

RX Family

Reality Al Data Acquisition Module (Data Collector / Data Shipper) - Sample Code

Introduction

This application note describes sample software for data acquisition for Reality Al. Acquired data is converted into any files using Reality Al Data Storage Tool on PC.

Target Device

RX Family MCUs

Operation confirmed MCU: RX65N

When using this application note with other Renesas MCUs, careful evaluation is recommended after making modifications to comply with the alternate MCU.

Contents

1.	Data acquisition for Reality AI	3
1.1	Overview of Data Collector	3
1.2	Overview of Data Shipper	3
1.3	Overview of Data Storage Tool	3
2.	How to implement data acquisition	4
2.1	Create New project	4
2.2	Import and setup for FIT Modules for Reality AI	8
2.3	Import sample project for Data Collector and Data Shipper	20
2.4	Setup BSP	21
2.5	Setup Sensor (HS300x)	22
2.5.1	1 Setup I2C for HS300x	23
2.6	Setup Data Collector	24
2.6.1	1 Setup DTC	26
2.7	Setup Data Shipper	27
2.7.1	1 Setup UART for Data Shipper	28
2.8	Generate source code by smart configurator.	28
2.9	Modify source code.	29
2.10	Build project	29
3.	How to get sensor data from evaluation board	30
3.1	Setup Reality AI Data Storage Tool	30
3.2	Modify debugger settings	33
3.3	Connect Evaluation Board and PC	35
3.4	Execute program.	35
3.5	Get sensor data	36
Rev	rision History	38

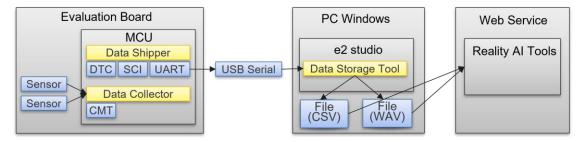
1. Data acquisition for Reality Al

Follow the steps below to collect data for Reality AI.

- Signal data such as sensors are stored in memory by Data Collector.
- The stored data is sent to the PC Data Shipper.
- Data Storage Tool running on a PC converts it into a file and uploads it to Reality AI.

Reality AI analyzes uploaded data and generates source code. Please see the e2 studio documentation for information on how Reality AI and e2 studio work together.

The following diagram is the system structure.



1.1 Overview of Data Collector

Data Collector collects data such as sensors in memory. There are two ways to collect it.

Snapshot

Data is collected using a timer provided by the Data Collector.

Data Feed

Data is collected using a timer provided by the user.

After collecting a specified number of data, it calls the Data Shipper's API.

1.2 Overview of Data Shipper

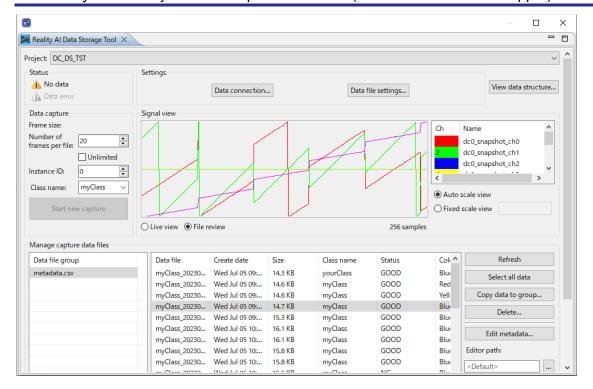
Data Shipper sends data stored in memory by Data Collector to the PC via UART.

UART settings are set in "UART Communication Driver Interface Middleware".

1.3 Overview of Data Storage Tool

Data Storage Tool convert file from sent data by Data Shipper.



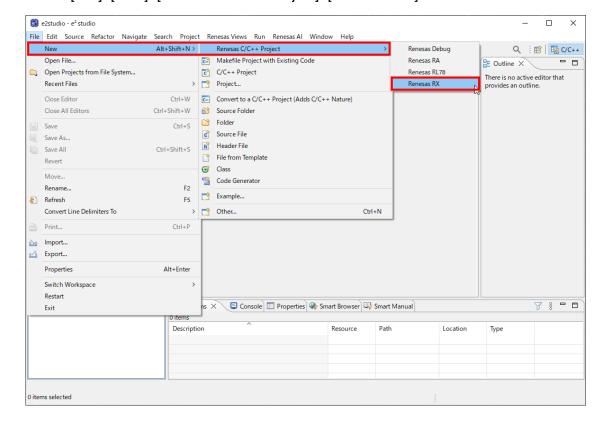


2. How to implement data acquisition

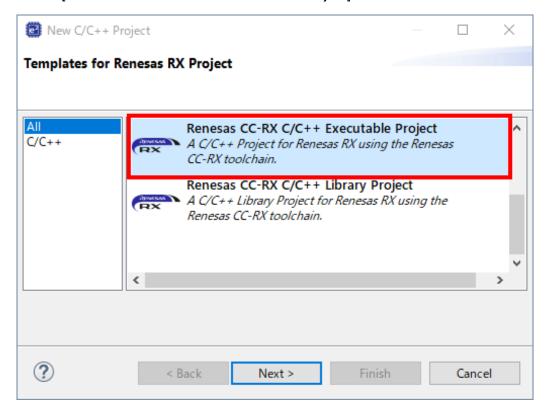
Describes how to implement a data acquisition module using Data Collector and Data Shipper into a program.

2.1 Create New project.

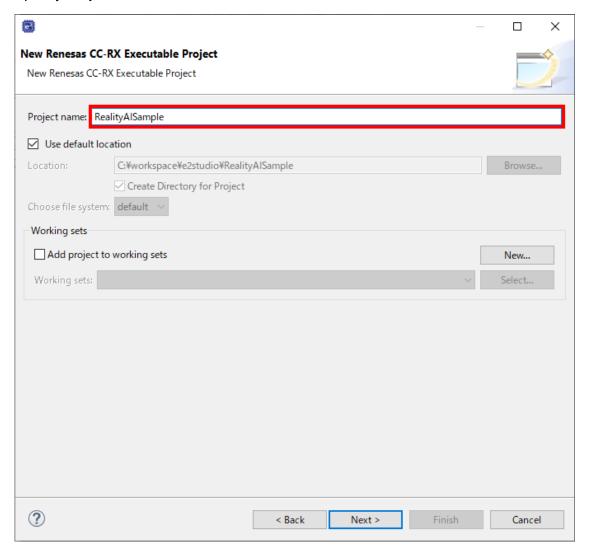
1. Select [File]>[New]>[Renesas C/C++ Project]>[Renesas RX] menu.



2. Select [Renesas CC-RX C/C++ Executable Project] item.

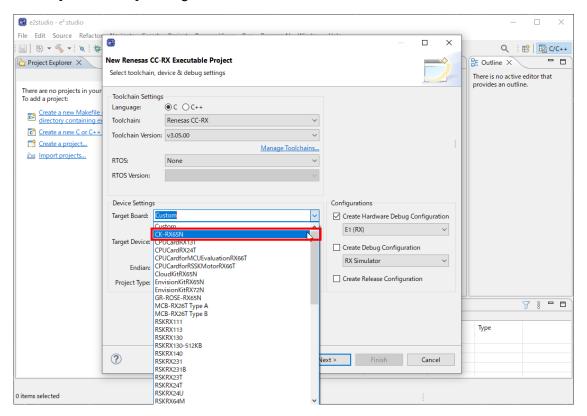


3. Specify Project Name.



Push [Next] button.

4. Select [CK-RX65N] in Target Board.

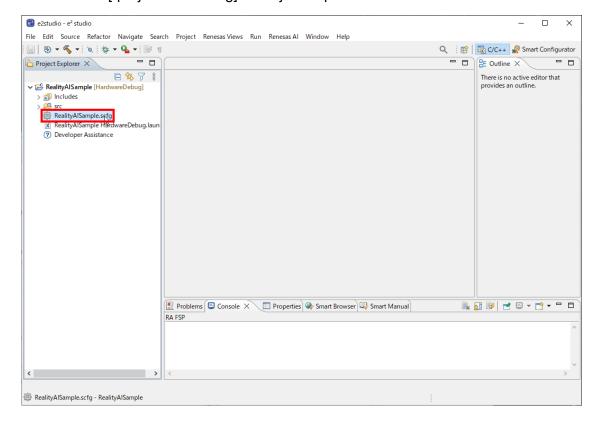


Push [Finish] button to create a new project.

2.2 Import and setup for FIT Modules for Reality AI

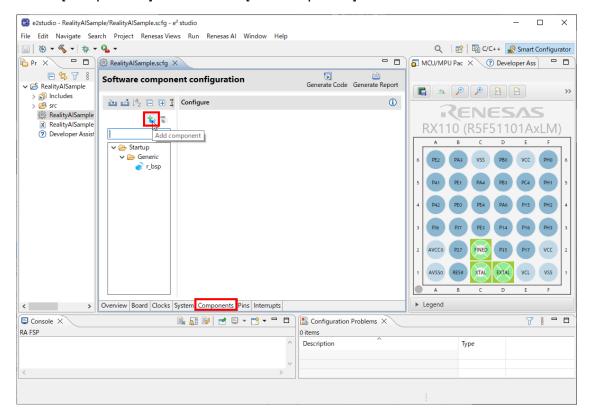
1. Open Smart Configurator.

Double Click ["projectname".scfg] in Project Explorer.



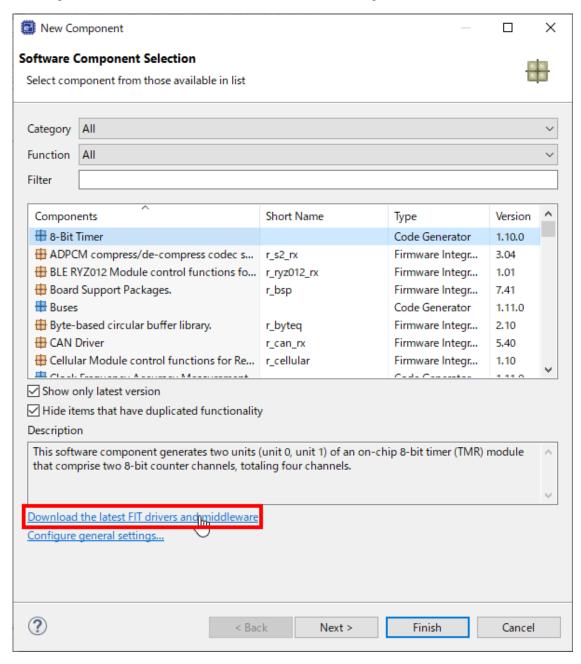
2. Add Components.

Select [Components] tab and Click [Add component] icon.

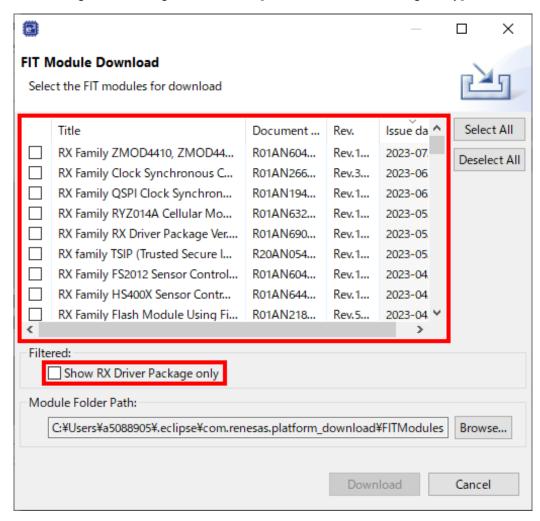


3. Download FIT modules.

Select [Download the latest FIT drivers and middleware] link.



- Select Region on dialog and uncheck [Show RX Driver Package only] .



Check the following FIT modules in list.

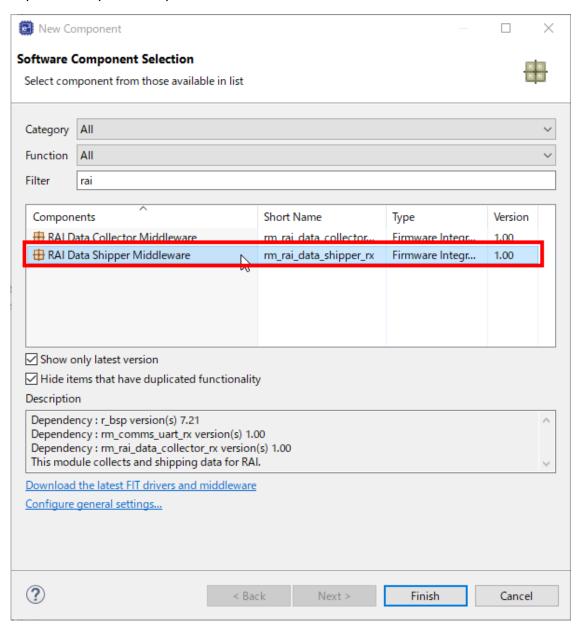
- RAI Data Collector Middleware
- RAI Data Shipper Middleware
- UART Communication Driver Interface Middleware

Push [Download] button

Confirm "End User License Agreement (Sample Code)". If you can agree this license, push [Accept] button.

Input [rai] in Filter and select [RAI Data Shipper Middleware] item.

When select [RAI Data Shipper Middleware], Smart Configurator will automatically import the required components.

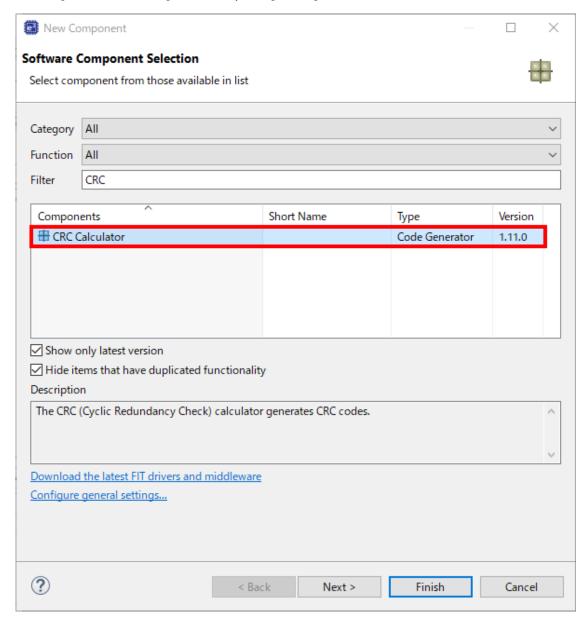


Push [Finish] button in New Component Dialog.

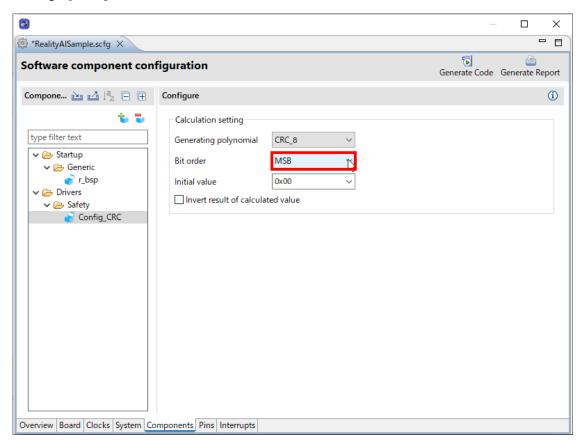
4. Import CRC Calculator and setup.

Data Shipper use CRC (Cyclic Redundancy Check) calculator feature. So, import FIT module for CRC Calculator.

- Select [Components] tab and Click [Add component] icon in Smart Configurator.
- Select [CRC Calculator] item and push [Finish] button.



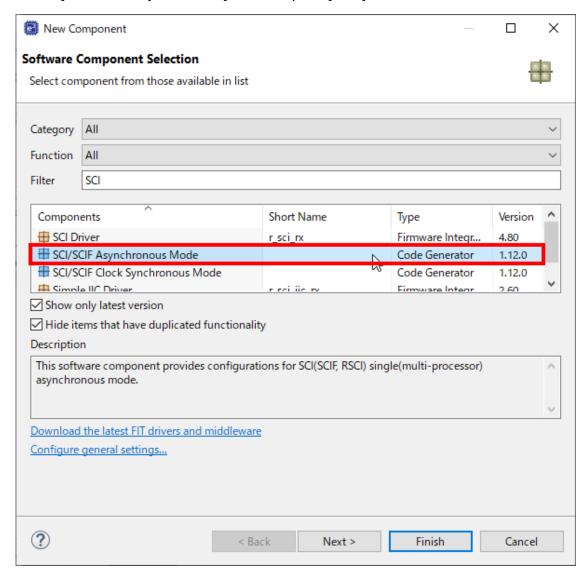
Change [MSB] of "Bit order" for CRC Calculator.



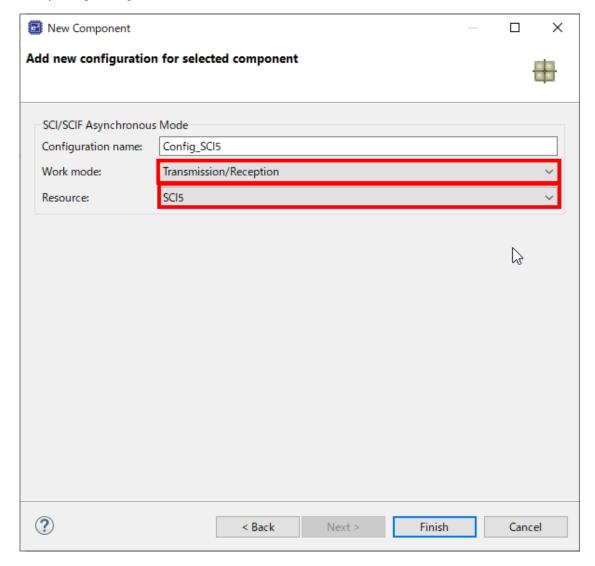
5. Import SCI/SCIF Asynchronous Mode and setup.

Data Shipper use SCI to connect to PC. So, import FIT module for SCI and change the resource for SCI for CK-RX65N.

- Select [Components] tab and Click [Add component] icon in Smart Configurator.
- Select [SCI/SCIF Asynchronous] item and push [Next] button.



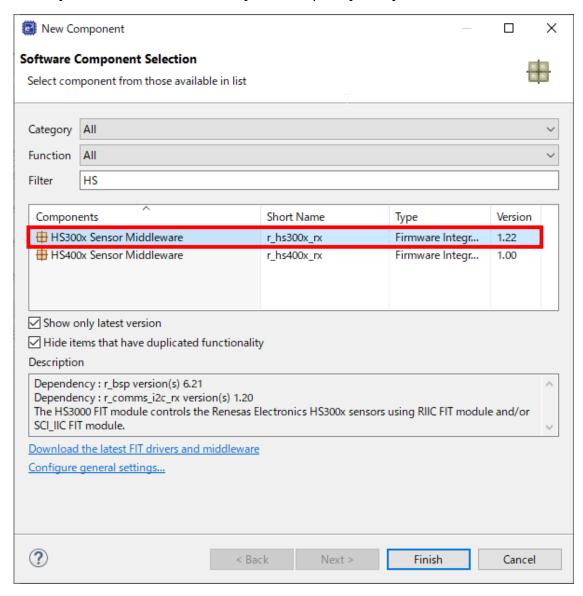
 Change [Transmission/Reception] of "Work mode" and change [SCI5] of "Resource" and push [Finish] button.



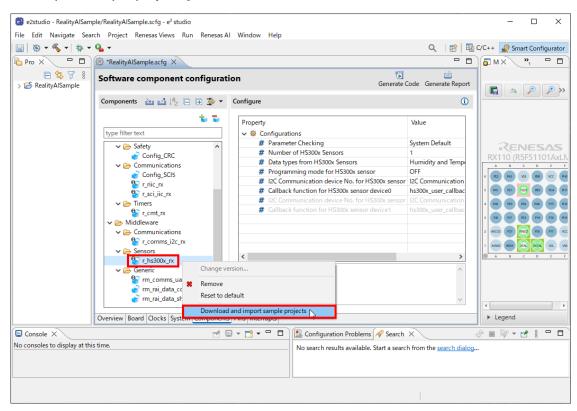
6. Import HS300x Sensor Middleware FIT module and import sample project to workspace.

CK-RX65N has many sensors. in this sample project use HS300x. So, import FIT module for HS300x and import sample project.

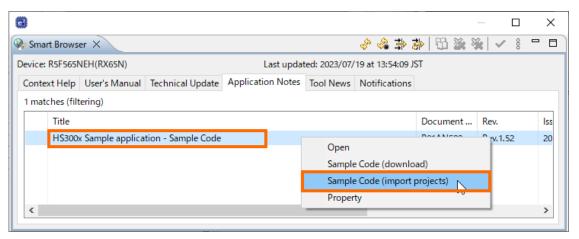
- Select [Components] tab and Click [Add component] icon in Smart Configurator.
- Select [HS300x Sensor Middleware] item and push [Finish] button.



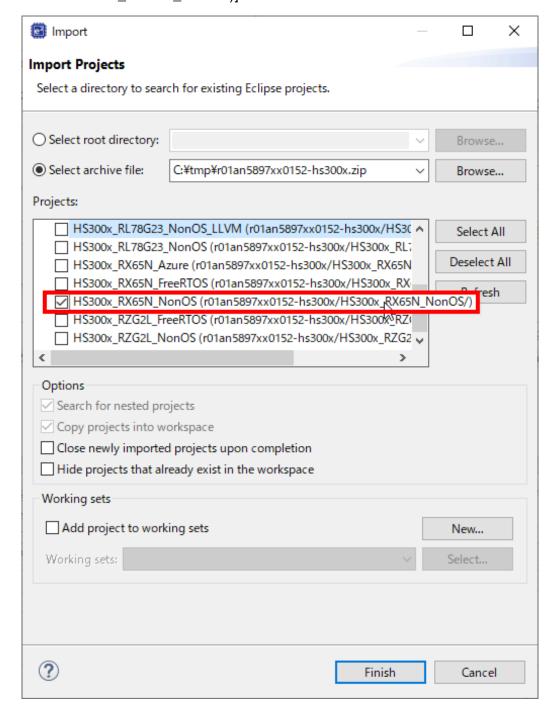
 Right-button click [r_hs300x_rx] in tree of Smart Configurator and select [Download and import sample projects] menu.



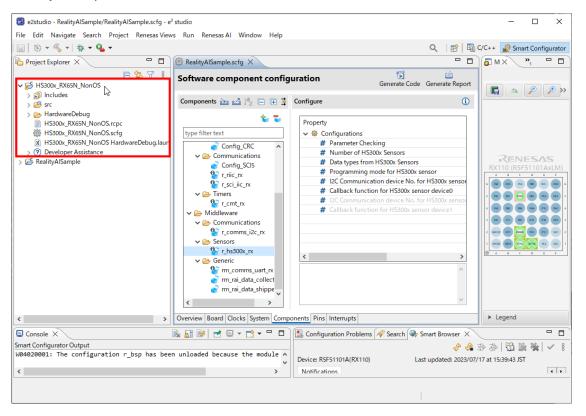
 Launch [Smart Browser] view and right button click [HS300x Sample application -Sample Code] list and select [Sample Code (import projects)]



 Select [HS300x_RX65N_NonOS(r01an5897xx0152hs300/HS300x_RX65N_NonOS)] item.



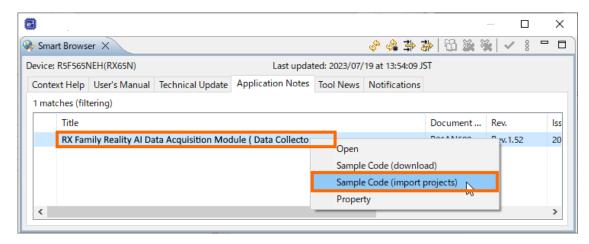
 After importing the sample project, the sample project will appear in the workspace in Project Explorer.



2.3 Import sample project for Data Collector and Data Shipper

A sample project created using the steps described in this application note is attached with this application note. Please import by the following steps. Please refer to the imported project as necessary.

- Right-button click [rm_rai_data_shipper_rx] in tree of Smart Configurator and select [Download and import sample projects] menu.
- Launch [Smart Browser] view and right button click [RX Family Reality AI Data Acquisition Module (Data Collector / Data Shipper) - Sample Code] list and select [Sample Code(import projects)] menu.



- Select [RealityAl DataAcquisition RX65N NonOS] item

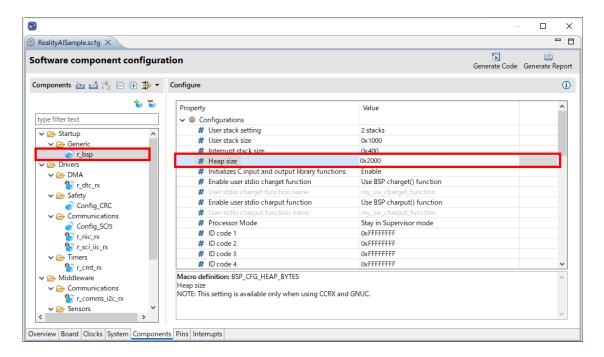


2.4 Setup BSP

Change Heap size.

Change the property of [r_bsp] as follows:

Property Value
Heap size 0x2000



2.5 Setup Sensor (HS300x)

Add source code for sending data to PC using Data Shipper into HS300x sample code. Copy and rename sample source file to src folder.

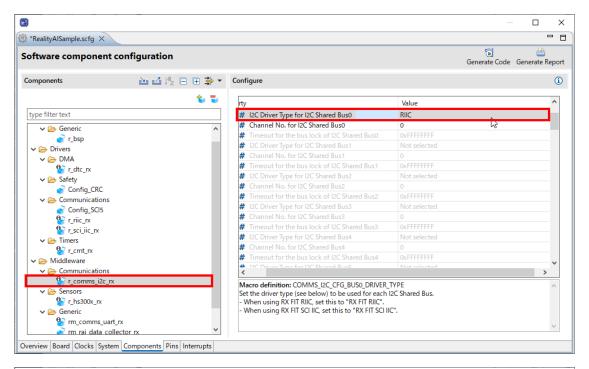
Сору	File
From	RealityAI_DataAcquisition_RX65N_NonOS/sample/RX_HS300X.c.sample
To	"Project Folder"/src/RX_HS300X.c

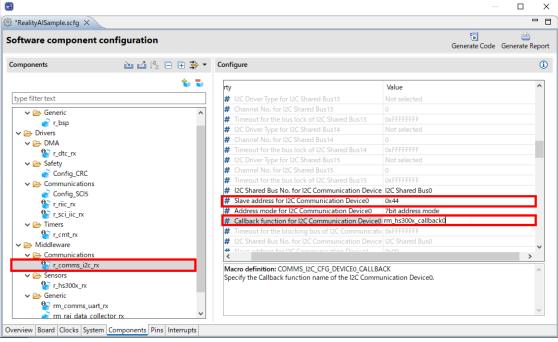


2.5.1 Setup I2C for HS300x

Change the property of [r_comms_i2c_rx] as follows:

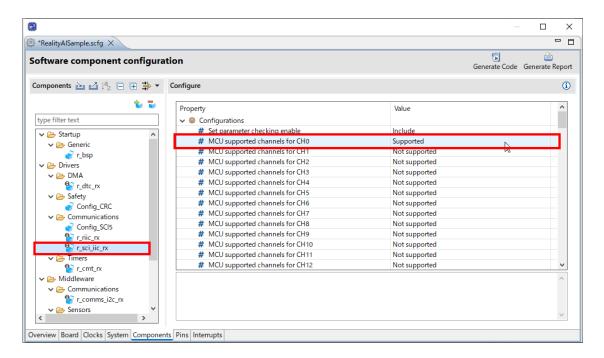
Property	Value
I2C Driver Type for I2C Shared Bus0	RIIC
Slave address for I2C Communication Device0	0x44
Callback function for I2C Communication Device0	rm_hs300x_callback0





Change the property of [r_sci_iic_rx] as follows:

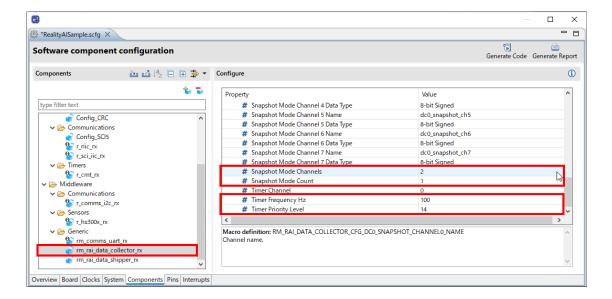
Property	Value
MCU supported channels for CH0	Supported



2.6 Setup Data Collector

Change the property of [rm_rai_data_collector_rx] as follows:

Value
Temperature
8-bit Unsigned
Humidity
8-bit Unsigned
2
1
100
14



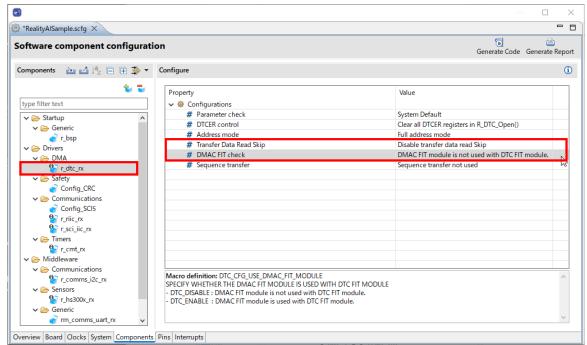
2.6.1 Setup DTC

Change the property of [r_dtc_rx] as follows:

Property Value

Transfer Data Read Skip Disable transfer data read Skip

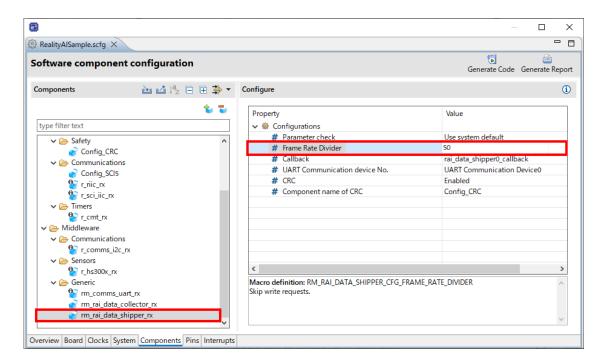
DMAC FIT check DMAC FIT module is not used with DTC FIT module



2.7 Setup Data Shipper

Change the property of [rm_rai_data_shipper_rx] as follows:

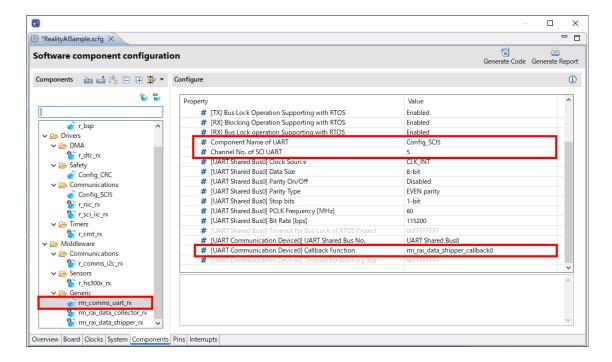
Property Value Frame Rate Divider 50



2.7.1 Setup UART for Data Shipper

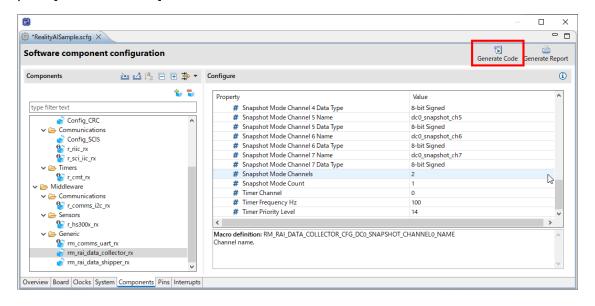
Change the property of [rm_comms_uart_rx] as follows:

Property	Value
Component name of UART	Config_SCI5
Channel of SCI UART	5
Callback function for UART Communication Device0	rm rai data shipper callback0



2.8 Generate source code by smart configurator.

• push [Generate Code] button.



2.9 Modify source code.

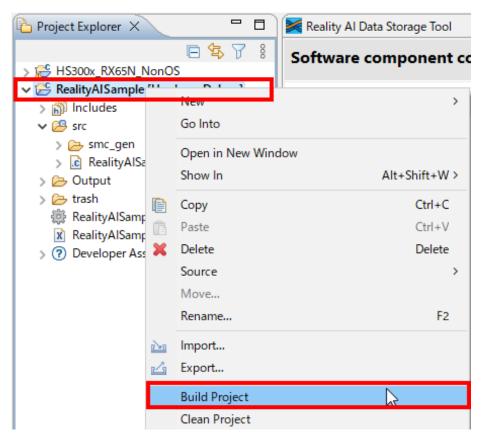
Add process of main function and add callback function to SCI.

Replace and rename sample source file to src folder.

Replace	File
From	RealityAI_DataAcquisition_RX65N_NonOS/sample/RealityAISample.c.sample
To	"Project Folder"/src/RealityAlSample.c
From	RealityAI_DataAcquisition_RX65N_NonOS /sample/Config_SCI5_user.c.sample
To	"Project Folder"/src/smc_gen/Config_SCI5/Config_SCI5_user.c

2.10 Build project.

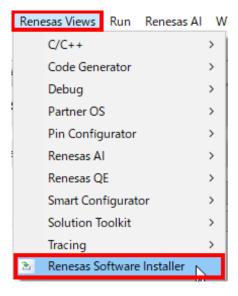
• Right-button click "Project Name" in Project Explorer and select [Build Project] menu.



3. How to get sensor data from evaluation board

3.1 Setup Reality Al Data Storage Tool

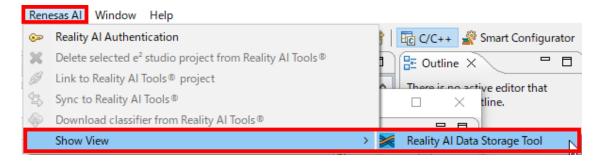
- Install Reality Al Data Storage Tool.
 - Select [Renesas View]>[Renesas Software Installer] in e2 studio.



- Select [Renesas Al] and push [Next] button.
- Check [Reality Al Data Storage Tool] and push [Finish] button.

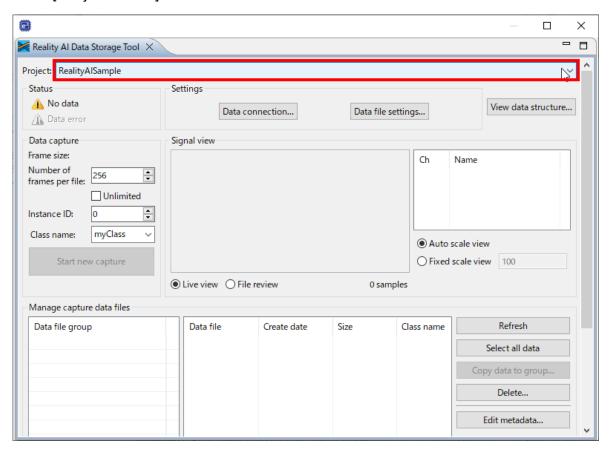
2. Launch Reality Al Data Storage Tool

Select [Renesas Al]>[Show View]>[Reality Al Data Storage Tool] menu.

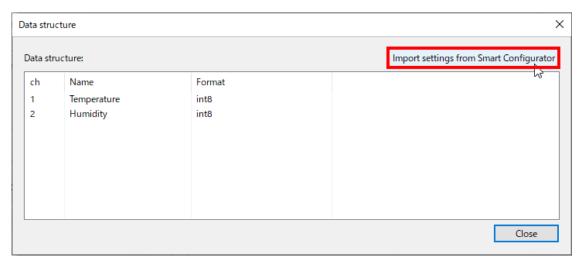


3. Select Project

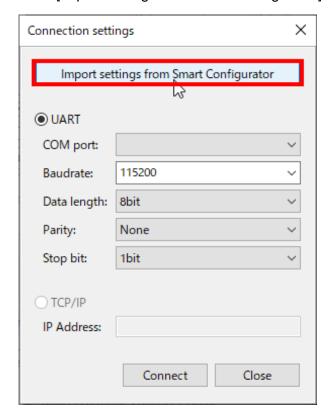
Select ["Project Name"] combo box.



- 4. Get data structure information from Smart Configurator
 - Push [View data structure] button in Reality Al Data Storage Tool.
 - Push [Import settings from Smart Configurator] button.

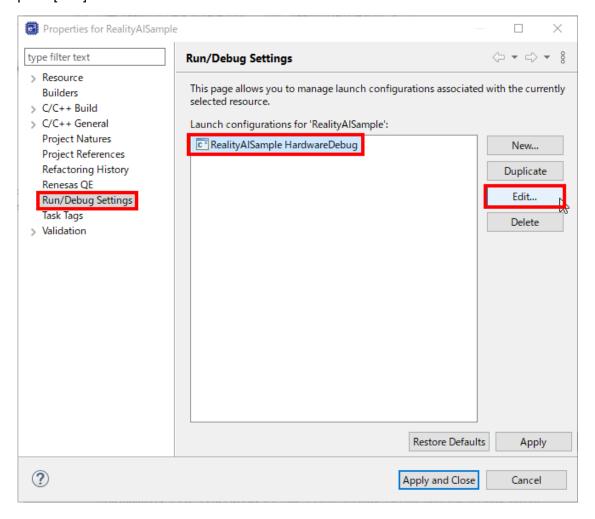


- 4. Get connection settings from Smart Configurator
- Push [Data connection] button in Reality Al Data Storage Tool.
- Push [Import settings from Smart Configurator] button.

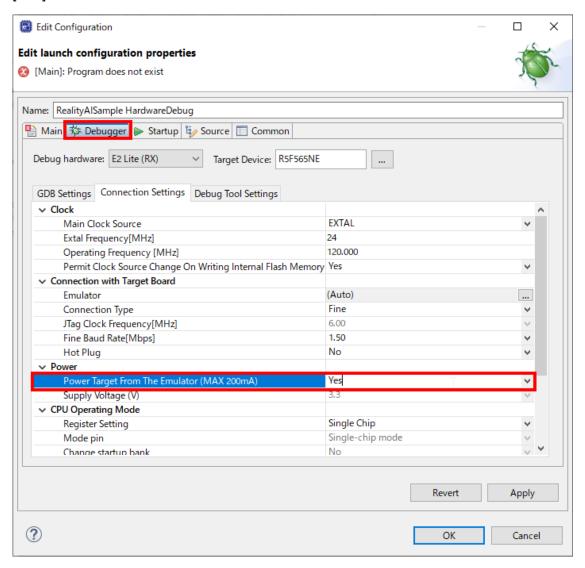


3.2 Modify debugger settings.

- Right-button click "Project Name" in Project Explorer and select [Properties] menu.
- Select [Run/Debug Settings] tree and select [RealityAlSample HardwareDebug] item and push [Edit] button.



• Select [Debugger] tab and Change "Power Target From The Emulator (MAX 200mA)" to [Yes].



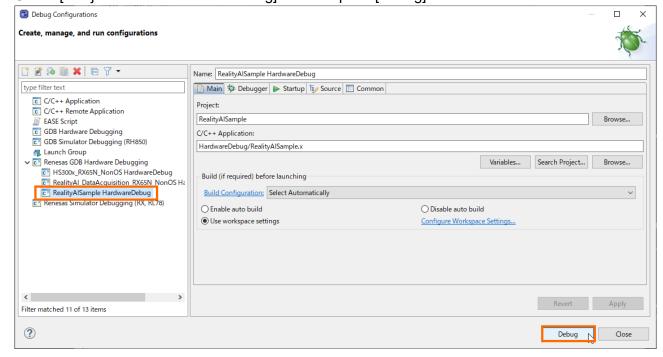
3.3 Connect Evaluation Board and PC

- Connect Evaluation Board and PC via USB.
- For Connection details, please refer CK-RX65N manual. The Manual is available on Renesas Web.



3.4 Execute program.

- Right-button click "Project Name" in Project Explorer.
- Select [Debug As]>[Debug Configuration] menu.
- Select ["Project Name" HardwareDebug] tree and push [Debug] button.



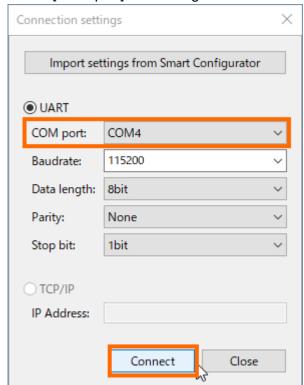
RENESAS

Push [Resume] icon on toolbar.

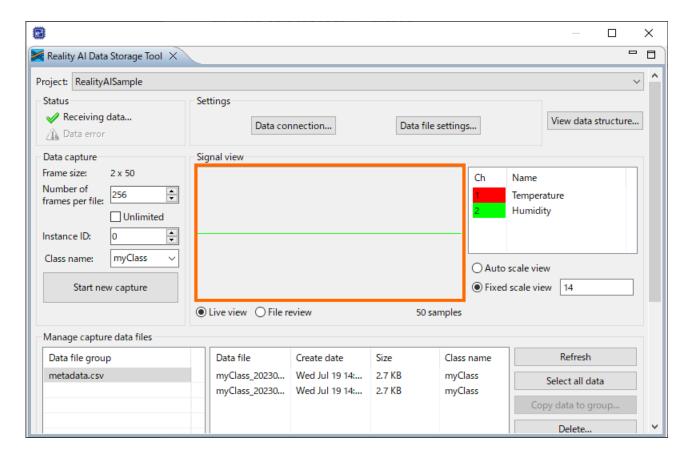


3.5 Get sensor data.

- Push [Data connection] button in Reality Al Data Storage Tool.
- Select [COM port] connecting CK-RX65N and PC and push [Connect] button.



When sensor data is acquired, a signal appears on the Reality Al Data Storage Tool view. For the operation of Reality Al Data Storage Tool, refer to the help.



Revision History

		Descript	ion
Rev.	Date	Page	Summary
1.0.0	20 Jul, 2023	-	First Release

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

- 6. Voltage application waveform at input pin
 - Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).
- 7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not quaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

Notice

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