

# RL78/G1F

Serial Array Unit (UART Communication) CC-RL

# APPLICATION NOTE

R01AN3314EJ0100 Rev. 1.00 July 20, 2016

### Introduction

This application note explains how to use UART communication through the serial array unit (SAU). ASCII characters transmitted from the device on the opposite side are analyzed to make responses.

### **Target Device**

RL78/G1F

When applying the sample program covered in this application note to another microcomputer, modify the program according to the specifications for the target microcomputer and conduct an extensive evaluation of the modified program.



## Contents

1.	Specifications
2.	Operation Check Conditions
3.	Related Application Note5
4.	Description of the Hardware
4.1	Hardware Configuration Example
4.2	List of Pins to be Used
5.	Description of the Software
5.1	Operation Outline
5.2	List of Option Byte Settings
5.3	List of Constants
5.4	List of Variables
5.5	List of Functions
5.6	Function Specifications
5.7	Flowcharts
5.7	1 Initialization Function
5.7	2 System Function
5.7	3 I/O Port Setup
5.7	4 CPU Clock Setup
5.7	5 Serial Array Unit Setup
5.7	6 UART0 Setup
5.7	7 Main Function
5.7	8 Main initializes settings
5.7	9 UART0 Reception Status Initialization Function
5.7	10 UART0 Operation Start Function
5.7	11 INTSR0 Interrupt Service Routine
5.7	
5.7	13 UART0 Data Transmission Function
5.7	
5.7	1
5.7	•
5.7	17 UART0 Transmission End Processing Function
6.	Sample Code
7.	Documents for Reference



### 1. Specifications

In this application note, UART communication is performed through the serial array unit (SAU). ASCII characters transmitted from the device on the opposite side are analyzed to make responses.

Table 1.1 shows the peripheral function to be used and its use. Figures 1.1 and 1.2 illustrate UART communication operation.

Table 1.1	Peripheral Function to be Used and its Use

Peripheral Function	Use
Serial array unit 0	Perform UART communication using the TxD0 pin
	(transmission) and the RxD0 pin (reception).

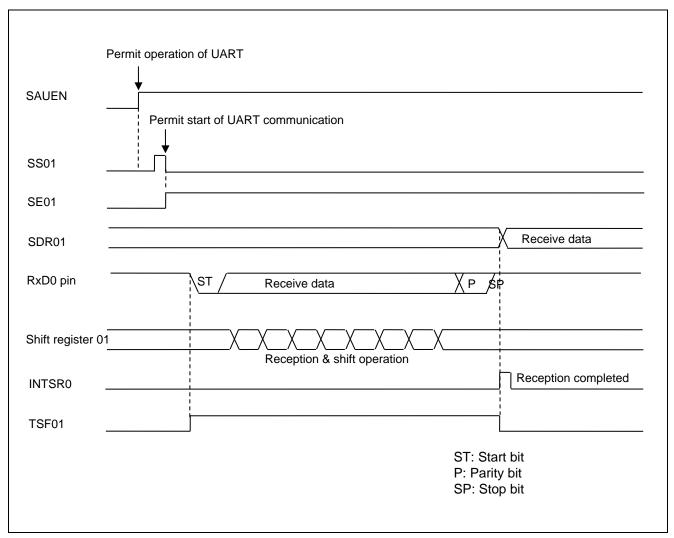


Figure 1.1 UART Reception Timing Chart



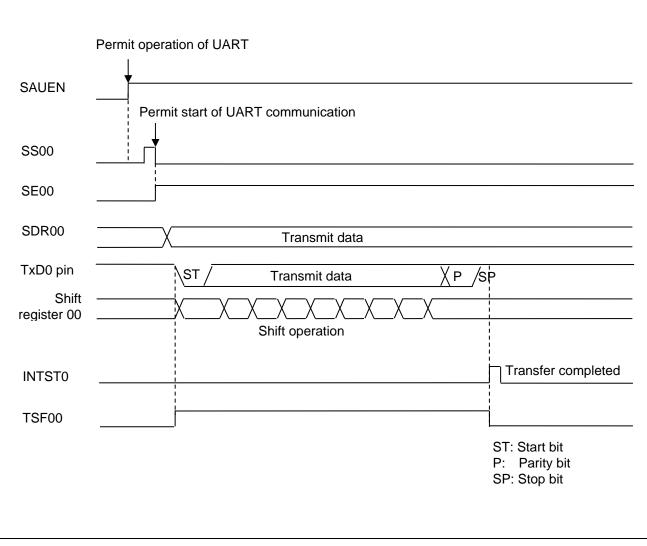


Figure 1.2 UART Transmission Timing Chart



# 2. Operation Check Conditions

The sample code contained in this application note has been checked under the conditions listed in the table below.

Item	Item Description	
Microcontroller used	r used RL78/G1F (R5F11BLE)	
Operating frequency	High-speed on-chip oscillator (HOCO) clock: 24 MHz	
	CPU/peripheral hardware clock: 24 MHz	
Operating voltage	5.0 V (can run on a voltage range of 2.9 V to 5.5 V.)	
	LVD operation (V <sub>LVD</sub> ): Reset mode 2.81 V (2.76V to 2.87V)	
Integrated development Renesas Electronics Corporation		
environment (CS+)	CS+ for CC V3.03.00	
C compiler (CS+)	Renesas Electronics Corporation	
	CC-RL V1.02.00	
Integrated development	Renesas Electronics Corporation	
environment (e <sup>2</sup> studio)	e <sup>2</sup> studio V4.0.0.26	
C compiler (e <sup>2</sup> studio)	Renesas Electronics Corporation	
	CC-RL V1.02.00	
Board RL78/G1F CPU board (RSKRL78G1F)		

Table 2.1	<b>Operation Check Conditions</b>
-----------	-----------------------------------

### 3. Related Application Note

The application note that is related to this application note is listed below for reference.

RL78/G13 Initialization (R01AN2575E) Application Note



### 4. Description of the Hardware

### 4.1 Hardware Configuration Example

Figure 4.1 shows an example of hardware configuration that is used for this application note.

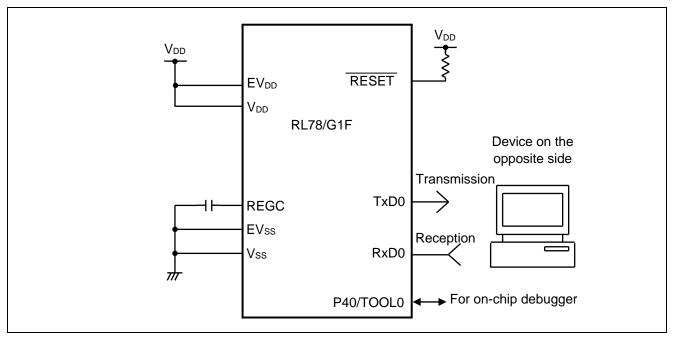


Figure 4.1 Hardware Configuration

- Caution: 1. The purpose of this circuit is only to provide the connection outline and the circuit is simplified accordingly. When designing and implementing an actual circuit, provide proper pin treatment and make sure that the hardware's electrical specifications are met (connect the input-only ports separately to  $V_{DD}$  or  $V_{SS}$  via a resistor).
  - 2. Connect any pins whose name begins with  $EV_{SS}$  to  $V_{SS}$  and any pins whose name begins with  $EV_{DD}$  to  $V_{DD}$ , respectively.
  - 3.  $V_{DD}$  must be held at not lower than the reset release voltage ( $V_{LVD}$ ) that is specified as LVD.

### 4.2 List of Pins to be Used

Table 4.1 lists the pins to be used and their function.

Table 4.1	Pins to be Used and their Functions
-----------	-------------------------------------

Pin Name	I/O	Description
P51/INTP2/SO00/TxD0/TOOLTxD	Output	Data transmission pin
P50/INTP1/SI00/RxD0/TOOLRxD/SDA00	Input	Data reception pin



### 5. Description of the Software

### 5.1 Operation Outline

This sample code transmits, to the device on the opposite side, the data corresponding to that received from the device. If an error occurs, it transmits to the device the data corresponding to the error. Tables 5.1 and 5.2 show the correspondence between transmit data and receive data.

Table 5.1	Correspondence between Receive Data and Transmit Data
-----------	---

Receive Data	Response (Transmit) Data
T (54H)	O (4FH), K (4BH), "CR" (0DH), "LF" (0AH)
t (74H)	o (6FH), k (6BH), "CR" (0DH), "LF" (0AH)
Other than above	U (55H), C (43H), "CR" (0DH), "LF" (0AH)

it Data
Ì

Error	Response (Transmit) Data
Parity error	P (50H), E (45H), "CR" (0DH), "LF" (0AH)
Framing error	F (46H), E (45H), "CR" (0DH), "LF" (0AH)
Overrun error	O (4FH), E (45H), "CR" (0DH), "LF" (0AH)

(1) Perform initial setting of UART.

<UART Setting Conditions>

- Use SAU0 channels 0 and 1 as UART.
- Use the P51/TxD0 pin and the P50/RxD0 pin for data output and data input, respectively.
- The data length is 8 bits.
- Set the data transfer direction to LSB first.
- Use even parity as the parity setting.
- Set the receive data level to standard.
- Set the transfer rate to 9600 bps.
- Use reception end interrupt (INTSR0), transmission end interrupt (INTST0), and error interrupt (INTSRE0).
- Select interrupt priority level 2 or 1 for INTSR0 and for INTSRE0. Select the low interrupt priority level (level 3) for INTST0.
- (2) After the system is made to enter a UART communication wait state by using the serial channel start register, a HALT instruction is executed. Processing is performed in response to reception end interrupt (INTSR0) and error interrupt (INTSRE0).
- When an INTSR0 occurs, the received data is taken in and the data corresponding to the received data is transmitted. When an INTSRE0 occurs, error handling is performed to transmit the data corresponding to the error.
- After data transmission, a HALT instruction is executed again to wait for reception end interrupt (INTSR0) and error interrupt (INTSRE0).



### 5.2 List of Option Byte Settings

Table 5.1 summarizes the settings of the option bytes.

Address	Value	Description
000C0H/010C0H	01101110B	Disables the watchdog timer.
		(Stops counting after the release from the reset state.)
000C1H/010C1H	0111111B	LVD reset mode, 2.81 V (2.76V to 2.87V)
000C2H/010C2H	11101000B	HS mode, HOCO: 32MHz
000C3H/010C3H	10000100B	Enables the on-chip debugger.

### Table 5.1 Option Byte Settings

### 5.3 List of Constants

Table 5.2 lists the constants that are used in this sample program.

Constant	Setting	Description
g_messageOK[4]	"OK¥r¥n"	Response message to reception of "T".
g_messageok[4]	"ok¥r¥n"	Response message to reception of "t".
g_messageUC[4]	"UC¥r¥n"	Response message to reception of characters other than "T" or "t".
g_messageFE[4]	"FE¥r¥n"	Response message to a framing error.
g_messagePE[4]	"PE¥r¥n"	Response message to a parity error.
g_messageOE[4]	"OE¥r¥n"	Response message to an overrun error.

 Table 5.2
 Constants for the Sample Program

### 5.4 List of Variables

Table 5.3 lists the global variable that is used by this sample program.

Туре	Variable Name	Contents	Function Used
uint8_t	g_uart0_rx_buffer	Receive data buffer	main()
uint8_t	gp_uart0_tx_address	Transmit data pointer	R_UART0_Send(),
			R_UART0_Interrupt_Send()
uint16_t	g_uart0_tx_count	Transmit data number	R_UART0_Send(),
		counter	R_UART0_Interrupt_Send()
uint8_t	gp_uart0_rx_address	Receive data pointer	R_UART0_Receive(),
			R_UART0_Interrupt_Receive(),
			R_UART0_Interrupt_Error()
uint16_t	g_uart0_rx_ count	Receive data number	R_UART0_Receive(),
		counter	R_UART0_Interrupt_Receive()
uint16_t	g_uart0_rx_length	Receive data number	R_UART0_Receive(),
			R_UART0_Interrupt_Receive()
MD_STATUS	g_uart0_tx_end	Transmit status	main(),
			r_uart0_callback_sendend()
unit8_t	g_uart0_rx_error	Receive error status	main(),
			r_uart0_callback_receiveend(),
			r_uart0_callback_error()

#### Table 5.3Global Variable



### 5.5 List of Functions

Table 5.4 lists the functions that are used in this sample program.

Function Name	Outline	
R_UART0_Start	UART0 operation start	
R_UART0_Receive	UART0 reception status initialization function	
R_UART0_Send	UART0 data transmission function	
r_uart0_interrupt_receive	UART0 reception end interrupt handling	
r_uart0_callback_receiveend	UART0 receive data classification function	
r_uart0_interrupt_error	UART0 error interrupt handling	
r_uart0_callback_error	UART0 reception error classification function	
r_uart0_interrupt_send	UART0 transmission end interrupt handling	
r_uart0_callback_sendend	UART0 transmission end processing function	
r_uart0_callback_softwareoverrun	UART0 overflow data receive function	

#### Table 5.4 Functions

## 5.6 Function Specifications

This section describes the specifications for the functions that are used in this sample program.

	—
Synopsis	UART0 operation start
Header	r_cg_macrodriver.h, r_cg_sau.h, and r_cg_userdefine.h
Declaration	void R_UART0_Start(void)
Explanation	Starts operation of channel 0 of serial array units 0 and 1 to make the system enter a communication wait state.
Arguments	None
Return value	None
Remarks	None

### [Function Name] R\_UART0\_Receive

Synopsis	UART0 reception status initialization function	า
Header	r_cg_macrodriver.h, r_cg_sau.h, r_cg_userd	lefine.h
Declaration	MD_STATUS R_UART0_Receive(uint8_t *r	x_buf, uint16_t rx_num)
Explanation	Makes initial setting for UART0 reception.	
Arguments	uint8_t *rx_buf	: [Receive data buffer address]
	uint16_t rx_num	: [Receive data buffer size]
Return value	[MD_OK]: Reception setting is completed	
	[MD_ARGERROR]: Reception setting failed	
Remarks	None	



# [Function Name] R\_UART0\_Send Synopsis UART0 data transmission function

Synopsis	UART0 data transmission fur	iction
Header	r_cg_macrodriver.h, r_cg_sau.h, r_cg_userdefine.h	
Declaration	MD_STATUS R_UART0_Send(uint8_t* tx_buf, uint16_t tx_num)	
Explanation	Makes initial setting for UART0 transmission, and starts data transmission.	
Arguments	uint8_t *tx_buf	: [Transmit data buffer address]
	uint16_t tx_num	: [Transmit data buffer size]
Return value	[MD_OK]: Transmission setting is completed	
[MD_ARGERROR]: Transmission setting failed		sion setting failed
Remarks	None	

### [Function Name] r\_uart0\_interrupt\_receive

UART0 reception end interrupt handling
r_cg_macrodriver.h, r_cg_sau.h, and r_cg_userdefine.h
static voidnear r_uart0_interrupt_receive(void)
Makes a response (data transmission) corresponding to received data.
None
None
None

### [Function Name ] r\_uart0\_interrupt\_erro

Synopsis	UART error interrupt function
Header	r_cg_macrodriver.h, r_cg_sau.h, and r_cg_userdefine.h
Declaration	static voidnear r_uart0_interrupt_error(void)
Explanation	Transmits the data corresponding to a detected error.
Arguments	None
Return value	None
Remarks	None

#### [Function Name ] r\_uart0\_callback\_receiveend

Synopsis	UART0 receive data classification function
Header	r_cg_macrodriver.h, r_cg_sau.h, and r_cg_userdefine.h
Declaration	static void r_uart0_callback_receiveend(void)
Explanation	Clears the reception error flag.
Arguments	None
Return value	None
Remarks	None

#### [Function Name] r\_uart0\_callback\_error

Synopsis	UART0 reception	UART0 reception error classification function	
Header	r_cg_macrodrive	r_cg_macrodriver.h, r_cg_sau.h, and r_cg_userdefine.h	
Declaration	static void r_uart	t0_callback_error(uint8_t err_type)	
Explanation	Makes flag settin	Makes flag setting for transmission of the data corresponding to an error.	
Arguments	err_type	: Error type	
Return value	None		
Remarks	None		



#### [Function Name] r\_uart0\_interrupt\_send

Synopsis	UART0 transmission end interrupt handling
Header	r_cg_macrodriver.h, r_cg_sau.h, and r_cg_userdefine.h
Declaration	<pre>static voidnear r_uart0_interrupt_send(void)</pre>
Explanation	Transmits a specified number of pieces of data.
Arguments	None
Return value	None
Remarks	None

#### [Function Name] r\_uart0\_callback\_sendend

Synopsis	UART0 transmission end processing function
Header	r_cg_macrodriver.h, r_cg_sau.h, r_cg_userdefine.h
Declaration	static void r_uart0_callback_sendend(void)
Explanation	Makes transmission end flag setting.
Arguments	None
Return value	None
Remarks	None

### [Function Name] r\_uart0\_callback\_softwareoverrun

Synopsis	UART0 overflow data receive function
Header	r_cg_macrodriver.h, r_cg_sau.h, r_cg_userdefine.h
Declaration	static void r_uart0_callback_softwareoverrun(void)
Explanation	Executes when detected overflow of data by software.
Arguments	None
Return value	None
Remarks	Unused function



### 5.7 Flowcharts

Figure 5.1 shows the overall flow of the sample program described in this application note.

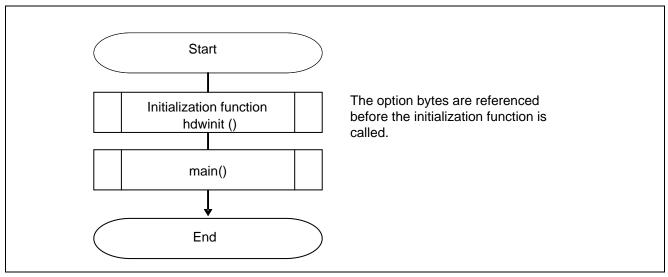


Figure 5.1 Overall Flow

Note: Startup routine is executed before and after the initialization function.

### 5.7.1 Initialization Function

Figure 5.2 shows the flowchart for the initialization function.

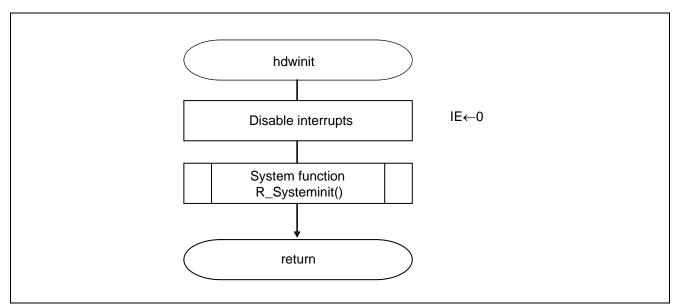


Figure 5.2 Initialization Function



### 5.7.2 System Function

Figure 5.3 shows the flowchart for the system function.

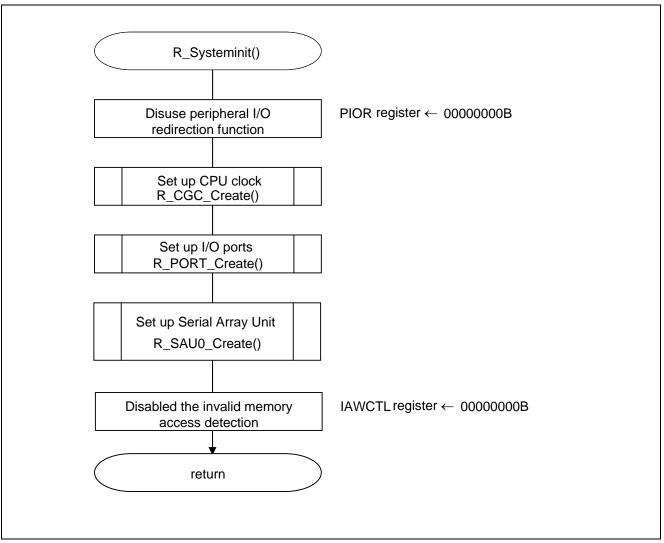


Figure 5.3 System Function



### 5.7.3 I/O Port Setup

Figure 5.4 shows the flowchart for setting up the I/O ports.

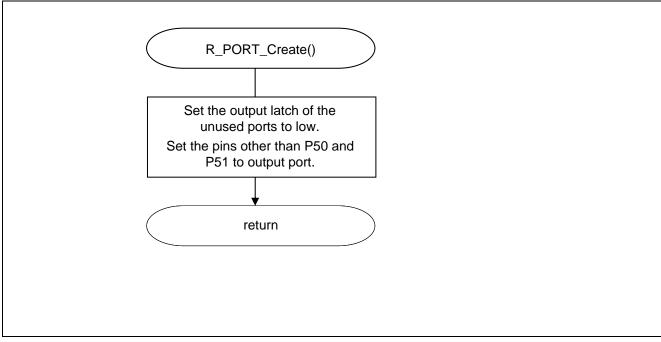


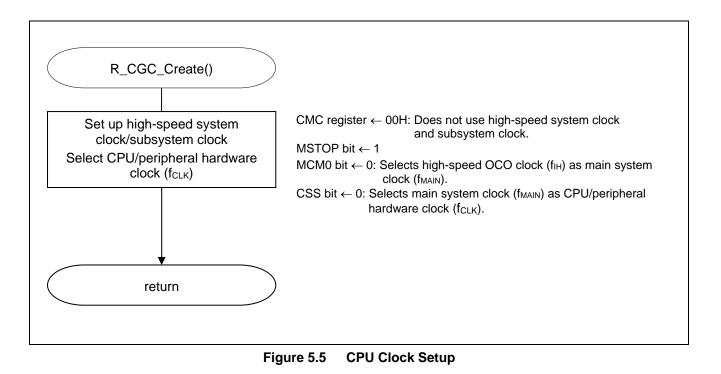
Figure 5.4 I/O Port Setup

- Note: Refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN2575E) for the configuration of the unused ports.
- Caution: Provide proper treatment for unused pins so that their electrical specifications are observed. Connect each of any unused input-only ports to  $V_{DD}$  or  $V_{SS}$  via a separate resistor.



### 5.7.4 CPU Clock Setup

Figure 5.5 shows the flowchart for setting up the CPU clock.



Caution: For details on the procedure for setting up the CPU clock (R\_CGC\_Create ()), refer to the section entitled "Flowcharts" in RL78/G13 Initialization Application Note (R01AN2575E).



### 5.7.5 Serial Array Unit Setup

Figure 5.6 shows the flowchart for setting up the serial array unit.

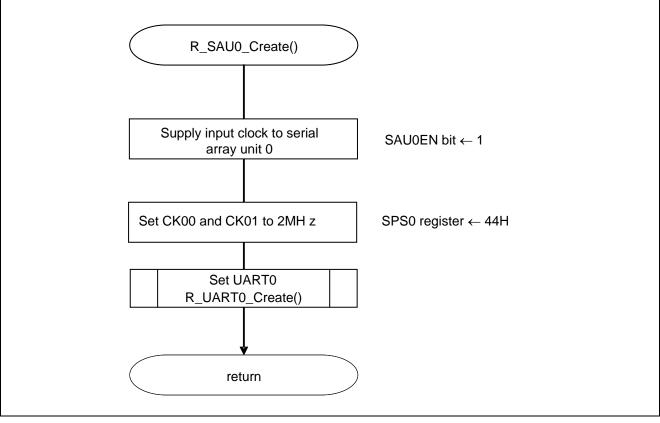


Figure 5.6 Serial Array Unit Setup



Start supplying clock to the SAU

• Peripheral enable register 0 (PER0) Clock supply

Symbol: PER0

7	6 5		4	3	2	1	0
RTCEN	IICA1EN ADCEN IICA		IICA0EN	SAU1EN	SAU0EN	0	TAU0EN
х	0 x		х	х	1	0	х

Bit 2

SAU0EN	Input clock control for serial array unit 0
0	Stops supply of input clock.
1	Starts supply of input clock.

Select serial clock

• Serial clock select register 0 (SPS0) Operation clock setting

Symbol: SPS0

1	5	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0 0	0	0	0	0	0	0	0 0	PRS							
		0	0	0					013	012	011	010	003	002	001	000
C	)	0	0	0	0	0	0	0	0	1	0	0	0	1	0	0

Bits 7 to 0

PRS	PRS	PRS	PRS		Operat	ion clock (Cl	K00) selectio	on (n = 0, 1)	
0n3	0n2	0n1	0n0		f <sub>CLK</sub> = 2 MHz	f <sub>CLK</sub> = 5 MHz	f <sub>CLK</sub> = 10 MHz	f <sub>CLK</sub> = 20 MHz	f <sub>CLK</sub> = 32MHz
0	0	0	0	fclk	2 MHz	5 MHz	10 MHz	20 MHz	32 MHz
0	0	0	1	fclk/2	1 MHz	2.5 MHz	5 MHz	10 MHz	16 MHz
0	0	1	0	$f_{CLK}/2^2$	500 kHz	1.25 MHz	2.5 MHz	5 MHz	8 MHz
0	0	1	1	fclk/2 <sup>3</sup>	250 kHz	625 kHz	1.25 MHz	2.5 MHz	4 MHz
0	1	0	0	fс∟к/2 <sup>4</sup>	125 kHz	312.5 kHz	625 kHz	1.25 MHz	2 MHz
0	1	0	1	f <sub>CLK</sub> /2 <sup>5</sup>	62.5 kHz	156.2 kHz	312.5 kHz	625 kHz	1 MHz
0	1	1	0	fclk/2 <sup>6</sup>	31.25 kHz	78.1 kHz	156.2 kHz	312.5 kHz	500 kHz
0	1	1	1	fclk/2 <sup>7</sup>	15.62 kHz	39.1 kHz	78.1 kHz	156.2 kHz	250 kHz
1	0	0	0	f <sub>CLK</sub> /2 <sup>8</sup>	7.81 kHz	19.5 kHz	39.1 kHz	78.1 kHz	125 kHz
1	0	0	1	fclк/2 <sup>9</sup>	3.91 kHz	9.76 kHz	19.5 kHz	39.1 kHz	62.5 kHz
1	0	1	0	fclk/2 <sup>10</sup>	1.95 kHz	4.88 kHz	9.76 kHz	19.5 kHz	31.3 kHz
1	0	1	1	fclk/2 <sup>11</sup>	977 Hz	2.44 kHz	4.88 kHz	9.76 kHz	15.6 kHz
1	1	0	0	fclk/2 <sup>12</sup>	488 Hz	1.22 kHz	2.44 kHz	4.88 kHz	7.8 kHz
1	1	0	1	fclk/2 <sup>13</sup>	244 Hz	610 Hz	1.22 kHz	2.44 kHz	3.9 kHz
1	1	1	0	f <sub>CLK</sub> /2 <sup>14</sup>	122 Hz	305 Hz	610 Hz	1.22 kHz	1.95 kHz
1	1	1	1	fclk/2 <sup>15</sup>	61 Hz	153 Hz	305 Hz	610 Hz	977 Hz



### 5.7.6 UART0 Setup

Figures 5.7, 5.8, and 5.9 show the flowcharts for setting up UARTO.

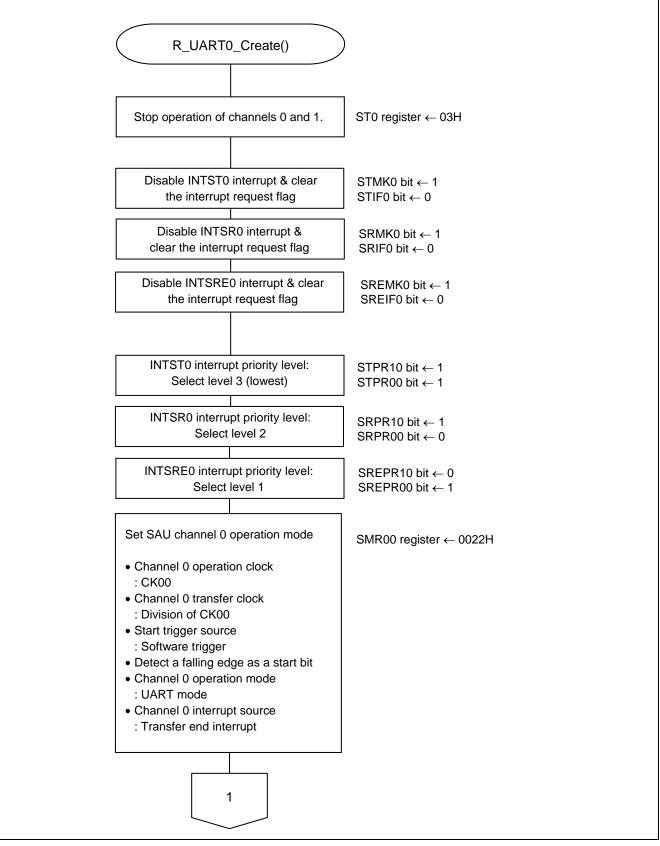


Figure 5.7 UART0 Setup (1/3)



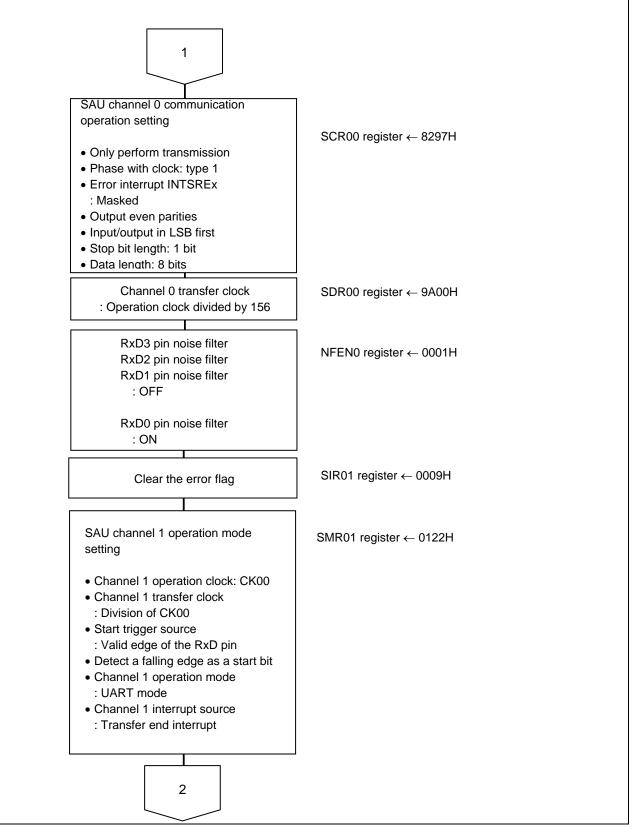


Figure 5.8 UART0 Setup (2/3)



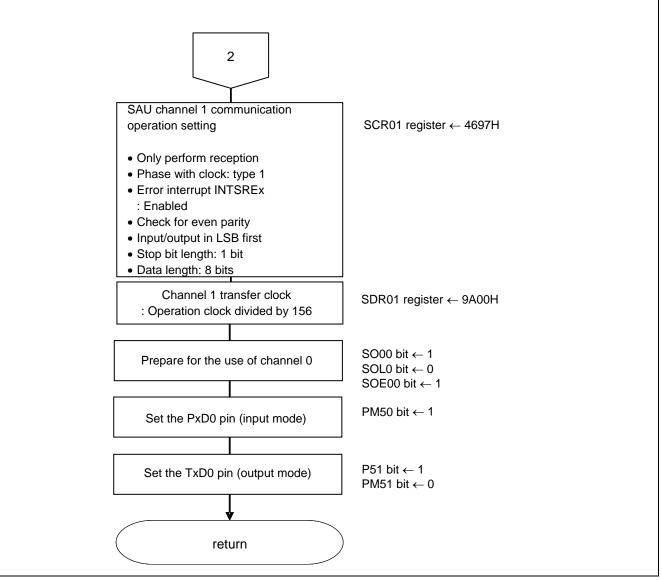


Figure 5.9 UART0 Setup (3/3)



Transmission channel operation mode setting

• Serial mode register 00 (SMR00) Interrupt source Operation mode Transfer clock selection f<sub>MCK</sub> selection

Symbol: SMR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS 00	CCS 00	0	0	0	0	0	0	0	0	1	0	0	MD 002	MD 001	MD 000
0	0	0	0	0	0	0	0	0	0	1	0	0	0	1	0

#### Bit 15

CKS00	Channel 0 operation clock (f <sub>MCK</sub> ) selection									
0	Prescaler output clock CK00 configured by the SPS0 register									
1	Prescaler output clock CK01 configured by the SPS0 register									

#### Bit 14

CCS00	Channel 0 transfer clock (TCLK) selection									
0	lock obtained by dividing the operation clock f <sub>MCK</sub> specified by the CKS00 bit.									
1	Clock input from the SCK pin.									

### Bits 2 and 1

MD002	MD001	Channel 0 operation mode setting
0	0	CSI mode
0	1	UART mode
1	0	Simplified I <sup>2</sup> C mode
1	1	Setting prohibited

#### Bit 0

MD000	Channel 0 interrupt source selection
0	Transfer end interrupt
1	Buffer empty interrupt



Transmission channel communication operation setting

• Serial communication operation setting register 00 (SCR00) Data length setting, data transfer order, error interrupt signal mask availability, and operation mode

Symbol: SCR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TXE 00	RXE 00	DAP 00	CKP 00	0	EOC 00	PTC 001	PTC 000	DIR 00	0	SLC 001	SLC 000	0	1	DLS 001	DLS 000
1	0	0	0	0	0	1	0	1	0	0	1	0	1	1	1

#### Bits 15 and 14

TXE00	RXE00	Channel 0 operation mode setting
0	0	Communication prohibited
0	1	Reception Only
1	0	Transmission only
1	1	Both transmission and reception

#### Bit 10

EOC00	Error interrupt signal (INTSREx ( $x = 0, 1$ )) mask availability selection
0	Error interrupt INTSREx is masked
1	Generation of error interrupt INTSREx is enabled

#### Bits 9 and 8

DTC001	PTC000	Parity bit	setting in UART mode
FICOUI	FICOUU	Transmission	Reception
0	0	No parity bit is output	Data is received without parity
0	1	0 parity is output	No parity check is made
1	0	Even parity is output	Check is made for even parity
1	1	Odd parity is output	Check is made for odd parity

#### Bit 7

DIR00	Selection of data transfer order in CSI and UART modes
0	Input and output in MSB first
1	Input and output in LSB first

#### Bits 5 and 4

SLC001	SLC000	Stop bit setting in UART mode
0	0	No stop bit
0	1	Stop bit length = 1 bit
1	0	Stop bit length = 2 bits
1	1	Setting prohibited



Symbol: SCR00

 15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TXE	RXE	DAP	CKP	0	EOC	PTC	PTC	DIR	0	SLC	SLC	0	1	DLS	DLS
00	00	00	00	Ũ	00	001	000	00	Ŭ	001	000	v	•	001	000
1	0	0	0	0	0	1	0	1	0	0	1	0	1	1	1

Bits 1 and 0

DLS001	DLS000	Data length setting in CSI mode
0	1	9-bit data length
1	0	7-bit data length
1	1	8-bit data length
Oth	iers	Setting prohibited

Transmission channel transfer clock setting

• Serial data register 00 (SDR00) Transfer clock frequency: f<sub>MCK</sub>/208(≈ 9600 Hz)

Symbol: SDR00

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	1	0	0	1	1	1	0	х	х	х	х	х	х	х	х

Bits 15 to 9

		SDF	R00[1	5:9]			Transfer clock setting by dividing operation clock ( $f_{MCK}$ )
0	0	0	0	0	0	0	f <sub>МСК</sub> /2
0	0	0	0	0	0	1	f <sub>MCK</sub> /4
0	0	0	0	0	1	0	f <sub>MCK</sub> /6
0	0	0	0	0	1	1	fмск /8
				•			
•		٠	٠		٠		•
1	1	0	0	1	1	1	fмск /208
				•			
•		•	٠		•	•	•
1	1	1	1	1	1	0	f <sub>мск</sub> /254
1	1	1	1	1	1	1	f <sub>мск</sub> /256



Reception channel operation mode setting

• Serial mode register 01 (SMR01) Interrupt source Operation mode Transfer clock selection f<sub>MCK</sub> selection

Symbol: SMR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
CKS 01	CCS 01	0	0	0	0	0	STS 01	0	SIS 010	1	0	0	MD 012	MD 011	MD 010
0	0	0	0	0	0	0	1	0	0	1	0	0	0	1	0

### Bit 15

CKS01	Channel 1 operation clock (f <sub>MCK</sub> ) selection
0	Prescaler output clock CK00 configured by the SPS0 register
1	Prescaler output clock CK01 configured by the SPS0 register

#### Bit 14

CCS01	Channel 1 transfer clock (TCLK) selection
0	Clock obtained by dividing the operation clock $f_{MCK}$ specified by the CKS01 bit
1	Clock input from the SCK pin

#### Bit 8

STS01	Start trigger source selection
0	Only software trigger is valid
1	Valid edge of the RxD pin (selected during UART reception)

#### Bit 6

SIS010	Control of receive data level inversion on channel 1 in UART mode
0	Falling edge is detected as a start bit
1	Rising edge is detected as a start bit

#### Bits 2 and 1

MD012	MD011	Channel 1 operation mode setting
0	0	CSI mode
0	1	UART mode
1	0	Simplified I <sup>2</sup> C mode
1	1	Setting prohibited

#### Bit 0

MD010	Channel 1 interrupt source selection
0	Transfer end interrupt
1	Buffer empty interrupt



Reception channel communication operation setting

• Serial communication operation setting register 01 (SCR01) Data length setting, data transfer order, error interrupt signal mask availability, and operation mode

Symbol: SCR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TXE 01	RXE 01	DAP 01	CKP 01	0	EOC 01		PTC 010	DIR 01	0	0	SLC 010	0	1	DLS 011	DLS 010
0	1	0	0	0	1	1	0	1	0	0	1	0	1	1	1

Bits 15 and 14

TXE01	RXE01	Channel 1 operation mode setting
0	0	Communication prohibited
0	1	Reception only
1	0	Transmission only
1	1	Both transmission and reception

For UART reception, wait for 4  $f_{CLK}$  clock cycles or more before setting SS01 to 1, after setting the RXE01 bit of the SCR01 register to 1.

#### Bit 10

EOC01	Error interrupt signal (INTSRE1) mask availability selection									
0	Error interrupt INTSRE1 is masked									
1	Generation of error interrupt INTSRE1 is enabled									

#### Bits 9 and 8

DTC011	PTC010	Parity bit setting in UART mode								
FICOTI	FICUIU	Transmission	Reception							
0	0	No parity bit is output	Data is received without parity							
0	1	0 parity is output	No parity check is made							
1	0	Even parity is output	Check is made for even parity							
1	1	Odd parity is output	Check is made for odd parity							

Bit 7

DIR01	Selection of data transfer order in CSI and UART modes							
0	Input and output in MSB first							
1	Input and output in LSB first							

#### Bits 5 and 4

SLC011	SLC010	Stop bit setting in UART mode
0	0	No stop bit
0	1	Stop bit length = 1 bit
1	0	Stop bit length = 2 bits
1	1	Setting prohibited



Symbol: SCR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
TXE 01	RXE 01	DAP 01	CKP 01	0		PTC 011		DIR 01	0	0	SLC 010	0	1	DLS 011	DLS 010
0	1	0	0	0	1	1	0	1	0	0	1	0	1	1	1

Bits 1 and 0

DLS011	DLS010	Data length setting in CSI mode
0	1	9-bit data length
1	0	7-bit data length
1	1	8-bit data length
oth	ers	Setting prohibited

Reception transfer clock setting

• Serial data register 01 (SDR01) Transfer clock frequency: f<sub>MCK</sub>/208 (≈ 9600 Hz)

Symbol: SDR01

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1	1	0	0	1	1	1	0								

Bits 15 to 9

		SDF	R01[1	5:9]			Transfer clock setting by dividing operation clock ( $f_{MCK}$ )
0	0	0	0	0	0	0	f <sub>МСК</sub> /2
0	0	0	0	0	0	1	f <sub>MCK</sub> /4
0	0	0	0	0	1	0	fмск /6
0	0	0	0	0	1	1	fмск /8
	•	•	•	•	•		
			•	-	-		
1	1	0	0	1	1	1	f <sub>мск</sub> /208
		•	•	-	-		
	•	•	•	•	•		
1	1	1	1	1	1	0	f <sub>МСК</sub> /254
1	1	1	1	1	1	1	fмск /256



Initial output level setting

• Serial output register 0 (SO0) Initial output: 1

Symbol: SO0

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	СКО	СКО	СКО	CKO 00	0	0	0	0	SO 03	SO		SO
	_	-	03	03	02	01	00	-			÷	03	02	01	00
0	0	0	0	х	х	х	х	0	0	0	0	х	х	х	1

Bit 0

SO00	Channel 0 serial data output
0	Serial data output value is "0"
1	Serial data output value is "1"

Enabling of data output on target channel

• Serial output enable register 0 (SOE0) Output enable

Symbol: SOE0

_	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	0	0	0	0	0	0	0	0	0	0	0	0	SOE 03	SOE 02	SOE 01	SOE 00
																1

Bit 0

SOE00	Channel 0 serial output enable/stop						
0	erial communication output is stopped						
1	Serial communication output is enabled						



Port setting

• Port register 5 (P5)

• Port mode register 5 (PM5) Port setting for each of transmit data and receive data.

Symbol: P5

7	6	5	4	3	2	1	0
0	0	0	0	0	0	P51	P50
0	0	0	0	0	0	1	0

Bit 1

P51	Output data control (in output mode)
0	0 is output
1	1 is output

Bit 0

P50	Output data control (in output mode)
0	0 is output
1	1 is output

Symbol: PM5

7	6	5	4	3	2	1	0
1	1	1	1	1	1	PM51	PM50
1	1	1	1	1	1	0	1

Bit 1

PM51	P51 I/O mode selection						
0	Output mode (output buffer is on)						
1	Input mode (output buffer is off)						

Bit 0

PM50	P50 I/O mode selection
0	Output mode (output buffer is on)
1	Input mode (output buffer is off)



### 5.7.7 Main Function

Figures 5.10, 5.11 and 5.12 show the flowchart for the main function.

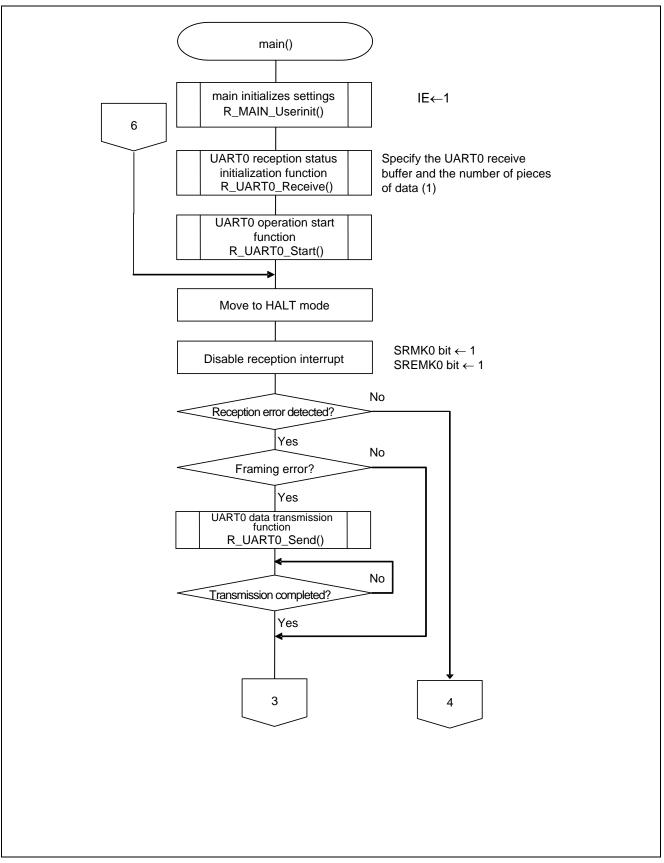


Figure 5.10 Main Function (1/3)



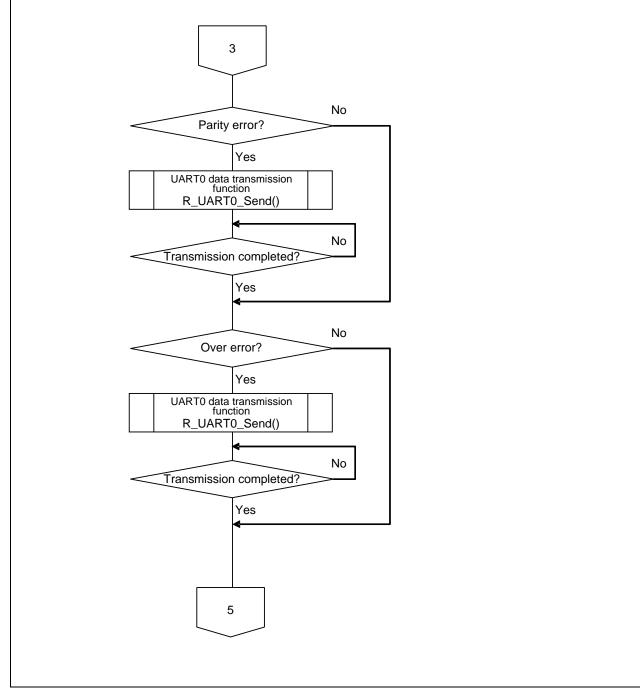


Figure 5.11 Main Function (2/3)



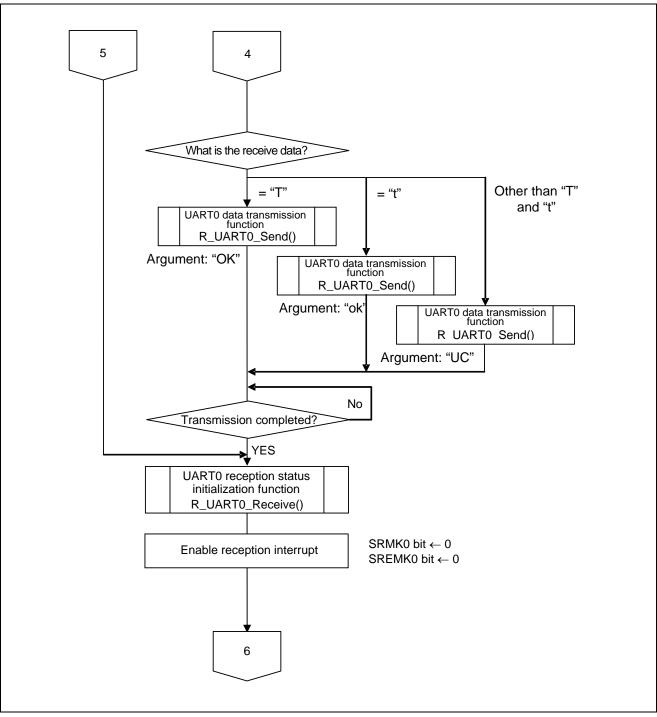


Figure 5.12 Main Function (3/3)



# 5.7.8 Main initializes settings

Figure 5.13 shows the flowchart for the main initializes settings.

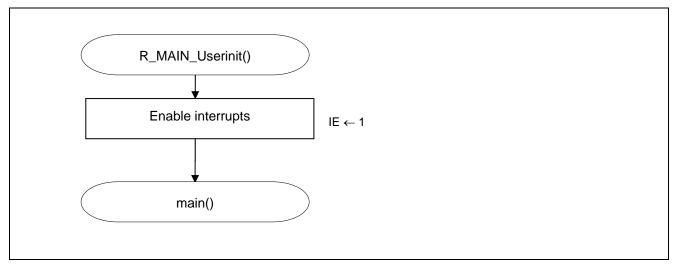


Figure 5.13 Main initializes settings



### 5.7.9 UART0 Reception Status Initialization Function

Figure 5.14 shows the flowchart for the UART0 reception status initialization function.

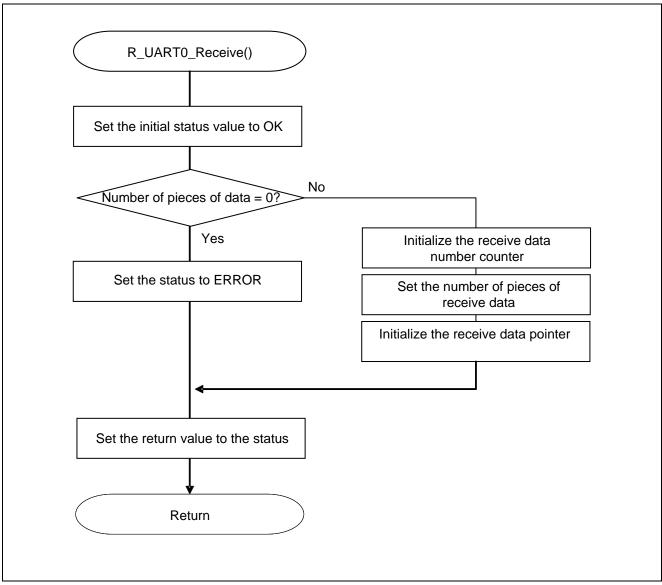


Figure 5.14 UART0 Reception Status Initialization Function



### 5.7.10 UART0 Operation Start Function

Figure 5.15 shows the flowchart for the UART0 operation start function.

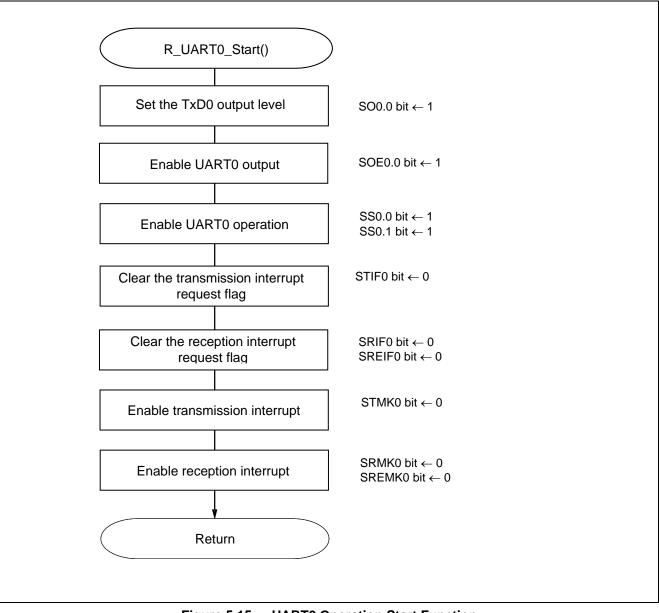


Figure 5.15 UART0 Operation Start Function



Interrupt setting

- Interrupt request flag register (IF0H) Clear the interrupt request flag
- Interrupt mask flag register (MK0H) Cancel interrupt mask

Symbol: IF0H

7	6	5	4	3	2	1	0
SREIF0 TMIF01H	SRIF0	STIF0 CSIIF00 IICIF00	0	0	SREIF2	SREIF2 CSIIF21 IICIF21	_
0	0	0	0	0	х	х	х

Bit 7

SREIF0	Interrupt request flag
0	No interrupt request signal is generated
1	Interrupt request is generated, interrupt request status

Bit 6

SRIF0	Interrupt request flag
0	No interrupt request signal is generated
1	Interrupt request is generated, interrupt request status

Bit 5

STIF0	Interrupt request flag
0	No interrupt request signal is generated
1	Interrupt request is generated, interrupt request status



Symbol: MK0H

7	6	5	4	3	2	1	0
SREMK0 TMMK01H		STMK0 CSIMK00 IICMK00	1	1	SREMK2		
0	0	0	1	1	х	х	х

Bit 7

SREMK0	Interrupt processing control
0	Enables interrupt processing.
1	Disables interrupt processing.

Bit 6

SRMK0	Interrupt processing control
0	Enables interrupt processing.
1	Disables interrupt processing.

Bit 5

STMK0	Interrupt processing control
0	Enables interrupt processing.
1	Disables interrupt processing.



Transition to communication wait state

• Serial channel start register 0 (SS0) Operation start

Symbol: SS0

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	0	0	0	0	0	0	0	0	SS03	SS02	SS01	SS00
0	0	0	0	0	0	0	0	0	0	0	0	X <sup>Note</sup>	х	1 <sup>Note</sup>	1

Bits 3 to 0

SS0n	Channel n operation start trigger				
0	Trigger operation is not performed				
1	SE0n is set to 1, and a communication wait state is entered.				

Note For UART reception, wait for 4  $f_{CLK}$  clock cycles or more before setting SSOn to 1, after setting the RXEOn bit of the SCROn register to 1.

Caution: For details on the register setup procedures, refer to RL78/G1F User's Manual: Hardware.



#### 5.7.11 INTSR0 Interrupt Service Routine

Figure 5.16 shows the flowchart for the INTSR0 interrupt service routine.

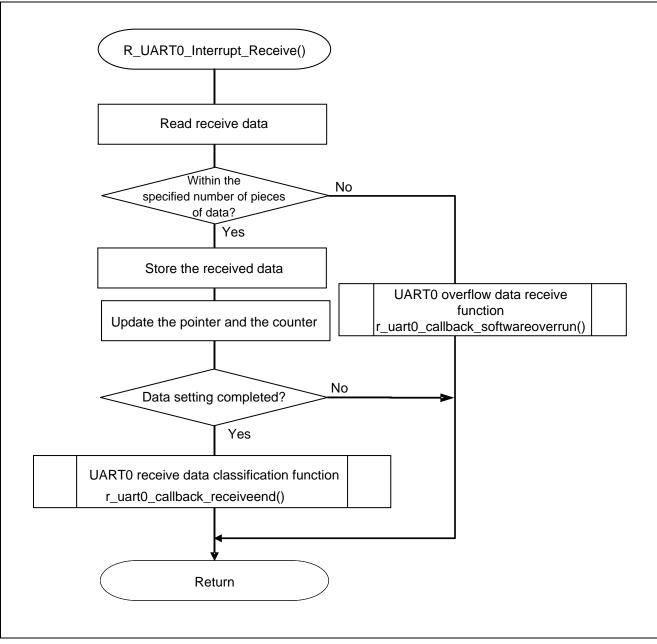


Figure 5.16 INTSR0 Interrupt Service Routine



### 5.7.12 UART0 Receive Data Classification Function

Figure 5.17 shows the flowchart for the UART0 receive data classification function.

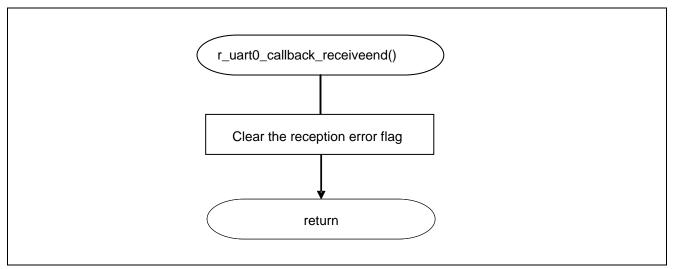


Figure 5.17 UART0 Receive Data Classification Function



#### 5.7.13 UART0 Data Transmission Function

Figure 5.18 shows the flowchart for the UART0 data transmission function.

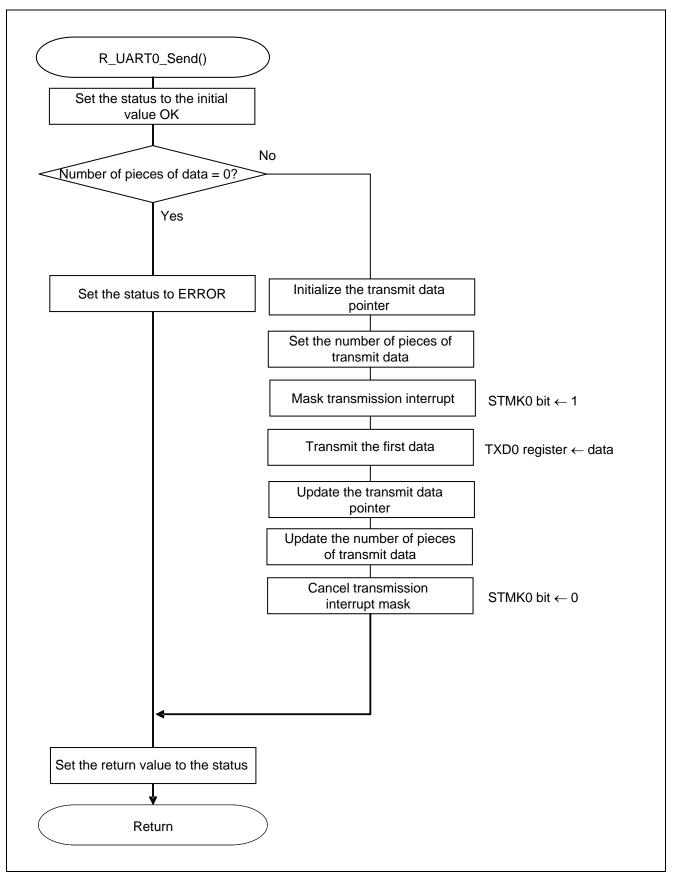


Figure 5.18 UART0 Data Transmission Function



#### 5.7.14 UART0 Reception Error Interrupt Function

Figure 5.19 shows the flowchart for the UART0 reception error interrupt function.

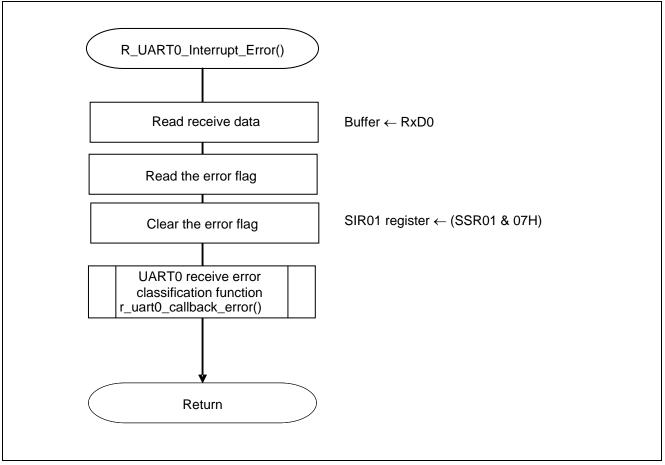


Figure 5.19 UART0 Reception Error Interrupt Function



### 5.7.15 UART0 Reception Error Classification Function

Figure 5.20 shows the flowchart for the UART0 reception error classification function.

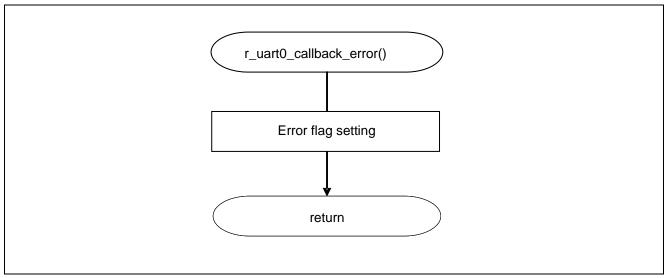


Figure 5.20 UART0 Reception Error Classification Function



#### 5.7.16 INTST0 Interrupt Service Routine

Figure 5.21 shows the flowchart for the INTST0 interrupt service routine.

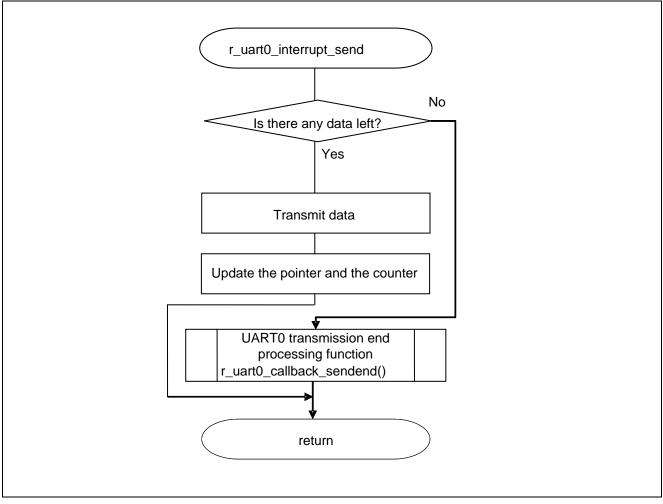


Figure 5.21 INTST0 Interrupt Service Routine



## 5.7.17 UART0 Transmission End Processing Function

Figure 5.22 shows the flowchart for the UART0 transmission end processing function.

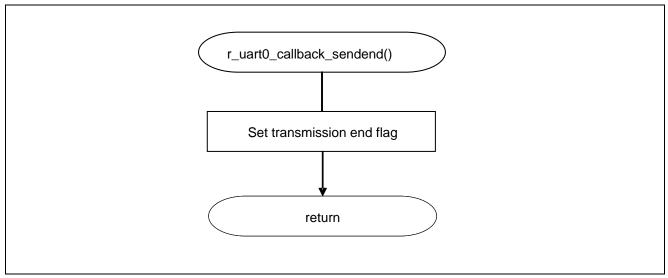


Figure 5.22 UART0 Transmission End Processing Function



#### 6. Sample Code

The sample code is available on the Renesas Electronics Website.

#### 7. Documents for Reference

RL78/G1F User's Manual: Hardware (R01UH0516E)

RL78 Family User's Manual: Software (R01US0015E)

(The latest versions of the documents are available on the Renesas Electronics Website.)

Technical Updates/Technical Brochures

(The latest versions of the documents are available on the Renesas Electronics Website.)

### Website and Support

Renesas Electronics Website

• http://www.renesas.com/index.jsp

Inquiries

• http://www.renesas.com/contact/



Revision Record	RL78/G1F Serial Array Unit (UART Communication) CC-RL
-----------------	---

Rev.	Dete	Description				
	Date	Page	Summary			
1.00	July 20, 2016	—	First edition issued			

All trademarks and registered trademarks are the property of their respective owners.

## General Precautions in the Handling of MPU/MCU Products

The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

— The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
 In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.
 In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access
  these addresses; the correct operation of LSI is not guaranteed if they are accessed.
- 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

Before changing from one product to another, i.e. to a product with a different part number, confirm that the change will not lead to problems.

— The characteristics of an MPU or MCU in the same group but having a different part number may differ in terms of the internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

#### Notice 1. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits software or information 2. Renesas Electronics has used reasonable care in preparing the information included in this document, but Renesas Electronics does not warrant that such information is error free. Renesas Electronics assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein 3. Renesas Electronics does not assume any liability for infringement of patents, copyrights, or other intellectual property rights of third parties by or arising from the use of Renesas Electronics products or technical information described in this document. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or 4. You should not alter, modify, copy, or otherwise misappropriate any Renesas Electronics product, whether in whole or in part. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from such alteration, modification, copy or otherwise misappropriation of Renesas Electronics product. 5. Renesas Electronics products are classified according to the following two quality grades: "Standard" and "High Quality". The recommended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below "Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; and industrial robots etc. "High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control systems; anti-disaster systems; anti-crime systems; and safety equipment etc. Renesas Electronics products are neither intended nor authorized for use in products or systems that may pose a direct threat to human life or bodily injury (artificial life support devices or systems, surgical implantations etc.), or may cause serious property damages (nuclear reactor control systems, military equipment etc.). You must check the quality grade of each Renesas Electronics product before using it in a particular application. You may not use any Renesas Electronics product for any application for which it is not intended. Renesas Electronics shall not be in any way liable for any damages or losses incurred by you or third parties arising from the use of any Renesas Electronics product for which the product is not intended by Renesas Electronics. 6. You should use the Renesas Electronics products described in this document within the range specified by Renesas Electronics, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas Electronics shall have no liability for malfunctions or damages arising out of the use of Renesas Electronics products beyond such specified ranges 7. Although Renesas Electronics endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, Renesas Electronics products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas Electronics product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult, lease evaluate the safety of the final products or systems manufactured by you 8. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. Please use Renesas Electronics products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Renesas Electronics assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations. 9. Renesas Electronics products and technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations. You should not use Renesas Electronics products or technology described in this document for any purpose relating to military applications or use by the military, including but not limited to the development of weapons of mass destruction. When exporting the Renesas Electronics products or technology described in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations 10. It is the responsibility of the buyer or distributor of Renesas Electronics products, who distributes, disposes of, or otherwise places the product with a third party, to notify such third party in advance of the contents and conditions set forth in this document, Renesas Electronics assumes no responsibility for any losses incurred by you or third parties as a result of unauthorized use of Renesas Electronics

products.

#### 11. This document may not be reproduced or duplicated in any form, in whole or in part, without prior written consent of Renesas Electronics.

- 12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products, or if you have any other inquiries.
- (Note 1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its majority-owned subsidiaries.
- (Note 2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.

Refer to "http://www.renesas.com/" for the latest and detailed information.

# RENESAS

#### SALES OFFICES

## Renesas Electronics Corporation

http://www.renesas.com

Renesas Electronics America Inc. 2801 Scott Boulevard Santa Clara, CA 95050-2549, U.S.A. Tel: +1-408-588-6000, Fax: +1-408-588-6130 Renesas Electronics Canada Limited 9251 Yonge Street, Suite 8309 Richmond Hill, Ontario Canada L4C 9T3 Tel: +1-905-237-2004 **Renesas Electronics Europe Limited** Dukes Meadow, Millboard Road, Bourne End, Buckinghamshire, SL8 5FH, U.K Tel: +44-1628-585-100, Fax: +44-1628-585-900 Renesas Electronics Europe GmbH Arcadiastrasse 10, 40472 Düsseldorf, German Tel: +49-211-6503-0, Fax: +49-211-6503-1327 Renesas Electronics (China) Co., Ltd. Room 1709, Quantum Plaza, No.27 ZhiChunLu Haidian District, Beijing 100191, P.R.China Tel: +88-10-8235-1155, Fax: +88-10-8235-7679 Renesas Electronics (Shanghai) Co., Ltd. Unit 301, Tower A, Central Towers, 555 Langao Road, Putuo District, Shanghai, P. R. China 200333 Tei: +86-21-2226-0888, Fax: +86-21-2226-0999 Renesas Electronics Hong Kong Limited Non-case Lectronics nong roug Limited Unit 1601-1611, 16/F., Tower 2, Grand Century Place, 193 Prince Edward Road West, Mongkok, Kowloon, Hong Kong Tel: +852-2265-6688, Fax: +852 2886-9022 Renesas Electronics Taiwan Co., Ltd. 13F, No. 363, Fu Shing North Road, Taipei 10543, Taiwan Tel: +886-2-8175-9600, Fax: +886 2-8175-9670 Renesas Electronics Singapore Pte. Ltd. 80 Bendemeer Road, Unit #06-02 Hyflux Innovation Centre, Singapore 339949 Tel: +55-631-30200, Fax: +65-6213-0300 1207, Block B, Menara Amcorp, Amcorp Trade Centre, No. 18, Jln Persiaran Barat, 46050 Petaling Jaya, Selangor Darul Ehsan, Malaysia +60-3-7955-9390, Fax: +60-3-7955-9510 Renesas Electronics Malaysia Sdn.Bhd. Unit 1207. Block B. Menara Amcorp. Amco Renesas Electronics India Pvt. Ltd. No.777C, 100 Feet Road, HAL II Stage, Indiranagar, Bangalore, India Tel: +91-80-67208700, Fax: +91-80-67208777 Renesas Electronics Korea Co., Ltd. 12F., 234 Teheran-ro, Gangnam-Gu, Seoul, 135-080, Korea Tel: +82-2-558-3737, Fax: +82-2-558-5141