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April 1st, 2010
Renesas Electronics Corporation

Issued by: Renesas Electronics Corporation (<http://www.renesas.com>)

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Application Note

μPD780058 Subseries

8-bit Single-Chip Microcontrollers

DA Converter in Normal Mode

μPD780053

μPD780054

μPD780055

μPD780056

μPD780058B

μPD78F0058

[MEMO]

NOTES FOR CMOS DEVICES

1. PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

2. HANDLING OF UNUSED INPUT PINS FOR CMOS

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

3. STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

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Contents

(A)	FEATURES OF THE DA CONVERTER	6
(B)	PROGRAM DESCRIPTION	6
(C)	PROGRAM SPECIFICATIONS	6
(D)	USED PINS.....	6
(E)	SOFTWARE FLOW CHART	7
(F)	SOFTWARE LISTING	8

(A) Features of the DA Converter

The 8-bit D/A converter in the μ PD7805x/78005x subseries can be used in normal output mode or real-time output mode.

(B) Program Description

This program demonstrates the D/A converter in normal mode, where the conversion result is output immediately after the conversion is completed. The program outputs a voltage ladder with 0-, 1-, 2-, 3-, 4- and 5-volt steps. After reaching the 5-volt step, the program starts outputting from 0 volts again. Each step is 36 μ s (Assembly program) or 170 μ s (C program) long.

(C) Program Specifications

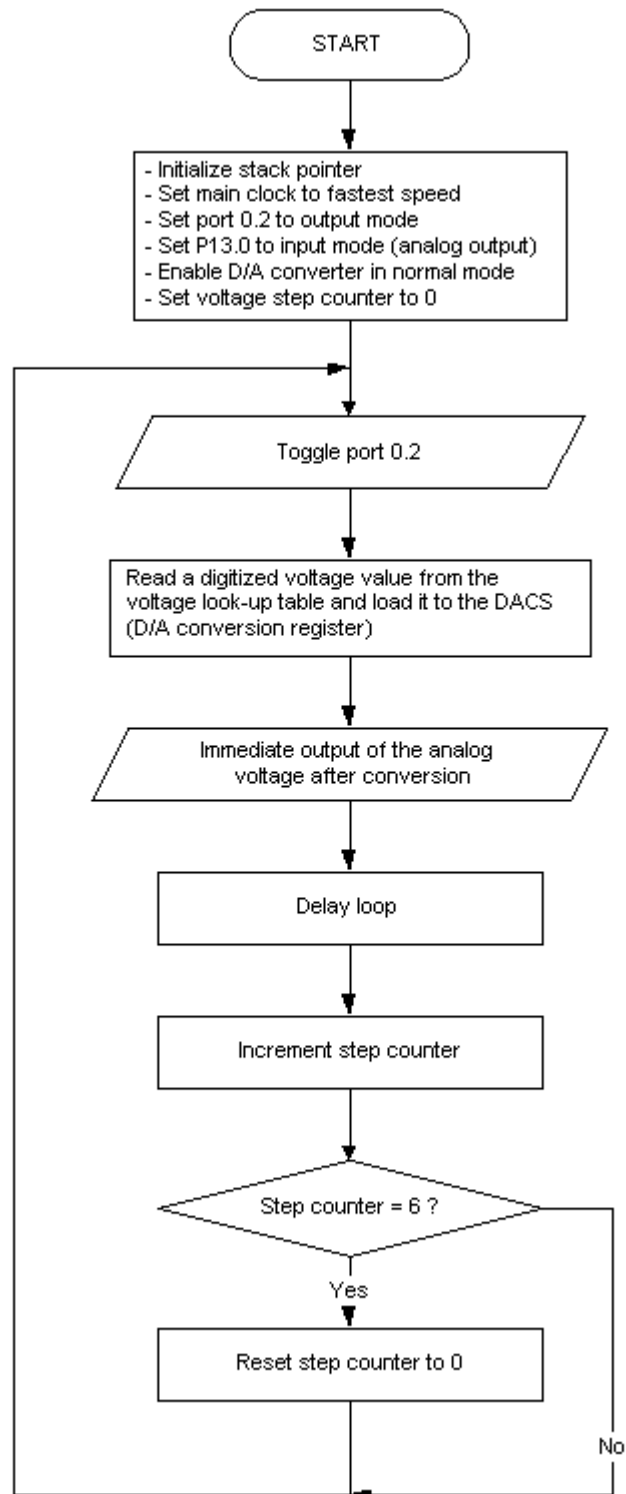
- D/A converter channel 0 in normal output mode
- D/A output triggered after conversion is completed
- D/A outputs analog voltages from 0 to 5 volts in 1-volt steps

(D) Used pins

- P02/INTP2: toggles every time, a new analog voltage is output
- ANO0/P130: outputs the analog voltage from D/A converter

(E) Software Flow Chart

Flowchart - Main Program



(F) Software Listing

```
/******  
; Date:    11/15/2002  
;  
;  
; Parameters: - CPU clock  
;              (fx = 5 MHz; 1 CPU clock cycle = 200 ns)  
;  
;              - 8-bit D/A channel 0  
;  
;              - Normal output operation mode (Writing to DACS0 register)  
;  
;              - Output ladder voltage:  0 V, 1 V, 2 V, 3 V, 4 V, 5 V, 0 V, ...  
;  
;              - Output ladder frequency: 2.9 kHz (each step is 170 µs)  
;  
;              - Reference voltages:    5 V (must be attached to Vref1 pin)  
;              - Port 0.2:              Toggles before each conversion  
;*****/  
;  
  
/*=====  
; Include Files  
;=====*/  
  
#include <in78000.h>  
#include "DF0058.h"  
  
/*=====  
; Constants/Variables      =  
;=====*/  
  
#define TRUE  1  
#define FALSE 0  
#define Vref1  5          /* Reference voltage value */  
#define Volts(n) 255 * n / Vref1  
  
const unsigned char VoltageTable[] =  
{  
    Volts(0),          /* 0 Volt */  
    Volts(1),          /* 1 Volt */  
    Volts(2),          /* 2 Volt */  
    Volts(3),          /* 3 Volt */  
    Volts(4),          /* 4 Volt */  
    Volts(5),          /* 5 Volt */  
};  
  
unsigned char StepCounter;    /* Voltage output step counter */  
unsigned char i;              /* Variable for delay loop */
```

```

/*=====
;               Main Program               =
;=====*/
void main(void)
{
    OSMS = 0x01;          /* Don't use scaler */
    PCC = 0x00;           /* Main system clock at fastest setting */
    P0.2 = 0;             /* Latch port 0.2 low */
    PM0.2 = 0;            /* Set port 0.2 to output mode */
    P13.1 = 0;            /* Latch port 13.1 to low */
    PM13.1 = 0;           /* Set port 13.1 to output mode */
    PM13.0 = 1;           /* Set port 13.0 to input mode
                          (analog output) */
    DAM = 0x01;           /* Enable D/A conversion in normal mode */
    StepCounter = 0;      /* Set voltage output step counter to 0 */

    while(TRUE)          /* Loop here */
    {
        P0 ^= 0x04;       /* Toggle port 0.2 */
        DACS0 = VoltageTable[StepCounter]; /* Output current step */
        for(i=1; i<20; i++); /* Delay loop for conversion time */
        StepCounter++;     /* increment step counter */
        if(StepCounter == sizeof VoltageTable ) /* Test max. step counter */
            StepCounter = 0; /* clear step counter */
    }                      /* end of while(TRUE) loop */
}                          /* end of function main() */

```

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