RZ/T2, RZ/N2 Group

Quick Start Guide: EtherCAT EoE SubDevice Software

Introduction

This application note explains sample program setup procedures for EtherCAT® SubDevice functionalities with the adapted EtherCAT Stack Code for RZ/T2, RZ/N2 series microprocessor.

This describes steps to confirm SubDevice behaviour and stack features using TwinCAT® MainDevice Configuration tool.

Target Device

RZ/T series: RZ/T2M, RZ/T2ME, RZ/T2L, RZ/T2H
RZ/N series: RZ/N2L, RZ/N2H

Contents

1. Overview

This application note explains sample program setup procedures for EtherCAT® SubDevice functionalities with the adapted EtherCAT Stack Code for RZ/T2, RZ/N2 series microprocessor.

1.1 Abbreviations / Definitions

Table 1.1 Abbreviations/Definitions

Index	Abbreviations/Definitions	Description
1	CoE	CAN application protocol over EtherCAT
2	CiA	CAN in Automation
3	DC	Distributed Clock
4	EEPROM	Electrically Erasable Programmable Read-Only Memory
5	EoE	Ethernet Over EtherCAT
6	ESC	EtherCAT SubDevice Controller
7	ESI	EtherCAT SubDevice Information
8	ESM	EtherCAT State Machine
9	ETG	EtherCAT Technology Group
10	FoE	File Access Over EtherCAT
11	PDO	Process Data Object
12	SDO	Service Data Object
13	SSC	SubDevice Stack Code
14	FSP	Flexible Software Package
15	IDE	Integrated Development Environment
16	GCC	GNU Compiler Collection

1.2 Reference

1.2.1 About RZ/T2, RZ/N2

Technical information about EtherCAT is available via ETG member site, and information about RZ/T2 and RZ/N2 is available via Renesas.

Table 1.2 Common Technical Inputs for RZ/T2, RZ/N2

Document Type	Description	Document Title	Document No.
Application Note	Describes how to use the Renesas Flexible Software Package (FSP) for writing applications for the RZ/T2, RZ/N2 microprocessor series.	RZ/T2, RZ/N2 Getting Started with Flexible Software Package	r01an6434ej****

Table 1.3 Technical Inputs for RZ/T2L

Document Type	Description	Document Title	Document No.
User's Manual	Describes the technical details of the RSK+RZT2L hardware.	Renesas Starter Kit+ for RZ/T2L User's Manual	r20ut5164eg****
User's Manual	Provides technical details of the RZ/T2L microprocessor.	RZ/T2L Group User's Manual Hardware	r01uh0985ej****

Table 1.4 Technical Inputs for RZ/N2L

Document Type	Description	Document Title	Document No.
User's Manual	Describes the technical details of the RSK+RZN2L hardware.	Renesas Starter Kit+ for RZ/N2L User's Manual	r20ut4984eg****
User's Manual	Provides technical details of the RZ/N2L microprocessor.	RZ/N2L Group User's Manual Hardware	r01uh0955eg****

Table 1.5 Technical Inputs for RZ/T2M and RZ/T2ME

Document Type	Description	Document Title	Document No.
User's Manual	Describes the technical details of the RSK+RZT2M and RSK+RZT2ME hardware.	Renesas Starter Kit+ for RZ/T2M, RZ/T2ME User's Manual	r20ut4939eg****
User's Manual	Provides technical details of the RZ/T2M microprocessor.	RZ/T2M Group User's Manual Hardware	r01uh0916eg****
User's Manual	Provides technical details of the RZ/T2ME microprocessor.	RZ/T2ME Group User's Manual Hardware	r01uh1062eg****

Table 1.6 Technical Inputs for RZ/T2H and RZ/N2H

Document Type	Description	Document Title	Document No.
User's Manual	Describes the technical details of the RZ/T2H EVB hardware.	RZ/T2H Evaluation Board User's Manual	r20ut5405ej****
User's Manual	Describes the technical details of the RZ/N2H EVB hardware.	RZ/N2H Evaluation Board User's Manual	r20ut5522ej****
User's Manual	Provides technical details of the RZ/T2H and RZ/N2H microprocessor.	RZ/T2H and RZ/N2H Groups User's Manual: Hardware	r01uh1039eg****

2. Features

This package includes the firmware for the EtherCAT SubDevice stack generated by SSC Tool on Renesas' RZ/T2 and RZ/N2 series processors.

This sample program includes the following features:

- ESM (EtherCAT State Machine)
- Mailbox protocols:
  - CoE (CAN application protocol over EtherCAT)
  - EoE (Ethernet Over EtherCAT)
- Synchronization Modes:
  - Free Run
  - Sync Manager Synchronization
  - DC Synchronization
- I/O function:
  - I/O Input DIP SW
  - I/O Output LED
- TCP/IP stack for Ethernet over EtherCAT:
  - lwIP

EtherCAT is a registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.

2.1 Folder structure relative to this application note

After extracting the package, the following structure is obtained.

Table 2.1 Sample package overview

Item	Description
r01an8274xx0410-rzt2-rzn2-ethercat-package	RZ/T2, N2 EtherCAT Sample Package
├── RZT2M_RZT2ME_EtherCAT_RSK_rev0410.zip	Archive for RZ/T2M, RZ/T2ME (RSK board)
├── RZT2L_EtherCAT_RSK_rev0410.zip	Archive for RZ/T2L (RSK board)
├── RZT2H_EtherCAT_EVB_rev0410.zip	Archive for RZ/T2H (EVB board)
├── RZN2L_EtherCAT_RSK_rev0410.zip	Archive for RZ/N2L (RSK board)
├── RZN2H_EtherCAT_EVB_rev0410.zip	Archive for RZ/N2H (EVB board)
└── r01an8276ej0410-rzt2-rzn2-ecat-eoe.pdf	This application note

After extracting the archive for multicore, the following structure is obtained.

Table 2.2 Multi-Core folder structure (RZ/T2M, RZ/T2ME)

Item	Description
RZT2M_RZT2ME_EtherCAT_RSK_rev0410	RZ/T2M, RZ/T2ME RSK folder
└── CR52_Dual	Cortex-R52 CPU0 and Cortex-R52 CPU1
├── common	Common resources for SSC Tool
│ └── EoE_lwIP	For EoE_lwIP
│ ├── ESI	EtherCAT SubDevice Information
│ ├── Patch	Patch for this EoE project
│ └── SSCconfig	SSC Tool setting file
└── project	IDE project folder
└── EoE_lwIP	For EoE_lwIP
├── e2studio	The e^{2}studio projects
│ ├── RZT2M_RSK_ESC_EoE_lwIP_CR52_Dual_Primary	Primary core project
│ └── RZT2M_RSK_ESC_EoE_lwIP_CR52_Dual_Secondary	Secondary core project
└── ewarm	The EWARM projects
├── RZT2M_RSK_ESC_EoE_lwIP_CR52_Dual_Primary	Primary core project
└── RZT2M_RSK_ESC_EoE_lwIP_CR52_Dual_Secondary	Secondary core project

Table 2.3 Multi-Core folder structure (RZ/T2H)

Item	Description
RZT2H_EtherCAT_EVB_rev0410	RZ/T2H EVB folder
├── CR52_Dual	Cortex-R52 CPU0 and Cortex-R52 CPU1
│ ├── common	Common resources for SSC Tool
│ │ └── EoE_lwIP	For EoE_lwIP
│ │ ├── ESI	EtherCAT SubDevice Information
│ │ ├── Patch	Patch for this EoE_lwIP project
│ │ └── SSCconfig	SSC Tool setting file
│ └── project	IDE project folder
│ └── EoE_lwIP	For EoE_lwIP
│ ├── e2studio	The e^{2}studio projects
│ │ ├── RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary	Primary core project
│ │ └── RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary	Secondary core project
│ └── ewarm	The EWARM projects
│ ├── RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary	Primary core project
│ └── RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary	Secondary core project
└── CR52_CA55	Cortex-R52 CPU0 and Cortex-A55 Core2
├── common	Common resources for SSC Tool
│ └── EoE_lwIP	For EoE_lwIP

│ ├── ESI	EtherCAT SubDevice Information
│ ├── Patch	Patch for this EoE_lwIP project
│ └── SSCconfig	SSC Tool setting file
└── project	IDE project folder
└── EoE_lwIP	For EoE_lwIP
├── e2studio	The e²studio projects
│ ├── RZT2H_EVB_ESC_EoE_lwIP_CR52_CA55_Primary	Primary core project
│ └── RZT2H_EVB_ESC_EoE_lwIP_CR52_CA55_Secondary	Secondary core project
└── ewarm	The EWARM project
├── RZT2H_EVB_ESC_EoE_lwIP_CR52_CA55_Primary	Primary core project
└── RZT2H_EVB_ESC_EoE_lwIP_CR52_CA55_Secondary	Secondary core project

Table 2.4 Multi-Core folder structure (RZ/N2H)

Item	Description
RZN2H_EtherCAT_EVB_rev0410	RZ/N2H EVB folder
├── CR52_Dual	Cortex-R52 CPU0 and Cortex-R52 CPU1
│ ├── common	Common resources for SSC Tool
│ │ └── EoE_lwIP	For EoE_lwIP
│ │ ├── ESI	EtherCAT SubDevice Information
│ │ ├── Patch	Patch for this EoE_lwIP project
│ │ └── SSCconfig	SSC Tool setting file
│ └── project	IDE project folder
│ └── EoE_lwIP	For EoE_lwIP
│ ├── e2studio	The e²studio projects
│ │ ├── RZN2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary	Primary core project
│ │ └── RZN2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary	Secondary core project
│ └── ewarm	The EWARM projects
│ ├── RZN2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary	Primary core project
│ └── RZN2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary	Secondary core project
├── CR52_CA55	Cortex-R52 CPU0 and Cortex-A55 Core2
│ ├── common	Common resources for SSC Tool
│ │ └── EoE_lwIP	For EoE_lwIP
│ │ ├── ESI	EtherCAT SubDevice Information
│ │ ├── Patch	Patch for this EoE_lwIP project
│ │ └── SSCconfig	SSC Tool setting file
│ └── project	IDE project folder
│ └── EoE_lwIP	For EoE_lwIP
│ ├── e2studio	The e²studio projects
│ │ ├── RZN2H_EVB_ESC_EoE_lwIP_CR52_CA55_Primary	Primary core project
│ │ └── RZN2H_EVB_ESC_EoE_lwIP_CR52_CA55_Secondary	Secondary core project
│ └── ewarm	The EWARM projects
│ ├── RZN2H_EVB_ESC_EoE_lwIP_CR52_CA55_Primary	Primary core project
│ └── RZN2H_EVB_ESC_EoE_lwIP_CR52_CA55_Secondary	Secondary core project

After extracting the archive for single core, the following structure is obtained.

Table 2.5 Single-Core folder structure (RZ/T2L)

Item	Description
RZT2L_EtherCAT_RSK_rev0410	RZ/T2L RSK folder
├─── common	Common resources for SSC Tool
│ └─── EoE_lwIP	For EoE_lwIP
│ ├─── ESI	EtherCAT SubDevice Information
│ ├─── Patch	Patch for this EoE_lwIP project
│ └─── SSCconfig	SSC Tool setting file
└─── project	IDE project folder
└─── EoE_lwIP	For EoE_lwIP
├─── e2studio	The e²studio projects
│ └─── RZT2L_RSK_ESC_EoE_lwIP	Single core project
└─── ewarm	The EWARM projects
└─── RZT2L_RSK_ESC_EoE_lwIP	Single core project

Table 2.6 Single-Core folder structure (RZ/N2L)

Item	Description
RZN2L_EtherCAT_RSK_rev0410	RZ/N2L RSK folder
├─── common	Common resources for SSC Tool
│ └─── EoE_lwIP	For EoE_lwIP
│ ├─── ESI	EtherCAT SubDevice Information
│ ├─── Patch	Patch for this EoE_lwIP project
│ └─── SSCconfig	SSC Tool setting file
└─── project	IDE project folder
└─── EoE_lwIP	For EoE_lwIP
├─── e2studio	The e²studio projects
│ └─── RZN2L_RSK_ESC_EoE_lwIP	Single core project
└─── ewarm	The EWARM projects
└─── RZN2L_RSK_ESC_EoE_lwIP	Single core project

2.2 Software structure overview

Table 2.7. shows the software structure of the sample program.

The sample program consists of the EtherCAT sample part and the TCP/IP sample part.

EoE enables Ethernet-based services and protocols to be used by encapsulating Ethernet communication frames in EtherCAT communication data.

The fragmentation of the Ethernet communication frame during assembly and transmission of the segmented Ethernet communication frame at the time of reception due to the encapsulation of the communication data is implemented as the EoE service of the SSC.

The virtual Ethernet driver replaces the Ethernet driver on the physical layer of the normal TCP/IP stack and is responsible for passing the Ethernet communication frame between the TCP/IP protocol stack and the EoE service.

The TCP/IP sample has the function of an echo server and echoes back received TCP or UDP packets.

The EtherCAT sample has the function of an I/O controller, and it is possible to check input/output control from the MainDevice with the LEDs and DIP SW on the RSK amd EVB board.

Table 2.7 Software structure

Layer / Sample	EtherCAT Sample	TCP/IP Sample
Application layer	I/O Controller*	TCP Echo Server*
Protocol stack layer	EtherCAT SubDevice Stack (SSC)** including EoE Service	FreeRTOS+TCP
Wrapper to driver layer	EtherCAT SSC port	lwIP wrapper
Driver layer	Ethernet PHY	Virtual Ethernet*
	Ethernet Selector	

*: provided by sample project
**: provided by Beckhoff, patched by sample project
unmarked: provided by FSP

Note). - In the Smart Configurator stack configuration, r_ether (GMAC) is added to the driver layer of the (FreeRTOS+TCP), but in the sample program it will be replaced with a virtual Ether driver, so it will not work.

- UDP Echo Server is not implemented in lwIP sample

3. Requirements (Software and Hardware)

This project has been developed and tested on these environments using the following boards and tools.

3.1 Requirements for this sample package

Table 3.1 Requirements

Category	Name	Version	Description
Board	Renesas Starter Kit+ for RZ/T2M	-	Renesas RZ/T2M-RSK - Renesas Starter Kit Plus for RZ/T2M | Renesas
	Renesas Starter Kit+ for RZ/T2ME	-	Renesas RZ/T2ME-RSK - Renesas Starter Kit+ for RZ/T2ME | Renesas
	Renesas Starter Kit+ for RZ/T2L	-	Renesas RZ/T2L-RSK - Renesas Starter Kit+ for RZ/T2L | Renesas
	RZ/T2H Evaluation Board	-	Renesas RZ/T2H-EVKIT - Evaluation Board Kit for RZ/T2H | Renesas
	Renesas Starter Kit+ for RZ/N2L	-	Renesas RZ/N2L-RSK - Renesas Starter Kit+ for RZ/N2L | Renesas
	RZ/N2H Evaluation Board	-	Renesas RZ/N2H-EVKIT - Evaluation Board Kit for RZ/N2H | Renesas
IDE	EWARM	9.60.3	IAR Systems IAR Embedded Workbench for Arm | IAR
	e^2 studio	2025-12	Renesas Release v4.0.0 · renesas/rz-fsp · GitHub
Configurator	FSP Smart Configurator	2025-12	
Flexible Software Package	FSP for Renesas RZ	4.0.0	
GCC Compiler	GNU ARM Embedded Toolchain	13.3.Rel1	
	GNU ARM A-Profile (AArch64 bare-metal)	13.2.Rel1	
Emulator	J-Link ™	8.60	SEGGER SEGGER - The Embedded Experts - Downloads - J-Link / J-Trace
	I-jet	-	IAR Systems IAR debug probes | IAR
Software	SSC Tool	5.13	Beckhoff Automation ET9300 | EtherCAT Slave Stack Code | Beckhoff Worldwide
	TwinCAT3	4026.19	Beckhoff Automation TwinCAT 3.1 Build 4026 | Beckhoff Worldwide
	Tera Term	5.5.1	Tera Term Tera Term Open Source Project

4. Hardware Setup

This document describes the major hardware. For more information about the boards, refer to the respective evaluation board user manuals and schematics.

4.1 RZ/T2M and RZ/T2ME RSK Board

Note) All descriptions are based on the RSK+RZT2M. When using the RSK+RZT2ME, substitute RZ/T2M with RZ/T2ME throughout this document.

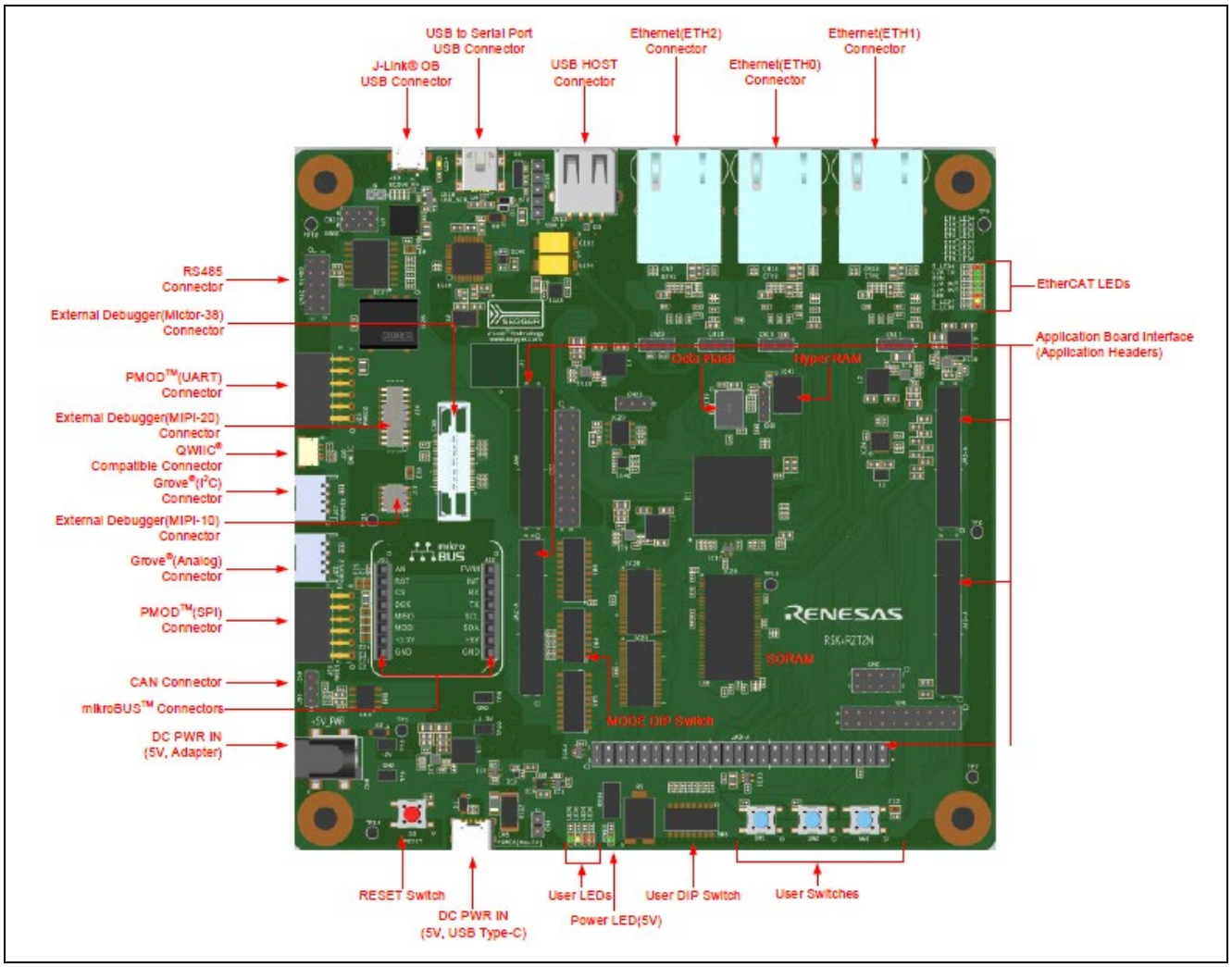


Figure 4.1 RZT2M RSK board layout

4.1.1 Jumper and Switch Configuration

The tables below show the jumper pin and switch settings.
Text in bold red type in the tables indicates the settings changed from the time of shipment of the board.

Table 4.1 RZ/T2M-RSK Jumper configuration

Reference	Jumper Position	Description
CN8	Short 2-3	Use QSPI Serial Flash
CN17	Short 2-3	VCC1833_2 Use power supply at 1.8V
CN18	Short 1-2	Use 3 ports in same PHY mode
CN19	Short 1-2	Use 3 ports in same PHY mode
CN20	Short 1-2	Use 3 ports in same PHY mode
CN21	Short 1-2	Use RS485 transmission method in full duplex
CN22	Short 1-2	Use RS485 transmission method in full duplex
J9	Open	Use J-Link OB

Table 4.2 RZ/T2M-RSK SW4 Settings

SW4	Setting	Description
SW4-1	ON	**16-bit bus boot mode (NOR Flash)**
SW4-2	**OFF**	* Refer to the Document No.”r20ut4939” and set according to the mode to be used.
SW4-3	ON	
SW4-4	ON	MDD=0, JTAG Authentication by Hash is disabled.
SW4-5	OFF	MDW=1, ACTM 1 wait, should be set when TCM is used with CPU operating frequencies above 400MHz
SW4-6	OFF	-
SW4-7	OFF	-
SW4-8	OFF	-

Table 4.3 RZ/T2M-RSK SW5 Setting.

SW5	Setting	Description
SW5-1	OFF	-
SW5-2	OFF	-
SW5-3	ON	Enable the "SCI_RTS" signal.
SW5-4	OFF	
SW5-5	ON	Enable the "SCI_RXD" signal.
SW5-6	OFF	
SW5-7	OFF	
SW5-8	OFF	Enable the "SCK3" signal.
SW5-9	ON	
SW5-10	OFF	

Table 4.4 RZ/T2M-RSK SW6 Setting

SW6	Setting	Description
SW6-1	OFF	Enable the "ETH2_MDIO" and "ETH2_MDC" signal.
SW6-2	OFF	-
SW6-3	ON	TRACE_CTL signal is enabled
SW6-4	OFF	
SW6-5	OFF	SCI_TXD signal is enabled
SW6-6	ON	
SW6-7	OFF	MB_RST# signal is enabled
SW6-8	ON	
SW6-9	OFF	CAN_RX_OB signal is enabled
SW6-10	ON	

4.1.2 Board Setup

Setting the board for running sample program is shown below.
Build and run the sample code on the RZ/T2M RSK board by following the steps below.
Both loading into RAM and flash can be done using IAR Embedded Workbench or e^2 studio.

1. Connect the debugger to the header "J20" on the RZ/T2M RSK board.

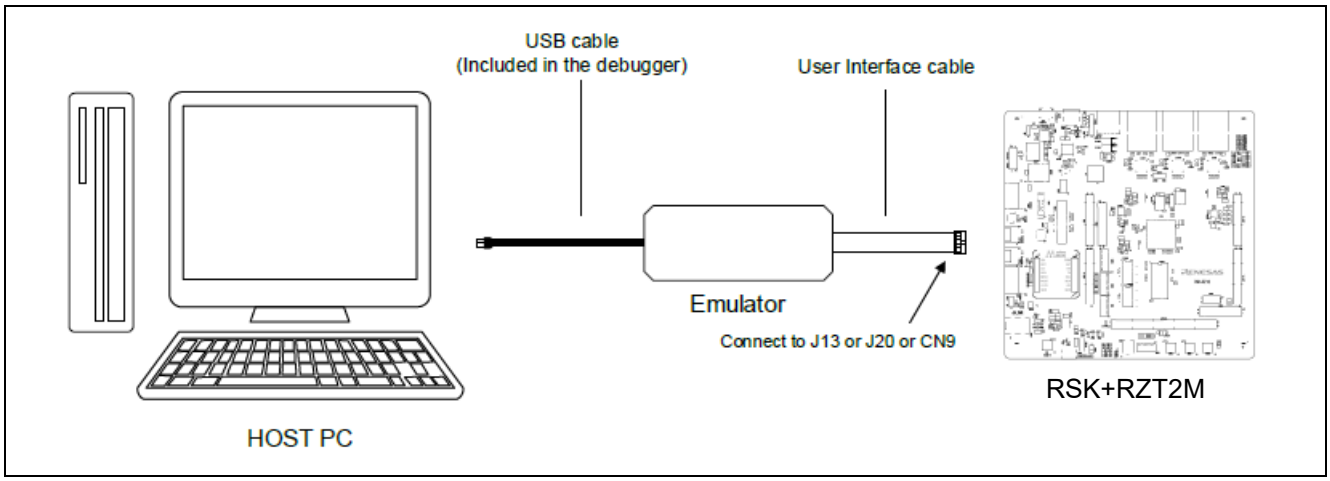


Figure 4.2 : RZ/T2M RSK board debug connection diagram

When using J-Link OB, connect the USB cable to the header "J10" and set "J9" to open.

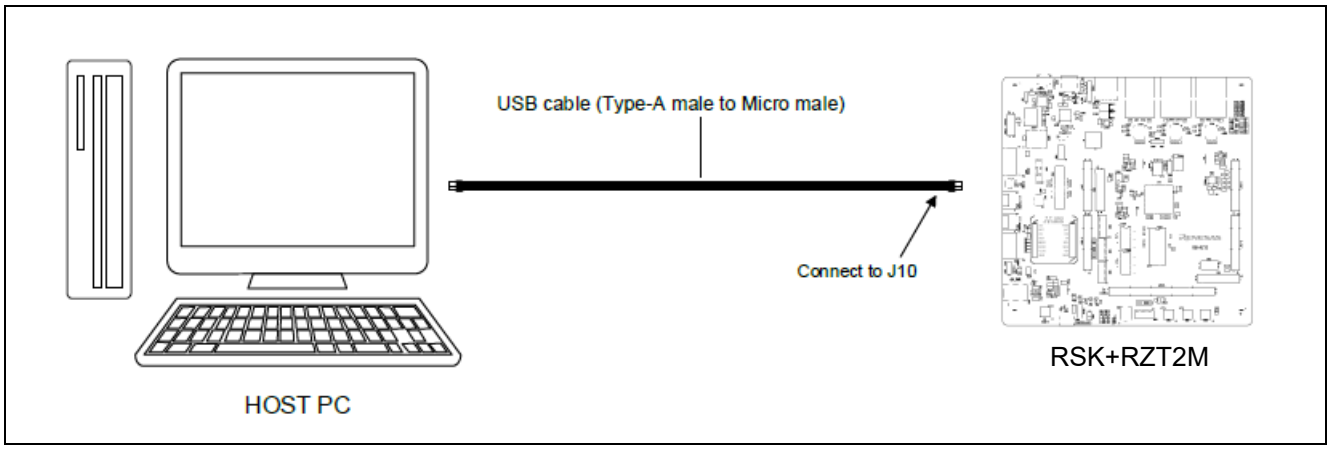


Figure 4.3 : RZ/T2M RSK board debug connection diagram (J-Link OB)

2. Power is supplied using a USB cable (Type-C) or an AC / DC adapter. When using a USB cable (Type-C), connect it to the USB connector "CN5" of the RZ/T2M RSK board. When connecting the AC/DC adapter, connect it to the “CN6” connector of the RZ/T2M RSK board.

3. Connect host PC and RZ/T2M RSK board using an ethernet cable. When using an ethernet cable, connect the ethernet cable into “ETH0” connector of the RZ/T2M RSK board.
Depending on the protocol specifications, it may be possible to connect to "ETH1".

4.2 RZ/N2L RSK Board

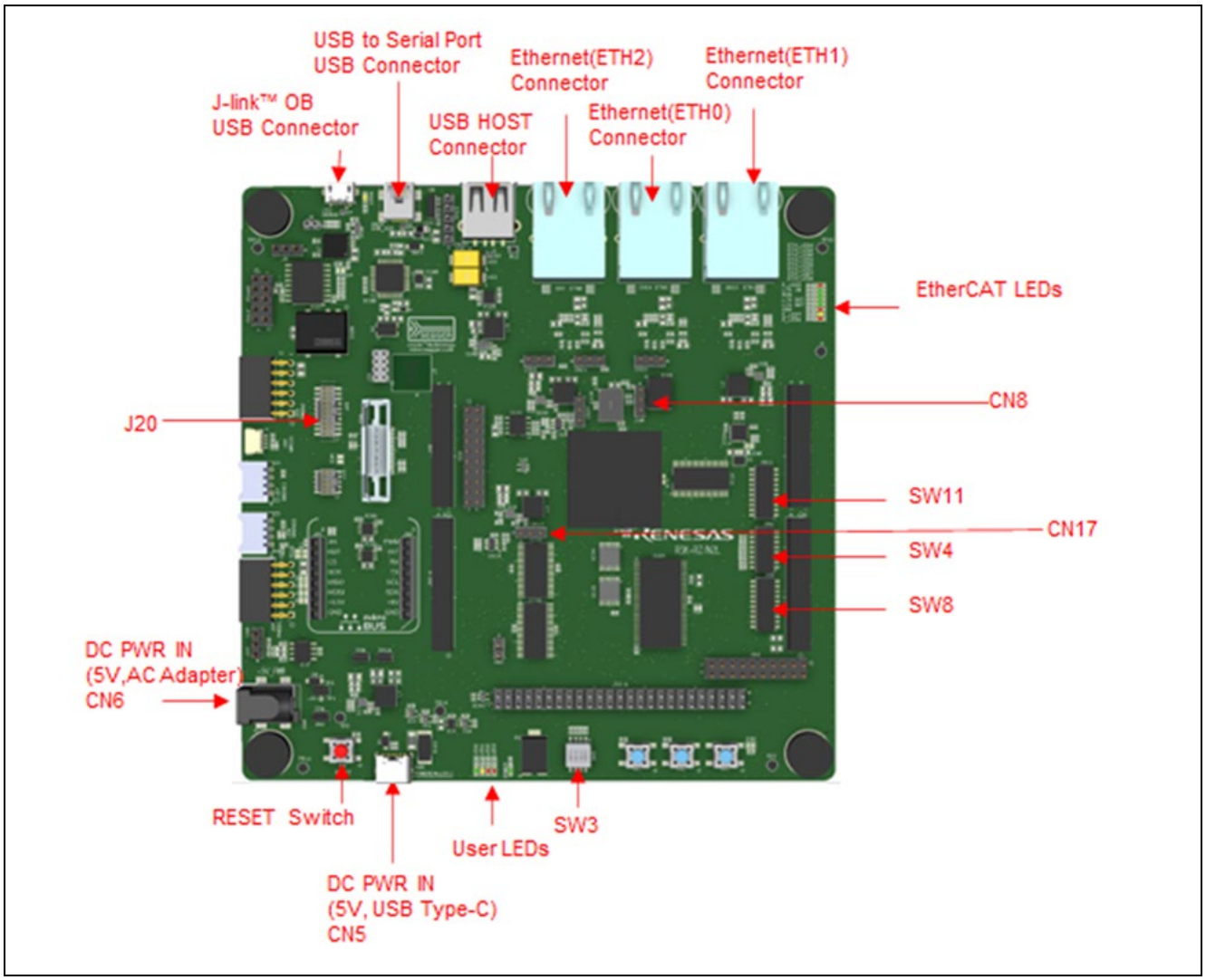


Figure 4.4 RZN2L RSK board layout

4.2.1 Jumper and Switch Configuration

The tables below show the jumper pin and switch settings.
Text in bold red type in the tables indicates the settings changed from the time of shipment of the board.

Table 4.5 RZ/N2L-RSK Jumper configuration

Reference	Jumper Position	Description
CN8	Short 2-3	Use QSPI Serial Flash
CN17	Short 2-3	VCC1833_2 Use power supply at 1.8V
CN20	Short 1-2	Use 3 ports in same PHY mode
CN21	Short 1-2	Use 3 ports in same PHY mode
CN22	Short 1-2	Use 3 ports in same PHY mode
CN24	Short 2-3	VCC1833_3 Use power supply at 1.8V
CN25	Short 1-2	When using other than the SHOST interface
CN27	Short 1-2	When using the HyperRAM
CN29	Short 1-2	When using the USB Serial
CN31	Short 1-2	Use RS485 transmission method in full duplex
CN32	Short 1-2	Use RS485 transmission method in full duplex
J9	Open	Use J-Link OB

Table 4.6 RZ/N2L-RSK SW4 Settings

SW4	Setting	Description
SW4-1	ON	**16-bit bus boot mode (NOR flash)**
SW4-2	**OFF**	* Refer to" r20ut4984egxxxx-rskplus-rzn2l-v1-um.pdf" and set according to the mode to be used.
SW4-3	ON	
SW4-4	ON	MDD=0, JTAG Authentication by Hash is disabled.
SW4-5	OFF	-
SW4-6	OFF	Enables signals other than the trace signal. (Motor, RS485, etc)
SW4-7	ON	Enables signals other than the external bus. (CAN, Emulator, I2C, etc.)
SW4-8	OFF	Enable SW3.

Table 4.7 RZ/N2L-RSK SW8 Setting.

SW8	Setting	Description
SW8-1	OFF	Enable the "LED_GREEN" signal.
SW8-2	ON	
SW8-3	OFF	
SW8-4	ON	Enable the "LED5" signal.
SW8-5	OFF	
SW8-6	OFF	RS485_DE & M2_VN Configuration Switch Setting
SW8-7	ON	
SW8-8	OFF	CAN_TX & IRQ4 & P02_2 Configuration Switch Setting
SW8-9	OFF	
SW8-10	ON	

Table 4.8 RZ/N2L-RSK SW11 Setting

SW11	Setting	Description
SW11-1	ON	Enable the "LED_RED2" signal.
SW11-2	OFF	
SW11-3	OFF	
SW11-4	OFF	RS485_RX & M2_UP Configuration Switch Setting
SW11-5	ON	
SW11-6	OFF	P21_5 & M2_VP Configuration Switch Setting
SW11-7	ON	
SW11-8	OFF	CAN_RX & ADTRG & P01_7 Configuration Switch Setting
SW11-9	OFF	
SW11-10	ON	

4.2.2 Board Setup

Setting the board for running sample program is shown below.
Build and run the sample code on the RZ/N2L RSK board by following the steps below.
Both loading into RAM and flash can be done using IAR Embedded Workbench or e^2 studio.

1. Connect the debugger to the header "J20" on the RZ/N2L RSK board.

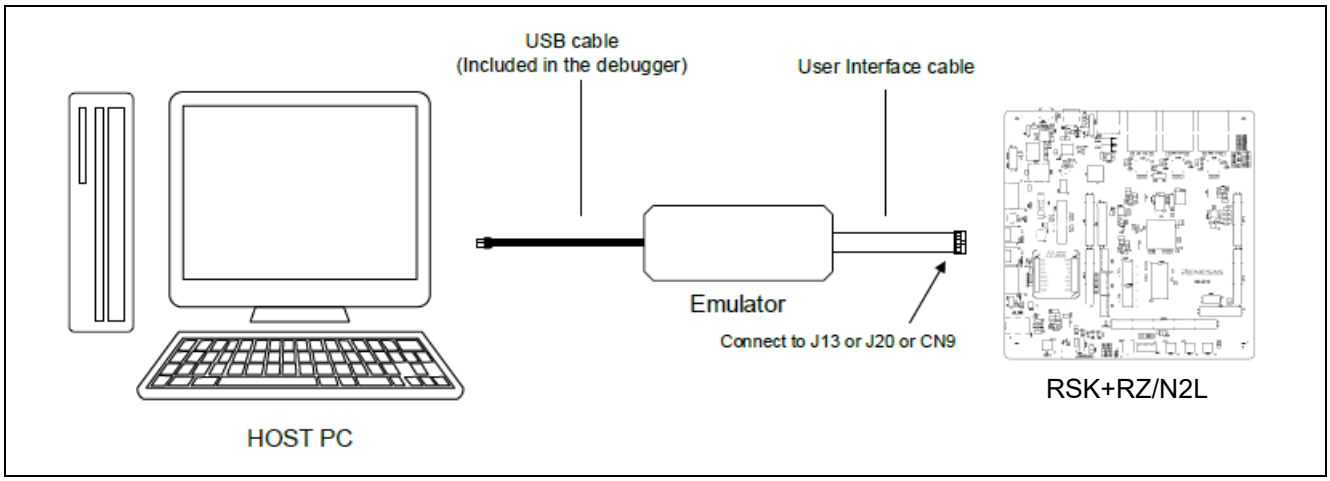


Figure 4.5 RZ/N2L RSK board debug connection diagram

When using J-Link OB, connect the USB cable to the header "J10" and set "J9" to open.

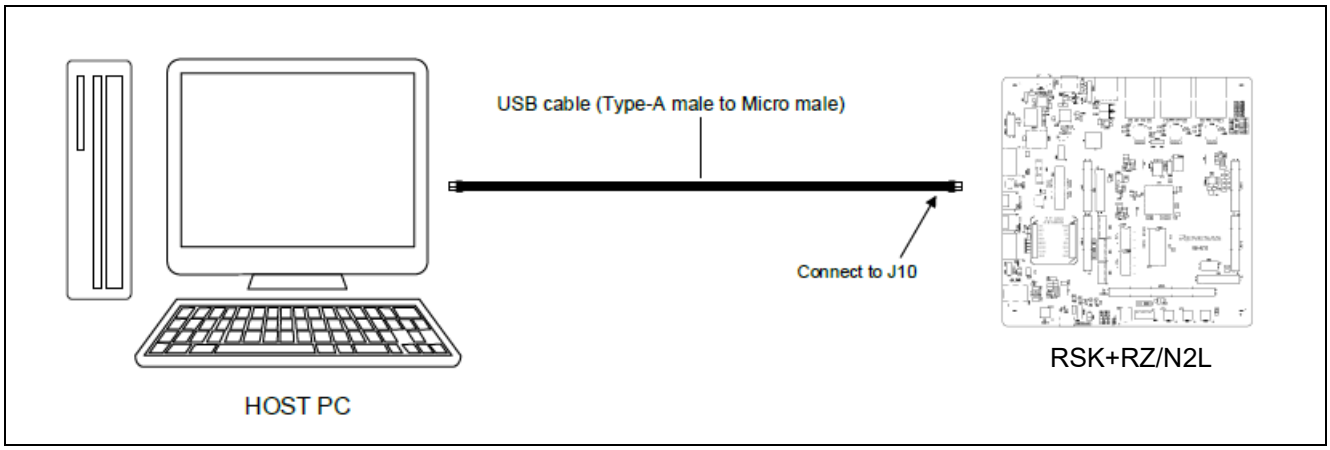


Figure 4.6 RZ/N2L RSK board debug connection diagram (J-Link OB)

2. Power is supplied using a USB cable (Type-C) or an AC / DC adapter. When using a USB cable (Type-C), connect it to the USB connector "CN5" of the RZ/N2L RSK board. When connecting the AC/DC adapter, connect it to the “CN6” connector of the RZ/N2L RSK board.

3. Connect host PC and RZ/N2L RSK board using an ethernet cable. When using an ethernet cable, connect the ethernet cable into “ETH0” connector of the RZ/N2L RSK board.
Depending on the protocol specifications, it may be possible to connect to "ETH1".

4.3 RZ/T2L RSK Board

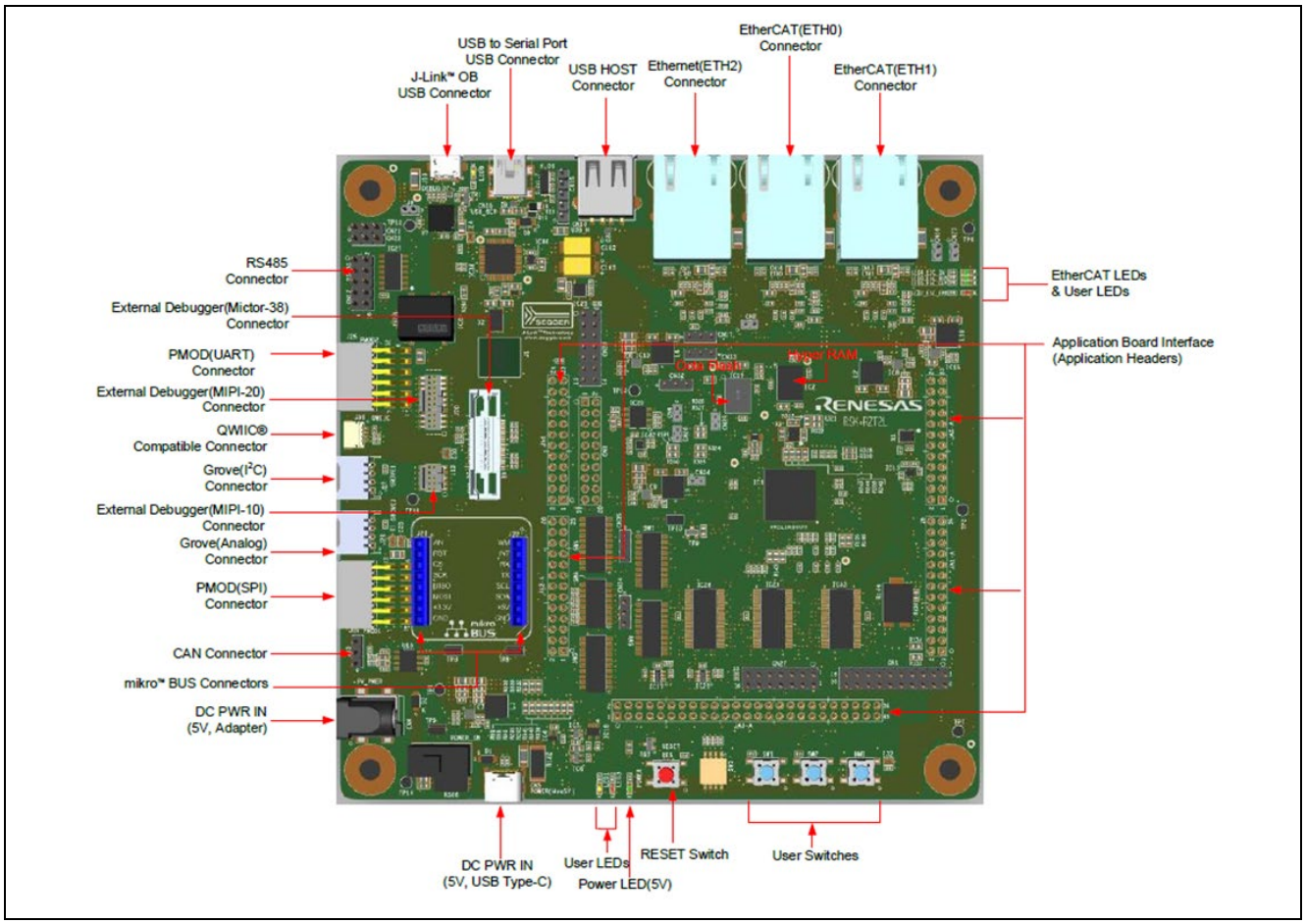


Figure 4.7 RZT2L RSK board layout

4.3.1 Jumper and Switch Configuration

The tables below show the jumper pin and switch settings.
Text in bold red type in the tables indicates the settings changed from the time of shipment of the board.

Table 4.9 RZ/T2L-RSK Jumper configuration

Reference	Jumper Position	Description
J9	**Open**	**The on-board debugging function J-Link® OB is enabled.**
CN2	Short	VCC1833_2 current measurement
CN4	Short	VCC1833_3 current measurement
CN24	Short	VCC11_RVCORE current measurement
CN25	Short	CPU1V8 current measurement
CN26	Short	CPU3V3 current measurement
CN17	Short 2-3	VCC1833_2 Use power supply at 1.8V
CN32	Short 1-2	VCC1833_3 Use power supply at 3.3V
CN21	Short 2-3	Half-duplex communication
CN22		
CN34	Short 1-2	Use TXD0_P16_0_JA1 as transmit data signal and RXD0_P16_1_JA1 as receive data signal (use SCI ch0)
CN35		
CN33	Short 1-2	Connect XSPI1_CS0# to CS# of QuadSPI FLASH (IC3)
CN18	Short 1-2	Connect P21_3 to LED0_ESC_RUN
CN23	Short 1-2	Connect P21_6 to LED4_ESC_IN

Table 4.10 RZ/T2L-RSK SW4 Settings

SW4	Setting	Description
SW4-1	ON	**xSPI0 x1 boot mode**
SW4-2	ON	* Refer to" r20ut5164ejxxxx-rskrzt2l.pdf" and set according to the mode to be used.
SW4-3	**ON**	
SW4-4	OFF	MDD=0, JTAG Authentication by Hash is disabled.
SW4-5	ON	JTAG mode = Normal mode
SW4-6	ON	VCC1833_2 = 1.8V
SW4-7	OFF	VCC1833_3 = 3.3V
SW4-8	OFF	-

Table 4.11 RZ/T2L-RSK SW5 Setting.

SW5	Setting	Description
SW5-1	ON	P01_7 is used as CAN_RX_OB of the CAN interface.
SW5-2	OFF	
SW5-3	OFF	
SW5-4	OFF	
SW5-5	OFF	P02_0 is used as CAN_TX1_JA5 of JA5-A.
SW5-6	OFF	
SW5-7	OFF	
SW5-8	ON	
SW5-9	OFF	-
SW5-10	OFF	-

Table 4.12 RZ/T2L-RSK SW6 Setting.

SW6	Setting	Description
SW6-1	ON	P02_2 is used as CAN_TX_OB of the CAN interface.
SW6-2	OFF	
SW6-3	OFF	
SW6-4	OFF	
SW6-5	OFF	P02_3 is used as CAN_RX1_JA5 of JA5-A.
SW6-6	OFF	
SW6-7	OFF	
SW6-8	ON	
SW6-9	OFF	-
SW6-10	OFF	-

Table 4.13 RZ/T2L-RSK SW7 Setting.

SW7	Setting	Description
SW7-1	ON	**Use P05_5 as ETH1_LINK for EtherCAT Port1**
SW7-2	**OFF**	
SW7-3	OFF	
SW7-4	OFF	Use P17_6 as LED1 for user LED control
SW7-5	OFF	
SW7-6	ON	
SW7-7	OFF	Use P18_1 as LED3 for user LED control
SW7-8	OFF	
SW7-9	OFF	
SW7-10	ON	

Table 4.14 RZ/T2L-RSK SW8 Setting.

SW8	Setting	Description
SW8-1	ON	Use P22_3 as Ethernet Port GMAC_RESETOUT#
SW8-2	OFF	
SW8-3	OFF	
SW8-4	ON	Use P22_1 as serial host interface, HSPI_IO7_M2POE_BSC_D08 for JA5-A and JA3-A (When SW8-10=OFF:TRACE_OPTION_SEL=H)
SW8-5	OFF	
SW8-6	OFF	–
SW8-7	**ON**	**ECAT0_OPTION_SEL = 'L'** **Select ETH0-related signals with bus switch IC33**
SW8-8	**ON**	**ECAT1_OPTION_SEL = 'L'** **Select ETH1-related signals with bus switch IC41**
SW8-9	**ON**	**XSPI1_OPTION_SEL = 'H'** **Select signals other than XSPI1 related signals with bus switch IC37**
SW8-10	OFF	TRACE_OPTION_SEL = 'H' Select signals other than TRACE-related signals with bus switch IC12

4.3.2 Board Setup

Setting the board for running sample program is shown below.
Build and run the sample code on the RZ/T2L RSK board by following the steps below.
Both loading into RAM and flash can be done using IAR Embedded Workbench or e^2 studio.

1. Connect the debugger to the header "J20" on the RZ/T2L RSK board.

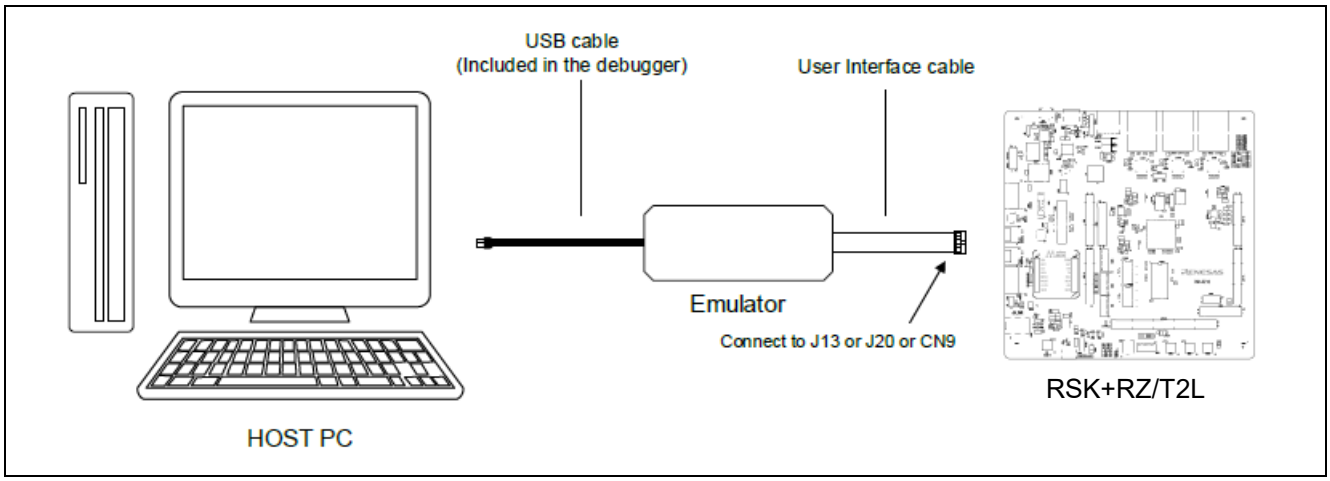


Figure 4.8: RZ/T2L RSK board debug connection diagram

When using J-Link OB, connect the USB cable to the header "J10" and set "J9" to open.

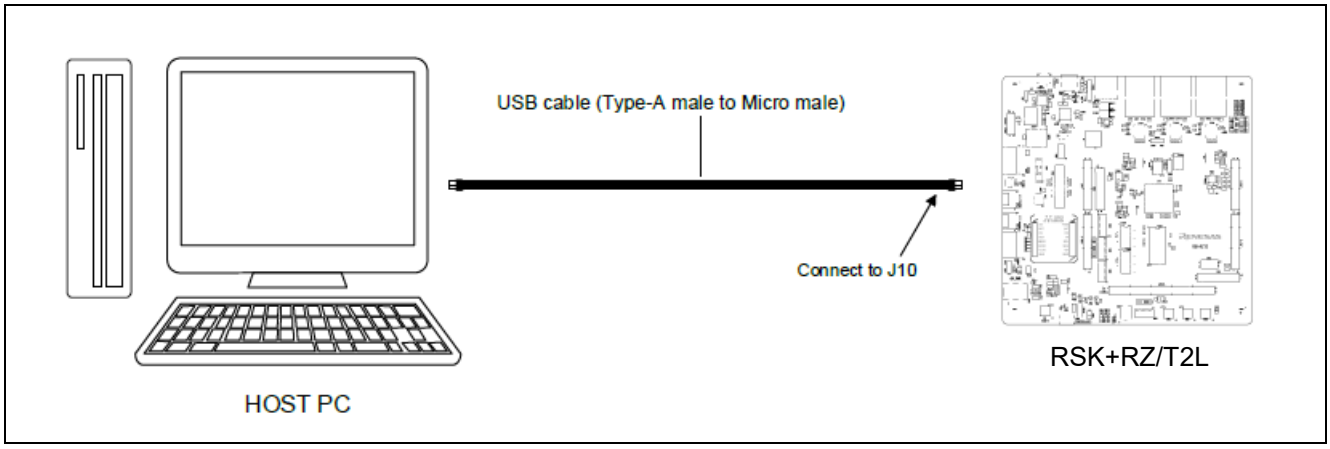


Figure 4.9: RZ/T2L RSK board debug connection diagram (J-Link OB)

2. Power is supplied using a USB cable (Type-C) or an AC / DC adapter. When using a USB cable (Type-C), connect it to the USB connector "CN5" of the RZ/T2L RSK board. When connecting to the AC/DC adapter, connect it to the connector "CN6" of the RZ/T2L RSK board.

3. Connect host PC and RZ/T2L RSK board using an ethernet cable. When using an ethernet cable, connect the ethernet cable into “ETH0” connector of the RZ/T2L RSK board.
Depending on the protocol specifications, it may be possible to connect to "ETH1".

4.4 RZ/T2H Evaluation Board

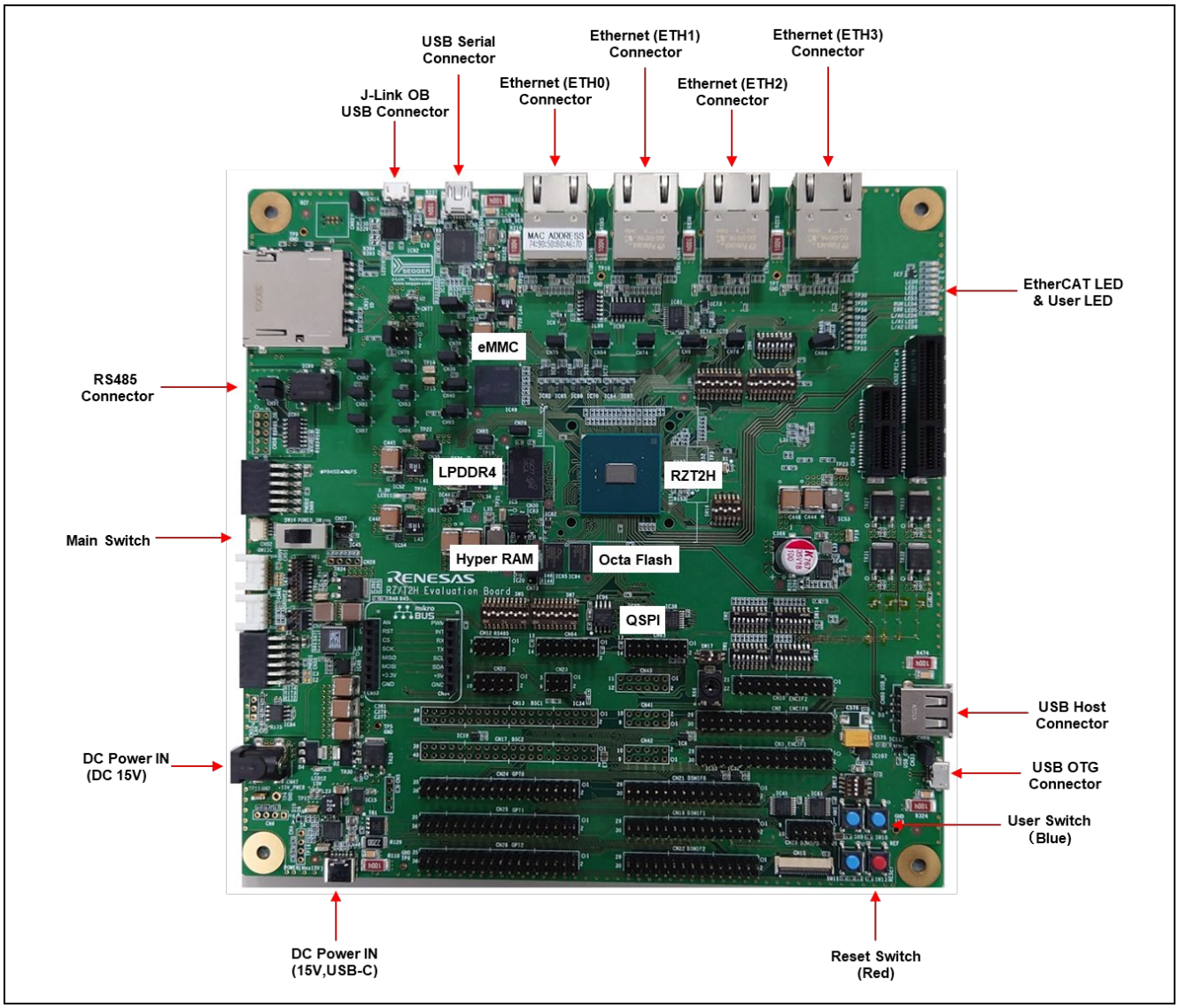


Figure 4.10: RZT2H Evaluation board layout

4.4.1 Jumper and Switch Configuration

The tables below show the jumper pin and switch settings.
Text in bold red type in the tables indicates the settings changed from the time of shipment of the board.

Table 4.15 RZ/T2H EVB Jumper configuration

Reference	Jumper Position	Description
CN62	**Open**	**The on-board debugging function J-Link™ OB is enabled.**
CN73	Open	PCIe reset is not included in the system reset factors.
CN9	Short 1-2	VCC1833_0 is supplied to VCC_ETH2_MDIO (SW2-6 is ON: When P21_4 and P21_5 are selected for MDIO).
CN37	Short 2-3	3.3-V power is supplied to VCC1833_0 (for Ethernet port 0).
CN38	Short 2-3	3.3-V power is supplied to VCC1833_1 (for Ethernet port 1).
CN39	Short 1-2	1.8-V power is supplied to VCC1833_2 (for Ethernet port 2).
CN40	Short 1-2	1.8-V power is supplied to VCC1833_3 (for Ethernet port 3).
CN77	Short 2-3	The output from the power-supply control IC for SD1 is supplied to VCC1833_7 (for SD1).
CN78	Short 5-6	1.8-V power is supplied to VCC1833_6 (for SD0).
CN56 CN57	Short 2-3	Half-duplex communication

Table 4.16 RZ/T2H EVB SW14 Settings

SW14	Setting	Description
SW14-1	ON	xSPI1 boot mode (x1 boot serial flash) * Refer to" r20ut5405ejxxxx-rzt2hevb.pdf" and set according to the mode to be used.
SW14-2	OFF	
SW14-3	ON	
SW14-4	OFF	CPU0 ATCM wait cycle = 1 wait cycle
SW14-5	OFF	CPU1 ATCM wait cycle = 1 wait cycle
SW14-6	OFF	Supply voltage of boot peripheral is 3.3 V
SW14-7	ON	JTAG mode = Normal mode
SW14-8	OFF	-

Table 4.17 RZ/T2H EVB SW1 Settings

SW1	Setting	Description
SW1-1	ON	XTALSEL = 'L' Select oscillator for RZ/T2H clock input.
SW1-2	OFF	-
SW1-3	ON	P35_3,4,5,6 are connected to SW12 and used as user DIPSW inputs.
SW1-4	OFF	P13_4, P13_5, and P14_0 are used as RXD3, TXD3, and DE3 of the RS485.
SW1-5	ON	P00_0,1,2 are used as USB power supply IC control signals.
SW1-6	ON	P01_0,1,2,4,5,6,7 and P02_0,1,2,3 are used as XSPI1 signals.
SW1-7	OFF	-
SW1-8	OFF	-

Table 4.18 RZ/T2H EVB SW2 Settings

SW2	Setting	Description
SW2-1	ON	P12_0 to 7, P13_0 to 2 are connected to eMMC.
SW2-2	ON	
SW2-3	**OFF**	**P17_4, P08_5, and P08_6 are connected to BSC1 (CN13), BSC2 (CN17), DSMIF0 (CN21), SEI (SW9), and LED3.**
SW2-4	OFF	-
SW2-5	OFF	-
SW2-6	ON	GMAC0 (P21_4, P21_5) are connected to MDC/MDIO of Ethernet Port2.
SW2-7	ON	P29_1 to 7, P30_0 to 4, P31_2 to 5 are used as Ethernet Port2 control signals.
SW2-8	ON	P27_2, P33_2 to P33_7, P34_0 to P34_5, P34_7, and P35_0 to P35_2 are used as control signals for Ethernet port 3.

Table 4.19 RZ/T2H EVB SW4 Settings

SW4	Setting	Description
SW4-1	ON	P27_0 is used as ETH1_CRS.
SW4-2	OFF	
SW4-3	ON	P27_1 is used as ETH1_COL.
SW4-4	OFF	
SW4-5	ON	P27_4 is used as RXD0 of USB-to-serial conversion.
SW4-6	OFF	
SW4-7	ON	P27_5 is used as TXD0 of USB-to-serial conversion.
SW4-8	OFF	

Table 4.20 RZ/T2H EVB SW5 Settings

SW5	Setting	Description
SW5-1	OFF	P32_2 is used as USER_LED1.
SW5-2	ON	
SW5-3	OFF	When SW2-3 = ON, P08-6 is used as SD1_IOVS.
SW5-4	ON	
SW5-5	OFF	P07_5 is used as XSPI0_ECS# for OctaFlash.
SW5-6	ON	
SW5-7	OFF	P23_0 is used as ESC_LINKACT1.
SW5-8	ON	
SW5-9	OFF	P22_7 is used as ESC_LINKACT0.
SW5-10	ON	

Table 4.21 RZ/T2H EVB SW6 Settings

SW6	Setting	Description
SW6-1	OFF	P11_0 is used as ESC_RESETOUT2#.
SW6-2	OFF	
SW6-3	ON	
SW6-4	OFF	P11_0 is used as ESC_RESETOUT01#.
SW6-5	ON	
SW6-6	OFF	-
SW6-7	ON	P23_3 is used as ESC_I2CCLK.
SW6-8	OFF	
SW6-9	ON	P23_4 is used as ESC_I2CDATA.
SW6-10	OFF	

Table 4.22 RZ/T2H EVB SW7 Settings

SW7	Setting	Description
SW7-1	OFF	P24_4 is used as CAN_TX.
SW7-2	ON	
SW7-3	OFF	P24_3 is used as CAN_RX.
SW7-4	ON	
SW7-5	OFF	P23_5 is used as ESC_LINKACT2.
SW7-6	ON	
SW7-7	OFF	VUBUSIN is used as USB_Function.
SW7-8	ON	
SW7-9	OFF	P00_0 is used as USB_HF_VBUSEN.
SW7-10	ON	

Table 4.23 RZ/T2H EVB SW8 Settings

SW8	Setting	Description
SW8-1	ON	P18_1 is used as ESC_LED_ERR.
SW8-2	OFF	
SW8-3	ON	P18_0 is used as ESC_LED_RUN.
SW8-4	OFF	
SW8-5	ON	P16_3 is used as RXD5 of USB-to-serial conversion.
SW8-6	OFF	
SW8-7	ON	P16_4 is used as TXD5 of USB-to-serial conversion.
SW8-8	OFF	
SW8-9	ON	P23_1 is used as USER_LED0.
SW8-10	OFF	

Table 4.24 RZ/T2H EVB SW15 Settings

SW15	Setting	Description
SW15-1	ON	PCIe functions is used as Root Complex.
SW15-2	ON	PCIe L1 is used as a root complex.
SW15-3	OFF	The PCIe function is used in a configuration of 2 lanes × 1 port.
SW15-4	OFF	-
SW15-5	OFF	The 12-V power supply of the PCIe x4 connector CN32 is OFF.
SW15-6	OFF	The 3.3-V power supply of the PCIe x4 connector CN32 is OFF.
SW15-7	OFF	The 3.3-V power supply of the PCIe x1 connector CN8 is OFF.
SW15-8	OFF	The 12-V power supply of the PCIe x1 connector CN8 is OFF.

Table 4.25 RZ/T2H EVB SW17 Settings

SW17	Setting	Description
SW17-1	ON	AN000 is connected to potentiometer.
SW17-2	OFF	

Table 4.26 RZ/T2H EVB SW18 Settings

SW18	Setting	Description
SW18-1	OFF	AN100 is connected to mikroBUS™.
SW18-2	ON	
SW18-3	OFF	AN101 is connected to Grove2.
SW18-4	ON	
SW18-5	OFF	AN102 is connected to Grove2.
SW18-6	ON	

4.4.2 Board Setup

Setting the board for running sample program is shown below.
Build and run the sample code on the RZ/T2H Evaluation board by following the steps below.
Both loading into RAM and flash can be done using IAR Embedded Workbench or e^2 studio.

1. Connect the debugger to the header "CN61" on the RZ/T2H evaluation board.

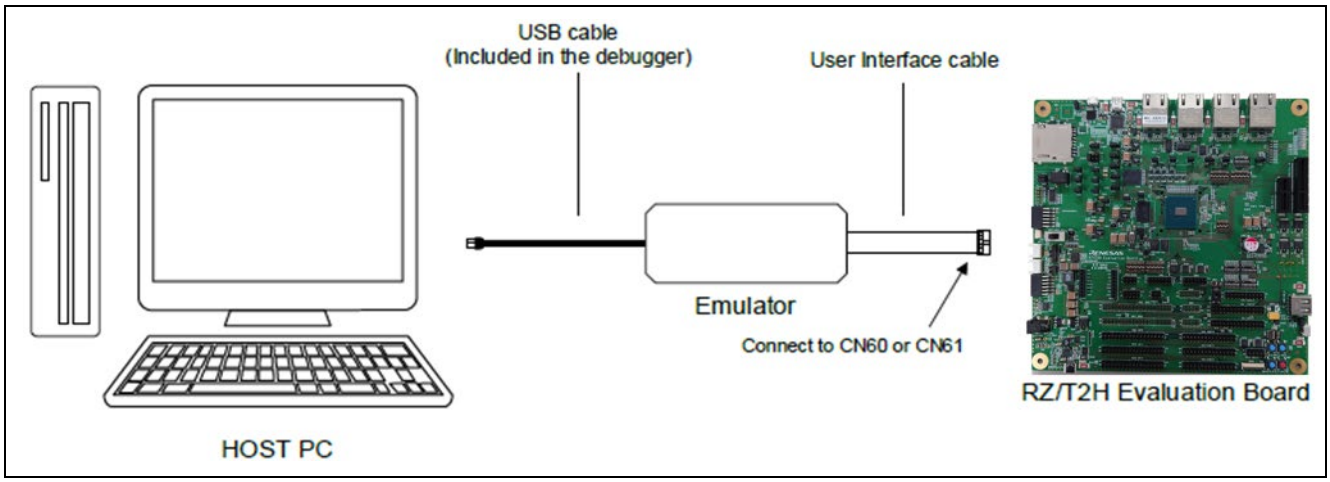


Figure 4.11: RZ/T2H evaluation board debug connection diagram

When using J-Link OB, connect the USB cable to the header "CN14" and set "CN62" to open.

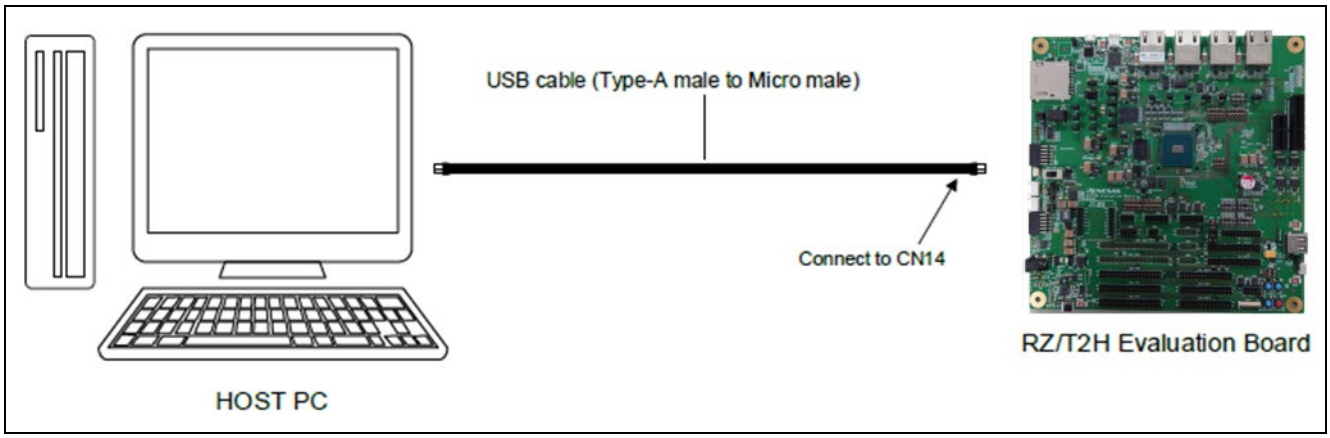


Figure 4.12: RZ/T2H evaluation board debug connection diagram (J-Link OB)

2. Power is supplied using a USB cable (Type-C) or an AC / DC adapter. When using a USB cable (Type-C), connect it to the USB connector "CN46" of the RZ/T2H evaluation board. When connecting to the AC/DC adapter, connect it to the connector "CN47" of the RZ/T2H evaluation board.

3. Connect host PC and RZ/T2H evaluation board using an ethernet cable. When using an ethernet cable, connect the ethernet cable into “ETH0” connector of the RZ/T2H evaluation board.
Depending on the protocol specifications, it may be possible to connect to "ETH1".

4.5 RZ/N2H Evaluation Board

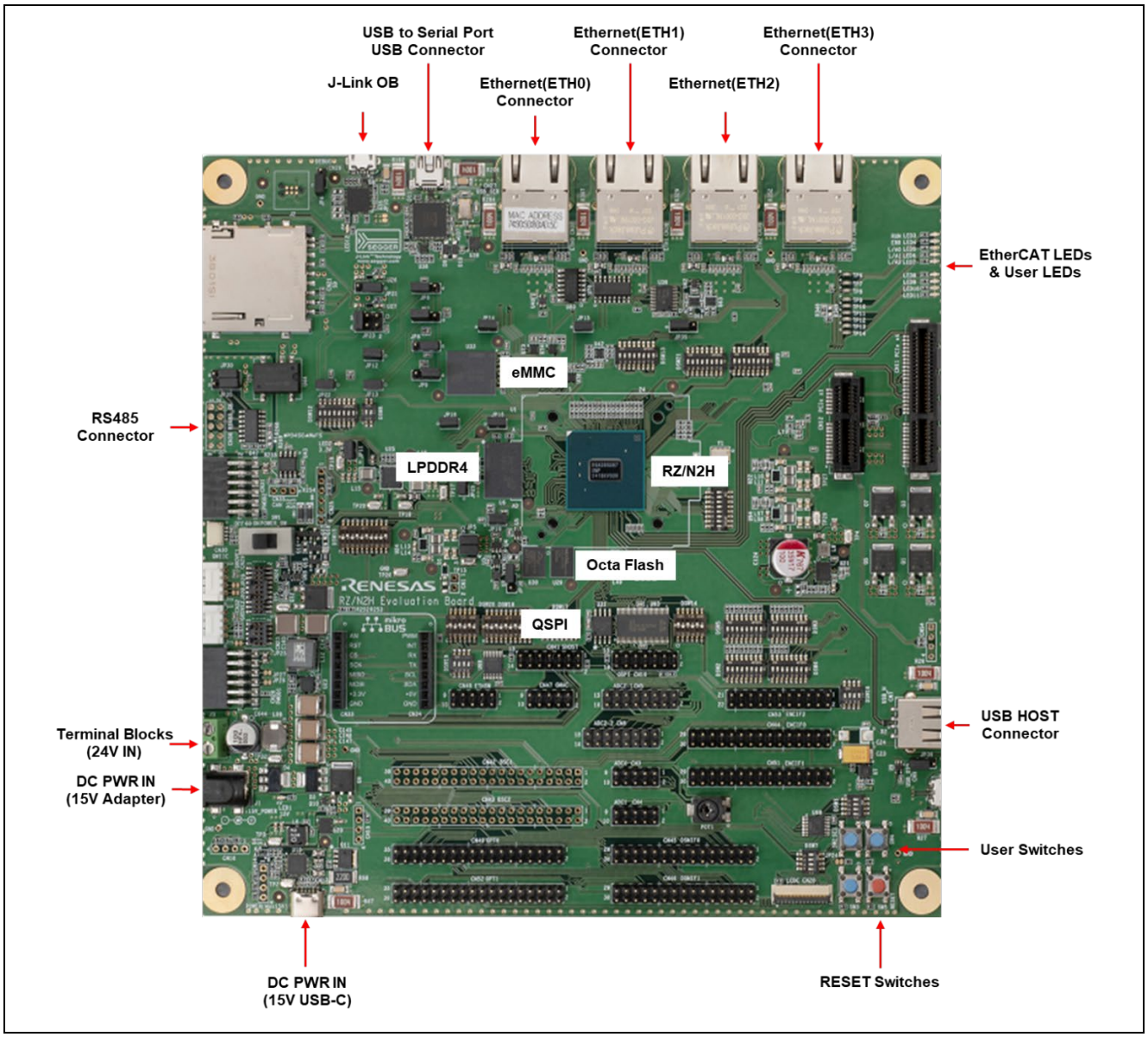


Figure 4.13: RZN2H Evaluation board layout

4.5.1 Jumper and Switch Configuration

The tables below show the jumper pin and switch settings.
Text in bold red type in the tables indicates the settings changed from the time of shipment of the board.

Table 4.27 RZ/N2H EVB Jumper configuration

Reference	Jumper Position	Description
JP6	Short 2-3	3.3-V power is supplied to VCC1833_0. (for Ethernet Port 0)
JP7	Short 2-3	3.3-V power is supplied to VCC1833_1. (for Ethernet Port 1)
JP8	Short 1-2	1.8-V power is supplied to VCC1833_2. (for Ethernet Port 2)
JP9	Short 1-2	1.8-V power is supplied to VCC1833_3. (for Ethernet Port 3)
JP21	Short 2-3	Power control IC output for SD1 is supplied to VCC1833_7. (for SD1)
JP23	Short 5-6	1.8-V power is supplied to VCC1833_6. (for SD0)
JP35	Short 1-2	VCC1833_0 is supplied to VCC_ETH2_MDIO (DSW5-6 is ON: When P21_4 and P21_5 are selected for MDIO).
JP40	**Open**	**The on-board debugging function J-Link OB is enabled.**
JP30	Short 2-3	Half-duplex communication
JP31		
JP38	Open	A PCIe reset is not included in the system reset factors.

Table 4.28 RZ/N2H EVB SW3 Settings

SW3	Setting	Description
SW3-1	ON	xSPI1 boot mode (x1 boot serial flash)
SW3-2	OFF	* Refer to" r20ut5522ejxxxx-rzn2hevb.pdf" and set according to the mode to be used.
SW3-3	ON	
SW3-4	OFF	The number of ATCM wait cycles of CPU0 in the Cortex-R52 is 1 wait cycle.
SW3-5	OFF	The number of ATCM wait cycles of CPU1 in the Cortex-R52 is 1 wait cycle.
SW3-6	OFF	The power-supply voltage of the boot peripheral is 3.3 V.
SW3-7	ON	JTAG mode = Normal mode
SW3-8	OFF	-

Table 4.29 RZ/N2H EVB SW2 Settings

SW2	Setting	Description
SW2-1	ON	XTALSEL = 'L' Select oscillator for RZ/N2H clock input.
SW2-2	OFF	-
SW2-3	ON	P27_2, P27_3, P27_6, and P31_3 are used as inputs to user DIP switches.
SW2-4	OFF	P13_4, P13_5, and P14_0 are used as RXD3, TXD3, and DE3 of the RS485.
SW2-5	ON	P00_0 to P00_2 are used as control signals for the USB power-supply IC. In this case, set DSW14-1, DSW14-3, and DSW14-5 to ON and DSW14-2, DSW14-4, and DSW14-6 to OFF.
SW2-6	ON	P01_0, P01_2, P01_4 to P01_7, and P02_0 to P02_3 are used as XSPI1 signals.
SW2-7	OFF	-
SW2-8	OFF	-

Table 4.30 RZ/N2H EVB SW4 Settings

SW4	Setting	Description
SW4-1	ON	PCIe L0 functions is used as Root Complex.
SW4-2	ON	PCIe L1functions is used as Root Complex.
SW4-3	OFF	The PCIe function is used in a configuration of 2 lanes × 1 port.
SW4-4	OFF	-
SW4-5	OFF	The 12-V power supply of the PCIe x1 connector CN12 is OFF.
SW4-6	OFF	The 3.3-V power supply of the PCIe x1 connector CN12 is OFF.
SW4-7	OFF	The 12-V power supply of the PCIe x4 connector CN11 is OFF.
SW4-8	OFF	The 3.3-V power supply of the PCIe x4 connector CN11 is OFF.

Table 4.31 RZ/N2H EVB SW5 Settings

SW5	Setting	Description
SW5-1	ON	P12_0 to 7, P13_0 to 2 are connected to eMMC.
SW5-2	ON	
SW5-3	ON	P08_6 and P17_4 are used as SD1 control signal.
SW5-4	OFF	-
SW5-5	OFF	-
SW5-6	ON	MDC and MDIO of Ethernet port 2 are connected to GMAC0 (P21_4 and P21_5).
SW5-7	ON	P29_1 to P29_7, P30_0 to P30_4, P30_7, P31_2, P31_4, and P31_5 are used as control signals for Ethernet Port 2.
SW5-8	ON	P00_0 to P00_2, P33_2 to P33_7, and P34_0 to P34_6 are used as control signals for Ethernet Port 3.

Table 4.32 RZ/N2H EVB SW6 Settings

SW6	Setting	Description
SW6-1	OFF	AN000 is connected to the potentiometer.
SW6-2	ON	
SW6-3	OFF	AN100 is connected to mikroBUS™(CN33).
SW6-4	ON	
SW6-5	OFF	AN101 is connected to Grove(Analog)(CN32).
SW6-6	ON	
SW6-7	OFF	AN102 is connected to Grove(Analog)(CN32).
SW6-8	ON	

Table 4.33 RZ/N2H EVB SW7 Settings

SW7	Setting	Description
SW7-1	ON	P03_3 is used as I2C_SCL of U11, LCDC(CN20), Grove(I2C)(CN29), QWIIC(CN30), and mikroBUS™(CN34).
SW7-2	OFF	
SW7-3	ON	P03_4 is used as I2C_SDA of U11, LCDC(CN20), Grove(I2C)(CN29), QWIIC(CN30), and mikroBUS™(CN34).
SW7-4	OFF	

Table 4.34 RZ/N2H EVB SW8 Settings

SW8	Setting	Description
SW8-1	**OFF**	**P11_0_ESC_RESETOUT# is used as RESET for Ethernet Port 2 as same as Ethernet Port 0 and 1.**
SW8-2	**ON**	

Table 4.35 RZ/N2H EVB SW9 Settings

SW9	Settings	Description
SW9-1	ON	P27_4 is used as RXD0 of the USB-to-serial conversion.
SW9-2	OFF	
SW9-3	ON	P27_5 is used as TXD0 of the USB-to-serial conversion.
SW9-4	OFF	
SW9-5	ON	P33_3 is used as RXD1 of the USB-to-serial conversion.
SW9-6	OFF	
SW9-7	ON	P33_4 is used as TXD1 of the USB-to-serial conversion.
SW9-8	OFF	

Table 4.36 RZ/N2H EVB SW12 Settings

SW12	Settings	Description
SW12-1	OFF	P00_3 is used as P00_3_ETH3_COL of Ethernet Port 3.
SW12-2	ON	
SW12-3	OFF	P11_0 is used as P11_0_ESC_RESETOUT# of Ethernet Port 0 and 1.
SW12-4	ON	
SW12-5	OFF	P03_2 is used as P03_2_GMAC_RESETOUT3# of Ethernet Port 3.
SW12-6	ON	
SW12-7	OFF	P03_1 is used as P03_1_GMAC_RESETOUT2# of Ethernet Port 2.
SW12-8	ON	In this case, set SW8-1 to ON and SW8-2 to OFF.

Table 4.37 RZ/N2H EVB SW13 Settings

SW13	Settings	Description
SW13-1	ON	P26_7 is used as P26_7_ETH1_RXER of Ethernet Port 1.
SW13-2	OFF	
SW13-3	ON	P27_0 is used as P27_0_ETH1_CRS of Ethernet Port 1.
SW13-4	OFF	
SW13-5	ON	P27_1 is used as P27_1_ETH1_COL of Ethernet Port 1.
SW13-6	OFF	
SW13-7	OFF	P13_7 is used as MDINT of Ethernet Port 2.
SW13-8	ON	

Table 4.38 RZ/N2H EVB SW14 Settings

SW14	Settings	Description
SW14-1	ON	P00_1 is used as USB_OVRCUR.
SW14-2	OFF	In this case, set SW2-5 to ON.
SW14-3	ON	Setting fixed
SW14-4	OFF	
SW14-5	ON	P00_0 is used as VBUSEN.
SW14-6	OFF	In this case, set SW2-5 to ON.

Table 4.39 RZ/N2H EVB SW15 Settings

SW15	Settings	Description
SW15-1	OFF	P22_6 is used as P22_6_SD0_WP.
SW15-2	ON	
SW15-3	OFF	P22_5 is used as P22_5_SD0_CD.
SW15-4	ON	
SW15-5	**ON**	**P14_7 is used as SDA of I2C for EEPROM access.**
SW15-6	**OFF**	
SW15-7	OFF	-
SW15-8	**OFF**	**P14_6 is used as SCK of I2C for EEPROM access.**
DSW15-9	**ON**	
SW15-10	**OFF**	

Table 4.40 RZ/N2H EVB SW16 Settings

SW16	Settings	Description
SW16-1	OFF	USB_VUBUSIN is connected to VBUS of CN8 for Function.
SW16-2	ON	
SW16-3	OFF	USB_VBUSEN is used as USB_HF_VBUSEN.
SW16-4	ON	

Table 4.41 RZ/N2H EVB SW17 Settings

SW17	Settings	Description
SW17-1	OFF	P03_0 is used as USER_LED3(LED11).
SW17-2	ON	
SW17-3	OFF	P02_7 is used as USER_LED2(LED10).
SW17-4	ON	
SW17-5	OFF	P02_6 is used as P02_6_SD0_IOVS.
SW17-6	ON	
SW17-7	OFF	P02_5 is used as P02_5_SD0_PWEN.
SW17-8	ON	

Table 4.42 RZ/N2H EVB SW18 Settings

SW18	Settings	Description
SW18-1	ON	P22_7 is used as ESC_LINKACT0(LED5).
SW18-2	OFF	
SW18-3	ON	P23_0 is used as ESC_LINKACT1(LED6).
SW18-4	OFF	
SW18-5	ON	P14_3 is used as ESC_LINKACT2(LED7).
SW18-6	OFF	
SW18-7	ON	P31_6 is used as ESC_LEDRUN(LED3).
SW18-8	OFF	
SW18-9	ON	P18_1 is used as ESC_LEDERR(LED4).
SW18-10	OFF	

Table 4.43 RZ/N2H EVB SW19 Settings

SW19	Settings	Description
SW19-1	OFF	P17_4 is used as SD1_CD.
SW19-2	ON	
SW19-3	OFF	P14_3 is used as DATG3 of LCDC(CN20), INT of PMOD1(CN28), TX of mikroBUS™(CN34), DREQ of BSC1(CN42), ENCIFOE00 of ENCIF0(CN44), or LED7 of LINKACT2.
SW19-4	ON	

Table 4.44 RZ/N2H EVB SW20 Settings

SW20	Settings	Description
SW20-1	ON	P14_3 is used as DREQ of BSC1(CN42) In this case, set SW18-5 to OFF, SW18-6 to ON, SW19-3 to OFF, and SW19-4 to ON.
SW20-2	OFF	
SW20-3	ON	P14_4 is used as DACK of BSC1(CN42).
SW20-4	OFF	
SW20-5	ON	P14_5 is used as TEND of BSC1(CN42).
SW20-6	OFF	

Table 4.45 RZ/N2H EVB SW21 Settings

SW21	Settings	Description
SW21-1	ON	P26_6 is used as P26_6_ETH1_TXER of Ethernet Port1 and P34_4 is used as CS2# of BSC1(CN42). In this case, set SW5-8 to OFF.
SW21-2	OFF	
SW21-3	ON	
SW21-4	OFF	P34_5 is used as CS3# of BSC1(CN42). In this case, set SW5-8 to OFF.
SW21-5	ON	
SW21-6	OFF	P34_6 is used as CS5# of BSC1(CN42). In this case, set SW5-8 to OFF.
SW21-7	ON	
SW21-8	OFF	-

4.5.2 Board Setup

Setting the board for running sample program is shown below.
Build and run the sample code on the RZ/N2H Evaluation board by following the steps below.
Both loading into RAM and flash can be done using IAR Embedded Workbench or e^2 studio.

1. Connect the debugger to the header "CN24" on the RZ/N2H evaluation board.

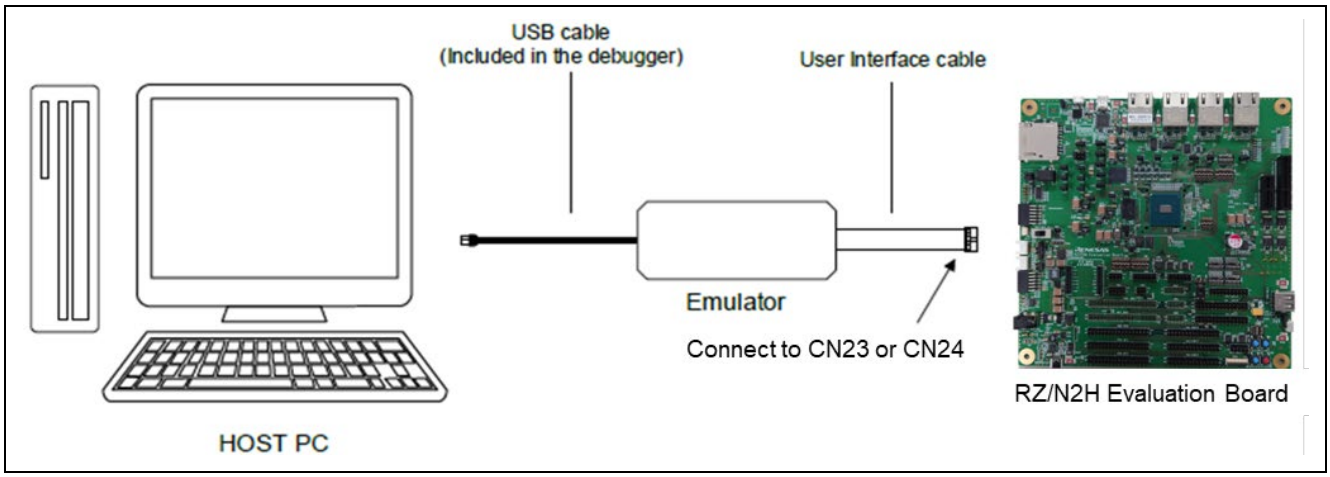


Figure 4.14: RZ/N2H evaluation board debug connection diagram

When using J-Link OB, connect the USB cable to the header "CN26" and set "JP40" to open.

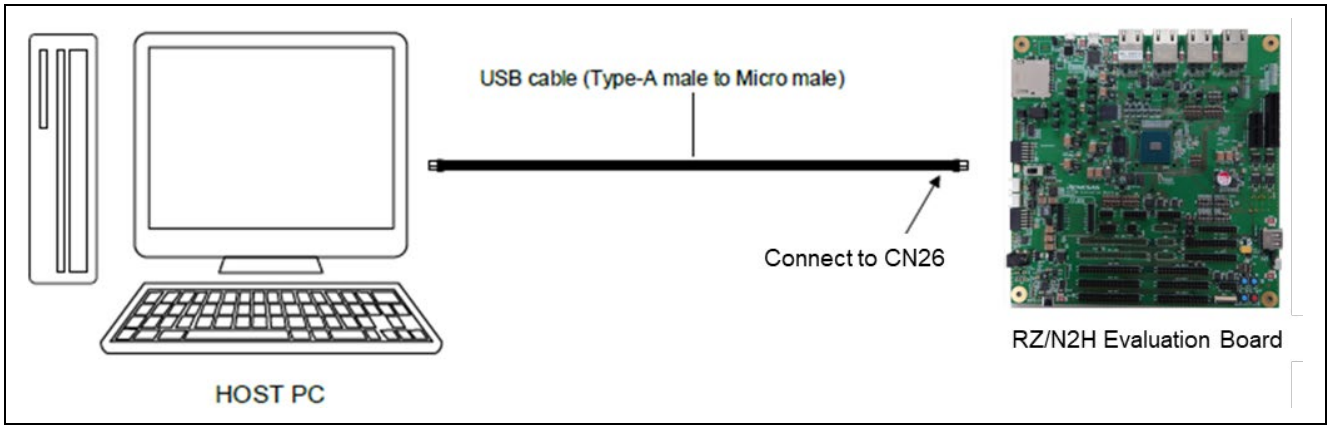


Figure 4.15: RZ/N2H evaluation board debug connection diagram (J-Link OB)

2. Power is supplied using a USB cable (Type-C) or an AC / DC adapter. When using a USB cable (Type-C), connect it to the USB connector "CN13" of the RZ/N2H evaluation board. When connecting to the AC/DC adapter, connect it to the connector "J1" of the RZ/N2H evaluation board.

3. Connect host PC and RZ/N2H evaluation board using an ethernet cable. When using an ethernet cable, connect the ethernet cable into “ETH0” connector of the RZ/N2H evaluation board.
Depending on the protocol specifications, it may be possible to connect to "ETH1".

5. Set up the Host

5.1 Setting up a TwinCAT3

5.1.1 Copying the ESI Files

Before starting TwinCAT, copy the ESI file(.xml) included in the release folder to the TwinCAT destination folder.

The release folder varies depending on the target device:

- For single-core projects (RZ/T2L, RZ/N2L):
  RZT2L_EtherCAT_RSK_rev0410\common\EoE_lwIP\ESI

  Note) If you are using RZ/N2L, replace “**RZT2L”** with “**RZN2L”**.

- For multi-core projects (RZ/T2M, RZ/T2ME, RZ/T2H, RZ/N2H):
  RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\common\EoE_lwIP\ESI

  Note) If you are using a different device or core configuration,
  replace the folder names according to your environment as shown below:

  - RZ/T2M, RZ/T2ME (CR52_Dual only):
    RZT2M_RZT2ME_EtherCAT_RSK_rev0410\CR52_Dual\common\EoE_lwIP\ESI

  - RZ/N2H (CR52_Dual):
    RZN2H_EtherCAT_EVB_rev0410\CR52_Dual\common\EoE_lwIP\ESI

  - RZ/N2H (CR52_CA55):
    RZN2H_EtherCAT_EVB_rev0410\CR52_CA55\common\EoE_lwIP\ESI

The ESI file:

- For RZ/T2L, RZ/T2M, RZ/T2ME, RZ/T2H
  Renesas EtherCAT RZT2 EoE.xml

- For RZ/N2L, RZ/N2H
  Renesas EtherCAT RZN2 EoE.xml

The TwinCAT destination folder:

\TwinCAT\3.x\Config\IO\EtherCAT

5.1.2 Add Driver

Add the Ether driver for TwinCAT. (First time only)

From the start menu, select [TwinCAT3] → [Show Realtime Ethernet Compatible Devices…].

Select the connected Ether port from the communication ports and install it.

If the selected ethernet adapter is moved in [Installed and ready to use devices(realtime capable)], there is no problem.

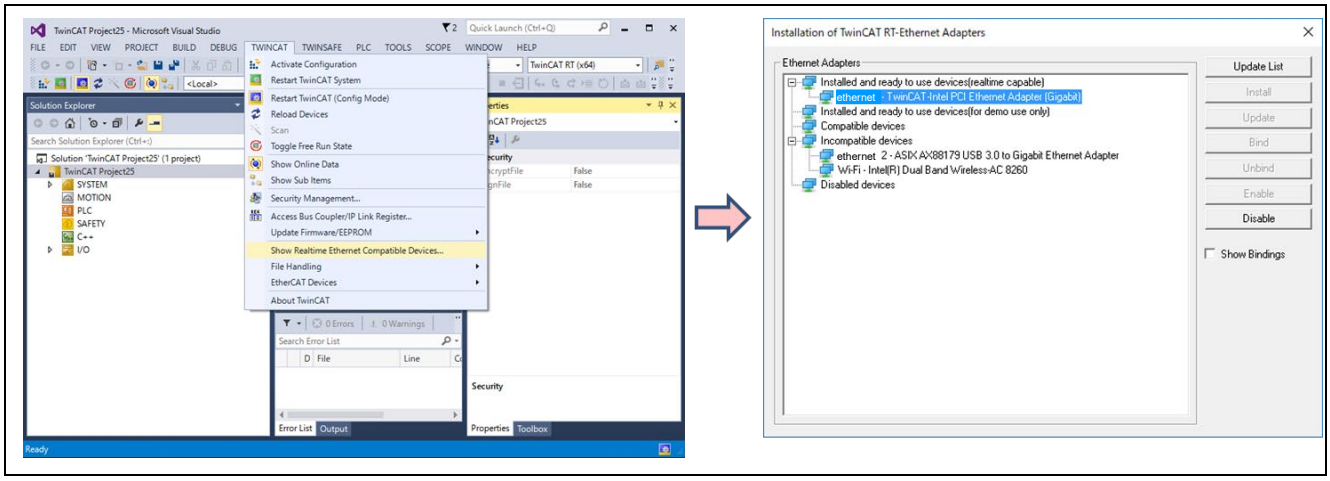


Figure 5.1 Add driver

Note). If you don't use the NIC made by Intel, ethernet adapter is moved in [Installed and ready to use devices(for demo use only)].

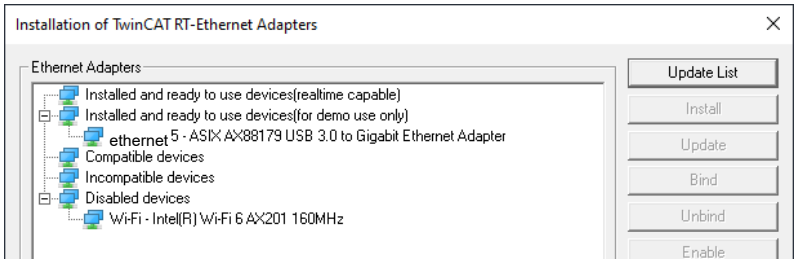


Figure 5.2 In the case of the NIC made by Intel

5.2 IP address setting

In order to operate the EoE sample program, it is necessary to set the IP address of the EtherCAT MainDevice and the EtherCAT SubDevice as fixed IP addresses.

Set the IP address of the EtherCAT SubDevice in the network configuration file of the TCP/IP stack of the sample program at the same time.

1. Enable EtherCAT and TCP/IP in the network connection settings as below figure.

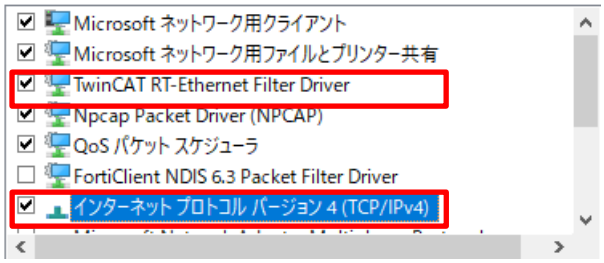


Figure 5.3 IP address setting (1)

2. Configure the host PC network connection as below figure.

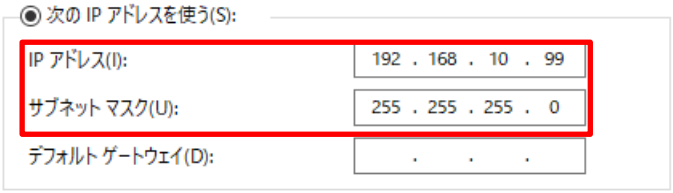


Figure 5.4 IP address setting (2)

3. IP address settings are possible to change in the following file.

   \tcpip\renesas\application\lwip_port_instance.c

6. Running the Sample Application

This chapter describes how to generate the EtherCAT SubDevice Stack Code (SSC), build the sample project, and start debugging using either EWARM or e² studio.

The procedures in this chapter use **RZ/T2L** as the representative example for single-core projects, and **RZ/T2H (CR52_Dual)** as the representative example for multi-core projects.

If you are using a different device or core configuration, replace the folder names and project names, and core configuration in the procedures with the values shown in **Table 6.1**.

Table 6.1 Folder Names and Project Names by Target Device

Target device	Folder Name	Core	Project name (Primary)	Project name (Secondary)
RZ/T2L	RZT2L_EtherCAT_RSK_rev0410	Single (Cortex-R52)	RZT2L_RSK_ESC_EoE_lwIP	(None)
RZ/N2L	RZN2L_EtherCAT_RSK_rev0410	Single (Cortex-R52)	RZN2L_RSK_ESC_EoE_lwIP	(None)
RZ/T2M, RZ/T2ME	RZT2M_RZT2ME_EtherCAT_RSK_rev0410	CR52_Dual (Cortex-R52 CPU0 and Cortex-R52 CPU1)	RZT2M_RSK_ESC_EoE_lwIP_CR52_Dual_Primary	RZT2M_RSK_ESC_EoE_lwIP_CR52_Dual_Secondary
RZ/T2H	RZT2H_EtherCAT_EVB_rev0410	CR52_Dual (Cortex-R52 CPU0 and Cortex-R52 CPU1)	RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary	RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary
		CR52_CA55 (Cortex-R52 CPU0 and Cortex-A55 Core2)	RZT2H_EVB_ESC_EoE_lwIP_CR52_CA55_Primary	RZT2H_EVB_ESC_EoE_lwIP_CR52_CA55_Secondary
RZ/N2H	RZN2H_EtherCAT_EVB_rev0410	CR52_Dual (Cortex-R52 CPU0 and Cortex-R52 CPU1)	RZN2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary	RZN2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary
		CR52_CA55 (Cortex-R52 CPU0 and Cortex-A55 Core2)	RZN2H_EVB_ESC_EoE_lwIP_CR52_CA55_Primary	RZN2H_EVB_ESC_EoE_lwIP_CR52_CA55_Secondary

6.1 Generating the SubDevice Stack Code

The SSC Tool is used to generate the EtherCAT SubDevice stack code before building the project.

Caution) There is a point of caution when using the SSC Tool.
Please refer to the section "Appendix A : A point of caution when using SSC Tool" in advance.

Caution) If the patch command is not installed on your PC, you will need to install the 64-bit patch.exe.
Refer to the section "Appendix B : How to install patch" for instructions.
If it is already installed, skip this step.

1. Open the .esp file corresponding to your target device and core configuration:

   - For **single-core projects** (RZ/T2L, RZ/N2L):

     RZT2L_EtherCAT_RSK_rev0410\common\EoE_lwIP\SSCconfig
     RZT2_EtherCAT_EoE_CR52.esp

   - For **multi-core projects** (RZ/T2M, RZ/T2ME, RZ/T2H, RZ/N2H):

     RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\common\EoE_lwIP\SSCconfig
     RZT2_EtherCAT_EoE_CR52.esp

Note) If you are using a different device or core configuration, replace the folder name and project name, according to Table 6.1.

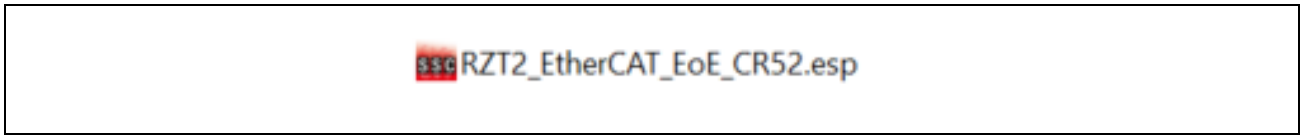


Figure 6.1 The .esp file (This is the example of RZ/T2L)

The following window opens.

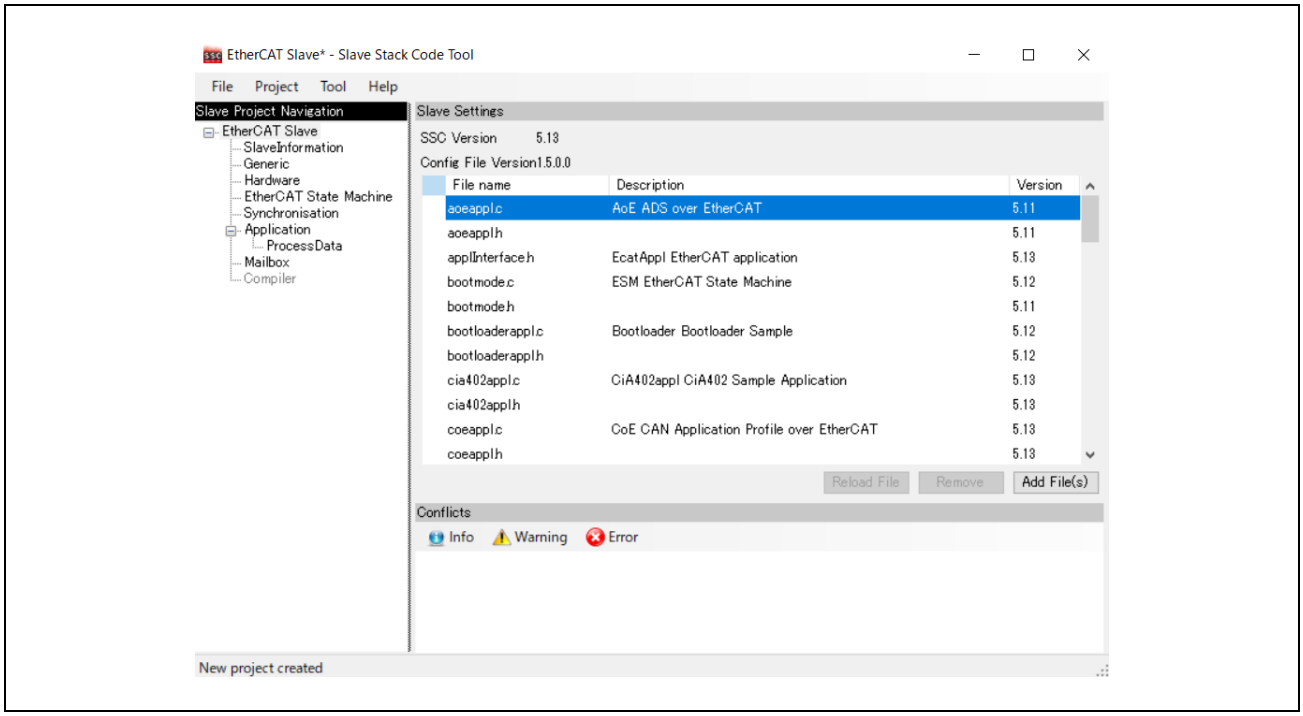


Figure 6.2 SSC tool main window

2. Select **[Project]** → **[Create new Slave Files]**.

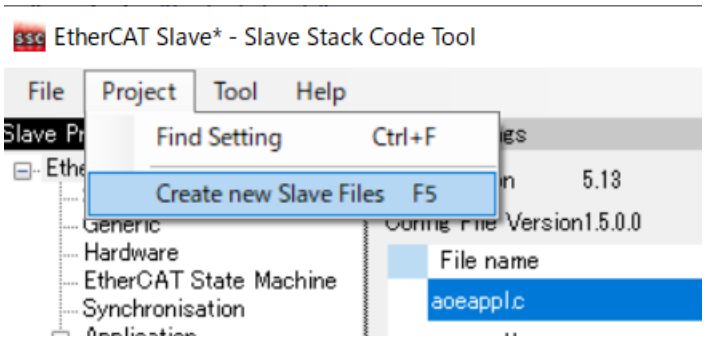


Figure 6.3 Generate EtherCAT SubDevice Stack (1)

3. Click the **[Start]** button to begin generating the EtherCAT SubDevice Stack Code.

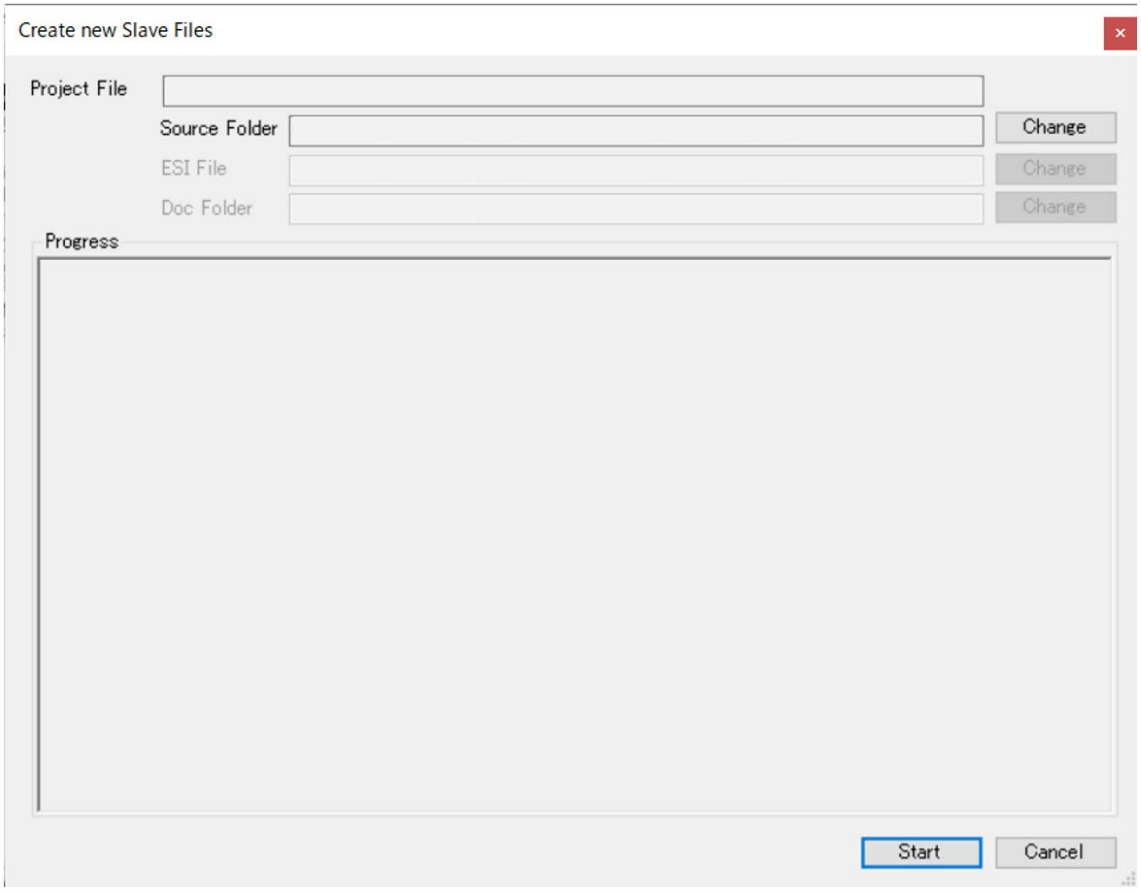


Figure 6.4 Generate EtherCAT SubDevice Stack (2)

4. When the message **"New file created successfully"** appears, the generation is complete.
   The source files are located in:
   - For **single-core projects** (RZ/T2L, RZ/N2L):
     RZT2L_EtherCAT_RSK_rev0410\common\EoE_lwIP\SSCconfig
   - For **multi-core projects** (RZ/T2M, RZ/T2ME, RZ/T2H, RZ/N2H):
     RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\common\EoE_lwIP\SSCconfig

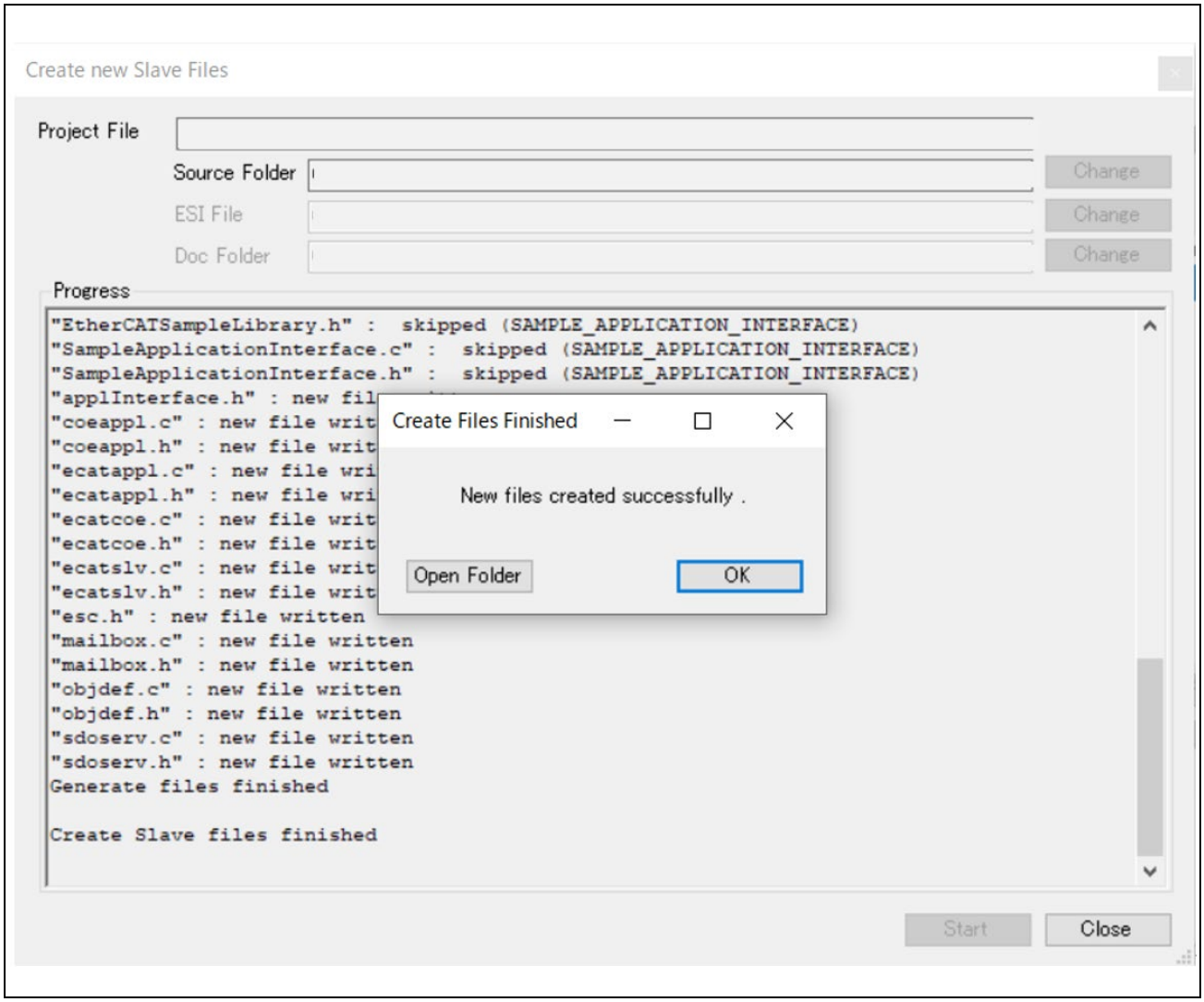


Figure 6.5 Generate EtherCAT SubDevice Stack (3)

5. Execute the batch file to apply the patch and copy the generated stack code to the project folder:

   - For **single-core projects** (RZ/T2L, RZ/N2L):

     RZT2L_EtherCAT_RSK_rev0410\common\EoE_lwIP\Patch\apply_patch_EoE_lwIP.bat

   - For **multi-core projects** (RZ/T2M, RZ/T2ME, RZ/T2H, RZ/N2H):

     RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\common\EoE_lwIP\Patch\apply_patch_EoE_lwIP.bat

   The batch file performs the following operations:

   A) Modifies the EtherCAT SubDevice stack code generated by the SSC Tool.

   The modifications are described in the patch file (.patch).

   B) Copies the Src folder containing the modified stack code to the following project directories:

   - For **single-core projects** (RZ/T2L, RZ/N2L):

     (1) RZT2L_EtherCAT_RSK_rev0410\project\EoE_lwIP\e2studio\RZT2L_RSK_ESC_EoE_lwIP\src\ethercat\beckhoff
     (2) RZT2L_EtherCAT_RSK_rev0410\project\EoE_lwIP\ewarm\RZT2L_RSK_ESC_EoE_lwIP\src\ethercat\beckhoff

   - For **multi-core projects** (RZ/T2M, RZ/T2ME, RZ/T2H, RZ/N2H):

     (1) RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\project\EoE_lwIP\e2studio\RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary\src\ethercat\beckhoff

     (2) RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\project\EoE_lwIP\ewarm\RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary\src\ethercat\beckhoff

Note) For multi-core projects, the Src folder is copied to the Secondary core project folder, not the Primary.

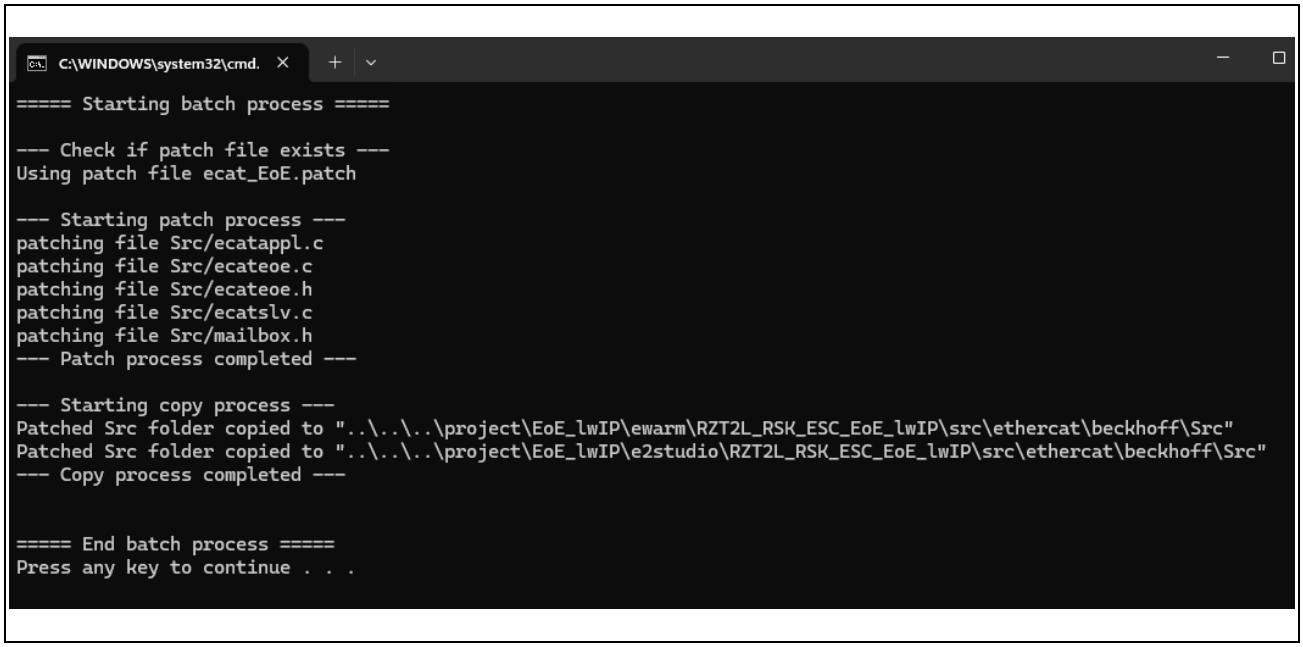


Figure 6.6 Execute the batch file (This is the example of RZ/T2L)

6.2 Debugging with EWARM

6.2.1 Single-Core Project (RZ/T2L, RZ/N2L)

1. Open the sample project (.eww).
   RZT2L_EtherCAT_RSK_rev0410\project\EoE_lwIP\ewarm\RZT2L_RSK_ESC_EoE_lwIP\RZT2L_RSK_ESC_EoE_lwIP.eww

Figure 6.7 Open EWARM workspace file

Note) If you are using a different device or core configuration, replace the folder name and project name, according to **Table 6.1**.

2. Open [Tools] > [Configure Tools…], register the following contents.

Table 6.2 Register the [Configure Tools…] settings

Setting item	Setting example
Menu Text	RZ Smart Configurator
Command	$RASC_EXE_PATH$
Argument	--compiler IAR configuration.xml
Initial Directory	$PROJ_DIR$

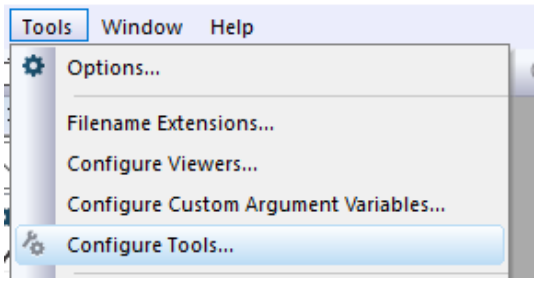


Figure 6.8 Open [Configure Tools…]

3. Open the buildinfo.ipcf file, enter your FSP Smart Configurator path in “RASC_EXE_PATH”.
   (FSP Smart Configurator is required to support RZ FSP v4.0.0 or later.)

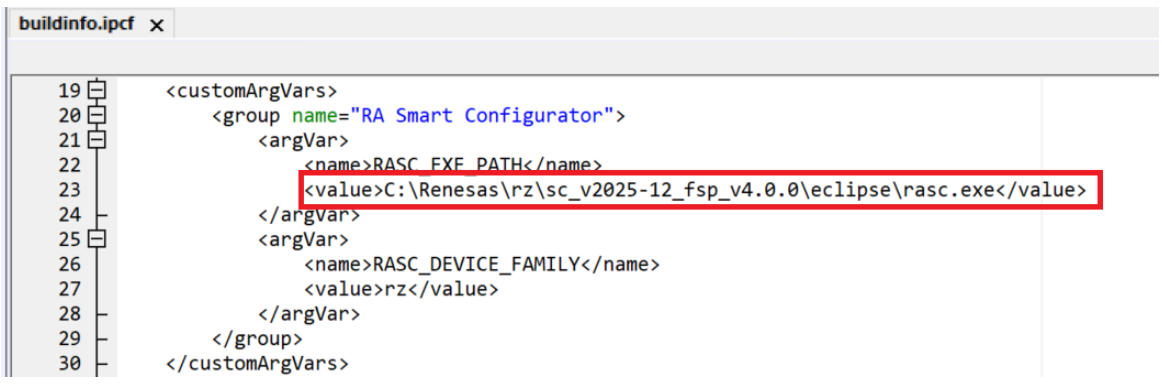


Figure 6.9 RASC_EXE_PATH in buildinfo.ipcf

4. Launch the Smart Configurator by selecting the registered menu entry (e.g., [RZ Smart Configurator]).

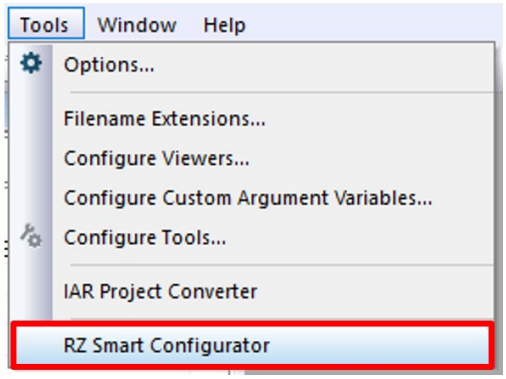


Figure 6.10 Open the Smart Configurator

5. Click "Generate Project Content" to generate the FSP code.

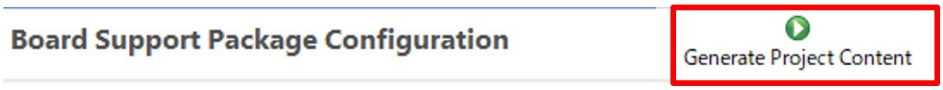


Figure 6.11 Generate Project Content

6. Select the “Options…” item in the “Project” menu, open the “Config” tab in the “Linker” category. Change “Linker configuration file” to the following linker script.

   $PROJ_DIR$/script/fsp_ram_execution_SystemRAM.icf

   That linker script file places EtherCAT protocols into System RAM.

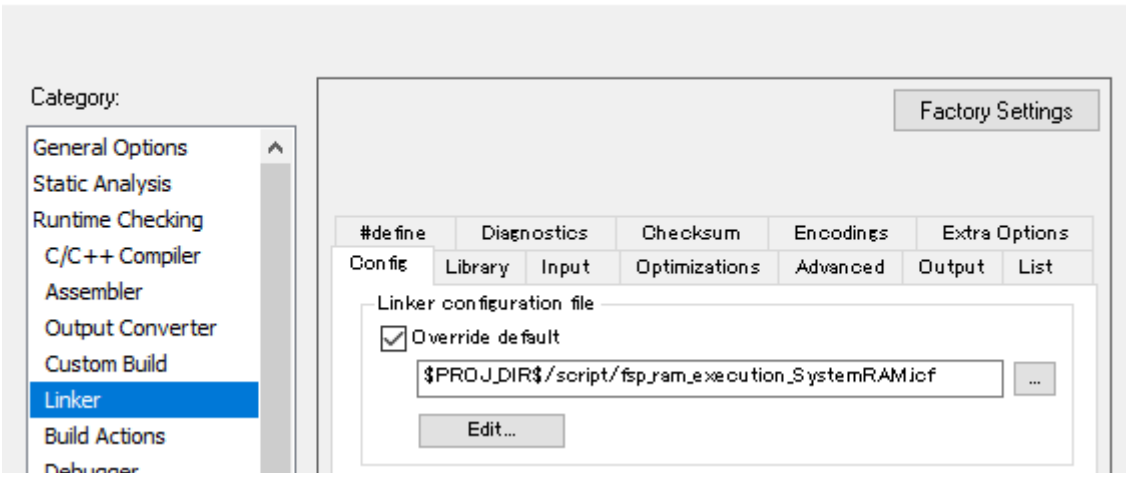


Figure 6.12 Setting the linker script

7. Click the "Make" button to build the project.

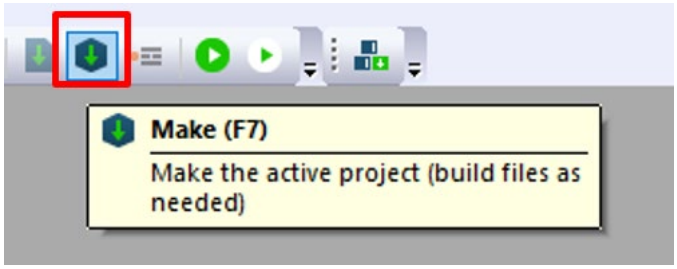


Figure 6.13 Make the project

8. Click the "Download and Debug" button to download the binary to the board.

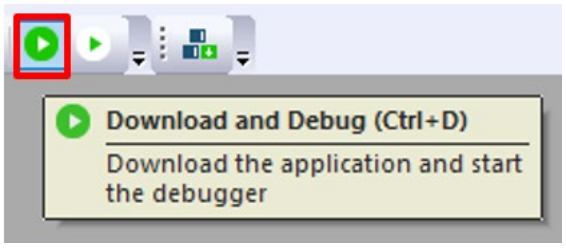


Figure 6.14 Download and Debug

9. Click the "Go" button to start program execution.

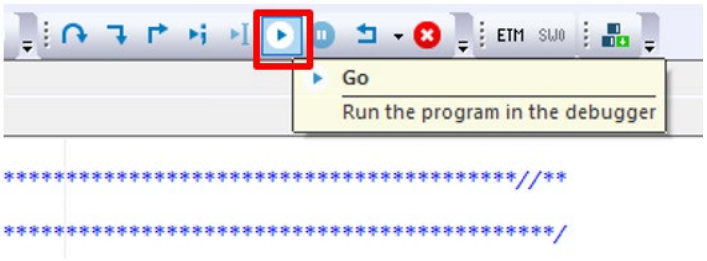


Figure 6.15 Run the program

Note) If a program is already written to flash memory when you start debugging, it may interfere with the debugging process and cause it to fail.

If this happens, erase the flash memory first and then retry.

For details, refer to "Appendix: How to Erase Flash Memory" in the document r01an6434ej**** listed in Table 1.2.

6.2.2 Multi-Core Project (RZ/T2M, RZ/T2ME, RZ/T2H, RZ/N2H)

6.2.2.1 Primary Core First Building

1. Open the Primary core project (.eww):
RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\project\EoE_lwIP\ewarm\RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary\RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary.eww

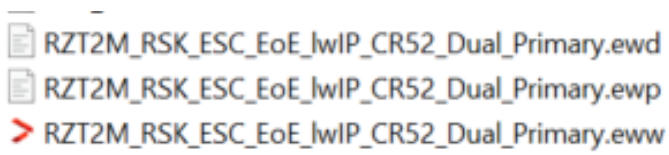


Figure 6.16 Open Primary EWARM workspace file

Note) If you are using a different device or core configuration, replace the folder name and project name, according to Table 6.1.

2. Open [Tools] > [Configure Tools…], register the following contents.

Table 6.3 Register the [Configure Tools…] settings

Setting item	Setting example
Menu Text	RZ Smart Configurator
Command	$RASC_EXE_PATH$
Argument	--compiler IAR configuration.xml
Initial Directory	$PROJ_DIR$

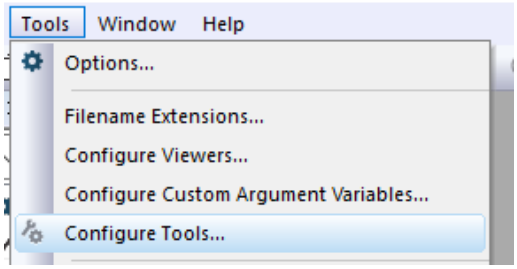


Figure 6.17 Open [Configure Tools…]

3. Open the buildinfo.ipcf file, enter your FSP Smart Configurator path in “RASC_EXE_PATH”.
(FSP Smart Configurator is required to support RZ FSP v4.0.0 or later.)

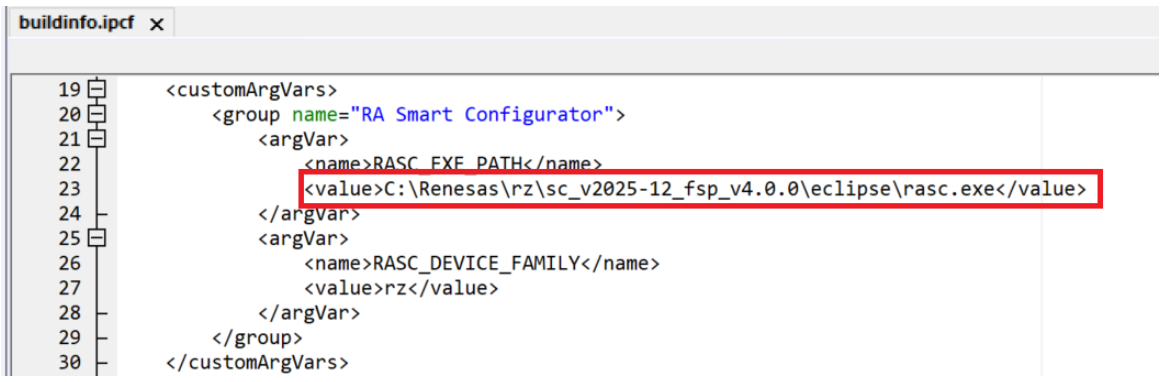


Figure 6.18 RASC_EXE_PATH in buildinfo.ipcf

4. Launch the Smart Configurator by selecting the registered menu entry (e.g., [RZ Smart Configurator]).

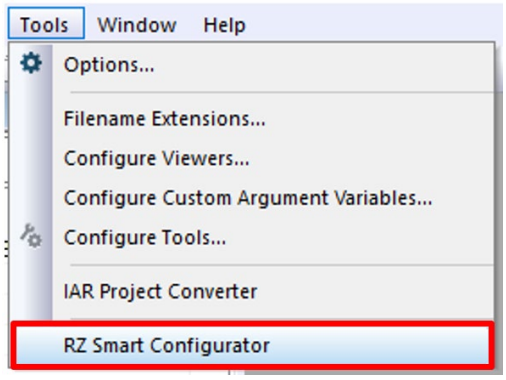


Figure 6.19 Open the Smart Configurator

Note) When using RZ/T2ME-RSK,
refer to the section Appendix C : How to Convert FSP Configuration from RZ/T2M to RZ/T2ME to change the primary core FSP configuration.

5. Click "Generate Project Content" to generate the FSP code.

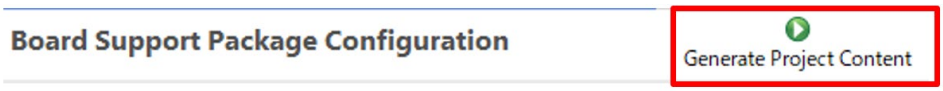


Figure 6.20 Generate Project Content

6. Click the "Make" button to build the Primary core project.

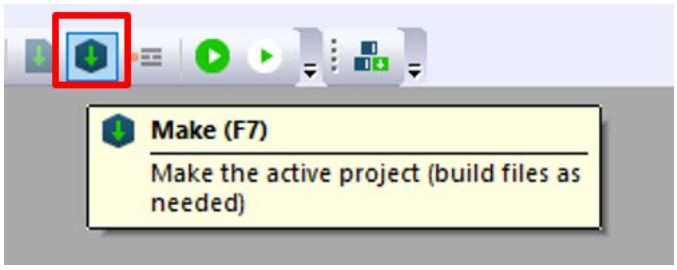


Figure 6.21 Make the Primary project

6.2.2.2 Secondary Core Building

1. Open the Secondary project (.eww):
RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\project\EoE_lwIP\ewarm\RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary\RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary.eww

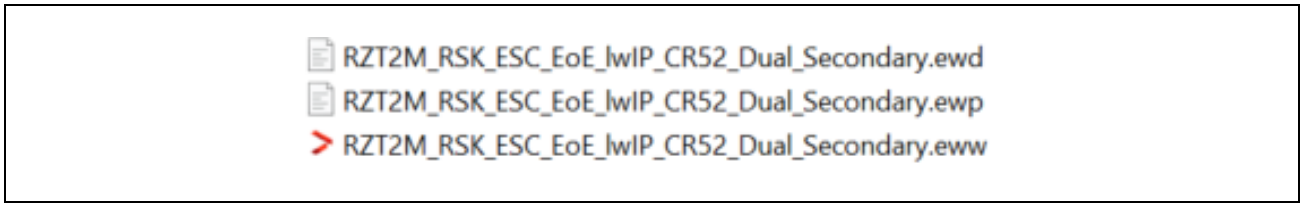


Figure 6.22 Open Secondary EWARM workspace file

2. Open the buildinfo.ipcf file, enter your FSP Smart Configurator path in “RASC_EXE_PATH”.
(FSP Smart Configurator is required to support RZ FSP v4.0.0 or later.)

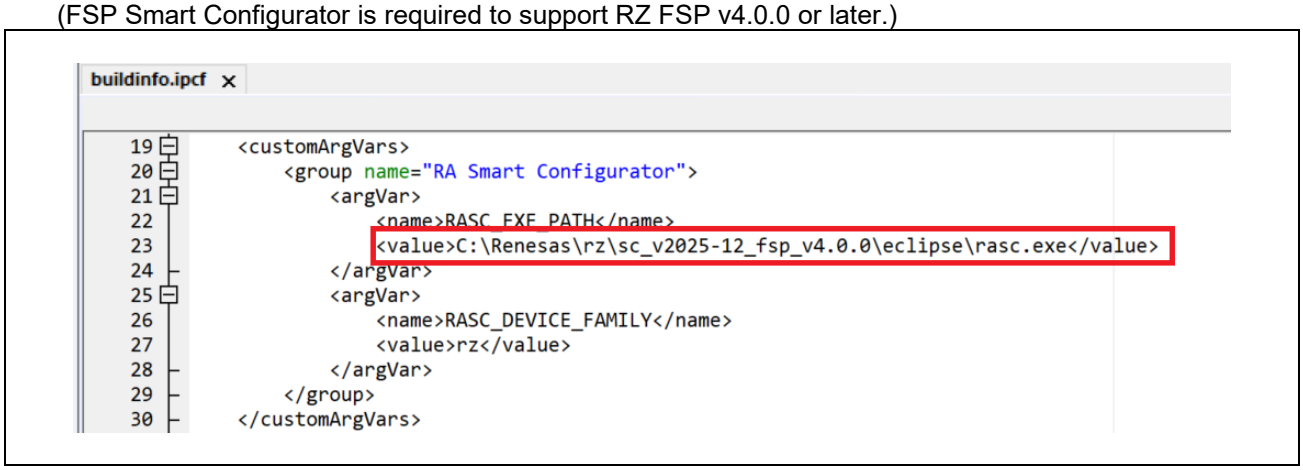


Figure 6.23 RASC_EXE_PATH in buildinfo.ipcf

3. Launch the Smart Configurator by selecting the registered menu entry (e.g., [RZ Smart Configurator]).

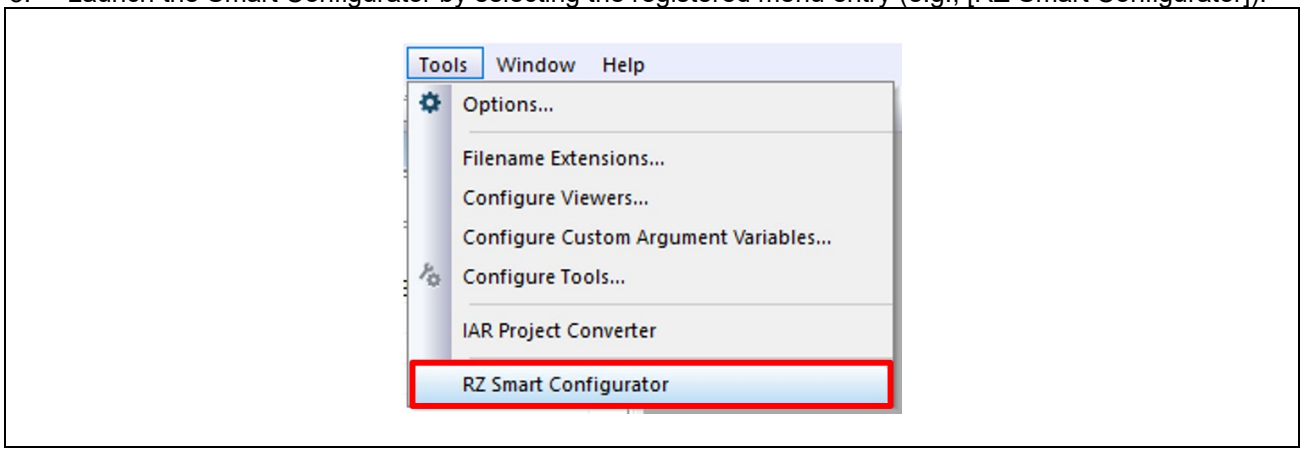


Figure 6.24 Open the Smart Configurator

Note) When using RZ/T2ME-RSK,
if you followed Appendix C : How to Convert FSP Configuration from RZ/T2M to RZ/T2ME
the secondary core FSP configuration has been automatically changed.

4. Click "Generate Project Content" to generate the FSP code.

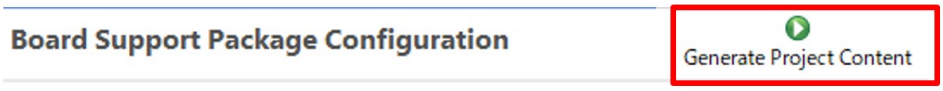


Figure 6.25 Generate Project Content

5. Click the "Make" button to build the Secondary core project.

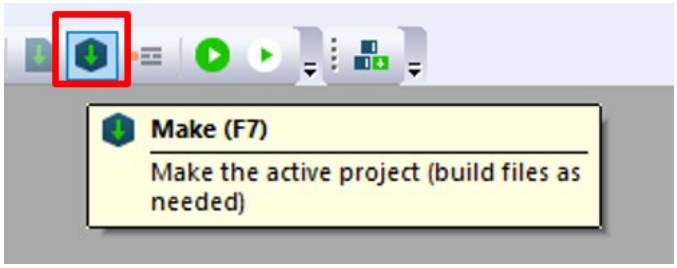


Figure 6.26 Make the Secondary project

6.2.2.3 Debug and Download

1. Close the Secondary core project and reopen the Primary core project.

2. Click the "Download and Debug" button to start dual-core debugging.
   The Secondary core project will be opened automatically.

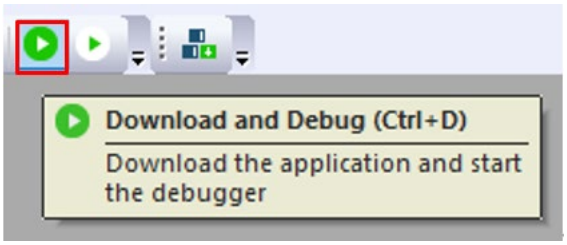


Figure 6.27 Download and Debug

Press the "Resume" button on the primary project.
Then, press the same button on the secondary project to start debugging the source code.

Note) If a program is already written to flash memory when you start debugging, it may interfere with the debugging process and cause it to fail.

If this happens, erase the flash memory first and then retry.

For details, refer to "Appendix: How to Erase Flash Memory" in the document r01an6434ej**** listed in Table 1.2.

6.3 Debugging with e²studio

6.3.1 Single-Core Project (RZ/T2L, RZ/N2L)

1. Launch e² studio and import the sample project by selecting [File] → [Import] → [Existing Projects into Workspace].

   Check the "select root directory" and push “Browse” button to select the following folder:

   RZT2L_EtherCAT_RSK_rev0410\project\EoE_lwIP

   Check the following project, push “Finish” button to import project.

   RZT2L_RSK_ESC_EoE_lwIP

Note) If you are using a different device or core configuration, replace the folder name and project name, according to Table 6.1.

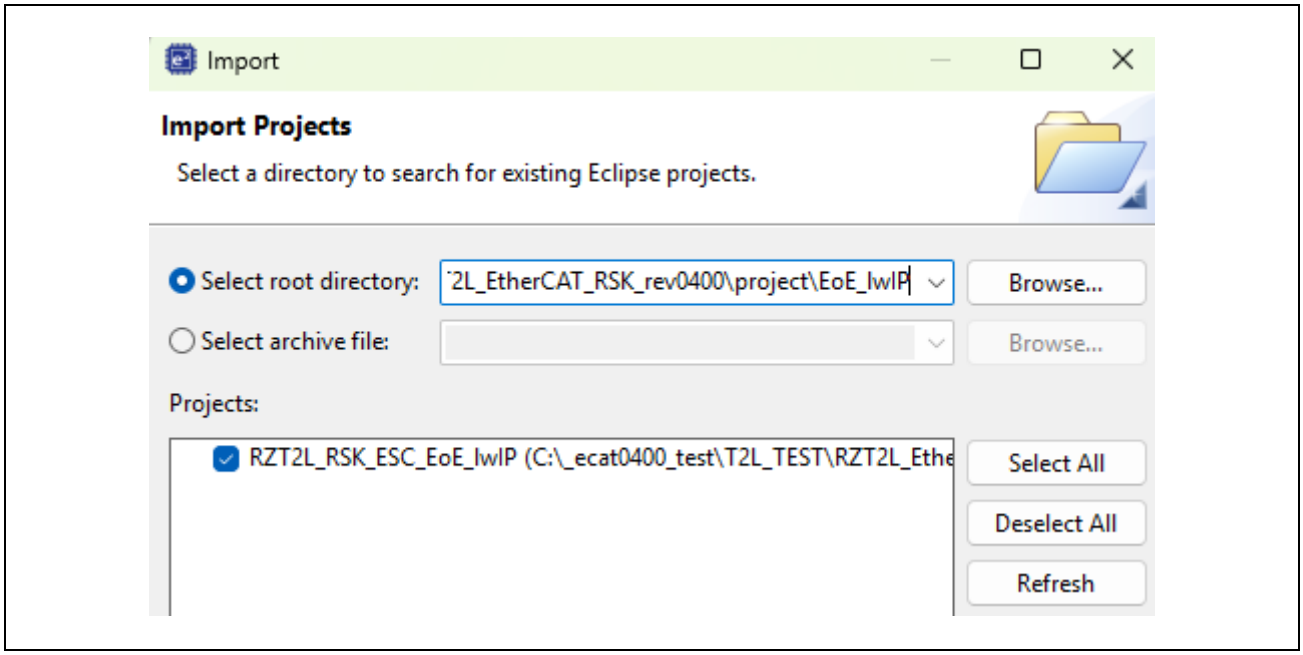


Figure 6.28 Import the project

2. Open configuration.xml in the project to launch the FSP Smart Configurator.

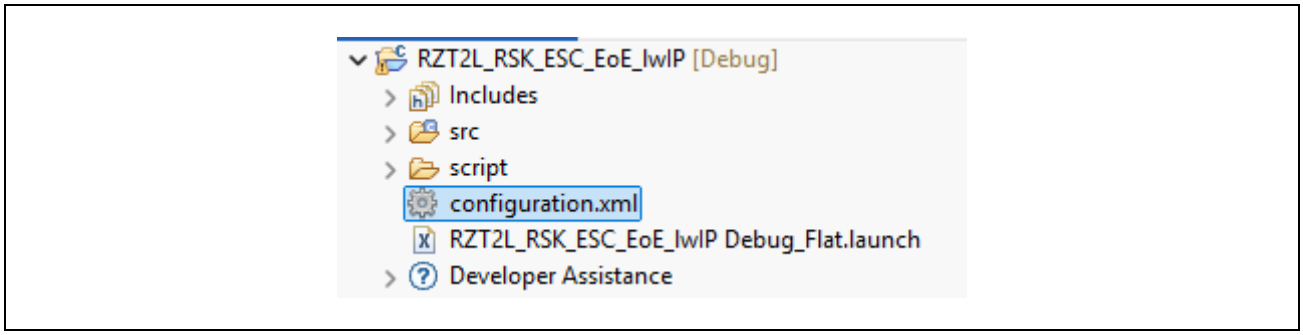


Figure 6.29 Open configuration

3. Click **"Generate Project Content"** to generate the FSP code.

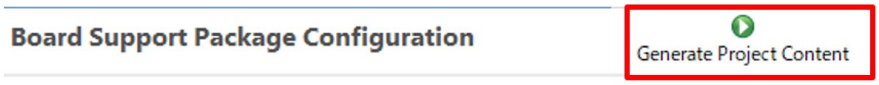


Figure 6.30 Generate Project Content

4. Click the build button (hammer icon) to build the project.

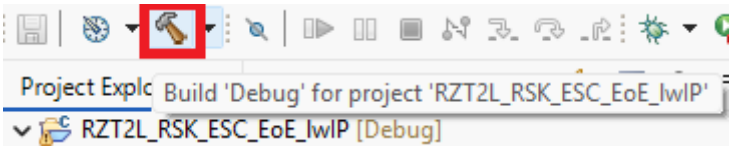


Figure 6.31 Build the project

5. Select the drop-down menu next to the debug icon and choose [Debug Configurations…].

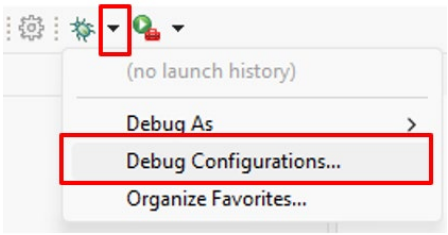


Figure 6.32 Select the drop-down menu

6. Under [Renesas DBG Hardware Debugging],
select RZT2L_RSK_ESC_EoE_lwIP Debug_Flat and click [Debug].

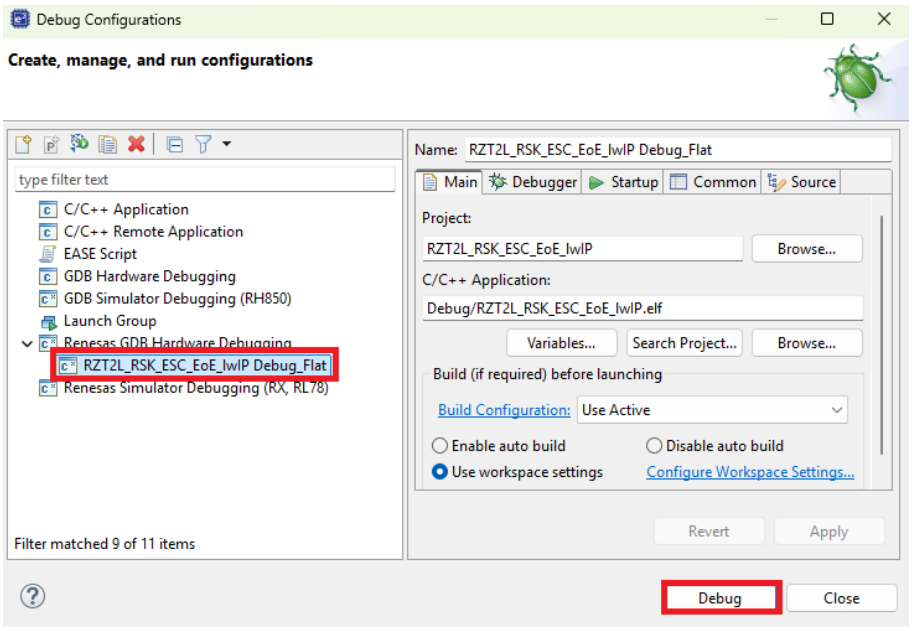


Figure 6.33 Debug Configuration window

Note) A perspective switch dialog will appear. Switch to the debug perspective.

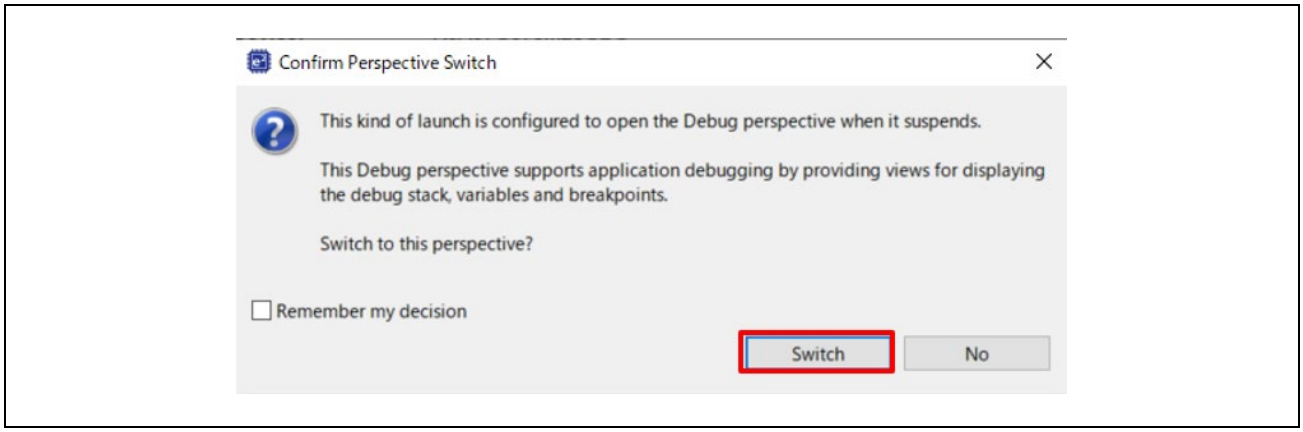


Figure 6.34 Confirm perspective switch dialog

7. The program will be downloaded to RAM and debugging will start. Press the "Resume" button.
   When the program pauses at hal_entry() in main.c, press "Resume" again to start execution.

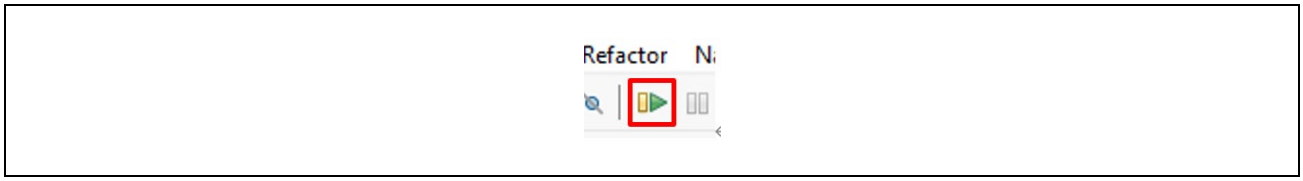


Figure 6.35 Resume button

Note) If a program is already written to flash memory when you start debugging, it may interfere with the debugging process and cause it to fail.

If this happens, erase the flash memory first and then retry.

For details, refer to "Appendix: How to Erase Flash Memory" in the document r01an6434ej**** listed in Table 1.2.

6.3.2 Multi-Core Project (RZ/T2M, RZ/T2ME, RZ/T2H, RZ/N2H)

6.3.2.1 Primary Core First Building

1. Launch e² studio and import the sample project by selecting [File] → [Import] → [Existing Projects into Workspace].

   Check the "select root directory" and push “Browse” button to select the following folder:

   RZT2H_EtherCAT_EVB_rev0410\CR52_Dual\project\EoE_lwIP

   Check the following project, push “Finish” button to import project.

   RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary

   RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary

Note) If you are using a different device or core configuration, replace the folder name and project name, according to Table 6.1.

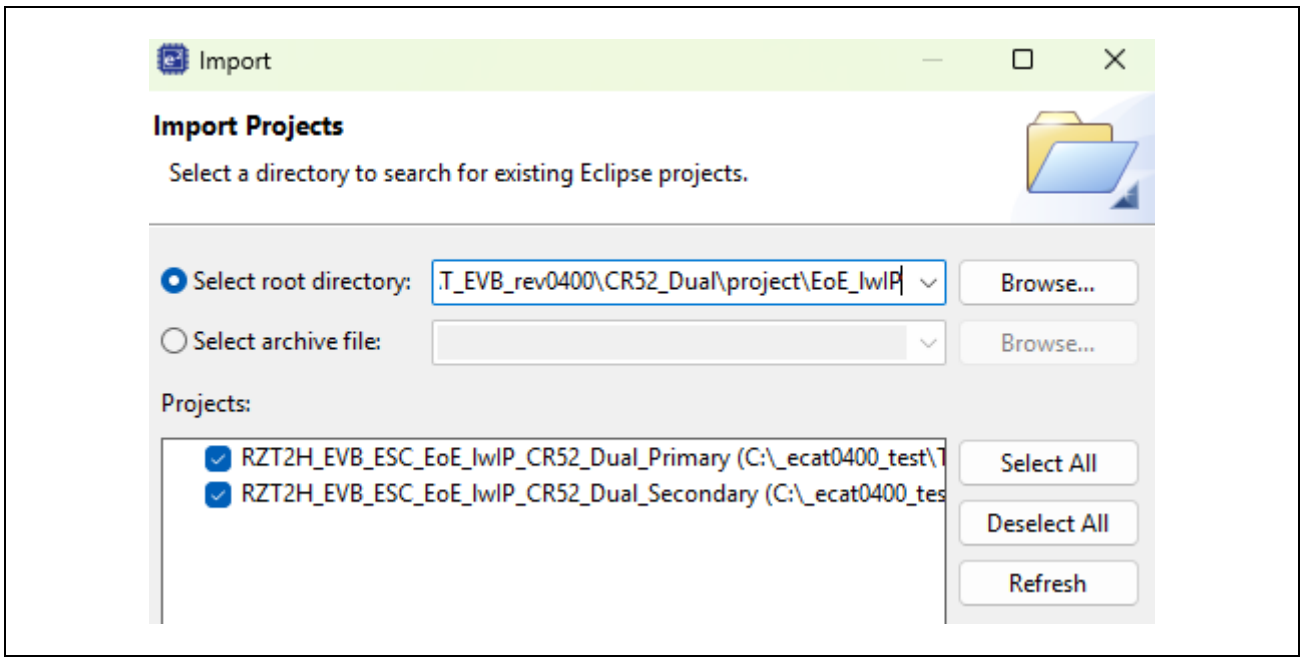


Figure 6.36 Import the projects

2. Open configuration.xml in the Primary project to launch the FSP Smart Configurator.

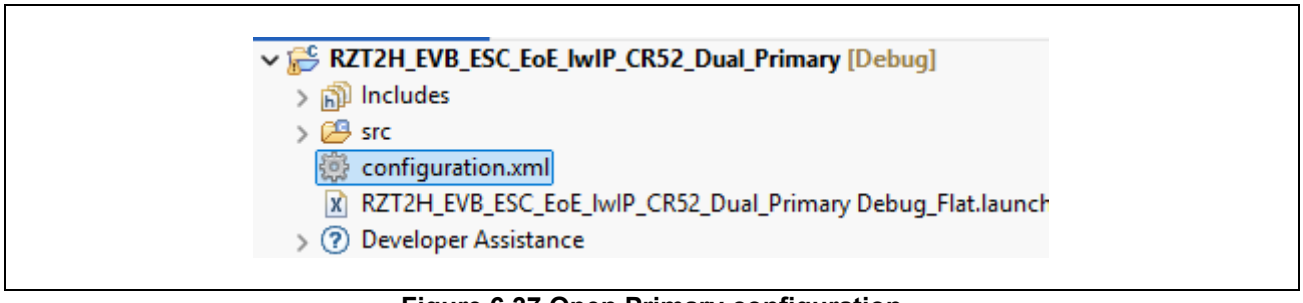


Figure 6.37 Open Primary configuration

Note) When using RZ/T2ME-RSK,
refer to the section Appendix C : How to Convert FSP Configuration from RZ/T2M to RZ/T2ME to change the primary core FSP configuration.

3. Click **"Generate Project Content"** to generate the FSP code.

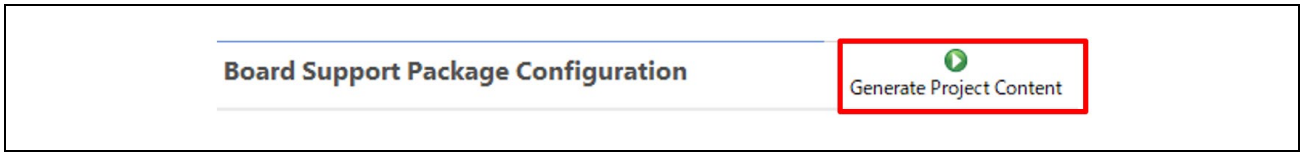


Figure 6.38 Generate Project Content

4. Click the build button (hammer icon) to build the Primary project.

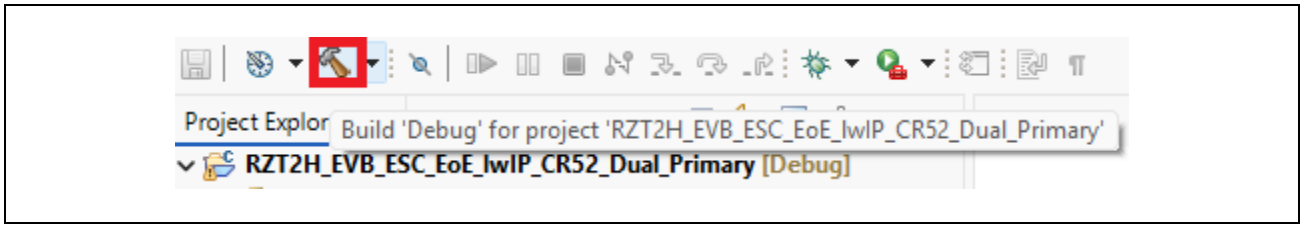


Figure 6.39 Build the Primary project

6.3.2.2 Secondary Core Building

1. Open configuration.xml in the Secondary project to launch the FSP Smart Configurator.

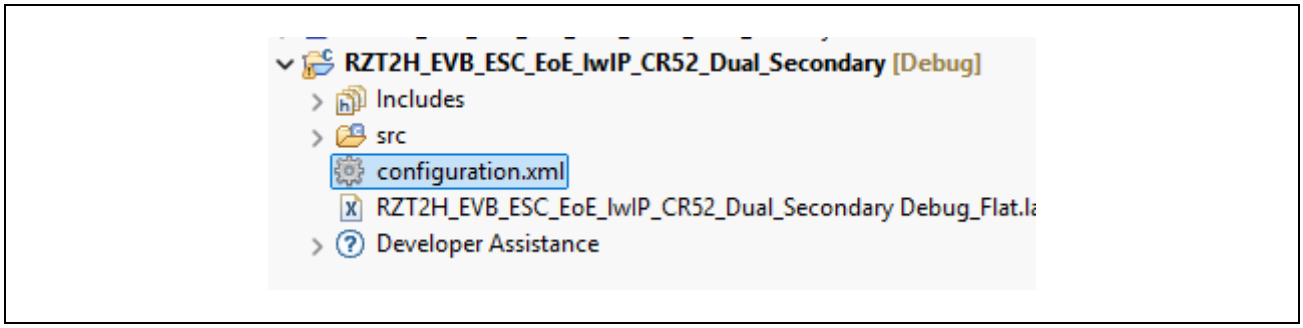


Figure 6.40 Open Secondary configuration

Note) When using RZ/T2ME-RSK,
if you followed Appendix C : How to Convert FSP Configuration from RZ/T2M to RZ/T2ME
the secondary core FSP configuration has been automatically changed.

2. Click **"Generate Project Content"** to generate the FSP code.

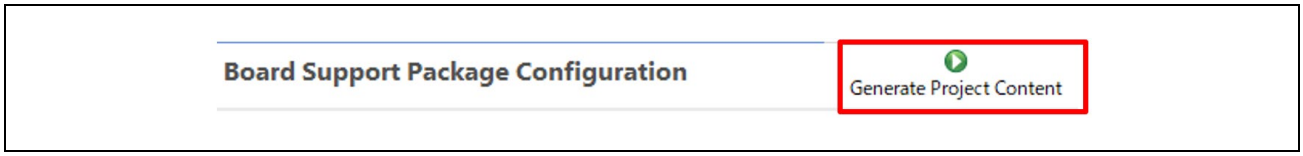


Figure 6.41 Generate Project Content

3. Click the build button (hammer icon) to build the Secondary project.

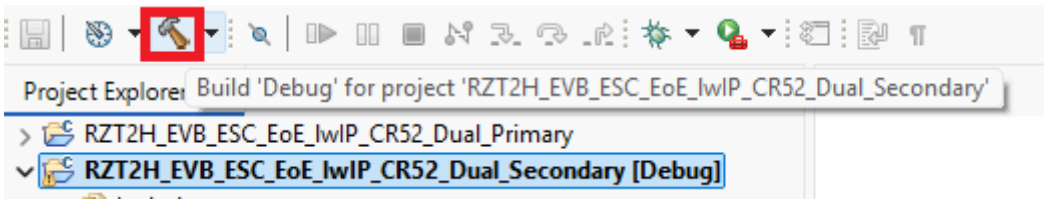


Figure 6.42 Build the Secondary project

6.3.2.3 Debug and Download for Dual Core

1. Select the drop-down menu next to the debug icon and choose [Debug Configurations…].

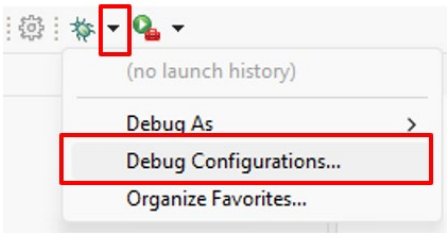


Figure 6.43 Select the drop-down menu

2. Under [Renesas DBG Hardware Debugging],
select [RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Primary Debug_Flat] and click [Debug].

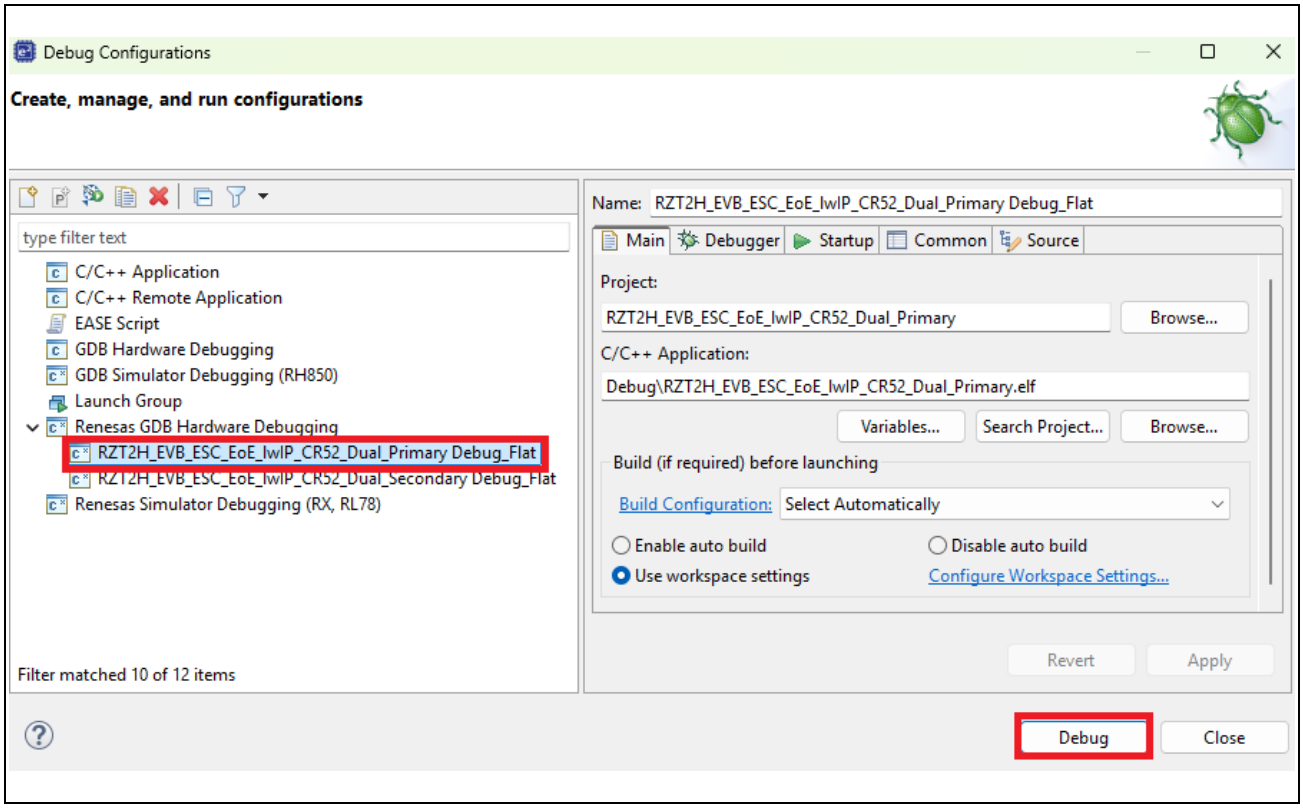


Figure 6.44 Select Primary Debug Configuration

Note) A perspective switch dialog will appear. Switch to the debug perspective.

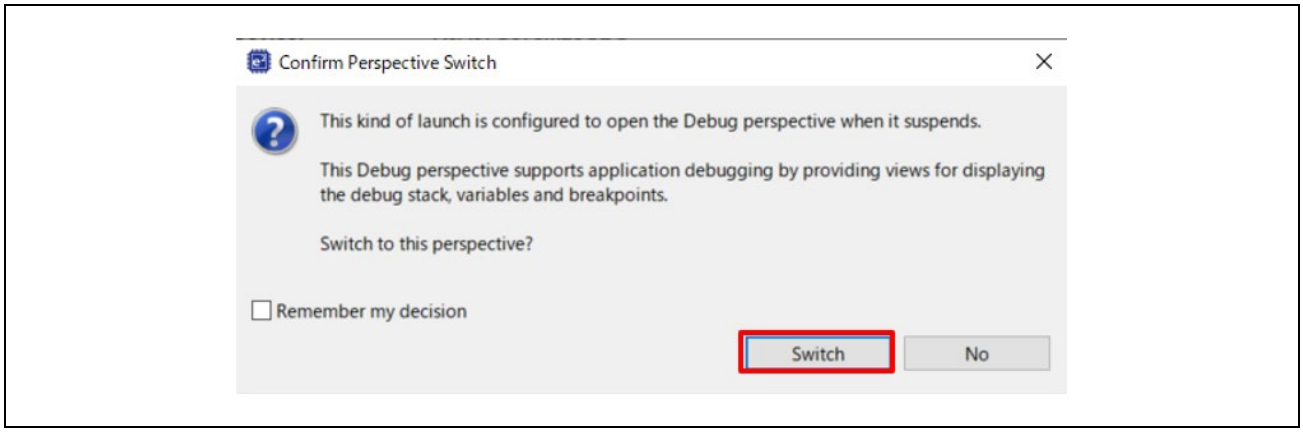


Figure 6.45 Select the drop-down menu

3. The Primary project program will be downloaded to RAM, and debugging will be started.
   Push again the triangle next to the [Debug] button, and [Debug Configurations].

   Select [Renesas DBG Hardware Debugging] →
   [RZT2H_EVB_ESC_EoE_lwIP_CR52_Dual_Secondary Debug_Flat] item, then press [Debug].

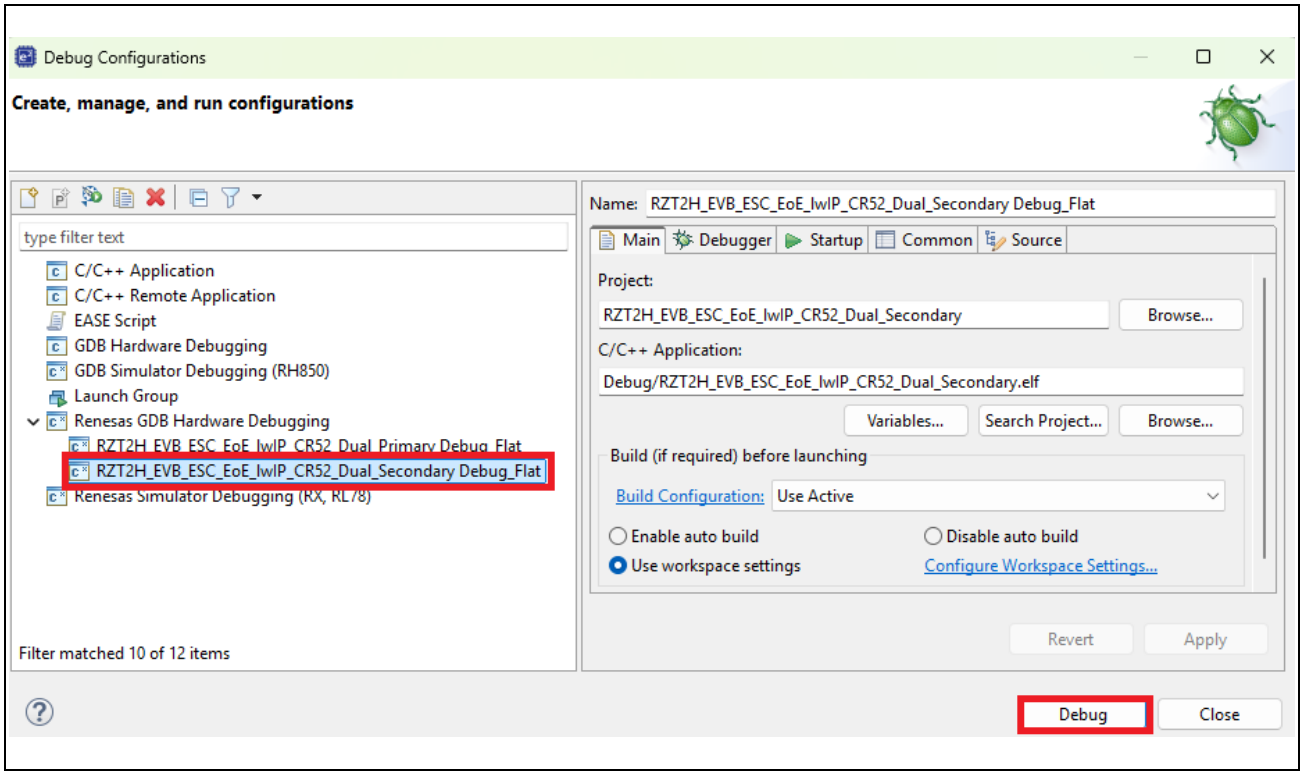


Figure 6.46 Select Secondary Debug Configuration

Note). The following dialog will appear, so click [No].

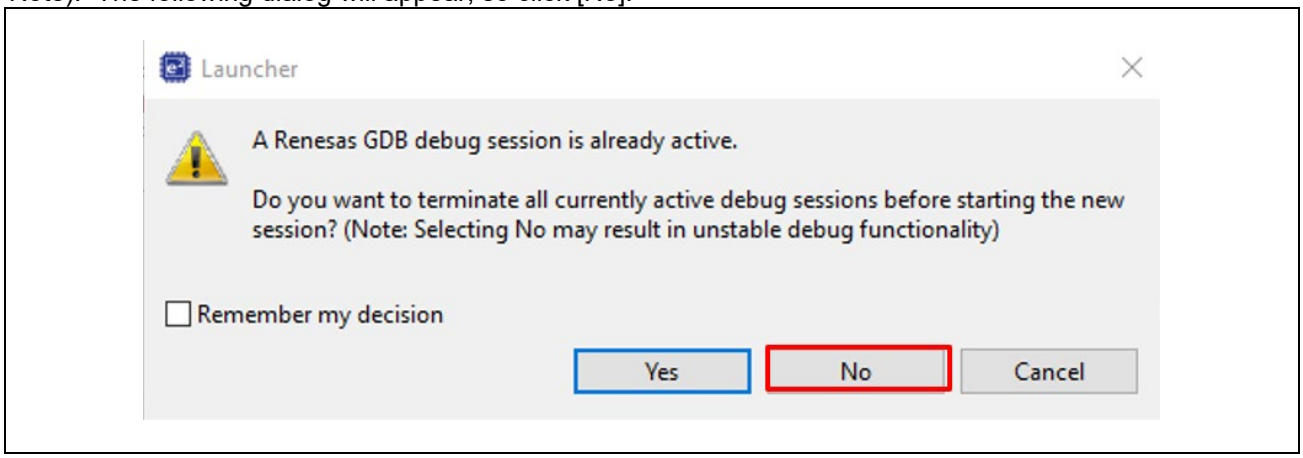


Figure 6.47 Already active dialog

Note). The following dialog will appear again, so click [Yes].

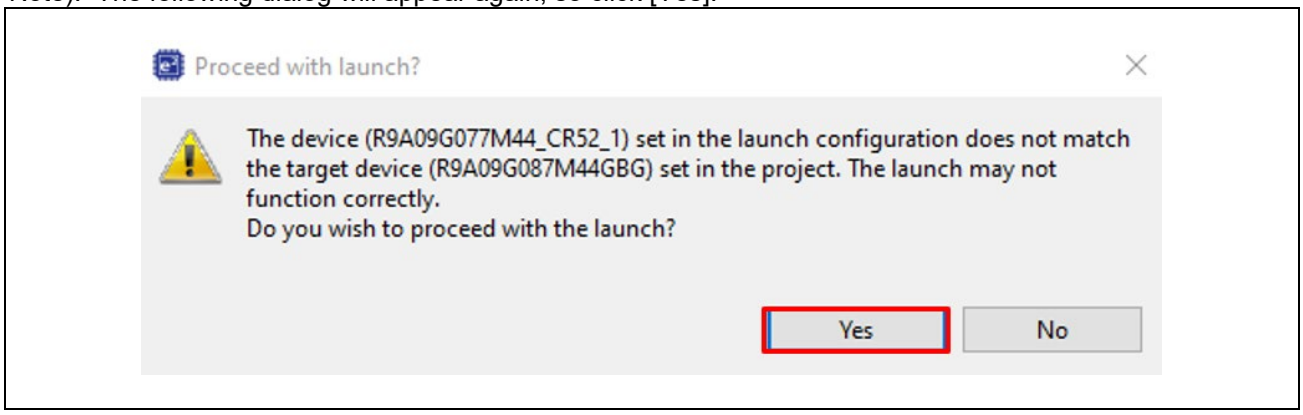


Figure 6.48 Proceed with launch dialog

4. The Secondary project program will be downloaded to RAM, and debugging will be started.
Press the "Resume" button on the primary and secondary project to start debugging the source code.

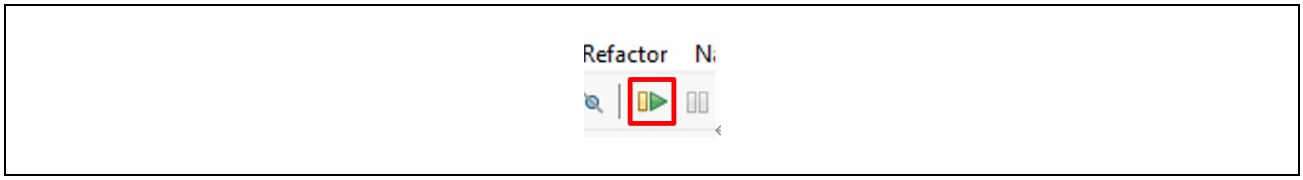


Figure 6.49 Resume button

Note) If a program is already written to flash memory when you start debugging, it may interfere with the debugging process and cause it to fail.

If this happens, erase the flash memory first and then retry.

For details, refer to "Appendix: How to Erase Flash Memory" in the document r01an6434ej**** listed in Table 1.2.

7. Demonstration of the Sample Application

Start TwinCAT3 by using the procedure described below,
From the start menu, select [Beckhoff] → [TwinCAT3] → [TwinCAT XAE (VS2013)].

After the program is started, by selecting [File] → [New] → [Project], create a new project of the TwinCAT XAE Project type. The subsequent procedure is described below.

7.1 Scanning I/O Devices

➢ (Scan for devices): Under solution explorer -> I/O -> Devices, select 'Scan' as in Figure below.

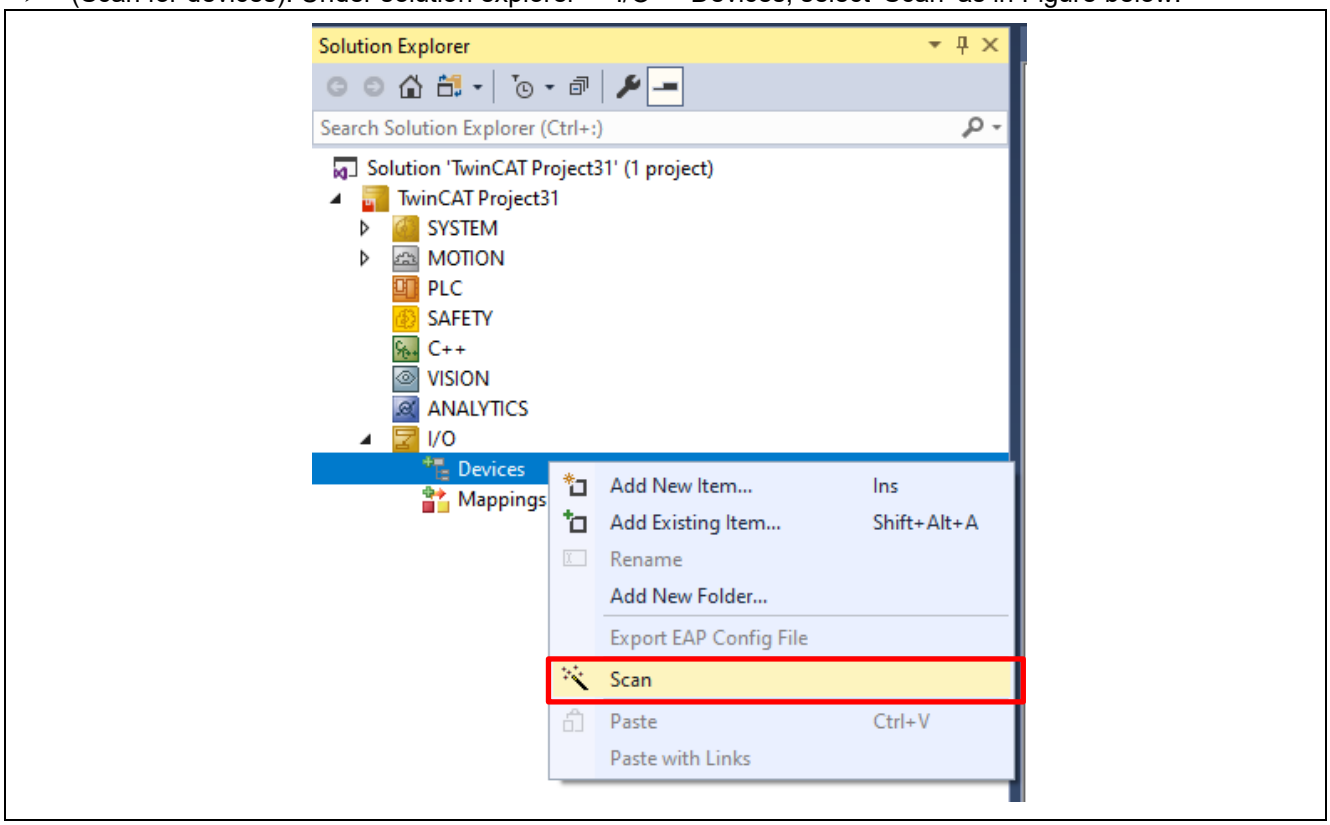


Figure 7.1 Scan devices

2. (Selecting port): EtherCAT port will be displayed as below. Select and press OK.

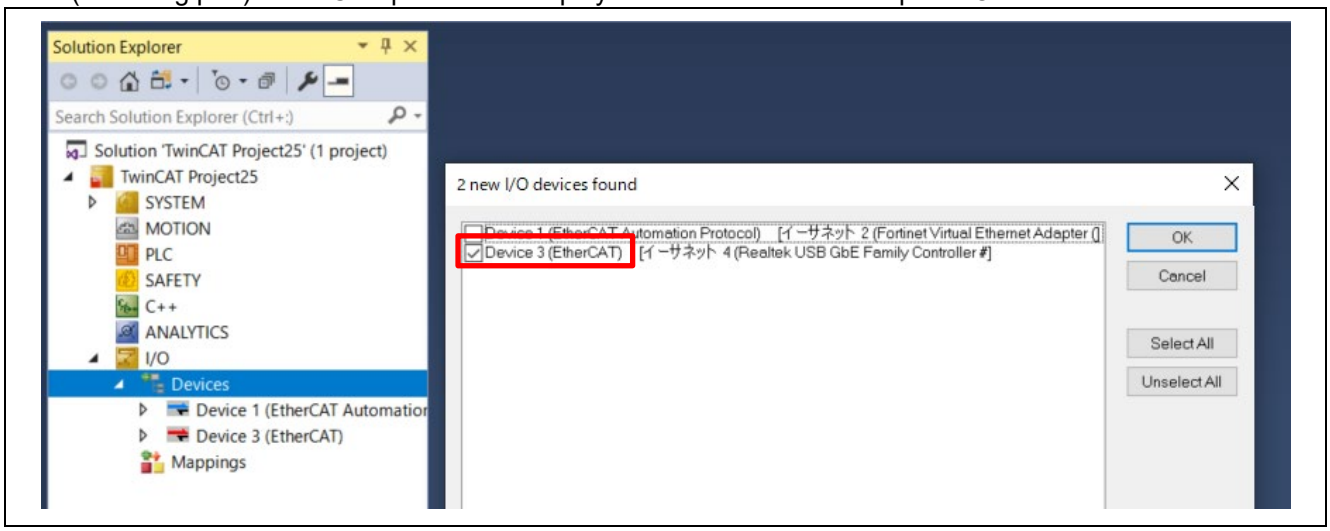


Figure 7.2 EtherCAT port is displayed

Note). If a valid EtherCAT SubDevice exists in the network, TwinCAT will display the candidate with a checkbox.

3. Start scanning the SubDevice.

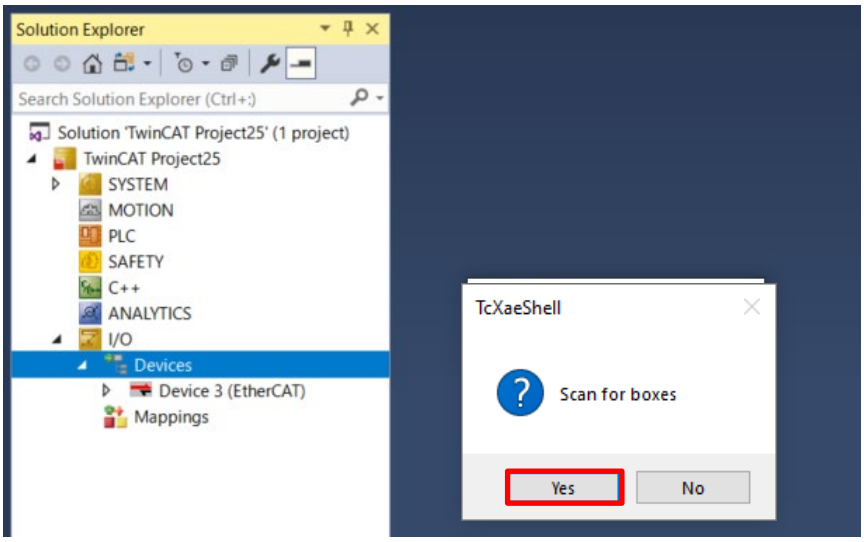


Figure 7.3 Scan SubDevice

4. (Activate SubDevice): The SubDevice is listed in the boxes. Click [Yes] on [Activate free run] dialog box.

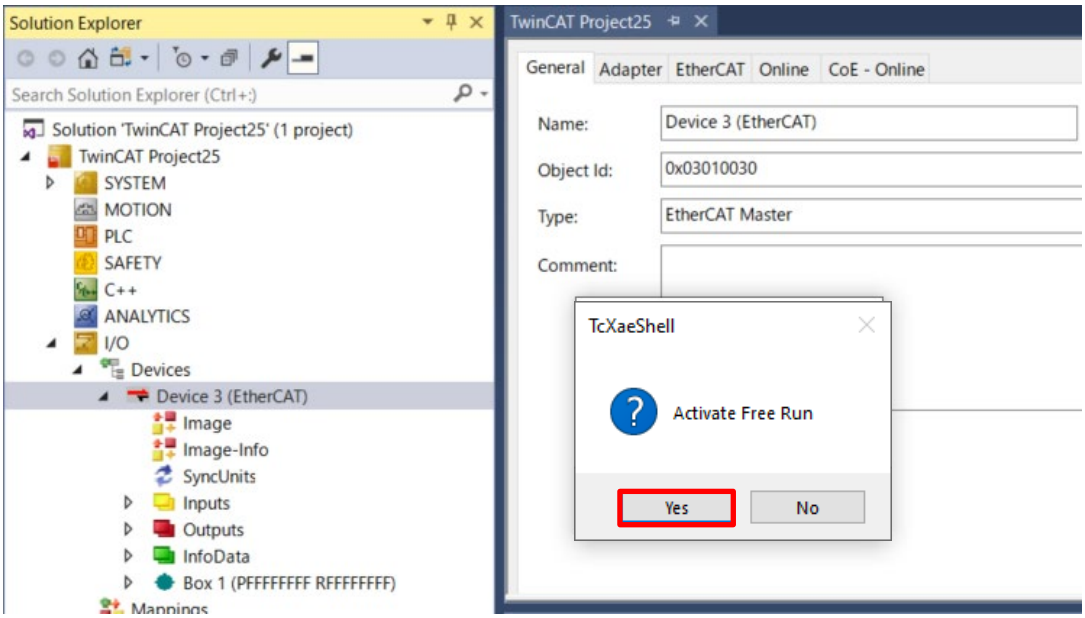


Figure 7.4 Activate Free Run

7.2 Updating EEPROM Data

If the data of another application has already been written to the EEPROM, replace the data.
The following shows the procedure for replacing the data on the EEPROM:

1. (Double-click [Box 1] to display a panel on the right side of the window.)
   Select the [EtherCAT] tab.

2. Click the [Advanced Setting] button.

3. Select [ESC Access] → [EEPROM] → [Hex Editor].

4. Select [Download from List]

5. Select the ESI according to the following list.

Table 7.1 Select the ESI

Target device	ESI
RZ/T2L-RSK	Renesas EtherCAT RZ/T2 EoE 2port
RZ/T2M-RSK, RZ/T2ME-RSK, RZ/T2H EVB	Renesas EtherCAT RZ/T2 EoE 3port
RZ/N2L-RSK, RZ/N2H EVB	Renesas EtherCAT RZ/N2 EoE 3port

6. OK and Download.

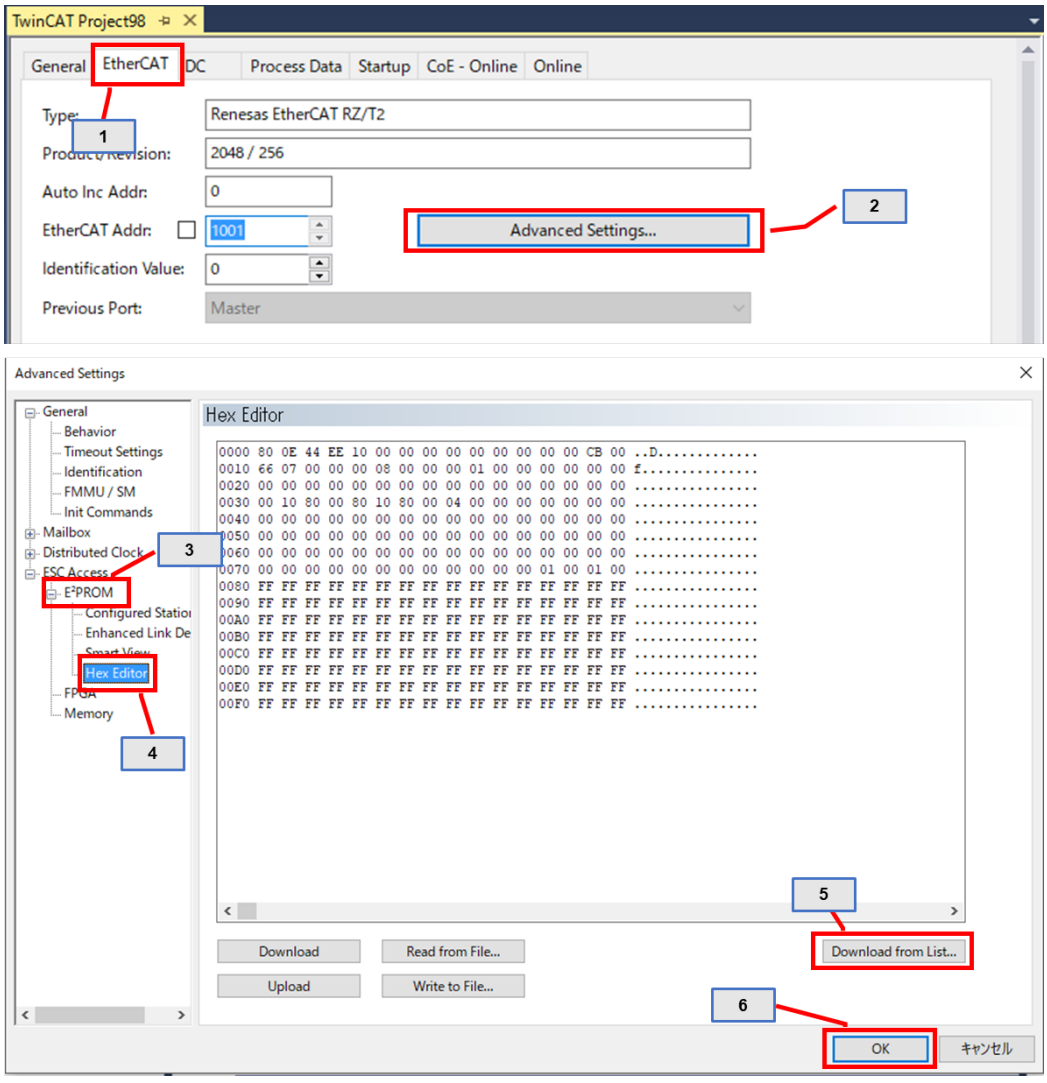


Figure 7.5 Download ESI to EEPROM

7. Apply the ESI file settings.
   Select the device and remove it.

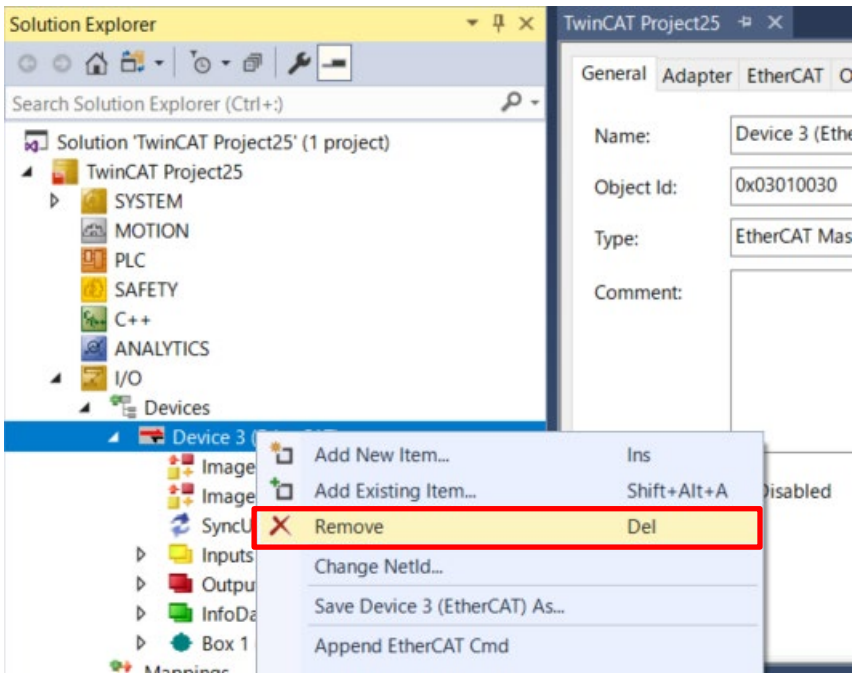


Figure 7.6 Remove the device to reflect

8. Scan the device again.
   If the desired ESI file is displayed, it is correct operation.

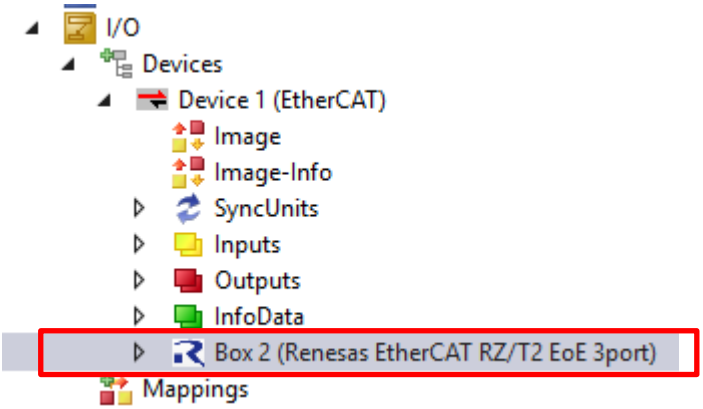


Figure 7.7 The desired ESI file (This is the example of RZ/T2H)

Option A - Create ESI binary file from ESI XML and download.

1. SSC Tool → [Tool] → [EEPROM Programmer].
2. [FILE] → [OPEN] →Browse and select the ESI file.
3. [FILE] → [Save AS] → Select type as binary.
4. A binary file will be generated in the specified folder.
5. [Read from File] Select the ESI binary file → [Download].
6. Confirm the write status using [Upload] option.

After the data is replaced, restart the RZ/x2x (by turning it off and on, or resetting it) so that the new data is applied to the microcomputer. Execute [Restart TwinCAT System].

7.3 Ethernet over EtherCAT Profile check

In this chapter, check the operation of the Ethernet over EtherCAT(EoE) profile.

7.3.1 Reload the Device

1. Press the [Restart TwinCAT (Config Mode)] button.
2. In the [Restart TwinCAT System in Config Mode] dialog box, click on [OK].
3. In the [Load I/O Devices] dialog box, click on [Yes].
4. In the [Active Free Run] dialog box, click on [Yes].

7.3.2 Checking the Operation Mode

1. If double-click on [Box 1] in the System Manager tree, panel will be displayed on the right side of the screen.
2. Select the [Online] tab and check that "Current Status" has turned to "OP".
3. In the System Manager tree, expand + on the left side of "Box 1".
   Bi-directional communication can be confirmed by input/output of “Inputcounter”/”Outputcounter”.

7.3.3 TwinCAT3 setting for EoE

Set TwinCAT3 for EoE operation.

1. Double-click [Device x (EtherCAT)], and Click [EtherCAT tab] → [Advanced Settings] button.

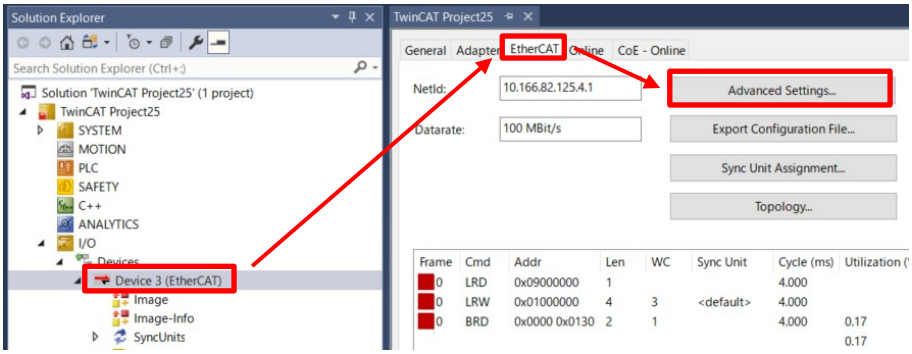


Figure 7.8 Setting for EoE (1)

2. Check the [EoE Support] items→[Virtual Ethernet Switch Enable] and [Connect TCP/IP Stack].

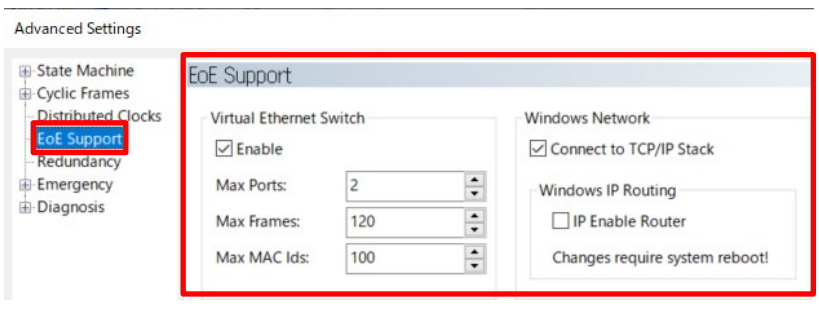


Figure 7.9 Setting for EoE (2)

3. Set the SubDevice information.
   Double-click [Renesas EtherCAT RZ/T2 EoE] or [Renesas EtherCAT RZ/N2 EoE], and Click [EtherCAT tab] → [Advanced Settings].

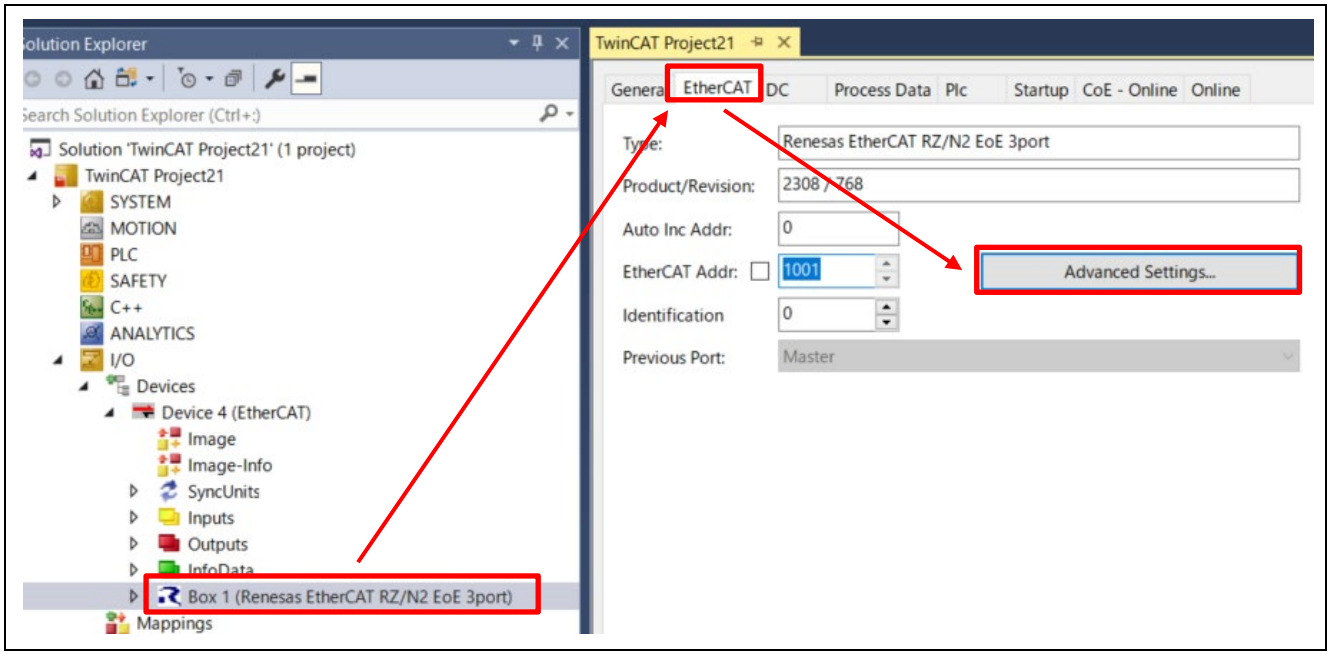


Figure 7.10 Setting for EoE (3)

4. Select [Mailbox] →[EoE]
   Select IP Port and set the following:
   IP Address: 192.168.10.100
   Subnet Mask: 255.255.255.0
   Default Gateway: 192.168.10.99

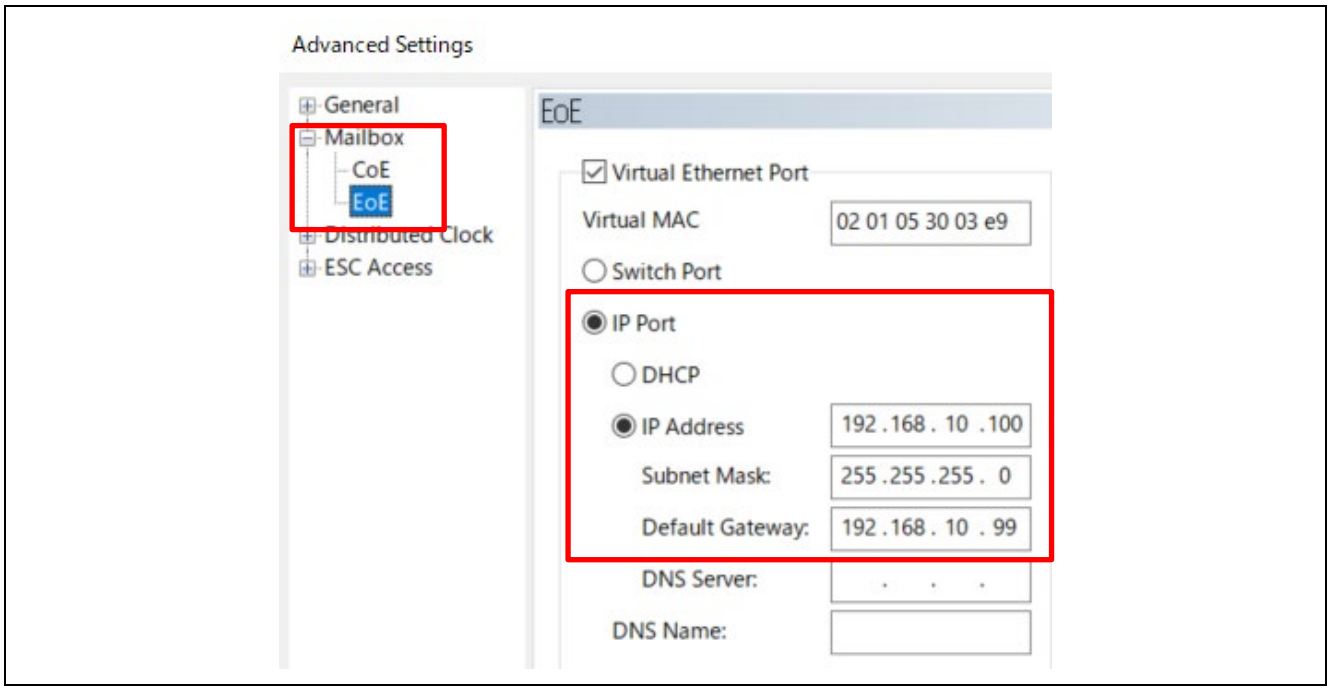


Figure 7.11 Setting for EoE (4)

5. Check TCP/IP operation. Start the command prompt and execute ping **192.168.10.100**, If get a response, connection is complete.

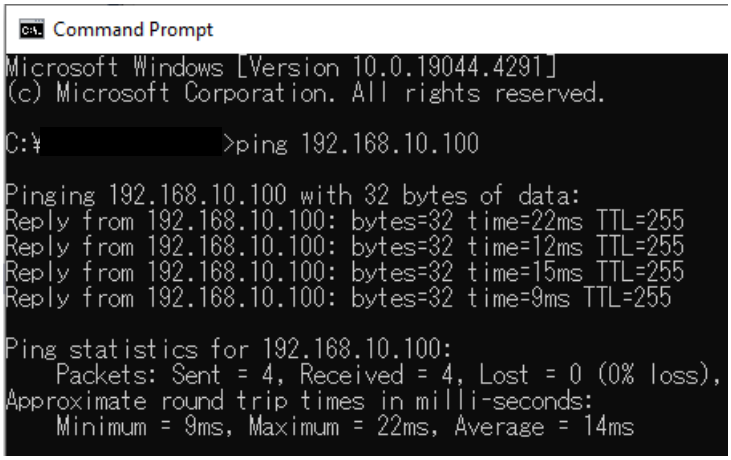


Figure 7.12 Check ping

7.3.4 Checking operation with echo server

1. Check the operation of the TCP echo server.

   Start Teraterm

   Select [TCP/IP], Enter the following settings:

   - Host : 192.168.10.100
   - Service: Telnet
   - TCP port# : 10000

   and click the [OK] button.

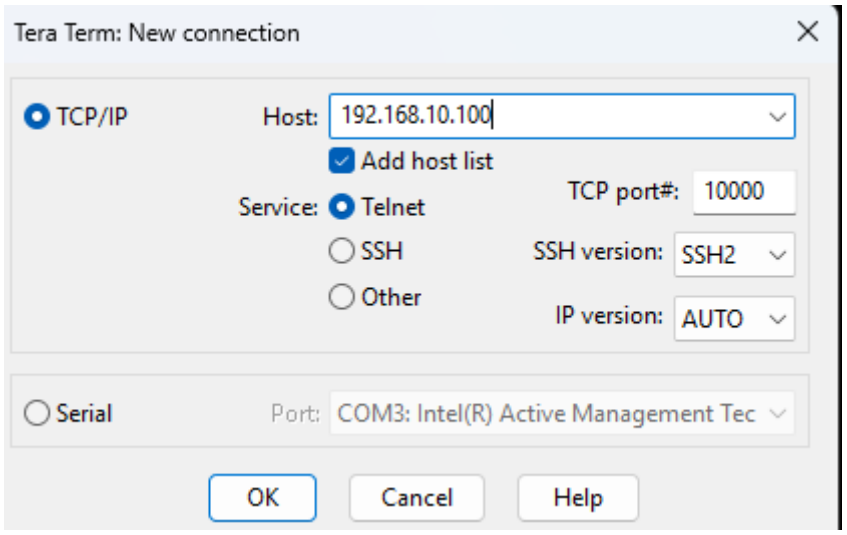
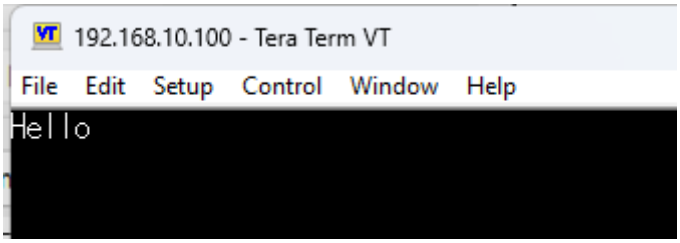


Figure 7.13 Connect the Host server

Enter text in the window and push [Enter] key.

The text you entered will be received and displayed.



8. Appendix

8.1 Appendix A : A point of caution when using SSC Tool

※ When opening SSC Tool

1. Please open the SSC Tool as an Administrator.
   Otherwise, generating SSC code may fail.

2. When opening the SSC Tool for the first time, the following window may be displayed.
   Please select [No] to not check for updates.

Figure 8.1 The update window

※ Regarding SSC Tool settings

3. Please go to [Tool] > [Options] to confirm SSC Tool settings.

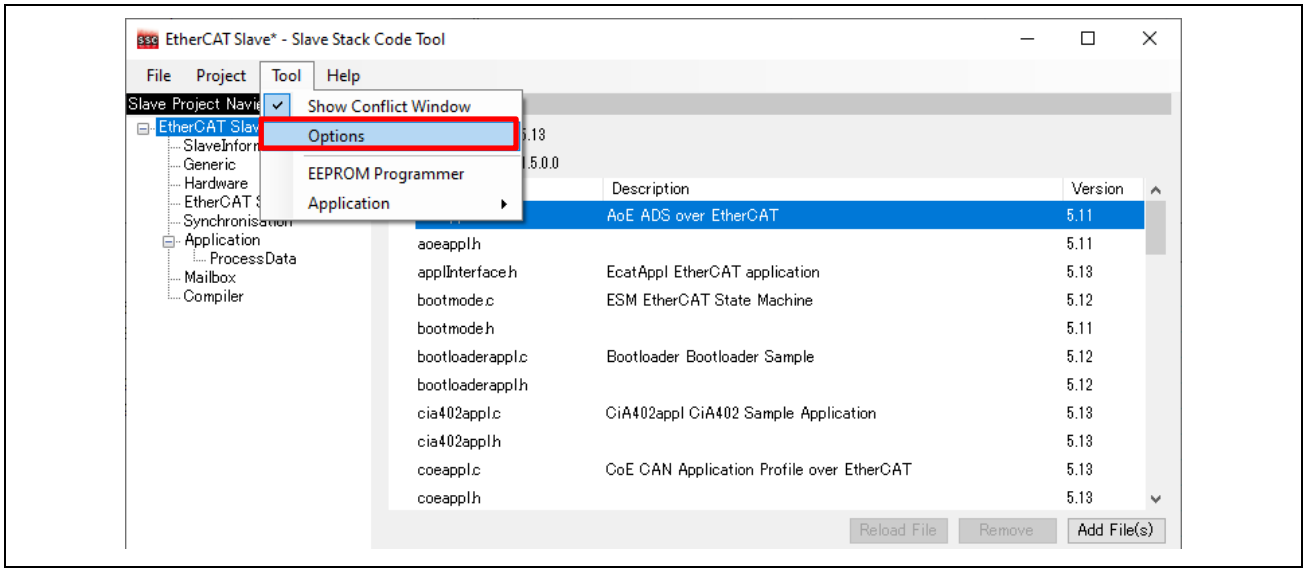


Figure 8.2 SSC tool main window

4. Under the [Generic] tab, uncheck [Open last project] and [Check for updates].

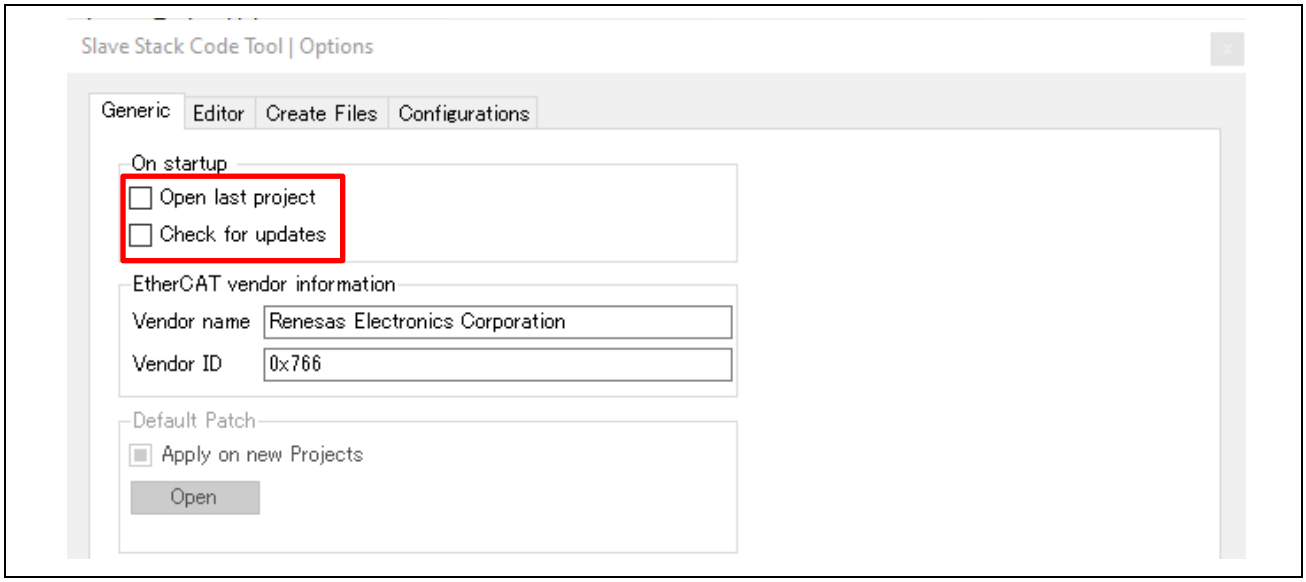


Figure 8.3 Option settings (1)

5. Under the [Create Files] tab, uncheck [Create device description (ESI)].

Figure 8.4 Option settings (2)

6. Click [OK] to apply the updated settings.
   This concludes with the SSC Tool setup for this sample program.

8.2 Appendix B : How to install patch

There are two methods as follows:

1. Via Git for Windows (64bit)
2. Via MinGW Installation Manager

8.2.1 Via Git for Windows (64bit)

This section describes how to install patch via Git for Windows.

1. Download the installer (e.g., Git-x.xx.x-64-bit.exe) from the official Git for Windows website.

   Git for Windows

2. Run the downloaded installer and follow the setup instructions. Use the default settings unless you have specific requirements.

3. After installation, add the path to patch.exe to your system's environment variables.
   For a default installation, the path is typically:

   "C:\Users\<your-username>\AppData\Local\Programs\Git\usr\bin"

   To apply the changes, restart your computer after updating the environment variables.

4. Start Command Prompt, enter "where patch".
   If the path to patch.exe is displayed, the installation was successful.

Figure 8.5 Confirm patch.exe (1)

8.2.2 Via MinGW Installation Manager

This section describes how to install patch.exe of MinGW.

1. Download “mingw-get-setup.exe” from the following URL.

   https://osdn.net/projects/mingw/downloads/68260/mingw-get-setup.exe/

2. Execute “mingw-get-setup.exe”, install “Mingw-installation-manager” according to the dialog.

3. If It’s completed and the Mingw-installation-manager window is displayed, select “Basic Setup” in the left window, right-click on “msys-base-bin” in the right window, and select “Mark for Installation”.

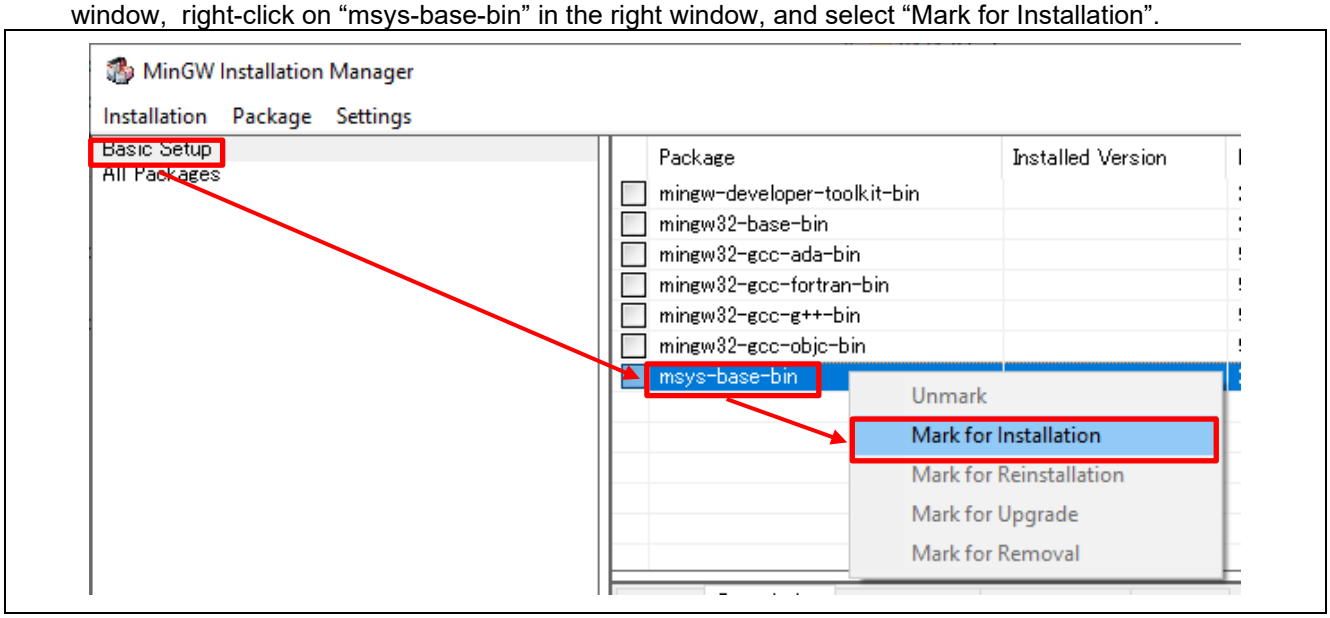


Figure 8.6 MinGW Installation Manager (1)

4. Select “All Packages” in the left window, right-click on “msys-patch-bin” in the right window, and select “Mark for Installation”.

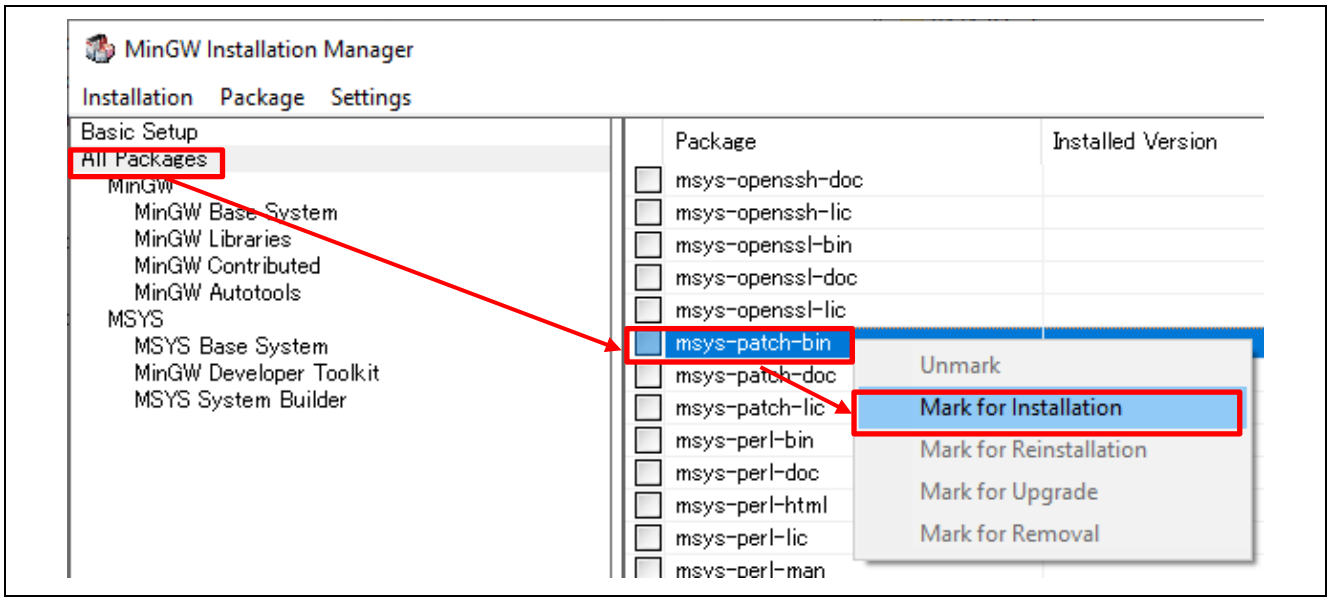


Figure 8.7 MinGW Installation Manager (2)

5. Select “Apply Changes” in “Installation” in the above menu bar.

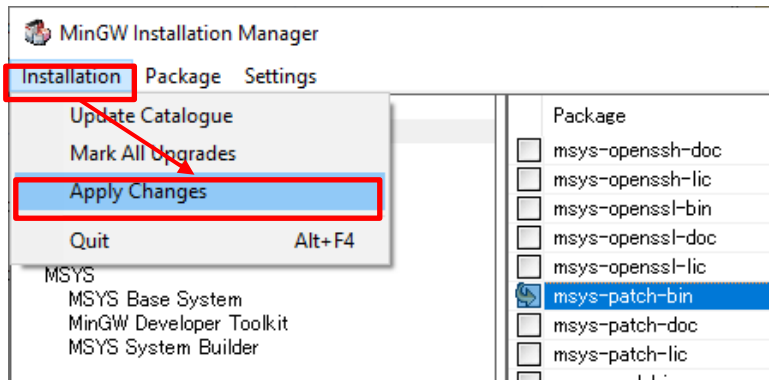


Figure 8.8 MinGW Installation Manager (3)

6. “Schedule of Pending Actions” window is displayed, click “Apply” button.

7. If “All changes were applied successfully; you may now clone this dialogue.” is displayed, Installing patch.exe is succeeded.

8. Add the path to the installed patch.exe to the system environment variables.
   For example, add the following path in the case of default path.

   “C:\MinGW\msys\1.0\bin”

   After updating the system environment variables, restart your computer to apply the changes.

9. Start Command Prompt, enter “where patch”.
   If the path to the installed patch.exe is displayed, there are no problem.

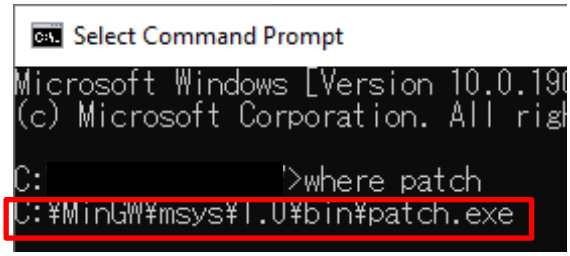


Figure 8.9 Confirm patch.exe (2)

8.3 Appendix C : How to Convert FSP Configuration from RZ/T2M to RZ/T2ME

➢ Open the FSP configuration and the [**BSP**] tab.

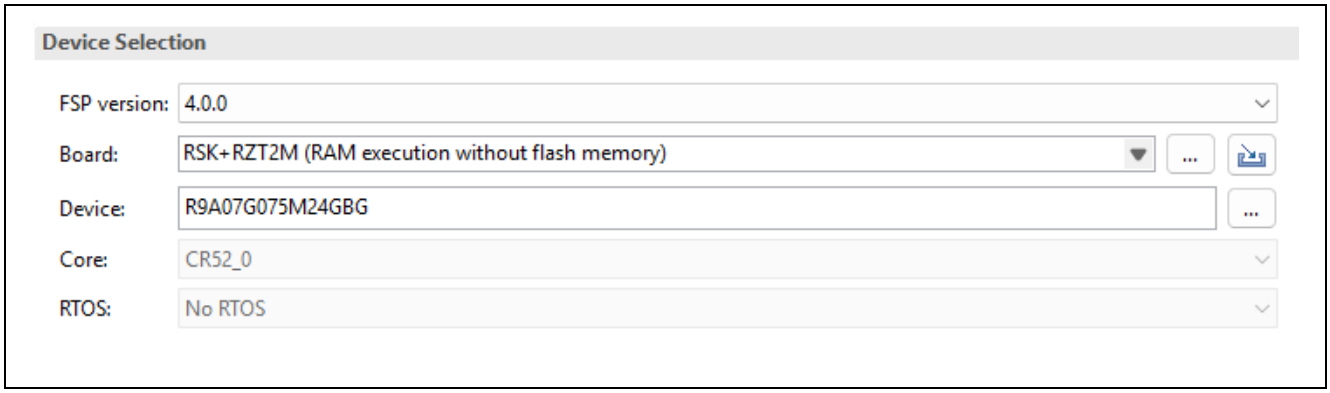


Figure 8.10 Open the FSP configuration

➢ Change [Board] from [RSK+RZT2M (RAM execution without flash memory)] to [RSK+RZT2ME (RAM execution without flash memory)].

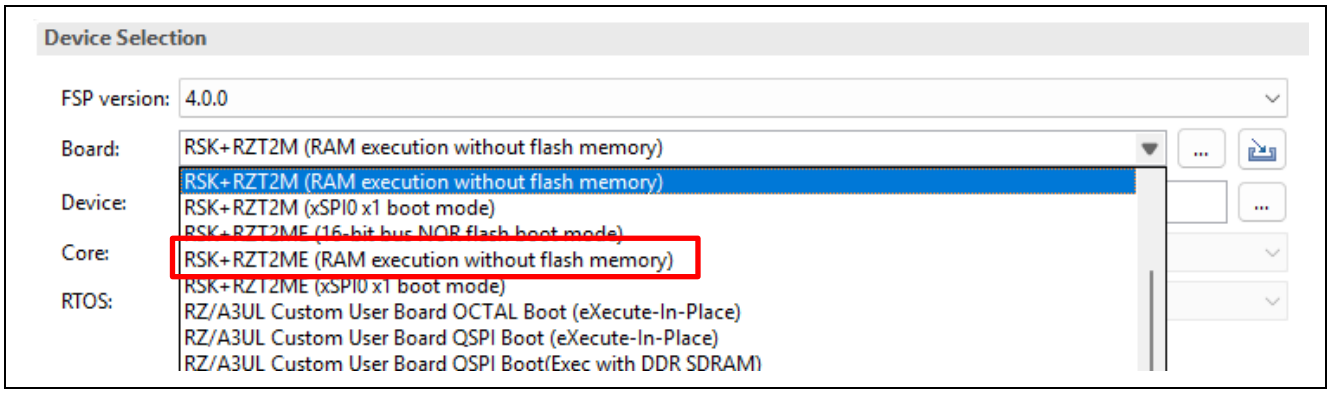


Figure 8.11 Change the board

➢ Open the [**Clocks**] tab. Change [CPU0CLK Mul x1] to [CPU0CLK Mul x4] and [CPU1CLK Mul x1] to [CPU1CLK Mul x4]

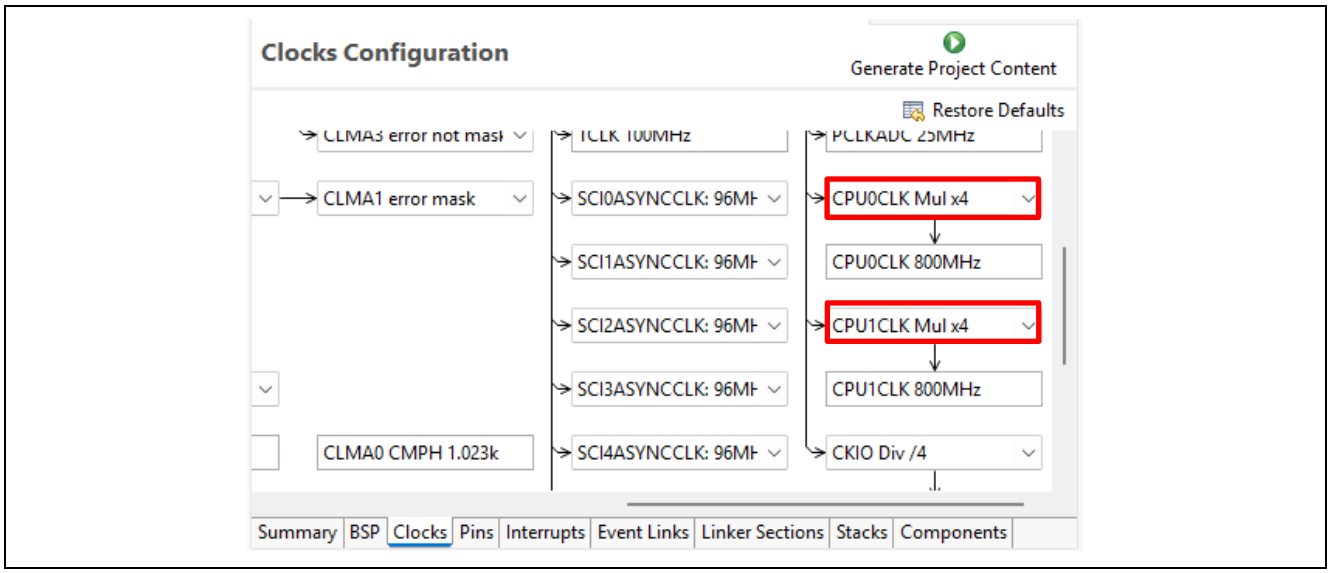


Figure 8.12 Change the clocks

➢ Click the [**Generate Project Content**] button to generate the file for **RZ/T2ME-RSK.**

8.4 Appendix D : ESC MDIO Type setting

It can change the settings from the smart configurator to change the PHY settings and the number of ports.

This appendix shows how to change the PHY management interface from GMAC to ESC.
Initially, it was set to GMAC.

1. Change PHY settings.
   Select each ether_phy stack. [Select MDIO type] → [ESC]

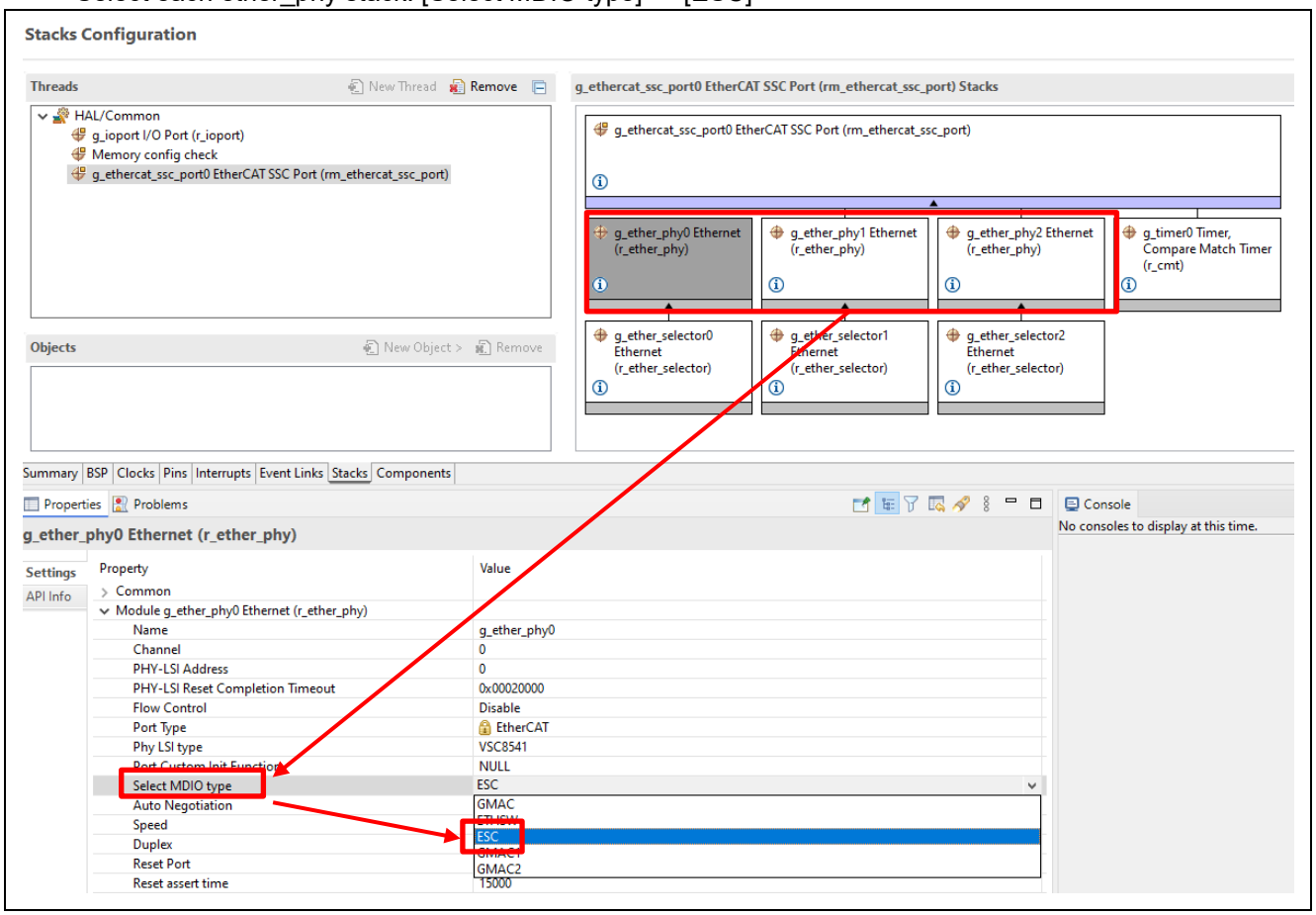


Figure 8.13 Change the MDIO type (1)

2. Change PHY management interface.
   Change ETHER_GMAC0 setting to Disabled.
   - GMAC0_MDC: None
   - GMAC0_MDIO: None

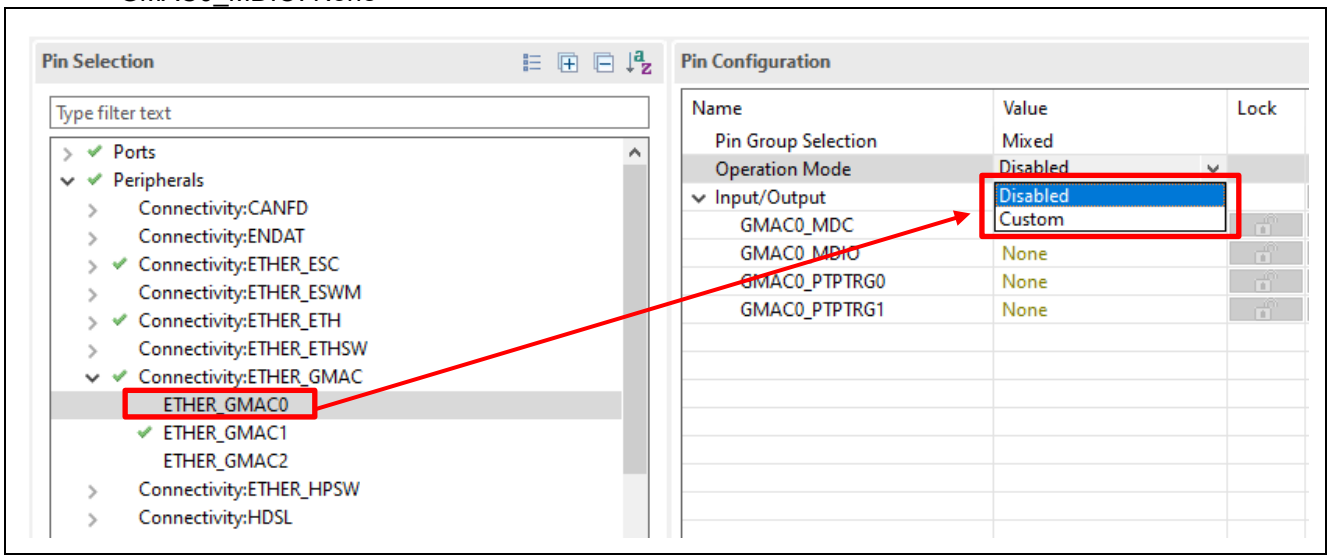


Figure 8.14 Change the MDIO type (2)

Change ETHER_ESC setting.

- In the case of RZ/T2M, RZ/T2ME, RZ/T2L, RZ/N2L RSK
  - ESC_MDC: P08_7
  - ESC_MDIO: P09_0
- In the case of RZ/T2H, RZ/N2H EVB
  - ESC_MDC: P21_4
  - ESC_MDIO: P21_5

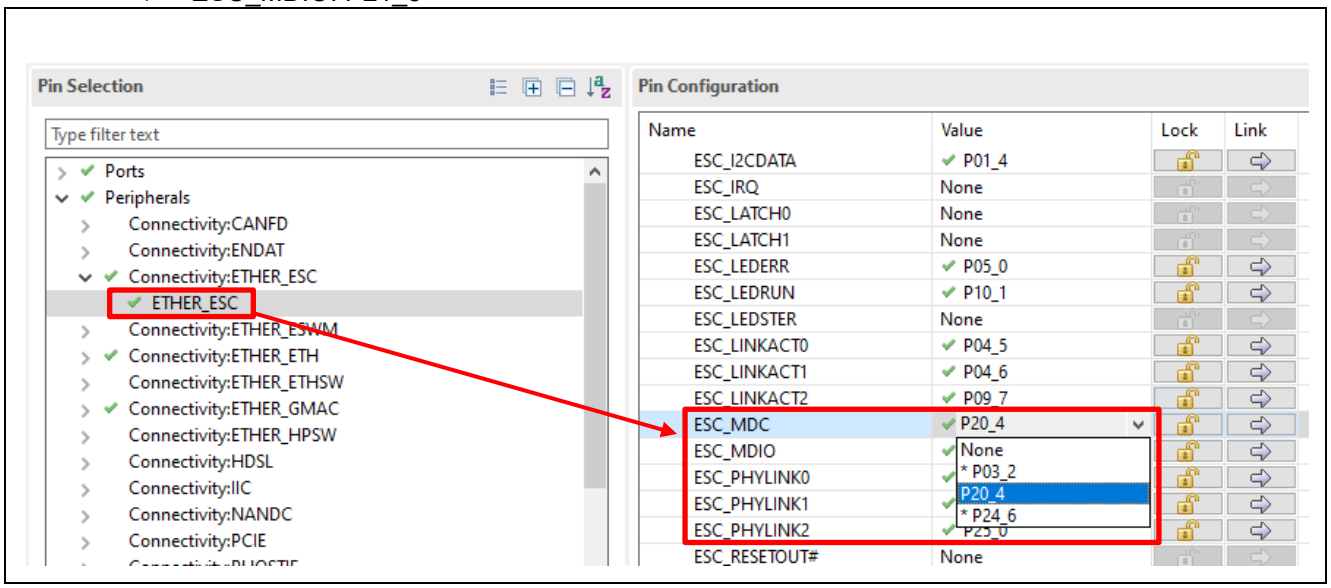


Figure 8.15 Change the MDIO type (3)

3. After completing all the settings, generate the code with "Generate Project Content".

8.5 Appendix E : EEPROM capacity setting change

Use the smart configurator to change the EEPROM capacity size and generate the code.

According to the EtherCAT specification, it is necessary to change the setting with 32 Kbit as the boundary.

1. Select SSC_port stack. [Properties] → [EEPROM Size]

2. Select "Under 32Kbits" or "Over 32Kbits" depending on the capacity of the EEPROM.

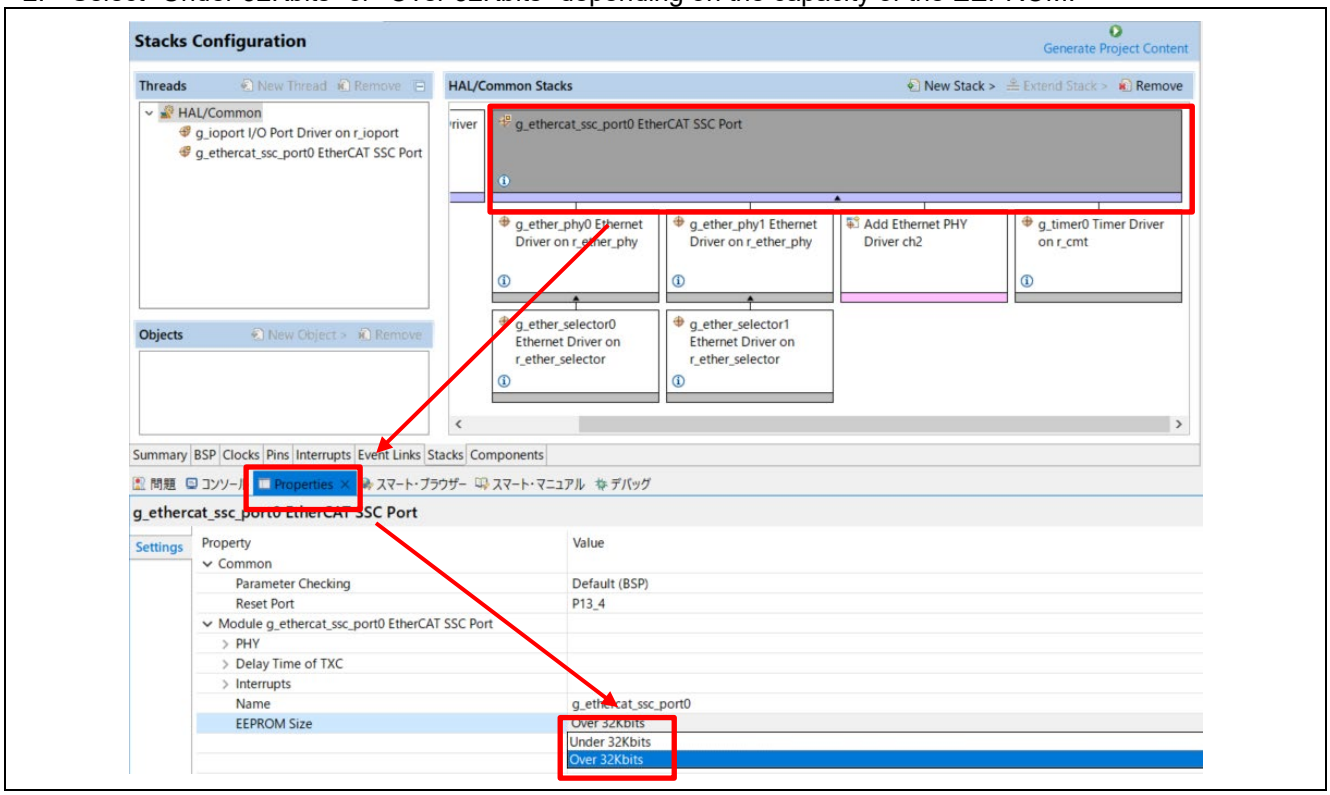


Figure 8.16 Change the EEPROM Size

3. Generate the code with "Generate Project Content".

9. Limitations

1. **When executing the EtherCAT sample program for the first time, be sure to set GMAC_MDC and GMAC_MDIO in Smart Configurator.**
   Write the EEPROM data with this configuration. It is not possible to set ESC_MDC and ESC_MDIO without writing the EEPROM data.

Revision History

Rev.	Date	Description	
		Page	Summary
4.00	Apr. 13, 2026	-	First issued
4.10	Jul. 17, 2026	-	Updated package revision number

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

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1. Precaution against Electrostatic Discharge (ESD)
   A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.
2. Processing at power-on
   The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.
3. Input of signal during power-off state
   Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.
4. Handling of unused pins
   Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.
5. Clock signals
   After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.
6. Voltage application waveform at input pin
   Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).
7. Prohibition of access to reserved addresses
   Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.
8. Differences between products
   Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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