

APPLICATION NOTE

RX63T Group USB Host Flash Boot Loader

R01AN1418EJ0100 Rev.1.00 May 14, 2014

Abstract

This application note describes a USB host flash boot loader that operates, in single-chip mode, the RX63T Group microcontroller USB 2.0 host/function module in host mode and rewrites the microcontroller's on-chip flash memory over a USB connection.

Note that this application note uses the sample code and drivers described in the following application notes. Renesas USB Device USB Host Mass Storage Class Driver, Renesas USB Device USB Basic Firmware, and M3S-TFAT-Tiny: Fat File System Software are included in the package.

- Erasing and writing internal flash memory RX600 and RX200 Series Simple Flash API for RX Rev.2.40 (R01AN0544EU0240)
- USB communication Renesas USB Device USB Basic Firmware Rev.2.00 (R01AN0512EJ0200) Renesas USB Device USB Host Mass Storage Class Driver Rev.2.00 (R01AN0513EJ0200)
- FAT file system M3S-TFAT-Tiny: Fat File System Software Rev.1.00 (R20AN0038EJ0100)

This application note has the following features.

- A Motorola S format program stored on a USB memory device can be written to flash memory. When the connection of a USB mass storage device (USB memory) that holds a Motorola S format program is recognized, the microcontroller's internal flash memory is erased and that program is written to the erased flash memory.
- The written program can be run. The Motorola S format program written to the microcontroller's internal flash memory can be executed on the microcontroller.
- USB specifications
 USB 2.0 standard full speed transfers are supported.
 USB mass storage class bulk-only transport (BOT) is supported.

USB mass storage subclass SFF-8070i (ATAPI) and SCSI are supported.

Products

RX63T Group, 144-pin and 120-pin versions

When using this application note with other Renesas MCUs, careful evaluation is recommended after making modifications to comply with the alternate MCU.



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1. Specifications

This application note's sample code operates on the RX63T-H RSK board.

If a reset is cleared with switch SW3 on the RX63T-H RSK not held down, the Motorola S format program (filename: download.mot) in the connected USB memory will be written to the microcontroller's internal flash memory. After this write has completed, if a reset is cleared with switch SW3 in the pressed state, the program written to the microcontroller's internal flash memory (also referred to as the downloaded code) will be executed.

Note that the area that this sample code can overwrite is limited to part of the user MAT and the area used by the sample code itself is not overwritten. See section 5.1, Operation Overview, for details.

The result of writing the program to internal flash memory is displayed in the LCD and LEDs on the RX63T-H RSK. See section 5.5, Sample Code LCD and LED Display, for details on the content displayed.

Table 1.1 lists the peripheral function used and their uses, and figure 1.1 shows an example of using this application note.

Table 1.1 Peripheral Functions and their Uses

| Peripheral Function | Use |
|--|---|
| ROM (Flash memory used for storing program code) | The internal flash memory is programmed using ROM P/E mode. |
| USB 2.0 host/function module | Communication with the USB memory device |

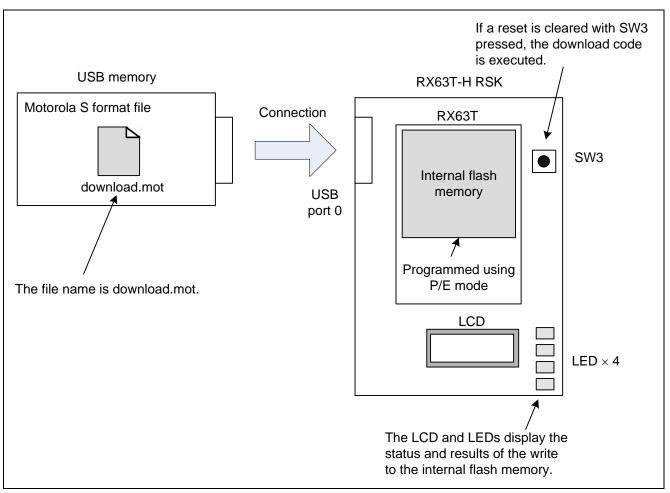


Figure 1.1 Usage Example



2. Operation Confirmation Conditions

The sample code accompanying this application note has been run and confirmed under the conditions below.

| Table 2.1 | Operation | Confirmation | Conditions |
|-----------|-----------|--------------|------------|
|-----------|-----------|--------------|------------|

| ltem | Contents |
|----------------------------|---|
| MCU used | R5F563TEADFB (RX63T Group) |
| Operating | Main clock: 12 MHz |
| frequency | PLL: 192 MHz (main clock frequency divided by 1 and multiplied by 16) |
| | System clock (ICLK): 96 MHz (PLL clock frequency divided by 2) |
| | Peripheral module clock B (PCLKB): 48 MHz (PLL clock frequency divided by 4) |
| | USB clock supplied to USB (UCLK): 48 MHz (PLL clock frequency divided by 4) |
| | FlashIF clock (FCLK): 48 MHz (PLL clock frequency divided by 4) |
| Operating voltage | 5.0 V |
| Integrated | Renesas electronics |
| development environment | High-performance Embedded Workshop Version 4.09.01.007 |
| C compiler | Renesas electronics |
| | RX Standard Toolchain Version 1.2.1.0 |
| | -cpu=rx600 -include="\$(WORKSPDIR)\WorkSpace\ANSI" - |
| | include="\$(WORKSPDIR)\WorkSpace\SmplMain\APL" - |
| | include="\$(WORKSPDIR)\WorkSpace\HwResourceForUSB\inc" - |
| | include="\$(WORKSPDIR)\WorkSpace\HwResourceForUSB\USBHW" - |
| | include="\$(WORKSPDIR)\WorkSpace\HwResourceForUSB\USBHW\DEF" - |
| | include="\$(WORKSPDIR)\WorkSpace\HwResourceForUSB\USBHW\REG" - |
| | include="\$(WORKSPDIR)\WorkSpace\HwResourceForUSB\USRCFG" - |
| | include="\$(WORKSPDIR)\WorkSpace\MSCFW\include" - include="\$(WORKSPDIR)\WorkSpace\MSCFW\TFAT\lib_src" - |
| | include= \$(WORKSPDIR)\WorkSpace\USBSTDFW\include" - |
| | include="\$(WORKSPDIR)\WorkSpace\FLASH" - |
| | include="\$(WORKSPDIR)\WorkSpace\FLASH\src" - |
| | include="\$(WORKSPDIR)\WorkSpace\FLASH\r_bsp" - |
| | include="\$(WORKSPDIR)\WorkSpace\FLASH\r_bsp\mcu\rx63t" - |
| | include="\$(WORKSPDIR)\WorkSpace\FLASH\r_bsp\board\rskrx63t_144pin" - |
| | define=USB_FW_PP=USB_FW_NONOS_PP,USB_TFAT_USE_PP=1,R_FLASH_USB |
| | -output=obj="\$(CONFIGDIR)\\$(FILELEAF).obj" -debug -nostuff - |
| | listfile="\$(CONFIGDIR)\\$(FILELEAF).lst" -optimize=0 -nologo |
| iodefine.h version | 0.50 |
| Endian order | Little-endian |
| Operating mode | Single-chip mode |
| Sample code version | Version 1.00 |
| Board used | Renesas Starter Kit for RX63T-H |



3. Reference Application Notes

For additional information associated with this document, refer to the following application notes.

- Renesas USB Device USB Basic Firmware Rev.2.00 (R01AN0512EJ)
- Renesas USB Device USB Host Mass Storage Class Driver Rev.2.00 (R01AN0513EJ)
- M3S-TFAT-Tiny: FAT File System Software Rev.1.00 (R20AN0038EJ)
- RX600 & RX200 Series Simple Flash API for RX Rev.2.40 (R01AN0544EU)



4. Hardware

4.1 Used Pins

Table 4.1 lists the pins and their functions.

| Table 4.1 Used Pins and Their Functio | Table 4.1 | Used Pins and Their Functions |
|---------------------------------------|-----------|--------------------------------------|
|---------------------------------------|-----------|--------------------------------------|

| Pin Name | I/O | Function |
|------------------|--------|---|
| USB0_DP I/O | | D+ I/O pin of the port 0 USB on-chip transceiver |
| | | This pin should be connected to the D+ pin of the USB bus. |
| USB0_DM | I/O | D– I/O pin of the port 0 USB on-chip transceiver |
| | | This pin should be connected to the D– pin of the USB bus. |
| P13/USB0_VBUSEN | Output | VBUS (5 V) supply enable signal for port 0 external power supply chip |
| PE1/USB0_OVRCURA | Input | Port 0 external overcurrent detection signals should be connected to these pins. VBUS comparator signals should be connected to these pins when the OTG power supply chip is connected. |
| PE3 | Input | Sample code mode selection pin |
| P71 | Output | LED 0 connection pin |
| P72 | Output | LED 1 connection pin |
| P73 | Output | LED 2 connection pin |
| P33 | Output | LED 3 connection pin |
| PG4 | Output | LCD module control pin |
| PG5 | Output | LCD module control pin |
| PG0 | Output | LCD module control pin |
| PG1 | Output | LCD module control pin |
| PG2 | Output | LCD module control pin |
| PG3 | Output | LCD module control pin |



5. Software

5.1 **Operation Overview**

5.1.1 Operation After a Reset Is Cleared

After a reset is cleared, the sample code checks the state of switch SW3 (pin PE3). If this switch is not being pressed (if pin PE3 is high), it runs the USB host flash boot loader and programs the internal flash memory over the USB bus. If this switch is being pressed (if pin PE3 is low), it runs the download code.

Figure 5.1 shows the operation after a reset.

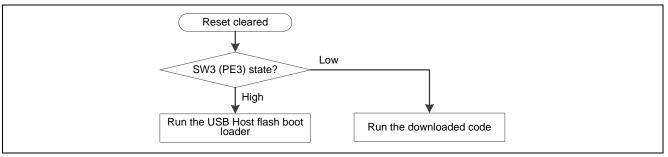


Figure 5.1 Operation After a Reset Is Cleared

5.1.2 Object of Overwriting

The object area that the USB host flash boot loader overwrites is restricted to a certain part of the user MAT (referred to as the download area in this document). The area used for the sample code itself, FFFE 0000h to FFFF FFFFh, is not overwritten.

Figure 5.2 shows the memory allocation.

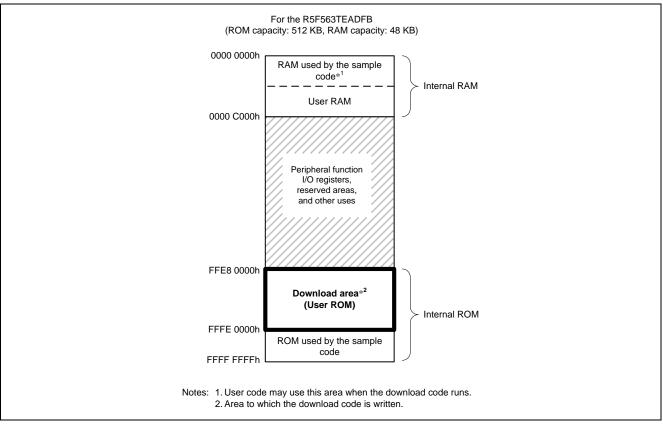


Figure 5.2 Memory Allocation



5.1.3 Programming the Download Area

The USB host flash boot loader uses the following procedure to program the download area. Figure 5.3 shows the download area programming procedure.

- (1) Monitor the USB device connection.
- (2) If a USB connection is detected, acquire the information for the connected device and determine whether or not access is possible.
- (3) If access to the connected USB device (USB memory) is possible, search for a Motorola S format file with the filename download.mot.
- (4) If a Motorola S format file with the filename download.mot is recognized, erase the download area.
- (5) After erasing the download area, read 2048 bytes of data from the Motorola S format file in the USB memory and store it in internal RAM.
- (6) After storing the data in RAM, analyze the data and write it to the download area in 128 byte units.
- (7) Repeat the processing of steps (5) and (6) until all the data has been written.
- Note that the end of the Motorola S format file is recognized by the occurrence of an end record (an S7, S8, or S9 record).
- (8) If the erase and programming of the download area completes normally, report that normal completion in the LCD and LEDs connected to the I/O ports.

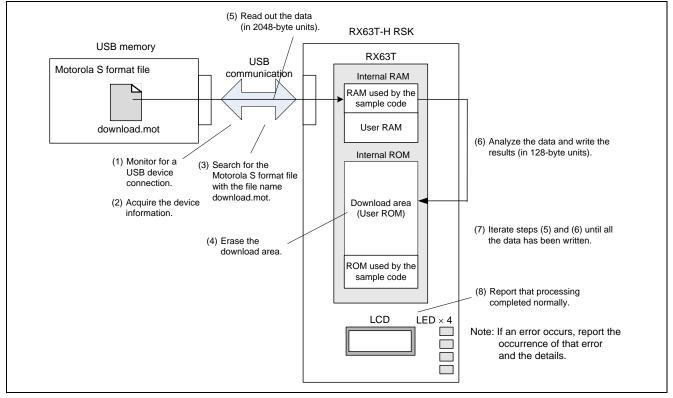


Figure 5.3 Programming the Download Area

Note: If an error occurs during sample code execution, the details of that error are reported in the LCD and LEDs. See section 5.5, Sample Code LCD and LED Display, for details on error occurrence conditions and the LCD and LED display.



5.2 Download Code Execution Start Position

If the switch SW3 state is the low level when a microcontroller reset is cleared, the sample code will run the download code. At this time, the starts executing the download code from the address stored at location FFFD FFFCh. That is, the reset vector for the download code is FFFD FFFCh. Therefore the download code must store its start address at location FFFD FFFCh.

Figure 5.4 shows the reset vector for the download code.

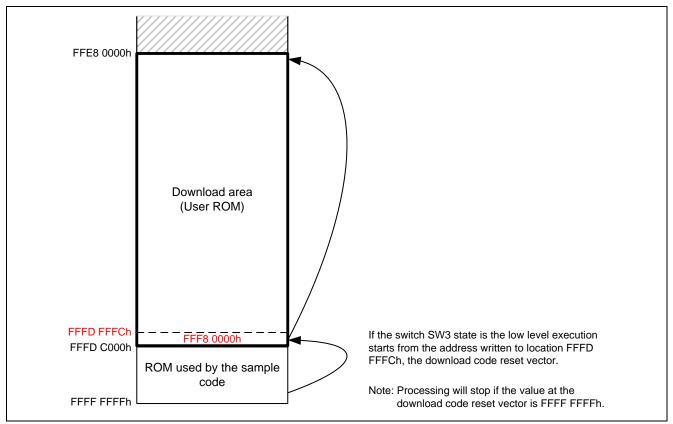


Figure 5.4 Download Code Reset Vector

Note: If nothing is written to the download code reset vector (that is, if the value at the download code reset vector is FFFF FFFFh), the sample code executes a while(1) infinite loop to stop processing.



5.3 Software Structure of the Sample Code

The sample code uses the Renesas USB Device USB Basic Firmware and the Renesas USB Device USB Host Mass Storage Class Driver for USB communication.

It uses the M3S-TFAT-Tiny: Fat File System Software as its FAT file system.

It also uses the RX600 & RX200 Series Simple Flash API for RX for erase and write processing for the internal flash memory.

Figure 5.5 shows software structure of the sample code and table 5.1 gives an overview of the software.

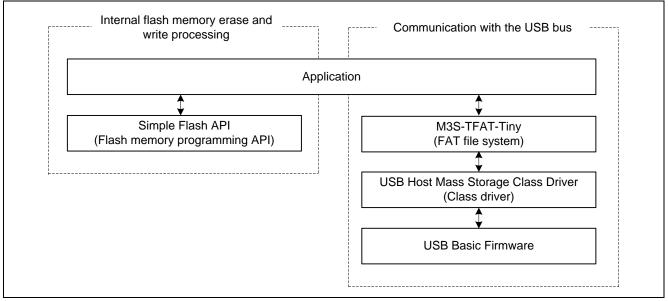


Figure 5.5 Software Structure of the Sample Code

Table 5.1 Software Overview

| Module | Overview |
|------------------------------------|--|
| Application | The application uses FAT library functions to read a Motorola S format program from the USB memory. It then uses the Simple Flash API functions to erase the internal flash memory and write that program to internal flash memory. |
| Simple Flash API for RX | API used to erase and write the internal flash memory |
| M3S-TFAT-Tiny | A FAT file system that supports FAT12 and FAT16. |
| USB Host Mass Storage Class Driver | A class driver that supports the USB mass storage class bulk- only transport (BOT) protocol. |
| USB Basic Firmware | A sample program that controls the USB interface. |



5.4 Data Flow During Write

Figure 5.6 shows the data flow internal to the microcontroller when the download code is written to flash memory.

- (1) The data acquired from the USB driver is transferred to a receive ring buffer.
- (2) One record of the Motorola S format data is copied to a Motorola S format buffer (this is ASCII data).
- (3) At the same time as analyzing the Motorola S format data header section, the ASCII data is converted to binary and stored in a Motorola S format buffer (for binary data).

See section 7, Motorola S format, for the Motorola S format data analysis specifications used in this application note. (4) The data is stored in a write buffer.

In the RX63T Group microcontroller, data is written to the user MAT in units of 128 bytes. Therefore, the sample code iterates steps (2) to (4) above until a total of 128 bytes of write data has been stored in the write buffer. Also, if the total amount of write data exceeds 128 bytes, the excess data is stored temporarily and used for the next write of 128 bytes of data.

(5) The assembled 128 bytes of data are written to flash memory using the Simple Flash API. After the write, if the size of the data stored in the temporary storage buffer is greater than the write unit, step (4) is repeated and write operation continues.

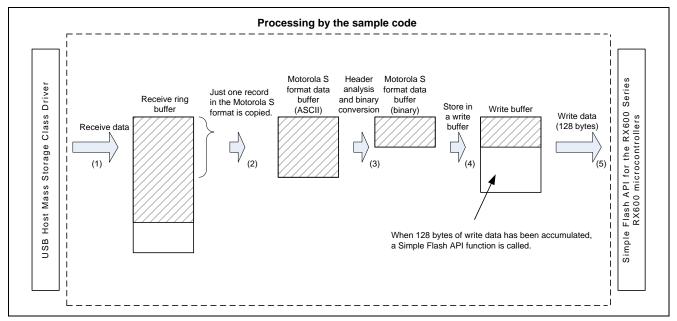


Figure 5.6 Data Flow During Write



Figure 5.7 shows the data structures used when writing data to flash memory.

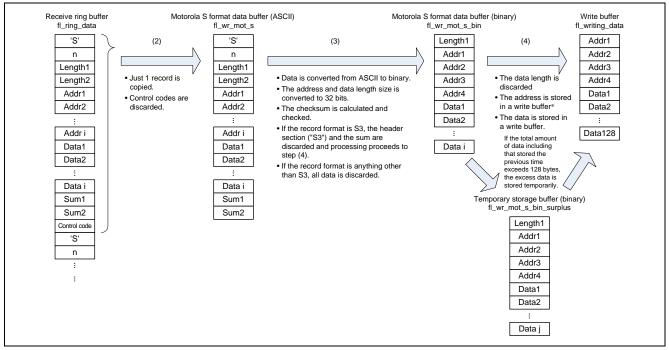


Figure 5.7 Data Structures Used for Writing

Note: In the RX63T Group microcontroller internal flash memory, a start address used for a write operation must be aligned on a 128-byte boundary. Accordingly, the sample code performs processing to assure that write start addresses are aligned on 128-byte boundaries when storing addresses to write buffers. See the flowchart in section 5.13.11, Download Area Write Data Creation, for details on this processing.



5.5 Sample Code LCD and LED Display

The sample code displays the state of progress of the program and the results in the LCD and LEDs mounted on the RX63T-H RSK board. Table 5.2 lists the LED patterns displayed by the sample code.

Table 5.2 Sample Code LED Display

 $\bigcirc: \mathsf{On}, \times: \mathsf{Off}$

LED Display State

| LED3 | LED2 | LED1 | LED0 | Order | Description |
|-----------------------|------|------|------|-------|--|
| × | × | × | × | . ▲ . | The LEDs display a binary counter during the download |
| × | × | × | 0 | - | processing. |
| × | × | 0 | × | - | The LED display is updated every 128 bytes (the unit of |
| × | × | 0 | 0 | - | writes to the RX63T Group user MAT) \times 128 (16 KB). |
| × | 0 | × | × | - | |
| × | 0 | × | 0 | - | |
| × | 0 | 0 | × | - | |
| × | 0 | 0 | 0 | - | |
| 0 | × | × | × | - | |
| 0 | × | × | 0 | - | |
| 0 0 0 0 0 | × | 0 | × | - | |
| 0 | × | 0 | 0 | - | |
| 0 | 0 | × | х | - | |
| 0 | 0 | × | 0 | - | |
| 0 | 0 | 0 | х | - | |
| 0 | 0 | 0 | 0 | - ▼ | |
| × | × | × | 0 | ▲] | When the sample code completes normally, a shifting display |
| × | × | 0 | × | - | pattern is displayed in the LEDs. The LED display is updated |
| × | 0 | × | × | - | once every 500 ms. |
| 0 | × | × | × | - ↓ | |
| × | × | × | × | | If the sample code terminates abnormally, the LEDs blink. |
| 0 | 0 | 0 | 0 | -↓ | The LED display is updated once every 500 ms. |



Table 5.3 lists the LCD patterns displayed by the sample code.

| LCD Display State | Description |
|-------------------|--|
| FLASH | Displayed when the USB host flash boot loader is run after a reset is cleared. |
| BOOT | |
| DETACH | Indicates that a USB was disconnected after having been connected.*1 |
| ATTACH | Indicates that there was a USB connected after a reset was cleared. *1 |
| FLASH | Indicates that download processing is in progress. |
| UPDATE | |
| ERROR!! | Indicates that no accessible drive was detected. (Drive open error) |
| D OPEN | |
| ERROR!! | Indicates that drive mount processing failed. (Drive mount error) |
| D MOUNT | |
| ERROR!! | Indicates that file open processing failed. (File open error) |
| F OPEN | |
| ERROR!! | Indicates that file read processing failed. (File read error) |
| F READ | |
| ERROR!! | Indicates that file close processing failed. (File close error) |
| F CLOSE | |
| ERROR!! | See section 7, Motorola S format. (Checksum error) |
| SUM | |
| ERROR!! | See section 7, Motorola S format. (Format error) |
| MOTS | |
| ERROR!! | Indicates that erase of the download area failed. (Erase error) |
| ERASE | |
| ERROR!! | Indicates that write of the download area failed. (Write error) |
| WRITE | |
| ERROR!! | See section 7, Motorola S format. (Address error) |
| ADDRESS | |
| ERROR!! | Indicates that the result of verifying the data written to the download area was |
| VERIFY | that an abnormality was detected. (Verify error) |
| ERROR!! | Indicates that no Motorola S format end record had been received even though |
| F END | an end of file was detected by the FAT library. (File end error) |
| ERROR!! | Indicates that a USB detach was detected during either drive open or download |
| ILL DET | processing. (Illegal detach error) |
| ERROR!! | Indicates that the endian order (MDES value) of the sample code and the |
| ENDIAN | download code do not match. (Endian error) |

Table 5.3 Sample Code LCD Display

Note: 1. The DETACH display used when a USB is disconnected, and the ATTACH display used when a USB is connected, follow the specifications of the USB Host Mass Storage Class Driver.



5.6 Required Memory Size

Table 5.4 lists the required memory sizes.

Table 5.4 Required Memory Size

| Memory Used | Size | Remarks |
|-------------------------------|---------------|--|
| ROM | 121,022 bytes | Since the sample code is allocated to locations FFFE 0000h to FFFF FFFFh, the amount of ROM that can be written is the total ROM capacity minus 131,072 bytes. |
| RAM | 38,002 bytes | The user code can use this area when it runs. |
| Maximum user stack usage | 588 bytes | |
| Maximum interrupt stack usage | 152 bytes | |

Note: The required memory size varies depending on the C compiler version and compile options.



5.7 File Composition

Table 5.5 lists the files used in the sample code. Files not generated by the integrated development environment should not be listed in this table.

| File Name | Description | Remarks |
|----------------------|--|--------------------------------|
| r_flash_api_rx.c | The RX600 & RX200 Series RX Simple Flash API | For details, see the RX600 & |
| | program | R200 Series RX Simple Flash |
| locking.c | The RX600 & RX200 Series RX Simple Flash API | API application note. |
| | program | - |
| mcu_locks.c | The RX600 & RX200 Series RX Simple Flash API | |
| | program | _ |
| r_flash_api_rx_if.h | External reference include header for the RX600 & | |
| | RX200 Series RX Simple Flash API program | |
| . flash set is a d | (r_flash_api_rx.c). | - |
| r_flash_api_rx_priv | Parameter settings include header for the RX600 | |
| ate.h | & RX200 Series RX Simple Flash API program. | - |
| r_flash_api_rx_confi | Parameter settings include header for the RX600 & RX200 Series RX Simple Flash API program. | |
| g.h r_bsp.h | External reference include header for the RX600 & | - |
| I_bsp.ii | R2X00 Series RX Simple Flash API program. | |
| r_bsp_config.h | Parameter settings include header for the RX600 | - |
| 1_00p_001ing.in | & RX200 Series RX Simple Flash API program. | |
| r_flash_api_rx63t.h | Parameter settings include header for the RX600 | - |
| | & RX200 Series RX Simple Flash API program. | |
| mcu_info.h | Parameter settings include header for the RX600 | - |
| | & RX200 Series RX Simple Flash API program. | |
| locking.h | External reference include header for the RX600 & | - |
| | RX200 Series RX Simple Flash API program | |
| | (locking.c). | _ |
| mcu_locks.h | External reference include header for the RX600 & | |
| | RX200 Series RX Simple Flash API program | |
| | (mcu_locks.c). | |
| r_Flash_main.c | Flash programming data processing | |
| r_Flash_main.h | External reference include header for the flash | |
| r Eloch buff o | programming data processing | |
| r_Flash_buff.c | USB receive ring buffer related processing | |
| r_Flash_buff.h | External reference include header for the USB receive ring buffer related processing | |
| TrgtPrgDmmy.c | Dummy program for allocating the download code | |
| | area | |
| Other files | The USB Host Mass Storage Class Driver | See the Renesas USB device |
| | program | USB Host Mass Storage Class |
| | | Driver and USB Basic Firmware |
| | | application notes for details. |

Table 5.5 Files Used in the Sample Code



5.8 Option-Setting Memory

Table 5.6 lists the option-setting memory configured in the sample code. When necessary, set a value suited to the user system.

| Table 5.6 | Option-Setting Memory Configured in the Sample Code |
|-----------|---|
|-----------|---|

| Symbol | Address | Setting Value | Contents |
|------------|--|------------------|--|
| OFS0 | FFFF FF8Fh to FFFF FF8Ch | FFFF FFFFh | IWDT stops after a reset. |
| | | | WDT stops after a reset. |
| OFS1 | FFFF FF8Bh to FFFF FF88h | FFFF FFFFh | Voltage monitor reset 0 is ignored after |
| | | | a reset. |
| MDES*1 | FFFF FF83h to FFFF FF80h | | (Single-chip mode) |
| | | FFFF FFFFh | Little endian |
| | | FFFF FFF8h | Big endian |
| Noto: 1 Th | a sotting in the sample code is little | andian Deferte 9 | 7 Endian Order for information on |

Note: 1. The setting in the sample code is little endian. Refer to 8.7, Endian Order, for information on changing the endian setting.



5.9 Constants

Table 5.7 and table 5.8 list the constants used in the sample code 1 and constants used in the sample code 2.

| Table 5.7 | Constants | Used in | the Sample | Code 1 |
|-----------|-----------|---------|------------|--------|
|-----------|-----------|---------|------------|--------|

| Constant | Set Value | Description |
|-----------------------------------|----------------|--|
| FL_MODE_ENTRY_WAIT_LCD_ PERIOD | 100000 | Wait time at mode entry |
| FL_UPDATE_WAIT_LED_PERIOD | 128 | Time for the interval between LED display updates during download processing |
| FL_ERROR_WAIT_LED_PERIOD | 500 | Time for the interval between LED display updates during error handling |
| FL_DONE_WAIT_LED_PERIOD | 500 | Time for the interval between LED display updates during normal termination |
| FL_RINGBUFF_SIZE | 4096 | Size of the USB data reception ring buffer |
| FL_TARGET_REST_VECT_ADDR | FFFDFFFCh | Reset vector address of download code |
| FL_START_BLOCK_NUM | 14 | First block in the download area |
| FL_END_BLOCK_NUM | 37 | Last block in the download area |
| FL_START_WRITE_ADDRESS | FFF80000h | First address in the download area |
| FL_END_WRITE_ADDRESS | FFFDFFFFh | Last address in the download area |
| MDES_START_ADDRESS | FFFFFF80h | MDES start address |
| MDES_END_ADDRESS | FFFFF83h | MDES end address |
| FL_UPDATE_FILE_NAME | "download.mot" | Download code file name |
| FL_MOTS_LNG_MAX_DATA | 0xFF | Max. data length value of Motorola S format |
| FL_MOTS_LNG_SIZE | 1 | Data length buffer size of Motorola S format |
| FL_MOTS_ADDR_MIN_SIZE | 2 | Min. address buffer size of Motorola S format |
| FL_MOTS0_ADDR_SIZE | 2 | S0 Motorola S format data address buffer size |
| FL_MOTS3_ADDR_SIZE | 4 | S3 Motorola S format data address buffer size |
| FL_MOTS7_ADDR_SIZE | 4 | S7 Motorola S format data address buffer size |
| FL_MOTS8_ADDR_SIZE | 3 | S8 Motorola S format data address buffer size |
| FL_MOTS9_ADDR_SIZE | 2 | S9 Motorola S format data address buffer size |
| FL_MOTS_SUM_SIZE | 1 | Motorola S format data checksum buffer size |



Constant Set Value Description FL_USB_RCV_BLANK_SIZE FL_RINGBUFF_SIZE / 2 Ring buffer capacity FL PORT MDE PORTE.PIDR.BIT.B3 PORT register for the port connected to SW3 FL_DDR_MDE PORTE.PDR.BIT.B3 PDR register for the port connected to SW3 ROM_PROGRAM_SIZE 128*¹ Sets the unit for writes to the user MAT on the target device. This value is contained in r_flash_api_rx63t.h, and it is referenced when this file is included.

Table 5.8 Constants Used in the Sample Code 2

Note: 1. Value for RX63N/RX63N Group as the target device.



5.10 Variables

Table 5.9 lists the static Variables (1), and Table 5.10 lists the static Variables (2).

Table 5.9 static Variables (1)

| Туре | Variable Name | Contents | Function Used |
|---------------------------------|--|---|--|
| static FIL | fl_file | Variable specifying the file object structure to be created* | R_FI_Flash_Update |
| static FATFS | fl_fatfs | Variable specifying the work area (file system object structure) to be registered* | R_FI_Flash_Update |
| static uint8_t | fl_usb_read_data[FL_RINGBUFF_SI ZE / 2] | Area for storing data read from USB memory | R_FI_Flash_Update |
| static FI_prg_mot_s_t | fl_wr_mot_s | Motorola S format storage buffer (ASCII) | R_FI_Prg_ProcessForMotS_data, R_FI_Prg_StoreMotS |
| static Fl_prg_mot_s_binary_t | fl_wr_mot_s_bin | Motorola S format storage buffer (binary) | R_FI_Prg_ProcessForMotS_data, R_FI_Prg_MakeWriteData |
| static Fl_prg_mot_s_binary_t | fl_wr_mot_s_bin_ surplus | Temporary storage area for redundant (exceeding the write unit) data (binary) | R_FI_Prg_ProcessForMotS_data, R_FI_Prg_MakeWriteData, R_FI_Prg_ClearMotSVariables |
| static Fl_prg_writing_data_t | fl_writing_data | Variable specifying the write area (address) | R_FI_Prg_ProcessForMotS_data, R_FI_Prg_MakeWriteData, R_FI_Prg_WriteData, R_FI_Prg_ClearMotSVariables |
| static uint8_t | fl_communication_ start_flg | Motorola S format start code (S0) detection flag 0: Start code not detected 1: Start code detected | R_FI_Prg_ProcessForMotS_data |
| static uint8_t | fl_communication_ end_flg | Motorola S format end code (S7, S8, S9) detection flag 0: End code not detected 1: End code detected | R_FI_PrgramTrgtArea, R_FI_Prg_ProcessForMotS_data |
| static uint8_t | fl_tfat_eof_flg | File end detection flag 0: File end not detected 1: File end detected | R_FI_Flash_Update, R_FI_PrgramTrgtArea |

Note: * For details, refer to the M3S-TFAT-Tiny: FAT File System Software.



Table 5.10 static Variables (2)

| Туре | Variable Name | Contents | Function Used |
|----------------------|--------------------------------------|--|-------------------|
| static uint8_t | fl_ring_data[FL_ | Receive ring buffer | R_FI_RingEnQueue, |
| | RINGBUFF_SIZE] | | R_FI_RingDeQueue |
| static uint32_t | fl_queue_head | Variable specifying receive ring | R_FI_RingEnQueue, |
| | | buffer read position | R_FI_RingDeQueue |
| static uint32_t | fl_queue_num | Data count stored in receive ring | R_FI_RingEnQueue, |
| | | buffer | R_FI_RingDeQueue, |
| | | | R_FI_RingCheck |
| static const uint8_t | fl_tbl_msg_drive_ open_err[] | Variable indicating drive open error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_drive_ mount_err[] | Variable indicating drive mount error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_file_ open_err[] | Variable indicating file open error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_file_ read_err[] | Variable indicating file read error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_file_ close_err[] | Variable indicating file close error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_program _erase_err[] | Variable indicating erase error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_program _write_err[] | Variable indicating write error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_s_format _sum_err[] | Variable indicating checksum error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_s_format _mots_err[] | Variable indicating format error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_program _verify_err[] | Variable indicating verify error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_program _address_err[] | Variable indicating address error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_illegal_ detach_err[] | Variable indicating illegal detach error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_tfat_end _err[] | Variable indicating file end error | R_FI_Error |
| static const uint8_t | fl_tbl_msg_endian_ err[] | Variable indicating endian error | R_FI_Error |
| static const uint8_t | *p_fl_output_msg[] | Pointer indicating error message | R_FI_Error |
| | | | |



5.11 Structures and Unions

Figure 5.8 shows the structures and unions used in the sample code.

```
/* buffer for mot S format data */
typedef struct {
  uint8_t type[2];
                           /* "S0", "S1" and so on */
                           /* "00"-"FF" */
  uint8_t len[2];
  uint8_t addr_data_sum[(FL_MOTS_LNG_MAX_DATA-FL_MOTS_LNG_SIZE)*2];
} Fl_prg_mot_s_t;
/* buffer for write data
   (this data is the converted data from mot S format data) */
typedef struct {
  uint8 t len;
  uint32_t addr;
  uint8_t data[(FL_MOTS_LNG_MAX_DATA-FL_MOTS_LNG_SIZE-FL_MOTS_ADDR_MIN_SIZE];
} Fl_prg_mot_s_binary_t;
/* buffer for writing flash */
typedef struct {
  uint32 t addr;
  uint8_t data[ROM_PROGRAM_SIZE];
} Fl_prg_writing_data_t;
```

Figure 5.8 Structures and Unions Used in the Sample Code



5.12 Functions

Table 5.11 lists the functions. Note, however, that the USB Mass Storage Class Driver, Simple Flash API, and FAT file system software functions are not shown here.

Table 5.11 Functions

| Function | Description |
|------------------------------|---|
| R_FI_Mode_Entry | Mode selection |
| R_FI_Flash_Update | Main function for flash memory write processing |
| R_FI_EraseTrgtArea | Erase processing |
| R_FI_Ers_EraseFlash | Erase download area |
| R_FI_PrgramTrgtArea | Write download area |
| R_FI_Prg_PrgramTrgtArea | Write processing |
| R_FI_Prg_StoreMotS | Store Motorola S format data |
| R_FI_Prg_ProcessForMotS_data | Header analysis, binary conversion, and write of a Motorola S |
| | format record |
| R_FI_Prg_MotS_AsciiToBinary | Convert Motorola S format data from ASCII to binary |
| R_FI_Prg_MakeWriteData | Create write data for the download area |
| R_FI_Prg_WriteData | Write to download area |
| R_FI_Prg_ClearMotSVariables | Clear the variables related to the Motorola S format data |
| R_FI_Run_StopUSB | Stop USB |
| R_FI_RcvDataString | Store USB receive data |
| R_FI_Error | Error handling |
| R_FI_RingCheckBlank | Verify amount of free space in receive ring buffer |
| R_FI_RingEnQueue | Store data in receive ring buffer |
| R_FI_RingDeQueue | Read data from receive ring buffer |
| R_FI_RingCheck | Verify data count in receive ring buffer |
| R_FI_AsciiToHexByte | Convert data from ASCII to binary |



5.13 Function Specifications

This section shows the specifications of the functions in the sample code.

| R_FI_Mode_Entry | |
|-----------------|---|
| Outline | Mode entry |
| Header | r_Flash_main.h |
| Declaration | void R_FI_Mode_Entry(void) |
| Description | Checks the state of SW3. |
| | If SW3 is not depressed, runs the USB host flash boot loader. |
| | If SW3 is depressed, runs the download code. |
| Arguments | None |
| Return Value | None |

| R_FI_Flash_Update | |
|-------------------|--|
| Outline | Flash memory write processing main routine |
| Header | r_Flash_main.h |
| Declaration | void R_FI_Flash_Update(void) |
| Description | Calls the function that performs the download area erase processing. |
| | Calls FAT library functions to read data from the Motorola S format file in the USB memory. |
| | Calls functions that analyze the Motorola S format data and write the data to the download area. |
| | Calls an error handler if execution of a FAT library function fails. |
| Arguments | None |
| Return Value | None |

| ea |
|---|
| Erase processing |
| None |
| static void R_FI_EraseTrgtArea(void) |
| Calls the function that erases the download area. |
| Calls an error handler if erase of the download area fails. |
| None |
| None |
| |

R_FI_Ers_EraseFlash

| Outline | Erase download area |
|--------------|--|
| Header | None |
| Declaration | static FI_API_SMPL_rtn_t R_FI_Ers_EraseFlash(void) |
| Description | Erases the download area. |
| Arguments | None |
| Return Value | If the erase operation completes normally: FLASH_API_SAMPLE_OK |
| | If the erase operation does not complete normally: FLASH_API_SAMPLE_NG |
| Notes | The processor status word (PSW) interrupt priority level (IPL) is modified to prevent |
| | ROM access by interrupts during the erase operation. |



| R_FI_PrgramTrgtA | rea |
|------------------|---|
| Outline | Write download area |
| Header | None |
| Declaration | static void R_FI_PrgramTrgtArea(void) |
| Description | Calls the function that performs the required write processing. |
| | Calls an error handler if the end of file is reached before receiving a Motorola S format end record. |
| Arguments | None |
| Return Value | None |

| R_FI_Prg_Prgram | TrgtArea |
|-----------------|--|
| Outline | Write processing |
| Header | None |
| Declaration | static FI_API_SMPL_rtn_t R_FI_Prg_PrgramFlash(void) |
| Description | If there is data in the receive ring buffer, calls the function that analyzes a single Motorola S format record. When a single Motorola S format record has been analyzed, calls the function |
| | that performs header analysis, conversion to binary, and writing to the download area. |
| Arguments | None |
| Return Value | If writing to the download area terminates normally: FLASH_API_SAMPLE_OK If writing to the download area did not terminate: FLASH_API_SAMPLE_NG |

| R_FI_Prg_StoreMotS | |
|--------------------|--|
| Outline | Store Motorola S format data |
| Header | None |
| Declaration | static FI_API_SMPL_rtn_t R_FI_Prg_StoreMotS(uint8_t) |
| Description | Stores the data passed in the argument as Motorola S format data one byte at a time. |
| | Discards all data until the first 'S' (ASCII data) is acquired. |
| Arguments | First argument: mot_data : Motorola S format data |
| Return Value | If a single Motorola S format data item (from the 'S' to the checksum) was stored: FLASH_API_SAMPLE_OK |
| | If a single Motorola S format data item was not stored: FLASH_API_SAMPLE_NG |
| Notes | This function is used by passing Motorola S format data 1 byte at a time in the argument. |
| | The checksum is not checked. |



| R_FI_Prg_ProcessForMotS_data | |
|------------------------------|--|
| Outline | Header analysis, binary conversion, and write of a Motorola S format record |
| Header | None |
| Declaration | static void R_FI_Prg_ProcessForMotS_data(void) |
| Description | Analyses the Motorola S format header and calls the function that converts to binary. |
| | Calls the function that stores data in a write buffer. |
| | Calls the function that writes data to the download area. |
| | Calls an error handler if data that differs from the Motorola Motorola S format is received. |
| Arguments | None |
| Return Value | None |

| R_FI_Prg_MotS_AsciiToBinary | |
|-----------------------------|--|
| Outline | Convert Motorola S format data from ASCII to binary |
| Header | None |
| Declaration | static FI_API_SMPL_rtn_t R_FI_Prg_MotS_AsciiToBinary(FI_prg_mot_s_t *, FI_prg_mot_s_binary_t *) |
| Description | Converts Motorola S format data in ASCII code to binary data. Verifies the checksum of the converted binary data. Calls an error handler if data that differs from the Motorola Motorola S format is received. |
| | Calls an error handler if a checksum error occurs. |
| Arguments | First argument: *tmp_mot_s : Pointer to Motorola S format data in ASCII Second argument: *tmp_mot_s_binary : Pointer to variable that holds the converted to binary data |
| Return Value | If conversion completed normally: FLASH_API_SAMPLE_OK If conversion does not complete normally: FLASH_API_SAMPLE_NG |

| R_FI_Prg_MakeWriteData | |
|------------------------|---|
| Outline | Create write data for the download area |
| Header | None |
| Declaration | static FI_API_SMPL_rtn_t R_FI_Prg_MakeWriteData(void) |
| Description | Creates data divided every 128 bytes, the unit of writes to the RX63T Group user MAT. |
| Arguments | None |
| Return Value | If creation of 128 bytes (the unit of writes to the RX63T Group user MAT) of write data completed: FLASH_API_SAMPLE_OK |
| | If creation of 128 bytes (the unit of writes to the RX63T Group user MAT) of write data did not complete: FLASH_API_SAMPLE_NG |



| R_FI_Prg_WriteData | |
|--------------------|---|
| Outline | Write to download area |
| Header | None |
| Declaration | static FI_API_SMPL_rtn_t R_FI_Prg_WriteData(void) |
| Description | Performs the write to the download area. |
| | When the endian order (MDES) of the download code is received, it is compared to the endian order (MDES) of the sample code, and if they do not match an error handler is called. |
| | Verifies the data written. |
| | Calls the error handler if the write failed. |
| | Calls an error handler if a verify error occurs. |
| Arguments | None |
| Return Value | If the write completed normally: FLASH_API_SAMPLE_OK |
| | If the write did not complete normally: FLASH_API_SAMPLE_NG |
| Notes | The processor status word (PSW) interrupt priority level (IPL) is modified to prevent ROM access by interrupts during the write operation. |

| R_FI_Prg_ClearMotSVariables | |
|-----------------------------|---|
| Outline | Clear the variables related to the Motorola S format data |
| Header | None |
| Declaration | static void R_FI_Prg_ClearMotSVariables(void) |
| Description | Clears the variables related to the Motorola S format data. |
| Arguments | None |
| Return Value | None |

| R_FI_Run_StopUSB | |
|------------------|-----------------------------|
| Outline | Stop USB |
| Header | r_Flash_main.h |
| Declaration | void R_FI_Run_StopUSB(void) |
| Description | Stops the USB. |
| Arguments | None |
| Return Value | None |
| | |

| R_FI_RcvDataString | |
|--------------------|---|
| Outline | Store USB receive data |
| Header | None |
| Declaration | static FI_API_SMPL_rtn_t R_FI_RcvDataString(void *, uint16_t) |
| Description | Stores the data received over the USB in a receive ring buffer. |
| Arguments | First argument: *p_tranadr : Pointer to a buffer to hold data received over the USB |
| | Second argument: length : Length of the data received over the USB |
| Return Value | If the store completes: FLASH_API_SAMPLE_OK |
| | If the receive ring buffer was full: FLASH_API_SAMPLE_NG |



| R_FI_Error | |
|--------------|---|
| Outline | Error handling |
| Header | r_Flash_main.h |
| Declaration | void R_FI_Error(FI_err_tbl_num_t err_num) |
| Description | Calls the USB stop function. |
| | Displays the error in the LCD and LEDs. |
| Arguments | First argument: err_num : Error number |
| Return Value | None |

| R_FI_RingCheckBlank | |
|---------------------|---|
| Outline | Verify amount of free space in receive ring buffer |
| Header | r_Flash_buff.h |
| Declaration | FI_API_SMPL_rtn_t R_FI_RingCheckBlank(void) |
| Description | Verifies whether or not there is space in the receive ring buffer for one data unit (2048 bytes) read by the file read function. |
| Arguments | None |
| Return Value | If there is adequate free space: FLASH_API_SAMPLE_OKIf there is not adequate free space: FLASH_API_SAMPLE_NG |

| R_FI_RingEnQueue | |
|------------------|---|
| Outline | Store data in receive ring buffer |
| Header | r_Flash_buff.h |
| Declaration | FI_API_SMPL_rtn_t R_FI_RingEnQueue(uint8_t) |
| Description | Stores data in the receive ring buffer. |
| Arguments | First argument: enq_data : Data to be stored |
| Return Value | If the store completed: FLASH_API_SAMPLE_OK |
| | If the buffer was full: FLASH_API_SAMPLE_NG |

| R_FI_RingDeQueue | 9 |
|------------------|--|
| Outline | Read data from receive ring buffer |
| Header | r_Flash_buff.h |
| Declaration | FI_API_SMPL_rtn_t R_FI_RingDeQueue(uint8_t *) |
| Description | Reads data from the receive ring buffer. |
| Arguments | First argument: *p_deq_data : Pointer to buffer to store data read |
| Return Value | If the data was read out normally: FLASH_API_SAMPLE_OK |
| | If there was no data to read: FLASH_API_SAMPLE_NG |

| R_FI_RingCheck | | |
|----------------|---|--|
| Outline | Verify data count in receive ring buffer | |
| Header | r_Flash_buff.h | |
| Declaration | uint32_t R_FI_RingCheck(void) | |
| Description | Verifies the number of data items in the receive ring buffer. | |
| Arguments | None | |
| Return Value | Returns the number of receive data items. | |



| R_FI_AsciiToHexByte | | | |
|---------------------|---|------------------------------|--|
| Outline | Convert data from ASCII to binary | | |
| Header | r_Flash_buff.h | | |
| Declaration | uint8_t R_FI_AsciiToHexByte(uint8_t, uint8_t) | | |
| Description | Converts a 2-byte ASCII coded data item to 1 byte of binary data. | | |
| Arguments | First argument: in_upper : A | ASCII code data (high order) | |
| | Second argument: in_lower : A | ASCII code data (low order) | |
| Return Value | Returns the converted binary data. | | |
| | | | |



5.14 Flowcharts

5.14.1 Main USB Processing

Figure 5.9 shows the flowchart for main USB processing.

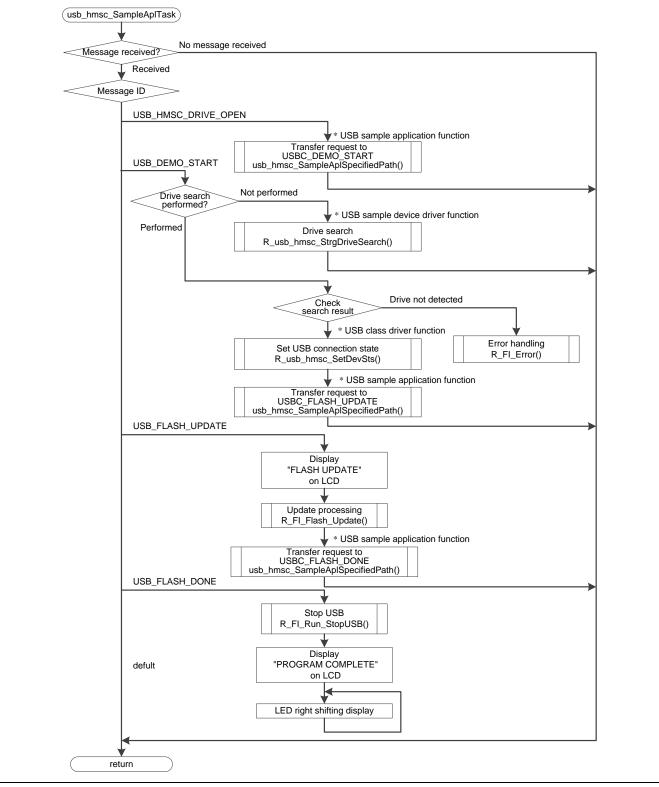


Figure 5.9 Main USB Processing



5.14.2 Mode Entry

Figure 5.10 shows the flowchart for mode entry.

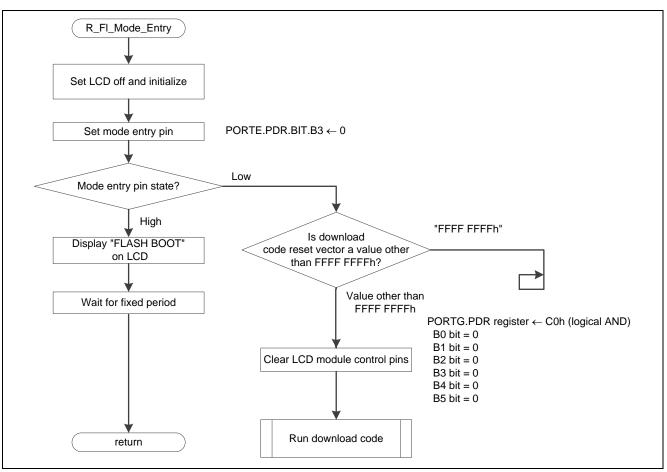


Figure 5.10 Mode Entry



5.14.3 Main Write Processing

Figure 5.11 shows the flowchart for main write processing.

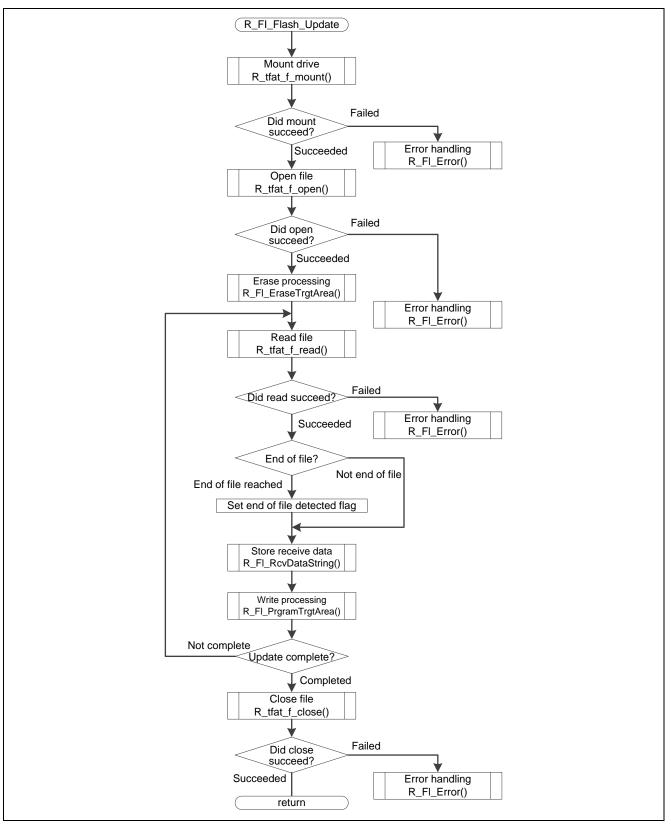


Figure 5.11 Main Write Processing



5.14.4 Erase Processing

Figure 5.12 shows the flowchart for erase processing.

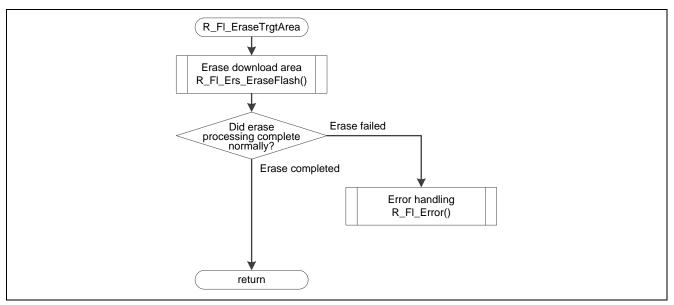


Figure 5.12 Erase Processing



5.14.5 Erase Download Area

Figure 5.13 shows the flowchart for erase download area.

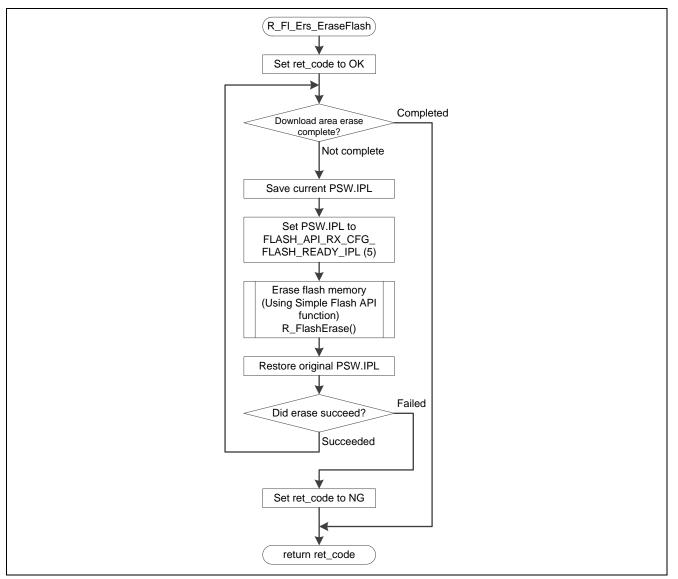


Figure 5.13 Erase Download Area



5.14.6 Write Processing

Figure 5.14 shows the flowchart for write processing.

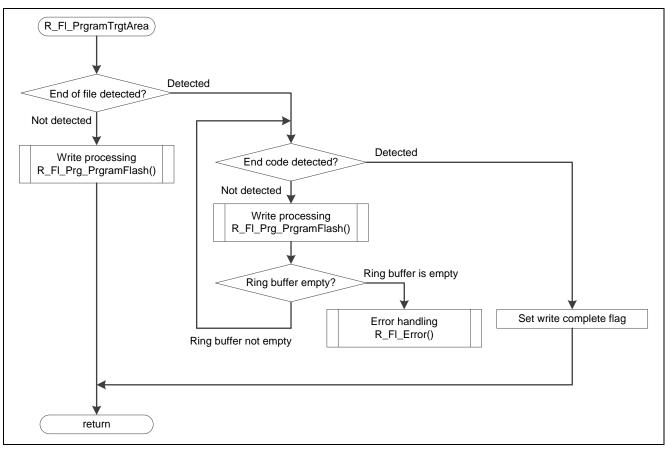


Figure 5.14 Write Processing



5.14.7 Download Area Write Operation

Figure 5.15 shows the flowchart for download area write operation.

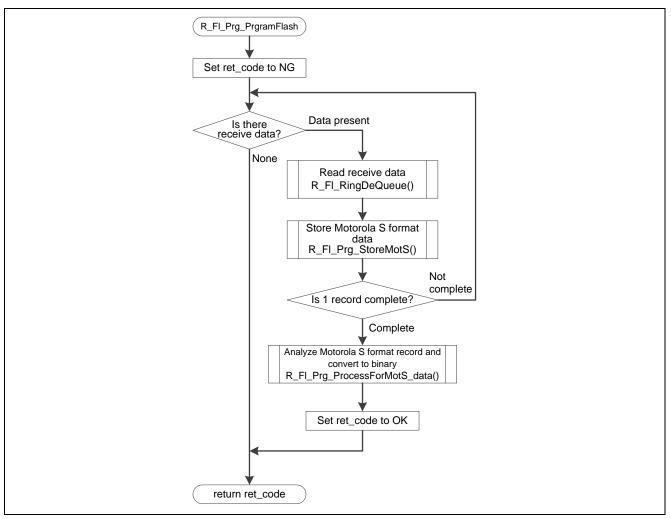


Figure 5.15 Download Area Write Operation



5.14.8 Motorola S Format Header Analysis, Conversion to Binary, and Write Operations

Figure 5.16 shows the flowchart for Motorola S format header analysis, conversion to binary, and write operations.

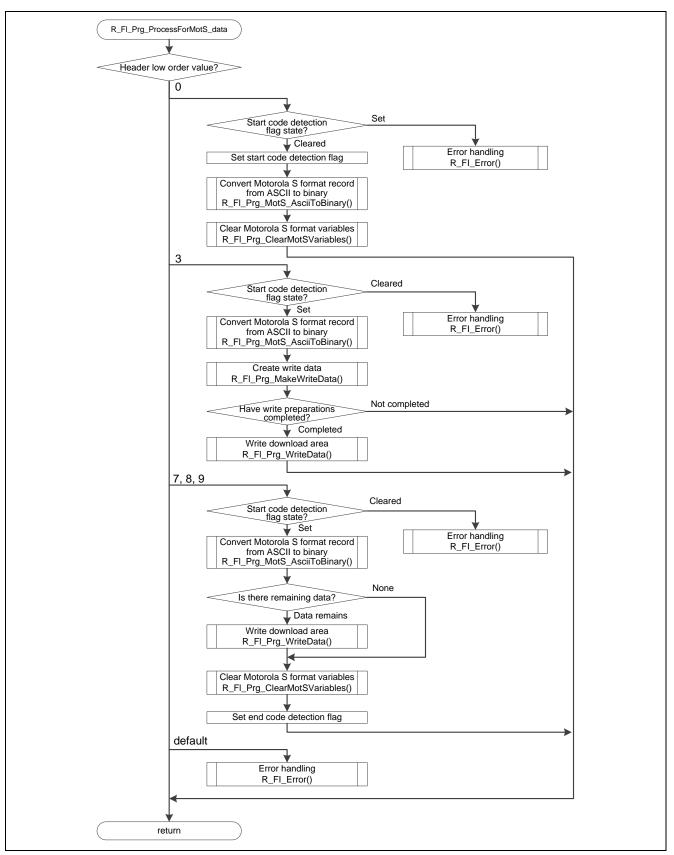


Figure 5.16 Motorola S Format Header Analysis, Conversion to Binary, and Write Operations

5.14.9 Motorola S Format Data Store Operation

Figure 5.17 shows the flowchart for Motorola S format data store operation.

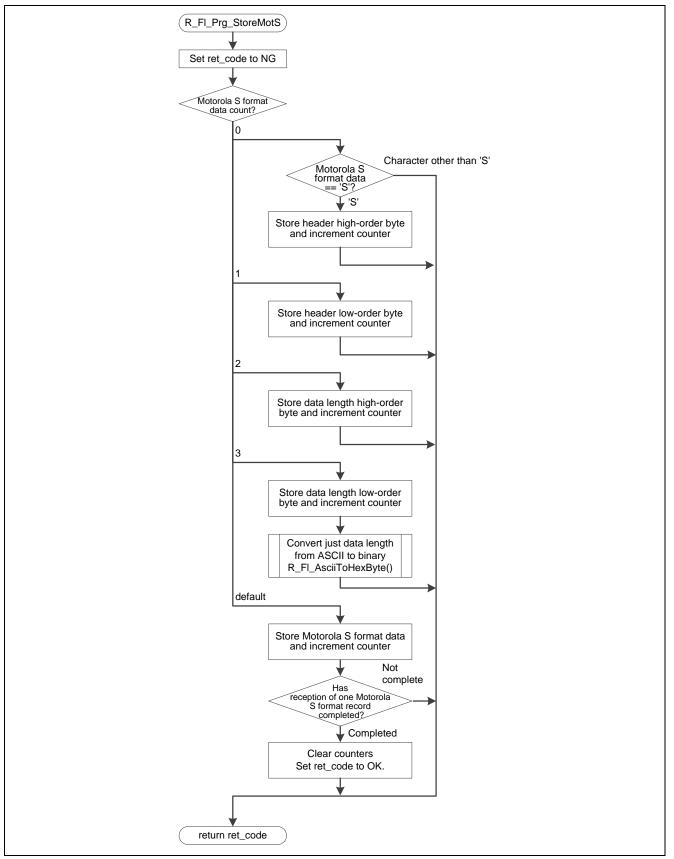


Figure 5.17 Motorola S Format Data Store Operation



5.14.10 Motorola S Format Data ASCII to Binary Conversion

Figure 5.18 shows the flowchart for Motorola S format data ASCII to binary conversion.

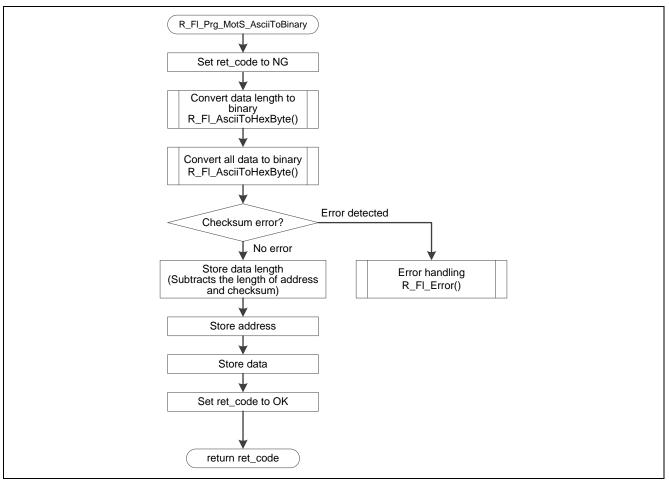


Figure 5.18 Motorola S Format Data ASCII to Binary Conversion



5.14.11 Download Area Write Data Creation

Figure 5.19 shows the flowchart for creating the data to be written to the download area.

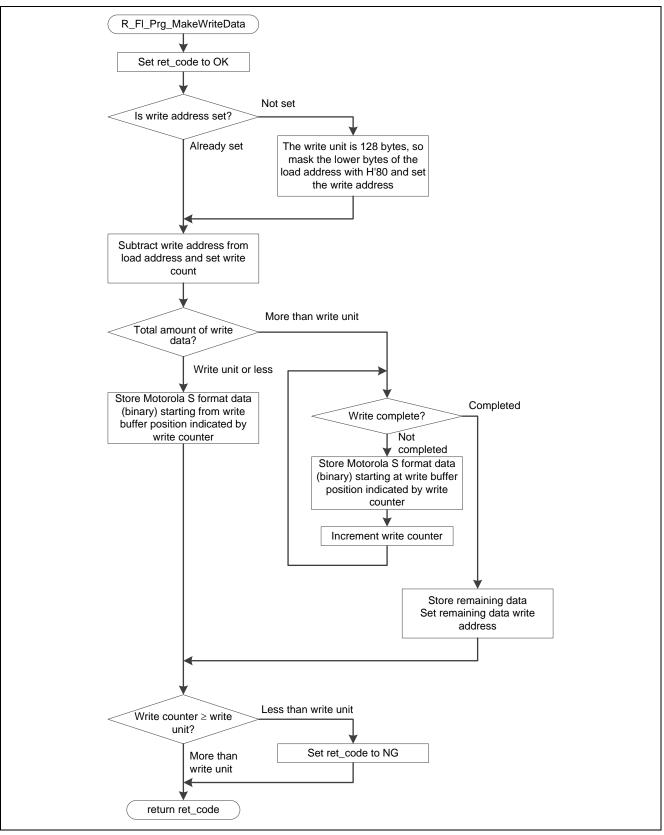


Figure 5.19 Download Area Write Data Creation

5.14.12 Download Area Write

Figure 5.20 shows the flowchart for download area write.

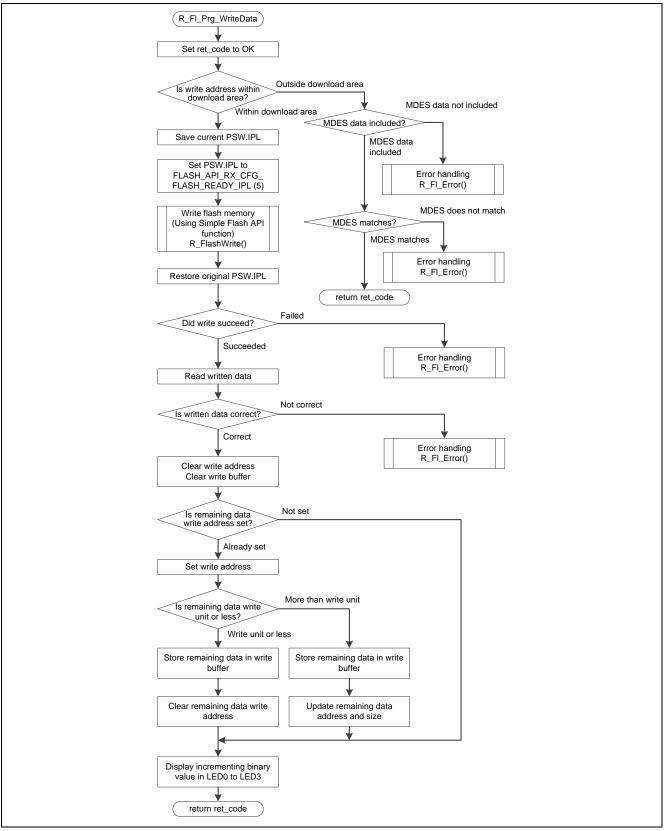


Figure 5.20 Download Area Write

5.14.13 Clear Motorola S Format Data Related Variables

Figure 5.21 shows the flowchart for clear Motorola S format data related variables.

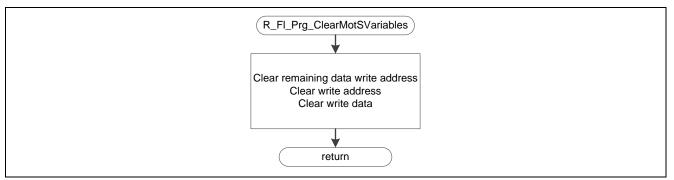


Figure 5.21 Clear Motorola S Format Data Related Variables

5.14.14 Store USB Receive Data

Figure 5.22 shows the flowchart for store USB receive data.

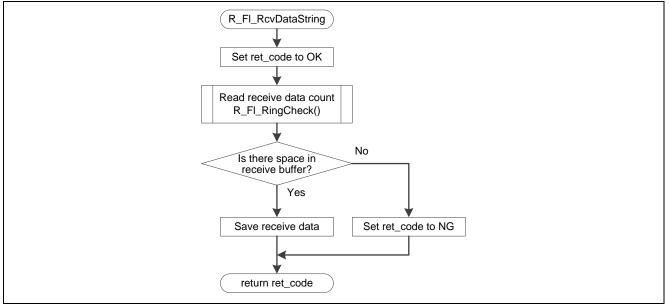


Figure 5.22 Store USB Receive Data



5.14.15 Check for Empty Space in Receive Data Storage Ring Buffer

Figure 5.23 shows the flowchart for check for empty space in receive data storage ring buffer.

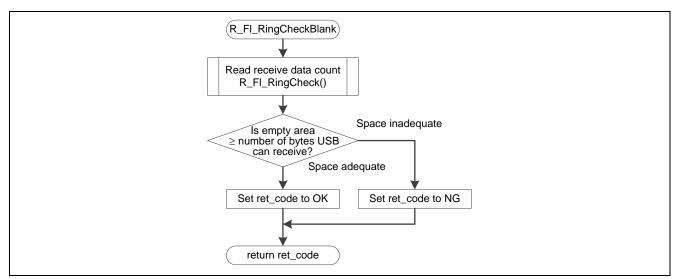


Figure 5.23 Check for Empty Space in Receive Data Storage Ring Buffer

5.14.16 Stop USB

Figure 5.24 shows the flowchart for stop USB.

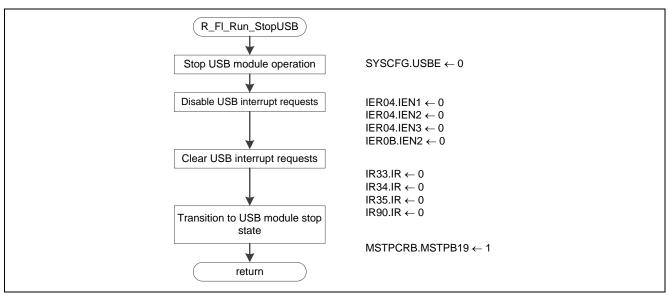


Figure 5.24 Stop USB



5.14.17 Error Handling

Figure 5.25 shows the flowchart for error handling.

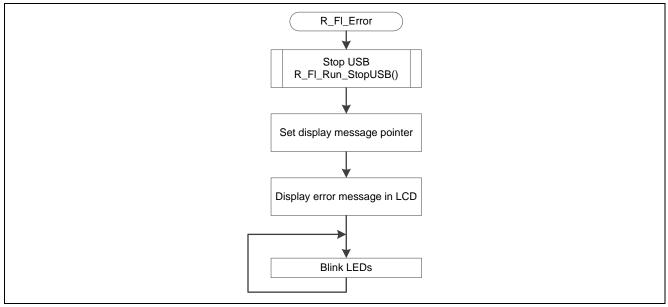


Figure 5.25 Error Handling

5.14.18 Store Data in Receive Data Ring Buffer

Figure 5.26 shows the flowchart for store data in receive data ring buffer.

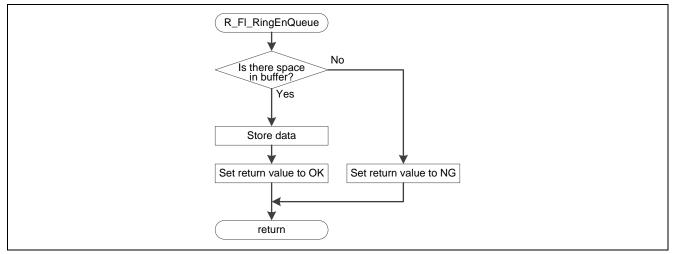


Figure 5.26 Store Data in Receive Data Ring Buffer



5.14.19 Read Data from Receive Data Ring Buffer

Figure 5.27 shows the flowchart for read data from receive data ring buffer.

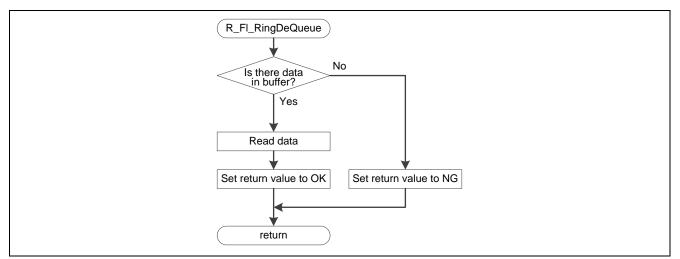


Figure 5.27 Read Data from Receive Data Ring Buffer

5.14.20 Check Data Count in Receive Data Ring Buffer

Figure 5.28 shows the flowchart for check data count in receive data ring buffer.

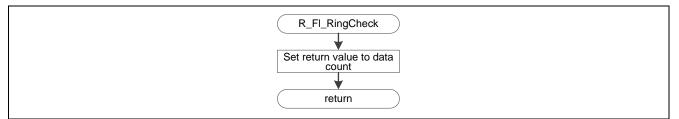


Figure 5.28 Check Data Count in Receive Data Ring Buffer

5.14.21 Convert Data from ASCII to Binary

Figure 5.29 shows the flowchart for convert data from ASCII to binary.

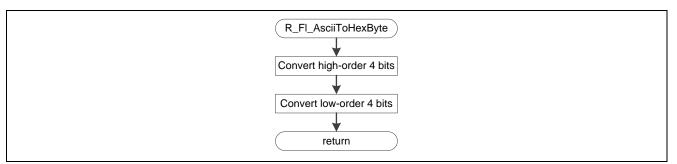


Figure 5.29 Convert Data from ASCII to Binary



6. Sample Download Code

This application note includes a sample download code file (download.zip). This program lights in sequence the LEDs on the board described in section 2, Operation Confirmation Conditions. Refer to this program for examples of download reset vector and section settings. Note that the download code is expected to use 512 KB of ROM.



7. Motorola S Format

This section describes the Motorola S format supported by the sample code.

7.1 Record Formats

Figure 7.1 shows the record formats supported by the sample code.

| Header | r record (S0 record) | | Data | Sum Sum Control | |
|---------|-----------------------|---------------------------------------|-----------------|-----------------|---|
| | ecord (S3 record) | | | Data | Sum Sum Control |
| End rec | cord (S7, S8, or S9 r | · · · · · · · · · · · · · · · · · · · | Adr Adr Adr S | Sum Sum Control | |
| S | X 8 Lng Lng Adr | | | Control | |
| S | ∑*9 S Lng Lng Adr | Adr Adr Adr | Sum Sum Control | | |
| S H | eader record | 0,3,7,8,9 | Record format | Control | Control code (newline or other code) |
| Lng D | ata length | Adr | Load address | | |
| Data D | Pata | Sum | Checksum | | |

Figure 7.1 Record Formats Supported by Sample Code

7.2 Record Structure

Figure 7.2 shows the record structure supported by the sample code. Motorola S format record sequences with orders other than those shown in figure 7.2 are not supported.

| Motorola S format sequence (S7, S8, or S9) | e consisting of a header record (S0), data | records (S3), and an end record |
|---|--|---------------------------------|
| S0 record | S3 record S3 record | S7 or S8 or S9 record |
| Header record | Data record | End record |

Figure 7.2 Record Structure Supported by the Sample Code

7.3 Load Address

The sample code only supports Motorola S format files with increasing load addresses. Do not use Motorola S format files with decreasing order or out of order load addresses.



7.4 Error Detection

The sample code detects errors if there are problems with the Motorola S format file received.

(a) Checksum error

The sample code verifies the checksum at each received Motorola S format record. A checksum error is detected if that verification finds an abnormality.

(b) Format error

A format error is detected if the sample code receives a Motorola S format file that meets any of the following conditions.

- If an unsupported record (S1, S2, S4, S5, or S6) is detected
- If a header record (S0) is detected twice
- If a data record (S3) or an end record (S7, S8, or S9) is detected before a header record (S0).

Figure 7.3 shows the format error detection conditions.

| [Exam | oorted record (S1 nples] | | , | | | |
|-------------|---|--|--------------------|-----------|-----------|-----------|
| | S0 record | S1 record | $\leq \cdots \leq$ | S1 record | S7 record | |
| | S0 record | S2 record | 55 | S2 record | S7 record | |
| | S0 record | S4 record | 55 | S4 record | S7 record | |
| | S0 record | S5 record | 55 | S5 record | S7 record | |
| | 0.0 | CC record | <u> </u> | S6 record | S7 record | |
| | S0 record leader records (S mple] | S6 record | 2 | | | |
| | | | | S3 record | S0 record | S7 record |
| [Exa | eader records (S mple] S0 record | 50) detected S3 record | | S3 record | S0 record | S7 record |
| Exa Data | eader records (S mple] S0 record | 50) detected S3 record | | S3 record | | S7 record |
| Exa Data | eader records (S mple] S0 record record (S3) or en | 50) detected S3 record | | S3 record | S0 record | S7 record |
| Exa Data | eader records (S mple] S0 record record (S3) or en nples] | 50) detected S3 record d record (S7, S | | S3 record | S0 record | S7 record |

Figure 7.3 Format Error Detection Conditions

(c) Address error

An address error is detected if write data for any address outside the download area is received.



8. Notes

8.1 USB Disconnection During Write or Erase

Do not disconnect the USB while erasing or writing the download area.

8.2 HEW Settings

The sample code runs by copying the code in ROM to RAM during flash memory write operations. See the RX600 & RX200 Series Simple Flash API for RX application note for details on the settings.

8.3 Fixed Vector Table Interrupts

Of the fixed vector table interrupts, this sample code only handles the reset interrupt. If any other fixed vector table interrupts are used, the sample code must be modified to handle those interrupts.

8.4 Reset Vector for the Download Code

The execution start position for the download code written using the sample code is determined by the value written at the download reset vector (FFFD FFFCh). Therefore the download code must be set up so that its reset vector is allocated at FFFD FFFCh. See section 5.2, Download Code Execution Start Position, for details.

Also, see section 6, Sample Download Code, for details on the download code.

8.5 Changing the ROM Capacity

The ROM capacity of the microcontroller used by the sample code is 512 KB. If a microcontroller with a ROM capacity of 384 KB or 256 KB, is used, change FL_END_BLOCK_NUM #define directive in the file r_Flash_main.h to match the capacity used.

Table 8.1 lists the ROM capacities.

Table 8.1 ROM Capacities

| Catalog Number | ROM Capacity | Download Area ROM Capacity | Download Area Start Address | Download Area Block Numbers |
|-------------------|-----------------|-------------------------------|--------------------------------|--------------------------------|
| R5F563TE | 512K | 384K | FFF8 0000h | EB14 to EB37 |
| R5F563TC | 384K | 256K | FFFA 0000h | EB14 to EB29 |
| R5F563TB | 256K | 128K | FFFC 0000h | EB14 to EB21 |
| | | | | |

Note: X: N or 1

8.6 while(1) Processing

Note that the sample code locks up by executing a while(1) loop if the USB ring buffer overflows.



8.7 Endian Order

The sample code in this application note supports both little endian and big endian orders. Note that the endian order settings of the flash boot loader and the download code must be the same.

8.7.1 Using Little Endian

When operating using the little endian order, perform the following settings.

- Compiler option settings Specify "Little-endian data" as the compiler option endian setting. Use the little endian MDES value shown in 5.8, Option-Setting Memory.
- Changes to the user system definitions file (r_usb_usrconfig.h) Set the value of the USB_CPUBYTE_PP macro definition to USB_BYTE_LITTLE_PP in the r_usb_usrconfig.h file.
- 3. Changing the TFAT library file (tfat_rx600_little.lib or tfat_rx600_big.lib) Specify \$(WORKSPDIR)\WorkSpace\MSCFW\TFAT\lib\tfat_rx600_little.lib as the linker input library file option.

8.7.2 Using Big Endian

When operating using the big endian order, perform the following settings.

- Compiler option settings Specify "Big-endian data" as the compiler option endian setting. Use the big endian MDES value shown in 5.8, Option-Setting Memory.
- 2. Changes to the user system definitions file (r_usb_usrconfig.h) Set the value of the USB_CPUBYTE_PP macro definition to USB_BYTE_BIG_PP in the r_usb_usrconfig.h file.
- 3. Changing the TFAT library file (tfat_rx600_little.lib or tfat_rx600_big.lib) Specify \$(WORKSPDIR)\WorkSpace\MSCFW\TFAT\lib\tfat_rx600_big.lib as the linker input library file option.



8.8 Changes to the RX600 & RX200 Simple Flash API

This application note uses sample code from the RX600 & RX200 Simple Flash API. See the RX600 & RX200 Simple Flash API application note for the specifications of the RX600 & RX200 Simple Flash API.

8.8.1 Changes

The files in the RX600 & RX200 Simple Flash API that are changed are r_flash_api_rx_config, r_bsp_config.h, r_bsp.h, and r_flash_api_rx.c

• Changes to the file r_flash_api_rx_config.h

To prevent ROM access by interrupts during flash write and erase operations, the processor status word (PSW) interrupt priority level (IPL) field is changed to the value specified in the following macro definition. In this application note, the value 5 is used.
 Macro definition: #define F FLASH_API_RX_CFG_FLASH_READY_IPL 5

Macro definition: #define F FLASH_API_KX_CFG_FLASH_KEADY_IPL

- (2) The following Simple Flash API settings are changed. Before change: //#define FLASH_API_RX_CFG_FLASH_TO_FLASH #define FLASH_API_RX_CFG_IGNORE_LOCK_BITS #define FLASH_API_RX_CFG_COPY_CODE_BY_API
 After change: #define FLASH_API_RX_CFG_FLASH_TO_FLASH //#define FLASH_API_RX_CFG_IGNORE_LOCK_BITS //#define FLASH_API_RX_CFG_COPY_CODE_BY_API
- Changes to the file r_bsp_config.h
 - (1) The Simple Flash API settings are changed. The settings of ICLK_HZ, PCLK_HZ, BCLK_HZ, and FCLK_HZ should match the settings of \$(WORKSPDIR)\WorkSpace\HwResourceForUSB\src\rx_mcu.c, which is included in the USB Host Mass Storage Class Driver files.
 Before change: #define BSP_CFG_BCK_DIV (8)
 After change: #define BSP_CFG_BCK_DIV (4)
- Changes to the file r_bsp.h

(1) The files hwsetup.h, lowscr.h, vexttbl.h, and iodefine_rx63th.h are commented out to avoid duplication of program files included with the USB Host Mass Storage Class Driver. The file rskrx63t_144pin.h is not used, so it is also commented out.

- $Before\ change:\ \#include\ "mcu/rx63t/register_access/iodefine_rx63th.h"$
 - #include "board/rskrx63t_144pin/rskrx63t_144pin.h"
 - #include "board/rskrx63t_144pin/hwsetup.h"
 - #include "board/rskrx63t_144pin/lowsrc.h"
 - #include "board/rskrx63t_144pin/vecttbl.h"
- After change: //#include "mcu/rx63t/register_access/iodefine_rx63th.h"
 - //#include "board/rskrx63t_144pin/rskrx63t_144pin.h"
 - //#include "board/rskrx63t_144pin/hwsetup.h"
 - //#include "board/rskrx63t_144pin/lowsrc.h"
 - //#include "board/rskrx63t_144pin/vecttbl.h"



• Changes to the file r_flash_api_rx.c

(1) The following changes have been to allow the sample program to access iddefine.h, which is included with the USB Host Mass Storage Class Driver.

Before change: #if !defined(R_BSP_VERSION_MAJOR) #include "iodefine.h" #include "mcu_info.h" #endif After change: #if !defined(R_BSP_VERSION_MAJOR) #include "iodefine.h"

#include "mcu_info.h"
#else

#include "iodefine.h"

#endif



8.9 Changes to the USB Host Mass Storage Class Driver

The sample code uses the USB Host Mass Storage Class Driver program code. For specifications of the USB Device USB Host Mass Storage Class Driver, see the USB Device USB Host Mass Storage Class Driver and USB Device USB Basic Firmware application notes.

8.9.1 Changes

The following three files in the USB Host Mass Storage Class Driver are modified for used with this sample code.

- r_usb_hmsc_apl.c
- dbsct_hmsc.c
- resetprg.c
- Places changed in the file r_usb_hmsc_apl.c: Places indicated by #ifdef R_FLASH_USB.
- Places changed in the file dbsct_hmsc.c:
- Places indicated by the comment "// Flash table".
- Places changed in the file resetprg.c:
 - An include file is added. Added: #include "r_Flash_main.h"
 - 2. The mode entry function is called in the function PowerON_Reset_PC(). Added: R_Fl_Mode_Entry();

8.9.2 Added Files

See section 5.7, File Structure, for the files added to the USB Host Mass Storage Class Driver.

8.9.3 Added Sections

Table 8.2 lists the sections added to the USB Host Mass Storage Class Driver.

| Section | Description |
|---------------------|--|
| R_flash_api_sec | Section for variables in the flash programming code that operates in RAM |
| D_flash_api_sec | Section for initialization area of flash programming code that operates in RAM |
| RPFRAM | Section for the flash programming code that operates in RAM |
| TRGT_DMMY_FIXEDVECT | Section for the download code fixed vector |

Table 8.2 Added Sections

8.9.4 Include File Directories

 $WorkSpace\FLASH, WorkSpace\FLASH\sc, WorkSpace\FLASH\r_bsp, WorkSpace\FLASH\r_bsp\mcu\rx63t, and WorkSpace\FLASH\r_bsp\board\rx63t_144pin have been added to the include file directories.$

8.9.5 Macro Definitions (Compiler options)

R_FLASH_USB is added as a compiler option macro definition.

8.9.6 Linker Settings

The following linker settings that map from ROM to RAM are added.

- ROM PFRAM is mapped to RPFRAM.
- ROM D_flash_api_sec is mapped to R_flash_api_sec.



9. Sample Programs

The sample program can be downloaded from the Renesas Electronics Web site.

10. Reference Documents

User's Manual: Hardware RX63T Group User's Manual: Hardware Rev.2.00 (The latest version can be downloaded from the Renesas Electronics Web site.)

Technical Updates/Technical News

(The latest information can be downloaded from the Renesas Electronics Web site.)

User's Manual: Development Environment

RX Family C/C++ Compiler Package V.1.01 User's Manual Rev.1.00 (includes V.1.02 supplementary documents) (The latest version can be downloaded from the Renesas Electronics Web site.)

Application Notes

Renesas USB Device USB Host Mass Storage Class Driver Rev.2.00 Renesas USB Device USB Basic Firmware Rev.2.00 M3S-TFAT-Tiny: Fat File System Software Rev.1.00 RX600 & R200 Series Simple Flash API for RX Rev.2.40 (The latest version can be downloaded from the Renesas Electronics Web site.)



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Revision History

| | | Description | |
|------|---------------|-------------|----------------------|
| Rev. | Date | Page | Summary |
| 1.00 | May. 14, 2014 | _ | First edition issued |
| - | | | |

General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

- 1. Handling of Unused Pins
 - Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.
 - The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.
- 2. Processing at Power-on
 - The state of the product is undefined at the moment when power is supplied.
 - The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

- 3. Prohibition of Access to Reserved Addresses
 - Access to reserved addresses is prohibited.
 - The reserved addresses are provided for the possible future expansion of functions. Do not access
 these addresses; the correct operation of LSI is not guaranteed if they are accessed.
- 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

 When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

Before changing from one product to another, i.e. to a product with a different type number, confirm that the change will not lead to problems.

— The characteristics of an MPU or MCU in the same group but having a different part number may differ in terms of the internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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