

SH7262/SH7264 Group

Serial Communication Interface with FIFO, Configuring

REJ06B0978-0100 Rev.1.00 Apr. 28, 2010

the Serial Communication in Clock Synchronous Mode (Full-duplex)

Summary

This application note describes the serial communication in clock synchronous mode provided by the SH7264 Serial Communication Interface with FIFO (SCIF).

Target Device

SH7262/7264 MCU (In this document, SH7262/SH7264 are described as SH7264.

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1. Introduction

1.1 Specifications

- Initializes the SH7264 Serial Communication Interface with FIFO (SCIF) channel 1 as the transmitter and received in clock synchronous mode
- Executes full-duplex communication on SCIF channel 1 by transmit and receive interrupts. The transmit interrupt processing is activated by the transmit-FIFO-data-empty interrupt, and the receive interrupt processing is activated by the receive-FIFO-data-full interrupt.

1.2 Modules Used

- Serial Communication Interface with FIFO (SCIF)
- Interrupt controller

1.3 Applicable Conditions

MCU	SH7262/SH7264
	Internal clock: 144 MHz
Operating Frequencies	Bus clock: 72 MHz
	Peripheral clock: 36 MHz
Integrated Development	Renesas Technology Corp.
Environment	High-performance Embedded Workshop Ver.4.07.00
C Compiler	Renesas Technology SuperH RISC engine Family
Complier	C/C++ Compiler Package Ver.9.03 Release 00
	Default setting in the High-performance Embedded Workshop
Compiler Options	(-cpu=sh2afpu -fpu=single -object="\$(CONFIGDIR)\\$(FILELEAF).obj"
	-debug-gbr=auto -chgincpath -errorpath -global_volatile=0 -opt_range=all
	-infinite_loop=0 -del_vacant_loop=0 -struct_alloc=1 -nologo)

1.4 Related Application Notes

- SH7262/SH7264 Group Example of Initialization
- SH7262/SH7264 Group Serial Communication Interface with FIFO, Configuration to Transmit Strings in Asynchronous Mode
- SH7262/SH7264 Group Serial Communication Interface with FIFO, Configuration to Receive Strings in Asynchronous Mode

1.5 About Active-low Pins (Signals)

The symbol "#" suffixed to the pin (or signal) names indicates that the pins (or signals) are active-low.



2. Applications

This application uses the Serial Communication Interface with FIFO (SCIF).

2.1 SCIF Overview

In clock synchronous mode, the SCIF transmits and receives data sync with the clock pulse. Either an internal clock or external clock from the SCK pin can be specified as the clock source. When specifying the internal clock, the SCIF outputs synchronous clock from the SCK pin. When specifying the external clock, the external device inputs the synchronous clock into the SCK pin. The communication format is specified as 8-bit data fixed.

Table 1 lists the overview of the clock synchronous mode. Figure 1 shows the SCIF block diagram.

ltem	Description				
Number of channels	8 (SCIF0 to SCIF7)				
Clock source	Internal clock: Pφ, Pφ/4, Pφ16, Pφ64 Pφ: internal peripheral clock				
	External clock: SCK0 to SCK3 pins input clock				
Data format	Transfer data length: 8-bit fixed				
	Order of transfer: LSB first fixed				
Baud rate	When specifying the internal clock: 549 bps to 9 Mbps (P ϕ is at 36 MHz)				
	When specifying the external clock: Up to 3 Mbps (Pφ is at 36 MHz, external clock is at 9 MHz)				
	Note: Make sure to satisfy the electric characteristics of the SH7264 and the				
	connected external device.				
Error detection	Overrun error				
Interrupt request	Transmit-FIFO-data-empty interrupt (TXI) by the transmit FIFO data empty (TDFE)				
	Break interrupt (BRI) by the break (BRK) or overrun error (ORER)				
	Receive-FIFO-data-full (RXI) by the Receive FIFO data full (RDF) or data ready (DR)				
	Receive-error interrupt (ERI) by the receive error (ER)				
Others	 Outputs the synchronous clock from the SCK pin when specifying the internal clock 				
	 Supplying clock to unused channels can be stopped to reduce power consumption 				
	The number of valid data stored in the Transmit and Receive FIFO data registers, and the number of receive errors stored in the Receive FIFO data register can be detected				

Table 1 SCIF (Clock Synchronous Mode) Overview

Note: For more information about the SCIF, refer to the Serial Communication Interface with FIFO chapter in the SH7262 Group, SH7264 Group Hardware Manual.



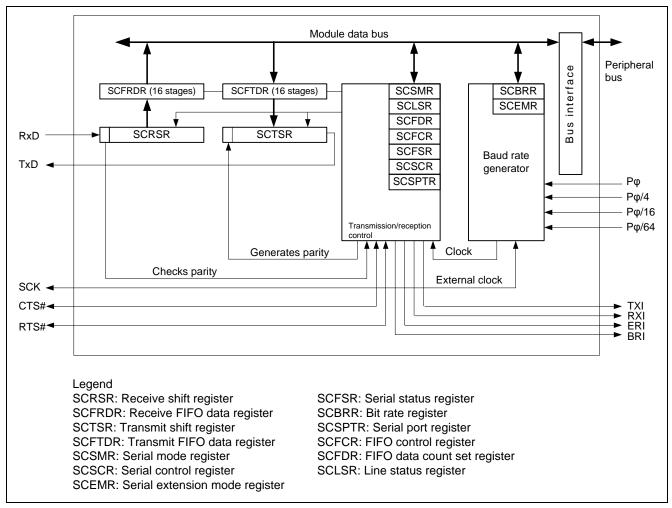


Figure 1 SCIF Block Diagram



2.2 Configuration Procedure

This section describes how to configure the SH7264 SCIF in clock synchronous mode. Figure 2 and Figure 3 show flow charts of configuring the transmission/reception in clock synchronous mode. Figure 4 shows the flow chart of the transmit interrupt processing in clock synchronous mode. Figure 5 shows the flow chart of the receive interrupt processing in clock synchronous mode. Figure 6 shows the flow chart of the overrun error interrupt processing.

For details on register settings, refer to the Serial Communication Interface with FIFO chapter in the SH7262 Group, SH7264 Group Hardware Manual.

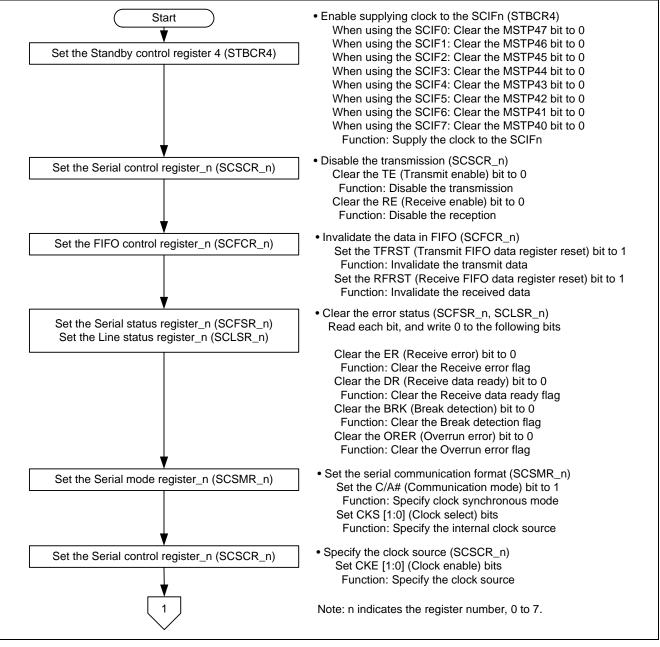


Figure 2 Flow Chart for Configuring the Transmission/Reception in Clock Synchronous Mode (1/2)



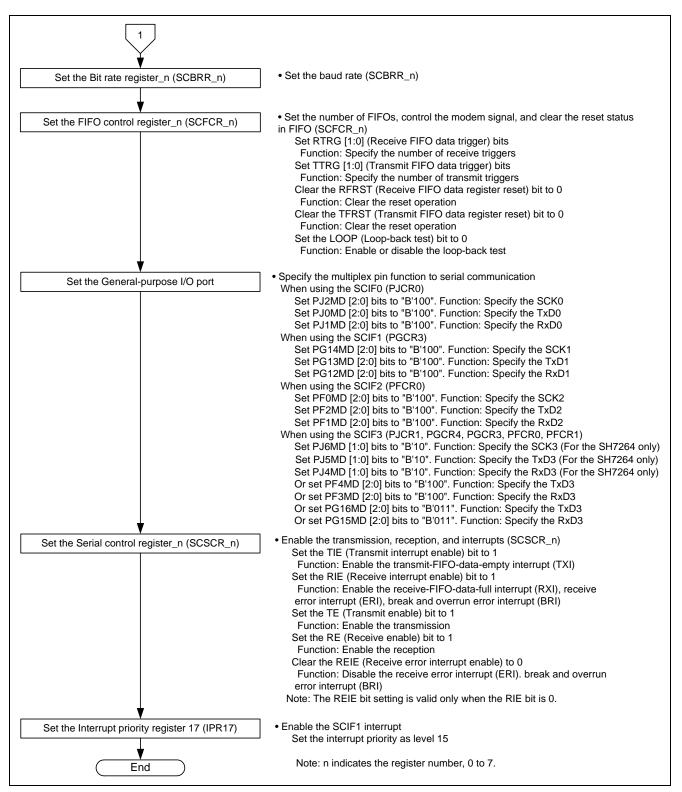


Figure 3 Flow Chart for Configuring the Transmission/Reception in Clock Synchronous Mode (2/2)



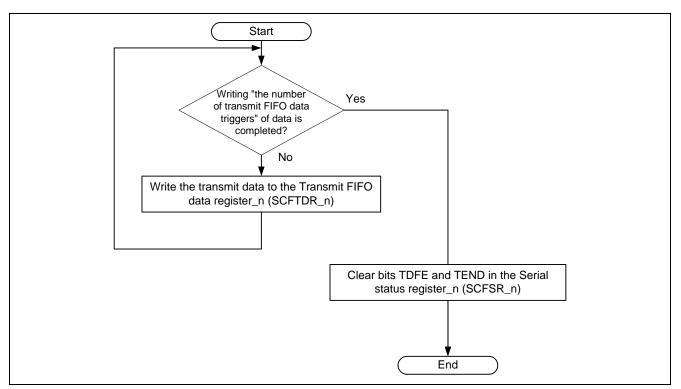


Figure 4 Flow Chart of the Transmit Interrupt Processing (TXI) in Clock Synchronous Mode

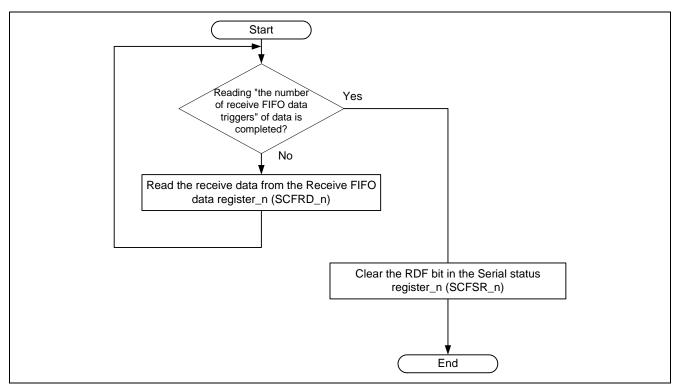


Figure 5 Flow Chart of the Receive Interrupt Processing (RXI) in Clock Synchronous Mode



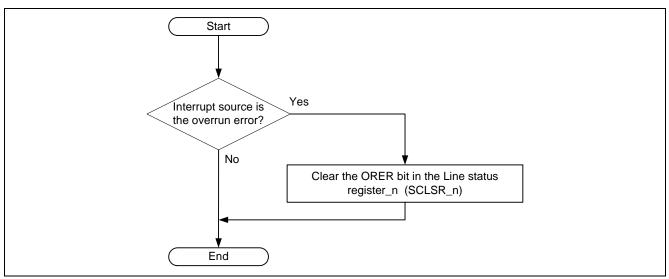


Figure 6 Flow Chart of the Overrun Error Interrupt Processing (BRI)



2.3 Sample Program Operation

This sample program uses the SCIF channel 1 as the transmitter and receiver in clock synchronous mode. It uses the SCIF1 loop-back test function, connects the TxD1 (serial transmit pin) and RxD1 (serial receive pin) internally, and executes the full-duplex serial communication. Set the LOOP (loop-back test) bit in the FIFO control register (SCFCR) to 1 to enable the loop-back test function.

Table 2 lists the transmission settings for the sample program. Figure 7 shows the operation timing of the sample program.

Communication Format	Setting
Communication mode	Clock synchronous mode
Number of channel to use	Channel 1
Interrupt	Transmit-FIFO-data-empty
	Receive-FIFO-data-full
Baud rate	100 kbps
Data length	8-bit
Bit order	LSB first
Synchronous clock	SCIF channel 1 external clock output
Number of FIFO data triggers	Receive: 8, transmit: 8
Loop-back test function	Enabled (TxD1 pin and RxD1 pin are connected internally)

Table 2 Sample Program Transmission (Reception) Settings



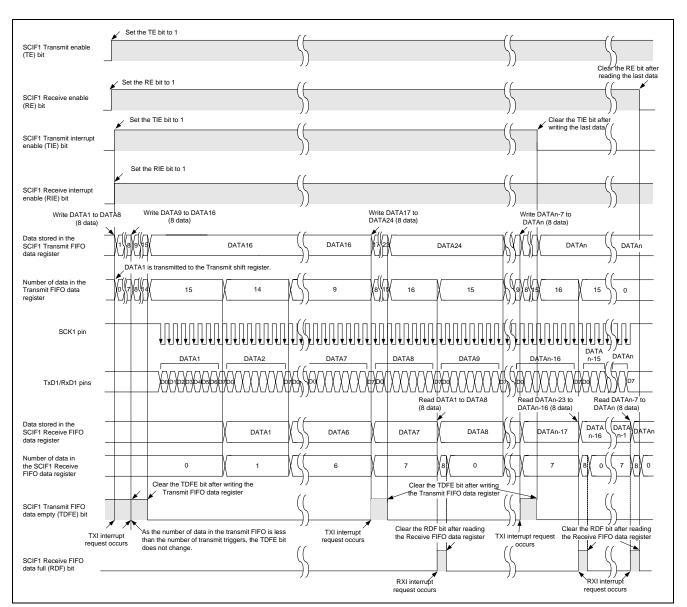


Figure 7 Sample Program Operation Timing



2.4 Sample Program Procedure

The sample program uses the SCIF channel 1 as the transmitter and receiver in clock synchronous mode to execute the full-duplex communication by the transmit and receive interrupts. The transmit interrupt processing specifies the number of transmit FIFO data triggers as 8 to write 8-byte transmit data in the Transmit FIFO data register (SCFTDR_1) by an interrupt processing. The receive interrupt processing specifies the number of receive FIFO data triggers as 8 to read 8-byte received data from the Receive FIFO data register (SCFRDR_1) by an interrupt processing.

Table 3 lists the register settings in the sample program. Figure 8 to Figure 10 show flow charts of the sample program.

Register Name	Address	Setting	Description	
Standby control register 4 (STBCR4)	H'FFFE 040C	H'BF	MSTP46 = "0": SCIF1 is operating (Supplies the clock)	
Port G control register 3 (PGCR3)	H'FFFE 38C8	H'0444	 PG14MD [2:0] = "B'100": SCK1 output (SCIF1) PG13MD [2:0] = "B'100": TxD1 output (SCIF1) PG12MD [2:0] = "B'100": RxD1 output (SCIF1) 	
Serial control register_1 (SCSCR_1)	H'FFFE 8808	H'0000	 TE = "0": Disable the transmission RE = "0": Disable the reception CKE [1:0] "B'00": Internal clock/SCK pin outputs the synchronous clock 	
		H'00F0	 TIE = "1": Enable the transmit interrupt RIE = "1": Enable the receive interrupt, receive error interrupt, break and overrun error interrupt TE = "1": Enable the transmission RE = "1": Enable the reception REIE = "0": Disable the interrupt error interrupt, break and overrun error interrupt 	
FIFO control register_1 (SCFCR_1)	H'FFFE 8818	H'0006 H'0081	 TFRST = "1": Enable to reset the transmit FIFO RFRST = "1": Enable to reset the receive FIFO RTRG [1:0] = B'10: Number of data in the receive FIFO is 8 TTRG [1:0] = B'00: Number of data in the transmit FIFO is 8 TFRST = "0": Disable to reset the transmit FIFO RFRST = "0": Disable to reset the receive FIFO LOOP = "1": Enable the loop-back test 	
Serial status register_1 (SCFSR_1)	H'FFFE 8810	H'FF6E	 ER = "0": Receive error BRK = "0": Break detected DR = "0": Receive data ready Read the bit before clearing to 0. 	
Line status register_1 (SCLSR_1)	H'FFFE 8824	H'0000	• ORER = "0": Overrun error Read the bit before clearing to 0.	
Serial mode register_1 (SCSMR_1)	H'FFFE 8800	H'0080	 C/A# = "1": Clock synchronous mode CKS [1:0] = "0": Peripheral clock 	
Bit rate register_1 (SCBRR_1)	H'FFFE 8804	H'59	Set the baud rate as 100 kbps	

Table 3 Register Settings



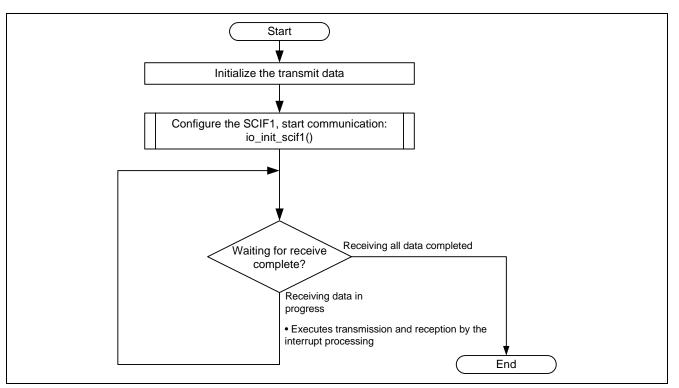


Figure 8 Sample Program Main Flow Chart



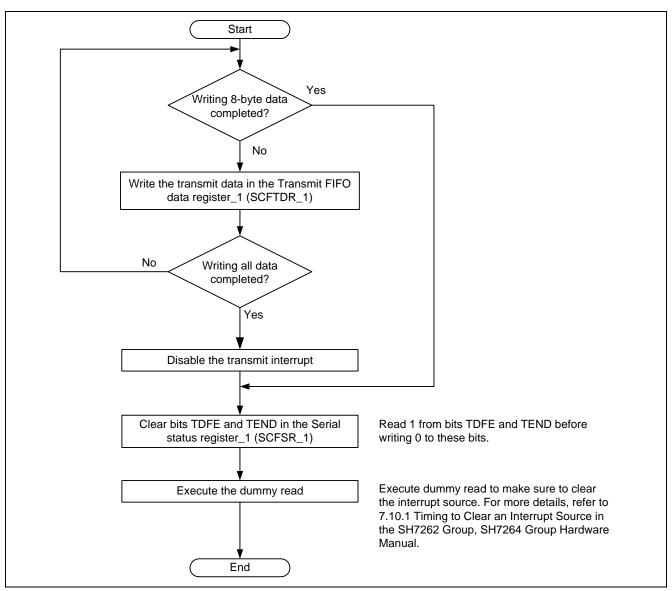


Figure 9 Sample Program Transmit Processing Flow Chart



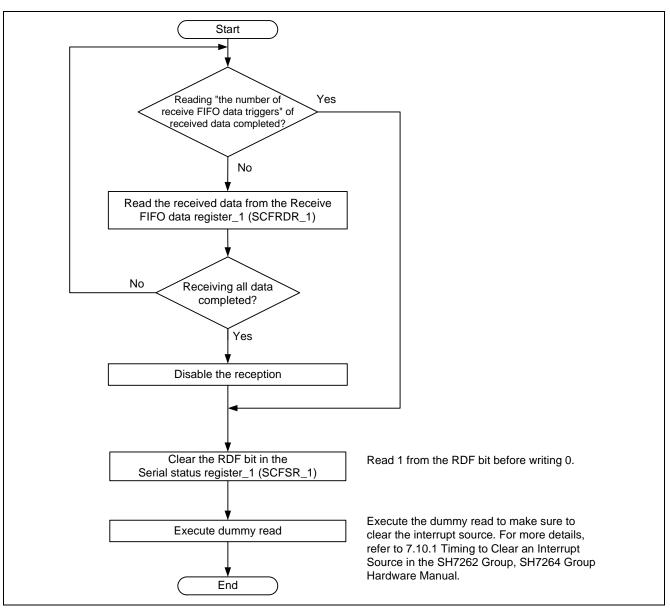


Figure 10 Sample Program Receive Processing Flow Chart



3. Sample Program Listing

3.1 Supplement to the Sample Program

As the capacity of the SH7264 large-capacity internal RAM varies as 1 MB or 640 KB, depending on the MCU type, the section alignment and register setting must be partly altered. To support both MCU types, this application note provides two types of sample programs (workspaces) for 1-MB RAM and 640-KB RAM.

As the MCU with 640-KB RAM must be write-enabled before writing data in the data-retention RAM, the System control register 5 (SYSCR5) is set to write-enable the RAM in the sample program for 640-KB RAM.

Review your product and use the appropriate workspace.



3.2 Sample Program Listing "main.c" (1/8)

```
1
       2
         DISCLAIMER
       *
3
4
          This software is supplied by Renesas Electronics Corp. and is only
5
       *
          intended for use with Renesas products. No other uses are authorized.
6
7
          This software is owned by Renesas Electronics Corp. and is protected under
8
          all applicable laws, including copyright laws.
9
10
       *
          THIS SOFTWARE IS PROVIDED "AS IS" AND RENESAS MAKES NO WARRANTIES
11
       *
          REGARDING THIS SOFTWARE, WHETHER EXPRESS, IMPLIED OR STATUTORY,
12
          INCLUDING BUT NOT LIMITED TO WARRANTIES OF MERCHANTABILITY, FITNESS FOR A
13
         PARTICULAR PURPOSE AND NON-INFRINGEMENT. ALL SUCH WARRANTIES ARE EXPRESSLY
14
         DISCLAIMED
15
16
         TO THE MAXIMUM EXTENT PERMITTED NOT PROHIBITED BY LAW, NEITHER RENESAS
17
          ELECTRONICS CORP. NOR ANY OF ITS AFFILIATED COMPANIES SHALL BE LIABLE
18
          FOR ANY DIRECT, INDIRECT, SPECIAL, INCIDENTAL OR CONSEQUENTIAL DAMAGES
19
          FOR ANY REASON RELATED TO THIS SOFTWARE, EVEN IF RENESAS OR ITS
20
          AFFILIATES HAVE BEEN ADVISED OF THE POSSIBILITY OF SUCH DAMAGES.
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25
          conditions found by accessing the following link:
26
          http://www.renesas.com/disclaimer
27
       28
       * (C) 2010 Renesas Electronics Corporation. All rights reserved.
29
       30
         System Name : SH7264 Sample Program
31
         File Name : main.c
32
          Abstract
                    : Serial Communication Interface with FIFO (SCIF), transmission and
33
                    : reception in clock synchronous mode sample program
34
       *
         Version : 1.00.00
35
       *
                   : SH7262/SH7264
         Device
36
       *
          Tool-Chain : High-performance Embedded Workshop (Ver.4.07.00).
37
                    : C/C++ compiler package for the SuperH RISC engine family
38
       *
                                            (Ver.9.03 Release00).
39
       *
         OS
                    : None
40
          H/W Platform: M3A-HS64G50(CPU board)
41
          Description :
42
       *****
43
         History : Jan.29,2010 ver.1.00.00
44
       45
       #include <machine.h>
46
       #include "iodefine.h" /* SH7264 iodefine */
47
```



3.3 Sample Program Listing "main.c" (2/8)

```
48
      /* ==== Prototype declaration ==== */
49
      void main(void);
50
     void io_init_scif1(int);
     void io_interrupt_scif1_bri(void);
51
52
     void io_interrupt_scif1_rxi(void);
53
     void io_interrupt_scif1_txi(void);
54
     /* ==== Type definition ==== */
55
56
      /* SCIF baud rate setting */
57
     typedef struct {
58
      unsigned char scbrr;
59
      unsigned short scsmr;
60
     } SH7264_BAUD_SET;
61
    /* ---- Baud rate specified value ---- */
62
63
     enum{
64
      CBR_500,
65
       CBR_1K,
66
      CBR_2_5K,
67
      CBR_5K,
68
      CBR_10K,
69
      CBR_25K,
70
       CBR_50K,
71
       CBR_100K,
72
       CBR_250K,
73
      CBR_500K,
74
      CBR_1M
75
   };
76
     /* ---- Number of data to transfer ---- */
77
      #define DATA_NUM 0x100u /* Set the value in multiples of the receive triggers */
78
      /* ==== Variable definition ==== */
79
     /* ---- Register setting table (P clock = 36 MHz) ---- */
80
81
     static SH7264_BAUD_SET scif_baud[] = {
82
      {255,3}, /*
                           500 Hz */
       {140, 3}, /* 1,000 Hz */
83
       {224, 2}, /* 2,500 Hz */
{112, 2}, /* 5,000 Hz */
{224, 1}, /* 10,000 Hz */
84
85
86
       { 89, 1}, /*
                         25,000 Hz */
87
       {179, 0}, /*
                         50,000 Hz */
88
       { 89, 0}, /* 100,000 Hz */
89
       { 35, 0}, /* 250,000 Hz */
90
        { 17, 0}, /* 500,000 Hz */
91
        { 8, 0}
                   /* 1,000,000 Hz */
92
```



3.4 Sample Program Listing "main.c" (3/8)

```
};
93
    unsigned int DataNum = DATA_NUM; /* Number of data to transmit */
94
                   /* Transmit counter */
/* Port'
95
    unsigned int SndCnt;
96
   unsigned int RcvCnt;
    unsigned char SndData[DATA_NUM]; /* Transmit data storage buffer */
97
98
    unsigned char RcvData[DATA_NUM]; /* Receive data storage buffer */
99
    100
    * ID
101
102
    * Outline
              : Sample program main (Clock synchronous serial I/O communication).
103
     *_____
               : "iodefine.h"
104
    * Include
105
    *_____
106
    * Declaration : void main(void);
    *_____
107
    * Description : Uses the SCIF1 transmit-FIFO-data-empty interrupt, and receive
108
109
    *
               : -FIFO-data-full interrupt to transmit or receive the test data.
110
     *_____
111
    * Argument
               : void
112
    *_____
113
     * Return Value : void
114
    *_____
    * Note
115
               :
    116
117
   void main(void)
118
   {
119
    int i;
120
    /* ==== Initializes the transmit data ==== */
121
    for( i = 0; i < DATA_NUM; i++ ){</pre>
122
123
     SndData[i] = (unsigned char)i;
124
     }
125
126
     /* ==== Initializes the SCIF1, and starts communication ==== */
127
     io_init_scifl(CBR_100K); /* Specifies the bit rate as 100 kbps */
128
     /* ==== Waits until the reception is completed ==== */
129
130
     while(RcvCnt < DATA_NUM){</pre>
      /* Transmits or receives data by the interrupt processing */
131
132
     }
133
134
    while (1) {
135
     /* Program end */
136
     }
137
    }
138
```



3.5 Sample Program Listing "main.c" (4/8)

```
139
140
     * ID :
141
     * Outline
                : Configure the SCIF1
142
     *_____
                                _____
143
     * Include
                : "iodefine.h"
     *_____
144
145
     * Declaration : void io_init_scif1(int bps);
     *_____
146
     * Description : Configures the SCIF1 in clock synchronous mode.
147
148
                 : Sets it in clock synchronous mode, and external clock output.
149
                 : Also, it enables the transmit/receive interrupts.
150
     *_____
151
     * Argument : int bps ; I : Bit rate specified value
152
     *_____
     * Return Value : void
153
154
     *_____
155
     * Note
                 : The above baud rate specified value is applicable when using
156
                 : the peripheral clock (operating frequency for the peripheral
157
                : module using the internal clock) is 36 MHz. Alter the baud rate
     *
158
                : setting when using other clocks.
     159
160
   void io_init_scif1(int bps)
161
    {
162
      /* ==== Wakes up the MCU from power-down mode ==== */
     /* ---- Sets the Standby control register 4 (STBCR4) ---- */
163
     CPG.STBCR4.BIT.MSTP46 = 0;
164
                            /* Starts to supplying clock to the SCIF1 */
165
166
     /* ==== Configures the SCIF1 ==== */
167
     /* ---- Sets the Serial control register (SCSCRi) ---- */
      SCIF1.SCSCR.WORD = 0x0000; /* SCIF1 stops transmission/reception */
168
169
170
      /* ---- Sets the FIFO control register (SCFCRi) ---- */
171
      SCIF1.SCFCR.WORD = 0x0006; /* Resets the receive/transmit FIF0 */
172
173
      /* ---- Sets the Serial status register (SCFSRi) ---- */
174
     SCIF1.SCFSR.WORD &= 0xff6eu; /* Clears bits ER, BRK, and DR */
175
176
      /* ---- Sets the Line status register (SCLSRi) ---- */
      SCIF1.SCLSR.BIT.ORER = 0; /* Clears the ORER bit */
177
178
      /* ---- Sets the Serial mode register (SCSMRi) ---- */
179
180
      SCIF1.SCSMR.WORD = scif_baud[bps].scsmr | 0x0080u ;
181
                           /* Communication mode, 1: Clock synchronous mode */
                           /* Clock select: Setting in table */
182
183
```



3.6 Sample Program Listing "main.c" (5/8)

```
/* ---- Sets the Serial control register (SCSCRi) ---- */
184
185
        SCIF1.SCSCR.BIT.CKE = 0x0; /* B'00: Outputs internal clock/synchronous clock */
186
       /* ---- Sets the Bit rate register (SCBRRi) ---- */
187
       SCIF1.SCBRR.BYTE = scif_baud[bps].scbrr;
188
189
190
       /* ---- Sets the FIFO control register (SCFCRi) ---- */
       SCIF1.SCFCR.WORD = 0x0081; /* RTS output active trigger: Default value */
191
                                  /* Number of receive FIFO data triggers, B'10: 8 */
192
193
                                  /* Number of transmit FIFO data triggers, B'00: 8 */
194
                                  /* Modem control enable: Disabled */
195
                                  /* Receive FIFO data register reset: Disabled */
196
                                  /* Transmit FIFO data register reset: Disabled */
197
                                  /* Loop-back test, 1: Enabled */
198
199
       /* ==== Sets the General-purpose I/O port ==== */
200
       /* Specifies the TxD1 pin */
       PORT.PGCR3.BIT.PG13MD = 4;
201
      PORT.PGCR3.BIT.PG12MD = 4;
                                   /* Specifies the RxD1 pin */
202
203
       /* ---- Enable transmission, reception, and interrupt ---- */
204
205
      SCIF1.SCSCR.WORD |= 0x00f0u;
206
207
       /* ---- Enable TXI1, RXI1 interrupts ---- */
208
       INTC.IPR17.BIT._SCIF1 = 15; /* Specifies as level 15 */
209
     }
210
```



3.7 Sample Program Listing "main.c" (6/8)

```
211
   * ID :
212
   * Outline : Interrupt processing by break signal or overrun error (BRI).
213
214
    *_____
215
    * Include
            : "iodefine.h"
216
    *_____
217
    * Declaration : void io_interrupt_scif1_bri(void);
    *_____
218
    * Description : Processes the overrun error which occurs in clock synchronous mode.
219
220
             : This sample program only clears the ORER bit.
221
    *_____
222
    * Argument
            : void
223
    *_____
224
    * Return Value : void
225
   *_____
   * Note
            :
226
   227
228
   void io_interrupt_scif1_bri(void)
229
  {
230
    volatile unsigned short dummy;
231
232
    /* ==== Checks the overrun error ==== */
    if(SCIF1.SCLSR.BIT.ORER == 1) {
233
234
235
    /* ---- Clears the interrupt source (clears the ORER bit) ---- */
236
    SCIF1.SCLSR.BIT.ORER = 0;
237
     dummy = SCIF1.SCLSR.WORD; /* Dummy read to make sure to clear the interrupt source */
238
   }
239
   }
```



3.8 Sample Program Listing "main.c" (7/8)

```
240
241
    * ID
                :
242
     * Outline
               : Receive-FIFO-data-full or data-ready interrupt (RXI)
243
     *_____
244
     * Include
               : "iodefine.h"
     *_____
245
     * Declaration : void io_interrupt_scif1_rxi(void);
246
247
     *_____
     * Description : Executes the SCIF1 RXI interrupt processing. The receive-FIF0
248
249
                : -data-full interrupt activates the processing in clock
250
                : synchronous mode. This sample program configures the number of
251
                : receive FIFO data triggers as 8, and reads data in units of 8.
252
               : Note that the data ready interrupt does not occur when
253
                : receiving data less than the number of receive FIFO data
254
               : triggers in clock synchronous mode.
     *_____
255
256
     * Argument
                : void
257
     *_____
258
     * Return Value : void
259
     *_____
260
     * Note
               :
    261
262
    void io_interrupt_scif1_rxi(void)
263
    {
264
    int fifo_cnt;
     volatile unsigned short dummy;
265
266
267
     /* ==== Calculates the readable size in the receive FIFO ==== */
268
     fifo cnt = 8;
269
270
     /* ==== Reads data from the receive FIFO ==== */
271
     while(fifo_cnt-- != 0 ){
272
273
      /* ---- Reads the received data ---- */
274
      RcvData[RcvCnt++] = SCIF1.SCFRDR.BYTE;
275
      /* ---- Reading all data is completed? ---- */
276
277
      if(RcvCnt == DataNum){
278
       /* ---- Disables the reception ---- */
279
         SCIF1.SCSCR.BIT.RE = 0;
280
        break;
281
      }
282
     }
     /* ==== Clears the interrupt source (clears the RDF bit) ==== */
283
284
     SCIF1.SCFSR.BIT.RDF = 0;
     dummy = SCIF1.SCFSR.WORD; /* Dummy read to make sure to clear the interrupt source */
285
286
    }
```

3.9 Sample Program Listing "main.c" (8/8)

287	/*""FUNC COMMENT""***********************************							
288	* ID :							
289	* Outline : SCIF1 transmit interrupt (TXI).							
290 291	** Include : "iodefine.h"							
292 293	<pre>* * Declaration : void io_interrupt_scif1_txi(void); .</pre>							
294 295 296 297 298 299	 *							
300 301	* Argument : void							
302 303	* * Return Value : void *							
304 305 306 307 308	* Note : After completing to write all transmit data, check to see the * : transmit end (SCFSR.TEND) bit that all transmit data in FIFO * : is emitted. *""FUNC COMMENT END""***********************************							
309	void io_interrupt_scif1_txi(void)							
310	{							
311	int i, fifo_cnt;							
312 313	volatile unsigned short dummy;							
314	/* ==== Calculates the readable size in the transmit FIFO ==== */							
315	<pre>fifo_cnt = 8;</pre>							
316								
317	/* ==== Writes data in the transmit FIFO ==== */							
318	<pre>while(fifo_cnt != 0){</pre>							
319								
320	/* Writes the transmit data */							
321	SCIF1.SCFTDR.BYTE = SndData[SndCnt++];							
322								
323	/* Writing all data is completed? */							
324	<pre>if(SndCnt == DataNum){ (t = Display=the terms with intervent to the terms to terms t</pre>							
325 326	/* Disables the transmit interrupt */							
326 327	<pre>SCIF1.SCSCR.BIT.TIE = 0; break;</pre>							
328	<pre>bleak, }</pre>							
329	}							
330	, /* ==== Clears the interrupt source, and starts transmission (Clears bits TDFE,and TEND) ==== */							
331	SCIF1.SCFSR.WORD &= ~0x0060u;							
332	dummy = SCIF1.SCFSR.WORD; /* Dummy read to make sure to clear the interrupt source */							
333	}							
334								
335	/* End of File */							



4. References

 Software Manual SH-2A/SH2A-FPU Software Manual Rev. 3.00 The latest version of the software manual can be downloaded from the Renesas website.

Hardware Manual

SH7262 Group, SH7264 Group Hardware Manual Rev. 2.00 The latest version of the hardware manual can be downloaded from the Renesas website.



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Revision Record

		Descript	ion	
Rev.	Date	Page	Summary	
1.00	Apr.28.10		First edition issued	

General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

- 1. Handling of Unused Pins
 - Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.
 - The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.
- 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

 The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

- 3. Prohibition of Access to Reserved Addresses Access to reserved addresses is prohibited.
 - The reserved addresses are provided for the possible future expansion of functions. Do not access
 these addresses; the correct operation of LSI is not guaranteed if they are accessed.
- 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.
- 5. Differences between Products

Before changing from one product to another, i.e. to one with a different type number, confirm that the change will not lead to problems.

— The characteristics of MPU/MCU in the same group but having different type numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different type numbers, implement a system-evaluation test for each of the products.

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