

RA4M2 Group

Voice Recognition Demonstration (Voice Trigger Middleware)

Introduction

This application note explains Voice Recognition demonstration using a word-based voice recognition library "Voice Trigger Middleware" (TOSHIBA DIGITAL SOLUTIONS CORPORATION) and Zoom Voice (Techno Mathematical Co., Ltd.) which is a library featuring noise suppressing and beamforming(optional) technology.

Target Device

RA4M2 Voice Recognition ECM Demo Board (RTK0EA0006D00001BJ)

Related Documents

- 1. RA4M2 Voice Recognition Demo Board (R12AN0117EJ0100)
- 2. RA4M2 Group Voice Recognition Sample software (Voice Trigger Middleware) (R11AN0540EJ0100)

Voice Trigger middleware is a product of TOSHIBA DIGITAL SOLUTIONS CORPORATION, and is referred to in this document as "Voice Trigger."

Zoom Voice is a product of Techno Mathematical Co., Ltd. (TMC)

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1. Outline

This demonstration realize the Voice Recognition using word voice recognition library 'Voice Trigger' and noise suppressor and beamforming (optional) library 'Zoom Voice'.

Figure 1.1 shows demo configuration.

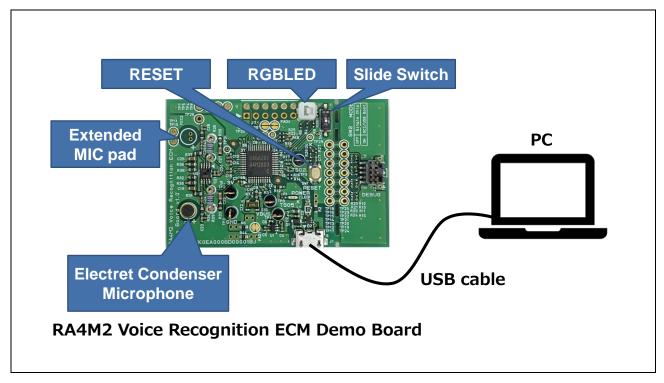


Figure 1.1 Demo configuration

2. Demo operation

Demo operation procedure is explained as below.

2.1 Power supply

The power supply for this demonstration is supplied via USB microB connector.

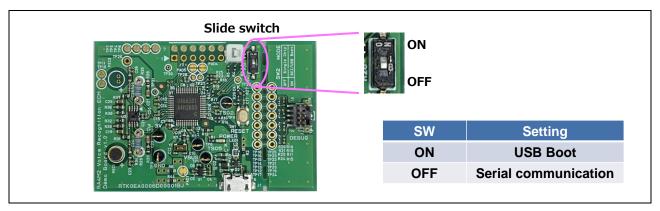
USB 5V supply capable USB AC adopter, mobile battery and PC can be used for power supply.

If you use a PC, you can use the terminal software to display the recognition results and change settings. (The recognition result can be checked by the RGB LED on the board without running the terminal software.)

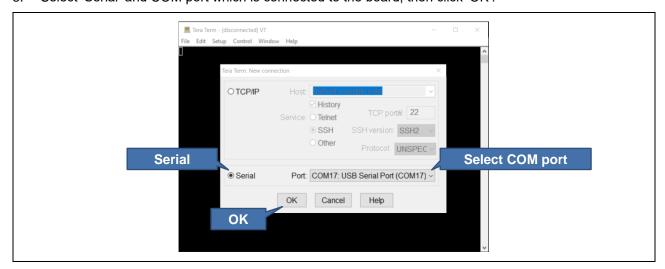
2.2 Terminal software setting

This section shows the setup of the terminal software (Tera Term) when connected to a PC.

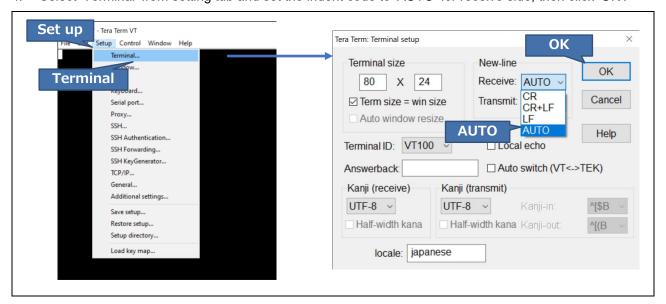
1. Turn off the slide switch on the board and connect the board to the PC via USB.



- 2. Start Tera Term.
- 3. Select 'Serial' and COM port which is connected to the board, then click 'OK'.



4. Select 'Terminal' from setting tub and set the indent code to 'AUTO' for receive side, then click 'OK'.



3. Demo procedure

Start demonstration by talking to the demo board.

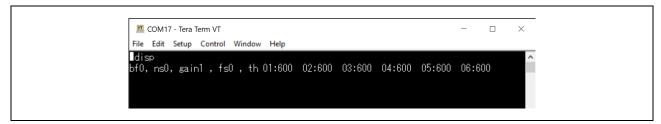
3.1 Voice Command

Refer Chapter4 for recognizable voice command and action according to the recognition result.

3.2 Display on PC

Below shows display example of TeraTerm. Refer Chapter4 for detail.

· Display the settings



· Display the recognition results



4. Functions

The function of this demonstration are as below.

- 1. Get audio input data from microphone
- 2. Noise suppression, beamforming (optional) and voice recognition processing
- 3. Turn ON the RGB LED
- 4. Transfer operation information via USB

4.1 Recognizable voice and actions by recognition results

When demo starts, the RGB LED is OFF and turns ON when the voice is recognized by Voice Trigger.

After utterance detection, demo operates by recognition result as listed Table 4.1.

Table 4.1 Recognizable voice and actions by recognition results

ID	Voice command	Acti	vity
ID	voice command	RGB LED	USB
1	OK TOSHIBA	Red on	Send results
2	Turn on the power	Green on	Send results
3	Sleep mode	Blue on	Send results
4	4 Continuous Purple on Ser		Send results
5 Quiet mode Purple on		Purple on	Send results
6	Stop swing	Purple on	Send results

4.2 Voice recognition setting on the terminal software

This demo can change setting and display of both Voice Trigger and Zoom Voice on terminal software (Tera Term).

Changeable conditions are as below.

- Condition1 Beamfoming reduction amount of Zoom Voice (optional)
- Condition2 Noise reduction of Zoom Voice
- Condition3 Amplification width of voice data
- Condition4 Number of flame skip of Voice Trigger
- Condition5 aThreshold value of Voice Trigger

4.2.1 Parameter display

To display current parameter, input 'disp' on TeraTerm and press Enter key.

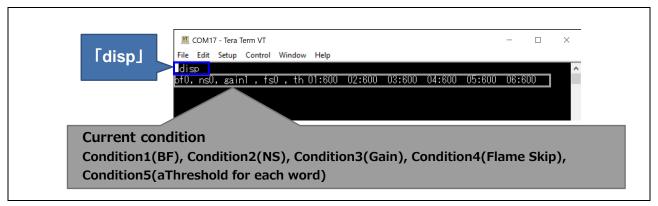


Figure 4.1 Parameter display

4.2.2 Parameter setting

To change the parameter setting, input the condition you want to change and value on Tera Term, then press Enter key.

Refer Chapter 4.2.3 for detail information.

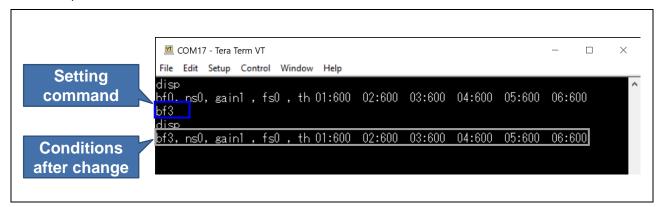


Figure 4.2 Parameter setting

4.2.3 Parameter setting command

This section describes the conditions you want to change and how to enter the changed values.

Change Zoom Voice Beamforming reduction amount (optional)
Zoom Voice Beamforming amount can be changed by inputting number 0 to 7 after 'bf'.

Note: To use beamforming in this demo, a microphone must be mounted on the expansion microphone connector, and software changes must be made. For more information about the beamforming function, please contact your <u>sales</u>.

Table 4.2 Zoom Voice Beamfoming reduction change

Setting	Changeable condition	String input to Tera Term
1	Function OFF	bf0
2	1	bf1
3	2	bf2
4	3	bf3
5	4	bf4
6	5	bf5
7	6	bf6
8	7	bf7

Change Zoom Voice noise reduction amount
Zoom Voice noise reduction can be changed by inputting number 0 to 9 after 'ns'.

Table 4.3 Zoom Voice noise reduction change

Setting	Changeable condition	String input to Tera Term
1	Function OFF	ns0
2	1	ns1
3	2	ns2
4	3	ns3
5	4	ns4
6	5	ns5
7	6	ns6
8	7	ns7
9	8	ns8
10	9	ns9

Change amplification width of voice data
To change amplification width of voice data, input number 0 to 9 after 'gain'.

Table 4.4 Amplification width of voice data change

Setting	Changeable condition	String input to Tera Term
1	Function OFF	gain0
2	1	gain1
3	2	gain2
4	3	gain3
5	4	gain4
6	5	gain5
7	6	gain6
8	7	gain7
9	8	gain8
10	9	gain9

Change Number of flame skip of Voice Trigger
To change the number of flame skip of Voice Trigger, input number 0 to 16 after 'fs'.

Table 4.5 Change number of flame skip of Voice Trigger

Setting	Changed value	String input to Tera Term
example	16	fs16

Change aThreshold value of Voice Trigger
To change the value of utterance detection threshold, input number 0 to 1000 as below in order to set per each word.

Table 4.6 Change aThreshold value of Voice Trigger

Setting	Changed value	String input to Tera Term
Example 1	Change the aThreshold value of ID3 word to 550	th03:550
Example 2	Change the aThreshold value of all word to 700	th00:700

Revision History

		Descript	ion
Rev.	Date	Page	Summary
1.00	Aug.31.21	-	First release

General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Precaution against Electrostatic Discharge (ESD)

A strong electrical field, when exposed to a CMOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop the generation of static electricity as much as possible, and quickly dissipate it when it occurs. Environmental control must be adequate. When it is dry, a humidifier should be used. This is recommended to avoid using insulators that can easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors must be grounded. The operator must also be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions must be taken for printed circuit boards with mounted semiconductor devices.

2. Processing at power-on

The state of the product is undefined at the time when power is supplied. The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the time when power is supplied. In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the time when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the time when power is supplied until the power reaches the level at which resetting is specified.

3. Input of signal during power-off state

Do not input signals or an I/O pull-up power supply while the device is powered off. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Follow the guideline for input signal during power-off state as described in your product documentation.

4. Handling of unused pins

Handle unused pins in accordance with the directions given under handling of unused pins in the manual. The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of the LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible.

5. Clock signals

After applying a reset, only release the reset line after the operating clock signal becomes stable. When switching the clock signal during program execution, wait until the target clock signal is stabilized. When the clock signal is generated with an external resonator or from an external oscillator during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Additionally, when switching to a clock signal produced with an external resonator or by an external oscillator while program execution is in progress, wait until the target clock signal is stable.

- 6. Voltage application waveform at input pin
 - Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (Max.) and V_{IH} (Min.) due to noise, for example, the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (Max.) and V_{IH} (Min.).
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- 8. Differences between products
 - Before changing from one product to another, for example to a product with a different part number, confirm that the change will not lead to problems. The characteristics of a microprocessing unit or microcontroller unit products in the same group but having a different part number might differ in terms of internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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