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# SH7285/SH7286 USB Function Module

## USB to Serial Conversion Application Note

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### Preface

This document describes how to implement USB to serial conversion system as an application example for the SH7285 and SH7286 MCU's USB function module. This document and the sample program described are examples of the USB function module, and are therefore not guaranteed by Renesas.

### Target Devices

SH7285 and SH7286 MCUs

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## 1. Introduction

### 1.1 Specifications

This document describes how to use the SH7285/SH7286 USB function module, and how to implement a USB to serial conversion system as an application example of the USB function module.

### 1.2 Functions

- USB function module
- Serial communication interface with FIFO (SCIF)

### 1.3 Applicable Conditions

- MCUs : SH7285 and SH7286
- Operating frequency : 100 MHz internal clock  
50 MHz bus clock  
50 MHz peripheral clock
- C compiler : Renesas Technology  
SuperH RISC engine Family C/C++ Compiler Package Ver.9.01 Release 01
- Compile options : `-cpu=sh2a -include="$(WORKSPDIR)¥inc"`  
`-object="$(CONFIGDIR)¥$(FILELEAF).obj" -debug -gbr=auto`  
`-chgincpath-errorpath -global_volatile=0 -opt_range=all`  
`-infinite_loop=0-del_vacant_loop=0 -struct_alloc=1 -nologo`

## 2. Applications

This sample program uses the USB function module to execute the control IN, control OUT, bulk IN, and bulk OUT transfers. The sample program also converts USB to serial signals and vice versa.

### 2.1 Features

The USB function module has an embedded USB 1.1 compliant USB Device Controller (UDC) to automatically process USB protocols. The function module has four mounted endpoints for each transfer mode, and transfers data in the control transfer, bulk OUT transfer, bulk IN transfer, and interrupt transfer to the USB host.

The following lists the USB function module features available in the SH7285 and SH7286 MCUs:

- Embedded USB 1.1 compliant UDC
- USB protocol processed automatically
- USB standard request to endpoint 0 processed automatically (some requests need to be processed by the firmware)
- Data rate: Full-speed
- Interrupt request: Generates various interrupt signals required for USB communication
- Clocks:
  - External clock (48 MHz)
  - Internal clock (enabled only when EXTAL 12 MHz is selected)
- Low Power Mode
  - When a USB cable is not connected, less power is consumed by stopping the UDC internal clock
- Endpoint configuration

Table 2.1 Endpoint Configurations

Endpoint	Name	Transfer Mode	Maximum Packet Size	FIFO Buffer Capacity	DMA Transfer
Endpoint 0	EP0s	Setup	8 bytes	8 bytes	N/A
	EP0i	Control IN	8 bytes	8 bytes	N/A
	EP0o	Control OUT	8 bytes	8 bytes	N/A
Endpoint 1	EP1	Bulk OUT	64 bytes	64 x 2 (128 bytes)	Available
Endpoint 2	EP2	Bulk IN	64 bytes	64 x 2 (128 bytes)	Available
Endpoint 3	EP3	Interrupt	8 bytes	8 bytes	N/A

### 2.2 USB Communication via the USB Function Module

As an example of using the USB function module for USB communication, the sample program implements the USB communication features listed in the table below.

Table 2.2 USB Communication Functions

USB Communication Features	Description
Detect a connection to the USB host	The port pulls up the D+ pin to detect a connection.
Control transfer	Decodes requests, processes the Data stage and Status stage of the USB request transmitted from the USB host in the control transfer.
Bulk IN/OUT transfers	Executes bulk IN/OUT transfers.

### 2.3 Detecting a Connection to the USB Host

A connection to the USB host is detected using the cable connect interrupt (the BRST bit in the USBIFR0 register). The cable connect interrupt occurs when a USB device cable is connected to the USB host.

After the user configures the MCU, the sample program pulls up the USB data bus D+ pin using the general output port. Figure 2.1 shows an operation flowchart of the sample program, and Figure 2.2 shows the USB Function Module Peripheral Block Circuit.

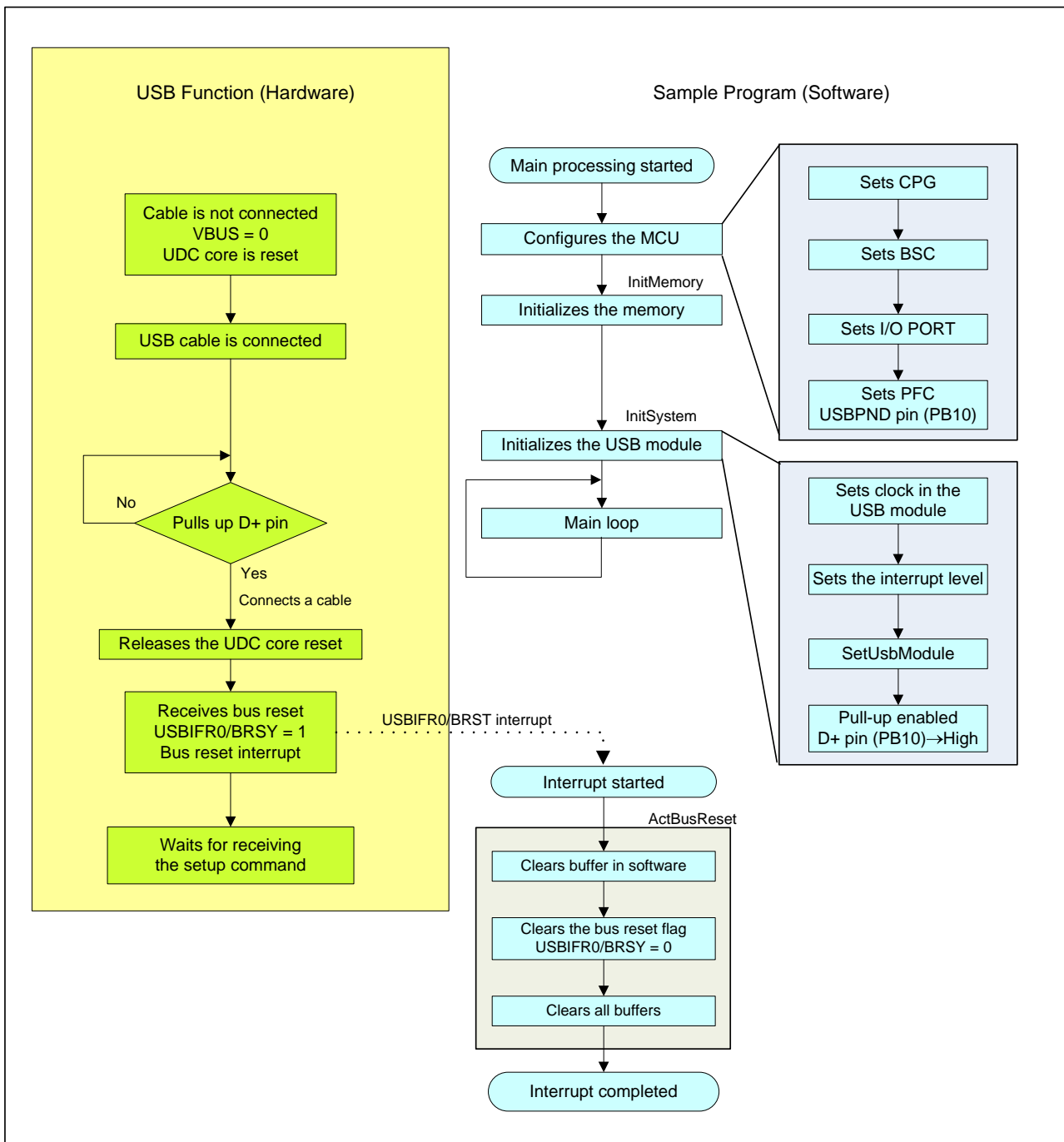


Figure 2.1 Detecting a Connection to the USB Host

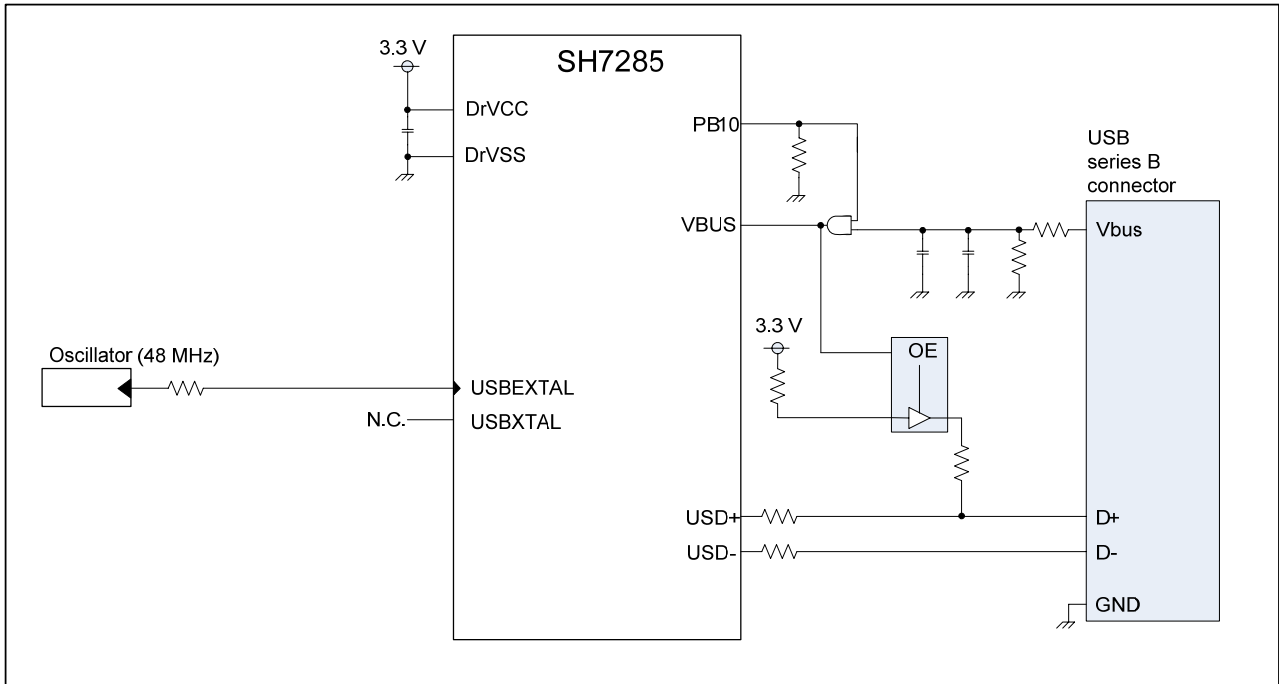


Figure 2.2 USB Function Module Peripheral Block Circuit

## 2.4 Control Transfer

A control transfer is a USB transfer that uses the endpoint 0 default pipe and must be supported by all USB devices. The USB host issues a USB standard request to the USB device and configures the device. A control transfer can be used to issue a class- or vendor-specific request.

A control transfer is composed of a Setup stage, Data stage (not in all cases), and Status stage. The Data stage consists of multiple bus transactions. Control transfers are supported via bi-directional communication flow, according to the data direction of the Data stage. A control OUT transfer is the data flow from the USB host to the USB device during the Data stage. A control IN transfer is the data flow from the USB device to the USB host during the Data stage. The Data stage is completed when the USB host transmits an inverted token of the data direction. The Status stage is the stage that transmits the inverted token to the USB host. Figure 2.3 shows Data Direction During the Data Stage and Figure 2.4 shows each Stage Configuration During Control Transfer.

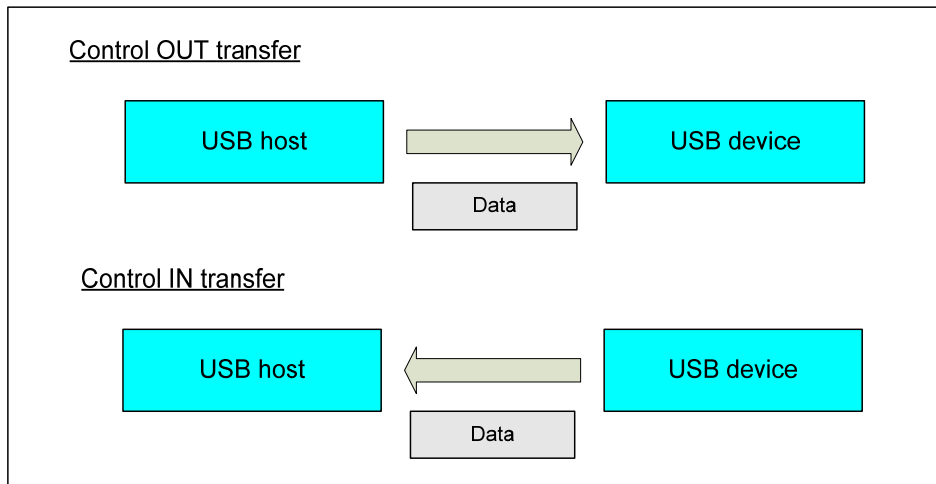


Figure 2.3 Data Direction During the Data Stage

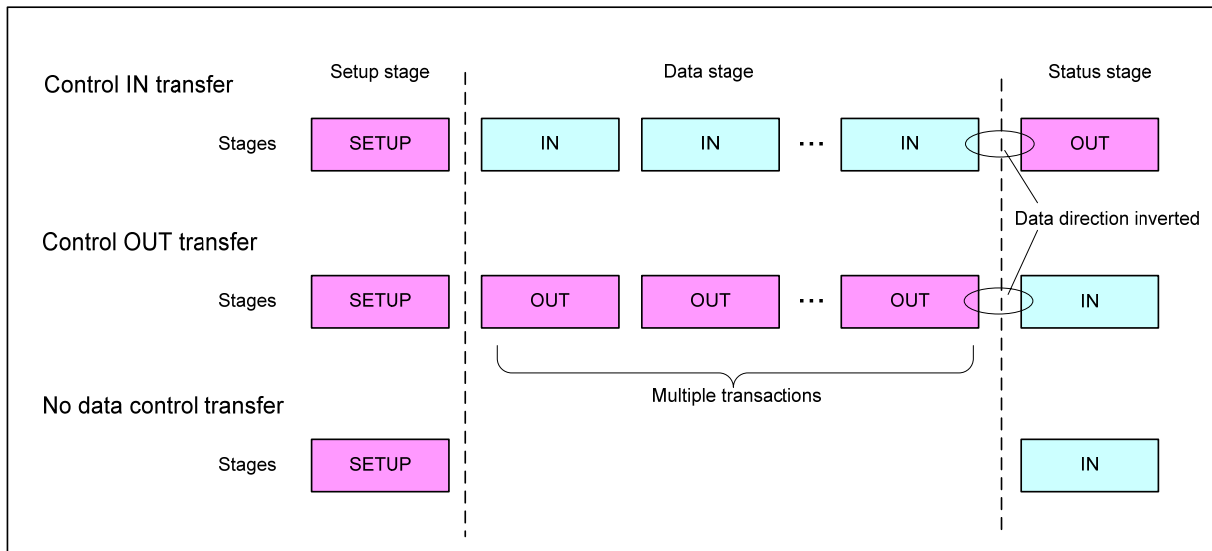


Figure 2.4 Stage Configuration During Control Transfer



The USB function module decodes the request, and automatically processes the Data stage and Status stage according to the USB standard request. However, some USB standard requests, class requests, and vendor requests should be executed by the software.

The sample program executes the Get Descriptor command, which is the USB standard request to be processed by the software. To convert USB communication into serial communication, the sample program executes USB communication class requests. Table 2.3 lists USB Commands and Processing in the Sample Program.

When the sample program receives a USB command that it does not support, it returns a STALL handshake.

Table 2.3 USB Commands and Processing in the Sample Program

USB Command	Type	Processing in the Sample Program
Clear Feature Get Configuration Get Interface Get Status Set Address Set Configuration Set Feature Set Interface	USB standard request	The hardware decodes the command, and executes the Data stage and the Status stage automatically. The software does nothing.
Get Descriptor		
Set Line Coding Set Control Line State Send Break Get Line Coding	USB communication class request	The software decodes the command, and executes the Data stage and the Status stage.
Other USB commands	-	The software returns a STALL handshake.

2.4.1 Setup Stage

The Setup stage is composed of one setup transaction. The USB host sends a setup token or data packet (USB command), then returns a handshake in response to the data packet (USB command) that the USB device received. Figure 2.5 shows the Setup Transaction Flowchart.

The USB function module automatically executes the Setup stage, Data stage, and Status stage in response to the USB requests (with some exceptions). If the received request is not a USB standard request, the USB function module holds the received request in the EPOS data register (USBEPDR0S), and generates the setup request receive complete interrupt using the SETUPTS bit in the USBIFR0 register.

The sample program reads the USB request held in the data register (USBEPDR0S) during the interrupt, and decodes the USB request to determine how to process subsequent stages. If the decoded USB request is a request to execute the control IN transfer, the sample program writes the first data to transfer to the USB host in the EP0iFIFO and the interrupt is completed. Figure 2.6 shows an operation chart of the sample program. The function (DecComCommand) processes USB communication class requests in the sample program.

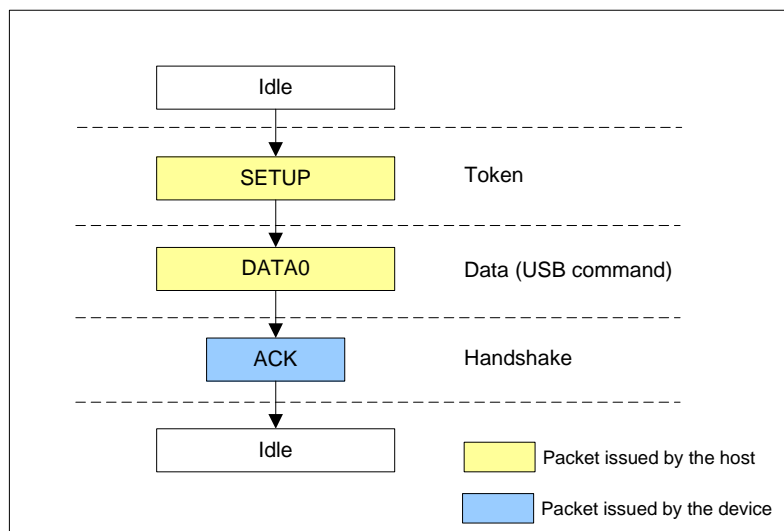


Figure 2.5 Setup Transaction Flowchart

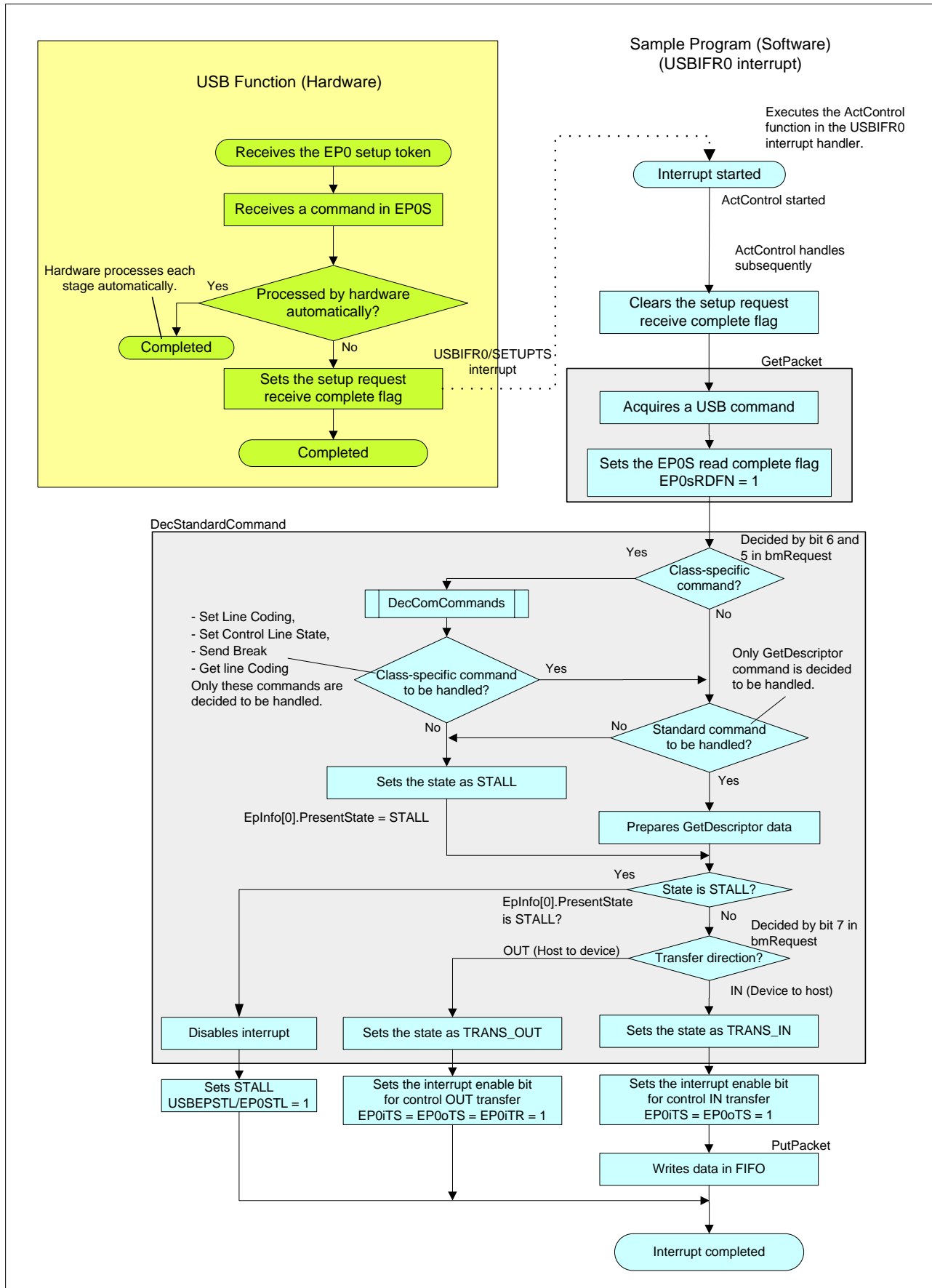


Figure 2.6 Setup Stage

### 2.4.2 Data Stage

The Data stage of the control IN transfer is composed of single or multiple data transactions. This is called “Data IN stage processing”. The Data stage of the control OUT transfer is composed of one data OUT transaction. This is called “Data OUT stage processing”.

#### (1) Data IN Stage

First, the USB host sends an IN token. When the USB device receives the IN token, it sends a data packet to the USB host and waits for an ACK handshake from the USB host. If the USB device cannot send a data packet when it receives the IN token, it returns a NAK handshake to the USB host. Figure 2.7 shows the data IN transaction flowchart.

When the USB function module receives an IN token without valid data in the EP0iFIFO, it automatically returns a NAK handshake to the USB host. When the module receives an IN token with valid data in the EP0iFIFO, it sends the data in the EP0iFIFO to the USB host and waits for an ACK handshake from the USB host. When the USB function module receives an ACK handshake, it generates the data transmit complete interrupt using the EP0iTS bit in the USBIFR0 register. On the contrary, when the module receives an OUT token that indicates the Data IN stage has been completed, it generates the data receive complete interrupt using the EP0oTS bit in the USBIFR0 register.

The sample program identifies the type of the interrupt while it is being processed. When it is the data receive complete interrupt (the EP0oTS bit in the USBIFR0 register), the sample program advances to the Status stage. When it is the data transmit complete interrupt (the EP0iTS bit in the USBIFR0 register), data that should be sent to the USB host is written in the EP0iFIFO, and the sample program waits for the next interrupt. Figure 2.8 shows an operation flowchart of the Data IN stage by the sample program.

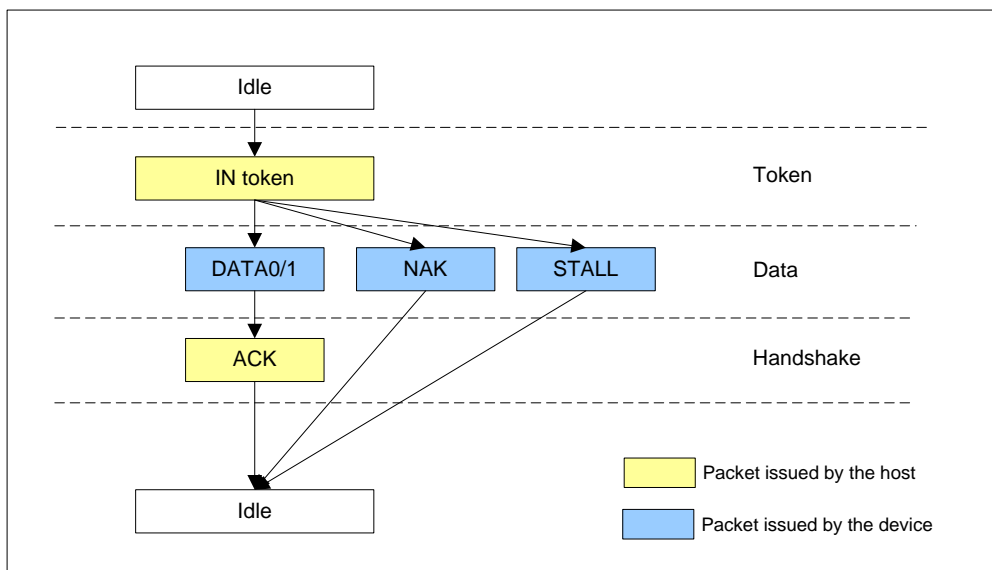


Figure 2.7 Data IN Transaction

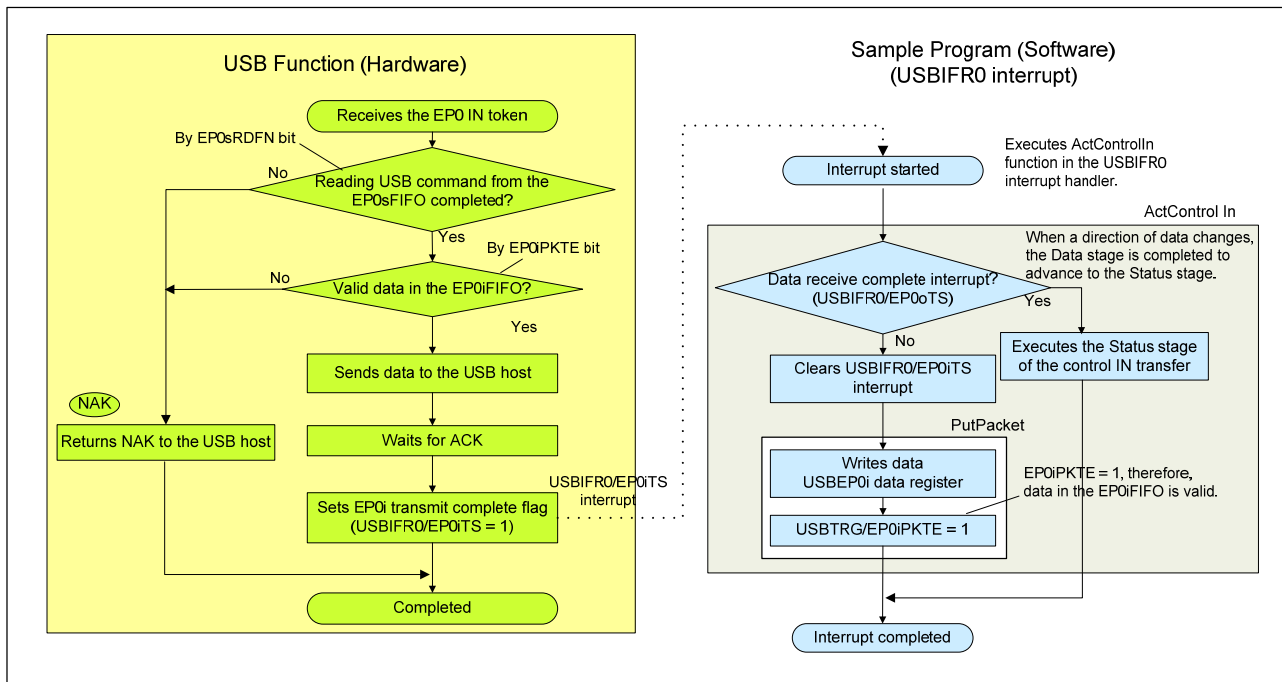


Figure 2.8 Data IN Stage (Control IN Transfer)

(2) Data OUT Stage

The USB host sends an OUT token and a data packet. The USB device receives the OUT token first, then receives the data packet, and then returns an ACK handshake. When the USB device cannot receive the data packet after it receives the OUT token, it ignores subsequent data packets, and returns a NAK handshake. When the USB host receives a NAK handshake, it tries to resend the OUT token and data packet. Figure 2.9 shows the Data OUT Transaction flowchart.

When the USB function module cannot receive data packets, when it receives the OUT token, it automatically discards the subsequent data packet and returns a NAK handshake to the USB host. When it receives the OUT token when it can accept data, it holds the data packet from the USB host in the EP0oFIFO and returns an ACK handshake to the USB host. After the USB function module transmits an ACK handshake, it generates the data receive complete interrupt using the EP0oTS bit in the USBIFR0 register. When the function module receives the IN token that indicates the Data OUT stage is completed, it generates the IN token receive interrupt using the EP0iTR bit in the USBIFR0 register.

The sample program identifies the type of the interrupt while it is being processed. When it is not the data receive complete interrupt (the EP0oTS bit in the USBIFR0 register), the sample program advances to the Status stage. When it is the data receive complete interrupt (the EP0oTS bit in the USBIFR0 register), the sample program reads data in the EP0oFIFO, sets the EP0oFIFO read complete bit, and waits for the next interrupt to be generated. Figure 2.10 shows an operation flowchart of Data OUT stage by the sample program.

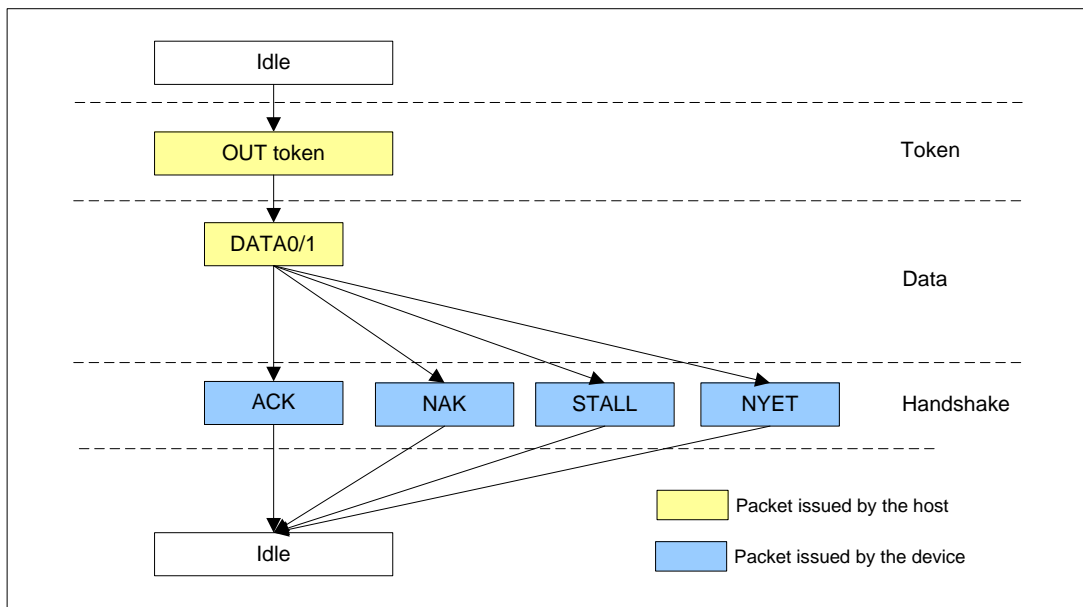


Figure 2.9 Data OUT Transaction

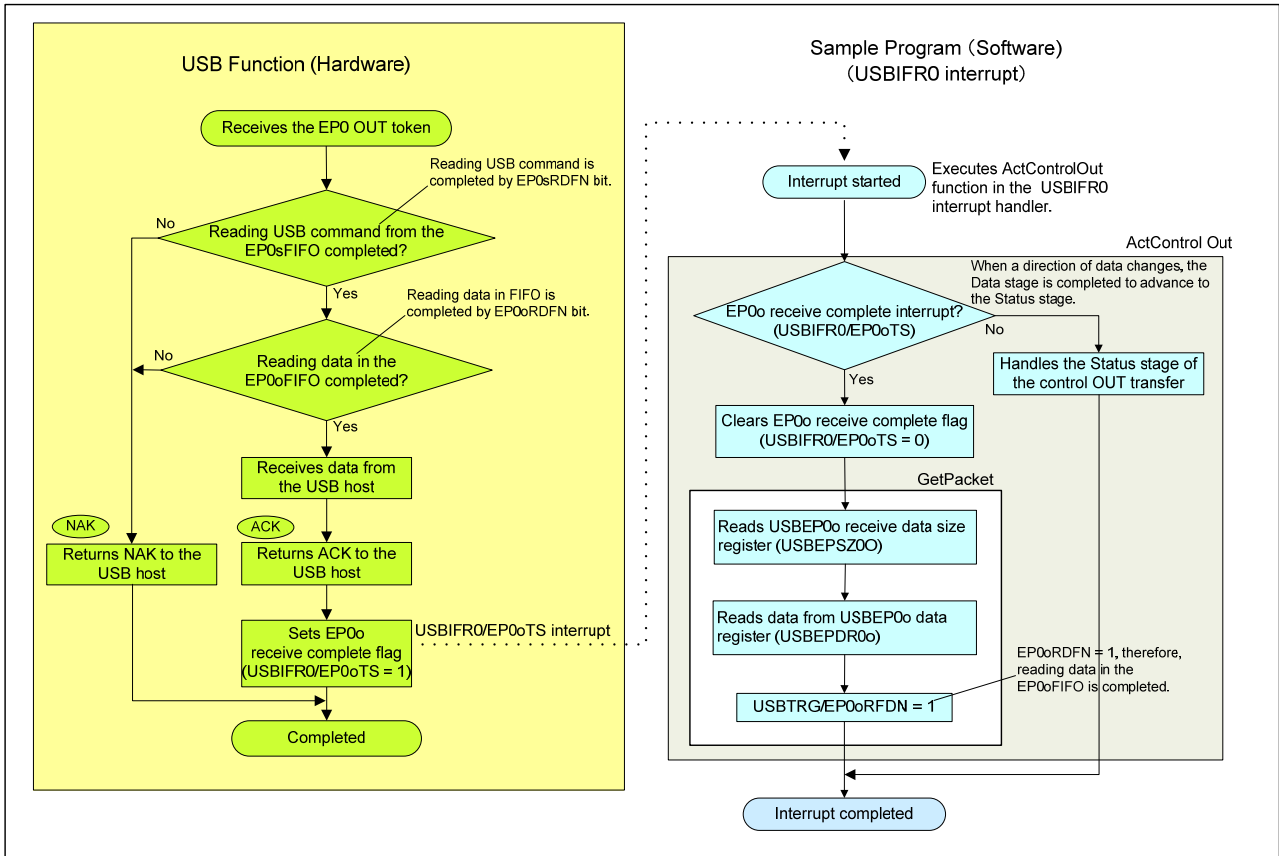


Figure 2.10 Data OUT Stage (Control OUT Transfer)

2.4.3 Status Stage

The direction of the data transaction in the Status stage differs from that of the Data stage; the data OUT transaction is executed during the Status stage of the control IN transfer, and the data OUT transaction is executed during the Status stage of the control OUT transfer.

(1) Status Stage of the Control IN Transfer

The USB host sends an OUT token and a 0-byte data packet. The USB device first receives the OUT token and then receives the 0-byte data packet. Then, it returns an ACK handshake to the USB host.

The USB function module receives the OUT token and the 0-byte data packet, and automatically sends an ACK handshake to the USB host. Then, the USB function module generates the data receive complete interrupt using the EP0oTS bit in the USBIFR0 register.

The sample program sets the EP0oFIFO read complete bit (USBTRG/EP0oRFDN) during an interrupt to wait for the next interrupt. Figure 2.11 shows an operation flowchart of the control IN transfer by the sample program.

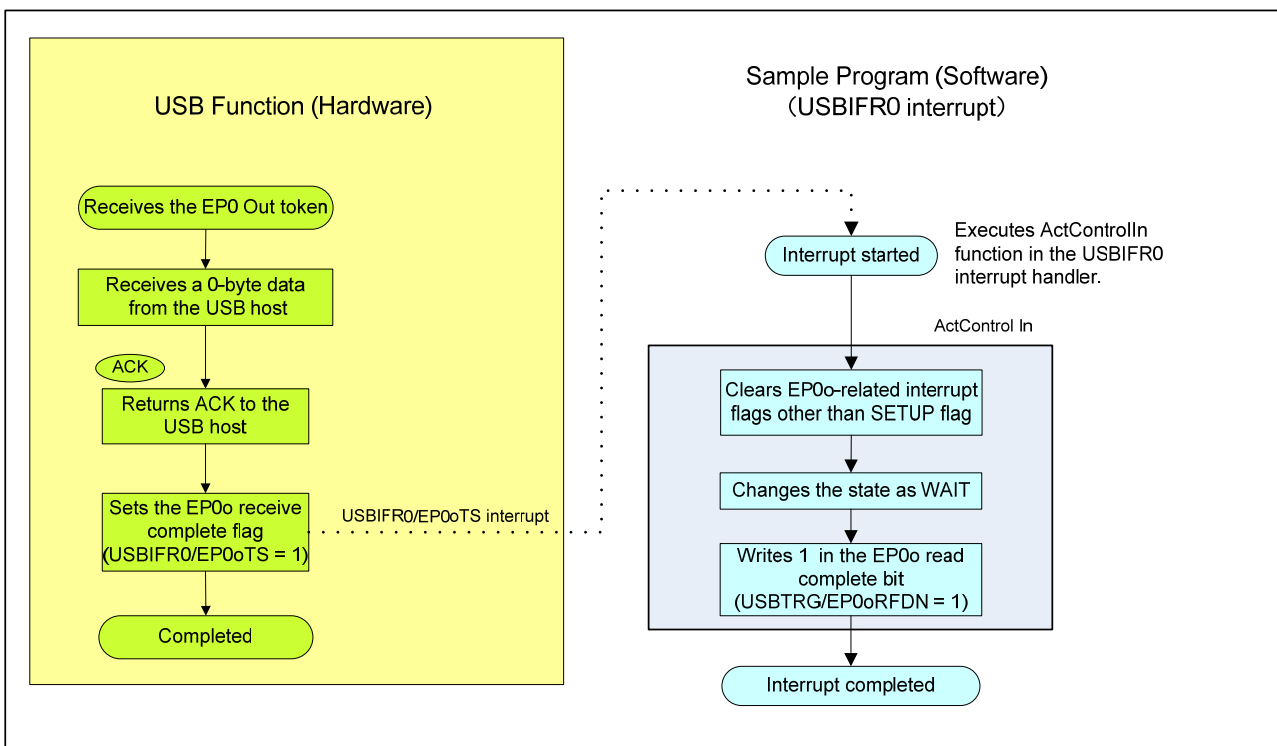


Figure 2.11 Status Stage (Control IN Transfer)



(2) Status Stage of the Control OUT Transfer

The USB host sends an IN token. The USB device sends a 0-byte data packet to the USB host after it receives the IN token. Then, the USB device waits for an ACK handshake from the USB host.

When the USB function module receives the IN token, it generates the IN token receive interrupt using the EP0iTR bit in the USBIFR0 register. When the USB function module receives an IN token although there is no valid 0-byte data packet in the EP0iFIFO, it automatically returns a NAK handshake to the USB host. When the USB function module has a valid 0-byte data packet in the EP0iFIFO when it receives the IN token, it sends a 0-byte data packet to the USB host and waits for an ACK handshake from the USB host. When the USB function module receives the ACK handshake, it generates the data transmit complete interrupt using the EP0iTS in the USBIFR0 register.

The sample program identifies the type of the interrupt while it is being processed. When it is the data transmit complete interrupt generated by the EP0iTS in the USBIFR0 register, the sample program clears the interrupt to complete the control transfer. When it is the IN token receive interrupt generated by the EP0iTR bit in the USBIFR0 register, the sample program enables 0-byte data in the EP0iFIFO by setting the EP0iPKTE bit in the USBTRG register to 1, and waits for the next interrupt to be generated. Figure 2.12 shows an operation flowchart of the Status Stage (Control OUT Transfer) by the sample program. When the command is a USB communication class command (Set Line Coding), the sample program uses a SciInit function to process the command.

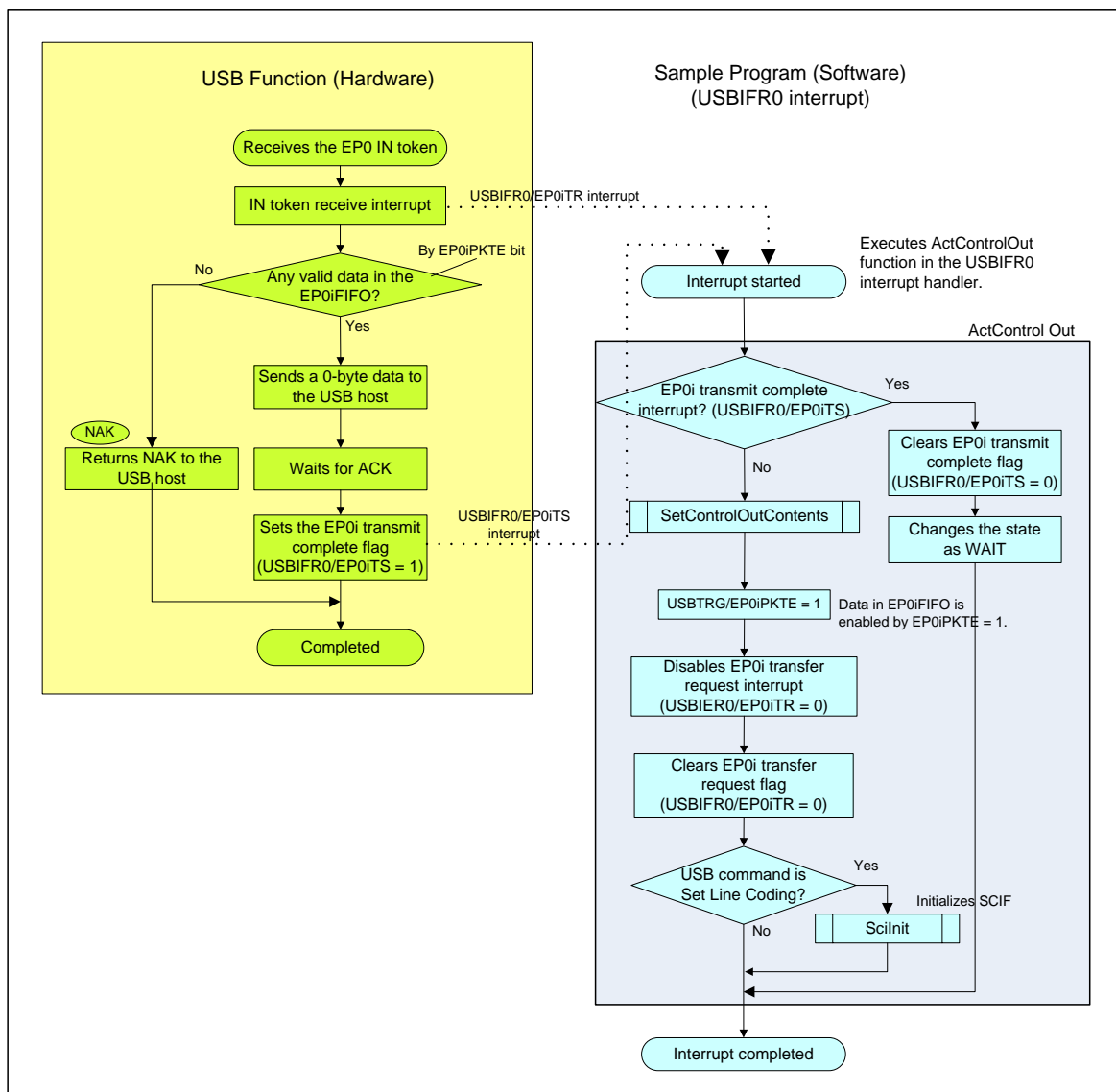


Figure 2.12 Status Stage (Control OUT Transfer)

## 2.5 Bulk Transfer

A bulk transfer is used to communicate large amounts of data between the USB host and the USB device. Bulk transfers are supported via bi-directional communication flow, according to the data direction. A bulk OUT transfer is the data flow from the USB host to the USB device, and a bulk IN transfer is the data flow from the USB device to the USB host. Figure 2.13 shows data directions of the bulk IN and bulk OUT transfers.

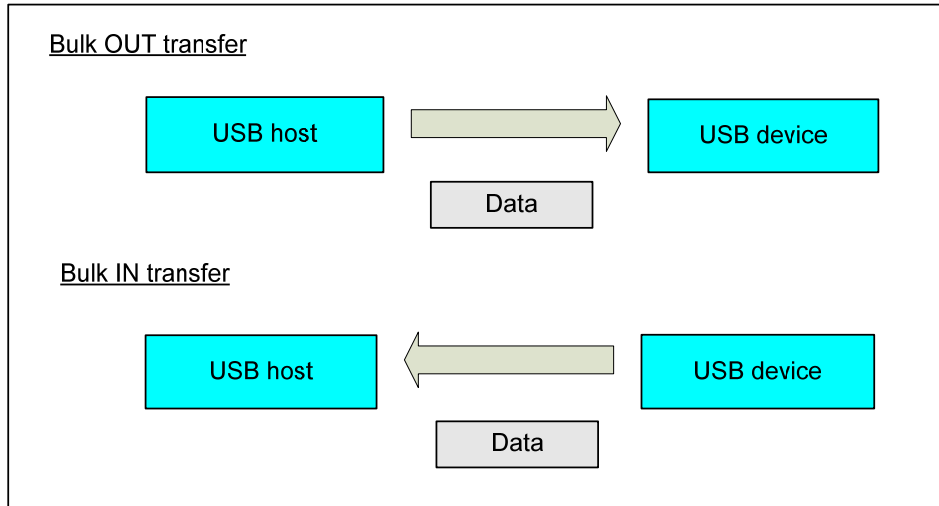


Figure 2.13 Bulk Transfer

2.5.1 Bulk OUT Transfer

A bulk OUT transfer is composed of single or multiple OUT transactions. The USB host sends an OUT token and a data packet in the OUT transaction. The USB device receives the out token first, then receives the data packet, and then returns an ACK handshake. When the USB device receives the OUT token although it is unable to receive data packets, it ignores subsequent data packets and returns a NAK handshake. When the USB host receives a NAK handshake, it attempts to resend the OUT token and data packet to the USB device. Figure 2.14 shows the OUT Transaction flowchart.

When the USB function module receives an OUT token although it is unable to receive data packets, it automatically discards subsequent data packets and returns a NAK handshake to the USB host. When the USB function module receives an OUT token when it can accept data packets, it holds the data from the USB host in the EP1FIFO and returns an ACK handshake to the USB host. Then, the USB function module generates the data receive complete interrupt using the EP1FULL bit in the USBIFR0 register.

The sample program reads the data in the EP1FIFO and stores it in the bulk OUT transfer RAM during the interrupt, sets the EP1 read complete flag (by setting the EP1RDFN bit in the USBTRG register to 1), and waits for the next interrupt to be generated. When the interrupt is generated, if there is no area in the EP1FIFO to store data, the sample program disables the EP1FULL interrupt, and the interrupt process is completed while it is in a suspended state. When serial communication is used to create an area in the bulk OUT transfer RAM, enabling the EP1FULL interrupt causes the suspended EP1FULL interrupt to be generated, and moves the data in the EP1FIFO to the bulk OUT transfer RAM during the interrupt, and sets the EP1 read complete flag to wait for the next interrupt to be generated.

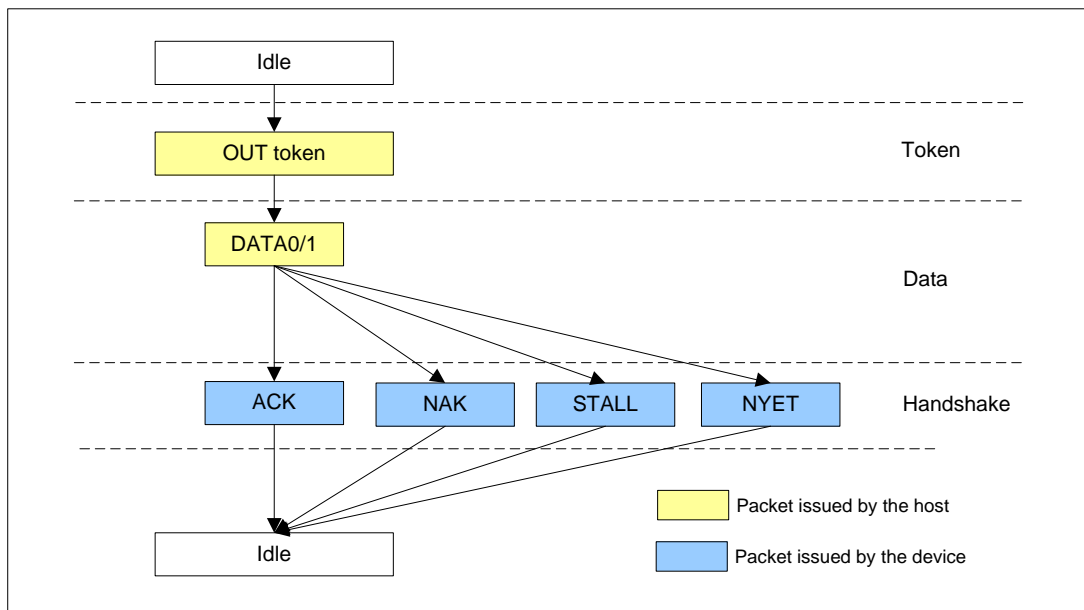


Figure 2.14 OUT Transaction

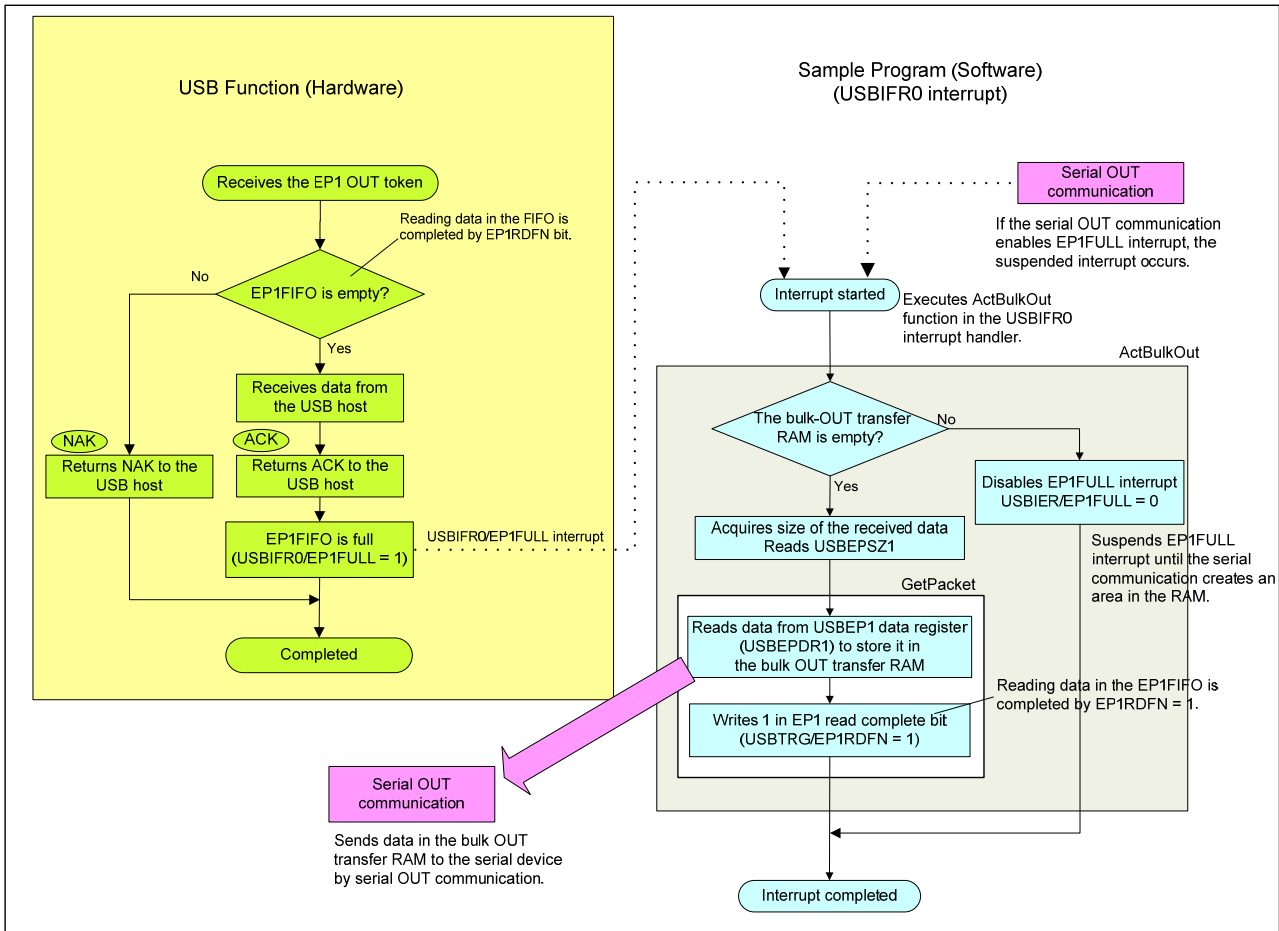


Figure 2.15 Bulk OUT Transfer

2.5.2 Bulk IN Transfer

A bulk IN transfer consists of single or multiple transactions. The USB host sends an IN token in the IN transaction. When the USB device receives the IN token, it sends a data packet to the USB host and waits for an ACK handshake from the USB host. When the USB device receives the IN token although it is unable to send data packets, it returns a NAK handshake to the USB host. Figure 2.16 shows the IN Transaction flowchart.

When the USB function module receives an IN token although there is no valid data in the EP2FIFO, it automatically returns a NAK handshake to the USB host. The USB function module determines if there is any valid data in the EP2FIFO using the EP2PKTE bit in the USBTRG register. When the module receives the IN token when there is valid data in the EP2FIFO, the USB function module sends the data in the EP2FIFO to the USB host and waits for an ACK handshake from the USB host. When the ACK handshake is received, the USB function module sets the data transmit complete flag using the EP2EMPTY bit in the USBIFR0 register.

The sample program periodically transfers data in bulk transfer mode within the main loop. When the serial communication generates data in the bulk IN transfer RAM that should be transmitted to the USB host, the sample program confirms if the EP2FIFO is empty. When the EP2FIFO is empty, the sample program writes the data in the EP2FIFO, sets the PE2PKTE bit to 1, and enables the data in the EP2FIFO. When the EP2FIFO is not empty, the sample program is idle and waits for the USB function module to finish transferring data to the USB host.

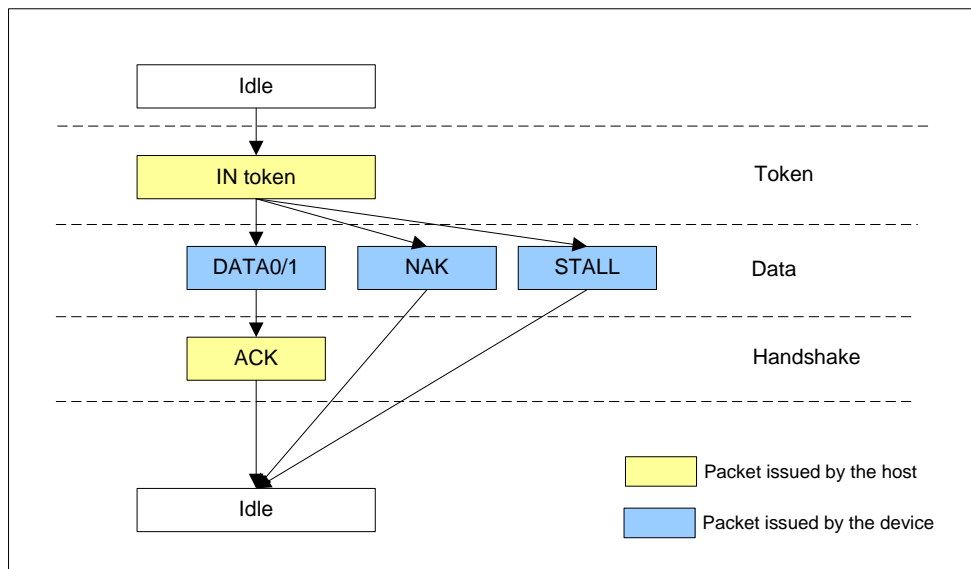


Figure 2.16 IN Transaction

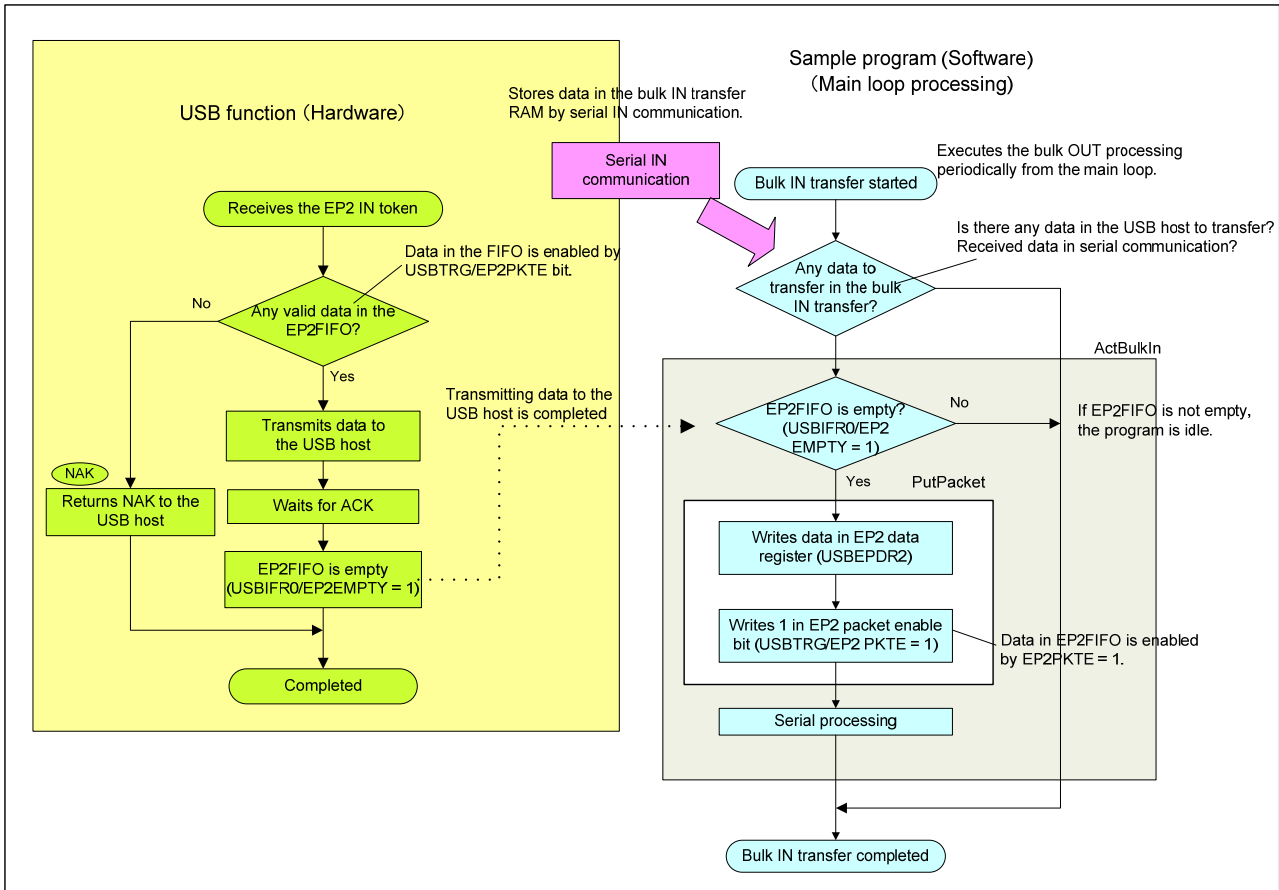


Figure 2.17 Bulk IN Transfer

### 3. USB to Serial Conversion System Using the USB Function Module

#### 3.1 Overview

The sample program converts USB to serial using the USB function module and the serial communication interface embedded in the SH7285 MCU. To transfer keyboard-input characters, text files, or binary files, activate the terminal software both on the USB host (a computer in this case), and on the serial device. For example, some characters are input using the keyboard of the USB host, and the characters are transferred to the serially connected device. On the other hand, some characters are input using keyboard of the serially connected device for transfer to the USB host.

A system configuration of the USB to serial conversion is shown in Figure 3.1, and Table 3.1 lists its specifications.

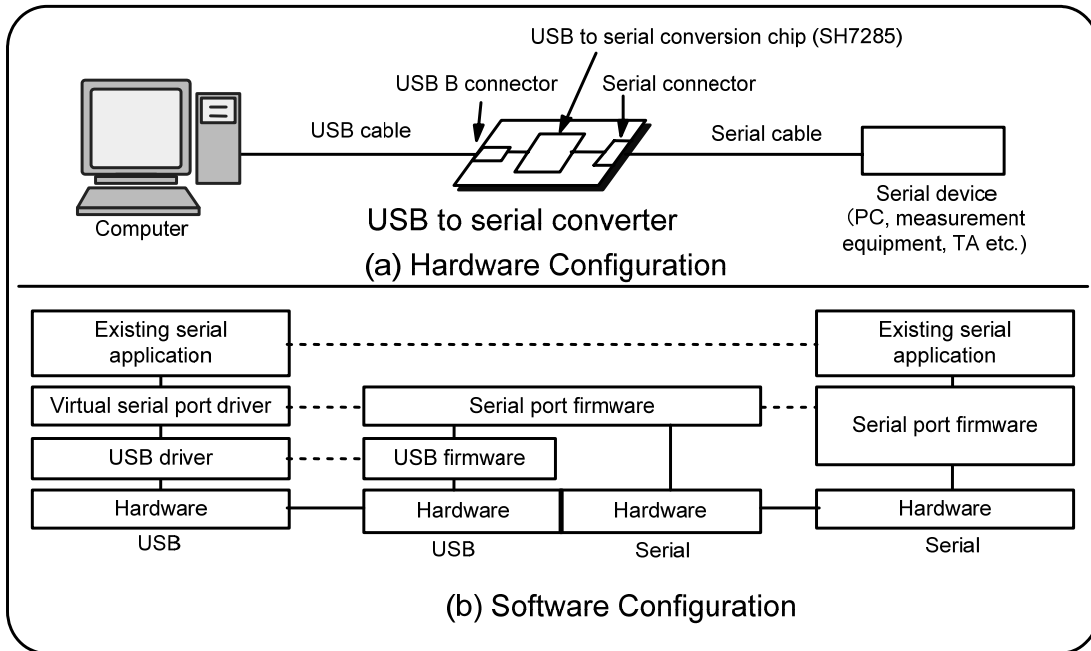


Figure 3.1 System Configuration

Table 3.1 Specifications

Features	Description
Detect a connection to the USB host	After the hardware detects a connection, the port pulls up the D+ pin.
Control transfer (USB standard request)	<ul style="list-style-type: none"> <li>Decode requests, processes the Data stage and Status stage of the USB request transmitted from the USB host in the control transfer.</li> <li>Sends the descriptor information shown in Figure 3.2 through Figure 3.4 to Get Descriptor command to connect with the USB host PC as a USB communication class.</li> <li>Descriptor samples to send to the USB host are shown in the SetUsbInfo.h file. Figure 3.2 shows the device descriptor sample, Figure 3.3 and Figure 3.4 shows the configuration descriptor samples. Table 3.2 lists Vendor ID and Product ID of the sample.</li> </ul>
Control transfer (USB communication class request)	Executes the following USB communication class commands: Get Line Coding, Set Line Coding, Set Control Line State, and Send Break
Bulk IN/OUT transfer	Executes the bulk IN/OUT transfer.
Serial/USB communication conversion	<p>(1) Sends the received data from the USB host in bulk OUT transfer to the serial device by serial OUT communication.</p> <p>(2) Sends the received data from the serial device by serial IN communication to the USB host in bulk IN transfer.</p>

```

/* Descriptor Information */
/* Device Descriptor */
unsigned char DeviceItem[] = {
    0x12,0x01,0x10,0x01,
    0x02, /* Communication Class */
    0x00,0x00,0x08,
    0x5B, /* Vendor = Renesas Technology */
    0x04, /* ""Attention"" Please use your company Vendor ID */
    0x20, /* Product ID 0x0020 */
    0x00,0x00,0x01,0x00,0x00,
    0x03, /* Strings Descriptor iSerialNumber */
    0x01
};

DeviceType deviceDescriptorGVar[] = {
    {18,DeviceItem}
};

```

Figure 3.2 Device Descriptor Sample

Note:

Table 3.2 lists the default value of the vendor ID and product ID in the device descriptor sample. These values MUST be changed when applied to the user system.

Table 3.2 Vendor ID and Product ID Sample

ID	Value	Description
Vendor ID	0x045B	Renesas Technology
Product ID	0x0020	Renesas SH7285 Serial-USB



```

/* Configuration Descriptor */
/* Configuration Descriptor informations , Data length = 67Byte */
unsigned char configurationItem[] = {
    /* Configuration Descriptor */
    0x09, /* 0:bLength */
    0x02, /* 1:bDescriptorType */
    0x43, /* 2:wTotalLength(L) */ /* 43'h (=67) */
    0x00, /* 3:wTotalLength(H) */
    0x02, /* 4:bNumInterfaces */
    0x01, /* 5:bConfigurationValue */
    0x00, /* 6:iConfiguration */
    0xC0, /* 7:bmAttributes */ /* self powered */
    0x10, /* 8:MAXPower */

    /* Interface Descriptor 1-0-0 [Communication Class] */
    0x09, /* 0:bLength */
    0x04, /* 1:bDescriptor */
    0x00, /* 2:bInterfaceNumber */
    0x00, /* 3:bAlternateSetting */
    0x01, /* 4:bNumEndpoints */ /* support INT IN (= EP3) */
    0x02, /* 5:bInterfaceClass */ /* Communication Interface Class */
    0x02, /* 6:bInterfaceSubClass */ /* Abstract Control Model */
    0x01, /* 7:bInterfaceProtocol */ /* Common AT commands */
    0x00, /* 8:iInterface */

    /* Class-Specific Configuration Descriptors */
    /* Header Functional Descriptor */
    0x05, /* 0:length of this desc. */
    0x24, /* 1:CS_INTERFACE */
    0x00, /* 2:Header Functional Descr. */
    0x10, /* 3:bcdCDC Rel. 1.10 */
    0x01, /* 4:bcdCDC Rel. 1.10 */

    /* Abstract Control Management Functional Descriptor */
    0x04, /* 0:length of this desc. */
    0x24, /* 1:CS_INTERFACE */
    0x02, /* 2:Abstr.Contr.Managm. F.D. */
    0x06, /* 3:bmCapabilities */ /* support Send Break, Set Line Coding,
                                     Set Control Line State, Get Line Coding */

    /* Union Functional Descriptor */
    0x05, /* 0:length of this desc. */
    0x24, /* 1:CS_INTERFACE */
    0x06, /* 2:Union Functional Descr. */
    0x00, /* 3:bMasterInterface */
    0x01, /* 4:bSlaveInterface0 */

    /* Call Management Functional Descriptor */
    0x05, /* 0:length of this desc. */
    0x24, /* 1:CS_INTERFACE */
    0x01, /* 2:Call Managment F.D. */
    0x03, /* 3:bmCapabilities */
    0x01, /* 4:bDataInterface */

    /* Endpoint Descriptor 1-0-0-0 */
    0x07, /* 0:bLength */
    0x05, /* 1:bDescriptorType */
    0x83, /* 2:bEndpointAddress */ /* IN, number = 3 */
    0x03, /* 3:bmAttribute */
    0x08, /* 4:wMAXPacketSize_lo */
    0x00, /* 5:wMAXPacketSize_hi */
    0x10, /* 6:bInterval */

```

Figure 3.3 Configuration Descriptor Sample (1/2)

```

/* Interface Descriptor 1-1-0 [Data Class Interface] */
0x09, /* 0:bLength */
0x04, /* 1:bDescriptor */
0x01, /* 2:bInterfaceNumber */
0x00, /* 3:bAlternateSetting */
0x02, /* 4:bNumEndpoints */ /* support Bulk OUT (= EP1) and Bulk IN (= EP2) */
0x0A, /* 5:bInterfaceClass */ /* Data Interface Class */
0x00, /* 6:bInterfaceSubClass */ /* unuse */
0x00, /* 7:bInterfaceProtocol */ /* USB */
0x00, /* 8:iInterface */

/* Endpoint Descriptor 1-1-0-0 */
0x07, /* 0:bLength */
0x05, /* 1:bDescriptorType */
0x01, /* 2:bEndpointAddress */
0x02, /* 3:bmAttribute */
0x40, /* 4:wMAXPacketSize_lo */
0x00, /* 5:wMAXPacketSize_hi */
0x00, /* 6:bInterval */

/* Endpoint Descriptor 1-1-0-1 */
0x07, /* 0:bLength */
0x05, /* 1:bDescriptorType */
0x82, /* 2:bEndpointAddress */
0x02, /* 3:bmAttribute */
0x40, /* 4:wMAXPacketSize_lo */
0x00, /* 5:wMAXPacketSize_hi */
0x00, /* 6:bInterval */

};

ConfigurationType configurationDescriptorGVar[] = {
    {67,configurationItem}
};

```

Figure 3.4 Configuration Descriptor Sample (2/2)

### 3.2 Operation Flowchart

The sample program enters the main loop after initial settings are completed.

When the sample program receives a data packet from the serial device in serial IN communication, it stores the received packet in the bulk IN transfer RAM. The stored data is transmitted to the USB host in a bulk IN transfer. For details on bulk IN transfer, refer to 2.5.2 Bulk IN Transfer. For details on serial IN communication, refer to 3.3.2 Serial IN Communication.

When the sample program receives a data packet from the USB host in a bulk OUT transfer, it stores the received data packet in the bulk OUT transfer RAM. The stored data is transmitted to the serial device in the serial OUT communication. For details on the bulk OUT transfer, refer to 2.5.1 Bulk OUT Transfer. For details on serial OUT communication, refer to 3.3.1 Serial OUT Communication.

Figure 3.5 shows an Operation Flowchart and Figure 3.6 shows the Data Flow.

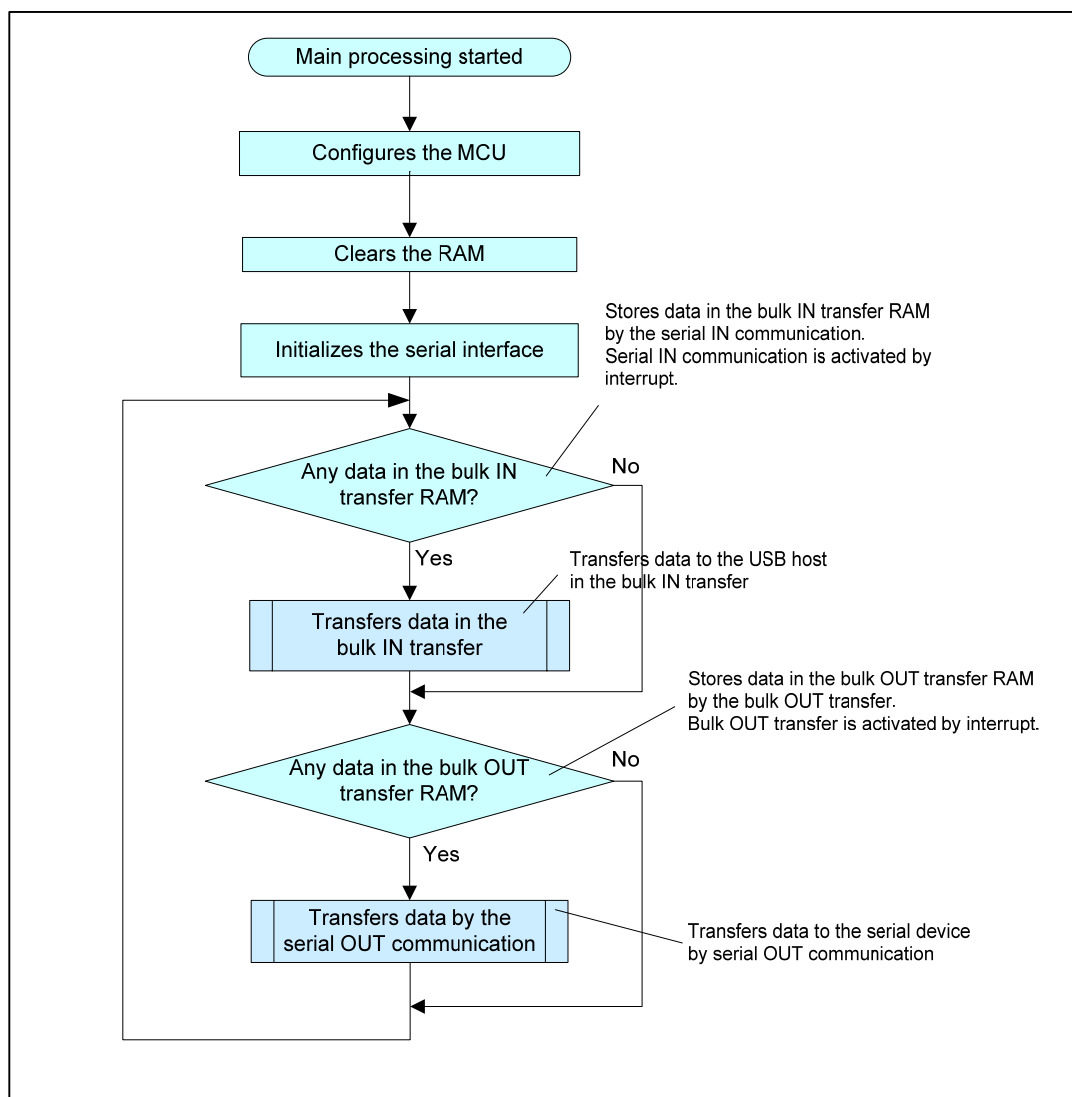


Figure 3.5 Operation Flowchart

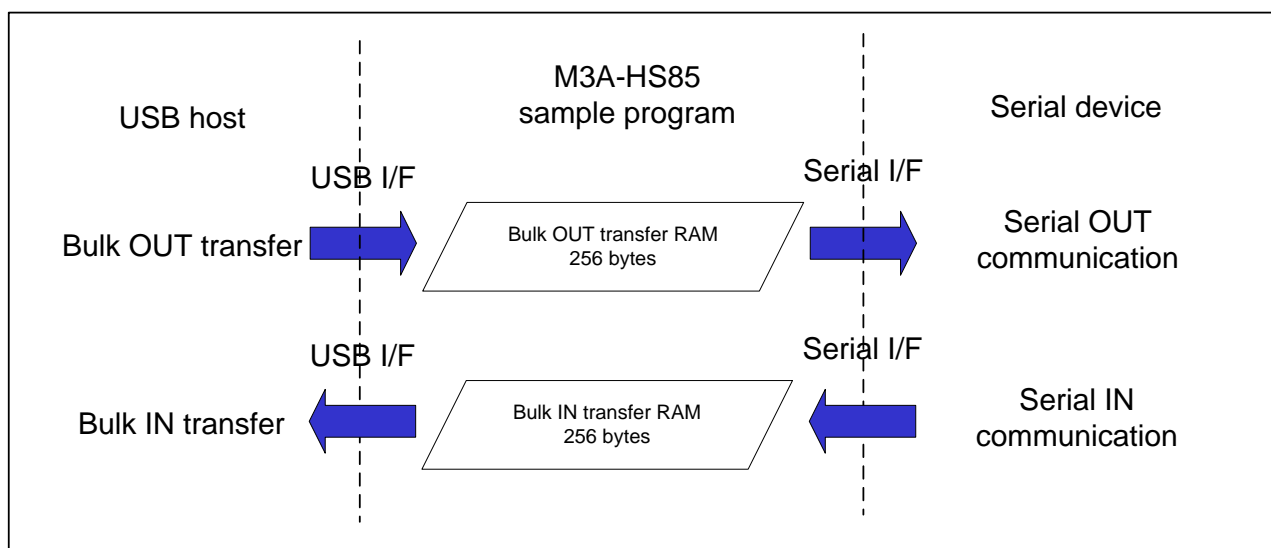


Figure 3.6 Data Flow

### 3.3 Serial Communication

The sample program uses a SCIF module<sup>1</sup> for serial communication. Serial OUT communication is executed only when there is data in the bulk OUT transfer RAM, and serial IN communication is executed only by the serial receive interrupt.

#### 3.3.1 Serial OUT Communication

The sample program uses the ActSerialout function to execute serial OUT communication. Data in the bulk OUT transfer RAM is serially transmitted in serial OUT communication. When the bulk OUT transfer RAM is sufficiently empty by the serial OUT communication, the sample program enables the EP1FULL interrupt. When the EP1FULL interrupt is enabled, the suspended EP1FULL interrupt occurs to transfer data in the bulk OUT transfer. Figure 3.7 shows an operation flowchart of the Serial OUT Communication.

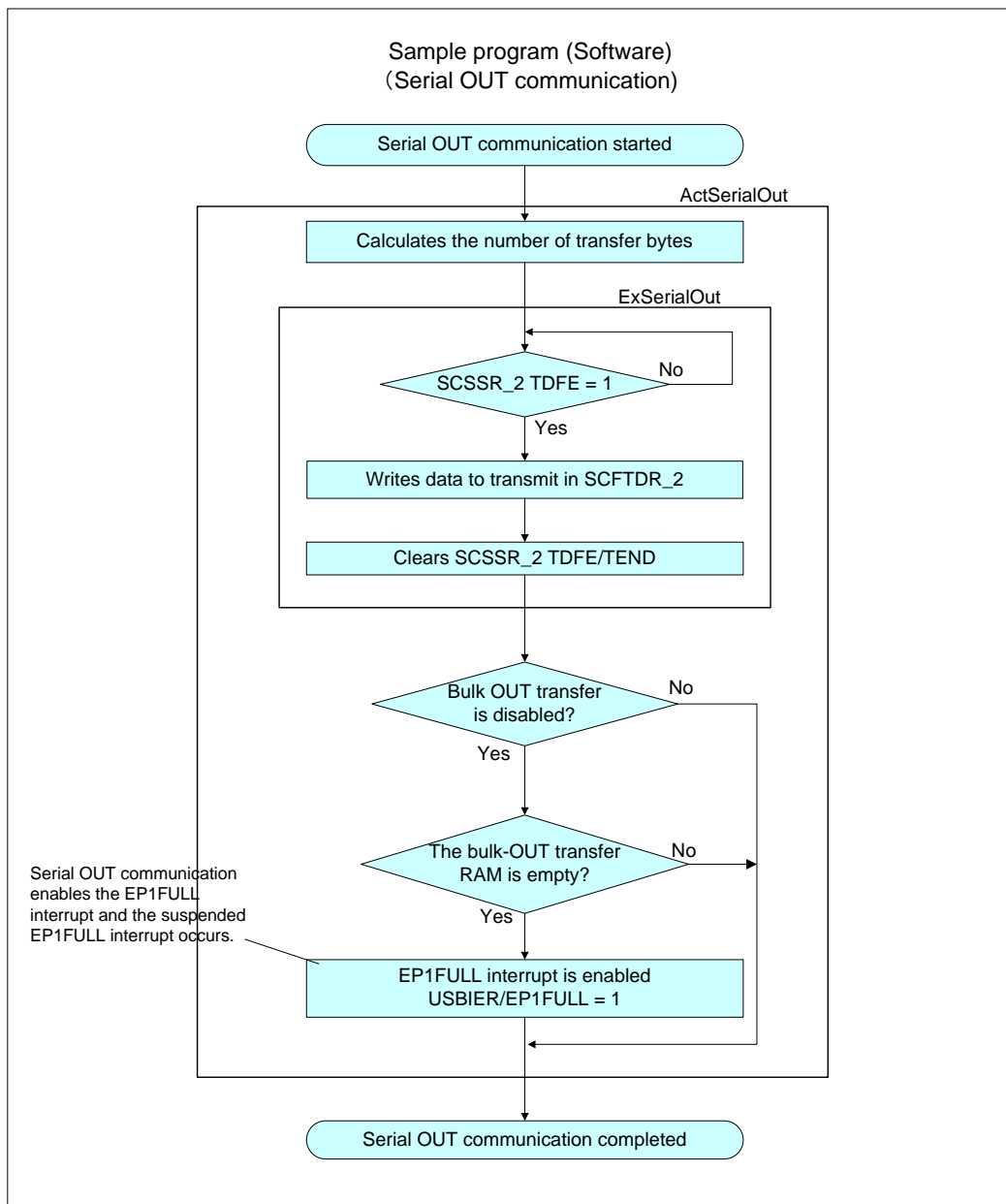


Figure 3.7 Serial OUT Communication

<sup>1</sup> This is for the M3A-HS85 with the SH7285 MCU. The SCI module is used on the M3A-HS87 with the SH7286 MCU.

3.3.2 Serial IN Communication

Serial IN communication is activated by the serial receive interrupt and executed by the ActSerialIn function. The sample program stores serially-received data in the RAM for the bulk IN transfer. When the RAM is full, the sample program transmits Xoff in serial communication to disable the serial IN communication. Figure 3.8 shows an operation flowchart of the Serial IN Communication.

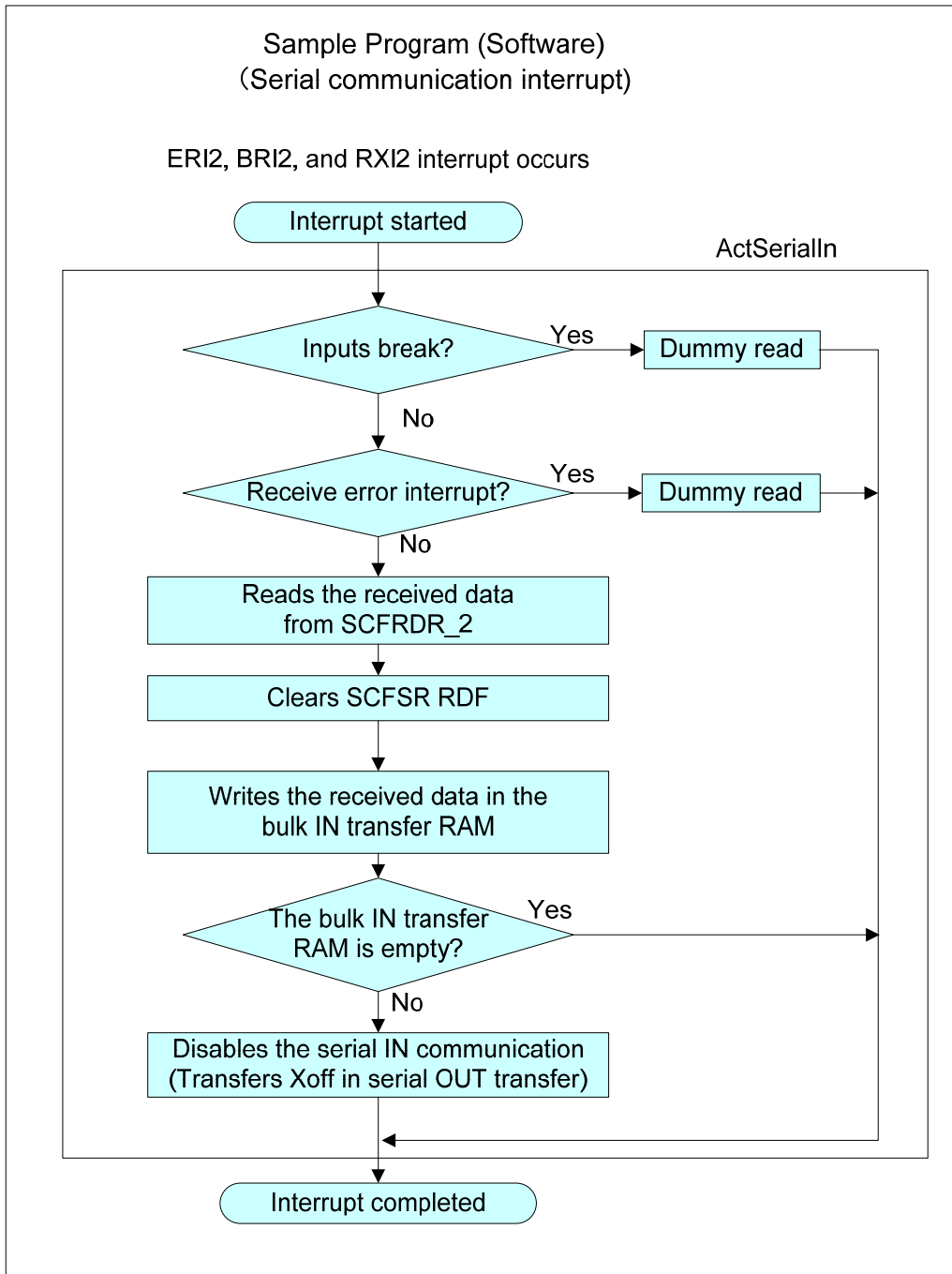


Figure 3.8 Serial IN Communication

### 3.4 Setting Environment

Use an RS-232C serial cable to connect the M3A-HS85 (SH7285 CPU board) to the computer (cross-connect). Then, use a USB cable to connect the M3A-HS19 to the computer. Figure 3.9 shows the Setting Environment.

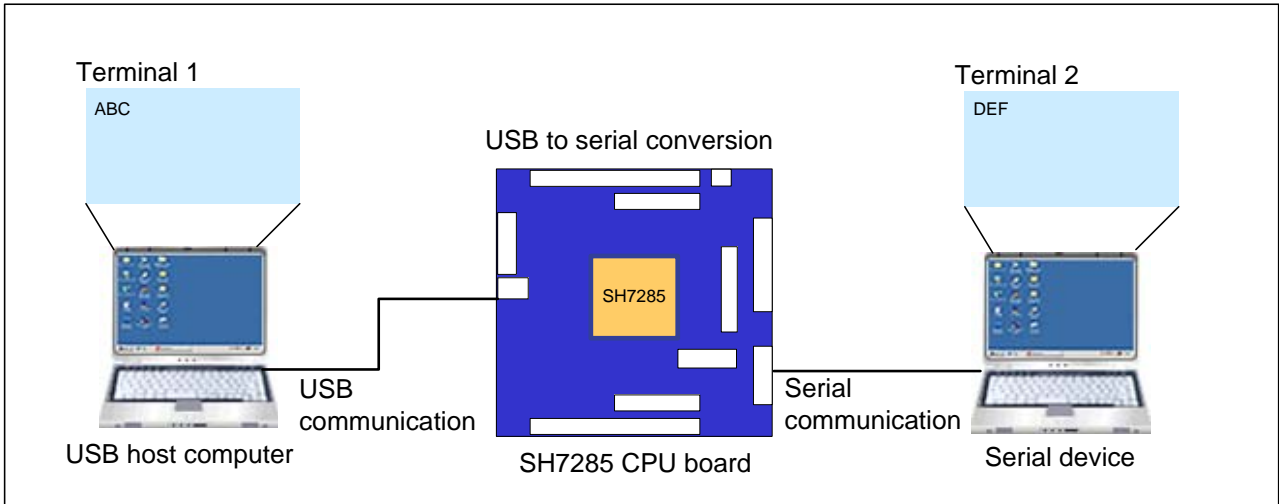


Figure 3.9 Setting Environment

#### 3.4.1 USB Host Computer Setting

After the sample program is written to the M3A-HS85 and is connected to the USB host computer with a USB cable for the first time, the device driver needs to be installed on the USB host computer. Install the Windows standard USB communication class device driver (usbser.sys) as the device driver. Figure 3.10 through Figure 3.12 show the INF files for Windows. These files are used for installation.

```

;-----
;   Renesas Technology Corp
;   USB Serial Ports Driver
;   for Windows2000 and WindowsXP
;   29 September 2003
;-----

[Version]
LayoutFile=layout.inf
Signature="$CHICAGO$"
Class=Ports
ClassGuid={4D36E978-E325-11CE-BFC1-08002BE10318}
Provider=%MyCompany%
DriverVer=29/09/2003,1.0.0.0

[DestinationDirs]
DefaultDestDir=12

[Manufacturer]
%MyCompany%=Models

[ClassInstall]
AddReg=PortsClass.AddReg
    
```

Figure 3.10 INF File Example for Windows (1/3)

```

[PortsClass.AddReg]
HKR,,,%PortsClassName%

[ClassInstall32.NT]
AddReg=PortsClass.NT.AddReg

[PortsClass.NT.AddReg]
HKR,,,%PortsClassName%
HKR,,Icon, "-23"
HKR,,Installer32,, "MsPorts.Dll,PortsClassInstaller"

[ControlFlags]
ExcludeFromSelect=*

;*****
; Please change to your company's VID and PID *
;*****

[Models]
%USB.PnP%=ComPort, USB%VID_045B&PID_0020 /* USB Vendor ID & Product ID */

[ComPort.NT]
CopyFiles=ComPort.Copy
AddReg=ComPort.AddReg, ComPort.NT.AddReg

[ComPort.NT.HW]
AddReg=ComPort.NT.HW.AddReg

[ComPort.NT.Services]
AddService = usbser, 0x00000002, Serial_Service_Inst,
Serial_EventLog_Inst
AddService = Serenum,,Serenum_Service_Inst

[ComPort.NT.HW.AddReg]
HKR,,"UpperFilters",0x00010000,"serenum"

; ----- USBSerial Port Driver install sections
[Serial_Service_Inst]
DisplayName = %Serial.SVCDESC%
ServiceType = 1 ; SERVICE_KERNEL_DRIVER
StartType = 3 ; SERVICE_DEMAND_START
ErrorControl = 1 ; SERVICE_ERROR_NORMAL
ServiceBinary = %12%\usbser.sys
LoadOrderGroup = Extended base

; ----- Serenum Driver install section
[Serenum_Service_Inst]
DisplayName = %Serenum.SVCDESC%
ServiceType = 1 ; SERVICE_KERNEL_DRIVER
StartType = 3 ; SERVICE_DEMAND_START
ErrorControl = 1 ; SERVICE_ERROR_NORMAL
ServiceBinary = %12%\serenum.sys
LoadOrderGroup = PNP Filter

[Serial_EventLog_Inst]
AddReg = Serial_EventLog_AddReg
    
```

Figure 3.11 INF File Example for Windows (2/3)



```
[Serial_EventLog_AddReg]
HKR,,EventMessageFile,0x00020000,"%SystemRoot%%¥System32¥IoLogMsg.dll;%
[SystemRoot%%¥System32¥drivers¥usbser.sys"
HKR,,TypesSupported,0x00010001,7

; COM sections
;-----
[ComPort.Copy]
usbser.sys,,0x20

[ComPort.AddReg]
HKR,,PortSubClass,1,01

[ComPort.NT.Copy]
CopyFiles=ComPort.Copy

[ComPort.NT.AddReg]
HKR,,EnumPropPages32,, "MsPorts.dll,SerialPortPropPageProvider"

;*****
; Please change to your company's information *
;*****
[Strings]
MyCompany="Renesas Technology Corp"
DiskName_Desc="Installation Disk"
PortsClassName = "Ports (COM & LPT)"
Serenum.SVCDESC = "Serenum Filter Driver"
Serial.SVCDESC = "USB Serial Ports Driver"
USB.PnP="USB Serial Ports Driver"
```

Figure 3.12 INF file example for Windows (3/3)

Note:

VID\_045B and PID\_0020 MUST be changed according to the Vendor ID and Product ID set in the device descriptor. Table 3.3 shows the default values.

Table 3.3 Vendor ID and Product ID

Value	Description
VID_045B	Indicates the Vendor ID = 0x045B.
PID_0020	Indicates the Product ID = 0x0020.

### 3.4.2 PC-PC Communication Settings

The table below lists the settings for the terminal software.

Table 3.4 Terminal Software Settings

Items	Description
Connection	Select the number of ports connected to an RS-232C serial cable or a USB cable
bps (B)	115200 bps
Data bits (D)	8
Parity (P)	None
Stop bit (S)	1
Flow control(F)	Xon/Xoff

#### 4. References

##### Software Manual

SH-1/SH-2/SH-DSP Software Manual Rev. 7.00

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## Revision History

Rev.	Date	Description	
		Page	Summary
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