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# 78K0R/Kx3 Microcontroller Sample Program Operation Manual (D/A Conversion (Real-Time Output Mode) (D/A Converter), C Source)

This software is for reference only and NEC Electronics does not guarantee its operation.

Thoroughly evaluate this software on your set prior to use.

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1st Product Solution Group, Multipurpose Microcomputer Systems Division, Microcomputer Operations Unit NEC Electronics Corporation

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# 1. OVERVIEW

This manual explains the sample program functions of the D/A converter (real-time output mode) for the 78K0R/Kx3.

In this sample program, D/A conversion is performed, triggered by the interrupt request signal (INTTM04) of timer channel 4.

# 2. RESOURCES USED

Resource	Description	Remark
Main clock specification	Internal high-speed oscillator used (8 MHz (TYP.))	Always oscillated
	High-speed system clock used (20 MHz)	Oscillated by initial processing.
		Supplied to CPU and peripheral hardware
Subclock	XT1 (32.768 kHz)	Oscillated by initial processing
Related hardware	Peripheral enable register 0 (PER0)	Controls supplying and stopping of the input
		clock supply.
	D/A converter mode register (DAM)	Sets real-time output mode.
	8-bit D/A conversion value setting register 0	
	(DACS0)	
	Port mode register 11 (PM11)	
	Port register 11 (P11)	
I/O	Analog output: ANO0 (P110)	
Interrupt	Timer channel 4 count end or capture end	
	interrupt (INTTM04)	
Others	Not used	

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# 3. SOFTWARE CONFIGURATION

#### Files

File Name	Processing Outline	Remark
K0R_def.h <sup>Note 1</sup>	Definition file	
K0R_init.c <sup>Note 1</sup>	Initialization processing	
K0R_ext.h	External declaration	
K0R_main.c	Main processing	
K0R_sfr_set.c	D/A converter processing	
	(real-time output mode)	
K0R_timer_int.c <sup>Note 2</sup>	Timer array unit	
	(interval timer)	

**Notes 1.** These files are commonly used by the sample programs.

This file generates an interrupt each time the interval timer counts 10 ms.For details of this module, refer to Timer Array Unit Processing (Interval Timer/Square Wave Output).

# 4. FUNCTION EXPLANATIONS

[File name]

K0R\_main.c

# Function

Function Name	Processing Outline	Argument	Return Value
MMA_STRT	Main routine	None	None

# Function explanations

Function name	main
Processing	Main routine
Argument	_
Return value	-
Description	Executes initialization processing and then performs D/A conversion processing.
Remark	-

[File name]

K0R\_sfr\_set.c

# **Functions**

Function Name	Processing Outline	Argument	Return Value
SDA_RINI	Initializes D/A converter processing.	None	None
SDA_RSTP	Stops D/A converter processing operation.	None	None

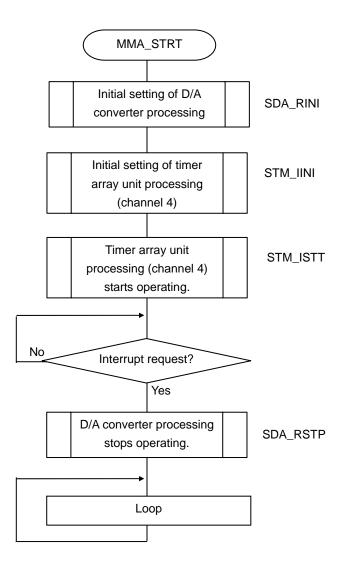
# Function explanations

Function name	SDA_RINI
Processing	Initializes D/A converter processing.
Argument	_
Return value	_
Description	Initializes the D/A converter.
Remark	-

Function name	SDA_RSTP
Processing	Stops D/A converter processing operation.
Argument	_
Return value	_
Description	Stops D/A conversion operation.
Remark	-

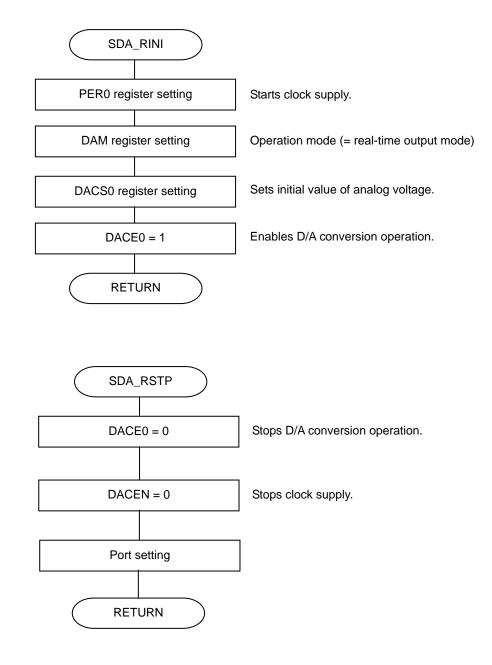
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# 5. FLOWCHARTS



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