

To our customers,

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## Old Company Name in Catalogs and Other Documents

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April 1<sup>st</sup>, 2010  
Renesas Electronics Corporation

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## 240 OUTPUT TFT-LCD SOURCE DRIVER (COMPATIBLE WITH 64 GRAY SCALE)

The  $\mu$ PD16631A is source driver for TFT-LCDs capable of dealing with display with 64 gray ascale. Data input is based on digital input configured as 6-bits by 6 dots, which can realize a full-color display of 260,000 colors by output of 64 values  $\gamma$ corrected by an internal D/A converter and 5-by-2 external power modules.

Because the output dynamic range is as large as 10 V<sub>P-P</sub>, level inversion operation of the LCD's common electrode is rendered unnecessary. Also, to be able to deal with dot-line inversion when mounted on a single side, this source driver is equipped with a built-in 6-bit D/A converter circuit whose odd output pins and even output pins respectively output gradation voltages of differing polarity. Assuring a maximum clock frequency of 33 MHz when driving 3 V, this driver is applicable to VGA-standard TFT-LCD panels.

### FEATURES

- Capable of outputting 64 values by means of 5-by-2 external power modules (10 units) and a D/A converter
- Output dynamic range 11.5 V<sub>P-P</sub> max. (when V<sub>DD2</sub> = 13.5 V)
- CMOS level input
- Input of 6 bits (gradation data) by 6 dots
- High-speed data transfer: f<sub>max</sub> = 33 MHz (internal data transfer speed when operating at 3.0 V)
- 240 outputs
- Single bank arrangement possible (loaded with slim TCP)

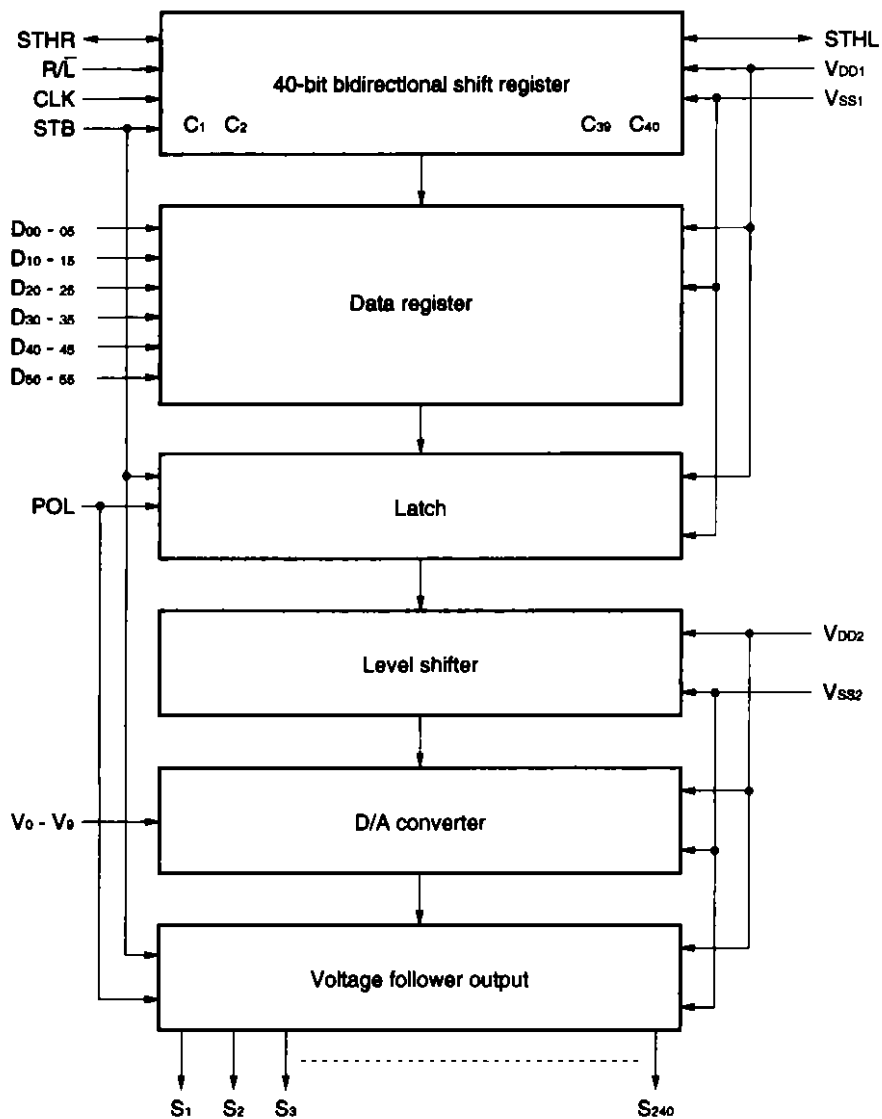
### ORDERING INFORMATION

Part Number	Package
$\mu$ PD16631AN-xxx	TCP (TAB package)

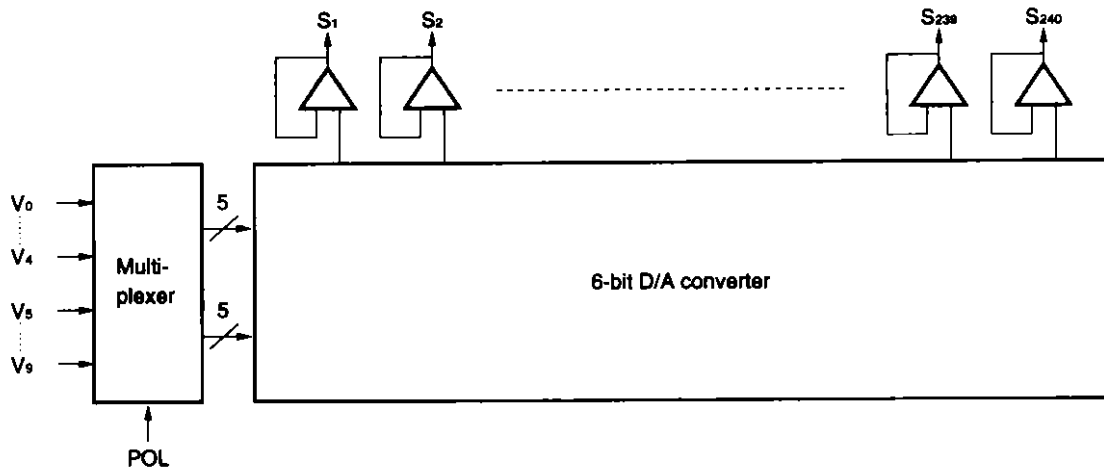
The TCP's external shape is customized. To order your TCP's external shape, please contact a NEC salesperson.

The information contained in this document is being issued in advance of the production cycle for the device. The parameters for the device may change before final production or NEC Corporation, at its own discretion, may withdraw the device prior to its production.

1. BLOCK DIAGRAM



2. RELATIONSHIP BETWEEN OUTPUT CIRCUIT AND D/A CONVERTER



POL	$S_{2n-1}$	$S_{2n}$
L	$V_0$ to $V_4$	$V_8$ to $V_9$
H	$V_8$ to $V_9$	$V_0$ to $V_4$

$S_{2n-1}$  (odd output),  $S_{2n}$  (even output)  $n = 1, 2, \dots, 120$

3. PIN FUNCTIONS

Pin Symbol	Pin Name	Description
S <sub>1</sub> to S <sub>240</sub>	Driver output	The analog voltage of the D/A-converted 64 gray-scale is output.
D <sub>00</sub> to D <sub>05</sub>	Display data input	The display data is input with a width of 36 bits, viz., the gradation data (6 bits) by 6 dots (RGB). D <sub>x0</sub> : LSB, D <sub>x5</sub> : MSB
D <sub>10</sub> to D <sub>15</sub>		
D <sub>20</sub> to D <sub>25</sub>		
D <sub>20</sub> to D <sub>25</sub>		
D <sub>20</sub> to D <sub>25</sub>		
D <sub>20</sub> to D <sub>25</sub>		
R/L	Shift direction switching input	These refer to the start pulse input/output pins when cascades are connected. The shift directions of the shift registers are as follows. R/L = H: STHR input, S <sub>1</sub> → S <sub>240</sub> , STHL output R/L = L: STHL input, S <sub>240</sub> → S <sub>1</sub> , STHR output
STHR	Right shift start pulse input/output	R/L = H: Becomes the start pulse input pin. R/L = L: Becomes the start pulse output pin.
STHL	Left shift start pulse input/output	R/L = H: Becomes the start pulse output pin. R/L = L: Becomes the start pulse input pin.
CLK	Shift clock input	Refers to the shift register's shift clock input. The display data is incorporated into the data register at the rising edge. At the rising edge of the 40th clock after the start pulse input, the start pulse output reaches the high level, thus becoming the start pulse of the next-level driver. The initial-level driver's 40th clock becomes valid as the next-level driver's start pulse is input. If 42 clock pulses are input after input of the start pulse, input of display data is halted automatically. The contents of the shift register are cleared at the STB's rising edge.
STB	Latch input	The contents of the data register are transferred to the latch at the rising edge. And, at the trailing edge, the gradation voltage is supplied to the driver. It is necessary to ensure input of one pulse per horizontal period.
POL	Polarity input	POL = L: The S <sub>2n-1</sub> output uses V <sub>0</sub> to V <sub>4</sub> as the reference supply; and the S <sub>2n</sub> output uses V <sub>5</sub> to V <sub>9</sub> as the reference supply. POL = H: The S <sub>2n-1</sub> output uses V <sub>5</sub> to V <sub>9</sub> as the reference supply; and the S <sub>2n</sub> output uses V <sub>0</sub> to V <sub>4</sub> as the reference supply. S <sub>2n-1</sub> indicates the odd output; and S <sub>2n</sub> indicates the even output. Input of the POL signal is allowed the setup time (t <sub>POL-STB</sub> ) with respect to STB's rising edge.
V <sub>0</sub> to V <sub>9</sub>	γcorrected power supplies	Input the γcorrected power supplies from outside. The γcorrected power supplies can not be applied by inverting their levels. Make sure to maintain the following relationships. During the gray scale voltage output, be sure to keep the gray scale power supply at a constant level. V <sub>DD2</sub> > V <sub>0</sub> > V <sub>1</sub> > V <sub>2</sub> > V <sub>3</sub> > V <sub>4</sub> > V <sub>5</sub> > V <sub>6</sub> > V <sub>7</sub> > V <sub>8</sub> > V <sub>9</sub> > V <sub>SS2</sub>
TEST	Test pin	Set it to open condition.
V <sub>DD1</sub>	Logic power supply	+2.2 3.3 V -0.3 V
V <sub>DD2</sub>	Driver power supply	+0.5 13.0 V -2.0 V
V <sub>SS1</sub>	Logic ground	Connect to the system ground.
V <sub>SS2</sub>	Driver ground	Connect to the system ground.

- Cautions**
1. The power start sequence must be V<sub>DD1</sub>, logic input, and V<sub>DD2</sub> & V<sub>0</sub> to V<sub>9</sub> in that order. Reverse this sequence to shut down.
  2. To stabilize the supply voltage, please be sure to insert a 0.1 μF bypass capacitor between V<sub>DD1</sub>-V<sub>SS1</sub> and V<sub>DD2</sub>-V<sub>SS2</sub>. Furthermore, for increased precision of the D/A converter, insertion of a bypass capacitor of about 0.1 μF is also advised between the γcorrected power supply terminals (V<sub>0</sub>, V<sub>1</sub>, V<sub>2</sub>, ..., V<sub>9</sub>) and V<sub>SS</sub>.

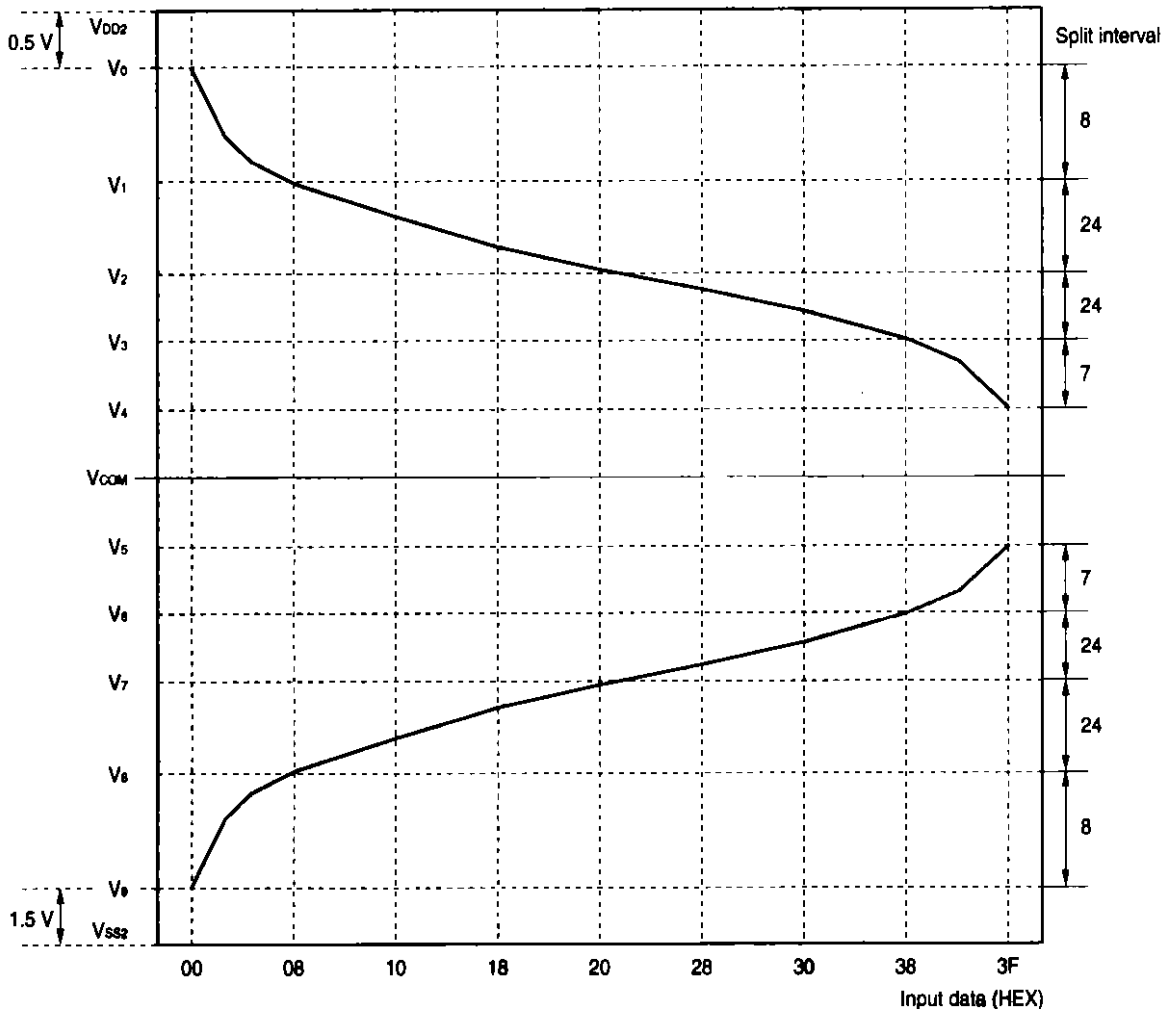
#### 4. RELATIONSHIP BETWEEN INPUT DATA AND OUTPUT VOLTAGE VALUE

This product incorporates a 6-bit D/A converter whose odd output pins and even output pins output respectively gray scale voltages of differing polarity with respect to the LCD's counter electrode (common electrode) voltage. The D/A converter consists of ladder resistors and switches. The ladder resistors  $r_0$  to  $r_{62}$  are so designed that the ratios between the LCD panel's  $\gamma$ -corrected voltages and  $V_0'$  to  $V_{63}'$  and  $V_0''$  to  $V_{63}''$  are roughly equal; and their respective resistance values are as shown on page 8. Among the 5-by-2  $\gamma$ -corrected voltages, please input gray scale voltages of the same polarity with respect to the common voltage, for the respective five  $\gamma$ -corrected voltages of  $V_0$  to  $V_4$  and  $V_5$  to  $V_9$ . If fine gray scale voltage precision is not necessary, the voltage follower circuit supplied to the  $\gamma$ -corrected power supplies  $V_1$  to  $V_3$  and  $V_6$  to  $V_8$  can be deleted.

Figure 1 shows the relationship between the driving voltages such as liquid-crystal driving voltages  $V_{DD2}$  and  $V_{SS2}$ , common electrode potential  $V_{COM}$ , and  $\gamma$ -corrected voltages  $V_0$  to  $V_9$  and the input data. Here, the voltage relationships have necessity to be set as  $V_{DD2} > V_0 > V_1 > V_2 > V_3 > V_4 > V_5 > V_6 > V_7 > V_8 > V_9 > V_{SS2}$ . Figures 2-1 and 2-2 show the relationship between the input data and the output data. Table 1 shows the resistance values of the resistor strings.

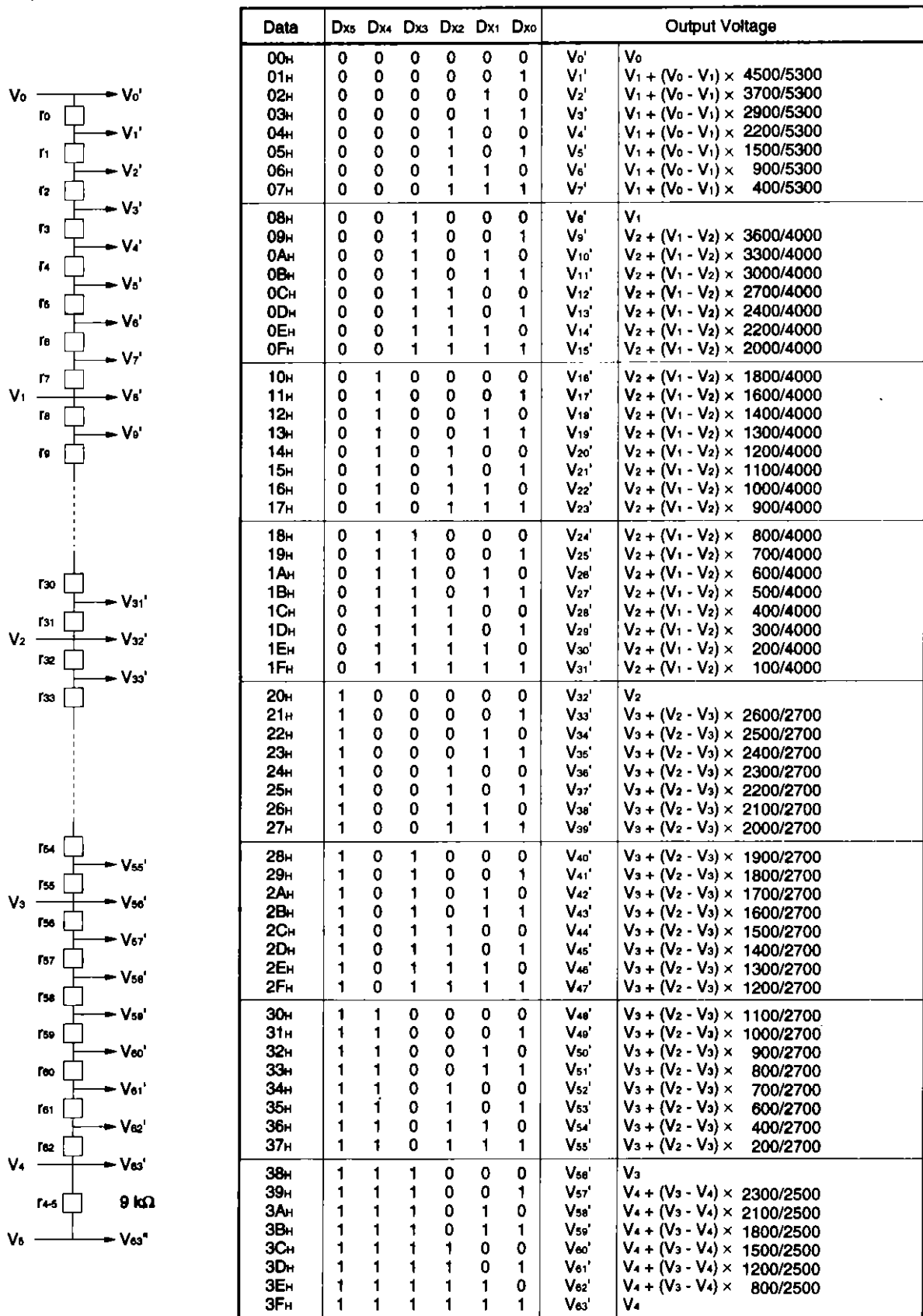
This driver IC is designed for single bank arrangement. Therefore, be sure not to use it for dual bank arrangement. The bias current flowing through ladder resistors  $r_0$  to  $r_{62}$  is so small that its use for dual bank arrangement impairs the IC's stable operation and causes display failures when the level of the  $\gamma$ -corrected power supply terminal is inverted.

Figure 1. Relationship Between Input Data and Output Voltage



Resistor Strings

Figure 2-1. Relationship Between Input Data and Output Voltage:  $V_{DD2} > V_0 > V_1 > V_2 > V_3 > V_4 > V_5$

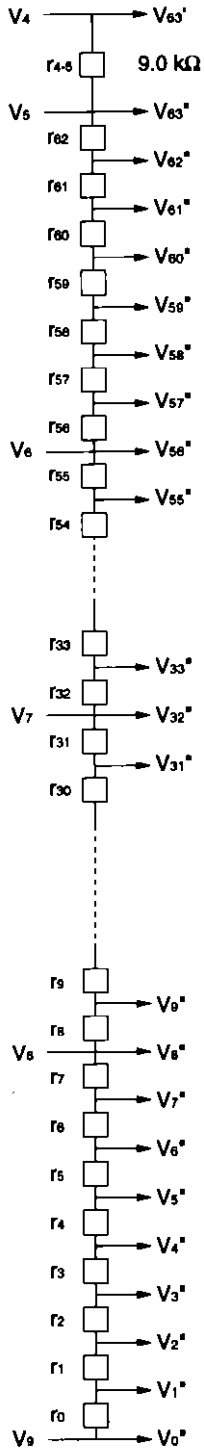


Caution  $V_4$  and  $V_5$  are interconnected inside the IC by resistors  $r_{4-5}$  (9.0 kΩ).



Resistor Strings

Figure 2-2. Relationship Between Input Data and Output Voltage:  $V_4 > V_5 > V_6 > V_7 > V_8 > V_9 > V_{SS2}$



Data	Dx5	Dx4	Dx3	Dx2	Dx1	Dx0	Output Voltage	
00H	0	0	0	0	0	0	$V_0''$	$V_9$
01H	0	0	0	0	0	1	$V_1''$	$V_9 + (V_8 - V_9) \times 800/5300$
02H	0	0	0	0	1	0	$V_2''$	$V_9 + (V_8 - V_9) \times 1600/5300$
03H	0	0	0	0	1	1	$V_3''$	$V_9 + (V_8 - V_9) \times 2400/5300$
04H	0	0	0	1	0	0	$V_4''$	$V_9 + (V_8 - V_9) \times 3100/5300$
05H	0	0	0	1	0	1	$V_5''$	$V_9 + (V_8 - V_9) \times 3800/5300$
06H	0	0	0	1	1	0	$V_6''$	$V_9 + (V_8 - V_9) \times 4400/5300$
07H	0	0	0	1	1	1	$V_7''$	$V_9 + (V_8 - V_9) \times 4900/5300$
08H	0	0	1	0	0	0	$V_8''$	$V_8$
09H	0	0	1	0	0	1	$V_9''$	$V_8 + (V_7 - V_8) \times 400/4000$
0AH	0	0	1	0	1	0	$V_{10}''$	$V_8 + (V_7 - V_8) \times 700/4000$
0BH	0	0	1	0	1	1	$V_{11}''$	$V_8 + (V_7 - V_8) \times 1000/4000$
0CH	0	0	1	1	0	0	$V_{12}''$	$V_8 + (V_7 - V_8) \times 1300/4000$
0DH	0	0	1	1	0	1	$V_{13}''$	$V_8 + (V_7 - V_8) \times 1600/4000$
0EH	0	0	1	1	1	0	$V_{14}''$	$V_8 + (V_7 - V_8) \times 1800/4000$
0FH	0	0	1	1	1	1	$V_{15}''$	$V_8 + (V_7 - V_8) \times 2000/4000$
10H	0	1	0	0	0	0	$V_{16}''$	$V_8 + (V_7 - V_8) \times 2200/4000$
11H	0	1	0	0	0	1	$V_{17}''$	$V_8 + (V_7 - V_8) \times 2400/4000$
12H	0	1	0	0	1	0	$V_{18}''$	$V_8 + (V_7 - V_8) \times 2600/4000$
13H	0	1	0	0	1	1	$V_{19}''$	$V_8 + (V_7 - V_8) \times 2700/4000$
14H	0	1	0	1	0	0	$V_{20}''$	$V_8 + (V_7 - V_8) \times 2800/4000$
15H	0	1	0	1	0	1	$V_{21}''$	$V_8 + (V_7 - V_8) \times 2900/4000$
16H	0	1	0	1	1	0	$V_{22}''$	$V_8 + (V_7 - V_8) \times 3000/4000$
17H	0	1	0	1	1	1	$V_{23}''$	$V_8 + (V_7 - V_8) \times 3100/4000$
18H	0	1	1	0	0	0	$V_{24}''$	$V_8 + (V_7 - V_8) \times 3200/4000$
19H	0	1	1	0	0	1	$V_{25}''$	$V_8 + (V_7 - V_8) \times 3300/4000$
1AH	0	1	1	0	1	0	$V_{26}''$	$V_8 + (V_7 - V_8) \times 3400/4000$
1BH	0	1	1	0	1	1	$V_{27}''$	$V_8 + (V_7 - V_8) \times 3500/4000$
1CH	0	1	1	1	0	0	$V_{28}''$	$V_8 + (V_7 - V_8) \times 3600/4000$
1DH	0	1	1	1	0	1	$V_{29}''$	$V_8 + (V_7 - V_8) \times 3700/4000$
1EH	0	1	1	1	1	0	$V_{30}''$	$V_8 + (V_7 - V_8) \times 3800/4000$
1FH	0	1	1	1	1	1	$V_{31}''$	$V_8 + (V_7 - V_8) \times 3900/4000$
20H	1	0	0	0	0	0	$V_{32}''$	$V_7$
21H	1	0	0	0	0	1	$V_{33}''$	$V_7 + (V_6 - V_7) \times 100/2700$
22H	1	0	0	0	1	0	$V_{34}''$	$V_7 + (V_6 - V_7) \times 200/2700$
23H	1	0	0	0	1	1	$V_{35}''$	$V_7 + (V_6 - V_7) \times 300/2700$
24H	1	0	0	1	0	0	$V_{36}''$	$V_7 + (V_6 - V_7) \times 400/2700$
25H	1	0	0	1	0	1	$V_{37}''$	$V_7 + (V_6 - V_7) \times 500/2700$
26H	1	0	0	1	1	0	$V_{38}''$	$V_7 + (V_6 - V_7) \times 600/2700$
27H	1	0	0	1	1	1	$V_{39}''$	$V_7 + (V_6 - V_7) \times 700/2700$
28H	1	0	1	0	0	0	$V_{40}''$	$V_7 + (V_6 - V_7) \times 800/2700$
29H	1	0	1	0	0	1	$V_{41}''$	$V_7 + (V_6 - V_7) \times 900/2700$
2AH	1	0	1	0	1	0	$V_{42}''$	$V_7 + (V_6 - V_7) \times 1000/2700$
2BH	1	0	1	0	1	1	$V_{43}''$	$V_7 + (V_6 - V_7) \times 1100/2700$
2CH	1	0	1	1	0	0	$V_{44}''$	$V_7 + (V_6 - V_7) \times 1200/2700$
2DH	1	0	1	1	0	1	$V_{45}''$	$V_7 + (V_6 - V_7) \times 1300/2700$
2EH	1	0	1	1	1	0	$V_{46}''$	$V_7 + (V_6 - V_7) \times 1400/2700$
2FH	1	0	1	1	1	1	$V_{47}''$	$V_7 + (V_6 - V_7) \times 1500/2700$
30H	1	1	0	0	0	0	$V_{48}''$	$V_7 + (V_6 - V_7) \times 1600/2700$
31H	1	1	0	0	0	1	$V_{49}''$	$V_7 + (V_6 - V_7) \times 1700/2700$
32H	1	1	0	0	1	0	$V_{50}''$	$V_7 + (V_6 - V_7) \times 1800/2700$
33H	1	1	0	0	1	1	$V_{51}''$	$V_7 + (V_6 - V_7) \times 1900/2700$
34H	1	1	0	1	0	0	$V_{52}''$	$V_7 + (V_6 - V_7) \times 2000/2700$
35H	1	1	0	1	0	1	$V_{53}''$	$V_7 + (V_6 - V_7) \times 2100/2700$
36H	1	1	0	1	1	0	$V_{54}''$	$V_7 + (V_6 - V_7) \times 2300/2700$
37H	1	1	0	1	1	1	$V_{55}''$	$V_7 + (V_6 - V_7) \times 2500/2700$
38H	1	1	1	0	0	0	$V_{56}''$	$V_6$
39H	1	1	1	0	0	1	$V_{57}''$	$V_6 + (V_5 - V_6) \times 200/2500$
3AH	1	1	1	0	1	0	$V_{58}''$	$V_6 + (V_5 - V_6) \times 400/2500$
3BH	1	1	1	0	1	1	$V_{59}''$	$V_6 + (V_5 - V_6) \times 700/2500$
3CH	1	1	1	1	0	0	$V_{60}''$	$V_6 + (V_5 - V_6) \times 1000/2500$
3DH	1	1	1	1	0	1	$V_{61}''$	$V_6 + (V_5 - V_6) \times 1300/2500$
3EH	1	1	1	1	1	0	$V_{62}''$	$V_6 + (V_5 - V_6) \times 1700/2500$
3FH	1	1	1	1	1	1	$V_{63}''$	$V_5$

Caution  $V_4$  and  $V_5$  are interconnected inside the IC by resistors r4-5 (9.0 kΩ).

LADDER RESISTANCE VALUES (r0 to r62)

	Resistor Name	Resistance Value (Ω)	Resistor Name	Resistance Value (Ω)	
V <sub>0</sub> , V <sub>6</sub> →	r <sub>0</sub>	800	r <sub>32</sub>	100	← V <sub>2</sub> , V <sub>7</sub>
	r <sub>1</sub>	800	r <sub>33</sub>	100	
	r <sub>2</sub>	800	r <sub>34</sub>	100	
	r <sub>3</sub>	700	r <sub>35</sub>	100	
	r <sub>4</sub>	700	r <sub>36</sub>	100	
	r <sub>5</sub>	600	r <sub>37</sub>	100	
	r <sub>6</sub>	500	r <sub>38</sub>	100	
V <sub>2</sub> , V <sub>6</sub> →	r <sub>7</sub>	400	r <sub>39</sub>	100	
	r <sub>8</sub>	400	r <sub>40</sub>	100	
	r <sub>9</sub>	300	r <sub>41</sub>	100	
	r <sub>10</sub>	300	r <sub>42</sub>	100	
	r <sub>11</sub>	300	r <sub>43</sub>	100	
	r <sub>12</sub>	300	r <sub>44</sub>	100	
	r <sub>13</sub>	200	r <sub>45</sub>	100	
	r <sub>14</sub>	200	r <sub>46</sub>	100	
	r <sub>15</sub>	200	r <sub>47</sub>	100	
	r <sub>16</sub>	200	r <sub>48</sub>	100	
	r <sub>17</sub>	200	r <sub>49</sub>	100	
	r <sub>18</sub>	100	r <sub>50</sub>	100	
	r <sub>19</sub>	100	r <sub>51</sub>	100	
	r <sub>20</sub>	100	r <sub>52</sub>	100	
	r <sub>21</sub>	100	r <sub>53</sub>	200	
	r <sub>22</sub>	100	r <sub>54</sub>	200	
	r <sub>23</sub>	100	r <sub>55</sub>	200	← V <sub>3</sub> , V <sub>6</sub>
	r <sub>24</sub>	100	r <sub>56</sub>	200	
	r <sub>25</sub>	100	r <sub>57</sub>	200	
	r <sub>26</sub>	100	r <sub>58</sub>	300	
	r <sub>27</sub>	100	r <sub>59</sub>	300	
	r <sub>28</sub>	100	r <sub>60</sub>	300	
	r <sub>29</sub>	100	r <sub>61</sub>	400	
	r <sub>30</sub>	100	r <sub>62</sub>	800	← V <sub>4</sub> , V <sub>5</sub>
V <sub>2</sub> , V <sub>7</sub> →	r <sub>31</sub>	100	Total	14500	

5. RELATIONSHIP BETWEEN INPUT DATA AND OUTPUT PIN

Data format : 1-pixel data (6 blits) by RGB (6 dots)

Input width : 36 blits

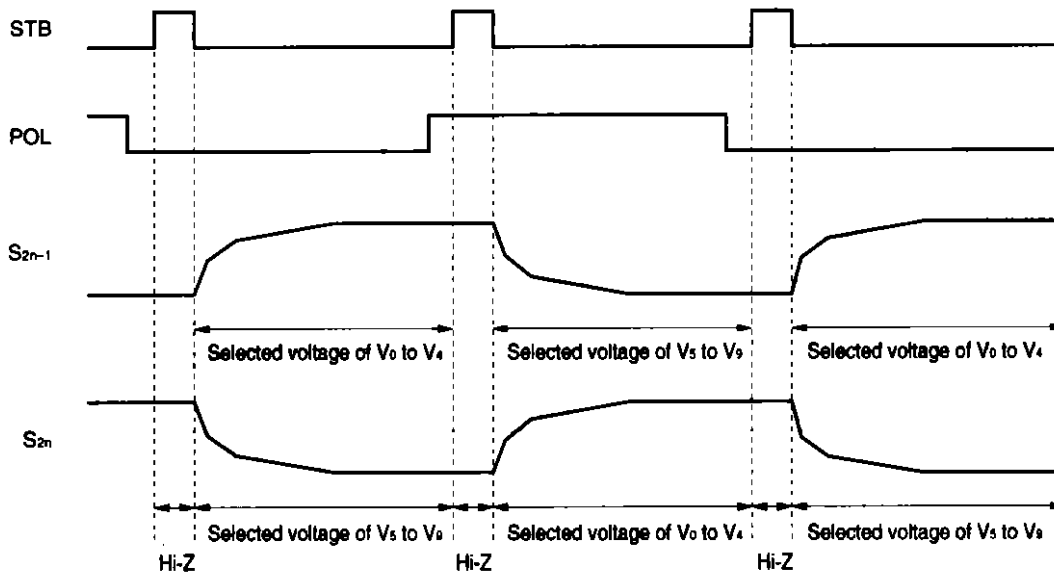
$R/\bar{L} = H$  (Right shift)

Output	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	...	S <sub>239</sub>	S <sub>240</sub>
Data	D <sub>00</sub> to D <sub>05</sub>	D <sub>10</sub> to D <sub>15</sub>	D <sub>20</sub> to D <sub>25</sub>	...	D <sub>40</sub> to D <sub>45</sub>	D <sub>05</sub> to D <sub>55</sub>

$R/\bar{L} = L$  (Left shift)

Output	S <sub>1</sub>	S <sub>2</sub>	S <sub>3</sub>	...	S <sub>239</sub>	S <sub>240</sub>
Data	D <sub>00</sub> to D <sub>05</sub>	D <sub>10</sub> to D <sub>15</sub>	D <sub>20</sub> to D <sub>25</sub>	...	D <sub>40</sub> to D <sub>45</sub>	D <sub>05</sub> to D <sub>55</sub>

Relationship Between STB, POL, and Output Waveform



POL	S <sub>2nD1</sub>	S <sub>2n</sub>
L	V <sub>0</sub> to V <sub>4</sub>	V <sub>5</sub> to V <sub>9</sub>
H	V <sub>5</sub> to V <sub>9</sub>	V <sub>0</sub> to V <sub>4</sub>

S<sub>2nD1</sub> (Odd output), S<sub>2n</sub> (Even output) n = 1, 2, ..., 120

**Absolute Maximum Ratings (TA = 25 °C, Vss1 = Vss2 = 0 V)**

Parameter	Symbol	Rating	Unit
Logic Part Supply Voltage	VDD1	-0.5 to +6.5	V
Driver Part Supply Voltage	VDD2	-0.5 to +15.0	V
-Logic Part Input Voltage	VI1	-0.5 to VDD1 + 0.5	V
Driver Part Input Voltage	VI2	-0.5 to VDD2 + 0.5	V
Logic Part Output Voltage	VO1	-0.5 to VDD1 + 0.5	V
Driver Part Output Voltage	VO2	-0.5 to VDD2 + 0.5	V
Allowable Dissipation	PD	150	mW
Operating Temperature	TA	-10 to +75	°C
Storage Temperature	Tstg.	-55 to +125	°C

**Recommended Operating Range (TA = -10 to +75 °C, Vss1 = Vss2 = 0 V)**

Parameter	Symbol	MIN.	TYP.	MAX.	Unit
Logic Part Supply Voltage	VDD1	3.0	3.3	5.5	V
Driver Part Supply Voltage	VDD2	11.0	13.0	13.5	V
High-Level Output Voltage	VIH	0.8 VDD1		VDD1	V
Low-Level Output Voltage	VIL	0		0.2 VDD1	V
γCorrected Voltage	Vo to V9	VSS2 + 1.5		VDD2 - 0.5	V
Driver Part Output Voltage	Vo	VSS2 + 1.5		VDD2 - 0.5	V
Maximum Clock Frequency	fmax.	33			MHz

**Electrical Specifications (TA = -10 to +75 °C, VDD1 = 3.3 V  $\begin{matrix} +2.2\text{ V} \\ -0.3\text{ V} \end{matrix}$ , VDD2 = 13.0 V  $\begin{matrix} +0.5\text{ V} \\ -0.2\text{ V} \end{matrix}$ , Vss1 = Vss2 = 0 V)**

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Input Leak Current	IL		-1.0		1.0	μA
High-Level Output Voltage	VOH	STHR (STHL), Io = 0 mA	VDD1 - 0.1			V
Low-Level Output Voltage	VOL	STHR (STHL), Io = 0 mA			0.1	V
γCorrected Supply Current		Vo - V9 = 10 V			0.6	mA
Driver Output Current	Ivoh	Vx - VOUT = 6 V			- 0.1	mA
	Ivol	Vx - VOUT = 6 V	0.1			mA

Vx refers to the output voltage of analog output pins S1 to S240.

VOUT refers to the voltage applied to analog output pins S1 to S240.

**Electrical Specifications** ( $T_A = -10$  to  $+75$  °C,  $V_{DD1} = 3.3$  V  $\begin{matrix} +2.2 \text{ V} \\ -0.3 \text{ V} \end{matrix}$ ,  $V_{DD2} = 13.0$  V  $\begin{matrix} +0.5 \text{ V} \\ -0.2 \text{ V} \end{matrix}$ ,  $V_{SS1} = V_{SS2} = 0$  V)

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Output Voltage Deviation <sup>Note 1</sup>	$\Delta V_o$	Input data: 00 <sub>H</sub> to 3F <sub>H</sub>			±20	mV
Mean Output Voltage Variation <sup>Note 2</sup>	$\Delta V_{AV}$	Input data: 00 <sub>H</sub> to 3F <sub>H</sub>		±10		mV
Output Voltage Range	$V_o$	Input data: 00 <sub>H</sub> to 3F <sub>H</sub>	1.5		$V_{DD2} - 0.5$	V
Logic Part Dynamic Current Consumption	$I_{DD1}$	$V_{DD1}$ ; when with no load <sup>Note 3, 4</sup>	3.3 V	0.4	12.0	mA
Driver Part Dynamic Current Consumption	$I_{DD2}$	$V_{DD2}$ ; when with no load <sup>Note 3, 4</sup>		2.0	9.2	mA
Logic Part Static Current Consumption	$I_{DD3}$	$V_{DD1}$			10	μA
Driver Part Static Current Consumption	$I_{DD4}$	$V_{DD2}$		1.5	5.0	mA

- Notes**
- The output voltage deviation refers to the voltage difference between adjoining output pins when the display data is the same (within the chip).
  - The mean output voltage variation refers to the mean output voltage difference between chips. The mean output voltage refers to the mean voltage between chips when the display data is the same.
  - The STB cycle is defined to be 30 μs at  $f_{CLK} = 25$  MHz.  
The TYP. values refer to an all black or all white input pattern.  
The MAX. value refers to the measured values in the dot checkerboard input pattern.
  - Refers to the current consumption per driver when cascades are connected under the assumption of VGA single-sided mounting (8 units).

**Switching Characteristics** ( $T_A = -10$  to  $+75$  °C,  $V_{DD1} = 3.3$  V  $\begin{matrix} +2.2 \text{ V} \\ -0.3 \text{ V} \end{matrix}$ ,  $V_{DD2} = 13.0$  V  $\begin{matrix} +0.5 \text{ V} \\ -0.2 \text{ V} \end{matrix}$ ,  $V_{SS1} = V_{SS2} = 0$  V)

Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Start Pulse Delay Time	$t_{PLH1}$	$C_L = 25$ pF			15	ns
Driver Output Delay Time 1	$t_{PHL2}$	$C_L = 50$ pF, $R = 50$ kΩ			11	μs
Driver Output Delay Time 2	$t_{PHL3}$	$C_L = 50$ pF, $R = 50$ kΩ			17	μs
Driver Output Delay Time 3	$t_{PLH2}$	$C_L = 50$ pF, $R = 50$ kΩ			11	μs
Driver Output Delay Time 4	$t_{PLH3}$	$C_L = 50$ pF, $R = 50$ kΩ			17	μs
γ-Corrected Power Supply Capacitance	$C_\gamma$	$T_A = 25$ °C		750		pF
Input Capacitance 1	C1	STHR, STHL excluded $T_A = 25$ °C			18	pF
Input Capacitance 2	C2	STHR, STHL $T_A = 25$ °C			20	pF

Timing Requirement ( $T_A = D10$  to  $+75\text{ }^\circ\text{C}$ ,  $V_{DD1} = 3.3\text{ V}$   $\begin{matrix} +2.2\text{ V} \\ -0.3\text{ V} \end{matrix}$ ,  $V_{SS1} = V_{SS2} = 0\text{ V}$ ,  $t_r = t_f = 12\text{ ns}$ )

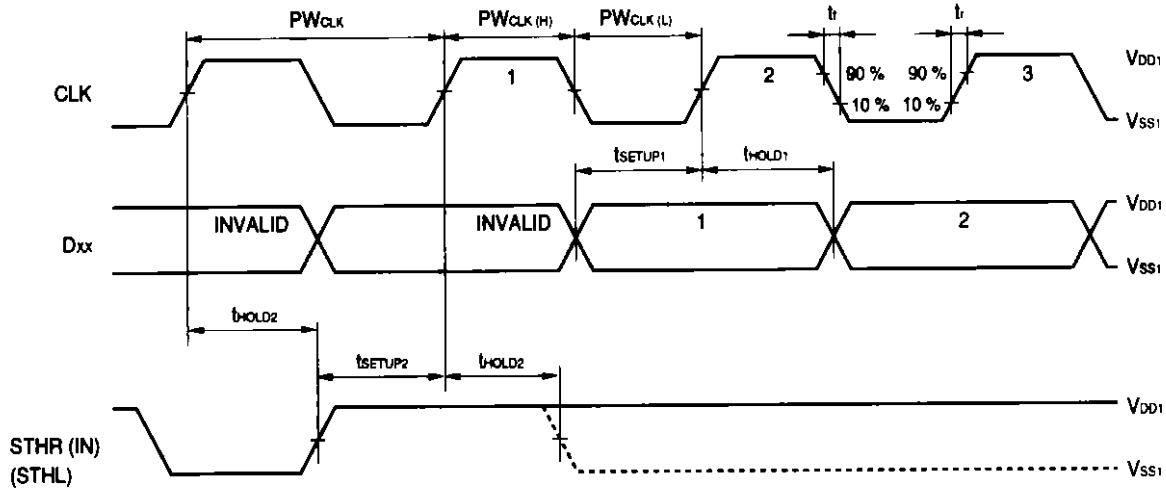
Parameter	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Clock Pulse Width	$PW_{CLK}$		30			ns
Clock Pulse Low Period	$PW_{CLK(L)}$		6.0			ns
Clock Pulse High Period	$PW_{CLK(H)}$		6.0			ns
Data Setup Time	$t_{SETUP1}$		6.0			ns
Data Hold Time	$t_{HOLD1}$		6.0			ns
Start Pulse Setup Time	$t_{SETUP2}$		6.0			ns
Start Pulse Hold Time	$t_{HOLD2}$		6.0			ns
Start Pulse Low Period	$t_{SPL}$		6.0			ns
STB Pulse Width	$PW_{STB}$		200			ns
Data Invalid Period	$t_{INV}$		1			CLK
Final Data Timing	$t_{LDT}$		2			CLK
CLK-STB Time	$t_{CLK-STB}$	CLK $\uparrow$ $\rightarrow$ STB $\downarrow$	6.0			ns
STB-CLK Time	$t_{STB-CLK}$	STB $\downarrow$ $\rightarrow$ CLK $\uparrow$	6.0			ns
Time Between STB and Start Pulse	$t_{STB-STH}$	STB $\downarrow$ $\rightarrow$ STHR $\uparrow$	50			ns
POL-STB Time	$t_{POL-STB}$	POL $\uparrow$ or $\downarrow$ $\rightarrow$ STB $\uparrow$	-5.0			ns
STB-POL Time	$t_{STB-POL}$	STB $\downarrow$ $\rightarrow$ POL $\uparrow$ or $\downarrow$	6.0			ns

**Switching Characteristics Waveform (R/L = H)**

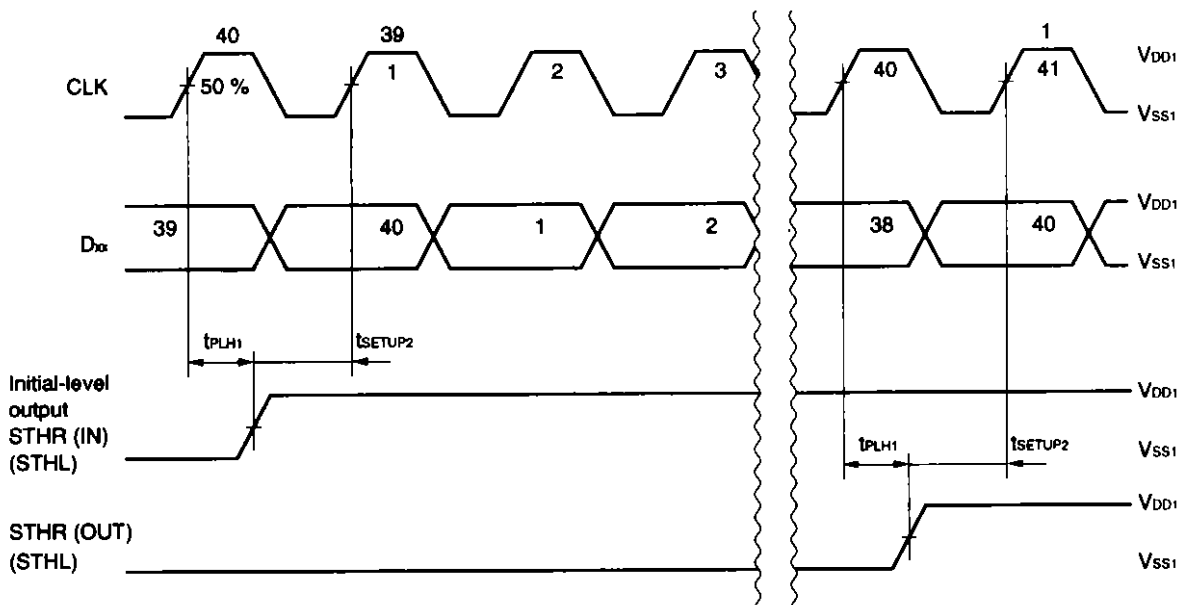
In ( ): R/L = L

Unless otherwise specified, the input level is defined to be 0.5 V<sub>DD1</sub>.

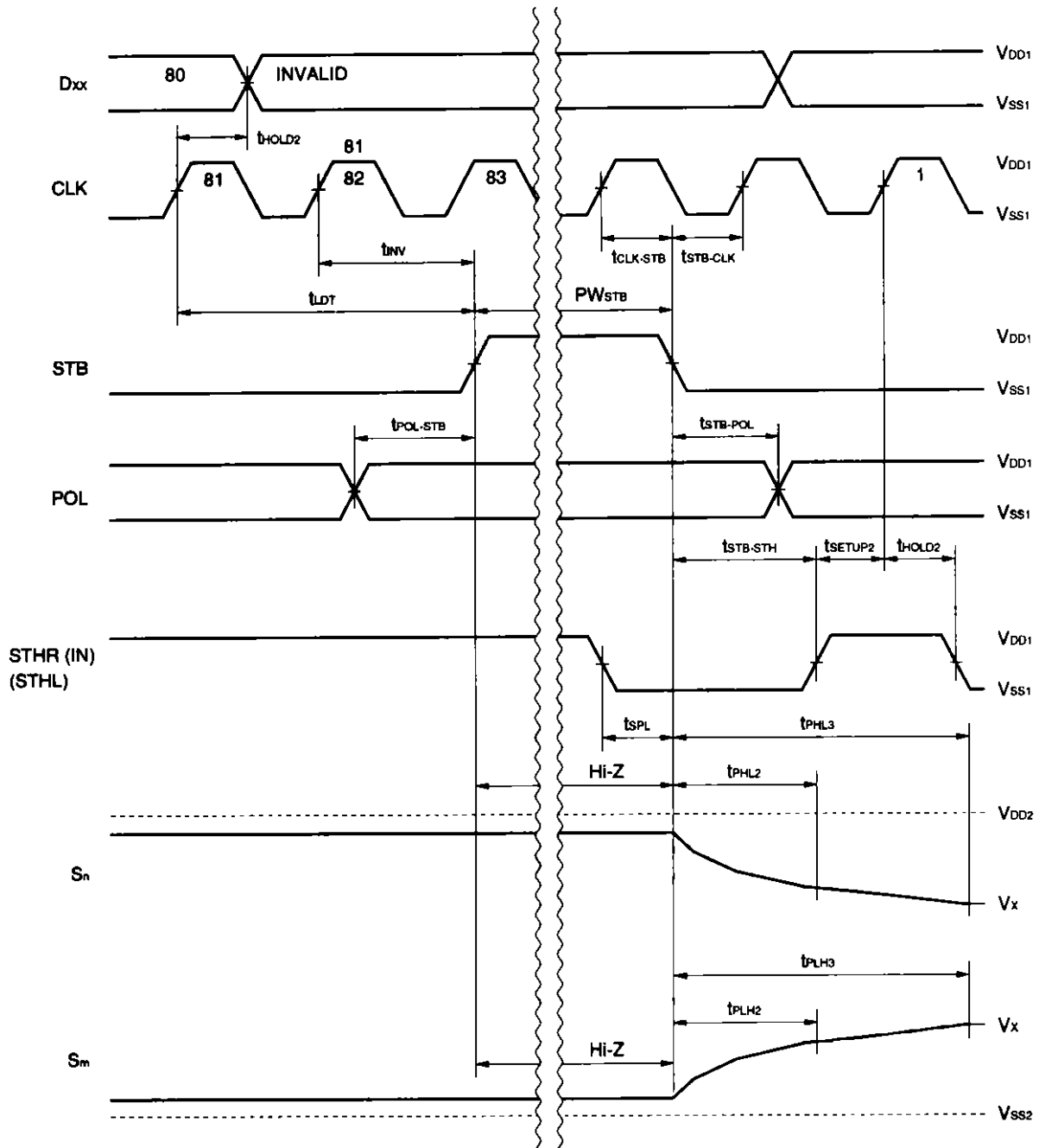
**1. Initial-Stage Driver's Input/Output Waveform**



**2. Second- to Final-Stage Drivers's Input/Output Timing**



3. DRIVER OUTPUT TIMING



V<sub>x</sub> refers to the final output voltage, t<sub>PLH2</sub>, t<sub>PHL2</sub> refers to the time required to reach an output precision level of 10 % (0.1 V<sub>x</sub>); and t<sub>PLH3</sub>, t<sub>PHL3</sub> refers to the time required to reach an output precision level of 6 bits.



**RECOMMENDED MOUNTING CONDITIONS**

The following mounting conditions for the μPD16631A are recommended.

For any other mounting conditions, consult NEC.

Mounting conditions	Mounting method	Conditions
Thermocompression	Soldering	Heating tool: 300 to 350 °C, time: 2 to 3 seconds, pressure: 100 g (per piece)
	ACF (sheet adhesive agent)	Preliminary adhesion: 70 to 100 °C, Pressure: 3 to 8 kg/cm <sup>2</sup> , Time: 3 to 5 seconds Actual adhesion: 165 to 180 °C, Pressure: 25 to 45 kg/cm <sup>2</sup> , Time: 30 to 40 seconds (with Sumitomo Bakelite's anisotropic film SUMIZAC1003)

- Caution**
1. For the mounting conditions for ACF, consult the ACF manufacturer before using the ACF.
  2. Do not use two or more mounting methods in combination.

**REFERENCE**

Document Name	Document No.
NEC semiconductor device reliability/quality control system.	IEI-1212
Quality grade on NEC semiconductor devices.	IEI-1209
Semiconductor device mounting technology manual.	C10535E

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Special: Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support)

Specific: Aircrafts, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems or medical equipment for life support, etc.

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Anti-radioactive design is not implemented in this product.