

Renesas RX Family

Using QE for Capacitive Touch for IAR EWRX

Introduction

This application note explains the steps involved in automatically adjusting and monitoring a touch sensor in a project of the IAR Embedded Workbench for Renesas RX (IAR EWRX) generated by the Smart Configurator with the use of the standalone version of QE for Capacitive Touch (standalone-version QE), which is a tool for development involving capacitive touch sensors.

Target Evaluation Kit

RSK-RX140 (RTK551406BS00000BE): CPU board (R5F51406BDFN)

Operating Environment

IDE	IAR Embedded Workbench for Renesas RX version 4.20.3 or later
Configuration tool	RX Smart Configurator V2.15.0 or later
FIT module	RX family RX Driver Package Ver.1.36 or later Firmware Integration Technology (FIT) for RX family <ul style="list-style-type: none"> • CTSU QE API (r_ctsu_qe): V2.10 (or later) • SCI Driver (r_sci_rx): V4.5 (or later) • Touch QE API (rm_touch): V2.10 (or later)
Toolchain	IAR EWRX Toolchain
QE	Standalone version of QE for Capacitive Touch V3.1.0 or later

Note: Download tools from the following URLs in advance.

- URL for downloading the IAR Embedded Workbench for Renesas RX
<https://www.iar.com/products/architectures/renesas/iar-embedded-workbench-for-renesas-rx/>
- URL for downloading QE for Capacitive Touch
<https://www.renesas.com/us/en/software-tool/qe-capacitive-touch-development-assistance-tool-capacitive-touch-sensors#download>
- URL for downloading the RX Smart Configurator
<https://www.renesas.com/jp/en/software-tool/rx-smart-configurator#download>
- URL for downloading the RX driver package
<https://www.renesas.com/jp/en/software-tool/rx-driver-package>
- RX Smart Configurator User's Guide: IAREW
<https://www.renesas.com/us/en/document/mat/rx-smart-configurator-users-guide-iarew>
- Renesas Starter Kit for RX140 User's Manual
<https://www.renesas.com/us/en/document/mat/renesas-starter-kit-rx140-users-manual>
- RX140 Group User's Manual: Hardware Rev.1.10
<https://www.renesas.com/us/en/document/mah/rx140-group-users-manual-hardware-rev110>

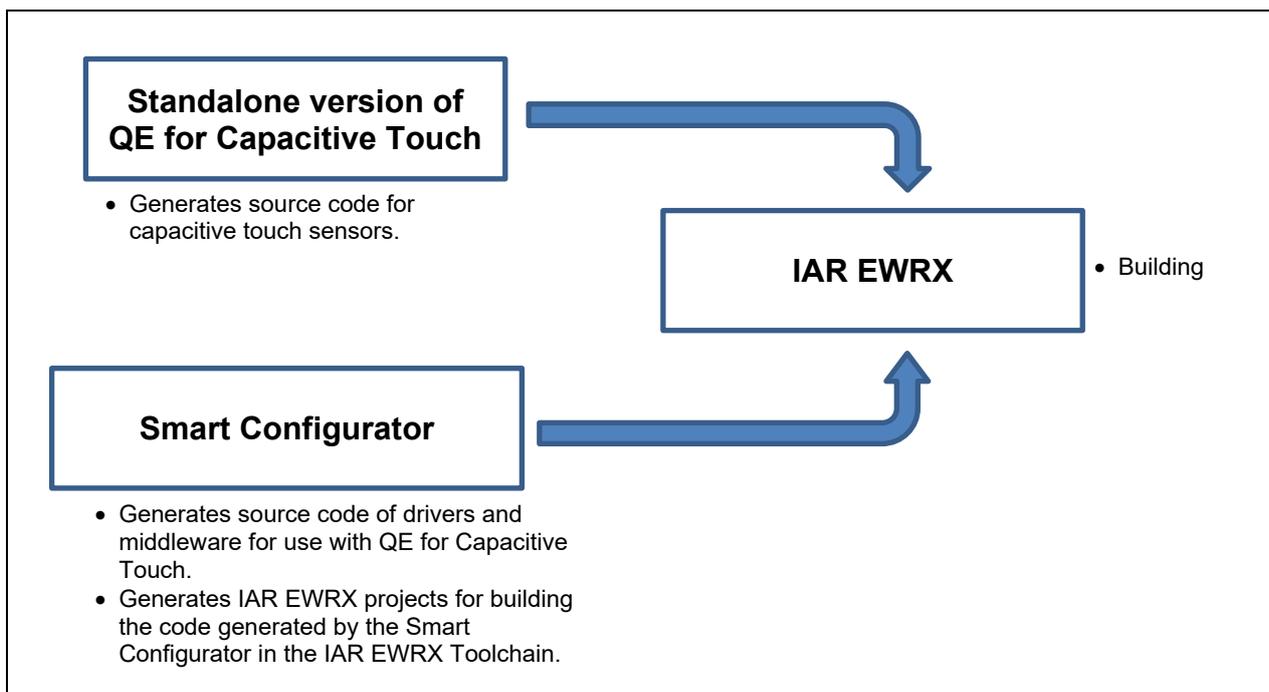


Figure 1 Configuration for Using QE for Capacitive Touch with IAR EWRX

Contents

1.	Installation	4
1.1	Installing the IAR EWRX	4
1.2	Installing the Smart Configurator.....	4
1.3	Installing the Standalone Version of QE for Capacitive Touch	4
2.	Preparing a Project.....	4
2.1	Creating a Configuration File.....	5
2.2	Setting the Smart Configurator.....	8
2.3	Generating Code	15
2.4	Setting the Project Folder and Target MCU	19
3.	Preparing the Touch Interfaces	20
3.1	Creating a Touch Interface Configuration	20
3.2	Outputting Files for Tuning Touch Sensors.....	23
3.3	Implementing Programs for Tuning.....	25
3.4	Building a Project	27
4.	Tuning Touch Sensors	31
4.1	Connecting the RSK-RX140 Board with a PC	31
4.2	Starting Tuning.....	32
4.3	Acquiring the Tuning Result	35
5.	Coding and Monitoring	37
5.1	Monitoring.....	37
5.2	Disconnecting Serial Communications.....	40
	Revision History	42

1. Installation

1.1 Installing the IAR EWRX

After starting the downloaded installer, install the IAR EWRX according to the procedure prompted by the installer.

Log in with administrator rights to proceed with installation.

1.2 Installing the Smart Configurator

After starting the downloaded installer, install the Smart Configurator according to the procedure prompted by the installer.

Log in with administrator rights to proceed with installation.

1.3 Installing the Standalone Version of QE for Capacitive Touch

The downloaded zip file has both the plugin version of QE for Capacitive Touch and the standalone version of QE for Capacitive Touch.

1. Expand the downloaded zip file.
2. Since the standalone-version QE for Capacitive Touch is stored in the QE-CapTouch folder, move that folder to a desired location. The QE-CapTouch folder must be moved to a folder that is close to the root of the drive so that the Windows path name does not exceed the limit on the number of characters (260 characters).

— Examples of folder name: C:\Renesas, C:\QeTouch

Note that the tool can be launched from "qe-captouch.exe" that is in the "QE-CapTouch\%eclipse" folder.

2. Preparing a Project

Using the Smart Configurator, create an IAR EWRX project that uses the standalone-version QE. The Smart Configurator has a simple wizard for creating projects. An IAR EWRX project can be created by specifying the location, file name, platform, toolchain, and project type of a project, making the RTOS setting, and setting the locations of FIT modules. Follow the procedure below to create a new IAR EWRX project.

Sections 2.1 to 2.3 explain the procedure of To Create Project in the workflow diagram of the standalone-version QE.

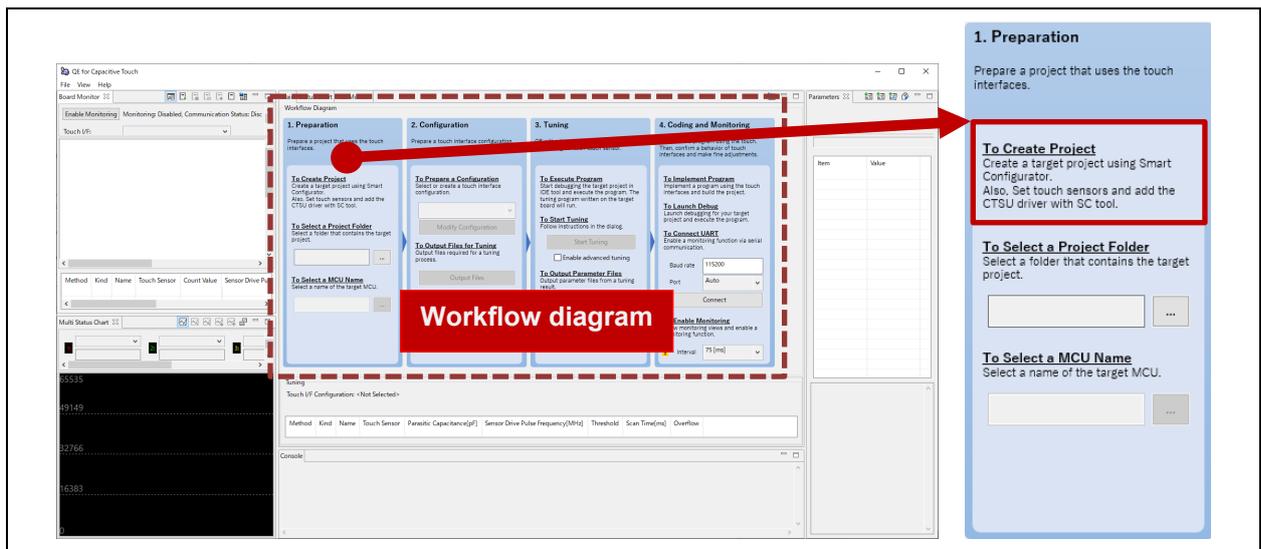


Figure 2-1 Standalone-Version QE - Workflow Diagram: To Create Project

2.1 Creating a Configuration File

1. From the Windows start menu, select [Renesas Electronics Smart Configurator] and then [Smart Configurator for RX Vx.x.x]. The main window of the Smart Configurator will be started.

Note: Vx.x.x should be replaced with the version in use.

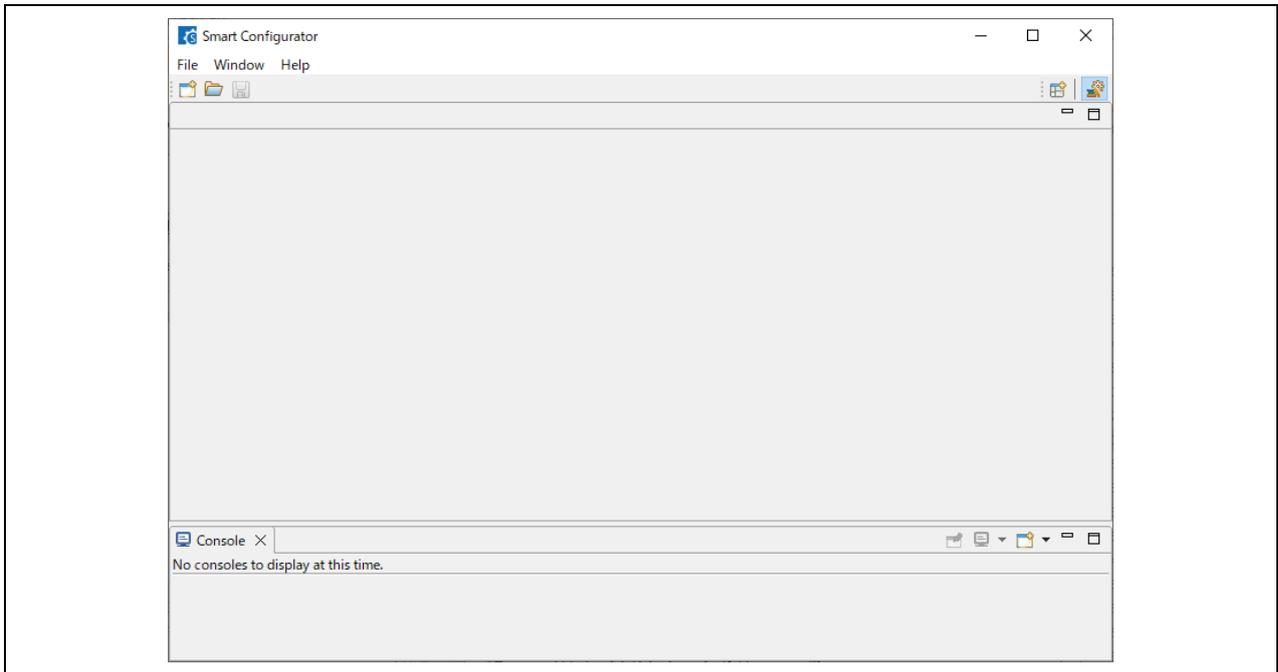


Figure 2-2 Starting the Smart Configurator

2. Select [New...] from the [File] menu or click on the  [New Configuration File] button on the main toolbar.

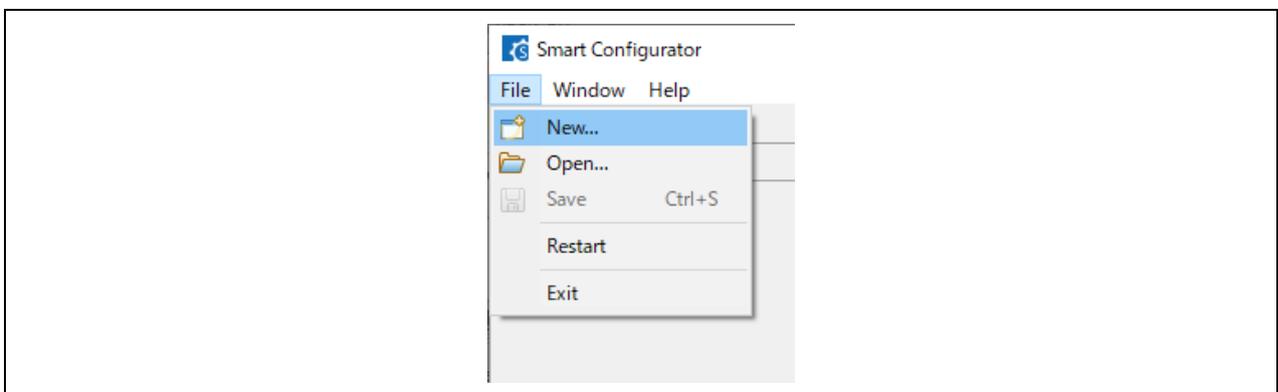


Figure 2-3 Creating a New Smart Configuration File

3. The dialog box for making Smart Configurator settings is displayed.

— Set the following items.

- (1) [Platform:] Enter "RX140" and select "RSKRX140 (R5F51406BxFN)" under "Board" that is displayed after filtering has finished.
- (2) [Toolchain:] Select "IAR EWRX Toolchain".
- (3) [File name:] Enter the name of the project to be created.
- (4) [Location:] Confirm the folder in which the project is to be created. To change the project folder, click on [Browse...] and select the folder for saving the project.

— Click on [Next >] and then set the items for the use of FIT modules and middleware.

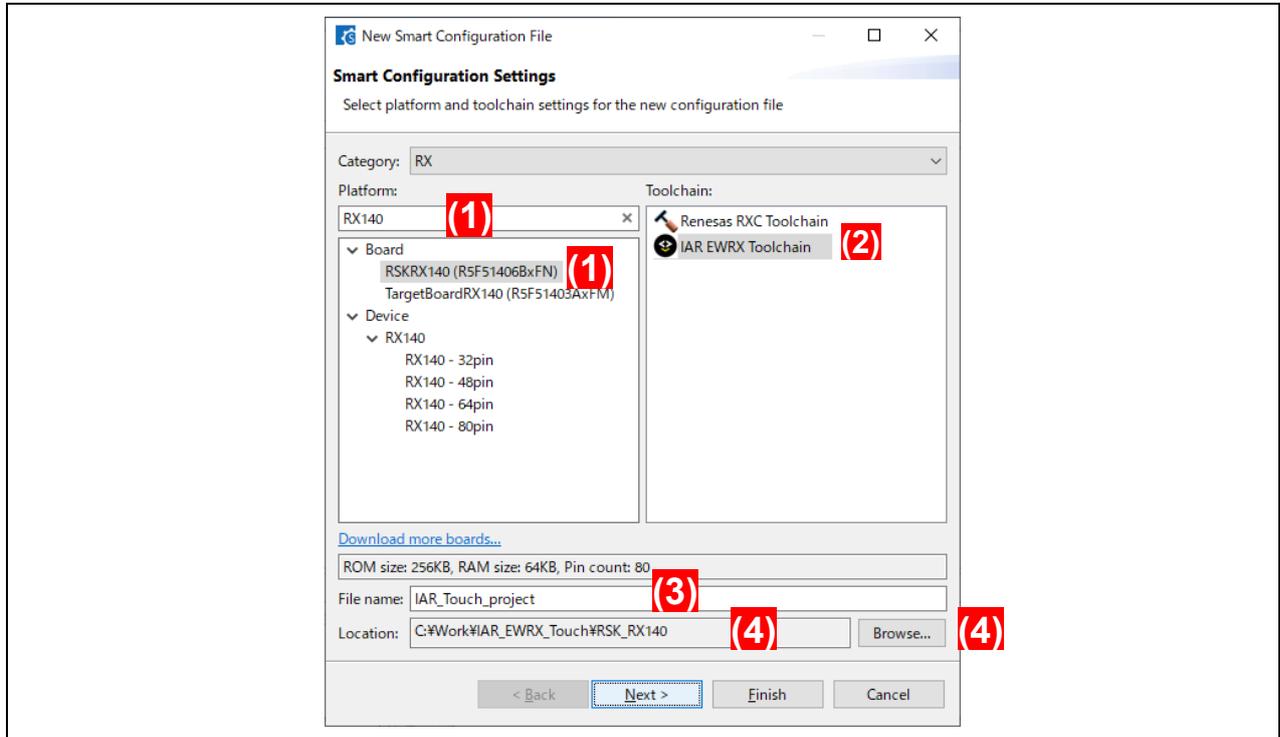


Figure 2-4 Smart Configurator Settings (1)

- Confirm that [RTOS:] in [RTOS Settings] is "None" and set the location of the FIT modules. Unzip the downloaded FIT module zip file. Click on [Browse...] and select the folder containing the unzipped FIT modules.

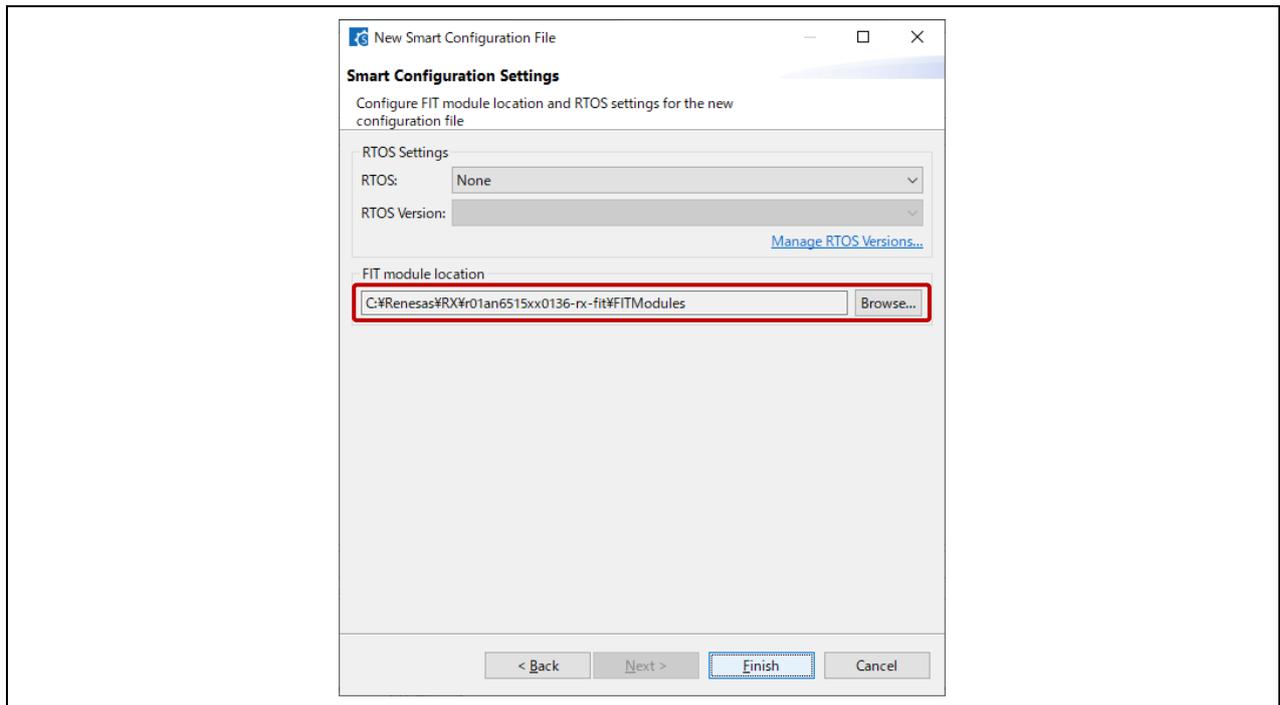


Figure 2-5 Smart Configurator Settings (2)

- Clicking on [Finish] creates a configuration file (*.scfg) and displays the main window.

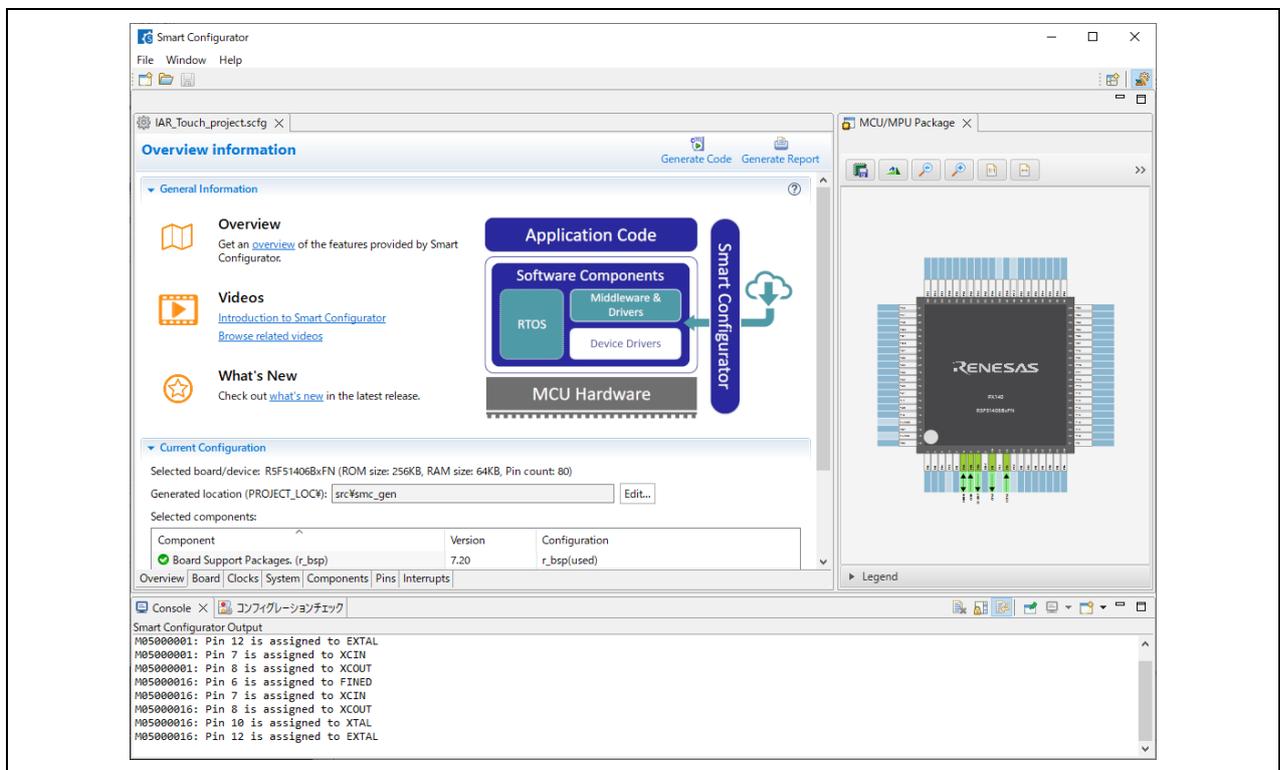


Figure 2-6 Main Window of Smart Configurator

2.2 Setting the Smart Configurator

When a tab at the bottom of the Smart Configurator view is selected, the displayed contents are switched. Select a tab as required and set the necessary items.

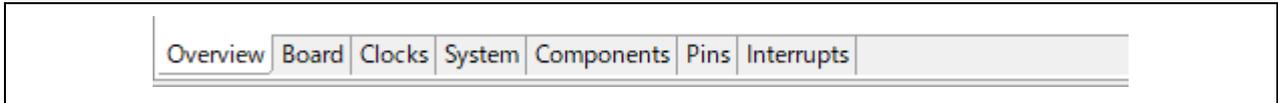


Figure 2-7 Tabs of the Smart Configurator View

1. Setting clocks

Select the [Clocks] tab.



Figure 2-8 Selecting the [Clocks] Tab

— VCC: Enter "5.0".

— Main clock: Tick the checkbox (✓).

Enter values so that the frequency of FCLK, ICLK, and PCLKD is 48 MHz, and the frequency of PCLKB is 24 MHz, as shown in Figure 2-9.

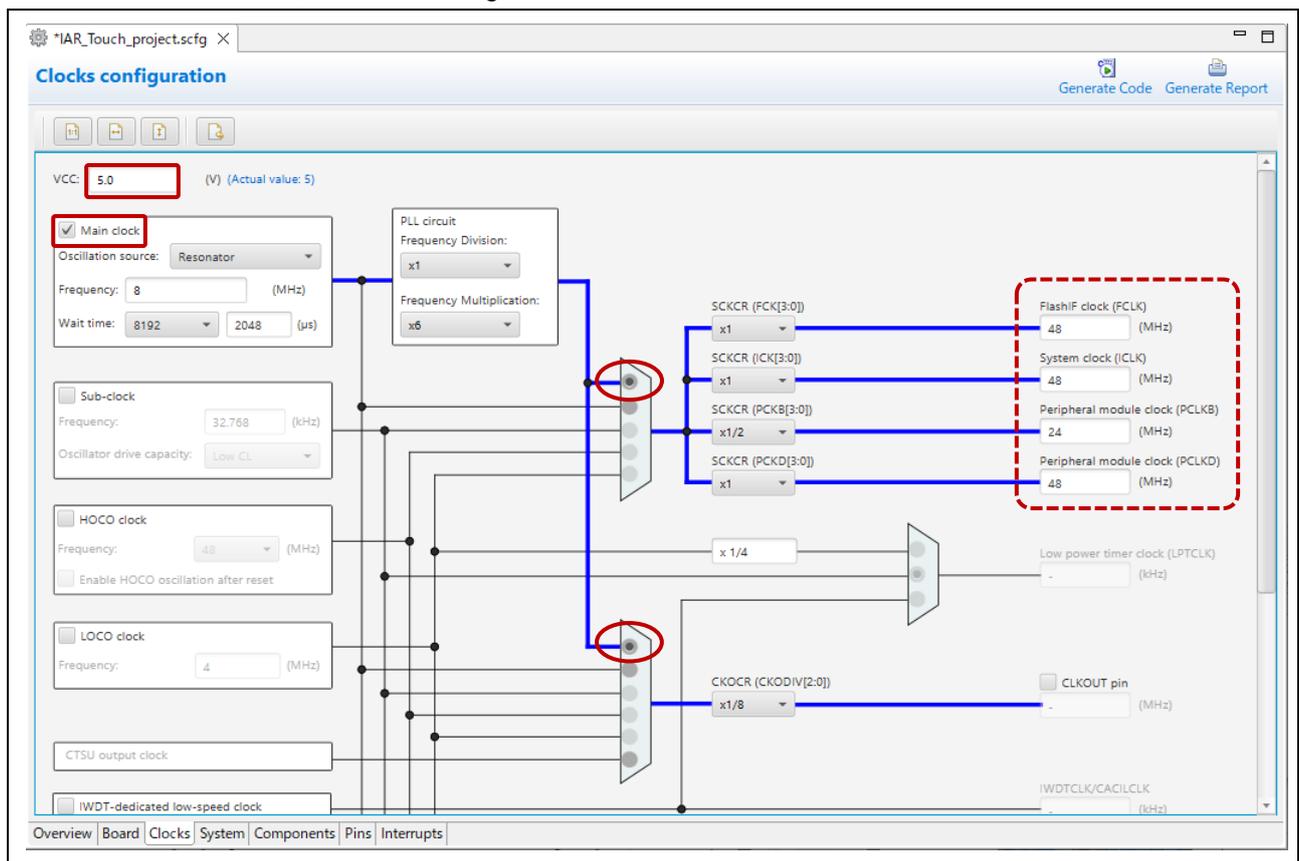


Figure 2-9 Setting Clocks

2. Setting the system
Select the [System] tab.

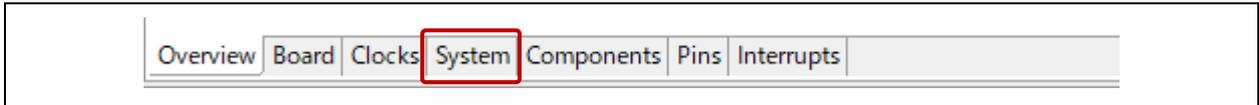


Figure 2-10 Selecting the [System] Tab

— Confirm that "FINE" is selected in [Debug interface setting].

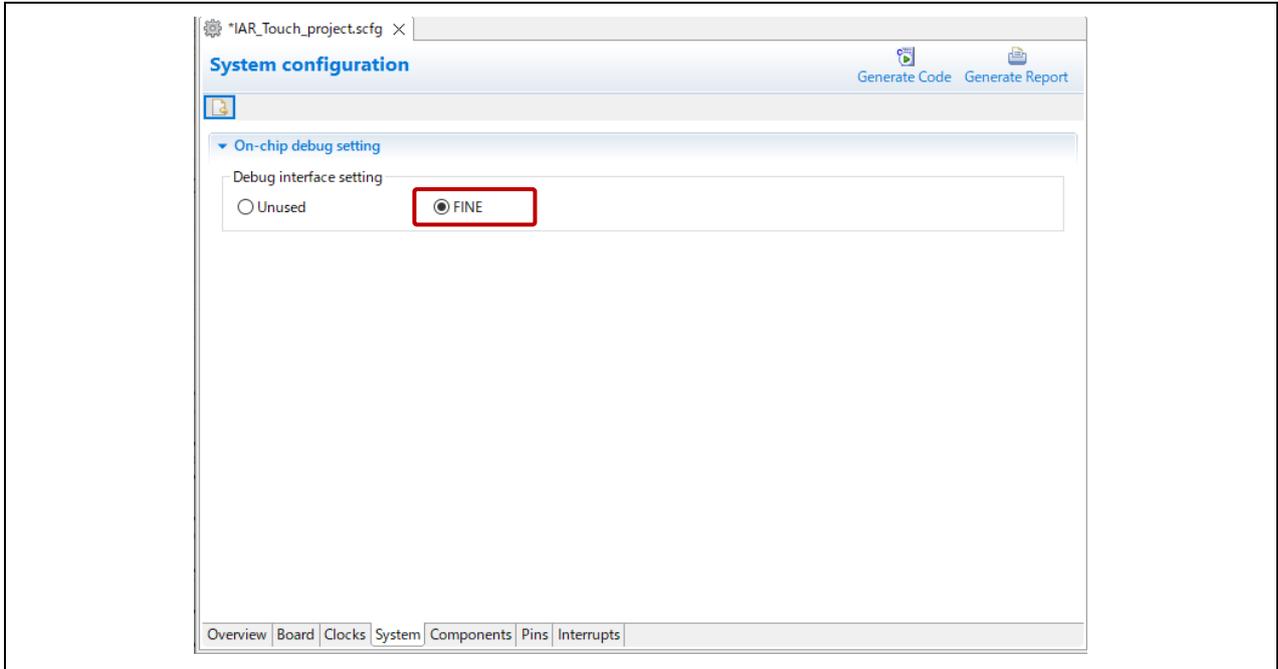


Figure 2-11 Setting the System

3. Setting software components
Select the [Components] tab.



Figure 2-12 Selecting the [Components] Tab

— Add a driver, middleware, and serial interface and set them up.

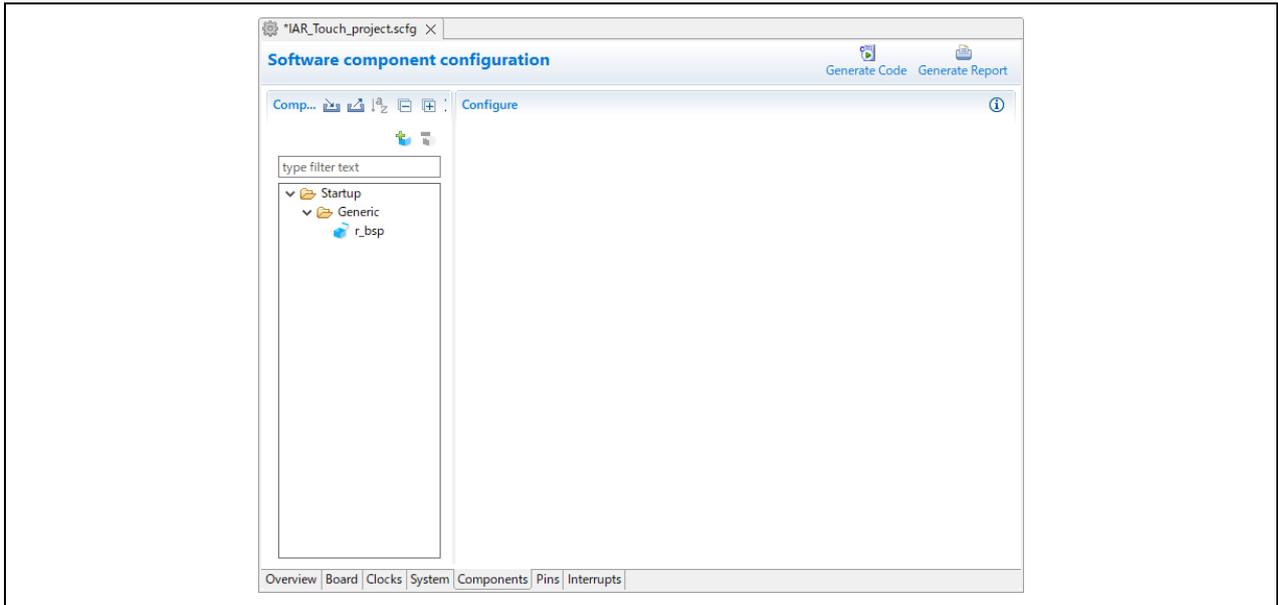


Figure 2-13 Setting Software Components

— To add a component, click on the  [Add component] button to open the "New Component" dialog box and select the component to be added.

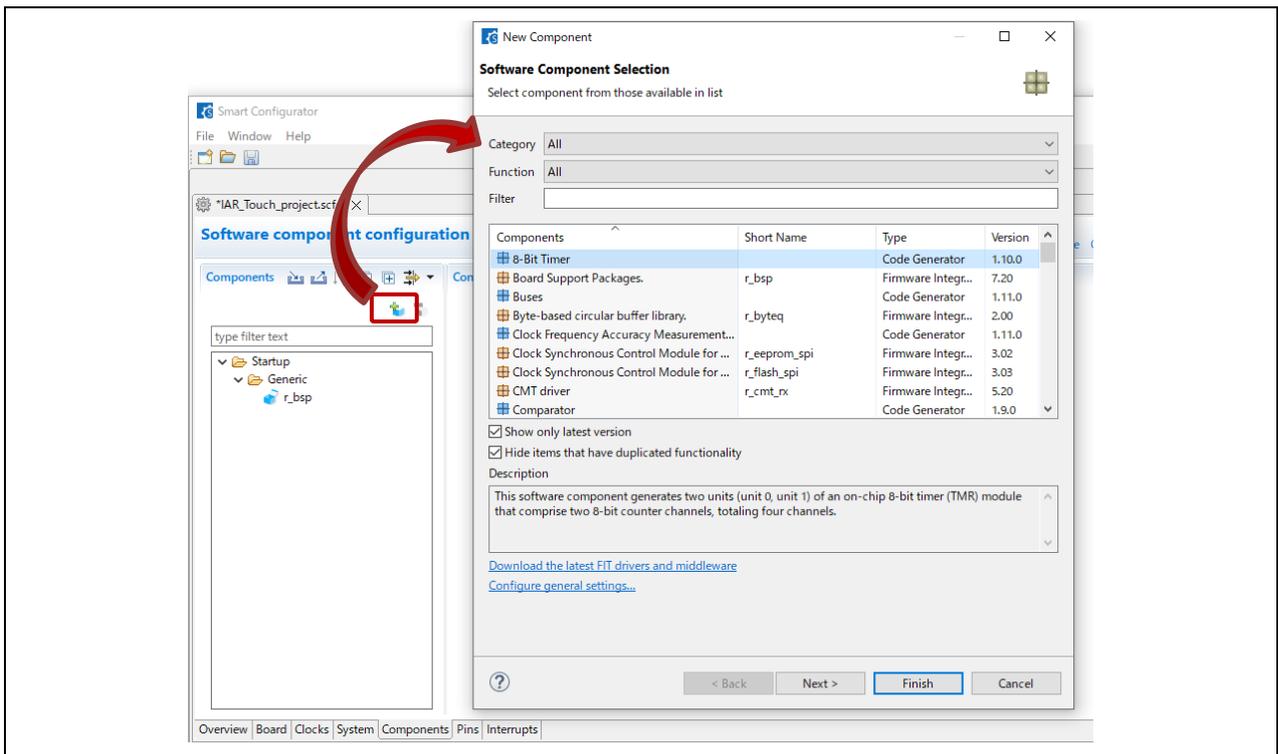


Figure 2-14 Displaying the "New Component" Dialog Box

a. Adding a CTSU driver

Open the "New Component" dialog box, select "r_ctorsu_qe", and click on [Finish].



Figure 2-15 Selecting "r_ctorsu_qe"

- Click on the added "r_ctorsu_qe" module and enable the TSCAP pin and the two TS pins to be used. For the assignment between the TS pins and touch sensors, confirm the user's manual of the target board in use.

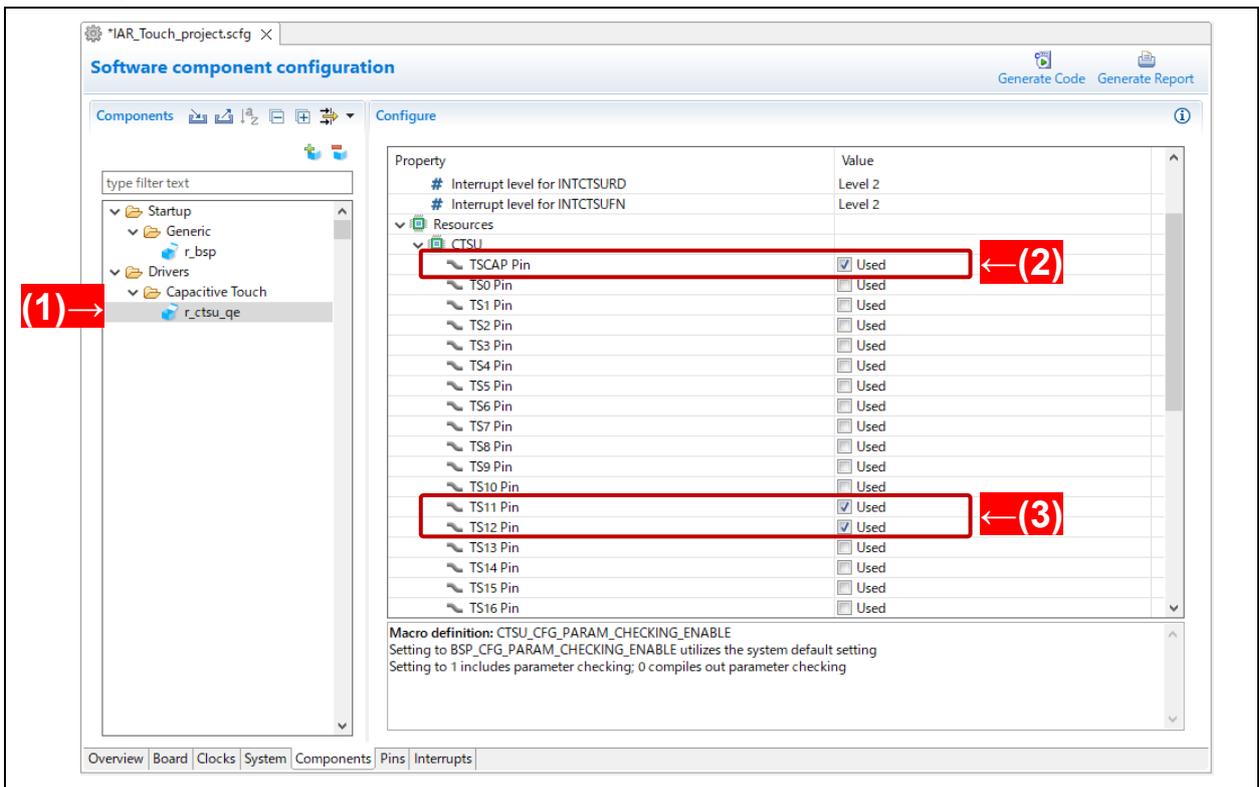


Figure 2-16 Enabling the Pins in Use ((1): r_ctorsu_qe, (2): TSCAP Pin, (3): Two TS Pins)

b. Adding touch middleware

Open the "New Component" dialog box, select "rm_touch_qe", and click on [Finish].

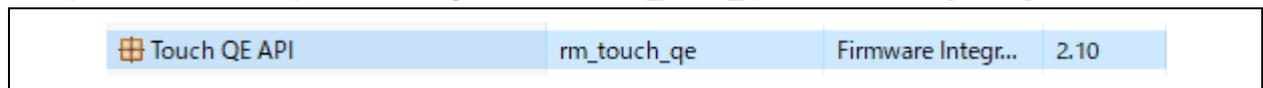


Figure 2-17 Selecting "rm_touch_qe"

- Click on the added "rm_touch_qe" module and set up serial communications monitoring through a UART.

Set items in [Value] as shown below.

Support for QE monitoring using UART: Include code to update sensor data for monitor

Support for Serial tuning using UART: Include code to serial tuning

UART channel: UART1

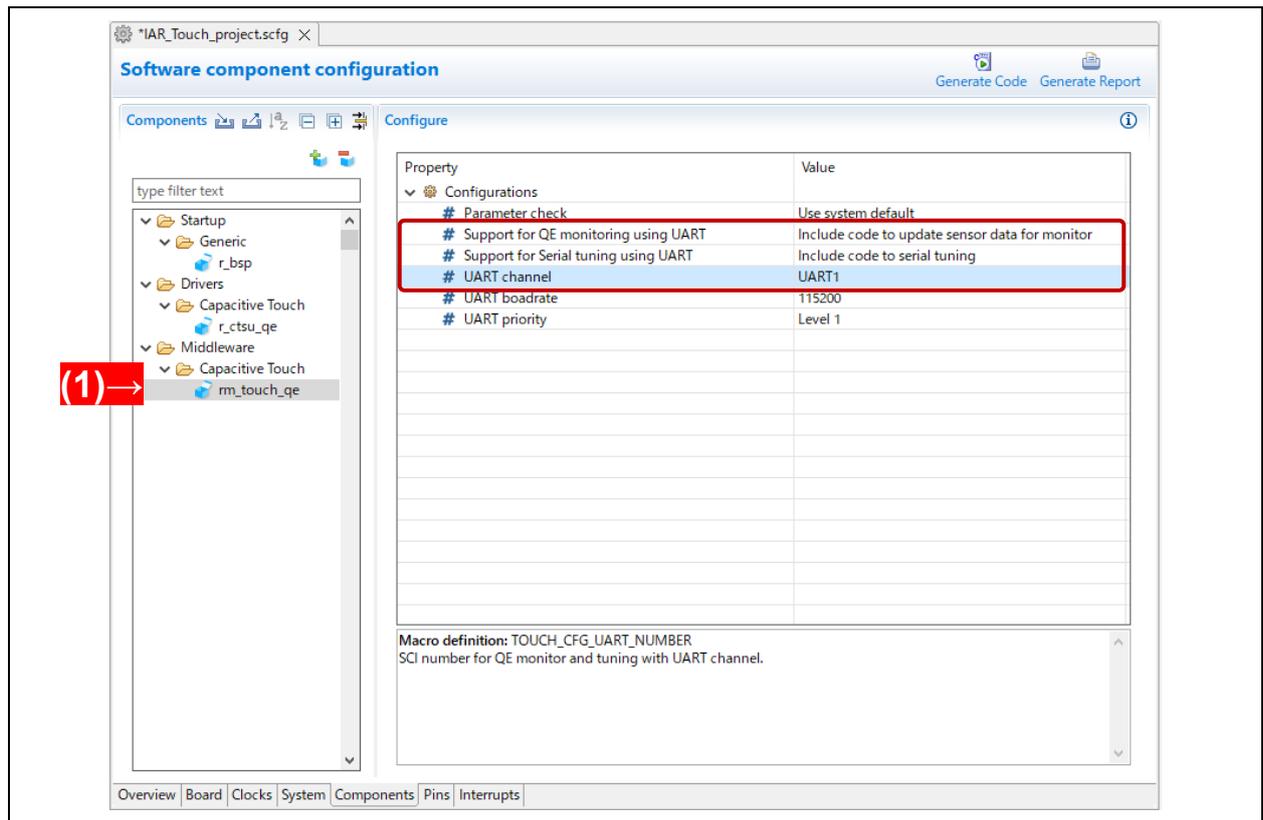


Figure 2-18 Selecting the Property of "rm_touch_qe" ((1): rm_touch_qe)

c. Adding a serial interface

Open the "New Component" dialog box, select "r_sci_rx", and click on [Finish].

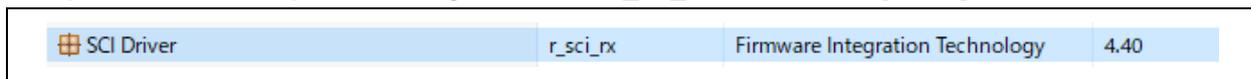


Figure 2-19 Selecting "r_sci_rx"

- Click on the added "r_sci_rx" module to display the related ports on the configuration panel and set items in [Value] as shown below.

Use ASYNC mode: Include
 # Include software support for channel 1: Include
 # Transmit end interrupt: Enable
 Resources > SCI > SCI1: Tick the checkbox (✓).
 RXD1, TXD1: Tick the "Used" checkbox (✓).

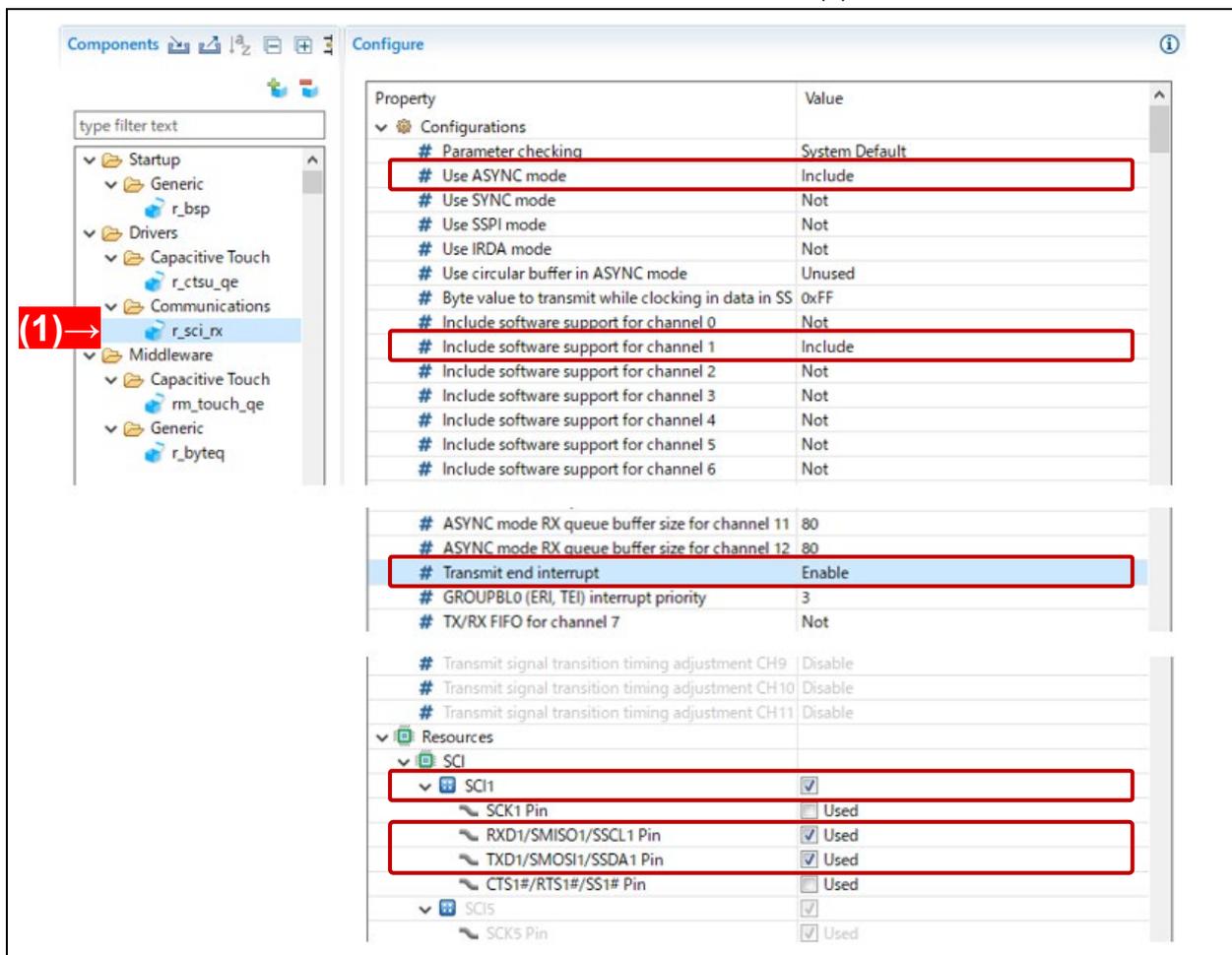


Figure 2-20 Setting "r_sci_rx" ((1): r_sci_rx)

- Assign the pin functions for SCI1.
Select the [Pins] tab.



Figure 2-21 Selecting the [Pins] Tab

- Expand "Serial communications interface" in the tree next to the [Pin Function] panel on the [Pin configuration] tabbed page and select SCI1.
Assign the "RXD1" function to "P30" and the "TXD1" function to "P26".

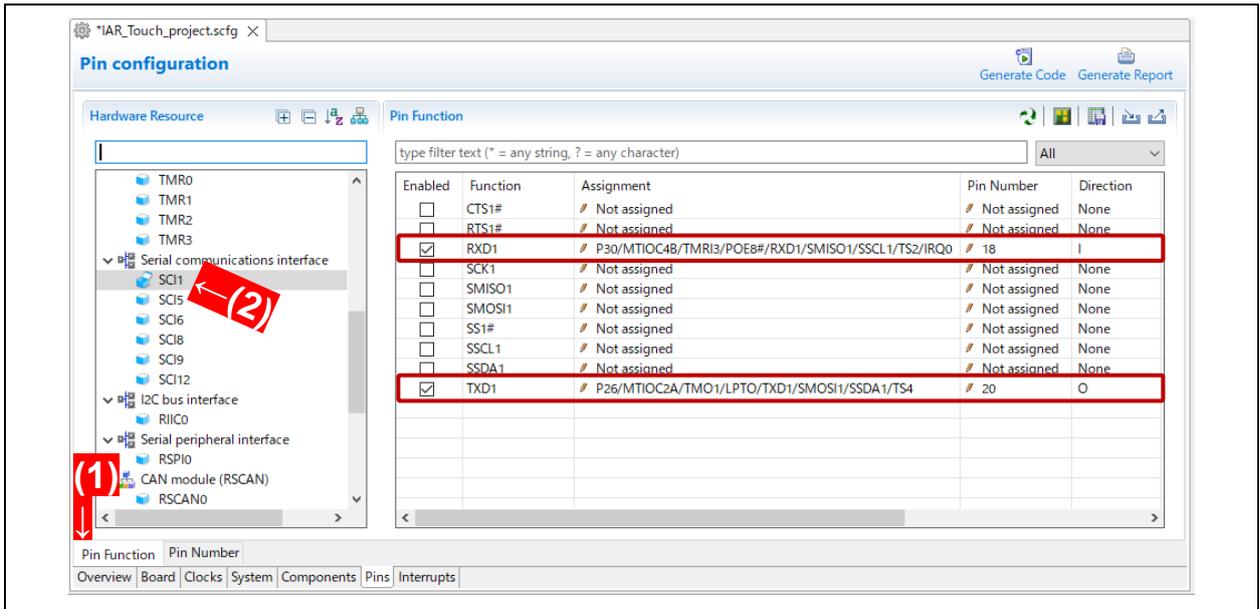


Figure 2-22 Assigning Pin Functions for SCI1 ((1): [Pin Function] Tab, (2): SCI1)

2.3 Generating Code

Generate code.

1. Click on the  button of the Smart Configurator and generate code.

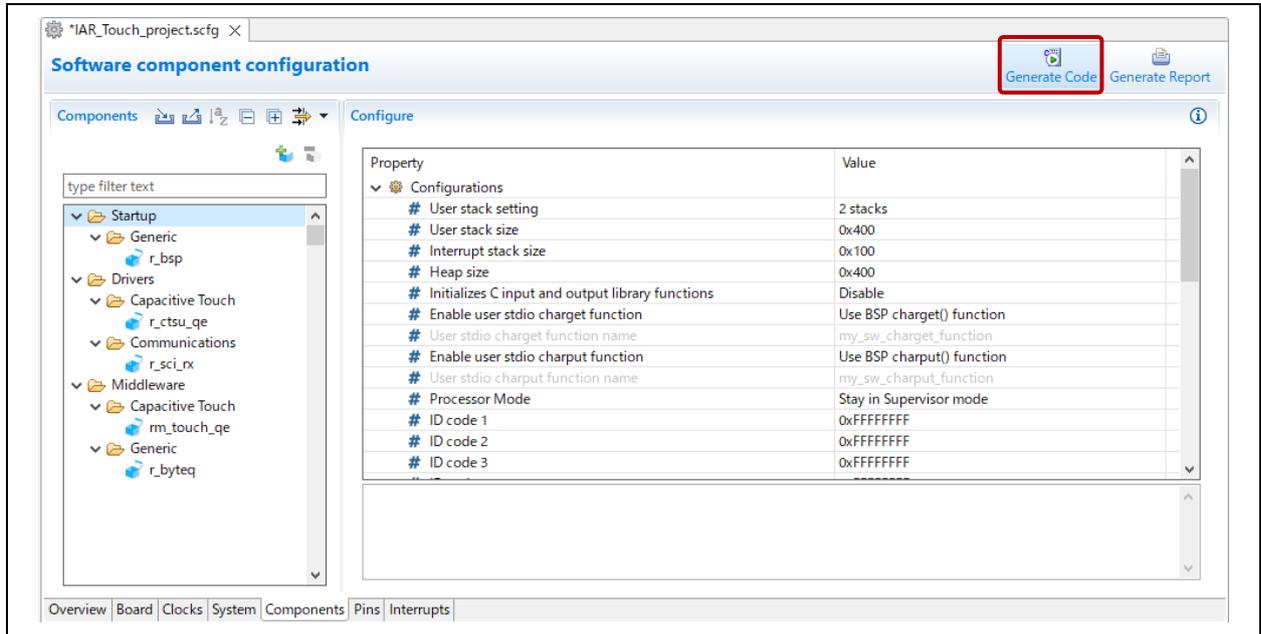


Figure 2-23 Generating Code

When the following message box is displayed, click on [Proceed].

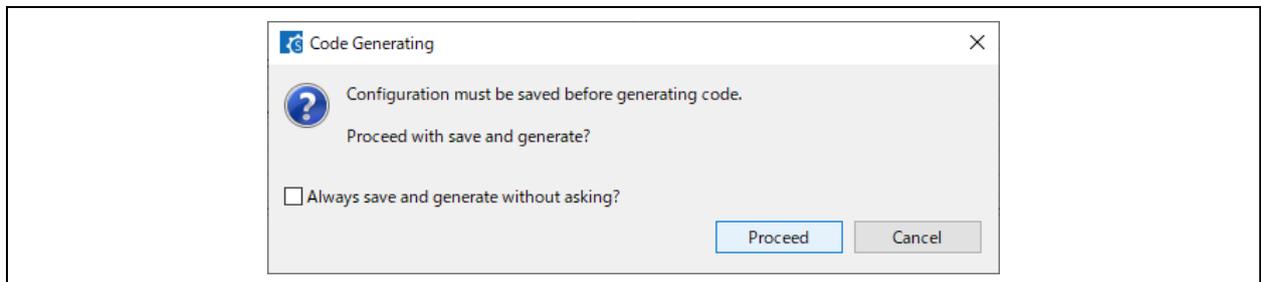


Figure 2-24 Message at Code Generation

2. Confirm that "Code generation is successful" is displayed in the Console view.



Figure 2-25 Termination of Code Generation

3. Terminate the Smart Configurator by selecting [Exit] from the [File] menu.

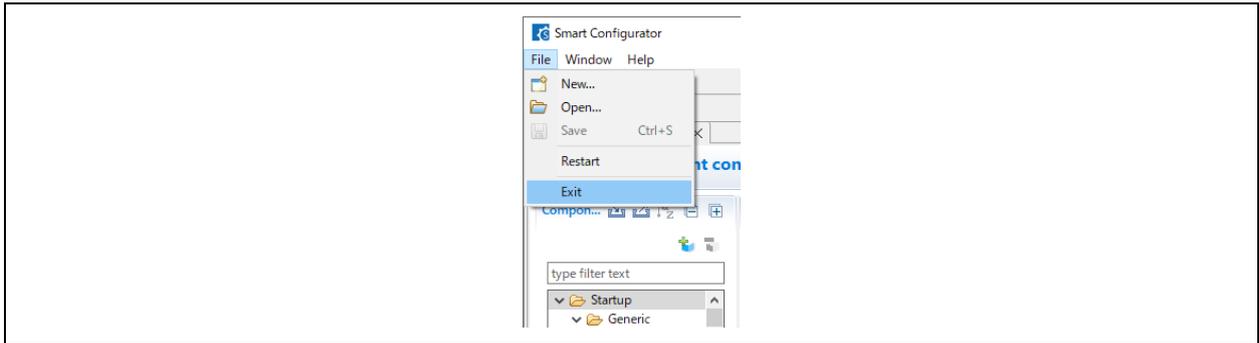


Figure 2-26 Terminating the Smart Configurator

4. In Windows Explorer, confirm that an IAR IDE Workspace file (*.eww) with the  icon has been created in the folder with the location specified in section 2.1.3 (3).

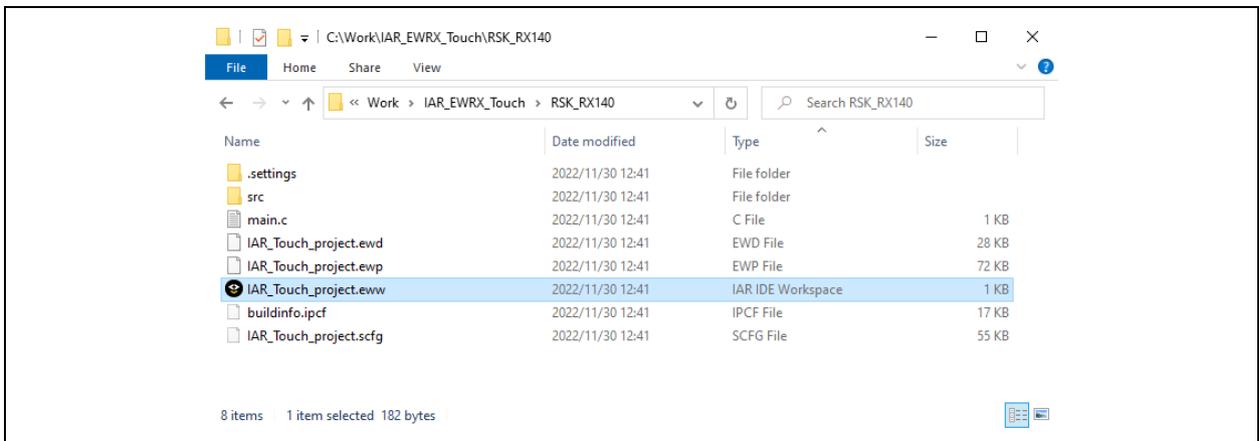


Figure 2-27 IAR EWRX Workspace Folder

5. Set items to allow launching the Smart Configurator from the [Tools] menu in the IAR EWRX window. Double-click on the IAR IDE Workspace file created in Windows Explorer to start the IDE. In the opened IAR EWRX window, select [Configure Tools...] from the [Tools] menu to open the [Configure Tools] dialog box.

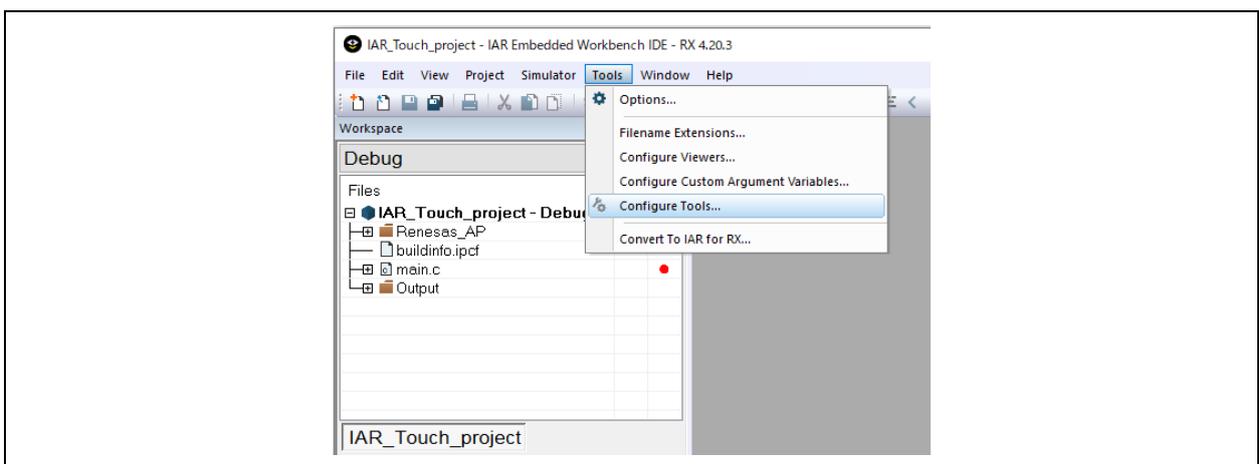


Figure 2-28 Tools

- In the [Configure Tools] dialog box, click on [New] and enter values for items (2) to (5) shown below.
 - (1) Menu Content: The contents entered in [Menu Text] are displayed.
 - (2) Menu Text: Smart Configurator for RX
 - (3) Command: [Installation folder]\eclipse\SmartConfigurator.exe
 - (4) Argument: \$PROJ_FNAME\$.scfg
 - (5) Initial Directory: \$PROJ_DIR\$
 Click on [OK] to close the "Configure Tools" window.

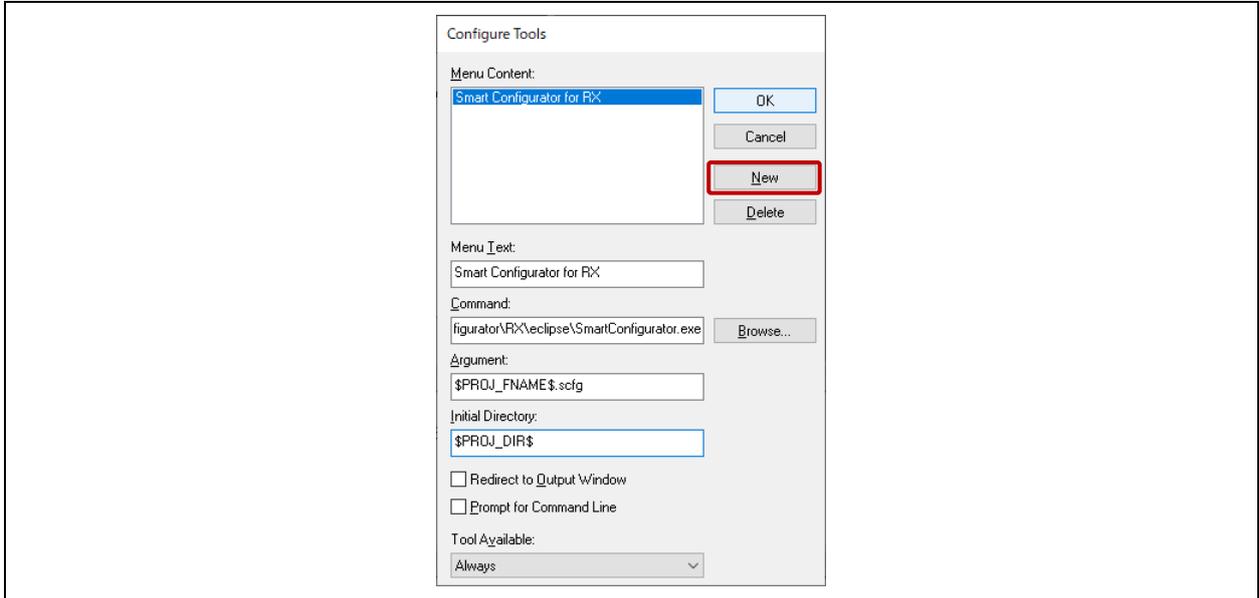


Figure 2-29 Setting Tools

- The Smart Configurator can now be selected from the [Tools] menu.

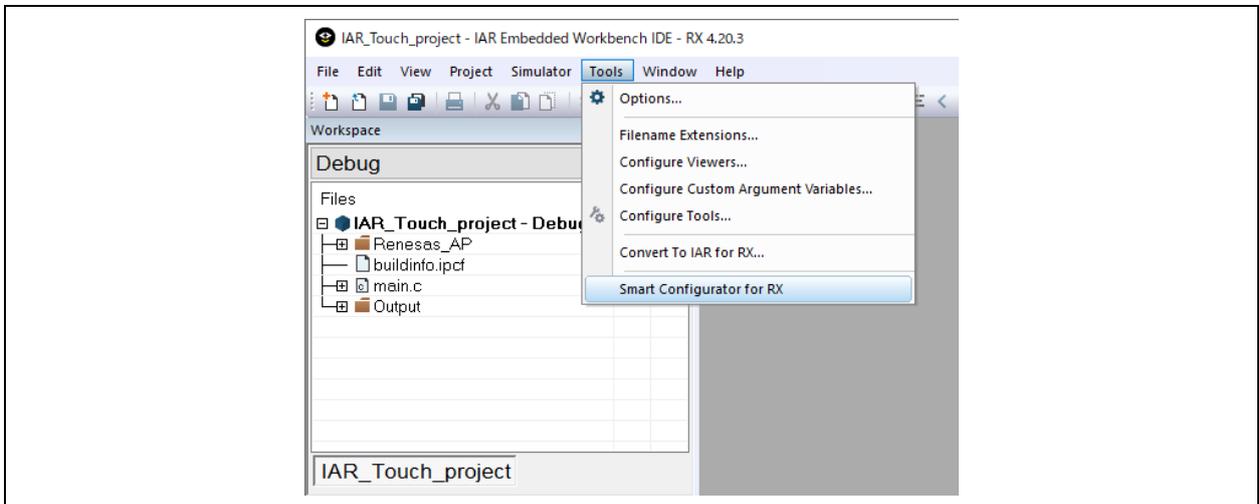


Figure 2-30 Settings Reflected in the [Tools] Menu

- Next, right-click on the project name in the [Workspace] window, then select [Rebuild All] to perform building. After building has finished, confirm that no errors are indicated in the [Build] window or status bar at the bottom of the main window.

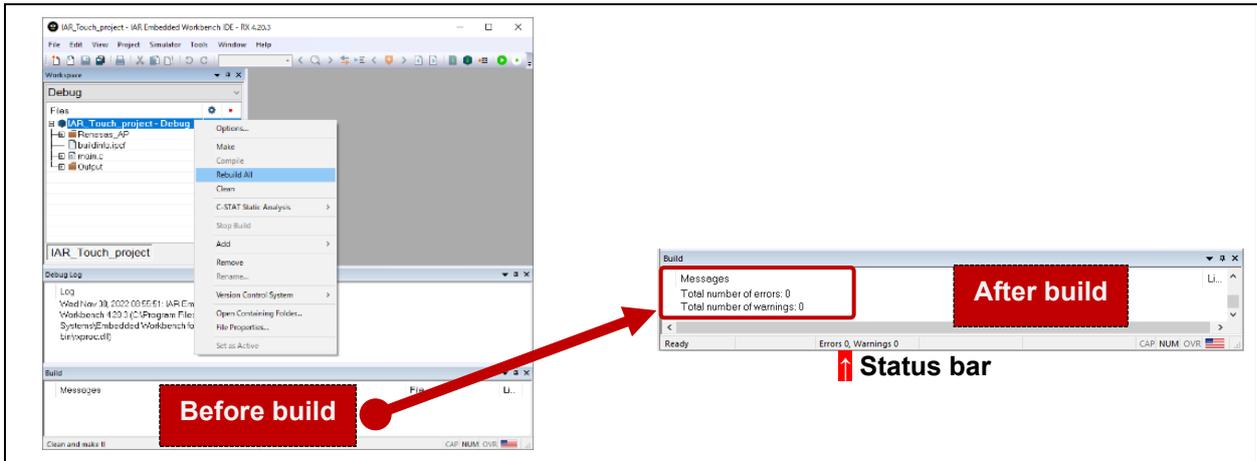


Figure 2-31 Building

- Select [Exit] from the [File] menu. In the [IarIdePm] dialog box that is displayed, click on [Yes] to save the project and terminate the IAR EWRX workspace.

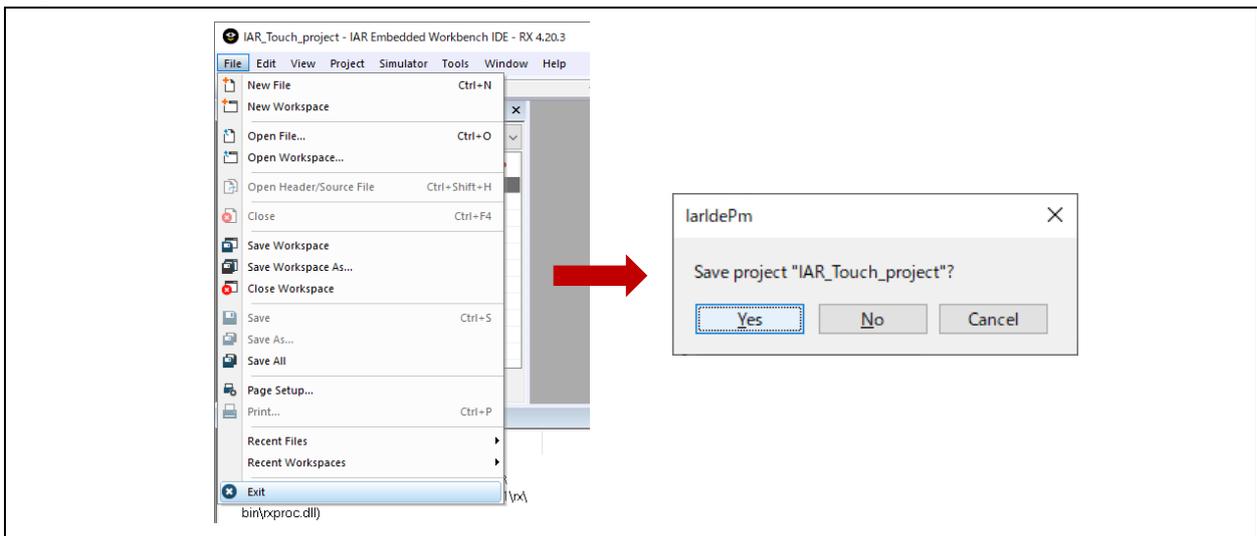


Figure 2-32 Terminating the IAR EWRX Workspace

2.4 Setting the Project Folder and Target MCU

After creating a project, launch the standalone-version QE. The folder containing the created project and MCU product information should be set, according to "1. Preparation" in the workflow diagram.

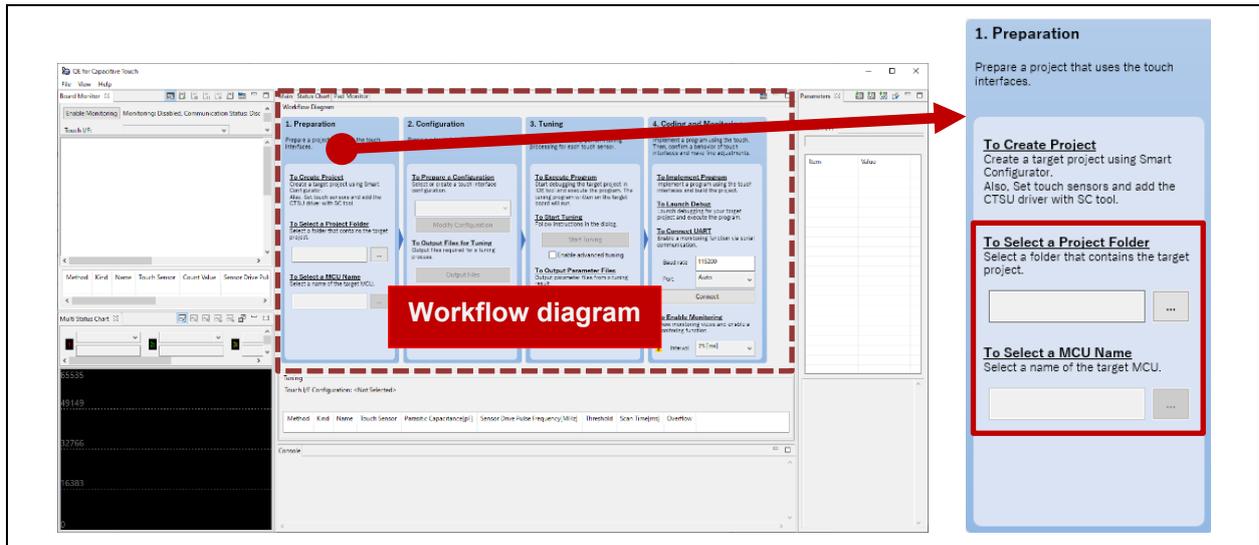


Figure 2-33 Standalone-Version QE - Workflow Diagram: <Step 1> Preparation

1. Select the project folder.
Click on [...] to the right of the input area under "To Select a Project Folder" to select the folder storing the project.
 2. Select product information on the microcontroller.
Click on [...] to the right of the input area under "To Select a MCU Name" to select an MCU by clicking on the ▾ labels in the "Product Name of Target MCU" dialog box that is displayed.
 - (1) Family Name Select "RX".
 - (2) Group Name Select "RX140".
 - (3) Pin Number Select "LQFP/80pin:FN".
 - (4) ROM Size Select "256KB:6".
 - (5) Product Name "R5F51406xxFN" will be displayed when the above items (1) to (4) have been selected correctly.
- Click on [OK] to close the dialog box.

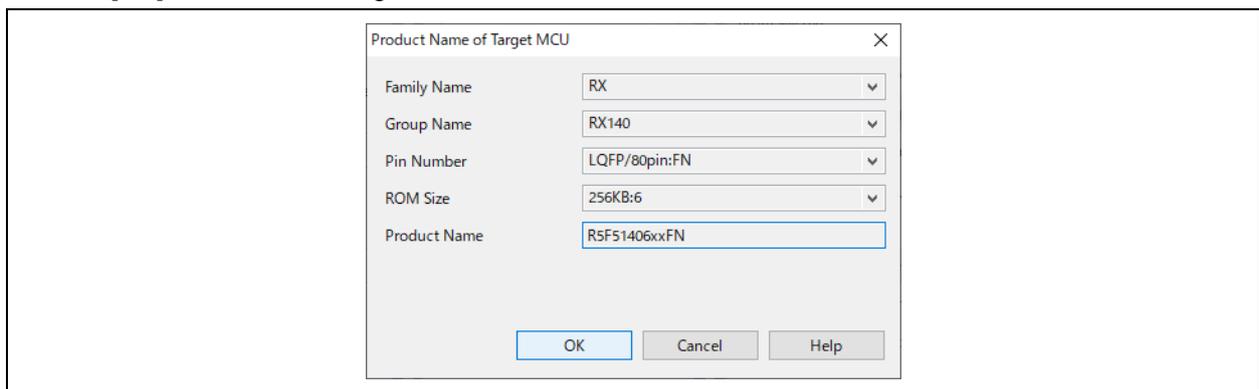


Figure 2-34 "Product Name of Target MCU" Dialog Box

3. Preparing the Touch Interfaces

Set items according to "2. Configuration" in the workflow diagram.

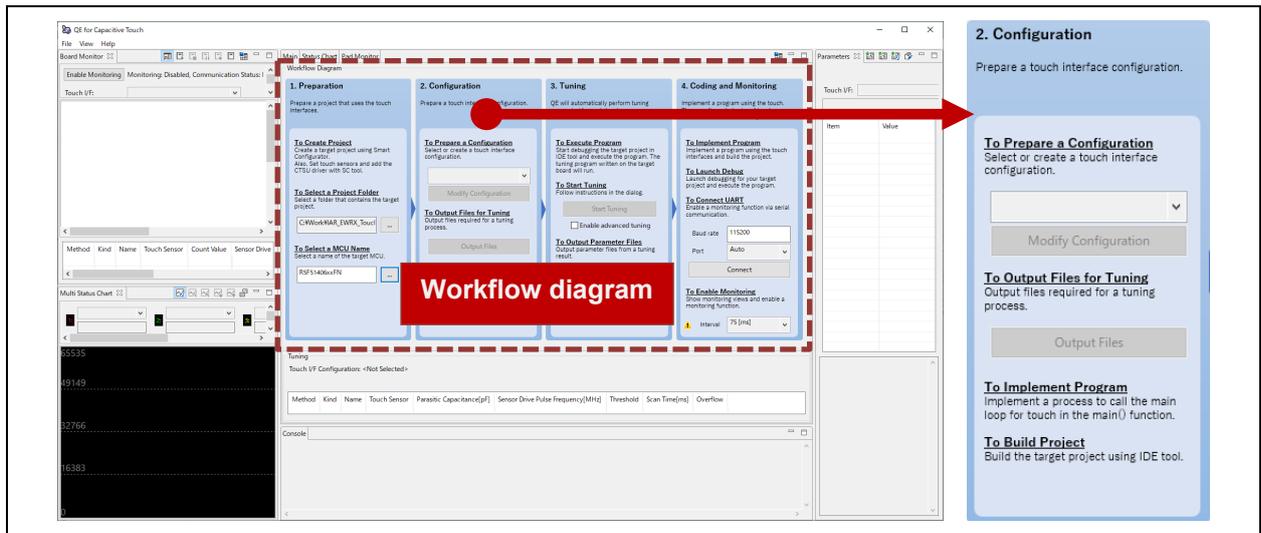


Figure 3-1 Standalone-Version QE - Workflow Diagram: <Step 2> Configuration

3.1 Creating a Touch Interface Configuration

Create a new touch interface configuration.

1. Click on  under "To Prepare a Configuration" and select "Create a new configuration". The "Create Configuration of Touch Interfaces" window appears and displays the area for placing touch interfaces.

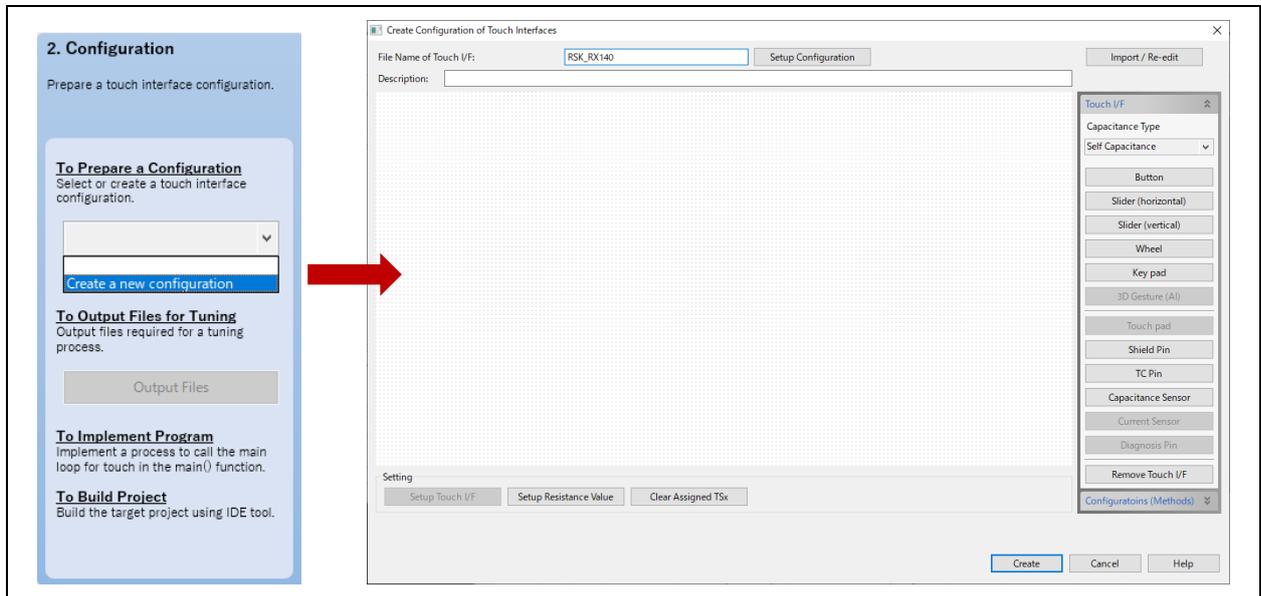


Figure 3-2 Creating a Touch Interface Configuration

- Clicking on [Button] in the "Touch I/F" panel on the right side of the "Create Configuration of Touch Interfaces" window enables the placement of buttons at the cursor position. Clicking on a position in the area causes a button to be placed there.
After having placed two buttons as shown below, press the [ESC] key to stop adding touch interfaces.

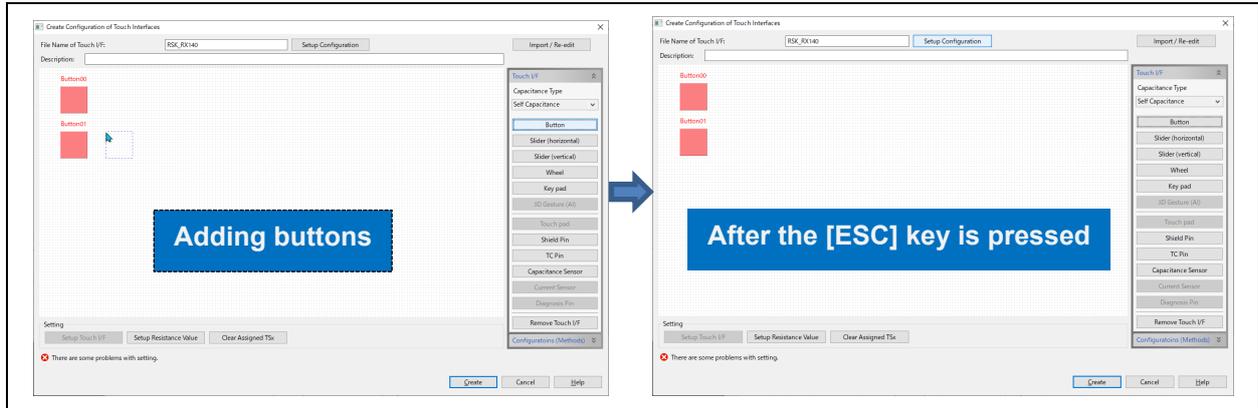


Figure 3-3 Adding Buttons

- Double-click on the placed buttons and set the following items in the displayed "Setup Touch Interface" dialog box.
 Button00: [Name] TS_B1 [Touch Sensor] TS11 [Resistance] 560
 Button01: [Name] TS_B2 [Touch Sensor] TS12 [Resistance] 560
 The color of the buttons will change to green if the items of the touch interface have been set correctly.

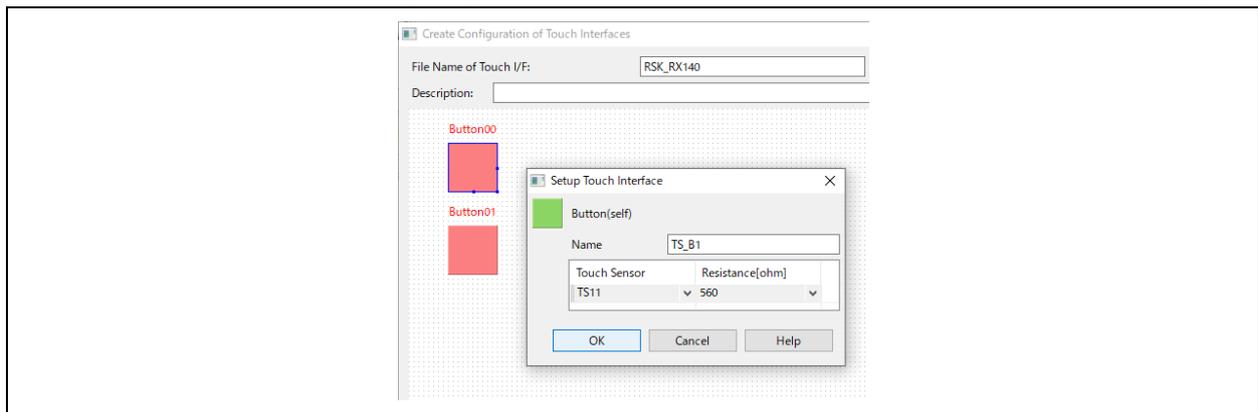


Figure 3-4 Setting the Touch Interface Items for Button00

- Confirm that the color of the two buttons that have been placed is green and click on [Create] to close the window.

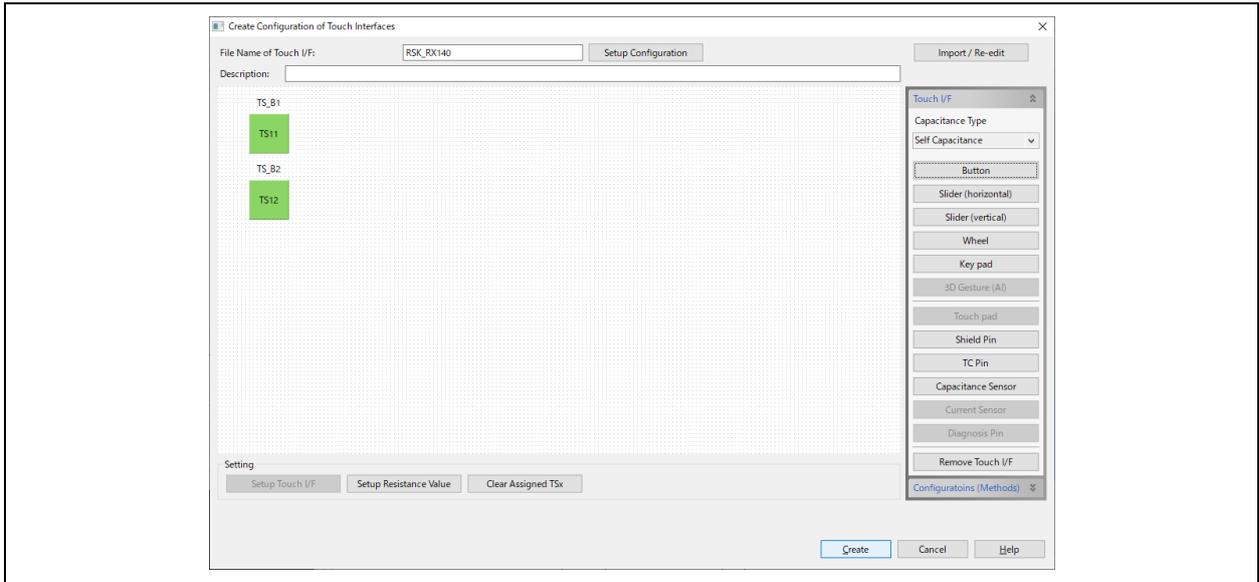


Figure 3-5 Stopping Creation of Touch Interface Configurations

- The touch interface configurations are displayed on the [Tuning] panel in the "Main" window.

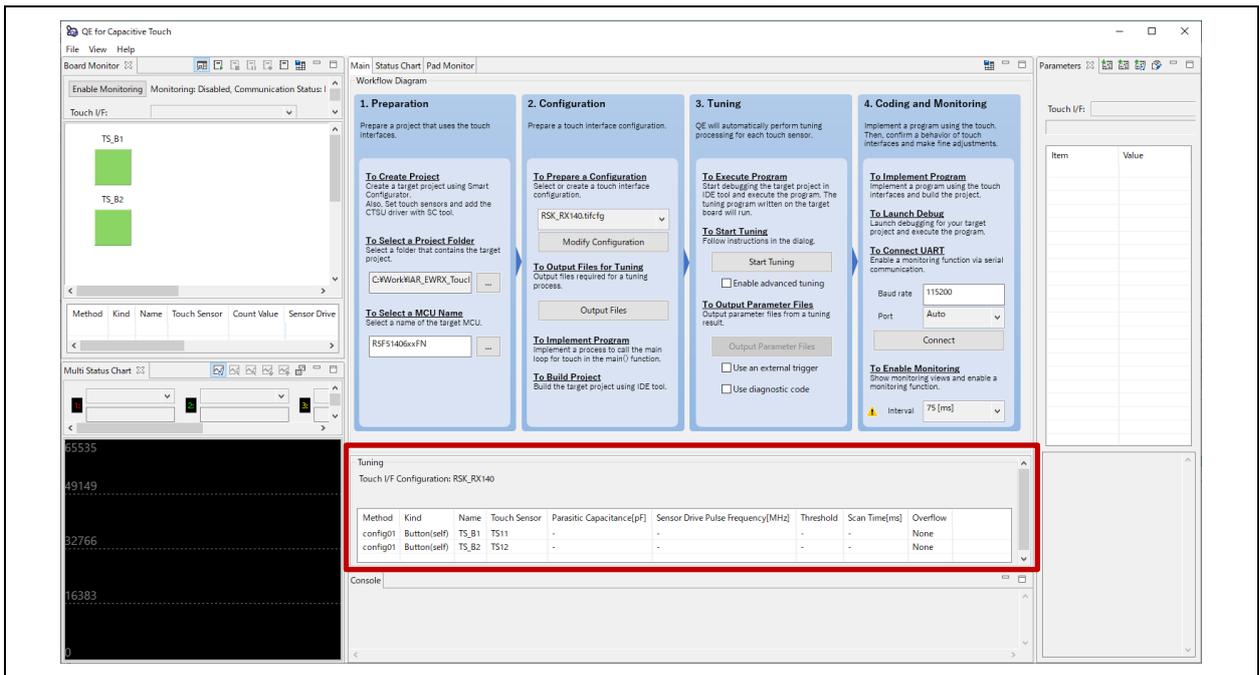


Figure 3-6 Touch Interface Configurations

3.2 Outputting Files for Tuning Touch Sensors

After the files for tuning touch sensors have been output to the specified folder, set the frequency of the peripheral module clock of the MCU and the voltage supplied to the microcontroller.

1. Click on [Output Files] to display the "The output folder of parameter files" dialog box. Click on the folder to which the files are to be output and then click on [Select Folder].

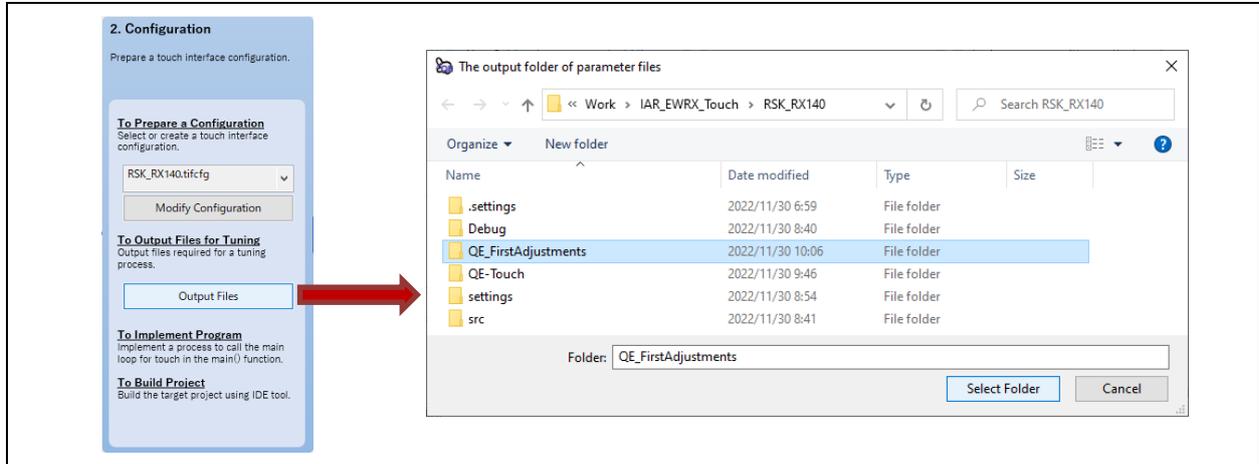


Figure 3-7 Outputting Files for Tuning

In the example shown in this figure, the "QE_FirstAdjustments" folder is created under the project folder and selected as the folder for output of the parameter files.

2. When the folder for outputting files is selected, the "Frequency of Peripheral Module Clock (PCLKB or PCLKL)" dialog box appears. Enter "48" for the frequency and click on [OK].

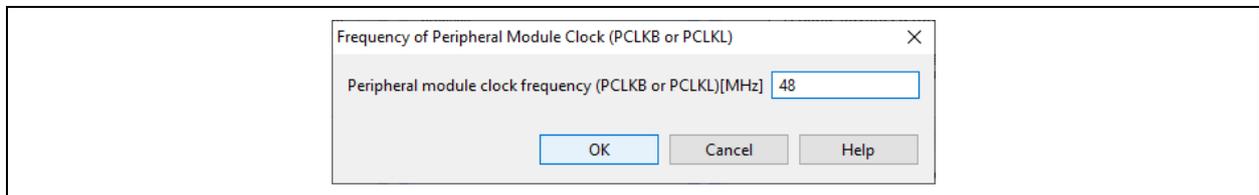


Figure 3-8 Setting the Frequency of the Peripheral Module Clock (PCLKB or PCLKL)

3. In the "Operating Voltage of MCU (VCC)" dialog box that appears next, click on . Then select [5.0V : (4.5V ≤ VCC ≤ 5.5V)] as the voltage value and click on [OK]. Since an external power supply is used, confirm the electrical characteristics of the microcontroller in use.

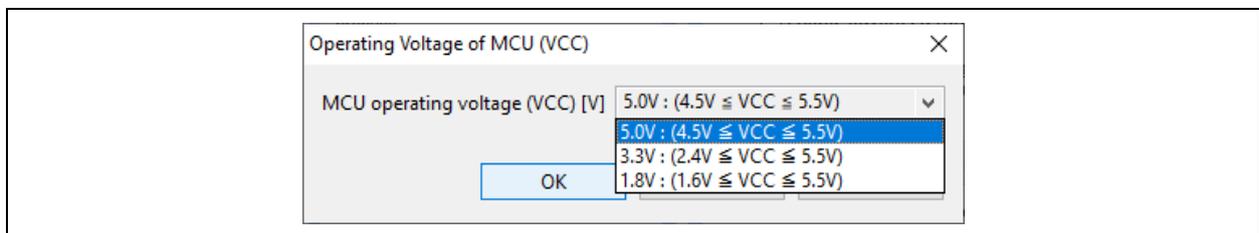


Figure 3-9 Setting the Operating Voltage (VCC) of the MCU

4. Finally, the "QE for Capacitive Touch" dialog box appears. Follow the instructions in the dialog box. The same contents are displayed in the "Console" panel at the bottom of the window.

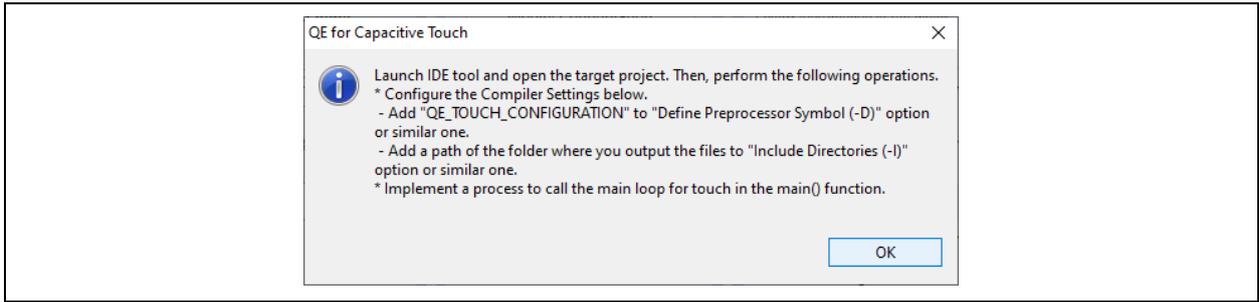


Figure 3-10 "QE for Capacitive Touch" Dialog Box

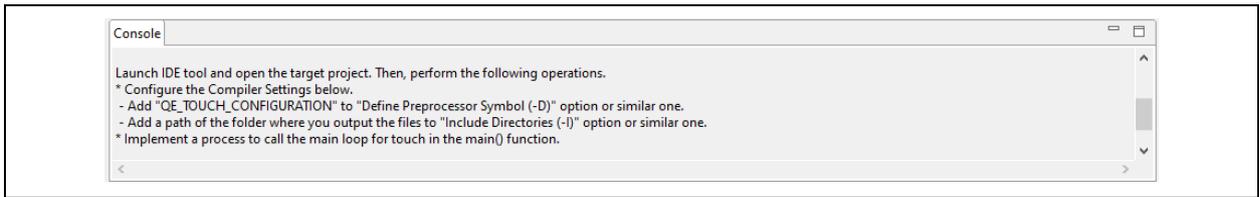


Figure 3-11 "Console" Panel

3.3 Implementing Programs for Tuning

In the IAR EWRX project, modify the main program to operate the programs for tuning, add the programs for tuning, add compiler options, and make settings for debugging.

1. In Windows Explorer, double-click on " <workspace file name>.eww" to open the IAR EWRX window.

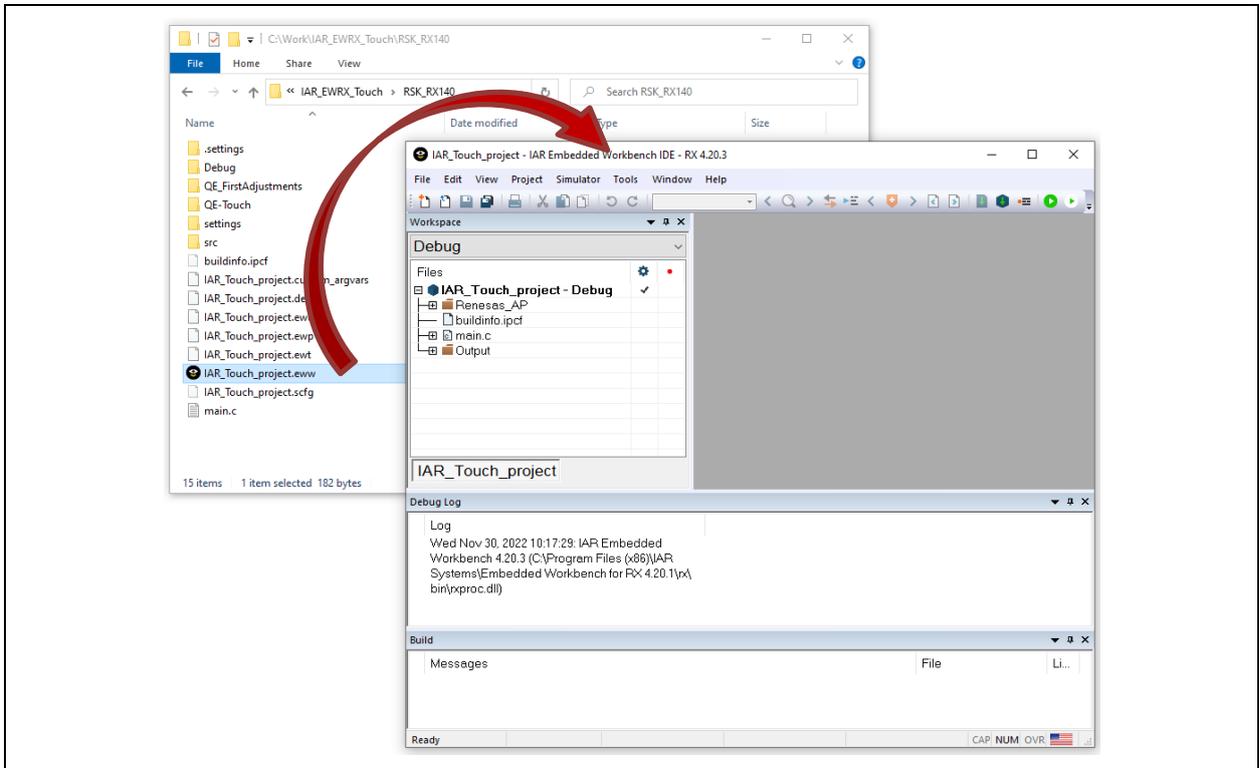


Figure 3-12 IAR EWRX Window

2. Change the main function.

Implement processing for calling the touch main function in the main() function.

— Double-click on main.c to open the file. Add the declaration of the touch main function and code for calling it, then save main.c and close the file.

Line 5: extern void qe_touch_main(void);

Line 9: qe_touch_main();

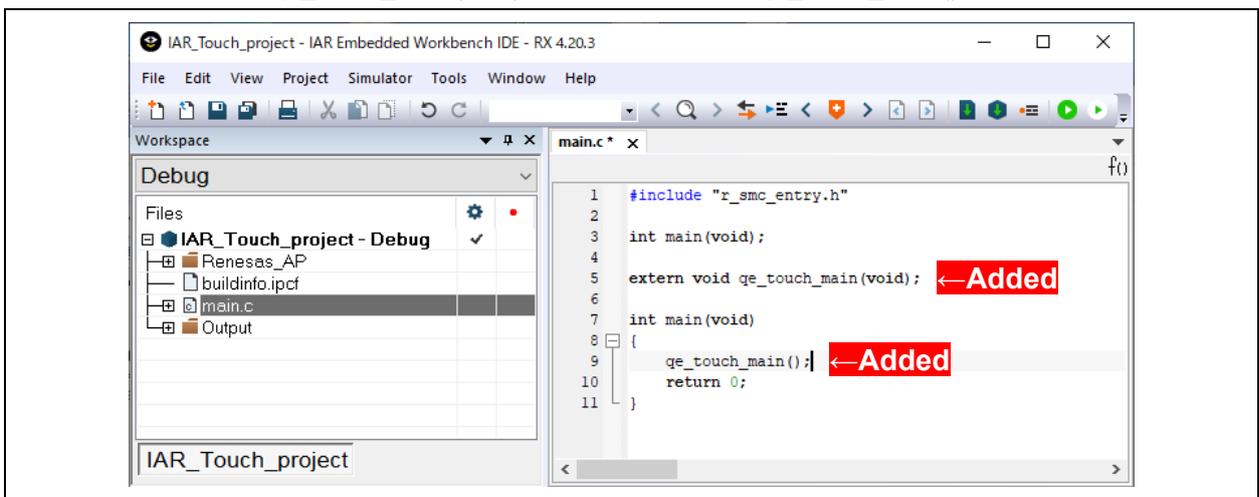


Figure 3-13 Modifying the main() Program

3. Add the files for tuning.

Copy the files for tuning to the "qe_gen" folder and add the files for tuning to the project.

- a. Create a "qe_gen" folder in the folder for storing the workspace file. Copy all files in the folder where the files for tuning were saved to the "qe_gen" folder.

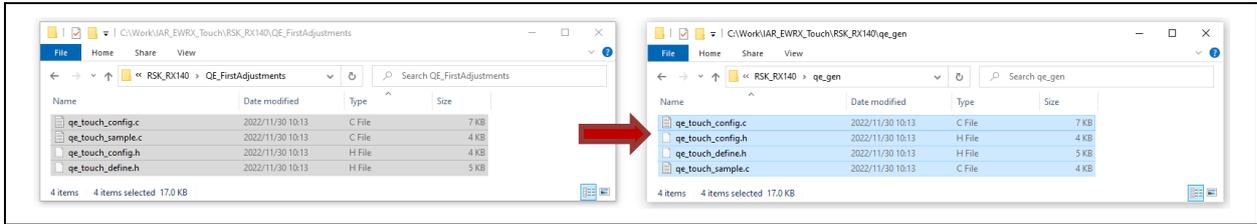


Figure 3-14 Copying the Files for Tuning

- b. Right-click on the project name in the [Workspace] window and select in the order of [Add] → [Add Group...]. In the [Add Group] dialog box, enter "qe_gen" and click on [OK].

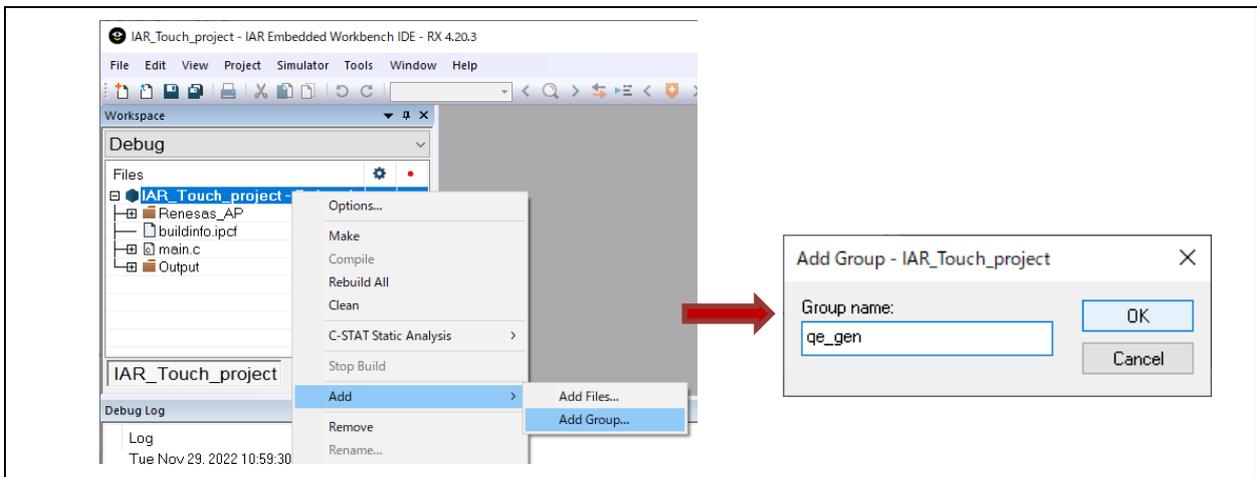


Figure 3-15 Adding a Group

- c. Right-click on the added group name and select in the order of [Add] → [Add Files...]. In the [Add Files] dialog box, select all files and click on [Open].

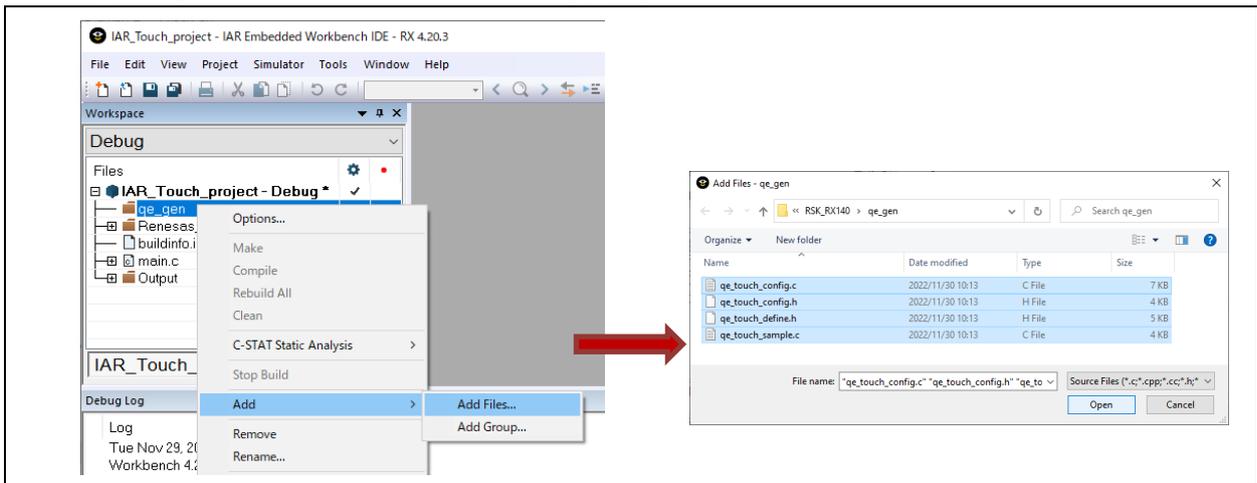


Figure 3-16 Adding Files

3.4 Building a Project

1. Add the compiler options.

Add the include paths and symbol definitions of the files for tuning to the preprocessor settings.

— Right-click on the project name in the [Workspace] window and select [Options...] to open the [Options] dialog box.

— Select "C/C++ Compiler" in [Category:] and then select the [Preprocessor] tab.

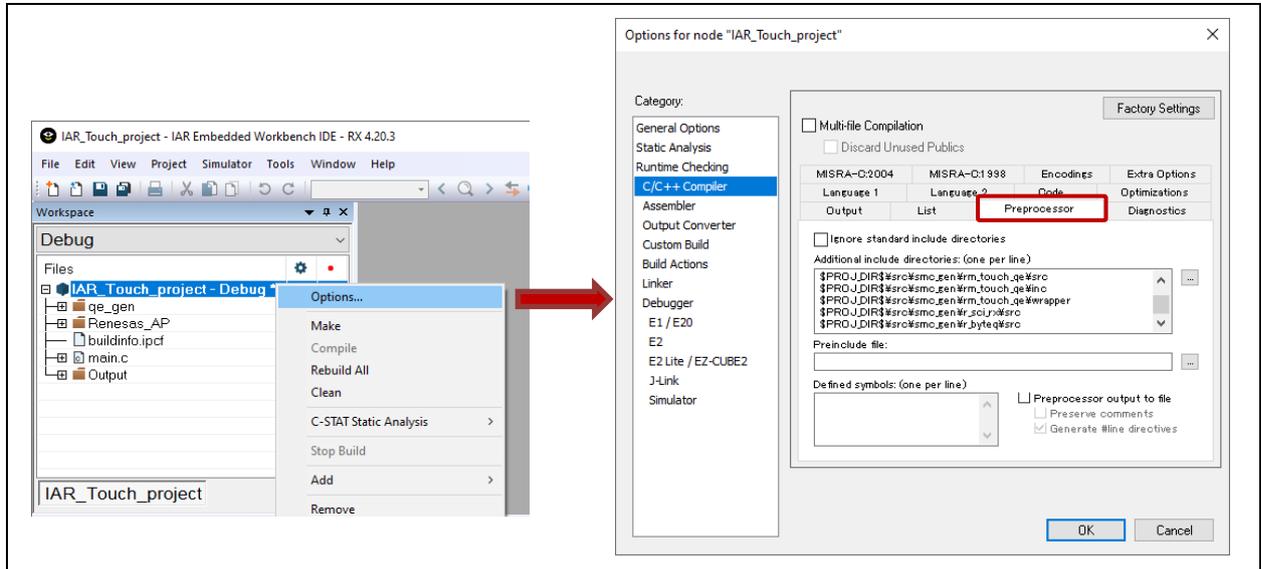


Figure 3-17 Displaying the [Preprocessor] Tab of "C/C++ Compiler"

a. Add the include paths.

- (1) On the [Preprocessor] tabbed page, click on [...] in [Additional include directories: (one per line)] to open the [Edit Include Directories] dialog box.
- (2) Scroll down to the bottom of the [Edit Include Directories] dialog box and click on <Click to add>.
- (3) The [Add Include Directory] dialog box appears. Select the folder where the files for tuning were saved and click on [Select Folder].

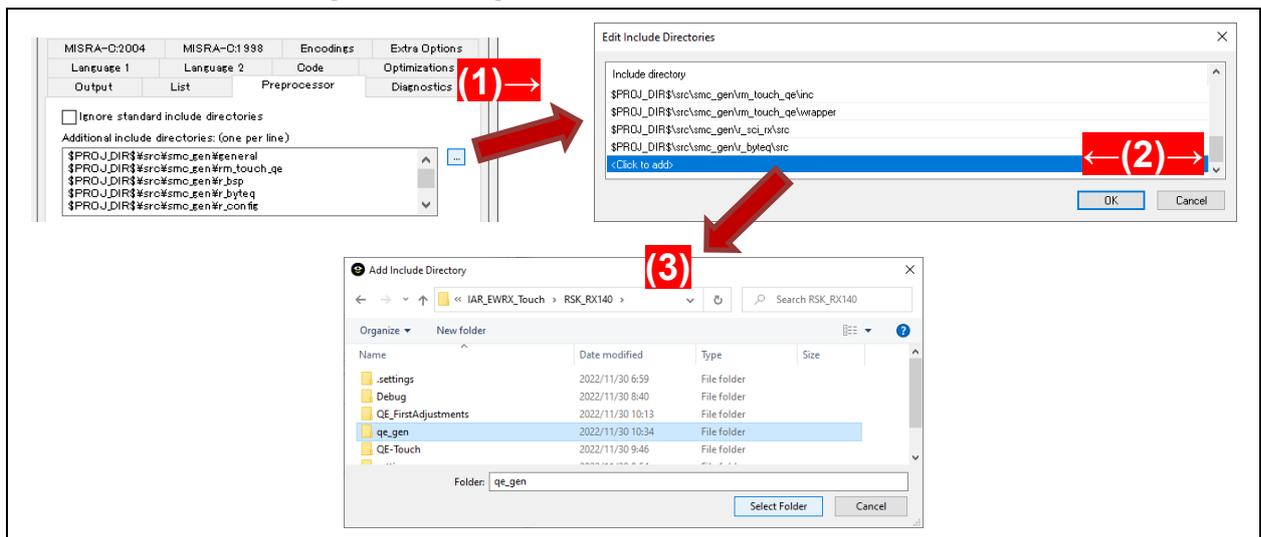


Figure 3-18 Adding an Include Directory

- (4) Change the path specification mode of the added include directory from absolute path to relative path.

Click on  in the [Edit Include Directories] dialog box and select the relative directory that starts with "\$PROJ_DIR\$". After confirming that the path has been changed to a relative path in the [Edit Include Directories] dialog box, click on [OK].

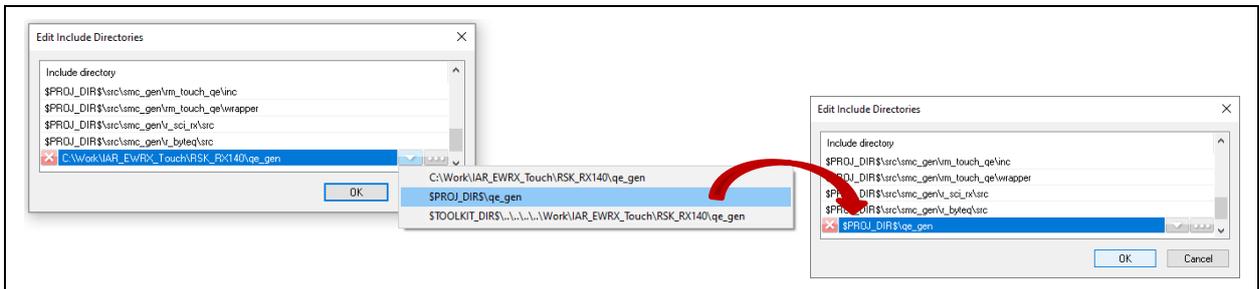


Figure 3-19 Changing the Path to the Include Directory to a Relative Path

- b. Enter "QE_TOUCH_CONFIGURATION" in [Defined symbols: (one per line)].

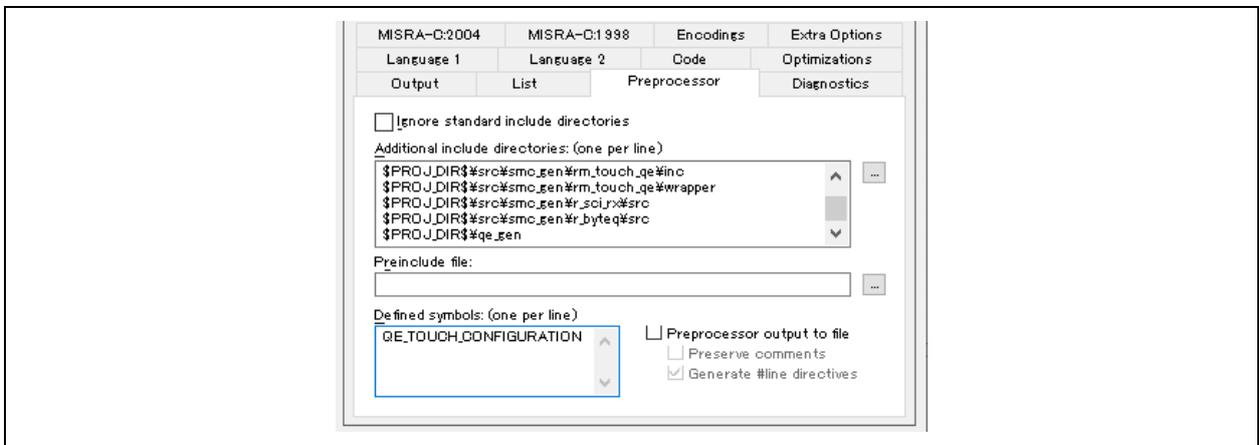


Figure 3-20 Adding a Symbol Definition

- Next, set up the debugger.
 - Select "Debugger" in [Category:] and select the [Setup] tab.
 - Click on  in [Driver:] and select "E2 Lite/EZ-CUBE2".
 - Enter "main" in [Run to:] and tick the checkbox (✓).
 - Click on [OK] to close the [Options] dialog box.

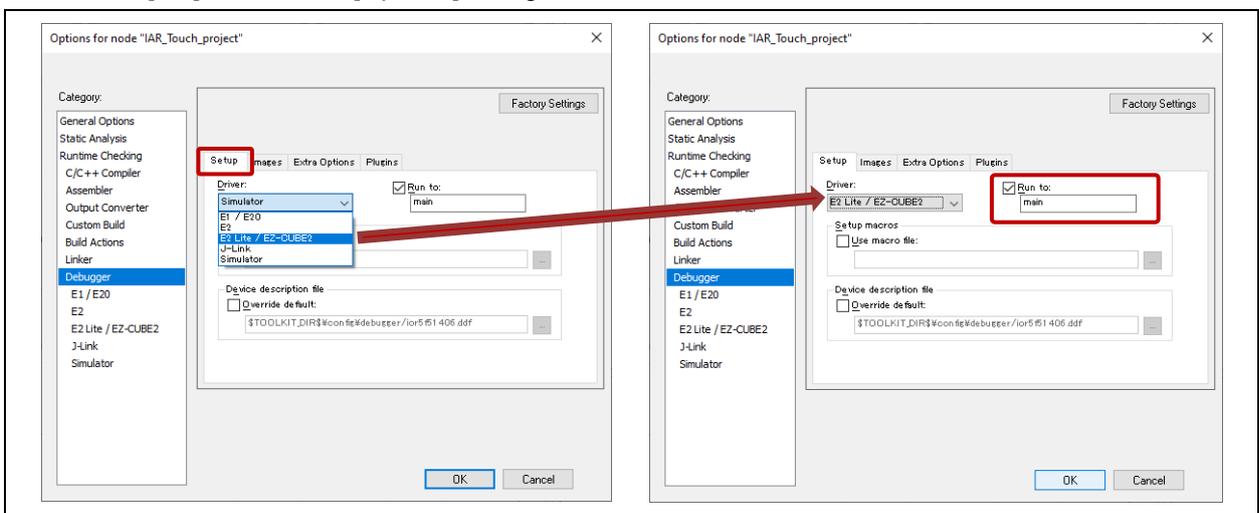


Figure 3-21 Debugger - [Setup] Tab

3. Set up the hardware.
 - a. The [E2/E2 Lite] menu will become selectable from the menu bar. Select [Hardware Setup...] from the [E2/E2 Lite] menu.

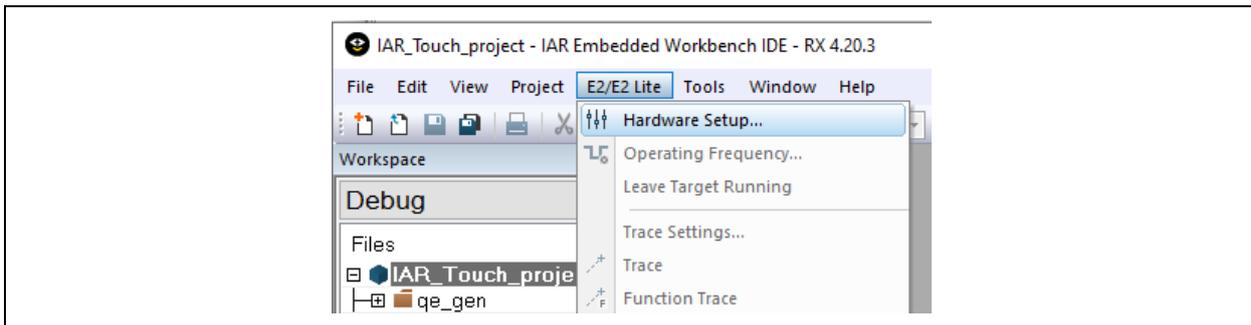


Figure 3-22 Selecting [Hardware Setup...]

- b. Select the [MCU] tab in the [Hardware Setup] dialog box and set the following items.
 - [ICLK frequency:] in [MCU] Enter "48.000".
 - [Power supply] "Power target from the emulator (MAX 200mA)"
 If the checkbox is ticked (✓), cancel the selection by clicking on the checkbox.

Click on [OK].

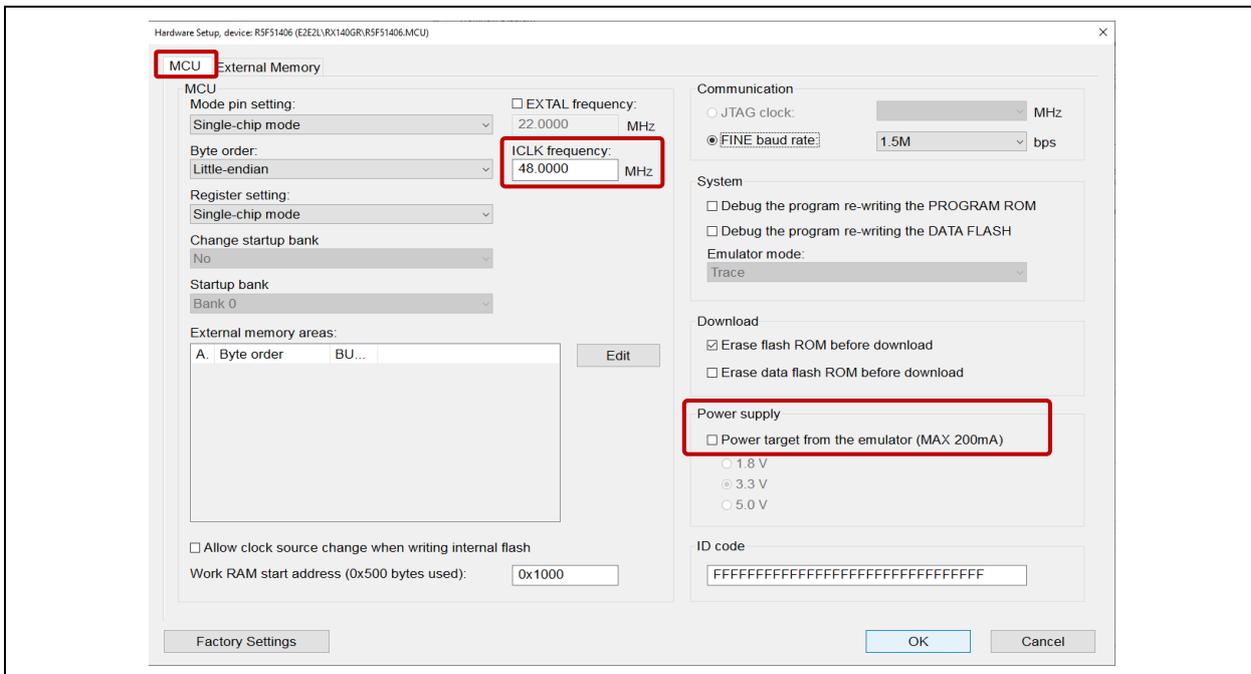


Figure 3-23 Hardware Setup - [MCU] Tab

4. Build the project with the files for tuning included.

Right-click on the project name in the [Workspace] window, then select [Rebuild All] to perform building. After building has finished, confirm that no error has occurred in the [Build] window or status bar at the bottom of the main window.

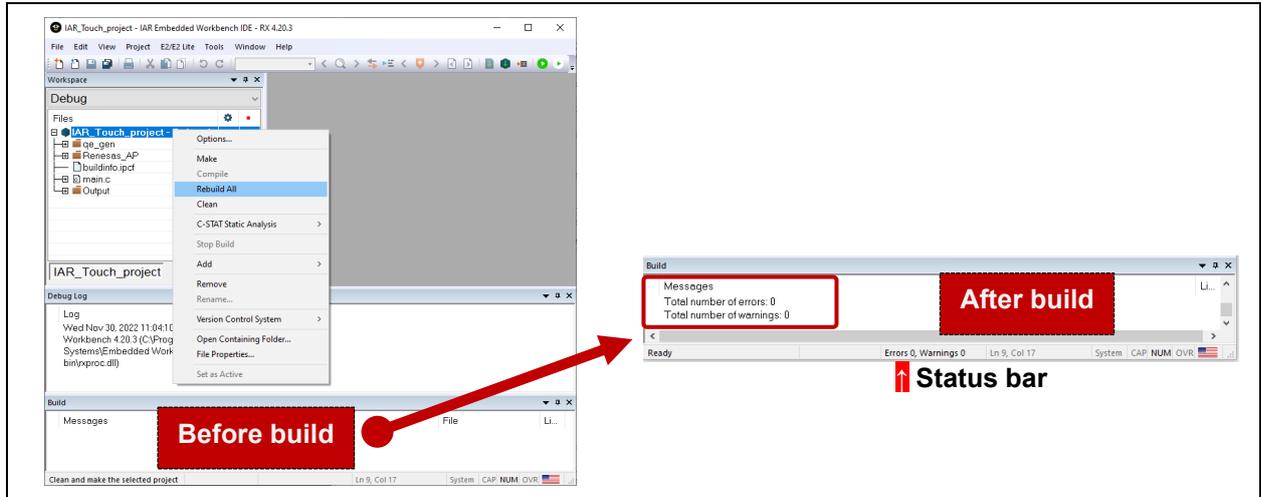


Figure 3-24 Building Including Files for Tuning

4. Tuning Touch Sensors

Connect RSK-RX140 with the host PC. Start debugging of the IAR EWRX project and perform automatic tuning processing for touch sensors in the standalone-version QE.

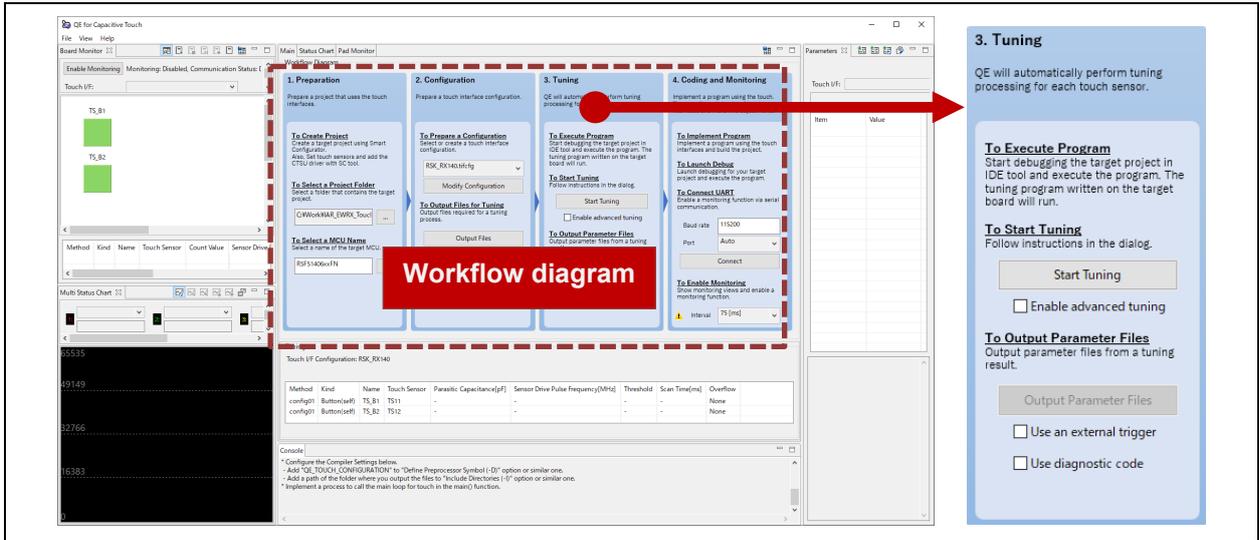


Figure 4-1 Standalone-Version QE - Workflow Diagram: <Step 3> Tuning

4.1 Connecting the RSK-RX140 Board with a PC

Connect the RSK-RX140 board with a host PC as shown in Figure 4-2. A center-positive power supply with a stabilized DC output (min. 10 W) must always be used as the power supply for connection to the board.

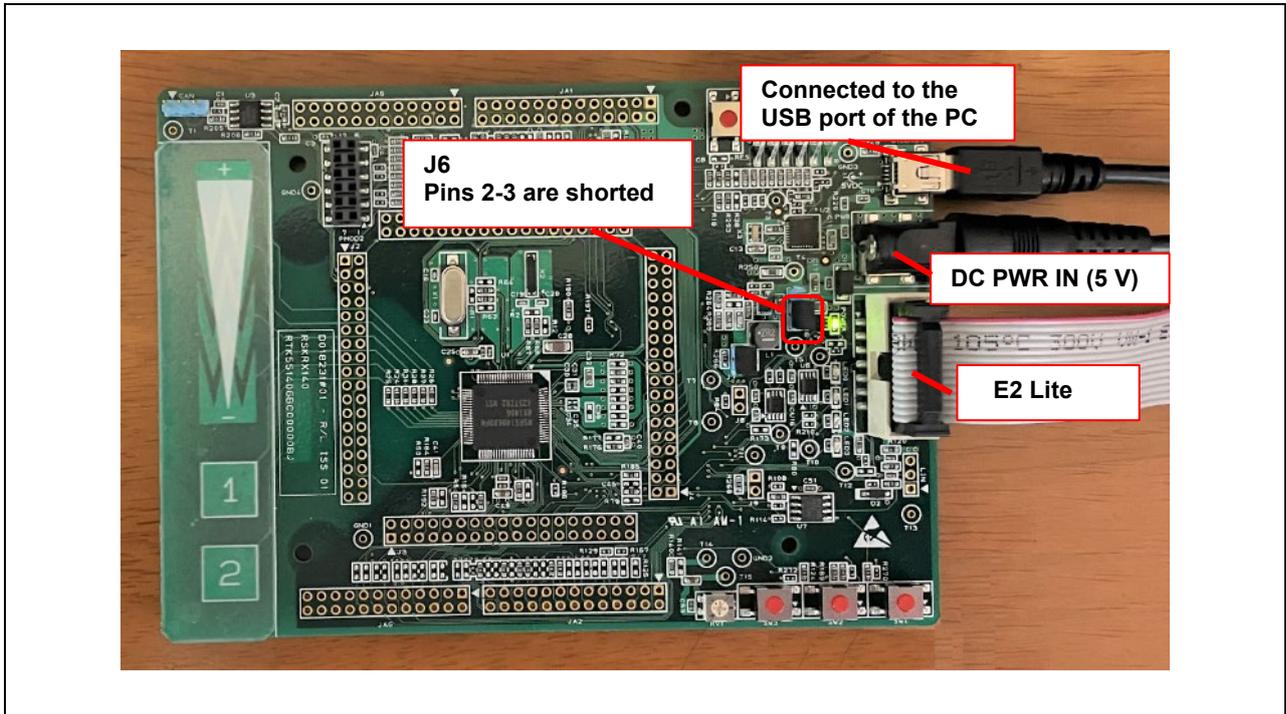


Figure 4-2 Connecting the RSK-RX140 Board

4.2 Starting Tuning

Execute the tuning program with IAR EWRX to start tuning in the standalone-version QE.

1. Execute the tuning program with IAR EWRX.
 - (1) Select [Download and Debug] from the [Project] menu and start debugging.
 - (2) After debugging has started, execution is stopped in the main() program.
 - (3) Select [Go] from the [Debug] menu and start execution.

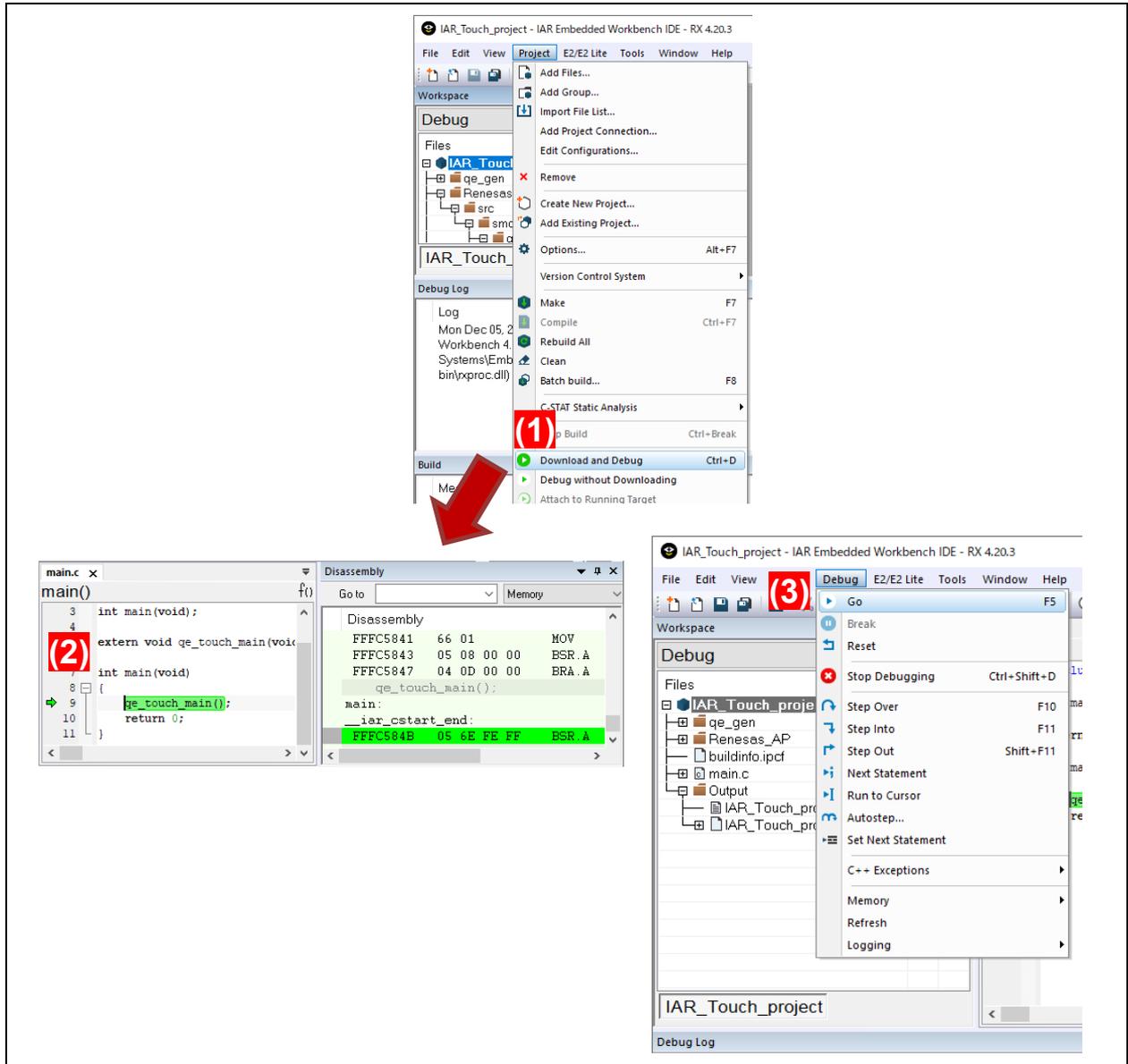


Figure 4-3 <Step 3> Tuning: Executing the Program

2. Start automatic tuning in the standalone-version QE.

Click on [Start Tuning] in the workflow to start automatic tuning in the standalone-version QE. For the interactive steps in automatic tuning processing, follow the instructions in the dialog box that provides guidance.

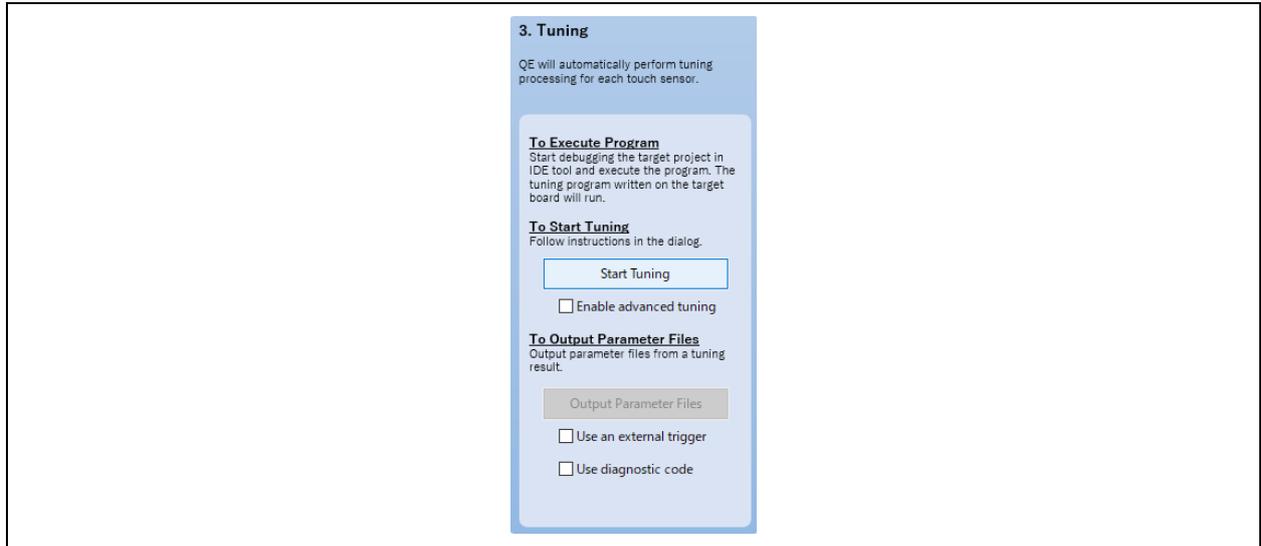


Figure 4-4 Automatic Tuning Processing

a. Confirm the "Automatic Tuning Processing" dialog box for guidance in the automatic tuning process as required. Normally, no manipulations are required during the initial stages of tuning.

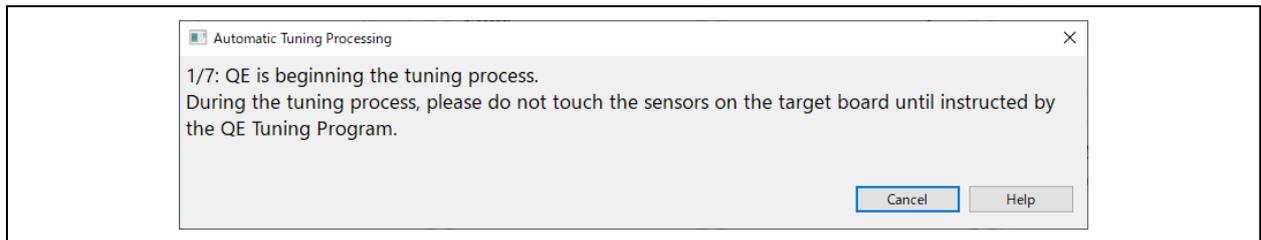


Figure 4-5 "Automatic Tuning Processing" - Initial Tuning

- b. If the touch sensitivity has been found to be measurable after a number of automated steps, a dialog box with a notification similar to that shown in the figure below will appear. This is the first interactive step in the tuning process.
- Touch the sensor (TS_B1/TS11) that is indicated in the dialog box.
 - While touching the sensor, the bar graph will grow to the right and the counted numerical value will increase.
 - While continuing to touch the sensor, press any key on the PC keyboard to secure the measured value.

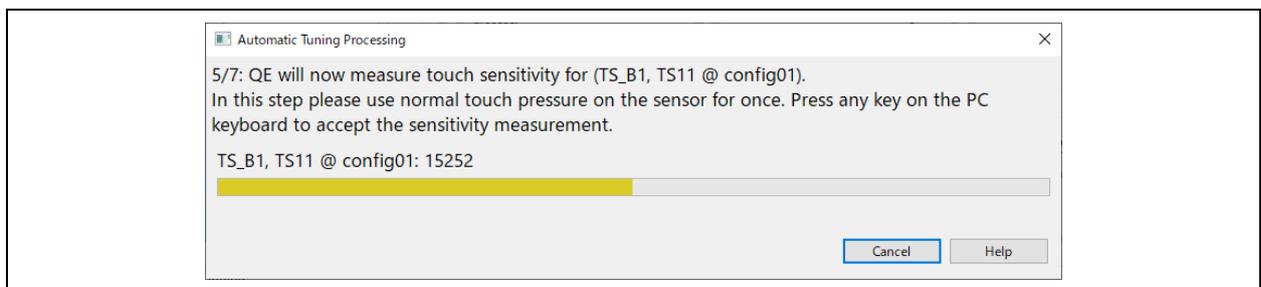


Figure 4-6 "Automatic Tuning Processing" - Measuring the Touch Sensitivity (TS_B1)

- c. Repeat the previous procedure for TS_B2/TS12.

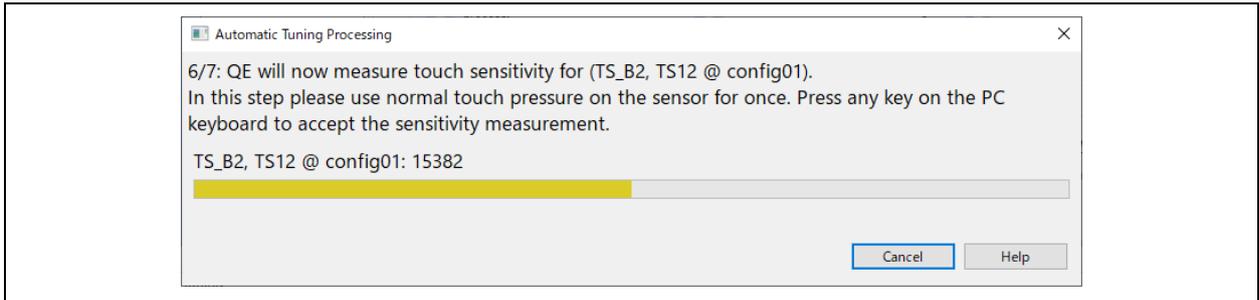


Figure 4-7 "Automatic Tuning Processing" - Measuring the Touch Sensitivity (TS_B2)

- d. Once automatic tuning has been completed for both buttons, the thresholds can be checked in a dialog box like that shown below. These thresholds are used by the middleware to determine if touch events have occurred.

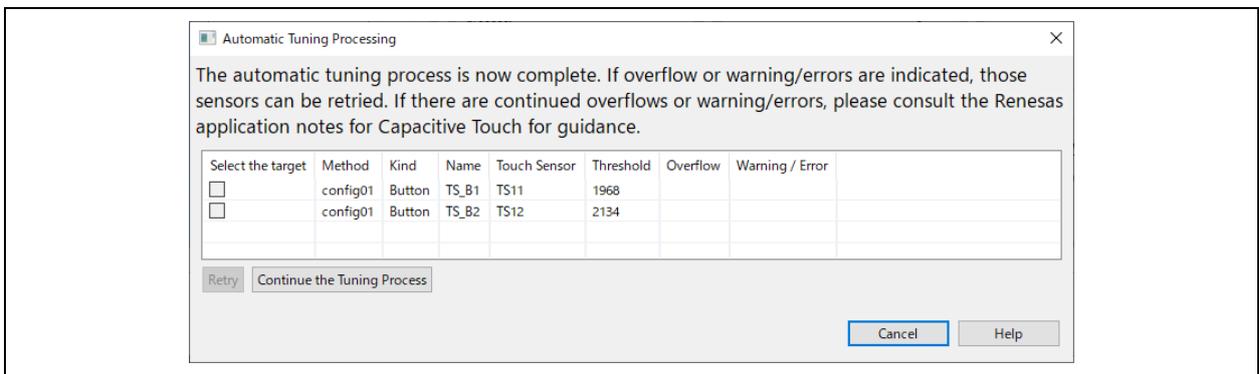


Figure 4-8 "Automatic Tuning Processing" - Displaying the Measurement Results

- 3. Stop tuning.

Click on the [Continue the Tuning Process] button in the dialog box that shows the thresholds of the touch sensors. The automatic tuning process is finished at this point and the debug session with the target board is cut off.

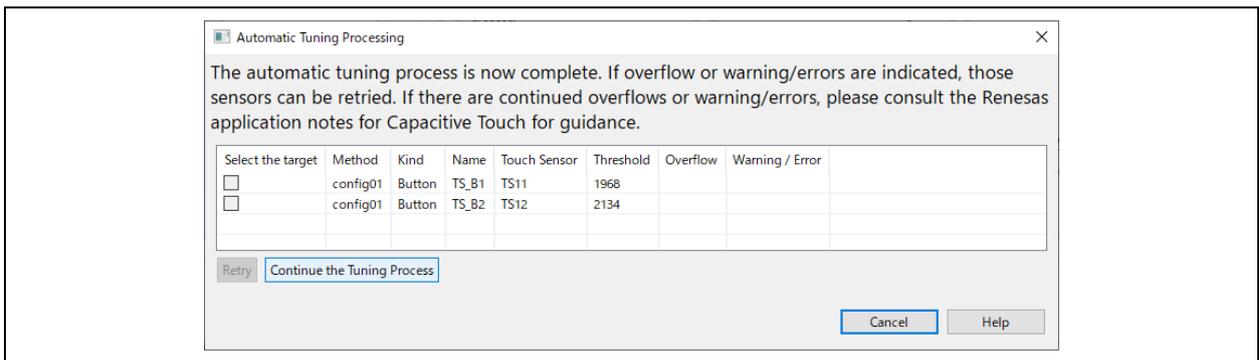


Figure 4-9 "Automatic Tuning Processing" - Continuing the Tuning Process

4.3 Acquiring the Tuning Result

Acquire the tuning result in the standalone-version QE.

1. Stop debugging of IAR EWRX.
Select [Stop Debugging] from the [Debug] menu.

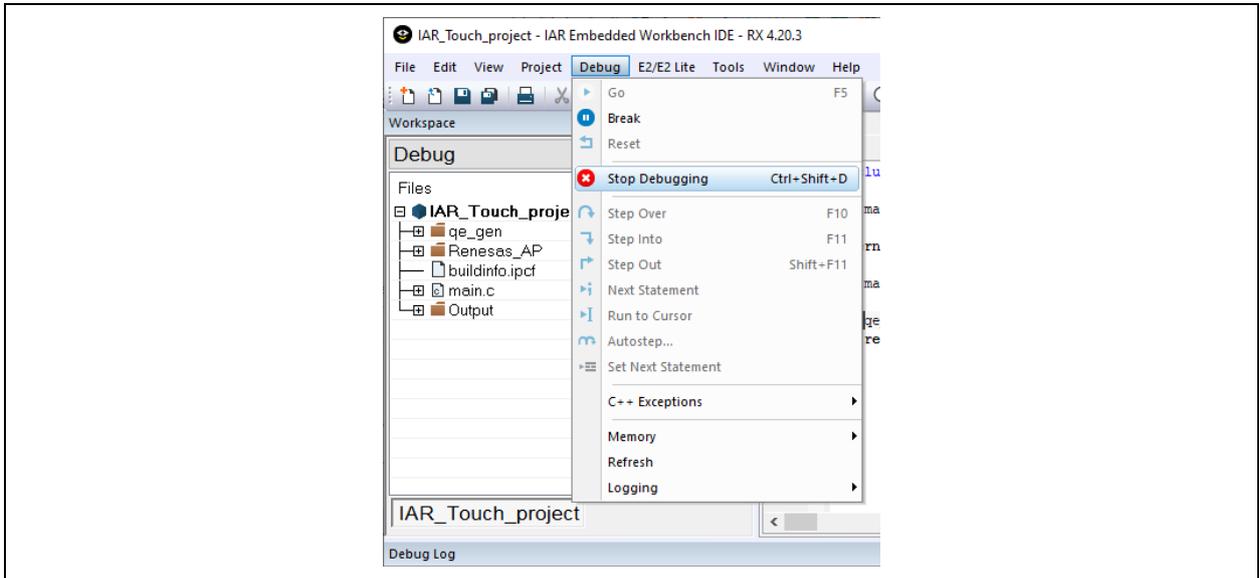


Figure 4-10 Tuning Related

2. Click on the [Output Parameter Files] button in the standalone-version QE.
In the "The output folder of parameter files" dialog box, select a folder and click on [Select Folder]. In the example below, the "qe_tuning_r1" folder was created in advance so it could be selected here.

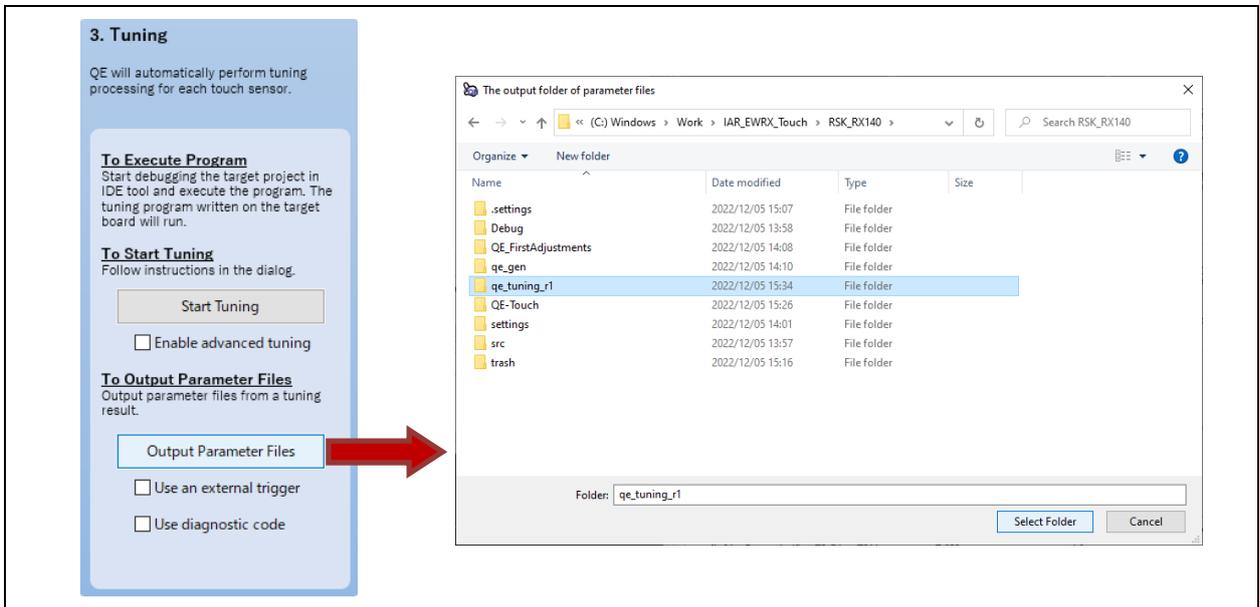


Figure 4-11 Outputting the Tuning Result

3. Reflect the values from tuning of the touch interfaces in the IAR EWRX project.
Open the folder where the files are saved and copy the following three files to the "qe_gen" folder in the workspace folder. If the file contents before tuning are unnecessary, overwrite the files. If the file contents are necessary, save the files before performing copy.

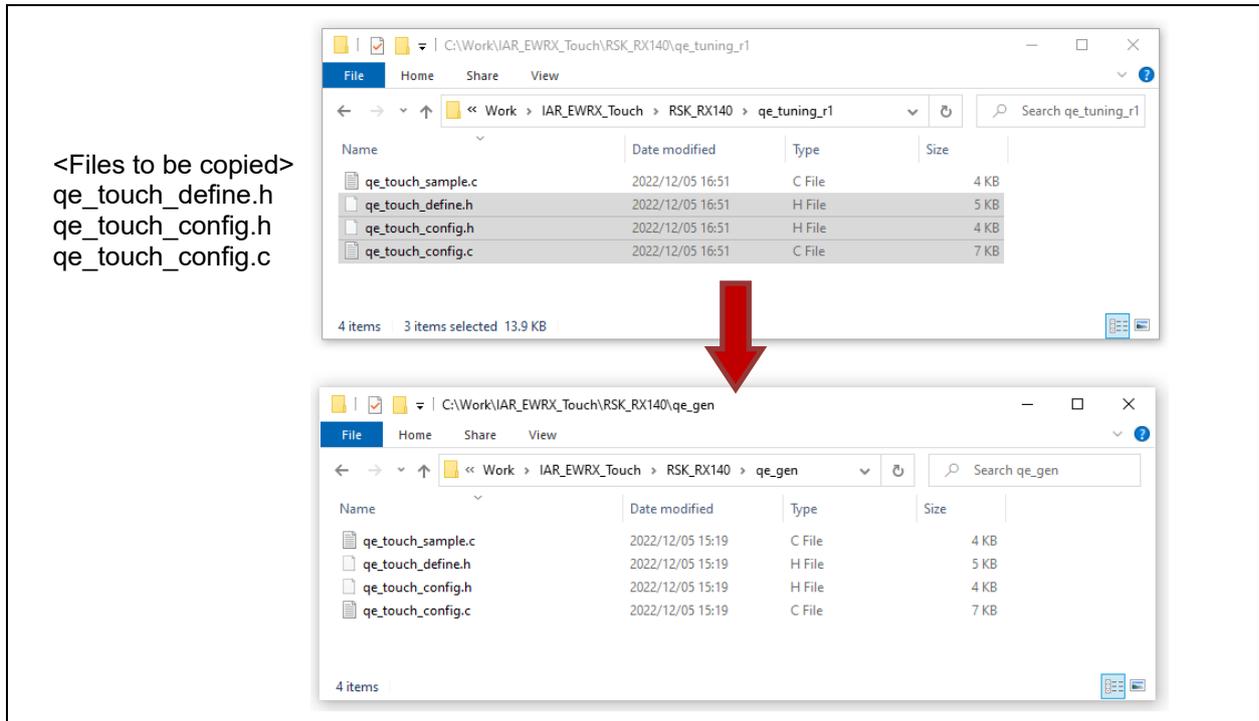


Figure 4-12 Copying the Files with Tuned Values

4. Build the IAR EWRX project and generate modules in which the tuned values of touch interfaces are reflected. For the method of building, refer to section 3.4.4.

5. Coding and Monitoring

Using the module of section 4.3 4 that was built with the parameter files obtained in automatic tuning processing, perform monitoring in the standalone-version QE. A facility for scanning the state of touch sensors is implemented in a function included in "qe_touch_sample.c", which is a tuning file obtained in "2. Configuration" of the workflow diagram of the standalone-version QE. Operation can be checked through monitoring without any particular requirements to change the program code.

5.1 Monitoring

Execute the program built with IAR EWRX, according to the procedure in section 4.2.1.

1. Start monitoring.

Click on the [Connect] button under "To Connect UART" in the workflow diagram. Wait for a while until connection is completed.

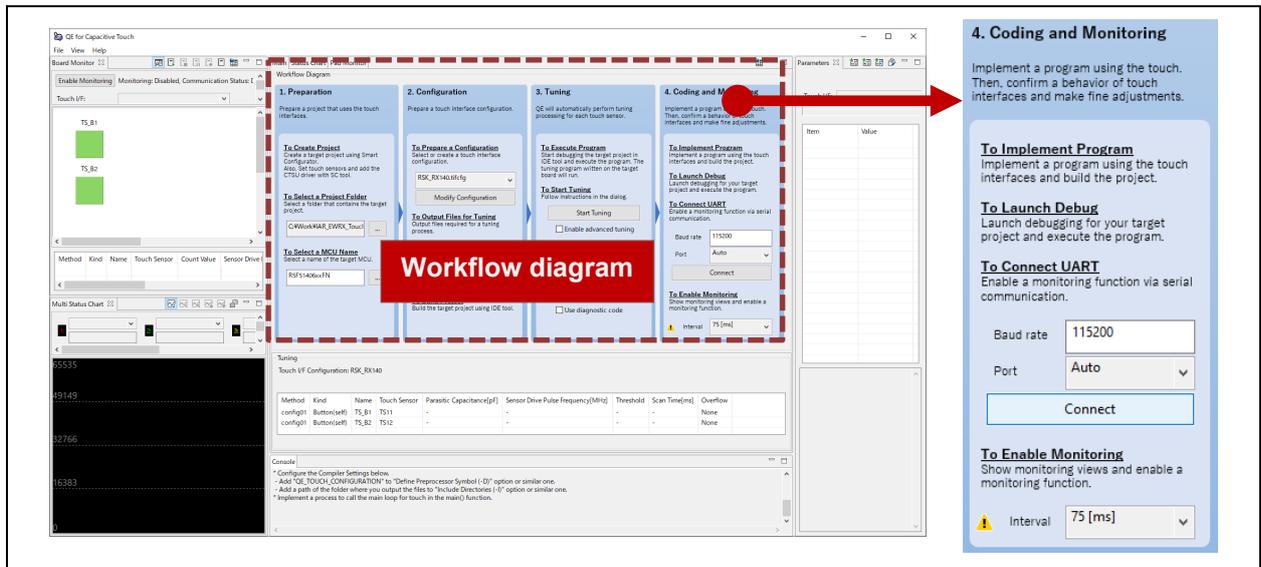


Figure 5-1 <Step 4> Coding and Monitoring: Connect

2. When connection is established, "Connecting via serial communication (UART/USB)" is displayed for "Communication Status" in the Board Monitor view.

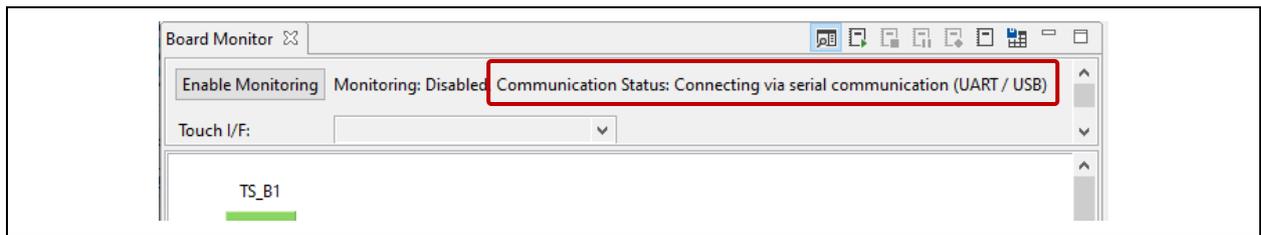


Figure 5-2 State of Serial Communications

- Click on [Enable Monitoring]. The display is switched between "Monitoring: Disabled" and "Monitoring: Enabled".

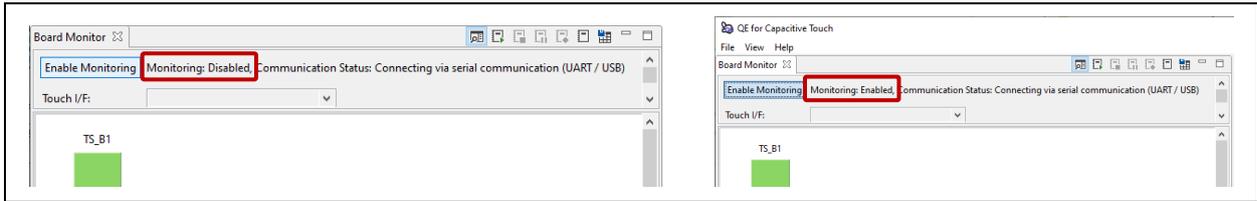


Figure 5-3 Enabling the Monitoring Function

- Touch the button TS_B2 on the target board. In the Board Monitor view, a finger icon on the button like that in the image below indicates that the button is being touched.

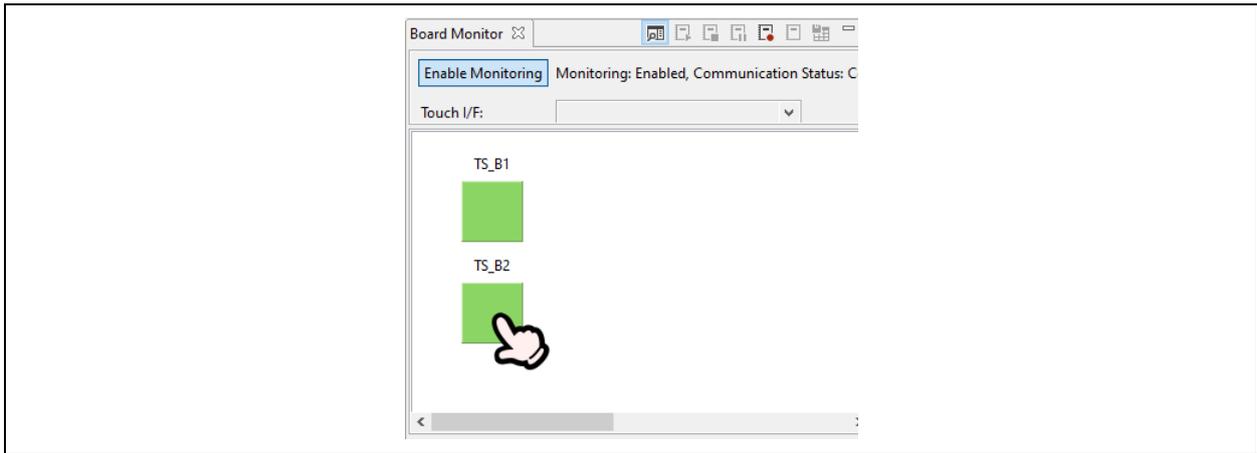


Figure 5-4 Board Monitoring: Finger Icon

- To see a graphical representation of the counted values, click on the [Status Chart] tab as shown below.



Figure 5-5 Selecting the [Status Chart] Tab

— Select "TS_B1@ config01" from the pull-down menu.

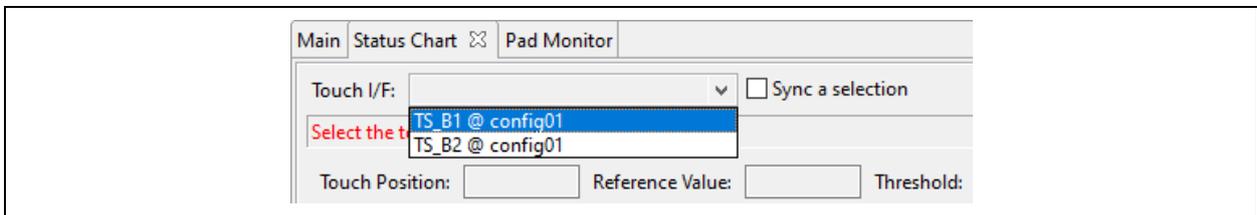


Figure 5-6 Selecting "Touch I/F"

- The graph will begin to display a running depiction of the values. The increases in the counted values while the TS_B1 button on the target board is being touched can be confirmed from the graph. The green line indicates the threshold, which is used by the "rm_touch_qe" FIT module to determine whether the button is being actuated, that is, touched. The red belt at the bottom of the graph indicates the periods over which the counted value was exceeding the threshold so that the button is judged to have been touched.

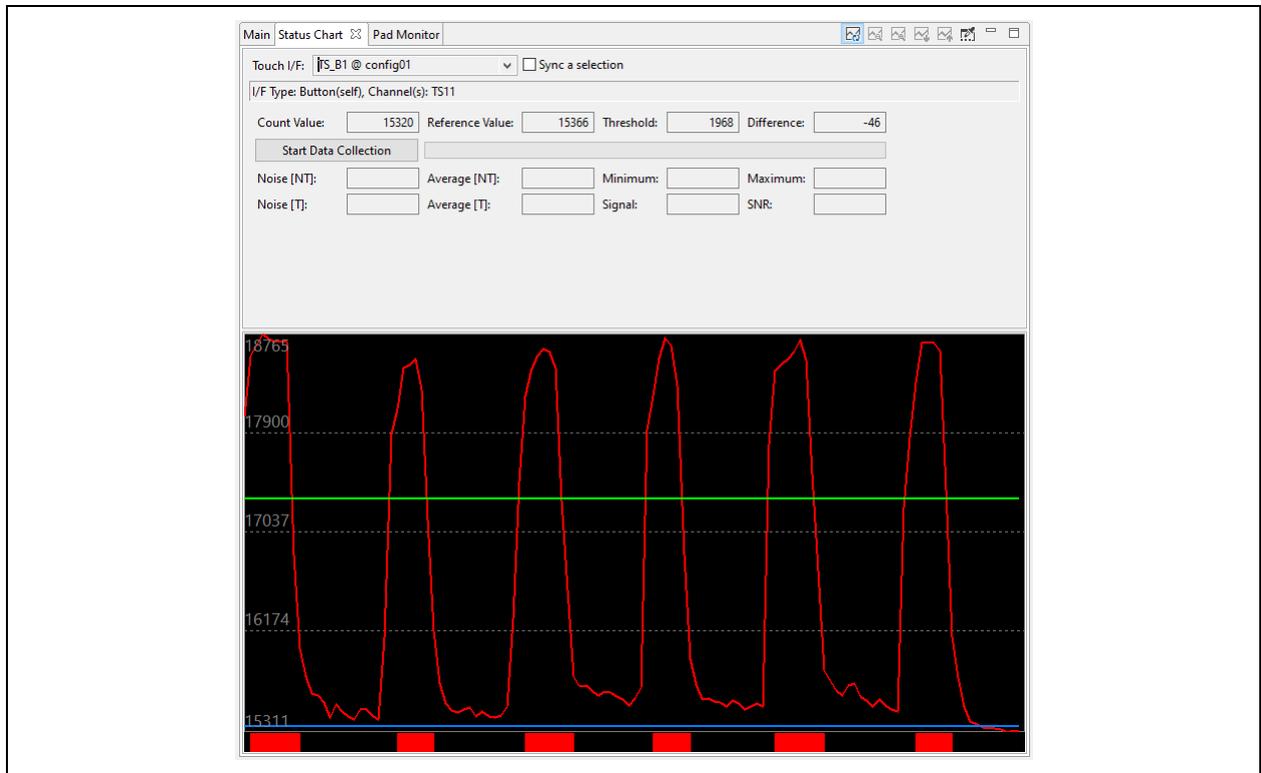


Figure 5-7 [Status Chart] Tab

- To see a graphical representation of counted values that indicate multiple touch sensors being touched, use the [Multi Status Chart] tab. It will be displayed when the touch interface is selected.

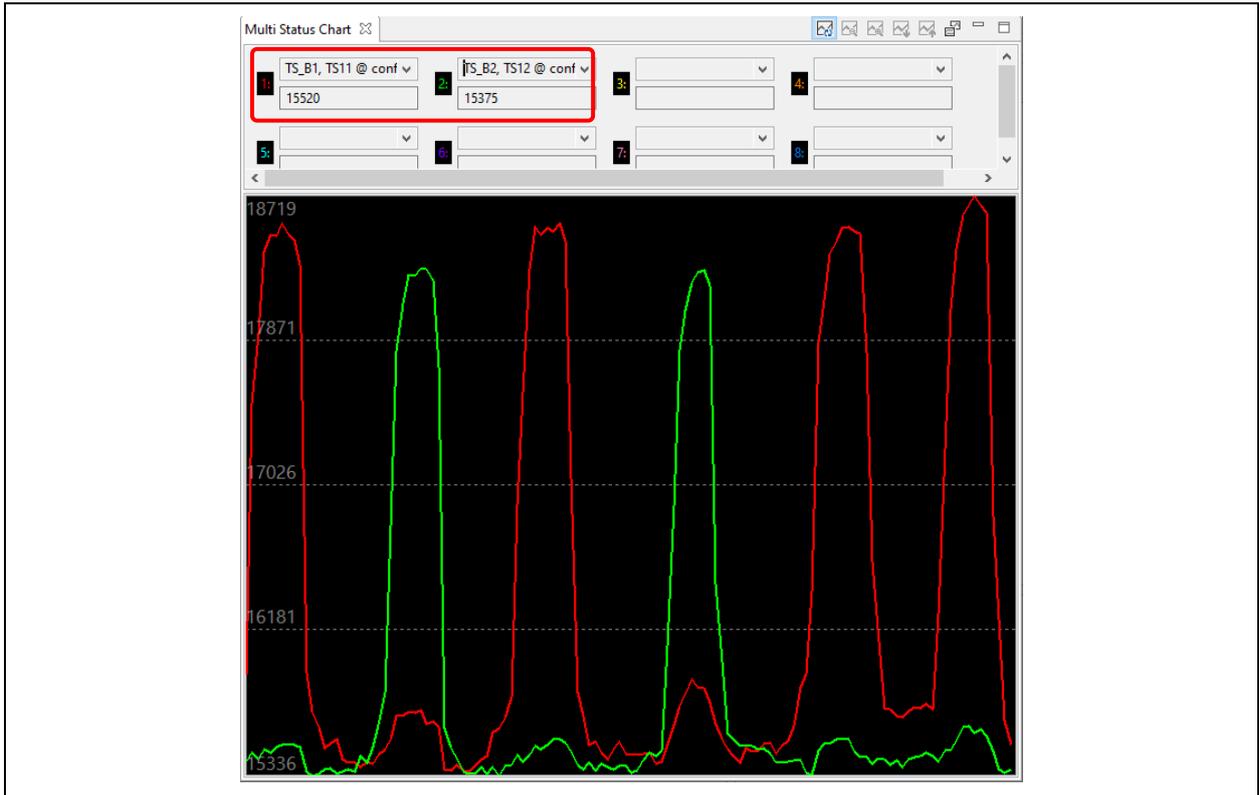


Figure 5-8 [Multi Status Chart] Tab

5.2 Disconnecting Serial Communications

- Stop monitoring.

When the monitoring function is enabled, click on [Enable Monitoring] and confirm that the monitoring function has become disabled.

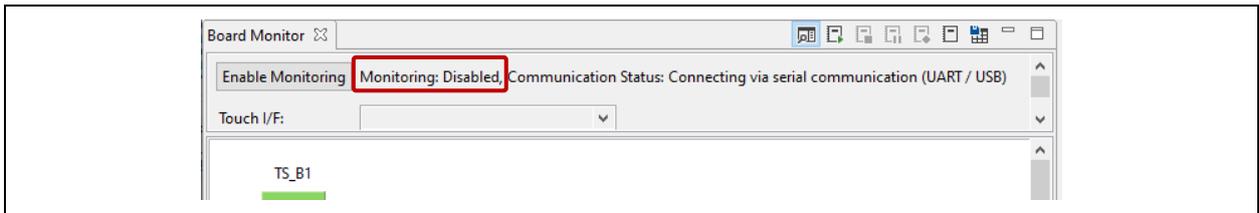


Figure 5-9 State of Serial Communications

2. Disconnect the serial connection.

Click on the [Disconnect] button under "To Connect UART" under "4. Coding and Monitoring" of the workflow diagram. When disconnection is completed, "Disconnected from \\.\COMx." is displayed in the Console view, and the label on the [Disconnect] button changes to [Connect].

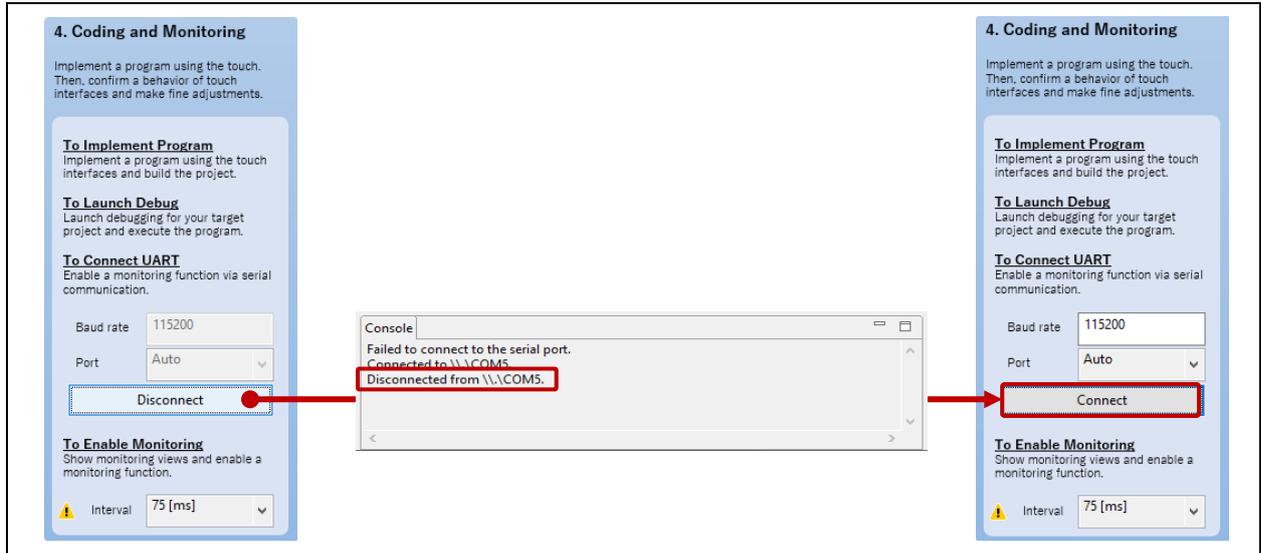


Figure 5-10 <Step 4> Coding and Monitoring: Disconnect

Revision History

Rev.	Date	Description	
		Page	Summary
1.00	Dec.22.22	—	First edition issued

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity.

Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

6. Voltage application waveform at input pin

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).

7. Prohibition of access to reserved addresses

Access to reserved addresses is prohibited. The reserved addresses are provided for possible future expansion of functions. Do not access these addresses as the correct operation of the LSI is not guaranteed.

8. Differences between products

Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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