

PWM Speed Control for Permanent Excited DC Motors

General Description

The monolithic integrated bipolar circuit CCU2350 is a MOSFET or IGBT-control circuit which works on the principle of pulse width modulation (PWM). The overall concept enables the construction of a power controller with mains voltage compensation where intermittent operation is also possible. In addition, the circuit also enables mains-voltage compensated current control, which maintains the power supplied at a constant level after the preset threshold has been exceeded.

1.1 Features

- Pulse width control up to 30 kHz clock frequency
- Mains supply compensation
- Current regulation
- Temperature monitoring with indicator
- Active operation indicator
- Blink-warn indicator
- Switchable to interval operation
- Push-pull output stage for separate supply
- Supply voltage monitoring
- Temperature compensated supply voltage limitation

1.2 Applications

- Domestic equipment, Household appliances, Toys
- Tools

1.3 Schematic

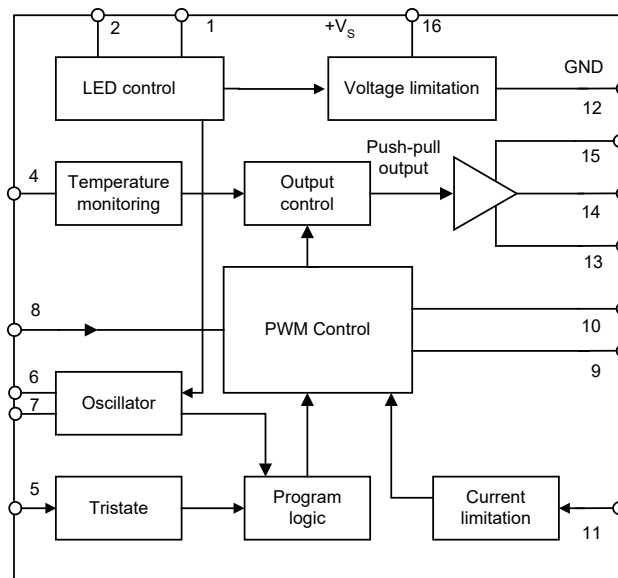


Figure 1: Block diagram CCU2350

PWM Speed Control for Permanent Excited DC Motors

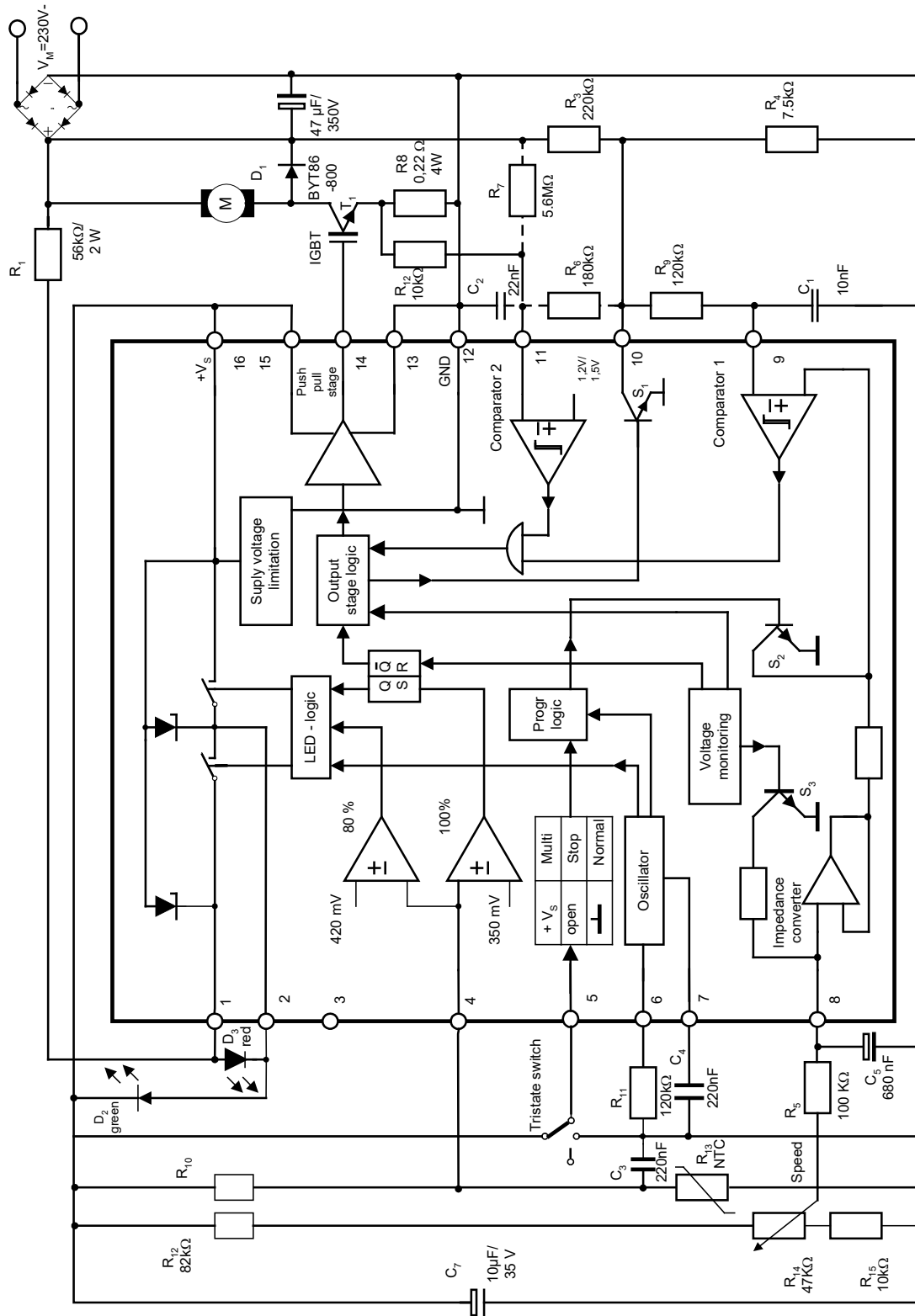
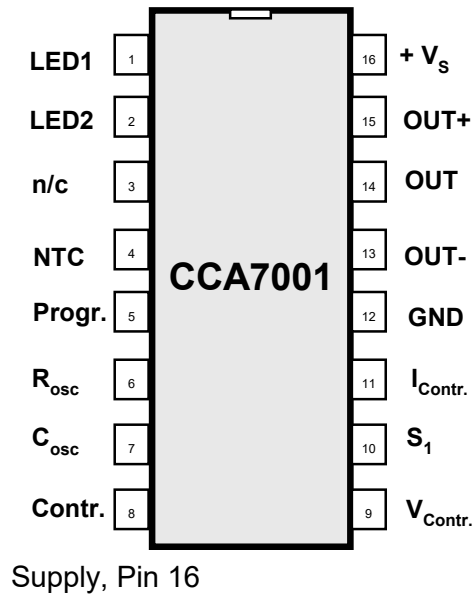


Figure 2: Block diagram with external circuit

PWM Speed Control for Permanent Excited DC Motors

2 Pinout

2.1 Pin Description



Pin no.	Symbol	Function
1	LED1	LED output 1
2	LED2	LED output 2
3	n.c.	Not connected
4	NTC	Monitoring input
5	Progr.	Tristate programming
6	R _{osc}	Resistor for oscillator
7	C _{osc}	Capacitor for oscillator
8	Contr.	Control input
9	V _{Contr.}	Voltage regulation input
10	S ₁	Switching output, output S1
11	I _{Contr.}	Current regulation input
12	GND	Ground
13	OUT-	- supply for output stage
14	OUT	Output
15	OUT+	+ supply for output stage
16	+V _s	Supply voltage

PWM Speed Control for Permanent Excited DC Motors

The internal voltage limiter in the CCU2350 enables a simple supply from the rectified line voltage. The supply voltage between Pin 16 (+V_S) and Pin 12 (ground) is built up via R₁ and is smoothed by C₇. The typically 5 mA supply current is simultaneously used to operate the two LEDs D₂, D₃, which can both be bridged internally. The supply current therefore reaches Pin 16 either via LEDs or the internal switches (V_{sat} ≤ 1.2V).

Series resistor, R₁, can be calculated as follows:

$$R_{1\max} = \frac{V_{M\min} - V_{S\max}}{I_{\text{out}}}$$

whereas

$$V_{M\min} = V_{\text{mains}} - 15 \%$$

V_{Smax} = maximum supply voltage

$$I_{\text{tot}} = I_{S\max} + I_x$$

I_{Smax} = Max. current consumption of the IC

I_x = Current consumption of the external components

Here, C₆ must be selected in this way that the voltage at C₇ (figure 2) is not noticeably affected by the load in any mode of operation. For further

Information regarding mains power supply, refer to figures 6 and 7.

2.2 Voltage Monitoring

Whilst the operating voltage is being built up or reduced, uncontrolled output pulses of insufficient amplitude are suppressed by the internal monitoring circuit. The latch is also reset, the LED D₂ (operating indicator) between Pin 2 and Pin 16 is switched off and the control input "Pin 8" is connected to ground via switch S₃ and a 1 kΩ resistor. In connection with a switching hysteresis of approximately 2 V, this mode of operation guarantees fail-safe start-up each time the operating voltage is switched on, in the same way as after short mains interruptions.

Connecting the control input Pin 8 with a capacitor can therefore make a soft start with rapid recovery possible.

2.3 Pulse Width Control with Mains Voltage Compensation, Pins 8, 9, 10

Average value of the voltage over the load is controlled to an infinitely selectable value by the comparator Comp. 1 with hysteresis. The rectified mains voltage is divided by R₃ and R₄ and lead in Pin 10. The capacitor C₁ is charged via R₉ until the voltage V₉, which is present at the inverting input of Comp. 1, is more positive than the control voltage V₈ arriving at the non-inverting input via an impedance converter.

During the charge time, which is dependent of the mains voltage, the pulse output is at high potential and the switching output Pin 10 is open. If V₉ now becomes greater than V₁₀, the output from Comp. 1 switches over the output stage logic via an AND gate.

The output stage logic now brings V₁₄ to low potential and closes the switching output Pin 10. This has the effect of discharging C₁ via R₉ and the switch S₁ until the approximately 300 mV hysteresis of the comparator is completed. The discharge time is dependent on the control voltage V₈.

PWM Speed Control for Permanent Excited DC Motors

Comp. 1 then switches over again and the cycle begins once more (see figure 3). This two-state controller compensates the influence of the mains voltage, with the result that the motor voltage or motor speed is largely determined by magnitude of the control voltage.

2.4 Current Control, Pin 11

If the current flowing through the IGBT (or MOSFET) and the shunt resistor R_8 becomes so high that a voltage higher than 1.5 V arises at Pin 11, a second control loop formed with the comparator Comp. 2 becomes active, and overrides the first control loop via an AND gate. This causes the average value of the current, fed to the motor, to be controlled to a constant value. This in turn results in a speed which decreases greatly with the increasing torque (see figure 4).

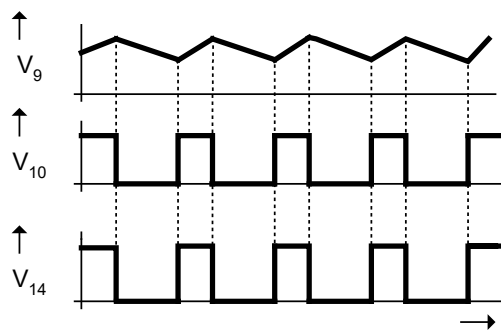


Figure 3: Pulse width control signal characteristics

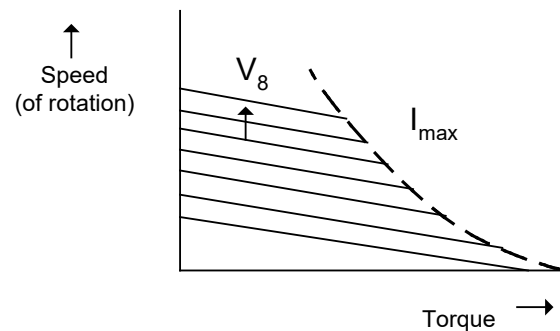


Figure 4: Influence of current control on the characteristic (curve) of a motor

By exceeding the maximum current which is adjustable with R_8 , the control dependent voltage V_8 (shunt characteristic) reaches the dotted lines (series characteristic). By applying a current which depends on the load voltage across R_8 , the constant value of the current can be further influenced. In addition the current control limits the starting current.

In the case of effective current limiting, alteration of the rectified mains voltage has an effect on the power taken up. In order to compensate for this influence, the resistor R_7 is connected to Pin 11. If dimensioned appropriately, the consumed power is independent of changes in the mains voltage within a wide range of this voltage.

PWM Speed Control for Permanent Excited DC Motors

2.5 Operation Mode Selection, Pin 5

It is possible to program three modes of operation with the tristate input, as follows:

- Intermittent operation (Pin 5 connected to + V_S)
A signal emitted by an internal oscillator (see figure 5) switches the output stage ON and OFF periodically via S₂. This intermittent operation is very suitable for certain uses.
- Stop function (Pin 5 open)
The output is continuously switched off, the motor is at reset.
- Normal function (Pin 5 connected to V₁₂) The motor runs continuously.

2.6 Temperature Monitoring, Pin 4

The circuit also has a monitoring input. If a NTC-resistor is connected to this input, for example, it functions as a temperature sensor. If the voltage V₄ falls below the first threshold V_{T80} (approximately 420 mV) as a result of the increasing temperature, an external LED D₃, which is connected between Pin 1 and Pin 2, starts to blink. If the temperature increases further and the voltage V₄ falls below a second threshold V_{T100} (approximately 350 mV), a latch is set. The latch makes this LED light up continuously, the output stage is blocked. The motor is switched-OFF and remains switched-OFF until the temperature has fallen and until the mains voltage is switched-OFF and switched-ON again (the latch is solely reset by the voltage monitoring).

A second LED D₂, which is connected between Pin 2 and Pin 16 and which is continuously illuminated (switch ON) during normal operation, is switched-OFF.

In the event of wire breakage in the sensor branch, Pin 4 is pulled up to + V_S. After the switch-OFF threshold V_{TOFF} (approximately V_S-1.8 V) has been exceeded, the circuit ensures that the latch is set here too. This guarantees safe operation.

3 Absolute Maximum Ratings

Reference point Pin 12, unless otherwise specified.

Parameters	Symbol	Value	Unit
Supply Current t ≤ 10 μs Pin 16	I _S i _S	30 60	mA
Push-pull output V ₁₃ ≤ V ₁₄ ≤ V ₁₅ , V ₁₅ ≤ V ₁₆ , V ₁₃ ≤ V ₁₂ Output current t ≤ 2 ms	I _O i _O	20 200	mA
Signal outputs Input current t ≤ 10 μs	I _I i _I	30 60	mA
Input currents Pin 6,8 Pin 10	I _I	1 10	mA
Input voltages Pin 4,5,7,9,10,11	V _I	0 V to V ₁₆	
Storage temperature range	T _{stg}	-40 to +125	°C
Junction temperature	T _J	+125	°C
Ambient temperature range	T _{amb}	-10 to +100	°C

PWM Speed Control for Permanent Excited DC Motors

Thermal Resistance

Parameters	Symbol	Value	Unit	
Junction ambient	R_{thJA}	DIP16	120	K/W
		SO16 on PC board	180	K/W
		SO16 on ceramic	100	K/W

4 Electrical Characteristics

$V_S = 15.5\text{ V}$, $T_{amb} = 25^\circ\text{C}$, reference point Pin 12, figure 2, unless otherwise specified.

Parameters	Test Conditions/	Pins	Symbol	Min.	Typ.	Max.	Unit
Supply voltage limitation	$I_S = 5\text{ mA}$	Pin 16	V_S	16		17.2	V
	$I_S = 20\text{ mA}$			16		17.8	
Current consumption			I_S			3.5	mA
Voltage monitoring		Pin 16					
Switch-on threshold			V_{SON}	10	14.0	14.5	V
Switch-off threshold			V_{SOFF}	12.0	12.5	16	V
Control input		Pin 8					
Input voltage range			V_I	0		7.5	V
Input quiescent current			I_{IB}			250	nA
Impedance at lower voltage			R_I		1		k Ω
Comparator 1		Pin 9					
Input voltage range			V_{IC}	0		7.5	V
Input quiescent current			I_{IB}			250	nA
Hysteresis	$V_8 = 1.5\text{ V}$	Pin 8-9	V_{hys}	320	355	390	mV
Delay time		Pin 9-14	t_d			3	μs
Switch S_1		Pin 10					
Leakage current	$V_{10} = 15.5\text{ V}, V_8 = 3\text{ V}, V_9 = 0\text{ V}, V_{11} = 0\text{ V}$		I_R			1	μA
Saturation voltage	$I_{10} = 2\text{ mA}, V_8 = 0\text{ V}, V_9 = 3\text{ V}$		V_{Sat}			0.25	V
Delay time		Pin 10-14	$t_{d(r)}$			3	μs
			$t_{d(f)}$			3	
Comparator 2		Pin 11					
Input current			I_I			1	μA
Switch-on threshold			V_{TON}	1.12	1.20	1.23	V
Switch-off threshold			V_{TOFF}	1.45	1.50	1.54	V
Delay time (output)		Pin 11-14	t_d			3	μs
Push-pull stage		Pin 14					
Saturation voltage	High side	Pin 14-16	V_{SatH}			2.4	V
	Low side		V_{SatL}			1.2	
Output current limitation	$V_{14} = V_{12}, V_{11} = 0\text{ V}, V_8 = 3\text{ V}, V_9 = 0\text{ V}, t \leq 1\text{ }\mu\text{s}$		$-I_o$	75		250	mA
	$V_{14} = V_{16}, V_8 = 0\text{ V}, V_9 = 3\text{ V}, t \leq 1\text{ }\mu\text{s}$		I_o	75		250	mA

PWM Speed Control for Permanent Excited DC Motors

Parameters	Test Conditions/	Pins	Symbol	Min.	Typ.	Max.	Unit
Rise time	$V_{15} = V_{16}, V_{13} = V_{12},$ $C_{Gate} = 1 \text{ nF}$		t_r		250		ns
Fall time	$C_{Gate} = 1 \text{ nF}$		t_f		600		ns
Operating indicator		$I_2 = 5 \text{ mA}$					
Saturation voltage	$V_{16} \leq V_{SoffOR}$ $(V_4 \leq V_{T100})$	Pin 2-16	V_{Sat}		1.0		V
Voltage limitation	$V_{16} \geq V_{Son},$ $(V_4 > V_{T100})$	Pin 2-16	V_{limit}		6.6		V
Overload output		$I_1 = 5 \text{ mA}$					
Saturation voltage	$V_4 > V_{T80}$	Pin 1-2	V_{Sat}		1.0		V
Voltage limitation	$V_4 \leq V_{T80}$	Pin 1 - 16	V_{limit}		8.6		V
Temperature monitoring		Pin 4					
Input current			I_I			500	nA
80%-threshold			V_{T80}	390	420	450	mV
100%-threshold			V_{T100}	325	350	375	mV
Switch-off threshold			V_{TOFF}		$V_S - 1.8$		V
Operation mode selection		Pin 5					
Voltage	Pin 5 open ($I_5 = 0$)		V_5		$V_S/2$		
Input current	$V_5 = V_{16}$		I_I		15		μA
	$V_5 = V_{12}$		$-I_I$		15		μA
Oscillator							
Input current		Pin 6	I_I			40	μA
Source voltage	$I_6 = -10 \mu\text{A}$	Pin 6	V_6		0.9		V
Upper saw tooth threshold		Pin 7	V_{Tmax}		9		V
Lower saw tooth threshold		Pin 7	V_{Tmin}		1.8		V
Oscillator frequency	$C_4 = C_{osc} = 220 \text{ nF},$ see figure 2 $R_{11} = R_{osc} = 120 \text{ k}\Omega$	Pin 7	f_{osc}		1.1		Hz
Blink frequency	$V_{T100} < V_4 \leq V_{T80}$	Pin 1	f_{blink}		2.2		Hz
Switching frequency	$V_5 = V_{16}$ interval operation	Pin 14	f_s		1.1		Hz
Pulse ratio switch		Pin 14	t_p/T	0.2	0.23	0.26	

PWM Speed Control for Permanent Excited DC Motors

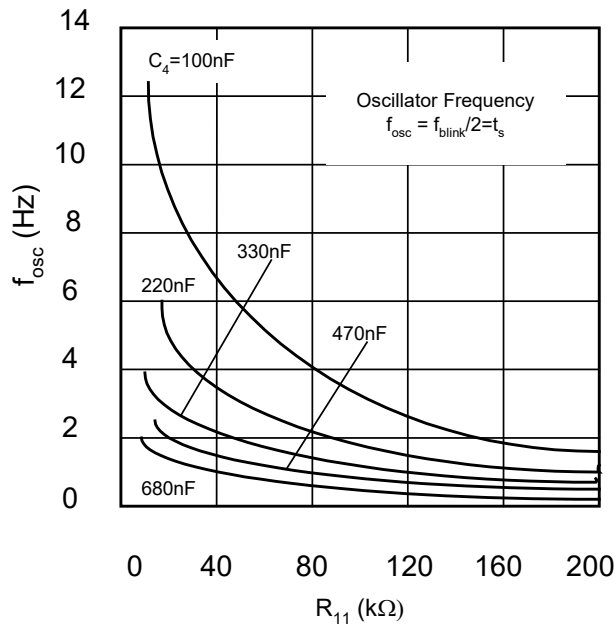


Figure 5

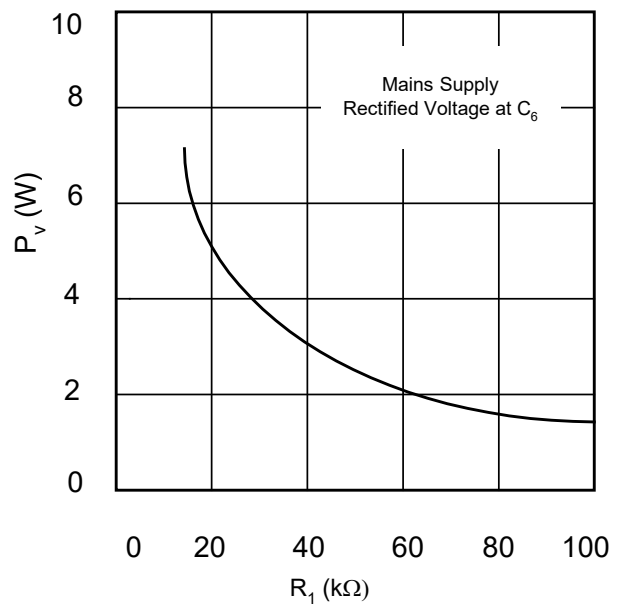


Figure 7

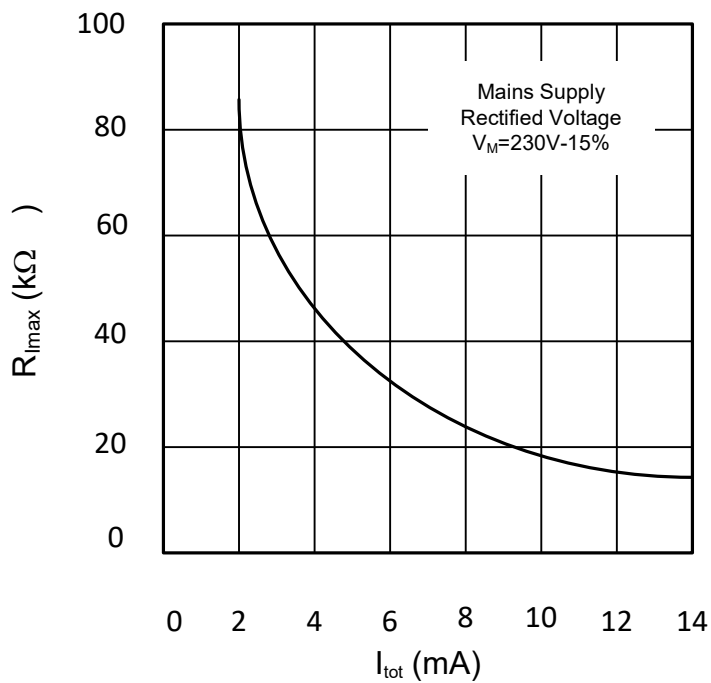


Figure 6

PWM Speed Control for Permanent Excited DC Motors

5 Revision History

Revision	Date	Description
1.1	31-Oct-2019	Updated Template
1.0	30-Jun-2005	Initial version

Contents

General Description	1
1.1 Features.....	1
2 Pinout	3
2.1 Pin Description	3
2.2 Voltage Monitoring.....	4
2.3 Pulse Width Control with Mains Voltage Compensation, Pins 8, 9, 10.....	4
2.4 Current Control, Pin 11.....	5
2.5 Operation Mode Selection, Pin 5.....	6
2.6 Temperature Monitoring, Pin 4.....	6
3 Absolute Maximum Ratings	7
4 Electrical Characteristics.....	7
5 Revision History	10
Contents	10

PWM Speed Control for Permanent Excited DC Motors

Disclaimer

Information in this document is believed to be accurate and reliable. However, Dialog Semiconductor does not give any representations or warranties, expressed or implied, as to the accuracy or completeness of such information. Dialog Semiconductor furthermore takes no responsibility whatsoever for the content in this document if provided by any information source outside of Dialog Semiconductor.

Dialog Semiconductor reserves the right to change without notice the information published in this document, including without limitation the specification and the design of the related semiconductor products, software and applications.

Applications, software, and semiconductor products described in this document are for illustrative purposes only. Dialog Semiconductor makes no representation or warranty that such applications, software and semiconductor products will be suitable for the specified use without further testing or modification. Unless otherwise agreed in writing, such testing or modification is the sole responsibility of the customer and Dialog Semiconductor excludes all liability in this respect.

Customer notes that nothing in this document may be construed as a license for customer to use the Dialog Semiconductor products, software and applications referred to in this document. Such license must be separately sought by customer with Dialog Semiconductor.

All use of Dialog Semiconductor products, software and applications referred to in this document are subject to Dialog Semiconductor's Standard Terms and Conditions of Sale, available on the company website (www.dialog-semiconductor.com) unless otherwise stated.

Dialog and the Dialog logo are trademarks of Dialog Semiconductor plc or its subsidiaries. All other product or service names are the property of their respective owners.

© 2019 Dialog Semiconductor. All rights reserved

IMPORTANT NOTICE AND DISCLAIMER

RENESAS ELECTRONICS CORPORATION AND ITS SUBSIDIARIES (“RENESAS”) PROVIDES TECHNICAL SPECIFICATIONS AND RELIABILITY DATA (INCLUDING DATASHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES “AS IS” AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS OR IMPLIED, INCLUDING, WITHOUT LIMITATION, ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, OR NON-INFRINGEMENT OF THIRD-PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for developers who are designing with Renesas products. You are solely responsible for (1) selecting the appropriate products for your application, (2) designing, validating, and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, or other requirements. These resources are subject to change without notice. Renesas grants you permission to use these resources only to develop an application that uses Renesas products. Other reproduction or use of these resources is strictly prohibited. No license is granted to any other Renesas intellectual property or to any third-party intellectual property. Renesas disclaims responsibility for, and you will fully indemnify Renesas and its representatives against, any claims, damages, costs, losses, or liabilities arising from your use of these resources. Renesas' products are provided only subject to Renesas' Terms and Conditions of Sale or other applicable terms agreed to in writing. No use of any Renesas resources expands or otherwise alters any applicable warranties or warranty disclaimers for these products.

(Disclaimer Rev.1.01 Jan 2024)

Corporate Headquarters

TOYOSU FORESIA, 3-2-24 Toyosu,
Koto-ku, Tokyo 135-0061, Japan
www.renesas.com

Trademarks

Renesas and the Renesas logo are trademarks of Renesas Electronics Corporation. All trademarks and registered trademarks are the property of their respective owners.

Contact Information

For further information on a product, technology, the most up-to-date version of a document, or your nearest sales office, please visit www.renesas.com/contact-us/.