

# RH850/U2Bx

## High-Resolution PWM (HRPWM)

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### Summary

This application note describes how to use the HRPWM of RH850/U2B6. The operation examples shown in this application note have been confirmed to work, but please be sure to check the operating environment before using the product.

### Operation confirmation device

RH850/U2B6-FCC (R7F702Z22EDBB)

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## 1. Introduction

This application note describes that how to add a delay to the PWM signal using the HRPWM of RH850/U2B6-FCC.

### 1.1 Functions

The hardware functions of RH850/U2B6 used in this application note are shown below.

- High-Resolution PWM (HRPWM)
- TSG3 (Motor Control Timer)
- PIC (Peripheral Interconnect)

## 2. HRPWM output

The HRPWM can be added some delay to a complementary PWM waves generated by GTM or TSG3. The delay can be set individually to each phase. In this application note, it shows the example of the adding a delay to PWM waves by HRPWM. The PWM waves are generated by the HT-PWM mode of TSG3.

Please set the Option Byte shown in Table 2-1 when using this function.

Table 2-1 Option Byte setting

Register name	Value	Operations
OPBT8.CKSEL_HRPWM	11b	Clock source select for HR-PWM : Set when HRPWM is used with TSG3

### 2.1 Operation overview

The HRPWM can be output the PWM wave with delay according to the setting value of it. The PWM waves are generated by TSG3.

The TSG31 and TSG32 can be used in conjunction with the HRPWM. In this application note, the TSG31 is used. The operation overview is shown in Figure 2-1.

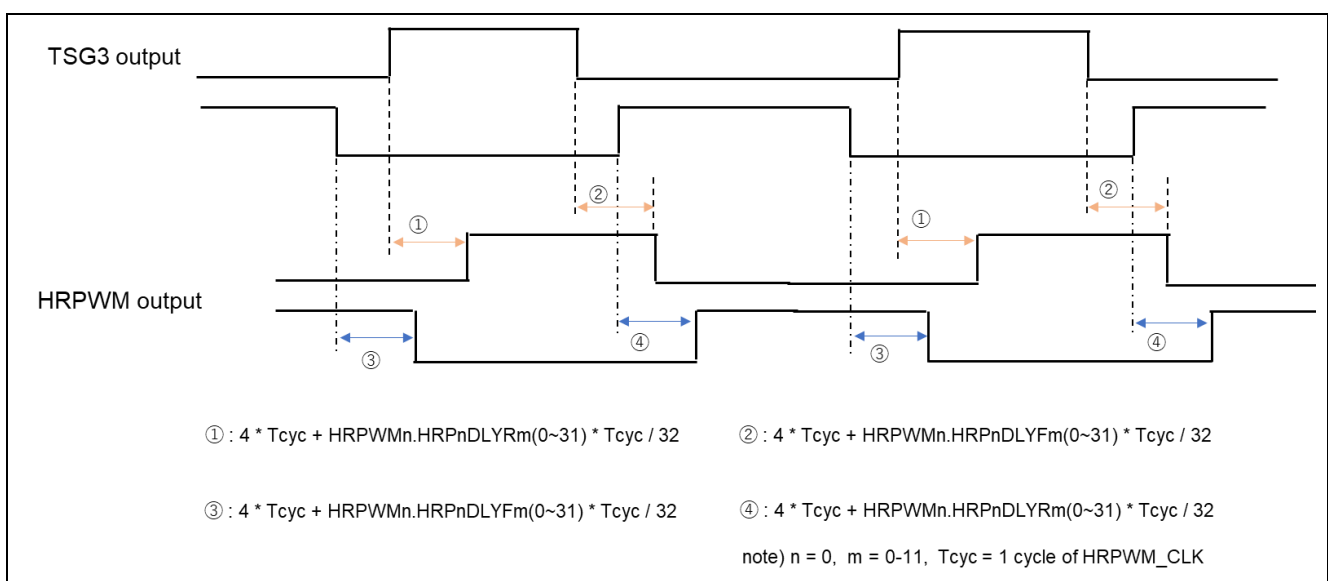


Figure 2-1 Operation overview of outputting the PWM waves with delay

2.2 Flowchart

The flowcharts are shown in Figure 2-2.

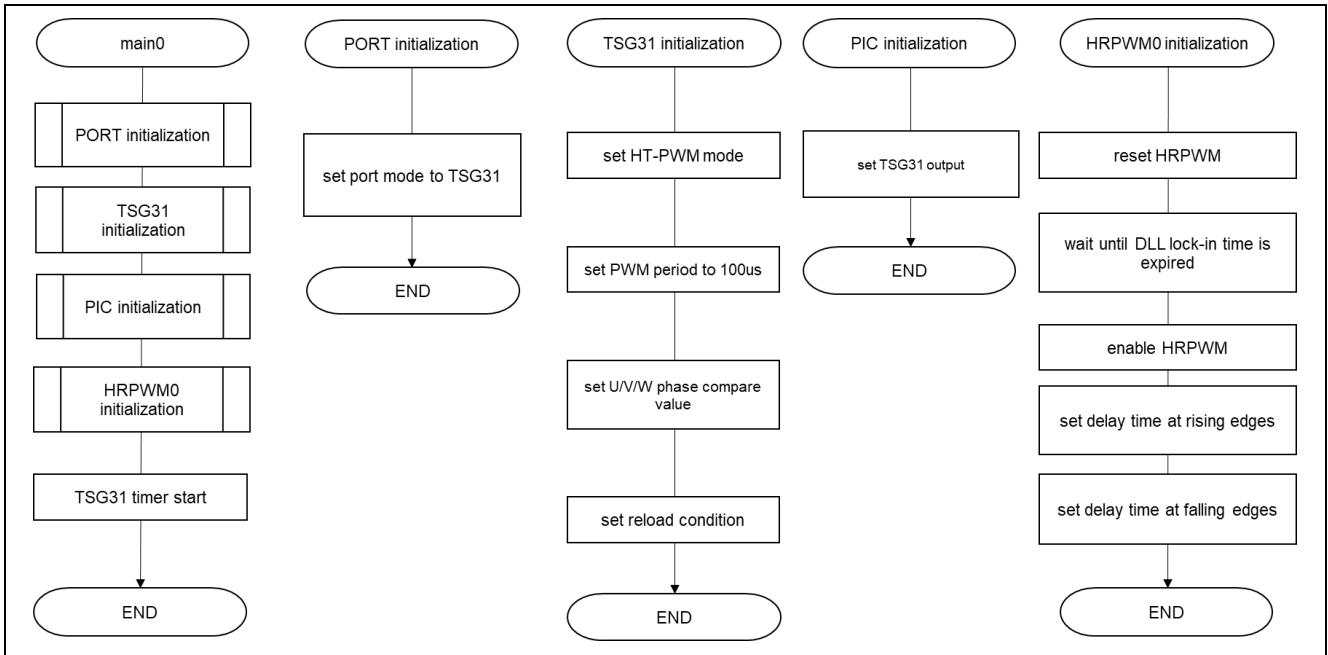


Figure 2-2 Flowchart of operation of PWM waves

## 2.3 Software operation

This chapter describes the software setting of this example.

The Register settings are shown at Table 2-2, Table 2-3, Table 2-4, Table 2-5.

Table 2-2 Register setting (HRPWM0)

Register name	Set value	Operations
HRP0DLYCTR	0x03 -> 0x01	PWM Delay Circuit Reset, and DLL Operation is enabled.
HRP0DLYEN	0x0003F	PWM Delay Circuit Channel 0 to 5 are enabled.
HRP0DLYR0-5	0x10	PWM delay value setting which will be appended to rising edges. 0x10 = 16/32 of HRPWM_CLK
HRP0DLYF0-5	0x10	PWM delay value setting which will be appended to falling edges. 0x10 = 16/32 of HRPWM_CLK

Table 2-3 Register setting (TSG31)

Register name	Set value	Operations
TSG31CTL0	0x01	Select timer mode to T-PWM mode.
TSG31CTL4	0x00000080	Enables reload operation at the peak timing of the 18-bit counter.
TSG31CMP0E	0x00001F40	Set the PWM cycle as 100 usec.
TSG31CMPUE	0x00000FA0	Set the U-phase compare value (50% duty ratio).
TSG31CMPVE	0x00000FA0	Set the V-phase compare value (50% duty ratio).
TSG31CMPWE	0x00000FA0	Set the W-phase compare value (50% duty ratio).
TSG31TRG0	0x01	The TSG31 timer is started.

Table 2-4 Register setting (PIC1)

Register name	Set value	Operations
PIC1LHSEL1	0x00	Selects low/high level output of the TSG31 output.
PIC1TSGOUTCTR1	0x00	Set output low/high level as TSG31 output is available.

Table 2-5 Register setting (PORT)

Register name	Set value	Operations
PORT0.PCR00_6	0x00000060	Set port output mode as TSG31O1_H.
PORT0.PCR02_0	0x00000069	Set port output mode as TSG31O2_H.
PORT0.PCR02_1	0x00000063	Set port output mode as TSG31O3_H.
PORT0.PCR02_2	0x00000069	Set port output mode as TSG31O4_H.
PORT0.PCR02_3	0x00000068	Set port output mode as TSG31O5_H.
PORT0.PCR02_4	0x00000067	Set port output mode as TSG31O6_H.

The software functions are shown in Table 2-6.

Table 2-6 Software functions

Function name	Overview
main0	Main application
hrpwm_init	HRPWM initialization
tsg3_init	TSG31 initialization
pic_init	PIC1 initialization
port_init	PORT initialization

## Revised record

Rev.	Date of issue	Revised contents	
		page	Point
1.00	2022.06.30	-	First edition issued

## General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

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### 1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

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### 3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

### 4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

### 5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

### 6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (Max.) and  $V_{IH}$  (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (Max.) and  $V_{IH}$  (Min.).

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