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M16C Family

How to Generate Variable Resolution PWM Using IAR C-Compiler

Introduction

This application note describes how to make use of the M16C family of microcontrollers one shot Timer mode to generate user defined PWM resolution.

M16C devices are able to automatically generate 5 independent PWM outputs. This is called the timer A PWM mode, but these have fixed selectable resolution of 8 or 16bit. The 8bit PWM mode can achieve high frequencies (up to 93KHZ) with a relatively low resolution while the 16bit PWM mode is high resolution but quite low frequency (typically $f_{Xin}/65536$) ranging from a few HZ to a maximum of 366HZ.

Many applications may need to have resolutions higher than 8bit, with higher PWM frequency than 16bit resolution can achieve. Therefore this application note explains how M16C is initialized in order to generate a 10bit resolution PWM without any CPU load, external hardware or extra MCU pin usage.

Contents

HOW TO GENERATE VARIABLE RESOLUTION PWM USING IAR C-COMPILER	1
INTRODUCTION	1
CONTENTS	1
OPERATION MODE.....	2
TIMER A BLOCK STRUCTURE.....	3
TIMER A ONE SHOT MODE	3
1. OPERATION TIMING OF TIMER A ONE-SHOT MODE	4
2. TIMER A REGISTERS.....	4
SOFTWARE DESCRIPTION	6
CONCLUSION.....	6
CODE.....	6
WEBSITE AND SUPPORT	8

Operation mode

M16C family processors have two Timer groups which are group A and group B. For any of the M16C devices a minimum of three type B timers and five type A timers are integrated (M16C6x and M32C have six B type timers).

Please note that only type A timers have output function which restricts output signal generation to these timers only.

The B group timers can be used to measure external signals and/or generate internal signals as well as interrupts.

Of the group B timers, timer B2 (TB2) internal overflow output is distributed (and made available) to the group A timers which makes it useful for this application note.

In this application note Timer A3 (TA3) has been chosen to generate the PWM output signal but any other group A timer could be used as well as they all have TB2 as trigger source. TA3 is programmed in one shot timer mode triggered by TB2. No external connection is needed which allows to optimise the pin usage.

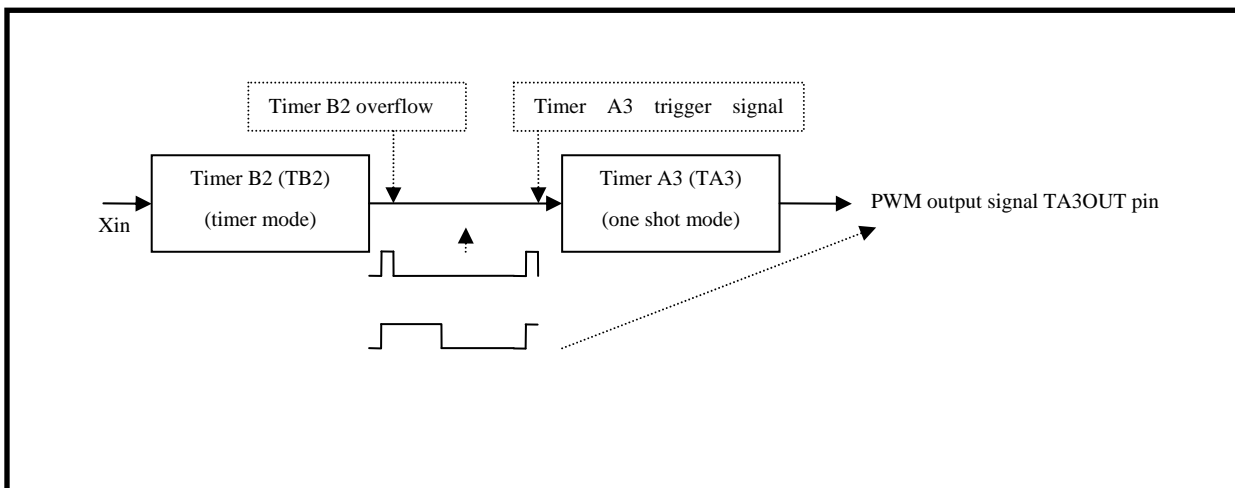
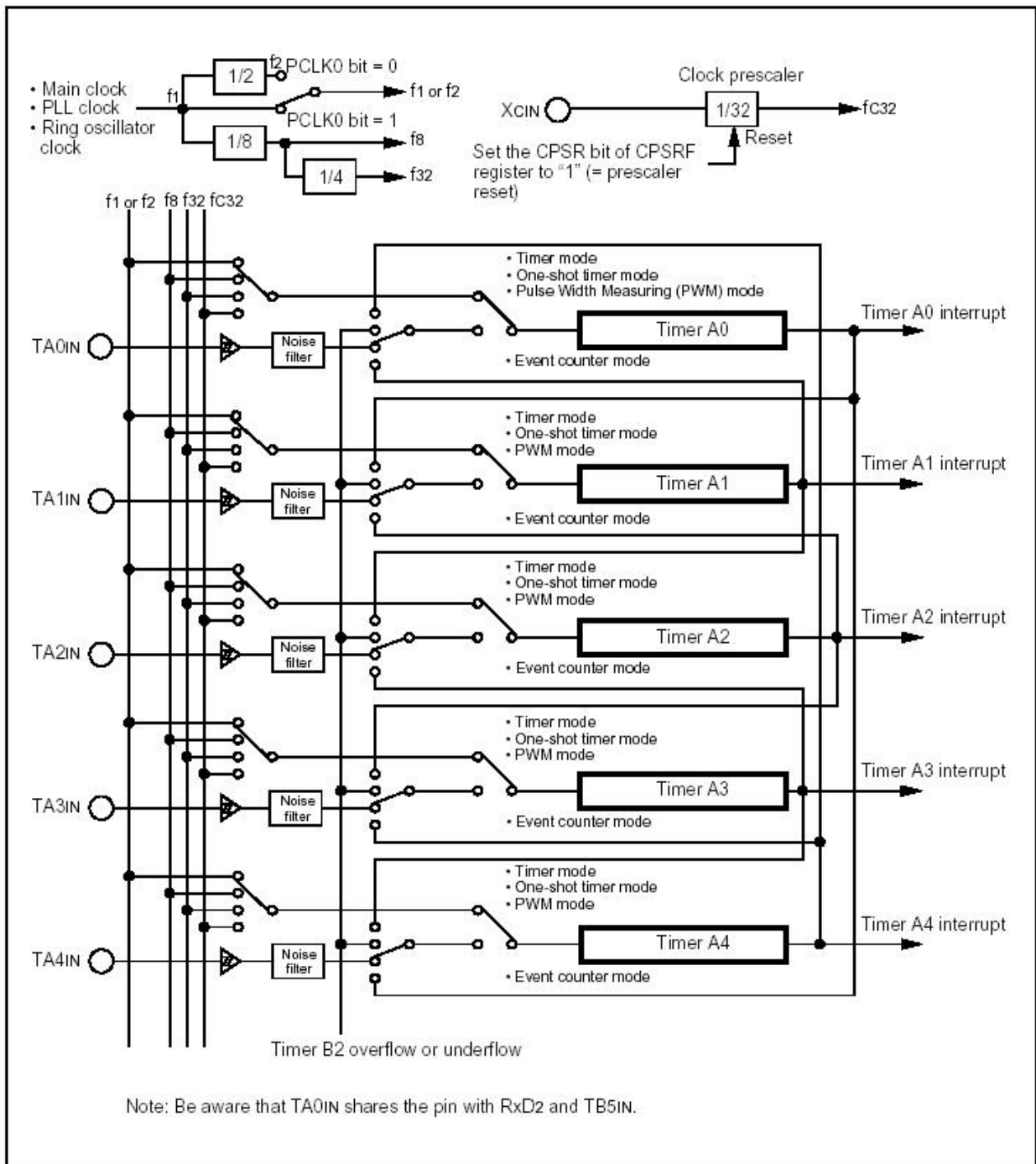


Fig 1.

Timer A block structure



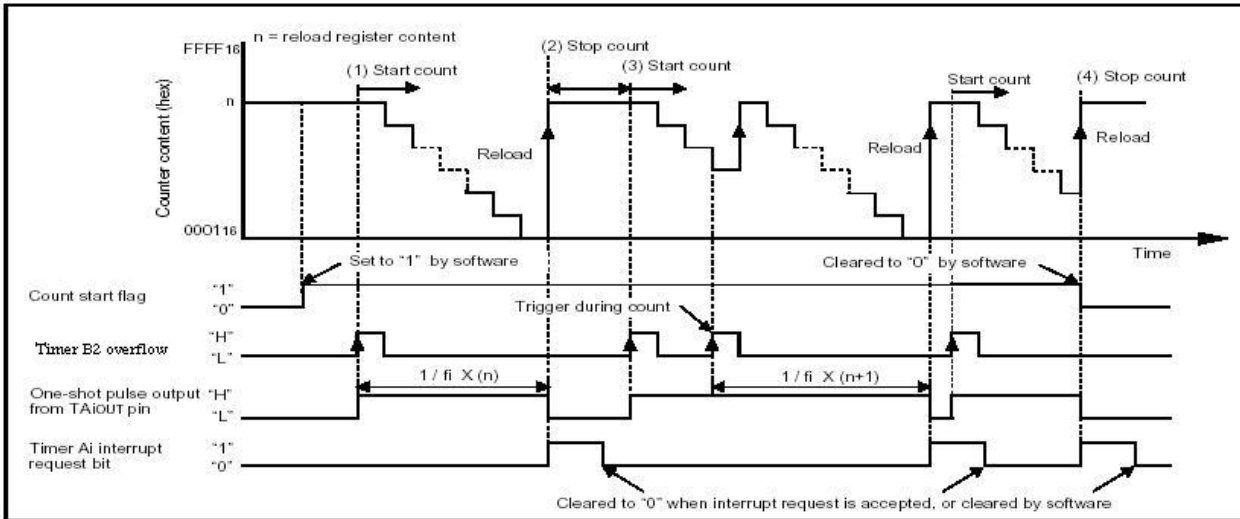
Timer A Configuration

Timer A one shot mode

Once initialized, every time TA3 is triggered by TB2 overflow the TA3OUT pin goes to high state and the counter starts decrementing. When timer reaches value 0000 the TAIOUT pin goes low and TA3 stops waiting for next trig.

TB2 is used as trig source to automatically re-start TA3 to define the signal period (see drawing below).

1. Operation timing of Timer A one-shot mode



Operation timing of one-shot mode

2. Timer A registers

Timer Ai mode register (i=0 to 4)

Bit	Symbol	Address	After reset
b7			
b6			
b5	0		
b4			
b3			
b2			
b1	1		
b0	0		

Symbol: TA0MR to TA4MR Address: 39616 to 039A16 After reset: 0016

Bit symbol	Bit name	Function	RW
TMOD0	Operation mode select bit	b1 b0 1 0 : One-shot timer mode	RW
TMOD1			RW
MR0	Pulse output function select bit	0 : Pulse is not output (TAiOUT pin functions as I/O port) 1 : Pulse is output (Note 1) (TAiOUT pin functions as a pulse output pin)	RW
MR1	External trigger select bit (Note 2)	0 : Falling edge of input signal to TAIin pin (Note 3) 1 : Rising edge of input signal to TAIin pin (Note 3)	RW
MR2	Trigger select bit	0 : TAIOS bit is enabled 1 : Selected by TAIiGH to TAIiGL bits	RW
MR3	Must be set to "0" in one-shot timer mode		RW
TCK0	Count source select bit	b7 b6 0 0 : f1 or f2 0 1 : f8 1 0 : f32 1 1 : fc32	RW
TCK1			RW

Note 1: TA0OUT pin is N-channel open drain output.
 Note 2: Effective when the TAIiGH and TAIiGL bits of ONSF or TRGSR register are '002' (TAiIn pin input).
 Note 3: The port direction bit for the TAIin pin must be set to "0" (= input mode).

TAiMR Register in One-shot Timer Mode

One-shot start flag

b7	b6	b5	b4	b3	b2	b1	b0	Symbol ONSF	Address 038216	After reset 0016
Bit symbol	Bit name		Function	RW						
TA0 OS	Timer A0 one-shot start flag		The timer starts counting by setting this bit to "1" while the TMOD1 to TMOD0 bits of TAI _i MR register (i = 0 to 4) = '102' (= one-shot timer mode) and the MR2 bit of TAI _i MR register = "0" (=TAi _i OS bit enabled). When read, its content is "0".	RW						
TA1 OS	Timer A1 one-shot start flag			RW						
TA2 OS	Timer A2 one-shot start flag			RW						
TA3 OS	Timer A3 one-shot start flag			RW						
TA4 OS	Timer A4 one-shot start flag			RW						
TA4 OS	Z-phase input enable bit		0 : Z-phase input disabled 1 : Z-phase input enabled	RW						
TA0 TGL	Timer A0 event/trigger select bit		b7 b6 0 0 : Input on TA0IN is selected (Note 1) 0 1 : TB2 overflow is selected (Note 2) 1 0 : TA4 overflow is selected (Note 2) 1 1 : TA1 overflow is selected (Note 2)	RW						
TA0 TGH				RW						

Trigger select register

b7	b6	b5	b4	b3	b2	b1	b0	Symbol TRGSR	Address 038316	After reset 0016
Bit symbol	Bit name		Function	RW						
TA1 TGL	Timer A1 event/trigger select bit		b1 b0 0 0 : Input on TA1IN is selected (Note) 0 1 : TB2 is selected 1 0 : TA0 is selected 1 1 : TA2 is selected	RW						
TA1 TGH				RW						
TA2 TGL	Timer A2 event/trigger select bit		b3 b2 0 0 : Input on TA2IN is selected (Note) 0 1 : TB2 is selected 1 0 : TA1 is selected 1 1 : TA3 is selected	RW						
TA2 TGH				RW						
TA3 TGL	Timer A3 event/trigger select bit		b5 b4 0 0 : Input on TA3IN is selected (Note) 0 1 : TB2 is selected 1 0 : TA2 is selected 1 1 : TA4 is selected	RW						
TA3 TGH				RW						
TA4 TGL	Timer A4 event/trigger select bit		b7 b6 0 0 : Input on TA4IN is selected (Note) 0 1 : TB2 is selected 1 0 : TA3 is selected 1 1 : TA0 is selected	RW						
TA4 TGH				RW						

Software Description

The application software project is available for download from our website and includes all necessary code to run the application with 10bit resolution PWM at 19KHZ minimum frequency (20MHZ/1024 ~ 19KHZ) using the MCU at maximum speed which is 20MHZ or 24MHZ depending on target device (M16C/62P or M16CTiny).

Signal period is defined by Timer B2, and pulse high duration is defined by contents of Timer TA3.

The timer B2 is loaded with $2^{10}-1 = 1023$ (this gives the 10bits resolution) and counts from f1, this generates a $Xin/1024$ with 10bit resolution PWM signal on TA3OUT.

The initialisation routine and main routine described in next page were tested on a 3DKM16C62P starter kit with IAR C/C++ compiler. (mentioned already)

Conclusion

After the peripherals have been initialised the CPU is free for the application as the timers are in auto-reload mode. When a new PWM value is required a simple change to the timer TA3 contents is enough to get the new value in operation. The basic peripheral initialisation functions are provided in a separate “c” file. It is also possible to create the initialisation functions with IAR MakeUp (download for free from www.iar.com).

Code

```

// -----
// Initialises processor and peripherals
// -----
// Input Parameters:      None
// -----
// Returned Parameters:  None
// -----
// modified globales:    None
// -----
void init(void)
{
    // configure the system clock
    // Xin / Xout Oscillation at 6MHz
    PRCR |= 0x01;          // Enable write to system clock
    CM1 = 0x20;           // Setting System clock control register 1
    CM0 = 0x18;           // Setting System clock control register 0
    PLC0 = 0x12;          // for M16C/62P using 6MHZ Xin
    PLC0 = 0x92;          // for M16C/62P using 6MHZ Xin (remove this line without PLL)
    CM1 = 0x22;           // Select PLL clock
    PRCR &= ~0x01;        // Inhibit write to system clock
    P2   = 0;
    PD2  = 0xff;
}

```



```

// -----
// Scans 3DKM16C62P switches and changes PWM value
// SW_INT2 increases duty ratio, SW_INT0 restores default value,
// SW_INT1 decreases duty ratio.
// -----
// Input Parameters:      None
// -----
// Returned Parameters:  None
// -----
// modified globales:    None
// -----
void main (void)
{
  unsigned int t; // Timer Period
  init();
  timer_a3_init_one_shot_timer_mode ();
  timer_b2_init_timer_mode ();
  timer_b2_set (1024-1); // BCLK = 24MHZ => 23.437KHZ periodic pulse
  timer_a3_set (256-1 ); // Set PWM to 256 (means 25% modulation ratio).
  timer_a3_start ();
  timer_b2_start ();
  tempo = TEMPO;
  t = T0;
  for(;;)          // Never ending loop
  {
  // Increase duty cycle
  if(!SW_INT2)    {
    LED4 = 1; // Light ON LED to show push button is pressed.
    tempo--;
    if(tempo == 0)      // Slow down loop
    {
      tempo = TEMPO;
      if(t<TMAX)  t++; // Increase duty cycle by one unit
    }
  }
  else LED4 = 0;
  // Decrease duty cycle
  if(!SW_INT0)    {
    LED8 = 1;
    tempo--;
    if(tempo == 0)
    {
      tempo = TEMPO;
      if(t>TMIN) t--;
    }
  }
  }
}

```

```
    }  
  }  
  else LED6 = 0;  
  // restore default duty cycle  
  if(!SW_INT1) {  
    LED6 = 1;  
    t = T0 ;  
  }  
  else LED8 = 0;  
  timer_a3_set(t);  
};  
}
```

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