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Application Note

78K0S/Kx1+

Sample Program (Low-Voltage Detection)

Reset Generation During Detection at Less than 2.7 V

This document describes an operation overview of the sample program, as well as how to use the sample program and how to set and use the low-voltage detection function. In the sample program, an internal reset (LVI reset) signal is generated by detecting that V_{DD} is less than V_{LVI} ($V_{LVI} = 2.85 \text{ V} \pm 0.15 \text{ V}$). With an LVI reset, the LED display data immediately before the reset is retained and LED output is restored after reset release.

Target devices

78K0S/KA1+ microcontroller 78K0S/KB1+ microcontroller 78K0S/KU1+ microcontroller 78K0S/KY1+ microcontroller

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M8E 02.11-1

CHAPTER 1 OVERVIEW

In this sample program, an example of using the low-voltage detection (LVI) function is presented.

An LVI circuit is set to generate an internal reset (LVI reset) signal by detecting that V_{DD} is less than V_{LVI} ($V_{LVI} = 2.85$ V ± 0.15 V).

After completion of the initial settings, an LED lighting pattern is displayed according to the number of switch inputs, by detecting the falling edge of the switch input and performing interrupt servicing. (This processing is the same as that described in the Sample Program (Interrupt).)

When a reset is generated by other than LVI, the program is used to initialize the number of switch inputs. When an LVI reset is generated, the number of switch inputs immediately before reset generation is restored and an LED lighting pattern is displayed accordingly after LVI reset release, because RAM retains the data immediately before the reset, unless it falls below the POC voltage.

1.1 Main Contents of Initial Settings

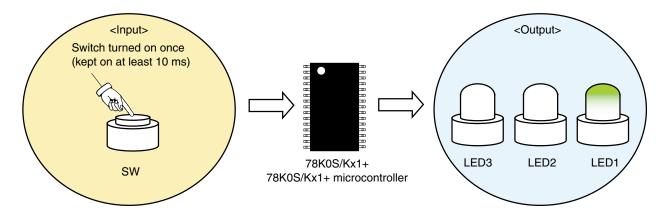
The contents of the initial settings are as follows.

- Selecting the high-speed internal oscillator as the system clock source^{Note}
- · Stopping watchdog timer operation
- Setting V_{LVI} (low-voltage detection voltage) to 2.85 V ± 0.15 V.
- Generating an internal reset (LVI reset) signal when it is detected that VDD is less than VLVI, after VDD (power supply voltage) becomes greater than or equal to VLVI.
- Setting the CPU clock frequency to 4 MHz
- · Setting I/O ports
- Setting the valid edge of INTP1 (external interrupt) to the falling edge
- Enabling interrupt

Note This is set by using the option byte.

1.2 Contents Following the Main Loop

Interrupt servicing is performed by detecting the falling edge of the INTP1 pin, caused by switch input. In interrupt servicing, the LED lighting pattern is changed by confirming that the switch is on, after about 10 ms have elapsed after the falling edge of the INTP1 pin was detected. If the switch is off, after about 10 ms have elapsed, processing is identified as chattering and the LED lighting pattern is not changed.



Number of Switch	LED Output			
Inputs ^{Note}	LED3	LED2	LED1	
0	OFF	OFF	OFF	
1	OFF	OFF	ON	
2	OFF	ON	OFF	
3	OFF	ON	ON	
4	ON	OFF	OFF	
5	ON	OFF	ON	
6	ON	ON	OFF	
7	ON	ON	ON	

Note The lighting patterns from the zeroth switch input are repeated after the eighth switch input.

Caution For cautions when using the device, refer to the user's manual of each product (<u>78K0S/KU1+</u>, <u>78K0S/KY1+</u>, <u>78K0S/KA1+</u>, <u>78K0S/KB1+</u>).



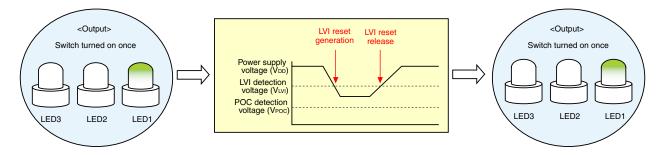
[Column] Chattering

Chattering is a phenomenon in which the electric signal repeats turning on and off due to a mechanical flip-flop of the contacts, immediately after the switch has been pressed.

1.3 Content of the Low-Voltage Detection (LVI) Function

In this sample program, an internal reset (LVI reset) is generated by the low-voltage detection (LVI) function when V_{DD} becomes less than V_{LVI}. At this time, register values are initialized, but RAM retains the data immediately before the reset, unless it falls below the POC voltage. The number of switch inputs immediately before the reset is retained, the number of switch inputs is restored after reset release, and an LED lighting pattern can therefore be displayed accordingly when an LVI reset is generated^{Note}. When a reset is generated by other than LVI, the program is used to initialize the number of switch inputs and all LEDs are turned off.

Note As mentioned in [Column] below, when a standard startup routine is used in a C language program, RAM data is initialized before the main function. To avoid this, a section of the standard startup routine is commented out in this C language version sample program, so that RAM data without initial values is not initialized (cleared to 0).





[Column] Processing of the startup routine

A standard startup routine mainly performs the following processing.

- · Stack pointer setting
- Hardware initialization (needed to be performed at an early stage)
- Initialization of variables to be used with a library
- Transferring from ROM to RAM the initial values of external variables with initial values, and sreg variables
- Assigning 0 to RAM of external variables without initial values, and sreg variables Note

Note This processing is commented out in the source file (cstart.asm) of the startup routine included in this C language version sample program.

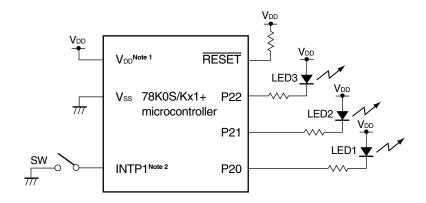
For details, refer to the chapter regarding the startup routine of the <u>CC78K0S C Compiler Operation</u> <u>User's Manual</u>.

CHAPTER 2 CIRCUIT DIAGRAM

This chapter describes a circuit diagram and the peripheral hardware to be used in this sample program.

2.1 Circuit Diagram

A circuit diagram is shown below.



- **Notes 1.** Use this in a voltage range of $3.0 \text{ V} \le \text{V}_{DD} \le 5.5 \text{ V}$.
 - 2. INTP1/P43: 78K0S/KA1+ and 78K0S/KB1+ microcontrollers INTP1/P32: 78K0S/KY1+ and 78K0S/KU1+ microcontrollers
- Cautions 1. Connect the AVREF pin directly to VDD (only for the 78K0S/KA1+ and 78K0S/KB1+ microcontrollers).
 - 2. Connect the AVss pin directly to GND (only for the 78K0S/KB1+ microcontroller).
 - 3. Leave all unused pins open (unconnected), except for the pins shown in the circuit diagram and the AVREF and AVss pins.

2.2 Peripheral Hardware

The peripheral hardware to be used is shown below.

(1) Switch (SW)

A switch is used as an input to control the lighting of an LED.

(2) LEDs (LED1, LED2, LED3)

The LEDs are used as outputs corresponding to switch inputs.

CHAPTER 3 SOFTWARE

This chapter describes the file configuration of the compressed file to be downloaded, internal peripheral functions of the microcontroller to be used, and initial settings and operation overview of the sample program, and shows a flow chart.

3.1 File Configuration

The following table shows the file configuration of the compressed file to be downloaded.

(1) Assembly language version

File Name	Description	Compressed (*.zip) File Included	
			₽M 32
main.asm	Source file for hardware initialization processing and main processing of microcontroller	•	•
op.asm	Assembler source file for setting the option byte (sets the system clock source)	•	•
lvi.prw	Work space file for integrated development environment PM+		•
lvi.prj	Project file for integrated development environment PM+		•

(2) C language version

File Name	Description	Compressed (*.2	zip) File Included
			₽M 132
main.c	Source file for hardware initialization processing and main processing of microcontroller	•	•
op.asm	Assembler source file for setting the option byte (sets the system clock source)		•
cstart.asm	Startup routine source file (comments out a section of ROM processing)		•
def.inc	Library type setting file (include file of "cstart.asm")	(include file of "cstart.asm")	
macro.inc	Macro definition file regarding various template patterns (include file of "cstart.asm") ■ ■		•
lvi.prw	Work space file for integrated development environment PM+ ●		•
lvi.prj	Project file for integrated development environment PM+		•

Remark



: Only the source files are included.



: The files to be used with integrated development environment PM+ are included.

3.2 Internal Peripheral Functions to Be Used

The following internal peripheral functions of the microcontroller are used in this sample program.

V_{DD} < V_{LVI} detection: Low-voltage detector (LVI)
 Switch input: INTP1^{Note} (external interrupt)
 LED outputs: P20, P21, P22 (output ports)

Note INTP1/P43: 78K0S/KA1+ and 78K0S/KB1+ microcontrollers INTP1/P32: 78K0S/KY1+ and 78K0S/KU1+ microcontrollers

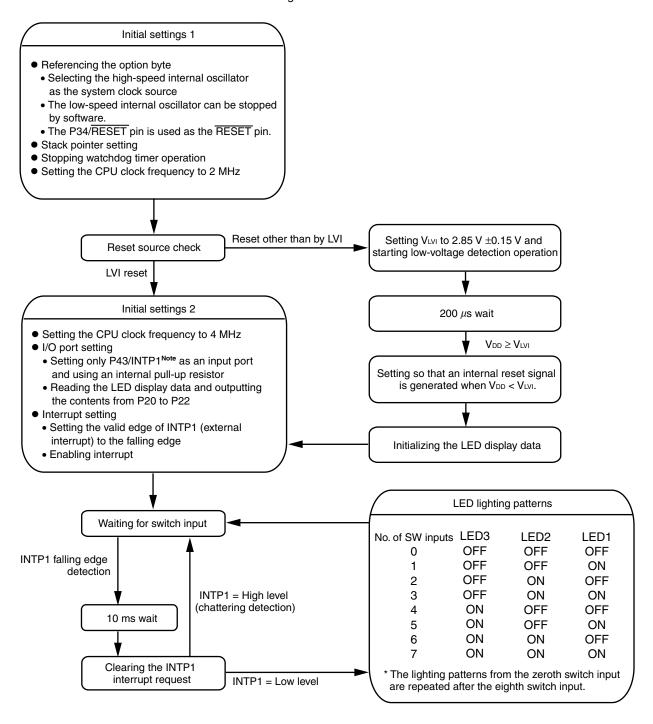
3.3 Initial Settings and Operation Overview

In this sample program, the selection of the clock frequency, setting of the I/O ports, setting of interrupt, setting of LVI, and the like are performed in the initial settings.

After completion of the initial settings, interrupt servicing is performed by detecting the falling edge of the switch input (SW) and the lighting of the three LEDs (LED1, LED2, and LED3) is controlled according to the number of switch inputs. (This processing is the same as that described in the Sample Program (Interrupt).)

When a reset is generated by other than LVI, the program is used to initialize the number of switch inputs. When an LVI reset is generated, the number of switch inputs immediately before reset generation is restored and an LED lighting pattern is displayed accordingly after LVI reset release, because RAM retains the data immediately before the reset, unless it falls below the POC voltage.

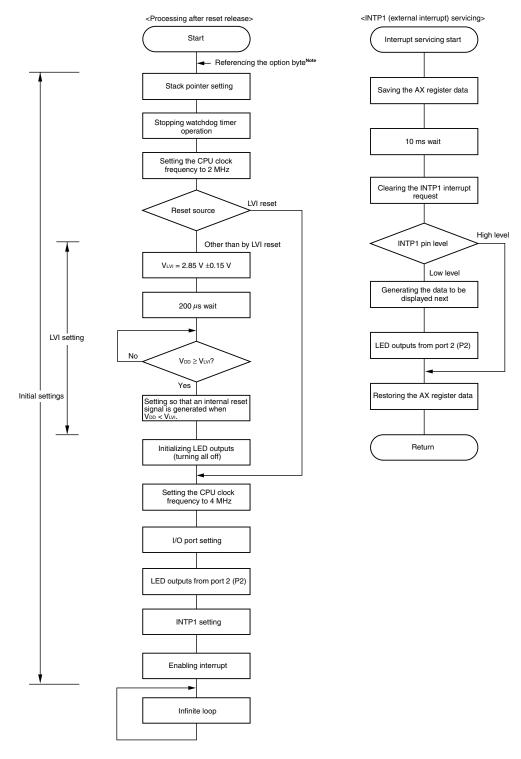
The details are described in the state transition diagram shown below.



Note INTP1/P43: 78K0S/KA1+ and 78K0S/KB1+ microcontrollers INTP1/P32: 78K0S/KY1+ and 78K0S/KU1+ microcontrollers

3.4 Flow Chart

A flow chart for the sample program is shown below.



Note Referencing the option byte is automatically performed by the microcontroller after reset release. In this sample program, the following contents are set by referencing the option byte.

- Using the high-speed internal oscillation clock (8 MHz (TYP.)) as the system clock source
- The low-speed internal oscillator can be stopped by using software
- Using the P34/RESET pin as the RESET pin

CHAPTER 4 SETTING METHODS

This chapter describes the low-voltage detection function.

For other initial settings, refer to the <u>78K0S/Kx1+ Sample Program (Initial Settings) LED Lighting Switch Control Application Note</u>. For interrupt, refer to the <u>78K0S/Kx1+ Sample Program (Interrupt) External Interrupt Generated by Switch Input Application Note</u>.

For how to set registers, refer to the user's manual of each product (<u>78K0S/KU1+</u>, <u>78K0S/KY1+</u>, <u>78K0S/KB1+</u>).

For assembler instructions, refer to the **78K/0S Series Instructions User's Manual**.

4.1 Low-Voltage Detection (LVI) Function Setting

The low-voltage detection function has the following two types of operation modes.

- Using it as a reset (see [Example 1])
- Using it as an interrupt (see [Example 2])

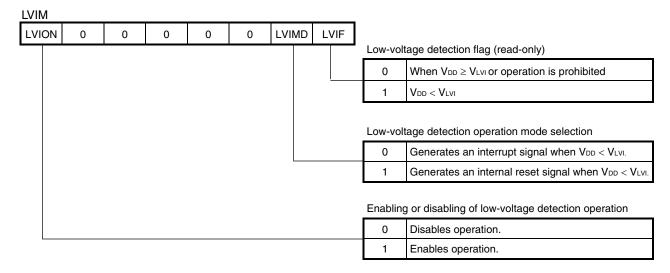
The low-voltage detection function is mainly controlled by the following two types of registers.

- Low-voltage detection register (LVIM)
- Low-voltage detection level select register (LVIS)

(1) Settings regarding low-voltage detection operation

The low-voltage detection register (LVIM) is used to set the low-voltage detection operation mode and control the operation.

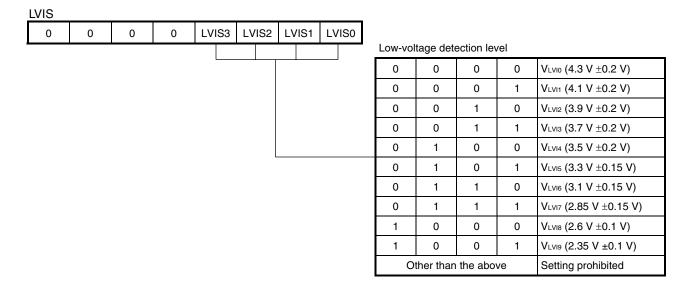
Figure 4-1. Format of Low-Voltage Detection Register (LVIM)



(2) Settings regarding the low-voltage detection level

The low-voltage detection level select register (LVIS) is used to set the low-voltage detection level.

Figure 4-2. Format of Low-Voltage Detection Level Select Register (LVIS)

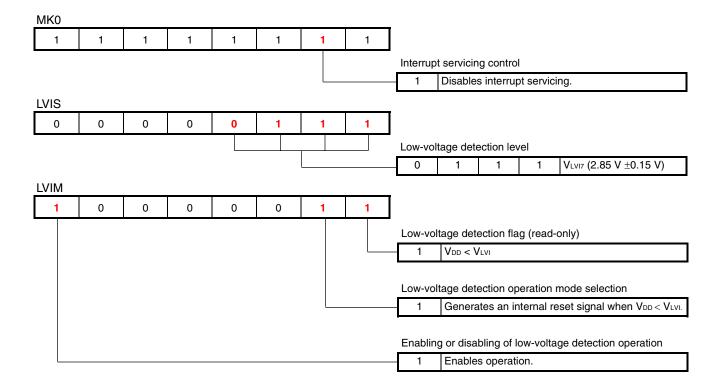


[Example 1] Using the low-voltage detection function as a reset by setting the low-voltage detection level (V_{LVI}) to 2.85 V \pm 0.15 V (same content as the sample program)

- Setting procedure
 - <1> Mask the LVI interrupt (LVIMK = 1) Note.
- <2> Set the detection level by using bits 3 to 0 (LVIS3 to LVIS0) of the LVIS register.
- <3> Enable LVI operation by setting bit 7 (LVION) of the LVIM register to 1.
- <4> Use software to wait at least 200 μ s.
- <5> Use bit 0 (LVIF) of the LVIM register to wait until " $V_{DD} \ge V_{LVI}$ (LVIF = 0)" can be confirmed.
- <6> Set bit 1 (LVIMD) of the LVIM register to 1, so that an internal reset signal is generated when LVI is detected.

Note The settings for the sample program and the program example on the next page are omitted, because the LVI interrupt is masked after the reset.

Remark <2> to <6> mentioned above correspond to <2> to <6> on the next page.



• Assembly language program example (same content as the sample program)

```
XMAIN CSEG
                       UNIT
       RESET_START:
<2>
                       LVIS, #00000111B ; Set the low-voltage detection level (VLVI) to 2.85 V +-0.15 V
               MOV
               SET1
                       LVION
                                               ; Enable the low-voltage detector operation
<3>
               MOV
                       Α,
                               #40
                                               ; Assign the 200 us wait count value
       WAIT_200US:
<4>
               DEC
                       $WAIT_200US
                                               0.5[us/clk] \times 10[clk] \times 40[count] = 200[us]
               BNZ
       WAIT LVI:
               NOP
               BT
                       LVIF, $WAIT_LVI
                                               ; Branch if VDD < VLVI
<5>
<6>
               SET1
                       LVIMD
                                               ; Set so that an internal reset signal is generated when VDD < VLVI
```

• C language program example (same content as the sample program)

```
void hdwinit(void){
              unsigned char ucCnt200us; /* 8-bit variable for 200 us wait */
<2>
                      LVIS = 0b00000111; /* Set the low-voltage detection level (VLVI) to 2.85 V +-0.15 V
      * /
<3>
                      LVION = 1;
                                             /* Enable the low-voltage detector operation */
                      for (ucCnt200us = 0; ucCnt200us < 9; ucCnt200us++) \{ /* Wait of about 200 us */
<4>
                             NOP();
                      while (LVIF) {
                                             /* Wait for VDD >= VLVI */
<5>
                             NOP();
<6>
                      LVIMD = 1;
                                             /* Set so that an internal reset signal is generated when VDD < VLVI */
```

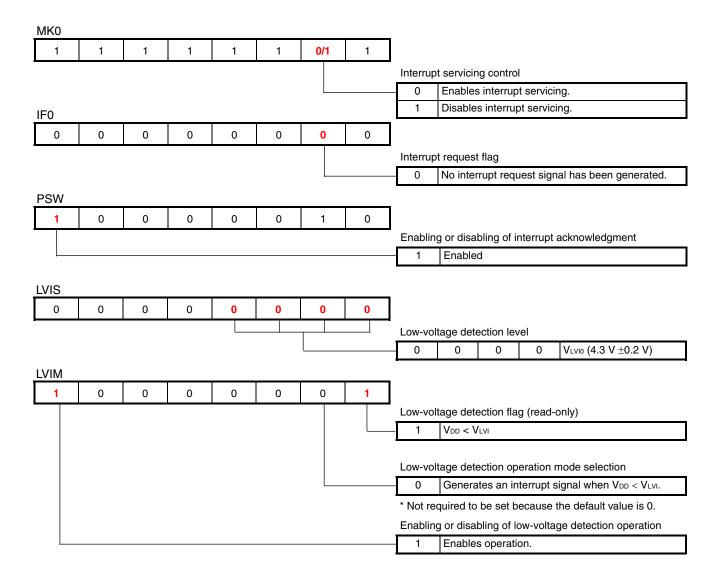
- **Remarks 1.** As in the sample program, the above-mentioned wait time (200 μ s) is calculated with fcpu (CPU clock frequency) being 2 MHz.
 - 2. <2> to <6> mentioned above correspond to <2> to <6> on the previous page.

[Example 2] Using the low-voltage detection function as an interrupt by setting the low-voltage detection level (V_{LVI}) to $4.3~V~\pm0.2~V$.

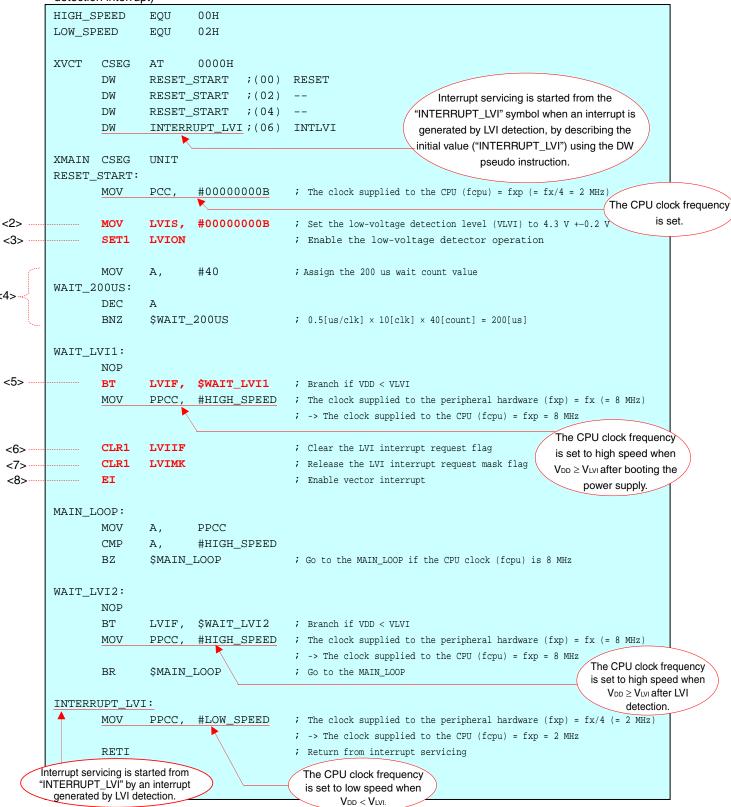
- Setting procedure
 - <1> Mask the LVI interrupt (LVIMK = 1) Note.
 - <2> Set the detection level by using bits 3 to 0 (LVIS3 to LVIS0) of the LVIS register.
 - <3> Enable LVI operation by setting bit 7 (LVION) of the LVIM register to 1.
 - <4> Use software to wait at least 200 μ s.
 - <5> Use bit 0 (LVIF) of the LVIM register to wait until "VDD ≥ VLVI (LVIF = 0)" can be confirmed.
 - <6> Clear the interrupt request flag of LVI (LVIIF = 0).
 - <7> Release the interrupt mask flag of LVI (LVIMK = 0).
 - <8> Execute the EI instruction (when using vector interrupts).

Note The settings for the program example shown below are omitted, because the LVI interrupt is masked after the reset.

Remark <2> to <8> mentioned above correspond to <2> to <8> on the next page and the page after next.



 Assembly language program example (setting the CPU clock frequency to low speed by using a low-voltage detection interrupt)



Remarks 1. The above-mentioned wait time (200 μs) and CPU clock frequency are calculated with fx (system clock oscillation frequency) being 8 MHz.

2. <2> to <8> mentioned above correspond to <2> to <8> on the previous page.

• C language program example (setting the CPU clock frequency to low speed by using a low-voltage detection interrupt)

```
SFR
                                                             /* SFR names can be described at the C source level */
       #pragma
       #pragma
                         ΕI
                                                             /* EI instructions can be described at the C source level */
                         NOP
                                                             /* NOP instructions can be described at the C source level */
       #pragma
       #pragma interrupt INTLVI fn_intlvi
                                                             /* Interrupt function declaration: INTLVI */
                                                                       Interrupt servicing is started from the interrupt function
                         HighSpeed 0x00
       #define
                                                                      declared with the _interrupt modifier when an interrupt is
                                                                        generated, by declaring the INTLVI interrupt function
       #define
                         LowSpeed 0x02
                                                                      ("fn_intlvi" in this example) in the preprocessing directive
                                                                       (#pragma directive) and declaring that interrupt function
       void hdwinit(void){
                                                                                  using the _interrupt modifier.
                        = 0b00000000; /* The clock supplied to the CPU (fcpu) = fxp (= fx/4 = 2 MHz) */
                                                                                                                 The CPU clock
<2>
                                                                                                                 frequency is set.
                LVIS = 0b00000000; /* Set the low-voltage detection level (VLVI) to 4.3 V +-0.2 V */
<3>
                                           /* Enable the low-voltage detector operation */
                for (ucCnt200us = 0; ucCnt200us < 9; ucCnt200us++){    /* Wait of about 200 us */
<4×
                         NOP();
<5>
                while (LVIF){
                                           /* Wait for VDD >= VLVI */
                         NOP();
                PPCC = HighSpeed;
                                           /* The clock supplied to the peripheral hardware (fxp) = fx (= 8 MHz)
                                               -> The clock supplied to the CPU (fcpu) = fxp = 8 MHz */
                                                                                                      The CPU clock frequency
<6>
                LVIIF = 0;
                                           /* Clear the LVI interrupt request flag */
                                                                                                      is set to high speed when
               LVIMK = 0;
                                           /* Release the LVI interrupt request mask flag */
<7>
                                                                                                      V_{DD} \ge V_{LVI} after booting the
                                           /* Enable vector interrupt */
                EI();
<8>
                                                                                                           power supply.
                return;
       void main(void){
               while (1)
                         while (PPCC == HighSpeed) { /* Wait for LVI interrupt */
                                  NOP();
                         while (LVIF) {
                                                    /* Wait for VDD >= VLVI */
                                  NOP();
                         PPCC = HighSpeed;
                                                    /* The clock supplied to the peripheral hardware (fxp) = fx (= 8 MHz)
                                                        -> The clock supplied to the CPU (fcpu) = fxp = 8 MHz
                                                                                                              The CPU clock
                                                                                                           frequency is set to high
                                                                                                           speed when V_{DD} \ge V_{LVI}
                                                                                                             after LVI detection.
          interrupt void fn_intlvi(){
               PPCC = LowSpeed;
                                                    /* The clock supplied to the peripheral hardware (fxp) = fx/4 (= 2 MHz)
                                                        -> The clock supplied to the CPU (fcpu) = fxp = 2 MHz */
                return;
                                                                 The CPU clock frequency
               Interrupt servicing is started from
                                                                 is set to low speed when
             "fn_intlvi" by an interrupt generated by
                                                                        V_{\text{DD}} < V_{\text{LVI}}
                        LVI detection.
```

Remarks 1. The above-mentioned wait time (200 μ s) and CPU clock frequency are calculated with fx (system clock oscillation frequency) being 8 MHz.

2. <2> to <8> mentioned above correspond to <2> to <8> on page 15.

CHAPTER 5 OPERATION CHECK USING THE DEVICE

This chapter describes the flow from building to the operation check using the device, using the downloaded sample program.

<R> 5.1 Building the Sample Program

This section describes how to build sample programs, using the assembly language version sample program (source files + project file) downloaded by clicking the icon and the C language version sample program (only source files) downloaded by clicking the icon. For how to build other downloaded programs, refer to 78KOS/Kx1+ Sample Program Startup Guide Application Note.

For the details of how to operate PM+, refer to the PM+ Project Manager User's Manual.



[Column] Build errors

Change the compiler option setting according to the following procedure when the error message "A006 File not found 'C:\NECTOOLS32\LIB78K0S\s0sl.rel'" or "*** ERROR F206 Segment '@@DATA' can't allocate to memory - ignored." is displayed, when building with PM+.

- <1> Select [Compiler Options] from the [Tool] menu.
- <2> The [Compiler Options] dialog box will be displayed. Select the [Startup Routine] tab.
- <3> Uncheck the [Using Fixed Area of Standard Library] check box. (Leave the other check boxes as they are.)

A RAM area of 118 bytes that has been secured as a fixed standard library area will be enabled for use when the [Using Fixed Area of Standard Library] check box is unchecked; however, the standard libraries (such as the getchar function and malloc function) will be disabled for use.

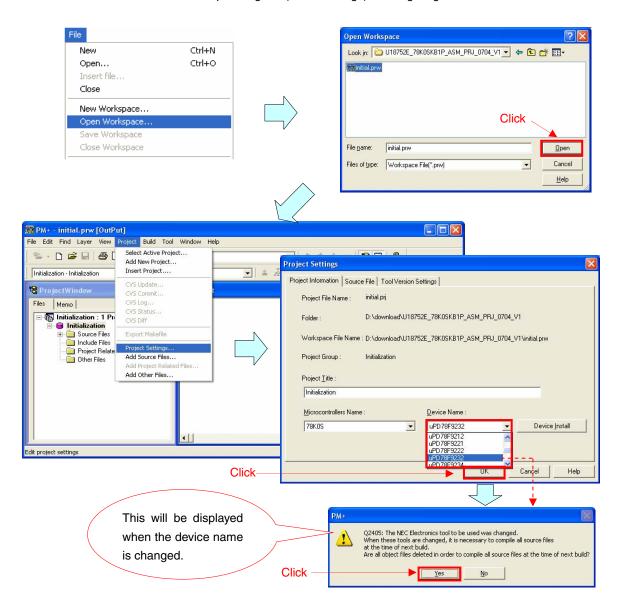
The [Using Fixed Area of Standard Library] check box is unchecked by default when the file that has been downloaded by clicking the icon is used in this sample program.

5.1.1 Assembly language version (source files + project file)

This section describes how to build a sample program, using the assembly language version file of the 78K0S/KB1+ microcontroller sample program (low-voltage detection) downloaded by clicking the icon.

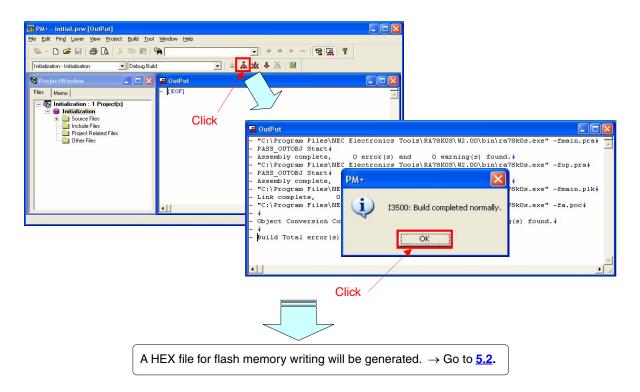
- (1) Start PM+.
- (2) Select "Ivi.prw" by clicking [Open Workspace] from the [File] menu and click [Open]. A workspace into which the source file will be automatically read will be created.
- (3) Select [Project Settings] from the [Project] menu. When the [Project Settings] window opens, select the name of the device to be used (the device with the largest ROM or RAM size will be selected by default), and click [OK].

Remark Screenshots of the Sample Program (Initial Settings) LED Lighting Switch Control are shown below.



- (4) Click [Build] button). When the source files are built normally, the message "I3500: Build completed normally," will be displayed.
- (5) Click the [OK] button in the message window. A HEX file for flash memory writing will be created.

Remark Screenshots of the Sample Program (Initial Settings) LED Lighting Switch Control are shown below.

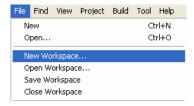


5.1.2 C language version (only source files)

This section describes how to build a sample program, using the C language version file of the 78K0S/KB1+ microcontroller sample program (low-voltage detection) downloaded by clicking the icon.

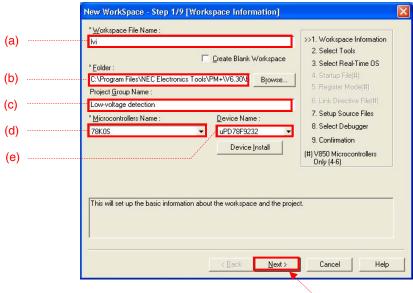
The C language version of this sample program includes the startup routine source file "cstart.asm", library type setting file "def.inc", and macro definition file "macro.inc", besides "main.c" and "op.asm". These files correspond to sections commented out from the standard startup routine. To create a PM+ project by applying these files, operations different from those for other C language version sample programs are required. The procedure is described below.

- · Project registration
 - (1) Start PM+.
 - (2) Select [New Workspace] from the [File] menu.



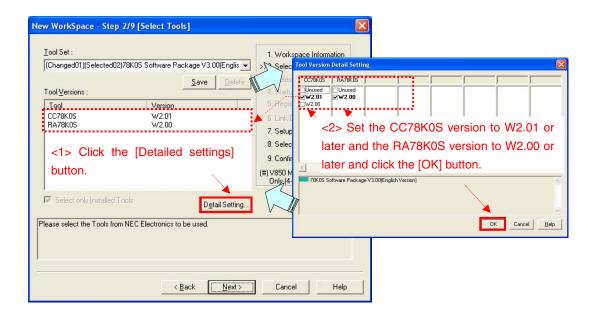
- (3) The [New WorkSpace Step 1/9 [Workspace Information]] dialog box will be displayed. Set the following items.
 - (a) Workspace File Name ("Ivi" is entered as the file name in this example.)
 - (b) Folder (An arbitrarily created "work" folder located under the default folder ("bin" folder in which PM+ exists) is specified in this example.)
 - (c) Project Group Name ("Low-voltage detection" is entered as the group name in this example.)
 - (d) Series Name ("78K0S" is selected as the series name in this example.)
 - (e) Device Name (The 78K0S/KB1+ microcontroller product "uPD78F9232" is set in this example.)

After setting items (a) to (e), click the [Next] button.

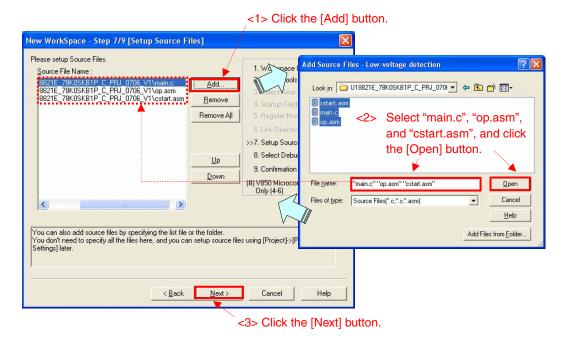


Click after setting (a) to (e)

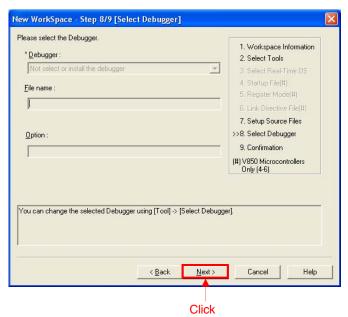
- (4) The [New WorkSpace Step 2/9 [Select tools]] dialog box will be displayed. Specify the tools to be used and their versions via the following procedure.
 - <1> Click the [Detailed settings] button.
 - <2> The [Detailed tool version settings] dialog box will be displayed. Set the CC78K0S version to W2.01 or later and the RA78K0S version to W2.00 or later and click the [OK] button.
 - <3> The tools selected in step <2> and their versions will be set. Click the [Next] button.



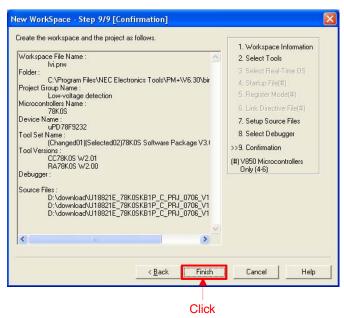
- (5) The [New WorkSpace Step 7/9 [Setup Source Files]] dialog box will be displayed. Set the source files in the order of the following procedure.
 - <1> Click the [Add] button.
 - <2> The [Add Source Files] dialog box will be displayed. Select the following source files and click the [Open] button.
 - main.c
 - op.asm
 - cstart.asm
 - <3> The source files selected in step <2> will be set. Click the [Next] button.



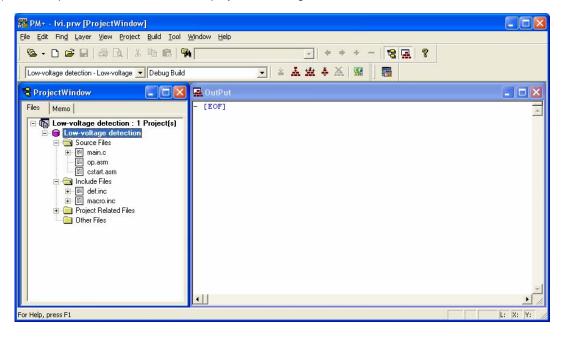
(6) The [New WorkSpace - Step 8/9 [Select Debugger]] dialog box will be displayed. Click the [Next] button.



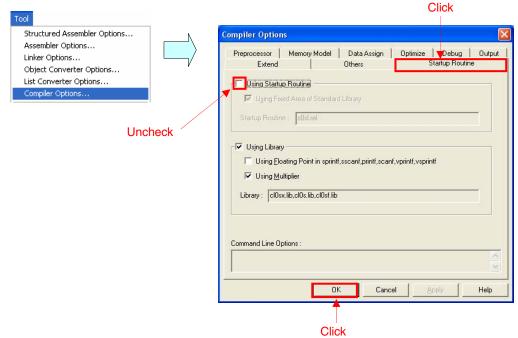
(7) The [New WorkSpace - Step 9/9 [Confirmation]] dialog box will be displayed. Confirm the settings and click the [Finish] button.



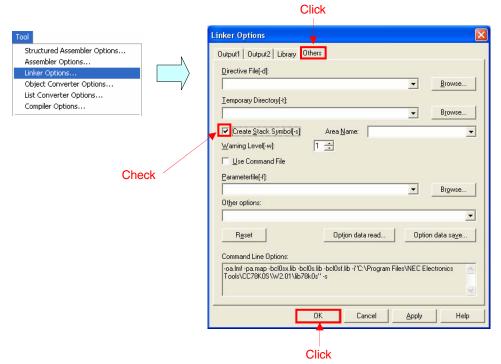
(8) A workspace will be created and the project will be registered.



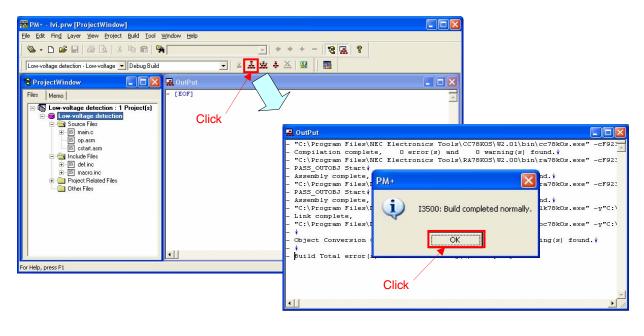
- · Compiler option settings
 - (9) Select [Compiler Options] from the [Tool] menu.
 - (10) The [Compiler Options] dialog box will be displayed. Click the [Startup Routine] tab, uncheck the [Using Startup Routine] check box and click the [OK] button.



- · Linker option settings
 - (11) Select [Linker Options] from the [Tool] menu.
 - (12) The [Linker Options] dialog box will be displayed. Click the [Others] tab, check the [Create Stack Symbol[-s]] check box, and click the [OK] button.



- Build execution
 - (13) Click [Build] button). When the source files are built normally, the message "I3500: Build completed normally." will be displayed.
 - (14) Click the [OK] button in the message window. A HEX file for flash memory writing will be created.





A HEX file for flash memory writing will be generated. \rightarrow Go to <u>5.2</u>.

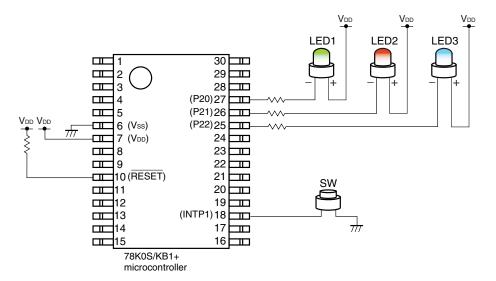
5.2 Operation with the Device

This section describes an example of an operation check using the device.

The HEX file generated by executing build can be written to the flash memory of the device.

For how to write to the flash memory of the device, refer to the Flash Programming Manual (Basic) MINICUBE2 version of each product (78K0S/KU1+, 78K0S/KY1+, 78K0S/KA1+, 78K0S/KB1+).

An example of how to connect the device and peripheral hardware (switch and LEDs) to be used is shown below.



An operation example of the device to which this sample program has been written is described below.

(1) When $V_{DD} \ge 3.0 \text{ V}$ (in normal operation)^{Note}

The LED lighting pattern changes depending on the number of switch inputs.

Note Perform switch input interrupt servicing operation at $V_{DD} \ge 3.0$ V, because the low-voltage detection voltage (V_{LVI}) is set to 2.85 V ± 0.15 V.

Number of Switch	LED Output		
Inputs ^{Note}	LED3	LED2	LED1
0	OFF	OFF	OFF
1	OFF	OFF	ON
2	OFF	ON	OFF
3	OFF	ON	ON
4	ON	OFF	OFF
5	ON	OFF	ON
6	ON	ON	OFF
7	ON	ON	ON

Note The lighting patterns from the zeroth switch input are repeated after the eighth switch input.

If the switch is pressed for less than 10 ms, the switch input is identified as chattering and the LED display pattern will not be changed (remains the same as before pressing the switch).

(2) $V_{DD} \ge 3.0 \text{ V} \rightarrow V_{DD} = 2.5 \text{ V} \text{ (low-voltage detection)} \rightarrow V_{DD} \ge 3.0 \text{ V}$

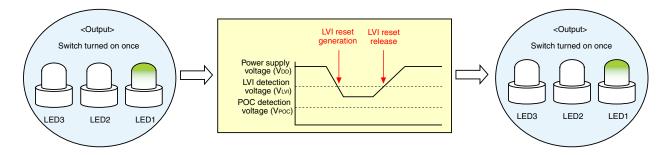
The lighting of the LEDs changes as follows in accordance with the change in power supply voltage.

<1> VDD ≥ 3.0 V \rightarrow VDD = 2.5 V

An LVI reset will be generated, because the low-voltage detection level (V_{LVI}) is set to 2.85 V ± 0.15 V and the low-voltage detection function is set to be used for reset. At this time, all LEDs will be turned off, but RAM retains the LED display data immediately before the reset.

<2> VDD = 2.5 V \rightarrow VDD ≥ 3.0 V

Operation is returned to normal mode. At this time, the lighting pattern immediately before the reset will be restored, because the reset source is confirmed to be an LVI reset and the LED display data retained in RAM is read.



(3) $V_{DD} \ge 3.0 \text{ V} \rightarrow 2.0 \text{ V} > V_{DD}$ (less than data retention power supply voltage) $\rightarrow V_{DD} \ge 3.0 \text{ V}$

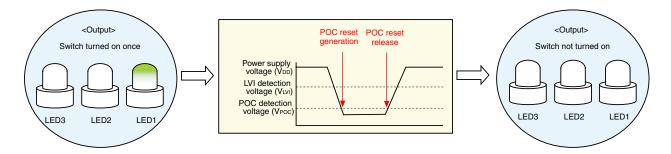
The lighting of the LEDs changes as follows in accordance with the change in power supply voltage.

<1> $V_{DD} \ge 3.0 \text{ V} \rightarrow 2.0 \text{ V} > V_{DD}$

A reset caused by power-on-clear (POC) will be generated. At this time, all LEDs will be turned off and RAM data becomes undefined.

<2> 2.0 V > VDD \rightarrow VDD \geq 3.0 V

Operation is returned to normal mode. At this time, all LEDs will be turned off (number of switch inputs = 0), because the reset source is confirmed to be other than an LVI reset and the LED lighting pattern of RAM is initialized.



Application Note U18821EJ2V0AN

CHAPTER 6 RELATED DOCUMENTS

Document Name			Japanese/English
78K0S/KU1+ User's Manual			<u>PDF</u>
78K0S/KY1+ User's	Manual		<u>PDF</u>
78K0S/KA1+ User's	Manual		<u>PDF</u>
78K0S/KB1+ User's	Manual		<u>PDF</u>
78K/0S Series Instru	ctions User's Manual		<u>PDF</u>
RA78K0S Assemble	r Package User's Manual	Language	<u>PDF</u>
	Operation		
CC78K0S C Compile	CC78K0S C Compiler User's Manual Language		
Operation			<u>PDF</u>
PM+ Project Manager User's Manual			<u>PDF</u>
SM+ System Simulator Operation User's Manual			<u>PDF</u>
Flash Programming Manual (Basic) MINICUBE2 version 78K0S/KU1+		78K0S/KU1+	<u>PDF</u>
		78K0S/KY1+	<u>PDF</u>
78K0S/KA1+ 78K0S/KB1+			<u>PDF</u>
			<u>PDF</u>
78K0S/Kx1+	Sample Program Startup Guide		<u>PDF</u>
Application Note	Sample Program (Initial Settings) LED Lighting Switch Control		<u>PDF</u>
	Sample Program (Interrupt) External Interrupt Generated by Switch Input		<u>PDF</u>

<R>

APPENDIX A PROGRAM LIST

As a program list example, the 78K0S/KB1+ microcontroller source program is shown below.

```
main.asm (Assembly language version)
;
    NEC Electronics
                    78K0S/KB1+
78KOS/KB1+ Sample program
Low-voltage detection
;<<History>>
   2007.6.-- Release
;<<Overview>>
;This sample program presents an example of using the low-voltage detection
;(LVI) function.
;A low-voltage detector (LVI) is used to set so that an internal reset signal
; is generated when VDD is less than VLVI (2.85 V +-0.15 V).
; After completion of the initial settings, the LED lighting pattern changes,
;depending on the number of switch inputs.
; (This is the same processing described in Sample Program Interrupt.)
; Here, the number of switch inputs is initialized when a reset is generated
; by other than LVI, but when a reset is generated by LVI, the number of switch
; inputs before the reset is restored and an LED lighting pattern is displayed
;accordingly, because RAM data is retained.
;
  <Principal setting contents>
; - Stop the watchdog timer operation
; - Set the low-voltage detection voltage (VLVI) to 2.85 V +-0.15 V
; - Generate an internal reset signal (low-voltage detector) when VDD < VLVI
after VDD >= VLVI
 - Set the CPU clock frequency to 4 MHz
  - Set the valid edge of external interrupt INTP1 to falling edge
  - Set the chattering removal time during switch input to 10 ms
  <LED lighting pattern after low-voltage detection and reset release>
; - Reset generated by other than the low-voltage detector ... Turn off all
LEDs
; - Reset generated by the low-voltage detector ... Retain the LED lighting
pattern before the reset
;
  <Number of switch inputs and LED lighting patterns>
;
   SW Inputs | LED3 | LED2 | LED1 |
```

```
(P43)
            | (P22) | (P21) | (P20)
;
      0 times
;
              OFF
                    OFF
                         OFF
;
     1 time
              OFF
                    OFF
                         ON
     2 times
              OFF
                    ON
                         OFF
     3 times
              OFF
                    ON
                         ON
     4 times
              ON
                    OFF
                         OFF
     5 times
              ON
                    OFF
                         ON
      6 times
              ON
                    ON
                         OFF
      7 times
             ON
                    ON
                         ON
   # The lighting patterns from the zeroth switch input are repeated after
the eighth switch input.
;<<I/O port settings>>
; Input: P43
; Output: P00-P03, P20-P23, P30-P33, P40-P42, P44-P47, P120-P123, P130
; # All unused ports are set as the output mode.
Vector table
XVCT CSEG AT 0000H
                    ;(00) RESET
    DW
        RESET_START
        RESET_START
                    ; (02) --
    DW
        RESET_START
                    ; (04) --
    DW
        RESET START
                    ;(06) INTLVI
                    ;(08) INTPO
        RESET START
    DW
                    ;(0A) INTP1
    DW
        INTERRUPT P1
        RESET START
                    ;(OC) INTTMH1
    DW
    DW
        RESET START
                    ;(0E) INTTM000
        RESET_START
    DW
                    ;(10) INTTM010
    DW
        RESET START
                    ;(12) INTAD
    DW
        RESET_START
                    ; (14) --
        RESET_START
                    ;(16) INTP2
    DW
    DW
        RESET_START
                    ;(18) INTP3
    DW
        RESET_START
                    ;(1A) INTTM80
    DW
        RESET_START
                    ;(1C) INTSRE6
        RESET_START
    DW
                    ;(1E) INTSR6
        RESET START
                    ;(20) INTST6
    DW
Define the RAM
XRAM DSEG SADDR
CNT 1:
        DS
            1
                    ; For major loop
CNT 2:
        DS
            1
                    ; For minor loop
LEDDATA:
        DS
            1
                    ; LED display pattern variable
```

```
Define the memory stack area
XSTK DSEG AT OFEEOH
STACKEND:
   DS
        20H
                     ; Memory stack area = 32 bytes
STACKTOP:
                     ; Start address of the memory stack area = FF00H
Initialization after RESET
XMAIN CSEG UNIT
RESET_START:
;------
   Initialize the stack pointer
;-----
    MOVW AX, #STACKTOP
    MOVW SP, AX
                 ; Set the stack pointer
;------
   Detect low-voltage + initialize the watchdog timer + set the clock
:______
;---- Initialize the watchdog timer ----
    MOV WDTM, #01110111B ; Stop the watchdog timer operation
;---- Set the clock <1> -----
        PCC, #00000000B ; The clock supplied to the CPU (fcpu) = fxp (=
    VOM
fx/4 = 2 MHz)
                #00000001B ; Stop the oscillation of the low-speed
   VOM
       LSRCM,
internal oscillator
;---- Check the reset source ----
            RESF
                ; Read the reset source
        Α,
        A.O, $SET_CLOCK ; Omit subsequent LVI-related processing and go
to SET_CLOCK during LVI reset
;---- Set low-voltage detection ----
   MOV LVIS, #00000111B ; Set the low-voltage detection level (VLVI) to
2.85 \text{ V} +-0.15 \text{ V}
    SET1 LVION
                    ; Enable the low-voltage detector operation
       A, #40
                    ; Assign the 200 us wait count value
    VOM
;---- 200 us wait -----
WAIT 200US:
    DEC
    BNZ
        MAIT_200US; 0.5[us/clk] \times 10[clk] \times 40[count] = 200[us]
;---- VDD >= VLVI wait processing ----
WAIT_LVI:
    NOP
        LVIF, $WAIT_LVI ; Branch if VDD < VLVI
    BT
    SET1 LVIMD
                    ; Set so that an internal reset signal is
generated when VDD < VLVI
    MOV LEDDATA, #00000111B ; Initialize the LED display data
```

```
;---- Set the clock <2> -----
SET CLOCK:
   MOV
      PPCC, #00000001B ; The clock supplied to the peripheral hardware
(fxp) = fx/2 (= 4 MHz)
                 ; -> The clock supplied to the CPU (fcpu) = fxp
= 4 MHz
;------
   Initialize the port 0
      VOM
      Р0,
          #0000000B ; Set output latches of P00-P03 as low
   VOM
      PMO, #11110000B ; Set P00-P03 as output mode
;-----
   Initialize the port 2
;------
   MOV A, LEDDATA ; Read the LED display data

MOV P2 A : Set LED output (P20-P22);
   MOV P2, A
                 ; Set LED output (P20-P22) and output latch of
P23 as low
      PM2, #11110000B ; Set P20-P23 as output mode
   VOM
;------
   Initialize the port 3
;------
      P3, #0000000B; Set output latches of P30-P33 as low
      PM3, #11110000B ; Set P30-P33 as output mode
   VOM
   Initialize the port 4
;-----
   MOV P4, #0000000B; Set output latches of P40-P47 as low
      PU4, #00001000B ; Connect on-chip pull-up resistor to P43
      PM4, #00001000B ; Set P43 as input mode, P40-P42 and P44-P47 as
   MOV
output mode
;-----
   Initialize the port 12
;______;
   VOM
      P12, #0000000B; Set output latches of P120-P123 as low
      PM12, #11110000B ; Set P120-P123 as output mode
   VOM
;-----
   Initialize the port 13
;-----
   MOV P13, #00000001B ; Set output latch of P130 as high
   Set the interrupt
               ______
   MOV INTMO, #0000000B; Set the valid edge of INTP1 to falling
edge
   CLR1 PIF1
                  ; Clear invalid interrupt requests in advance
   CLR1 PMK1
                 ; Release the INTP1 interrupt mask
   ΕI
                  ; Enable vector interrupt
;
```

```
Main loop
MAIN LOOP:
    NOP
    BR
         $MAIN_LOOP
                      ; Go to the MAIN_LOOP
External interrupt INTP1
; ***************************
INTERRUPT_P1:
    PUSH AX
                       ; Save the AX register data to the stack
;---- 10 ms wait to handle chattering ----
    MOV CNT 1,
                #215 ; Assign the count value for the major loop
    NOP
    NOP
LOOP 1:
    MOV CNT_2, #17 ; Assign the count value for the minor loop
    NOP
LOOP_2:
    NOP
    DBNZ CNT_2,
                  $LOOP_2
                                ; Minor loop
    DBNZ CNT_1,
                  $LOOP 1
                               ; Major loop
                      ; Clear the INTP1 interrupt request
    CLR1 PIF1
;---- Identification of chattering detection ----
         P4.3, $END_INTP1 ; Branch if there is no switch input
;---- LED lighting processing ----
    DEC
         LEDDATA
                  ; Decrement the current LED display data by 1
         LEDDATA, #00000111B ; Mask bits other than bits 0 to 2
    AND
         A, LEDDATA ; Read the LED display data
    MOV
            A
    VOM
         P2,
                       ; Output the LED light
END_INTP1:
    POP AX
                       ; Restore the AX register data
    RETI
                       ; Return from interrupt servicing
end
```

Application Note U18821EJ2V0AN

main.c (C language version)

NEC Electronics 78K0S/KB1+

78KOS/KB1+ Sample program

Low-voltage detection

<<History>>

2007.6.-- Release

<<Overview>>

This sample program presents an example of using the low-voltage detection (LVI) function.

A low-voltage detector (LVI) is used to set so that an internal reset signal is generated when VDD is less than VLVI (2.85 V +-0.15 V).

After completion of the initial settings, the LED lighting pattern changes, depending on the number of switch inputs.

(This is the same processing described in Sample Program Interrupt.) Here, the number of switch inputs is initialized when a reset is generated by other than LVI, but when a reset is generated by LVI, the number of switch inputs before the reset is restored and an LED lighting pattern is displayed accordingly, because RAM data is retained.

<Principal setting contents>

- Declare a function run by an interrupt: INTP1 -> fn_intp1()
- Stop the watchdog timer operation
- Set the low-voltage detection voltage (VLVI) to 2.85 V +-0.15 V
- Generate an internal reset signal (low-voltage detector) when VDD < VLVI after VDD >= VLVI
 - Set the CPU clock frequency to 4 MHz
 - Set the valid edge of external interrupt INTP1 to falling edge
 - Set the chattering detection time during switch input to 10 ms

<LED lighting pattern after low-voltage detection and reset release>

- Reset generated by other than the low-voltage detector \dots Turn off all LEDs
- Reset generated by the low-voltage detector \dots Retain the LED lighting pattern before the reset

<Number of switch inputs and LED lighting patterns>

+			+
SW Inputs (P43)	LED3 (P22)	LED2 (P21)	LED1 (P20)
0 times 1 time	OFF OFF	OFF OFF	OFF
2 times	OFF	OFF	OFF
3 times	OFF	ON	ON

OFF

ON

4 times

5 times

on

ON

OFF

OFF

```
6 times
               ON
                      ON
                            OFF
      7 times
               on
                      ON
                            on
   # The lighting patterns from the zeroth switch input are repeated after
the eighth switch input.
<<I/O port settings>>
 Input: P43
 Output: P00-P03, P20-P23, P30-P33, P40-P42, P44-P47, P120-P123, P130
 # All unused ports are set as the output mode.
******************************
/*-----
    Preprocessing directive (#pragma)
_____*/
#pragma SFR
                           /* SFR names can be described at the C
source level */
                           /* EI instructions can be described at the
#pragma
        EI
C source level */
                           /* NOP instructions can be described at
#pragma
        NOP
the C source level */
#pragma interrupt INTP1 fn_intp1
                           /* Interrupt function declaration:INTP1 */
/*****************************
    Initialization after RESET
*************************
    sreg unsigned char g_ucLED; /* 8-bit variable for LED display data
(high-speed internal RAM area) */
void hdwinit(void){
    unsigned char ucCnt200us;
                           /* 8-bit variable for 200 us wait */
/*_____
    Initialize the watchdog timer + detect low-voltage + set the clock
    /* Initialize the watchdog timer */
    WDTM = 0b01110111;
                           /* Stop the watchdog timer operation */
    /* Set the clock <1> */
    PCC = 0b00000000;
                           /* The clock supplied to the CPU (fcpu) =
fxp (= fx/4 = 2 MHz) */
    LSRCM = 0b0000001;
                           /* Stop the oscillation of the low-speed
internal oscillator */
    /* Check the reset source */
    if (!(RESF & 0b00000001)){ /* Omit subsequent LVI-related processing
during LVI reset */
         /* Set low-voltage detection */
```

```
LVIS = 0b00000111;
                     /* Set the low-voltage detection level
(VLVI) to 2.85 V +-0.15 V */
       LVION = 1;
                     /* Enable the low-voltage detector
operation */
       about 200 us */
          NOP();
       }
       while (LVIF){
                  /* Wait for VDD >= VLVI */
          NOP();
       LVIMD = 1;
                     /* Set so that an internal reset signal is
generated when VDD < VLVI */
       q ucLED = 0b00000111; /* Initialize the LED display data */
   }
   /* Set the clock <2> */
                     /* The clock supplied to the peripheral
   PPCC = 0b0000001;
hardware (fxp) = fx/2 (= 4 MHz)
                     -> The clock supplied to the CPU (fcpu) =
fxp = 4 MHz */
/*-----
   Initialize the port 0
   -----*/
   /*-----
   Initialize the port 2
_____*/
      = g_ucLED;
= 0b11110000;
                     /* Output the LED display data */
                     /* Set P20-P23 as output mode */
   PM2
/*-----
   Initialize the port 3
-----*/
                     /* Set output latches of P30-P33 as low */
/* Set P30-P33 as output mode */
      = 0b0000000;
   P3
   PM3 = 0b11110000;
/*-----
   Initialize the port 4
                     /* Set output latches of P40-P47 as low */
   P4 = 0b00000000;
   PU4 = 0b00001000;
                     /* Connect on-chip pull-up resistor to P43
   PM4 = 0b00001000; /* Set P43 as input mode, P40-P42 and P44-
P47 as output mode */
/*-----
   Initialize the port 12
_____*/
   P12 = 0b00000000;
                     /* Set output latches of P120-P123 as low
   PM12 = 0b11110000;
                     /* Set P120-P123 as output mode */
```

```
/*-----
    Initialize the port 13
-----*/
    P13 = 0b00000001;
                         /* Set output latch of P130 as high */
    Set the interrupt
 _____*/
    INTM0 = 0b00000000;
                         /* Set the valid edge of INTP1 to falling
edge */
    PIF1 = 0;
                         /* Clear invalid interrupt requests in
advance */
    PMK1 = 0;
                        /* Release the INTP1 interrupt mask */
    return;
}
/****************************
    Main loop
************************
void main(void){
    EI();
                         /* Enable vector interrupt */
    while (1){
        NOP();
        NOP();
    }
/***************************
    External interrupt INTP1
*************************
__interrupt void fn_intp1(){
    unsigned int unChat; /* 16-bit variable for the chattering removal
timer */
    for (unChat = 0; unChat < 555; unChat++){ /* Wait of about 10 ms (for
chattering removal) */
        NOP();
    }
    PIF1 = 0;
                         /* Clear the INTP1 interrupt request */
    if (!P4.3){ /* Processing performed if SW is on for 10 ms or more
        g_ucLED -= 1;
                         /* Decrement the current LED display data
by 1 */
        g_ucled \&= 0b000000111; /* Mask bits other than bits 0 to 2 */
        P2 = g_ucled;
                         /* Output the LED light */
    }
    return;
}
```

• op.asm (Common to assembly language and C language versions)

```
Option byte
OPBT CSEG AT 0080H
          10011100B
                  ; Option byte area
                ----- Low-speed internal oscillator can be
stopped by software
             |++---- High-speed internal oscillation clock (8
MHz) is selected for system clock source
            +----- P34/RESET pin is used as RESET pin
     DB
          11111111B
                   ; Protect byte area (for the self programming
mode)
          ++++++ all blocks can be written or erased
end
```

APPENDIX B REVISION HISTORY

The mark "<R>" shows major revised points. The revised points can be easily searched by copying an "<R>" in the PDF file and specifying it in the "Find what." field.

Edition	Date Published	Page	Revision
1st edition	October 2007	-	-
2nd edition	September 2008	pp.18 to 26	Modification of 5.1 Building the Sample Program
		p.29	CHAPTER 6 RELATED DOCUMENTS
			Addition of Flash Programming Manual (Basic) MINICUBE2 version

For further information, please contact:

NEC Electronics Corporation

1753, Shimonumabe, Nakahara-ku, Kawasaki, Kanagawa 211-8668, Japan Tel: 044-435-5111

http://www.necel.com/

[America]

NEC Electronics America, Inc.

2880 Scott Blvd. Santa Clara, CA 95050-2554, U.S.A. Tel: 408-588-6000 800-366-9782 http://www.am.necel.com/

[Europe]

NEC Electronics (Europe) GmbH

Arcadiastrasse 10 40472 Düsseldorf, Germany Tel: 0211-65030 http://www.eu.necel.com/

Hanover Office

Podbielskistrasse 166 B 30177 Hannover Tel: 0 511 33 40 2-0

Munich Office

Werner-Eckert-Strasse 9 81829 München Tel: 0 89 92 10 03-0

Stuttgart Office

Industriestrasse 3 70565 Stuttgart Tel: 0 711 99 01 0-0

United Kingdom Branch

Cygnus House, Sunrise Parkway Linford Wood, Milton Keynes MK14 6NP, U.K. Tel: 01908-691-133

Succursale Française

9, rue Paul Dautier, B.P. 52 78142 Velizy-Villacoublay Cédex France

Tel: 01-3067-5800

Sucursal en España

Juan Esplandiu, 15 28007 Madrid, Spain Tel: 091-504-2787

Tyskland Filial

Täby Centrum Entrance S (7th floor) 18322 Täby, Sweden Tel: 08 638 72 00

Filiale Italiana

Via Fabio Filzi, 25/A 20124 Milano, Italy Tel: 02-667541

Branch The Netherlands

Steijgerweg 6 5616 HS Eindhoven The Netherlands Tel: 040 265 40 10

[Asia & Oceania]

NEC Electronics (China) Co., Ltd

7th Floor, Quantum Plaza, No. 27 ZhiChunLu Haidian District, Beijing 100083, P.R.China Tel: 010-8235-1155 http://www.cn.necel.com/

Shanghai Branch

Room 2509-2510, Bank of China Tower, 200 Yincheng Road Central, Pudong New Area, Shanghai, P.R.China P.C:200120 Tel:021-5888-5400 http://www.cn.necel.com/

Shenzhen Branch

Unit 01, 39/F, Excellence Times Square Building, No. 4068 Yi Tian Road, Futian District, Shenzhen, P.R.China P.C:518048 Tel:0755-8282-9800 http://www.cn.necel.com/

NEC Electronics Hong Kong Ltd.

Unit 1601-1613, 16/F., Tower 2, Grand Century Place, 193 Prince Edward Road West, Mongkok, Kowloon, Hong Kong Tel: 2886-9318 http://www.hk.necel.com/

NEC Electronics Taiwan Ltd. 7F, No. 363 Fu Shing North Road Taipei, Taiwan, R. O. C. Tel: 02-8175-9600 http://www.tw.necel.com/

NEC Electronics Singapore Pte. Ltd.

238A Thomson Road, #12-08 Novena Square, Singapore 307684 Tel: 6253-8311 http://www.sg.necel.com/

NEC Electronics Korea Ltd.

11F., Samik Lavied'or Bldg., 720-2, Yeoksam-Dong, Kangnam-Ku, Seoul, 135-080, Korea Tel: 02-558-3737 http://www.kr.necel.com/