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Renesas Electronics Corporation

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SH7046 Group

Complementary PWM 3-Phase Output

1. Specifications

Three-phase PWM waveform output is performed with a non-overlapping relationship between positive and negative phases, as shown in figure 1.

The duty can be changed between 0% and 100% by setting an arbitrary value in RAM.

$$\text{Duty} = \frac{\text{Pulse high width}}{\text{Pulse period}} \times 100 (\%)$$

Toggle waveform output is performed synchronized with the period.

When operating with on-chip peripheral clock $P\phi = 20.0 \text{ MHz}$, the output pulse period can be set arbitrarily in the range 100.0 ns to 3.27 ms.

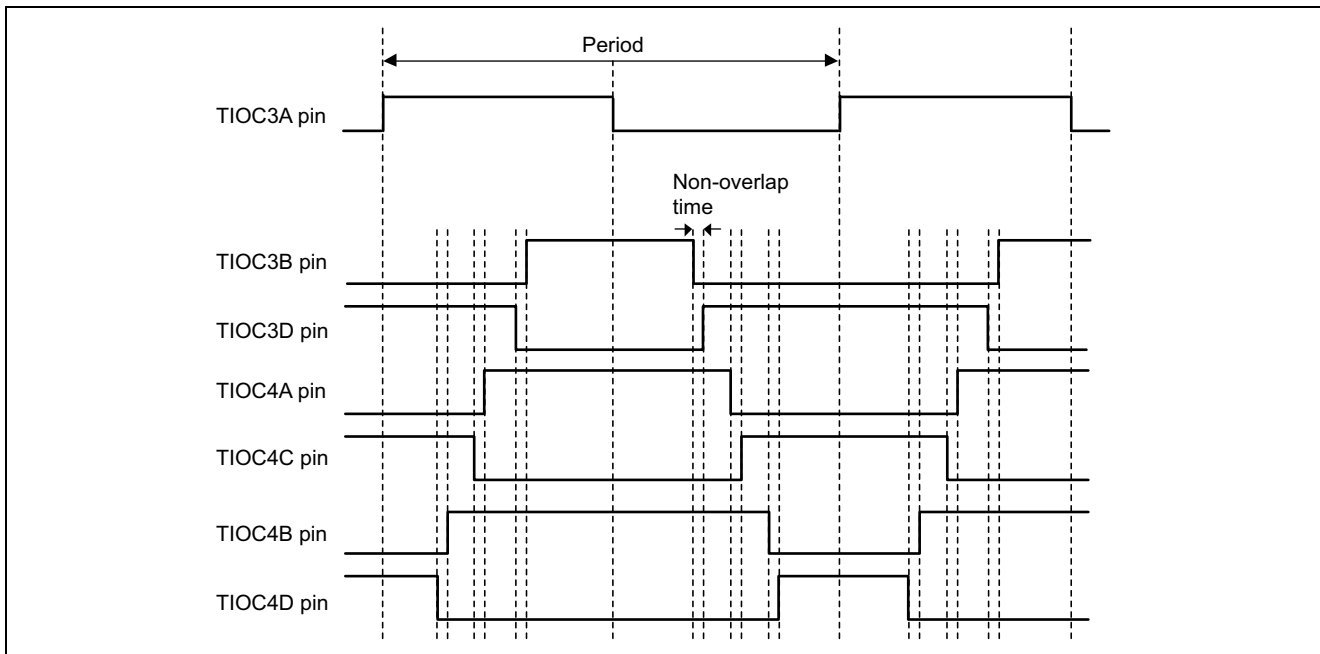


Figure 1 Complementary PWM 3-Phase Output Waveforms

2. Functions Used

In this sample task, 3-phase PWM waveform output with a non-overlapping relationship between positive and negative phases is performed using MTU channels 3 and 4.

Figure 2 shows a block diagram of MTU/ch3 and ch4 as used in this sample task.

This sample task uses the following functions.

- A function that performs 3-phase PWM waveform output with a non-overlapping relationship between positive and negative phases (complementary PWM mode)
- A function that transfers buffer register (TGRC/D_3, TGRC/D_4) contents to compare registers (TGRA/B_3, TGRA/B_4) when a compare match occurs
- A function that outputs a toggle waveform synchronized with the PWM waveform period

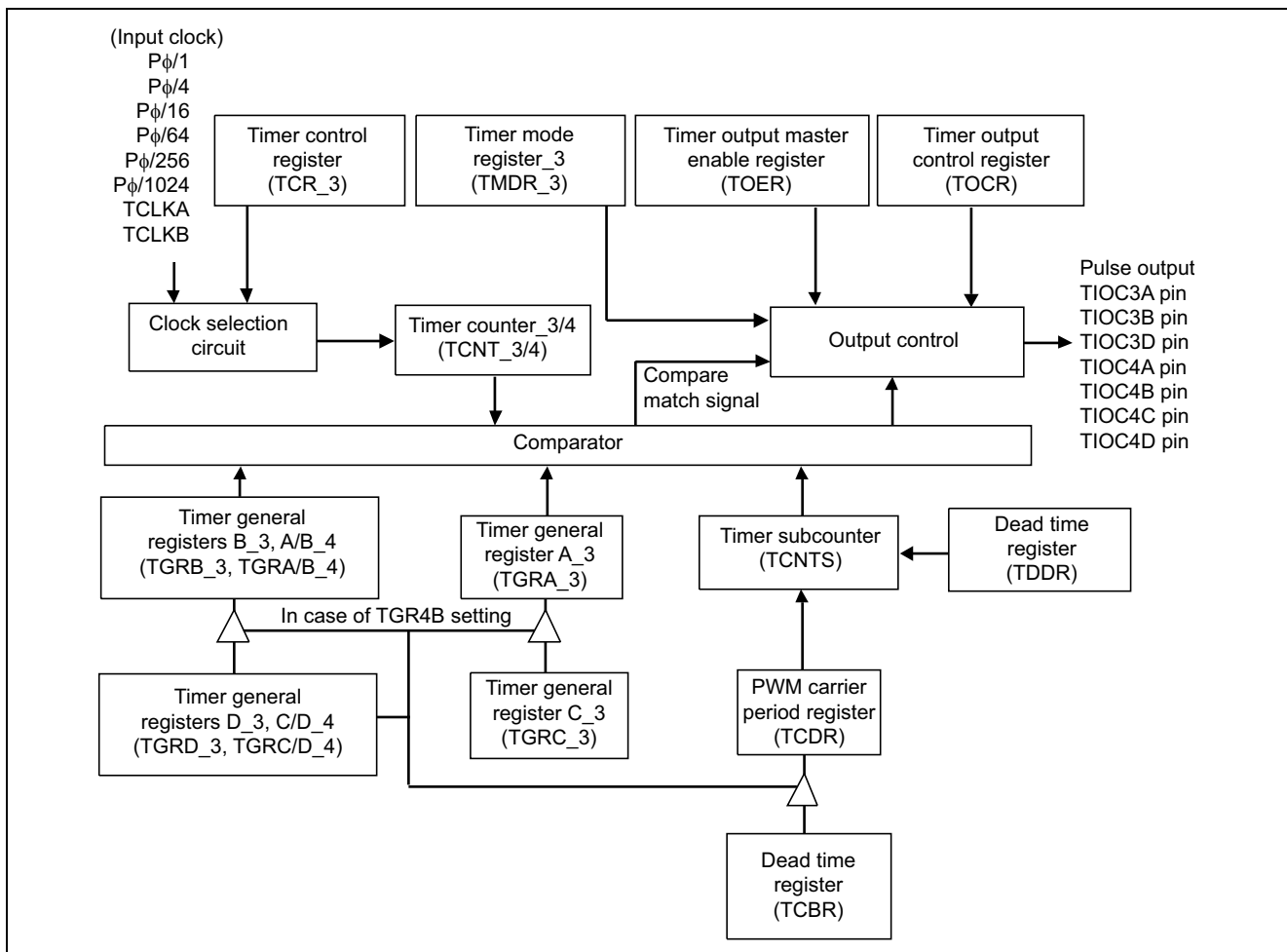


Figure 2 Block Diagram of MTU/ch3, ch4

Table 1 shows the function assignments used in this task. PWM pulses are output by assigning MTU functions as shown in the table.

Table 1 Function Assignments

| Pin or Register Name | Function | Function Assignment |
|-----------------------------|-----------------|---|
| TIOC3A | Pin | Toggle output synchronized with PWM period |
| TIOC3C | Pin | PWM output 1 |
| TIOC3D | Pin | Negative-phase waveform in non-overlapping relationship with PWM output 1 |
| TIOC4A | Pin | PWM output 2 |
| TIOC4B | Pin | PWM output 3 |
| TIOC4C | Pin | Negative-phase waveform in non-overlapping relationship with PWM output 2 |
| TIOC4D | Pin | Negative-phase waveform in non-overlapping relationship with PWM output 3 |
| TOCR | Register | Enabling/disabling of toggle output synchronized with PWM period |
| TOER | Register | Complementary PWM output pin signal output enabling/disabling |
| TCR_3 | Register | Selection of ch3 timer counter clearing source and input clock |
| TMDR_3 | Register | Ch3, ch4 set to complementary PWM mode operation |
| TGRA_3 | Register | Used to set value of 1/2 PWM period + dead time |
| TGRC_3 | Register | TGRA_3 buffer register |
| TGRB_3 | Registers | Output pulse transition point setting (compare register) |
| TGRA_4 | | |
| TGRB_4 | | |
| TGRD_3 | Register | TGRB_3 buffer register |
| TGRC_4 | Register | TGRA_4 buffer register |
| TGRD_4 | Register | TGRB_4 buffer register |
| TDDR | Register | Dead time setting |
| TCDR | Register | Setting of 1/2 period |
| TCBR | Register | TCDR buffer register |

3. Operation

Figure 3 illustrates the principles of operation. Complementary PWM waveform output is performed by SH7046 hardware and software processing.

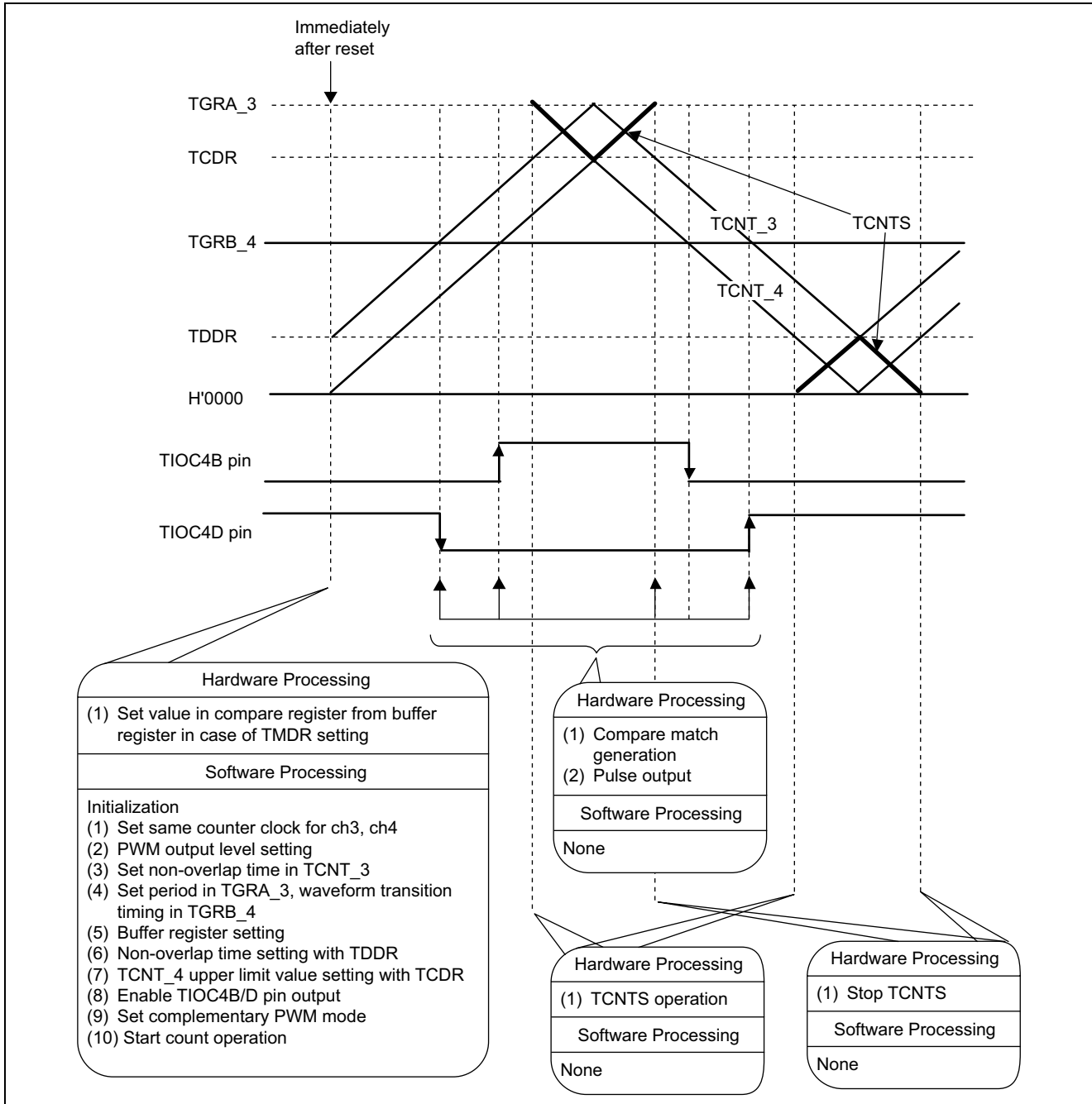


Figure 3 Principles of Operation of Complementary PWM Single-Phase Waveform Output

Figure 4 shows the PWM waveform output method. When complementary PWM mode is set, the following rules apply to data transfer and compare operations.

- Data Transfer
 - In period T_a , data written to a buffer register (at the point at which data is set in TGRD_4) is transferred to a temporary register.
 - In period T_{b1} , when the transfer mode is set to transfer at the peak, data is not transferred from a buffer register to a temporary register. In period T_{b2} , the operation is the same as in period T_a . Similarly, when a trough setting is made, data is not transferred in period T_{b2} .
 - Data transfer to a buffer register can be performed arbitrarily.
 - When period T_b ends, a value transferred to a temporary register is transferred to a compare match register. This transfer timing can be selected with timer mode register (TMDR) bits MD3 to MD0.
 - Compare Match
 - In period T_b , two registers—the temporary register and compare register—and three counters—TCNT_3/4 and TCNTS—are compared, and the PWM waveform is controlled.
 - In area (a), pre-change data and compare matches (3) and (4) have priority.
 - In area (b), post-change data and compare matches (1) and (2) have priority.
- Generation of a compare match whereby the output waveform goes to the active level (compare match (1) or (3)) occurs only after generation of a compare match whereby the respective output waveform goes to the positive level (compare match (4) or (2)).

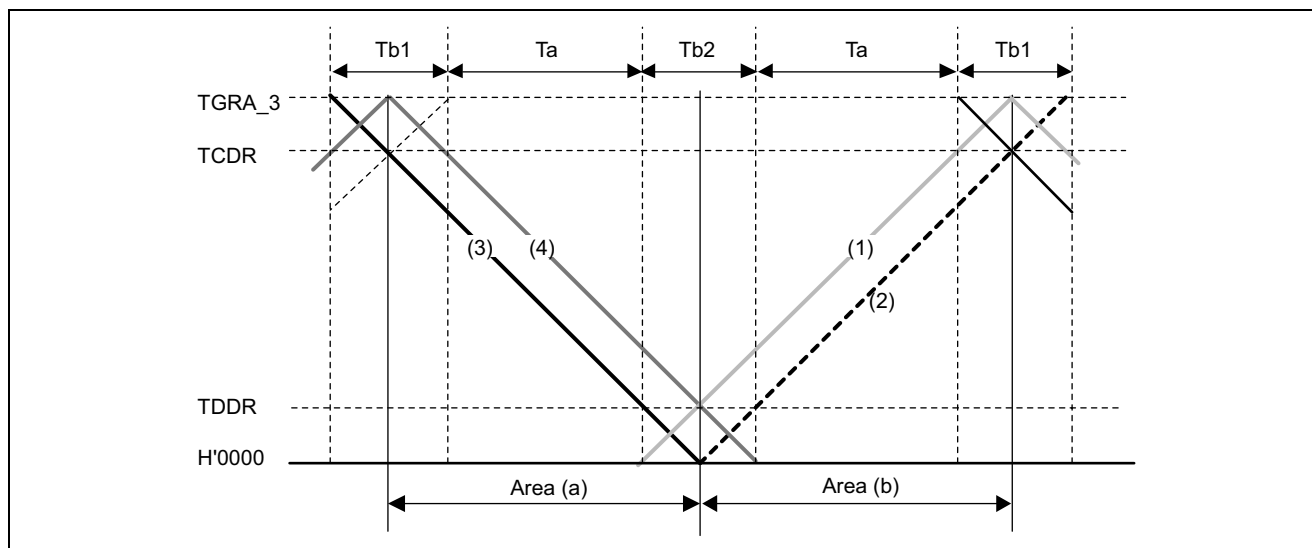


Figure 4 Principles of Operation of PWM Waveform Output Method

Figure 5 illustrates the principles of operation. Complementary PWM waveform output is performed by SH7046 hardware and software processing. The transfer mode selected in this sample task is the mode in which data is changed at a peak.

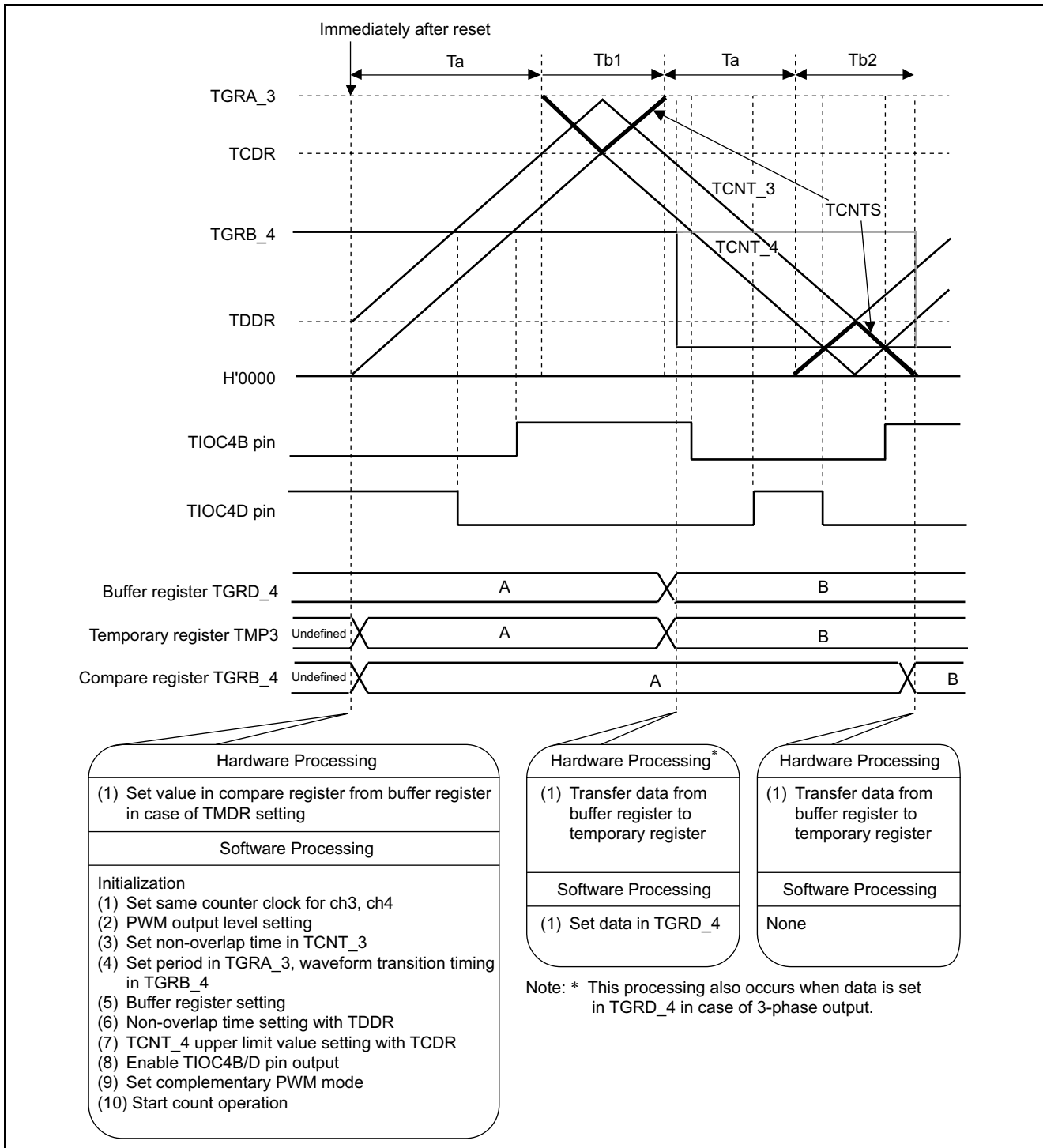


Figure 5 Principles of Operation of Complementary PWM Single-Phase Waveform Output

Figure 6 illustrates the principles of operation. Three-phase PWM output is performed from the ch3 and ch4 PWM output pins (TIOC3B/D, TIOC4A/B/C/D) by SH7046 hardware and software processing as shown in the figure.

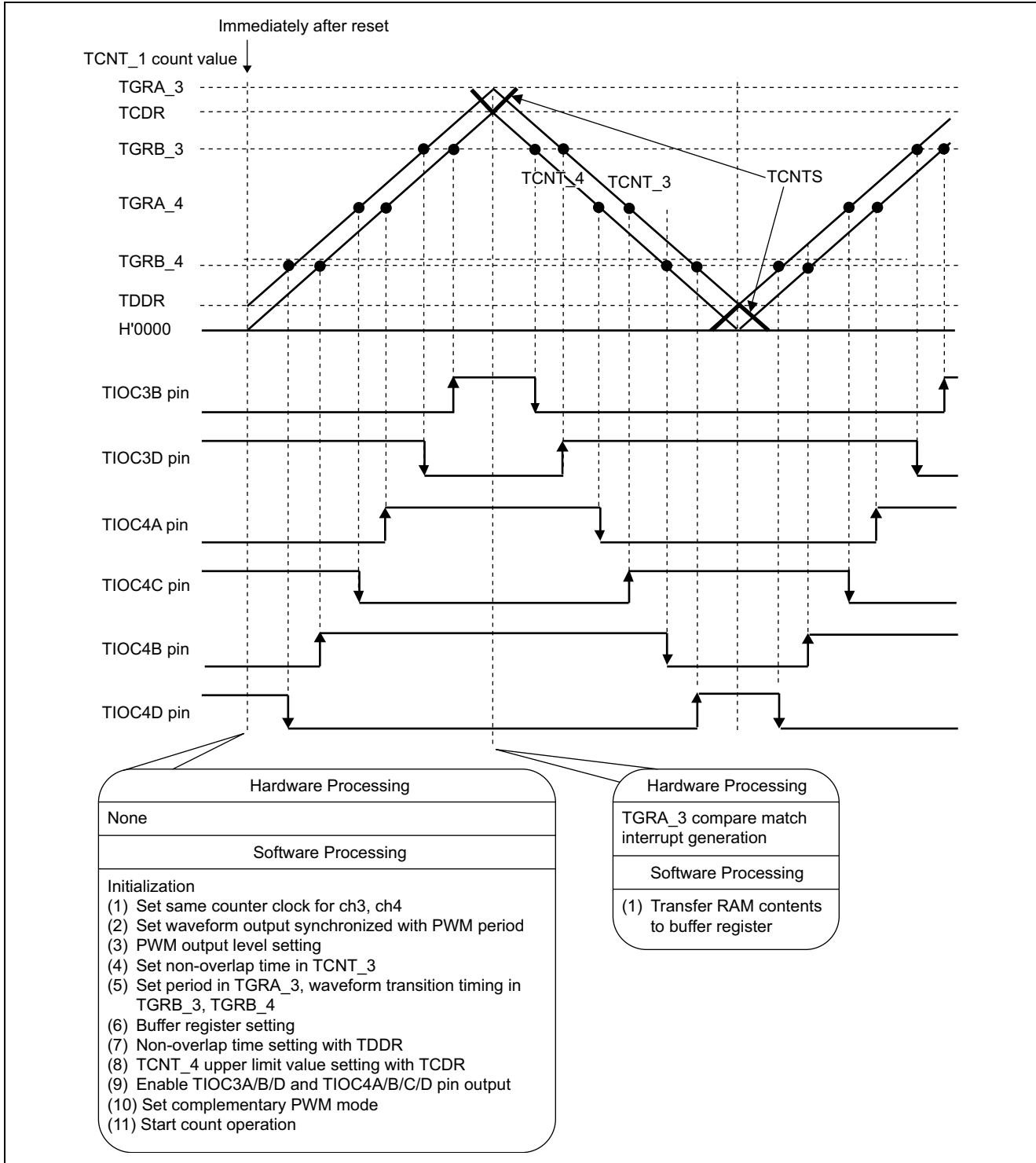


Figure 6 Principles of Operation of PWM Waveforms

Figure 7 illustrates the principles of operation. Toggle output synchronized with the PWM period is performed by SH7046 hardware and software processing.

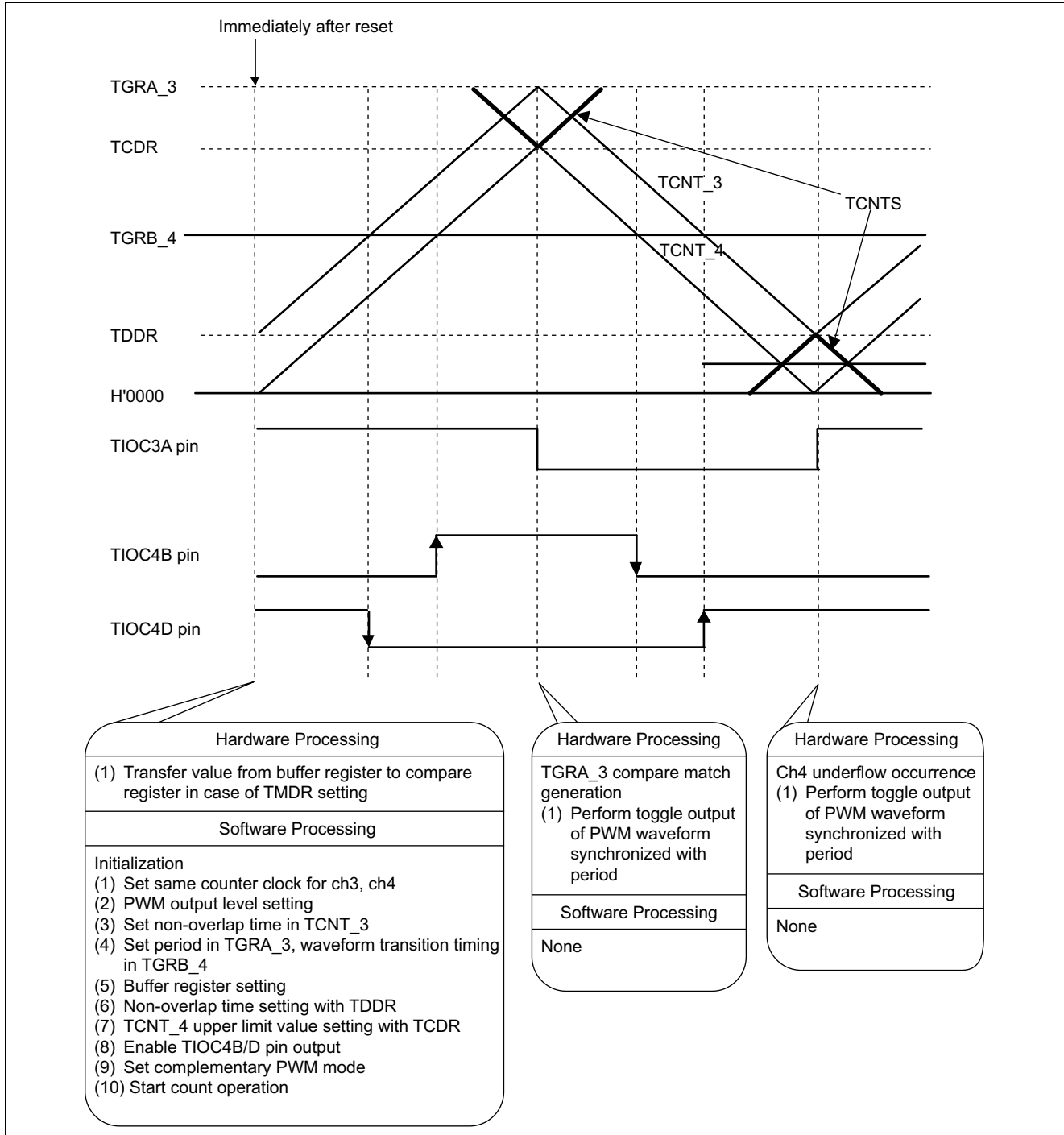


Figure 7 Principles of Operation of Toggle Waveform Output Synchronized with PWM Period

4. Software

(1) Modules

| Module Name | Label | Function Assignment |
|--------------|---------|--|
| Main routine | comple | Complementary PWM output setting |
| Data setting | setdata | Sets waveform transition timing in buffer register |

(2) Arguments

| Label or Register Name | Function | Data Length | Module | Input/Output |
|------------------------|---|-------------|------------------------------|--------------|
| pul_cyc1 | Used to set pulse 1/2 period + dead time value Pulse period is calculated using following equation: Pulse period (ns) = timer value × φ period (50.0 ns at 20.0 MHz operation) | 1 word | Main routine | Input |
| pul_duty3d | Used to set TIOC pin output waveform transition timing | | | |
| pul_duty4c | | | | |
| pul_duty4d | | | | |
| c_cyc | PWM carrier period register value setting | | | |
| dead_time | Non-overlap time setting | | Main routine Data setting | |

(3) Internal Registers Used

| Register Name | Function | Address | Set Value |
|----------------|--|------------|------------|
| P_STBY.MSTCR2 | MTU module standby mode clearing, and setting of MTU to operational status | H'FFFF861E | H'd2fd |
| P_PORTE.PECRH | Used to set multiplex pins as MTU timer output pins | H'FFFF83BC | H'0000 |
| P_PORTE.PECRL1 | TIOC3A, TIOC3B, TIOC3D, TIOC4A, TIOC4B, | H'FFFF83B8 | H'5545 |
| P_PORTE.PECRL2 | TIOC4C, TIOC4D | H'FFFF83BA | H'0000 |
| P_PORTE.PEIORH | | H'FFFF83B6 | H'0000 |
| P_PORTE.PEIORL | | H'FFFF83B4 | H'fb00 |
| P_MTU34.TCR_3 | Selects timer counter clearing source and input clock | H'FFFF8200 | H'00 |
| P_MTU34.TCR_4 | Selects timer counter clearing source and input clock | H'FFFF8201 | H'00 |
| P_MTU34.TIER_3 | Enables TGR3A interrupt | H'FFFF8208 | H'01 |
| P_MTU34.TGRA_3 | Used to set 1/2 carrier period + dead time register value | H'FFFF8218 | pul_cyc1 |
| P_MTU34.TGRC_3 | Used to set 1/2 carrier period + dead time register value | H'FFFF8224 | pul_cyc1 |
| P_MTU34.TGRB_3 | Setting of PWM duty value of waveform output from TIOC3B, TIOC3D | H'FFFF821A | pul_duty3d |
| P_MTU34.TGRD_3 | Setting of PWM duty value of waveform output from TIOC3B, TIOC3D | H'FFFF8226 | pul_duty3d |
| P_MTU34.TGRA_4 | Setting of PWM duty value of waveform output from TIOC4A, TIOC4C | H'FFFF821C | pul_duty4c |
| P_MTU34.TGRC_4 | Setting of PWM duty value of waveform output from TIOC4A, TIOC4C | H'FFFF821C | pul_duty4c |

| Register Name | Function | Address | Set Value |
|----------------|--|------------|------------|
| P_MTU34.TGRB_4 | Setting of PWM duty value of waveform output from TIOC4B, TIOC4D | H'FFFF821E | pul_duty4d |
| P_MTU34.TGRD_4 | Setting of PWM duty value of waveform output from TIOC4B, TIOC4D | H'FFFF821E | pul_duty4d |
| P_MTU34.TCNT_3 | Dead time value setting | H'FFFF8210 | dead_time |
| P_MTU34.TDDR | Dead time value setting | H'FFFF8216 | dead_time |
| P_MTU34.TCDR | Setting of upper limit value of timer counter TCNT_4 (1/2 carrier period) | H'FFFF8214 | c_cyc |
| P_MTU34.TCBR | Setting of upper limit value of timer counter TCNT_4 (1/2 carrier period) | H'FFFF8222 | c_cyc |
| P_MTU34.TOCR | Enabling of toggle output synchronized with PWM period, and positive-phase/negative phase output level setting | H'FFFF820B | H'43 |
| P_MTU34.TOER | Complementary PWM output enabling setting | H'FFFF820A | H'ff |
| P_MTU34.TMDR_3 | Complementary PWM mode setting | H'FFFF8202 | H'ff |
| P_INTC.IPRE | Sets 15 as MTU channel 3 interrupt priority level | H'FFFF8350 | H'00f0 |

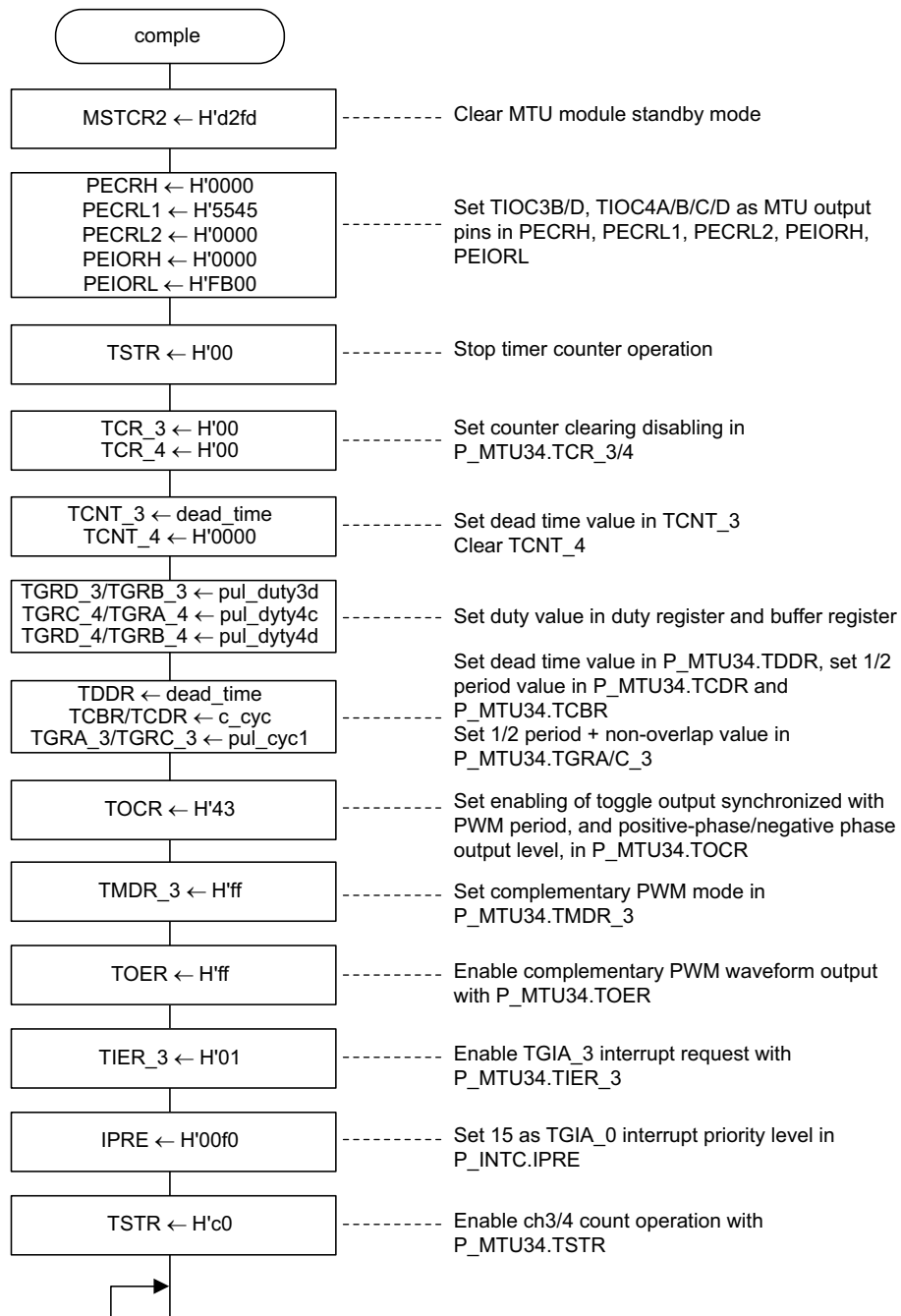
(4) RAM Used

This sample application does not use any RAM apart from the arguments.

Note: SH7046 header file names are used for register label names.

5. Flowcharts

(1) Main routine



6. Program Listing

```

/*-----*/
/*                                     INCLUDE FILE                                     */
/*-----*/
#include <machine.h>
#include "iodefine_7046.h"
/*-----*/
/*                                     PROTOTYPE                                     */
/*-----*/
extern void comple(void);
#pragma interrupt(setdata)
/*-----*/
/*                                     RAM ALLOCATION                                 */
/*-----*/
#define pul_cycl1          (*(unsigned short *)0xffffd000)
#define pul_duty3d        (*(unsigned short *)0xffffd002)
#define pul_duty4c        (*(unsigned short *)0xffffd004)
#define pul_duty4d        (*(unsigned short *)0xffffd006)
#define c_cyc             (*(unsigned short *)0xffffd008)
#define dead_time        (*(unsigned short *)0xffffd00a)
/*-----*/
/*                                     MAIN PROGRAM                                 */
/*-----*/
void comple(void)
{
    P_STBY.MSTCR2 = 0xd2fd;          /* MTU module stop mode clear */
    P_PORTE.PECRH.WORD = 0x0000;     /* TIOC3A/B/D,TIOC4A/B/C/D output */
    P_PORTE.PECRL1.WORD = 0x5545;
    P_PORTE.PECRL2.WORD = 0x0000;
    P_PORTE.PEIORH.WORD = 0x0000;
    P_PORTE.PEIORL.WORD = 0xFB00;
    P_MTU34.TSTR.BYTE = 0x00;
    P_MTU34.TCR_3.BYTE = 0x00;      /* not clear */
    P_MTU34.TCR_4.BYTE = 0x00;      /* not clear */
    P_MTU34.TCNT_3 = dead_time;     /* initial data */
    P_MTU34.TCNT_4 = 0x0000;
    P_MTU34.TGRD_3 = pul_duty3d;     /* TGRD_3 buffer register */
    P_MTU34.TGRB_3 = pul_duty3d;     /* PWM output1 compare register */
    P_MTU34.TGRC_4 = pul_duty4c;     /* TGRA_4 buffer register */
    P_MTU34.TGRA_4 = pul_duty4c;     /* PWM output2 compare register */
    P_MTU34.TGRD_4 = pul_duty4d;     /* TGRB_4 buffer register */
    P_MTU34.TGRB_4 = pul_duty4d;     /* PWM output3 compare register */
    P_MTU34.TDDR = dead_time;        /* dead time set */
    P_MTU34.TCDR = c_cyc;            /* 1/2 carrer period */
    P_MTU34.TCBR = c_cyc;            /* TCDR buffer register */
    P_MTU34.TGRA_3 = pul_cycl1;      /* 1/2 carrer period + dead time */
    P_MTU34.TGRC_3 = pul_cycl1;      /* TGRA_3 buffer register */
    P_MTU34.TOCR.BYTE = 0x43;        /* timer output control register */
    P_MTU34.TMDR_3.BYTE = 0xff;      /* complementary-pwm mode */
    P_MTU34.TOER.BYTE = 0xff;        /* timer output enable register */
    P_MTU34.TIER_3.BYTE = 0x01;      /* timer interrupt enable register */
    P_INTC.IPRE.WORD = 0x00f0;       /* set interrput level = 15 */
    set_imask(0x0);                  /* set imask level = 0 */
}

```

```
P_MTU34.TSTR.BYTE = 0xc0;    /* timer start */
while(1); /* loop */
}
void setdata()
{
    P_MTU34.TSR_3.BYTE &= 0xfe;    /* interrupt flag clear */
    P_MTU34.TCBR = c_cyc;
    P_MTU34.TGRC_3 = pul_cycl;
    P_MTU34.TGRD_3 = pul_duty3d;
    P_MTU34.TGRC_4 = pul_duty4c;
    P_MTU34.TGRD_4 = pul_duty4d;
}
```

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