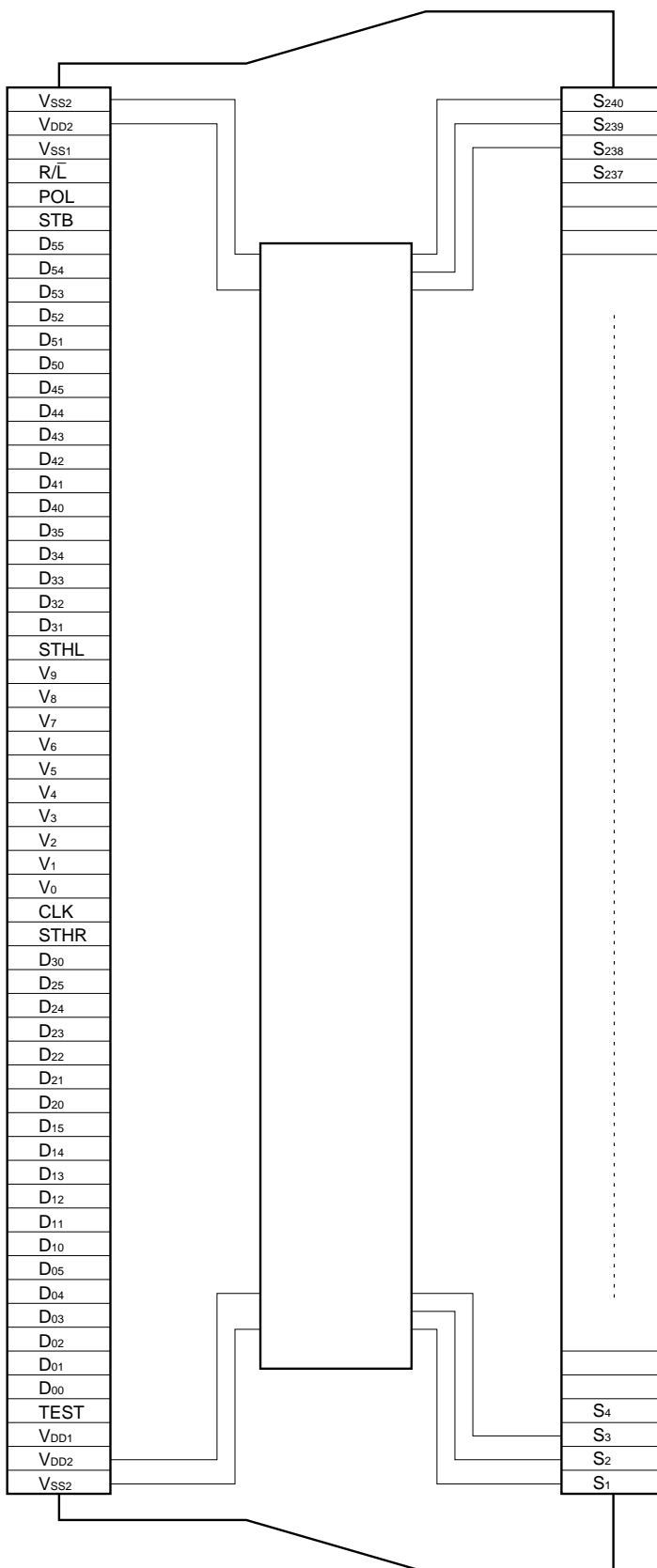
2. RELATIONSHIP BETWEEN OUTPUT CIRCUIT AND D/A CONVERTER



POL	$S_{2n-1}$	$S_{2n}$
L	$V_0$ to $V_4$	$V_5$ to $V_9$
H	$V_5$ to $V_9$	$V_0$ to $V_4$

$S_{2n-1}$  (odd output),  $S_{2n}$  (even output)  $n = 1, 2, \dots, 120$

3. PIN CONFIGURATION (μPD16635N-xxx)



This figure shows the pin connection, not a TCP package.

## 4. PIN FUNCTIONS

Pin Symbol	Pin Name	Description
S <sub>1</sub> to S <sub>240</sub>	Driver output	The D/A converted 64-gray-scale analog voltage is output.
D <sub>00</sub> to D <sub>05</sub>	Display data input	The display data is input with a width of 36 bits, viz., the gray scale data (6 bits) by 6 dots (2 pixels). D <sub>X0</sub> : LSB, D <sub>X5</sub> : MSB
D <sub>10</sub> to D <sub>15</sub>		
D <sub>20</sub> to D <sub>25</sub>		
D <sub>31</sub> to D <sub>35</sub>		
D <sub>40</sub> to D <sub>45</sub>		
D <sub>50</sub> to D <sub>55</sub>		
R/L	Shift direction switching input	These refer to the start pulse input/output pins when cascades are connected. The shift directions of the shift registers are as follows. R/L = H: STHR input, S <sub>1</sub> → S <sub>240</sub> , STHL output R/L = L: STHL input, S <sub>240</sub> → S <sub>1</sub> , STHR output
STHR	Right shift start pulse input/output	R/L = H: Becomes the start pulse input pin. R/L = L: Becomes the start pulse output pin.
STHL	Left shift start pulse input/output	R/L = H: Becomes the start pulse output pin. R/L = L: Becomes the start pulse input pin.
CLK	Shift clock input	Refers to the shift register's shift clock input. The display data is incorporated into the data register at the rising edge. At the rising edge of the 40th clock after the start pulse input, the start pulse output reaches the high level, thus becoming the start pulse of the next-stage driver. The initial-stage driver's 40th clock becomes valid as the next-stage driver's start pulse is input. If 42 clock pulses are input after input of the start pulse, input of display data is halted automatically. The contents of the shift register are cleared at the STB's rising edge.
STB	Latch input	The contents of the data register are transferred to the latch at the rising edge. And, at the falling edge, the gray scale voltage is supplied to the driver. It is necessary to ensure input of one pulse per horizontal period.
POL	Polarity input	POL = L; The S <sub>2n-1</sub> output uses V <sub>0</sub> to V <sub>4</sub> as the reference supply; and the S <sub>2n</sub> output uses V <sub>5</sub> to V <sub>9</sub> as the reference supply. POL = H; The S <sub>2n-1</sub> output uses V <sub>5</sub> to V <sub>9</sub> as the reference supply; and the S <sub>2n</sub> output uses V <sub>0</sub> to V <sub>4</sub> as the reference supply. S <sub>2n-1</sub> indicates the odd output; and S <sub>2n</sub> indicates the even output. Input of the POL signal is allowed the setup time (t <sub>POL-STB</sub> ) with respect to STB's rising edge.
V <sub>0</sub> to V <sub>9</sub>	$\gamma$ -corrected power supplies	Input the $\gamma$ -corrected power supplies from outside. Make sure to maintain the following relationships. During the gray scale voltage output, be sure to keep the gray scale level power supply at a constant level. V <sub>DD2</sub> > V <sub>0</sub> > V <sub>1</sub> > V <sub>2</sub> > V <sub>3</sub> > V <sub>4</sub> > V <sub>5</sub> > V <sub>6</sub> > V <sub>7</sub> > V <sub>8</sub> > V <sub>9</sub> > V <sub>SS2</sub>
TEST	Test pin	Set it to "OPEN".
V <sub>DD1</sub>	Logic power supply	3.3 V $\pm$ 0.3 V
V <sub>DD2</sub>	Driver power supply	11.0 V to 13.5 V
V <sub>SS1</sub>	Logic ground	Grounding
V <sub>SS2</sub>	Driver ground	Grounding

- Cautions**
1. The power start sequence must be V<sub>DD1</sub>, logic input, and V<sub>DD2</sub> & V<sub>0</sub> to V<sub>9</sub> in that order. Reverse this sequence to shut down. (Simultaneous power application to V<sub>DD2</sub> and V<sub>0</sub> to V<sub>9</sub> is possible.)
  2. To stabilize the supply voltage, please be sure to insert a 0.1  $\mu$ F bypass capacitor between V<sub>DD1</sub>-V<sub>SS1</sub> and V<sub>DD2</sub>-V<sub>SS2</sub>. Furthermore, for increased precision of the D/A converter, insertion of a bypass capacitor of about 0.01  $\mu$ F is also advised between the  $\gamma$ -corrected power supply terminals (V<sub>0</sub>, V<sub>1</sub>, V<sub>2</sub>, ..., V<sub>9</sub>) and V<sub>SS2</sub>.

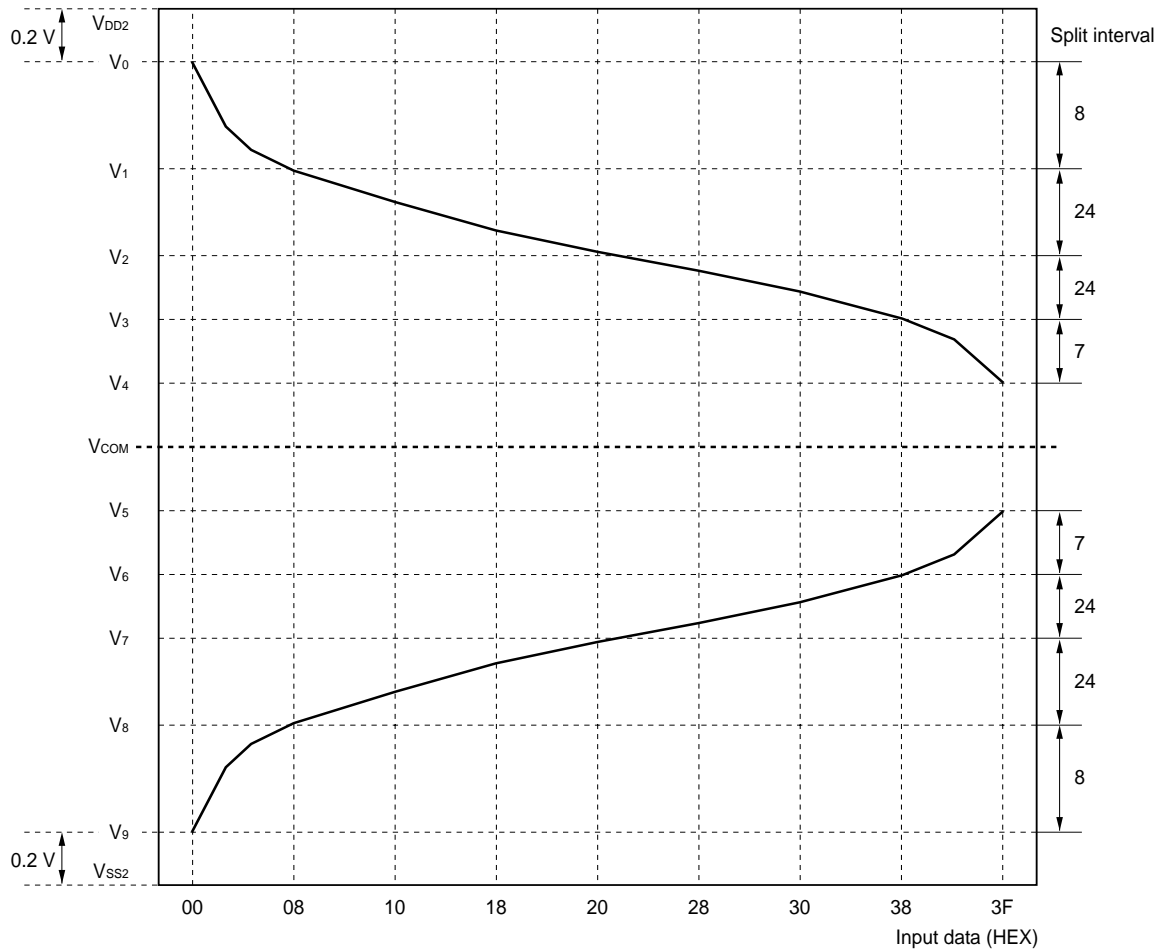
### 5. RELATIONSHIP BETWEEN INPUT DATA AND OUTPUT VOLTAGE VALUE

This product incorporates a 6-bit D/A converter whose odd output pins and even output pins output respectively gray scale voltages of differing polarity with respect to the LCD's counter electrode (common electrode) voltage. The D/A converter consists of ladder resistors and switches. The ladder resistors  $r_0$  to  $r_{62}$  are so designed that the ratios between the LCD panel's  $\gamma$ -corrected voltages and  $V_0'$  to  $V_{63}'$  and  $V_0''$  to  $V_{63}''$  are roughly equal; and their respective resistance values are as shown on page 9. Among the 5-by-2  $\gamma$ -corrected voltages, input gray scale voltages of the same polarity with respect to the common voltage, for the respective five  $\gamma$ -corrected voltages of  $V_0$  to  $V_4$  and  $V_5$  to  $V_9$ . If fine gray scale voltage precision is not necessary, the voltage follower circuit supplied to the  $\gamma$ -corrected power supplies  $V_1$  to  $V_3$  and  $V_6$  to  $V_8$  can be deleted.

Figure 1 shows the relationship between the driving voltages such as liquid-crystal driving voltages  $V_{DD2}$  and  $V_{SS2}$ , common electrode potential  $V_{COM}$ , and  $\gamma$ -corrected voltages  $V_0$  to  $V_9$  and the input data. Be sure to maintain the voltage relationships of  $V_{DD2} > V_0 > V_1 > V_2 > V_3 > V_4 > V_5 > V_6 > V_7 > V_8 > V_9 > V_{SS2}$ . Figures 2-1 and 2-2 show the relationship between the input data and the output data. Table 1 shows the resistance values of the resistor strings.

This driver IC is designed for single-sided dot inversion mounting. Therefore, it cannot be used in double-sided mounting.

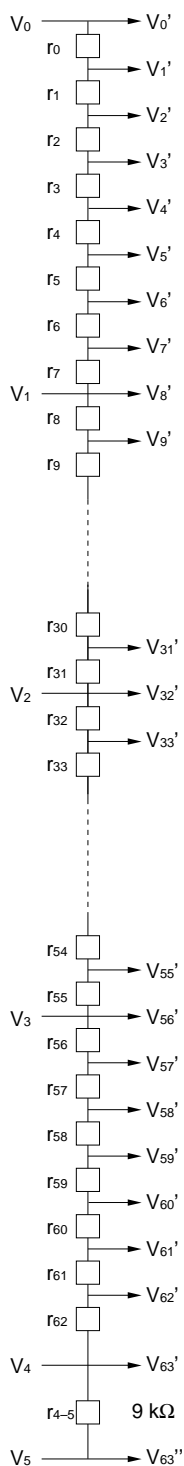
Figure 1. Relationship Between Input Data and Output Voltage





Resistor Strings

Figure 2-1. Relationship Between Input Data and Output Voltage:  $V_{DD2} > V_0 > V_1 > V_2 > V_3 > V_4 > V_5$

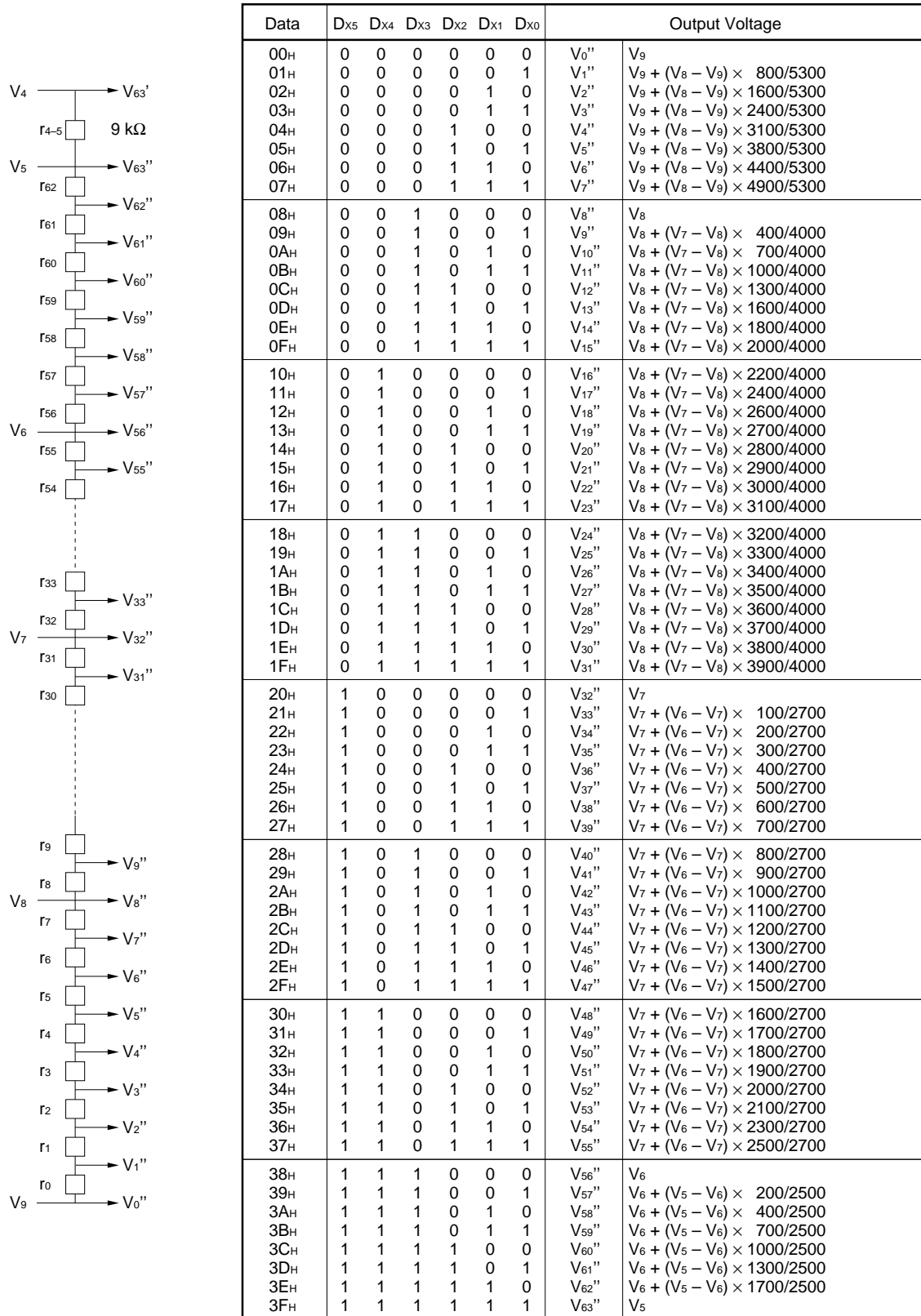


Data	Dx5	Dx4	Dx3	Dx2	Dx1	Dx0	Output Voltage	
00H	0	0	0	0	0	0	$V_0'$	$V_0$
01H	0	0	0	0	0	1	$V_1'$	$V_1 + (V_0 - V_1) \times 4500/5300$
02H	0	0	0	0	1	0	$V_2'$	$V_1 + (V_0 - V_1) \times 3700/5300$
03H	0	0	0	0	1	1	$V_3'$	$V_1 + (V_0 - V_1) \times 2900/5300$
04H	0	0	0	1	0	0	$V_4'$	$V_1 + (V_0 - V_1) \times 2200/5300$
05H	0	0	0	1	0	1	$V_5'$	$V_1 + (V_0 - V_1) \times 1500/5300$
06H	0	0	0	1	1	0	$V_6'$	$V_1 + (V_0 - V_1) \times 900/5300$
07H	0	0	0	1	1	1	$V_7'$	$V_1 + (V_0 - V_1) \times 400/5300$
08H	0	0	1	0	0	0	$V_8'$	$V_1$
09H	0	0	1	0	0	1	$V_9'$	$V_2 + (V_1 - V_2) \times 3600/4000$
0AH	0	0	1	0	1	0	$V_{10}'$	$V_2 + (V_1 - V_2) \times 3300/4000$
0BH	0	0	1	0	1	1	$V_{11}'$	$V_2 + (V_1 - V_2) \times 3000/4000$
0CH	0	0	1	1	0	0	$V_{12}'$	$V_2 + (V_1 - V_2) \times 2700/4000$
0DH	0	0	1	1	0	1	$V_{13}'$	$V_2 + (V_1 - V_2) \times 2400/4000$
0EH	0	0	1	1	1	0	$V_{14}'$	$V_2 + (V_1 - V_2) \times 2200/4000$
0FH	0	0	1	1	1	1	$V_{15}'$	$V_2 + (V_1 - V_2) \times 2000/4000$
10H	0	1	0	0	0	0	$V_{16}'$	$V_2 + (V_1 - V_2) \times 1800/4000$
11H	0	1	0	0	0	1	$V_{17}'$	$V_2 + (V_1 - V_2) \times 1600/4000$
12H	0	1	0	0	1	0	$V_{18}'$	$V_2 + (V_1 - V_2) \times 1400/4000$
13H	0	1	0	0	1	1	$V_{19}'$	$V_2 + (V_1 - V_2) \times 1300/4000$
14H	0	1	0	1	0	0	$V_{20}'$	$V_2 + (V_1 - V_2) \times 1200/4000$
15H	0	1	0	1	0	1	$V_{21}'$	$V_2 + (V_1 - V_2) \times 1100/4000$
16H	0	1	0	1	1	0	$V_{22}'$	$V_2 + (V_1 - V_2) \times 1000/4000$
17H	0	1	0	1	1	1	$V_{23}'$	$V_2 + (V_1 - V_2) \times 900/4000$
18H	0	1	1	0	0	0	$V_{24}'$	$V_2 + (V_1 - V_2) \times 800/4000$
19H	0	1	1	0	0	1	$V_{25}'$	$V_2 + (V_1 - V_2) \times 700/4000$
1AH	0	1	1	0	1	0	$V_{26}'$	$V_2 + (V_1 - V_2) \times 600/4000$
1BH	0	1	1	0	1	1	$V_{27}'$	$V_2 + (V_1 - V_2) \times 500/4000$
1CH	0	1	1	1	0	0	$V_{28}'$	$V_2 + (V_1 - V_2) \times 400/4000$
1DH	0	1	1	1	0	1	$V_{29}'$	$V_2 + (V_1 - V_2) \times 300/4000$
1EH	0	1	1	1	1	0	$V_{30}'$	$V_2 + (V_1 - V_2) \times 200/4000$
1FH	0	1	1	1	1	1	$V_{31}'$	$V_2 + (V_1 - V_2) \times 100/4000$
20H	1	0	0	0	0	0	$V_{32}'$	$V_2$
21H	1	0	0	0	0	1	$V_{33}'$	$V_3 + (V_2 - V_3) \times 2600/2700$
22H	1	0	0	0	1	0	$V_{34}'$	$V_3 + (V_2 - V_3) \times 2500/2700$
23H	1	0	0	0	1	1	$V_{35}'$	$V_3 + (V_2 - V_3) \times 2400/2700$
24H	1	0	0	1	0	0	$V_{36}'$	$V_3 + (V_2 - V_3) \times 2300/2700$
25H	1	0	0	1	0	1	$V_{37}'$	$V_3 + (V_2 - V_3) \times 2200/2700$
26H	1	0	0	1	1	0	$V_{38}'$	$V_3 + (V_2 - V_3) \times 2100/2700$
27H	1	0	0	1	1	1	$V_{39}'$	$V_3 + (V_2 - V_3) \times 2000/2700$
28H	1	0	1	0	0	0	$V_{40}'$	$V_3 + (V_2 - V_3) \times 1900/2700$
29H	1	0	1	0	0	1	$V_{41}'$	$V_3 + (V_2 - V_3) \times 1800/2700$
2AH	1	0	1	0	1	0	$V_{42}'$	$V_3 + (V_2 - V_3) \times 1700/2700$
2BH	1	0	1	0	1	1	$V_{43}'$	$V_3 + (V_2 - V_3) \times 1600/2700$
2CH	1	0	1	1	0	0	$V_{44}'$	$V_3 + (V_2 - V_3) \times 1500/2700$
2DH	1	0	1	1	0	1	$V_{45}'$	$V_3 + (V_2 - V_3) \times 1400/2700$
2EH	1	0	1	1	1	0	$V_{46}'$	$V_3 + (V_2 - V_3) \times 1300/2700$
2FH	1	0	1	1	1	1	$V_{47}'$	$V_3 + (V_2 - V_3) \times 1200/2700$
30H	1	1	0	0	0	0	$V_{48}'$	$V_3 + (V_2 - V_3) \times 1100/2700$
31H	1	1	0	0	0	1	$V_{49}'$	$V_3 + (V_2 - V_3) \times 1000/2700$
32H	1	1	0	0	1	0	$V_{50}'$	$V_3 + (V_2 - V_3) \times 900/2700$
33H	1	1	0	0	1	1	$V_{51}'$	$V_3 + (V_2 - V_3) \times 800/2700$
34H	1	1	0	1	0	0	$V_{52}'$	$V_3 + (V_2 - V_3) \times 700/2700$
35H	1	1	0	1	0	1	$V_{53}'$	$V_3 + (V_2 - V_3) \times 600/2700$
36H	1	1	0	1	1	0	$V_{54}'$	$V_3 + (V_2 - V_3) \times 400/2700$
37H	1	1	0	1	1	1	$V_{55}'$	$V_3 + (V_2 - V_3) \times 200/2700$
38H	1	1	1	0	0	0	$V_{56}'$	$V_3$
39H	1	1	1	0	0	1	$V_{57}'$	$V_4 + (V_3 - V_4) \times 2300/2500$
3AH	1	1	1	0	1	0	$V_{58}'$	$V_4 + (V_3 - V_4) \times 2100/2500$
3BH	1	1	1	0	1	1	$V_{59}'$	$V_4 + (V_3 - V_4) \times 1800/2500$
3CH	1	1	1	1	0	0	$V_{60}'$	$V_4 + (V_3 - V_4) \times 1500/2500$
3DH	1	1	1	1	0	1	$V_{61}'$	$V_4 + (V_3 - V_4) \times 1200/2500$
3EH	1	1	1	1	1	0	$V_{62}'$	$V_4 + (V_3 - V_4) \times 800/2500$
3FH	1	1	1	1	1	1	$V_{63}'$	$V_4$

Caution  $V_4$  and  $V_5$  are interconnected inside the IC by resistors  $r_{4-5}$  (9 kΩ).

Resistor Strings

Figure 2-1. Relationship Between Input Data and Output Voltage:  $V_4 > V_5 > V_6 > V_7 > V_8 > V_9 > V_{SS2}$



Caution V4 and V5 are interconnected inside the IC by resistors r4-5 (9 kΩ).

Ladder Resistance Values (r<sub>0</sub> to r<sub>62</sub>): Reference Value

	Resistor Name	Resistance Value (Ω)	Resistor Name	Resistance Value (Ω)	
V <sub>0</sub> , V <sub>9</sub> →	r <sub>0</sub>	800	r <sub>32</sub>	100	← V <sub>2</sub> , V <sub>7</sub>
	r <sub>1</sub>	800	r <sub>33</sub>	100	
	r <sub>2</sub>	800	r <sub>34</sub>	100	
	r <sub>3</sub>	700	r <sub>35</sub>	100	
	r <sub>4</sub>	700	r <sub>36</sub>	100	
	r <sub>5</sub>	600	r <sub>37</sub>	100	
	r <sub>6</sub>	500	r <sub>38</sub>	100	
V <sub>1</sub> , V <sub>8</sub> →	r <sub>7</sub>	400	r <sub>39</sub>	100	
	r <sub>8</sub>	400	r <sub>40</sub>	100	
	r <sub>9</sub>	300	r <sub>41</sub>	100	
	r <sub>10</sub>	300	r <sub>42</sub>	100	
	r <sub>11</sub>	300	r <sub>43</sub>	100	
	r <sub>12</sub>	300	r <sub>44</sub>	100	
	r <sub>13</sub>	200	r <sub>45</sub>	100	
	r <sub>14</sub>	200	r <sub>46</sub>	100	
	r <sub>15</sub>	200	r <sub>47</sub>	100	
	r <sub>16</sub>	200	r <sub>48</sub>	100	
	r <sub>17</sub>	200	r <sub>49</sub>	100	
	r <sub>18</sub>	100	r <sub>50</sub>	100	
	r <sub>19</sub>	100	r <sub>51</sub>	100	
	r <sub>20</sub>	100	r <sub>52</sub>	100	
	r <sub>21</sub>	100	r <sub>53</sub>	200	
	r <sub>22</sub>	100	r <sub>54</sub>	200	
	r <sub>23</sub>	100	r <sub>55</sub>	200	← V <sub>3</sub> , V <sub>6</sub>
	r <sub>24</sub>	100	r <sub>56</sub>	200	
	r <sub>25</sub>	100	r <sub>57</sub>	200	
	r <sub>26</sub>	100	r <sub>58</sub>	300	
	r <sub>27</sub>	100	r <sub>59</sub>	300	
	r <sub>28</sub>	100	r <sub>60</sub>	300	
	r <sub>29</sub>	100	r <sub>61</sub>	400	
	r <sub>30</sub>	100	r <sub>62</sub>	800	← V <sub>4</sub> , V <sub>5</sub>
V <sub>2</sub> , V <sub>7</sub> →	r <sub>31</sub>	100	Total	14500	

6. RELATIONSHIP BETWEEN INPUT DATA AND OUTPUT PIN

Data format : 6 bits × 2 RGBs (6 dots)

Input width : 36 bits (2-pixel data)

$R/\bar{L} = H$  (Right shift)

Output	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	S <sub>4</sub>	S <sub>5</sub>	...	S <sub>239</sub>	S <sub>240</sub>
Data	D <sub>00</sub> to D <sub>05</sub>	D <sub>10</sub> to D <sub>15</sub>	D <sub>20</sub> to D <sub>25</sub>	D <sub>30</sub> to D <sub>35</sub>	D <sub>40</sub> to D <sub>45</sub>	...	D <sub>40</sub> to D <sub>45</sub>	D <sub>50</sub> to D <sub>55</sub>

$R/\bar{L} = L$  (Left shift)

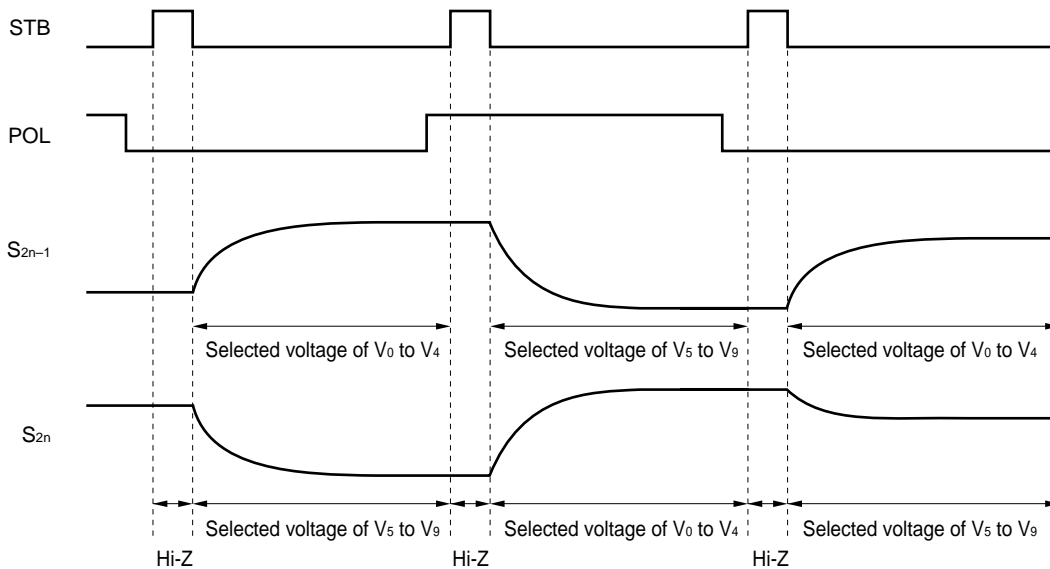
Output	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	S <sub>4</sub>	S <sub>5</sub>	...	S <sub>239</sub>	S <sub>240</sub>
Data	D <sub>00</sub> to D <sub>05</sub>	D <sub>10</sub> to D <sub>15</sub>	D <sub>20</sub> to D <sub>25</sub>	D <sub>30</sub> to D <sub>35</sub>	D <sub>40</sub> to D <sub>45</sub>	...	D <sub>40</sub> to D <sub>45</sub>	D <sub>50</sub> to D <sub>55</sub>

POL	S <sub>2n-1</sub>	S <sub>2n</sub>
L	V <sub>0</sub> to V <sub>4</sub>	V <sub>5</sub> to V <sub>9</sub>
H	V <sub>5</sub> to V <sub>9</sub>	V <sub>0</sub> to V <sub>4</sub>

S<sub>2n-1</sub> (Odd output), S<sub>2n</sub> (Even output) n = 1, 2, ..., 120

7. RELATIONSHIP BETWEEN STB, POL, AND OUTPUT WAVEFORM

The output voltage is written to the LCD panel synchronized with the STB rising edge.



**Absolute Maximum Ratings (T<sub>A</sub> = 25 °C, V<sub>SS1</sub> = V<sub>SS2</sub> = 0 V)**

Parameter	Symbol	Rating	Unit
Logic Part Supply Voltage	V <sub>DD1</sub>	-0.5 to +6.5	V
Driver Part Supply Voltage	V <sub>DD2</sub>	-0.5 to +15.0	V
Logic Part Input Voltage	V <sub>I1</sub>	-0.5 to V <sub>DD1</sub> + 0.5	V
Driver Part Input Voltage	V <sub>I2</sub>	-0.5 to V <sub>DD2</sub> + 0.5	V
Logic Part Output Voltage	V <sub>O1</sub>	-0.5 to V <sub>DD1</sub> + 0.5	V
Driver Part Output Voltage	V <sub>O2</sub>	-0.5 to V <sub>DD2</sub> + 0.5	V
Operating Temperature Range	T <sub>A</sub>	-10 to +75	°C
Storage Temperature Range	T <sub>stg.</sub>	-55 to +125	°C

**Recommended Operating Range (T<sub>A</sub> = -10 to +75 °C, V<sub>SS1</sub> = V<sub>SS2</sub> = 0 V)**

Parameter	Symbol	MIN.	TYP.	MAX.	Unit
Logic Part Supply Voltage	V <sub>DD1</sub>	3.0	3.3	3.6	V
Driver Part Supply Voltage	V <sub>DD2</sub>	11.0	13.0	13.5	V
High-Level Input Voltage	V <sub>IH</sub>	0.8 V <sub>DD1</sub>		V <sub>DD1</sub>	V
Low-Level Input Voltage	V <sub>IL</sub>	0		0.2 V <sub>DD1</sub>	V
γ-Corrected Voltage	V <sub>0</sub> to V <sub>9</sub>	V <sub>SS2</sub> + 0.1		V <sub>DD2</sub> - 0.1	V
Driver Part Output Voltage	V <sub>O</sub>	V <sub>SS2</sub> + 0.2		V <sub>DD2</sub> - 0.2	V
Maximum Clock Frequency	f <sub>max.</sub>	33			MHz

**Electrical Specifications (T<sub>A</sub> = -10 to +75 °C, V<sub>DD1</sub> = 3.3 V ±0.3 V, V<sub>DD2</sub> = 13.0 V ±0.5 V, V<sub>SS1</sub> = V<sub>SS2</sub> = 0 V)**

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input Leak Current	I <sub>L</sub>				±1.0	μA
High-Level Output Voltage	V <sub>OH</sub>	STHR (STHL), I <sub>o</sub> = 0 mA	V <sub>DD1</sub> - 0.1			V
Low-level Output Voltage	V <sub>OL</sub>	STHR (STHL), I <sub>o</sub> = 0 mA			0.1	V
γ-Corrected Supply Current		V <sub>0</sub> - V <sub>9</sub> = 10 V		0.3	0.6	mA
Driver Output Current	I <sub>VOH</sub>	V <sub>X</sub> - V <sub>OUT</sub> = 6 V			-0.3	mA
	I <sub>VOL</sub>	V <sub>X</sub> - V <sub>OUT</sub> = -6 V	0.3			mA

V<sub>X</sub> refers to the output voltage of analog output pins S<sub>1</sub> to S<sub>240</sub>.

V<sub>OUT</sub> refers to the voltage applied to analog output pins S<sub>1</sub> to S<sub>240</sub>.

**Electrical Specifications (T<sub>A</sub> = -10 to +75 °C, V<sub>DD1</sub> = 3.3 V ±0.3 V, V<sub>DD2</sub> = 13.0 V ±0.5 V, V<sub>SS1</sub> = V<sub>SS2</sub> = 0 V)**

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Output Voltage Deviation <sup>Note 1</sup>	ΔV <sub>O</sub>	Input data: 00 <sub>H</sub> to 3F <sub>H</sub>		±5	±20	mV
Average Output Voltage Variation <sup>Note 2</sup>	ΔV <sub>AV</sub>	Input data: 00 <sub>H</sub> to 3F <sub>H</sub>		±10		mV
Output Voltage Range	V <sub>O</sub>	Input data: 00 <sub>H</sub> to 3F <sub>H</sub>	0.2		V <sub>DD2</sub> - 0.2	V
Logic Part Dynamic Current Consumption	I <sub>DD1</sub>	V <sub>DD1</sub> ; when with no load <sup>Notes 3, 4</sup>		1.0	6.0	mA
Driver Part Dynamic Current Consumption	I <sub>DD2</sub>	V <sub>DD2</sub> ; when with no load <sup>Notes 3, 4</sup>		3.5	9.0	mA

- Notes**
1. The output voltage deviation refers to the voltage difference between adjoining output pins when the display data is the same (within the chip).
  2. The average output voltage variation refers to the average output voltage difference between chips. The average output voltage refers to the average voltage between chips when the display data is the same.
  3. The STB cycle is defined to be 30 μs at f<sub>CLK</sub> = 25 MHz. The TYP. values refer to an all black or all white input pattern. The MAX. value refers to the measured values in the dot checkerboard input pattern.
  4. Refers to the current consumption per driver when cascades are connected under the assumption of SVGA single-sided mounting (10 units).

**Switching Characteristics (T<sub>A</sub> = -10 to +75 °C, V<sub>DD1</sub> = 3.3 V ±0.3 V, V<sub>DD2</sub> = 13.0 V ±0.5 V, V<sub>SS1</sub> = V<sub>SS2</sub> = 0 V)**

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Start Pulse Delay Time	t <sub>PLH1</sub>	C <sub>L</sub> = 25 pF		10	15	ns
Driver Output Delay Time 1	t <sub>PHL2</sub>	C <sub>L</sub> = 50 pF, R = 50 kΩ		7	11	μs
Driver Output Delay Time 2	t <sub>PHL3</sub>	C <sub>L</sub> = 50 pF, R = 50 kΩ		13	17	μs
Driver Output Delay Time 3	t <sub>PLH2</sub>	C <sub>L</sub> = 50 pF, R = 50 kΩ		7	11	μs
Driver Output Delay Time 4	t <sub>PLH3</sub>	C <sub>L</sub> = 50 pF, R = 50 kΩ		13	17	μs
Input Capacitance 1	C <sub>1</sub>	STHR, STHL excluded T <sub>A</sub> = 25 °C		5	15	pF
Input Capacitance 2	C <sub>2</sub>	STHR, STHL T <sub>A</sub> = 25 °C		5	15	pF

**Conditions Required for Timing**

( $T_A = -10$  to  $+75$  °C,  $V_{DD1} = 3.3$  V  $\pm 0.3$  V,  $V_{SS1} = V_{SS2} = 0$  V,  $t_r = t_f = 8.0$  ns)

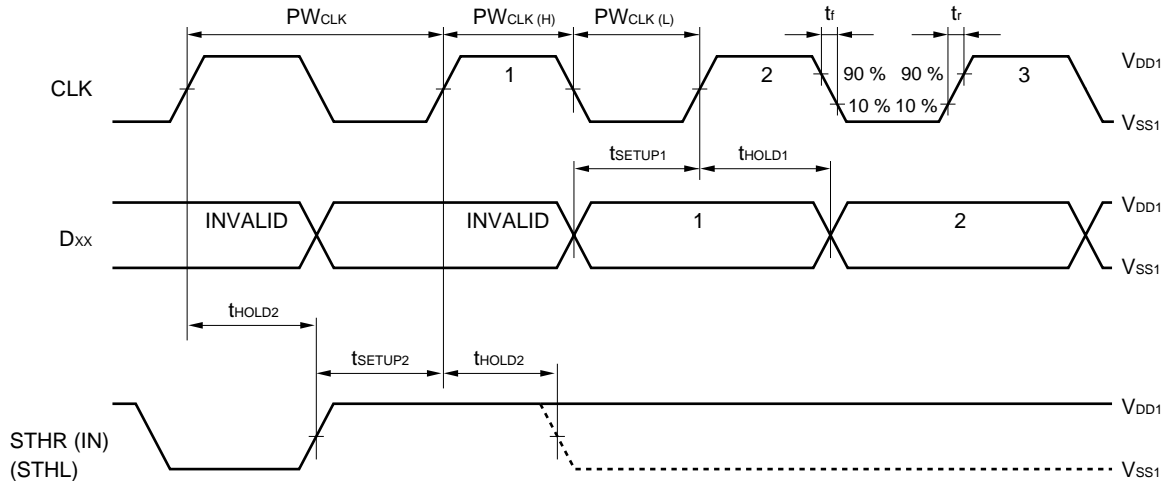
Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Clock Pulse Width	PW <sub>CLK</sub>		30			ns
Clock Pulse Low Period	PW <sub>CLK(L)</sub>		6			ns
Clock Pulse High Period	PW <sub>CLK(H)</sub>		6			ns
Data Setup Time	t <sub>SETUP1</sub>		6			ns
Data Hold Time	t <sub>HOLD1</sub>		6			ns
Start Pulse Setup Time	t <sub>SETUP2</sub>		6			ns
Start Pulse Hold Time	t <sub>HOLD2</sub>		6			ns
Start Pulse Low Period	t <sub>SPL</sub>		6			ns
STB Pulse Width	PW <sub>STB</sub>		1			μs
Data Invalid Period	t <sub>INV</sub>		1			CLK
Final Data Timing	t <sub>LDT</sub>		2			CLK
CLK-STB Time	t <sub>CLK-STB</sub>	CLK ↑ → STB ↓	6			ns
STB-CLK Time	t <sub>STB-CLK</sub>	STB ↓ → CLK ↑	6			ns
Time Between STB and Start Pulse	t <sub>STB-STH</sub>	STB ↓ → STHR ↑	60			ns
POL-STB Time	t <sub>POL-STB</sub>	POL ↑ or ↓ → STB ↑	-5			ns
STB-POL Time	t <sub>STB-POL</sub>	STB ↓ → POL ↑ or ↓	6			ns

**Switching Characteristics Waveform (R/L = H)**

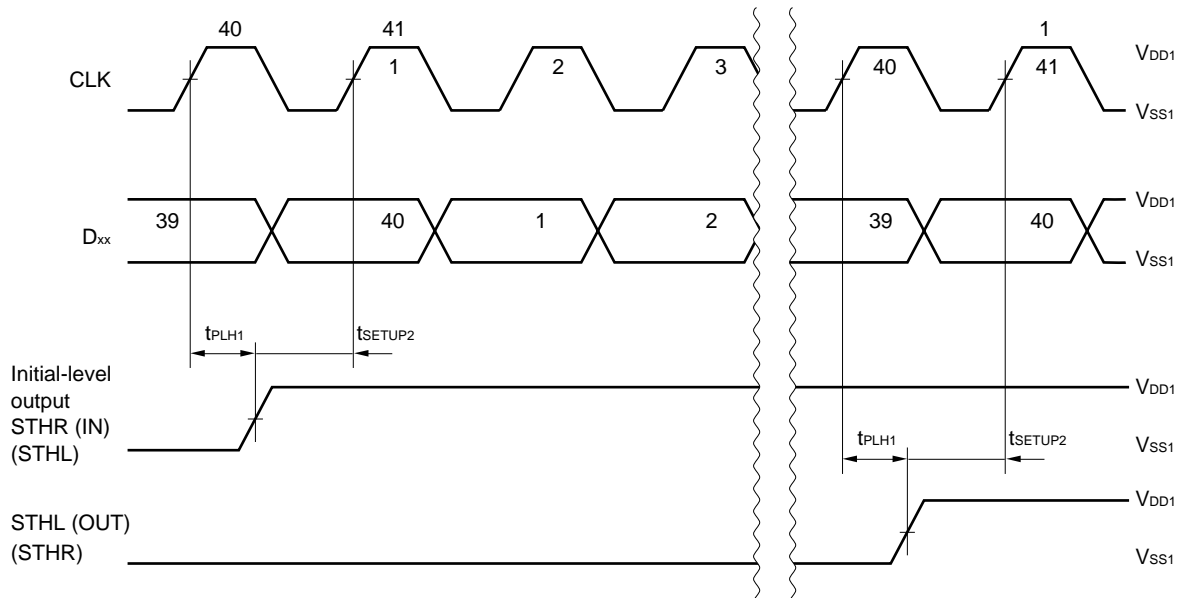
In ( ): R/L = L

Unless otherwise specified, the input level is defined to be 0.5 V<sub>DD1</sub>.

**(1) Initial-Level Driver's Input/Output Waveform**

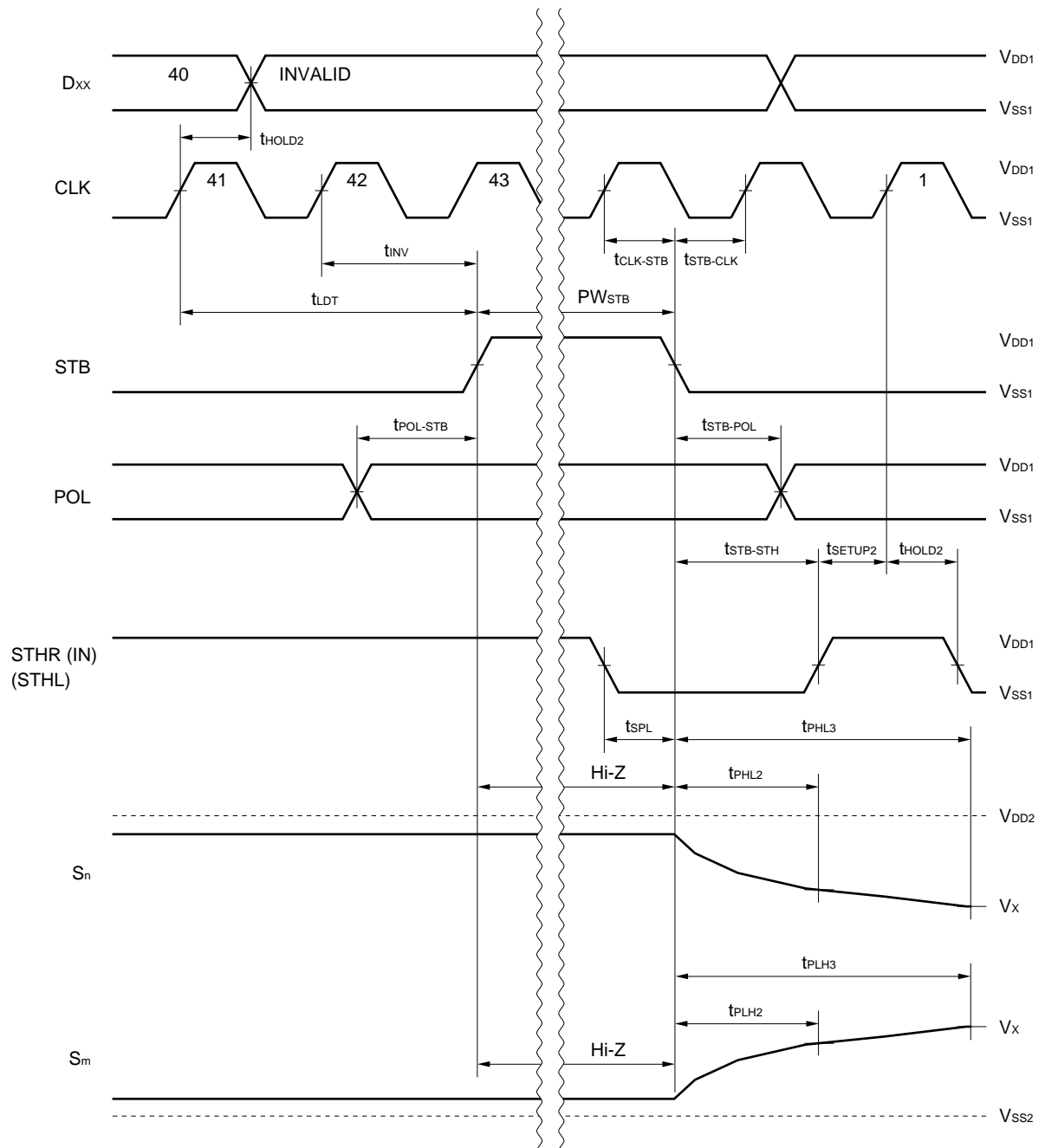


**(2) Second- to Final-Level Drivers's Input/Output Timing**





(3) Driver Output Timing



$V_x$  refers to the final output voltage.  $t_{PLH2}$  and  $t_{PHL2}$  refer to the time required to reach an output precision level of 10 % ( $0.1 V_x$ ); and  $t_{PLH3}$  and  $t_{PHL3}$  refer to the time required to reach an output precision level of 6 bits.

**RECOMMENDED CONDITIONS FOR INSTALLATION**

This product should be installed under the following recommended conditions. Consult one of our sales representatives for installation under conditions other than those recommended.

Installation condition	Installation method	Condition
Thermocompression bonding	Soldering	Heat with heating tool at 300 °C to 350 °C under pressure of 100 g (per pin) for 2 to 3 seconds
	ACF (sheet-type adhesive agent)	Temporary adhesion at 70 °C to 100 °C under pressure of 3 to 8 kg/cm <sup>2</sup> for 3 to 5 seconds Permanent adhesion at 165 °C to 180 °C under pressure of 25 to 45 kg/cm <sup>2</sup> for 30 to 40 seconds (when aeolotropic conductive film SUMIZAC1003 from Sumitomo Bakelite Co., Ltd. is used)

**Caution** For installation conditions for the ACF part, contact the ACF manufacturer beforehand. Do not mix different installation methods.

**REFERENCE**

Document name	Document No.
NEC semiconductor device reliability/quality control system	IEI-1212
Quality grade on NEC semiconductor devices	C11531E
Semiconductor device package manual	IEI-1213
Guide to quality assurance for semiconductor devices	MEI-1202
Semiconductor selection guide	X10679E

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Specific: Aircrafts, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems or medical equipment for life support, etc.

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