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April 1st, 2010
Renesas Electronics Corporation

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Note : Mitsubishi Electric will continue the business operations of high frequency & optical devices and power devices.

Renesas Technology Corp.
Customer Support Dept.
April 1, 2003

PRELIMINARY

Notice: This is not a final specification.
Some parametric limits are subject to change.

MITSUBISHI MICROCOMPUTERS

M37733EHLXXXHP

PROM VERSION OF M37733MHLXXXHP

DESCRIPTION

The M37733EHLXXXHP is a single-chip microcomputer using the 7700 Family core. This single-chip microcomputer has a CPU and a bus interface unit. The CPU is a 16-bit parallel processor that can be an 8-bit parallel processor, and the bus interface unit enhances the memory access efficiency to execute instructions fast. This microcomputer also includes a 32 kHz oscillation circuit, in addition to the PROM, RAM, multiple-function timers, serial I/O, A-D converter, and so on.

Its strong points are the low power dissipation, the low supply voltage, and the small package.

The M37733EHLXXXHP has the same function as the M37733MHLXXXHP except that the built-in ROM is PROM. (Refer to the basic function blocks description.)

FEATURES

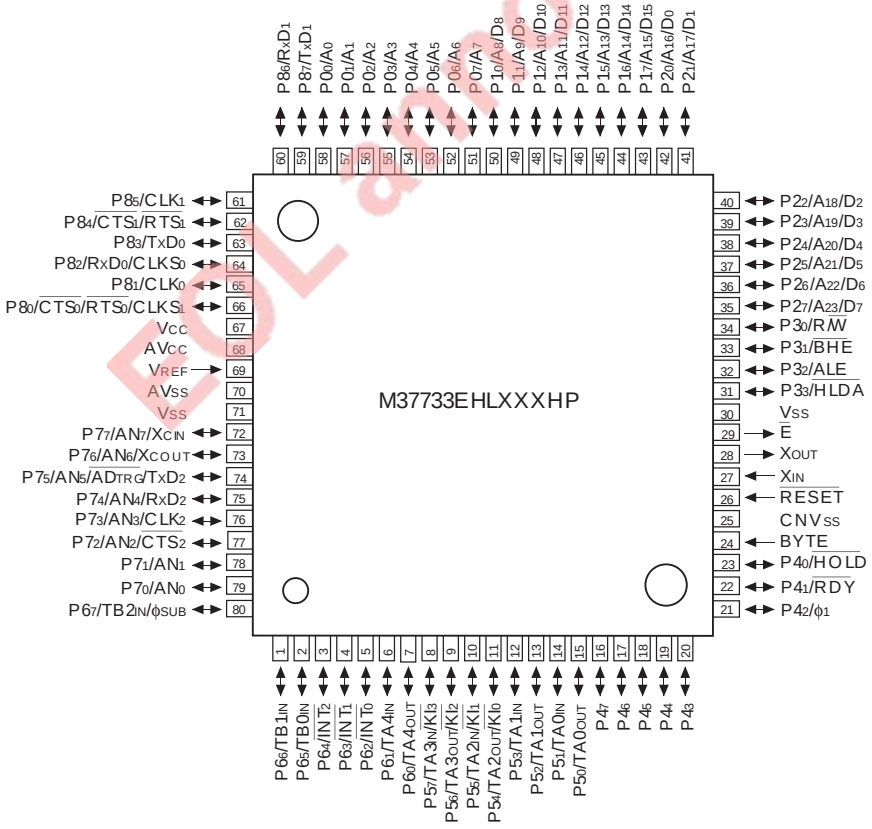
- Number of basic instructions 103
- Memory size PROM ..... 124 Kbytes
  RAM ..... 3968 bytes
- Instruction execution time
  The fastest instruction at 12 MHz frequency ..... 333 ns
- Single power supply ..... 2.7–5.5 V
- Low power dissipation (At 3 V supply voltage, 12 MHz frequency) ..... 9 mW (Typ.)
- Interrupts ..... 19 types, 7 levels
- Multiple-function 16-bit timer ..... 5 + 3
- Serial I/O (UART or clock synchronous) 3
- 10-bit A-D converter ..... 8-channel inputs
- Watchdog timer
- Programmable input/output
  (ports P0, P1, P2, P3, P4, P5, P6, P7, P8) 68
- Clock generating circuit ..... 2 circuits built-in
- Small package ..... 80-pin plastic molded fine-pitch QFP
  (0.5 mm lead pitch)

APPLICATION

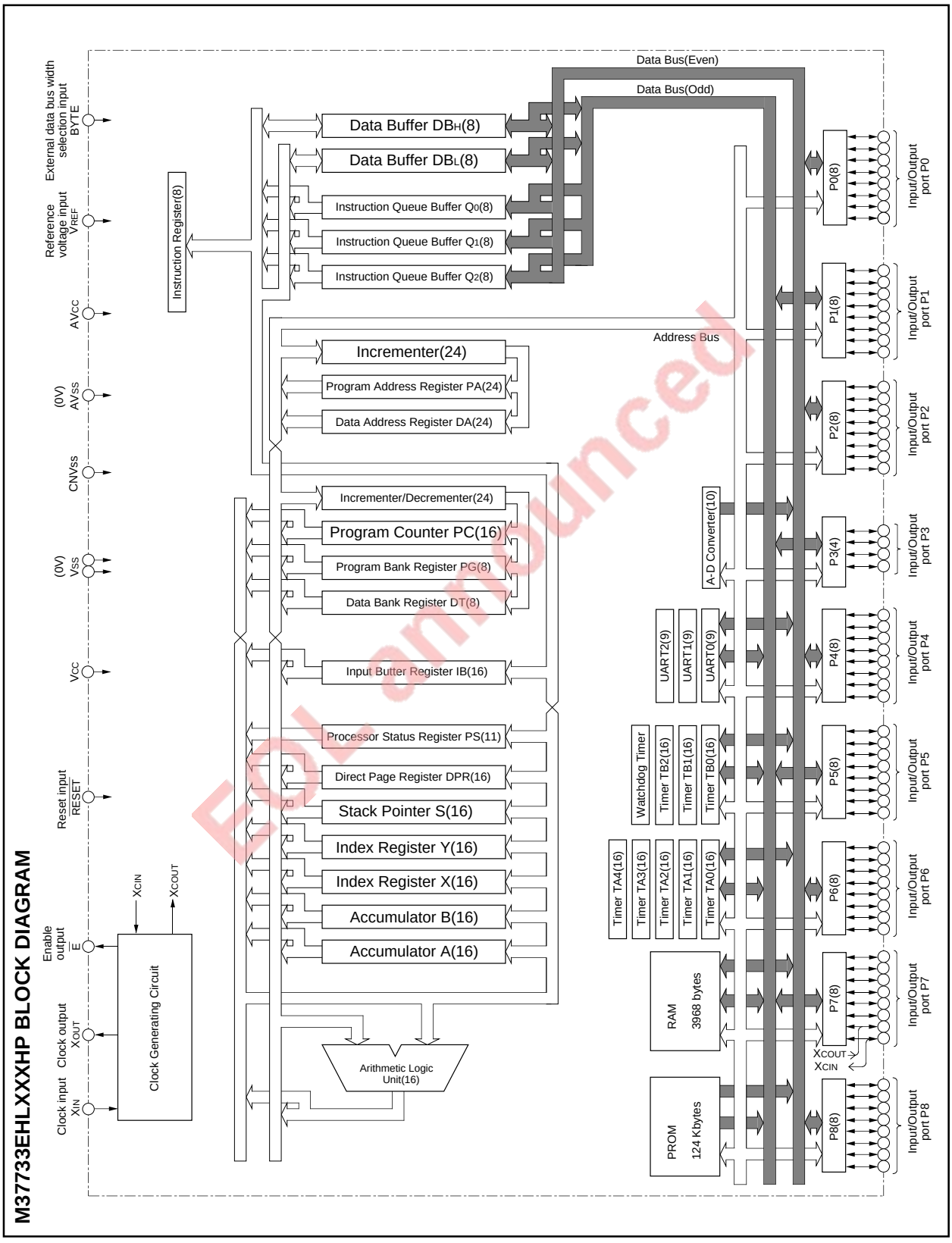
Control devices for general commercial equipment such as office automation, office equipment, personal information equipment, and so on.

Control devices for general industrial equipment such as communication equipment, and so on.

PIN CONFIGURATION (TOP VIEW)



Outline 80P6D-A, 80P6Q-A



FUNCTIONS OF M37733EHLXXXHP

Parameter		Functions
Number of basic instructions		103
Instruction execution time		333 ns (the fastest instruction at external clock 12 MHz frequency)
Memory size	PROM	124 Kbytes
	RAM	3968 bytes
Input/Output ports	P0 – P2, P4 – P8	8-bit × 8
	P3	4-bit × 1
Multi-function timers	TA0, TA1, TA2, TA3, TA4	16-bit × 5
	TB0, TB1, TB2	16-bit × 3
Serial I/O		(UART or clock synchronous serial I/O) × 3
A-D converter		10-bit × 1 (8 channels)
Watchdog timer		12-bit × 1
Interrupts		3 external types, 16 internal types Each interrupt can be set to the priority level (0 – 7.)
Clock generating circuit		2 circuits built-in (externally connected to a ceramic resonator or a quartz-crystal oscillator)
Supply voltage		2.7 – 5.5 V
Power dissipation		9 mW (at 3 V supply voltage, external clock 12 MHz frequency)
		22.5 mW (at 5 V supply voltage, external clock 12 MHz frequency)
Input/Output characteristic	Input/Output voltage	5 V
	Output current	5 mA
Memory expansion		Maximum 16 Mbytes
Operating temperature range		–40 to 85 °C
Device structure		CMOS high-performance silicon gate process
Package		80-pin plastic molded fine-pitch QFP (80P6D-A;0.5 mm lead pitch)

PIN DESCRIPTION

Pin	Name	Input/Output	Functions
Vcc, Vss	Power source		Apply 2.7 – 5.5 V to Vcc and 0 V to Vss.
CNVss	CNVss input	Input	This pin controls the processor mode. Connect to Vss for the single-chip mode and the memory expansion mode, and to Vcc for the microprocessor mode.
$\overline{\text{RESET}}$	Reset input	Input	When "L" level is applied to this pin, the microcomputer enters the reset state.
X_{IN}	Clock input	Input	These are pins of main-clock generating circuit. Connect a ceramic resonator or a quartz-crystal oscillator between X_{IN} and X_{OUT}. When an external clock is used, the clock source should be connected to the X_{IN} pin, and the X_{OUT} pin should be left open.
X_{OUT}	Clock output	Output	
$\overline{E}$	Enable output	Output	This pin functions as the enable signal output pin which indicates the access status in the internal bus. When output level of $\overline{E}$ signal is "L", data/instruction read or data write is performed.
BYTE	External data bus width selection input	Input	In the memory expansion mode or the microprocessor mode, this pin determines whether the external data bus has an 8-bit width or a 16-bit width. The data bus has a 16-bit width when "L" signal is input and an 8-bit width when "H" signal is input.
AVcc, AVss	Analog power source input		Power source input pin for the A-D converter. Externally connect AVcc to Vcc and AVss to Vss.
V_{REF}	Reference voltage input	Input	This is reference voltage input pin for the A-D converter.
$P0_0$ – $P0_7$	I/O port P0	I/O	In the single-chip mode, port P0 becomes an 8-bit I/O port. An I/O direction register is available so that each pin can be programmed for input or output. These ports are in the input mode when reset. In the memory expansion mode or the microprocessor mode, these pins output address (A_0 – A_7).
$P1_0$ – $P1_7$	I/O port P1	I/O	In the single-chip mode, these pins have the same functions as port P0. When the BYTE pin is set to "L" in the memory expansion mode or the microprocessor mode and external data bus has a 16-bit width, high-order data (D_8 – D_{15}) is input/output or an address (A_8 – A_{15}) is output. When the BYTE pin is "H" and an external data bus has an 8-bit width, only address (A_8 – A_{15}) is output.
$P2_0$ – $P2_7$	I/O port P2	I/O	In the single-chip mode, these pins have the same functions as port P0. In the memory expansion mode or the microprocessor mode, low-order data (D_0 – D_7) is input/output or an address (A_{16} – A_{23}) is output.
$P3_0$ – $P3_3$	I/O port P3	I/O	In the single-chip mode, these pins have the same function as port P0. In the memory expansion mode or the microprocessor mode, R/$\overline{W}$, $\overline{BHE}$, ALE, and $\overline{HLDA}$ signals are output.
$P4_0$ – $P4_7$	I/O port P4	I/O	In the single-chip mode, these pins have the same functions as port P0. In the memory expansion mode or the microprocessor mode, $P4_0$, $P4_1$, and $P4_2$ become $\overline{HOLD}$ and $\overline{RDY}$ input pins, and a clock ϕ_1 output pin, respectively. Functions of the other pins are the same as in the single-chip mode. However, in the memory expansion mode, $P4_2$ can be selected as an I/O port.
$P5_0$ – $P5_7$	I/O port P5	I/O	In addition to having the same functions as port P0 in the single-chip mode, these pins also function as I/O pins for timers A0 to A3 and input pins for key input interrupt input ($\overline{KI_0}$ – $\overline{KI_3}$).
$P6_0$ – $P6_7$	I/O port P6	I/O	In addition to having the same functions as port P0 in the single-chip mode, these pins also function as I/O pins for timer A4, input pins for external interrupt input ($\overline{INT_0}$ – $\overline{INT_2}$) and input pins for timers B0 to B2. $P6_7$ also functions as sub-clock ϕ_{SUB} output pin.
$P7_0$ – $P7_7$	I/O port P7	I/O	In addition to having the same functions as port P0 in the single-chip mode, these pins function as input pins for A-D converter. $P7_2$ to $P7_5$ also function as I/O pins for UART2. Additionally, $P7_6$ and $P7_7$ have the function as the output pin (X_{COUT}) and the input pin (X_{CIN}) of the sub-clock (32 kHz) oscillation circuit, respectively. When $P7_6$ and $P7_7$ are used as the X_{COUT} and X_{CIN} pins, connect a resonator or an oscillator between the both.
$P8_0$ – $P8_7$	I/O port P8	I/O	In addition to having the same functions as port P0 in the single-chip mode, these pins also function as I/O pins for UART 0 and UART 1.

PIN DESCRIPTION (EPROM MODE)

Pin	Name	Input/Output	Functions
V_{CC}, V_{SS}	Power supply		Supply 5V±10% to V_{CC} and 0V to V_{SS}.
CNV$_{SS}$	V_{PP} input	Input	Connect to V_{PP} when programming or verifying.
BYTE	V_{PP} input	Input	Connect to V_{PP} when programming or verifying.
$\overline{RESET}$	Reset input	Input	Connect to V_{SS}.
X_{IN}	Clock input	Input	Connect a ceramic resonator between X_{IN} and X_{OUT}.
X_{OUT}	Clock output	Output	
$\overline{E}$	Enable output	Output	Keep open.
AV$_{CC}$, AV$_{SS}$	Analog supply input		Connect AV$_{CC}$ to V_{CC} and AV$_{SS}$ to V_{SS}.
V_{REF}	Reference voltage input	Input	Connect to V_{SS}.
P0$_0$ – P0$_7$	Address input (A$_0$ – A$_7$)	Input	Port P0 functions as the lower 8 bits address input (A$_0$ – A$_7$).
P1$_0$ – P1$_7$	Address input (A$_8$ – A$_{15}$)	Input	Port P1 functions as the higher 8 bits address input (A$_8$ – A$_{15}$).
P2$_0$ – P2$_7$	Data I/O (D$_0$ – D$_7$)	I/O	Port P2 functions as the 8 bits data bus(D$_0$ – D$_7$).
P3$_0$	Address input (A$_{16}$)	Input	P3$_0$ functions as the most significant bit address input (A$_{16}$).
P3$_1$ – P3$_3$	Input port P3	Input	Connect to V_{SS}.
P4$_0$ – P4$_7$	Input port P4	Input	Connect to V_{SS}.
P5$_0$ – P5$_7$	Control signal input	Input	P5$_0$, P5$_1$ and P5$_2$ function as $\overline{PGM}$, $\overline{OE}$ and $\overline{CE}$ input pins respectively. Connect P5$_3$, P5$_4$, P5$_5$ and P5$_6$ to V_{CC}. Connect P5$_7$ to V_{SS}.
P6$_0$ – P6$_7$	Input port P6	Input	Connect to V_{SS}.
P7$_0$ – P7$_7$	Input port P7	Input	Connect to V_{SS}.
P8$_0$ – P8$_7$	Input port P8	Input	Connect to V_{SS}.

BASIC FUNCTION BLOCKS

The M37733EHLXXXHP has the same functions as the M37733MHBXXXFP except for the following :

(1) The built-in ROM is PROM.
(2) The package is different.
(3) The reset circuit is different.
(4) The status of bit 3 of the oscillation circuit control register 1 (address $6F_{16}$) at a reset is different.
(5) The usage condition of bit 3 of the oscillation circuit control register 1 is different.

Accordingly, refer to the basic function blocks description in the M37733MHBXXXFP except for Figure 1 (bit configuration of the oscillation circuit control register 1) , Figure 3 and Figure 4 (reset circuit).

In the M37733EHLXXXHP, bit 3 of the oscillation circuit control register 1 must be “1”. (Refer to Figure 1.) The status of this bit at a reset is “1”.

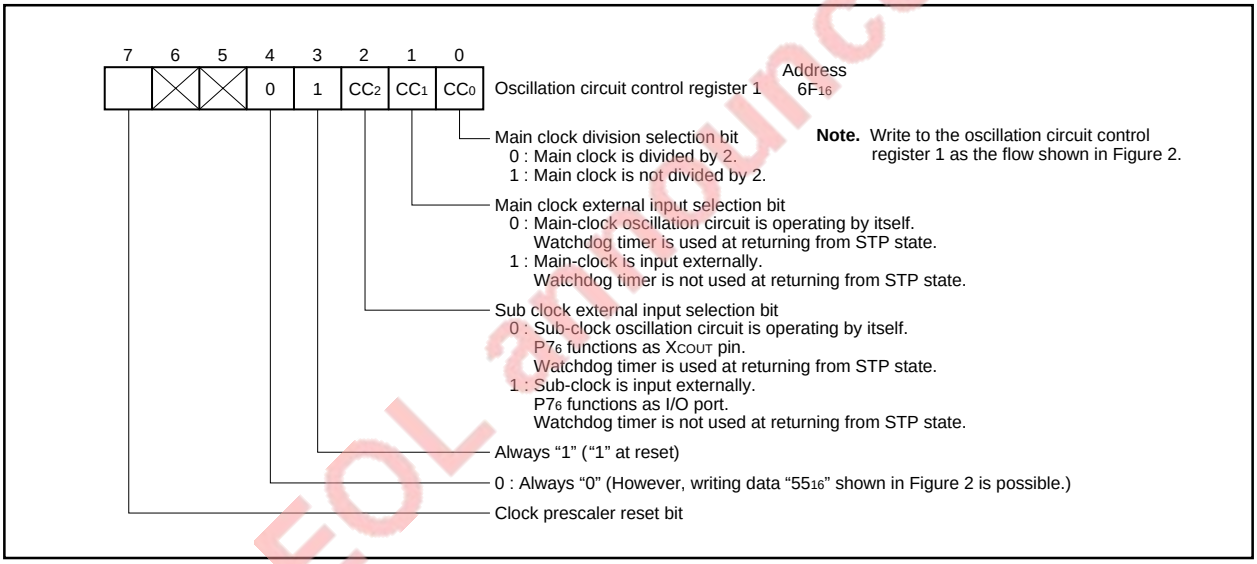


Fig. 1 Bit configuration of oscillation circuit control register 1 (corresponding to Figure 63 in data sheet “M37733MHBXXXFP”)

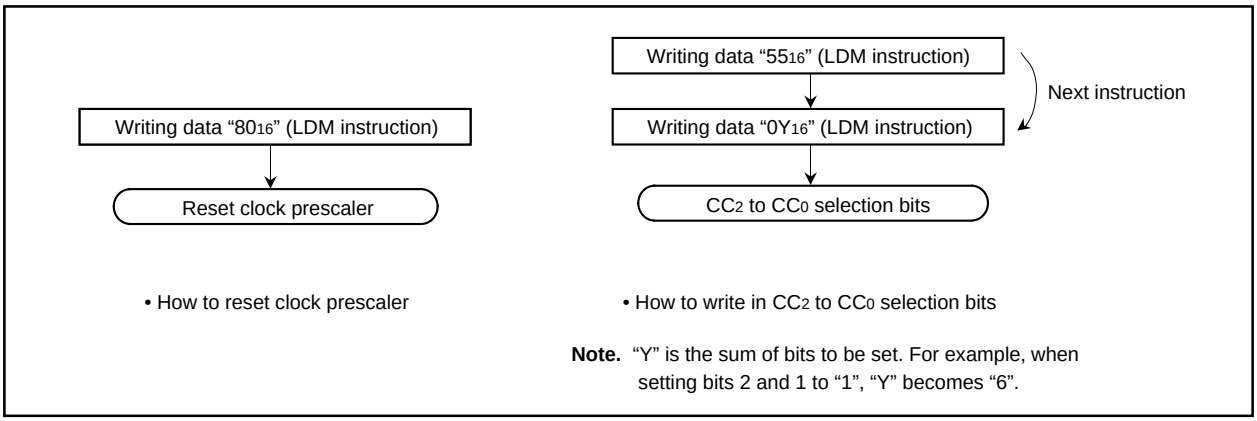
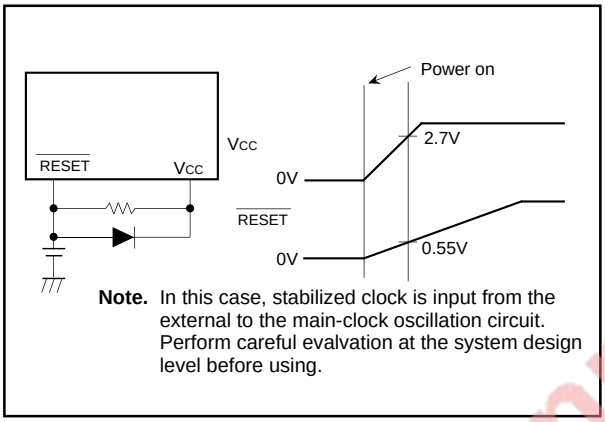


Fig. 2 How to write data in oscillation circuit control register 1 (identical with Figure 64 in data sheet “M37733MHBXXXFP”)

RESET CIRCUIT

The microcomputer is released from the reset state when the $\overline{\text{RESET}}$ pin is returned to "H" level after holding it at "L" level with the power source voltage at 2.7 – 5.5 V. Program execution starts at the address formed by setting address A_{23} – A_{16} to 00_{16}, A_{15} – A_8 to the contents of address $FFFF_{16}$, and A_7 – A_0 to the contents of address $FFFE_{16}$. Figure 3 shows the microcomputer internal status during reset. Figure 4 shows an example of a reset circuit. When the stabilized clock is input from the external to the main-clock oscillation circuit, the reset input voltage must be 0.55 V or less when the power source voltage reaches 2.7 V. When a resonator/oscillator is connected to the main-clock oscillation circuit, change the reset input voltage from "L" to "H" after the main-clock oscillation is fully stabilized.



Note. In this case, stabilized clock is input from the external to the main-clock oscillation circuit. Perform careful evalvation at the system design level before using.

Fig. 4 Example of a reset circuit

	Address	
Port P0 direction register	(04$_{16}$)•••	00$_{16}$
Port P1 direction register	(05$_{16}$)•••	00$_{16}$
Port P2 direction register	(08$_{16}$)•••	00$_{16}$
Port P3 direction register	(09$_{16}$)•••	××××0000
Port P4 direction register	(0C$_{16}$)•••	00$_{16}$
Port P5 direction register	(0D$_{16}$)•••	00$_{16}$
Port P6 direction register	(10$_{16}$)•••	00$_{16}$
Port P7 direction register	(11$_{16}$)•••	00$_{16}$
Port P8 direction register	(14$_{16}$)•••	00$_{16}$
A-D control register 0	(1E$_{16}$)•••	00000???
A-D control register 1	(1F$_{16}$)•••	××000×11
UART 0 transmit/receive mode register	(30$_{16}$)•••	00$_{16}$
UART 1 transmit/receive mode register	(38$_{16}$)•••	00$_{16}$
UART 0 transmit/receive control register 0	(34$_{16}$)•••	00001000
UART 1 transmit/receive control register 0	(3C$_{16}$)•••	00001000
UART 0 transmit/receive control register 1	(35$_{16}$)•••	00000010
UART 1 transmit/receive control register 1	(3D$_{16}$)•••	00000010
Count start flag	(40$_{16}$)•••	00$_{16}$
One- shot start flag	(42$_{16}$)•••	×××00000
Up-down flag	(44$_{16}$)•••	00$_{16}$
Timer A0 mode register	(56$_{16}$)•••	00$_{16}$
Timer A1 mode register	(57$_{16}$)•••	00$_{16}$
Timer A2 mode register	(58$_{16}$)•••	00$_{16}$
Timer A3 mode register	(59$_{16}$)•••	00$_{16}$
Timer A4 mode register	(5A$_{16}$)•••	00$_{16}$
Timer B0 mode register	(5B$_{16}$)•••	00100000
Timer B1 mode register	(5C$_{16}$)•••	001×0000
Timer B2 mode register	(5D$_{16}$)•••	001×0000
Processor mode register 0	(5E$_{16}$)•••	00$_{16}$
Processor mode register 1	(5F$_{16}$)•••	×××××××0
Watchdog timer register	(60$_{16}$)•••	FFF$_{16}$

	Address	
Watchdog timer frequency selection flag	(61$_{16}$)•••	×××××××0
Memory allocation control register	(63$_{16}$)•••	×××00000
UART2 transmit/receive mode register	(64$_{16}$)•••	×0000000
UART2 transmit/receive control register 0	(68$_{16}$)•••	××××1000
UART2 transmit/receive control register 1	(69$_{16}$)•••	00000010
Oscillation circuit control register 0	(6C$_{16}$)•••	×00000×1
Port function control register	(6D$_{16}$)•••	00$_{16}$
Serial transmit control register	(6E$_{16}$)•••	××00××××
Oscillation circuit control register 1	(6F$_{16}$)•••	0××01000
A-D/UART2 trans./rece. interrupt control register	(70$_{16}$)•••	××××0000
UART 0 transmission interrupt control register	(71$_{16}$)•••	××××0000
UART 0 receive interrupt control register	(72$_{16}$)•••	××××0000
UART 1 transmission interrupt control register	(73$_{16}$)•••	××××0000
UART 1 receive interrupt control register	(74$_{16}$)•••	××××0000
Timer A0 interrupt control register	(75$_{16}$)•••	××××0000
Timer A1 interrupt control register	(76$_{16}$)•••	××××0000
Timer A2 interrupt control register	(77$_{16}$)•••	××××0000
Timer A3 interrupt control register	(78$_{16}$)•••	××××0000
Timer A4 interrupt control register	(79$_{16}$)•••	××××0000
Timer B0 interrupt control register	(7A$_{16}$)•••	××××0000
Timer B1 interrupt control register	(7B$_{16}$)•••	××××0000
Timer B2 interrupt control register	(7C$_{16}$)•••	××××0000
$\overline{INT_0}$ interrupt control register	(7D$_{16}$)•••	××000000
$\overline{INT_1}$ interrupt control register	(7E$_{16}$)•••	××000000
$\overline{INT_2}$/Key input interrupt control register	(7F$_{16}$)•••	××000000
Processor status register (PS)		000???0001??
Program bank register (PG)		00$_{16}$
Program counter (PC_H)		Content of FFFF$_{16}$
Program counter (PC_L)		Content of FFFE$_{16}$
Direct page register (DPR)		0000$_{16}$
Data bank register (DT)		00$_{16}$

Contents of other registers and RAM are undefined during reset. Initialize them by software.

Fig. 3 Microcomputer internal status during reset

EPROM MODE

The M37733EHLXXXHP features an EPROM mode in addition to its normal modes. When the $\overline{\text{RESET}}$ signal level is "L", the chip automatically enters the EPROM mode. Table 1 list the correspondence between pins and Figure 5 shows the pin connections in the EPROM mode.

The EPROM mode is the 1M mode for the EPROM that is equivalent to the M5M27C101K.

When in the EPROM mode, ports P0, P1, P2, $P3_0$, $P5_0$, $P5_1$, $P5_2$, CNV_{SS} and BYTE are used for the EPROM (equivalent to the M5M27C101K). When in this mode, the built-in PROM can be programmed or read from using these pins in the same way as with the M5M27C101K.

This chip does not have Device Identifier Mode, so that set the corresponding program algorithm. The program area should specify address 0100_{16} – $1FFFF_{16}$.

Connect the clock which is either ceramic resonator or external clock to X_{IN} pin and X_{OUT} pin.

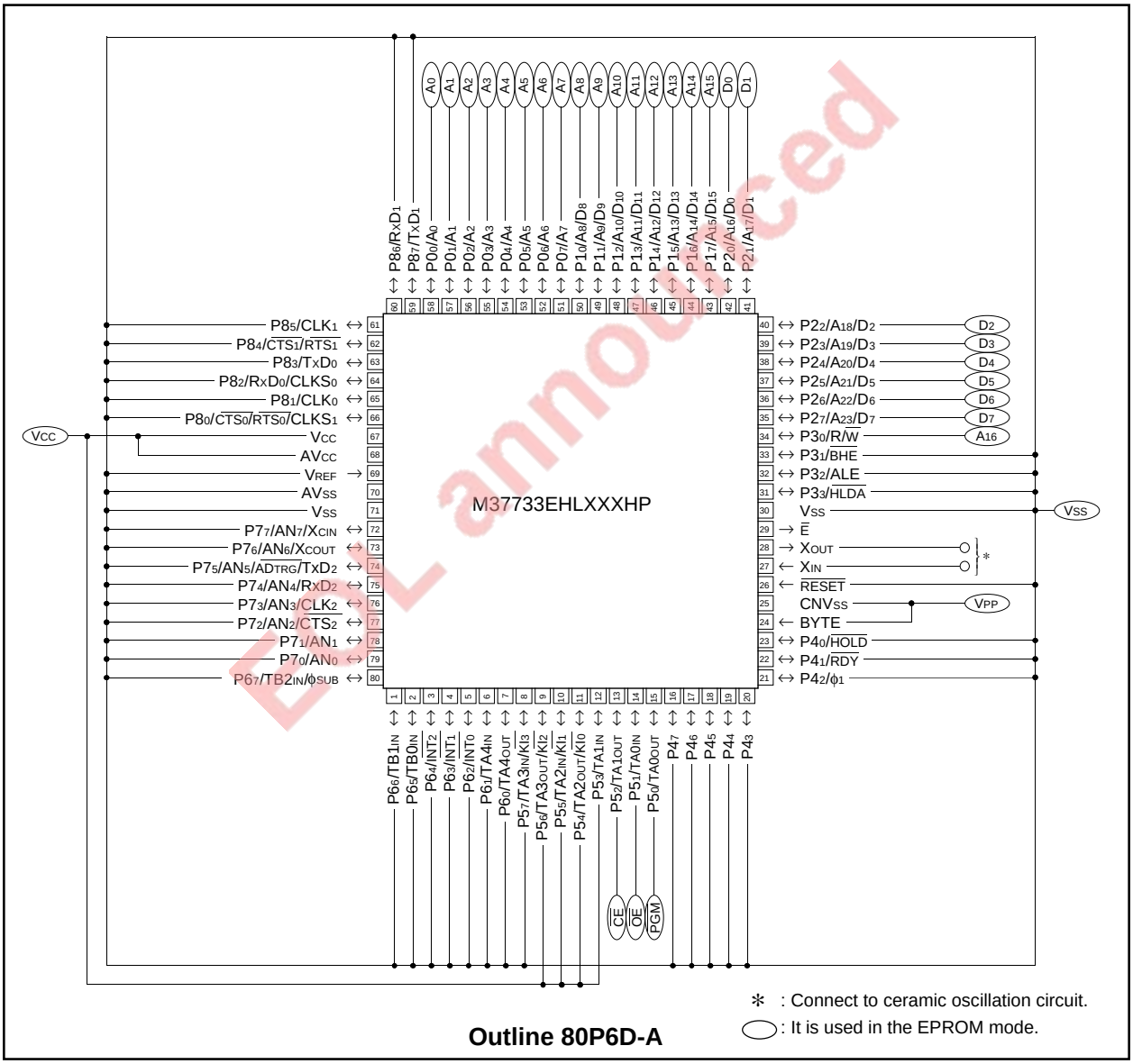


Fig. 5 Pin connection in EPROM mode

Table 1 Pin function in EPROM mode

	M37733EHLXXXHP	M5M27C101K
V_{CC}	V_{CC}	V_{CC}
V_{PP}	CNV_{SS}, BYTE	V_{PP}
V_{SS}	V_{SS}	V_{SS}
Address input	Ports P0, P1, $P3_0$	A_0 – A_{16}
Data I/O	Port P2	D_0 – D_7
$\overline{CE}$	$P5_2$	$\overline{CE}$
$\overline{OE}$	$P5_1$	$\overline{OE}$
$\overline{PGM}$	$P5_0$	$\overline{PGM}$

FUNCTION IN EPROM MODE
1M mode (equivalent to the M5M27C101K)

Reading

To read the EPROM, set the $\overline{CE}$ and $\overline{OE}$ pins to a "L" level. Input the address of the data (A_0 – A_{16}) to be read, and the data will be output to the I/O pins D_0 – D_7. The data I/O pins will be floating when either the $\overline{CE}$ or $\overline{OE}$ pins are in the "H" state.

Programming

Programming must be performed in 8 bits by a byte program. To program to the EPROM, set the $\overline{CE}$ pin to a "L" level and the $\overline{OE}$ pin to a "H" level. The CPU will enter the programming mode when 12.5 V is applied to the V_{PP} pin. The address to be programmed to is selected with pins A_0 – A_{16}, and the data to be programmed is input to pins D_0 – D_7. Set the $\overline{PGM}$ pin to a "L" level to being programming.

Programming operation

To program the M37733EHLXXXHP, first set V_{CC} = 6 V, V_{PP} = 12.5 V, and set the address to 0100_{16}. Apply a 0.2 ms programming pulse, check that the data can be read, and if it cannot be read OK, repeat the procedure, applying a 0.2 ms programming pulse and checking that the data can be read until it can be read OK. Record the accumulated number of pulse applied (X) before the data can be read OK, and then write the data again, applying a further once this number of pulses (0.2 × X ms).

When this series of programming operations is complete, increment the address, and continue to repeat the procedure above until the last address has been reached.

Finally, when all addresses have been programmed, read with V_{CC} = V_{PP} = 5 V (or V_{CC} = V_{PP} = 5.5 V).

Table 2. I/O signal in each mode

Mode \ Pin	$\overline{CE}$	$\overline{OE}$	$\overline{PGM}$	V_{PP}	V_{CC}	Data I/O
Read-out	V_{IL}	V_{IL}	X	5 V	5 V	Output
Output	V_{IL}	V_{IH}	X	5 V	5 V	Floating
Disable	V_{IH}	X	X	5 V	5 V	Floating
Programming	V_{IL}	V_{IH}	V_{IL}	12.5 V	6 V	Input
Programming Verify	V_{IL}	V_{IL}	V_{IH}	12.5 V	6 V	Output
Program Disable	V_{IH}	V_{IH}	V_{IH}	12.5 V	6 V	Floating

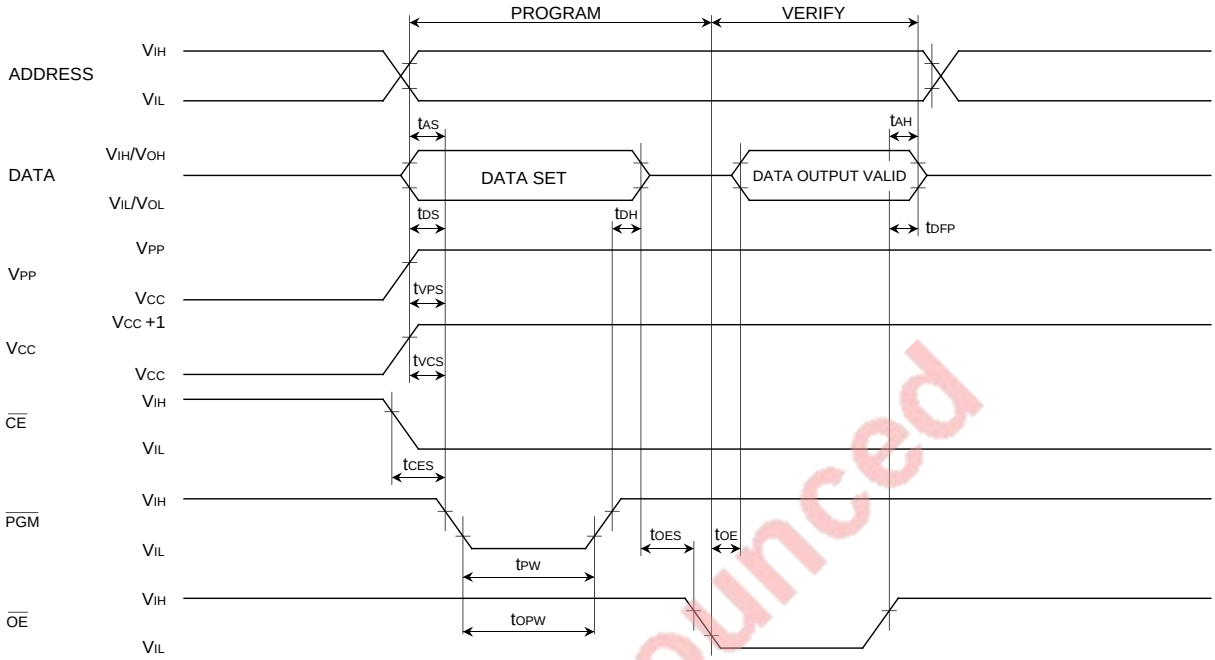
Note 1 : An X indicates either V_{IL} or V_{IH}.

Programming operation (equivalent to the M5M27C101K)

AC ELECTRICAL CHARACTERISTICS (T_a = 25 ± 5 °C, V_{CC} = 6 V ± 0.25 V, V_{PP} = 12.5 ± 0.3 V, unless otherwise noted)

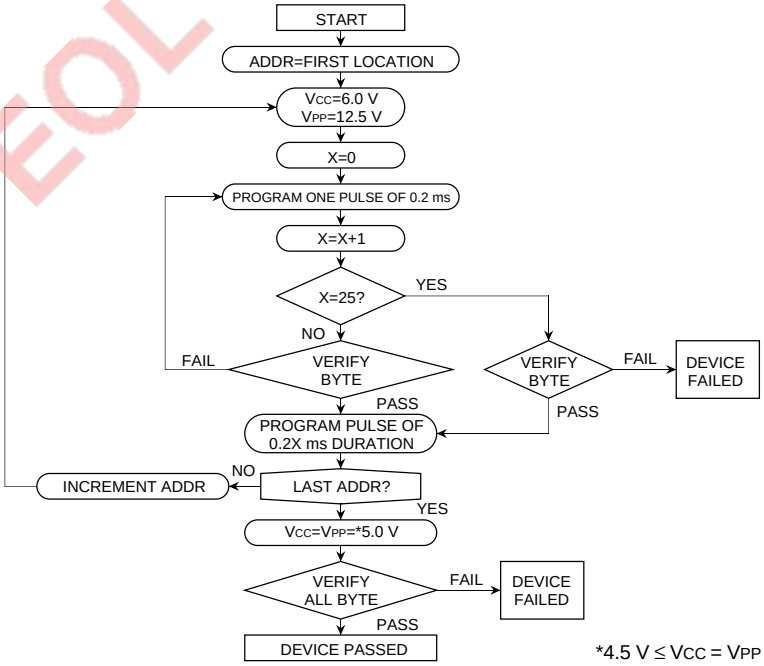
Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
t_{AS}	Address setup time		2			µs
t_{OES}	$\overline{OE}$ setup time		2			µs
t_{DS}	Data setup time		2			µs
t_{AH}	Address hold time		0			µs
t_{DH}	Data hold time		2			µs
t_{DFP}	Output enable to output float delay		0		130	ns
t_{VCS}	V_{CC} setup time		2			µs
t_{VPS}	V_{PP} setup time		2			µs
t_{PW}	$\overline{PGM}$ pulse width		0.19	0.2	0.21	ms
t_{OPW}	$\overline{PGM}$ over program pulse width		0.19		5.25	ms
t_{CES}	$\overline{CE}$ setup time		2			µs
t_{OE}	Data valid from $\overline{OE}$				150	ns

AC waveforms



Test conditions for A.C. characteristics
Input voltage : V_{IL} = 0.45 V, V_{IH} = 2.4 V
Input rise and fall times (10 % – 90 %) : ≤ 20 ns
Reference voltage at timing measurement : Input, Output
"L" = 0.8 V, "H" = 2 V

Programming algorithm flow chart

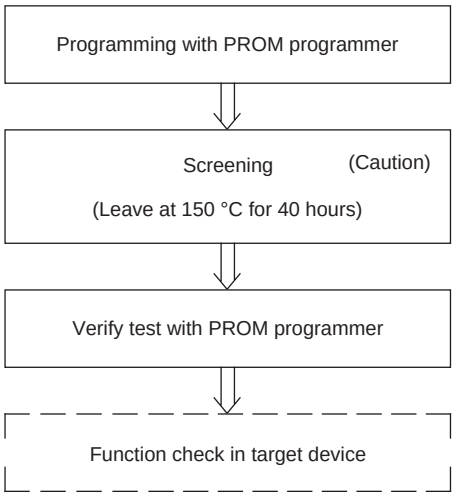


*4.5 V ≤ V_{CC} = V_{PP} ≤ 5.5 V

SAFETY INSTRUCTIONS

(1) A high voltage is used for programming. Take care that over-voltage is not applied. Take care especially at power on.

(2) The programmable M37733EHLHP that is shipped in blank is also provided. For the M37733EHLHP, Mitsubishi Electric corp. does not perform PROM programming test and screening following the assembly processes. To improve reliability after programming, performing programming and test according to the flow below before use is recommended.



Caution : Never expose to 150 °C exceeding 100 hours.

ADDRESSING MODES

The M37733EHLXXXHP has 28 powerful addressing modes. Refer to the “7700 Family Software Manual” for the details.

MACHINE INSTRUCTION LIST

The M37733EHLXXXHP has 103 machine instructions. Refer to the “7700 Family Software Manual” for the details.

DATA REQUIRED FOR PROM ORDERING

Please send the following data for writing to PROM.

(1) M37733EHLXXXHP writing to PROM order confirmation form

(2) 80P6D, 80P6Q mark specification form

(3) ROM data (EPROM 3 sets)

ABSOLUTE MAXIMUM RATINGS

Symbol	Parameter	Conditions	Ratings	Unit
Vcc	Power source voltage		–0.3 to +7	V
AVcc	Analog power source voltage		–0.3 to +7	V
V_I	Input voltage $\overline{RESET}$, CNVss, BYTE		–0.3 to +12 (Note)	V
V_I	Input voltage $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$, V_{REF}, X_{IN}		–0.3 to Vcc + 0.3	V
V_O	Output voltage $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$, X_{OUT}, $\overline{E}$		–0.3 to Vcc + 0.3	V
P_d	Power dissipation	Ta = 25 °C	200	mW
T_{opr}	Operating temperature		–40 to +85	°C
T_{stg}	Storage temperature		–65 to +150	°C

Note. When the EPROM is programmed, input voltage of pins CNV_{SS} and BYTE is 13 V respectively.

RECOMMENDED OPERATING CONDITIONS (Vcc = 2.7 – 5.5 V, Ta = –40 to +85 °C, unless otherwise noted)

Symbol	Parameter		Limits			Unit
			Min.	Typ.	Max.	
Vcc	Power source voltage	f(X_{IN}) : Operating	2.7		5.5	V
		f(X_{IN}) : Stopped, f(X_{CIN}) = 32.768 kHz	2.7		5.5	
AVcc	Analog power source voltage			Vcc		V
Vss	Power source voltage			0		V
AVss	Analog power source voltage			0		V
V_{IH}	High-level input voltage $P0_0$ – $P0_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$, X_{IN}, $\overline{RESET}$, CNV_{SS}, BYTE, X_{CIN} (Note 3)		0.8 Vcc		Vcc	V
V_{IH}	High-level input voltage $P1_0$ – $P1_7$, $P2_0$ – $P2_7$ (in single-chip mode)		0.8 Vcc		Vcc	V
V_{IH}	High-level input voltage $P1_0$ – $P1_7$, $P2_0$ – $P2_7$ (in memory expansion mode and microprocessor mode)		0.5 Vcc		Vcc	V
V_{IL}	Low-level input voltage $P0_0$ – $P0_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$, X_{IN}, $\overline{RESET}$, CNVss, BYTE, X_{CIN} (Note 3)		0		0.2Vcc	V
V_{IL}	Low-level input voltage $P1_0$ – $P1_7$, $P2_0$ – $P2_7$ (in single-chip mode)		0		0.2Vcc	V
V_{IL}	Low-level input voltage $P1_0$ – $P1_7$, $P2_0$ – $P2_7$ (in memory expansion mode and microprocessor mode)		0		0.16Vcc	V
$I_{OH(peak)}$	High-level peak output current $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$				–10	mA
$I_{OH(avg)}$	High-level average output current $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$				–5	mA
$I_{OL(peak)}$	Low-level peak output current $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_3$, $P5_4$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$				10	mA
$I_{OL(peak)}$	Low-level peak output current $P4_4$ – $P4_7$, $P5_0$ – $P5_3$				16	mA
$I_{OL(avg)}$	Low-level average output current $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_3$, $P5_4$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$				5	mA
$I_{OL(avg)}$	Low-level average output current $P4_4$ – $P4_7$, $P5_0$ – $P5_3$				12	mA
f(X_{IN})	Main-clock oscillation frequency (Note 4)				12	MHz
f(X_{CIN})	Sub-clock oscillation frequency			32.768	50	kHz

Notes 1. Average output current is the average value of a 100 ms interval.

2. The sum of $I_{OL(peak)}$ for ports P0, P1, P2, P3, and P8 must be 80 mA or less,
the sum of $I_{OH(peak)}$ for ports P0, P1, P2, P3, and P8 must be 80 mA or less,
the sum of $I_{OL(peak)}$ for ports P4, P5, P6, and P7 must be 100 mA or less, and
the sum of $I_{OH(peak)}$ for ports P4, P5, P6, and P7 must be 80 mA or less.

3. Limits V_{IH} and V_{IL} for X_{CIN} are applied when the sub clock external input selection bit = “1”.

4. The maximum value of f(X_{IN}) = 6 MHz when the main clock division selection bit = “1”.

ELECTRICAL CHARACTERISTICS (V_{CC} = 5 V, V_{SS} = 0 V, Ta = –40 to +85 °C, f(X_{IN}) = 12 MHz, unless otherwise noted)

Symbol	Parameter	Test conditions		Limits Min.	Limits Typ.	Limits Max.	Unit
V_{OH}	High-level output voltage $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$	V_{CC} = 5 V, I_{OH} = –10 mA		3			V
		V_{CC} = 3 V, I_{OH} = –1 mA		2.5			
V_{OH}	High-level output voltage $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_3$	V_{CC} = 5 V, I_{OH} = –400 µA		4.7			V
V_{OH}	High-level output voltage $P3_0$ – $P3_2$	V_{CC} = 5 V, I_{OH} = –10 mA		3.1			V
		V_{CC} = 5 V, I_{OH} = –400 µA		4.8			
		V_{CC} = 3 V, I_{OH} = –1 mA		2.6			
V_{OH}	High-level output voltage $\overline{E}$	V_{CC} = 5 V, I_{OH} = –10 mA		3.4			V
		V_{CC} = 5 V, I_{OH} = –400 µA		4.8			
		V_{CC} = 3 V, I_{OH} = –1 mA		2.6			
V_{OL}	Low-level output voltage $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_3$, $P4_0$ – $P4_3$, $P5_4$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$	V_{CC} = 5 V, I_{OL} = 10 mA				2	V
		V_{CC} = 3 V, I_{OL} = 1 mA				0.5	
V_{OL}	Low-level output voltage $P4_4$ – $P4_7$, $P5_0$ – $P5_3$	V_{CC} = 5 V, I_{OL} = 16 mA				1.8	V
		V_{CC} = 3 V, I_{OL} = 10 mA				1.5	
V_{OL}	Low-level output voltage $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_3$	V_{CC} = 5 V, I_{OL} = 2 mA				0.45	V
V_{OL}	Low-level output voltage $P3_0$ – $P3_2$	V_{CC} = 5 V, I_{OL} = 10 mA				1.9	V
		V_{CC} = 5 V, I_{OL} = 2 mA				0.43	
		V_{CC} = 3 V, I_{OL} = 1 mA				0.4	
V_{OL}	Low-level output voltage $\overline{E}$	V_{CC} = 5 V, I_{OL} = 10 mA				1.6	V
		V_{CC} = 5 V, I_{OL} = 2 mA				0.4	
		V_{CC} = 3 V, I_{OL} = 1 mA				0.4	
$V_{T+} – V_{T–}$	Hysteresis $\overline{HOLD}$, $\overline{RDY}$, $TA0_{IN}$ – $TA4_{IN}$, $TB0_{IN}$ – $TB2_{IN}$, $\overline{INT_0}$ – $\overline{INT_2}$, $\overline{AD_{TRG}}$, $\overline{CTS_0}$, $\overline{CTS_1}$, $\overline{CTS_2}$, CLK_0, CLK_1, CLK_2, $\overline{KI_0}$ – $\overline{KI_3}$	V_{CC} = 5 V		0.4		1	V
		V_{CC} = 3 V		0.1		0.7	
$V_{T+} – V_{T–}$	Hysteresis $\overline{RESET}$	V_{CC} = 5 V		0.2		0.5	V
		V_{CC} = 3 V		0.1		0.4	
$V_{T+} – V_{T–}$	Hysteresis X_{IN}	V_{CC} = 5 V		0.1		0.4	V
		V_{CC} = 3 V		0.06		0.26	
$V_{T+} – V_{T–}$	Hysteresis X_{CIN} (When external clock is input)	V_{CC} = 5 V		0.1		0.4	V
		V_{CC} = 3 V		0.06		0.26	
I_{IH}	High-level input current $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_7$, $P6_0$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$, X_{IN}, $\overline{RESET}$, CNVss, BYTE	V_{CC} = 5 V, V_I = 5 V				5	µA
		V_{CC} = 3 V, V_I = 3 V				4	
I_{IL}	Low-level input current $P0_0$ – $P0_7$, $P1_0$ – $P1_7$, $P2_0$ – $P2_7$, $P3_0$ – $P3_3$, $P4_0$ – $P4_7$, $P5_0$ – $P5_3$, $P6_0$, $P6_1$, $P6_5$ – $P6_7$, $P7_0$ – $P7_7$, $P8_0$ – $P8_7$, X_{IN}, $\overline{RESET}$, CNVss, BYTE	V_{CC} = 5 V, V_I = 0 V				–5	µA
		V_{CC} = 3 V, V_I = 0 V				–4	
I_{IL}	Low-level input current $P5_4$ – $P5_7$, $P6_2$ – $P6_4$	V_I = 0 V, without a pull-up transistor	V_{CC} = 5 V			–5	µA
			V_{CC} = 3 V			–4	
		V_I = 0 V, with a pull-up transistor	V_{CC} = 5 V	–0.25	–0.5	–1.0	mA
			V_{CC} = 3 V	–0.08	–0.18	–0.35	
V_{RAM}	RAM hold voltage	When clock is stopped.		2			V

ELECTRICAL CHARACTERISTICS (V_{CC} = 5 V, V_{SS} = 0 V, Ta = –40 to +85 °C, unless otherwise noted)

Symbol	Parameter	Test conditions		Limits			Unit
				Min.	Typ.	Max.	
I_{CC}	Power source current	When single-chip mode, output pins are open, and other pins are V_{SS}.	V_{CC} = 5 V, $f(X_{IN})$ = 12 MHz (square waveform), ($f(f_2)$ = 6 MHz), $f(X_{CIN})$ = 32.768 kHz, in operating (Note 1)		4.5	9	mA
			V_{CC} = 3 V, $f(X_{IN})$ = 12 MHz (square waveform), ($f(f_2)$ = 6 MHz), $f(X_{CIN})$ = 32.768 kHz, in operating (Note 1)		3	6	mA
			V_{CC} = 3 V, $f(X_{IN})$ = 12 MHz (square waveform), ($f(f_2)$ = 0.75 MHz), $f(X_{CIN})$: Stopped, in operating		0.4	0.8	mA
			V_{CC} = 3 V, $f(X_{IN})$ = 12 MHz (square waveform), $f(X_{CIN})$ = 32.768 kHz, when a WIT instruction is executed (Note 2)		6	12	µA
			V_{CC} = 3 V, $f(X_{IN})$: Stopped, $f(X_{CIN})$ = 32.768 kHz, in operating (Note 3)		30	60	µA
			V_{CC} = 3 V, $f(X_{IN})$: Stopped, $f(X_{CIN})$ = 32.768 kHz, when a WIT instruction is executed (Note 4)		3	6	µA
			Ta = 25 °C, when clock is stopped			1	µA
			Ta = 85 °C, when clock is stopped			20	µA

Notes 1. This applies when the main clock external input selection bit = "1", the main clock division selection bit = "0", and the signal output stop bit = "1".

2. This applies when the main clock external input selection bit = "1" and the system clock stop bit at wait state = "1".

3. This applies when CPU and the clock timer are operating with the sub clock (32.768 kHz) selected as the system clock.

4. This applies when the X_{COUT} drivability selection bit = "0" and the system clock stop bit at wait state = "1".

A–D CONVERTER CHARACTERISTICS

(V_{CC} = AV_{CC} = 5 V, V_{SS} = AV_{SS} = 0 V, Ta = –40 to +85 °C, $f(X_{IN})$ = 12 MHz, unless otherwise noted (Note))

Symbol	Parameter	Test conditions	Limits			Unit
			Min.	Typ.	Max.	
—	Resolution	V_{REF} = V_{CC}			10	Bits
—	Absolute accuracy	V_{REF} = V_{CC}			± 3	LSB
R_{LADDER}	Ladder resistance	V_{REF} = V_{CC}	10		25	kΩ
t_{CONV}	Conversion time		19.6			µs
V_{REF}	Reference voltage		2.7		V_{CC}	V
V_{IA}	Analog input voltage		0		V_{REF}	V

Note. This applies when the main clock division selection bit = "0" and $f(f_2)$ = 6 MHz.

TIMING REQUIREMENTS (V_{CC} = 2.7 – 5.5 V, V_{SS} = 0 V, Ta = –40 to +85 °C, f(X_{IN}) = 12 MHz, unless otherwise noted (Note 1))

Notes 1. This applies when the main clock division selection bit = "0" and f(f_2) = 6 MHz.

2. Input signal's rise/fall time must be 100 ns or less, unless otherwise noted.

External clock input

Symbol	Parameter	Limits		Unit
		Min.	Max.	
t_c	External clock input cycle time (Note 1)	83		ns
$t_{w(H)}$	External clock input high-level pulse width (Note 2)	33		ns
$t_{w(L)}$	External clock input low-level pulse width (Note 2)	33		ns
t_r	External clock rise time		15	ns
t_f	External clock fall time		15	ns

Notes 1. When the main clock division selection bit = "1", the minimum value of t_c = 166 ns.

2. When the main clock division selection bit = "1", values of $t_{w(H)}$ / t_c and $t_{w(L)}$ / t_c must be set to values from 0.45 through 0.55.

Single-chip mode

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{su(P0D–E)}$	Port P0 input setup time	200		ns
$t_{su(P1D–E)}$	Port P1 input setup time	200		ns
$t_{su(P2D–E)}$	Port P2 input setup time	200		ns
$t_{su(P3D–E)}$	Port P3 input setup time	200		ns
$t_{su(P4D–E)}$	Port P4 input setup time	200		ns
$t_{su(P5D–E)}$	Port P5 input setup time	200		ns
$t_{su(P6D–E)}$	Port P6 input setup time	200		ns
$t_{su(P7D–E)}$	Port P7 input setup time	200		ns
$t_{su(P8D–E)}$	Port P8 input setup time	200		ns
$t_{h(E–P0D)}$	Port P0 input hold time	0		ns
$t_{h(E–P1D)}$	Port P1 input hold time	0		ns
$t_{h(E–P2D)}$	Port P2 input hold time	0		ns
$t_{h(E–P3D)}$	Port P3 input hold time	0		ns
$t_{h(E–P4D)}$	Port P4 input hold time	0		ns
$t_{h(E–P5D)}$	Port P5 input hold time	0		ns
$t_{h(E–P6D)}$	Port P6 input hold time	0		ns
$t_{h(E–P7D)}$	Port P7 input hold time	0		ns
$t_{h(E–P8D)}$	Port P8 input hold time	0		ns

Memory expansion mode and microprocessor mode

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{su(D–E)}$	Data input setup time	50		ns
$t_{su(RDY–\ 1)}$	$\overline{RDY}$ input setup time	80		ns
$t_{su(HOLD–\ 1)}$	$\overline{HOLD}$ input setup time	80		ns
$t_{h(E–D)}$	Data input hold time	0		ns
$t_{h(\ 1–RDY)}$	$\overline{RDY}$ input hold time	0		ns
$t_{h(\ 1–HOLD)}$	$\overline{HOLD}$ input hold time	0		ns

Timer A input (Count input in event counter mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time	250		ns
$t_{w(TAH)}$	TAiIN input high-level pulse width	125		ns
$t_{w(TAL)}$	TAiIN input low-level pulse width	125		ns

Timer A input (Gating input in timer mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time (Note)	666		ns
$t_{w(TAH)}$	TAiIN input high-level pulse width (Note)	333		ns
$t_{w(TAL)}$	TAiIN input low-level pulse width (Note)	333		ns

Note. Limits change depending on f(XIN). Refer to “DATA FORMULAS” on page 20.

Timer A input (External trigger input in one-shot pulse mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time (Note)	666		ns
$t_{w(TAH)}$	TAiIN input high-level pulse width	166		ns
$t_{w(TAL)}$	TAiIN input low-level pulse width	166		ns

Note. Limits change depending on f(XIN). Refer to “DATA FORMULAS” on page 20.

Timer A input (External trigger input in pulse width modulation mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{w(TAH)}$	TAiIN input high-level pulse width	166		ns
$t_{w(TAL)}$	TAiIN input low-level pulse width	166		ns

Timer A input (Up-down input in event counter mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(UP)}$	TAiOUT input cycle time	3333		ns
$t_{w(UPH)}$	TAiOUT input high-level pulse width	1666		ns
$t_{w(UPL)}$	TAiOUT input low-level pulse width	1666		ns
$t_{su(UP-TIN)}$	TAiOUT input setup time	666		ns
$t_{h(TIN-UP)}$	TAiOUT input hold time	666		ns

Timer A input (Two-phase pulse input in event counter mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TA)}$	TAjIN input cycle time	2000		ns
$t_{su(TAjIN-TAjOUT)}$	TAjIN input setup time	500		ns
$t_{su(TAjOUT-TAjIN)}$	TAjOUT input setup time	500		ns

Timer B input (Count input in event counter mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time (one edge count)	250		ns
$t_{w(TBH)}$	TBiIN input high-level pulse width (one edge count)	125		ns
$t_{w(TBL)}$	TBiIN input low-level pulse width (one edge count)	125		ns
$t_{c(TB)}$	TBiIN input cycle time (both edges count)	500		ns
$t_{w(TBH)}$	TBiIN input high-level pulse width (both edges count)	250		ns
$t_{w(TBL)}$	TBiIN input low-level pulse width (both edges count)	250		ns

Timer B input (Pulse period measurement mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time (Note)	666		ns
$t_{w(TBH)}$	TBiIN input high-level pulse width (Note)	333		ns
$t_{w(TBL)}$	TBiIN input low-level pulse width (Note)	333		ns

Note. Limits change depending on f(XIN). Refer to “DATA FORMULAS” on page 20.

Timer B input (Pulse width measurement mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time (Note)	666		ns
$t_{w(TBH)}$	TBiIN input high-level pulse width (Note)	333		ns
$t_{w(TBL)}$	TBiIN input low-level pulse width (Note)	333		ns

Note. Limits change depending on f(XIN). Refer to “DATA FORMULAS” on page 20.

A-D trigger input

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(AD)}$	$\overline{\text{ADTRG}}$ input cycle time (minimum allowable trigger)	1333		ns
$t_{w(ADL)}$	$\overline{\text{ADTRG}}$ input low-level pulse width	166		ns

Serial I/O

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(CK)}$	CLKi input cycle time	333		ns
$t_{w(CKH)}$	CLKi input high-level pulse width	166		ns
$t_{w(CKL)}$	CLKi input low-level pulse width	166		ns
$t_{d(C-Q)}$	TxDi output delay time		100	ns
$t_{h(C-Q)}$	TxDi hold time	0		ns
$t_{su(D-C)}$	RxDi input setup time	65		ns
$t_{h(C-D)}$	RxDi input hold time	75		ns

External interrupt $\overline{\text{INT}}_i$ input, key input interrupt $\overline{\text{KI}}_i$ input

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{w(INH)}$	$\overline{\text{INT}}_i$ input high-level pulse width	250		ns
$t_{w(INL)}$	$\overline{\text{INT}}_i$ input low-level pulse width	250		ns
$t_{w(KIL)}$	$\overline{\text{KI}}_i$ input low-level pulse width	250		ns

DATA FORMULAS

Timer A input (Gating input in timer mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time	$\frac{8 \times 10^9}{2 \cdot f(f_2)}$		ns
$t_{w(TAH)}$	TAiIN input high-level pulse width	$\frac{4 \times 10^9}{2 \cdot f(f_2)}$		ns
$t_{w(TAL)}$	TAiIN input low-level pulse width	$\frac{4 \times 10^9}{2 \cdot f(f_2)}$		ns

Timer A input (External trigger input in one-shot pulse mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiIN input cycle time	$\frac{8 \times 10^9}{2 \cdot f(f_2)}$		ns

Timer B input (In pulse period measurement mode or pulse width measurement mode)

Symbol	Parameter	Limits		Unit
		Min.	Max.	
$t_{c(TB)}$	TBiIN input cycle time	$\frac{8 \times 10^9}{2 \cdot f(f_2)}$		ns
$t_{w(TBH)}$	TBiIN input high-level pulse width	$\frac{4 \times 10^9}{2 \cdot f(f_2)}$		ns
$t_{w(TBL)}$	TBiIN input low-level pulse width	$\frac{4 \times 10^9}{2 \cdot f(f_2)}$		ns

Note. $f(f_2)$ represents the clock f_2 frequency.
For the relation to the main clock and sub clock, refer to Table 9 in data sheet “M37733MHBXXXFP”.

SWITCHING CHARACTERISTICS

(V_{CC} = 2.7 – 5.5 V, V_{SS} = 0 V, Ta = –40 to +85°C, f(X_{IN}) = 12 MHz, unless otherwise noted (Note))

Single-chip mode

Symbol	Parameter	Test conditions	Limits		Unit
			Min.	Max.	
$t_{d(E-P0Q)}$	Port P0 data output delay time	Fig. 6		300	ns
$t_{d(E-P1Q)}$	Port P1 data output delay time			300	ns
$t_{d(E-P2Q)}$	Port P2 data output delay time			300	ns
$t_{d(E-P3Q)}$	Port P3 data output delay time			300	ns
$t_{d(E-P4Q)}$	Port P4 data output delay time			300	ns
$t_{d(E-P5Q)}$	Port P5 data output delay time			300	ns
$t_{d(E-P6Q)}$	Port P6 data output delay time			300	ns
$t_{d(E-P7Q)}$	Port P7 data output delay time			300	ns
$t_{d(E-P8Q)}$	Port P8 data output delay time			300	ns

Note. This applies when the main clock division selection bit = "0" and f(f_2) = 6 MHz.

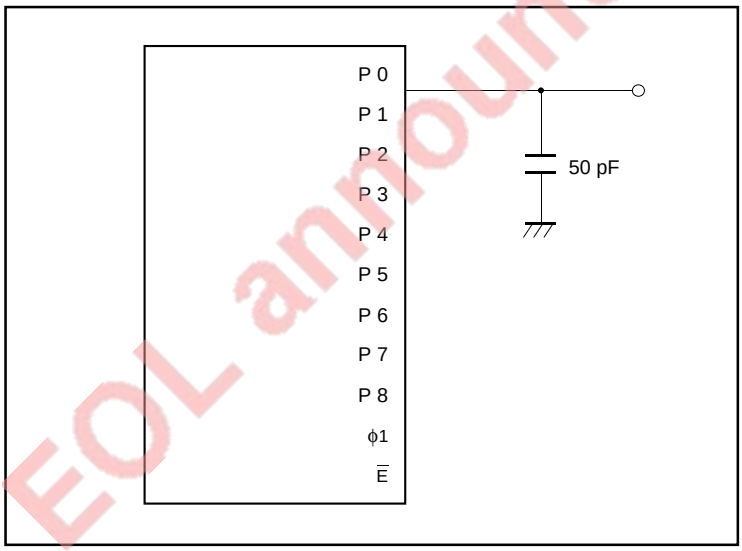


Fig. 6 Measuring circuit for ports P0 – P8 and ϕ_1

Memory expansion mode and microprocessor mode

(V_{CC} = 2.7 – 5.5 V, V_{SS} = 0 V, Ta = –40 to +85°C, f(X_{IN}) = 12 MHz (Note 1), unless otherwise noted)

Symbol	Parameter	(Note 2) Wait mode	Test conditions	Limits Min.	Limits Max.	Unit
$t_{d(An–E)}$	Address output delay time	No wait Wait 1	Fig. 6	20		ns
		Wait 0		182		ns
$t_{d(A–E)}$	Address output delay time	No wait Wait 1		20		ns
		Wait 0		162		ns
$t_{h(E–An)}$	Address hold time			40		ns
$t_{w(ALE)}$	ALE pulse width	No wait Wait 1		40		ns
		Wait 0		123		ns
$t_{su(A–ALE)}$	Address output setup time	No wait Wait 1		10		ns
		Wait 0		93		ns
$t_{h(ALE–A)}$	Address hold time	No wait Wait 1		9		ns
		Wait 0		40		ns
$t_{d(ALE–E)}$	ALE output delay time	No wait Wait 1		4		ns
		Wait 0		40		ns
$t_{d(E–DQ)}$	Data output delay time				90	ns
$t_{h(E–DQ)}$	Data hold time			40		ns
$t_{w(EL)}$	$\overline{E}$ pulse width	No wait		131		ns
		Wait 1 Wait 0		298		ns
$t_{pxz(E–DZ)}$	Floating start delay time				10	ns
$t_{pzx(E–DZ)}$	Floating release delay time			53		ns
$t_{d(BHE–E)}$	$\overline{BHE}$ output delay time	No wait Wait 1		20		ns
		Wait 0		182		ns
$t_{d(R/W–E)}$	R/$\overline{W}$ output delay time	No wait Wait 1		20		ns
		Wait 0		182		ns
$t_{h(E–BHE)}$	$\overline{BHE}$ hold time			33		ns
$t_{h(E–R/W)}$	R/$\overline{W}$ hold time			33		ns
$t_{d(E–\phi 1)}$	ϕ_1 output delay time			0	30	ns
$t_{d(\phi 1–HLDA)}$	$\overline{HLDA}$ output delay time				120	ns

Notes 1. This applies when the main clock division selection bit = “0” and f(f_2) = 6 MHz.

2. No wait : Wait bit = “1”.
Wait 1 : The external memory area is accessed with wait bit = “0” and wait selection bit = “1”.
Wait 0 : The external memory area is accessed with wait bit = “0” and wait selection bit = “0”.

Memory expansion mode and microprocessor mode

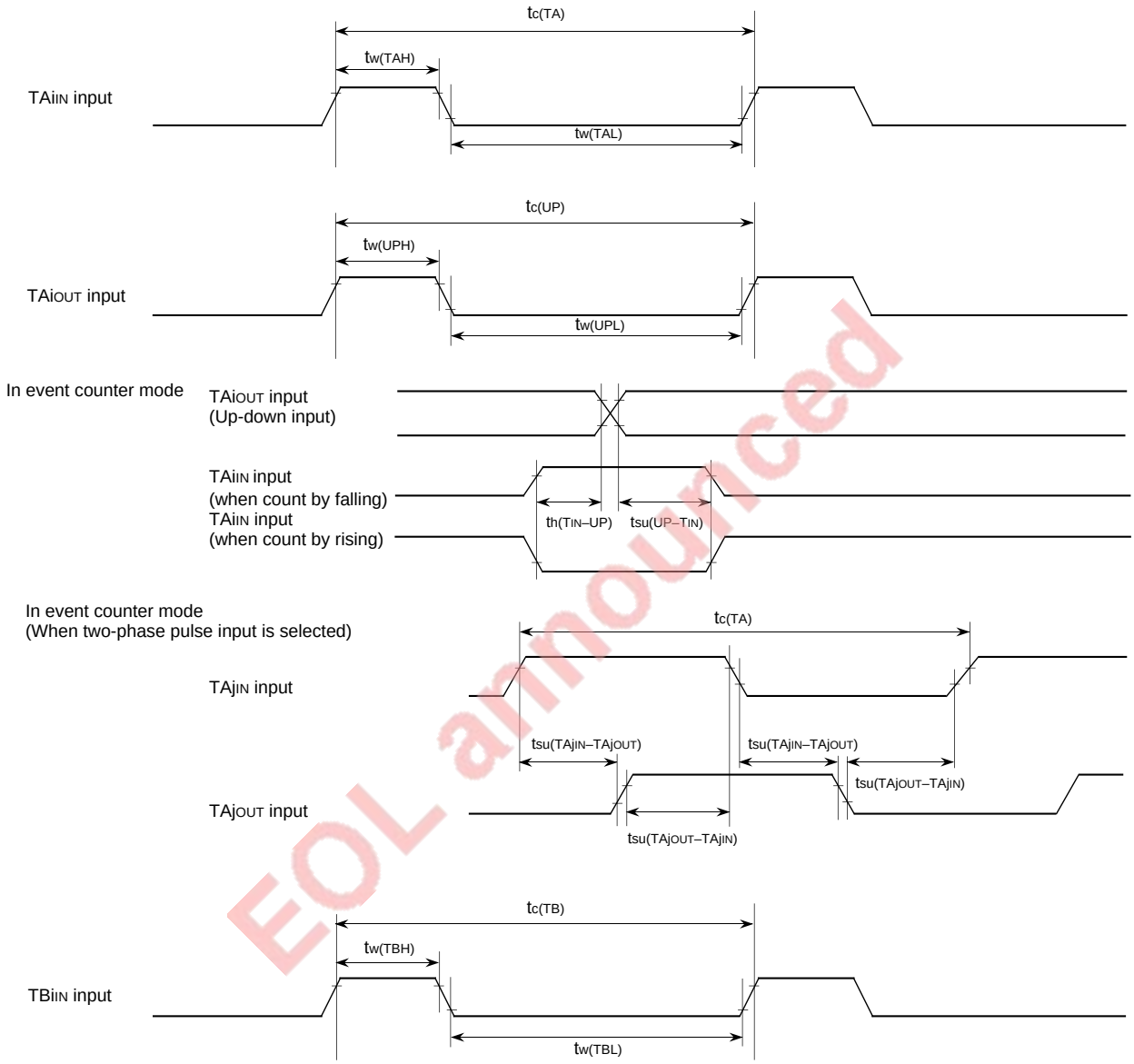
Bus timing data formulas (V_{CC} = 2.7 – 5.5 V, V_{SS} = 0 V, Ta = –40 to +85 °C, f(X_{IN}) = 12 MHz (Max., Note 1), unless otherwise noted)

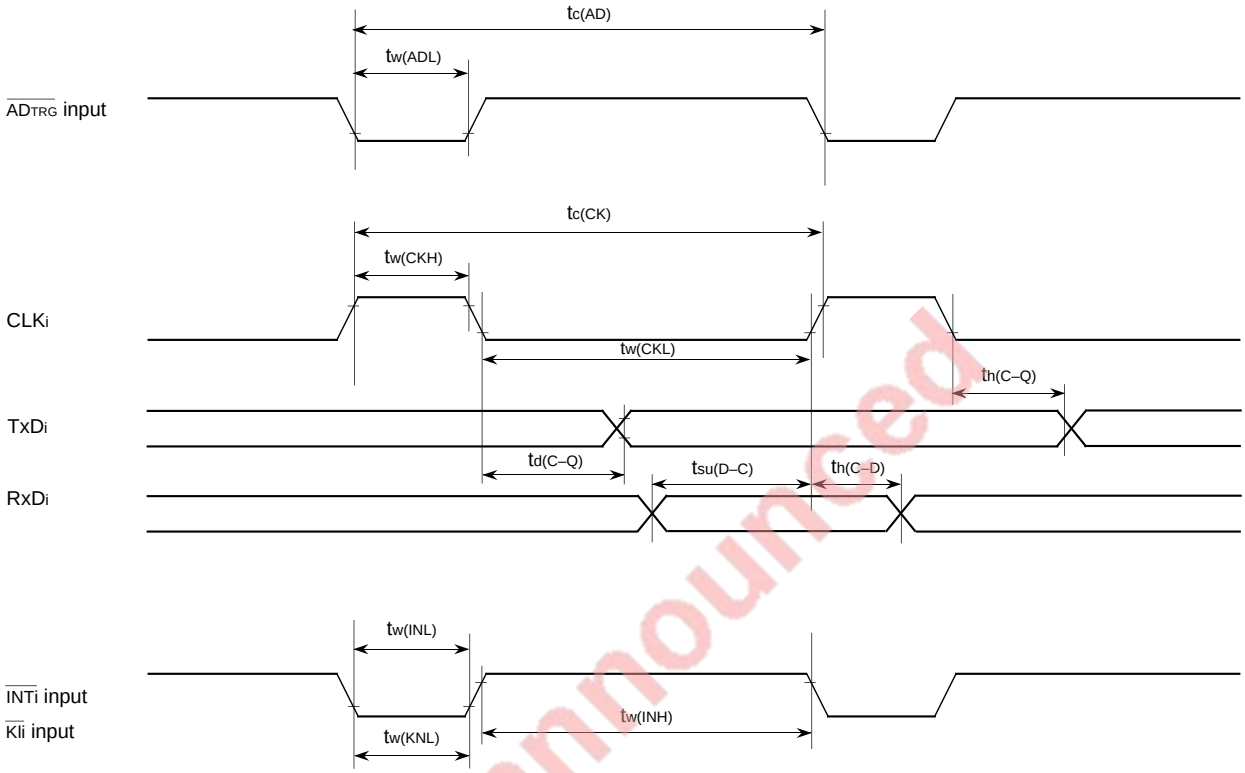
Symbol	Parameter	Wait mode	Limits Min.	Limits Max.	Unit
$t_{d(An-E)}$	Address output delay time	No wait Wait 1	$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 63$		ns
		Wait 0	$\frac{3 \times 10^9}{2 \cdot f(f_2)} - 68$		ns
$t_{d(A-E)}$	Address output delay time	No wait Wait 1	$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 63$		ns
		Wait 0	$\frac{3 \times 10^9}{2 \cdot f(f_2)} - 88$		ns
$t_{h(E-An)}$	Address hold time		$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 43$		ns
$t_{w(ALE)}$	ALE pulse width	No wait Wait 1	$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 43$		ns
		Wait 0	$\frac{2 \times 10^9}{2 \cdot f(f_2)} - 43$		ns
$t_{su(A-ALE)}$	Address output setup time	No wait Wait 1	$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 73$		ns
		Wait 0	$\frac{2 \times 10^9}{2 \cdot f(f_2)} - 73$		ns
$t_{h(ALE-A)}$	Address hold time	No wait Wait 1	9		ns
		Wait 0	$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 43$		ns
$t_{d(ALE-E)}$	ALE output delay time	No wait Wait 1	4		ns
		Wait 0	$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 43$		ns
$t_{d(E-DQ)}$	Data output delay time			90	ns
$t_{h(E-DQ)}$	Data hold time		$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 43$		ns
$t_{w(EL)}$	$\overline{E}$ pulse width	No wait	$\frac{2 \times 10^9}{2 \cdot f(f_2)} - 35$		ns
		Wait 1 Wait 0	$\frac{4 \times 10^9}{2 \cdot f(f_2)} - 35$		ns
$t_{pxz(E-DZ)}$	Floating start delay time			10	ns
$t_{pzx(E-DZ)}$	Floating release delay time		$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 30$		ns
$t_{d(BHE-E)}$	$\overline{BHE}$ output delay time	No wait Wait 1	$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 63$		ns
		Wait 0	$\frac{3 \times 10^9}{2 \cdot f(f_2)} - 68$		ns
$t_{d(R/W-E)}$	R/$\overline{W}$ output delay time	No wait Wait 1	$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 63$		ns
		Wait 0	$\frac{3 \times 10^9}{2 \cdot f(f_2)} - 68$		ns
$t_{h(E-BHE)}$	$\overline{BHE}$ hold time		$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 50$		ns
$t_{h(E-R/W)}$	R/$\overline{W}$ hold time		$\frac{1 \times 10^9}{2 \cdot f(f_2)} - 50$		ns
$t_{d(E-\phi 1)}$	ϕ_1 output delay time		0	30	ns

Notes 1. This applies when the main-clock division selection bit = “0”.

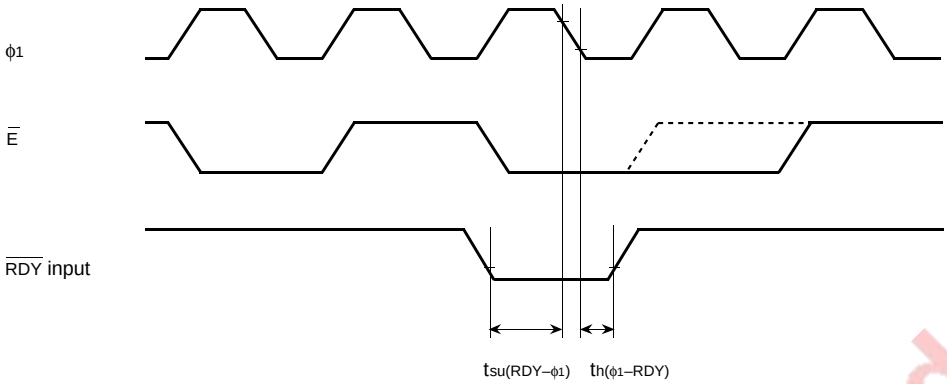
2. f(f_2) represents the clock f_2 frequency.
For the relation to the main clock and sub clock, refer to Table 9 in data sheet “M37733MHBXXXFP”.

TIMING DIAGRAM

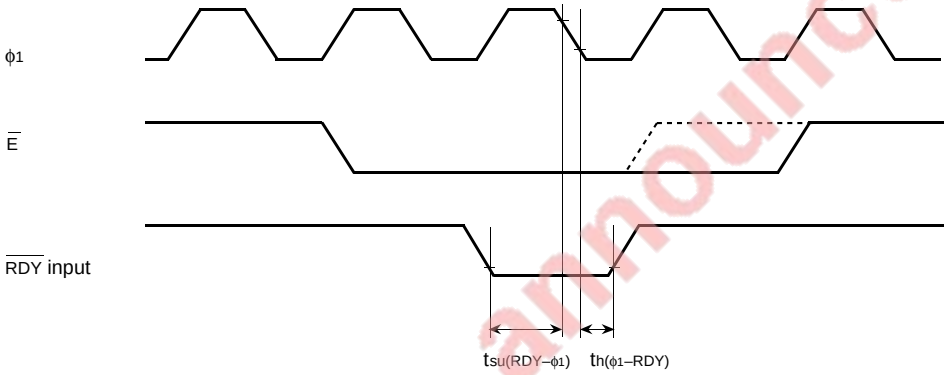




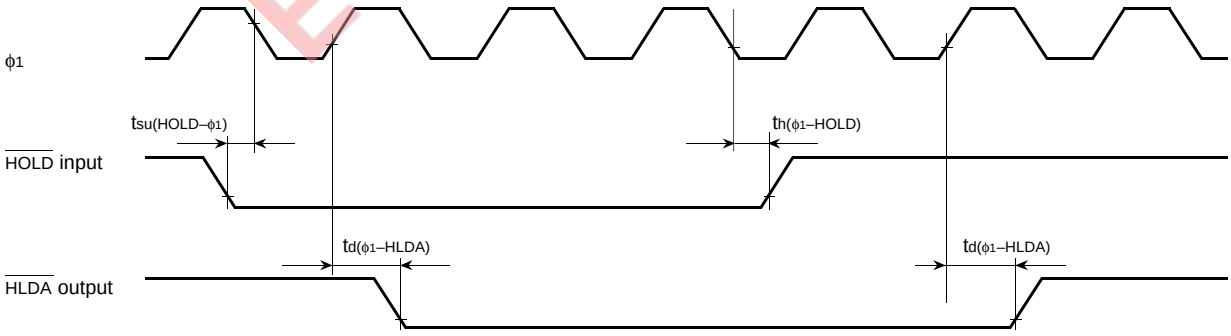
Memory expansion mode and microprocessor mode
(When wait bit = “1”)



(When wait bit = “0”)

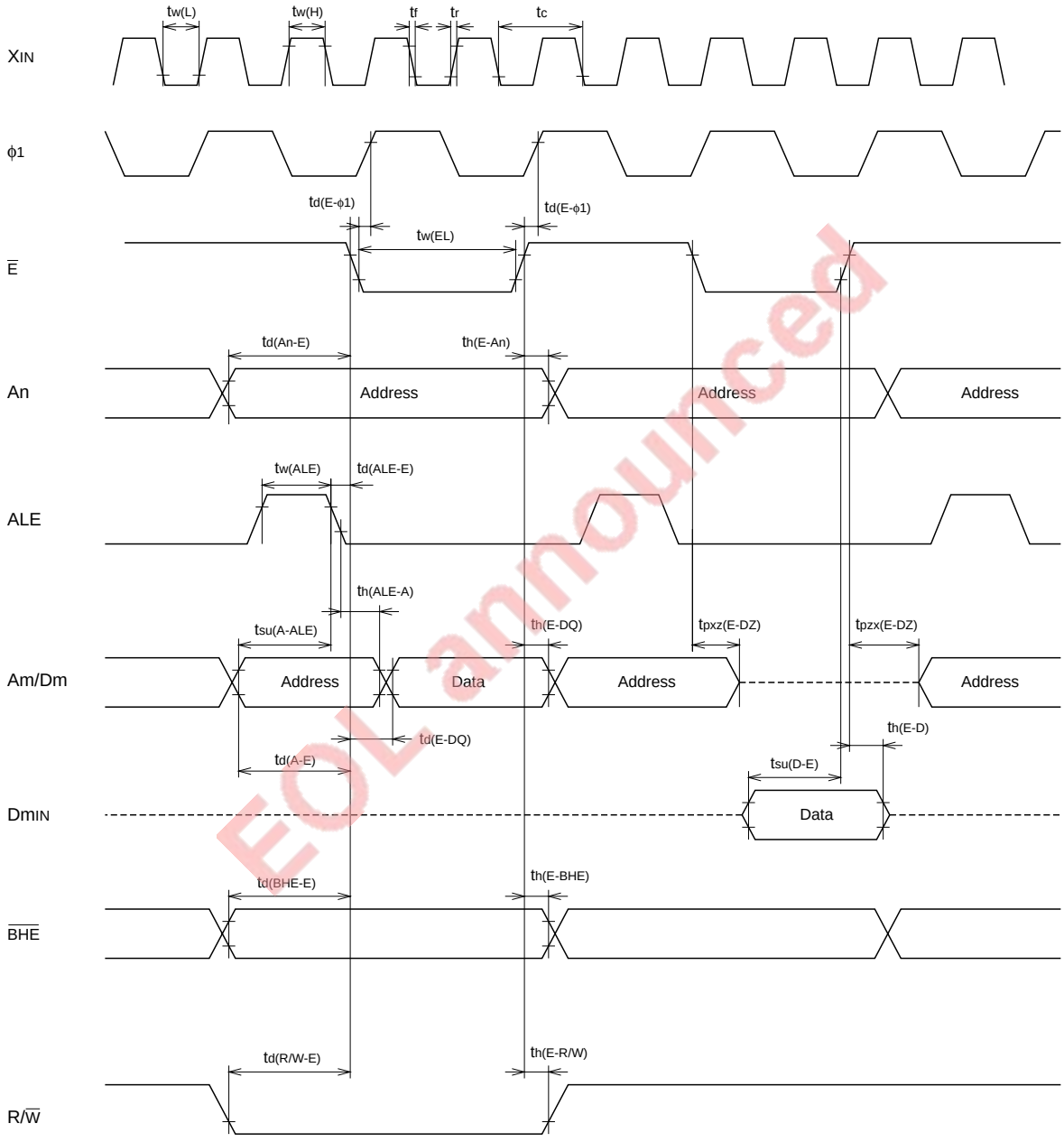


(When wait bit = “1” or “0” in common)



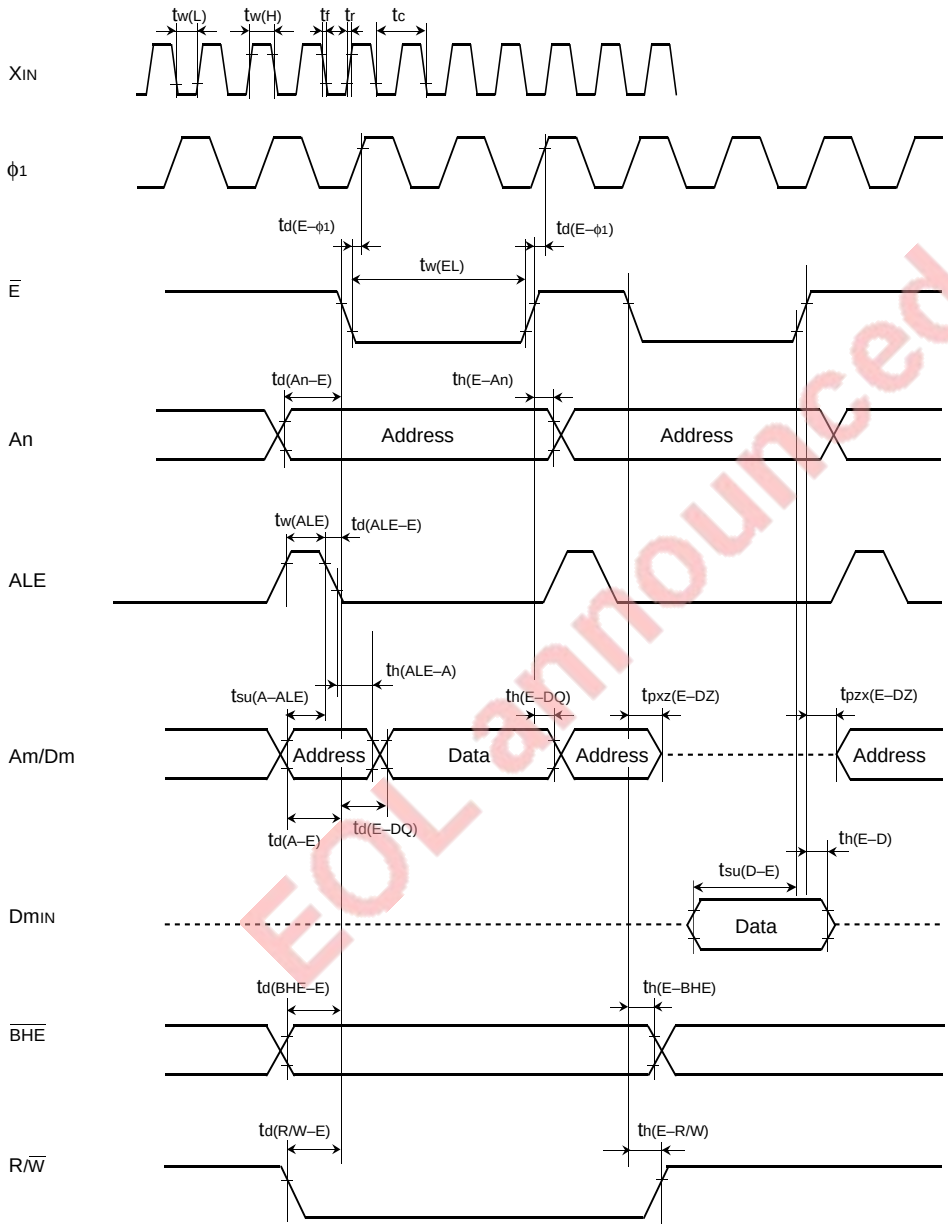
Test conditions
- V_{CC} = 2.7 – 5.5 V
- Input timing voltage : V_{IL} = 0.2 V_{CC}, V_{IH} = 0.8 V_{CC}
- Output timing voltage : V_{OL} = 0.8 V, V_{OH} = 2.0 V

Memory expansion mode and microprocessor mode
(No wait : When wait bit = "1")



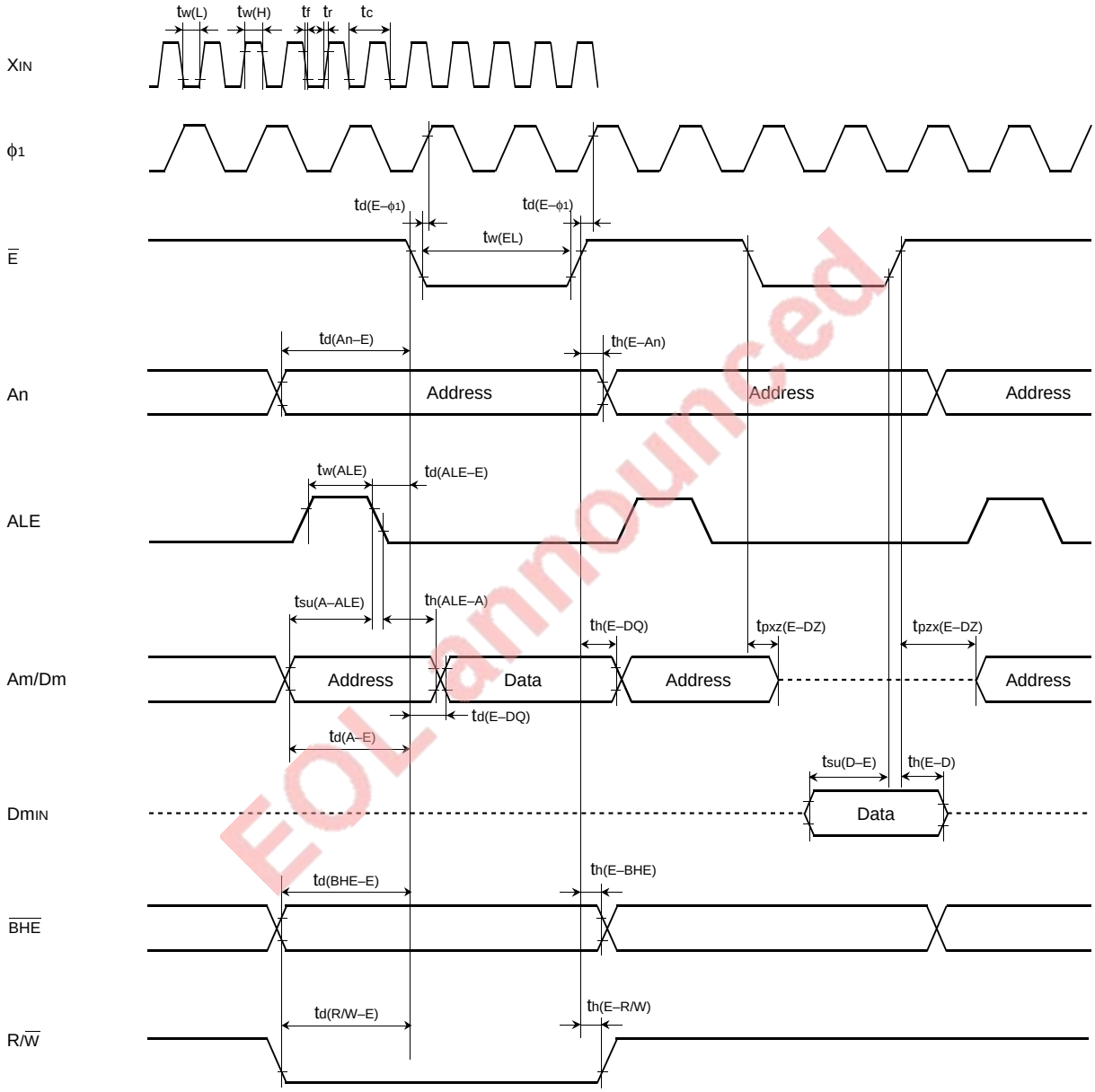
Test conditions
- V_{CC} = 2.7 – 5.5 V
- Output timing voltage : V_{OL} = 0.8 V, V_{OH} = 2.0 V
- Data input Dm_{IN} : V_{IL} = 0.16 V_{CC}, V_{IH} = 0.5 V_{CC}

Memory expansion mode and microprocessor mode
(Wait 1 : The external memory area is accessed when wait bit = “0” and wait selection bit = “1”.)



Test conditions
• Vcc = 2.7 – 5.5 V
• Output timing voltage : VOL = 0.8 V, VOH = 2.0 V
• Data input DmIN : VIL = 0.16 Vcc, VIH = 0.5 Vcc

Memory expansion mode and microprocessor mode
(Wait 0 : The external memory area is accessed when wait bit = “0” and wait selection bit = “0”.)



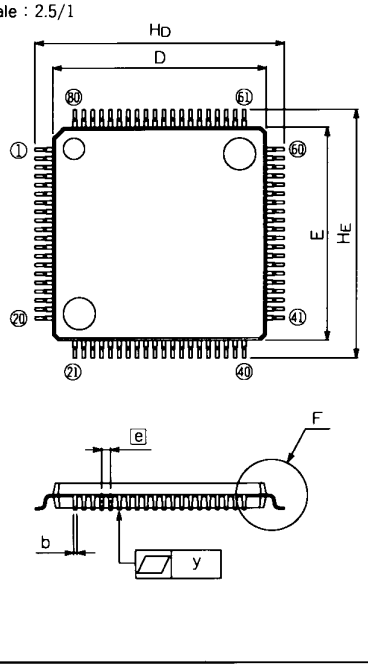
Test conditions
• Vcc = 2.7 – 5.5 V
• Output timing voltage : V_{OL} = 0.8 V, V_{OH} = 2.0 V
• Data input Dm_{IN} : V_{IL} = 0.16 Vcc, V_{IH} = 0.5 Vcc

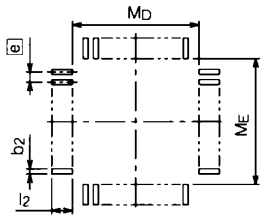
PACKAGE OUTLINE

80P6D−A — Plastic 80pin 12×12mm body LQFP

EIAJ Package Code	JEDEC Code	Weight(g)	Lead Material
LQFP80-P-1212-0.50	—	0.44	Alloy 42

Scale : 2.5/1





Recommended Mount Pad

Symbol	Dimension in Millimeters		
	Min	Nom	Max
A	—	—	1.7
A_1	0	0.1	0.2
A_2	—	1.4	—
b	0.13	0.18	0.28
c	0.105	0.125	0.175
D	11.9	12.0	12.1
E	11.9	12.0	12.1
e	—	0.5	—
H_D	13.8	14.0	14.2
H_E	13.8	14.0	14.2
L	0.3	0.5	0.7
L_1	—	1.0	—
y	—	—	0.1
θ	0°	—	10°
b_2	—	0.225	—
l_2	1.0	—	—
M_D	—	12.4	—
M_E	—	12.4	—

GZZ–SH00–42B<68A0>

ROM number	

Receipt	Date:	
	Section head signature	Supervisor signature

7700 FAMILY WRITING TO PROM ORDER CONFIRMATION FORM
SINGLE-CHIP 16-BIT MICROCOMPUTER
M37733EHLXXXHP
MITSUBISHI ELECTRIC

Note : Please fill in all items marked ※

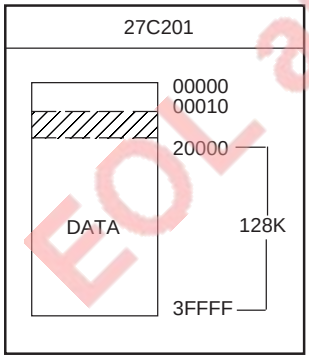
					Issuance signatures	Responsible officer	Supervisor
※	Customer	Company name	TEL ( )				
		Date issued	Date:				

※1. Confirmation

Specify the name of the product being ordered and the type of EPROMs submitted.
Three sets of EPROMs are required for each pattern.
If at least two of the three sets of EPROMs submitted contain the identical data, we will produce writing to PROM based on this data. We shall assume the responsibility for errors only if the written PROM data on the products we produce differ from this data. Thus, the customer must be especially careful in verifying the data contained in the EPROMs submitted.

Checksum code for entire EPROM areas | | | | | (hexadecimal notation)

EPROM Type :



(1) Set "FF16" in the shaded area.
(2) Address 016 to 0F16 are the area for storing the data on model designation.This area must be written with the data shown below.
Address and data are written in hexadecimal notation.

Address		Address	
4D	0	4C	8
33	1	FF	9
37	2	FF	A
37	3	FF	B
33	4	FF	C
33	5	FF	D
45	6	FF	E
48	7	FF	F

※2. Mark specification

Mark specification must be submitted using the correct form for the type of package being ordered fill out the appropriate 80P6D Mark Specification Form (for M37733EHLXXXHP) and attach to the Writing to PROM Order Confirmation Form.

※3. Comments

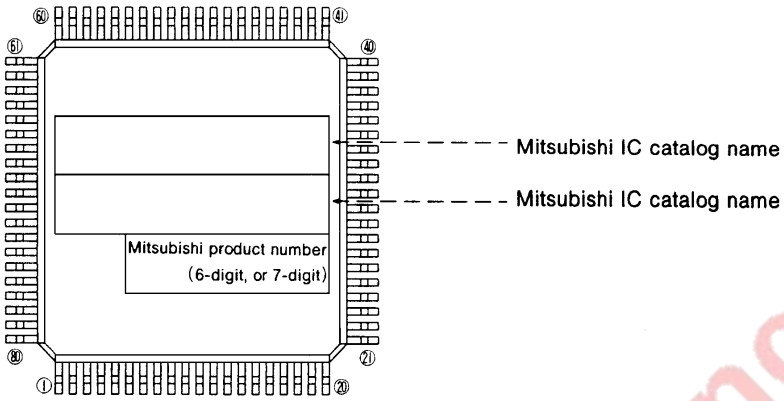
PROM VERSION OF M37733MHLXXXHP

80P6S (80-PIN QFP) MARK SPECIFICATION FORM
80P6D (80-PIN Fine-pitch QFP)

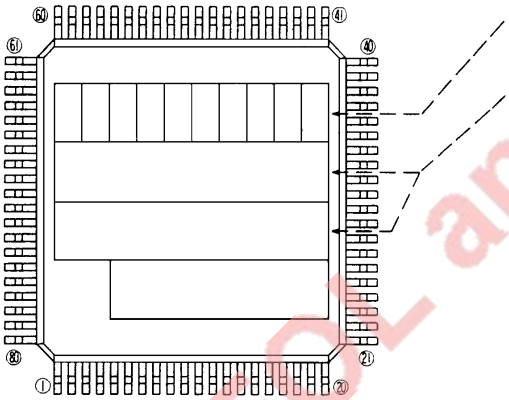
Mitsubishi IC catalog name

Please choose one of the marking types below (A, B, C), and enter the Mitsubishi IC catalog name and the special mark (if needed).

A. Standard Mitsubishi Mark

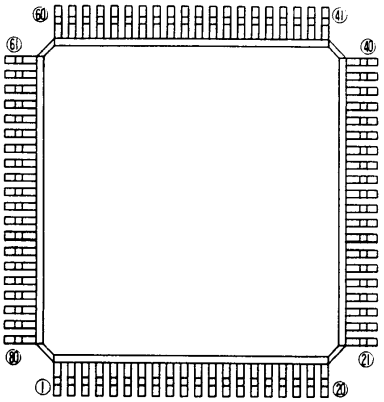


B. Customer's Parts Number + Mitsubishi IC Catalog Name



Notes1 : The mark field should be written right aligned.
2 : The fonts and size of characters are standard Mitsubishi type.
3 : Customer's parts number can be up to 10 alphanumeric characters for capital letters, hyphens, commas, periods and so on.

C. Special Mark Required



Notes1 : If special mark is to be printed, indicate the desired layout of the mark in the left figure. The layout will be duplicated technically as close as possible. Mitsubishi product number (6-digit, or 7-digit) and Mask ROM number (3-digit) are always marked for sorting the products.
2 : If special character fonts (e.g., customer's trade mark logo) must be used in Special Mark, check the box below.
For the new special character fonts a clean font original (ideally logo drawing) must be submitted.

Special character fonts required ☐

MITSUBISHI MICROCOMPUTERS

M37733EHLXXXHP

PROM VERSION OF M37733MHLXXXHP

Renesas Technology Corp.
Nippon Bldg.,6-2,Otemachi 2-chome,Chiyoda-ku,Tokyo,100-0004 Japan

H-LF447-A KI-9610 Printed in Japan (ROD) II
New publication, effective Oct. 1996.
Specifications subject to change without notice.

RENESAS
Renesas Technology Corp.

REVISION DESCRIPTION LIST	M37733EHLXXXHP Datasheet

<table>
<tr><th>Rev. No.</th><th>Revision Description</th><th>Rev. date</th></tr>
<tr><td>1.00</td><td>First Edition</td><td>970604</td></tr>
<tr><td>1.01</td><td>The following are added:
• PROM ORDER CONFIRMATION FORM
• MARK SPECIFICATION FORM</td><td>980421</td></tr>
<tr><td>2.00</td><td>The following are revised:
<table>
<tr><th>Page</th><th>Previous Version</th><th>Revised Version</th></tr>
<tr><td>P1
PIN CONFIGURATION (TOP VIEW)

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Fig. 5</td><td>Outline 80P6D-A</td><td>Outline 80P6D-A, 80P6Q-A</td></tr>
<tr><td>P13
Right column
Line 2</td><td>The M37733EHLXXXHP has 28 powerful addressing modes. Refer to the MITSUBISHI SEMICONDUCTORS DATA BOOK SINGLE-CHIP 16-BIT MICROCOMPUTERS for the details of each addressing mode.

MACHINE INSTRUCTION LIST
The M37733EHLXXXHP has 103 machine instructions. Refer to the MITSUBISHI SEMICONDUCTORS DATA BOOK SINGLE-CHIP 16-BIT MICROCOMPUTERS for details.</td><td>The M37733EHLXXXHP has 28 powerful addressing modes. Refer to the “7700 Family Software Manual” for the details.

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<tr><td>Line 10</td><td>(2) 80P6D mark specification form</td><td>(2) 80P6D, 80P6Q mark specification form</td></tr>
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Memory expansion mode and microprocessor mode</td><td colspan="2">Previous Version
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<tr><th>Min.</th><th>Max.</th></tr>
<tr><td>tsu(D–E)</td><td>Data input setup time</td><td>80</td><td></td><td>ns</td></tr>
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Revised Version
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<tr><td>tsu(D–E)</td><td>Data input setup time</td><td>50</td><td></td><td>ns</td></tr>
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