

RL78/G23

Timer Array Unit (Pulse Interval Measurement: Width)

Introduction

This application note describes how the timer array unit (TAU) measures the interval of the pulse. This unit detects both the rising and falling edges of the pulse that are input to the timer input pin (TI00) and measures the high-level width and low-level width of the pulse. Then, measurement results are stored in the on-chip RAM.

Target Device

RL78/G23

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.

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1. Specifications

1.1 Overview of Specifications

This application note describes the measurement of the high-level width and low-level width of the input pulse by using channel 0 of the timer array unit 0 (TAU0).

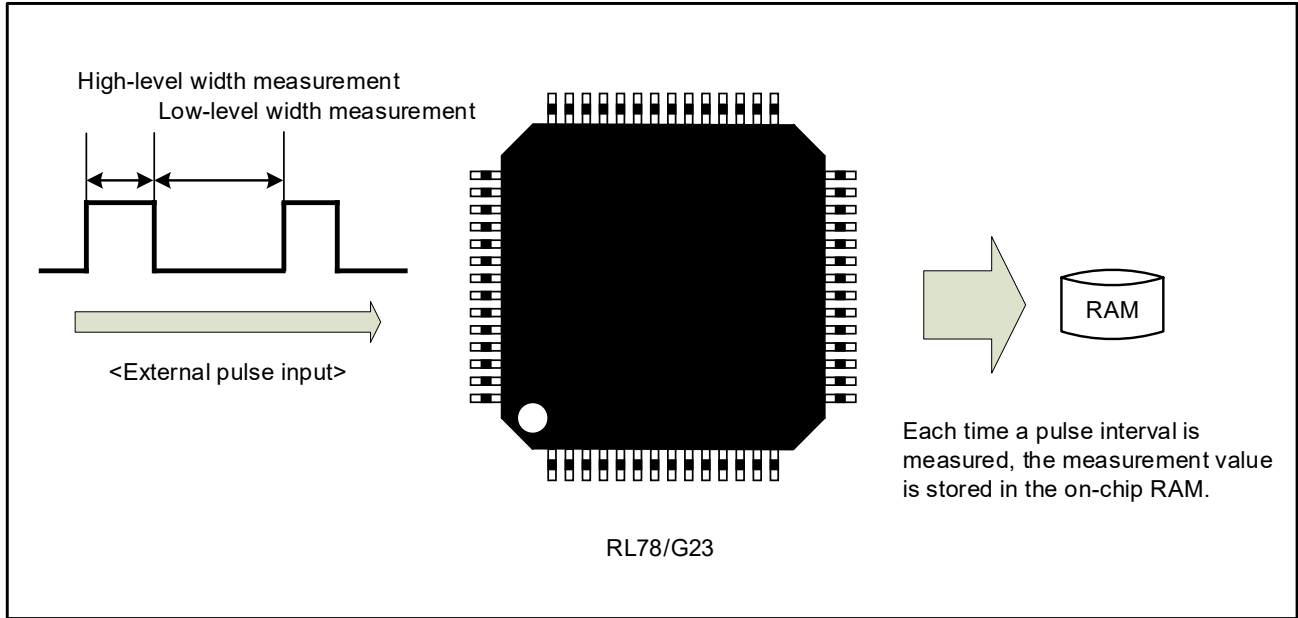
Each time a valid edge is detected on the timer input pin (TI00), the count value of the timer is captured to measure the pulse interval. The measurement result is stored in the on-chip RAM. The type of the detected edge is determined by reading the input data in the P0 register when a valid edge is detected on the timer input pin (TI00).

Table 1-1 shows the required peripheral functions and their uses. Figure 1-1 presents an overview of the pulse interval measurement.

Table 1-1 Peripheral Function and Use

Peripheral Function	Use
Timer array unit 0 (TAU0) channel 0	Measurement of the interval of the pulse input to the timer input pin (TI00)

Figure 1-1 Overview of Pulse Interval Measurement



1.2 Outline of Operation

In this sample code, each time a rising edge or a falling edge is detected on the timer input pin (TI00), the counter value of the timer is captured and a high-level width or a low-level width of the pulse input to the timer input pin (TI00) is measured.

To measure the pulse interval accurately, the capture end interrupts of channel 0 of TAU0 (INTTM00) after the first capture end interrupt are used. When capture end interrupts occur after the first capture end interrupt, the type of the detected edge (rising or falling) is determined, and the determination result is reflected in the edge determination flag. Then, according to the edge determination flag, the measured high-level width or low-level width is stored in the appropriate variable in the on-chip RAM.

Note that if a short pulse is detected and a counter value of the timer is captured before the measurement result is stored in the variable in the on-chip RAM, the measurement result is discarded.

(1) Initialize TAU0.

- Use the P00/TI00 pin for inputting capture trigger.
- Set the operation clock of TAU0 channel 0 to f_{CLK} .
- Set TAU0 channel 0 to the capture mode.
- Set the TI00 pin input valid edge to "Both edge".
- Set the capture trigger of TAU0 channel 0 to "Valid edge of the TI00 pin input".
- Use the capture end interrupt (INTTM00) from TAU0 channel 0.

(2) Set the TS00 bit of the timer channel start register 0 (TS0) to 1 to enable count operation. This clears the timer count register (TCR00) to 0000H and starts counting.

(3) Switch to a HALT mode and wait for a detection of a valid edge.

(4) When a valid edge is detected, the count value of the TCR00 register is captured to the timer data register (TDR00), at the same time, the TCR00 register is cleared to 0000H, and the capture end interrupt (INTTM00) is requested, and then a HALT mode is released. After a HALT mode is released, the capture end interrupt request flag is cleared. The first capture value of the TDR00 register is invalid and cannot be used.

(5) Set the numbers of measurement times of the high-level width and low-level width.

(6) Enable interrupt requests.

(7) Switch to a HALT mode and wait for a detection of a valid edge.

(8) When a valid edge is detected, a HALT mode is released, and in the capture end interrupt processing, the capture value of the TDR00 register is temporarily stored in the on-chip RAM.

(9) Read the data of the P0 register twice to determine the detected edge.

(10) If a valid edge is not detected during the capture end interrupt processing and the two data of the P0 register are same, the determination result (00H or 01H) of the P0 register is set to the edge determination flag. According to the value of the edge determination flag, either a high-level width or a low-level width is selected, and the capture value temporarily stored is stored in the variable in the on-chip RAM appropriately for the selected width type.

If a valid edge is detected during the capture end interrupt processing or the two data of the P0 register are not same, the capture value temporarily stored is not stored in the variable in the on-chip RAM, and the capture end interrupt request flag is cleared, and the number of the discarded edge is incremented.

(11) Repeat steps (7) to (10) until high-level widths and low-level widths are measured four times each.

(12) After the measurement of the setting number is finished, set the TT00 bit of the timer channel stop register 0 (TT0) to 1 to disable count operation, and switch to a HALT mode.

2. Operation Confirmation Conditions

The operation of the sample code provided with this application note has been tested under the following conditions.

Table 2-1 Operation Confirmation Conditions

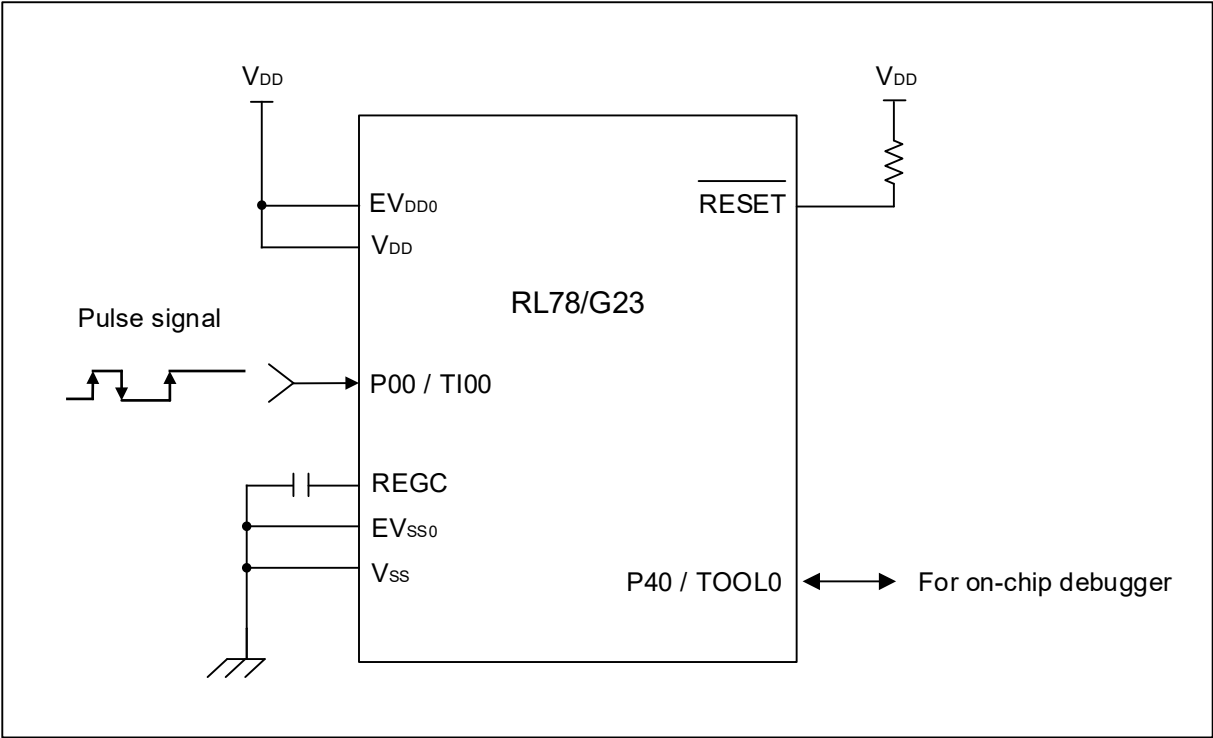
Item	Description
MCU used	RL78/G23 (R7F100GLG)
Board used	RL78/G23 Fast Prototyping Board (RTK7RLG230CLG000BJ)
Operating frequency	High-speed on-chip oscillator clock: 32 MHz CPU/peripheral hardware clock: 32 MHz
Operating voltage	3.3 V (can be operated at 1.8 V to 5.5 V) LVD0 detection voltage: Reset mode At rising edge TYP. 1.90 V (1.84 V to 1.95 V) At falling edge TYP. 1.86 V (1.80 V to 1.91 V)
Integrated development environment (CS+)	CS+ V8.06.00 from Renesas Electronics Corp.
C compiler (CS+)	CC-RL V1.10.00 from Renesas Electronics Corp.
Integrated development environment (e2studio)	e2 studio V2021-07 (21.7.0) from Renesas Electronics Corp.
C compiler (e2studio)	CC-RL V1.10.00 from Renesas Electronics Corp.
Integrated development environment (IAR)	IAR Embedded Workbench for Renesas RL78 V4.21.1 from IAR Systems Corp.
C compiler (IAR)	IAR C/C++ Compiler for Renesas RL78 V4.21.1 from IAR Systems Corp.
Smart configurator (SC)	V1.1.0 from Renesas Electronics Corp.
Board support package (BSP)	V1.11 from Renesas Electronics Corp.

3. Hardware Descriptions

3.1 Example of Hardware Configuration

Figure 3-1 shows an example of the hardware configuration used in the application note.

Figure 3-1 Hardware Configuration



- Note 1. This simplified circuit diagram was created to show an overview of connections only. When actually designing your circuit, make sure the design includes appropriate pin handling and meets electrical characteristic requirements (connect each input-only port to V_{DD} or V_{SS} through a resistor).
- Note 2. Connect any pins whose name begins with EV_{SS} to V_{SS}, and any pins whose name begins with EV_{DD} to V_{DD}, respectively.
- Note 3. V_{DD} must not be lower than the reset release voltage (V_{LVD0}) that is specified for the LVD0.

3.2 List of Pins to be Used

Table 3-1 lists the pins to be used and their functions.

Table 3-1 Pins to be Used and Their Functions

Pin name	I/O	Function
P00 / TI00	Input	Timer input pin of TAU0 channel 0

Caution In this application note, only the used pins are processed. When actually designing your circuit, make sure the design includes sufficient pin processing and meets electrical characteristic requirements.

4. Software Explanation

4.1 Setting of Option Byte

Table 4-1 shows the option byte settings. Set the values that are most suited to your system as necessary.

Table 4-1 Option Byte Settings

Address	Setting Value	Contents
000C0H / 040C0H	11101111B	Disables the watchdog timer. (Counting stopped after reset)
000C1H / 040C1H	11111110B	LVD0 detection voltage: reset mode At rising edge TYP. 1.90 V (1.84 V to 1.95 V) At falling edge TYP. 1.86 V (1.80 V to 1.91 V)
000C2H / 040C2H	11101000B	HS mode, High-speed on-chip oscillator clock (f_{IH}): 32 MHz
000C3H / 040C3H	10000101B	Enables on-chip debugging

4.2 List of Constants

Table 4-2 shows the constants that are used in this sample program.

Table 4-2 Constants for the Sample Program

Constant	Setting	Description
_0001_TAU_OVERFLOW_OCCURS	0x0001U	Overflow occurrence is detected

4.3 List of Variables

Table 4-3 lists global variables.

Table 4-3 Global Variables

Type	Variable Name	Description	Function Used
uint8_t	g_count	Number of times to measure pulse interval	main r_Config_TAU0_0_interrupt
uint8_t	g_times_high	Number of times to measure high-level width	main r_Config_TAU0_0_interrupt
uint8_t	g_times_low	Number of times to measure low-level width	main r_Config_TAU0_0_interrupt
uint8_t	e_edge_flag	Edge determination flag	r_Config_TAU0_0_interrupt
uint8_t	g_port_data[2]	Storage of input level of P00/TI00 pin	r_Config_TAU0_0_interrupt
uint32_t	g_width_high[4]	Storage of measurement value of high-level width	r_Config_TAU0_0_interrupt
uint32_t	g_width_low[4]	Storage of measurement value of low-level width	r_Config_TAU0_0_interrupt
volatile uint8_t	g_times_invalid	Number of times of discarded measurement value	r_Config_TAU0_0_interrupt
volatile uint32_t	g_tau0_ch0_width	Temporary storage of measurement value of pulse interval	r_Config_TAU0_0_interrupt

4.4 List of Functions

Table 4-4 shows a list of functions.

Table 4-4 Functions

Function name	Outline
r_Config_TAU0_0_interrupt()	TAU0 channel 0 capture end interrupt processing (INTTM00)

4.5 Specification of Functions

The function specifications of the sample code are shown below.

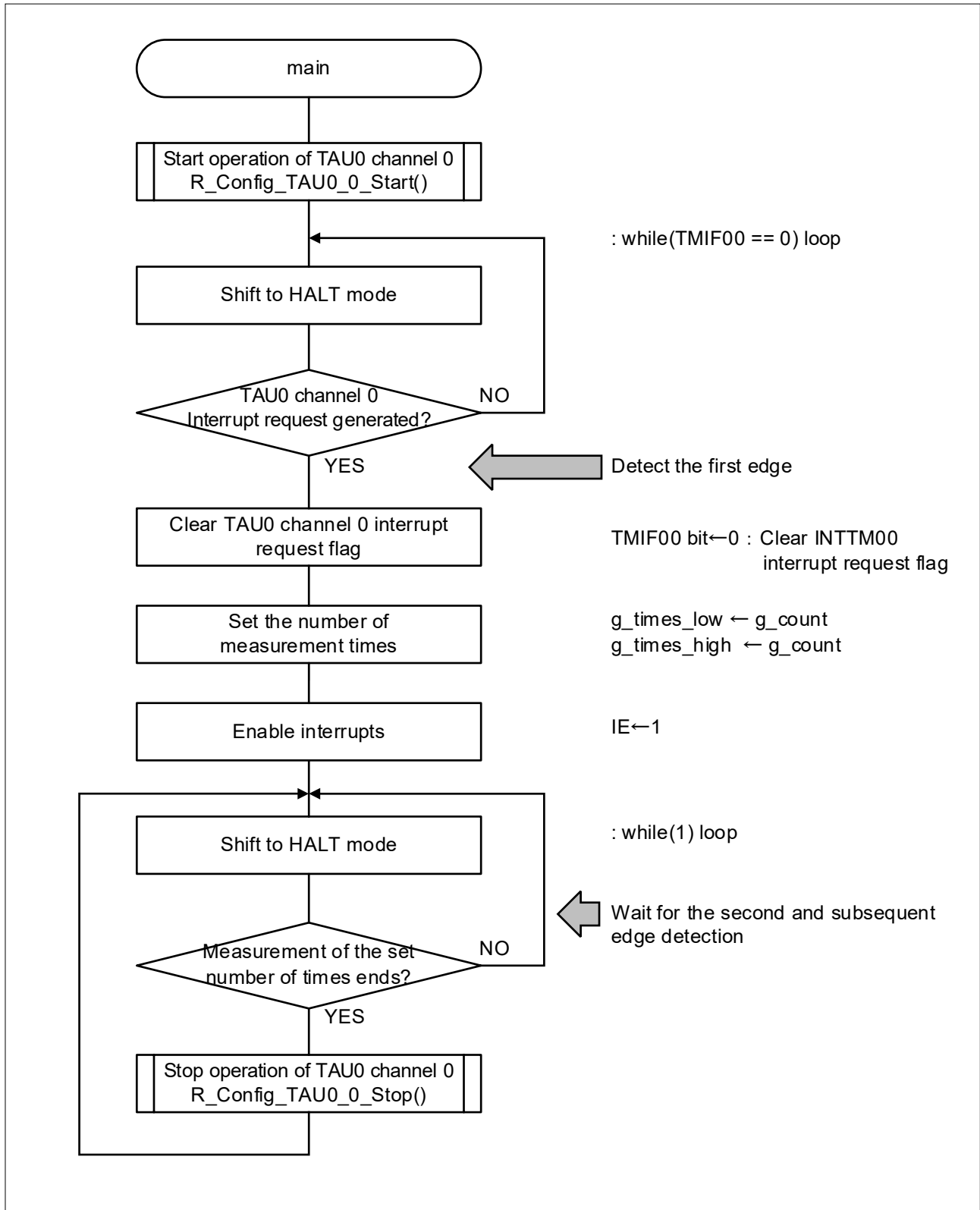
r_Config_TAU0_0_interrupt()	
Outline	TAU0 channel 0 capture end interrupt processing
Header	r_cg_macrodriver.h, r_cg_userdefine.h, Config_TAU0_0.h
Declaration	static void __near r_Config_TAU0_0_interrupt(void)
Description	Determine the type of the input pulse edge and store the measured pulse interval in the variable in the on-chip RAM according to the detected edge.
Argument	None
Return Value	None

4.6 Flowcharts

4.6.1 Main Processing

Figure 4-1 shows the flowchart of the main processing.

Figure 4-1 Main Processing



4.6.2 TAU0 Channel 0 Capture End Interrupt Processing

Figure 4-2 and Figure 4-3 show the flowchart of TAU0 channel 0 capture end interrupt processing.

Figure 4-2 TAU0 Channel 0 Capture End Interrupt Processing (1/2)

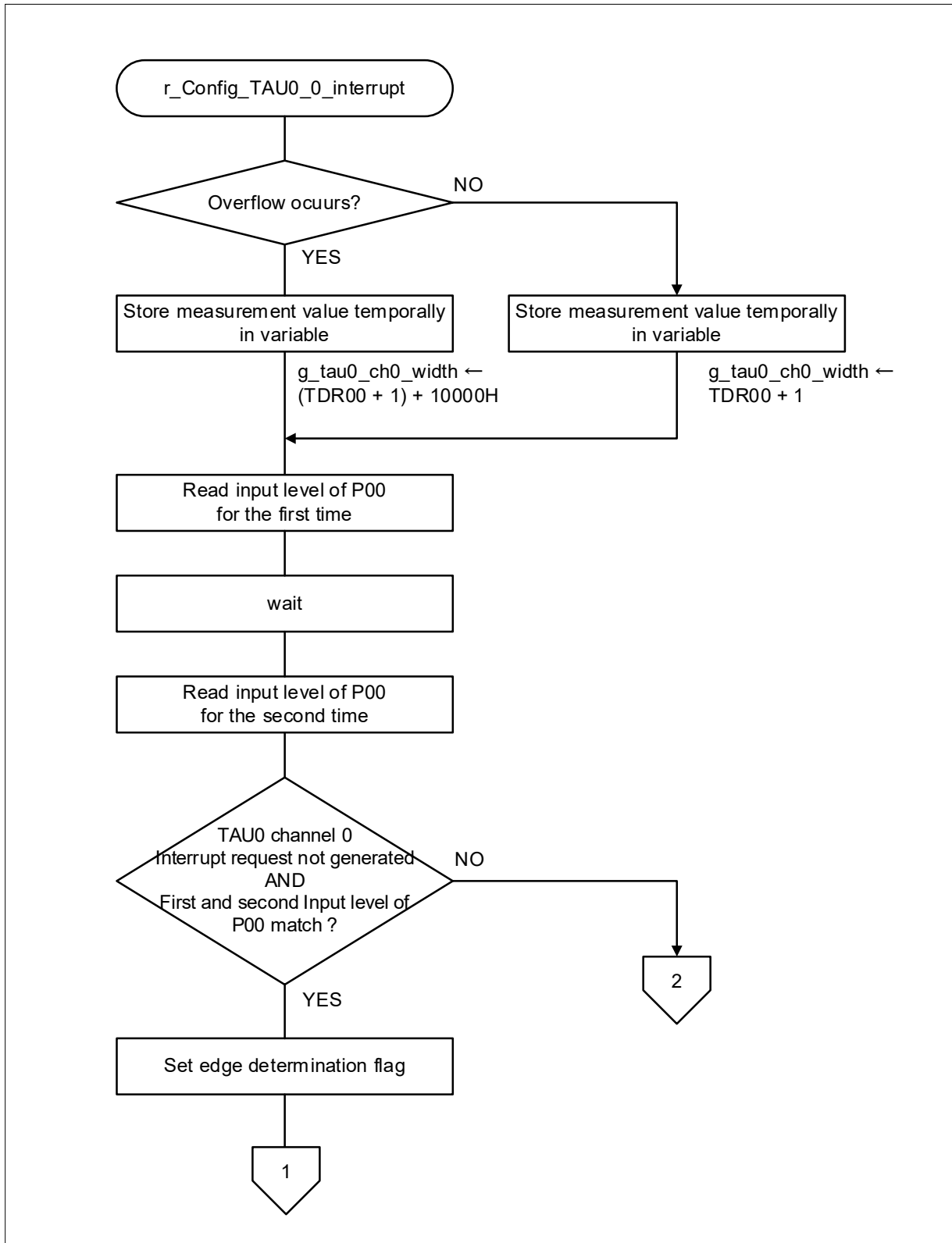
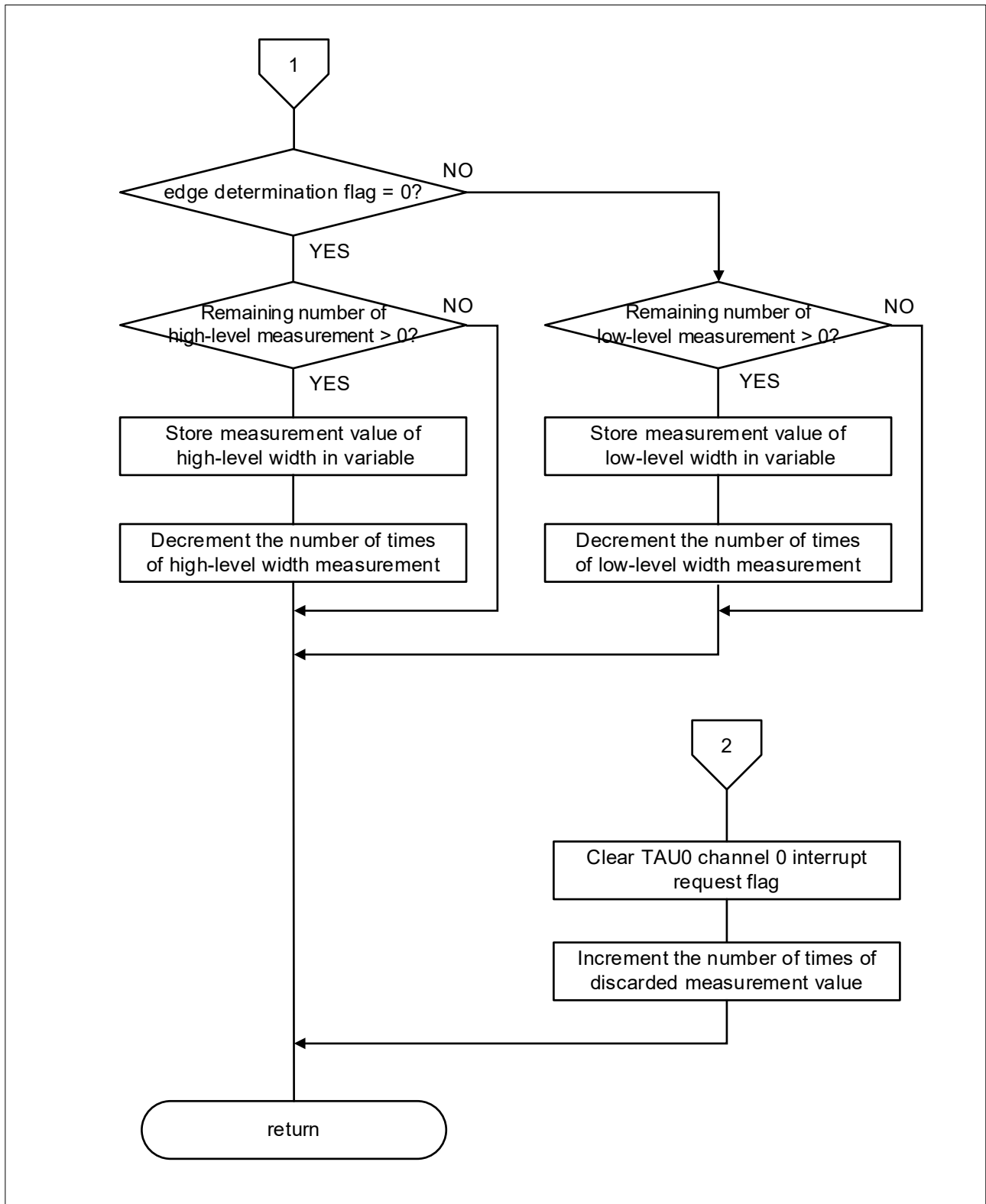


Figure 4-3 TAU0 Channel 0 Capture End Interrupt Processing (2/2)



5. Sample Code

Sample code can be downloaded from the Renesas Electronics website.

6. Reference Documents

RL78/G23 User's Manual: Hardware (R01UH0896J)

RL78 family user's manual software (R01US0015J)

The latest versions can be downloaded from the Renesas Electronics website.

Technical update

The latest versions can be downloaded from the Renesas Electronics website.

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Revision History

Rev.	Date	Description	
		Page	Summary
1.00	Jul.26,2021	-	First Edition

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1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity.

Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

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Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

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