

## PureTouch™\* Capacitive Touch Sensor IC Configuration Registers Detailed Register Information and Default Values

#### **Purpose:**

The purpose of this document is to provide detail on the registers available for configuration and performance optimization of the LDS6107 device.

#### Scope:

This register document covers the LDS6107 (13-channel touch controller). The other members of the LDS61xx family have their own Detailed Register documents as the relevant bit locations vary by device.

#### Initialization:

Not all registers need to be initialized under normal usage conditions, as the default conditions may be appropriate and certain functions and features may not be used in the application.

However, the following registers should be initialized in all cases, as their proper configuration is necessary for fundamental operation:

- 0x00A: DCM configuration
  - Pin C4/DCM11 is set as a DCM pin by default. It must be reset during initialization if not used as a DCM pin.
- 0x041 and 0x042: Touch Sensor Enable
  - Only those channels to be used as sensor input should be set to the "1" state. All other bits in these registers (including reserved/unused bits) should be set to "0"
- 0x043 and 0x044: Touch Interrupt Enable
  - To enable proper interrupt operation, these registers should be configured identically to the Touch Sensor Enable registers 0x041 and 0x042
- 0x061-0x073 (non-contiguous, memory page 1): Touch Threshold Levels
  - Sets the touch threshold levels which affect the sensitivity of each sensor.
  - Register 0x05F should be set to Memory Page 1 prior to writing to these registers

If using Low Power/Sleep mode, the following registers should be initialized:

- 0x055: Idle Configuration Register
  - Set value to 24 (dec) to enable sleep period configuration (0x056) in 1ms increments
- 0x056: Sleep Period Configuration
  - Sets the sleep period between scan cycles. See the LDS61xx AN1 application note for more information.
- 0x003: Sleep Wait
  - Sets the time the device will wait after the last touch before reverting back to Low Power mode

#### **Configuration Register Map and Description**



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#### **Recommended Initialization:**

The following registers are recommended to be initialized for optimized operation.

#### 0x04E: SELC\_Unit Configuration

• Determines SELC unit steps utilized during calibration process. Use of adaptive SELC algorithm will accelerate calibration process. Recommended register setting: 5000h.

#### • 0x051: Ambient Calibration

•Determines how quickly ambient calibration occurs when no-touch value drifts above/below the plus/minus noise region. Recommended register setting: 0A1Fh.

#### • 0x052: Recalibration Configuration

• Sets the delay before a recalibration is initiated when capacitive signal is above the ambient threshold and below the touch threshold. The default IC value (99 decimal) results in a delay of "0.8s x # of active sensor channels". When few sensor channels are utilized, this may result in too short a delay. This delay should be at least 4-5s to avoid calibrating out an approaching finger.

#### 0x053: Stuck Touch

• Determines how quickly forced recalibration occurs when touch persists for abnormally long length of time. Optimal setting depends upon usage model.

#### • 0x061-0x073 (non-contiguous, memory page 0): Initial SELC

 Sets the starting value for SELC for each sensor. Loading initial SELC values for each sensor will result in faster recalibration times. Recommended setting determined during prototype stage.

#### • 0x075: Touch Hysteresis

• Sets the amount of capacitance value units below Touch Threshold to still be considered a continuation of current/active touch. Recommended register setting: 0005h to 000Ah.

By default, the INTB (Interrupt) pin is configured as an active-low CMOS output, with a fixed duration of 2us when a touch or untouch event occurs. INTB may also be configured as active high (0x008 bit 15 = 1) and as an open drain output requiring a pull-up or pull-down resistor (0x008 bit 3 = 1), depending upon system requirements.

Finally, INTB may also be configured in "Read Reset" mode (0x008 bit 1 = 1), in which case Touch Status Register 0x045 must be read in order to release/reset the INTB pin. Read Reset mode corresponds to the default INTB mode of operation of IDT's LDS60xx family of products.

#### **Configuration Register Map and Description**



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#### **Functional Groupings**

Function	Register	Description
RESET	0x000 0x001	Cold Reset Software Reset
POWER	0x002 0x055 0x056 0x003	Normal Operation, Low Power Mode, Shutdown Idle Time - For Low Power Mode Sleep Configuration Sleep Wait
INTERRUPT	0x008 0x043-0x044	INTERRUPT Configuration Touch Interupt Enable
GPIO	0x009	GPIO Config
DCM	0x00A	DCM Mode
MANUFACTURER ID	0x01F	Manufacturer/Product Family ID
TOUCH CONFIGURATION	0x040 0x041 - 0x042 0x05F	Touch mode - All touches reported, Strongest Touch, Dual Strongest Touches Touch Sensor Enable Touch Parameter Memory Page Selection
TOUCH STATUS	0x045 - 0x046 0x084 - 0x0CD (non-contiguous)	Touch Status Cap Value (Read Only)
THRESHOLD SETTING (SENSITIVITY)	0x05F 0x061 - 0x073	Touch Parameter Memory Page Selection - Touch threshold conditions Touch Threshold Value (Memory Page 1)
BUILT-IN SLIDER/SCROLL	0x04B 0x074	Slider/Scroll Position and Direction Reading Slider/Scroll Enable
CALIBRATION & SELC	0x04E 0x050 0x051 0x052 0x053 0x05F 0x061 - 0x073 (non-contiguous) 0x084 - 0x0CD (non-contiguous)	SELC Step Size, Ambient Calibration Enable, Calibration Status Calibration Timeout Ambient Calibration Recalibration Configuration Stuck Touch (Forced Recalibration) Touch Paramater Page Selection  Calibration Parameters (Memory Pages 0, 2, 3, and 4)  SELC Value (Read Only)
STRONGEST TOUCH CONFIGURATION	0x040 0x057 0x075	Strongest Touch Enable Strongest Touch Replacement Time Strongest Touch Hysteresis
RELATIVE STRONGEST\ TOUCH	0x076	Relative Strongest Touch Mode Enable
UNDEBOUNCE	0x076	# of consecutive scan cycles required before untouch is recognized
DEBOUNCE	0x057	Debounce time criteria
HYSERESIS	0x075	Touch Hysteresis Value + Strongest Touch Hysteresis
GUARD/SUPPRESS CHANNEL	0x07C-0x07D 0x07E-0x07F	Guard Channel Enable Guard Channel Mask
NOISE IMMUNITY	0x077	Set to 8001 (hex) for optimal noise filtering.





									Reset								
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x000	W		Cold Reset														
0x001	W	W Software Reset															

Register Name	Position	Description	Function	Remark
COLD RESET		Hardware reset	Any value invokes HW reset (all configuration registers revert to default)	
SOFT RESET		Software reset	Any value invokes SW reset (keeps user settings, but recalibrates)	

								F	OWER								
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x002	R/W							Internal	Internal							LP	SHUTDOWN
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
LP	[1]	power saving mode	0 : Normal mode, 1 : Low Power Mode	
SHUTDOWN	[0]	shutdown mode	0 : Normal mode, 1 : Shutdown mode (only Serial I/F bus active)	

			SLEEP WAIT														
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x003	R/W		SLEEP WAIT														
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
		Full Power to Low Power wait time	Wait time = SLEEP WAIT x Scan Cycle Time	
SLEEP WAIT	[15:0]		(Scan Cycle Time = ~2ms x # of active sensors)	

								INT	<b>B</b> Confi	g							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x008	R/W	INT_POL	Internal										INTB [	DRIVE		INTB	MODE
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
INT POL	[15]	interrupt polarity	0 : active Low, 1: active High	
INTB DRIVE	[4:3]	interupt drive	0x0 : CMOS output	
			0x1 : OPEN-DRAIN output (pull up resistor required)	
INTB MODE	[1:0]	interupt signaling type	00: Fixed Duration Mode (INTB pin drives for 2us Fixed Duration)	
			01: Internal mode	
			1x: Read Reset Mode (INTB pin drives until Register 0x045 is read)	

								GPI	O Confi	g							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x009	R/W												GPI	O Input Co	onfig	GP	1/0
Default Values	0002h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0

Register Name	Position	Description	Function	Remark
GPIO Input Config	[4:2]	GPIO input configuration	0x0 : not used	
			0x1 : negative level-sensitive 0x2 : positive level-sensitive	
			0x3 : not used	
			0x4 : not used	
			0x5 : negative edge-triggered	
			0x6 : positive edge-triggered	
			0x7 : both edge-triggered	
GPI/O	[1:0]	GPIO state	0x0 : not used	
			0x1 : input	
			0x2 : active low output	
			0x3 : active high output	

## Configuration Register Map and Description



								DC	M Confi	g							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x00A	R/W							Internal	DCM11		Internal			DCM9	-DCM6		Internal
Default Values	0100h	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
DCM Enable	[8], [4:1]		0 : disable, 1: enable	

									MID								
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x01F	R				Inte	rnal				Manufac	cturer ID			Devic	e ID		
Default Values	00F2h	0	0	0	0	0	0	0	0	1	1	1	1	0	0	1	0

Register Name	Position	Description	Function	Remark
Manufacturer ID	[7:4]	IDT PureTouch	IDT PureTouch = 1111	
Device Family ID	[3:0]	LDS61xx Family	LDS61xx Family = 0010	

					TOUCH CONFIG														
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0		
0x040	R/W	TCH_ENABLE		Internal				BUTTON	N_MODE			Inte	rnal	READY	[	Decimation			
Default Values	8030h	1	0	0	0	0	0	0	0	0	0	1	1	0	0	0	0		

Register Name	Position	Description	Function	Remark
TCH_ENABLE	[15]	Touch Function Enable	0 : Touch function in idle state, 1: Touch function in active state	
BUTTON_MODE	[9:8]	Touch Preference Mode (Strongest Touch Modes)	0x0 : Unrestricted mode, All touches reported 0x1 : Strongest Touch Mode	
			0x2 : Two Strongest Touches Mode	
			0x3 : reserved	
DEVICE_READY	[3]	Device Ready	0 : Self initialization state, 1: OK for host communication If DEVICE_READY=0, all bits except DEVICE_READY should be ignored.	Read Only Bit
Decimation	[2:0]	CDC decimation	0x0 : 1024 (default)	Consult IDT
			0x1 : 512 0x2 : 256	representative if decimation
			0x3 : 128	is changed from
	II		0x4 : 2048	1024 default

							Touch S	Sensor E	nable (0	Channel	s 0-4)						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x041	R/W							Internal	C4		Internal		C3-C0			Internal	
Default Values	001Eh	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	0

							Touch S	ensor E	nable (C	hannels	5-12)						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x042	R/W							C12	C12-C11		rnal			C10	)-C5		
Default Values	0100h	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
TOUCH_ENBL	[8], [4:1]	Touch enable for each channel	0 : Channel disabled as touch sensor	
	[9:8], [5:0]		1 : Channel enabled as touch sensor (may be overridden by LED Enable)	
			DCM register 0x00A has priority over 0x041 in case of dual assignment	

							INTERR	UPT EN	ABLE (C	Channel	s 0-4)						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x043	R/W							Internal	C4		Internal INT_ENABLE (C3-C0)			Internal			
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

							NTERR	UPT EN	ABLE (C	hannels	5-12)						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x044	R/W							C12-	-C11	Inte	rnal		INT	_ENABL	E (C10-0	C5)	
Default Values	0300h	0	0	0	0	0	0	1	1	0	0	0	0	0	0	0	0

	Register Name	Position	Description	Function	Remark
ı	TOUCH_INT_EN	[8], [4:1]	Touch interrupt enable for each channel	0 : disable	
١		[9:8], [5:0]	·	1 : enable	
- 1					i

## Configuration Register Map and Description



							TOU	CH STAT	TUS (Ch	annels 0	)-4)						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x045	R							Internal	C4		Internal		Touch Status (C3-C0)			Internal	
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

						TOUCH STATUS (Channels 5-12)											
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x046	R	GPI_INT						C12-	-C11	Inte	rnal		To	uch Stati	us (C10-0	C5)	
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
GPI_INT	[15]	GPI interrupt status	0 : no GPI interrupt, 1 : GPI interrupt	
			(Used if GPIO is configured as input via Register 0x009)	
TOUCH_INT_STS	[8], [4:1]	Touch interrupt status for each channel	Indicates which touch sensor channel was activated by a touch when	
	[9:8], [5:0]	·	INTB signal is triggered	

		SCROLL STATUS															
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x04B	R/W	Internal	Internal							SCROLL_INT	DIR_ENBL	SCROLL_DIR		P	OSITION_I	D	
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
SCROLL_INT	[7]	Scroll/Slider Touch Interrupt	0 : Not Touched	Read Only Bit
		•	1 : Position Interrupt Status	-
DIR_ENBL	[6]	Scroll/Slider Touch Direction	0 : Not movement	
		Enable(Active) Status	1 : Direction Enable(Active)	
SCROLL_DIR	[5]	Scroll/Slider Touch Direction Status	0 : Low/Left/CCW Direction	Read Only
			1 : High/Right/CW Direction	
POSITION_ID	[4:0]	Scroll/Slider Touch Position ID	- Value : 0 (Not Used for Scroll/Slider Input Type)	Read Only
_	' '		- Value : 1~10 (Scroll/Slider Touch Position ID)	

						SE	LC CON	FIG and	CALIBR	ATION	STATUS						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x04E	R/W	Internal	ACTIVE	AMB_DIS	Internal										SELC	UNIT	
Default Values	0002h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0

Register Name	Position	Description	Function	Remark
ACTIVE	[14]	touch calibration status	0 : in calibration state	Read Only Bit
			1 : calibration finished	-
AMB_DIS	[13]	ambient calibration disable	0 : ambient calibration active	Optional disabling
			1 : disable ambient calibration	of ambient cal
SELC_UNIT	[3:0]	SELC change amount during calibration	0 : adaptive SELC tracking algorithm used	Refer to 6100
	[		others: During tracking, SELC changes its value by the amount of SELC_UNIT	AN2 App Note

							C	ALIBRA	TION TIM	MEOUT							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x050	R/W	Internal	Inte	rnal									CALIB_T	IMEOUT			
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
CALIB_TIMEOUT	[7:0]	calibration timeout limit	0x0 : infinite	
			0x1 : when calibration iteration reaches CALIB_TIMEOUT, tracking is done.	

							A	<b>MBIENT</b>	CALIBR	RATION							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x051	R/W	CNT DEC LIMIT CNT INC LIMIT															
Default Values	1F1Fh	0	0	0	1	1	1	1	1	0	0	0	1	1	1	1	1

Register Name	Position	Description	Function	Remark
CNT_DEC_LIMIT	[15:8]	Value determines how quickly ambient	0x0 : INVALID	
		calibration is triggered (negative side)	others : count limit	
CNT_INC_LIMIT	[7:0]	Value determines how quickly ambient calibration is triggered (posative side)		
		cameration is triggered (posative side)	Saloro . South min	





				RECALIBRATION CONFIGURATION													
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x052	R/W										RE	CAL_DEL	.AY				
Default Values	0063h	0	0	0	0	0	0	0	0	0	1	1	0	0	0	1	1

Register Name	Position	Description	Function	Remark
RECAL_DELAY	[10:0]	Wait time prior to forced recalibration	wait time = (RECAL_DELAY+1) * single round time * 4	Default is 0.8s
		when cap value above ambient threshold	Max time = 16.4s (1 ch) to 213s (13ch)	x # of active ch
		but below touch threshold (i.e. not an		with 1024
		actual touch)		decimation

								STU	CK TOU	СН							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x053	R/W										CNT	TOUCH	LIMIT				
Default Values	0063h	0	0	0	0	0	0	0	0	0	1	1	0	0	0	1	1

Register Name	Position	Description	Function	Remark
CNT_TOUCH_LIMIT	[10:0]	Wait time prior to forced recalibration	wait time = (CNT_TOUCH_LIMIT+1) * single round period * 4	Default is 0.8s
		when cap value is above threshold level	Max time = 16.4s (1 ch) to 213s (13ch)	x # of active ch
		(stuck touch scenario)		with 1024
		,		decimation

		IDLE CONFIG															
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x055	R/W		MAX_DEÂCT_IDLE														
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
MAX_DEACT_IDLE	[15:0]	staying IDLE time during inactive touch	Idle time = (MAX_DEACT_IDLE+1) * OSC period (2us)	Init file must set
		channel selected	All channels treated as inactive during Sleep Period	this to 24(dec)
				to enable 1ms
				increments of
				SLEEP_TIME
				with 1024
				decimation

								SLEE	P CONF	ig.							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x056	R/W	SLEEP TIME															
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
SLEEP_TIME	[15:0]	# of ms of desired sleep time	Determines duty cycle between active (full power) and sleep (reduced	Init file must set
			power) that determines average current consumption in low power mode	0x055 to
				24(dec) to
				enable 1ms
				increments of
				SLEEP_TIME
				with 1024
				decimation

					DE	BOUNC	E AND	STRONG	EST TO	UCH C	ONFIGU	RATION					
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x057	R/W		DEBO	UNCE						F	REPLACEN	MENT_TIM	E				
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
DEBOUNCE	[15:12]	# of consecutive scan cycles required	Debounce time criteria required to register first touch	
		before first touch is recognized	Time = DEBOUNCE x scan cycle time, where scan cycle time is	
			equal to 2ms x # of active sensors	
REPLACEMENT_TIME	[11:0]	# of consecutive scan cycles required	Strongest Touch Mode (Absolute or Relative) option to minimize frequent	Set to "0"
		for new touch with strongest signal to	toggling between two touches of comparable strength	for Two
		replace current strongest touch	Time = REPLACEMENT_TIME x scan cycle time, where scan cycle	Strongest
			time is equal to 2ms x # of active sensors	Touch





						T	OUCH P.	ARAME	TER PAG	GE SELE	CTION						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x05F	W			0:initial SE	LC, 1: touc	h threshol	ld, 2:ambie	ent thresho	ld, 3:minu	s noise lev	el, 4:plus i	noise level				PAGE	
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
PAGE	[2:0]	indirect memory access address	0 : Initial SELC (May be used to accelerate calibration times)	Refer to 6100
			Please refer to 6100 AN2 app note for detaills	AN2 App Note
			1 : Touch Threshold (# capacitive units above baseline to activate touch)	
			2 : Ambient Threshold (Defines region, along with touch threshold,	
			within which recalibration is delayed by RECAL_DELAY 0x052)	
			3 : Minus Noise Level (Defines - region within which baseline may vary	
			without triggering an ambient recalibration)	
			4 : Plus Noise Level (Defines + region within which baseline may vary	
			without triggering an ambient recalibration)	

							1	OUCH	PARAME	TERS							$\neg \neg$
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11			Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x061	W										Touc	h0 PARAN	/[10:0]				
0x062	W										Touc	h1 PARAN	Λ[10:0]				
0x063	W										Touc	h2 PARAN	Λ[10:0]				
0x064	W										Touc	h3 PARAN	Λ[10:0]				
0x068	W										Touc	h4 PARAN	Λ[10:0]				
0x06A	W										Touc	h5 PARAN	Λ[10:0]				
0x06B	W										Touc	h6 PARAN	Л[10:0]				
Эx06C	W						Touch7 PARAM[10:0]										
Ĵx06D	W										Touc	h8 PARAN	Λ[10:0]				
0x06E	W										Touc	h9 PARAN	Л[10:0]				
0x06F	W										Touch	10 PARAI	M[10:0]				
0x072	W										Touch	11 PARAI	M[10:0]				
0x073	W										Touch	12 PARAI	M[10:0]				
Default Values (PAGE=0)	00B8h	0	0	0	0	0											
Default Values (PAGE=1)	0028h	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0	0
Default Values (PAGE=2)	000Ah	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0
Default Values (PAGE=3)	0003h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	1
Default Values (PAGE=4)	0003h	0	0	0	0	0											

Register Name	Position	Description	Function	Remark
Touch PARAM	[10:0]	multiplexed touch parameter	0 : Initial SELC (May be used to accelerate calibration times)	Refer to 6100
	1 1		Please refer to 6100 AN2 app note for detaills	AN2 App Note
	1 1		1 : Touch Threshold (# capacitive units above baseline to activate touch)	
	1 1		2 : Ambient Threshold (Defines region, along with touch threshold,	
	1 1		within which recalibration is delayed by RECAL_DELAY 0x052)	
	1 1		3 : Minus Noise Level (Defines - region within which baseline may vary	
	1 1		without triggering an ambient recalibration)	
			4 : Plus Noise Level (Defines + region within which baseline may vary without triggering an ambient recalibration)	

							SCROLI	_/SLIDE	R CHAN	NEL EN	ABLE						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x074	R/W	INT_SEL			Inte	rnal			SCE C4		Internal		Scro	II Channel	Enable (C	3-C0)	Internal
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
INT_SEL	[15]	SCROLL/SLIDER Touch channel	0 : disable, 1: enable	
		Interrupt Enable		
SCROLL CH[4]	[8]	channel 4 Scroll/Slider Touch Enable	0 : disable, 1: enable	
SCROLL_CH[3]	[4]	channel 3 Scroll/Slider Touch Enable	0 : disable, 1: enable	
SCROLL_CH[2]	[3]	channel 2 Scroll/Slider Touch Enable	0 : disable, 1: enable	
SCROLL_CH[1]	[2]	channel 1 Scroll/Slider Touch Enable	0 : disable, 1: enable	
SCROLL CH[0]	[1]	channel 0 Scroll/Slider Touch Enable	0 : disable, 1: enable	





								TOUCH	HYSTE	RESIS							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x075	R/W			S1	R_HYSTE	RESIS[15	:8]						HYSTER	ESIS[7:0]			
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
STR_HYSTERESIS	[15:8]		Extra/additional capacitance value required for new strongest touch to replace current strongest touch. For example, if STR_HYSTERESIS is set to a value of 15 (decimal), the capacitance value required to displace the current strongest touch must be at least 15 capacitance units higher than the current value of the current strongest touch.	
HYSTERESIS	[7:0]	Touch Hysteresis Value (# of cap value units permitted to decrease below Touch Threshold while still maintaining touch status)	Value range: 0–255 Example: Assuming baseline value of 510 and Touch Threshold setting of 40, capacitive value above 550 triggers an initial touch event. If HYSTERESIS value is set to "15", then the sensor capacitive value may go as low as 535 (550-35) and still be considered as original touch.	

						REL	ATIVE S	STRONG	EST AN	D UNDE	BOUNC	E					
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x076	R/W	RELATIVE_EN	INTERNAL											Ī	JN_DEBO	JNCE [3:0	]
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
RELATIVE_EN	[15]	Relative Strongest Touch Mode	0 : disable, 1: enable	
UN_DEBOUNCE	[3:0]	# of consecutive scan cycles required	Debounce time required for UNtouch event to be recognized	
		before UNtouch is recognized	Time = DEBOUNCE x scan cycle time, where scan cycle time is	
			equal to 2ms x # of active sensors	

							NC	ISE IMN	JUNITY	ENABLE							
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x077	R/W	NI_ENBL		INTERNAL NI_OPTION													
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
Noise Immunity EN	[15]	Enable Noise Immunity	0 : disable, 1: enable. Recommended Value = 1	Set to "1"
Noise Immunity	[11:0]	Noise Immunity Option	Setting Options. Recommended Value = 1	
Option				Set to "1"

		Guard Channel Enable Register [C0~C10]															
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x07C	R/W			GUARD	CH[10:5	5]		INTERNAL	GC4		Internal			GUARD	_CH[3:0]		INTERNAL
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
GUARD CH[10]	[15]	channel 10 guard channel enable	0 : disable, 1: enable	
GUARD_CH[9]	[14]	channel 9 guard channel enable	0 : disable, 1: enable	
GUARD_CH[8]	[13]	channel 8 guard channel enable	0 : disable, 1: enable	
GUARD_CH[7]	[12]	channel 7 guard channel enable	0 : disable, 1: enable	
GUARD_CH[6]	[11]	channel 6 guard channel enable	0 : disable, 1: enable	
GUARD CH[5]	[10]	channel 5 guard channel enable	0 : disable, 1: enable	
GUARD_CH[4]	[8]	channel 4 guard channel enable	0 : disable, 1: enable	
GUARD_CH[3]	[4]	channel 3 guard channel enable	0 : disable, 1: enable	
GUARD CH[2]	[3]	channel 2 guard channel enable	0 : disable, 1: enable	
GUARD CH[1]	[2]	channel 1 guard channel enable	0 : disable, 1: enable	
GUARD_CH[0]	[1]	channel 0 guard channel enable	0 : disable, 1: enable	·

						Gu	ard Cha	nnel En	<u>able Re</u>	gister [C	:11-C12]						
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x07D	R/W													GUARD_	CH[12:11]	Inte	rnal
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
GUARD CH[12]	[3]	channel 12 guard channel enable	0 : disable, 1: enable	
GUARD_CH[11]	[2]	channel 11 guard channel enable	0 : disable, 1: enable	





	Guard Channel Mask Register [C0-C10]																
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x07E	R/W	GUARD_MASK[10:5]						INTERNAL	GM4		Internal		GUARD_MASK[3:0]				
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
GUARD_MSK[10]	[15]	channel 10 guard mask enable	0 : disable, 1: enable	
GUARD MSK[9]	[14]	channel 9 guard mask enable	0 : disable, 1: enable	
GUARD MSK[8]	[13]	channel 8 quard mask enable	0 : disable, 1: enable	
GUARD_MSK[7]	[12]	channel 7 guard mask enable	0 : disable, 1: enable	
GUARD_MSK[6]	[11]	channel 6 guard mask enable	0 : disable, 1: enable	
GUARD_MSK[5]	[10]	channel 5 guard mask enable	0 : disable, 1: enable	
GUARD_MSK[4]	[8]	channel 4 guard mask enable	0 : disable, 1: enable	
GUARD MSK[3]	[4]	channel 3 quard mask enable	0 : disable, 1: enable	
GUARD_MSK[2]	[3]	channel 2 guard mask enable	0 : disable, 1: enable	
GUARD_MSK[1]	[2]	channel 1 guard mask enable	0 : disable, 1: enable	
GUARD_MSK[0]	[1]	channel 0 guard mask enable	0 : disable, 1: enable	

	Guard Channel Mask Register [C11-C12]																
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x07F	R/W													GUARD_MSK[12:11]		Internal	
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

Register Name	Position	Description	Function	Remark
GUARD MSK[12]	[3]	channel 12 guard mask enable	0 : disable, 1: enable	
GUARD MSK[11]	[2]	channel 11 quard mask enable	0 : disable, 1: enable	

							Cap Value and SELC Value													
Register Address	Direction	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	В	it 2	Bit 1	Bit 0		
0x084	R						Touch0 Cap													
0x085	R	Touch(	SELP								T	ouch0 SE	LC							
0x088	R						Touch1 Cap													
0x089	R	Touch'	1 SELP				Touch1 SELC													
0x08C	R						Touch2 Cap													
0x08D	R	Touch	2 SELP				Touch2 SELC													
0x090	R						Touch3 Cap													
0x091	R	Touch	3 SELP				Touch3 SELC													
0x0A0	R						Touch4 Cap													
0x0A1	R	Touch4	4 SELP				Touch4 SELC													
0x0A8	R						Touch5 Cap													
0x0A9	R	Touch!	SELP								Ī	ouch5 SE	LC							
0x0AC	R											Touch6 C	ар							
0x0AD	R	Touch	6 SELP								Ī	ouch6 SE	LC							
0x0B0	R											Touch7 C	ар							
0x0B1	R	Touch	7 SELP								Ī	ouch7 SE	LC							
0x0B4	R											Touch8 C	ар							
0x0B5	R	Touch	SELP								T	ouch8 SE	LC							
0x0B8	R											Touch9 C	ар							
0x0B9	R	Touch9	9 SELP								T	ouch9 SE	LC							
0x0BC	R											Fouch10 C	Сар							
0x0BD	R	Touch1	0 SELP								T	ouch10 SI	ELC							
0x0C8	R							,				Fouch11 C	Сар				,			
0x0C9	R	Touch1	1 SELP								T	ouch11 SI	ELC							
0x0CC	R											Fouch12 C	Cap							
0x0CD	R	Touch1	2 SELP								T	ouch12 Sl	ELC							
Default Values	0000h	0	0	0	0	0	0	0	0	0	0	0	0	0		0	0	0		

#### **Configuration Register Map and Description**



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