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# R8C/10群

定时器X运行 (脉冲输出模式)

#### 1. 概要

本资料说明了定时器X的脉冲输出模式的使用例。脉冲输出模式的选择功能如表1所示。在此,对选择了 表1所示的〇符号后内容时的运行进行说明。

表1 脉冲输出模式的选择功能

设定项目	设定内容		
	0	从"H"电平开始输出	
CNTRo极性切换		从"L"电平开始输出	
		可编程输入/输出端口	
P30/CNRTo引脚功能	0	脉冲输出 (CNTRo输出的取反输出)	

#### 2. 前言

在本资料中说明的例子,适合以下单片机在下列条件下使用。

单片机 : R8C/10、R8C/11、R8C/12、R8C/13群

主时钟输入振荡频率 : 16MHz

和R8C/10群有相同SFR(外围控制寄存器)的其它的R8C/Tiny系列,也可以使用本程序。但有时会因增加一部分功能等情况而有所改变,所以必须通过手册进行确认。在使用本应用说明时必须进行充分的评价。

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#### 3. 脉冲输出模式的运行

对选择了表1所示的O符号后内容时的运行进行说明。

- (1) 如果将计数开始标志置"1", 计数器则对计数源进行递减计数。
- 从P17/INT1/CNTR0引脚输出"H"电平,从P30/CNTR0引脚输出"L"电平 (CNTR0的取反信号) (2)下溢时,重新装入再装入寄存器的内容,然后继续计数。同时,定时器X中断请求位变为"1"。并
  - 且,将INT1/CNTR0引脚和P30/CNTR0引脚的输出取反。
- (3)如果将计数开始标志清"0",计数器则保持计数值并停止。

脉冲输出模式运行时序如图1所示。



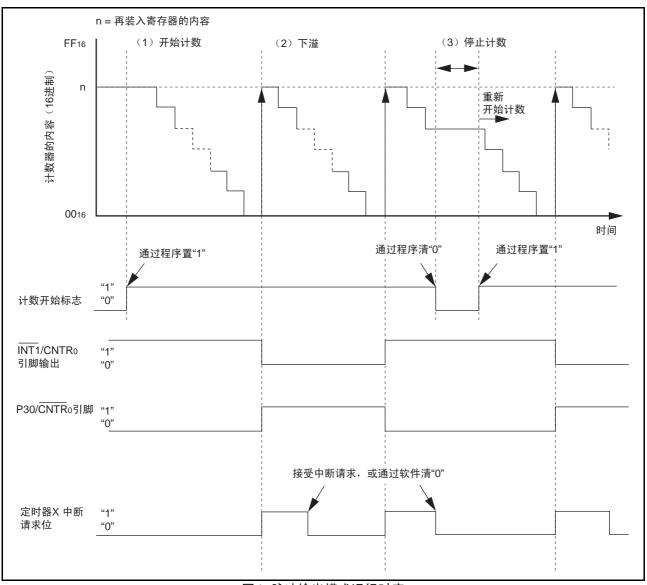


图1 脉冲输出模式运行时序



#### 4. 应用例

#### 4.1 应用例的说明

(1)定时器X每4ms产生一次下溢。

 $4ms = (1/f1) \times (预分频器X+1) \times (定时器X+1)$ 

= 62.5ns  $\times (255 + 1) \times (249 + 1)$ 

定时器X每下溢一次,就产生一次定时器X中断请求。通过程序对定时器X中断进行250次计数,就 会建立1秒的时序,并更新显示数据。

(2) LED 连接到端口 P11~P14,显示"L"有效电平。显示数据为0000b~1111b,并且每过1秒就加1。

(3)通过定时器X的上溢时序从CNTRo引脚和CNTRo引脚输出取反的脉冲信号。CNTRo引脚从"H"电平开始输出, CNTRo引脚从"L"电平开始输出。

使用的引脚如图2所示。

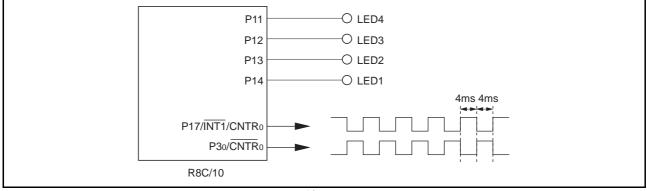
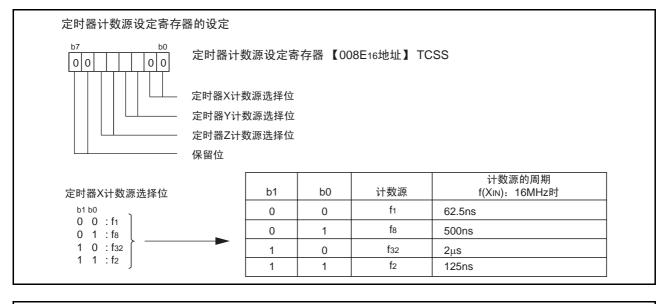


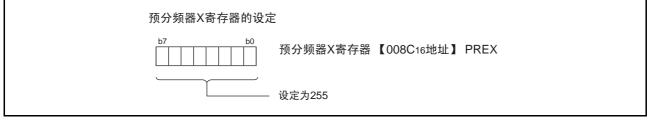
图2 使用的引脚

另外,本样本程序在SFR的位分配的情况下,有可能对不使用的功能位进行操作。这些设定值请根据用户 系统的使用情况进行设定。

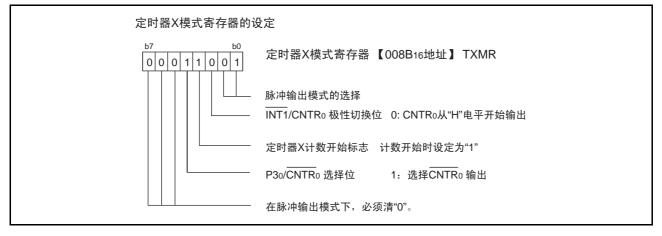


#### 4.2 主要寄存器的设定











## 4.3 流程图

res	set	
asm("FC	CLR I")	;禁止中断
prc0	= 1	;解除系统控制寄存器保护
cm13	5 = 1	;选择XIN-XOUT引脚
cm15	5 = 1	;选择XIN-XOUT 驱动能力:选择HIGH
cm05	5 = 0	;主时钟振荡
cm16	δ = 0	;无主时钟分频
cm17	r = 0	,无土可钟劳频
cm06	8 = 0	; 主时钟分频 CM16、 CM17 有效
no	p	
no	p	
no	qu	;等待主时钟振荡稳定
no	q	
ocd2	= 0	;选择主时钟
prc0	= 0	;系统控制寄存器保护
SFR的初	])始设定	;SFR的初始设定(端口初始设定●定时器设定)
sfr		、などの中間
asm("FS	SET I")	;允许中断



sfr_init			
p1 = p1 0x1e	; 端口P11~P14的初始设定		
pd1 = pd1 0x1e	;端口P11~P14方向位的初始设定		
txck0 = 0	]		
txck1 = 0	}		
prex = 256-1	∫ ;预分频器X的设定(15.9375ms)		
$tx = 250 \cdot 1$	; 定时器X的设定(4ms)		
	;定时裔A的设定(4ms) ;脉冲输出模式		
txmr = 0x11	; 於冲铜山侯式; ; 允许定时器X中断(优先级5)		
txic = 5			
timerX_data = 0	;清除数据		
timerX_count_10 = 0			
ir_txic = 0	;清除中断请求		
txs = 1	;定时器X计数开始		
(rts)			
timer_x			
timerX_count_10++	;建立1秒时序的计数器加法运算		
timerX_count_10 = 250 No	;是否经过1秒?		
Yes			
timerX_count_10 = 0	;清除计数器		
timerX_data++	;显示数据累加计数		
timerX_data &= 0x0f	;清除显示数据的高4位		

;显示数据左移1位(为了设定到P14~P11)

;设定掩模数据

;LED显示处理

; LED OFF

display\_data = timerX\_data << 1

display\_data = $\sim$ display\_data

p1 |= 0x1e

p1 &= display\_data



#### 5. 参考程序例

```
*
  File Name : main.c
Contents : R8C/10
                                                                     *
*
*
             : R8C/10 Timer X Pulse output mode test program
  Copyright, 2004 RENESAS TECHNOLOGY CORPORATION
              AND RENESAS SOLUTIONS CORPORATION, All rights reserved.
*
  Version
            : 1.10
+
  note
            : 0.01 : First version
             : 1.10(2004.08.23): Comment is revised
#include "sfr_r810.h"
                      /* Definition of the R8C/10 SFR */
/* Definition of RAM area */
unsigned int timerX_data;
unsigned int timerX_count_10;
/* Declaration of function prototype */
void sfr_init(void); /* Initial setting of SFR registers */
main() {
       asm("FCLR I");
                          /* Interrupt disable */
   /*_____
   -Change on-chip oscillator clock to Main clock -
   */
     prc0 = 1;
                          /* Protect off */
                          /* Xin Xout */
      cm13 = 1;
      cm15 = 1;
                          /* XCIN-XCOUT drive capacity select bit : HIGH */
      cm05 = 0;
                          /* Xin on */
                          /* Main clock = No division mode */
      cm16 = 0;
      cm17 = 0;
                          /* CM16 and CM17 enable */
      cm06 = 0;
      asm("nop");
                          /* Waiting for stable of oscillation */
      asm("nop");
      asm("nop");
      asm("nop");
      ocd2 = 0;
                          /* Main clock change */
      prc0 = 0;
                          /* Protect on */
      /*-----
      -Initialize SFR
       */
                          /* Initial setting of SFR registers */
      sfr_init();
      asm("FSET I");
                          /* Interrupt enable */
      /*_____
      -Loop of main
      -----*/
      while(1){
                          /* Main processing
      }
}
```



```
Name:
           sfr_init
Parameters:
          None
Returns:
          None
Description: Initial setting of SFR registers
***************
                                   void sfr_init(void){
     /* Setting port registers */
     p1 = p1 | 0x1e;
                                    /* P14-P11 = H(Led 4.3.2.1) */
     /* Setting port direction registers */
                                    /* P14-P11 port direction = output */
     pd1 = pd1 | 0x1e;
     txck0 = 0;
                                    /* Timer X count source = f1 */
     txck1 = 0;
      /* Setting main cycle timer */
     /* 16MHz * 1/1 * 256 * 250 = 4ms */
                                    /* Setting Prescaler X register */
      prex = 256 - 1i
     tx = 250-1;
                                    /* Setting timer X register */
     txmr = 0x11;
                                    /* Timer X : pulse output mode */
     txic = 5;
                                    /* Interrupt priority level = 5 */
     timerX_data = 0;
                                    /* RAM clear */
                                    /* RAM clear */
     timerX_count_10 = 0;
     ir_txic = 0;
                                    /* interrupt request clear */
     txs = 1;
                                    /* Timer X count start flag = start */
}
interrupt Timer X
Name:
Parameters: None
          None
Returns:
Description:
           Timer X
#pragma interrupt timer_x
void timer_x(void){
      unsigned int display_data;
      timerX_count_10++;
                                    /* 1 second counter increment */
      if ( timerX_count_10 == 250 ) {
                                    /* 1 second have passed ? */
                                    /* 1 second counter clear */
         timerX_count_10 = 0;
                                   /* Display data increment */
         timerX_data++;
                                   /* Display data mask */
         timerX_data &= 0x0f;
        /* LED Clear */
         p1 |= 0x1e;
        p1 &= display_data;
                                   /* LED On */
     }
}
```



# 6. 参考文档

硬件手册 R8C/10群硬件手册 (最新版请从瑞萨科技公司主页获取。)



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- 10. 本公司一直致力于提高产品的质量和可靠性,但一般来说,半导体产品总会以一定的概率发生故障、或者由于使用条件不同而出现错误运行等。为了避免因本公司的产品发生故障或者错误运行而导致人身事故和火灾或造成社会性的损失,希望客户能自行负责进行冗余设计、采取延烧对策及进行防止错误运行等的安全设计(包括硬件和软件两方面的设计)以及老化处理等,这是作为机器和系统的出厂保证。特别是单片机的软件,由于单独进行验证很困难,所以要求在顾客制造的最终的机器及系统上进行安全检验工作。
- 11. 如果把本资料所记载的产品从其载体设备上卸下,有可能造成婴儿误吞的危险。顾客在将本公司产品安装到 顾客的设备上时,请顾客自行负责将本公司产品设置为不容易剥落的安全设计。如果从顾客的设备上剥落而 造成事故时,本公司将不承担任何责任。
- 12. 在未得到本公司的事先书面认可时,不可将本资料的一部分或者全部转载或者复制。
- 13. 如果需要了解关于本资料的详细内容,或者有其他关心的问题,请向本公司的营业窗口咨询。

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