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April 1st, 2010
Renesas Electronics Corporation

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User's Manual

SuperH™ Family E10A-USB Emulator

Additional Document for User's Manual Supplementary Information on Using the SH7201 and SH7261

Renesas Microcomputer Development Environment System

SuperH™ Family / SH7200 Series

SH7260 Series

E10A-USB for SH7261 HS7261KCU01HE

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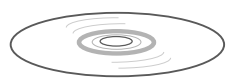
Contents

Section 1 Connecting the Emulator with the User System

1.1 Components of the Emulator

The E10A-USB emulator supports the SH7201 and SH7261 (R5S72611, R5S72612, and R5S72613). Table 1.1 lists the components of the emulator.

Table 1.1 Components of the Emulator

Classi-fication	Component	Appearance	Quan-tity	Remarks
Hard-ware	Emulator box		1	HS0005KCU01H: Depth: 65.0 mm, Width: 97.0 mm, Height: 20.0 mm, Mass: 72.9 g or HS0005KCU02H: Depth: 65.0 mm, Width: 97.0 mm, Height: 20.0 mm, Mass: 73.7 g
	User system interface cable		1	14-pin type: Length: 20 cm, Mass: 33.1 g
	User system interface cable		1	36-pin type: Length: 20 cm, Mass: 49.2 g (only for HS0005KCU02H)
	USB cable		1	Length: 150 cm, Mass: 50.6 g
Soft-ware	E10A-USB emulator setup program, SuperH™ Family E10A-USB Emulator User's Manual, Supplementary Information on Using the SH7201 and SH7261*, and Test program manual for HS0005KCU01H and HS0005KCU02H		1	HS0005KCU01SR, HS0005KCU01HJ, HS0005KCU01HE, HS7261KCU01HJ, HS7261KCU01HE, HS0005TM01HJ, and HS0005TM01HE (provided on a CD-R)

Note: Additional document for the MCUs supported by the emulator is included. Check the target MCU and refer to its additional document.

1.2 Connecting the Emulator with the User System

To connect the E10A-USB emulator (hereinafter referred to as the emulator), the H-UDI port connector must be installed on the user system to connect the user system interface cable. When designing the user system, refer to the recommended circuit between the H-UDI port connector and the MCU. In addition, read the E10A-USB emulator user's manual and hardware manual for the related device.

Table 1.2 shows the type number of the emulator, the corresponding connector type, and the use of AUD function.

Table 1.2 Type Number, AUD Function, and Connector Type

Type Number	Connector	AUD Function
HS0005KCU02H	36-pin connector	Available
HS0005KCU01H, HS0005KCU02H	14-pin connector	Not available
HS0005KCU02H	38-pin connector	Available

The H-UDI port connector has the 36-pin, 14-pin, and 38-pin types as described below. Use them according to the purpose of the usage.

1. 36-pin type (with AUD function)
   The AUD trace function is supported. A large amount of trace information can be acquired in realtime. The window trace function is also supported for acquiring memory access in the specified range (memory access address or memory access data) by tracing.
2. 14-pin type (without AUD function)
   The AUD trace function cannot be used because only the H-UDI function is supported. Since the 14-pin type connector is smaller than the 36-pin type (1/2.5), the size of the area where the connector is installed on the user system can be reduced.
3. 38-pin type (with AUD function)
   The AUD trace function is supported. As well as the 36-pin type, a large amount of trace information can be acquired in realtime. Since the 38-pin type connector is smaller than the 36-pin type (1/2.5), the size of the area where the connector is installed on the user system can be reduced. To use the 38-pin type connector, however, an optional cable (HS0005ECK01H) is required.

1.3 Installing the H-UDI Port Connector on the User System

Table 1.3 shows the recommended H-UDI port connectors for the emulator.

Table 1.3 Recommended H-UDI Port Connectors

Connector	Type Number	Manufacturer	Specifications
36-pin connector	DX10M-36S	Hirose Electric Co., Ltd.	Screw type
	DX10M-36SE, DX10G1M-36SE		Lock-pin type
14-pin connector	2514-6002	Minnesota Mining & Manufacturing Ltd.	14-pin straight type
38-pin connector	2-5767004-2	Tyco Electronics AMP K.K.	38-pin Mictor type

Note: When designing the 36-pin connector layout on the user board, do not connect any components under the H-UDI connector. When designing the 14-pin connector layout on the user board, do not place any components within 3 mm of the H-UDI port connector. When designing the 38-pin connector layout on the user board, reduce cross-talk noise etc. by keeping other signal lines out of the region where the H-UDI port connector is situated. As shown in figure 1.1, an upper limit (5 mm) applies to the heights of components mounted around the user system connector.

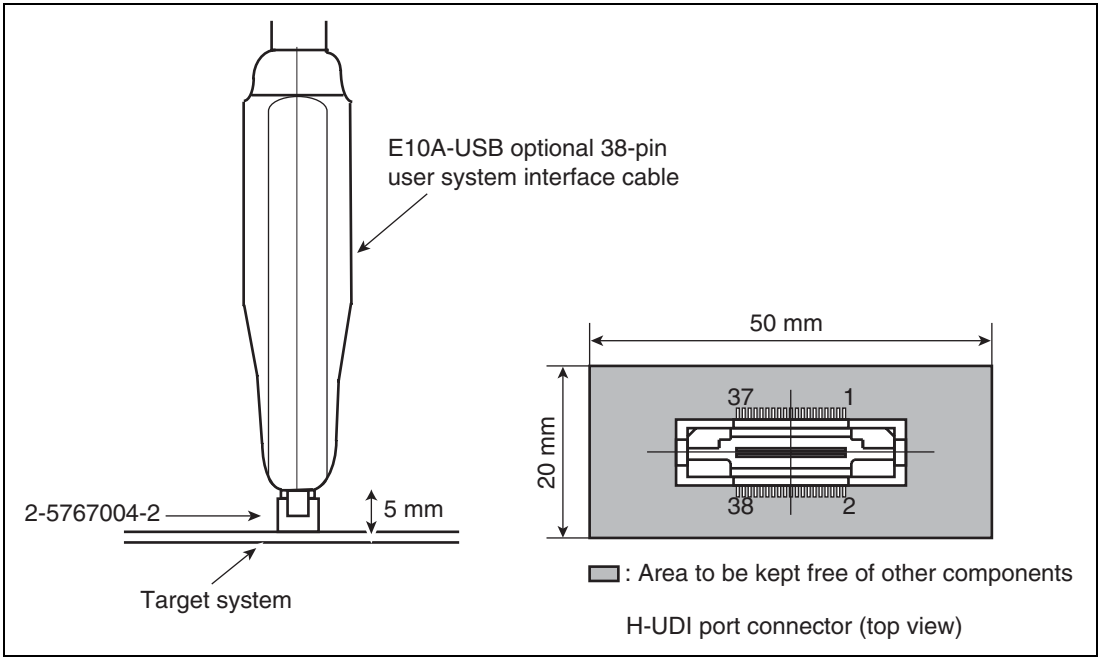


Figure 1.1 Restriction on Component Mounting

1.4 Pin Assignments of the H-UDI Port Connector

Figures 1.2 through 1.4 show the pin assignments of the 36-pin, 14-pin, and 38-pin H-UDI port connectors, respectively.

Note: Note that the pin number assignments of the H-UDI port connector shown on the following pages differ from those of the connector manufacturer.

Pin No.	Signal	Input/ Output*1	SH7201 or SH7261 Pin No.	Note	Pin No.	Signal	Input/ Output*1	SH7201 or SH7261 Pin No.	Note
1	AUDCK	Output	97		19	TMS	Input	128	
2	GND	——			20	GND	——		
3	AUDATA0	Output	99		21	_TRST*2	Input	126	
4	GND	——			22	(GND)*4	——		
5	AUDATA1	Output	100		23	TDI	Input	130	
6	GND	——			24	GND	——		
7	AUDATA2	Output	102		25	TDO	Output	129	
8	GND	——			26	GND	——		
9	AUDATA3	Output	104		27	_ASEBRKAK /_ASEBRK*2	Input/ output	132	
10	GND	——			28	GND	——		
11	_AUDSYNC*2	Output	98		29	UVCC	Output		
12	GND	——			30	GND	——		
13	N.C.	——			31	_RES*2	Output	2	User reset
14	GND	——			32	GND	——		
15	N.C.	——			33	GND*3	Output		
16	GND	——			34	GND	——		
17	TCK	Input	131		35	N.C.	——		
18	GND	——			36	GND	——		

Notes: 1. Input to or output from the user system.
2. The symbol (_) means that the signal is active-low.
3. The emulator monitors the GND signal of the user system and detects whether or not the user system is connected.
4. When the user system interface cable is connected to this pin and the _ASEMD pin is set to 0, do not connect to GND but to the _ASEMD pin directly.

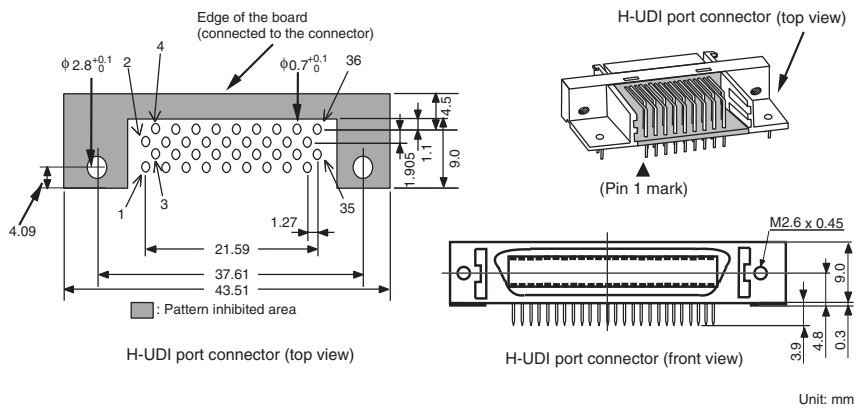


Figure 1.2 Pin Assignments of the H-UDI Port Connector (36 Pins)

Pin No.	Signal		Input/ Output*1	SH7201 or SH7261 Pin No.	Note
1	TCK		Input	131	
2	_TRST	*2	Input	126	
3	TDO		Output	129	
4	_ASEBRKAK / _ASEBRK	*2	Input/ output	132	
5	TMS		Input	128	
6	TDI		Input	130	
7	_RES	*2	Output	2	User reset
8	N.C.		—		
9	(GND)	*4	—		
11	UVCC		Output		
10, 12, and 13	GND		—		
14	GND	*3	Output		

Notes: 1. Input to or output from the user system.
2. The symbol (_) means that the signal is active-low.
3. The emulator monitors the GND signal of the user system and detects whether or not the user system is connected.
4. When the user system interface cable is connected to this pin and the _ASEMD pin is set to 0, do not connect to GND but to the _ASEMD pin directly.

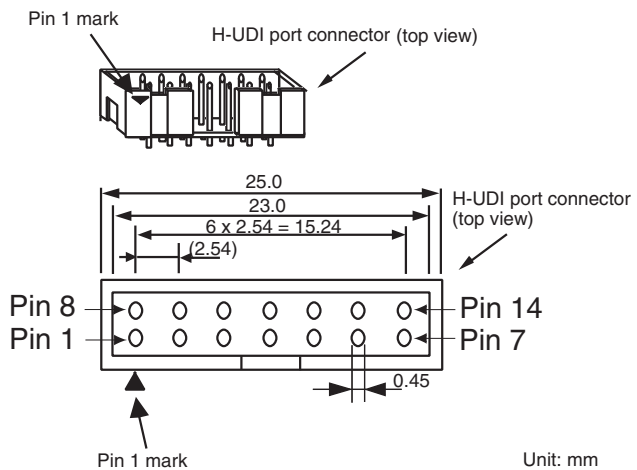
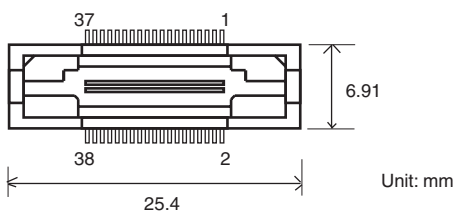


Figure 1.3 Pin Assignments of the H-UDI Port Connector (14 Pins)

Pin No.	Signal	Input/ Output*1	SH7201 or SH7261 Pin No.	Note	Pin No.	Signal	Input/ Output*1	SH7201 or SH7261 Pin No.	Note
1	N.C.	—			20	N.C.	—		
2	N.C.	—			21	_TRST*2	Input	126	
3	_ASEMD (GND)*4	—			22	N.C.	—		
4	N.C.	—			23	N.C.	—		
5	_UCON (GND) *3	—			24	AUDATA3	Output	104	
6	AUDCK	Output	97		25	N.C.	—		
7	N.C.	—			26	AUDATA2	Output	102	
8	_ASEBRKAK/ _ASEBRK*2	Input/ Output	132		27	N.C.	—		
9	_RES*2	Output	2	User reset	28	AUDATA1	Output	100	
10	N.C.	—			29	N.C.	—		
11	TDO	Output	129		30	AUDATA0	Output	99	
12	UVCC_AUD	Output			31	N.C.	—		
13	N.C.	—			32	_AUDSYNC	Output	98	
14	UVCC	Output			33	N.C.	—		
15	TCK	Input	131		34	N.C.	—		
16	N.C.	—			35	N.C.	—		
17	TMS	Input	128		36	N.C.	—		
18	N.C.	—			37	N.C.	—		
19	TDI	Input	130		38	N.C.	—		

Notes: 1. Input to or output from the user system.
2. The symbol (_) means that the signal is active-low.
3. The emulator monitors the GND signal of the user system and detects whether or not the user system is connected.
4. When the user system interface cable is connected to this pin and the _ASEMD pin is set to 0, do not connect to GND but to the _ASEMD pin directly.
5. The GND bus lead at the center of the H-UDI port connector must be grounded.



H-UDI port connector (top view)

Figure 1.4 Pin Assignments of the H-UDI Port Connector (38 Pins)

1.5 Recommended Circuit between the H-UDI Port Connector and the MCU

1.5.1 Recommended Circuit (36-Pin Type)

Figure 1.5 shows a recommended circuit for connection between the H-UDI and AUD port connectors (36 pins) and the MCU when the emulator is in use.

Notes: 1. Do not connect anything to the N.C. pins of the H-UDI port connector.

2. The _ASEMD pin must be 0 when the emulator is connected and 1 when the emulator is not connected, respectively.
   (1) When the emulator is used: _ASEMD = 0
   (2) When the emulator is not used: _ASEMD = 1
   Figure 1.5 shows an example of circuits that allow the _ASEMD pin to be GND (0) whenever the emulator is connected by using the user system interface cable.
   When the _ASEMD pin is changed by switches, etc., ground pin 22. Do not connect this pin to the _ASEMD pin.
3. When a network resistance is used for pull-up, it may be affected by a noise. Separate TCK from other resistances.
4. The pattern between the H-UDI port connector and the MCU must be as short as possible. Do not connect the signal lines to other components on the board.
5. The AUD signals (AUDCK, AUDATA3 to AUDATA0, and _AUDSYNC) operate in high speed. Isometric connection is needed if possible. Do not separate connection nor connect other signal lines adjacently.
6. Since the H-UDI and the AUD of the MCU operate with the PVcc, supply only the PVcc to the UVCC pin. Make the emulator's switch settings so that the user power will be supplied (SW2 = 1 and SW3 = 1).
7. The resistance value shown in figure 1.5 is for reference.
8. For the AUDCK pin, guard the pattern between the H-UDI port connector and the MCU at GND level.
9. The _TRST pin must be at the low level for a certain period when the power is supplied whether the H-UDI is used or not.
10. For the pin processing in cases where the emulator is not used, refer to the hardware manual of the related MCU.

When the circuit is connected as shown in figure 1.5, the switches of the emulator are set as SW2 = 1 and SW3 = 1. For details, refer to section 3.8, Setting the DIP Switches, in the SuperH™ Family E10A-USB Emulator User's Manual.

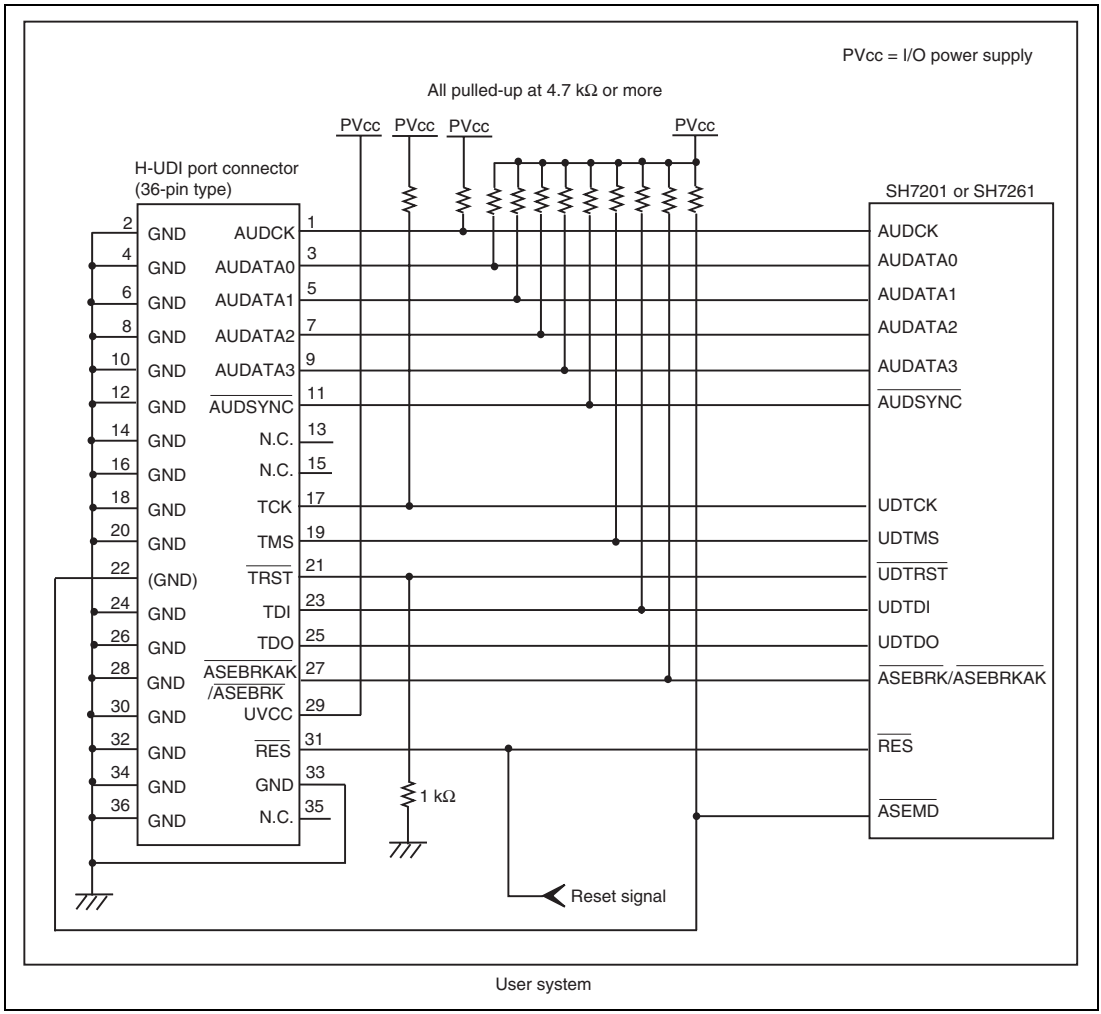


Figure 1.5 Recommended Circuit for Connection between the H-UDI Port Connector and MCU when the Emulator is in Use (36-Pin Type)

Note: When the emulator is used, the AUD trace mode is set without using AUDMD or _AUDRST. If those functions are enabled, do not set these pins in PFC because the settings of AUD will be changed.

1.5.2 Recommended Circuit (14-Pin Type)

Figure 1.6 shows a recommended circuit for connection between the H-UDI port connector (14 pins) and the MCU when the emulator is in use.

Notes: 1. Do not connect anything to the N.C. pins of the H-UDI port connector.

2. The _ASEMD pin must be 0 when the emulator is connected and 1 when the emulator is not connected, respectively.
   (1) When the emulator is used: _ASEMD = 0
   (2) When the emulator is not used: _ASEMD = 1
   Figure 1.6 shows an example of circuits that allow the _ASEMD pin to be GND (0) whenever the emulator is connected by using the user system interface cable.
   When the _ASEMD pin is changed by switches, etc., ground pin 9. Do not connect this pin to the _ASEMD pin.
3. When a network resistance is used for pull-up, it may be affected by a noise. Separate TCK from other resistances.
4. The pattern between the H-UDI port connector and the MCU must be as short as possible. Do not connect the signal lines to other components on the board.
5. Since the H-UDI of the MCU operates with the PVcc, supply only the PVcc to the UVCC pin. Make the emulator's switch settings so that the user power will be supplied (SW2 = 1 and SW3 = 1).
6. The resistance value shown in figure 1.6 is for reference.
7. The _TRST pin must be at the low level for a certain period when the power is supplied whether the H-UDI is used or not.
8. For the pin processing in cases where the emulator is not used, refer to the hardware manual of the related MCU.

When the circuit is connected as shown in figure 1.6, the switches of the emulator are set as SW2 = 1 and SW3 = 1. For details, refer to section 3.8, Setting the DIP Switches, in the SuperH™ Family E10A-USB Emulator User's Manual.

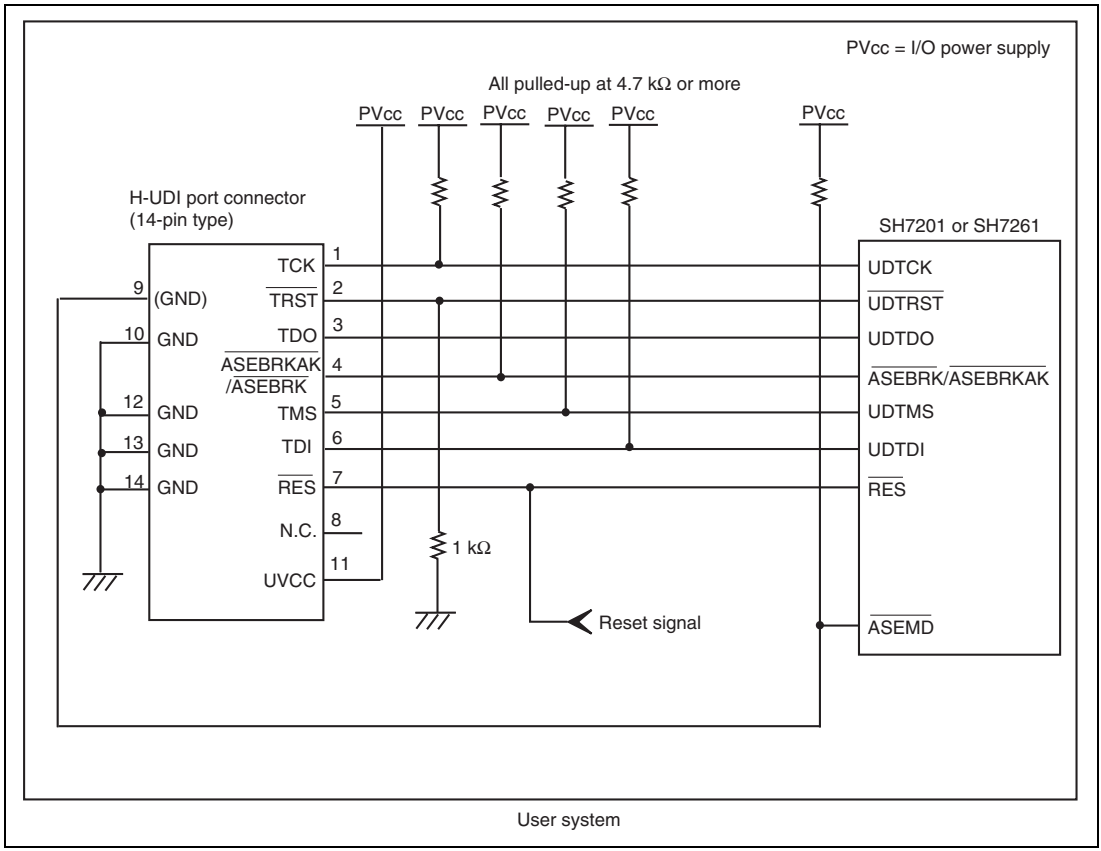


Figure 1.6 Recommended Circuit for Connection between the H-UDI Port Connector and MCU when the Emulator is in Use (14-Pin Type)

1.5.3 Recommended Circuit (38-Pin Type)

Figure 1.7 shows a recommended circuit for connection between the H-UDI and AUD port connectors (38 pins) and the MCU when the emulator is in use.

Notes: 1. Do not connect anything to the N.C. pins of the H-UDI port connector.

2. The _ASEMD pin must be 0 when the emulator is connected and 1 when the emulator is not connected, respectively.
   (1) When the emulator is used: _ASEMD = 0
   (2) When the emulator is not used: _ASEMD = 1
   Figure 1.7 shows an example of circuits that allow the _ASEMD pin to be GND (0) whenever the emulator is connected by using the user system interface cable.
   When the _ASEMD pin is changed by switches, etc., ground pin 3. Do not connect this pin to the _ASEMD pin.
3. When a network resistance is used for pull-up, it may be affected by a noise. Separate TCK from other resistances.
4. The pattern between the H-UDI port connector and the MCU must be as short as possible. Do not connect the signal lines to other components on the board.
5. The AUD signals (AUDCK, AUDATA3 to AUDATA0, and _AUDSYNC) operate in high speed. Isometric connection is needed if possible. Do not separate connection nor connect other signal lines adjacently.
6. Since the H-UDI and the AUD of the MCU operate with the PVcc, supply only the PVcc to the UVCC pin. Make the emulator's switch settings so that the user power will be supplied (SW2 = 1 and SW3 = 1).
7. The resistance value shown in figure 1.7 is for reference.
8. For the AUDCK pin, guard the pattern between the H-UDI port connector and the MCU at GND level.
9. The _TRST pin must be at the low level for a certain period when the power is supplied whether the H-UDI is used or not.
10. The GND bus lead at the center of the H-UDI port connector must be grounded.
11. For the pin processing in cases where the emulator is not used, refer to the hardware manual of the related MCU.

When the circuit is connected as shown in figure 1.7, the switches of the emulator are set as SW2 = 1 and SW3 = 1. For details, refer to section 3.8, Setting the DIP Switches, in the SuperH™ Family E10A-USB Emulator User's Manual.

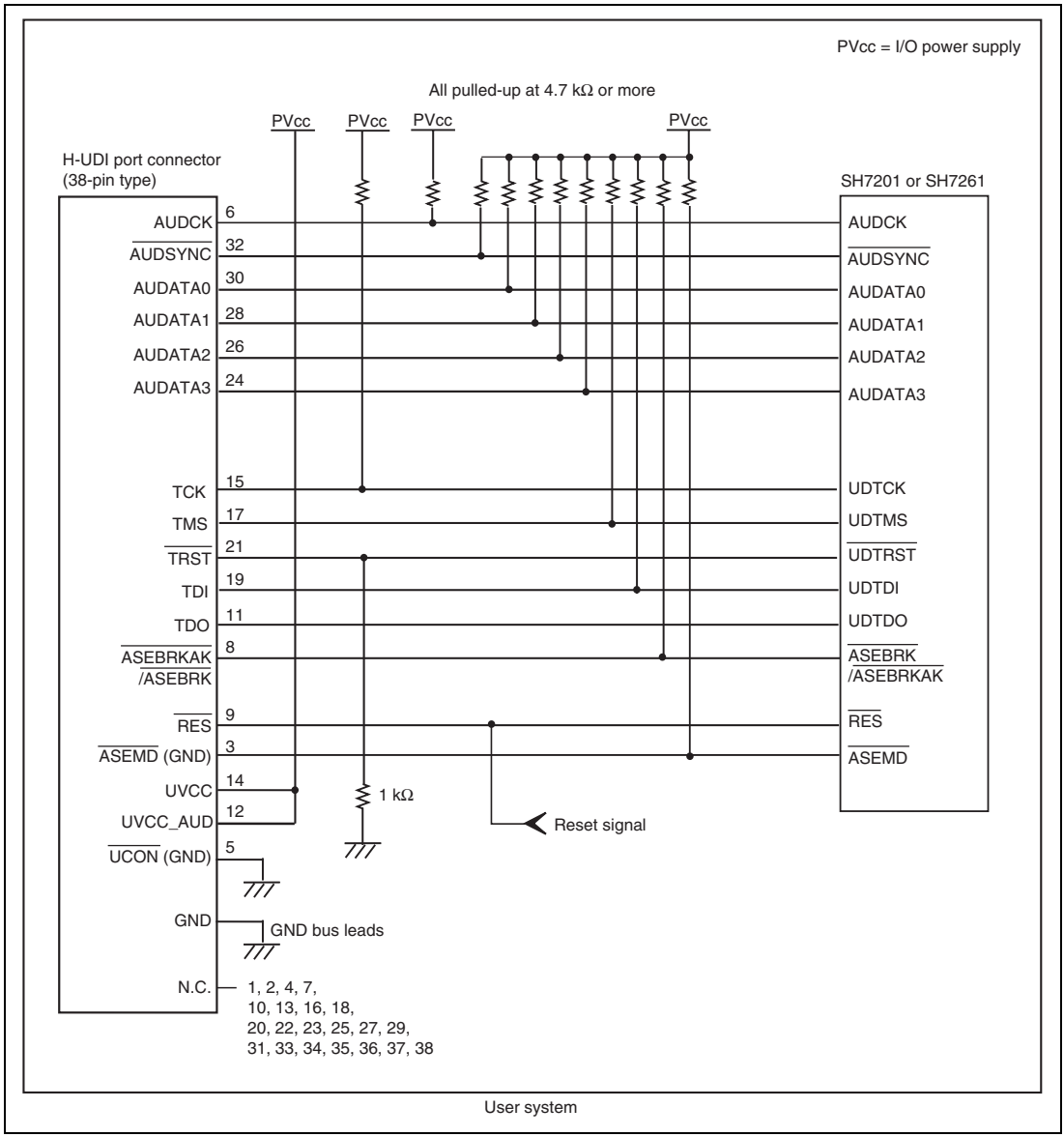


Figure 1.7 Recommended Circuit for Connection between the H-UDI Port Connector and MCU when the Emulator is in Use (38-Pin Type)

Note: When the emulator is used, the AUD trace mode is set without using AUDMD or _AUDRST. If those functions are enabled, do not set these pins in PFC because the settings of AUD will be changed.

Section 2 Software Specifications when Using the SH7201 or SH7261

2.1 Differences between the MCU and the Emulator

1. When the emulator system is initiated, it initializes the general registers and part of the control registers as shown in table 2.1. The initial values of the MCU are undefined. When the emulator is initiated from the workspace, a value to be entered is saved in a session.

Table 2.1 Register Initial Values at Emulator Link Up

Register	Emulator at Link Up
R0 to R14	H'00000000
R15 (SP)	Value of the SP in the power-on reset vector table
PC	Value of the PC in the power-on reset vector table
SR	H'000000F0
GBR	H'00000000
VBR	H'00000000
TBR	H'00000000
MACH	H'00000000
MACL	H'00000000
PR	H'00000000
FPSCR*	H'00040001
FPUL*	H'00000000
FPR0-15*	H'00000000

Note: If the MCU does not incorporate the floating-point unit (FPU), these registers are not displayed.

Note: When a value of the interrupt mask bit in the SR register is changed in the [Registers] window, it is actually reflected in that register immediately before execution of the user program is started. It also applies when the value is changed by the REGISTER_SET command.

2. The emulator uses the H-UDI; do not access the H-UDI.

3. Low-Power States
   - When the emulator is used, the sleep state can be cleared with either the clearing function or with the [STOP] button, and a break will occur.
   - The memory must not be accessed or modified in software standby state.
   - The memory must not be accessed or modified in deep standby state.
   - Do not stop inputting the clock to the H-UDI module by using the module standby function.

4. Reset Signals

   The MCU reset signals are only valid during emulation started with clicking the GO or STEP-type button. If these signals are enabled on the user system in command input wait state, they are not sent to the MCU.

Note: Do not break the user program when the _RES or _WAIT signal is being low. A TIMEOUT error will occur. If the _WAIT signal is fixed to low during break, a TIMEOUT error will occur at memory access.

5. Direct Memory Access Controller (DMAC)

   The DMAC operates even when the emulator is used. When a data transfer request is generated, the DMAC executes DMA transfer.

6. Memory Access during User Program Execution

   During execution of the user program, memory is accessed by the following two methods, as shown in table 2.2; each method offers advantages and disadvantages.

Table 2.2 Memory Access during User Program Execution

Method	Advantage	Disadvantage
H-UDI read/write	The stopping time of the user program is short because memory is accessed by the dedicated bus master.	Cache access is disabled. Actual memory is always accessed by the H-UDI read or write.
Short break	Cache access is enabled.	The stopping time of the user program is long because the user program temporarily breaks.

Note: Accessing memory to cache control registers 1 and 2 is fixed as a short break during execution of the user program.

The method for accessing memory during execution of the user program is specified by using the [Configuration] dialog box.

Table 2.3 Stopping Time by Memory Access (Reference)

Method	Condition	Stopping Time
H-UDI read/write	Reading of one longword for the internal RAM	Reading: Maximum three bus clocks (Bϕ)
	Writing of one longword for the internal RAM	Writing: Maximum two bus clocks (Bϕ)
Short break	CPU clock: 160 MHz JTAG clock: 20 MHz Reading or writing of one longword for the external area	About 50 ms

7. Memory Access to the External Flash Memory Area

   The emulator can download the load module to the external flash memory area (for details, refer to section 6.22, Download Function to the Flash Memory Area, in the SuperH™ Family E10A-USB Emulator User's Manual). Other memory write operations are enabled for the RAM area. Therefore, an operation such as memory write or BREAKPOINT should be set only for the RAM area.

8. Operation while Cache is Enabled

When cache is enabled, the emulator operates as shown in table 2.4.

Table 2.4 Operation while Cache is Enabled

Function	Operation	Notes
Memory write	Searches for whether or not the address to be written hits the instruction and operand caches. • When the address hits, the corresponding position of the data array is changed by the data to be written and single write is performed to the external area. • When the address does not hit, the cache contents are not changed and single write is performed to the external area.	• The contents of the address array are not changed before or after writing of memory.
Memory read	Searches for whether or not the address to be read hits the operand cache. • When the address hits, the corresponding position of the data array is read. • When the address does not hit, single write is performed to the external area.	• The instruction cache is not searched for. • The contents of the address array are not changed before or after reading of memory.
BREAKPOINT	Clears the V and LRU bits of all entries in the instruction cache to 0 if a BREAKPOINT is set or canceled. Clears the V and LRU bits of all entries in the instruction cache to 0 if a break occurs when a BREAKPOINT has been set.	• Use the Event Condition if you do not wish to change the contents of the instruction cache.
Program load	Writes the contents of the data cache to the external memory and clears the V and LRU bits of entries in the instruction and data caches to 0 after loading of the program has been completed.	

If memory is read from or written to the disabled cache area, cache is not searched for but the external area is accessed.

9. Multiplexing the AUD Pins

   The AUD pin is multiplexed as shown in table 2.5.

Table 2.5 Multiplexed Functions

Function 1	Function 2
PF2/TCLKD/SCK7*	AUDCK
PF3*	_AUDSYNC
PF4*	AUDATA0
PF5*	AUDATA1
PF6*	AUDATA2
PF7*	AUDATA3

Note: Function 1 can be used when the AUD pins of the device are not connected to the emulator.

The AUD pins are multiplexed with other pins. The AUD function cannot be used for the initial values because they are used as other functions. To use the initial value as the AUD function, set the AUD pins to be used from [AUD pin select] of the [Configuration] dialog box. The emulator rewrites the registers for the pin function controller (PFC) to enable the specified AUD pins before executing the user program. When those registers are changed by the user program, note that the settings of the AUD pins will not be changed.

Table 2.6 shows the bits and the values corresponding to the AUD function.

Table 2.6 Registers and Values Set for the AUD Function

Pin Name of the Port Function	AUD Function	Register and Bit to be Set	Value to be Set
PF2	AUDCK	PFCR1[9:8]	2'b01
PF3	_AUDSYNC	PFCR1[12]	1'b1
PF4	AUDATA0	PFCR2[1:0]	2'b01
PF5	AUDATA1	PFCR2[5:4]	2'b01
PF6	AUDATA2	PFCR2[9:8]	2'b01
PF7	AUDATA3	PFCR2[12]	1'b1

10. Using WDT

    The WDT does not operate during break.

11. Loading Sessions

    Information in [JTAG clock] of the [Configuration] dialog box cannot be recovered by loading sessions. Thus the TCK value will be as follows:

    - When HS0005KCU01H or HS0005KCU02H is used: TCK = 1.25 MHz

12. [IO] Window

    - Display and modification

      For registers with different read and write access sizes, there are two registers to be separately used for read and write operations.

Table 2.7 Registers with Different Access Sizes

Register Name	Usage	Register
WTCSR(W)	Write	Watchdog timer control/status register
WTCNT(W)	Write	Watchdog timer counter
WTCSR(R)	Read	Watchdog timer control/status register
WTCNT(R)	Read	Watchdog timer counter
WRCSR(W)	Write	Watchdog reset control/status register
WRCSR(R)	Read	Watchdog reset control/status register
STRMDIN0_1(R)	Read	CD-ROM decoder stream data input register 0/1
STRMDIN2_3(R)	Read	CD-ROM decoder stream data input register 2/3
STRMDIN0_3(W)	Write	CD-ROM decoder stream data input register 0/1/2/3

- Customization of the I/O-register definition file

  The internal I/O registers can be accessed from the [IO] window. However, note the following when accessing the SDMR register of the bus-state controller. Before accessing the SDMR register, specify addresses to be accessed in the I/O-register definition file (SH7201.IO, SH7261x.IO, or (MCU name).IO) and then activate the High-performance Embedded Workshop. After the I/O-register definition file is created, the MCU's specifications may be changed. If each I/O register in the I/O-register definition file differs from addresses described in the hardware manual, change the I/O-register definition file according to the description in the hardware manual. The I/O-register definition file can be customized depending on its format. Note that, however, the emulator does not support the bit-field function.

- Verify

  In the [IO] window, the verify function of the input value is disabled.

- CD-ROM

  When the emulator is in use, the CD-ROM decoder cannot be accessed in the module standby state. Clear the module standby state before accessing the corresponding registers in the [IO] window, etc.

13. Illegal Instructions

    Do not execute illegal instructions with STEP-type commands.

14. Reset Input

    During execution of the user program, the emulator may not operate correctly if a contention occurs between the following operations for the emulator and the reset input to the target device:

    - Setting an Event Condition
    - Setting an internal trace
    - Displaying the content acquired by an internal trace
    - Reading or writing of a memory

    Note that those operations should not contend with the reset input to the target device.

15. Contention between the Change of the FRQCR Register and the Debugging Functions

    The following notes are required for the user program for changing the multiplication rate of PLL circuit 1 to change the frequency:

    - Avoid contention between the change of the FRQCR register in the user program and the memory access from the [Memory] window, etc.
    - When the automatic updating function is used in the [Monitor] window or [Watch] window, generate and set a break of Event Condition for an instruction immediately before changing the FRQCR register. Contention will be avoided by generating a break and executing the user program again.

    For the change of the multiplication rate of PLL circuit 1 and the FRQCR register, refer to the hardware manual for the MCU.

16. Contention among Cache-Fill by Connecting SDRAM to the 32-bit Bus, Access to the MCU, and the Debugging Functions

    Malfunction may occur if the following conditions are in contention in the system in which SDRAM has been connected to the 32-bit bus:

    - Cache-fill (burst) by connecting SDRAM to the 32-bit bus
    - Access to the MCU
    - H-UDI read/write access

When the emulator is used, note the following to avoid H-UDI read/write access:

- Display of the toolchip on the C source
  - — Disabling H-UDI read/write access in the toolchip display during execution of the user program

    When [Disable] is set for [Read/Write on the fly] in the [General] page of the [Configuration] dialog box, no memory access will occur during execution of the user program. An undefined value is displayed during execution of the user program. A correct value is displayed when the user program is halted.
  - — Always disabling the display of the toolchip on the C source

    When a dialog box is opened by selecting [Options] from [Setup], select the [Editor] sheet. When a checked mark (initial value) of the toolchip watch is removed, the toolchip watch function becomes disabled.

- Update (refresh) of the [Memory] window, modification of the memory contents, and change of the position
- Update (refresh) of the [IO] window, modification of the register contents, and change of the position
- Update (refresh) of the [Disassembly] window, modification of the memory contents, and change of the position
- Auto-update of the [Watch] window and change of the position
- Auto-update of the [Image] window and change of the position
- Auto-update of the [Waveform] window and change of the position
- New opening of the [Stack Trace] window and change of the position
  - — Disabling the memory access during execution of the user program

    When [Disable] is set for [Read/Write on the fly] in the [General] page of the [Configuration] dialog box, no memory access will occur during execution of the user program. An undefined value is displayed during execution of the user program. A correct value is displayed when the user program is halted.
- [Monitor] function
  - — This function must not be used.
- Setting of the on-chip breakpoint and changing the setting
- Setting of the [Performance Analysis] function and changing the setting
  - — The conditions must not be set or changed during execution of the user program.

2.2 Specific Functions for the Emulator when Using the SH7201 or SH7261

2.2.1 Event Condition Functions

The emulator is used to set event conditions for the following two functions:

- Break of the user program
- Start or end of performance measurement

Table 2.8 lists the types of Event Condition.

Table 2.8 Types of Event Condition

Event Condition Type	Description
Address bus condition (Address)	Sets a condition when the address bus (data access) value or the program counter value (before or after execution of instructions) is matched.
Data bus condition (Data)	Sets a condition when the data bus value is matched. Byte, word, or longword can be specified as the access data size.
Bus state condition (Bus State)	There are two bus state condition settings: Bus state condition: Sets a condition when the data bus value is matched. Read/Write condition: Sets a condition when the read/write condition is matched.
Count	Sets a condition when the specified other conditions are satisfied for the specified counts.
Reset point	A reset point is set when the count and the sequential condition are specified.
Action	Selects the operation (break) when a condition is matched.

Using the [Combination action (Sequential or PtoP)] dialog box, which is opened by selecting [Combination action (Sequential or PtoP)] from the pop-up menu on the [Event Condition] sheet, specifies the sequential condition and the start or end of performance measurement.

Since this MCU does not incorporate the internal trace module, it is not possible to set the internal trace condition of the Event Condition function.

Table 2.9 lists the combinations of conditions that can be set under Ch1 to Ch11 and the software trace.

Table 2.9 Dialog Boxes for Setting Event Conditions

Dialog Box		Function				
		Address Bus Condition (Address)	Data Bus Condition (Data)	Bus State Condition (Bus Status)	Count Condition (Count)	Action
[Event Condition 1]	Ch1	O	O	O	O	O (B and P)
[Event Condition 2]	Ch2	O	O	O	X	O (B and P)
[Event Condition 3]	Ch3	O	X	X	X	O (B)
[Event Condition 4]	Ch4	O	X	X	X	O (B)
[Event Condition 5]	Ch5	O	X	X	X	O (B)
[Event Condition 6]	Ch6	O	X	X	X	O (B)
[Event Condition 7]	Ch7	O	X	X	X	O (B)
[Event Condition 8]	Ch8	O	X	X	X	O (B)
[Event Condition 9]	Ch9	O	X	X	X	O (B)
[Event Condition 10]	Ch10	O	X	X	X	O (B)
[Event Condition 11]	Ch11	O (reset point)	X	X	X	O (B)

Notes: 1. O: Can be set in the dialog box.
X: Cannot be set in the dialog box.
2. For the Action item,
B: Setting a break is enabled.
P: Setting a performance-measurement start or end condition is enabled.

The [Event Condition 11] dialog box is used to specify the count of [Event Condition 1] and becomes a reset point when the sequential condition is specified.

Sequential Setting: Using the [Combination action (Sequential or PtoP)] dialog box specifies the sequential condition and the start or end of performance measurement.

Table 2.10 Conditions to Be Set

Classification	Item	Description
[Ch1, 2, 3] list box	Sets the sequential condition and the start or end of performance measurement using Event Conditions 1 to 3 and 11.	
	Don't care	Sets no sequential condition or the start or end of performance measurement.
	Break: Ch3-2-1	Breaks when a condition is satisfied in the order of Event Condition 3, 2, 1.
	Break: Ch3-2-1, Reset point	Breaks when a condition is satisfied in the order of Event Condition 3, 2, 1. Enables the reset point of Event Condition 11.
	Break: Ch2-1	Breaks when a condition is satisfied in the order of Event Condition 2, 1.
	Break: Ch2-1, Reset point	Breaks when a condition is satisfied in the order of Event Condition 2, 1. Enables the reset point.
	I-Trace stop: Ch3-2-1	Setting is disabled in this MCU.
	I-Trace stop: Ch3-2-1, Reset point	Setting is disabled in this MCU.
	I-Trace stop: Ch2-1	Setting is disabled in this MCU.
	I-Trace stop: Ch2-1, Reset point	Setting is disabled in this MCU.
	Ch2 to Ch1 PA	Sets the performance measurement period during the time from the satisfaction of the condition set in Event Condition 2 (start condition) to the satisfaction of the condition set in Event Condition 1 (end condition).
	Ch1 to Ch2 PA	Sets the performance measurement period during the time from the satisfaction of the condition set in Event Condition 1 (start condition) to the satisfaction of the condition set in Event Condition 2 (end condition).

Table 2.10 Conditions to Be Set (cont)

Classification	Item	Description
[Ch4, 5] list box	Setting is disabled in this MCU.	
	Don't care	[Don't care] is fixed in this MCU.
	I-Trace: Ch5 to Ch4 PtoP	Setting is disabled in this MCU.
	I-Trace: Ch5 to Ch4 PtoP, power-on reset	Setting is disabled in this MCU.

Notes: 1. After the sequential condition and the count specification condition of Event Condition 1 have been set, a break will be halted if the sequential condition is satisfied for the specified count.

2. If a reset point is satisfied, the satisfaction of the condition set in Event Condition will be disabled. For example, if the condition is satisfied in the order of Event Condition 3, 2, reset point, 1, a break will not be halted. If the condition is satisfied in the order of Event Condition 3, 2, reset point, 3, 2, 1, the break will be halted.

3. If the start condition is satisfied after the end condition has been satisfied by measuring performance, performance measurement will be restarted. For the measurement result after a break, the measurement results during performance measurement are added.

Usage Example of Sequential Break Extension Setting: A tutorial program provided for the product is used as an example. For the tutorial program, refer to section 6, Tutorial, in the SuperH™ Family E10A-USB Emulator User's Manual.

The conditions of Event Condition are set as follows:

1. Ch3

   Breaks address H'00001068 when the condition [Only program fetched address after] is satisfied.
2. Ch2

   Breaks address H'0000107a when the condition [Only program fetched address after] is satisfied.
3. Ch1

   Breaks address H'00001086 when the condition [Only program fetched address after] is satisfied.
   Note: Do not set other channels.
4. Sets the content of the [Ch1,2,3] list box to [Break: Ch 3-2-1] in the [Combination action (Sequential or PtoP)] dialog box.
5. Enables the condition of Event Condition 1 from the popup menu by clicking the right mouse button on the [Event Condition] sheet.

Then, set the program counter and stack pointer (PC = H'00000800, R15 = H'00010000) in the [Registers] window and click the [Go] button. If this does not execute normally, issue a reset and execute the above procedures.

The program is executed up to the condition of Ch1 and halted. Here, the condition is satisfied in the order of Ch3 -> 2 -> 1.

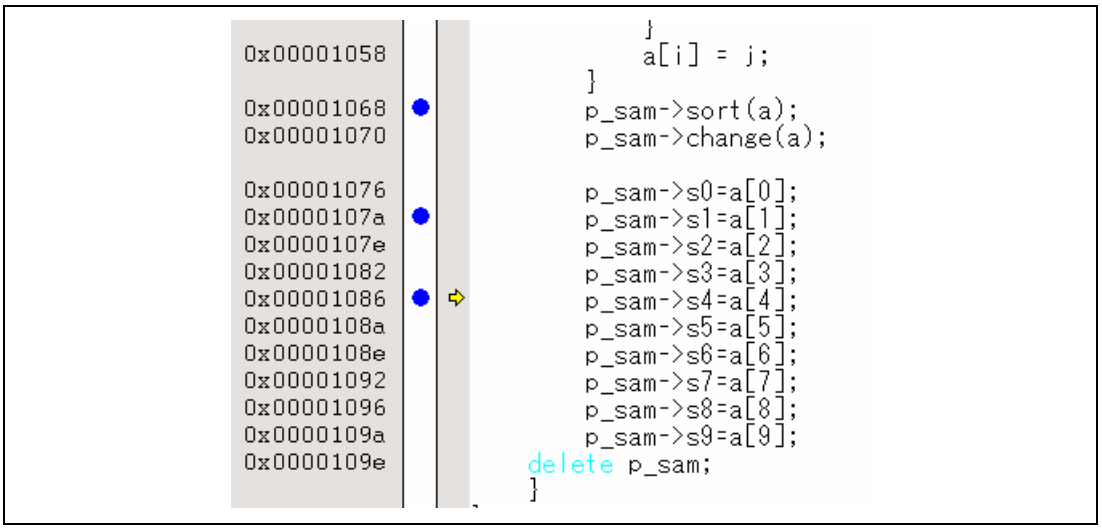


Figure 2.1 [Source] Window at Execution Halted (Sequential Break)

If the sequential condition or performance measurement start/end is set, conditions of Event Condition to be used will be disabled. Such conditions must be enabled from the popup menu by clicking the right mouse button on the [Event Condition] sheet.

Notes: 1. If the Event condition is set for the slot in the delayed branch instruction by the program counter (after execution of the instruction), the condition is satisfied before executing the instruction in the branch destination (when a break has been set, it occurs before executing the instruction in the branch destination).

2. Do not set the Event condition for the SLEEP instruction by the program counter (after execution of the instruction).
3. When the Event condition is set for the 32-bit instruction by the program counter, set that condition in the upper 16 bits of the instruction.
4. If the power-on reset and the Event condition are matched simultaneously, no condition will be satisfied.
5. Do not set the Event condition for the DIVU or DIVS instruction by the program counter (after execution of the instruction).
6. If a condition of which intervals are satisfied closely is set, no sequential condition will be satisfied.
   - Set the Event conditions, which are satisfied closely, by the program counter with intervals of two or more instructions.
   - After the Event condition has been matched by accessing data, set the Event condition by the program counter with intervals of 17 or more instructions.

7. If the settings of the Event condition or the sequential conditions are changed during execution of the program, execution will be suspended. (The number of clocks to be suspended during execution of the program is a maximum of about 102 bus clocks (Bϕ). If the bus clock (Bϕ) is 66.6 MHz, the program will be suspended for 1.53 μs.)
8. If the settings of Event conditions or the sequential conditions are changed during execution of the program, the emulator temporarily disables all Event conditions to change the settings. During this period, no Event condition will be satisfied.
9. If the break condition before executing an instruction is set to the instruction followed by DIVU and DIVS, the factor for halting a break will be incorrect under the following condition:
   If a break occurs during execution of the above DIVU and DIVS instructions, the break condition before executing an instruction, which has been set to the next instruction, may be displayed as the factor for halting a break.
10. If the break conditions before and after executing instructions are set to the same address, the factor for halting a break will be incorrectly displayed. The factor for halting a break due to the break condition after executing an instruction will be displayed even if a break is halted by the break condition before executing an instruction.
11. Do not set the break condition after executing instructions and BREAKPOINT (software break) to the same address.
12. When the emulator is being connected, the user break controller (UBC) function is not available.

2.2.2 Trace Functions

The emulator supports the trace functions listed in table 2.11.

Table 2.11 Trace Functions

Function	Internal Trace	AUD Trace
Branch trace	Not supported	Supported
Memory access trace	Not supported	Supported
Software trace	Not supported	Supported

Table 2.12 shows the type numbers that the AUD function can be used.

Table 2.12 Type Number and AUD Function

Type Number	AUD Function
HS0005KCU01H	Not supported
HS0005KCU02H	Supported

The internal and AUD traces are set in the [Acquisition] dialog box of the [Trace] window.

Internal Trace Function: Since this MCU does not incorporate the internal trace module, it is not possible to use the internal trace function.

AUD Trace Functions: This function is operational when the AUD pin of the device is connected to the emulator. Table 2.13 shows the AUD trace acquisition mode that can be set in each trace function.

Table 2.13 AUD Trace Acquisition Mode

Type	Mode	Description
Continuous trace occurs	Realtime trace	When the next branch occurs while the trace information is being output, all the information may not be output. The user program can be executed in realtime, but some trace information will be lost.
	Non realtime trace	When the next branch occurs while the trace information is being output, the CPU stops operations until the information is output. The user program is not executed in realtime.
Trace buffer full	Trace continue	This function overwrites the latest trace information to store the oldest trace information.
	Trace stop	After the trace buffer becomes full, the trace information is no longer acquired. The user program is continuously executed.

To set the AUD trace acquisition mode, click the [Trace] window with the right mouse button and select [Setting] from the pop-up menu to display the [Acquisition] dialog box. The AUD trace acquisition mode can be set in the [AUD mode1] or [AUD mode2] group box in the [Trace mode] page of the [Acquisition] dialog box.

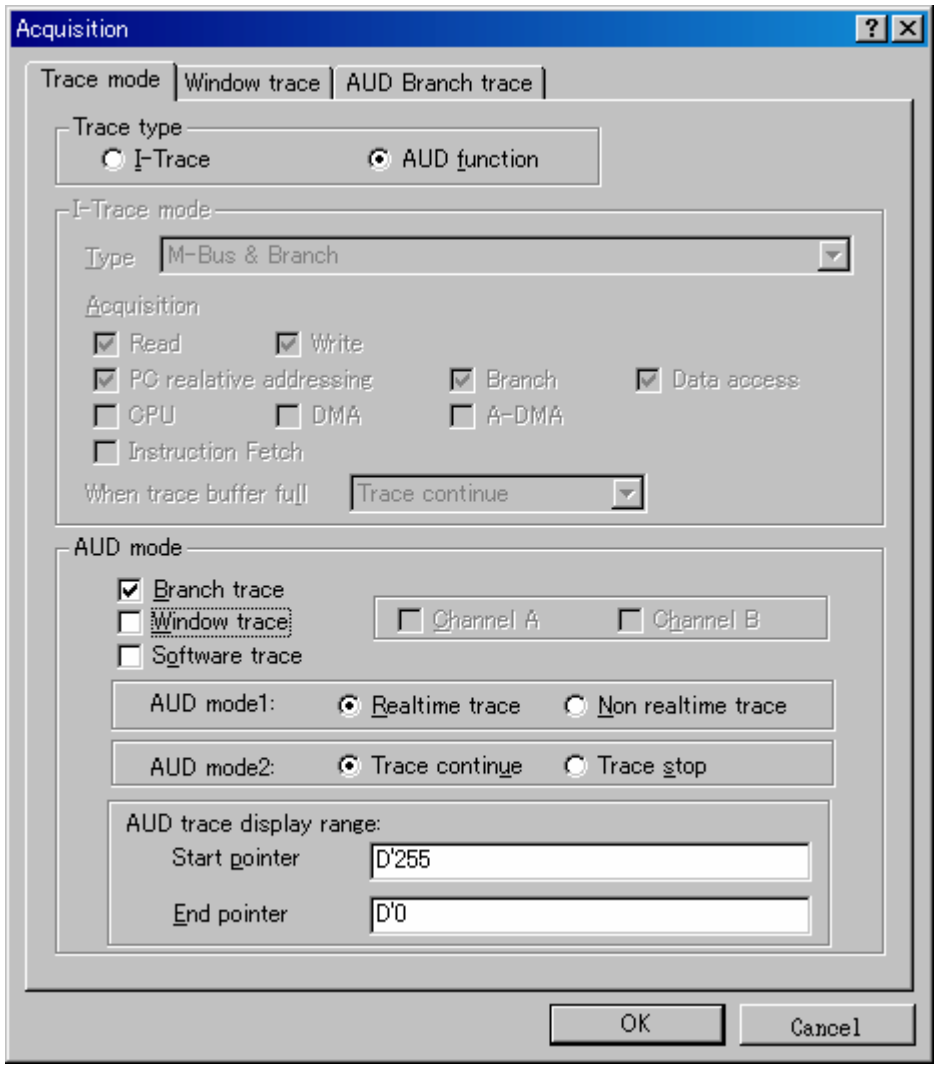


Figure 2.2 [Trace mode] Page

When the AUD trace function is used, select the [AUD function] radio button in the [Trace type] group box of the [Trace mode] page.

(a) Branch Trace Function

The branch source and destination addresses and their source lines are displayed.

Branch trace can be acquired by selecting the [Branch trace] check box in the [AUD function] group box of the [Trace mode] page.

The branch type can be selected in the [AUD Branch trace] page.

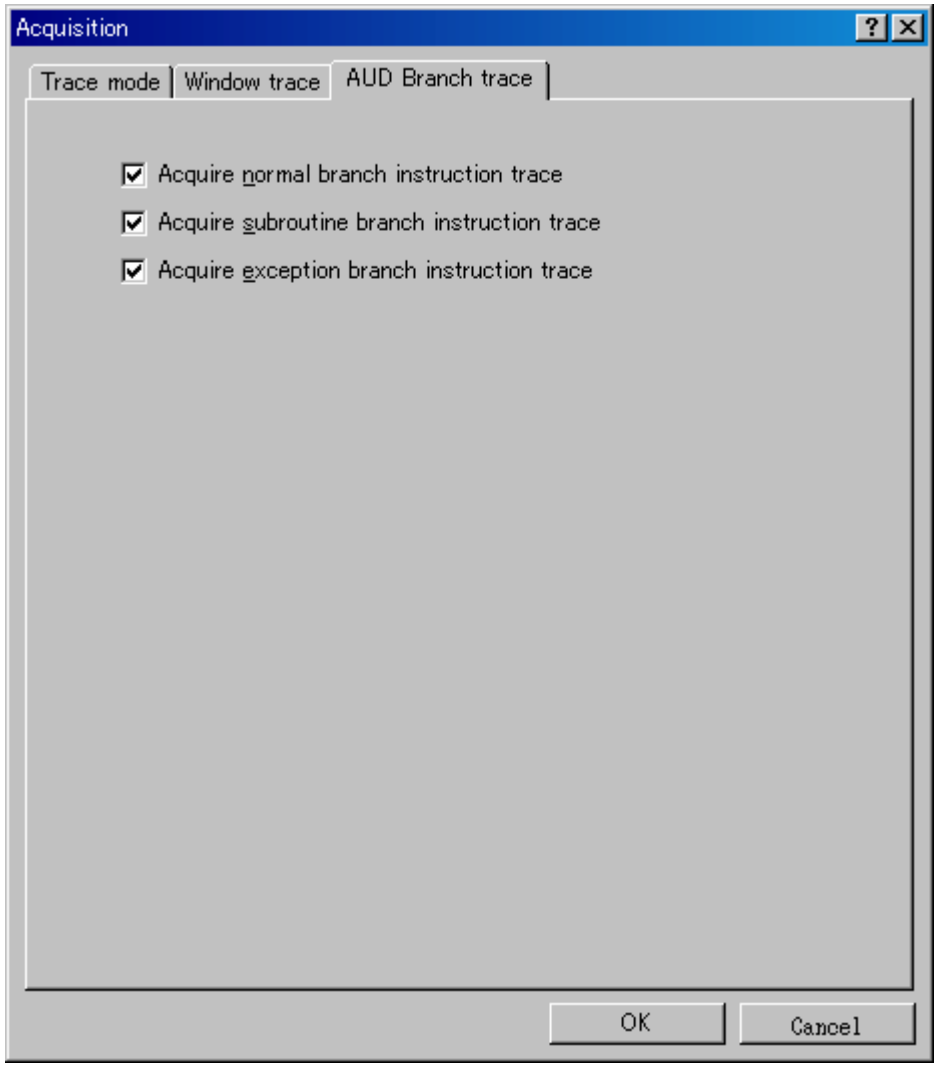


Figure 2.3 [AUD Branch trace] Page

(b) Window Trace Function

Memory access in the specified range can be acquired by trace.

Two memory ranges can be specified for channels A and B. The read, write, or read/write cycle can be selected as the bus cycle for trace acquisition.

[Setting Method]

(i) Select the [Channel A] and [Channel B] check boxes in the [AUD function] group box of the [Trace mode] page. Each channel will become valid.

(ii) Open the [Window trace] page and specify the bus cycle, memory range, and bus type that are to be set for each channel.

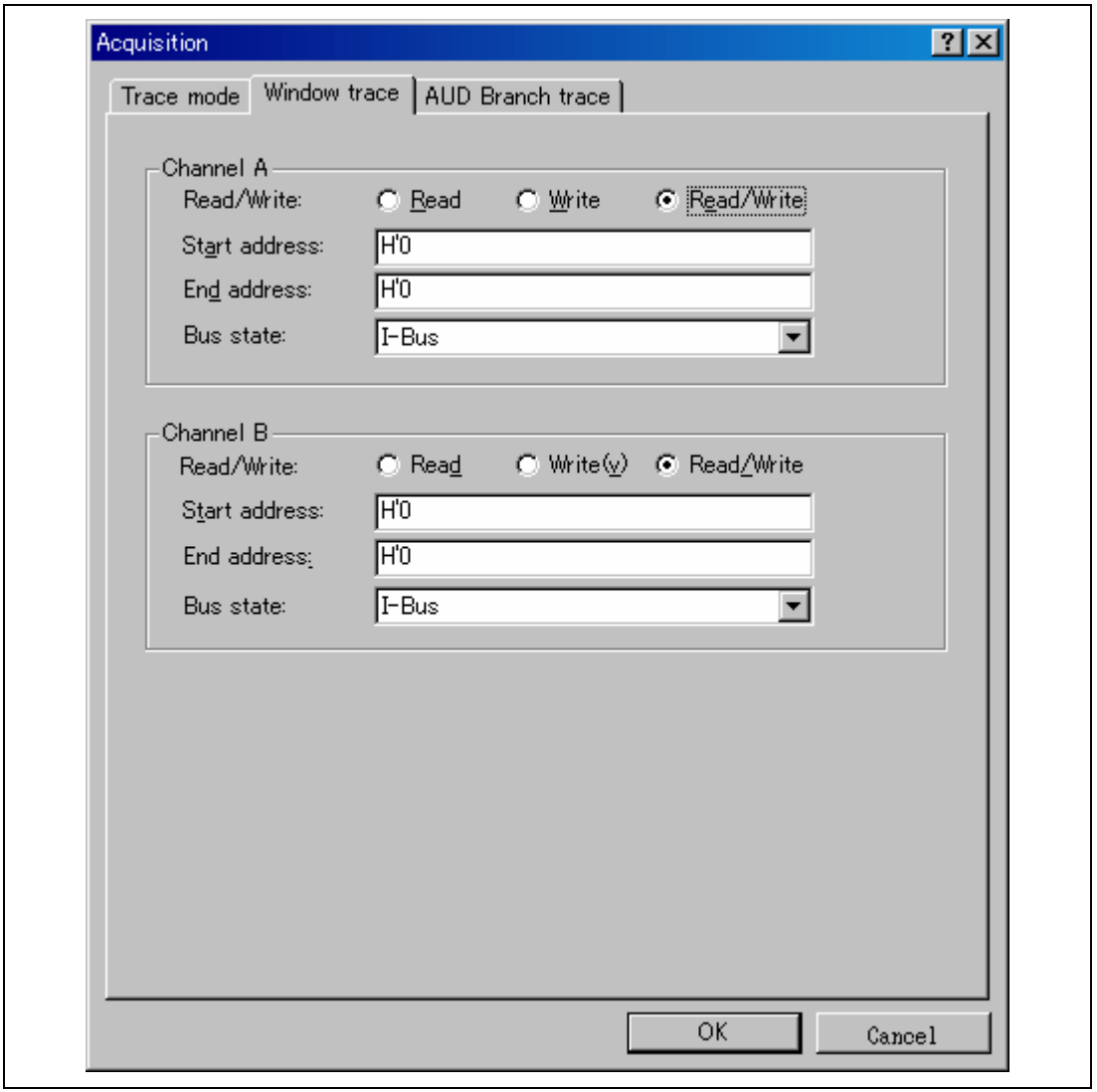


Figure 2.4 [Window trace] Page

Note: When [M-Bus] or [I-Bus] is selected, the following bus cycles will be traced.

- M-Bus: A bus cycle generated by the CPU is acquired. A bus cycle is also acquired when the cache has been hit.
- I-Bus: A bus cycle generated by the CPU or DMA is acquired. A bus cycle is not acquired when the cache has been hit.

(c) Software Trace Function

Note: This function can be supported with SHC/C++ compiler (manufactured by Renesas Technology Corp.; including OEM and bundle products) V7.0 or later.

When a specific instruction is executed, the PC value at execution and the contents of one general register are acquired by trace. Describe the Trace(x) function (x is a variable name) to be compiled and linked beforehand. For details, refer to the SHC manual.

When the load module is downloaded on the target system and is executed while a software trace function is valid, the PC value that has executed the Trace(x) function, the general register value for x, and the source lines are displayed.

To activate the software trace function, select the [Software trace] check box in the [AUD function] group box of the [Trace mode] page.

Notes on AUD Trace:

1. When the trace display is performed during user program execution, the mnemonics, operands, or source is not displayed.
2. The AUD trace function outputs the differences between newly output branch source addresses and previously output branch source addresses. The window trace function outputs the differences between newly output addresses and previously output addresses. If the previous branch source address is the same as the upper 16 bits, the lower 16 bits are output. If it matches the upper 24 bits, the lower 8 bits are output. If it matches the upper 28 bits, the lower 4 bits are output.
   The emulator regenerates the 32-bit address from these differences and displays it in the [Trace] window. If the emulator cannot display the 32-bit address, it displays the difference from the previously displayed 32-bit address.
3. If the 32-bit address cannot be displayed, the source line is not displayed.
4. If a completion-type exception occurs during exception branch acquisition, the next address to the address in which an exception occurs is acquired.
5. The AUD trace is disabled while the profiling function is used.
6. Set the AUD clock (AUDCK) frequency to 50 MHz or lower. If the frequency is higher than 50 MHz, the emulator will not operate normally.

7. If breaks occur immediately after executing non-delayed branch and TRAPA instructions and generating a branch due to exception or interrupt, a trace for one branch will not be acquired immediately before such breaks. However, this does not affect on generation of breaks caused by a BREAKPOINT and a break before executing instructions of Event Condition.
8. For the result by software trace, a value in the [Data] item is not correct (that value is correct for window trace).

2.2.3 Notes on Using the JTAG (H-UDI) Clock (TCK)

1. Set the JTAG clock (TCK) frequency to lower than the frequency of the peripheral module clock.
2. The initial value of the JTAG clock (TCK) is 1.25 MHz.
3. A value to be set for the JTAG clock (TCK) is initialized after executing [Reset CPU] or [Reset Go]. Thus the TCK value will be 1.25 MHz.

2.2.4 Notes on Setting the [Breakpoint] Dialog Box

1. When an odd address is set, the next lowest even address is used.
2. A BREAKPOINT is accomplished by replacing instructions of the specified address. It cannot be set to the following addresses:
   - An area other than CS and the internal RAM
   - An instruction in which Break Condition 2 is satisfied
   - A slot instruction of a delayed branch instruction
3. During step operation, specifying BREAKPOINTs and Event Condition breaks are disabled.
4. When execution resumes from the address where a BREAKPOINT is specified and a break occurs before Event Condition execution, single-step operation is performed at the address before execution resumes. Therefore, realtime operation cannot be performed.
5. When a BREAKPOINT is set to the slot instruction of a delayed branch instruction, the PC value becomes an illegal value. Accordingly, do not set a BREAKPOINT to the slot instruction of a delayed branch instruction.
6. If an address of a BREAKPOINT cannot be correctly set in the ROM or flash memory area, a mark ● will be displayed in the [BP] area of the address on the [Source] or [Disassembly] window by refreshing the [Memory] window, etc. after Go execution. However, no break will occur at this address. When the program halts with the event condition, the mark ● disappears.
7. If you wish to use a BREAKPOINT (software break), specify the SH2A_SBSTK command to enable use of a user stack before setting a PC break. While enabled, extra four bytes of a user stack are used when a break occurs. The value of the stack pointer (R15) must be correctly set

in advance because a user stack is to be used. By default, use of a user stack is disabled. For details on the command, refer to the help file.

- Example
  To enable use of a user stack:
  >SH2A_SBSTK enable

2.2.5 Notes on Setting the [Event Condition] Dialog Box and the BREAKCONDITION_SET Command

1. When [Go to cursor], [Step In], [Step Over], or [Step Out] is selected, the settings of Event Condition 3 are disabled.
2. When an Event Condition is satisfied, emulation may stop after two or more instructions have been executed.

2.2.6 Performance Measurement Function

The emulator supports the performance measurement function.

1. Setting the performance measurement conditions
   To set the performance measurement conditions, use the [Performance Analysis] dialog box and the PERFORMANCE_SET command. When any line in the [Performance Analysis] window is clicked with the right mouse button, a popup menu is displayed and the [Performance Analysis] dialog box can be displayed by selecting [Setting].

Note: For the command line syntax, refer to the online help.

(a) Specifying the measurement start/end conditions

The measurement start/end conditions are specified by using Event Condition 1,2. The [Ch1,2,3] list box of the [Combination action (Sequential or PtoP)] dialog box can be used.

Table 2.14 Measurement Period

Classification	Item	Description
Selection in the [Ch1, 2, 3] list box	Ch2 to Ch1 PA	The period from the satisfaction of the condition set in Event Condition 2 (start condition) to the satisfaction of the condition set in Event Condition 1 (end condition) is set as the performance measurement period.
	Ch1 to Ch2 PA	The period from the satisfaction of the condition set in Event Condition 1 (start condition) to the satisfaction of the condition set in Event Condition 2 (end condition) is set as the performance measurement period.
	Other than above	The period from the start of execution of the user program to the occurrence of a break is measured.

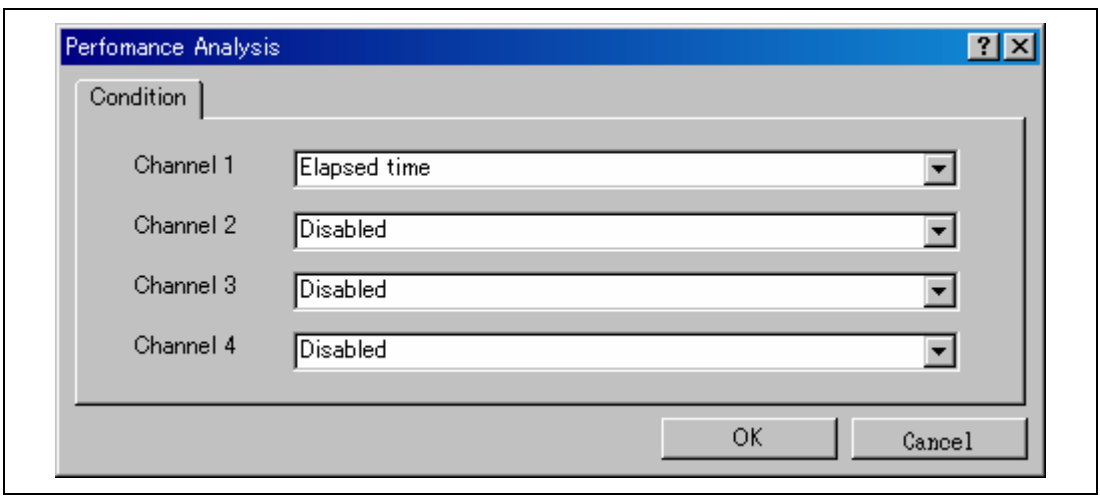


Figure 2.5 [Performance Analysis] Dialog Box

For measurement tolerance,

- The measured value includes tolerance.
- Tolerance will be generated before or after a break.

Note: When [Ch2 to Ch1 PA] or [Ch1 to Ch2 PA] is selected, to execute the user program, specify conditions set in Event Condition 2 and Event Condition 1 and one or more items for performance measurement.

(b) Measurement item

Items are measured with [Channel 1 to 4] in the [Performance Analysis] dialog box.
Maximum four conditions can be specified at the same time.

Table 2.15 Measurement Item

Selected Name	Option
Disabled	None
Elapsed time	AC (The number of execution cycles (Iϕ) is set as the measurement item.)
Branch instruction counts	BT
Number of execution instructions	I
Number of execution 32bit-instructions	I32
Exception/interrupt counts	EA
Interrupt counts	INT
Data cache-miss counts	DC
Instruction cache-miss counts	IC
All area access counts	ARN
All area instruction access counts	ARIN
All area data access counts	ARND
Cacheable area access counts	CDN (data access)
Cacheable area instruction access counts	CIN
Non cacheable area data access counts	NCN
URAM area access counts	UN
URAM area instruction access counts	UIN
URAM area data access counts	UDN
Internal I/O area data access counts	IODN
Internal ROM area access counts	RN
Internal ROM area instruction access counts	RIN
Internal ROM area data access counts	RDN
All area access cycle	ARC
All area instruction access cycle	ARIC
All area data access cycle	ARDC
All area access stall	ARS
All area instruction access stall	ARIS
All area data access stall	ARDS

Note: Selected names are displayed for CONDITION in the [Performance Analysis] window. Options are parameters for <mode> of the PERFORMANCE_SET command.

Notes: 1. In the non-realtime trace mode of the AUD trace, normal counting cannot be performed because the generation state of the stall or the execution cycle is changed.
2. If the internal ROM is not installed on the product, do not set the measurement item for the internal ROM area.

2. Displaying the measured result

The measured result is displayed in the [Performance Analysis] window or the PERFORMANCE_ANALYSIS command with hexadecimal (32 bits).

Note: If a performance counter overflows as a result of measurement, "********" will be displayed.

3. Initializing the measured result

To initialize the measured result, select [Initialize] from the popup menu in the [Performance Analysis] window or specify INIT with the PERFORMANCE_ANALYSIS command.

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Additional Document for User's Manual
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