

# 8-Bit Timer/Event Counters (TM1 and TM2) in 16-Bit Timer Counter Mode

### On-Chip Peripheral Program Example

August 1999

### **Description**

The 8-bit timer/event counters (TM1 and TM2) in the  $\mu$ PD7805x/78005x subseries can be cascaded to become one 16-bit timer/counter, which can be used as a 16-bit interval timer, 16-bit external event counter, or 16-bit square-wave output.

This program demonstrates how the TM1 and TM2 operate in 16-bit interval timer mode. The count clock clocks TM1 and the overflow signal from TM1 clocks TM2. When the count value of TM1 matches the value set to compare register CR10 and the count value of TM2 matches the value set to compare register CR20, the interrupt request flag (TMIF2) is set to 1, causing a vectored interrupt that toggles port pin 0.2 in the interrupt service routine. At the same time, TM1 and TM2 are cleared to 0.

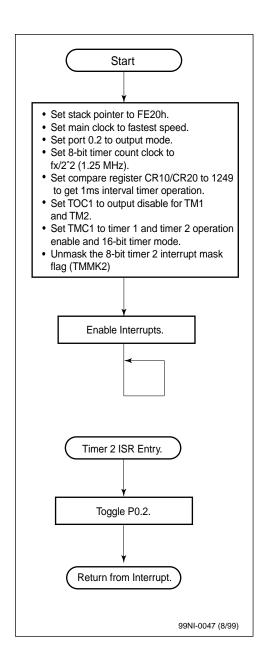
# Program Specifications

- Count clock frequency: 1.25 MHz at 5 MHz main system clock
- ☐ Square wave frequency: 500 Hz (2 ms period)
- ☐ Pins used in program: P02/INTP2 (port pin toggles every 1 ms)

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## **Flowchart**





#### **Assembly Language Program**

```
06/16/1999
; Parameters: - fastest CPU clock
           (fx = 5.00 \text{ MHz}, 1 \text{ CPU clock cycle} = 200 \text{ ns})
         - Count clock: fx (1.25 MHz)
          - Interval time: 1 ms (2 ms period)
         - enable interrupt handling for timer 2
          - port 0.2 toggles every 1 ms
Specify Interrupt Vectors
CSEG AT 0000h ; Set main program start vector.
Res_Vec
         DW
              Start
                       ; Set interrupt vector
         ORG
              0026h
                       ; for 8-bit timer 2
              TM2_ISR
         DW
; =
         Main Program
MAIN CSEG
                        ; Disable interrupts
Start:
         DI
         MOVW AX, #0FE20h ; Load SP address
         MOVW SP, AX ; Set Stack Pointer
              OSMS,#01h ; Don't use scaler
         MOV
         VOM
              PCC, #00h ; Main system clock at fastest setting
         CLR1
              P0.2
                       ; Latch port 0.2 low
              PM0.2 ; Latch port 0.2 low
PM0.2 ; Set port 0.2 to output mode
         CLR1
              TCL1,#07h ; Select counter clock to fx(1.25 MHz)
         MOV
              CR10,#0E1h ; Set compare register 1 (low byte) to E1h for 1 ms interval
         MOV
              CR20,#04h ; Set compare register 2 (high byte) to 04h for 1 ms interval
         MOV
         MOV
              TOC1,#00h ; Disable output function
              TMC1,#07h ; Set TM1 and TM2 operational enable and 16-bit timer mode
         VOM
         CLR1
              TMMK2
                     ; Unmask the 8-bit timer 2 interrupt bit
         ET
                       ; Enable interrupts
Loop1:
         BR
              $Loop1 ; Endless loop
8-bit timer 2 ISR
ISR
         CSEG
        XOR P0,#04h ; Toggle port 0.2
TM2 ISR:
         RETI
                       ; Return from interrupt
    END
```



### **C Language Program**

```
/************************************
; Date:
         06/16/1999
; Parameters: - fastest CPU clock
          (fx=5.00 MHz, 1 CPU clock cycle = 200 ns)
        - Count clock: fx (1.25 MHz)
         - Interval time: 1 ms (2 ms period)
         - Enable interrupt handling for timer 2
         - Port 0.2 toggles every 1 ms
/* extension functions in KO/KOS compiler */
#pragma sfr /* key word to allow SFR names in C code */
Specify Interrupt vectors
;========*/
/* Set interrupt vector for the 8-bit Timer 0 */
#pragma interrupt INTTM2 TM2_ISR
Constants/Variables
;=========*/
#define TRUE 1
#define FALSE
             Ω
;= Main Program =
;========*/
void main(void)
                 /* Don't use scaler */
/* Main system clock at fastest setting */
    OSMS = 0x01;
    PCC = 0x00;
                   /* Latch port 0.2 output low */
    P0.2 = 0;
                   /* Set port 0.2 output mode*/
    PM0.2 = 0;
                   /* Select counter clock to fx(1.25 \text{ MHz}) */
    TCL1 = 0x07;
                   /* Set compare register 1(low byte) for 1 ms interval */
    CR10 = 0xE1;
    CR20 = 0x04;
                   /* Set compare register 2(high byte) for 1 ms interval */
    TOC1 = 0x00;
                   /* Disable output function */
    TMC1 = 0x07; /* Set TMC1 to TM1 and TM2 operational enable and
                       16-bit timer mode */
    TMMK2 = 0;
               /* Unmask the 8-bit timer 2 interrupt bit */
                    /* Enable interrupts */
    EI();
    while(TRUE);
                    /* loop here */
                    /* end of function main() */
8-bit TIMER 2 ISR
;========*/
void TM2_ISR(void)
{
   P0 ^= 0x04; /* toggle port 0.2 */
}
```



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