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April 1st, 2010 Renesas Electronics Corporation

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M50224FP

1.5 Channel Motor Driver-with DC/DC Control

REJ03F0070-0100Z Rev.1.0 Sep.19.2003

Description

M50224FP is the semiconductor integrated circuit which builds in the Motor drive circuit and DC/DC circuit suitable for the camera etc.

1.5 H bridges, the DC/DC circuit of 5VDC/DC, and AE operation circuit were built in one tip by adoption of a detailed CMOS process.

The reduction in power consumption and the miniaturization are considered as the high composition of the flexibility realized with one chip.

Features

- Minute CMOS process acceptance.Low consumption
- 1.5 full swing voltage drive H Bridge circuit built-in (PWM drive correspondence)
- DC/DC circuit built-in of 5V
- One AE operation circuit built-in AE (A sensor corresponds to amorphous and SPD)
- Low voltage incorrect operation prevention circuit thermole shutdown circuit built-in
- A thermometer, with a power save function

Application

motor driver for cameras etc

Recommend Operating Condition

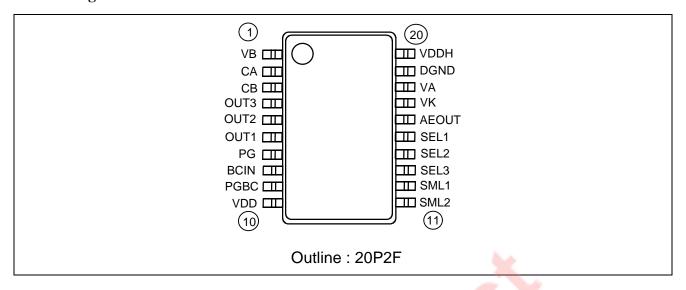
Supply voltage range...... VB:1.6V to 3.5V

Rated supply voltage VB:3.0V

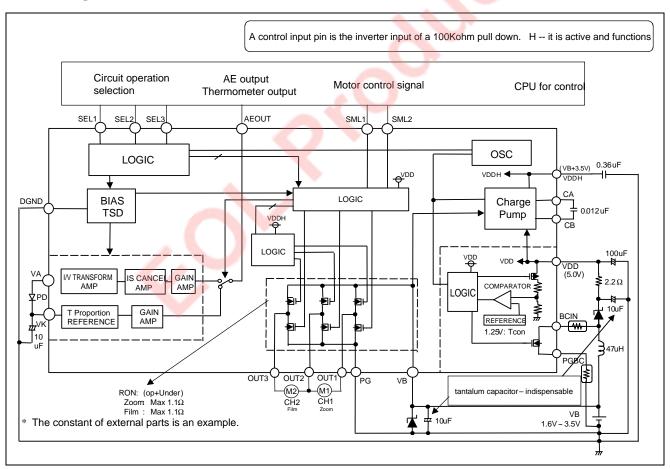




Pin Configuration



Block Diagram



Absolute Maximum Ratings

(Ta=25°C, unless otherwise noted)

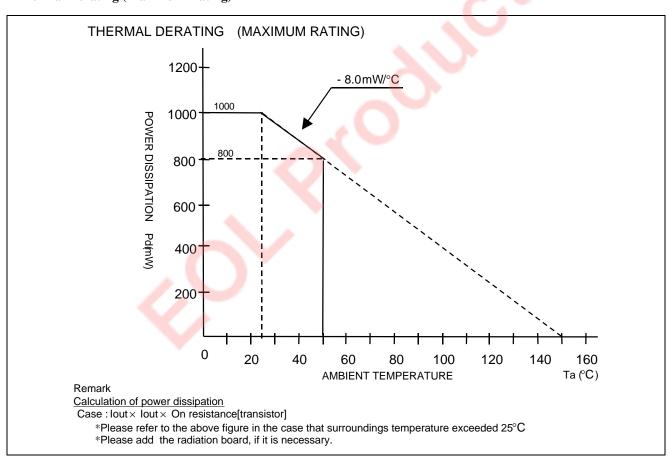
Parameter	Symbol	Ratings	Unit	Remark
Supply voltage1	VB	3.5	V	Note1
Supply voltage2	VDD	6.5	V	Note1
Supply voltage3	VDDH	VB+4.5	V	Note1
Voltage between BCIN and PGBC	VDSS	15	V	Note1 (VGS=0V)
Power dissipation	Pd	1000	mW	Note2 (Ta=25° C)
Thermal derating	Κθ	-8.0	mW/° C	Note2 (Tæ25° C)
Pin input Voltage	Vin	0 to VDD+0.3	V	Note3
Operating temperature	Topr	-10 to 50	° C	
Storage temperature	Tstg	-40 to 150	° C	

note1: As a principle, do not provide reversely

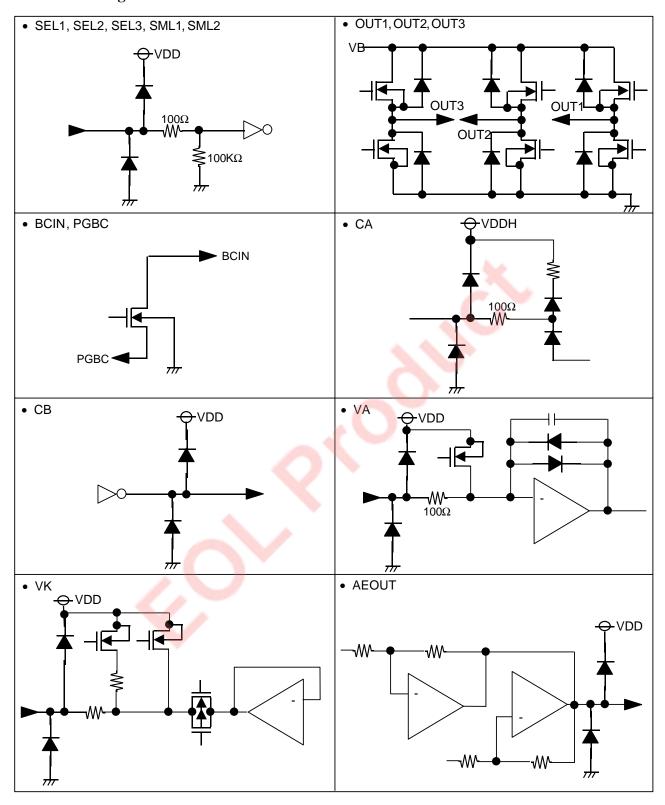
note2: Glass epoxy circuit board:70mm ×70mm ×1.6mm 1layer circuit board Cu Share 10%

note3: As a principle, do not provide over supply voltage or under ground voltage

Thermal Derating (Maximum Rating)



I/O Circuit Diagram



Electrical Characteristics

(Ta =25°C, VB=3.0V, VDD=5.0V, unless otherwise noted)

				Limits	_				
	Parameter	Symbol	Test condition	MIN	MIN TYP		Unit	Note	
	Voltage range of operation	VB		2.0	3.0	3.5	V		
	Current at the time of standby	IB1	SEL1:L SEL2:L SEL3:L	-	0.1	5	μА		
Consumption current	Usual consuming current 1	IDD1	Only a DC/DC circuit is turned ON. SEL1:H SEL2:L SEL3:L	-			mA		
-	Usual consuming current 2	IDD2	DC/DC+AE+MD circuit ON SEL1:H SEL2:L SEL3 :H	-			mA		
	Hi level input current	IIH	VIN=VDD=5.0V	25	50	100	μΑ	Note1	
=	Lo level input current	IIL		-1.0		-	μΑ	<u>-</u> '	
Input terminal	Input pull down resistance	RIND		50	100	200	ΚΩ	•	
mina	Hi level input voltage	VIH	VDD=4.5 to 5.5V	VDD×0.7	6 4	VDD	V	-	
<u> </u>	Lo level input voltage	VIL	VDD=4.5 to 5.5V	0		VDD x0.3	V	•	
	Oscillation frequency	fosc	VDD=5.0V	44	63	82	kHz	Note2	
•	DUTY	DUTY	VDD=5.0V		75		%	<u>-</u> '	
D	Operating start Voltage	Vstart1	VB voltage	0	-	2.0	V	•	
DC/DC Circuit	Operating stop Voltage	Vstop1	VB voltage	-	-	1.0	V	-	
ircu	Output voltage	Vout	VDD voltage	4.7	5.0	5.3	V	_	
∓ :	Input stability	∆Vout1	VB=2.0V to 3.3V IDD=50mA	-	-	100	mV		
	Load stability	∆Vout2	VB=2.85V IDD=100mA	-	-	100	mV		
	Maximum output current	lout	VB=2.85V VDD≥4.5V	100	-	-	mA		
Cha	Oscillation frequency	fosc2	VDD=5.0V	150	227	320	kHz	Note3	
arge	DUTY	DUTY2	VDD=5.0V		50		%		
Charge pump circuit	Operating start Voltage	Vstart2	VDD voltage	4.5	5.0	5.3	V		
cuit	Output voltage	Vout2	VDDH voltage	VB+2.6	VB+3.3	VB+4.5	V	-	
	Operating voltage	VBDCM	VB voltage	1.6	-	3.5	V		
	ON Resistance RVON 1	RVON 1	Io=0.5A, VB=3V, VDD=5V, VDDH=5.5V	-	0.75	1.1	Ω	Note4	
Motor	Maximum output current	Iomax	T < ***S	1.8	-	-	Α		
Motor driver(1, 2)	Continual maximum output current	locont		500	-	-	mA		
, 2)	Turn on time	TvON	RM=5.0Ω	-	0.5	2	μs		
	Turn off time	TvOFF	Fig. 1	-	0.1	0.5	μs		
	Output rise time Tr	Tr	-	-	0.3	1.0	μs		
	Output fall time Tf	Tvf	-	-	0.01	0.2	μs		

(Ta =25°C, VB=3.0V, VDD=5.0V, unless otherwise noted)

				Limit				
	Parameter	Symbol	Test condition	MIN	TYP	MAX	Unit	Note
	Temperature output absolute value	VTE		·	2713	3392	mV	
AE circuit (Thermometer)	Temperature output power supply voltage change 1	dVTE1	VDD=5.5V	-45	-	45	mV	
	Temperature output power supply voltage change 2	dVTE2	VDD=4.5V	-45	-	45	mV	
ometer)	Temperature output voltage load change	dVTE3	lo=-0.2mA	-20	-	20	mV	
	The amount of temperature output change	dVTE4	The Amount of Change (-10 to 50° C)	-22.7	-22.0	-19.1	mV	
Þ	Input range	IA		50p	- 4	120u	Α	
AE circuit (Light measurement circuit)	Light measurement output absolute value	VAE	IA=10nA		1914		mV	
	The amount of change per two step	dEVA1	IA=10nA -> 40nA		-242		mV	
eas	Output linearity 1	DEVS1	IA=50pA to 1.6nA	-30	_/_	30	%	
urer	Output linearity 2	DEVS2	IA=1.6nA to 410nA	-23	-	23	%	
nen	Output linearity 3	DEVS3	IA=410nA to 13.1μA	-23	-	23	%	_
C <u>i</u>	Output linearity 4	DEVS4	IA=13.1μA to 120μA	-30	-	30	%	
cuit)	Power supply response	Trs	IA=50pA	_	-	50	ms	
T S D	thermole shutdown temperature	TTSD	Tip temp <mark>erature i</mark> n case H bridge output turns off		150		° C	Note5

Note1: Input terminal: 11 to15 PIN

Note2: L=47 μ H, C=100uF

Note3: Since it is a power supply only for the insides of IC, please do not connect a charge pump circuit to others.

Note4: The sum of upper and lower sides side ON resistance.

ON resistance is changed with VB, VDD, and VDDH voltage.

Note5: A shipment test is not performed although the TSD circuit characteristic presents reference data.

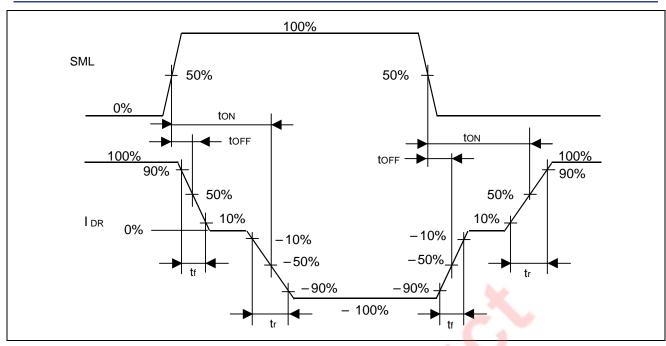
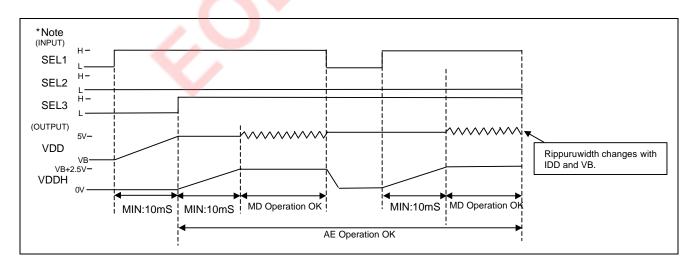


Fig 1 H bridge part switching characteristic waveform

SEL Truth value table

SEL1	SEL2	SEL3	The contents of control
L	L	L	Standby
Н	L	L	Only a DC/DC circuit is turned ON (*note)
Н	L	Н	DC/DC + AE circuit ON + motor1 contorol (AEOUT: right out)
Н	Н	Н	DC/DC + AE circuit ON + motor2 contorol(AEOUT: right out)
Н	Н	L	DC/DC + AE circuit ON + shutter contorol(AEOUT : temperature out)
L	L	Н	Only AE circuit ON (AEOUT: right out)
L	Н	Н	Only AE circuit ON (AEOUT: right out)
L	Н	L	Only AE circuit ON (AEOUT : temperature out)

^{*1.} SEL1:DC/DC and Charge pump contorol (L=OFF, H=ON)



Motor control Truth value table

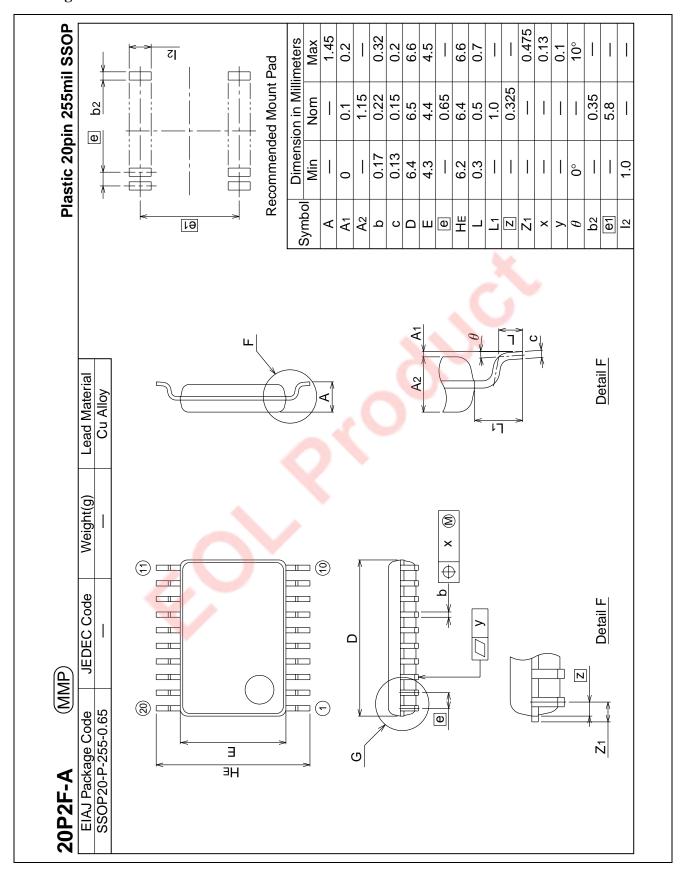
	INPUT								MOTOR Each output		
	SEL1	SEL2	SEL3	SML1	SML2	MOTOR1	MOTOR2	Shutter	OUT1	OUT2	OUT3
MOTOR1	Н	L	Н	L	L	Standby	Standby	Standby	OFF	OFF	OFF
Control	Н	L	Н	Н	L	Forward Rotation	Standby	Standby	L	Н	OFF
	Н	L	Н	L	Н	Reverse	Standby	Standby	Н	L	OFF
	Н	L	Н	Н	Н	Brake	Standby	Standby	Н	Н	OFF
MOTOR2	Н	Н	Н	L	L	Standby	Standby	Standby	OFF	OFF	OFF
Control	Н	Н	Н	Н	L	Standby	Forward Rotation	Standby	OFF	Н	L
	Н	Н	Н	L	Н	Standby	Reverse	Standby	OFF	L	Н
	Н	Н	Н	Н	Н	Standby	Brake	Standby	OFF	Н	Н
Shutter	Н	Н	L	L	L	Standby	Standby	Standby	OFF	OFF	OFF
Control	Н	Н	L	Н	L	Standby	Standby	Forward Rotation	OFF	OFF	L
	Н	Н	L	L	Н	Standby	Standby	Reverse	OFF	OFF	Н
	Н	Н	L	Н	Н	Standby	Standby	Brake	OFF	OFF	Н

^{*:} Please pass through the Brake or Stand-by mode by all means in case of moving from forward rotation to Reverse rotation or from

Reverse rotation to forward rotation by the motor control.

⁽ex.) Forward rotation -> Brake -> Reverse rotation, Reverse rotation -> Stand-by -> Forward rotation

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Renesas Technology Singapore Pte. Ltd.
1, Harbour Front Avenue, #06-10, Keppel Bay Tower, Singapore 098632 Tel: <65> 6213-0200, Fax: <65> 6278-8001