#### **POWERNAVIGATOR 5.4**

DIGITAL POINT OF LOAD USER GUIDE

**MARCH 2018** 

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#### **OVERVIEW**

- This guide walks a user though the steps to setup and configure a digital power device using Renesas's PowerNavigator GUI.
- For Digital Multiphase products (ISL691xx and ISL681xx), please see the dedicated Digital Multiphase user guide.
- This guide assumes the user has followed the instructions on the website for downloading and installing PowerNavigator and is able to launch the program successfully.

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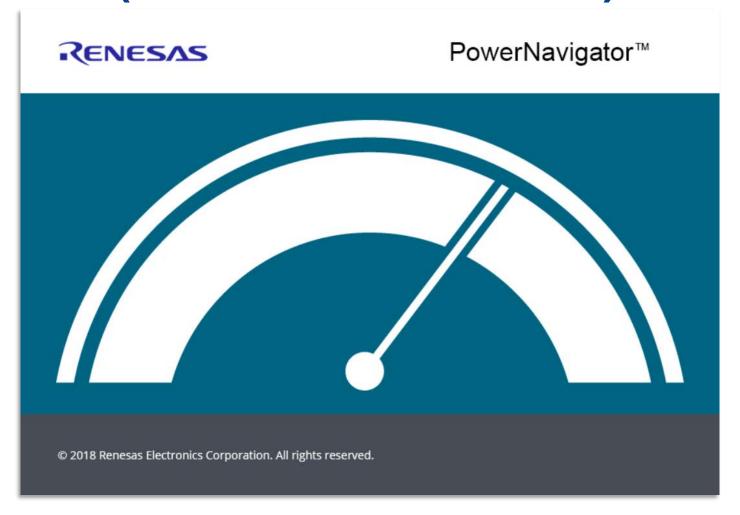
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#### **OVERVIEW**

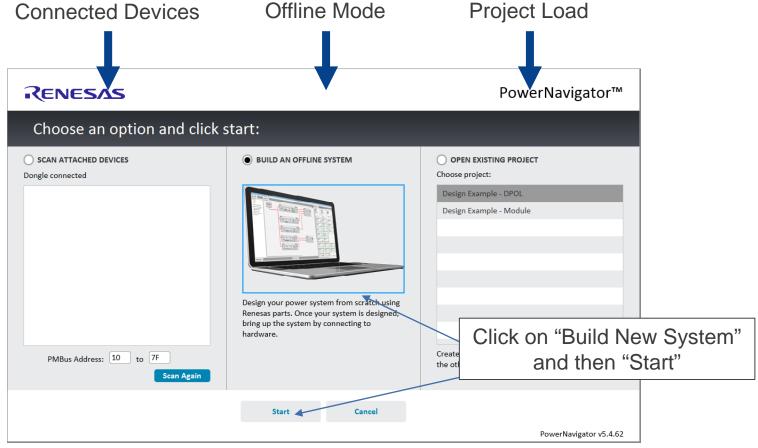
- The following sections are shown in this guide:
  - Hardware free mode
    - Selection of devices
    - Power architecture setup
    - Current sharing
  - Connecting to hardware
    - Auto scan of devices
  - Device setup with Rail Inspector
    - Changing device parameters
    - Configuration file load and save
  - Sequencing
    - Time based sequencing
    - Event based sequencing
  - RailScope
    - Adding/monitoring devices
    - Logging
  - Production File HEX Creation



# Offline Mode (Hardware Free Mode)

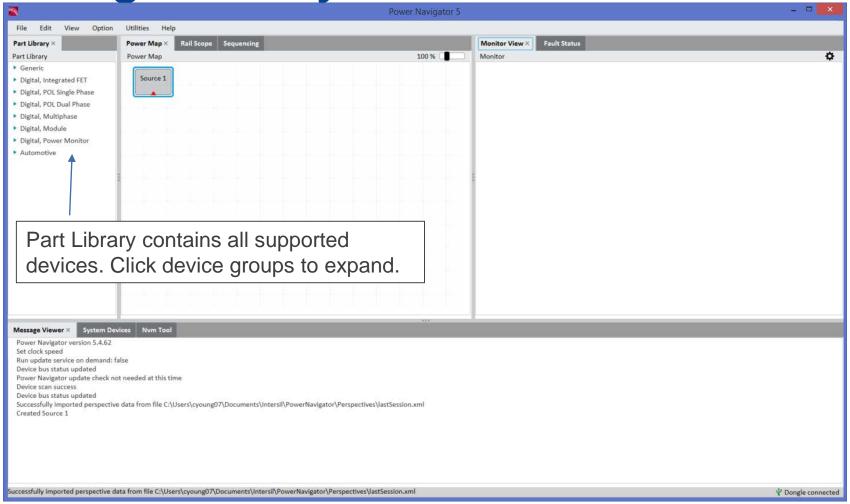


## PowerNavigator Launch Screen – Offline Mode



The PowerNavigator launch screen allows you to select online (hardware connected) or offline modes of operation.

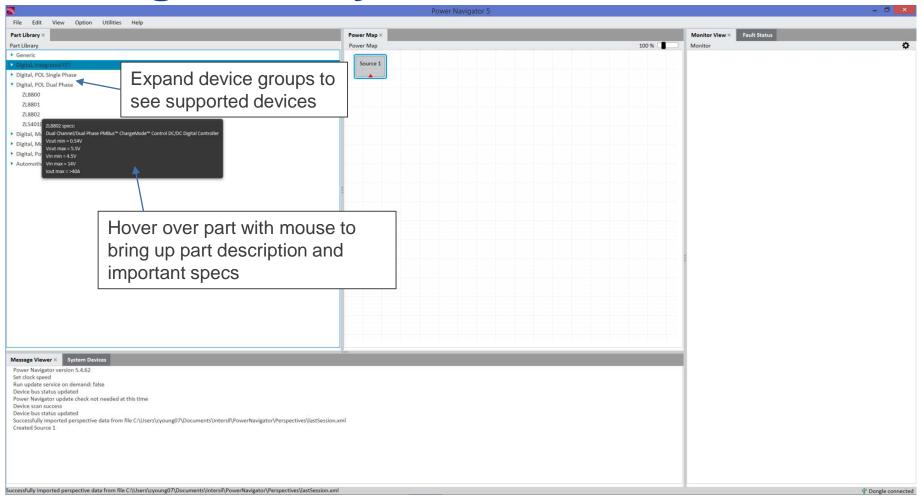
PowerNavigator – System Screen Offline Mode



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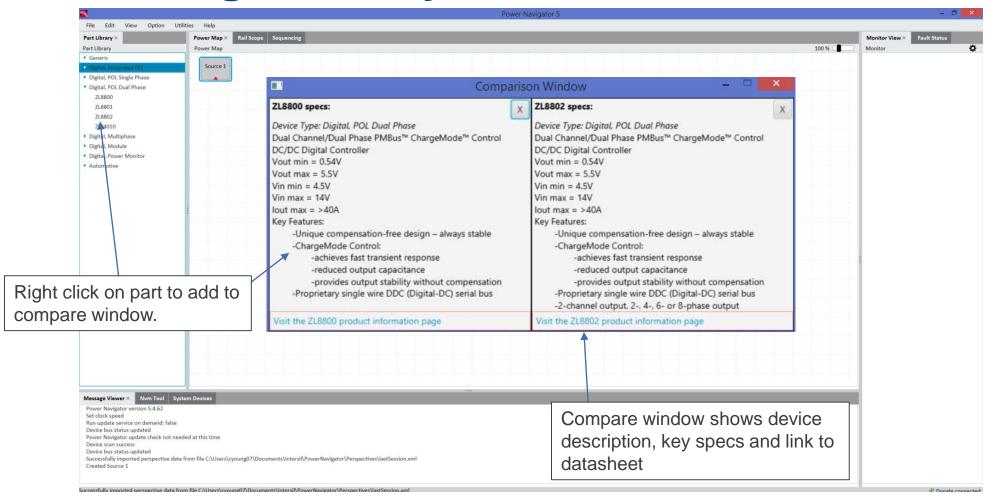
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# PowerNavigator – System Screen Offline Mode

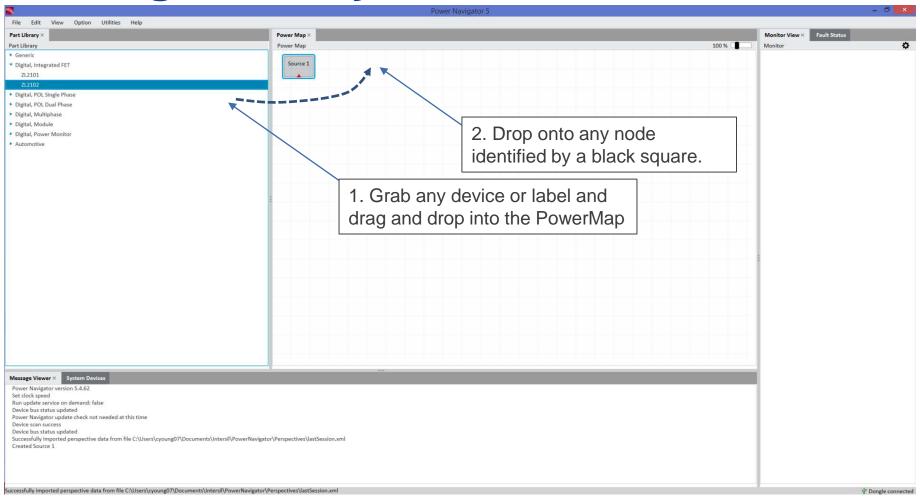




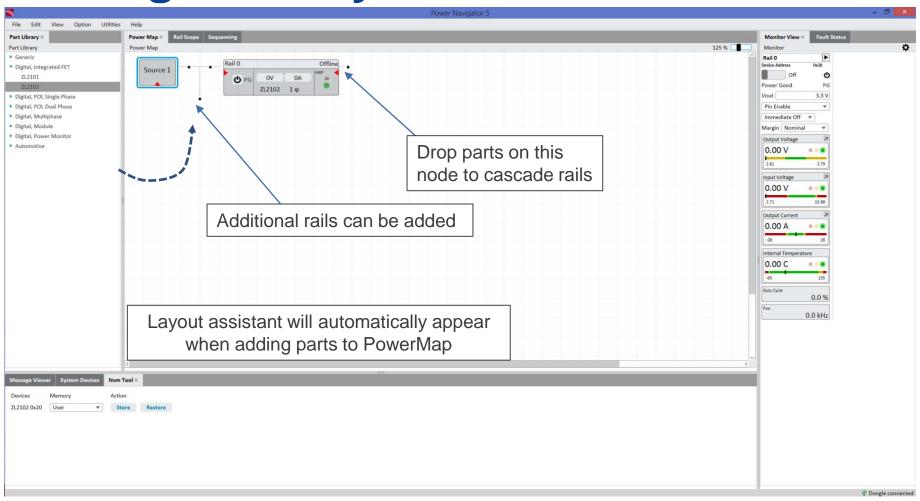
# PowerNavigator – System Screen Offline Mode

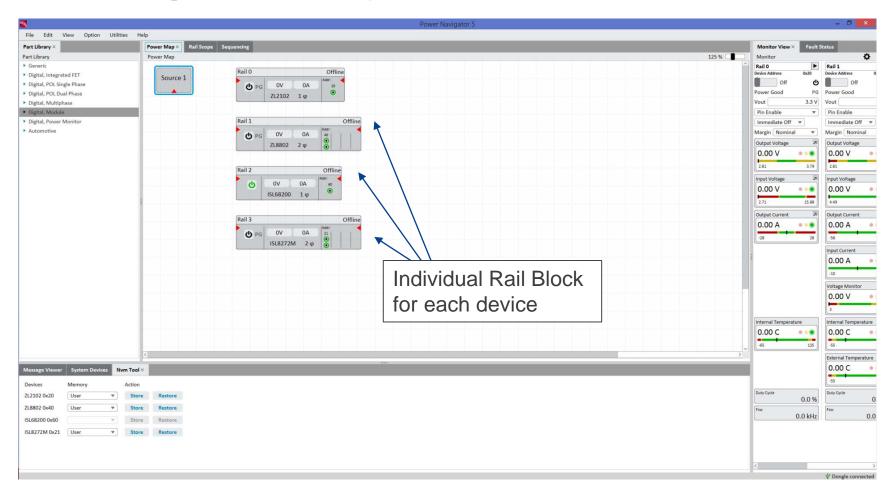


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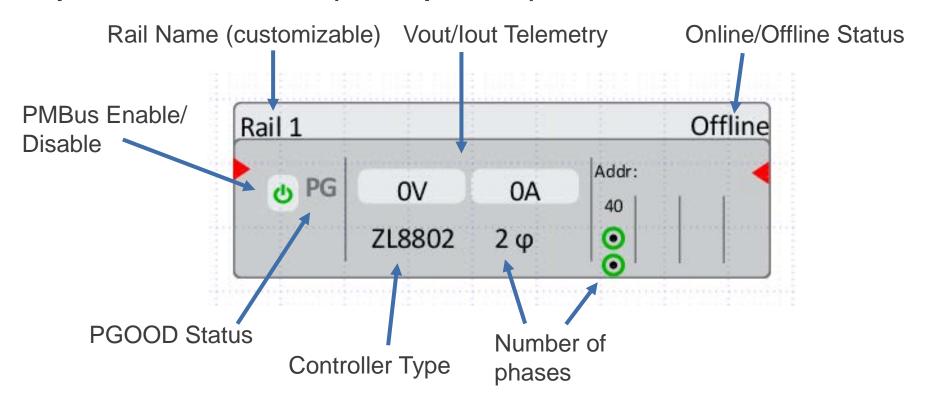




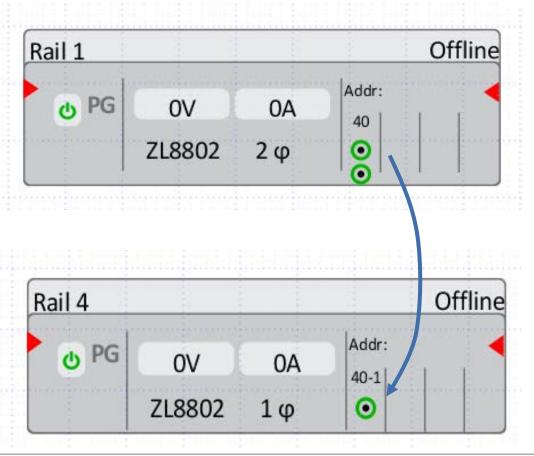
Multiple parts can be added to PowerMap, representing system level view.



#### **Example ZL8802 RailBlock (2-PH operation):**



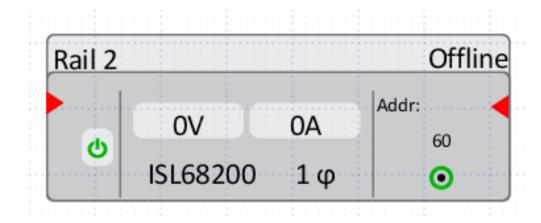
**Example ZL8802 RailBlock (2-CH operation):** 



Drag and drop interface for configuration of a rail from 2-phase to dual output.

Drag "Phase Dot" to change from 2-phase to 2-Channel operation

#### **Example ISL68200 RailBlock:**

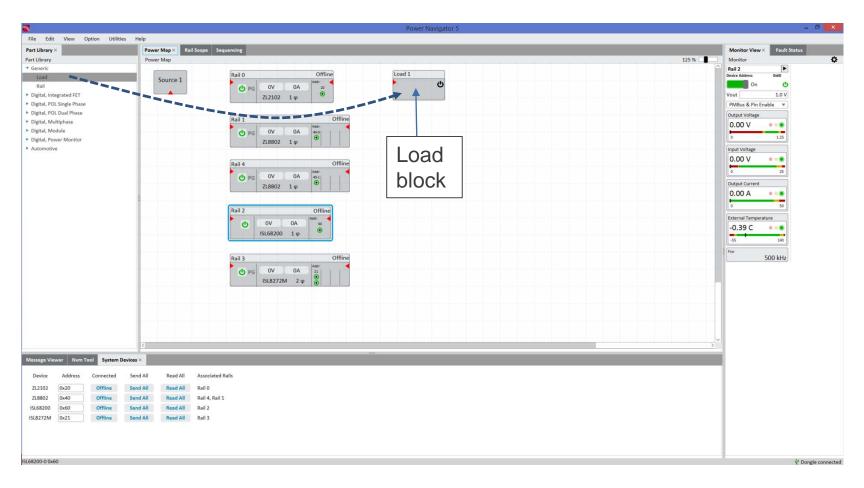


Controllers which do not support current share will only have one "slot".

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In this case, we have a single phase ISL68200 controller at PMBus address 0x60.

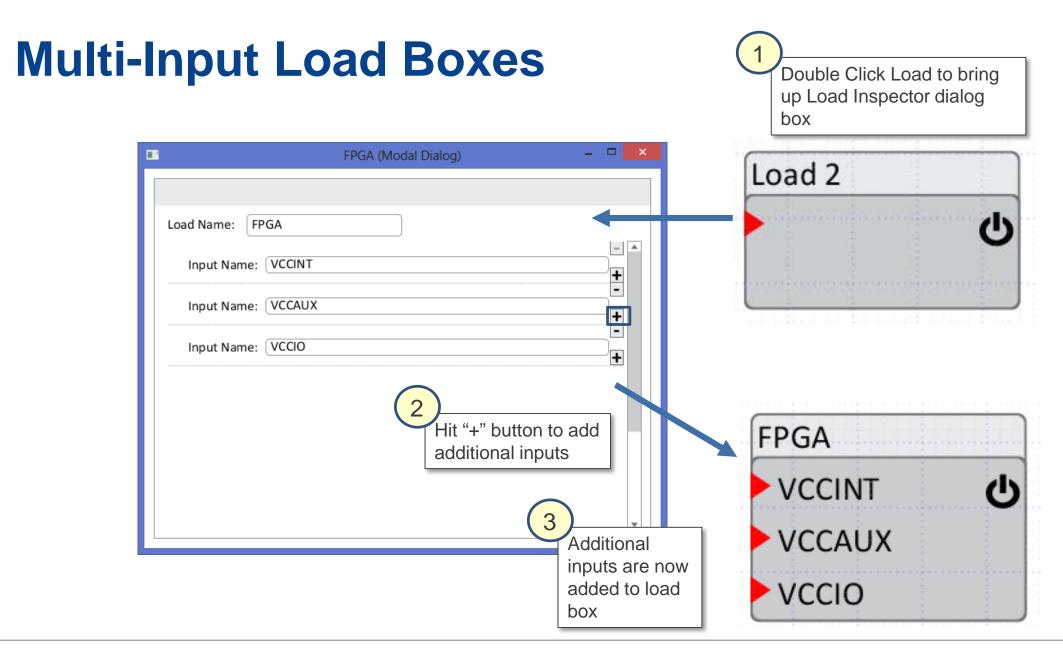


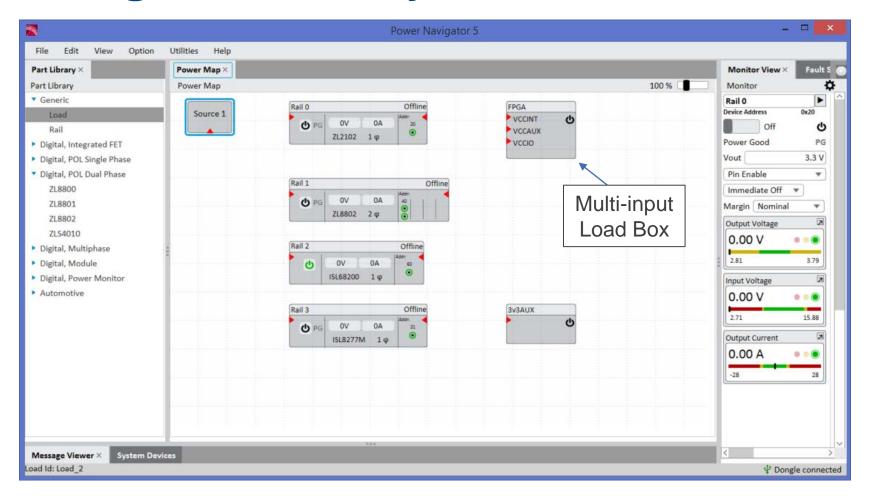


Load Blocks represent system load and can be added to the PowerMap from the Part Library. Double Click to add additional inputs.



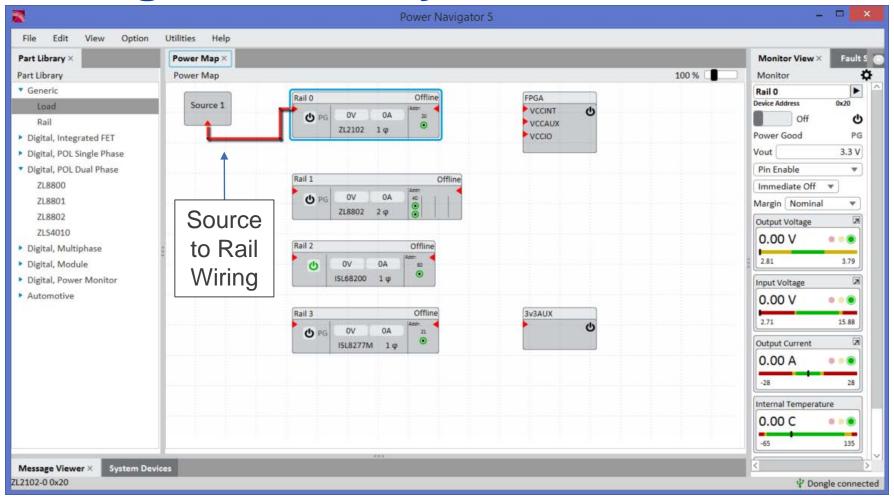
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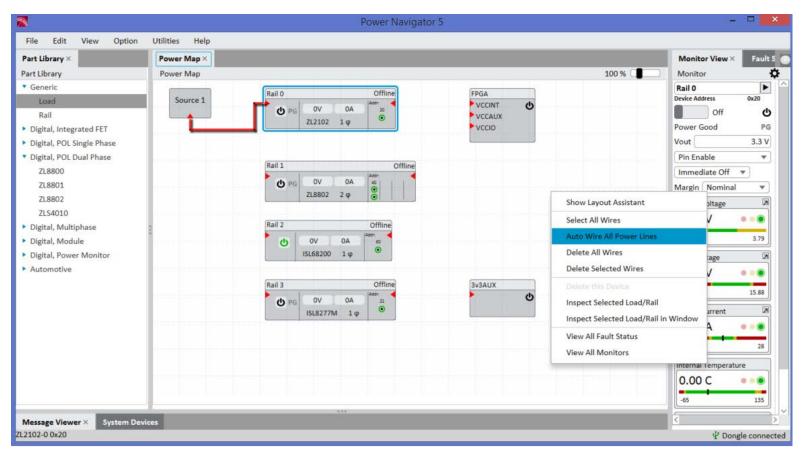




After configuring system, all sources, rails and loads can be wired together.





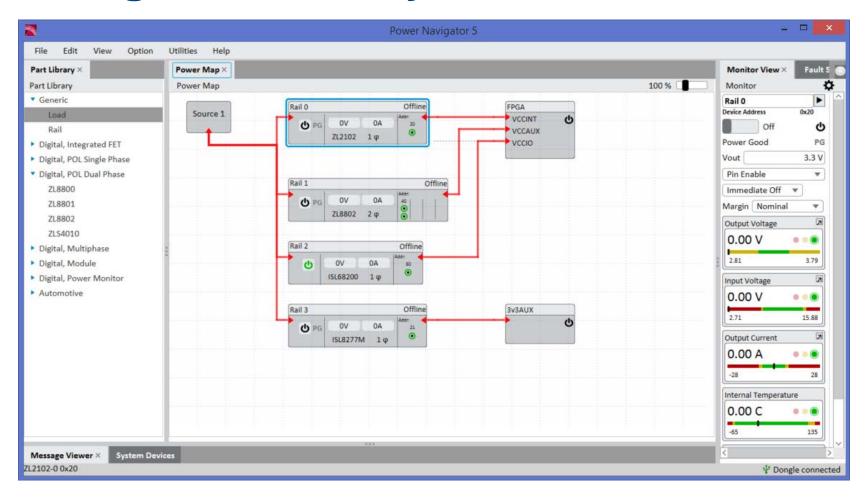


Right-click on PowerMap to bring up contextual menu. Select "Auto Wire All Power Lines" to auto wire PowerMap.



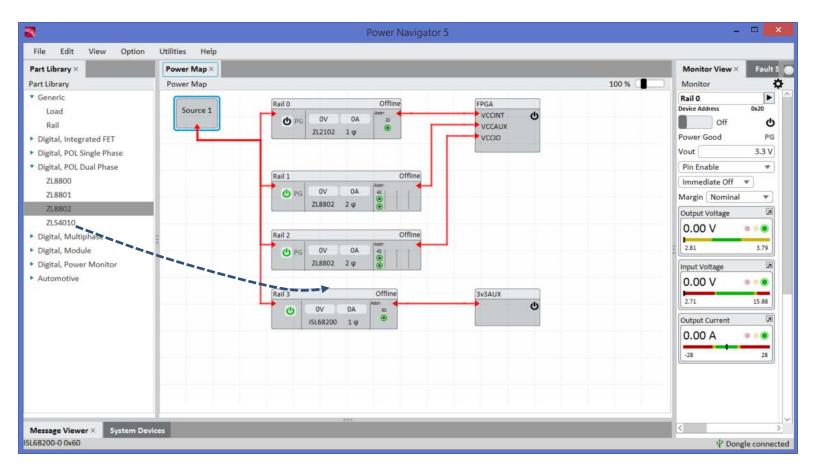
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Fully wired PowerMap with multi-input loads.

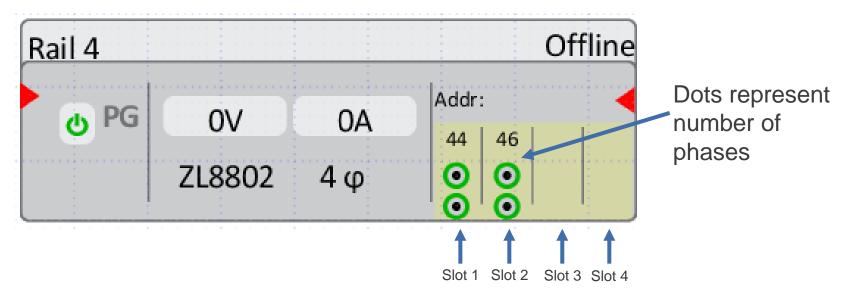




To implement a current sharing rail, drag a part from the part library onto an open RailBlock "slot".



#### **Example ZL8802 RailBlock (4-PH operation):**

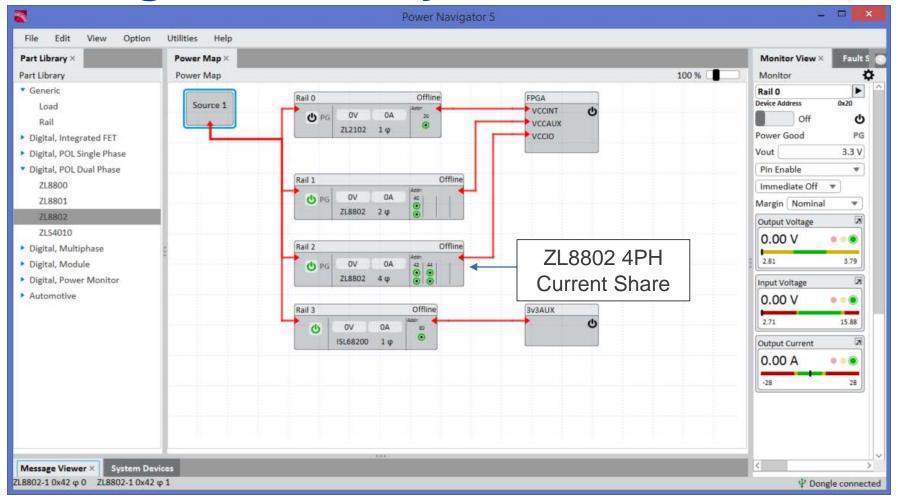


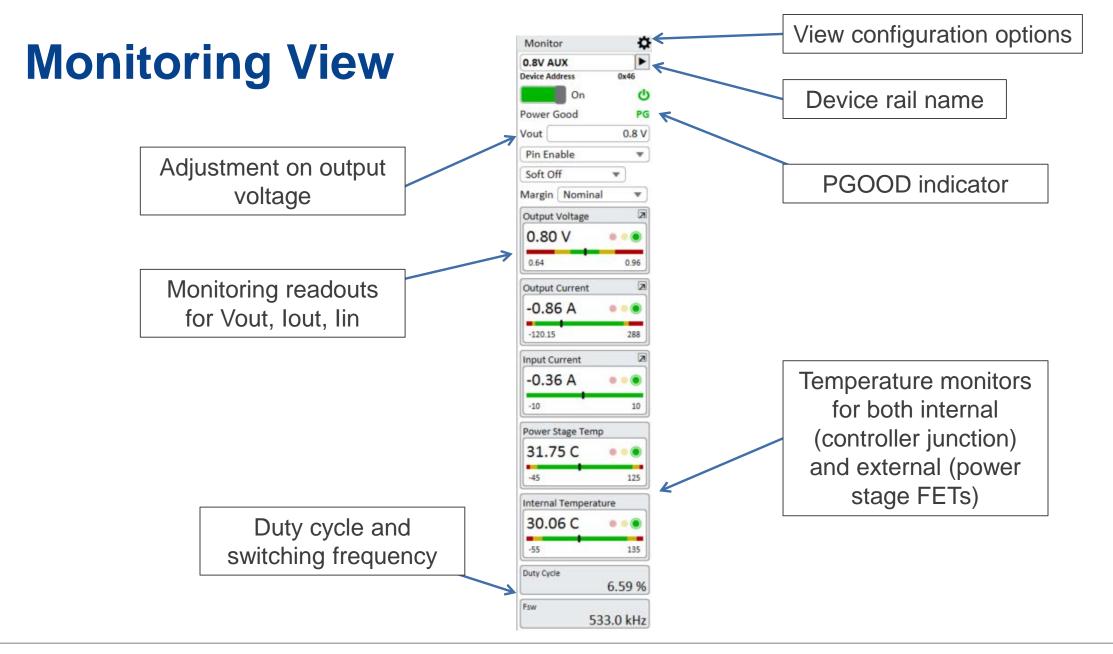
- The ZL8802 allows for 2-PH, 4-PH, 6-PH or 8-PH operation via current share.
- Each "slot" in the RailBlock represents shows how many controllers can be paralleled in a current share group.
- To create a current share group, a controller can be dragged from the part library into a "slot", creating a current share rail.
- In this case, we have a 4-phase design, with two ZL8802 controllers one at PMBus address 0x44 and another at 0x46.

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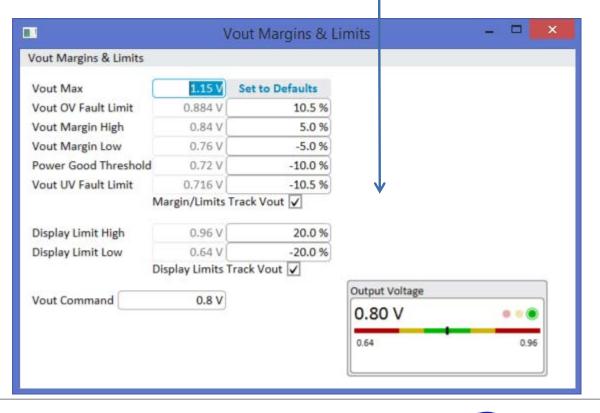
#### Readouts

Analog sliding meter with color indicators. Green is within normal limits, yellow in PMBus warning limits, red for exceeding OVP/UVP settings.

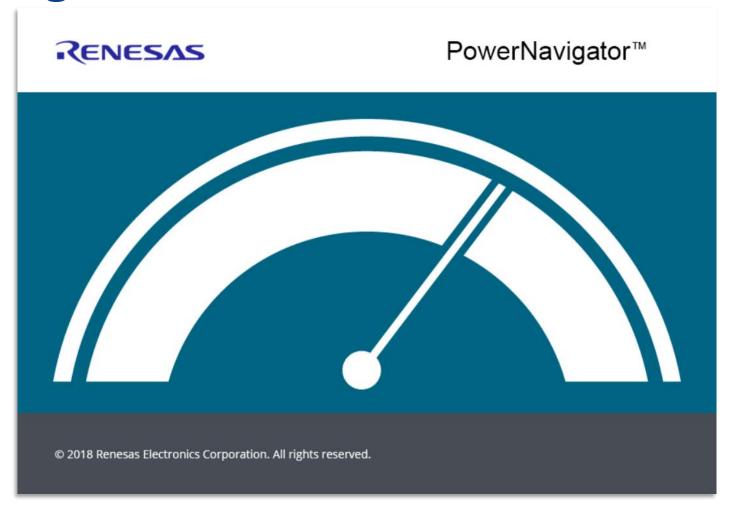
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**Output Voltage** 0.80 V Operation and fault lights Digital readout of output voltage

Clicking this button will open the window below allowing adjustment of limits



# **Connecting to Hardware**





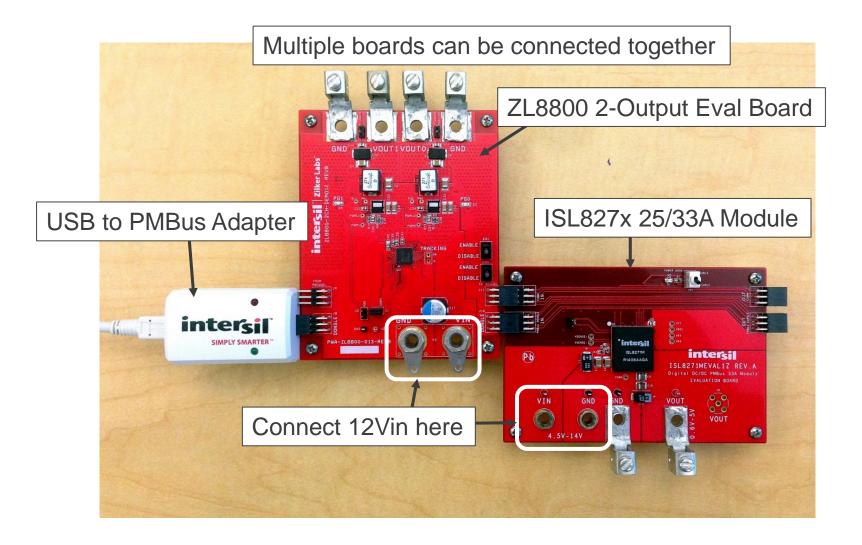
#### Connect to Hardware . . .

- To connect to hardware, a USB to PMBus adapter (ZLUSBEVAL3Z, included with all demo kits) is required.
- STEP 1: Connect USB cable from PC to USB adapter
- STEP 2: Connect USB to PMBus adapter to demo board hardware
- STEP 3: Power demo board

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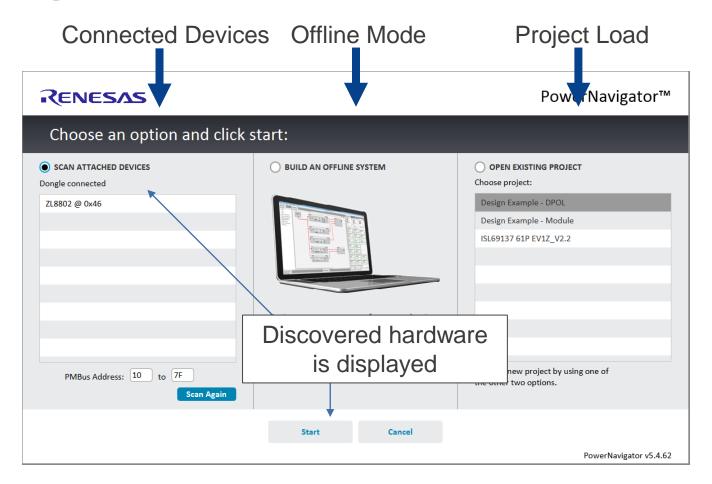
STEP 4: Launch PowerNavigator software

#### Connect to Hardware . . .





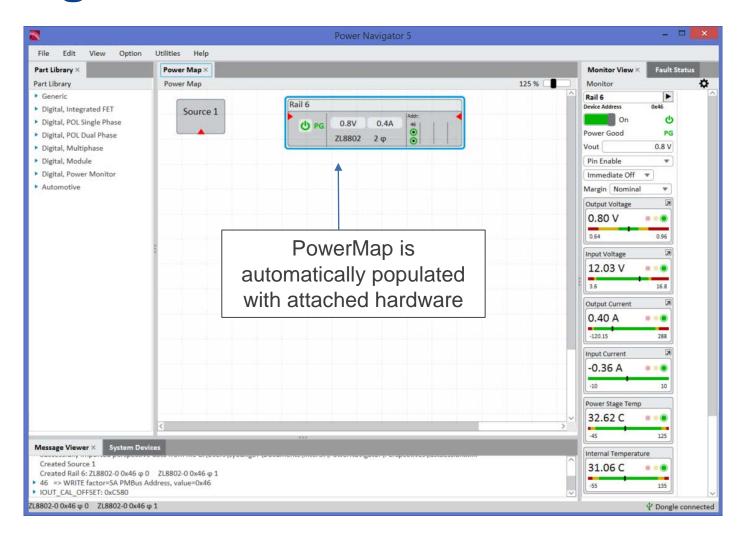
# PowerNavigator Launch Screen



All discovered hardware is displayed in the "Scan Attached Devices" window. The PMBus scan range can be adjust – default range is 0x10 to 0x7F.

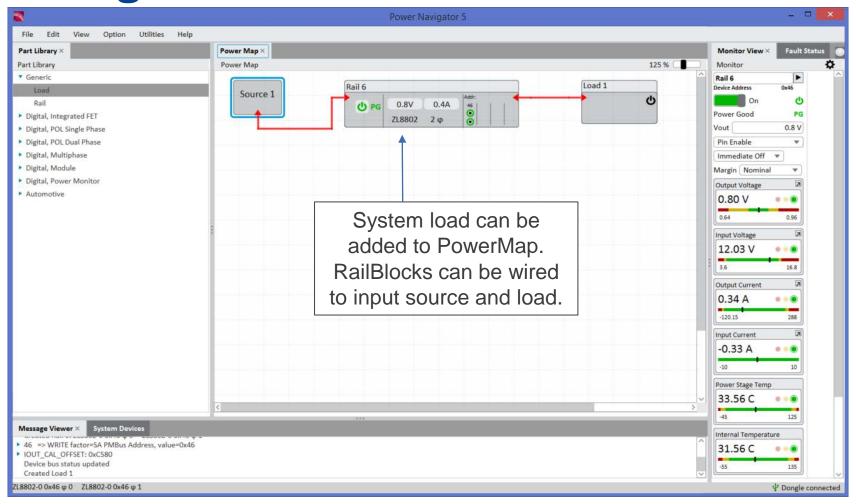


# PowerNavigator 5.4 – Connect to HW



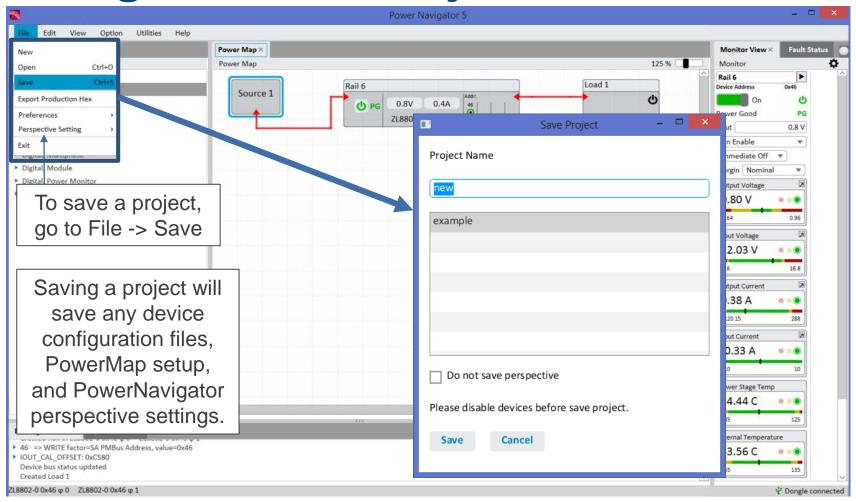
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# PowerNavigator 5.4 – Connect to HW

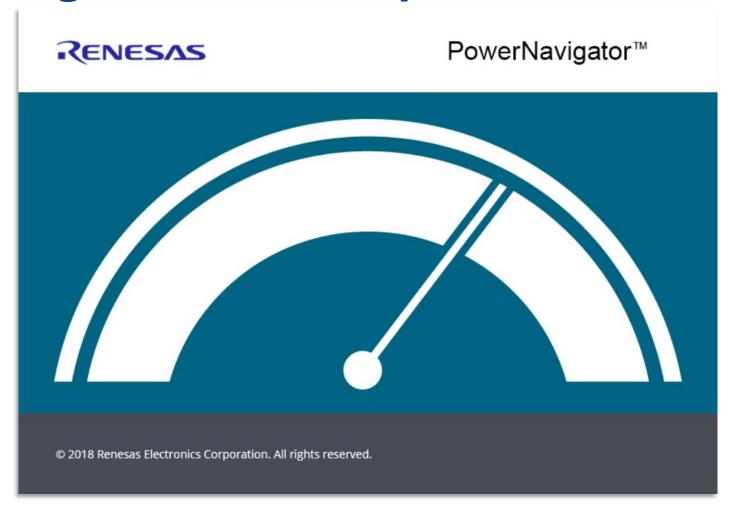


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#### PowerNavigator 5.4 – Project Save



# PowerNavigator – Rail Inspector





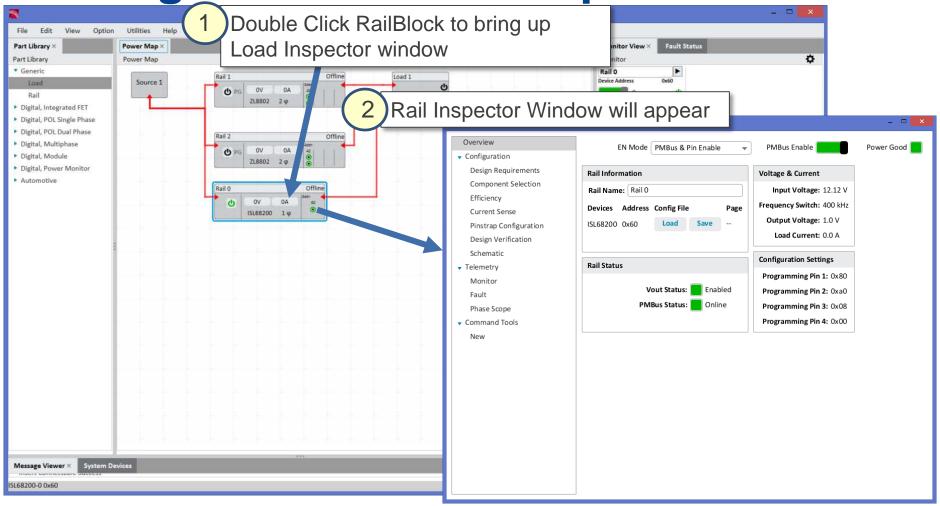
## PowerNavigator 5.4 – Rail Inspector

- Rail Inspector tool eases device configuration
  - Double click on RailBlocks to bring up individual Rail Inspector for each device.
  - Each device in PowerNavigator can have its own, customized Rail Inspector.
- Rail Inspector tool can be used to:
  - Quickly see rail summary, including PMBus addresses, controller type, PMBus status, device options, fault status, etc.

- Save/Load Configuration Files
- Configure device using command tool
- Allows for future expandability
  - Future releases of PowerNavigator will expand Rail Inspector features



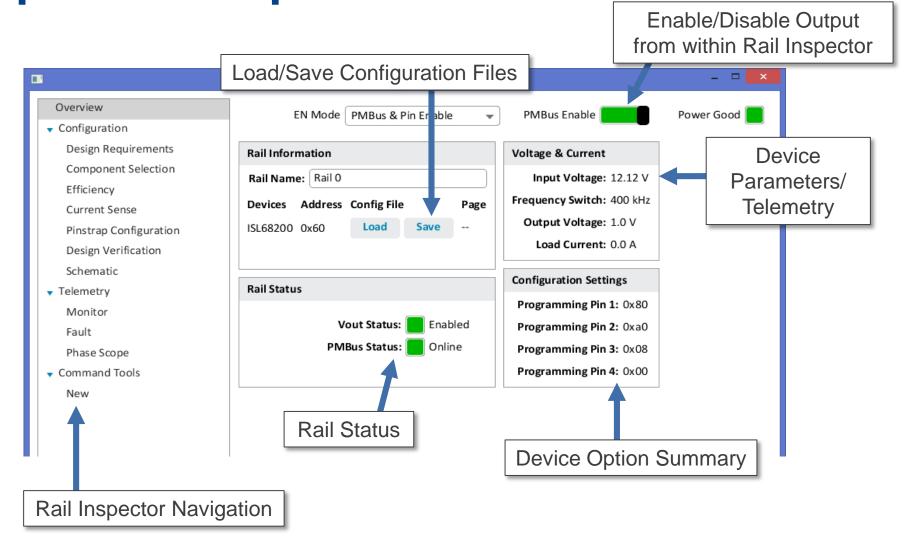
PowerNavigator 5.4 – Rail inspector



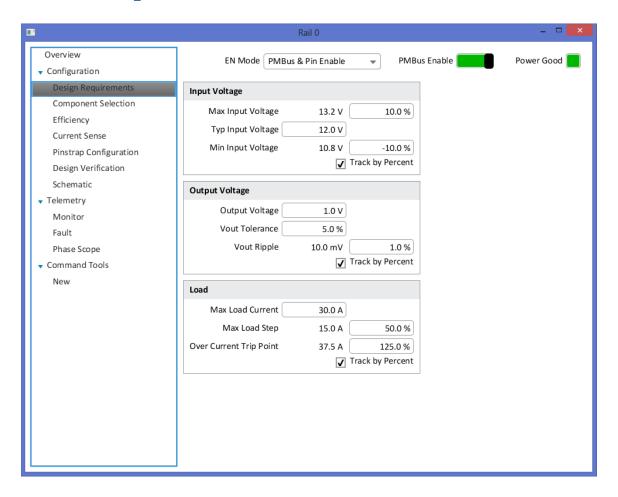
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#### **Example Rail Inspector – ISL68200**

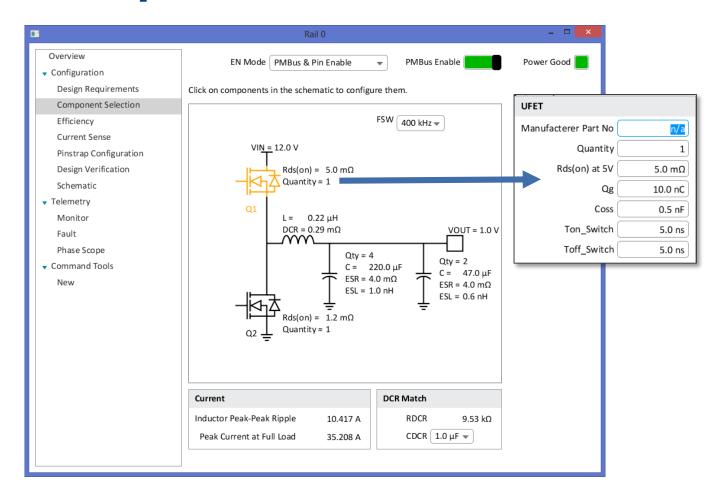


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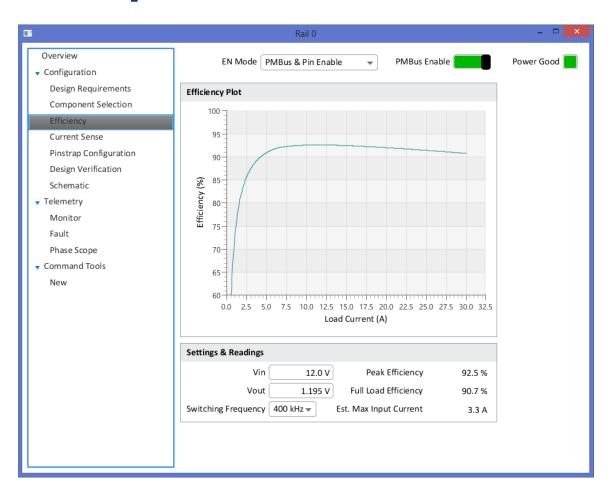
Design Requirements - Enter Vin, Vout and lout requirements





Component Selection – Enter FET, Inductor and Output Cap information

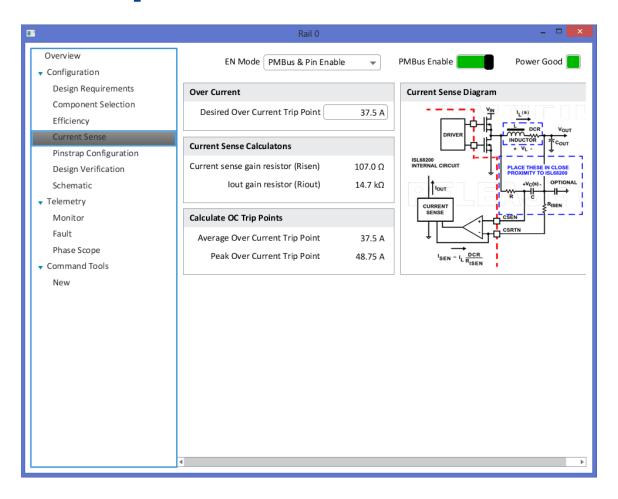




Efficiency – Real time plot of efficiency with selected components and switching frequency.

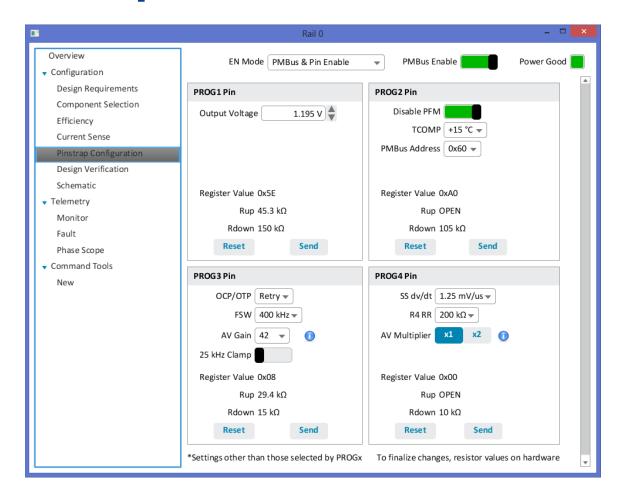


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Current Sense – Automatic calculation of current sense resistor settings based on desired OC trip point.

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Pinstrap Configuration – Select pinstrap resistors to setup device default settings.



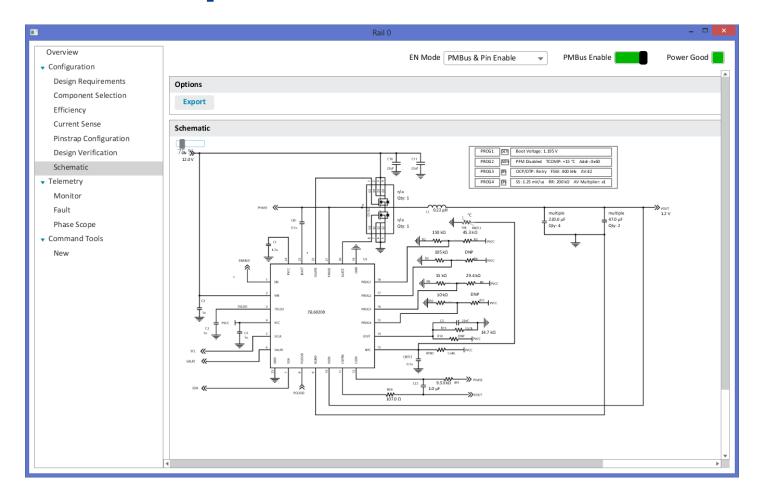
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Design Verification—Bode and Output Impedance plots of design.

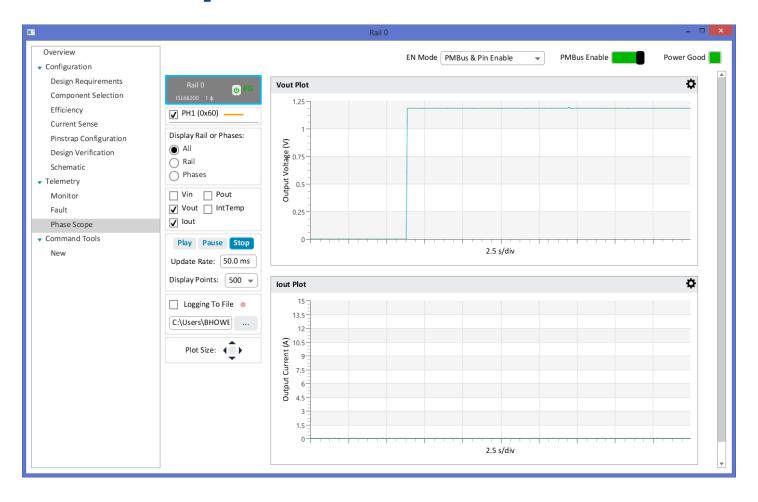
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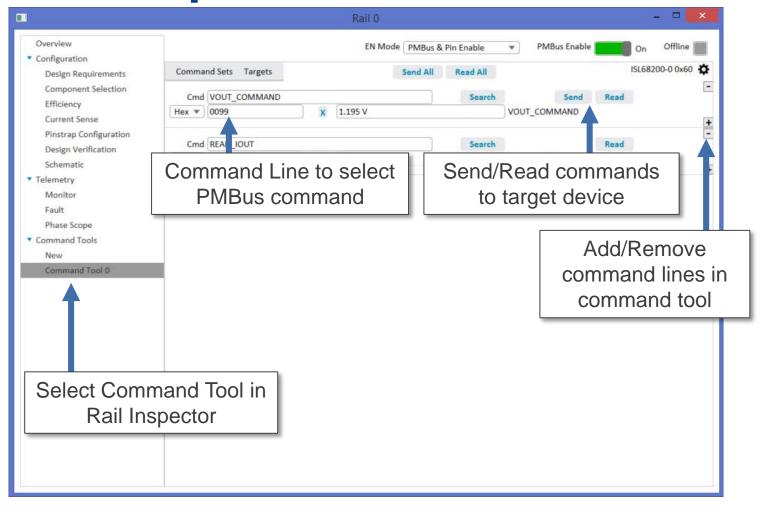
Schematic Generation – Final schematic, with customized components, generated automatically.

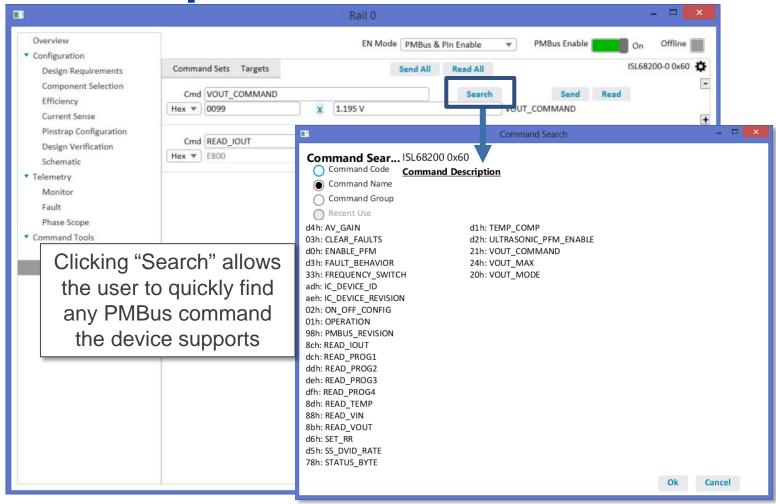




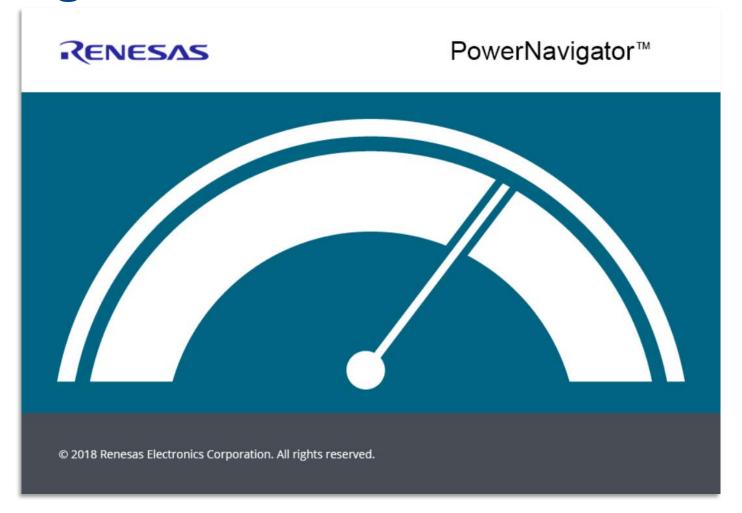
Phase Scope – Real time plotting of all telemetry parameters.







# Sequencing

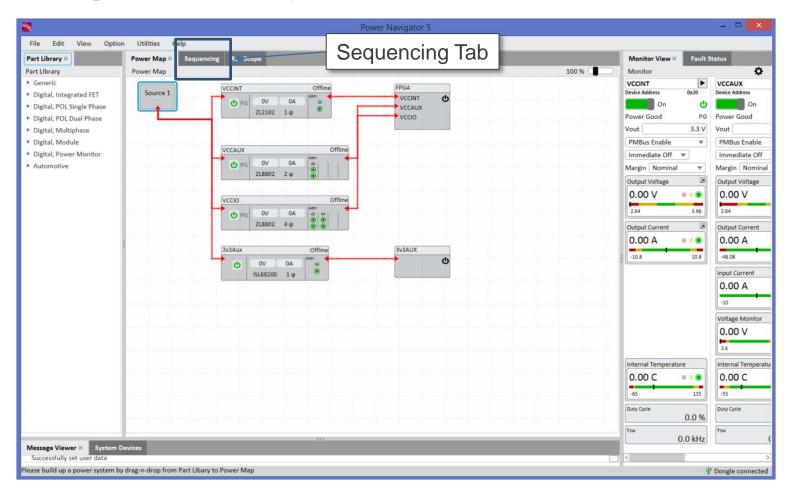


# PowerNavigator – Sequencing

- All Renesas Digital Power Controllers and modules with a DDC bus support autonomous sequencing between rails.
- Sequencing is configured using the PowerNavigator sequencing tool.
- Once configured, all sequencing events are handled automatically using Renesas's proprietary DDC bus.
  - Controllers and/or modules will automatically communicate via DDC bus, synchronizing sequencing events.



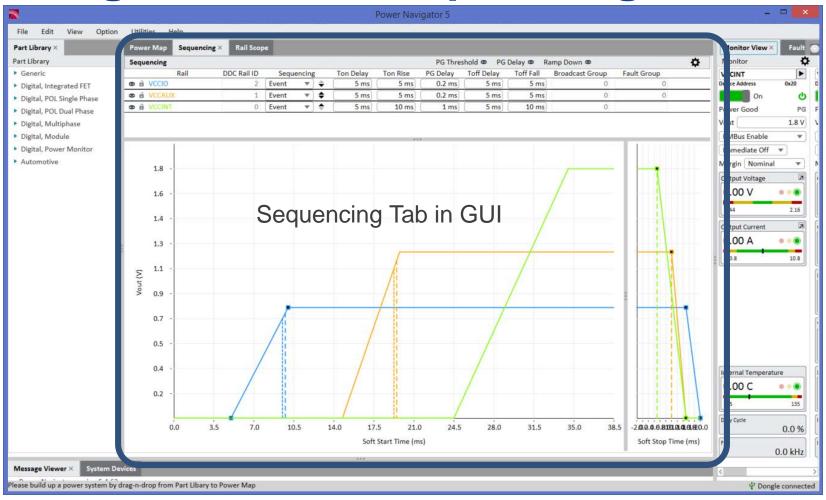
# PowerNavigator – System Screen



The sequencing tab allows for power up and power down sequencing of devices in the PowerMap.



# PowerNavigator GUI – Sequencing

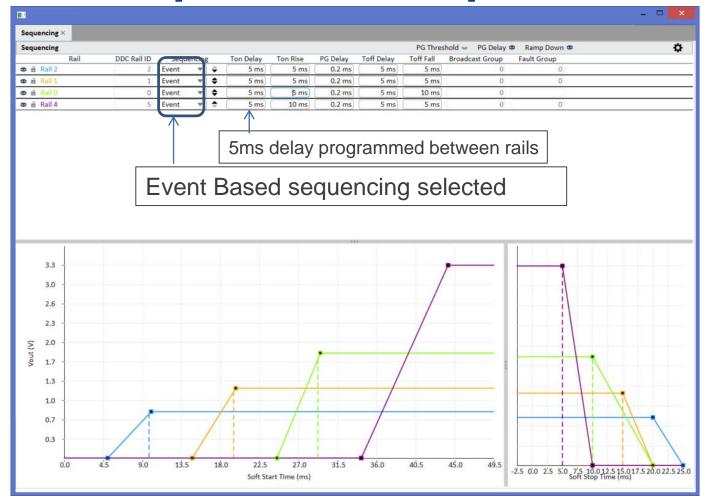


# PowerNavigator – Sequencing

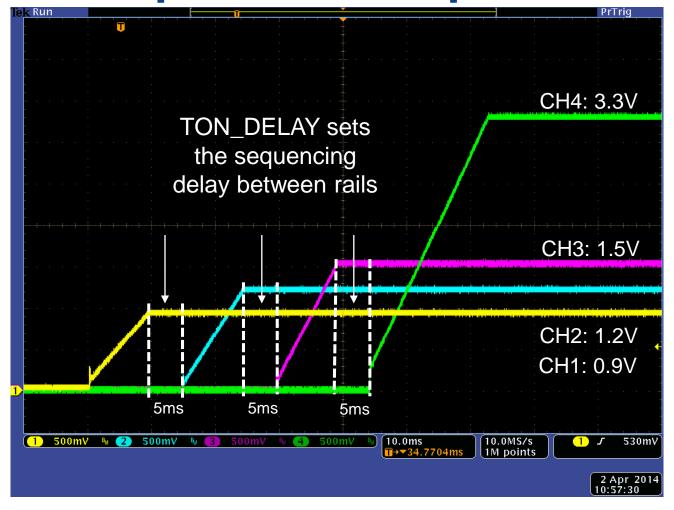
- Event based sequencing waits for the device PGOOD to transition high (the event) before sequential rails start-up
  - Sequence order is set by Prequel/Sequel using the SEQUENCE PMBus command
  - TON\_DELAY is used to set the time delay between sequenced rails
- Timed based sequencing uses a timer from a global enable to sequence rails at start-up.
  - TON\_DELAY sets the sequence order on the way up. TOFF\_DELAY sets the order on the way down.



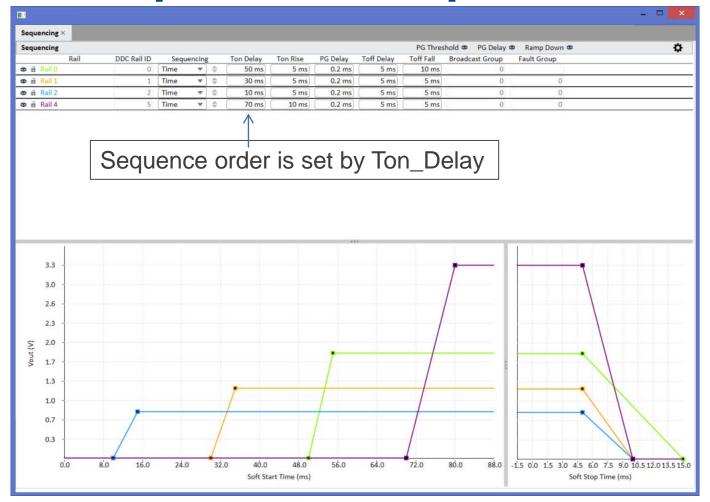
## **Event Based Sequence Example**



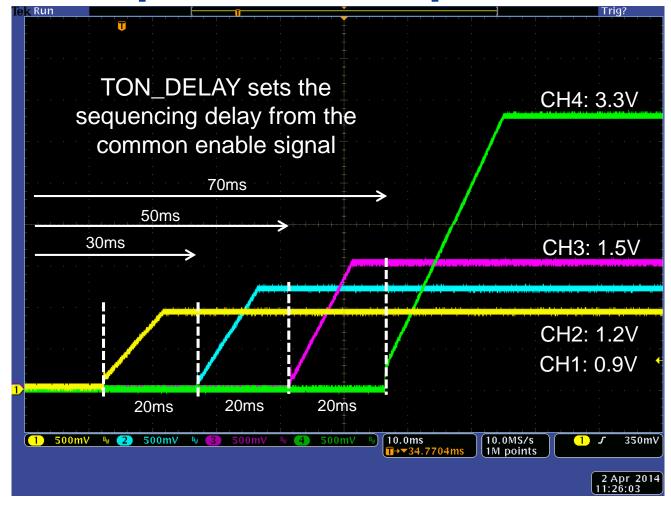
#### **Event Based Sequence Example**



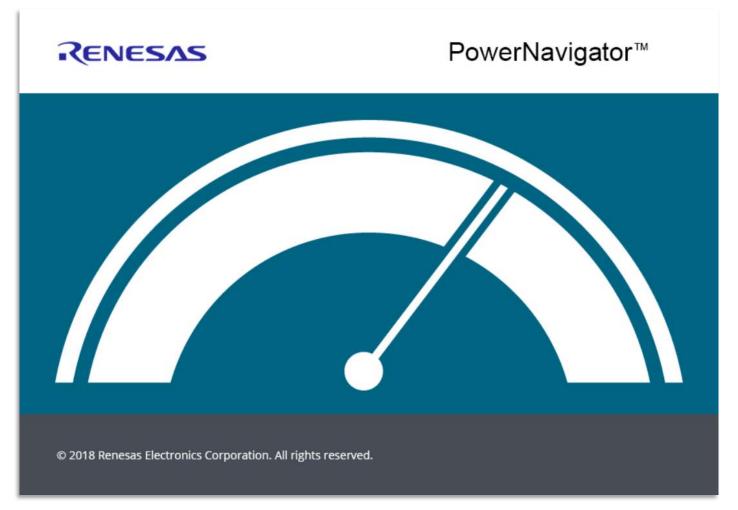
## Time Based Sequence Example



## Time Based Sequence Example



# Railscope



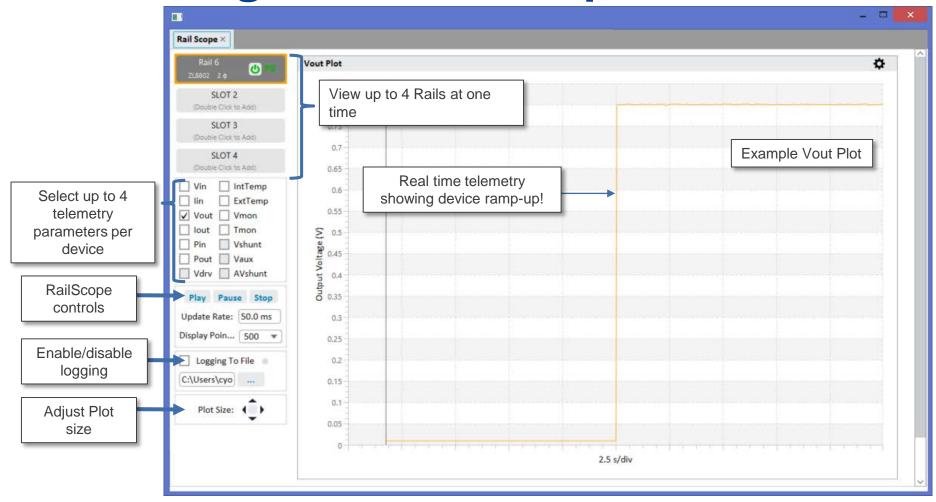
#### PowerNavigator 5.4 – RailScope

- New RailScope allows the user to plot telemetry parameters from up to 4 devices.
  - Similar to a Low Bandwidth Oscilloscope integrated into PowerNavigator.
  - Allows user to plot multiple telemetry values at a time.
- Logging capability is also built-in.
  - All telemetry values can be logged to a .csv file for later viewing.
  - Status registers are also logged.
- Adjustable update rate allows users to control how much data they collect.
  - Data can be updated as fast as 1ms and as slow as 1000ms.
  - Displayed points can be as few as 50 to as many as 500.

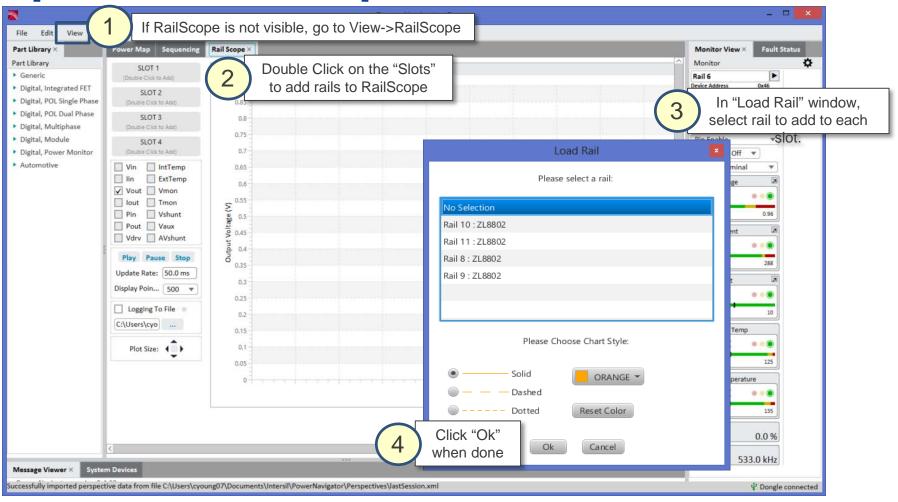


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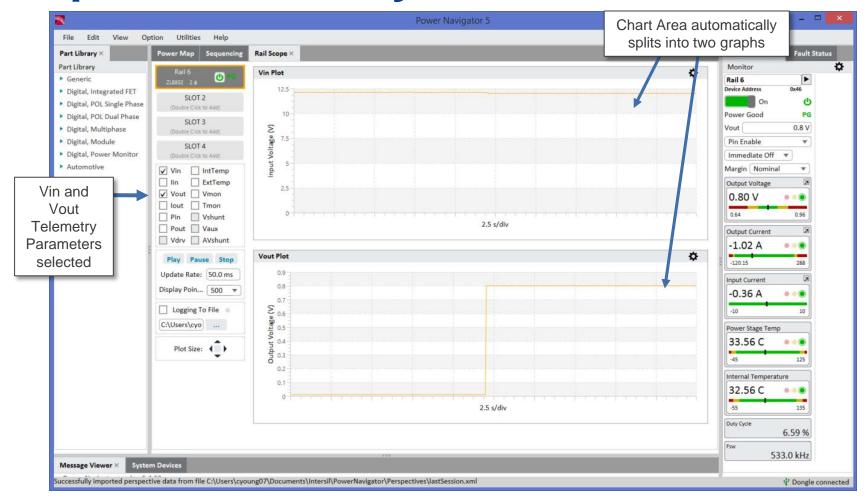
# PowerNavigator – RailScope



#### RailScope: Initial Setup



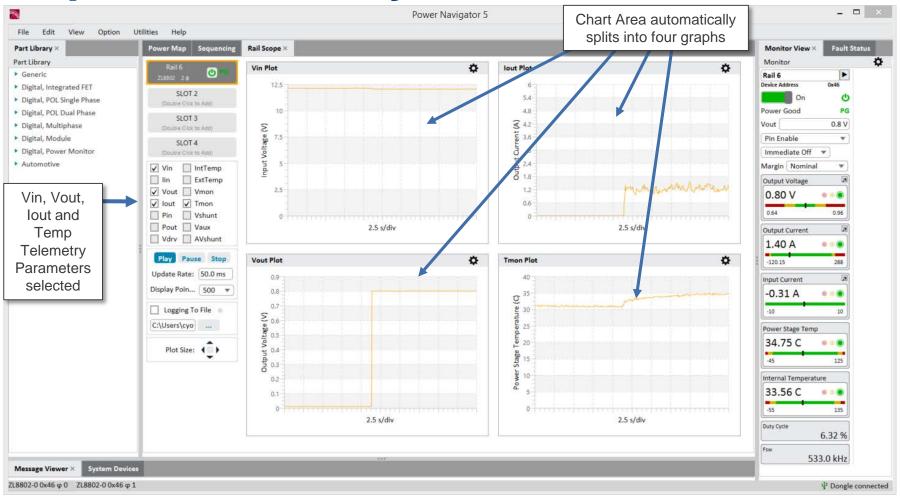
## RailScope: 2 Telemetry Parameters



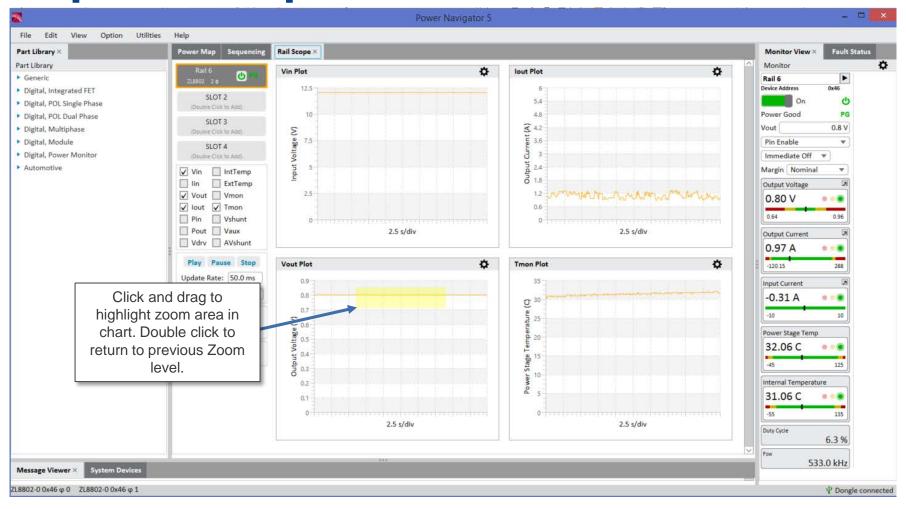
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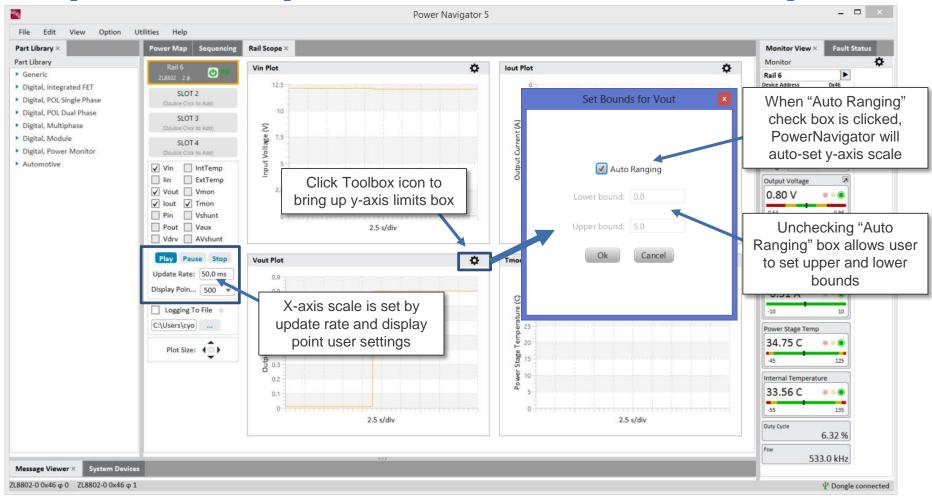
# RailScope: 4 Telemetry Parameters



#### RailScope: Example Zoom-in



# RailScope: Example X & Y-axis Scale Options



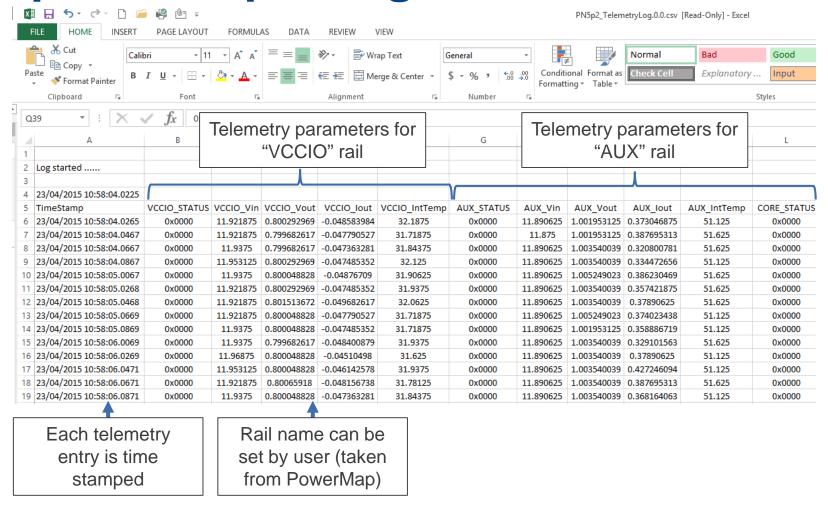
# RailScope: Logging Feature

- Once enabled, logging feature will automatically log all selected telemetry parameters and the STATUS\_WORD register for each device.
- All data is saved to a .csv file, which can be opened in Excel for later data analysis.

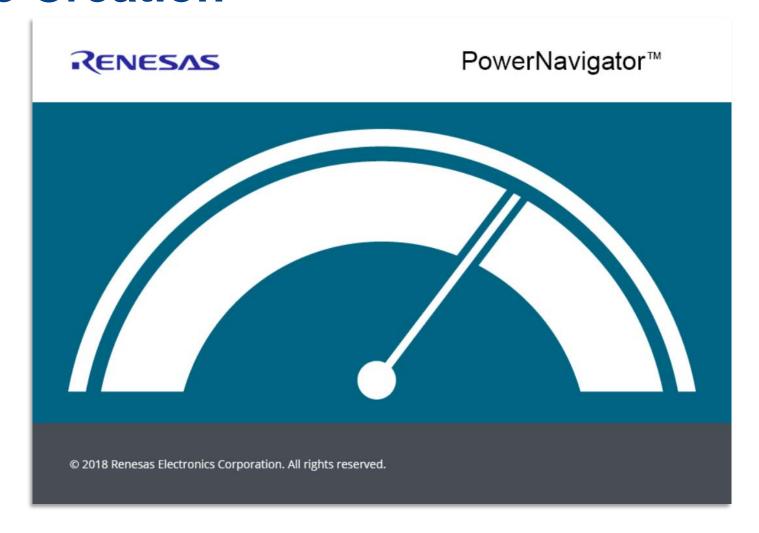
- Once the .csv file size exceeds 50MB, a new file will automatically be created.
- There is no limit on how long logging can run for.
- The log file name and path can be changed by the end user.



# RailScope: Example Log File



#### **HEX File Creation**





# **Configuration File Overview**

- Renesas Digital Power controllers use configuration files to program important device parameters.
  - Configuration files are basically a list of PMBus commands defining device operation. i.e. Vout Command = 1.0V, lout Cal Gain = 0.5mV/A, etc.
- Device configuration only needs to be done one time programmed parameters are stored inside non-volatile memory for future use. NVM supports multiple writes and is re-programmable.

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 Several Options are available for programming devices in a production environment.



#### **Programming Devices in Manufacturing Environment**

#### Option 1: Program controllers pre-board assembly

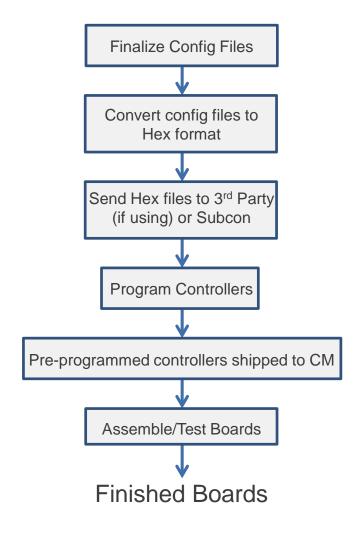
- Devices are programmed on a high speed production programmer before being assembled on a board.
- Can use a supported 3rd party programming house OR offline programmer at subcontractor.

#### Option 2: Program controllers after board assembly

- Devices are programmed on PCB post board assembly
- Can be done at ICT (using a bed of nails approach or onboard microcontroller) OR using Renesas dongle and Production Configuration Tool (PCT).
- Requires board to be powered up with all controllers DISABLED until they are fully programmed.

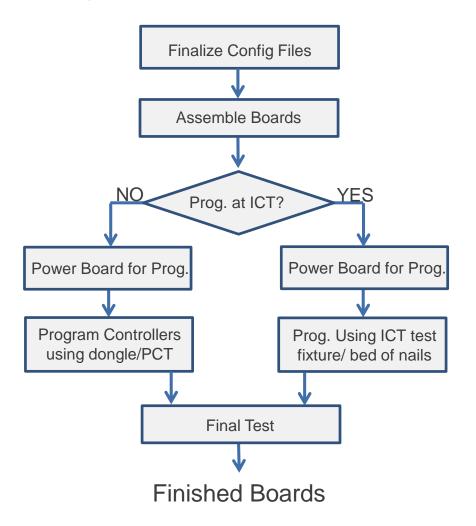


# Typical Flow – Pre-Programmed Devices



- Controllers are programmed prior to PCB manufacture.
- Hex files are created using PowerNavigator software (File->Export Production Hex).
- Programming is done either with a 3rd party or using offline programmer at subcon.
- Typical programming time: 4-7 seconds per device.
- Individual part numbers are assigned to each device after programming to make sure boards are assembled correctly.

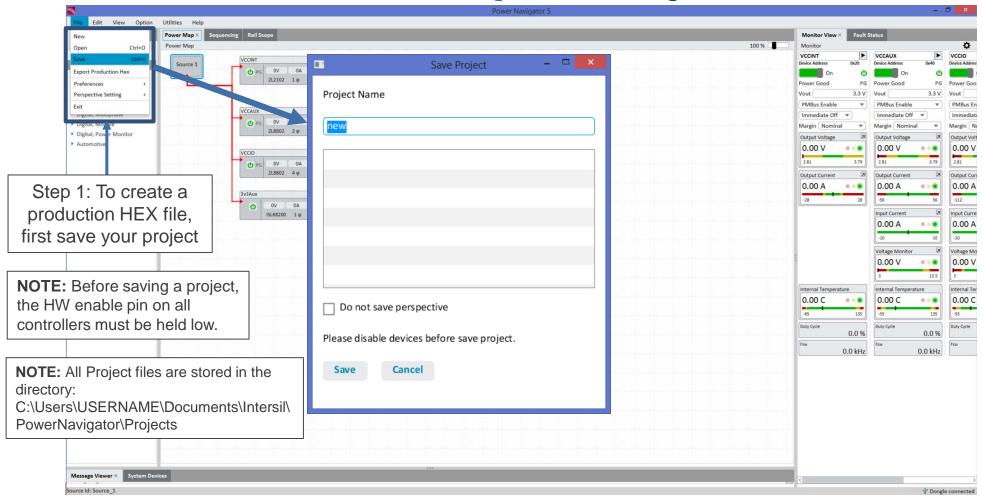
# Typical Flow – Programming Parts on Board



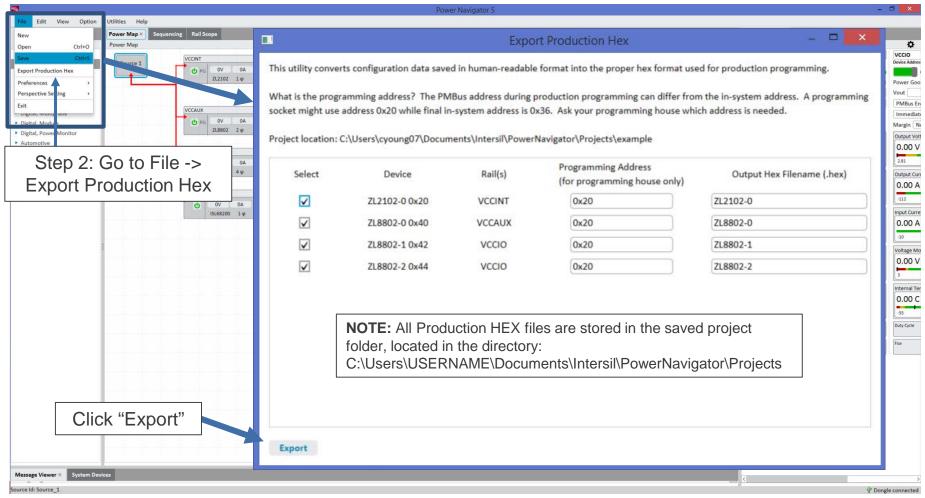
- Controllers are programmed after board assembly.
- Typical Programming time: 5-10s per device.
- Simplified inventory and configuration file management.
- Controllers must be powered to program, but output must remain disabled until part is fully programmed.
- Special attention to sequencing must be made when using self-enabled parts.

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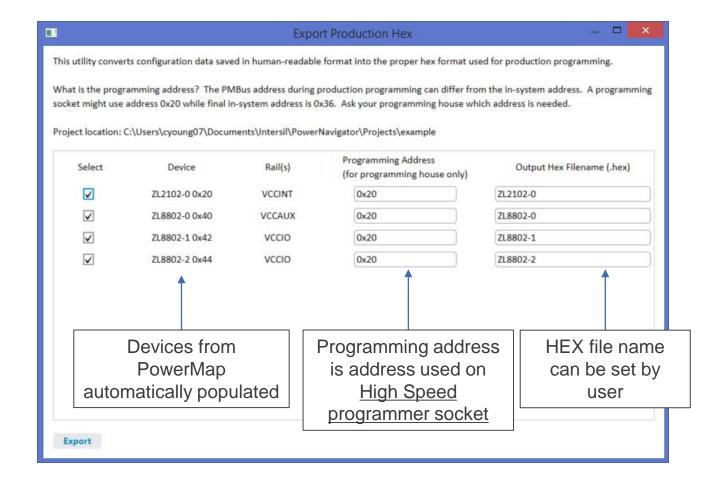
# HEX File Creation – Step 1, Project Save



# **HEX File Creation – Step 2, Export HEX Files**



#### **Example HEX File Creation**



## **Example Configuration File**

```
# ZL8800-0 0x28
                                                                    Header information with device type,
# connected: true
                                     ZL8800----01.04
# DEVICE_ID
                                                                   FW version, creation date, etc.
                                     0x49A02400
# IC_DEVICE_ID
# IC_DEVICE_REV
                                     0x01040000
# 2014/01/16 17:55:45000
RESTORE_FACTORY
                                           This sequence of commands is
STORE_DEFAULT_ALL
STORE_USER_ALL
                                           used to clear contents of NVM.
### Begin User Store
RESTORÉ_USER_ALL
# Global commands
                                   0xfa50
                                                       # 296 kHz
FREQUENCY_SWITCH
                                   0xd380
VIN_OV_FAULT_LIMIT
                                                       # 14 V
VIN_OV_FAULT_RESPONSE
                                   0x80
                                                       # 13.5 V
                                                                    Programmed device parameters
VIN_OV_WARN_LIMIT
                                   0xd360
                                                       # 4.734 V
VIN_UV_WARN_LIMIT
                                   0xca5e
                                                       # 4.594 V
VIN_UV_FAULT_LIMIT
                                   0xca4c
VIN_UV_FAULT_RESPONSE
                                   0x80
                                   0xba00
                                                       # 1 mV/A
IIN_CAL_GAIN
USER_GLOBAL_CONFIG
                                   0x80
                                   0x80
VMON_OV_FAULT_RESPONSE
VMON_UV_FAULT_RESPONSE
                                   0x80
PRIVATE_PASSWORD
PUBLIC_PASSWORD
```

#### **Example HEX File**

000340F499 000440F10087 0003401530 000440F10087 000340112C 000440F10087 00054046C0DB82 0005404B80D562 l000540E720DBE2 l000540E800D628 000440D80193 00054038E9C295 l0005403924C4E8 000540D0C0AB01 000440DCAC8D 000D40D50940CC7BF0AEFC60997B74 l000540D750A2C9 0003401120 000440F10087 0003401225 000440F10087

Configuration file translated into machine readable HEX format.



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