

16-Bit Timer/Event Counter 0 (TM0) in Interval Timer Mode

On-Chip Peripheral Program Example

August 1999

Description	The 16-bit timer/event counter (TM0) in the μ PD7805x/78005x subseries can be used as an interval timer, external event counter, pulse-width modulator output, square-wave output, one-shot pulse output or for pulse-width measurement.
	This program demonstrates the 16-bit timer/event counter in interval timer mode. When the count value of the 16-bit timer register (TM0) matches the value set to capture/compare register 0 (CR00), counting continues with the TM0 value cleared to 0 and the interrupt request signal (INTTM00) generated. This sets the interrupt flag TMIF00 in the interrupt request flag register (IF0H). Each time the program detects the flag set to one, it toggles port 0.2 and clears the flag.
Program Specifications	Timer count clock: 5 MHz
	Interval time: 1 ms (2 ms period)
	Square wave frequency: 500 Hz
	Interrupt handling: polling the interrupt request flag TMIF00

Derived Pins used in program: P02/INTP2 (toggles every 1 ms)

Flowchart





Assembly Language Program

```
; Date:
          07/19/1999
;
; Parameters: - fastest CPU clock
            (fx=5.00 \text{ MHz}, 1 \text{ CPU clock cycle} = 200 \text{ ns})
;
           - interval time: 1 ms
;
;
           - Count clock: fx = 5 MHz
;
           - Unmask the 16-bit timer interrupt mask bit for
                 polling the timer interrupt flag
           - Port 0.2 toggles every 1 ms
;
;
; =
    Specify Interrupt Vectors
Res_Vec CSEG AT 0000h
                          ; Set main program start vector
      DW Start
Main Program
;
                                =
MAIN
      CSEG
Start: DI
                          ; Disable interrupts
              AX, #0FE20h ; Load SP address
       MOVW
       MOVW
              SP, AX ; Set Stack Pointer
              OSMS,#01h ; Don't use scaler
       MOV
               PCC, #00h ; Main system clock at fastest setting
       MOV
               P0.2; Latch port 0.2 lowPM0.2; Set port 0.2 as outputTCL0,#020h; Select counter clock to fx = 5 MHz
       CLR1
       CLR1
       MOV
              CR00,#5000 ; Set compare register to 5000 for 1 ms interval
       MOVW
       MOV
               TMC0,#0Ch ; Set to clear and start of match TMO and CROO
       CLR1
              CRC0.0 ; Set CR00 operation to compare register
              TMMK00; Mask the 16-bit timer interrupt mask bitTMIF00; Clear 16-bit timer interrupt flag
       SET1
       CLR1
       ΕI
                          ; Enable interrupts
              TMIF00,$$ ; Branch if timer interrupt flag is high
      BF
Loop:
              TMIF00 ; Clear timer interrupt flag
P0,#04h ; Toggle port 0.2
Loop ; Loop back
       CLR1
       XOR
       BR
                Loop
                           ; Loop back
     END
```

C Language Program

```
; Date: 07/19/1999
;
; Parameters: - fastest CPU clock
    (fx = 5.00 MHz, 1 CPU clock cycle = 200 ns)
;
             - interval time: 1 ms
;
;
             - Count clock: fx = 5 MHz
             - Unmask the 16-bit timer interrupt mask bit for
;
                   polling the timer interrupt flag
;
             - Port 0.2 toggles every 1 ms
;
/* extension functions in K0/K0S compiler */
#pragma sfr /* key word to allow SFR names in C code */
#pragma asm /* key word to allow ASM statements in C code */
#pragma DI /* key word for DI instruction in C code */
#pragma EI /* key word for EI instruction in C code */
; Constants/Variables
;=========*/
#define TRUE
                  1
#define FALSE
                 0
; Main Program =
;========*/
void main(void)
{
                            /* Don't use scaler */
      OSMS = 0x01;
                        /* Main system clock at fastest setting */
/* Latch port 0.2 low */
/* Set port 0.2 as output */
/* Select counter clock to fx = 5 MHz */
/* Set compare register to 5000 for a 1 ms interval */
/* Set to clear and start on match of TMO and CR00 */
/* Set CR00 operation to compare register */
/* Mask the 16-bit timer interrupt mask bit */
/* Clear timer interrupt flag */
/* Enable interrupts */
      PCC = 0 \times 00;
      P0.2 = 0;
      PM0.2 = 0;
      TCL0 = 0x20;
      CR00 = 5000;
      TMC0 = 0 \times 0 c;
      CRC0.0 = 0;
      TMMK00= 1;
      TMIF00 = 0;
      EI();
                              /* Enable interrupts */
      while(TRUE)
                               /* while loop*/
      {
            while( !TMIF00 ); /* Wait until timer interrupt flag is high */
            TMIF00 = 0;  /* Clear timer interrupt flag */
            P0 ^= 0x04;
                              /* toggle port 0.2 */
                               /* end of while loop */
      }
}
                                /* end of function main() */
```



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